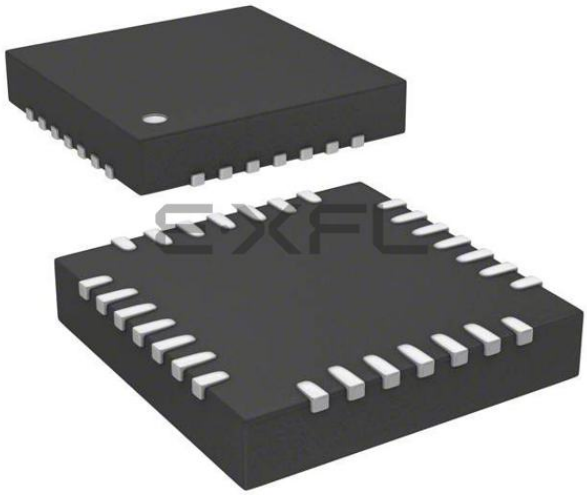

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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	STM8
Core Size	8-Bit
Speed	16MHz
Connectivity	I²C, IrDA, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, IR, POR, PWM, WDT
Number of I/O	26
Program Memory Size	8KB (8K x 8)
Program Memory Type	FLASH
EEPROM Size	256 x 8
RAM Size	1K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.6V
Data Converters	A/D 18x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	28-UFQFN
Supplier Device Package	28-UFQFPN (4x4)
Purchase URL	https://www.e-xfl.com/product-detail/stmicroelectronics/stm8l151g3u6tr

3.1 Low-power modes

The low-density STM8L151x2/3 devices support five low power modes to achieve the best compromise between low power consumption, short startup time and available wakeup sources:

- **Wait mode**: The CPU clock is stopped, but selected peripherals keep running. An internal or external interrupt or a Reset can be used to exit the microcontroller from Wait mode (WFE or WFI mode). Wait consumption: refer to *Table 20*.
- **Low power run mode**: The CPU and the selected peripherals are running. Execution is done from RAM with a low speed oscillator (LSI or LSE). Flash and data EEPROM are stopped and the voltage regulator is configured in ultra-low-power mode. The microcontroller enters Low power run mode by software and can exit from this mode by software or by a reset.
  All interrupts must be masked. They cannot be used to exit the microcontroller from this mode. Low power run mode consumption: refer to *Table 21*.
- **Low power wait mode:** This mode is entered when executing a Wait for event in Low power run mode. It is similar to Low power run mode except that the CPU clock is stopped. The wakeup from this mode is triggered by a Reset or by an internal or external event (peripheral event generated by the timers, serial interfaces, DMA controller (DMA1), comparators and I/O ports). When the wakeup is triggered by an event, the system goes back to Low power run mode.
  All interrupts must be masked. They cannot be used to exit the microcontroller from this mode. Low power wait mode consumption: refer to *Table 22*.
- **Active-halt mode**: CPU and peripheral clocks are stopped, except RTC. The wakeup can be triggered by RTC interrupts, external interrupts or reset. Active-halt consumption: refer to *Table 23* and *Table 24*.
- **Halt mode**: CPU and peripheral clocks are stopped, the device remains powered on. The RAM content is preserved. The wakeup is triggered by an external interrupt or reset. A few peripherals have also a wakeup from Halt capability. Switching off the internal reference voltage reduces power consumption. Through software configuration it is also possible to wake up the device without waiting for the internal reference voltage wakeup time to have a fast wakeup time of 5 µs. Halt consumption: refer to *Table 25*.

3.2 Central processing unit STM8

3.2.1 Advanced STM8 Core

The 8-bit STM8 core is designed for code efficiency and performance with an Harvard architecture and a 3-stage pipeline.

It contains 6 internal registers which are directly addressable in each execution context, 20 addressing modes including indexed indirect and relative addressing, and 80 instructions.

Architecture and registers

- Harvard architecture
- 3-stage pipeline
- 32-bit wide program memory bus - single cycle fetching most instructions
- X and Y 16-bit index registers - enabling indexed addressing modes with or without offset and read-modify-write type data manipulations
- 8-bit accumulator
- 24-bit program counter - 16 Mbyte linear memory space
- 16-bit stack pointer - access to a 64 Kbyte level stack
- 8-bit condition code register - 7 condition flags for the result of the last instruction

Addressing

- 20 addressing modes
- Indexed indirect addressing mode for lookup tables located anywhere in the address space
- Stack pointer relative addressing mode for local variables and parameter passing

Instruction set

- 80 instructions with 2-byte average instruction size
- Standard data movement and logic/arithmetic functions
- 8-bit by 8-bit multiplication
- 16-bit by 8-bit and 16-bit by 16-bit division
- Bit manipulation
- Data transfer between stack and accumulator (push/pop) with direct stack access
- Data transfer using the X and Y registers or direct memory-to-memory transfers

3.2.2 Interrupt controller

The low-density STM8L151x2/3 feature a nested vectored interrupt controller:

- Nested interrupts with 3 software priority levels
- 32 interrupt vectors with hardware priority
- Up to 40 external interrupt sources on 11 vectors
- Trap and reset interrupts

3.15 Communication interfaces

3.15.1 SPI

The serial peripheral interface (SPI1) provides half/ full duplex synchronous serial communication with external devices.

- Maximum speed: 8 Mbit/s (f_{SYSCLK}/2) both for master and slave
- Full duplex synchronous transfers
- Simplex synchronous transfers on 2 lines with a possible bidirectional data line
- Master or slave operation - selectable by hardware or software
- Hardware CRC calculation
- Slave/master selection input pin

Note: SPI1 can be served by the DMA1 Controller.

3.15.2 I²C

The I^2C bus interface (I^2C1) provides multi-master capability, and controls all I²C bus-specific sequencing, protocol, arbitration and timing.

- Master, slave and multi-master capability
- Standard mode up to 100 kHz and fast speed modes up to 400 kHz.
- 7-bit and 10-bit addressing modes.
- SMBus 2.0 and PMBus support
- Hardware CRC calculation

Note: I^2C1 can be served by the DMA1 Controller.

3.15.3 USART

The USART interface (USART1) allows full duplex, asynchronous communications with external devices requiring an industry standard NRZ asynchronous serial data format. It offers a very wide range of baud rates.

- 1 Mbit/s full duplex SCI
- SPI1 emulation
- High precision baud rate generator
- SmartCard emulation
- IrDA SIR encoder decoder
- Single wire half duplex mode

Note: USART1 can be served by the DMA1 Controller.

3.16 Infrared (IR) interface

The low-density STM8L151x2/3 devices contain an infrared interface which can be used with an IR LED for remote control functions. Two timer output compare channels are used to generate the infrared remote control signals.

Table 8. General hardware register map (continued)

Address	Block	Register label	Register name	Reset status
0x00 5140	RTC	RTC_TR1	RTC time register 1	0x00
0x00 5141		RTC_TR2	RTC time register 2	0x00
0x00 5142		RTC_TR3	RTC time register 3	0x00
0x00 5143		Reserved area (1 byte)		
0x00 5144		RTC_DR1	RTC date register 1	0x01
0x00 5145		RTC_DR2	RTC date register 2	0x21
0x00 5146		RTC_DR3	RTC date register 3	0x00
0x00 5147		Reserved area (1 byte)		
0x00 5148		RTC_CR1	RTC control register 1	0x00(2)
0x00 5149		RTC_CR2	RTC control register 2	0x00(2)
0x00 514A		RTC_CR3	RTC control register 3	0x00(2)
0x00 514B		Reserved area (1 byte)		
0x00 514C		RTC_ISR1	RTC initialization and status register 1	0x01
0x00 514D		RTC_ISR2	RTC initialization and Status register 2	0x00
0x00 514E 0x00 514F		Reserved area (2 byte)		
0x00 5150		RTC_SPRERH	RTC synchronous prescaler register high	0x00(2)
0x00 5151		RTC_SPRERL	RTC synchronous prescaler register low	0xFF(2)
0x00 5152		RTC_APRER	RTC asynchronous prescaler register	0x7F(2)
0x00 5153		Reserved area (1 byte)		
0x00 5154		RTC_WUTRH	RTC wakeup timer register high	0xFF(2)
0x00 5155		RTC_WUTRL	RTC wakeup timer register low	0xFF(2)
0x00 5156		Reserved area (1 byte)		
0x00 5157		RTC_SSRL	RTC subsecond register low	0x00
0x00 5158		RTC_SSRH	RTC subsecond register high	0x00
0x00 5159		RTC_WPR	RTC write protection register	0x00
0x00 5158		RTC_SSRH	RTC subsecond register high	0x00
0x00 5159		RTC_WPR	RTC write protection register	0x00
0x00 515A		RTC_SHIFTRH	RTC shift register high	0x00
0x00 515B		RTC_SHIFTRL	RTC shift register low	0x00
0x00 515C		RTC_ALRMAR1	RTC alarm A register 1	0x00(2)
0x00 515D		RTC_ALRMAR2	RTC alarm A register 2	0x00(2)
0x00 515E		RTC_ALRMAR3	RTC alarm A register 3	0x00(2)
0x00 515F		RTC_ALRMAR4	RTC alarm A register 4	0x00(2)

Table 9. CPU/SWIM/debug module/interrupt controller registers (continued)

Address	Block	Register Label	Register Name	Reset Status
0x00 7F90	DM	DM_BK1RE	DM breakpoint 1 register extended byte	0xFF
0x00 7F91		DM_BK1RH	DM breakpoint 1 register high byte	0xFF
0x00 7F92		DM_BK1RL	DM breakpoint 1 register low byte	0xFF
0x00 7F93		DM_BK2RE	DM breakpoint 2 register extended byte	0xFF
0x00 7F94		DM_BK2RH	DM breakpoint 2 register high byte	0xFF
0x00 7F95		DM_BK2RL	DM breakpoint 2 register low byte	0xFF
0x00 7F96		DM_CR1	DM Debug module control register 1	0x00
0x00 7F97		DM_CR2	DM Debug module control register 2	0x00
0x00 7F98		DM_CSR1	DM Debug module control/status register 1	0x10
0x00 7F99		DM_CSR2	DM Debug module control/status register 2	0x00
0x00 7F9A		DM_ENFCTR	DM enable function register	0xFF
0x00 7F9B to 0x00 7F9F	Reserved area (5 byte)			

1. Accessible by debug module only

7 Option bytes

Option bytes contain configurations for device hardware features as well as the memory protection of the device. They are stored in a dedicated memory block.

All option bytes can be modified in ICP mode (with SWIM) by accessing the EEPROM address. See *Table 11* for details on option byte addresses.

The option bytes can also be modified ‘on the fly’ by the application in IAP mode, except for the ROP and UBC values which can only be taken into account when they are modified in ICP mode (with the SWIM).

Refer to the STM8L15x Flash programming manual (PM0054) and STM8 SWIM and Debug Manual (UM0470) for information on SWIM programming procedures.

Table 11. Option byte addresses

Addr.	Option name	Option byte No.	Option bits								Factory default setting
			7	6	5	4	3	2	1	0	
0x00 4800	Read-out protection (ROP)	OPT0	ROP[7:0]								0xAA
0x00 4802	UBC (User Boot code size)	OPT1	UBC[7:0]								0x00
0x00 4807	Reserved										0x00
0x00 4808	Independent watchdog option	OPT3 [3:0]	Reserved				WWDG_HALT	WWDG_HW	IWDG_HALT	IWDG_HW	0x00
0x00 4809	Number of stabilization clock cycles for HSE and LSE oscillators	OPT4	Reserved				LSECNT[1:0]		HSECNT[1:0]		0x00
0x00 480A	Brownout reset (BOR)	OPT5 [3:0]	Reserved				BOR_TH			BOR_ON	0x01
0x00 480B	Bootloader option bytes (OPTBL)	OPTBL [15:0]	OPTBL[15:0]								0x00
0x00 480C											0x00

8 Unique ID

STM8 devices feature a 96-bit unique device identifier which provides a reference number that is unique for any device and in any context. The 96 bits of the identifier can never be altered by the user.

The unique device identifier can be read in single bytes and may then be concatenated using a custom algorithm.

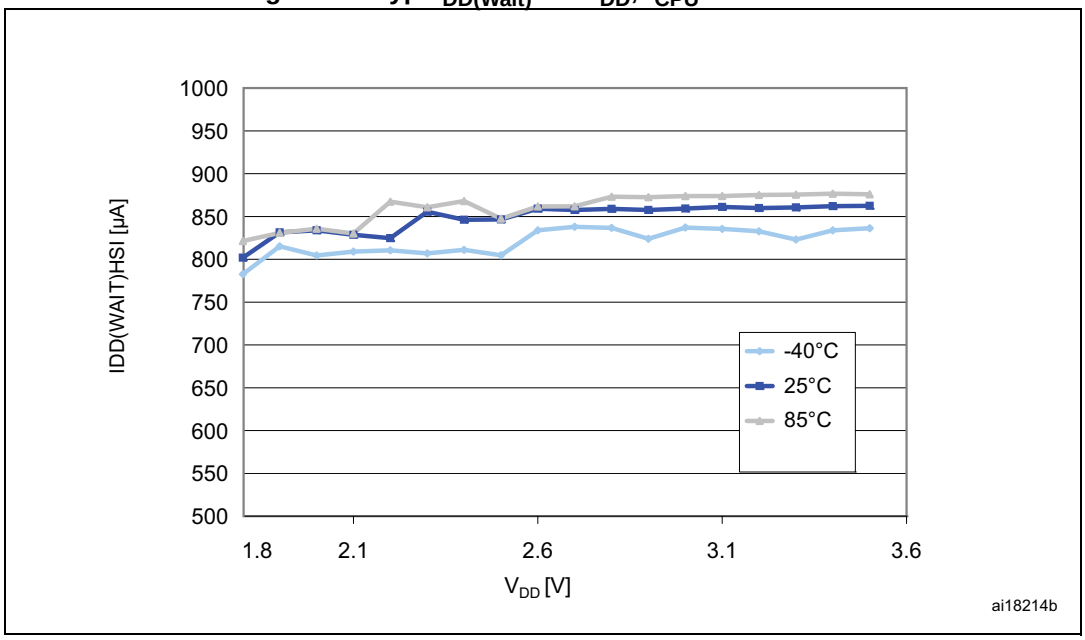
The unique device identifier is ideally suited:

- For use as serial numbers
- For use as security keys to increase the code security in the program memory while using and combining this unique ID with software cryptographic primitives and protocols before programming the internal memory.
- To activate secure boot processes

Table 13. Unique ID registers (96 bits)

Address	Content description	Unique ID bits							
		7	6	5	4	3	2	1	0
0x4926	X co-ordinate on the wafer	U_ID[7:0]							
0x4927		U_ID[15:8]							
0x4928	Y co-ordinate on the wafer	U_ID[23:16]							
0x4929		U_ID[31:24]							
0x492A	Wafer number	U_ID[39:32]							
0x492B	Lot number	U_ID[47:40]							
0x492C		U_ID[55:48]							
0x492D		U_ID[63:56]							
0x492E		U_ID[71:64]							
0x492F		U_ID[79:72]							
0x4930		U_ID[87:80]							
0x4931		U_ID[95:88]							

Figure 13. Typ. $I_{DD(Wait)}$ vs. V_{DD}, f_{CPU} = 16 MHz [1)]



1. Typical current consumption measured with code executed from Flash memory.

In the following table, data is based on characterization results, unless otherwise specified.

Table 22. Total current consumption in Low power wait mode at V_{DD} = 1.65 V to 3.6 V

Symbol	Parameter	Conditions(1)(2)			Typ	Max	Unit
$I_{DD(LPW)}$	Supply current in Low power wait mode	LSI RC osc. (at 38 kHz)	all peripherals OFF	T_A = -40 °C to 25 °C	3	3.3	µA
				T_A = 55 °C	3.3	3.6	
				T_A = 85 °C	4.4	5	
				T_A = 105 °C	6.7	8	
				T_A = 125 °C	11	14	
			with TIM2 active(3)	T_A = -40 °C to 25 °C	3.4	3.7	
				T_A = 55 °C	3.7	4	
				T_A = 85 °C	4.8	5.4	
				T_A = 105 °C	7	8.3	
				T_A = 125 °C	11.3	14.5	
		LSE external clock(4) (32.768 kHz)	all peripherals OFF	T_A = -40 °C to 25 °C	2.35	2.7	
				T_A = 55 °C	2.42	2.82	
				T_A = 85 °C	3.10	3.71	
				T_A = 105 °C	4.36	5.7	
				T_A = 125 °C	7.20	11	
			with TIM2 active (3)	T_A = -40 °C to 25 °C	2.46	2.75	
				T_A = 55 °C	2.50	2.81	
				T_A = 85 °C	3.16	3.82	
				T_A = 105 °C	4.51	5.9	
				T_A = 125 °C	7.28	11	

1. No floating I/Os.
2. T_A > 85 °C is valid only for devices with suffix 3 temperature range.
3. Timer 2 clock enabled and counter is running.
4. Oscillator bypassed (LSEBYP = 1 in CLK_ECKCR). When configured for external crystal, the LSE consumption ($I_{DD\ LSE}$) must be added. Refer to *Table 31*.

In the following table, data is based on characterization results, unless otherwise specified.

Table 25. Total current consumption and timing in Halt mode at V_{DD} = 1.65 to 3.6 V

Symbol	Parameter	Condition(1)(2)	Typ	Max	Unit
$I_{DD(Halt)}$	Supply current in Halt mode (Ultra-low-power ULP bit =1 in the PWR_CSR2 register)	T_A = -40 °C to 25 °C	350	1400(3)	nA
		T_A = 55 °C	580	2000	
		T_A = 85 °C	1160	2800(3)	
		T_A = 105 °C	2560	6700(3)	
		T_A = 125 °C	4.4	13(3)	µA
$I_{DD(WUHalt)}$	Supply current during wakeup time from Halt mode (using HSI)	-	2.4	-	mA
$t_{WU\_HSI(Halt)}$(4)(5)	Wakeup time from Halt to Run mode (using HSI)	-	4.7	7	µs
$t_{WU\_LSI(Halt)}$ (4)(5)	Wakeup time from Halt mode to Run mode (using LSI)	-	150	-	µs

1. T_A = -40 to 125 °C, no floating I/O, unless otherwise specified.
2. T_A > 85 °C is valid only for devices with suffix 3 temperature range.
3. Tested in production.
4. ULP=0 or ULP=1 and FWU=1 in the PWR_CSR2 register.
5. Wakeup time until start of interrupt vector fetch.
The first word of interrupt routine is fetched 4 CPU cycles after t_{WU}.

9.3.8 Communication interfaces

SPI1 - Serial peripheral interface

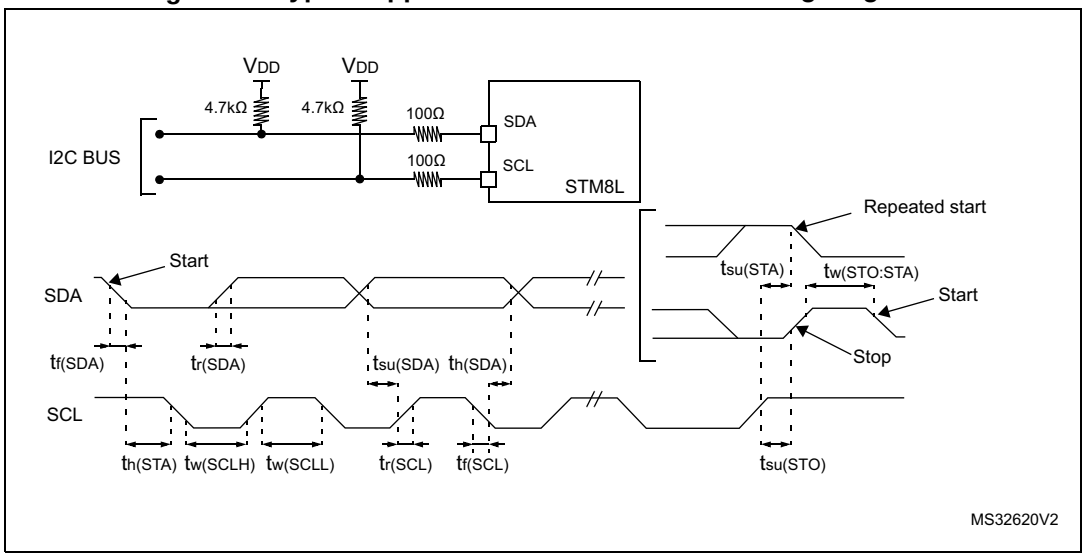
Unless otherwise specified, the parameters given in *Table 42* are derived from tests performed under ambient temperature, f_{SYSCLK} frequency and V_{DD} supply voltage conditions summarized in *Section 9.3.1*. Refer to I/O port characteristics for more details on the input/output alternate function characteristics (NSS, SCK, MOSI, MISO).

Table 42. SPI1 characteristics

Symbol	Parameter	Conditions(1)	Min	Max	Unit
f_{SCK} $1/t_{c(SCK)}$	SPI1 clock frequency	Master mode	0	8	MHz
		Slave mode	0	8	
$t_{r(SCK)}$ $t_{f(SCK)}$	SPI1 clock rise and fall time	Capacitive load: C = 30 pF	-	30	ns
$t_{su(NSS)}$(2)	NSS setup time	Slave mode	4 x $1/f_{SYSCLK}$	-	
$t_{h(NSS)}$(2)	NSS hold time	Slave mode	80	-	
$t_{w(SCKH)}$(2) $t_{w(SCKL)}$(2)	SCK high and low time	Master mode, f_{MASTER} = 8 MHz, f_{SCK}= 4 MHz	105	145	
$t_{su(MI)}$(2) $t_{su(SI)}$(2)	Data input setup time	Master mode	30	-	
		Slave mode	3	-	
$t_{h(MI)}$(2) $t_{h(SI)}$(2)	Data input hold time	Master mode	15	-	
		Slave mode	0	-	
$t_{a(SO)}$(2)(3)	Data output access time	Slave mode	-	3x $1/f_{SYSCLK}$	
$t_{dis(SO)}$(2)(4)	Data output disable time	Slave mode	30	-	
$t_{v(SO)}$(2)	Data output valid time	Slave mode (after enable edge)	-	60	
$t_{v(MO)}$(2)	Data output valid time	Master mode (after enable edge)	-	20	
$t_{h(SO)}$(2)	Data output hold time	Slave mode (after enable edge)	15	-	
$t_{h(MO)}$(2)		Master mode (after enable edge)	1	-	

1. Parameters are given by selecting 10 MHz I/O output frequency.
2. Values based on design simulation and/or characterization results, and not tested in production.
3. Min time is for the minimum time to drive the output and max time is for the maximum time to validate the data.
4. Min time is for the minimum time to invalidate the output and max time is for the maximum time to put the data in Hi-Z.

Figure 36. Typical application with I²C bus and timing diagram [1)]



1. Measurement points are done at CMOS levels: 0.3 x V_{DD} and 0.7 x V_{DD}

9.3.9 Embedded reference voltage

In the following table, data is based on characterization results, not tested in production, unless otherwise specified.

Table 44. Reference voltage characteristics

Symbol	Parameter	Conditions	Min	Typ	Max.	Unit
I_{REFINT}	Internal reference voltage consumption	-	-	1.4	-	µA
$T_{S\_VREFINT}$(1)(2)	ADC1 sampling time when reading the internal reference voltage	-	-	5	10	µs
I_{BUF}(2)	Internal reference voltage buffer consumption (used for ADC1)	-	-	13.5	25	µA
$V_{REFINT\ out}$	Reference voltage output	-	1.202(3)	1.224	1.242(3)	V
I_{LPBUF}(2)	Internal reference voltage low power buffer consumption (used for comparators or output)	-	-	730	1200	nA
I_{REFOUT}(2)	Buffer output current(4)	-	-	-	1	µA
C_{REFOUT}	Reference voltage output load	-	-	-	50	pF
$t_{VREFINT}$	Internal reference voltage startup time	-	-	2	3	ms
t_{BUFEN}(2)	Internal reference voltage buffer startup time once enabled (1)	-	-	-	10	µs
$ACC_{VREFINT}$	Accuracy of V_{REFINT} stored in the VREFINT_Factory_CONV byte(5)	-	-	-	± 5	mV
$STAB_{VREFINT}$	Stability of V_{REFINT} over temperature	-40 °C ≤ T_A ≤ 125 °C	-	20	50	ppm/°C
	Stability of V_{REFINT} over temperature	0 °C ≤ T_A ≤ 50 °C	-	-	20	ppm/°C
$STAB_{VREFINT}$	Stability of V_{REFINT} after 1000 hours	-	-	-	TBD	ppm

1. Defined when ADC1 output reaches its final value ±1/2LSB
2. Data guaranteed by Design. Not tested in production.
3. Tested in production at V_{DD} = 3 V ±10 mV.
4. To guaranty less than 1% V_{REFOUT} deviation.
5. Measured at V_{DD} = 3 V ±10 mV. This value takes into account V_{DD} accuracy and ADC1 conversion accuracy.

In the following table, data is guaranteed by design, not tested in production.

Table 47. Comparator 2 characteristics

Symbol	Parameter	Conditions	Min	Typ	Max(1)	Unit
V_{DDA}	Analog supply voltage	-	1.65	-	3.6	V
T_A	Temperature range	-	-40	-	125	°C
V_{IN}	Comparator 2 input voltage range	-	0	-	V_{DDA}	V
t_{START}	Comparator startup time	Fast mode	-	15	20	µs
		Slow mode	-	20	25	
$t_{d\ slow}$	Propagation delay in slow mode(2)	1.65 V ≤ V_{DDA} ≤ 2.7 V	-	1.8	3.5	
		2.7 V ≤ V_{DDA} ≤ 3.6 V	-	2.5	6	
$t_{d\ fast}$	Propagation delay in fast mode(2)	1.65 V ≤ V_{DDA} ≤ 2.7 V	-	0.8	2	
		2.7 V ≤ V_{DDA} ≤ 3.6 V	-	1.2	4	
V_{offset}	Comparator offset error	-	-	±4	±20	mV
I_{COMP2}	Current consumption(3)	Fast mode	-	3.5	5	µA
		Slow mode	-	0.5	2	

1. Based on characterization, not tested in production.
2. The delay is characterized for 100 mV input step with 10 mV overdrive on the inverting input, the non-inverting input set to the reference.
3. Comparator consumption only. Internal reference voltage not included.

Figure 37. ADC1 accuracy characteristics

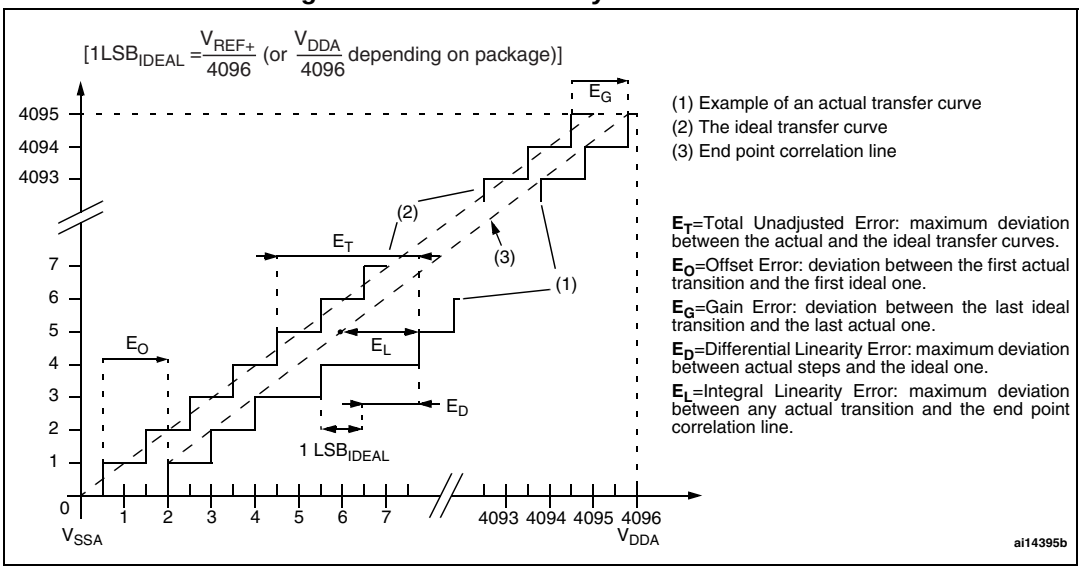
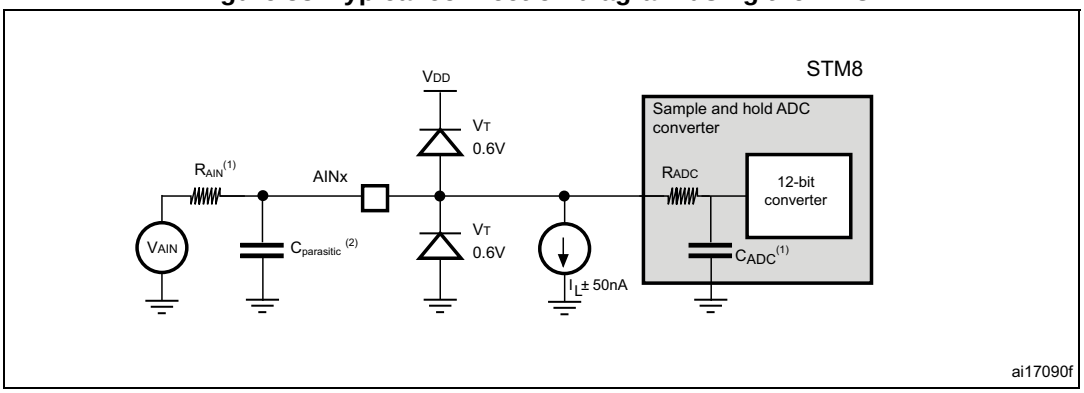


Figure 38. Typical connection diagram using the ADC1



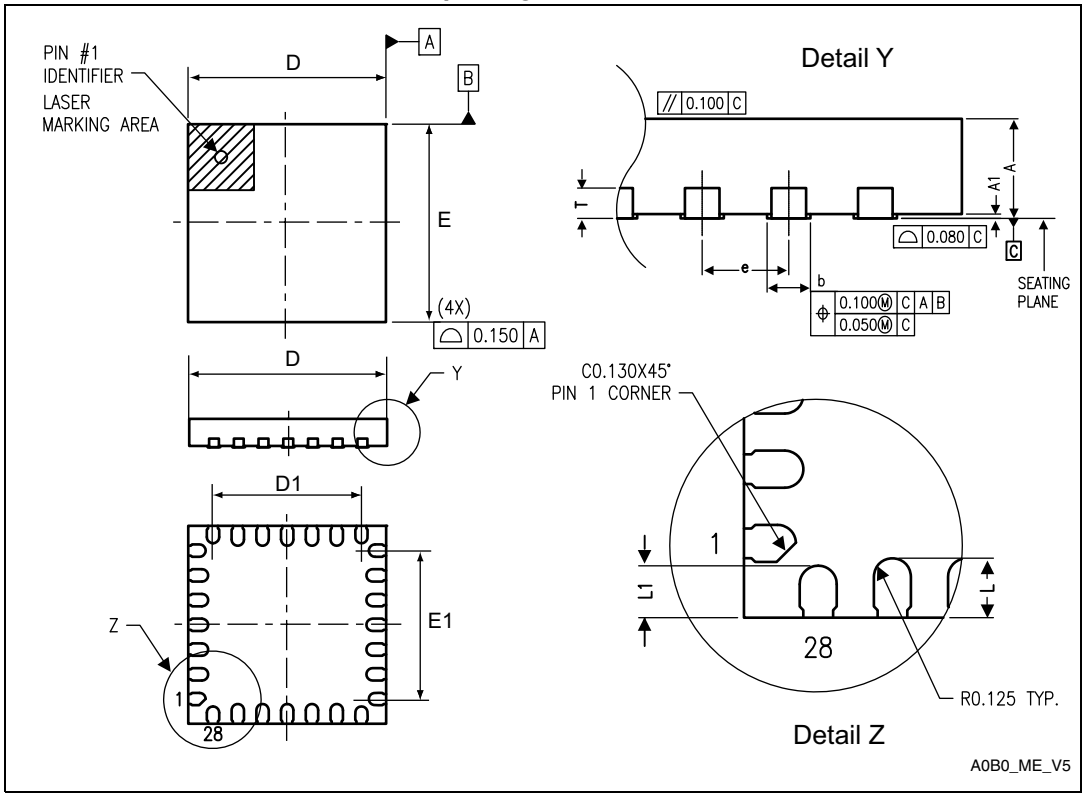
1. Refer to *Table 48* for the values of R_{AIN} and C_{ADC1}.
2. $C_{parasitic}$ represents the capacitance of the PCB (dependent on soldering and PCB layout quality) plus the pad capacitance (roughly 7 pF). A high $C_{parasitic}$ value will downgrade conversion accuracy. To remedy this, f_{ADC1} should be reduced.

General PCB design guidelines

Power supply decoupling should be performed as shown in *Figure 39* or *Figure 40*, depending on whether V_{REF+} is connected to V_{DDA} or not. Good quality ceramic 10 nF capacitors should be used. They should be placed as close as possible to the chip.

10.4 UFQFPN28 package information

Figure 48. UFQFPN28 - 28-lead, 7x7 mm, 0.5 mm pitch, ultra thin fine pitch quad flat package outline



1. Drawing is not to scale.

Table 59. UFQFPN28 - 28-lead, 7x7 mm, 0.5 mm pitch, ultra thin fine pitch quad flat package mechanical data(1)

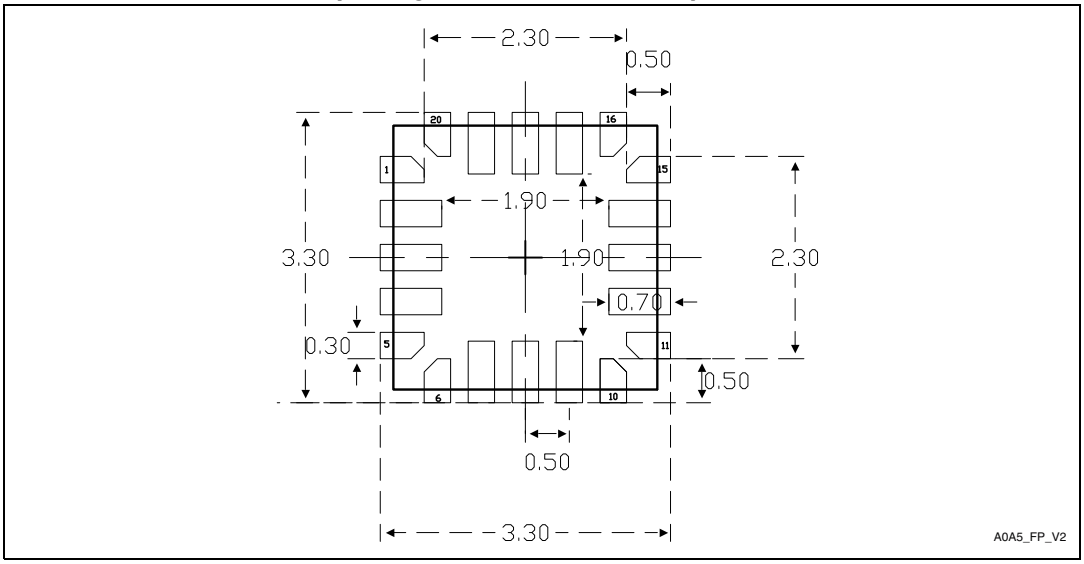
Symbol	millimeters			inches		
	Min	Typ	Max	Min	Typ	Max
A	0.500	0.550	0.600	0.0197	0.0217	0.0236
A1	-	0.000	0.050	-	0.0000	0.0020
D	3.900	4.000	4.100	0.1535	0.1575	0.1614
D1	2.900	3.000	3.100	0.1142	0.1181	0.1220
E	3.900	4.000	4.100	0.1535	0.1575	0.1614
E1	2.900	3.000	3.100	0.1142	0.1181	0.1220
L	0.300	0.400	0.500	0.0118	0.0157	0.0197
L1	0.250	0.350	0.450	0.0098	0.0138	0.0177
T	-	0.152	-	-	0.0060	-
b	0.200	0.250	0.300	0.0079	0.0098	0.0118
e	-	0.500	-	-	0.0197	-

Table 60. UFQFPN20 - 20-lead, 3x3 mm, 0.5 mm pitch, ultra thin fine pitch quad flat package mechanical data

Symbol	millimeters			inches[1]		
	Min	Typ	Max	Min	Typ	Max
A	0.500	0.550	0.600	0.0197	0.0217	0.0236
A1	0.000	0.020	0.050	0.0000	0.0008	0.0020
A3	-	0.152	-	-	0.060	-
D	-	3.000	-	-	0.1181	-
E	-	3.000	-	-	0.1181	-
L1	0.500	0.550	0.600	0.0197	0.0217	0.0236
L2	0.300	0.350	0.400	0.0118	0.0138	0.0157
L3	-	0.375	-		0.0148	
L4	-	0.200	-		0.0079	
L5	-	0.150	-		0.0059	
b	0.180	0.250	0.300	0.0071	0.0098	0.0118
e	-	0.500	-	-	0.0197	-
ddd	-	-	0.050	-	-	0.0020

1. Values in inches are converted from mm and rounded to 4 decimal digits.

Figure 52. UFQFPN20 - 20-lead, 3x3 mm, 0.5 mm pitch, ultra thin fine pitch quad flat package recommended footprint

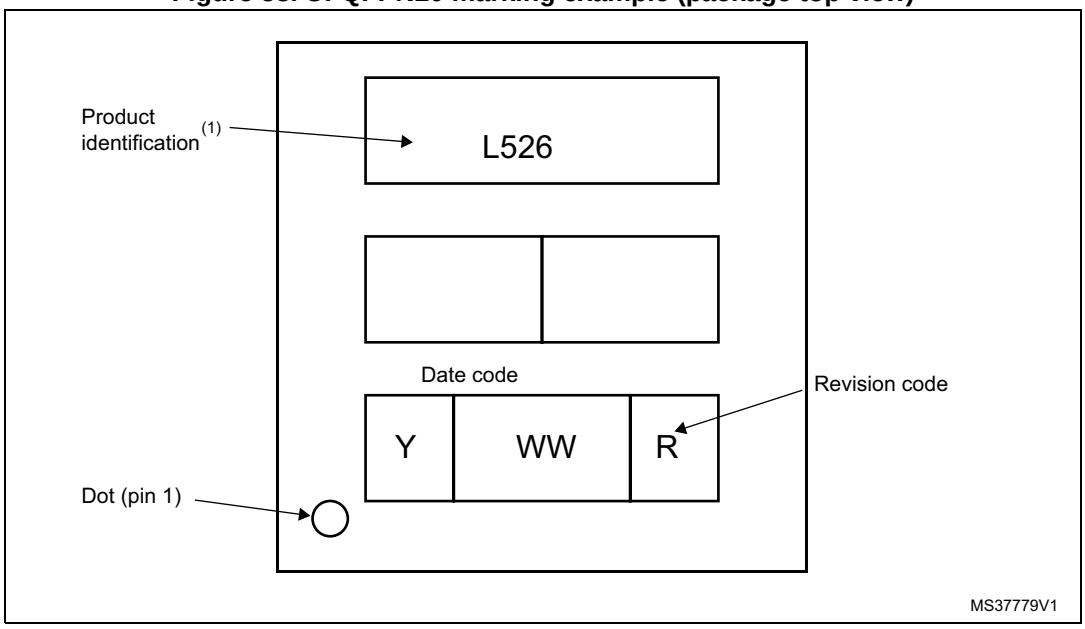


1. Dimensions are expressed in millimeters.

Device marking

The following figure gives an example of topside marking orientation versus pin 1 identifier location.

Figure 53. UFQFPN20 marking example (package top view)



1. Parts marked as “ES”, “E” or accompanied by an Engineering Sample notification letter, are not yet qualified and therefore not yet ready to be used in production and any consequences deriving from such usage will not be at ST charge. In no event, ST will be liable for any customer usage of these engineering samples in production. ST Quality has to be contacted prior to any decision to use these Engineering Samples to run qualification activity.

11 Part numbering

For a list of available options (memory, package, and so on) or for further information on any aspect of this device, please contact your nearest ST sales office.

Table 63. Low-density STM8L151x2/3 ordering information scheme

Example: STM8 L 151 K 3 U 3 TR

Device family

STM8 = 8-bit microcontroller

Product type

L = Low power

Sub-family

151 = ultra-low power

Pin count

C = 48 pins
K = 32 pins
G = 28 pins
F = 20 pins

Program memory size

3 = 8 Kbyte of Flash memory
2 = 4 Kbyte of Flash memory

Package

U = UFQFPN
T = LQFP
P = TSSOP

Temperature range

3 = –40 to 125 °C
6 = –40 to 85 °C

Packing

No character = tray or tube
TR = tape and reel