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Details

Details	
Product Status	Active
Core Processor	Z8
Core Size	8-Bit
Speed	12MHz
Connectivity	EBI/EMI
Peripherals	POR, WDT
Number of I/O	24
Program Memory Size	4KB (4K x 8)
Program Memory Type	OTP
EEPROM Size	-
RAM Size	237 x 8
Voltage - Supply (Vcc/Vdd)	3.5V ~ 5.5V
Data Converters	-
Oscillator Type	Internal
Operating Temperature	0°C ~ 70°C (TA)
Mounting Type	Through Hole
Package / Case	28-DIP (0.600", 15.24mm)
Supplier Device Package	-
Purchase URL	https://www.e-xfl.com/product-detail/zilog/z86e3312psg

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Table 1. Z86E33/733/E34, E43/743/E44 Features (Continued)

Device	ROM (KB)	RAM ¹ (Bytes)	I/O Lines	Speed (MHz)
Z86E44	16	236	32	12
¹ General-Purpos	se			

- Standard Temperature ($V_{CC} = 3.5 \text{ V to } 5.5 \text{ V}$)
- Extended Temperature ($V_{CC} = 3.5 \text{ V to } 5.5 \text{ V}$)
- Available Packages:
 - 28-Pin DIP/SOIC/PLCC OTP (E33/733/E34)
 - 40-Pin DIP OTP (E43/743/E44)
 - 44-Pin PLCC/LQFP OTP (E43/743/E44)
- Software Enabled Watchdog Timer (WDT)
- Push-Pull/Open-Drain Programmable on Port 0, Port 1, and Port 2
- 24/32 Input/Output Lines
- Clock-Free WDT Reset
- Auto Power-On Reset (POR)
- Programmable OTP Options:
 - RC Oscillator
 - EPROM Protect
 - Auto Latch Disable
 - Permanently Enabled WDT
 - Crystal Oscillator Feedback Resistor Disable
 - RAM Protect
- Low-Power Consumption: 60 mW
- Fast Instruction Pointer: 0.75 µs
- Two Standby Modes: STOP and HALT
- Digital Inputs CMOS Levels, Schmitt-Triggered
- Software Programmable Low EMI Mode
- Two Programmable 8-Bit Counter/Timers Each with a 6-Bit Programmable Prescaler
- Six Vectored, Priority Interrupts from Six Different Sources
- Two Comparators

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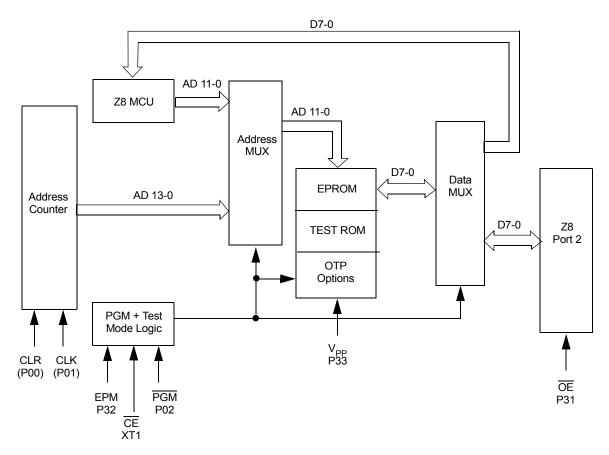


Figure 2. EPROM Programming Block Diagram

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Pin No	Symbol	Function	Direction
15	XTAL1	Crystal Oscillator	Input
16-18	P31-P33	Port 3, Pins 1,2,3	Input
19	P34	Port 3, Pin 4	Output
20	AS	Address Strobe	Output
21	RESET	Reset	Input
22	P35	Port 3, Pin 5	Output
23	P37	Port 3, Pin 7	Output
24	P36	Port 3, Pin 6	Output
25	P30	Port 3, Pin 0	Input
26-27	P00-P01	Port 0, Pins 0,1	Input/Output
28-29	P10-P11	Port 1, Pins 0,1	Input/Output
30	P02	Port 0, Pin 2	Input/Output
31	GND	Ground	
32-33	P12-P13	Port 1, Pins 2,3	Input/Output
34	P03	Port 0, Pin 3	Input/Output
35-39	P20-P24	Port 2, Pins 0, 1,2,3,4	Input/Output
40	DS	Data Strobe	Output

Table 2. 40-Pin DIP Pin Identification Standard Mode (Continued)



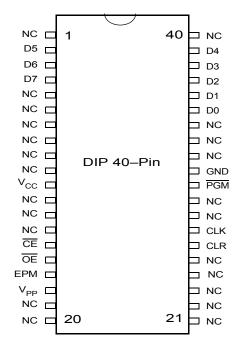


Figure 6. 40-Pin DIP Pin Configuration EPROM Mode

Table 5. 40-Pin DIP Package Pin Identification EPROM Mode

Pin No	Symbol	Function	Direction
1	NC	No Connection	
2-4	D5-D7	Data 5,6,7	Input/Output
5-10	NC	No Connection	
11	V _{CC}	Power Supply	
12-14	NC	No Connection	
15	CE	Chip Select	Input
16	OE	Output Enable	Input
17	EPM	EPROM Prog. Mode	Input
18	V _{PP}	Prog. Voltage	Input
19-25	NC	No Connection	
26	CLR	Clear	Input
27	CLK	Clock	Input
28-29	NC	No Connection	

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Total power dissipation should not exceed 1.21 W for the package. Power dissipation is calculated as follows:

 $\begin{array}{ll} \mbox{Total Power Dissipation} = & V_{DD} \; x \; [I_{DD} - (\mbox{sum of } I_{OH}), \\ & + \; \mbox{sum of } [(V_{DD} - V_{OH}) \; x \; I_{OH}] \\ & + \; \mbox{sum of } (V_{OL} \; x \; I_{OL}) \end{array}$

Standard Test Conditions

The characteristics listed below apply for standard test conditions as noted. All voltages are referenced to GND. Positive current flows into the referenced pin (Test Load).

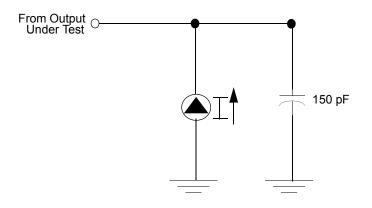


Figure 13. Test Load Diagram

Capacitance

 $T_A = 25$ °C, $V_{CC} = GND = 0$ V, f = 1.0 MHz, unmeasured pins returned to GND.

Parameter	Min	Max
Input capacitance	0	12 pF
Output capacitance	0	12 pF
I/O capacitance	0	12 pF

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Symbol	Parameter	V _{cc} ¹	Min	Max	Typical @ 25°C	Units	Conditions	Notes
V _{OFFSET}	Comparator	3.5V		25	10	mV		
	Input Offset Voltage	5.5V		25	10	mV		
V _{ICR}	Input Common	3.5V	0	V _{CC} -1.0V	,	V		4
	Mode Voltage Range	5.5V	0	V _{CC} -1.0V	,	V		4
I _{IL}	Input	3.5V	-1	2	0.032	μA	$V_{IN} = 0V, V_{CC}$	
	Leakage	5.5V	-1	2	0.032	μA	$V_{IN} = 0V, V_{CC}$	
I _{OL}	Output Leakage	3.5V	-1	2	0.032	μA	V_{IN} = 0V, V_{CC}	
		5.5V	-1	2	0.032	μA	$V_{IN} = 0V, V_{CC}$	
I _{IR}	Reset Input	3.5V	-20	-130	-65	μA		
	Current	5.5V	-20	-180	-112	μA		
I _{CC}	Supply	3.5V		15	5	mA	@ 12 MHz	5,6
	Current	5.5V		20	15	mA	@ 12 MHz	5,6
I _{CC1}	Standby	3.5V		4	2	mA	$V_{IN} = 0V, V_{CC}$	5,6
	Current HALT Mode	5.5V		6	4	mA	@ 12 MHz	5,6
		3.5V		3	1.5	mA	Clock Divide by	5,6
		5.5V		5	3	mA	[–] 16 @ 12 MHz	5,6
CC2	Standby Current	3.5V		10	2	μA	$V_{IN} = 0V, V_{CC}$	7,8,9
	STOP Mode	5.5V		10	3	μA	$V_{IN} = 0V, V_{CC}$	7,8,9
		3.5V		15	7	μA	$V_{IN} = 0V, V_{CC}$	7,8
		5.5V		30	10	μA	$V_{IN} = 0V, V_{CC}$	7,8
ALL	Auto Latch Low	3.0V	0.7	8	2.4	μA	$0V < V_{IN} < V_{CC}$	10
	Current	5.5V	1.4	15	4.7	μA	$0V < V_{IN} < V_{CC}$	10
ALH	Auto Latch High	3.5V	-0.6	-5	-1.8	μA	$0V < V_{IN} < V_{CC}$	10
ALII	Current	5.5V	-1	-8	-3.8	μA	$0V < V_{IN} < V_{CC}$	10

Table 11. DC Electrical Characteristics $T_A = 0$ °C to +70 °C (Continued)

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Symbo I	Parameter	V _{cc} ¹	Min	Мах	Typical @ 25°C	Units	Conditions	Notes
I _{CC2}	Standby Current	4.5V		10	2	μA	$V_{IN} = 0V, V_{CC}$	7,8,9
	STOP Mode	5.5V		10	3	μA	$V_{IN} = 0V, V_{CC}$	7,8,9
		4.5V		40	10	μA	$V_{IN} = 0V, V_{CC}$	7,8
		5.5V		40	10	μA	$V_{IN} = 0V, V_{CC}$	7,8
I _{ALL}	Auto Latch Low Current	4.5V	1.4	20	4.7	μA	$0V < V_{IN} < V_{CC}$	10
		5.5V	1.4	20	4.7	μA	$0V < V_{IN} < V_{CC}$	10
I _{ALH}	Auto Latch High	4.5V	-1.0	-10	-3.8	μA	$0V < V_{IN} < V_{CC}$	10
	Current	5.5V	-1.0	-10	-3.8	μA	$0V < V_{IN} < V_{CC}$	10
T _{POR}	Power-On Reset	4.5V	1.0	14	4	ms		
		5.5V	1.0	14	4	ms		
V _{LV}	Auto Reset Voltage	9	2.0	3.3	2.8	V		11

Table 12. DC Electrical Characteristics T_A= -40 °C to +105 °C (Continued)

Notes

1. The V_{CC} voltage specification of 5.5 V guarantees 5.0 V \pm 0.5 V and the V_{CC} voltage specification of 3.5 V guarantees only 3.5 V.

2. STD Mode (not Low EMI Mode).

3. Z86E43/743/E44 only.

4. For analog comparator inputs when analog comparators are enabled.

5. All outputs unloaded, I/O pins floating, inputs at rail.

- 6. CL1=CL2=22 pF.
- Same as note 5 except inputs at V_{CC}.
 Clock must be forced Low, when XTAL1 is clock driven and XTAL2.
- 9. WDT is not running.
- 10. Auto Latch (mask option) selected.
- 11. Device does function down to the Auto Reset voltage.

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No	Symbol	Parameter	V _{cc} ¹	Min	Max	Min	Max	Units	Notes
5	TwTinH	Timer Input High Width	3.5V	5TpC		5TpC			2,3,4
			5.5V	5TpC		5TpC			2,3,4
6	TpTin	Timer Input Period	3.5V	8TpC		8TpC			2,3,4
			5.5V	8TpC		8TpC			2,3,4
7 TrTin, TfTin	Timer Input Rise & Fall	3.5V		100		100	ns	2,3,4	
	TfTin	Timer	5.5V		100		100	ns	2,3,4
8A	TwIL	Int. Request Low Time	3.5V	100		100		ns	2,3,4,5
			5.5V	70		70		ns	2,3,4,5
8B	TwIL	Int. Request Low Time	3.5V	5TpC		5TpC			2,3,4,6
			5.5V	5TpC		5TpC			2,3,4,6
9	TwIH	Int. Request Input High	3.5V	5TpC		5TpC			2,3,4,5
		Time	5.5V	5TpC		5TpC			2,3,4,5
10	Twsm	Stop Mode Recovery	3.5V	12		12		ns	4,7
		Width Spec	5.5V	12		12		ns	4,7
11	Tost	Oscillator Startup Time	3.5V		5TpC		5TpC		4,7,8
			5.5V		5TpC		5TpC		4,7,8

Table 15. Additional Timing Table (Divide-By-One Mode) $T_A = 0$ °C to +70 °C (Continued)

Notes

1. The V_{CC} voltage specification of 5.5 V guarantees 5.0 V \pm 0.5 V and the V_{CC} voltage specification of 3.5 V guarantees only 3.5 V.

2. Timing Reference uses 0.7 V_{CC} for a logic 1 and 0.2 $V_{CC};$ for a logic 0.

3. SMR D1 = 0.

4. Maximum frequency for internal system clock is 4 MHz when using Low EMI OSC PCON Bit D7 = 0.

5. Interrupt request via Port 3 (P31-P33).

6. Interrupt request via Port 3 (P30).

7. SMR-D5 = 1, POR STOP Mode Delay is on.

8. For RC and LC oscillator, and for oscillator driven by clock driver.

Table 16. Additional Timing Table (Divide-By-One Mode) $T_A = -40$ °C to +105 °C

No	Symbol	Parameter	V _{cc} ¹	Min	Мах	Min	Max	Units	Notes
1	ТрС	Input Clock Period	4.5V	250	DC	166	DC	ns	2,3,4
			5.5V	250	DC	166	DC	ns	2,3,4

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Table 18. Additional Timing Table (Divide by Two Mode) T_A = -40 °C to +105 °C (Continued)

No	Symbol	Parameter	V _{cc} ¹	Min	Max	Min	Max	Units	Conditions	Notes
12	Twdt	Watchdog Timer	3.5V	7		10		ms	D0 =0	8,9
		Delay Time Before	5.5V	3.5		5		ms	D1 = 0	5,11
		Timeout	3.5V	14		20		ms	D0 =1	5,11
			5.5V	7		10		ms	D1 = 0	5,11
			3.5V	28		40		ms	D1 = 0	5,11
			5.5V	14		20		ms	D1 = 1	5,11
			3.5V	112		160		ms	D0 = 1	5,11
			5.5V	56		80		ms	D1 = 1	5,11

Notes

The V_{CC} voltage specification of 5.5 V guarantees 5.0 V ± 0.5 V and the V_{CC} voltage specification of 3.5 V guarantees only 3.5 V.

- 2. Timing Reference uses 0.7 VC0 for a logic 1 and 0.2 VGC for a logic 0.
- 3. SMR D1 = 0.
- 4. SMR-D5 = 1, POR STOP Mode Delay is on
- 5. Interrupt request via Port 3 (P31-P33)
- 6. Interrupt request via Port 3 (P30).
- 7. Maximum frequency for internal system clock is 2 MHz when using Low EMI OSC PCON Bit D7 = 0
- 8. Reg. WDTMR.
- 9. Using internal RC.

Pin Functions

EPROM Programming Mode

D7-D0 Data Bus. The data can be read from or written to external memory through the data bus.

 V_{CC} Power Supply. This pin must supply 5 V during the EPROM read mode and 6 V during other modes.

CE Chip Enable (active Low). This pin is active during EPROM Read Mode, Program Mode, and Program Verify Mode.

OE Output Enable (active Low). This pin drives the direction of the Data Bus. When this pin is Low, the Data Bus is output, when High, the Data Bus is input.

EPM EPROM Program Mode. This pin controls the different EPROM Program Mode by applying different voltages.

 V_{PP} Program Voltage. This pin supplies the program voltage.

PGM Program Mode (active Low). When this pin is Low, the data is programmed to the EPROM through the Data Bus.

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Port 1 can be placed in the high-impedance state along with Port 0, \overline{AS} , \overline{DS} , and R/\overline{W} , allowing the Z86E43/743/E44 to share common resources in multiprocessor and DMA applications. In ROM mode, Port 1 is defined as input after reset.

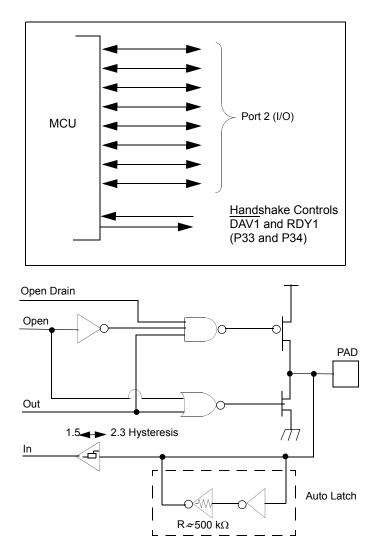


Figure 19. Port 1 Configuration (Z86E43/743/E44 Only)

Port 2 (P27-P20). Port 2 is an 8-bit, bidirectional, CMOS-compatible I/O port. These eight I/O lines can be configured under software control as an input or output, independently. All input buffers are Schmitt-triggered. Bits programmed as outputs can be globally programmed as either push-pull or open-drain. Low EMI output buffers can be globally programmed by the software. When used as an I/O port, Port 2 can be placed under handshake control. After reset, Port 2 is defined as an input.

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In Handshake Mode, Port 3 lines P31 and P36 are used as handshake control lines. The handshake direction is determined by the configuration (input or output) assigned to bit 7 of Port 2 (see Figure 20).

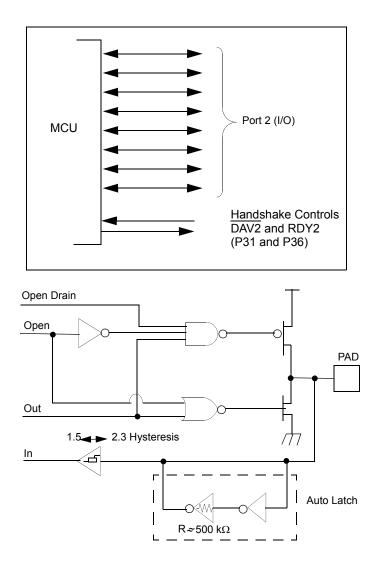


Figure 20. Port 2 Configuration

Port 3 (P37-P30). Port 3 is an 8-bit, CMOS-compatible port with four fixed inputs (P33-P30) and four fixed outputs (P37-P34). These eight lines can be configured by software for interrupt and handshake control functions. Port 3, Pin 0 is Schmitt- triggered. P31, P32, and P33 are standard CMOS inputs with single trip point (no Auto Latches) and P34, P35, P36, and P37 are push-pull output lines. Low EMI output buffers can be globally programmed by the software. Two on-board comparators can process analog signals on P31



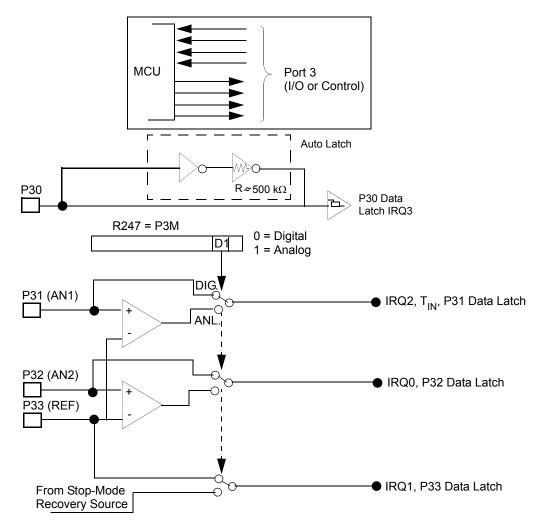


Figure 21. Port 3 Configuration

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Pin	I/O	CTC1	Analog	Interrup	t P0 HS	P1 HS	P2 HS	Ext
P30	IN			IRQ3				
P31	IN	T _{IN}	AN1	IRQ2		D/R		
P32	IN		AN2	IRQ0	D/R			
P33	IN		REF	IRQ1		D/R		
P34	OUT		AN1-Out			R/D		DM
P35	OUT				R/D			
P36	OUT	T _{OUT}				R/D		
P37	OUT		An2-Out					
-								

Table 19. Port 3 Pin Assignments

Comparator Inputs. Port 3, P31, and P32, each have a comparator front end. The comparator reference voltage P33 is common to both comparators. In analog mode, P31 and P32 are the positive input of the comparators and P33 is the reference voltage of the comparators.

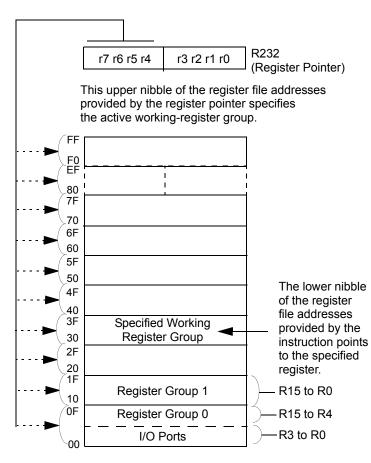
Auto Latch. The Auto Latch puts valid CMOS levels on all CMOS inputs (except P33-P31) that are not externally driven. Whether this level is 0 or 1, cannot be determined. A valid CMOS level, rather than a floating node, reduces excessive supply current flow in the input buffer. Auto Latches are available on Port 0, Port 1, Port 2, and P30. There are no Auto Latches on P31, P32, and P33.

Low EMI Emission. The Z86E43/743/E44 can be programmed to operate in a low EMI Emission Mode in the PCON register. The oscillator and all I/O ports can be programmed as low EMI emission mode independently. Use of this feature results in:

- The pre-drivers slew rate reduced to 10 ns typical.
- Low EMI output drivers have resistance of 200 Ohms (typical).
- Low EMI Oscillator.
- Internal SCLK/TCLK= XTAL operation limited to a maximum of 4 MHz 250 ns cycle time, when Low EMI Oscillator is selected.

Note: For emulation only: Do not set the emulator to emulate Port 1 in low EMI mode. Port 1 must always be configured in Standard Mode.

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* Expanded Register Group (0) is selected in this figure by handling bits D3 to D0 as "0" in Register R253 (RP).

Figure 25. Register Pointer



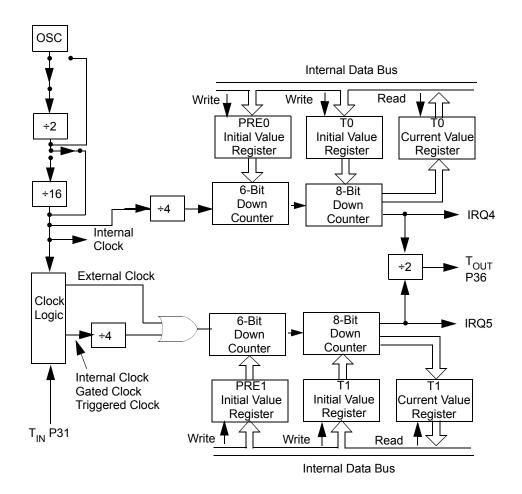


Figure 27. Counter/Timer Block Diagram

Interrupts. The MCU has six different interrupts from six different sources. The interrupts are maskable and prioritized (Figure 28). The six sources are divided as follows: four sources are claimed by Port 3 lines P33-P30) and two in counter/timers. The Interrupt Mask Register globally or individually enables or disables the six interrupt requests (Table 20).

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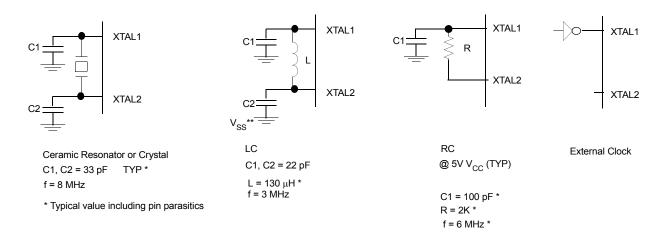


Figure 29. Oscillator Configuration

Power-On Reset (POR). A timer circuit clocked by a dedicated on-board RC oscillator is used for the Power-On Reset (POR) timer function. The POR timer allows V_{CC} and the oscillator circuit to stabilize before instruction execution begins.

The POR timer circuit is a one-shot timer triggered by one of three conditions:

- 1. Power fail to Power OK status
- 2. Stop Mode Recovery (if D5 of SMR=0)
- 3. WDT time-out

The POR time is a nominal 5 ms. Bit 5 of the STOP mode Register (SMR) determines whether the POR timer is by-passed after Stop Mode Recovery (typical for an external clock and RC/LC oscillators with fast start up times).

HALT. Turns off the internal CPU clock, but not the XTAL oscillation. The counter/timers and external interrupt IRQ0, IRQ1, and IRQ2 remain active. The device is recovered by interrupts, either externally or internally generated. An interrupt request must be executed (enabled) to exit HALT Mode. After the interrupt service routine, the program continues from the instruction after the HALT. In order to enter STOP or HALT Mode, it is necessary to first flush the instruction pipeline to avoid suspending execution in mid-instruction. To do this, you must execute a NOP (Opcode = FFh) immediately before the appropriate sleep instruction, that is:

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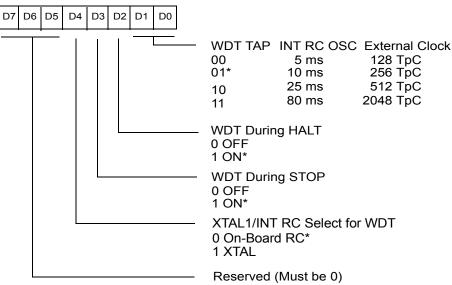
Note: WDT time-out in STOP Mode will not reset SMR,SMR2,PCON, WDTMR, P2M, P3M, Ports 2 & 3 Data Registers, but will activate the T_{POR} delay.

WDTMR Register Accessibility. The WDTMR register is accessible only during the first 60 internal system clock cycles from the execution of the first instruction after Power-On Reset, Watchdog reset or a Stop Mode Recovery (Figure 33 and Figure 34). After this point, the register cannot be modified by any means, intentional or otherwise. The WDTMR cannot be read and is located in Bank F of the Expanded Register File at address location 0Fh.

Clock Free WDT Reset. The WDT will enable the Z8 to reset the I/0 pins whenever the WDT times out, even without a clock source running on the XTAL1 and XTAL2 pins. WDTMR Bit D4 must be 0 for the clock Free WDT to work. The I/O pins will default to their default settings.

WDTMR (F) 0F

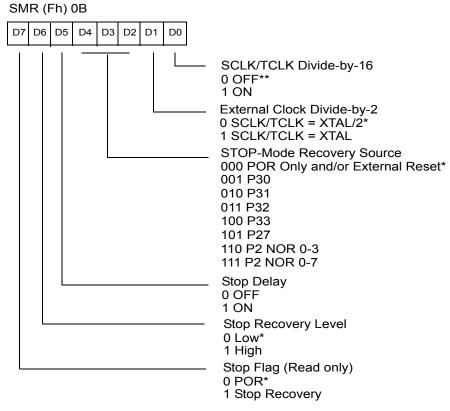
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* Default setting after RESET

Figure 33. Watchdog Timer Mode Register Write Only

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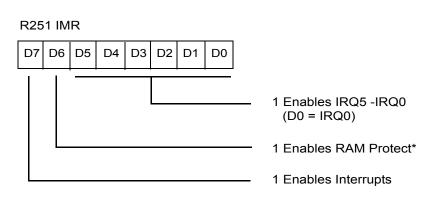
Note: Note used in conjunction with SMR2 Source

* Default setting after RESET

** Default setting after RESET and STOP-Mode Recovery

Figure 37. Stop Mode Recovery Register (Write Only Except Bit D7, Which is Read Only)





* This option must be selected when ROM code is submitted for ROM Masking, otherwise this control bit is disabled permanently



