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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

| | |
|----------------------------|---|
| Product Status | Obsolete |
| Core Processor | PIC |
| Core Size | 8-Bit |
| Speed | 20MHz |
| Connectivity | - |
| Peripherals | Brown-out Detect/Reset, LVD, POR, WDT |
| Number of I/O | 11 |
| Program Memory Size | 3.5KB (2K x 14) |
| Program Memory Type | FLASH |
| EEPROM Size | - |
| RAM Size | 128 x 8 |
| Voltage - Supply (Vcc/Vdd) | 2V ~ 3.6V |
| Data Converters | - |
| Oscillator Type | Internal |
| Operating Temperature | -40°C ~ 125°C (TA) |
| Mounting Type | Through Hole |
| Package / Case | 20-DIP (0.300", 7.62mm) |
| Supplier Device Package | 20-PDIP |
| Purchase URL | https://www.e-xfl.com/product-detail/microchip-technology/pic16f639-e-p |

PIC12F635/PIC16F636/639

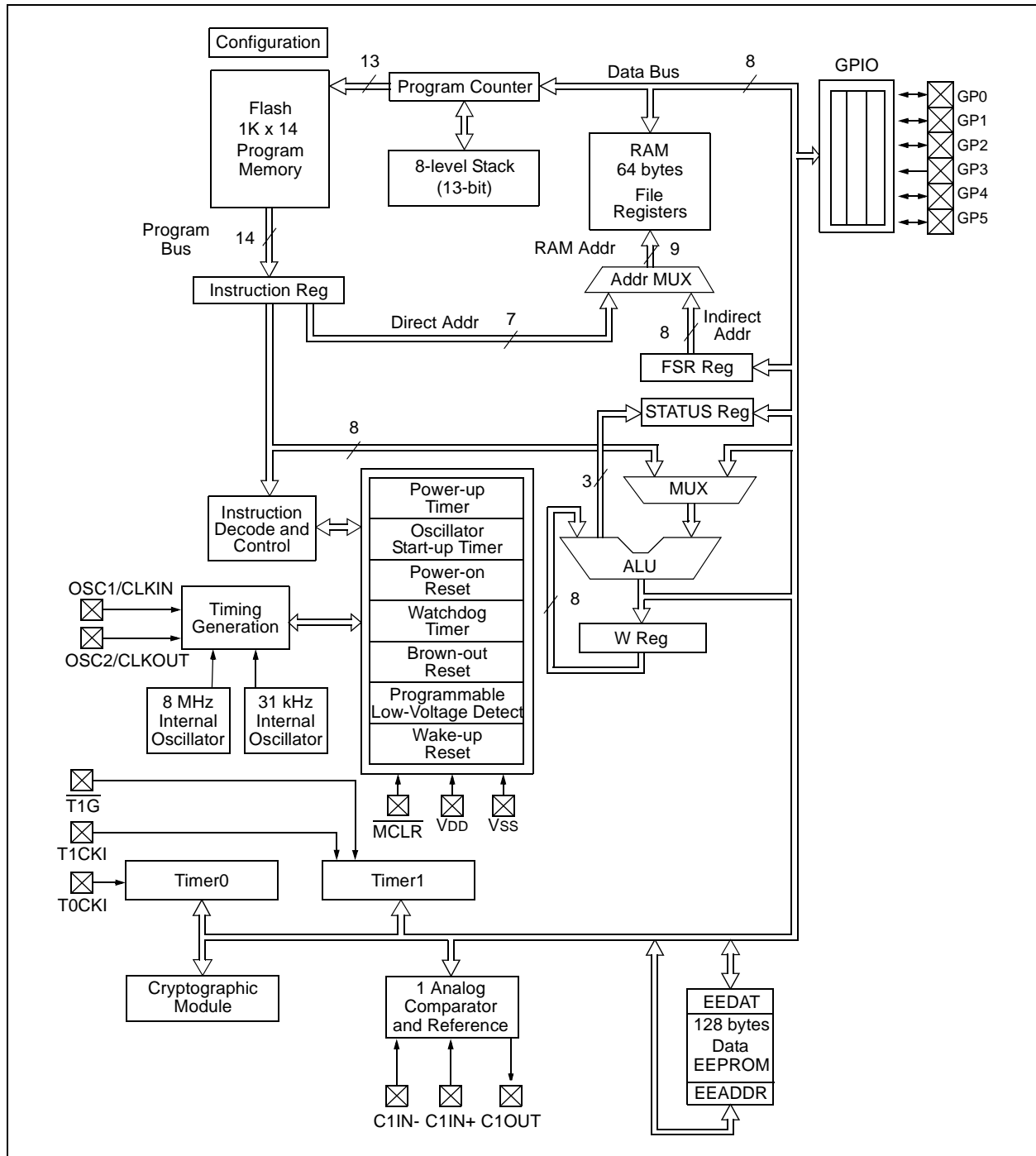
1.0 DEVICE OVERVIEW

This document contains device specific information for the PIC12F635/PIC16F636/639 devices.

Block Diagrams and pinout descriptions of the devices are as follows:

- PIC12F635 (Figure 1-1, Table 1-1)
- PIC16F636 (Figure 1-2, Table 1-2)
- PIC16F639 (Figure 1-3, Table 1-3)

FIGURE 1-1: PIC12F635 BLOCK DIAGRAM



PIC12F635/PIC16F636/639

NOTES:

PIC12F635/PIC16F636/639

TABLE 2-5: PIC12F635/PIC16F636/639 SPECIAL FUNCTION REGISTERS SUMMARY BANK 2

| Addr | Name | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | Value on POR/BOR/WUR | Page |
|--------|-----------------------|-------------------------------|---------|-------|-------|-------|-------|--------|--------|----------------------|-----------|
| Bank 2 | | | | | | | | | | | |
| 10Ch | — | Unimplemented | | | | | | | | — | — |
| 10Dh | — | Unimplemented | | | | | | | | — | — |
| 10Eh | — | Unimplemented | | | | | | | | — | — |
| 10Fh | — | Unimplemented | | | | | | | | — | — |
| 110h | CRCON | GO/DONE | ENC/DEC | — | — | — | — | CRREG1 | CRREG0 | 00-- --00 | 00-- --00 |
| 111h | CRDAT0 ⁽²⁾ | Cryptographic Data Register 0 | | | | | | | | 0000 0000 | 0000 0000 |
| 112h | CRDAT1 ⁽²⁾ | Cryptographic Data Register 1 | | | | | | | | 0000 0000 | 0000 0000 |
| 113h | CRDAT2 ⁽²⁾ | Cryptographic Data Register 2 | | | | | | | | 0000 0000 | 0000 0000 |
| 114h | CRDAT3 ⁽²⁾ | Cryptographic Data Register 3 | | | | | | | | 0000 0000 | 0000 0000 |
| 115h | — | Unimplemented | | | | | | | | — | — |
| 116h | — | Unimplemented | | | | | | | | — | — |

Legend: — = Unimplemented locations read as '0', u = unchanged, x = unknown, α = value depends on condition, shaded = unimplemented

- Note 1:** Other (non Power-up) Resets include $\overline{\text{MCLR}}$ Reset and Watchdog Timer Reset during normal operation.
- 2:** CRDAT<3:0> registers are KEELOQ[®] hardware peripheral related registers and require the execution of the "KEELOQ Encoder License Agreement" regarding implementation of the module and access to related registers. The "KEELOQ Encoder License Agreement" may be accessed through the Microchip web site located at www.microchip.com/KEELOQ or by contacting your local Microchip Sales Representative.

PIC12F635/PIC16F636/639

NOTES:

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FIGURE 3-9: FSCM TIMING DIAGRAM

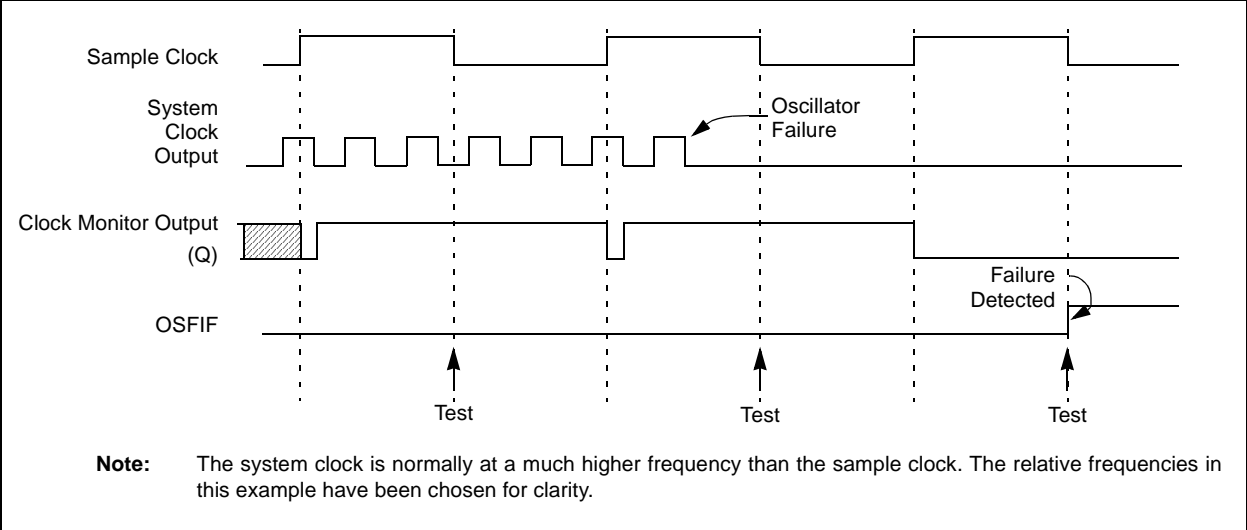


TABLE 3-2: SUMMARY OF REGISTERS ASSOCIATED WITH CLOCK SOURCES

| Name | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | Value on POR, BOR | Value on all other Resets ⁽¹⁾ |
|-----------------------|-------|-------|-------|---------------------|-------|-------|-------|--------|-------------------|--|
| CONFIG ⁽²⁾ | CPD | CP | MCLRE | PWRTE | WDTE | FOSC2 | FOSC1 | FOSC0 | — | — |
| INTCON | GIE | PEIE | T0IE | INTE | RAIE | T0IF | INTF | RAIF | 0000 000x | 0000 000x |
| OSCCON | — | IRCF2 | IRCF1 | IRCF0 | OSTS | HTS | LTS | SCS | -110 x000 | -110 x000 |
| OSCTUNE | — | — | — | TUN4 | TUN3 | TUN2 | TUN1 | TUN0 | ---0 0000 | ---u uuuu |
| PIE1 | EEIE | LVDIE | CRIE | C2IE ⁽³⁾ | C1IE | OSFIE | — | TMR1IE | 000- 00-0 | 000- 00-0 |
| PIR1 | EEIF | LVDIF | CRIF | C2IF ⁽³⁾ | C1IF | OSFIF | — | TMR1IF | 000- 00-0 | 000- 00-0 |

Legend: x = unknown, u = unchanged, - = unimplemented locations read as '0'. Shaded cells are not used by oscillators.

Note 1: Other (non Power-up) Resets include MCLR Reset and Watchdog Timer Reset during normal operation.

2: See Configuration Word register (CONFIG) for operation of all register bits.

3: PIC16F636/639 only.

4.0 I/O PORTS

There are as many as twelve general purpose I/O pins available. Depending on which peripherals are enabled, some or all of the pins may not be available as general purpose I/O. In general, when a peripheral is enabled, the associated pin may not be used as a general purpose I/O pin.

4.1 PORTA and the TRISA Registers

PORTA is a 6-bit wide, bidirectional port. The corresponding data direction register is TRISA (Register 4-2). Setting a TRISA bit (= 1) will make the corresponding PORTA pin an input (i.e., put the corresponding output driver in a High-Impedance mode). Clearing a TRISA bit (= 0) will make the corresponding PORTA pin an output (i.e., put the contents of the output latch on the selected pin). The exception is RA3, which is input only and its TRIS bit will always read as '1'. Example 4-1 shows how to initialize PORTA.

Note: PORTA = GPIO
TRISA = TRISIO

Reading the PORTA register (Register 4-1) reads the status of the pins, whereas writing to it will write to the PORT latch. All write operations are read-modify-write operations. Therefore, a write to a port implies that the port pins are read, this value is modified and then written to the PORT data latch. RA3 reads '0' when MCLRE = 1.

The TRISA register controls the direction of the PORTA pins, even when they are being used as analog inputs. The user must ensure the bits in the TRISA register are maintained set when using them as analog inputs. I/O pins configured as analog inputs always read '0'.

Note: The CMCON0 register must be initialized to configure an analog channel as a digital input. Pins configured as analog inputs will read '0'.

EXAMPLE 4-1: INITIALIZING PORTA

```
BANKSEL PORTA      ;
CLRF  PORTA         ;Init PORTA
MOVLW 07h           ;Set RA<2:0> to
MOVWF CMCON0        ;digital I/O
BSF    STATUS,RP0    ;Bank 1
BCF    STATUS,RP1    ;
MOVLW 0Ch           ;Set RA<3:2> as inputs
MOVWF TRISA          ;and set RA<5:4,1:0>
                      ;as outputs
```

4.2 Additional Pin Functions

Every PORTA pin on the PIC12F635/PIC16F636/639 has an interrupt-on-change option and a weak pull-up/pull-down option. RA0 has an Ultra Low-Power Wake-up option. The next three sections describe these functions.

4.2.1 WEAK PULL-UP/PULL-DOWN

Each of the PORTA pins, except RA3, has an internal weak pull-up and pull-down. The WDA bits select either a pull-up or pull-down for an individual port bit. Individual control bits can turn on the pull-up or pull-down. These pull-ups/pull-downs are automatically turned off when the port pin is configured as an output, as an alternate function or on a Power-on Reset, setting the RAPU bit of the OPTION register. A weak pull-up on RA3 is enabled when configured as MCLR in the Configuration Word register and disabled when high voltage is detected, to reduce current consumption through RA3, while in Programming mode.

Note: PORTA = GPIO
TRISA = TRISIO

4.2.3 ULTRA LOW-POWER WAKE-UP

The Ultra Low-Power Wake-up (ULPWU) on RA0 allows a slow falling voltage to generate an interrupt-on-change on RA0 without excess current consumption. The mode is selected by setting the ULPWUE bit of the PCON register. This enables a small current sink which can be used to discharge a capacitor on RA0.

To use this feature, the RA0 pin is configured to output '1' to charge the capacitor, interrupt-on-change for RA0 is enabled and RA0 is configured as an input. The ULPWUE bit is set to begin the discharge and a SLEEP instruction is performed. When the voltage on RA0 drops below VIL, an interrupt will be generated which will cause the device to wake-up. Depending on the state of the GIE bit of the INTCON register, the device will either jump to the interrupt vector (0004h) or execute the next instruction when the interrupt event occurs. See **Section 4.2.2 "Interrupt-on-Change"** and **Section 12.9.3 "PORTA Interrupt"** for more information.

This feature provides a low-power technique for periodically waking up the device from Sleep. The time-out is dependent on the discharge time of the RC circuit on RA0. See Example 4-2 for initializing the Ultra Low Power Wake-up module.

The series resistor provides overcurrent protection for the RA0 pin and can allow for software calibration of the time-out (see Figure 4-1). A timer can be used to measure the charge time and discharge time of the capacitor. The charge time can then be adjusted to provide the desired interrupt delay. This technique will compensate for the affects of temperature, voltage and component accuracy. The Ultra Low-Power Wake-up peripheral can also be configured as a simple Programmable Low-Voltage Detect or temperature sensor.

Note: For more information, refer to the Application Note AN879, "Using the Microchip Ultra Low-Power Wake-up Module" (DS00879).

EXAMPLE 4-2: ULTRA LOW-POWER WAKE-UP INITIALIZATION

```
BANKSEL PORTA      ;
BSF    PORTA,0      ;Set RA0 data latch
MOVLW  H'7'         ;Turn off
MOVWF  CMCON0       ; comparators
BANKSEL TRISA      ;
BCF    TRISA,0      ;Output high to
CALL   CapDelay     ; charge capacitor
BSF    PCON,ULPWUE  ;Enable ULP Wake-up
BSF    IOCA,0       ;Select RA0 IOC
BSF    TRISA,0      ;RA0 to input
MOVLW  B'10001000' ;Enable interrupt
MOVWF  INTCON       ; and clear flag
SLEEP                ;Wait for IOC
NOP                ;
```


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5.1.3 SOFTWARE PROGRAMMABLE PRESCALER

A single software programmable prescaler is available for use with either Timer0 or the Watchdog Timer (WDT), but not both simultaneously. The prescaler assignment is controlled by the PSA bit of the OPTION register. To assign the prescaler to Timer0, the PSA bit must be cleared to a '0'.

There are 8 prescaler options for the Timer0 module ranging from 1:2 to 1:256. The prescale values are selectable via the PS<2:0> bits of the OPTION register. In order to have a 1:1 prescaler value for the Timer0 module, the prescaler must be assigned to the WDT module.

The prescaler is not readable or writable. When assigned to the Timer0 module, all instructions writing to the TMR0 register will clear the prescaler.

When the prescaler is assigned to WDT, a CLRWDT instruction will clear the prescaler along with the WDT.

5.1.3.1 Switching Prescaler Between Timer0 and WDT Modules

As a result of having the prescaler assigned to either Timer0 or the WDT, it is possible to generate an unintended device Reset when switching prescaler values. When changing the prescaler assignment from Timer0 to the WDT module, the instruction sequence shown in Example 5-1, must be executed.

EXAMPLE 5-1: CHANGING PRESCALER (TIMER0 → WDT)

```
BANKSEL    TMR0          ;
CLRWDT     ;Clear WDT
CLRWF      TMR0          ;Clear TMR0 and
                ;prescaler

BANKSEL    OPTION_REG    ;
BSF        OPTION_REG,PSA ;Select WDT
CLRWDT     ;
                ;

MOVLW      b'11111000'    ;Mask prescaler
ANDWF      OPTION_REG,W   ;bits
IORLW      b'00000101'    ;Set WDT prescaler
MOVWF      OPTION_REG     ;to 1:32
```

When changing the prescaler assignment from the WDT to the Timer0 module, the following instruction sequence must be executed (see Example 5-2).

EXAMPLE 5-2: CHANGING PRESCALER (WDT → TIMER0)

```
CLRWDT     ;Clear WDT and
                ;prescaler

BANKSEL    OPTION_REG    ;
MOVLW      b'11110000'    ;Mask TMR0 select and
ANDWF      OPTION_REG,W   ;prescaler bits
IORLW      b'00000011'    ;Set prescale to 1:16
MOVWF      OPTION_REG     ;
```

5.1.4 TIMER0 INTERRUPT

Timer0 will generate an interrupt when the TMR0 register overflows from FFh to 00h. The T0IF interrupt flag bit of the INTCON register is set every time the TMR0 register overflows, regardless of whether or not the Timer0 interrupt is enabled. The T0IF bit must be cleared in software. The Timer0 interrupt enable is the T0IE bit of the INTCON register..

Note: The Timer0 interrupt cannot wake the processor from Sleep since the timer is frozen during Sleep.

5.1.5 USING TIMER0 WITH AN EXTERNAL CLOCK

When Timer0 is in Counter mode, the synchronization of the T0CKI input and the Timer0 register is accomplished by sampling the prescaler output on the Q2 and Q4 cycles of the internal phase clocks. Therefore, the high and low periods of the external clock source must meet the timing requirements as shown in the **Section 15.0 “Electrical Specifications”**.

7.0 COMPARATOR MODULE

Comparators are used to interface analog circuits to a digital circuit by comparing two analog voltages and providing a digital indication of their relative magnitudes. The comparators are very useful mixed signal building blocks because they provide analog functionality independent of the program execution. The Analog Comparator module includes the following features:

- Dual comparators (PIC16F636/639 only)
- Multiple comparator configurations
- Comparator(s) output is available internally/externally
- Programmable output polarity
- Interrupt-on-change
- Wake-up from Sleep
- Timer1 gate (count enable)
- Output synchronization to Timer1 clock input
- Programmable voltage reference

7.1 Comparator Overview

A comparator is shown in Figure 7-1 along with the relationship between the analog input levels and the digital output. When the analog voltage at V_{IN+} is less than the analog voltage at V_{IN-} , the output of the

comparator is a digital low level. When the analog voltage at V_{IN+} is greater than the analog voltage at V_{IN-} , the output of the comparator is a digital high level.

The PIC12F635 contains a single comparator as shown in Figure 7-2.

The PIC16F636/639 devices contains two comparators as shown in Figure 7-3 and Figure 7-4. The comparators are not independently configurable.

FIGURE 7-1: SINGLE COMPARATOR

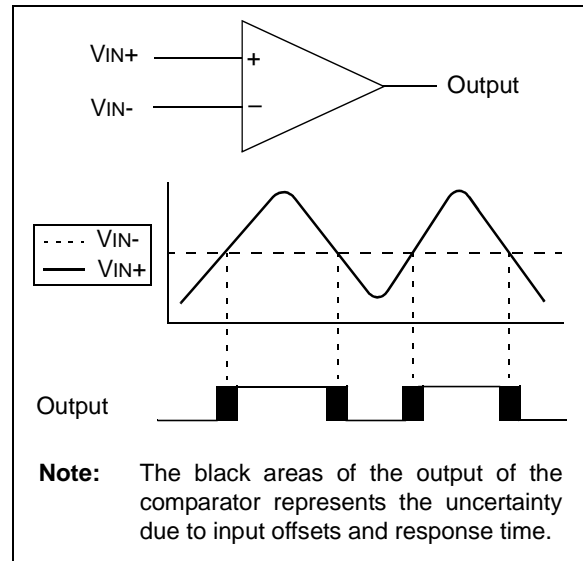
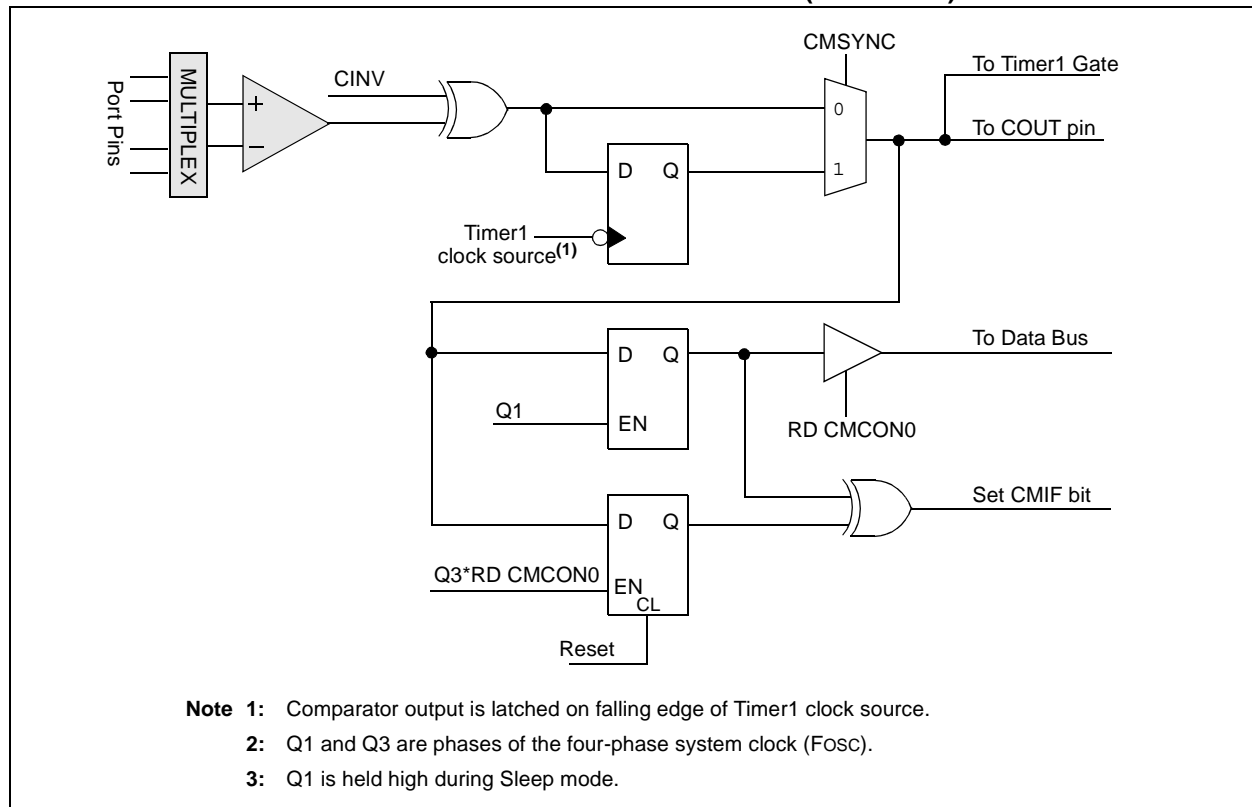


FIGURE 7-2: COMPARATOR OUTPUT BLOCK DIAGRAM (PIC12F635)



PIC12F635/PIC16F636/639

TABLE 7-2: SUMMARY OF REGISTERS ASSOCIATED WITH THE COMPARATOR AND VOLTAGE REFERENCE MODULES

| Name | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | Value on POR, BOR | Value on all other Resets |
|--------|-------|-------|--------|--------|--------|--------|--------|--------|-------------------|---------------------------|
| CMCON0 | — | COUT | — | CINV | CIS | CM2 | CM1 | CM0 | -0-0 0000 | -0-0 0000 |
| CMCON1 | — | — | — | — | — | — | T1GSS | CMSYNC | ---- --10 | ---- --10 |
| INTCON | GIE | PEIE | T0IE | INTE | RAIE | T0IF | INTF | RAIF | 0000 000x | 0000 000x |
| PIE1 | EEIE | LVDIE | CRIE | — | C1IE | OSFIE | — | TMR1IE | 000- 00-0 | 000- 00-0 |
| PIR1 | EEIF | LVDIF | CRIF | — | C1IF | OSFIF | — | TMR1IF | 000- 00-0 | 000- 00-0 |
| PORTA | — | — | RA5 | RA4 | RA3 | RA2 | RA1 | RA0 | --xx xxxx | --uu uuuu |
| PORTC | — | — | RC5 | RC4 | RC3 | RC2 | RC1 | RC0 | --xx xxxx | --uu uuuu |
| TRISA | — | — | TRISA5 | TRISA4 | TRISA3 | TRISA2 | TRISA1 | TRISA0 | --11 1111 | --11 1111 |
| TRISC | — | — | TRISC5 | TRISC4 | TRISC3 | TRISC2 | TRISC1 | TRISC0 | --11 1111 | --11 1111 |
| VRCON | VREN | — | VRR | — | VR3 | VR2 | VR1 | VR0 | 0-0- 0000 | 0-0- 0000 |

Legend: x = unknown, u = unchanged, - = unimplemented, read as '0'. Shaded cells are not used for comparator.

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REGISTER 8-1: LVDCON: LOW-VOLTAGE DETECT CONTROL REGISTER

| | | | | | | | |
|-------|-----|----------------------|--------|-----|--------|--------|--------|
| U-0 | U-0 | R-0 | R/W-0 | U-0 | R/W-1 | R/W-0 | R/W-0 |
| — | — | IRVST ⁽¹⁾ | LV DEN | — | LV DL2 | LV DL1 | LV DL0 |
| bit 7 | | | | | | | bit 0 |

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-6 **Unimplemented:** Read as '0'

bit 5 **IRVST:** Internal Reference Voltage Stable Status Flag bit⁽¹⁾

1 = Indicates that the PLVD is stable and PLVD interrupt is reliable

0 = Indicates that the PLVD is not stable and PLVD interrupt must not be enabled

bit 4 **LV DEN:** Low-Voltage Detect Module Enable bit

1 = Enables PLVD Module, powers up PLVD circuit and supporting reference circuitry

0 = Disables PLVD Module, powers down PLVD circuit and supporting reference circuitry

bit 3 **Unimplemented:** Read as '0'

bit 2-0 **LV DL<2:0>:** Low-Voltage Detection Level bits (nominal values)

111 = 4.5V

110 = 4.2V

101 = 4.0V

100 = 2.3V (default)

011 = 2.2V

010 = 2.1V

001 = 2.0V⁽²⁾

000 = Reserved

Note 1: The IRVST bit is usable only when the HFINTOSC is running.

2: Not tested and below minimum operating conditions.

TABLE 8-1: REGISTERS ASSOCIATED WITH PROGRAMMABLE LOW-VOLTAGE DETECT

| Name | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | Value on POR, BOR | Value on all other Resets |
|--------|-------|-------|-------|--------|-------|--------|--------|--------|-------------------|---------------------------|
| INTCON | GIE | PEIE | T0IE | INTE | RAIE | T0IF | INTF | RAIF | 0000 000x | 0000 000x |
| PIE1 | OSFIE | C2IE | C1IE | LCDIE | — | LV DIE | — | CCP2IE | 0000 -0-0 | 0000 -0-0 |
| PIR1 | OSFIF | C2IF | C1IF | LCDIF | — | LV DIF | — | CCP2IF | 0000 -0-0 | 0000 -0-0 |
| LVDCON | — | — | IRVST | LV DEN | — | LV DL2 | LV DL1 | LV DL0 | --00 -100 | --00 -100 |

Legend: x = unknown, - = unimplemented read as '0'. Shaded cells are not used by the PLVD module.

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9.0 DATA EEPROM MEMORY

The EEPROM data memory is readable and writable during normal operation (full VDD range). This memory is not directly mapped in the register file space. Instead, it is indirectly addressed through the Special Function Registers. There are four SFRs used to read and write this memory:

- EECON1
- EECON2 (not a physically implemented register)
- EEDAT
- EEADR

EEDAT holds the 8-bit data for read/write and EEADR holds the address of the EEPROM location being accessed. PIC16F636/639 has 256 bytes of data EEPROM and the PIC12F635 has 128 bytes.

The EEPROM data memory allows byte read and write. A byte write automatically erases the location and writes the new data (erase before write). The EEPROM data memory is rated for high erase/write cycles. The write time is controlled by an on-chip timer. The write time will vary with voltage and temperature as well as from chip-to-chip. Please refer to A/C specifications in **Section 15.0 “Electrical Specifications”** for exact limits.

When the data memory is code-protected, the CPU may continue to read and write the data EEPROM memory. The device programmer can no longer access the data EEPROM data and will read zeroes.

REGISTER 9-1: EEDAT: EEPROM DATA REGISTER

| R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|--------|--------|--------|--------|--------|--------|--------|--------|
| EEDAT7 | EEDAT6 | EEDAT5 | EEDAT4 | EEDAT3 | EEDAT2 | EEDAT1 | EEDAT0 |
| bit 7 | | | | | | | bit 0 |

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0

EEDATn: Byte Value to Write To or Read From Data EEPROM bits

REGISTER 9-2: EEADR: EEPROM ADDRESS REGISTER

| R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|-----------------------|--------|--------|--------|--------|--------|--------|--------|
| EEADR7 ⁽¹⁾ | EEADR6 | EEADR5 | EEADR4 | EEADR3 | EEADR2 | EEADR1 | EEADR0 |
| bit 7 | | | | | | | bit 0 |

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0

EEADR: Specifies One of 256 Locations for EEPROM Read/Write Operation bits

Note 1: PIC16F636/639 only. Read as '0' on PIC12F635.

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9.1 EECON1 AND EECON2 Registers

EECON1 is the control register with four low-order bits physically implemented. The upper four bits are non-implemented and read as '0's.

Control bits RD and WR initiate read and write, respectively. These bits cannot be cleared, only set in software. They are cleared in hardware at completion of the read or write operation. The inability to clear the WR bit in software prevents the accidental, premature termination of a write operation.

The WREN bit, when set, will allow a write operation. On power-up, the WREN bit is clear. The WRERR bit is set when a write operation is interrupted by a MCLR Reset, or a WDT Time-out Reset during normal operation. In these situations, following Reset, the user can check the WRERR bit, clear it and rewrite the location. The data and address will be cleared. Therefore, the EEDAT and EEADR registers will need to be re-initialized.

Interrupt flag, EEIF bit of the PIR1 register, is set when write is complete. This bit must be cleared in software.

EECON2 is not a physical register. Reading EECON2 will read all '0's. The EECON2 register is used exclusively in the data EEPROM write sequence.

Note: The EECON1, EEDAT and EEADR registers should not be modified during a data EEPROM write (WR bit = 1).

REGISTER 9-3: EECON1: EEPROM CONTROL REGISTER

| U-0 | U-0 | U-0 | U-0 | R/W-x | R/W-0 | R/S-0 | R/S-0 |
|-------|-----|-----|-----|-------|-------|-------|-------|
| — | — | — | — | WRERR | WREN | WR | RD |
| bit 7 | | | | bit 0 | | | |

Legend:

S = Bit can only be set

R = Readable bit

-n = Value at POR

W = Writable bit

'1' = Bit is set

U = Unimplemented bit, read as '0'

'0' = Bit is cleared

x = Bit is unknown

bit 7-4 **Unimplemented:** Read as '0'

bit 3 **WRERR:** EEPROM Error Flag bit

1 = A write operation is prematurely terminated (any MCLR Reset, any WDT Reset during normal operation or BOR Reset)

0 = The write operation completed

bit 2 **WREN:** EEPROM Write Enable bit

1 = Allows write cycles

0 = Inhibits write to the data EEPROM

bit 1 **WR:** Write Control bit

1 = Initiates a write cycle (The bit is cleared by hardware once write is complete. The WR bit can only be set, not cleared, in software.)

0 = Write cycle to the data EEPROM is complete

bit 0 **RD:** Read Control bit

1 = Initiates an EEPROM read (Read takes one cycle. RD is cleared in hardware. The RD bit can only be set, not cleared, in software.)

0 = Does not initiate an EEPROM read

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REGISTER 11-4: CONFIGURATION REGISTER 3

| | | | | | | | | |
|-------|-----|---------|---------|---------|---------|---------|---------|-------|
| U-0 | U-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
| — | — | LCZTUN5 | LCZTUN4 | LCZTUN3 | LCZTUN2 | LCZTUN1 | LCZTUN0 | R3PAR |
| bit 8 | | | | | | | | |
| | | | | | | | | bit 0 |

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'
 -n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 8-7 **Unimplemented:** Read as '0'

bit 6-1 **LCZTUN<5:0>:** LCZ Tuning Capacitance bit

000000 = +0 pF (Default)

:

111111 = +63 pF

bit 0 **R3PAR:** Register Parity Bit – set/cleared so the 9-bit register contains odd parity – an odd number of set bits

REGISTER 11-5: CONFIGURATION REGISTER 4

| | | | | | | | | |
|---------|---------|---------|---------|---------|---------|---------|---------|-------|
| R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
| LCXSEN3 | LCXSEN2 | LCXSEN1 | LCXSEN0 | LCYSEN3 | LCYSEN2 | LCYSEN1 | LCYSEN0 | R4PAR |
| bit 8 | | | | | | | | |
| | | | | | | | | bit 0 |

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'
 -n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 8-5 **LCXSEN<3:0>⁽¹⁾:** Typical LCX Sensitivity Reduction bit

0000 = -0 dB (Default)

0001 = -2 dB

0010 = -4 dB

0011 = -6 dB

0100 = -8 dB

0101 = -10 dB

0110 = -12 dB

0111 = -14 dB

1000 = -16 dB

1001 = -18 dB

1010 = -20 dB

1011 = -22 dB

1100 = -24 dB

1101 = -26 dB

1110 = -28 dB

1111 = -30 dB

bit 4-1 **LCYSEN<3:0>⁽¹⁾:** Typical LCY Sensitivity Reduction bit

0000 = -0 dB (Default)

:

1111 = -30 dB

bit 0 **R4PAR:** Register Parity Bit – set/cleared so the 9-bit register contains odd parity – an odd number of set bits

Note 1: Assured monotonic increment (or decrement) by design.

SUBWF Subtract W from f

Syntax: [*label*] SUBWF f,d

Operands: $0 \leq f \leq 127$
 $d \in [0,1]$

Operation: $(f) - (W) \rightarrow (\text{destination})$

Status Affected: C, DC, Z

Description: Subtract (2's complement method) W register from register 'f'. If 'd' is '0', the result is stored in the W register. If 'd' is '1', the result is stored back in register 'f'.

| | |
|--------|----------------------|
| C = 0 | $W > f$ |
| C = 1 | $W \leq f$ |
| DC = 0 | $W<3:0> > f<3:0>$ |
| DC = 1 | $W<3:0> \leq f<3:0>$ |

XORLW Exclusive OR literal with W

Syntax: [*label*] XORLW k

Operands: $0 \leq k \leq 255$

Operation: $(W) .XOR. k \rightarrow (W)$

Status Affected: Z

Description: The contents of the W register are XOR'ed with the eight-bit literal 'k'. The result is placed in the W register.

SWAPF Swap Nibbles in f

Syntax: [*label*] SWAPF f,d

Operands: $0 \leq f \leq 127$
 $d \in [0,1]$

Operation: $(f<3:0>) \rightarrow (\text{destination}<7:4>)$,
 $(f<7:4>) \rightarrow (\text{destination}<3:0>)$

Status Affected: None

Description: The upper and lower nibbles of register 'f' are exchanged. If 'd' is '0', the result is placed in the W register. If 'd' is '1', the result is placed in register 'f'.

XORWF Exclusive OR W with f

Syntax: [*label*] XORWF f,d

Operands: $0 \leq f \leq 127$
 $d \in [0,1]$

Operation: $(W) .XOR. (f) \rightarrow (\text{destination})$

Status Affected: Z

Description: Exclusive OR the contents of the W register with register 'f'. If 'd' is '0', the result is stored in the W register. If 'd' is '1', the result is stored back in register 'f'.

PIC12F635/PIC16F636/639

FIGURE 15-1: PIC12F635/16F636 VOLTAGE-FREQUENCY GRAPH, $-40^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$

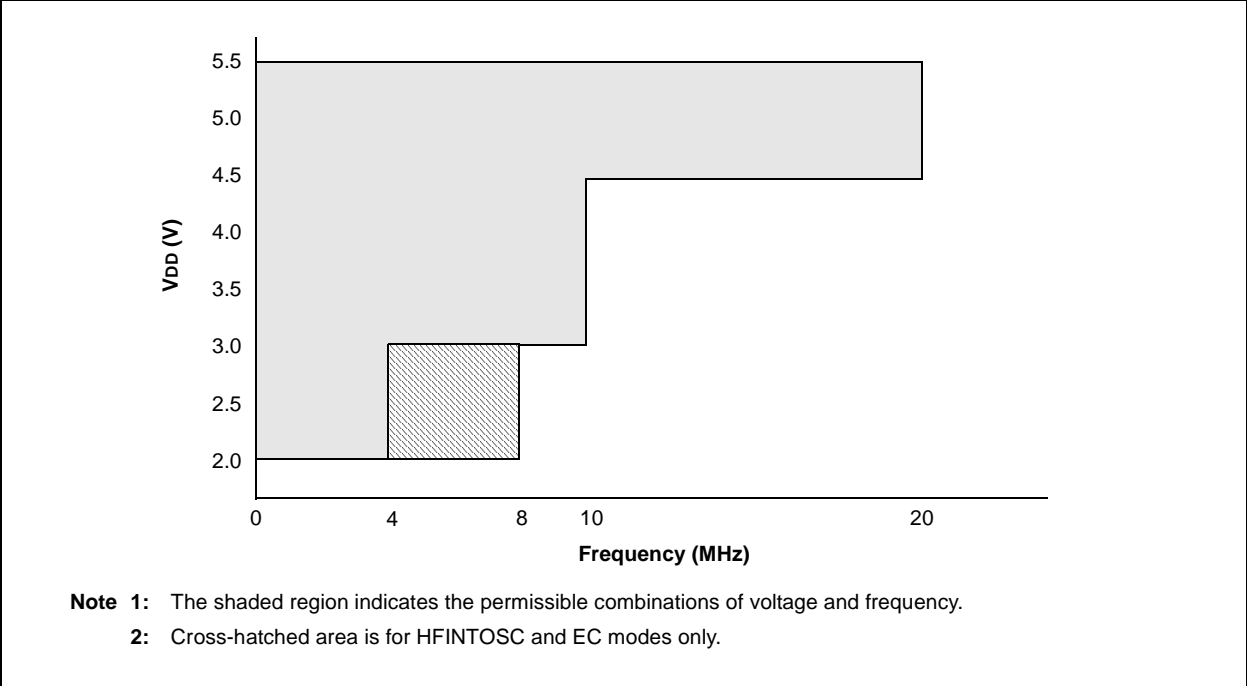
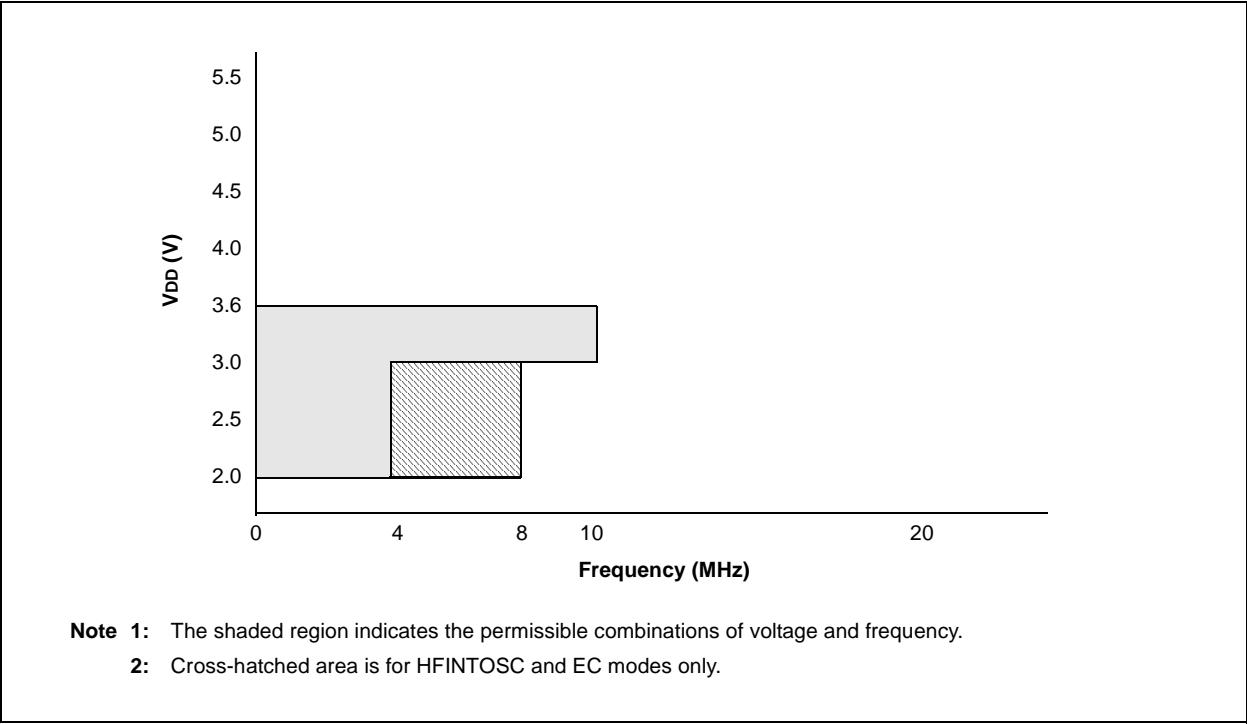


FIGURE 15-2: PIC16F639 VOLTAGE-FREQUENCY GRAPH, $-40^{\circ}\text{C} \leq T_A \leq +85^{\circ}\text{C}$



PIC12F635/PIC16F636/639

15.1 DC Characteristics: PIC12F635/PIC16F636-I (Industrial) PIC12F635/PIC16F636-E (Extended)

| DC CHARACTERISTICS | | | Standard Operating Conditions (unless otherwise stated) | | | | |
|---------------------------------|------|--|---|------------------|--------------------------|------------------|--|
| | | | Operating temperature -40°C ≤ TA ≤ +85°C for industrial -40°C ≤ TA ≤ +125°C for extended | | | | |
| Param No. | Sym | Characteristic | Min | Typ† | Max | Units | Conditions |
| D001 D001A D001B D001C | VDD | Supply Voltage | 2.0 2.0 3.0 4.5 | — — — — | 5.5 5.5 5.5 5.5 | V V V V | FOSC ≤ 4 MHz FOSC ≤ 8 MHz, HFINTOSC, EC FOSC ≤ 10 MHz FOSC ≤ 20 MHz |
| D002 | VDR | RAM Data Retention Voltage ⁽¹⁾ | 1.5* | — | — | V | Device in Sleep mode |
| D003 | VPOR | VDD Start Voltage to ensure internal Power-on Reset signal | — | VSS | — | V | See Section 12.3 “Power-on Reset” for details. |
| D004 | SVDD | VDD Rise Rate to ensure internal Power-on Reset signal | 0.05* | — | — | V/ms | See Section 12.3 “Power-on Reset” for details. |
| D005 | VBOD | Brown-out Reset | 2.0 | 2.1 | 2.2 | V | |

* These parameters are characterized but not tested.

† Data in “Typ” column is at 5.0V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

Note 1: This is the limit to which VDD can be lowered in Sleep mode without losing RAM data.

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FIGURE 16-34: MAXIMUM HFINTOSC START-UP TIMES vs. VDD OVER TEMPERATURE

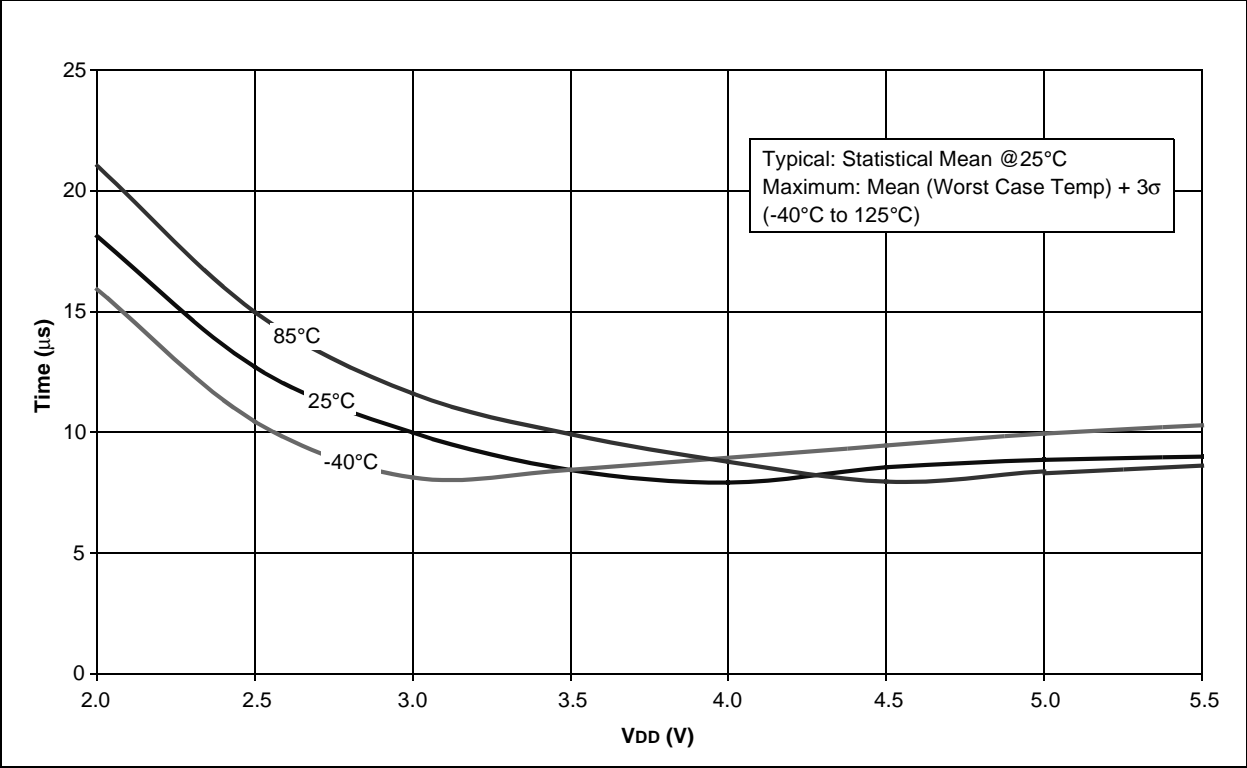
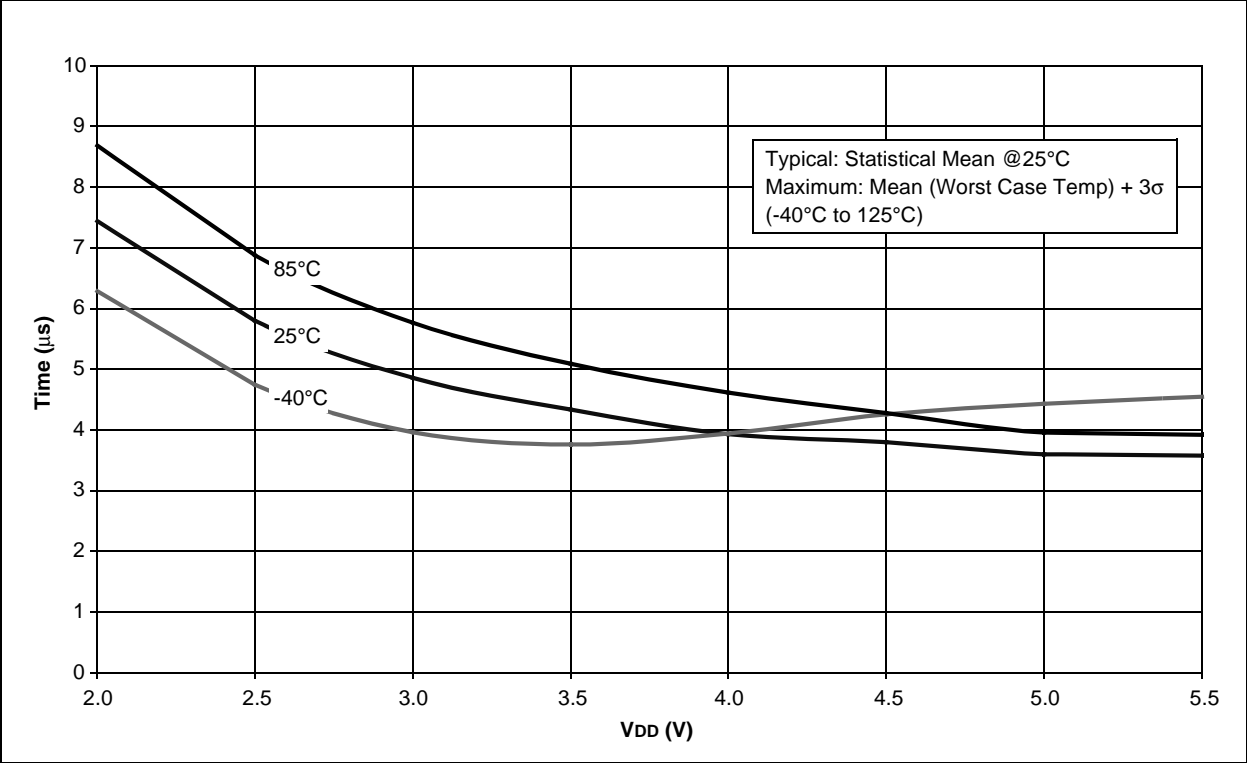


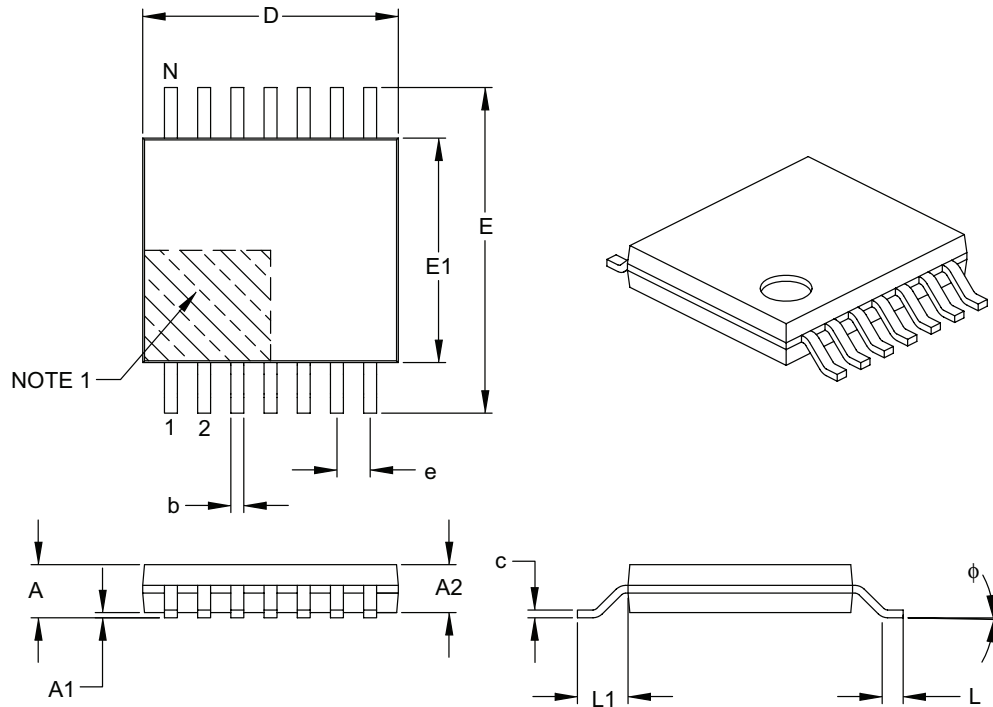
FIGURE 16-35: MINIMUM HFINTOSC START-UP TIMES vs. VDD OVER TEMPERATURE



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14-Lead Plastic Thin Shrink Small Outline (ST) – 4.4 mm Body [TSSOP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



| Units | | MILLIMETERS | | |
|--------------------------|----|-------------|------|------|
| Dimension Limits | | MIN | NOM | MAX |
| Number of Pins | N | 14 | | |
| Pitch | e | 0.65 BSC | | |
| Overall Height | A | – | – | 1.20 |
| Molded Package Thickness | A2 | 0.80 | 1.00 | 1.05 |
| Standoff | A1 | 0.05 | – | 0.15 |
| Overall Width | E | 6.40 BSC | | |
| Molded Package Width | E1 | 4.30 | 4.40 | 4.50 |
| Molded Package Length | D | 4.90 | 5.00 | 5.10 |
| Foot Length | L | 0.45 | 0.60 | 0.75 |
| Footprint | L1 | 1.00 REF | | |
| Foot Angle | φ | 0° | – | 8° |
| Lead Thickness | c | 0.09 | – | 0.20 |
| Lead Width | b | 0.19 | – | 0.30 |

Notes:

- Pin 1 visual index feature may vary, but must be located within the hatched area.
- Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.15 mm per side.
- Dimensioning and tolerancing per ASME Y14.5M.

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-087B

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