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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Obsolete
Core Processor	STM8A
Core Size	8-Bit
Speed	16MHz
Connectivity	I ² C, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	38
Program Memory Size	16KB (16K x 8)
Program Memory Type	FLASH
EEPROM Size	512 x 8
RAM Size	2K x 8
Voltage - Supply (Vcc/Vdd)	3V ~ 5.5V
Data Converters	A/D 10x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	48-LQFP
Supplier Device Package	48-LQFP (7x7)
Purchase URL	https://www.e-xfl.com/product-detail/stmicroelectronics/stm8af6248tcx

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5 Product overview

This section describes the family features that are implemented in the products covered by this datasheet.

For more detailed information on each feature please refer to STM8S series and STM8AF series 8-bit microcontrollers reference manual (RM0016).

5.1 STM8A central processing unit (CPU)

The 8-bit STM8A core is a modern CISC core and has been designed for code efficiency and performance. It contains 21 internal registers (six directly addressable in each execution context), 20 addressing modes including indexed indirect and relative addressing and 80 instructions.

5.1.1 Architecture and registers

- Harvard architecture
- 3-stage pipeline
- 32-bit wide program memory bus with single cycle fetching for most instructions
- X and Y 16-bit index registers, enabling indexed addressing modes with or without offset and read-modify-write type data manipulations
- 8-bit accumulator
- 24-bit program counter with 16-Mbyte linear memory space
- 16-bit stack pointer with access to a 64 Kbyte stack
- 8-bit condition code register with seven condition flags for the result of the last instruction.

5.1.2 Addressing

- 20 addressing modes
- Indexed indirect addressing mode for look-up tables located anywhere in the address space
- Stack pointer relative addressing mode for efficient implementation of local variables and parameter passing

5.1.3 Instruction set

- 80 instructions with 2-byte average instruction size
- Standard data movement and logic/arithmetic functions
- 8-bit by 8-bit multiplication
- 16-bit by 8-bit and 16-bit by 16-bit division
- Bit manipulation
- Data transfer between stack and accumulator (push/pop) with direct stack access
- Data transfer using the X and Y registers or direct memory-to-memory transfers

5.4.4 Read-out protection (ROP)

The STM8A provides a read-out protection of the code and data memory which can be activated by an option byte setting (see the ROP option byte in section 10).

The read-out protection prevents reading and writing Flash program memory, data memory and option bytes via the debug module and SWIM interface. This protection is active in all device operation modes. Any attempt to remove the protection by overwriting the ROP option byte triggers a global erase of the program and data memory.

The ROP circuit may provide a temporary access for debugging or failure analysis. The temporary read access is protected by a user defined, 8-byte keyword stored in the option bytes area. This keyword must be entered via the SWIM interface to temporarily unlock the device.

If desired, the temporary unlock mechanism can be permanently disabled by the user through OPT6/NOPT6 option bytes.

5.5 Clock controller

The clock controller distributes the system clock coming from different oscillators to the core and the peripherals. It also manages clock gating for low-power modes and ensures clock robustness.

5.5.1 Features

- **Clock sources**
 - 16 MHz high-speed internal RC oscillator (HSI)
 - 128 kHz low-speed internal RC (LSI)
 - 1-16 MHz high-speed external crystal (HSE)
 - Up to 16 MHz high-speed user-external clock (HSE user-ext)
- **Reset:** After reset the microcontroller restarts by default with an internal 2-MHz clock (16 MHz/8). The clock source and speed can be changed by the application program as soon as the code execution starts.
- **Safe clock switching:** Clock sources can be changed safely on the fly in Run mode through a configuration register. The clock signal is not switched until the new clock source is ready. The design guarantees glitch-free switching.
- **Clock management:** To reduce power consumption, the clock controller can stop the clock to the core or individual peripherals.
- **Wakeup:** In case the device wakes up from low-power modes, the internal RC oscillator (16 MHz/8) is used for quick startup. After a stabilization time, the device switches to the clock source that was selected before Halt mode was entered.
- **Clock security system (CSS):** The CSS permits monitoring of external clock sources and automatic switching to the internal RC (16 MHz/8) in case of a clock failure.
- **Configurable main clock output (CCO):** This feature permits to output a clock signal for use by the application.

- Interrupt:
 - Successful address/data communication
 - Error condition
 - Wakeup from Halt
- Wakeup from Halt on address detection in slave mode

5.9.3 Universal asynchronous receiver/transmitter with LIN support (LINUART)

The devices covered by this datasheet contain one LINUART interface. The interface is available on all the supported packages. The LINUART is an asynchronous serial communication interface which supports extensive LIN functions tailored for LIN slave applications. In LIN mode it is compliant to the LIN standards rev 1.2 to rev 2.2.

Detailed feature list:

LIN mode

Master mode:

- LIN break and delimiter generation
- LIN break and delimiter detection with separate flag and interrupt source for read back checking.

Slave mode:

- Autonomous header handling – one single interrupt per valid header
- Mute mode to filter responses
- Identifier parity error checking
- LIN automatic resynchronization, allowing operation with internal RC oscillator (HSI) clock source
- Break detection at any time, even during a byte reception
- Header errors detection:
 - Delimiter too short
 - Synch field error
 - Deviation error (if automatic resynchronization is enabled)
 - Framing error in synch field or identifier field
 - Header time-out

Table 8. STM8AF6246/48/66/68 (32 Kbyte) microcontroller pin description⁽¹⁾⁽²⁾ (continued)

LQFP48 VQFPN/LQFP32	Pin number	Pin name	Type	Input			Output			Main function (after reset)	Default alternate function	Alternate function after remap [option bit]	
				floating	wpu	Ext. interrupt	High sink	Speed	OD				
24		PE6/AIN9	I/O	X	X	X	-	O1	X	X	Port E7	Analog input 9	-
25	17	PE5/SPI_NSS	I/O	X	X	X	-	O1	X	X	Port E5	SPI master/slave select	-
26	18	PC1/TIM1_CH1	I/O	X	X	X	HS	O3	X	X	Port C1	Timer 1 - channel 1	-
27	19	PC2/TIM1_CH2	I/O	X	X	X	HS	O3	X	X	Port C2	Timer 1- channel 2	-
28	20	PC3/TIM1_CH3	I/O	X	X	X	HS	O3	X	X	Port C3	Timer 1 - channel 3	-
29	21	PC4/TIM1_CH4	I/O	X	X	X	HS	O3	X	X	Port C4	Timer 1 - channel 4	-
30	22	PC5/SPI_SCK	I/O	X	X	X		O3	X	X	Port C5	SPI clock	-
31	-	V _{SSIO_2}	S	-	-	-	-	-	-	-		I/O ground	-
32	-	V _{DDIO_2}	S	-	-	-	-	-	-	-		I/O power supply	-
33	23	PC6/SPI_MOSI	I/O	X	X	X	-	O3	X	X	Port C6	SPI master out/ slave in	-
34	24	PC7/SPI_MISO	I/O	X	X	X	-	O3	X	X	Port C7	SPI master in/ slave out	-
35	-	PG0	I/O	X	X	-	-	O1	X	X	Port G0	-	-
36	-	PG1	I/O	X	X	-	-	O1	X	X	Port G1	-	-
37	-	PE3/TIM1_BKIN	I/O	X	X	X	-	O1	X	X	Port E3	Timer 1 - break input	-
38	-	PE2/I ² C_SDA	I/O	X	-	X	-	O1	T ⁽⁶⁾	-	Port E2	I ² C data	-
39	-	PE1/I ² C_SCL	I/O	X	-	X	-	O1	T ⁽⁶⁾	-	Port E1	I ² C clock	-
40	-	PE0/CLK_CCO	I/O	X	X	X	-	O3	X	X	Port E0	Configurable clock output	-
41	25	PD0/TIM3_CH2	I/O	X	X	X	HS	O3	X	X	Port D0	Timer 3 - channel 2	TIM1_BKIN [AFR3]/ CLK_CCO [AFR2]
42	26	PD1/SWIM ⁽⁷⁾	I/O	X	X	X	HS	O4	X	X	Port D1	SWIM data interface	-
43	27	PD2/TIM3_CH1	I/O	X	X	X	HS	O3	X	X	Port D2	Timer 3 - channel 1	TIM2_CH3 [AFR1]
44	28	PD3/TIM2_CH2	I/O	X	X	X	HS	O3	X	X	Port D3	Timer 2 - channel 2	ADC_ETR [AFR0]
45	29	PD4/TIM2_CH1/ BEEP	I/O	X	X	X	HS	O3	X	X	Port D4	Timer 2 - channel 1	BEEP output [AFR7]
46	30	PD5/ LINUART_TX	I/O	X	X	X	-	O1	X	X	Port D5	LINUART data transmit	-

Table 11. General hardware register map (continued)

Address	Block	Register label	Register name	Reset status
0x00 5265	TIM1	TIM1_CCR1H	TIM1 capture/compare register 1 high	0x00
0x00 5266		TIM1_CCR1L	TIM1 capture/compare register 1 low	0x00
0x00 5267		TIM1_CCR2H	TIM1 capture/compare register 2 high	0x00
0x00 5268		TIM1_CCR2L	TIM1 capture/compare register 2 low	0x00
0x00 5269		TIM1_CCR3H	TIM1 capture/compare register 3 high	0x00
0x00 526A		TIM1_CCR3L	TIM1 capture/compare register 3 low	0x00
0x00 526B		TIM1_CCR4H	TIM1 capture/compare register 4 high	0x00
0x00 526C		TIM1_CCR4L	TIM1 capture/compare register 4 low	0x00
0x00 526D		TIM1_BKR	TIM1 break register	0x00
0x00 526E		TIM1_DTR	TIM1 dead-time register	0x00
0x00 526F		TIM1_OISR	TIM1 output idle state register	0x00
0x00 5270 to 0x00 52FF		Reserved area (147 bytes)		
0x00 5300	TIM2	TIM2_CR1	TIM2 control register 1	0x00
0x00 5301		TIM2_IER	TIM2 interrupt enable register	0x00
0x00 5302		TIM2_SR1	TIM2 status register 1	0x00
0x00 5303		TIM2_SR2	TIM2 status register 2	0x00
0x00 5304		TIM2_EGR	TIM2 event generation register	0x00
0x00 5305		TIM2_CCMR1	TIM2 capture/compare mode register 1	0x00
0x00 5306		TIM2_CCMR2	TIM2 capture/compare mode register 2	0x00
0x00 5307		TIM2_CCMR3	TIM2 capture/compare mode register 3	0x00
0x00 5308		TIM2_CCER1	TIM2 capture/compare enable register 1	0x00
0x00 5309		TIM2_CCER2	TIM2 capture/compare enable register 2	0x00
0x00 530A		TIM2_CNTRH	TIM2 counter high	0x00
0x00 530B		TIM2_CNTRL	TIM2 counter low	0x00
00 530C0x		TIM2_PSCR	TIM2 prescaler register	0x00
0x00 530D		TIM2_ARRH	TIM2 auto-reload register high	0xFF
0x00 530E		TIM2_ARRL	TIM2 auto-reload register low	0xFF
0x00 530F		TIM2_CCR1H	TIM2 capture/compare register 1 high	0x00
0x00 5310		TIM2_CCR1L	TIM2 capture/compare register 1 low	0x00
0x00 5311		TIM2_CCR2H	TIM2 capture/compare reg. 2 high	0x00
0x00 5312		TIM2_CCR2L	TIM2 capture/compare register 2 low	0x00
0x00 5313		TIM2_CCR3H	TIM2 capture/compare register 3 high	0x00

Table 11. General hardware register map (continued)

Address	Block	Register label	Register name	Reset status
0x00 5314	TIM2	TIM2_CCR3L	TIM2 capture/compare register 3 low	0x00
0x00 5315 to 0x00 531F	Reserved area (11 bytes)			
0x00 5320	TIM3	TIM3_CR1	TIM3 control register 1	0x00
0x00 5321		TIM3_IER	TIM3 interrupt enable register	0x00
0x00 5322		TIM3_SR1	TIM3 status register 1	0x00
0x00 5323		TIM3_SR2	TIM3 status register 2	0x00
0x00 5324		TIM3_EGR	TIM3 event generation register	0x00
0x00 5325		TIM3_CCMR1	TIM3 capture/compare mode register 1	0x00
0x00 5326		TIM3_CCMR2	TIM3 capture/compare mode register 2	0x00
0x00 5327		TIM3_CCER1	TIM3 capture/compare enable register 1	0x00
0x00 5328		TIM3_CNTRH	TIM3 counter high	0x00
0x00 5329		TIM3_CNTRL	TIM3 counter low	0x00
0x00 532A		TIM3_PSCR	TIM3 prescaler register	0x00
0x00 532B		TIM3_ARRH	TIM3 auto-reload register high	0xFF
0x00 532C		TIM3_ARRL	TIM3 auto-reload register low	0xFF
0x00 532D		TIM3_CCR1H	TIM3 capture/compare register 1 high	0x00
0x00 532E		TIM3_CCR1L	TIM3 capture/compare register 1 low	0x00
0x00 532F		TIM3_CCR2H	TIM3 capture/compare register 2 high	0x00
0x00 5330		TIM3_CCR2L	TIM3 capture/compare register 2 low	0x00
0x00 5331 to 0x00 533F	Reserved area (15 bytes)			
0x00 5340	TIM4	TIM4_CR1	TIM4 control register 1	0x00
0x00 5341		TIM4_IER	TIM4 interrupt enable register	0x00
0x00 5342		TIM4_SR	TIM4 status register	0x00
0x00 5343		TIM4_EGR	TIM4 event generation register	0x00
0x00 5344		TIM4_CNTR	TIM4 counter	0x00
0x00 5345		TIM4_PSCR	TIM4 prescaler register	0x00
0x00 5346		TIM4_ARR	TIM4 auto-reload register	0xFF
0x00 5347 to 0x00 53DF	Reserved area (185 bytes)			

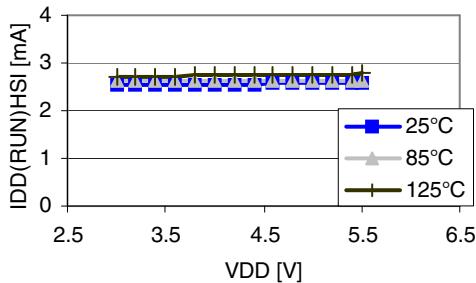
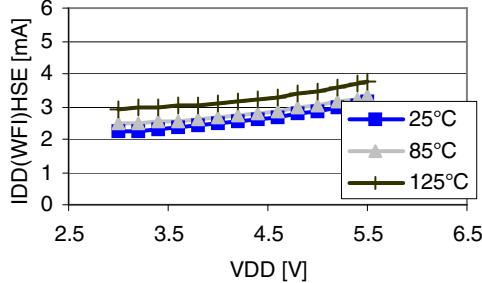
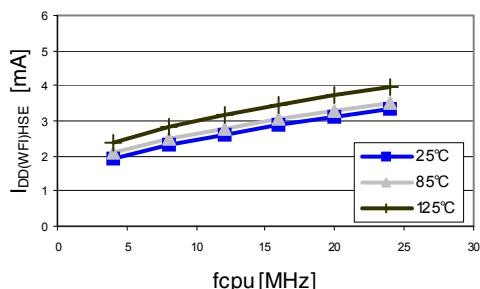
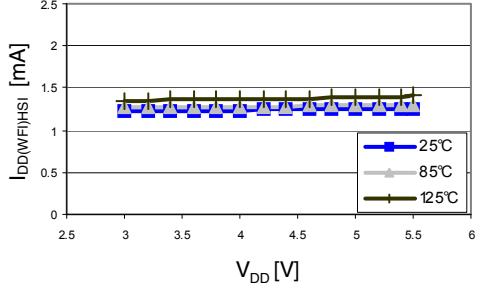
Table 11. General hardware register map (continued)

Address	Block	Register label	Register name	Reset status
0x00 53E0	ADC	ADC_DB0RH	ADC data buffer register 0 high	0x00
0x00 53E1		ADC_DB0RL	ADC data buffer register 0 low	0x00
0x00 53E2		ADC_DB1RH	ADC data buffer register 1 high	0x00
0x00 53E3		ADC_DB1RL	ADC data buffer register 1 low	0x00
0x00 53E4		ADC_DB2RH	ADC data buffer register 2 high	0x00
0x00 53E5		ADC_DB2RL	ADC data buffer register 2 low	0x00
0x00 53E6		ADC_DB3RH	ADC data buffer register 3 high	0x00
0x00 53E7		ADC_DB3RL	ADC data buffer register 3 low	0x00
0x00 53E8		ADC_DB4RH	ADC data buffer register 4 high	0x00
0x00 53E9		ADC_DB4RL	ADC data buffer register 4 low	0x00
0x00 53EA		ADC_DB5RH	ADC data buffer register 5 high	0x00
0x00 53EB		ADC_DB5RL	ADC data buffer register 5 low	0x00
0x00 53EC		ADC_DB6RH	ADC data buffer register 6 high	0x00
0x00 53ED		ADC_DB6RL	ADC data buffer register 6 low	0x00
0x00 53EE		ADC_DB7RH	ADC data buffer register 7 high	0x00
0x00 53EF		ADC_DB7RL	ADC data buffer register 7 low	0x00
0x00 53F0		ADC_DB8RH	ADC data buffer register 8 high	0x00
0x00 53F1		ADC_DB8RL	ADC data buffer register 8 low	0x00
0x00 53F2		ADC_DB9RH	ADC data buffer register 9 high	0x00
0x00 53F3		ADC_DB9RL	ADC data buffer register 9 low	0x00
0x00 53F4 to 0x00 53FF		Reserved area (12 bytes)		
0x00 5400	ADC	ADC_CSR	ADC control/status register	0x00
0x00 5401		ADC_CR1	ADC configuration register 1	0x00
0x00 5402		ADC_CR2	ADC configuration register 2	0x00
0x00 5403		ADC_CR3	ADC configuration register 3	0x00
0x00 5404		ADC_DRH	ADC data register high	0XX
0x00 5405		ADC_DRL	ADC data register low	0XX
0x00 5406		ADC_TDRH	ADC Schmitt trigger disable register high	0x00
0x00 5407		ADC_TDRL	ADC Schmitt trigger disable register low	0x00
0x00 5408		ADC_HTRH	ADC high threshold register high	0xFF
0x00 5409		ADC_HTRL	ADC high threshold register low	0x03
0x00 540A		ADC_LTRH	ADC low threshold register high	0x00

Table 15. Option bytes (continued)

Addr.	Option name	Option byte no.	Option bits								Factory default setting	
			7	6	5	4	3	2	1	0		
0x00 480B	TMU	OPT6	TMU[3:0]								0x00	
0x00 480C		NOPT6	NTMU[3:0]								0xFF	
0x00 480D	Flash wait states	OPT7	Reserved						WAIT STATE	0x00		
0x00 480E		NOPT7	Reserved						NWAIT STATE	0xFF		
0x00 480F			Reserved									
0x00 4810	TMU	OPT8	TMU_KEY 1 [7:0]								0x00	
0x00 4811		OPT9	TMU_KEY 2 [7:0]								0x00	
0x00 4812		OPT10	TMU_KEY 3 [7:0]								0x00	
0x00 4813		OPT11	TMU_KEY 4 [7:0]								0x00	
0x00 4814		OPT12	TMU_KEY 5 [7:0]								0x00	
0x00 4815		OPT13	TMU_KEY 6 [7:0]								0x00	
0x00 4816		OPT14	TMU_KEY 7 [7:0]								0x00	
0x00 4817		OPT15	TMU_KEY 8 [7:0]								0x00	
0x00 4818		OPT16	TMU_MAXATT [7:0]								0xC7	
0x00 4819 to 487D			Reserved									
0x00 487E	Boot-loader ⁽¹⁾	OPT17	BL [7:0]								0x00	
0x00 487F		NOPT17	NBL[7:0]								0xFF	

1. This option consists of two bytes that must have a complementary value in order to be valid. If the option is invalid, it has no effect on EMC reset.

Figure 12. Typ. $I_{DD(RUN)HSI}$ vs. V_{DD} @ $f_{CPU} = 16$ MHz, peripheral = off**Figure 13. Typ. $I_{DD(WFI)HSE}$ vs. V_{DD} @ $f_{CPU} = 16$ MHz, peripheral = on****Figure 14. Typ. $I_{DD(WFI)HSE}$ vs. f_{CPU} @ $V_{DD} = 5.0$ V, peripheral = on****Figure 15. Typ. $I_{DD(WFI)HSI}$ vs. V_{DD} @ $f_{CPU} = 16$ MHz, peripheral = off**

10.3.3 External clock sources and timing characteristics

HSE user external clock

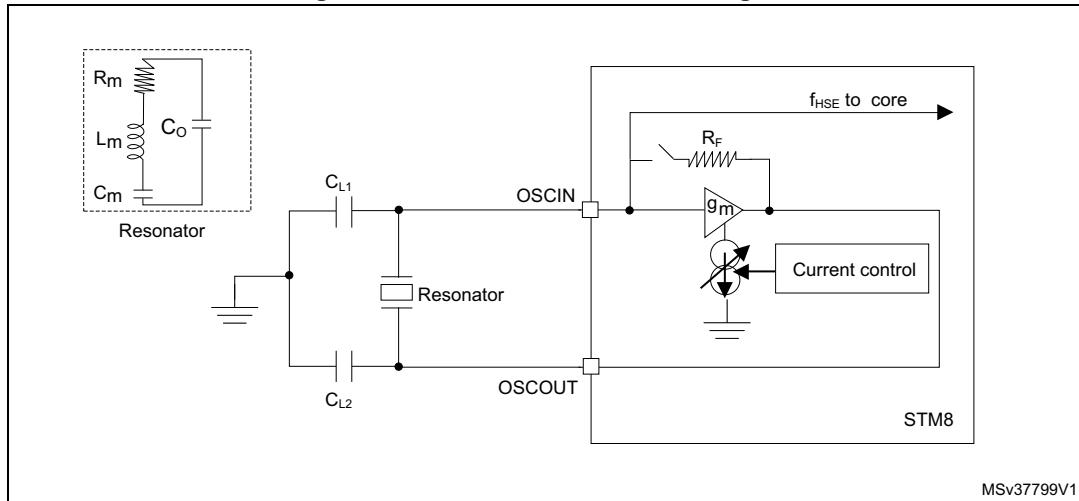
Subject to general operating conditions for V_{DD} and T_A .

Table 28. HSE user external clock characteristics

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
f_{HSE_ext}	User external clock source frequency	T_A is -40 to 150 °C	0 ⁽¹⁾	-	16	MHz
V_{HSEdHL}	Comparator hysteresis	-	$0.1 \times V_{DD}$	-	-	V
V_{HSEH}	OSCIN input pin high level voltage	-	$0.7 \times V_{DD}$	-	V_{DD}	
V_{HSEL}	OSCIN input pin low level voltage	-	V_{SS}	-	$0.3 \times V_{DD}$	
I_{LEAK_HSE}	OSCIN input leakage current	$V_{SS} < V_{IN} < V_{DD}$	-1	-	+1	µA

1. In CSS is used, the external clock must have a frequency above 500 kHz.

Figure 17. HSE oscillator circuit diagram



HSE oscillator critical g_m formula

The crystal characteristics have to be checked with the following formula:

$$g_m \gg g_{mcrit}$$

where g_{mcrit} can be calculated with the crystal parameters as follows:

$$g_{mcrit} = (2 \times \pi \times f_{HSE})^2 \times R_m (2C_0 + C)^2$$

R_m : Notional resistance (see crystal specification)

L_m : Notional inductance (see crystal specification)

C_m : Notional capacitance (see crystal specification)

C_0 : Shunt capacitance (see crystal specification)

$C_{L1} = C_{L2} = C$: Grounded external capacitance

10.3.4 Internal clock sources and timing characteristics

Subject to general operating conditions for V_{DD} and T_A .

High speed internal RC oscillator (HSI)

Table 30. HSI oscillator characteristics

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
f_{HSI}	Frequency	-	-	16	-	MHz

Figure 27. Typ. V_{OL} @ $V_{DD} = 3.3$ V (high sink ports)

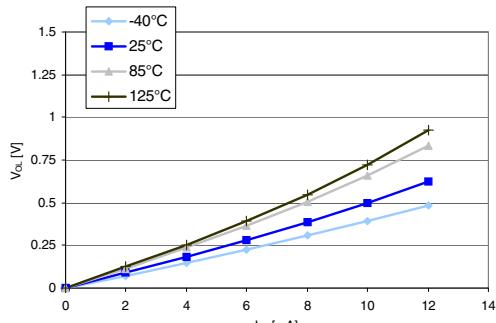


Figure 28. Typ. V_{OL} @ $V_{DD} = 5.0$ V (high sink ports)

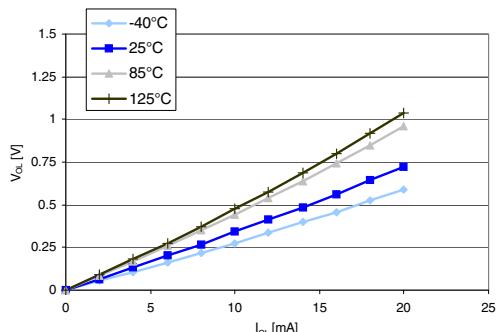


Figure 29. Typ. $V_{DD} - V_{OH}$ @ $V_{DD} = 3.3$ V (standard ports)

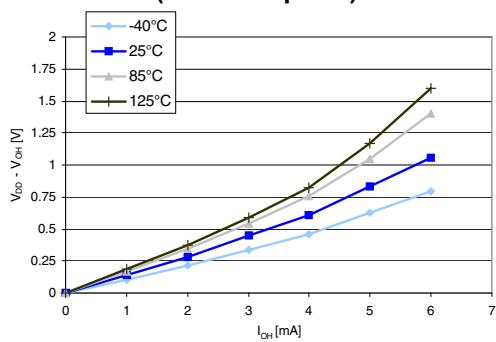


Figure 30. Typ. $V_{DD} - V_{OH}$ @ $V_{DD} = 5.0$ V (standard ports)

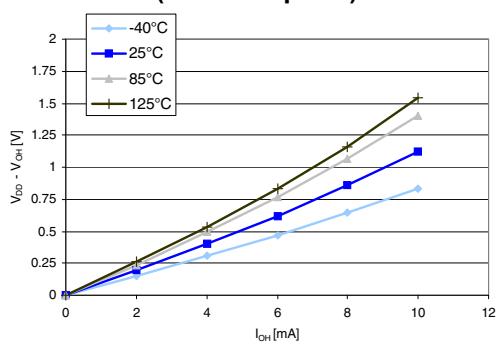


Figure 31. Typ. $V_{DD} - V_{OH}$ @ $V_{DD} = 3.3$ V (high sink ports)

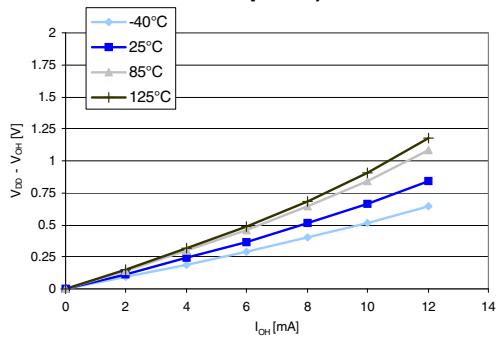
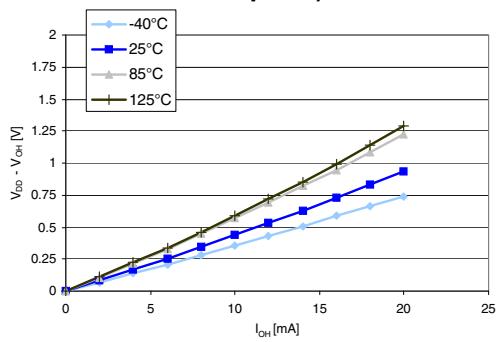


Figure 32. Typ. $V_{DD} - V_{OH}$ @ $V_{DD} = 5.0$ V (high sink ports)



10.3.7 Reset pin characteristics

Subject to general operating conditions for V_{DD} and T_A unless otherwise specified.

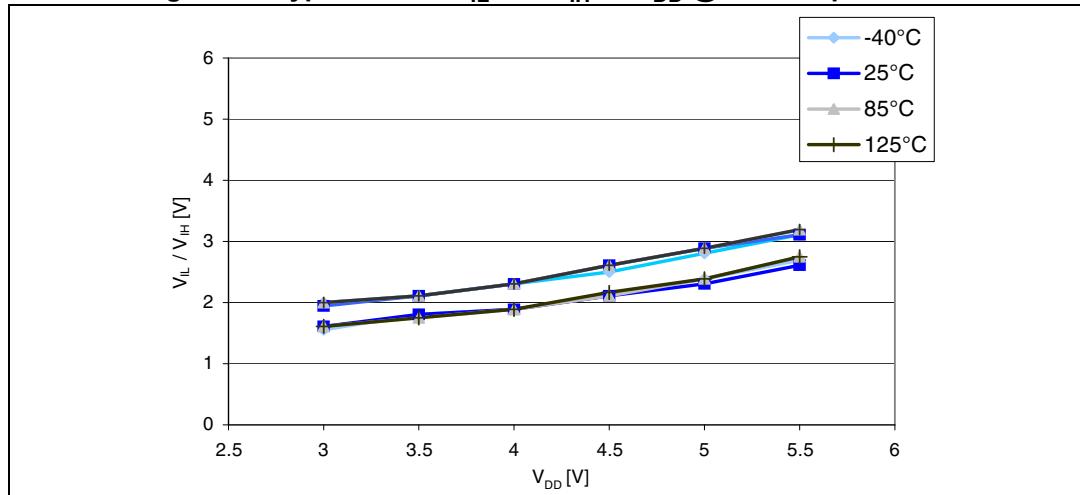
Table 36. NRST pin characteristics

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$V_{IL(NRST)}$	NRST input low level voltage ⁽¹⁾	-	V_{SS}	-	$0.3 \times V_{DD}$	V
$V_{IH(NRST)}$	NRST input high level voltage ⁽¹⁾	-	$0.7 \times V_{DD}$	-	V_{DD}	
$V_{OL(NRST)}$	NRST output low level voltage ⁽¹⁾	$I_{OL} = 3 \text{ mA}$	-	-	0.6	
$R_{PU(NRST)}$	NRST pull-up resistor	-	30	40	60	$\text{k}\Omega$
t_{IFP}	NRST input filtered pulse ⁽¹⁾	-	85	-	315	ns
$t_{INFP(NRST)}$	NRST Input not filtered pulse duration ⁽²⁾	-	500	-	-	

1. Data based on characterization results, not tested in production.

2. Data guaranteed by design, not tested in production.

Figure 33. Typical NRST V_{IL} and V_{IH} vs V_{DD} @ four temperatures



10.3.8 TIM 1, 2, 3, and 4 timer specifications

Subject to general operating conditions for V_{DD} , f_{MASTER} , and T_A unless otherwise specified.

Table 37. TIM 1, 2, 3, and 4 electrical specifications

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
f_{EXT}	Timer external clock frequency ⁽¹⁾	-	-	-	16	MHz

1. Not tested in production. On 64 Kbyte devices, the frequency is limited to 16 MHz.

10.3.9 SPI serial peripheral interface

Unless otherwise specified, the parameters given in [Table 38](#) are derived from tests performed under ambient temperature, f_{MASTER} frequency and V_{DD} supply voltage conditions. $t_{MASTER} = 1/f_{MASTER}$.

Refer to I/O port characteristics for more details on the input/output alternate function characteristics (NSS, SCK, MOSI, MISO).

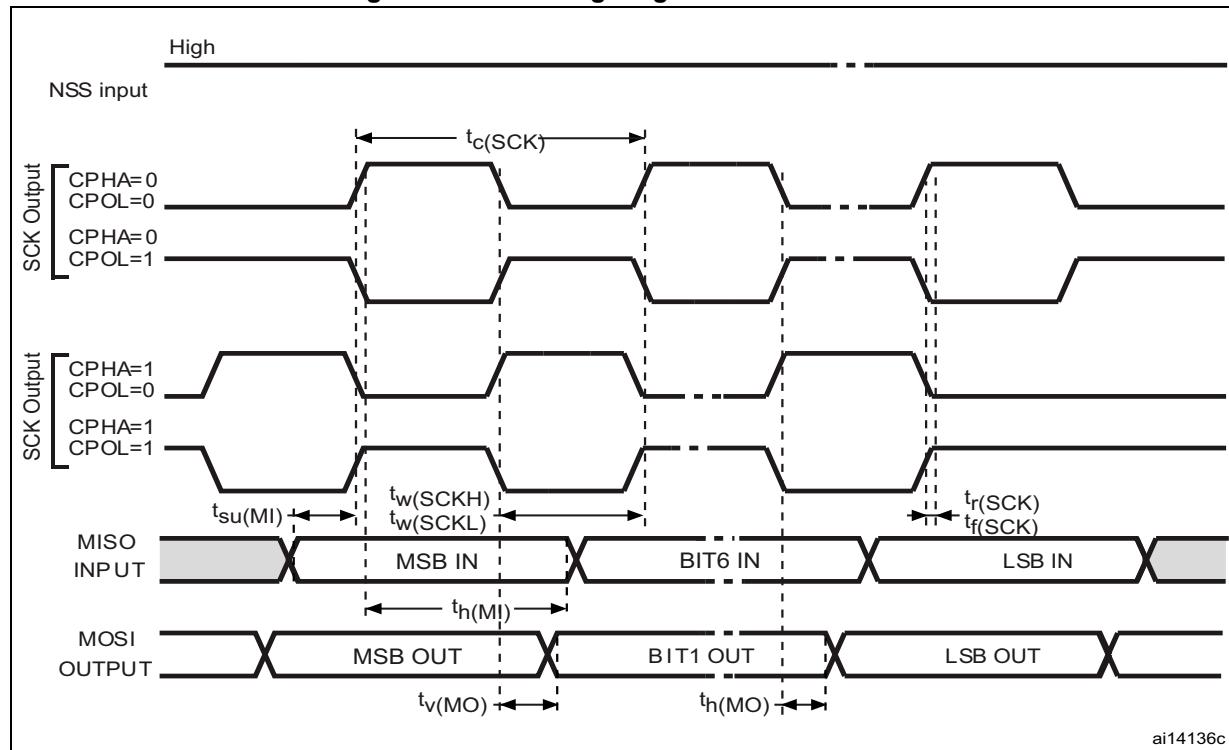
Table 38. SPI characteristics

Symbol	Parameter	Conditions		Min	Max	Unit
f_{SCK} $1/t_c(SCK)$	SPI clock frequency	Master mode		0	10	MHz
		Slave mode	$V_{DD} < 4.5$ V	0	6 ⁽¹⁾	
			$V_{DD} = 4.5$ V to 5.5 V	0	8 ⁽¹⁾	
$t_{r(SCK)}$ $t_{f(SCK)}$	SPI clock rise and fall time	Capacitive load: C = 30 pF		-	25 ⁽²⁾	ns
$t_{su(NSS)}^{(3)}$	NSS setup time	Slave mode		$4 * t_{MASTER}$	-	
$t_{h(NSS)}^{(3)}$	NSS hold time	Slave mode		70	-	
$t_{w(SCKH)}^{(3)}$ $t_{w(SCKL)}^{(3)}$	SCK high and low time	Master mode		$t_{SCK}/2 - 15$	$t_{SCK}/2 + 15$	
$t_{su(MI)}^{(3)}$ $t_{su(SI)}^{(3)}$	Data input setup time	Master mode		5	-	
		Slave mode		5	-	
$t_{h(MI)}^{(3)}$ $t_{h(SI)}^{(3)}$	Data input hold time	Master mode		7	-	
		Slave mode		10	-	
$t_{a(SO)}^{(3)(4)}$	Data output access time	Slave mode		-	$3 * t_{MASTER}$	
$t_{dis(SO)}^{(3)(5)}$	Data output disable time	Slave mode		25	-	
$t_{v(SO)}^{(3)}$	Data output valid time	Slave mode (after enable edge)	$V_{DD} < 4.5$ V	-	75	
			$V_{DD} = 4.5$ V to 5.5 V	-	53	
$t_{v(MO)}^{(3)}$	Data output valid time	Master mode (after enable edge)		-	30	
$t_{h(SO)}^{(3)}$ $t_{h(MO)}^{(3)}$	Data output hold time	Slave mode (after enable edge)		31	-	
		Master mode (after enable edge)		12	-	

1. $f_{SCK} < f_{MASTER}/2$.

2. The pad has to be configured accordingly (fast mode).

Figure 39. SPI timing diagram - master mode



1. Measurement points are at CMOS levels: 0.3 V_{DD} and 0.7 V_{DD} .

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10.3.11 10-bit ADC characteristics

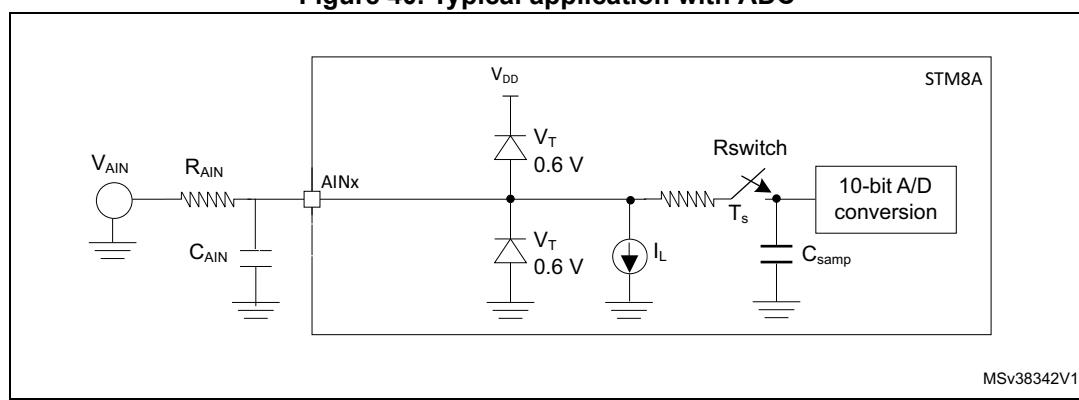
Subject to general operating conditions for V_{DDA} , f_{MASTER} , and T_A unless otherwise specified.

Table 40. ADC characteristics

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
f_{ADC}	ADC clock frequency	-	111 kHz	-	4 MHz	kHz/MHz
V_{DDA}	Analog supply	-	3	-	5.5	V
V_{REF+}	Positive reference voltage	-	2.75	-	V_{DDA}	
V_{REF-}	Negative reference voltage	-	V_{SSA}	-	0.5	
V_{AIN}	Conversion voltage range ⁽¹⁾	-	V_{SSA}	-	V_{DDA}	
		Devices with external V_{REF+} / V_{REF-} pins	V_{REF-}	-	V_{REF+}	
C_{samp}	Internal sample and hold capacitor	-	-	-	3	pF
$t_S^{(1)}$	Sampling time ($3 \times 1/f_{ADC}$)	$f_{ADC} = 2$ MHz	-	1.5	-	μs
		$f_{ADC} = 4$ MHz	-	0.75	-	
t_{STAB}	Wakeup time from standby	$f_{ADC} = 2$ MHz	-	7	-	
		$f_{ADC} = 4$ MHz	-	3.5	-	
t_{CONV}	Total conversion time including sampling time ($14 \times 1/f_{ADC}$)	$f_{ADC} = 2$ MHz	-	7	-	
		$f_{ADC} = 4$ MHz	-	3.5	-	
R_{switch}	Equivalent switch resistance	-	-	-	30	k Ω

- During the sample time, the sampling capacitance, C_{samp} (3 pF typ), can be charged/discharged by the external source. The internal resistance of the analog source must allow the capacitance to reach its final voltage level within t_S . After the end of the sample time t_S , changes of the analog input voltage have no effect on the conversion result.

Figure 40. Typical application with ADC



- Legend: R_{AIN} = external resistance, C_{AIN} = capacitors, C_{samp} = internal sample and hold capacitor.

Electromagnetic interference (EMI)

Emission tests conform to the IEC 61967-2 standard for test software, board layout and pin loading.

Table 43. EMI data

Symbol	Parameter	Conditions			Unit
		General conditions	Monitored frequency band	Max f _{CPU} ⁽¹⁾	
				8 MHz	
S_{EMI}	Peak level	$V_{\text{DD}} = 5 \text{ V}$, $T_A = 25^\circ\text{C}$, LQFP80 package conforming to IEC 61967-2	0.1 MHz to 30 MHz	15	17
			30 MHz to 130 MHz	18	22
			130 MHz to 1 GHz	-1	3
	EMI level		-	2	2.5

1. Data based on characterization results, not tested in production.

Absolute maximum ratings (electrical sensitivity)

Based on two different tests (ESD and LU) using specific measurement methods, the product is stressed to determine its performance in terms of electrical sensitivity. For more details, refer to the application note AN1181.

Electrostatic discharge (ESD)

Electrostatic discharges (3 positive then 3 negative pulses separated by 1 second) are applied to the pins of each sample according to each pin combination. The sample size depends on the number of supply pins in the device (3 parts*(n+1) supply pin). This test conforms to the JESD22-A114A/A115A standard. For more details, refer to the application note AN1181.

Table 44. ESD absolute maximum ratings

Symbol	Ratings	Conditions	Class	Maximum value ⁽¹⁾	Unit
$V_{\text{ESD(HBM)}}$	Electrostatic discharge voltage (Human body model)	$T_A = 25^\circ\text{C}$, conforming to JESD22-A114	3A	4000	V
$V_{\text{ESD(CDM)}}$	Electrostatic discharge voltage (Charge device model)	$T_A = 25^\circ\text{C}$, conforming to JESD22-C101	3	500	
$V_{\text{ESD(MM)}}$	Electrostatic discharge voltage (Machine model)	$T_A = 25^\circ\text{C}$, conforming to JESD22-A115	B	200	

1. Data based on characterization results, not tested in production

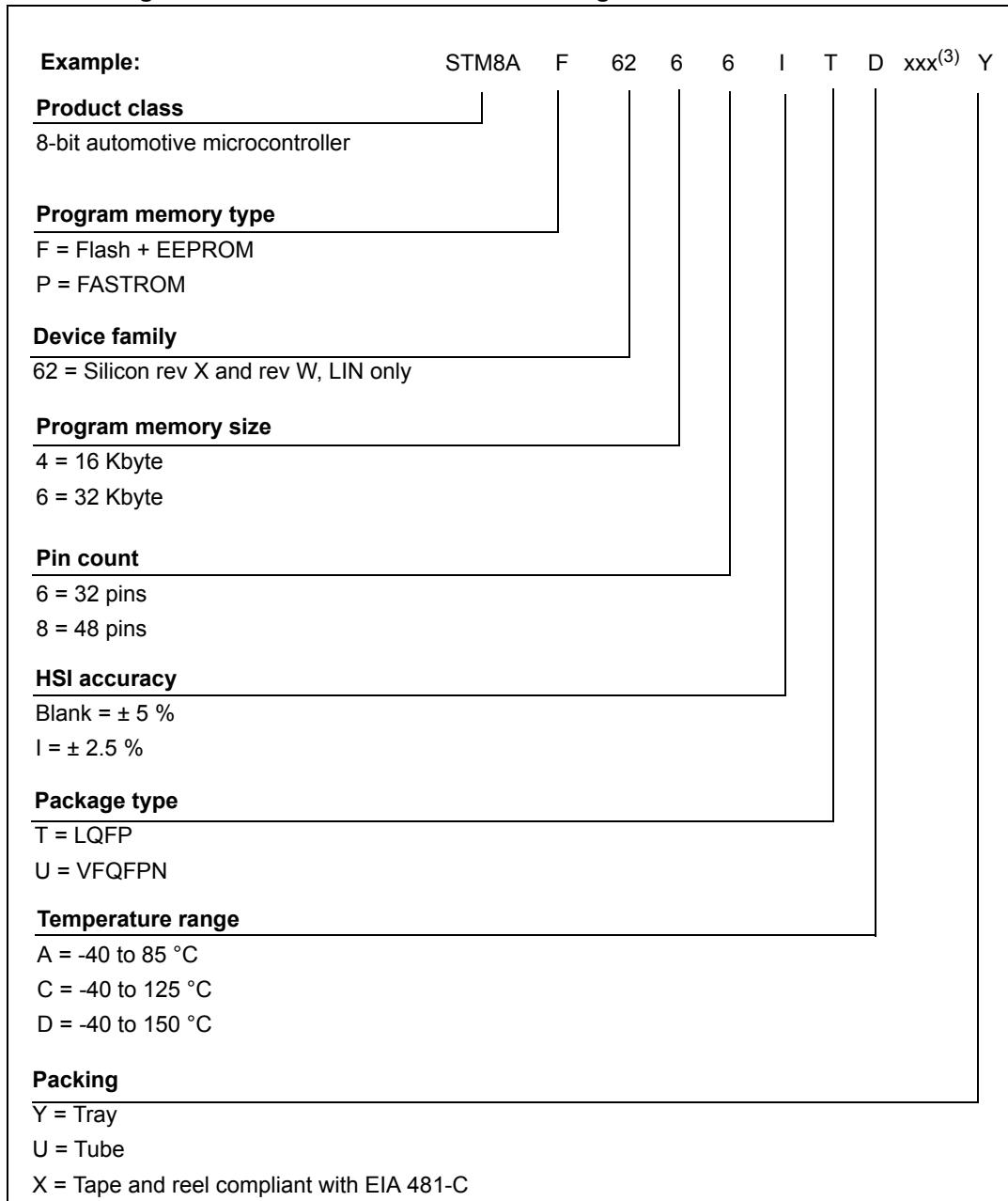
**Table 48. LQFP32 - 32-pin, 7 x 7 mm low-profile quad flat package
mechanical data**

Symbol	millimeters			inches⁽¹⁾		
	Min	Typ	Max	Min	Typ	Max
A	-	-	1.600	-	-	0.0630
A1	0.050	-	0.150	0.0020	-	0.0059
A2	1.350	1.400	1.450	0.0531	0.0551	0.0571
b	0.300	0.370	0.450	0.0118	0.0146	0.0177
c	0.090	-	0.200	0.0035	-	0.0079
D	8.800	9.000	9.200	0.3465	0.3543	0.3622
D1	6.800	7.000	7.200	0.2677	0.2756	0.2835
D3	-	5.600	-	-	0.2205	-
E	8.800	9.000	9.200	0.3465	0.3543	0.3622
E1	6.800	7.000	7.200	0.2677	0.2756	0.2835
E3	-	5.600	-	-	0.2205	-
e	-	0.800	-	-	0.0315	-
L	0.450	0.600	0.750	0.0177	0.0236	0.0295
L1	-	1.000	-	-	0.0394	-
k	0°	3.5°	7°	0°	3.5°	7°
ccc	-	-	0.100	-	-	0.0039

1. Values in inches are converted from mm and rounded to 4 decimal digits.

12 Ordering information

Figure 51. STM8AF6246/48/66/68 ordering information scheme⁽¹⁾ (2)



- For a list of available options (e.g. memory size, package) and orderable part numbers or for further information on any aspect of this device, please go to www.st.com or contact the nearest ST Sales Office.
- Parts marked as "ES", "E" or accompanied by an Engineering Sample notification letter, are not yet qualified and therefore not yet ready to be used in production and any consequences deriving from such usage will not be at ST charge. In no event, ST will be liable for any customer usage of these engineering samples in production. ST Quality has to be contacted prior to any decision to use these Engineering Samples to run qualification activity.
- Customer specific FASTROM code or custom device configuration. This field shows 'SSS' if the device contains a super set silicon, usually equipped with bigger memory and more I/Os. This silicon is supposed to be replaced later by the target silicon.

Table 50. Document revision history (continued)

Date	Revision	Changes
09-Jun-2015	10	<p>Updated:</p> <ul style="list-style-type: none">– the product naming in the document headers and captions,– LIN version in <i>Features</i> and <i>Section 5.9.3: Universal asynchronous receiver/transmitter with LIN support (LINUART)</i>. <p>Added:</p> <ul style="list-style-type: none">– the third table footnote to <i>Table 22: Operating conditions at power-up/power-down</i>,– <i>Figure 44: VFQFPN32 marking example (package top view)</i>,– <i>Figure 47: LQFP48 marking example (package top view)</i>,– <i>Figure 50: LQFP32 marking example (package top view)</i>,– the note about the parts marked “E” and “ES” below <i>Figure 51: STM8AF6246/48/66/68 ordering information scheme(1) (2)</i>,– the standard for EMI characteristics in <i>Table 43: EMI data</i>. <p>Removed the references to STM8AF61xx and STM8AH61xx obsolete products.</p> <p>Moved <i>Section 11.4: Thermal characteristics</i> to <i>Section 11: Package information</i>.</p>
14-Jun-2016	11	Update <i>Table 46: VFQFPN32 - 32-pin, 5x5 mm, 0.5 mm pitch very thin profile fine pitch quad flat package mechanical data</i>