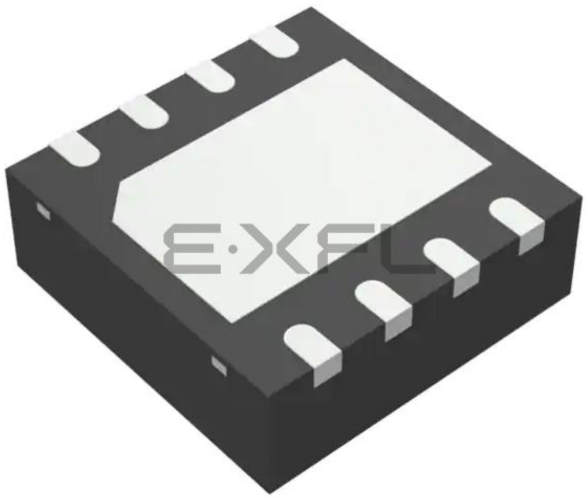


What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Obsolete
Core Processor	PIC
Core Size	8-Bit
Speed	20MHz
Connectivity	-
Peripherals	Brown-out Detect/Reset, POR, WDT
Number of I/O	5
Program Memory Size	1.75KB (1K x 14)
Program Memory Type	FLASH
EEPROM Size	128 x 8
RAM Size	64 x 8
Voltage - Supply (Vcc/Vdd)	2V ~ 5.5V
Data Converters	-
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	8-VDFN Exposed Pad
Supplier Device Package	8-DFN-S (6x5)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic12f635t-i-mf

Note the following details of the code protection feature on Microchip devices:

- Microchip products meet the specification contained in their particular Microchip Data Sheet.
- Microchip believes that its family of products is one of the most secure families of its kind on the market today, when used in the intended manner and under normal conditions.
- There are dishonest and possibly illegal methods used to breach the code protection feature. All of these methods, to our knowledge, require using the Microchip products in a manner outside the operating specifications contained in Microchip's Data Sheets. Most likely, the person doing so is engaged in theft of intellectual property.
- Microchip is willing to work with the customer who is concerned about the integrity of their code.
- Neither Microchip nor any other semiconductor manufacturer can guarantee the security of their code. Code protection does not mean that we are guaranteeing the product as "unbreakable."

Code protection is constantly evolving. We at Microchip are committed to continuously improvi

TABLE 2-2: PIC12F635 SPECIAL FUNCTION REGISTERS SUMMARY BANK 1

Addr	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR/BOR/ WUR	Page
Bank 1											
80h	INDF	Addressing this location uses contents of FSR to address data memory (not a physical register)								xxxx xxxx	32,137
81h	OPTION_REG	$\overline{\text{RAPU}}$	INTEDG	T0CS	T0SE	PSA	PS2	PS1	PS0	1111 1111	63,137
82h	PCL	Program Counter's (PC) Least Significant Byte								0000 0000	32,137
83h	STATUS	IRP	RP1	RP0	$\overline{\text{TO}}$	$\overline{\text{PD}}$	Z	DC	C	0001 1xxx	26,137
84h	FSR	Indirect Data Memory Address Pointer								xxxx xxxx	32,137
85h	TRISIO	—	—	TRISIO5	TRISIO4	TRISIO3	TRISIO2	TRISIO1	TRISIO0	--11 1111	--11 1111
86h	—	Unimplemented								—	—
87h	—	Unimplemented								—	—
88h	—	Unimplemented								—	—
89h	—	Unimplemented								—	—
8Ah	PCLATH	—	—	—	Write Buffer for upper 5 bits of Program Counter					---0 0000	32,137
8Bh	INTCON	GIE	PEIE	T0IE	INTE	RAIE	T0IF	INTF	RAIF(3)	0000 000x	28,137
8Ch	PIE1	EEIE	LVDIE	CRIE	—	C1IE	OSFIE	—	TMR1IE	000- 00-0	29,137
8Dh	—	Unimplemented								—	—
8Eh	PCON	—	—	ULPWUE	SBOREN	$\overline{\text{WUR}}$	—	$\overline{\text{POR}}$	$\overline{\text{BOR}}$	--01 q-qq	31,137
8Fh	OSCCON	—	IRCF2	IRCF1	IRCF0	OSTS	HTS	LTS	SCS	-110 q000	36,137
90h	OSCTUNE	—	—	—	TUN4	TUN3	TUN2	TUN1	TUN0	---0 0000	40,137
91h	—	Unimplemented								—	—
92h	—	Unimplemented								—	—
93h	—	Unimplemented								—	—
94h	LVDCON	—	—	IRVST	LVDEN	—	LVDL2	LVDL1	LVDL0	--00 -000	--00 -000
95h	WPUDA(2)	—	—	WPUDA5	WPUDA4	—	WPUDA2	WPUDA1	WPUDA0	--11 -111	--11 -111
96h	IOCA	—	—	IOCA5	IOCA4	IOCA3	IOCA2	IOCA1	IOCA0	--00 0000	--00 0000
97h	WDA(2)	—	—	WDA5	WDA4	—	WDA2	WDA1	WDA0	--11 -111	--11 -111
9Bh	—	Unimplemented								—	—
99h	VRCON	VREN	—	VRR	—	VR3	VR2	VR1	VR0	0-0- 0000	0-0- 0000
9Ah	EEDAT	EEDAT7	EEDAT6	EEDAT5	EEDAT4	EEDAT3	EEDAT2	EEDAT1	EEDAT0	0000 0000	0000 0000
9Bh	EEADR	EEADR7	EEADR6	EEADR5	EEADR4	EEADR3	EEADR2	EEADR1	EEADR0	0000 0000	0000 0000
9Ch	EECON1	—	—	—	—	WRERR	WREN	WR	RD	---- x000	---- q000
9Dh	EECON2	EEPROM Control Register 2 (not a physical register)								---- ----	---- ----
9Eh	—	Unimplemented								—	—
9Fh	—	Unimplemented								—	—

Legend: – = Unimplemented locations read as '0', u = unchanged, x = unknown, q = value depends on condition, shaded = unimplemented

Note 1: Other (non Power-up) Resets include $\overline{\text{MCLR}}$ Reset and Watchdog Timer Reset during normal operation.

2: GP3 pull-up is enabled when pin is configured as $\overline{\text{MCLR}}$ in the Configuration Word register.

3: $\overline{\text{MCLR}}$ and WDT Reset do not affect the previous value data latch. The RAIF bit will be cleared upon Reset, but will set again if the mismatch exists.

4.3.6 RC4/C2OUT

Figure 4-9 shows the diagram for this pin. The RC4 pin is configurable to function as one of the following:

- a general purpose I/O
- a digital output from the comparator

FIGURE 4-9: BLOCK DIAGRAM OF RC4

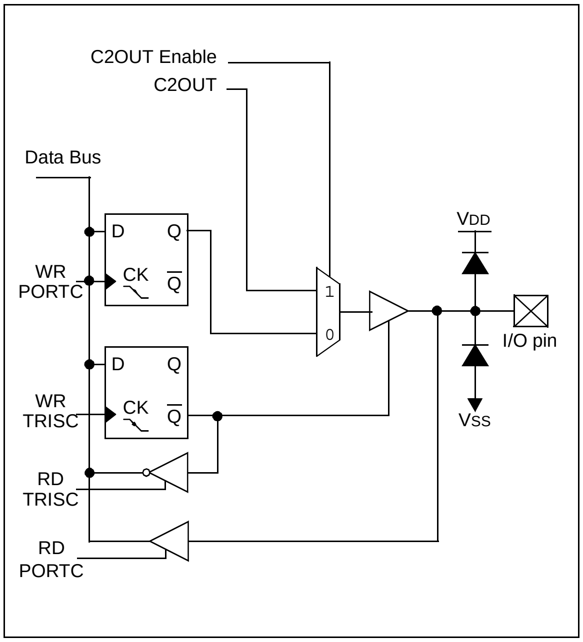


TABLE 4-2: SUMMARY OF REGISTERS ASSOCIATED WITH PORTC

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR, BOR, WUR	Value on all other Resets
PORTC	—	—	RC5	RC4	RC3	RC2	RC1	RC0	`--xx xx00`	`--uu uu00`
CMCON0	C2OUT	C1OUT	C2INV	C1INV	CIS	CM2	CM1	CM0	`0000 0000`	`0000 0000`
TRISC	—	—	TRISC5	TRISC4	TRISC3	TRISC2	TRISC1	TRISC0	`--11 1111`	`--11 1111`

Legend: `x` = unknown, `u` = unchanged, – = unimplemented locations read as ‘`0`’. Shaded cells are not used by PORTA.

5.1.3 SOFTWARE PROGRAMMABLE PRESCALER

A single software programmable prescaler is available for use with either Timer0 or the Watchdog Timer (WDT), but not both simultaneously. The prescaler assignment is controlled by the PSA bit of the OPTION register. To assign the prescaler to Timer0, the PSA bit must be cleared to a ‘0’.

There are 8 prescaler options for the Timer0 module ranging from 1:2 to 1:256. The prescale values are selectable via the PS<2:0> bits of the OPTION register. In order to have a 1:1 prescaler value for the Timer0 module, the prescaler must be assigned to the WDT module.

The prescaler is not readable or writable. When assigned to the Timer0 module, all instructions writing to the TMR0 register will clear the prescaler.

When the prescaler is assigned to WDT, a `CLRWDT` instruction will clear the prescaler along with the WDT.

5.1.3.1 Switching Prescaler Between Timer0 and WDT Modules

As a result of having the prescaler assigned to either Timer0 or the WDT, it is possible to generate an unintended device Reset when switching prescaler values. When changing the prescaler assignment from Timer0 to the WDT module, the instruction sequence shown in Example 5-1, must be executed.

EXAMPLE 5-1: CHANGING PRESCALER (TIMER0 WDT)

```
BANKSEL  TMR0             ;
CLRWDT                    ;Clear WDT
CLRF     TMR0             ;Clear TMR0 and
                          ;prescaler
BANKSEL  OPTION_REG       ;
BSF      OPTION_REG,PSA   ;Select WDT
CLRWDT                    ;
                          ;
MOVLW    b’11111000’      ;Mask prescaler
ANDWF    OPTION_REG,W     ;bits
IORLW    b’00000101’      ;Set WDT prescaler
MOVWF    OPTION_REG       ;to 1:32
```

When changing the prescaler assignment from the WDT to the Timer0 module, the following instruction sequence must be executed (see Example 5-2).

EXAMPLE 5-2: CHANGING PRESCALER (WDT TIMER0)

```
CLRWDT                  ;Clear WDT and
                        ;prescaler
BANKSEL OPTION_REG      ;
MOVLW   b’11110000’     ;Mask TMR0 select and
ANDWF   OPTION_REG,W    ;prescaler bits
IORLW   b’00000011’     ;Set prescale to 1:16
MOVWF   OPTION_REG      ;
```

5.1.4 TIMER0 INTERRUPT

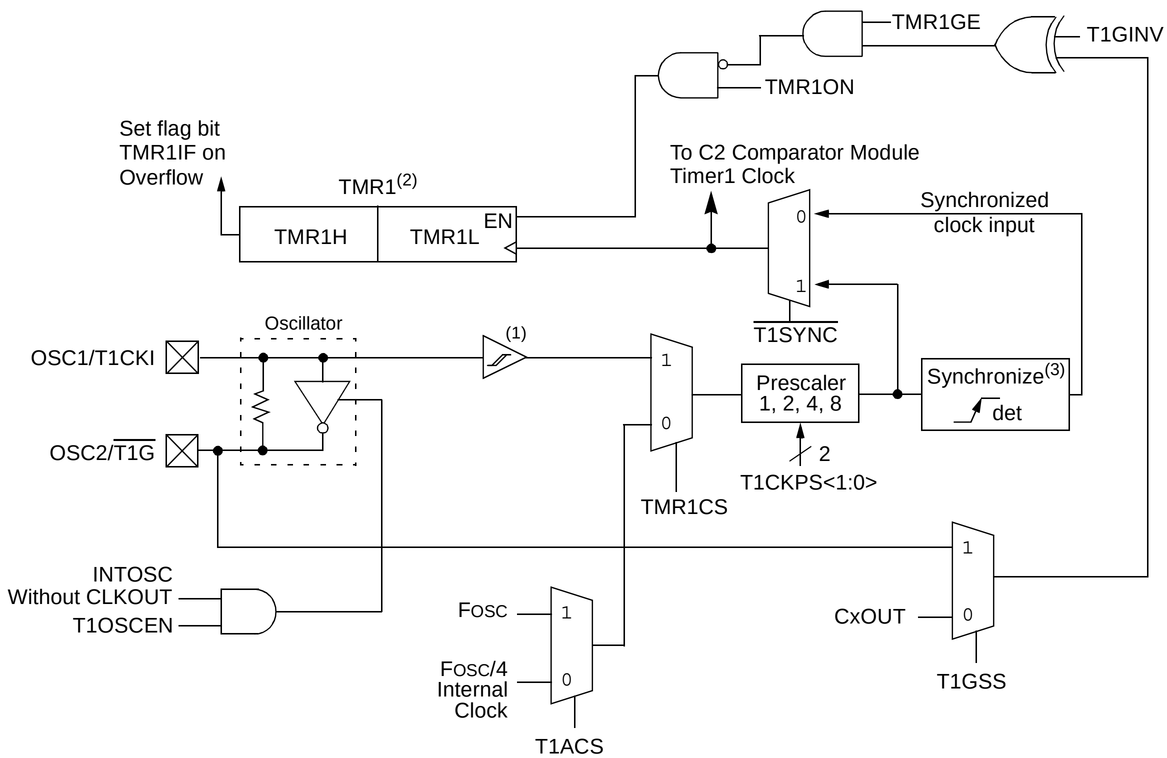
Timer0 will generate an interrupt when the TMR0 register overflows from FFh to 00h. The T0IF interrupt flag bit of the INTCON register is set every time the TMR0 register overflows, regardless of whether or not the Timer0 interrupt is enabled. The T0IF bit must be cleared in software. The Timer0 interrupt enable is the T0IE bit of the INTCON register..

Note:	The Timer0 interrupt cannot wake the processor from Sleep since the timer is frozen during Sleep.

5.1.5 USING TIMER0 WITH AN EXTERNAL CLOCK

When Timer0 is in Counter mode, the synchronization of the T0CKI input and the Timer0 register is accomplished by sampling the prescaler output on the Q2 and Q4 cycles of the internal phase clocks. Therefore, the high and low periods of the external clock source must meet the timing requirements as shown in the Section 15.0 “Electrical Specifications” .

FIGURE 6-1: TIMER1 BLOCK DIAGRAM



Note 1: ST Buffer is low power type when using LP osc, or high speed type when using T1CKI.
2: Timer1 register increments on rising edge.
3: Synchronize does not operate while in Sleep.

NOTES:

11.22 Low-Current Sleep Mode

The Sleep command from the microcontroller, via an SPI Interface command, places the AFE into an ultra Low-current mode. All circuits including the RF Limiter, except the minimum circuitry required to retain register memory and SPI capability, will be powered down to minimize the AFE current draw. Power-on Reset or any SPI command, other than Sleep command, is required to wake the AFE from Sleep.

11.23 Low-Current Standby Mode

The AFE is in Standby mode when no LF signal is present on the antenna inputs but the AFE is powered and ready to receive any incoming signals.

11.24 Low-Current Operating Mode

The AFE is in Low-current Operating mode when a LF signal is present on an LF antenna input and internal circuitry is switching with the received data.

11.25 Error Detection of AFE Configuration Register Data

The AFE's Configuration registers are volatile memory. Therefore, the contents of the registers can be corrupted or cleared by any electrical incidence such as battery disconnect. To ensure the data integrity, the AFE has an error detection mechanism using row an2.2(rren)12.2(t)0.

FIGURE 11-15: RSSI OUTPUT CURRENT VS. INPUT SIGNAL LEVEL EXAMPLE

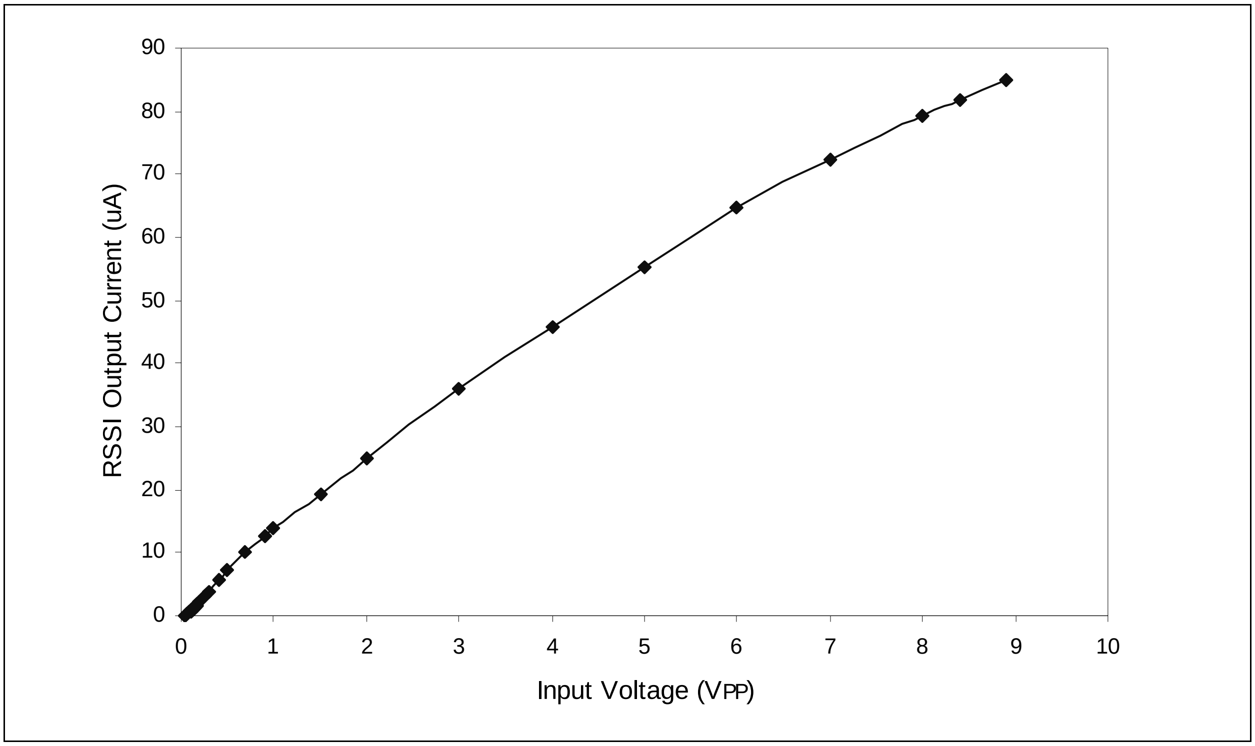


TABLE 15-4: RESET, WATCHDOG TIMER, OSCILLATOR START-UP TIMER, POWER-UP TIMER AND BROWN-OUT RESET PARAMETERS

Standard Operating Conditions (unless otherwise stated)
Operating Temperature -40°C T_A +125°C

Param No.	Sym	Characteristic	Min	Typ†	Max	Units	Conditions
30	T_{MCL}	$\overline{\text{MCLR}}$ Pulse Width (low)	2 5	— —	— —	μs μs	V_{DD} = 5V, -40°C to +85°C V_{DD} = 5V
31	T_{WDT}	Watchdog Timer Time-out Period (No Prescaler)	10 10	16 16	29 31	ms ms	V_{DD} = 5V, -40°C to +85°C V_{DD} = 5V
32	T_{OST}	Oscillation Start-up Timer Period(1, 2)	—	1024	—	T_{OSC}	(NOTE 3)
33*	T_{PWRT}	Power-up Timer Period	40	65	140	ms	
34*	T_{IOZ}	I/O High-impedance from $\overline{\text{MCLR}}$ Low or Watchdog Timer Reset	—	—	2.0	μs	
35	V_{BOR}	Brown-out Reset Voltage	2.0	—	2.2	V	(NOTE 4)
36*	V_{HYST}	Brown-out Reset Hysteresis	—	50	—	mV	
37*	T_{BOR}	Brown-out Reset Minimum Detection Period	100	—	—	μs	V_{DD} V_{BOR}

* These parameters are characterized but not tested.

† Data in "Typ" column is at 5V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

Note 1: Instruction cycle period (T_{CY}) equals four times the input oscillator time base period. All specified values are based on characterization data for that particular oscillator type under standard operating conditions with the device executing code. Exceeding these specified limits may result in an unstable oscillator operation and/or higher than expected current consumption. All devices are tested to operate at "min" values with an external clock applied to the OSC1 pin. When an external clock input is used, the "max" cycle time limit is "DC" (no clock) for all devices.

2: By design.

3: Period of the slower clock.

4: To ensure these voltage tolerances, V_{DD} and V_{SS} must be capacitively decoupled as close to the device as possible. 0.1 μF and 0.01 μF values in parallel are recommended.

FIGURE 16-18: MAXIMUM WDT I_{PD} vs. V_{DD} OVER TEMPERATURE

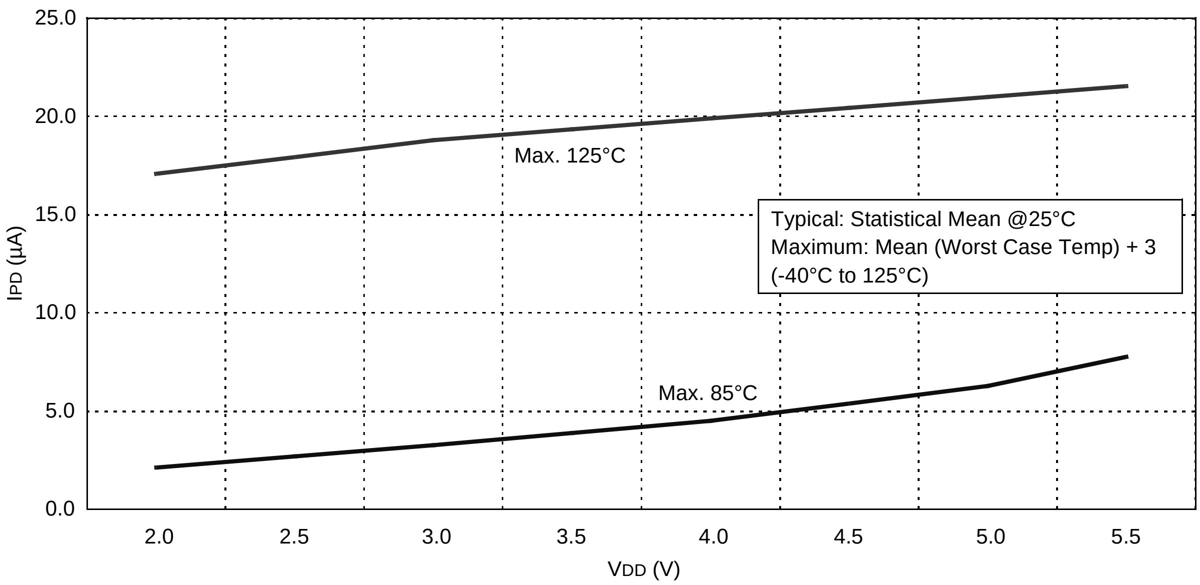


FIGURE 16-19: WDT PERIOD vs. V_{DD} OVER TEMPERATURE