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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Obsolete
Core Processor	Z8
Core Size	8-Bit
Speed	12MHz
Connectivity	EBI/EMI
Peripherals	POR, WDT
Number of I/O	24
Program Memory Size	8KB (8K x 8)
Program Memory Type	OTP
EEPROM Size	-
RAM Size	237 x 8
Voltage - Supply (Vcc/Vdd)	3.5V ~ 5.5V
Data Converters	-
Oscillator Type	Internal
Operating Temperature	0°C ~ 70°C (TA)
Mounting Type	Surface Mount
Package / Case	28-LCC (J-Lead)
Supplier Device Package	-
Purchase URL	https://www.e-xfl.com/product-detail/zilog/z8673312vsc

Revision History

Each instance in Revision History reflects a change to this document from its previous revision. For more details, refer to the corresponding pages and appropriate links in the table below.

Date	Revision Level	Description	Page No
May 2008	01	Original issue.	All

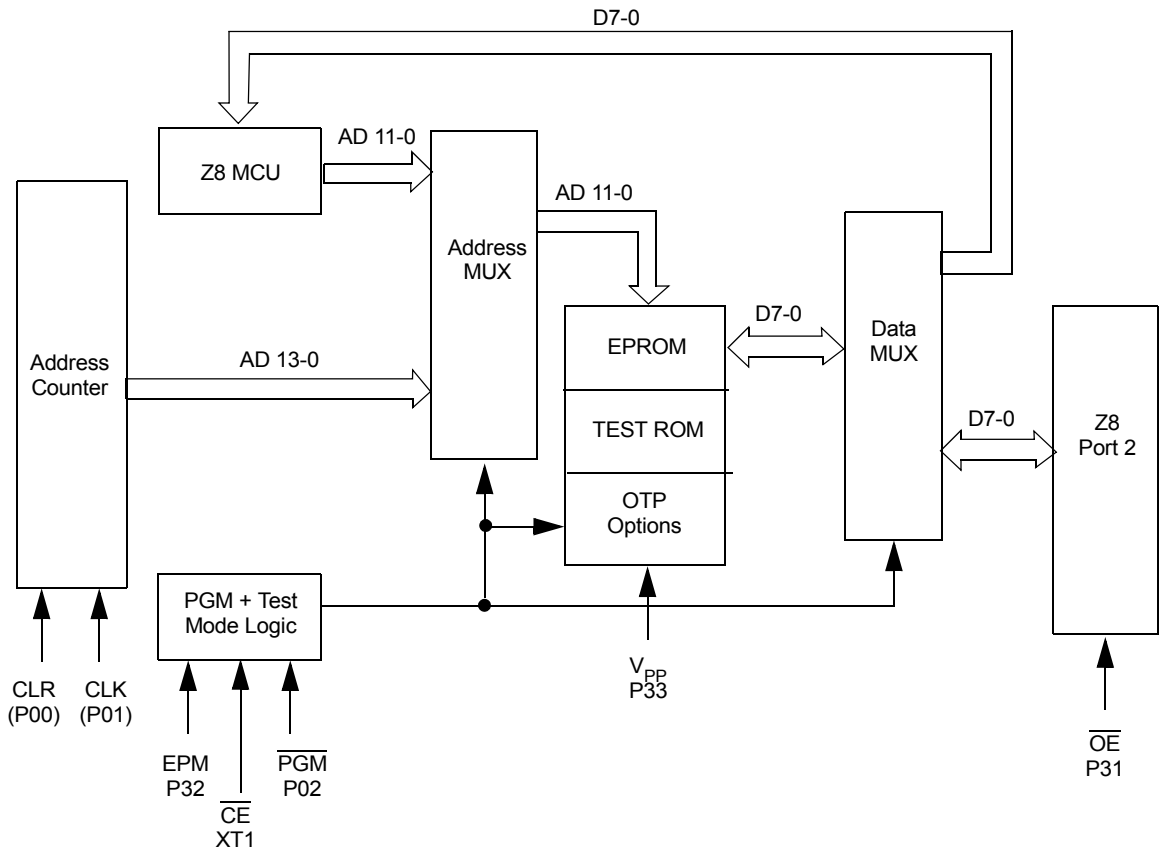


Figure 2. EPROM Programming Block Diagram

Pin Description

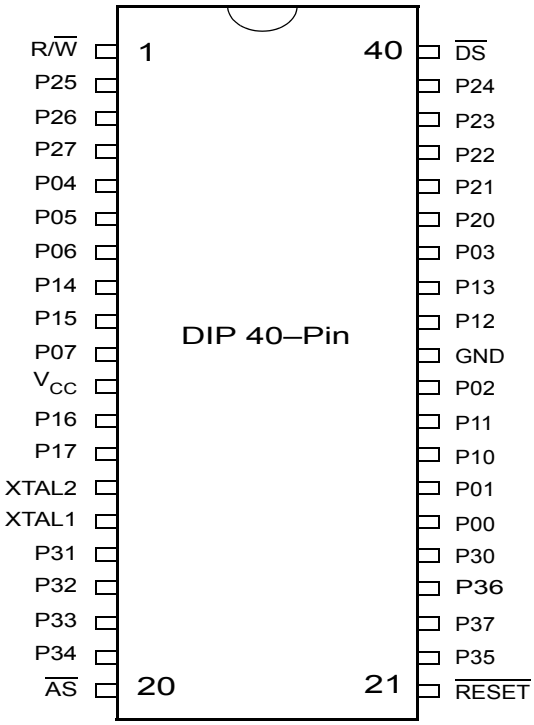


Figure 3. 40-Pin DIP Pin Configuration Standard Mode

Table 2. 40-Pin DIP Pin Identification Standard Mode

Pin No	Symbol	Function	Direction
1	R/$\overline{W}$	Read/Write	Output
2-4	P25-P27	Port 2, Pins 5,6,7	Input/Output
5-7	P04-P06	Port 0, Pins 4,5,6	Input/Output
8-9	P14-P15	Port 1, Pins 4,5	Input/Output
10	P07	Port 0, Pin 7	Input/Output
11	V_{CC}	Power Supply	
12-13	P16-P17	Port 1, Pins 6,7	Input/Output
14	XTAL2	Crystal Oscillator	Output

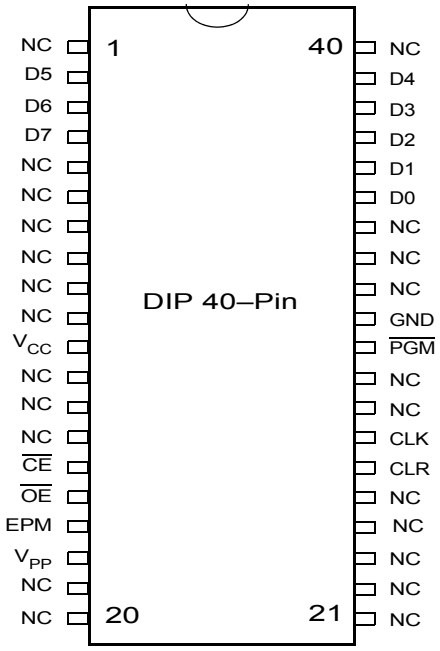


Figure 6. 40-Pin DIP Pin Configuration EPROM Mode

Table 5. 40-Pin DIP Package Pin Identification EPROM Mode

Pin No	Symbol	Function	Direction
1	NC	No Connection	
2-4	D5-D7	Data 5,6,7	Input/Output
5-10	NC	No Connection	
11	V_{CC}	Power Supply	
12-14	NC	No Connection	
15	CE	Chip Select	Input
16	OE	Output Enable	Input
17	EPM	EPROM Prog. Mode	Input
18	V_{PP}	Prog. Voltage	Input
19-25	NC	No Connection	
26	CLR	Clear	Input
27	CLK	Clock	Input
28-29	NC	No Connection	

Table 5. 40-Pin DIP Package Pin Identification EPROM Mode (Continued)

Pin No	Symbol	Function	Direction
30	/PGM	Prog. Mode	Input
31	GND	Ground	
32-34	NC	No Connection	
35-39	D0-D4	Data 0,1,2,3,4	Input/Output
40	NC	No Connection	

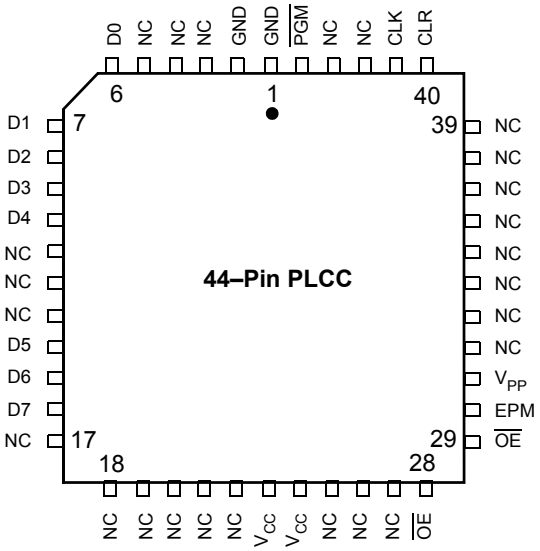


Figure 7. 44-Pin PLCC Pin Configuration EPROM Programming Mode

Table 6. 44-Pin PLCC Pin Configuration EPROM Programming Mode

Pin No	Symbol	Function	Direction
1-2	GND	Ground	
3-5	NC	No Connection	
6-10	D0-D4	Data 0,1,2,3,4	Input/Output
11-13	NC	No Connection	
14-16	D5-D7	Data 5,6,7	Input/Output
17-22	NC	No Connection	
23-24	V_{CC}	Power Supply	
25-27	NC	No Connection	
28	CE	Chip Select	Input
29	OE	Output Enable	Input
30	EPM	EPROM Prog. Mode	Input
31	V_{PP}	Prog. Voltage	Input

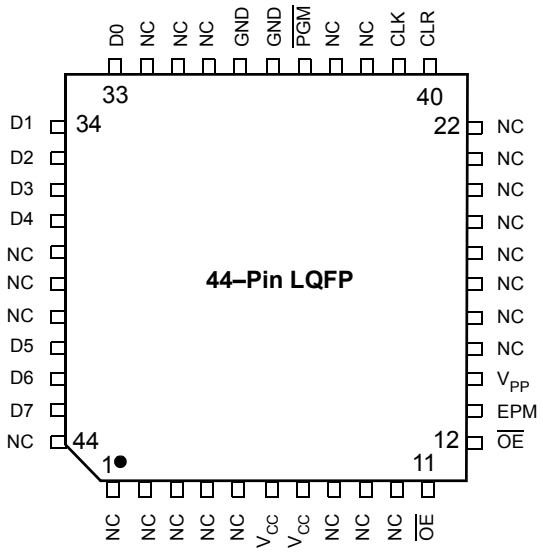


Figure 8. 44-Pin LQFP Pin Configuration EPROM Programming Mode

Table 7. 44-Pin LQFP Pin Identification EPROM Programming Mode

Pin No	Symbol	Function	Direction
1-5	NC	No Connection	
6-7	V_{CC}	Power Supply	
8-10	NC	No Connection	
11	CE	Chip Select	Input
12	OE	Output Enable	Input
13	EPM	EPROM Prog. Mode	Input
14	V_{PP}	Prog. Voltage	Input
15-22	NC	No Connection	
23	CLR	Clear	Input
24	CLK	Clock	Input
25-26	NC	No Connection	
27	/PGM	Prog. Mode	Input
28-29	GND	Ground	
30-32	NC	No Connection	

Table 7. 44-Pin LQFP Pin Identification EPROM Programming Mode (Continued)

Pin No	Symbol	Function	Direction
33-37	D0-D4	Data 0,1,2,3,4	Input/Output
38-40	NC	No Connection	
41-43	D5-D7	Data 5,6,7	Input/Output
44	NC	No Connection	

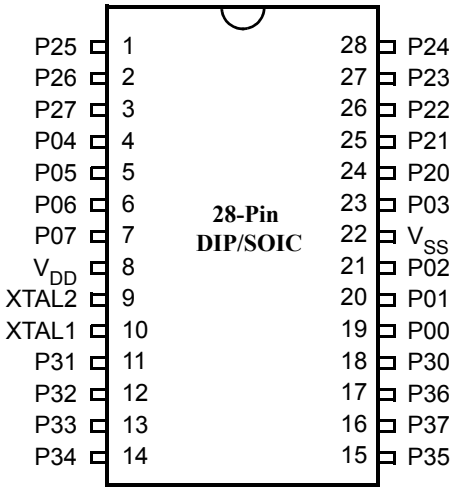


Figure 9. Standard Mode 28-Pin DIP/SOIC Pin Configuration

Table 8. 28-Pin DIP/SOIC/PLCC Pin Identification Standard Mode

Pin No	Symbol	Function	Direction
1-3	P25-P27	Port 2, Pins 5,6,	Input/Output
4-7	P04-P07	Port 0, Pins 4,5,6,7 In/Output	
8	V_{CC}	Power Supply	
9	XTAL2	Crystal Oscillator	Output
10	XTAL1	Crystal Oscillator	Input
11-13	P31-P33	Port 3, Pins 1,2,3	Input
14-15	P34-P35	Port 3, Pins 4,5	Output
16	P37	Port 3, Pin 7	Output
17	P36	Port 3, Pin 6	Output
18	P30	Port 3, Pin 0	Input
19-21	P00-P02	Port 0, Pins 0,1,2	Input/Output
22	V_{SS}	Ground	
23	P03	Port 0, Pin 3	Input/Output
24-28	P20-P24	Port 2, Pins 0,1,2,3,4	Input/Output

Table 13. DC Electrical Characteristics T_A = 0 °C to +70 °C, 12 MHz (Continued)

No.	Symbol	Parameter	V_{CC} [1]	Min	Max	Units	Notes
4	TwAS	$\overline{AS}$ Low Width	3.5V	55		ns	2
			5.5V	55		ns	2
5	TdAS(DS)	Address Float to $\overline{DS}$ Fall	3.5V	0		ns	
			5.5V	0		ns	
6	TwDSR	$\overline{DS}$ (Read) Low Width	3.5V	200		ns	2,3
			5.5V	200		ns	2,3
7	TwDSW	$\overline{DS}$ (Write) Low Width	3.5V	110		ns	2,3
			5.5V	110		ns	2,3
8	TdDSR(DR)	$\overline{DS}$ Fail to Read Data Req'd Valid	3.5V		150	ns	2,3
			5.5V		150	ns	2,3
9	ThDR(DS)	Read Data to $\overline{DS}$ Rise Hold Time	3.5V	0		ns	2
			5.5V	0		ns	2
10	TdDS(A)	$\overline{DS}$ Rise to Address Active Delay	3.5V	45		ns	2
			5.5V	55		ns	2
11	TdDS(AS)	$\overline{DS}$ Rise to $\overline{AS}$ Fall Delay	3.5V	30		ns	2
			5.5V	45		ns	2
12	TdR/W(AS)	R/$\overline{W}$ Valid to $\overline{AS}$ Rise Delay	3.5V	45		ns	2
			5.5V	45		ns	2
13	TdDS(R/W)	$\overline{DS}$ Rise to R/$\overline{W}$ Not Valid	3.5V	45		ns	2
			5.5V	45		ns	2
14	TdDW(DSW)	Write Data Valid to $\overline{DS}$ Fall (Write) Delay	3.5V	55		ns	2
			5.5V	55		ns	2
15	TdDS(DW)	$\overline{DS}$ Rise to Write Data Not Valid Delay	3.5V	45		ns	2
			5.5V	55		ns	2
16	TdA(DR)	Address Valid to Read Data Req'd Valid	3.5V		310	ns	2,3
			5.5V		310	ns	2,3
17	TdAS(DS)	$\overline{AS}$ Rise to $\overline{DS}$ Fall Delay	3.5V	65		ns	2
			5.5V	65		ns	2

Table 18. Additional Timing Table (Divide by Two Mode) T_A = -40 °C to +105 °C (Continued)

No	Symbol	Parameter	V_{CC} [1]	Min	Max	Min	Max	Units	Conditions	Notes
12	Twdt	Watchdog Timer Delay Time Before Timeout	3.5V	7		10		ms	D0 =0	8,9
			5.5V	3.5		5		ms	D1 = 0	5,11
			3.5V	14		20		ms	D0 =1	5,11
			5.5V	7		10		ms	D1 = 0	5,11
			3.5V	28		40		ms	D1 = 0	5,11
			5.5V	14		20		ms	D1 = 1	5,11
			3.5V	112		160		ms	D0 = 1	5,11
			5.5V	56		80		ms	D1 = 1	5,11

Notes
1. The V_{CC} voltage specification of 5.5 V guarantees 5.0 V ± 0.5 V and the V_{CC} voltage specification of 3.5 V guarantees only 3.5 V.
2. Timing Reference uses 0.7 VC0 for a logic 1 and 0.2 VGC for a logic 0.
3. SMR D1 = 0.
4. SMR-D5 = 1, POR STOP Mode Delay is on
5. Interrupt request via Port 3 (P31-P33)
6. Interrupt request via Port 3 (P30).
7. Maximum frequency for internal system clock is 2 MHz when using Low EMI OSC PCON Bit D7 = 0
8. Reg. WDTMR.
9. Using internal RC.

Pin Functions

EPROM Programming Mode

D7-D0 Data Bus. The data can be read from or written to external memory through the data bus.

V_{CC} Power Supply. This pin must supply 5 V during the EPROM read mode and 6 V during other modes.

$\overline{CE}$ Chip Enable (active Low). This pin is active during EPROM Read Mode, Program Mode, and Program Verify Mode.

$\overline{OE}$ Output Enable (active Low). This pin drives the direction of the Data Bus. When this pin is Low, the Data Bus is output, when High, the Data Bus is input.

EPM EPROM Program Mode. This pin controls the different EPROM Program Mode by applying different voltages.

V_{PP} Program Voltage. This pin supplies the program voltage.

PGM Program Mode (active Low). When this pin is Low, the data is programmed to the EPROM through the Data Bus.

and P32 with reference to the voltage on P33. The analog function is enabled by setting the D1 of Port 3 Mode Register (P3M). The comparator output can be outputted from P34 and P37, respectively, by setting PCON register Bit D0 to 1 state. For the interrupt function, P30 and P33 are falling edge triggered interrupt inputs. P31 and P32 can be programmed as falling, rising or both edges triggered interrupt inputs (see Figure 21). Access to Counter/Timer 1 is made through P31 (T_{IN}) and P36 (T_{OUT}). Handshake tines for Port 0, Port 1, and Port 2 are also available on Port 3 (see Table 19).

Note: *When enabling or disabling analog mode, the following is recommended:*

1. Allow two NOP decays before reading this comparator output.
2. Disable global interrupts, switch to analog mode, clear interrupts, and then re-enable interrupts.
3. IRQ register bits 3 to 0 must be cleared after enabling analog mode.

Note: *P33-P30 differs from the Z86C33/C43/233/243 in that there is no clamping diode to V_{CC} due to the EPROM high-voltage circuits. Exceeding the V_{IH} maximum specification during standard operating mode may cause the device to enter EPROM mode.*

Functional Description

The MCU incorporates the following special functions to enhance the standard Z8 architecture to provide the user with increased design flexibility.

RESET. The device is reset in one of three ways:

1. Power-On Reset
2. Watchdog Timer
3. Stop Mode Recovery Source

Note: *Having the Auto Power-On Reset circuitry built-in, the MCU does not need to be connected to an external power-on reset circuit. The reset time is T_{POR}. The MCU does not re-initialize WDTMR, SMR, P2M, and P3M registers to their reset values on a Stop Mode Recovery operation.*

Note: *The device V_{CC} must rise up to the operating V_{CC} specification before the T_{POR} expires.*

Program Memory. The MCU can address up to 4/8/16 KB of Internal Program Memory (see Figure 22). The first 12 bytes of program memory are reserved for the interrupt vectors. These locations contain six 16-bit vectors that correspond to the six available interrupts. For EPROM mode, byte 12 (000Ch) to address 4095 (0FFFh)/8191 (1FFFh)/16384 (3FFFh), consists of programmable EPROM. After reset, the program counter points at the address 000Ch, which is the starting address of the user program.

In ROMless mode, the Z86E43/743/E44 can address up to 64 KB of External Program Memory. The ROM/ROMless option is only available on the 44-pin devices.

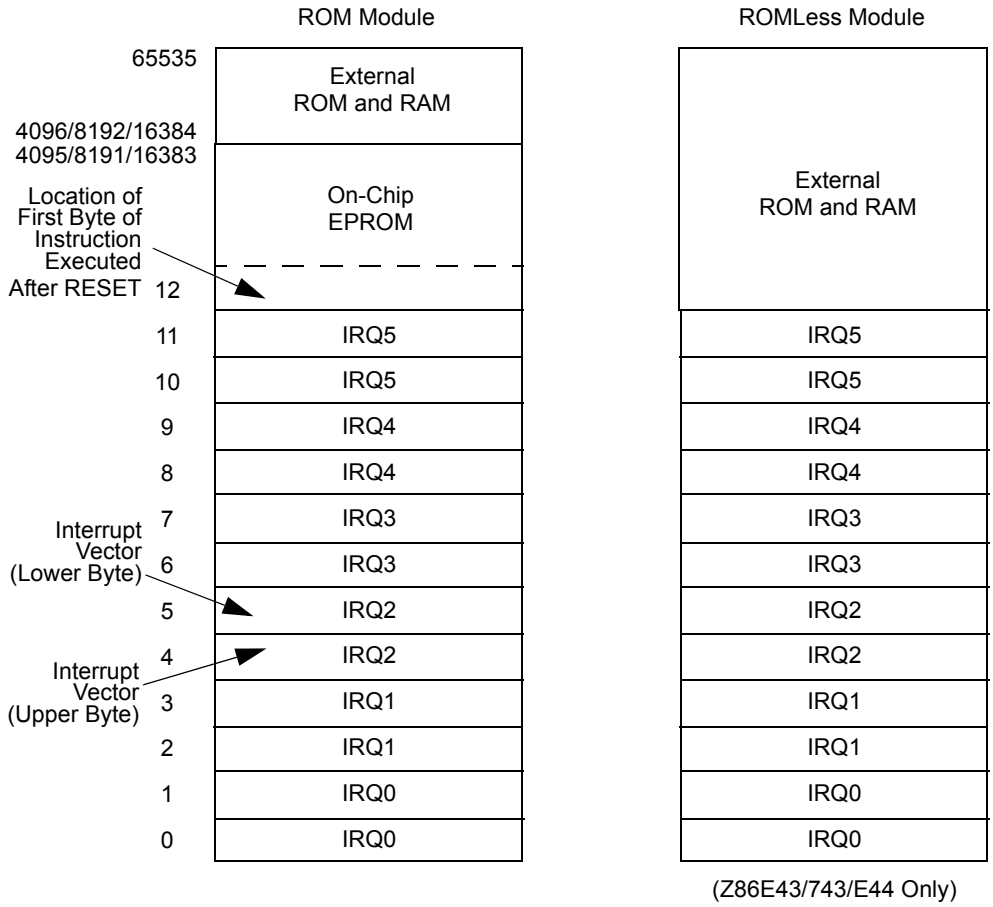


Figure 22. Program Memory Map

EPROM Protect. When in ROM Protect Mode, and executing out of External Program Memory, instructions LDC, LDCI, LDE, and LDEI cannot read Internal Program Memory.

When in EPROM Protect Mode and executing out of Internal Program Memory, instructions LDC, LDCI, LDE, and LDEI can read Internal Program Memory.

Data Memory ($\overline{DM}$). In ROM Mode, the Z86E43/743/E44 can address up to 60156/48 KB of external data memory beginning at location 4096/8192/16384. In ROMless mode, the Z86E43/743/E44 can address up to 64 KB of data memory. External data memory may be included with, or separated from, the external program memory space. $\overline{DM}$, an optional I/0 function that can be programmed to appear on pin P34, is used to distinguish between data and program memory space (Figure 23). The state of the $\overline{DM}$ signal is controlled by the type of instruction being executed. An LDC opcode references PROGRAM ($\overline{DM}$ inactive) memory, and an LDE instruction references data ($\overline{DM}$ active Low) memory.

RAM Protect. The upper portion of the RAM's address spaces 80h to EFh (excluding the control registers) can be protected from reading and writing. This option can be selected during the EPROM Programming Mode. After this option is selected, the user can activate this feature from the internal EPROM. D6 of the IMR control register (R251) is used to turn off/on the RAM protect by loading a 0 or 1, respectively. A "1" in D6 indicates RAM Protect enabled.

Stack. The Z86E43/743/E44 external data memory or the internal register file can be used for the stack. The 16-bit Stack Pointer (R254-R255) is used for the external stack, which can reside anywhere in the data memory for ROMless mode, but only from 4096/8192/16384 to 65535 in ROM mode. An 8-bit Stack Pointer (R255) is used for the internal stack on the Z8 that resides within the 236 general-purpose registers (R4-R239). SPH (R254) can be used as a general-purpose register when using internal stack only. R254 and R255 are set to 00H after any reset or Stop Mode Recovery.

Counter/Timers. There are two 8-bit programmable counter/timers (T0 and T1), each driven by its own 6-bit programmable prescaler. The Ti prescaler is driven by internal or external clock sources; however, the TO prescaler is driven by the internal clock only (see Figure 27).

The 6-bit prescalers can divide the input frequency of the clock source by any integer number from 1 to 64. Each prescaler drives its counter, which decrements the value (1 to 256), that has been loaded into the counter. When the counter reaches the end of count, a timer interrupt request, IRQ4 (T0) or IRQ5 (T1), is generated.

The counters can be programmed to start, stop, restart to continue, or restart from the initial value. The counters can also be programmed to stop upon reaching one (single pass mode) or to automatically reload the initial value and continue counting (modulo-n continuous mode).

The counters, but not the prescalers, can be read at any time without disturbing their value or count mode. The clock source for T1 is user-definable and can be either the internal microprocessor clock divided by four, or an external signal input through Port 3. The Timer Mode register configures the external timer input (P31) as an external clock, a trigger input that can be retriggerable or non-retriggerable, or as a gate input for the internal clock. Port 3 line P36 serves as a timer output (T_{OUT}) through which T0, T1, or the internal clock can be output. The counter/timers can be cascaded by connecting the T0 output to the input of T1.

Comparator Output Port 3 (D0). Bit 0 controls the comparator output in Port 3. A "1" in this location brings the comparator outputs to P34 and P37, and a "0" releases the Port to its standard I/O configuration. The default value is 0.

Port 1 Open-Drain (D1). Port 1 can be configured as an open-drain by resetting this bit (D1=0) or configured as push-pull active by setting this bit (D1=1). The default value is 1.

Port 0 Open-Drain (D2). Port 0 can be configured as an open-drain by resetting this bit (D2=0) or configured as push-pull active by setting this bit (D2=1). The default value is 1.

Low EMI Port 0 (D3). Port 0 can be configured as a Low EMI Port by resetting this bit (D3=0) or configured as a Standard Port by setting this bit (D3=1). The default value is 1.

Low EMI Port 1 (D4). Port 1 can be configured as a Low EMI Port by resetting this bit (D4=0) or configured as a Standard Port by setting this bit (D4=1). The default value is 1.

Note: *The emulator does not support Port 1 low EMI mode and must be set D4 = 1.*

Low EMI Port 2 (D5). Port 2 can be configured as a Low EMI Port by resetting this bit (D5=0) or configured as a Standard Port by setting this bit (D5=1). The default value is 1.

Low EMI Port 3 (D6). Port 3 can be configured as a Low EMI Port by resetting this bit (D6=0) or configured as a Standard Port by setting this bit (D6=1). The default value is 1.

Low EMI OSC (D7). This bit of the PCON Register controls the low EMI noise oscillator. A "1" in this location configures the oscillator with standard drive. While a "0" configures the oscillator with low noise drive, however, it does not affect the relationship of SCLK and XTAL. The low EMI mode will reduce the drive of the oscillator (OSC). The default value is 1.

Note: *4 MHz is the maximum external clock frequency when running in the low EMI oscillator mode.*

Stop-Mode Recovery Register (SMR). This register selects the clock divide value and determines the mode of Stop Mode Recovery (Figure 31). All bits are Write Only except bit 7 which is a Read Only. Bit 7 is a flag bit that is hardware set on the condition of STOP Recovery and reset by a power-on cycle. Bit 6 controls whether a low or high level is required from the recovery source. Bit 5 controls the reset delay after recovery. Bits 2, 3, and 4 of the SMR register specify the Stop Mode Recovery Source. The SMR is located in Bank F of the Expanded Register File at address 0BH.

from STOP mode when programmed as analog inputs. When the Stop Mode Recovery sources are selected in this register then SMR2 register bits D0, D1 must be set to zero.

Note: *If the Port 2 pin is configured as an output, this output level will be read by the SMR circuitry.*

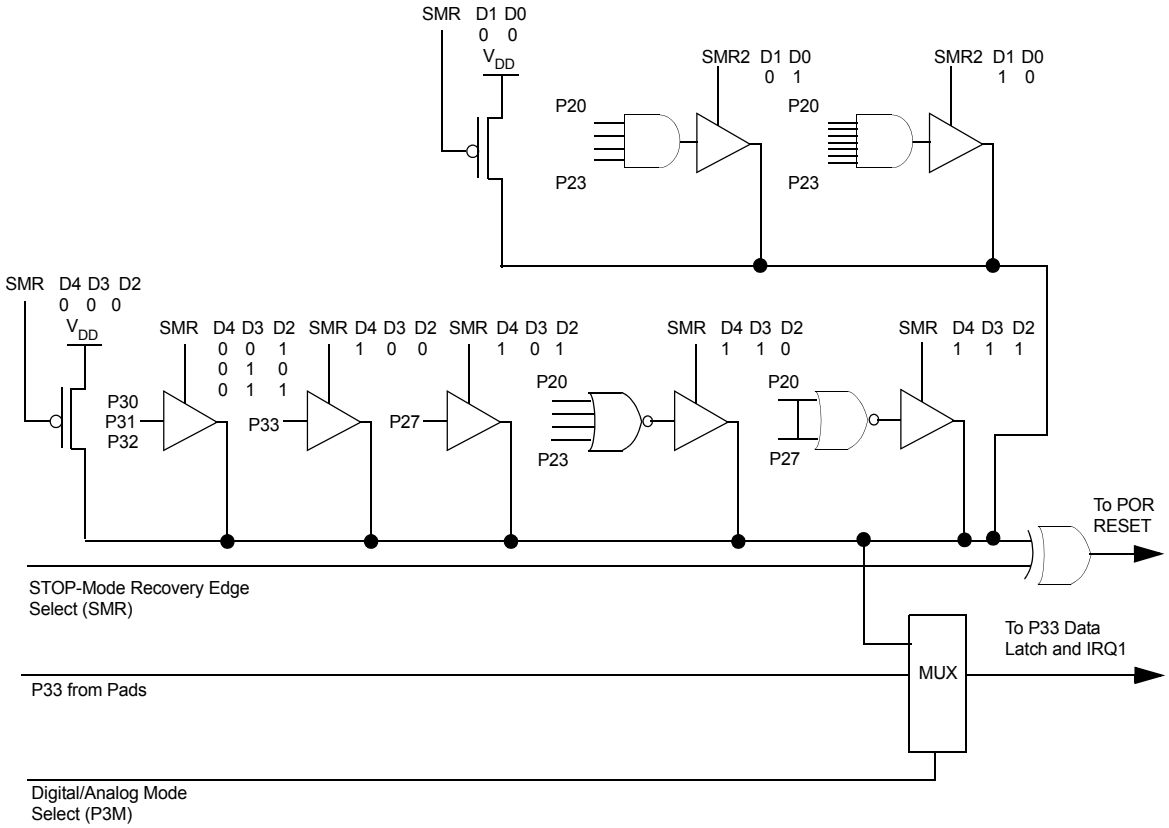


Figure 32. Stop Mode Recovery Source

Reset and initially enabled by executing the WDT instruction and refreshed on subsequent executions of the WDT instruction. The WDT is driven either by an on-board RC oscillator or an external oscillator from XTAL1 pin. The POR clock source is selected with bit 4 of the WDT register.

Note: *Execution of the WDT instruction affects the Z (Zero), S (Sign), and V (Overflow) flags.*

WDT Time-Out Period (D0 and D1). Bits 0 and 1 control a tap circuit that determines the time-out periods that can be obtained (Table 23). The default value of DO and Dl are 1 and 0, respectively.

Table 23. Time-out Period of WDT

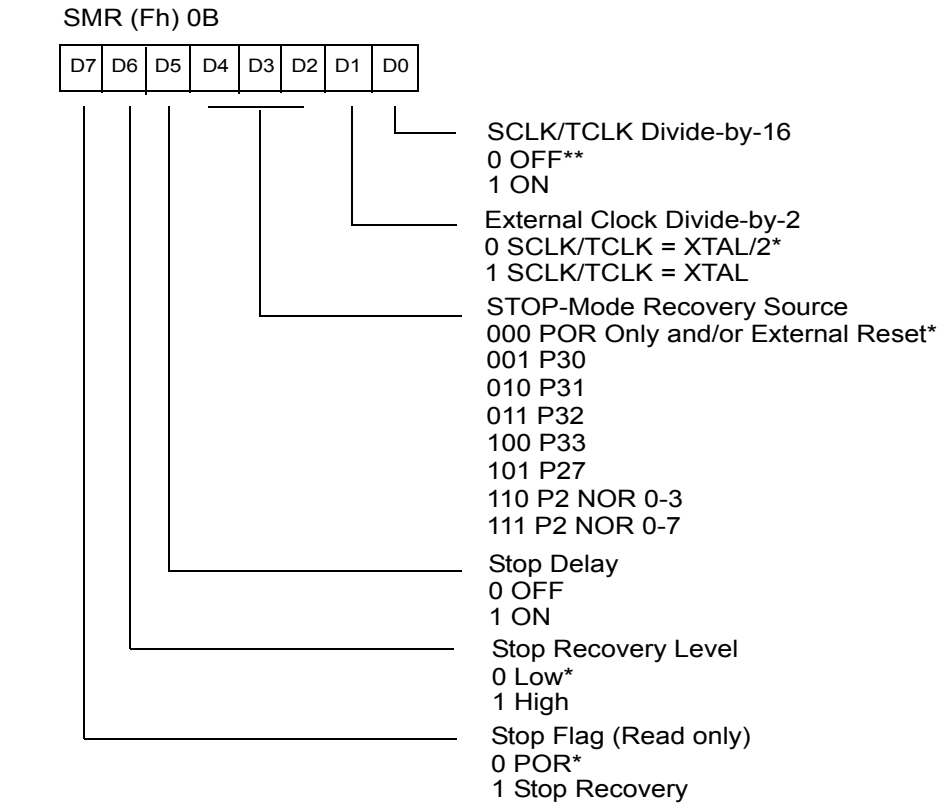
D1	DO	Time-out of the Internal RC OSC	Time-out of the System Clock
0	0	5 ms	128 SCLK
0	1	10 ms[1]	256 SCLK[1]
1	0	20 ms	512 SCLK
1	1	80 ms	2048 SCLK

Note: The default setting is 10 ms.

WDT During HALT Mode (D2). This bit determines whether or not the WDT is active during HALT Mode. A “1” indicates that the WDT is active during HALT. A “0” disables the WDT in HALT Mode. The default value is “1 “. WDT During STOP Mode (D3). This bit determines whether or not the WDT is active during STOP mode. A “1” indicates active during STOP. A “0” disables the WDT during STOP Mode. This is applicable only when the WDT clock source is the internal RC oscillator.

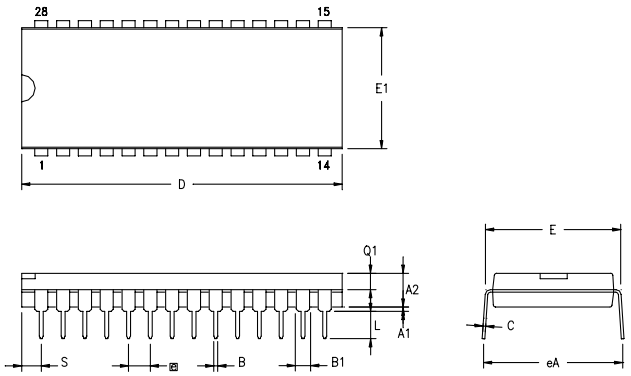
Clock Source For WDT (D4). This bit determines which oscillator source is used to clock the internal POR and WDT counter chain. If the bit is a 1, the internal RC oscillator is bypassed and the POR and WDT clock source is driven from the external pin, XTAL1, and the WDT is stopped in STOP Mode. The default configuration of this bit is 0, which selects the RC oscillator.

Permanent WDT. When this feature is enabled, the WDT is enabled after reset and will operate in Run and HALT Mode. The control bits in the WDTMR do not affect the WDT operation. If the clock source of the WDT is the internal RC oscillator, then the WDT will run in STOP mode. If the clock source of the WDT is the XTAL1 pin, then the WDT will not run in STOP mode.



Note: Note used in conjunction with SMR2 Source
* Default setting after RESET
** Default setting after RESET and STOP-Mode Recovery

Figure 37. Stop Mode Recovery Register (Write Only Except Bit D7, Which is Read Only)

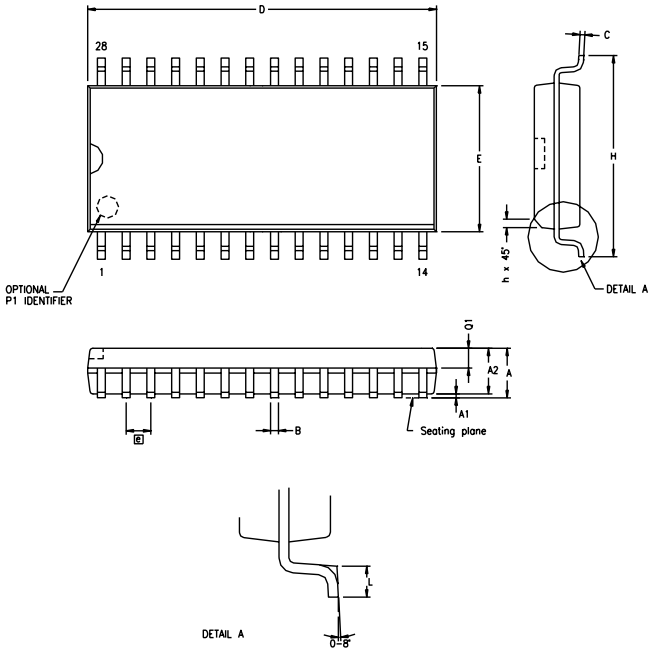


SYMBOL	OPT #	MILLIMETER		INCH	
		MIN	MAX	MIN	MAX
A1		0.38	1.02	.015	.040
A2		3.18	4.19	.125	.165
B		0.38	0.53	.015	.021
B1	01	1.40	1.65	.055	.065
	02	1.14	1.40	.045	.055
C		0.23	0.38	.009	.015
D	01	36.58	37.34	1.440	1.470
	02	35.31	35.94	1.390	1.415
E		15.24	15.75	.600	.620
E1	01	13.59	14.10	.535	.555
	02	12.83	13.08	.505	.515
e		2.54 TYP		.100 TYP	
eA		15.49	16.76	.610	.660
L		3.05	3.81	.120	.150
Q1	01	1.40	1.91	.055	.075
	02	1.40	1.78	.055	.070
S	01	1.52	2.29	.060	.090
	02	1.02	1.52	.040	.060

CONTROLLING DIMENSIONS : INCH

OPTION TABLE	
OPTION #	PACKAGE
01	STANDARD
02	IDF

Figure 58. 28-Pin DIP Package Diagram



SYMBOL	MILLIMETER		INCH	
	MIN	MAX	MIN	MAX
A	2.40	2.64	.094	.104
A1	0.10	0.30	.004	.012
A2	2.24	2.44	.088	.096
B	0.36	0.46	.014	.018
C	0.23	0.30	.009	.012
D	17.78	18.00	.700	.710
E	7.40	7.60	.291	.299
e	1.27 BSC		.050 BSC	
H	10.00	10.65	.394	.419
h	0.30	0.71	.012	.028
L	0.61	1.00	.024	.039
Q1	0.97	1.09	.038	.043

CONTROLLING DIMENSIONS : MM
LEADS ARE COPLANAR WITHIN .004 INCH.

Figure 59. 28-Pin SOIC Package Diagram