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#### What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded -</u> <u>Microcontrollers</u>"

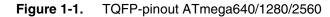
#### Details

Product Status	Active
Core Processor	AVR
Core Size	8-Bit
Speed	16MHz
Connectivity	EBI/EMI, I <sup>2</sup> C, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	86
Program Memory Size	64KB (32K x 16)
Program Memory Type	FLASH
EEPROM Size	4K x 8
RAM Size	8K x 8
Voltage - Supply (Vcc/Vdd)	2.7V ~ 5.5V
Data Converters	A/D 16x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	100-TQFP
Supplier Device Package	100-TQFP (14x14)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/atmega640-16au

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

## 1. Pin Configurations



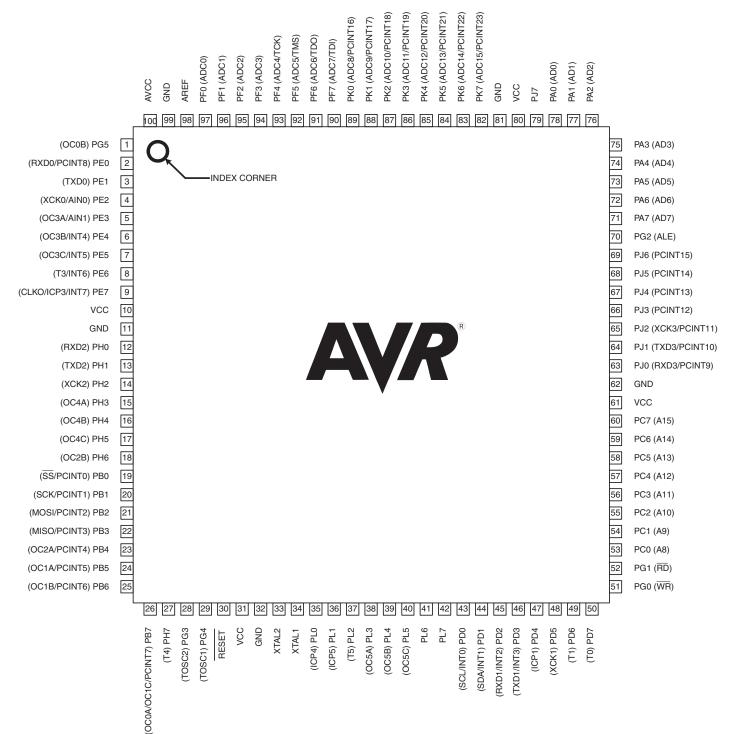
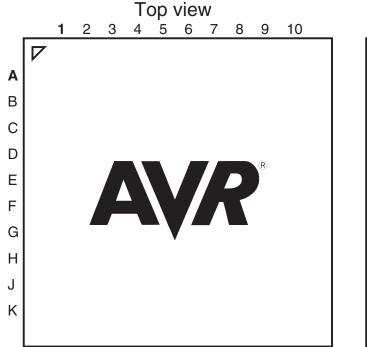


Figure 1-2. CBGA-pinout ATmega640/1280/2560



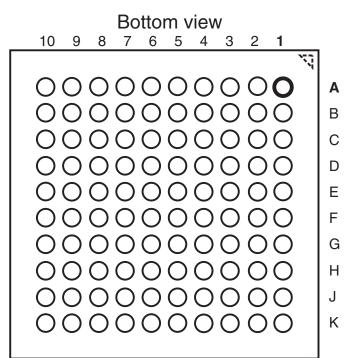


Table 1-1. CBGA-pinout ATmega640/1280/2560

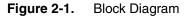
						1				
	1	2	3	4	5	6	7	8	9	10
Α	GND	AREF	PF0	PF2	PF5	PK0	PK3	PK6	GND	VCC
В	AVCC	PG5	PF1	PF3	PF6	PK1	PK4	PK7	PA0	PA2
С	PE2	PE0	PE1	PF4	PF7	PK2	PK5	PJ7	PA1	PA3
D	PE3	PE4	PE5	PE6	PH2	PA4	PA5	PA6	PA7	PG2
Е	PE7	PH0	PH1	PH3	PH5	PJ6	PJ5	PJ4	PJ3	PJ2
F	VCC	PH4	PH6	PB0	PL4	PD1	PJ1	PJ0	PC7	GND
G	GND	PB1	PB2	PB5	PL2	PD0	PD5	PC5	PC6	VCC
н	PB3	PB4	RESET	PL1	PL3	PL7	PD4	PC4	PC3	PC2
J	PH7	PG3	PB6	PL0	XTAL2	PL6	PD3	PC1	PC0	PG1
К	PB7	PG4	VCC	GND	XTAL1	PL5	PD2	PD6	PD7	PG0

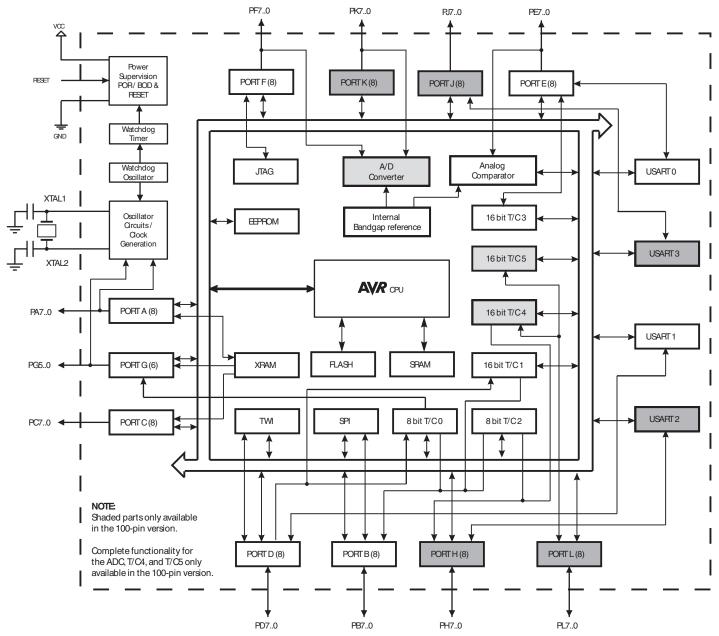
Note: The functions for each pin is the same as for the 100 pin packages shown in Figure 1-1 on page 2.

## 2. Overview

The ATmega640/1280/1281/2560/2561 is a low-power CMOS 8-bit microcontroller based on the AVR enhanced RISC architecture. By executing powerful instructions in a single clock cycle, the ATmega640/1280/1281/2560/2561 achieves throughputs approaching 1 MIPS per MHz allowing the system designer to optimize power consumption versus processing speed.

### 2.1 Block Diagram





The Atmel<sup>®</sup> AVR<sup>®</sup> core combines a rich instruction set with 32 general purpose working registers. All the 32 registers are directly connected to the Arithmetic Logic Unit (ALU), allowing two independent registers to be accessed in one single instruction executed in one clock cycle. The resulting architecture is more code efficient while achieving throughputs up to ten times faster than conventional CISC microcontrollers.

The ATmega640/1280/1281/2560/2561 provides the following features: 64K/128K/256K bytes of In-System Programmable Flash with Read-While-Write capabilities, 4Kbytes EEPROM, 8Kbytes SRAM, 54/86 general purpose I/O lines, 32 general purpose working registers, Real Time Counter (RTC), six flexible Timer/Counters with compare modes and PWM, four USARTs, a byte oriented 2-wire Serial Interface, a 16-channel, 10-bit ADC with optional differential input stage with programmable gain, programmable Watchdog Timer with Internal Oscillator, an SPI serial port, IEEE® std. 1149.1 compliant JTAG test interface, also used for accessing the On-chip Debug system and programming and six software selectable power saving modes. The Idle mode stops the CPU while allowing the SRAM, Timer/Counters, SPI port, and interrupt system to continue functioning. The Power-down mode saves the register contents but freezes the Oscillator, disabling all other chip functions until the next interrupt or Hardware Reset. In Power-save mode, the asynchronous timer continues to run, allowing the user to maintain a timer base while the rest of the device is sleeping. The ADC Noise Reduction mode stops the CPU and all I/O modules except Asynchronous Timer and ADC, to minimize switching noise during ADC conversions. In Standby mode, the Crystal/Resonator Oscillator is running while the rest of the device is sleeping. This allows very fast start-up combined with low power consumption. In Extended Standby mode, both the main Oscillator and the Asynchronous Timer continue to run.

Atmel offers the QTouch<sup>®</sup> library for embedding capacitive touch buttons, sliders and wheels functionality into AVR microcontrollers. The patented charge-transfer signal acquisition offersrobust sensing and includes fully debounced reporting of touch keys and includes Adjacent Key Suppression<sup>®</sup> (AKS<sup>®</sup>) technology for unambiguous detection of key events. The easy-to-use QTouch Suite toolchain allows you to explore, develop and debug your own touch applications.

The device is manufactured using the Atmel high-density nonvolatile memory technology. The On-chip ISP Flash allows the program memory to be reprogrammed in-system through an SPI serial interface, by a conventional non-volatile memory programmer, or by an On-chip Boot program running on the AVR core. The boot program can use any interface to download the application program in the application Flash memory. Software in the Boot Flash section will continue to run while the Application Flash section is updated, providing true Read-While-Write operation. By combining an 8-bit RISC CPU with In-System Self-Programmable Flash on a monolithic chip, the Atmel ATmega640/1280/1281/2560/2561 is a powerful microcontroller that provides a highly flexible and cost effective solution to many embedded control applications.

The ATmega640/1280/1281/2560/2561 AVR is supported with a full suite of program and system development tools including: C compilers, macro assemblers, program debugger/simulators, in-circuit emulators, and evaluation kits.

#### 2.3.6 Port D (PD7..PD0)

Port D is an 8-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The Port D output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port D pins that are externally pulled low will source current if the pull-up resistors are activated. The Port D pins are tri-stated when a reset condition becomes active, even if the clock is not running.

Port D also serves the functions of various special features of the ATmega640/1280/1281/2560/2561 as listed on page 80.

#### 2.3.7 Port E (PE7..PE0)

Port E is an 8-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The Port E output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port E pins that are externally pulled low will source current if the pull-up resistors are activated. The Port E pins are tri-stated when a reset condition becomes active, even if the clock is not running.

Port E also serves the functions of various special features of the ATmega640/1280/1281/2560/2561 as listed on page 82.

#### 2.3.8 Port F (PF7..PF0)

Port F serves as analog inputs to the A/D Converter.

Port F also serves as an 8-bit bi-directional I/O port, if the A/D Converter is not used. Port pins can provide internal pull-up resistors (selected for each bit). The Port F output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port F pins that are externally pulled low will source current if the pull-up resistors are activated. The Port F pins are tri-stated when a reset condition becomes active, even if the clock is not running. If the JTAG interface is enabled, the pull-up resistors on pins PF7(TDI), PF5(TMS), and PF4(TCK) will be activated even if a reset occurs.

Port F also serves the functions of the JTAG interface.

#### 2.3.9 Port G (PG5..PG0)

Port G is a 6-bit I/O port with internal pull-up resistors (selected for each bit). The Port G output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port G pins that are externally pulled low will source current if the pull-up resistors are activated. The Port G pins are tri-stated when a reset condition becomes active, even if the clock is not running.

Port G also serves the functions of various special features of the ATmega640/1280/1281/2560/2561 as listed on page 86.

#### 2.3.10 Port H (PH7..PH0)

Port H is a 8-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The Port H output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port H pins that are externally pulled low will source current if the pull-up resistors are activated. The Port H pins are tri-stated when a reset condition becomes active, even if the clock is not running.

Port H also serves the functions of various special features of the ATmega640/1280/2560 as listed on page 88.

#### 2.3.11 Port J (PJ7..PJ0)

Port J is a 8-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The Port J output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port J pins that are externally pulled low will source current if the pull-up resistors are activated. The Port J pins are tri-stated when a reset condition becomes active, even if the clock is not running. Port J also serves the functions of various special features of the ATmega640/1280/2560 as listed on page 90.



## 8. Instruction Set Summary

Mnemonics	Operands	Description	Operation	Flags	#Clocks
ARITHMETIC AND L	OGIC INSTRUCTIONS	6		·	
ADD	Rd, Rr	Add two Registers	$Rd \leftarrow Rd + Rr$	Z, C, N, V, H	1
ADC	Rd, Rr	Add with Carry two Registers	$Rd \leftarrow Rd + Rr + C$	Z, C, N, V, H	1
ADIW	Rdl,K	Add Immediate to Word	$Rdh:Rdl \leftarrow Rdh:Rdl + K$	Z, C, N, V, S	2
SUB	Rd, Rr	Subtract two Registers	$Rd \leftarrow Rd - Rr$	Z, C, N, V, H	1
SUBI	Rd, K	Subtract Constant from Register	$Rd \leftarrow Rd - K$	Z, C, N, V, H	1
SBC	Rd, Rr	Subtract with Carry two Registers	$Rd \leftarrow Rd - Rr - C$	Z, C, N, V, H	1
SBCI	Rd, K	Subtract with Carry Constant from Reg.	$Rd \leftarrow Rd - K - C$	Z, C, N, V, H	1
SBIW	Rdl,K	Subtract Immediate from Word	Rdh:Rdl ← Rdh:Rdl - K	Z, C, N, V, S	2
AND	Rd, Rr	Logical AND Registers	$Rd \leftarrow Rd \bullet Rr$	Z, N, V	1
ANDI	Rd, K	Logical AND Register and Constant	$Rd \leftarrow Rd \bullet K$	Z, N, V	1
OR	Rd, Rr	Logical OR Registers	$Rd \leftarrow Rd \lor Rr$	Z, N, V	1
ORI	Rd, K	Logical OR Register and Constant	$Rd \leftarrow Rd \vee K$	Z, N, V	1
EOR	Rd, Rr	Exclusive OR Registers	$Rd \leftarrow Rd \oplus Rr$	Z, N, V	1
COM	Rd	One's Complement	$Rd \leftarrow 0xFF - Rd$	Z, C, N, V	1
NEG	Rd	Two's Complement	Rd ← 0x00 – Rd	Z, C, N, V, H	1
SBR	Rd,K	Set Bit(s) in Register	$Rd \leftarrow Rd \vee K$	Z, N, V	1
CBR	Rd,K	Clear Bit(s) in Register	$Rd \leftarrow Rd \bullet (0xFF - K)$	Z, N, V	1
INC	Rd	Increment	$Rd \leftarrow Rd + 1$	Z, N, V	1
DEC	Rd	Decrement	$Rd \leftarrow Rd - 1$	Z, N, V Z, N, V	1
-	Rd	Test for Zero or Minus			
TST			$Rd \leftarrow Rd \bullet Rd$	Z, N, V	1
CLR	Rd	Clear Register		Z, N, V	1
SER	Rd	Set Register		None	1
MUL	Rd, Rr	Multiply Unsigned	$R1:R0 \leftarrow Rd \times Rr$	Z, C	2
MULS	Rd, Rr	Multiply Signed	$R1:R0 \leftarrow Rd \times Rr$	Z, C	2
MULSU	Rd, Rr	Multiply Signed with Unsigned	$R1:R0 \leftarrow Rd \times Rr$	Z, C	2
FMUL	Rd, Rr	Fractional Multiply Unsigned	$R1:R0 \leftarrow (Rd \times Rr) << 1$	Z, C	2
FMULS	Rd, Rr	Fractional Multiply Signed	$R1:R0 \leftarrow (Rd \times Rr) << 1$	Z, C	2
FMULSU	Rd, Rr	Fractional Multiply Signed with Unsigned	$R1:R0 \leftarrow (Rd \times Rr) << 1$	Z, C	2
BRANCH INSTRUCT	TIONS				
RJMP	k	Relative Jump	$PC \leftarrow PC + k + 1$	None	2
IJMP		Indirect Jump to (Z)	$PC \leftarrow Z$	None	2
EIJMP		Extended Indirect Jump to (Z)	$PC \leftarrow (EIND:Z)$	None	2
JMP	k	Direct Jump	$PC \leftarrow k$	None	3
RCALL	k	Relative Subroutine Call	$PC \leftarrow PC + k + 1$	None	4
ICALL		Indirect Call to (Z)	$PC \leftarrow Z$	None	4
EICALL		Extended Indirect Call to (Z)	PC ←(EIND:Z)	None	4
CALL	k	Direct Subroutine Call	PC ← k	None	5
RET		Subroutine Return	$PC \leftarrow STACK$	None	5
RETI		Interrupt Return	$PC \leftarrow STACK$	1	5
CPSE	Rd,Rr	Compare, Skip if Equal	if (Rd = Rr) PC $\leftarrow$ PC + 2 or 3	None	1/2/3
CP	Rd,Rr	Compare	Rd – Rr	Z, N, V, C, H	1
CPC	Rd,Rr	Compare with Carry	Rd – Rr – C	Z, N, V, C, H	1
CPI	Rd,K	Compare Register with Immediate	Rd – K	Z, N, V, C, H	1
SBRC	Rr, b	Skip if Bit in Register Cleared	if $(\text{Rr}(b)=0) \text{ PC} \leftarrow \text{PC} + 2 \text{ or } 3$	None	1/2/3
SBRS	Rr, b	Skip if Bit in Register is Set	if $(\text{Rr}(b)=0) \text{ PC} \leftarrow \text{PC} + 2 \text{ or } 3$ if $(\text{Rr}(b)=1) \text{ PC} \leftarrow \text{PC} + 2 \text{ or } 3$	None	1/2/3
SBIC	P, b	Skip if Bit in I/O Register Cleared	if $(P(b)=0) PC \leftarrow PC + 2 \text{ or } 3$ if $(P(b)=0) PC \leftarrow PC + 2 \text{ or } 3$	None	1/2/3
SBIS	P, b	Skip if Bit in I/O Register is Set	if $(P(b)=1) PC \leftarrow PC + 2 \text{ or } 3$	None	1/2/3
BRBS	s, k	Branch if Status Flag Set	if $(SREG(s) = 1)$ then $PC \leftarrow PC+k+1$	None	1/2
BRBC	s, k	Branch if Status Flag Cleared	if (SREG(s) = 0) then $PC \leftarrow PC + k + 1$	None	1/2
BREQ	k	Branch if Equal	if (Z = 1) then PC $\leftarrow$ PC + k + 1	None	1/2
BRNE	k	Branch if Not Equal	if (Z = 0) then $PC \leftarrow PC + k + 1$	None	1/2
BRCS	k	Branch if Carry Set	if (C = 1) then PC $\leftarrow$ PC + k + 1	None	1/2
BRCC	k	Branch if Carry Cleared	if (C = 0) then PC $\leftarrow$ PC + k + 1	None	1/2
BRSH	k	Branch if Same or Higher	if (C = 0) then PC $\leftarrow$ PC + k + 1	None	1/2
BRLO	k	Branch if Lower	if (C = 1) then PC $\leftarrow$ PC + k + 1	None	1/2
BRMI	k	Branch if Minus	if (N = 1) then PC $\leftarrow$ PC + k + 1	None	1/2
BRPL	k	Branch if Plus	if (N = 0) then PC $\leftarrow$ PC + k + 1	None	1/2
BRGE	k	Branch if Greater or Equal, Signed	if (N $\oplus$ V= 0) then PC $\leftarrow$ PC + k + 1	None	1/2
BRLT	k	Branch if Less Than Zero, Signed	if (N $\oplus$ V= 1) then PC $\leftarrow$ PC + k + 1	None	1/2
BRHS	k	Branch if Half Carry Flag Set	if (H = 1) then PC $\leftarrow$ PC + k + 1	None	1/2
BRHC	k	Branch if Half Carry Flag Cleared	if (H = 0) then PC $\leftarrow$ PC + k + 1	None	1/2
				None	1/2
BRTS	k	Branch II I Flag Sel	$  (1 = 1) $ then PC $\leftarrow$ PC + K + 1		
BRTS BRTC	k k	Branch if T Flag Set Branch if T Flag Cleared	if (T = 1) then PC $\leftarrow$ PC + k + 1 if (T = 0) then PC $\leftarrow$ PC + k + 1	None	1/2



Mnemonics	Operands	Description	Operation	Flags	#Clocks
OUT	P, Rr	Out Port	P ← Rr	None	1
PUSH	Rr	Push Register on Stack	$STACK \leftarrow Rr$	None	2
POP	Rd	Pop Register from Stack	$Rd \leftarrow STACK$	None	2
MCU CONTROL INS	TRUCTIONS				
NOP		No Operation		None	1
SLEEP		Sleep	(see specific descr. for Sleep function)	None	1
WDR		Watchdog Reset	(see specific descr. for WDR/timer)	None	1
BREAK		Break	For On-chip Debug Only	None	N/A

Note: EICALL and EIJMP do not exist in ATmega640/1280/1281. ELPM does not exist in ATmega640.

## 9. Ordering Information

### 9.1 ATmega640

Speed [MHz] <sup>(2)</sup>	Power Supply	Ordering Code	Package <sup>(1)(3)</sup>	Operation Range	
8	1.8 - 5.5V	ATmega640V-8AU ATmega640V-8AUR <sup>(4)</sup> ATmega640V-8CU ATmega640V-8CUR <sup>(4)</sup>	100A 100A 100C1 100C1	- Industrial (-40°C to 85°C)	
16	2.7 - 5.5V	ATmega640-16AU ATmega640-16AUR <sup>(4)</sup> ATmega640-16CU ATmega640-16CUR <sup>(4)</sup>	100A 100A 100C1 100C1		

Notes: 1. This device can also be supplied in wafer form. Contact your local Atmel sales office for detailed ordering information and minimum quantities.

2. See "Speed Grades" on page 357.

3. Pb-free packaging, complies to the European Directive for Restriction of Hazardous Substances (RoHS directive). Also Halide free and fully Green.

4. Tape & Reel.

	Package Type				
100A	100-lead, Thin (1.0mm) Plastic Gull Wing Quad Flat Package (TQFP)				
100C1	100-ball, Chip Ball Grid Array (CBGA)				

## 9.3 ATmega1281

Speed [MHz] <sup>(2)</sup>	Power Supply	Ordering Code	Package <sup>(1)(3)</sup>	<b>Operation Range</b>	
8	1.8 - 5.5V	ATmega1281V-8AU ATmega1281V-8AUR <sup>(4)</sup> ATmega1281V-8MU ATmega1281V-8MUR <sup>(4)</sup>	64A 64A 64M2 64M2	Industrial (-40°C to 85°C)	
16	2.7 - 5.5V	ATmega1281-16AU ATmega1281-16AUR <sup>(4)</sup> ATmega1281-16MU ATmega1281-16MUR <sup>(4)</sup>	64A 64A 64M2 64M2		

Notes: 1. This device can also be supplied in wafer form. Contact your local Atmel sales office for detailed ordering information and minimum quantities.

2. See "Speed Grades" on page 357.

3. Pb-free packaging, complies to the European Directive for Restriction of Hazardous Substances (RoHS directive). Also Halide free and fully Green.

4. Tape & Reel.

Package Type				
64A	64-lead, Thin (1.0mm) Plastic Gull Wing Quad Flat Package (TQFP)			
64M2	64-pad, 9mm × 9mm × 1.0mm Body, Quad Flat No-lead/Micro Lead Frame Package (QFN/MLF)			

## 9.4 ATmega2560

Speed [MHz] <sup>(2)</sup>	Power Supply	Ordering Code	Package <sup>(1)(3)</sup>	Operation Range	
8	1.8V - 5.5V	ATmega2560V-8AU ATmega2560V-8AUR <sup>(4)</sup> ATmega2560V-8CU ATmega2560V-8CUR <sup>(4)</sup>	100A 100A 100C1 100C1	Industrial (-40°C to 85°C)	
16	4.5V - 5.5V	ATmega2560-16AU ATmega2560-16AUR <sup>(4)</sup> ATmega2560-16CU ATmega2560-16CUR <sup>(4)</sup>	100A 100A 100C1 100C1		

Notes: 1. This device can also be supplied in wafer form. Contact your local Atmel sales office for detailed ordering information and minimum quantities.

2. See "Speed Grades" on page 357.

3. Pb-free packaging, complies to the European Directive for Restriction of Hazardous Substances (RoHS directive). Also Halide free and fully Green.

4. Tape & Reel.

	Package Type				
100A	100-lead, Thin (1.0mm) Plastic Gull Wing Quad Flat Package (TQFP)				
100C1	100-ball, Chip Ball Grid Array (CBGA)				

## 9.5 ATmega2561

Speed [MHz] <sup>(2)</sup>	Power Supply	Ordering Code	Package <sup>(1)(3)</sup>	Operation Range
8	1.8V - 5.5V	ATmega2561V-8AU ATmega2561V-8AUR <sup>(4)</sup> ATmega2561V-8MU ATmega2561V-8MUR <sup>(4)</sup>	64A 64A 64M2 64M2	Industrial
16	4.5V - 5.5V	ATmega2561-16AU ATmega2561-16AUR <sup>(4)</sup> ATmega2561-16MU ATmega2561-16MUR <sup>(4)</sup>	64A 64A 64M2 64M2	(-40°C to 85°C)

Notes: 1. This device can also be supplied in wafer form.Contact your local Atmel sales office for detailed ordering information and minimum quantities.

2. See "Speed Grades" on page 357.

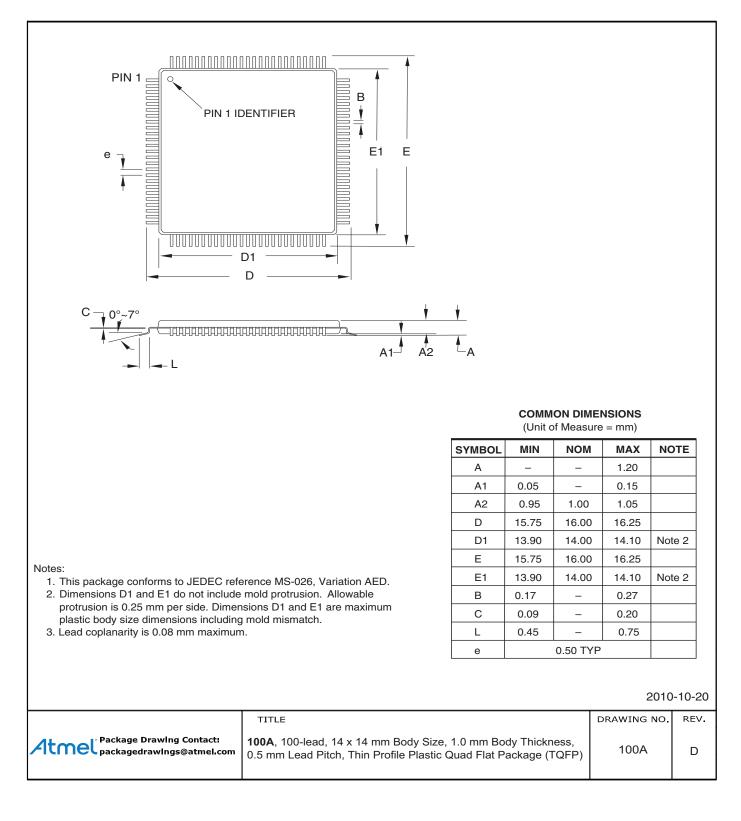
3. Pb-free packaging, complies to the European Directive for Restriction of Hazardous Substances (RoHS directive). Also Halide free and fully Green.

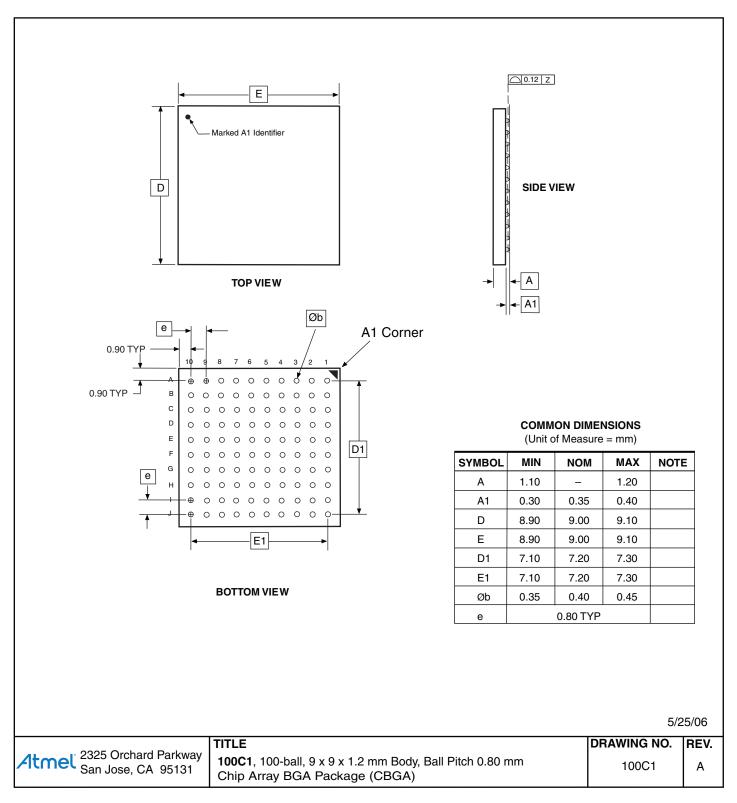
4. Tape & Reel.

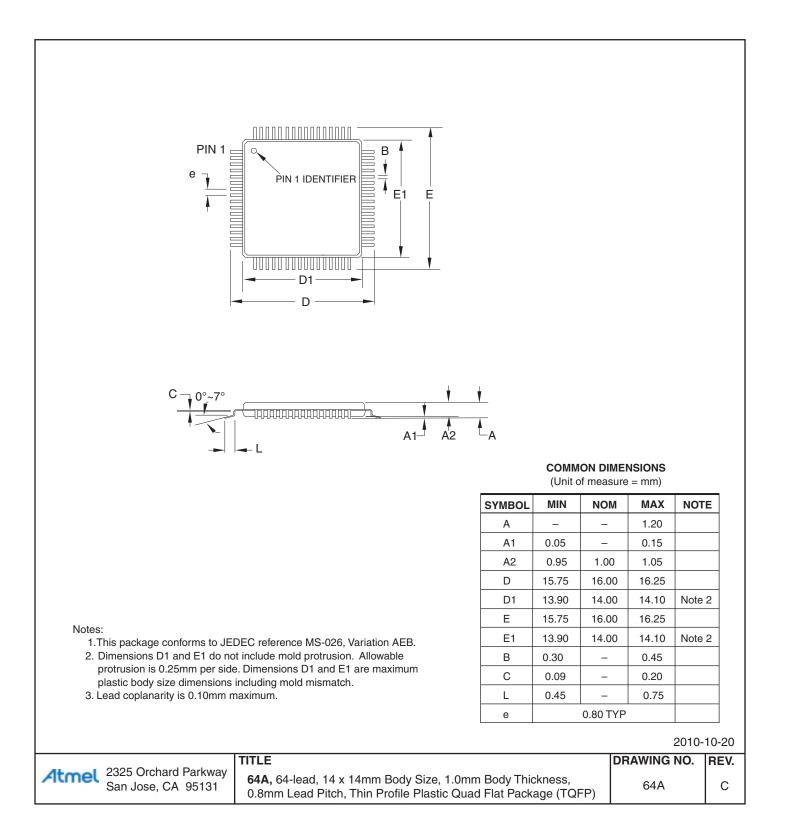
	Package Type				
64 <b>A</b>	64-lead, Thin (1.0mm) Plastic Gull Wing Quad Flat Package (TQFP)				
64M2	64-pad, 9mm $\times$ 9mm $\times$ 1.0mm Body, Quad Flat No-lead/Micro Lead Frame Package (QFN/MLF)				

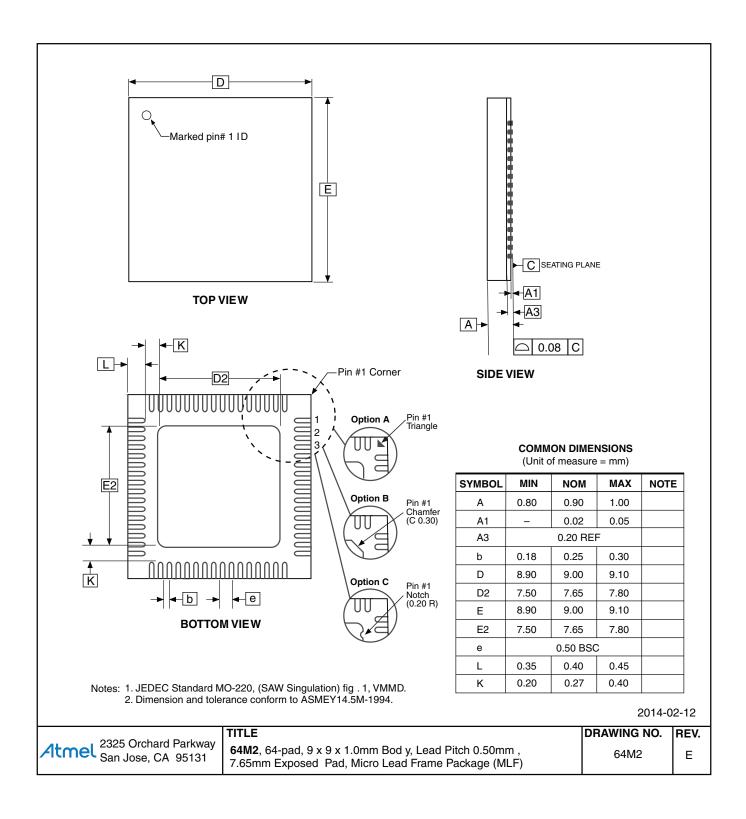
## 10. Packaging Information

## 10.1 100A









#### **Problem Fix/Workaround**

None.

#### 2. High current consumption in sleep mode

If a pending interrupt cannot wake the part up from the selected sleep mode, the current consumption will increase during sleep when executing the SLEEP instruction directly after a SEI instruction.

#### **Problem Fix/Workaround**

Before entering sleep, interrupts not used to wake the part from the sleep mode should be disabled.

### 11.5 ATmega1281 rev. B

#### High current consumption in sleep mode

#### 1. High current consumption in sleep mode

If a pending interrupt cannot wake the part up from the selected sleep mode, the current consumption will increase during sleep when executing the SLEEP instruction directly after a SEI instruction.

#### **Problem Fix/Workaround**

Before entering sleep, interrupts not used to wake the part from the sleep mode should be disabled.

### 11.6 ATmega1281 rev. A

- Inaccurate ADC conversion in differential mode with 200× gain
- High current consumption in sleep mode
- 1. Inaccurate ADC conversion in differential mode with 200× gain

With AVCC <3.6V, random conversions will be inaccurate. Typical absolute accuracy may reach 64 LSB.

### Problem Fix/Workaround

None.

#### 2. High current consumption in sleep mode

If a pending interrupt cannot wake the part up from the selected sleep mode, the current consumption will increase during sleep when executing the SLEEP instruction directly after a SEI instruction.

#### **Problem Fix/Workaround**

Before entering sleep, interrupts not used to wake the part from the sleep mode should be disabled.

### 11.7 ATmega2560 rev. F

- ADC differential input amplification by 46dB (200x) not functional
- ADC differential input amplification by 46dB (200x) not functional Problem Fix/Workaround None.

#### 11.8 ATmega2560 rev. E

No known errata.

### 11.9 ATmega2560 rev. D

Not sampled.

#### 5. IN/OUT instructions may be executed twice when Stack is in external RAM

If either an IN or an OUT instruction is executed directly before an interrupt occurs and the stack pointer is located in external ram, the instruction will be executed twice. In some cases this will cause a problem, for example:

- If reading SREG it will appear that the I-flag is cleared.

- If writing to the PIN registers, the port will toggle twice.
- If reading registers with interrupt flags, the flags will appear to be cleared.

#### **Problem Fix/Workaround**

There are two application workarounds, where selecting one of them, will be omitting the issue:

- Replace IN and OUT with LD/LDS/LDD and ST/STS/STD instructions.
- Use internal RAM for stack pointer.

#### 6. EEPROM read from application code does not work in Lock Bit Mode 3

When the Memory Lock Bits LB2 and LB1 are programmed to mode 3, EEPROM read does not work from the application code.

#### **Problem Fix/Workaround**

Do not set Lock Bit Protection Mode 3 when the application code needs to read from EEPROM.

#### 11.13 ATmega2561 rev. F

- ADC differential input amplification by 46dB (200x) not functional
- ADC differential input amplification by 46dB (200x) not functional Problem Fix/Workaround None.

#### 11.14 ATmega2561 rev. E

No known errata.

#### 11.15 ATmega2561 rev. D

Not sampled.

#### 11.16 ATmega2561 rev. C

• High current consumption in sleep mode.

#### 1. High current consumption in sleep mode

If a pending interrupt cannot wake the part up from the selected sleep mode, the current consumption will increase during sleep when executing the SLEEP instruction directly after a SEI instruction.

#### **Problem Fix/Workaround**

Before entering sleep, interrupts not used to wake the part from the sleep mode should be disabled.

### 11.17 ATmega2561 rev. B

Not sampled.

### 11.18 ATmega2561 rev. A

- Non-Read-While-Write area of flash not functional
- Part does not work under 2.4 Volts
- Incorrect ADC reading in differential mode
- Internal ADC reference has too low value
- IN/OUT instructions may be executed twice when Stack is in external RAM
- EEPROM read from application code does not work in Lock Bit Mode 3

#### 1. Non-Read-While-Write area of flash not functional

The Non-Read-While-Write area of the flash is not working as expected. The problem is related to the speed of the part when reading the flash of this area.

#### **Problem Fix/Workaround**

- Only use the first 248K of the flash.

- If boot functionality is needed, run the code in the Non-Read-While-Write area at maximum 1/4th of the maximum frequency of the device at any given voltage. This is done by writing the CLKPR register before entering the boot section of the code.

#### 2. Part does not work under 2.4 volts

The part does not execute code correctly below 2.4 volts.

#### **Problem Fix/Workaround**

Do not use the part at voltages below 2.4 volts.

#### 3. Incorrect ADC reading in differential mode

The ADC has high noise in differential mode. It can give up to 7 LSB error.

#### **Problem Fix/Workaround**

Use only the 7 MSB of the result when using the ADC in differential mode.

#### 4. Internal ADC reference has too low value

The internal ADC reference has a value lower than specified.

#### **Problem Fix/Workaround**

- Use AVCC or external reference.

- The actual value of the reference can be measured by applying a known voltage to the ADC when using the internal reference. The result when doing later conversions can then be calibrated.

#### 5. IN/OUT instructions may be executed twice when Stack is in external RAM

If either an IN or an OUT instruction is executed directly before an interrupt occurs and the stack pointer is located in external ram, the instruction will be executed twice. In some cases this will cause a problem, for example:

- If reading SREG it will appear that the I-flag is cleared.
- If writing to the PIN registers, the port will toggle twice.
- If reading registers with interrupt flags, the flags will appear to be cleared.

#### **Problem Fix/Workaround**

There are two application workarounds, where selecting one of them, will be omitting the issue:

- Replace IN and OUT with LD/LDS/LDD and ST/STS/STD instructions.

- Use internal RAM for stack pointer.

#### 6. EEPROM read from application code does not work in Lock Bit Mode 3

When the Memory Lock Bits LB2 and LB1 are programmed to mode 3, EEPROM read does not work from the application code.

#### **Problem Fix/Workaround**

Do not set Lock Bit Protection Mode 3 when the application code needs to read from EEPROM.

# Atmel Enabling Unlimited Possibilities



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