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Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	32MHz
Connectivity	I²C, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	18
Program Memory Size	28KB (16K x 14)
Program Memory Type	FLASH
EEPROM Size	256 x 8
RAM Size	2K x 8
Voltage - Supply (Vcc/Vdd)	2.3V ~ 5.5V
Data Converters	A/D 17x10b; D/A 1x5b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	20-SOIC (0.295", 7.50mm Width)
Supplier Device Package	20-SOIC
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic16f18346-i-so

TABLE 1-3: PIC16(L)F18346 PINOUT DESCRIPTION

Name	Function	Input Type	Output Type	Description
RA0/ANA0/C1IN0+/DAC1OUT/ ICDDAT/ICSPDAT	RA0	TTL/ST	CMOS	General purpose I/O.
	ANA0	AN	—	ADC Channel A0 input.
	C1IN0+	AN	—	Comparator C1 positive input.
	DAC1OUT	—	AN	Digital-to-Analog Converter output.
	ICDDAT	TTL/ST	CMOS	In-Circuit Debug Data I/O.
	ICSPDAT	TTL/ST	CMOS	ICSP™ Data I/O.
RA1/ANA1/VREF+/C1IN0-/ C2IN0-/ DAC1REF+/$\overline{SS2}$(1)/ ICDCLK/ ICSPCLK	RA1	TTL/ST	CMOS	General purpose I/O.
	ANA1	AN	—	ADC Channel A1 input.
	VREF+	AN	—	ADC positive voltage reference input.
	C1IN0-	AN	—	Comparator C1 negative input.
	C2IN0-	AN	—	Comparator C2 negative input.
	DAC1REF+	AN	—	Digital-to-Analog Converter positive reference input.
	$\overline{SS2}$	TTL/ST	—	Slave Select 2 input.
	ICDCLK	TTL/ST	CMOS	In-Circuit Debug Clock I/O.
	ICSPCLK	TTL/ST	CMOS	ICSP Clock I/O.
RA2/ANA2/VREF-/ DAC1REF-/ T0CKI(1)/ CCP3(1)/CWG1IN(1)/ CWG2IN(1)/CLCIN0(1)/ INT(1)	RA2	TTL/ST	CMOS	General purpose I/O.
	ANA2	AN	—	ADC Channel A2 input.
	VREF-	AN	—	ADC negative voltage reference input.
	DAC1REF-	AN	—	Digital-to-Analog Converter negative reference input.
	T0CKI	TTL/ST	—	TMR0 Clock input.
	CCP3	TTL/ST	CMOS	Capture/Compare/PWM 3 input.
	CWG1IN	TTL/ST	—	Complementary Waveform Generator 1 input.
	CWG2IN	TTL/ST	—	Complementary Waveform Generator 2 input.
	CLCIN0	TTL/ST	—	Configurable Logic Cell 0 input.
	INT	TTL/ST	—	External interrupt input.
RA3/$\overline{MCLR}$/VPP	RA3	TTL/ST	CMOS	General purpose I/O.
	$\overline{MCLR}$	TTL/ST	—	Master Clear with internal pull-up.
	VPP	HV	—	Programming voltage.
RA4/ANA4/T1G(1)/T3G(1)/ T5G(1)/SOSCO/CCP4(1)/ CLKOUT/OSC2	RA4	TTL/ST	CMOS	General purpose I/O.
	ANA4	AN	—	ADC Channel A4 input.
	T1G	TTL/ST	—	TMR1 gate input.
	T3G	TTL/ST	—	TMR3 gate input.
	T5G	TTL/ST	—	TMR5 gate input.
	SOSCO	—	XTAL	Secondary Oscillator connection.
	CCP4	TTL/ST	CMOS	Capture/Compare/PWM 4 input.
	CLKOUT	—	CMOS	FOSC/4 output.
	OSC2	—	XTAL	Crystal/Resonator (LP, XT, HS modes).

Legend: AN = Analog input or output CMOS= CMOS compatible input or output OD = Open-Drain
TTL = TTL compatible input ST = Schmitt Trigger input with CMOS levels I^2C = Schmitt Trigger input with I^2C
HV = High Voltage XTAL = Crystal levels

Note 1: Default peripheral input. Input can be moved to any other pin with the PPS input selection registers. See Register 13-2.

2: All pin outputs default to PORT latch data. Any pin can be selected as a digital peripheral output with the PPS output selection registers. See Register 13-2.

3: These I^2C functions are bidirectional. The output pin selections must be the same as the input pin selections.

TABLE 4-4: SPECIAL FUNCTION REGISTER SUMMARY BANKS 0-31

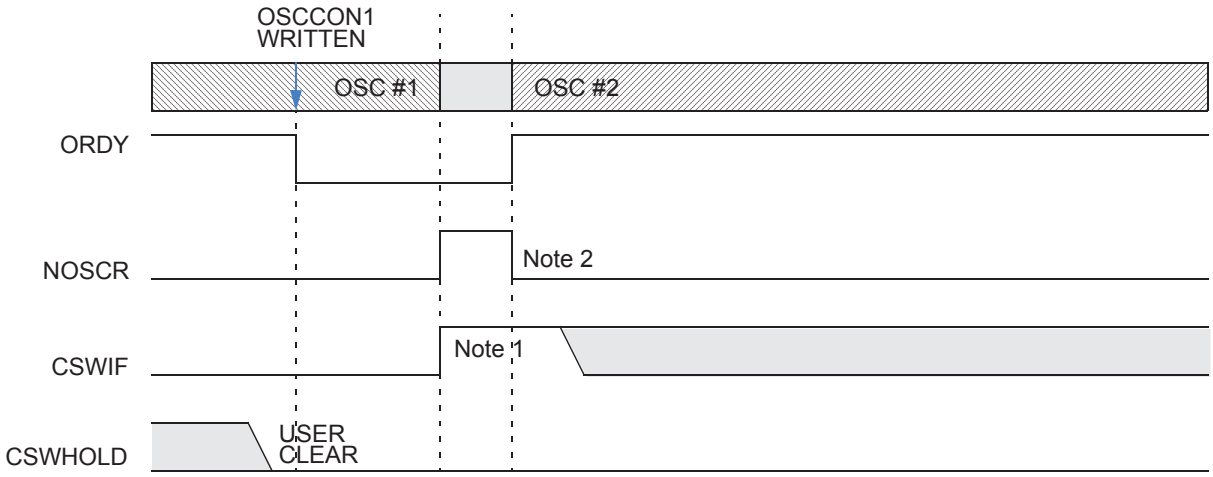
Address	Name	PIC16(L)F18326	PIC16(L)F18346	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on: POR, BOR	Value on all other Resets
Bank 0													
CPU CORE REGISTERS; see Table 4-2 for specifics													
00Ch	PORTA			—	—	RA5	RA4	RA3	RA2	RA1	RA0	--xx xxxx	--uu uuuu
00Dh	PORTB	X	—	Unimplemented								—	—
		—	X	RB7	RB6	RB5	RB4	—	—	—	—	xxxx ----	uuuu ----
00Eh	PORTC	X	—	—	—	RC5	RC4	RC3	RC2	RC1	RC0	--xx xxxx	--uu uuuu
		—	X	RC7	RC6	RC5	RC4	RC3	RC2	RC1	RC0	xxxx xxxx	uuuu uuuu
00Fh	—	—		Unimplemented								—	—
010h	PIR0			—	—	TMR0IF	IOCIF	—	—	—	INTF	--00 ---0	--00 ---0
011h	PIR1			TMR1GIF	ADIF	RCIF	TXIF	SSP1IF	BCL1IF	TMR2IF	TMR1IF	0000 0000	0000 0000
012h	PIR2			TMR6IF	C2IF	C1IF	NVMIF	SSP2IF	BCL2IF	TMR4IF	NCO1IF	0000 0000	0000 0000
013h	PIR3			OSFIF	CSWIF	TMR3GIF	TMR3IF	CLC4IF	CLC3IF	CLC2IF	CLC1IF	0000 0000	0000 0000
014h	PIR4			CWG2IF	CWG1IF	TMR5GIF	TMR5IF	CCP4IF	CCP3IF	CCP2IF	CCP1IF	0000 0000	0000 0000
015h	TMR0L			TMR0L<7:0>								xxxx xxxx	xxxx xxxx
016h	TMR0H			TMR0H<7:0>								1111 1111	1111 1111
017h	T0CON0			T0EN	—	T0OUT	T016BIT	T0OUTPS<3:0>				0-00 0000	0-00 0000
018h	T0CON1			T0CS<2:0>			T0ASYNC	T0CKPS<3:0>				0000 0000	0000 0000
019h	TMR1L			TMR1L<7:0>								xxxx xxxx	uuuu uuuu
01Ah	TMR1H			TMR1H<7:0>								xxxx xxxx	uuuu uuuu
01Bh	T1CON			TMR1CS<1:0>		T1CKPS<1:0>		T1SOSC	$\overline{\text{T1SYNC}}$	—	TMR1ON	0000 00-0	uuuu uu-u
01Ch	T1GCON			TMR1GE	T1GPOL	T1GTM	T1GSPM	T1GGO/$\overline{\text{DONE}}$	T1GVAL	T1GSS<1:0>		0000 0x00	uuuu uxuu
01Dh	TMR2			TMR2<7:0>								0000 0000	0000 0000
01Eh	PR2			PR2<7:0>								1111 1111	1111 1111
01Fh	T2CON			—	T2OUTPS<3:0>				TMR2ON	T2CKPS<1:0>		-000 0000	-000 0000

Legend: x = unknown, u = unchanged, q = depends on condition, - = unimplemented, read as '0', r = reserved. Shaded locations unimplemented, read as '0'.

Note 1: Only on PIC16F18326/18346.

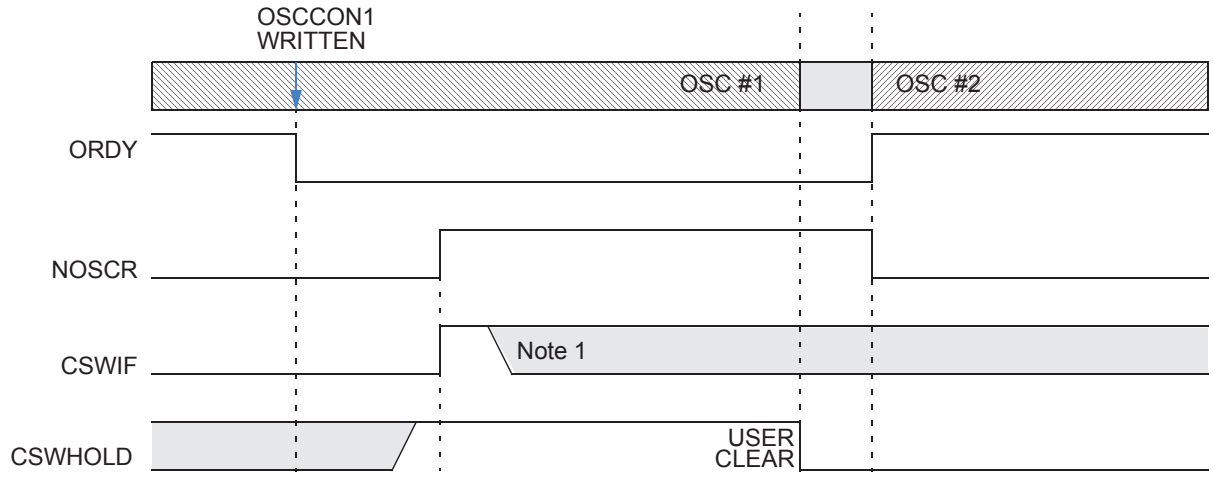
2: Register accessible from both User and ICD Debugger.

FIGURE 7-6: CLOCK SWITCH (CSWHOLD = 0)



Note 1: CSWIF is asserted coincident with NOSCR; interrupt is serviced at OSC#2 speed.
2: The assertion of NOSCR is hidden from the user because it appears only for the duration of the switch.

FIGURE 7-7: CLOCK SWITCH (CSWHOLD = 1)



Note 1: CSWIF is asserted coincident with NOSCR, and may be cleared before or after clearing CSWHOLD = 0.

8.6 Register Definitions: Interrupt Control

REGISTER 8-1: INTCON: INTERRUPT CONTROL REGISTER

R/W/HS/HC	R/W-0/0	U-0	U-0	U-0	U-0	U-0	R-1/1
GIE	PEIE	—	—	—	—	—	INTEDG
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets	
'1' = Bit is set	'0' = Bit is cleared	HS = Hardware set	HC = Hardware clear

bit 7 **GIE:** Global Interrupt Enable bit
1 = Enables all active interrupts
0 = Disables all interrupts

bit 6 **PEIE:** Peripheral Interrupt Enable bit
1 = Enables all active peripheral interrupts
0 = Disables all peripheral interrupts

bit 5-1 **Unimplemented:** Read as '0'

bit 0 **INTEDG:** Interrupt Edge Select bit
1 = Interrupt on rising edge of INT pin
0 = Interrupt on falling edge of INT pin

Note: Interrupt flag bits are set when an interrupt condition occurs, regardless of the state of its corresponding enable bit or the Global Enable bit, GIE, of the INTCON register. User software should ensure the appropriate interrupt flag bits are clear prior to enabling an interrupt.

REGISTER 8-4: PIE2: PERIPHERAL INTERRUPT ENABLE REGISTER 2

R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
TMR6IE	C2IE	C1IE	NVMIE	SSP2IE	BCL2IE	TMR4IE	NCO1IE
bit 7							bit 0

Legend:		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7 **TMR6IE:** TMR6 to PR6 Match Interrupt Enable bit
1 = TMR6 to PR6 match interrupt is enabled
0 = TMR6 to PR6 match is not enabled

bit 6 **C2IE:** Comparator C2 Interrupt Enable bit
1 = Enables the Comparator C2 interrupt
0 = Disables the Comparator C2 interrupt

bit 5 **C1IE:** Comparator C1 Interrupt Enable bit
1 = Enables the Comparator C1 interrupt
0 = Disables the Comparator C1 interrupt

bit 4 **NVMIE:** NVM Interrupt Enable Bit
1 = ENVM task complete interrupt enabled
0 = NVM interrupt not enabled

bit 3 **SSP2IE:** Master Synchronous Serial Port (MSSP2) Interrupt Enable bit
1 = Enables the MSSP2 interrupt
0 = Disables the MSSP2 interrupt

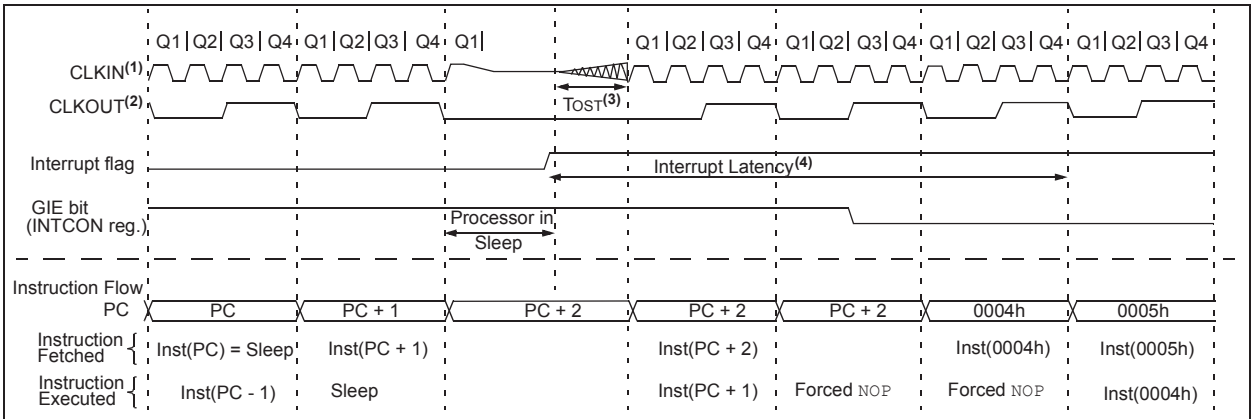
bit 2 **BCL2IE:** MSSP2 Bus Collision Interrupt Enable bit
1 = MSSP bus collision interrupt enabled
0 = MSSP bus collision interrupt not enabled

bit 1 **TMR4IE:** TMR4 to PR4 Match Interrupt Enable bit
1 = TMR4 to PR4 match interrupt is enabled
0 = TMR4 to PR4 match is not enabled

bit 0 **NCO1IE:** NCO Interrupt Enable bit
1 = NCO rollover interrupt enabled
0 = NCO rollover interrupt not enabled

Note: Bit PEIE of the INTCON register must be set to enable any peripheral interrupt.

FIGURE 9-2: WAKE-UP FROM SLEEP THROUGH INTERRUPT



Note 1: External clock. High, Medium, Low mode assumed.
2: CLKOUT is shown here for timing reference.
3: TOST = 1024 TOSC. This delay does not apply to EC and INTOSC Oscillator modes.
4: GIE = 1 assumed. In this case after wake-up, the processor calls the ISR at 0004h. If GIE = 0, execution will continue in-line.

TABLE 10-3: SUMMARY OF REGISTERS ASSOCIATED WITH WATCHDOG TIMER

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register on Page
STATUS	—	—	—	$\overline{TO}$	$\overline{PD}$	Z	DC	C	30
WDTCON	—	—	WDTPS<4:0>					SWDTEN	121

Legend: x = unknown, u = unchanged, – = unimplemented locations read as '0'. Shaded cells are not used by Watchdog Timer.

TABLE 10-4: SUMMARY OF CONFIGURATION WORD WITH WATCHDOG TIMER

Name	Bits	Bit -/7	Bit -/6	Bit 13/5	Bit 12/4	Bit 11/3	Bit 10/2	Bit 9/1	Bit 8/0	Register on Page
CONFIG2	13:8	—	—	$\overline{DEBUG}$	STVREN	PPS1WAY	—	BORV	—	65
	7:0	BOREN1	BOREN0	$\overline{LPBOREN}$	—	WDTE1	WDTE0	$\overline{PWRTE}$	MCLRE	

Legend: — = unimplemented location, read as '0'. Shaded cells are not used by Watchdog Timer.

TABLE 12-2: SUMMARY OF REGISTERS ASSOCIATED WITH PORTA

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register on Page
PORTA	—	—	RA5	RA4	RA3	RA2	RA1	RA0	143
TRISA	—	—	TRISA5	TRISA4	—	TRISA2	TRISA1	TRISA0	143
LATA	—	—	LATA5	LATA4	—	LATA2	LATA1	LATA0	144
ANSELA	—	—	ANSA5	ANSA4	—	ANSA2	ANSA1	ANSA0	144
WPUA	—	—	WPUA5	WPUA4	WPUA3	WPUA2	WPUA1	WPUA0	145
ODCONA	—	—	ODCA5	ODCA4	—	ODCA2	ODCA1	ODCA0	145
SLRCONA	—	—	SLRA5	SLRA4	—	SLRA2	SLRA1	SLRA0	146
INLVLA	—	—	INLVLA5	INLVLA4	INLVLA3	INLVLA2	INLVLA1	INLVLA0	146

Legend: – = unimplemented locations read as '0'. Shaded cells are not used by PORTA.

TABLE 12-3: SUMMARY OF CONFIGURATION WORD WITH PORTA

Name	Bits	Bit -/7	Bit -/6	Bit 13/5	Bit 12/4	Bit 11/3	Bit 10/2	Bit 9/1	Bit 8/0	Register on Page
CONFIG2	13:8	—	—	$\overline{\text{DEBUG}}$	STVREN	PPS1WAY	—	BORV	—	65
	7:0	BOREN1	BOREN0	$\overline{\text{LPBOREN}}$	—	WDTE1	WDTE0	$\overline{\text{PWRTE}}$	MCLRE	

Legend: — = unimplemented location, read as '0'. Shaded cells are not used by PORTA.

REGISTER 14-6: PMD5: PMD CONTROL REGISTER 5

U-0	U-0	U-0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
—	—	—	CLC4MD	CLC3MD	CLC2MD	CLC1MD	DSMMD
bit 7							bit 0

Legend:		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	q = Value depends on condition

bit 7-5 **Unimplemented:** Read as '0'

bit 4 **CLC4MD:** Disable CLC4 bit
1 = CLC4 module disabled
0 = CLC4 module enabled

bit 3 **CLC3MD:** Disable CLC3 bit
1 = CLC3 module disabled
0 = CLC3 module enabled

bit 2 **CLC2MD:** Disable CLC2 bit
1 = CLC2 module disabled
0 = CLC2 module enabled

bit 1 **CLC1MD:** Disable CLC1 bit
1 = CLC1 module disabled
0 = CLC1 module enabled

bit 0 **DSMMD:** Disable Data Signal Modulator bit
1 = DSM module disabled
0 = DSM module enabled

15.6 Register Definitions: Interrupt-on-Change Control

REGISTER 15-1: IOCAP: INTERRUPT-ON-CHANGE PORTA POSITIVE EDGE REGISTER

U-0	U-0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
—	—	IOCAP5	IOCAP4	IOCAP3	IOCAP2	IOCAP1	IOCAP0
bit 7							bit 0

Legend:		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7-6 **Unimplemented:** Read as '0'

bit 5-0 **IOCAP<5:0>:** Interrupt-on-Change PORTA Positive Edge Enable bits
1 = Interrupt-on-Change enabled on the pin for a positive going edge. IOCAFx bit and IOCIF flag will be set upon detecting an edge.
0 = Interrupt-on-change disabled for the associated pin

REGISTER 15-2: IOCAN: INTERRUPT-ON-CHANGE PORTA NEGATIVE EDGE REGISTER

U-0	U-0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
—	—	IOCAN5	IOCAN4	IOCAN3	IOCAN2	IOCAN1	IOCAN0
bit 7							bit 0

Legend:		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7-6 **Unimplemented:** Read as '0'

bit 5-0 **IOCAN<5:0>:** Interrupt-on-Change PORTA Negative Edge Enable bits
1 = Interrupt-on-Change enabled on the pin for a negative going edge. IOCAFx bit and IOCIF flag will be set upon detecting an edge.
0 = Interrupt-on-Change disabled for the associated pin

REGISTER 18-3: CMOUT: COMPARATOR OUTPUT REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	R-0/0	R-0/0
—	—	—	—	—	—	MC2OUT	MC1OUT
bit 7							bit 0

Legend:		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7-2 **Unimplemented:** Read as '0'

bit 1 **MC2OUT:** Mirror Copy of C2OUT bit

bit 0 **MC1OUT:** Mirror Copy of C1OUT bit

TABLE 18-3: SUMMARY OF REGISTERS ASSOCIATED WITH COMPARATOR MODULE

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register on Page
ANSELA	—	—	ANSA5	ANSA4	—	ANSA2	ANSA1	ANSA0	144
ANSELB(1)	ANSB7	ANSB6	ANSB5	ANSB4	—	—	—	—	150
ANSELC	ANSC7(1)	ANSC6(1)	ANSC5	ANSC4	ANSC3	ANSC2	ANSC1	ANSC0	157
TRISA	—	—	TRISA5	TRISA4	—	TRISA2	TRISA1	TRISA0	143
TRISB(1)	TRISB7	TRISB6	TRISB5	TRISB4	—	—	—	—	149
TRISC	TRISC7(1)	TRISC6(1)	TRISC5	TRISC4	TRISC3	TRISC2	TRISC1	TRISC0	155
CMxCON0	CxON	CxOUT	—	CxPOL	—	CxSP	CxHYS	CxSYNC	190
CMxCON1	CxINTP	CxINTN	CxPCH<2:0>			CxNCH<2:0>			191
CMOUT	—	—	—	—	—	—	MC2OUT	MC1OUT	192
FVRCON	FVREN	FVRRDY	TSEN	TSRNG	CDAFVR<1:0>		ADFVR<1:0>		180
DACCON0	DAC1EN	—	DAC1OE	—	DAC1PSS<1:0>		—	DAC1NSS	263
DACCON1	—	—	—	DAC1R<4:0>					264
INTCON	GIE	PEIE	—	—	—	—	—	INTEDG	100
PIE2	TMR6IE	C2IE	C1IE	NVMIE	SSP2IE	BLC2IE	TMR4IE	NCO1IE	103
PIR2	TMR6IF	C2IF	C1IF	NVMIF	SSP2IF	BLC2IF	TMR4IF	NCO1IF	108
CLCINxPPS	—	—	—	CLCINxPPS<4:0>					162
MDMINPPS	—	—	—	MDMINPPS<4:0>					162
T1GPPS	—	—	—	T1GPPS<4:0>					162
CWGxAS1	—	—	—	AS4E	AS3E	AS2E	AS1E	AS0E	218

Legend: — = unimplemented location, read as '0'. Shaded cells are unused by the comparator module.
Note 1: PIC16(L)F18346 only.

REGISTER 20-2: CWGxCON1: CWGx CONTROL REGISTER 1

U-0	U-0	R-x	U-0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
—	—	IN	—	POLD	POLC	POLB	POLA
bit 7							bit 0

Legend:		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	q = Value depends on condition

bit 7-6 **Unimplemented:** Read as '0'

bit 5 **IN:** CWGx Data Input Signal (read-only)

bit 4 **Unimplemented:** Read as '0'

bit 3 **POLD:** WGxD Output Polarity bit
1 = Signal output is inverted polarity
0 = Signal output is normal polarity

bit 2 **POLC:** WGxC Output Polarity bit
1 = Signal output is inverted polarity
0 = Signal output is normal polarity

bit 1 **POLB:** WGxB Output Polarity bit
1 = Signal output is inverted polarity
0 = Signal output is normal polarity

bit 0 **POLA:** WGxA Output Polarity bit
1 = Signal output is inverted polarity
0 = Signal output is normal polarity

REGISTER 20-3: CWGxCLKCON: CWGx CLOCK INPUT SELECTION REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	R/W-0/0
—	—	—	—	—	—	—	CS
bit 7							bit 0

Legend:		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	q = Value depends on condition

bit 7-1 **Unimplemented:** Read as '0'

bit 0 **CS:** CWG Clock Source Selection Select bits

WGCLK	Clock Source
0	FOSC
1	HFINTOSC (remains operating during Sleep)

REGISTER 27-3: TMRxL(1): TIMERx LOW BYTE REGISTER

R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u
TMRxL<7:0>							
bit 7							bit 0

Legend:		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7-0 **TMRxL<7:0>:** TMRx Low Byte bits

Note 1: 'x' refers to either '1', '3' or '5' for the respective Timer1/3/5 registers.

REGISTER 27-4: TMRxH(1): TIMERx HIGH BYTE REGISTER

R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u
TMRxH<7:0>							
bit 7							bit 0

Legend:		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7-0 **TMRxH<7:0>:** TMRx High Byte bits

Note 1: 'x' refers to either '1', '3' or '5' for the respective Timer1/3/5 registers.

30.2.4 SPI SLAVE MODE

In Slave mode, the data is transmitted and received as external clock pulses appear on SCK. When the last bit is latched, the SSPxIF interrupt flag bit is set.

Before enabling the module in SPI Slave mode, the clock line must match the proper Idle state. The clock line can be observed by reading the SCK pin. The Idle state is determined by the CKP bit of the SSPxCON1 register.

While in Slave mode, the external clock is supplied by the external clock source on the SCK pin. This external clock must meet the minimum high and low times as specified in the electrical specifications.

While in Sleep mode, the slave can transmit/receive data. The shift register is clocked from the SCK pin input and when a byte is received, the device will generate an interrupt. If enabled, the device will wake-up from Sleep.

30.2.4.1 Daisy-Chain Configuration

The SPI bus can sometimes be connected in a daisy-chain configuration. The first slave output is connected to the second slave input, the second slave output is connected to the third slave input, and so on. The final slave output is connected to the master input. Each slave sends out, during a second group of clock pulses, an exact copy of what was received during the first group of clock pulses. The whole chain acts as one large communication shift register. The daisy-chain feature only requires a single Slave Select line from the master device.

Figure 30-7 shows the block diagram of a typical daisy-chain connection when operating in SPI mode.

In a daisy-chain configuration, only the most recent byte on the bus is required by the slave. Setting the BOEN bit of the SSPxCON3 register will enable writes to the SSPxBUF register, even if the previous byte has not been read. This allows the software to ignore data that may not apply to it.

30.2.5 SLAVE SELECT SYNCHRONIZATION

The Slave Select can also be used to synchronize communication. The Slave Select line is held high until the master device is ready to communicate. When the Slave Select line is pulled low, the slave knows that a new transmission is starting.

If the slave fails to receive the communication properly, it will be reset at the end of the transmission, when the Slave Select line returns to a high state. The slave is then ready to receive a new transmission when the Slave Select line is pulled low again. If the Slave Select line is not used, there is a risk that the slave will eventually become out of sync with the master. If the slave misses a bit, it will always be one bit off in future transmissions. Use of the Slave Select line allows the slave and master to align themselves at the beginning of each transmission.

The $\overline{SS}$ pin allows a Synchronous Slave mode. The SPI must be in Slave mode with $\overline{SS}$ pin control enabled (SSPxCON1<3:0> = 0100).

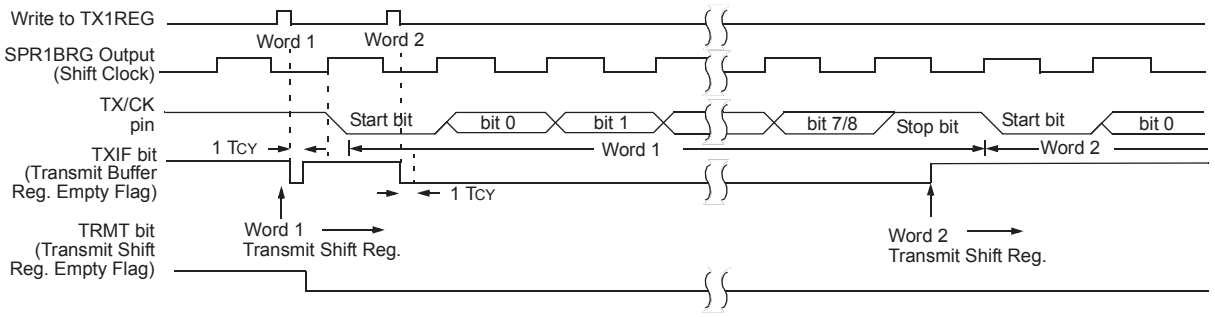
When the $\overline{SS}$ pin is low, transmission and reception are enabled and the SDO pin is driven.

When the $\overline{SS}$ pin goes high, the SDO pin is no longer driven, even if in the middle of a transmitted byte and becomes a floating output. External pull-up/pull-down resistors may be desirable depending on the application.

Note 1:	When the SPI is in Slave mode with $\overline{SS}$ pin control enabled (SSPxCON1<3:0> = 0100), the SPI module will reset if the $\overline{SS}$ pin is set to VDD.
2:	When the SPI is used in Slave mode with CKE set; the user must enable $\overline{SS}$ pin control.
3:	While operated in SPI Slave mode the SMP bit of the SSPxSTAT register must remain clear.

When the SPI module resets, the bit counter is forced to '0'. This can be done by either forcing the $\overline{SS}$ pin to a high level or clearing the SSPEN bit.

FIGURE 31-4: ASYNCHRONOUS TRANSMISSION (BACK-TO-BACK)



Note: This timing diagram shows two consecutive transmissions.

31.1.2 EUSART1 ASYNCHRONOUS RECEIVER

The Asynchronous mode is typically used in RS-232 systems. The receiver block diagram is shown in Figure 31-2. The data is received on the RX/DT pin and drives the data recovery block. The data recovery block is actually a high-speed shifter operating at 16 times the baud rate, whereas the serial Receive Shift Register (RSR) operates at the bit rate. When all eight or nine bits of the character have been shifted in, they are immediately transferred to a two character First-In-First-Out (FIFO) memory. The FIFO buffering allows reception of two complete characters and the start of a third character before software must start servicing the EUSART1 receiver. The FIFO and RSR registers are not directly accessible by software. Access to the received data is via the RC1REG register.

31.1.2.1 Enabling the Receiver

The EUSART1 receiver is enabled for asynchronous operation by configuring the following three control bits:

- CREN = 1
- SYNC = 0
- SPEN = 1

All other EUSART1 control bits are assumed to be in their default state.

Setting the CREN bit of the RC1STA register enables the receiver circuitry of the EUSART1. Clearing the SYNC bit of the TX1STA register configures the EUSART1 for asynchronous operation. Setting the SPEN bit of the RC1STA register enables the EUSART1. The programmer must set the corresponding TRIS bit to configure the RX/DT I/O pin as an input.

Note:	If the RX/DT function is on an analog pin, the corresponding ANSEL bit must be cleared for the receiver to function.

31.1.2.2 Receiving Data

The receiver data recovery circuit initiates character reception on the falling edge of the first bit. The first bit, also known as the Start bit, is always a zero. The data recovery circuit counts one-half bit time to the center of the Start bit and verifies that the bit is still a zero. If it is not a zero then the data recovery circuit aborts character reception, without generating an error, and resumes looking for the falling edge of the Start bit. If the Start bit zero verification succeeds then the data recovery circuit counts a full bit time to the center of the next bit. The bit is then sampled by a majority detect circuit and the resulting '0' or '1' is shifted into the RSR. This repeats until all data bits have been sampled and shifted into the RSR. One final bit time is measured and the level sampled. This is the Stop bit, which is always a '1'. If the data recovery circuit samples a '0' in the Stop bit position then a framing error is set for this character, otherwise the framing error is cleared for this character. See **Section 31.1.2.4 "Receive Framing Error"** for more information on framing errors.

Immediately after all data bits and the Stop bit have been received, the character in the RSR is transferred to the EUSART1 receive FIFO and the RCIF interrupt flag bit of the PIR1 register is set. The top character in the FIFO is transferred out of the FIFO by reading the RC1REG register.

Note:	If the receive FIFO is overrun, no additional characters will be received until the Overrun condition is cleared. See **Section 31.1.2.5 "Receive Overrun Error"** for more information on overrun errors.

31.4.2 SYNCHRONOUS SLAVE MODE

The following bits are used to configure the EUSART1 for synchronous slave operation:

- SYNC = 1
- CSRC = 0
- SREN = 0 (for transmit); SREN = 1 (for receive)
- CREN = 0 (for transmit); CREN = 1 (for receive)
- SPEN = 1

Setting the SYNC bit of the TX1STA register configures the device for synchronous operation. Clearing the CSRC bit of the TX1STA register configures the device as a slave. Clearing the SREN and CREN bits of the RC1STA register ensures that the device is in the Transmit mode, otherwise the device will be configured to receive. Setting the SPEN bit of the RC1STA register enables the EUSART1.

31.4.2.1 EUSART1 Synchronous Slave Transmit

The operation of the Synchronous Master and Slave modes are identical (see **Section 31.4.1.3 "Synchronous Master Transmission"**), except in the case of the Sleep mode.

If two words are written to the TX1REG and then the SLEEP instruction is executed, the following will occur:

1. The first character will immediately transfer to the TSR register and transmit.
2. The second word will remain in the TX1REG register.
3. The TXIF bit will not be set.
4. After the first character has been shifted out of TSR, the TX1REG register will transfer the second character to the TSR and the TXIF bit will now be set.
5. If the PEIE and TXIE bits are set, the interrupt will wake the device from Sleep and execute the next instruction. If the GIE bit is also set, the program will call the Interrupt Service Routine.

31.4.2.2 Synchronous Slave Transmission Setup

1. Set the SYNC and SPEN bits and clear the CSRC bit.
2. Clear the ANSEL bit for the CK pin (if applicable).
3. Clear the CREN and SREN bits.
4. If interrupts are desired, set the TXIE bit of the PIE1 register and the GIE and PEIE bits of the INTCON register.
5. If 9-bit transmission is desired, set the TX9 bit.
6. Enable transmission by setting the TXEN bit.
7. If 9-bit transmission is selected, insert the Most Significant bit into the TX9D bit.
8. Start transmission by writing the Least Significant eight bits to the TX1REG register.

31.4.2.3 EUSART1 Synchronous Slave Reception

The operation of the Synchronous Master and Slave modes is identical (**Section 31.4.1.5 "Synchronous Master Reception"**), with the following exceptions:

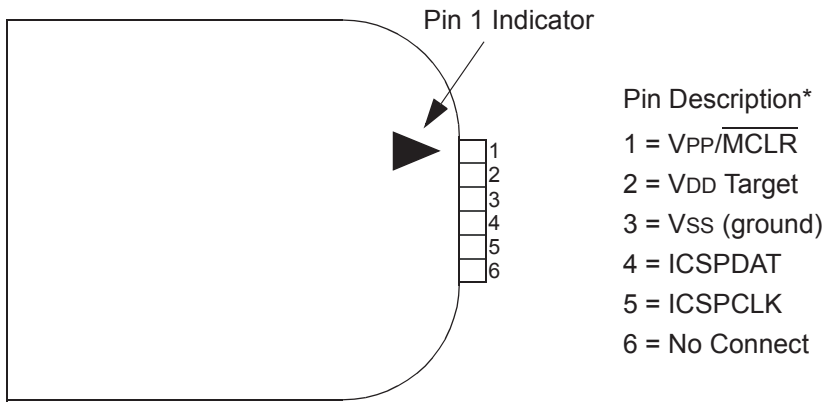
- Sleep
- CREN bit is always set, therefore the receiver is never idle
- SREN bit, which is a "don't care" in Slave mode

A character may be received while in Sleep mode by setting the CREN bit prior to entering Sleep. Once the word is received, the RSR register will transfer the data to the RC1REG register. If the RCIE enable bit is set, the interrupt generated will wake the device from Sleep and execute the next instruction. If the GIE bit is also set, the program will branch to the interrupt vector.

31.4.2.4 Synchronous Slave Reception Setup

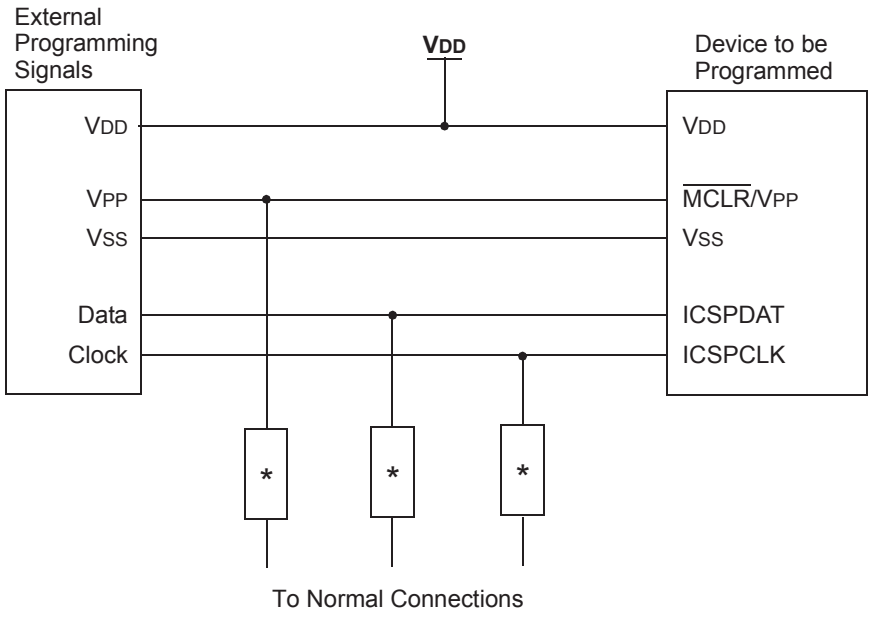
1. Set the SYNC and SPEN bits and clear the CSRC bit.
2. Clear the ANSEL bit for both the CK and DT pins (if applicable).
3. If interrupts are desired, set the RCIE bit of the PIE1 register and the GIE and PEIE bits of the INTCON register.
4. If 9-bit reception is desired, set the RX9 bit.
5. Set the CREN bit to enable reception.
6. The RCIF bit will be set when reception is complete. An interrupt will be generated if the RCIE bit was set.
7. If 9-bit mode is enabled, retrieve the Most Significant bit from the RX9D bit of the RC1STA register.
8. Retrieve the eight Least Significant bits from the receive FIFO by reading the RC1REG register.
9. If an overrun error occurs, clear the error by either clearing the CREN bit of the RC1STA register or by clearing the SPEN bit which resets the EUSART1.

FIGURE 33-2: PICkit™ PROGRAMMER STYLE CONNECTOR INTERFACE



* The 6-pin header (0.100" spacing) accepts 0.025" square pins.

FIGURE 33-3: TYPICAL CONNECTION FOR ICSP™ PROGRAMMING



* Isolation devices (as required).

34.2 Instruction Descriptions

ADDFSR — Add Literal to FSRn

Syntax:	[*label*] ADDFSR FSRn, k
Operands:	-32 ≤ k ≤ 31 n ∈ [0, 1]
Operation:	FSR(n) + k → FSR(n)
Status Affected:	None
Description:	The signed 6-bit literal 'k' is added to the contents of the FSRnH:FSRnL register pair. FSRn is limited to the range 0000h-FFFFh. Moving beyond these bounds will cause the FSR to wrap-around.

ADDLW — Add literal and W

Syntax:	[*label*] ADDLW k
Operands:	0 ≤ k ≤ 255
Operation:	(W) + k → (W)
Status Affected:	C, DC, Z
Description:	The contents of the W register are added to the 8-bit literal 'k' and the result is placed in the W register.

ADDWF — Add W and f

Syntax:	[*label*] ADDWF f,d
Operands:	0 ≤ f ≤ 127 d ∈ [0,1]
Operation:	(W) + (f) → (destination)
Status Affected:	C, DC, Z
Description:	Add the contents of the W register with register 'f'. If 'd' is '0', the result is stored in the W register. If 'd' is '1', the result is stored back in register 'f'.

ADDWFC — ADD W and CARRY bit to f

Syntax:	[*label*] ADDWFC f {,d}
Operands:	0 ≤ f ≤ 127 d ∈ [0,1]
Operation:	(W) + (f) + (C) → dest
Status Affected:	C, DC, Z
Description:	Add W, the Carry flag and data memory location 'f'. If 'd' is '0', the result is placed in W. If 'd' is '1', the result is placed in data memory location 'f'.

ANDLW — AND literal with W

Syntax:	[*label*] ANDLW k
Operands:	0 ≤ k ≤ 255
Operation:	(W) .AND. (k) → (W)
Status Affected:	Z
Description:	The contents of W register are AND'ed with the 8-bit literal 'k'. The result is placed in the W register.

ANDWF — AND W with f

Syntax:	[*label*] ANDWF f,d
Operands:	0 ≤ f ≤ 127 d ∈ [0,1]
Operation:	(W) .AND. (f) → (destination)
Status Affected:	Z
Description:	AND the W register with register 'f'. If 'd' is '0', the result is stored in the W register. If 'd' is '1', the result is stored back in register 'f'.

ASRF — Arithmetic Right Shift

Syntax:	[*label*] ASRF f {,d}
Operands:	0 ≤ f ≤ 127 d ∈ [0,1]
Operation:	(f<7>)→ dest<7> (f<7:1>) → dest<6:0>, (f<0>) → C,
Status Affected:	C, Z
Description:	The contents of register 'f' are shifted one bit to the right through the Carry flag. The MSb remains unchanged. If 'd' is '0', the result is placed in W. If 'd' is '1', the result is stored back in register 'f'.

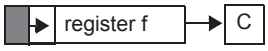


TABLE 35-3: POWER-DOWN CURRENTS (I_{PD})(1,2,3)

PIC16LF18326/18346			Standard Operating Conditions (unless otherwise stated)						
PIC16F18326/18346			Standard Operating Conditions (unless otherwise stated) VREGPM = 1						
Param. No.	Symbol	Device Characteristics	Min.	Typ.†	Max. +85°C	Max. +125°C	Units	Conditions	
								V_{DD}	Note
D200	I_{PD}	I_{PD} Base	—	0.05	2	9	µA	3.0V	
D200	I_{PD}	I_{PD} Base	—	0.8	4	12	µA	3.0V	
			—	13	22	27	µA	3.0V	VREGPM = 0
D201	I_{PD_WDT}	Low-Frequency Internal Oscillator/WDT	—	0.8	5	13	µA	3.0V	
D201	I_{PD_WDT}	Low-Frequency Internal Oscillator/WDT	—	0.9	5	13	µA	3.0V	
D202	I_{PD_SOSC}	Secondary Oscillator (SOSC)	—	0.6	5	13	µA	3.0V	
D202	I_{PD_SOSC}	Secondary Oscillator (SOSC)	—	0.8	9	15	µA	3.0V	
D203	I_{PD_FVR}	FVR	—	40	47	47	µA	3.0V	
D203	I_{PD_FVR}	FVR	—	33	44	44	µA	3.0V	
D204	I_{PD_BOR}	Brown-out Reset (BOR)	—	12	17	19	µA	3.0V	
D204	I_{PD_BOR}	Brown-out Reset (BOR)	—	12	18	20	µA	3.0V	
D205	I_{PD_LPBOR}	Low Power Brown-out Reset (LPBOR)	—	3	5	13	µA	3.0V	
D205	I_{PD_LPBOR}	Low Power Brown-out Reset (LPBOR)	—	4	5	13	µA	3.0V	
D207	I_{PD_ADCA}	ADC - Active	—	0.9	5	13	µA	3.0V	ADC is converting(4)
D207	I_{PD_ADCA}	ADC - Active	—	0.9	5	13	µA	3.0V	ADC is converting(4)
D208	I_{PD_CMP}	Comparator	—	32	43	45	µA	3.0V	
D208	I_{PD_CMP}	Comparator	—	31	42	44	µA	3.0V	

* These parameters are characterized but not tested.

† Data in "Typ." column is at 3.0V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

Note 1: The peripheral current is the sum of the base I_{PD} and the additional current consumed when this peripheral is enabled. The peripheral Δ current can be determined by subtracting the base I_{DD} or I_{PD} current from this limit. Max values should be used when calculating total current consumption.

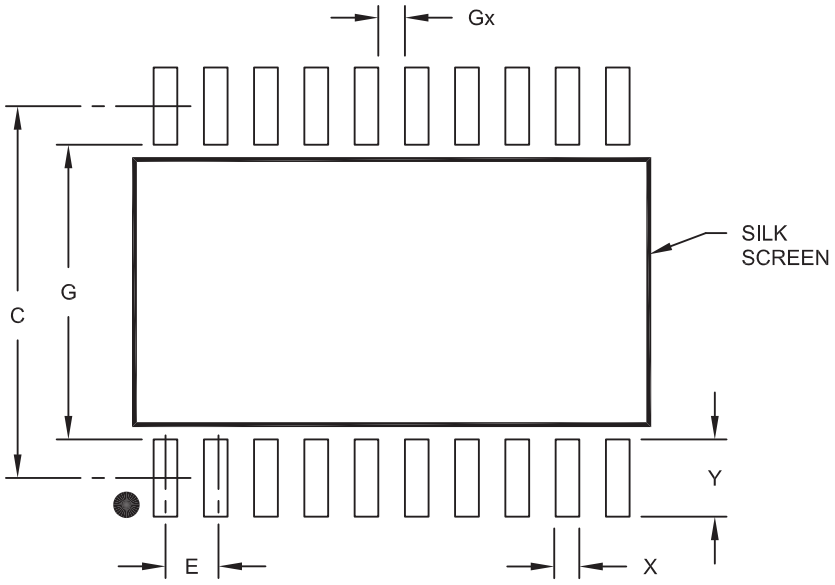
2: The power-down current in Sleep mode does not depend on the oscillator type. Power-down current is measured with the part in Sleep mode, with all I/O pins in high-impedance state and tied to V_{SS}.

3: All peripheral currents listed are on a per-peripheral basis if more than one instance of a peripheral is available.

4: ADC clock source is ADCRC.

20-Lead Plastic Small Outline (SO) - Wide, 7.50 mm Body [SOIC]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



RECOMMENDED LAND PATTERN

Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Contact Pitch	E		1.27 BSC	
Contact Pad Spacing	C		9.40	
Contact Pad Width (X20)	X			0.60
Contact Pad Length (X20)	Y			1.95
Distance Between Pads	Gx	0.67		
Distance Between Pads	G	7.45		

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2094A