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### Understanding [Embedded - CPLDs \(Complex Programmable Logic Devices\)](#)

Embedded - CPLDs, or Complex Programmable Logic Devices, are highly versatile digital logic devices used in electronic systems. These programmable components are designed to perform complex logical operations and can be customized for specific applications. Unlike fixed-function ICs, CPLDs offer the flexibility to reprogram their configuration, making them an ideal choice for various embedded systems. They consist of a set of logic gates and programmable interconnects, allowing designers to implement complex logic circuits without needing custom hardware.

### Applications of Embedded - CPLDs

#### Details

Product Status	Obsolete
Programmable Type	EE PLD
Delay Time tpd(1) Max	20 ns
Voltage Supply - Internal	4.5V ~ 5.5V
Number of Logic Elements/Blocks	-
Number of Macrocells	8
Number of Gates	-
Number of I/O	-
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	28-LCC (J-Lead)
Supplier Device Package	28-PLCC (11.51x11.51)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/lattice-semiconductor/gal20v8b-20qjni">https://www.e-xfl.com/product-detail/lattice-semiconductor/gal20v8b-20qjni</a>

## Functional Block Diagram

## Description

## Pin Configuration

**Lead-Free Packaging  
Commercial Grade Specifications**

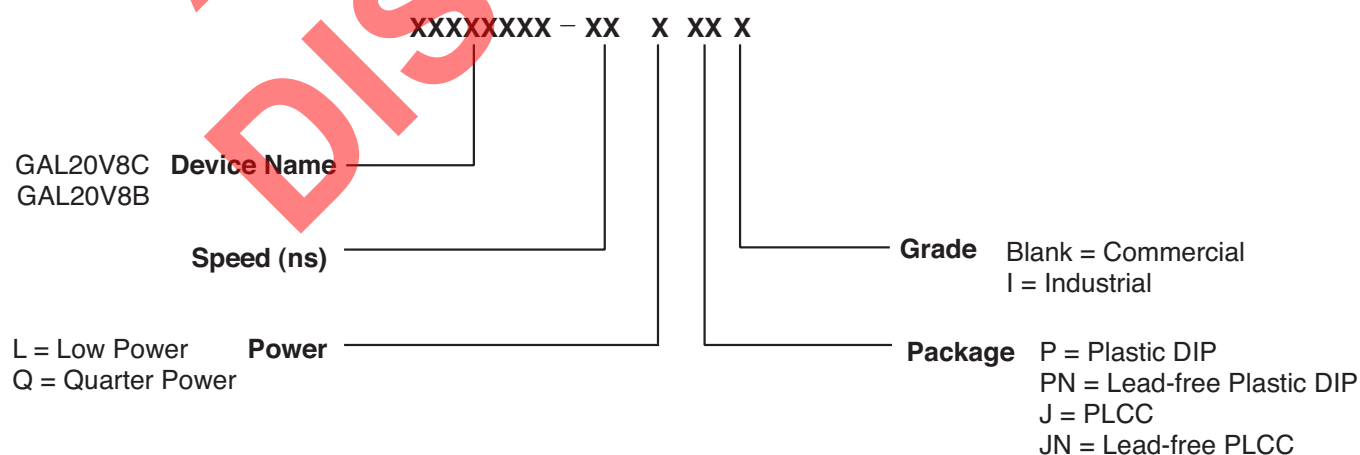
Tpd (ns)	Tsu (ns)	Tco (ns)	Icc (mA)	Ordering #	Package
5	3	4	115	GAL20V8C-5LJN <sup>1</sup>	Lead-Free 28-Lead PLCC
7.5	7	5	115	GAL20V8C-7LJN	Lead-Free 28-Lead PLCC
			115	GAL20V8B-7LPN <sup>1</sup>	Lead-Free 24-Pin Plastic DIP
10	10	7	115	GAL20V8C-10LJN	Lead-Free 28-Lead PLCC
			115	GAL20V8B-10LPN	Lead-Free 24-Pin Plastic DIP
15	12	10	55	GAL20V8B-15QJN	Lead-Free 28-Lead PLCC
			55	GAL20V8B-15QPN	Lead-Free 24-Pin Plastic DIP
			90	GAL20V8B-15LJN	Lead-Free 28-Lead PLCC
			90	GAL20V8B-15LPN	Lead-Free 24-Pin Plastic DIP
25	15	12	55	GAL20V8B-25QJN	Lead-Free 28-Lead PLCC
			55	GAL20V8B-25QPN	Lead-Free 24-Pin Plastic DIP
			90	GAL20V8B-25LJN	Lead-Free 28-Lead PLCC
			90	GAL20V8B-25LPN	Lead-Free 24-Pin Plastic DIP

**Industrial Grade Specifications**

Tpd (ns)	Tsu (ns)	Tco (ns)	Icc (mA)	Ordering #	Package
10	10	7	130	GAL20V8C-10LJN <sup>1</sup>	Lead-Free 28-Pin Plastic DIP
			130	GAL20V8B-10LPN <sup>1</sup>	Lead-Free 24-Pin Plastic DIP
15	12	10	130	GAL20V8B-15LJN <sup>1</sup>	Lead-Free 28-Lead PLCC
			130	GAL20V8B-15LPN <sup>1</sup>	Lead-Free 24-Pin Plastic DIP
20	13	11	65	GAL20V8B-20QJN <sup>1</sup>	Lead-Free 28-Lead PLCC
			65	GAL20V8B-20QPN <sup>1</sup>	Lead-Free 24-Pin Plastic DIP
25	15	12	65	GAL20V8B-25QJN <sup>1</sup>	Lead-Free 28-Lead PLCC
			65	GAL20V8B-25QPN <sup>1</sup>	Lead-Free 24-Pin Plastic DIP
			130	GAL20V8B-25LJN <sup>1</sup>	Lead-Free 28-Lead PLCC
			130	GAL20V8B-25LPN <sup>1</sup>	Lead-Free 24-Pin Plastic DIP

1. Discontinued per PCN #06-07. Contact Rochester Electronics for available inventory.

**Part Number Description**



## Output Logic Macrocell (OLMC)

The following discussion pertains to configuring the output logic macrocell. It should be noted that actual implementation is accomplished by development software/hardware and is completely transparent to the user.

There are three global OLMC configuration modes possible: **simple**, **complex**, and **registered**. Details of each of these modes is illustrated in the following pages. Two global bits, SYN and AC0, control the mode configuration for all macrocells. The XOR bit of each macrocell controls the polarity of the output in any of the three modes, while the AC1 bit of each of the macrocells controls the input/output configuration. These two global and 16 individual architecture bits define all possible configurations in a GAL20V8. The information given on these architecture bits is only to give a better understanding of the device. Compiler software will transparently set these architecture bits from the pin definitions, so the user should not need to directly manipulate these architecture bits.

The following is a list of the PAL architectures that the GAL20V8 can emulate. It also shows the OLMC mode under which the devices emulate the PAL architecture.

PAL Architectures Emulated by GAL20V8	GAL20V8 Global OLMC Mode
20R8 20R6 20R4 20RP8 20RP6 20RP4	Registered Registered Registered Registered Registered Registered
20L8 20H8 20P8	Complex Complex Complex
14L8 16L6 18L4 20L2 14H8 16H6 18H4 20H2 14P8 16P6 18P4 20P2	Simple Simple Simple Simple Simple Simple Simple Simple Simple Simple Simple Simple Simple

## Compiler Support for OLMC

Software compilers support the three different global OLMC modes as different device types. These device types are listed in the table below. Most compilers have the ability to automatically select the device type, generally based on the register usage and output enable (OE) usage. Register usage on the device forces the software to choose the registered mode. All combinatorial outputs with OE controlled by the product term will force the software to choose the complex mode. The software will choose the simple mode only when all outputs are dedicated combinatorial without OE control. The different device types listed in the table can be used to override the automatic device selection by the software. For further details, refer to the compiler software manuals.

When using compiler software to configure the device, the user must pay special attention to the following restrictions in each mode. In **registered mode** pin 1 and pin 13 (DIP pinout) are permanently

configured as clock and output enable, respectively. These pins cannot be configured as dedicated inputs in the registered mode.

In **complex mode** pin 1 and pin 13 become dedicated inputs and use the feedback paths of pin 22 and pin 15 respectively. Because of this feedback path usage, pin 22 and pin 15 do not have the feedback option in this mode.

In **simple mode** all feedback paths of the output pins are routed via the adjacent pins. In doing so, the two inner most pins ( pins 18 and 19) will not have the feedback option as these pins are always configured as dedicated combinatorial output.

	Registered	Complex	Simple	Auto Mode Select
ABEL	P20V8R	P20V8C	P20V8AS	P20V8
CUPL	G20V8MS	G20V8MA	G20V8AS	G20V8
LOG/IC	GAL20V8_R	GAL20V8_C7	GAL20V8_C8	GAL20V8
OrCAD-PLD	"Registered" <sup>1</sup>	"Complex" <sup>1</sup>	"Simple" <sup>1</sup>	GAL20V8A
PLDesigner	P20V8R <sup>2</sup>	P20V8C <sup>2</sup>	P20V8C <sup>2</sup>	P20V8A
TANGO-PLD	G20V8R	G20V8C	G20V8AS <sup>3</sup>	G20V8

1) Used with **Configuration** keyword.

2) Prior to Version 2.0 support.

3) Supported on Version 1.20 or later.

## Registered Mode

In the Registered mode, macrocells are configured as dedicated registered outputs or as I/O functions.

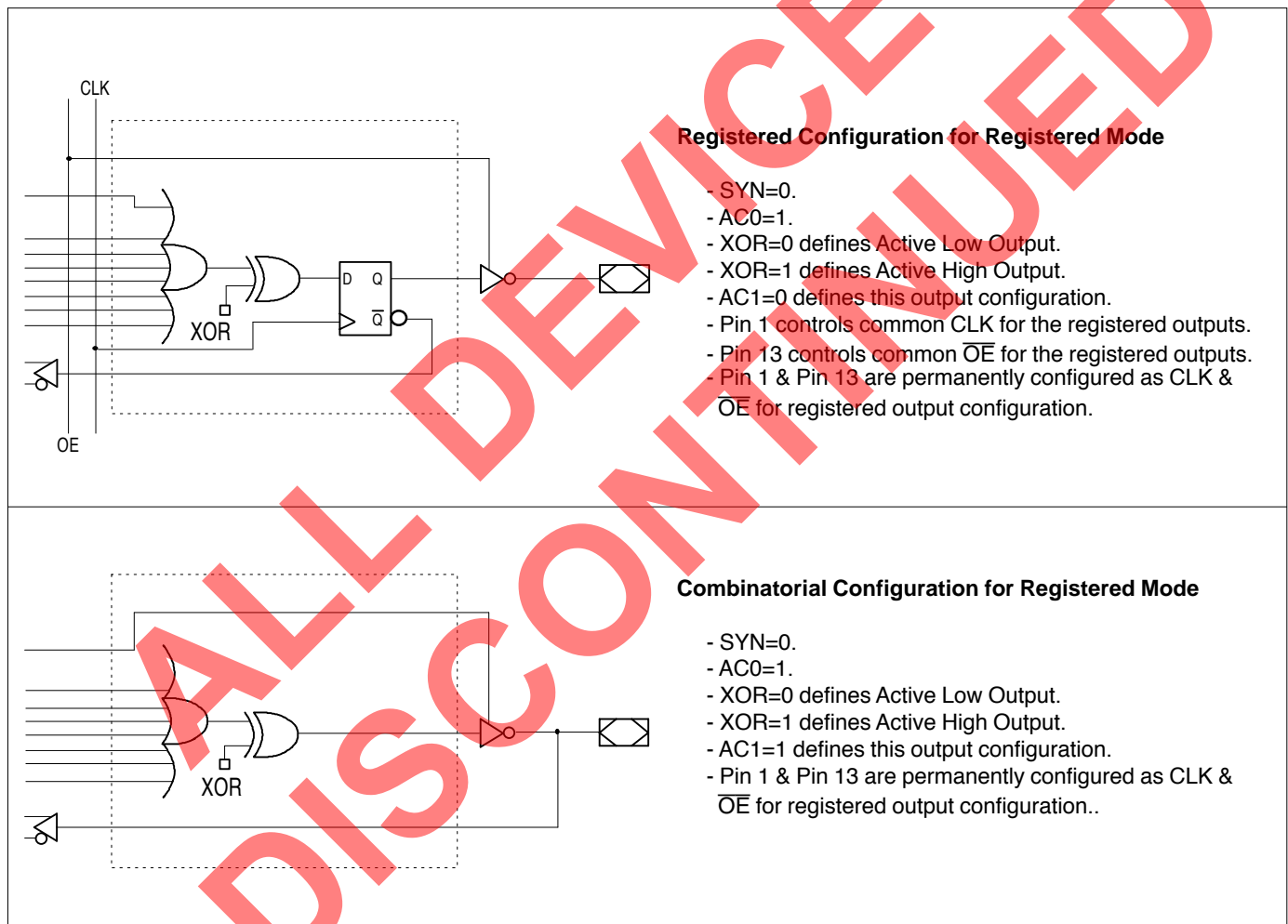
Architecture configurations available in this mode are similar to the common 20R8 and 20RP4 devices with various permutations of polarity, I/O and register placement.

All registered macrocells share common clock and output enable control pins. Any macrocell can be configured as registered or I/O. Up to eight registers or up to eight I/Os are possible in this mode.

Dedicated input or output functions can be implemented as subsets of the I/O function.

Registered outputs have eight product terms per output. I/Os have seven product terms per output.

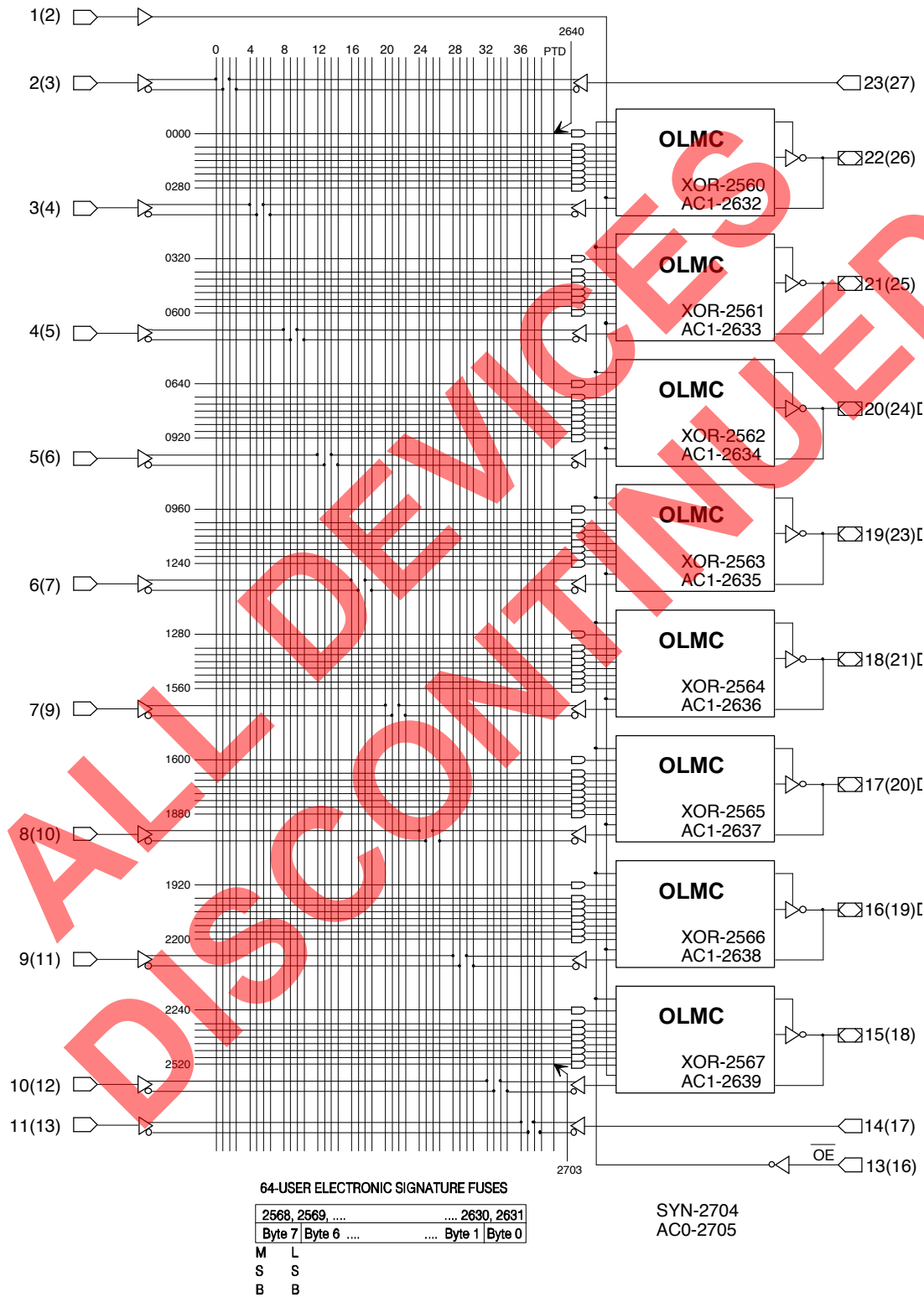
The JEDEC fuse numbers, including the User Electronic Signature (UES) fuses and the Product Term Disable (PTD) fuses, are shown on the logic diagram on the following page.



Note: The development software configures all of the architecture control bits and checks for proper pin usage automatically.

**Registered Mode Logic Diagram**

**DIP (PLCC) Package Pinouts**



## Complex Mode

In the Complex mode, macrocells are configured as output only or I/O functions.

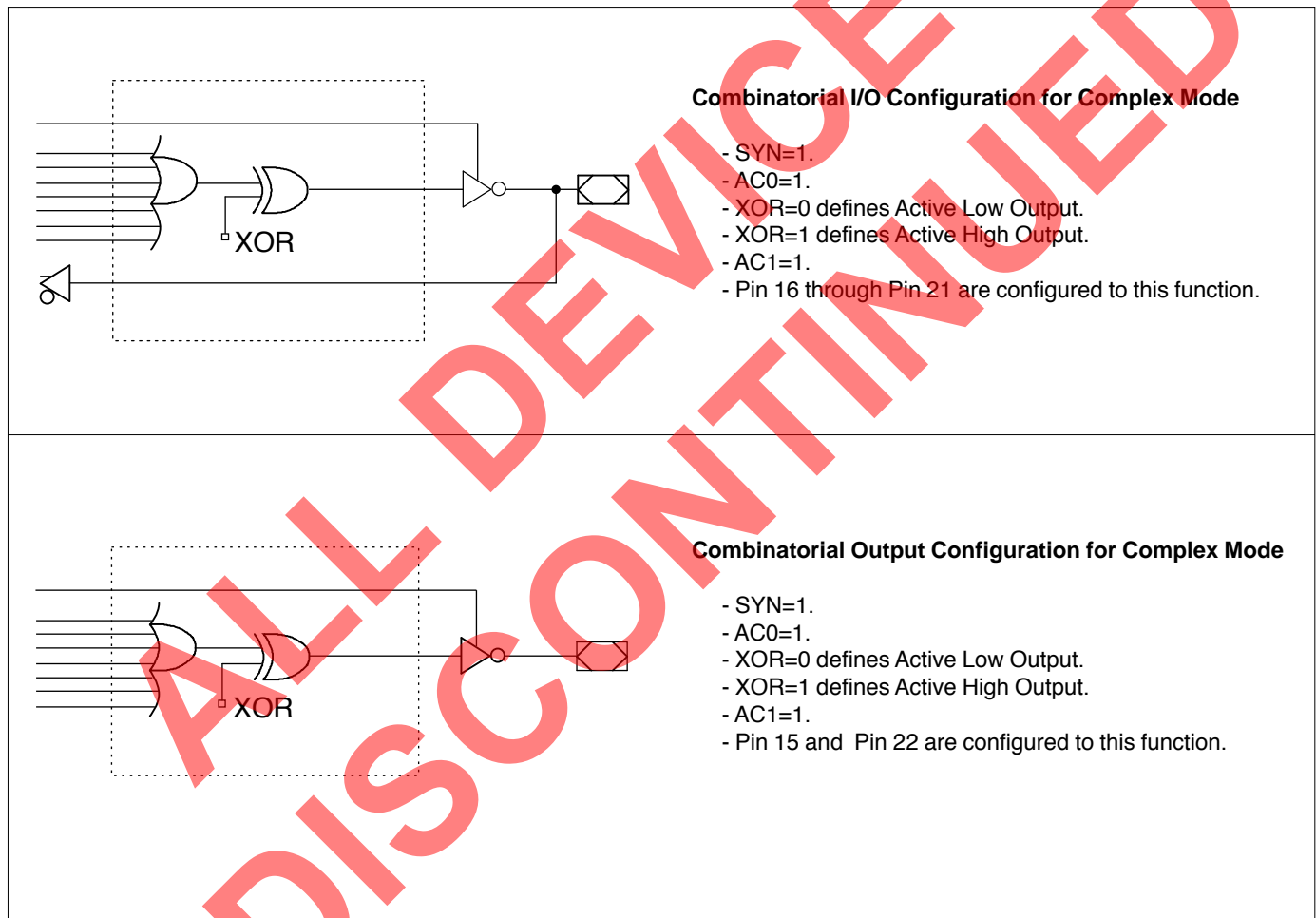
Architecture configurations available in this mode are similar to the common 20L8 and 20P8 devices with programmable polarity in each macrocell.

Up to six I/Os are possible in this mode. Dedicated inputs or outputs can be implemented as subsets of the I/O function. The two outer most macrocells (pins 15 & 22) do not have input capability. De-

signs requiring eight I/Os can be implemented in the Registered mode.

All macrocells have seven product terms per output. One product term is used for programmable output enable control. Pins 1 and 13 are always available as data inputs into the AND array.

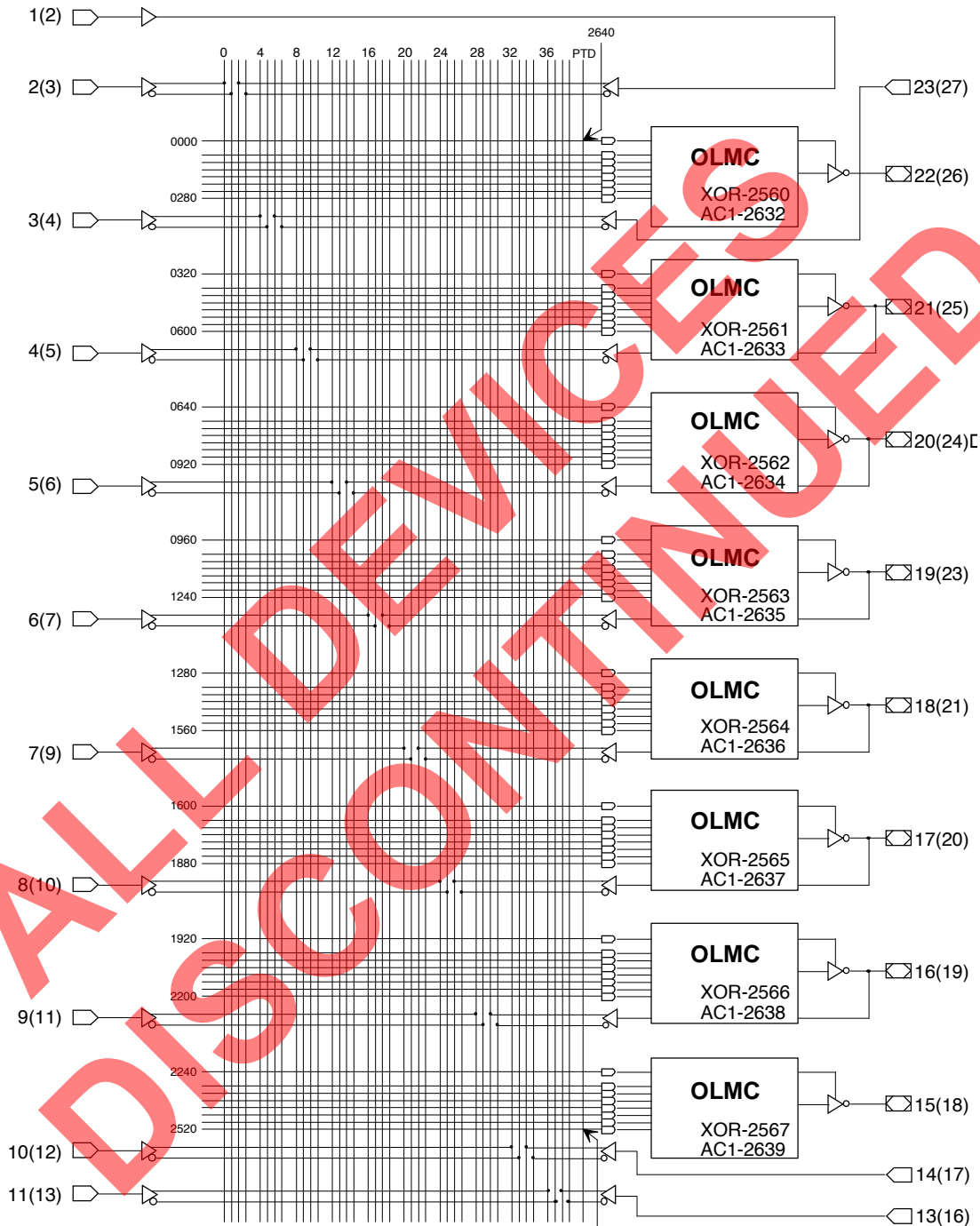
The JEDEC fuse numbers including the UES fuses and PTD fuses are shown on the logic diagram on the following page.



Note: The development software configures all of the architecture control bits and checks for proper pin usage automatically.

**Complex Mode Logic Diagram**

**DIP (PLCC) Package Pinouts**



**64-USER ELECTRONIC SIGNATURE FUSES**

2568, 2569, ....	.... 2630, 2631
Byte 7 Byte 6 ....	.... Byte 1 Byte 0

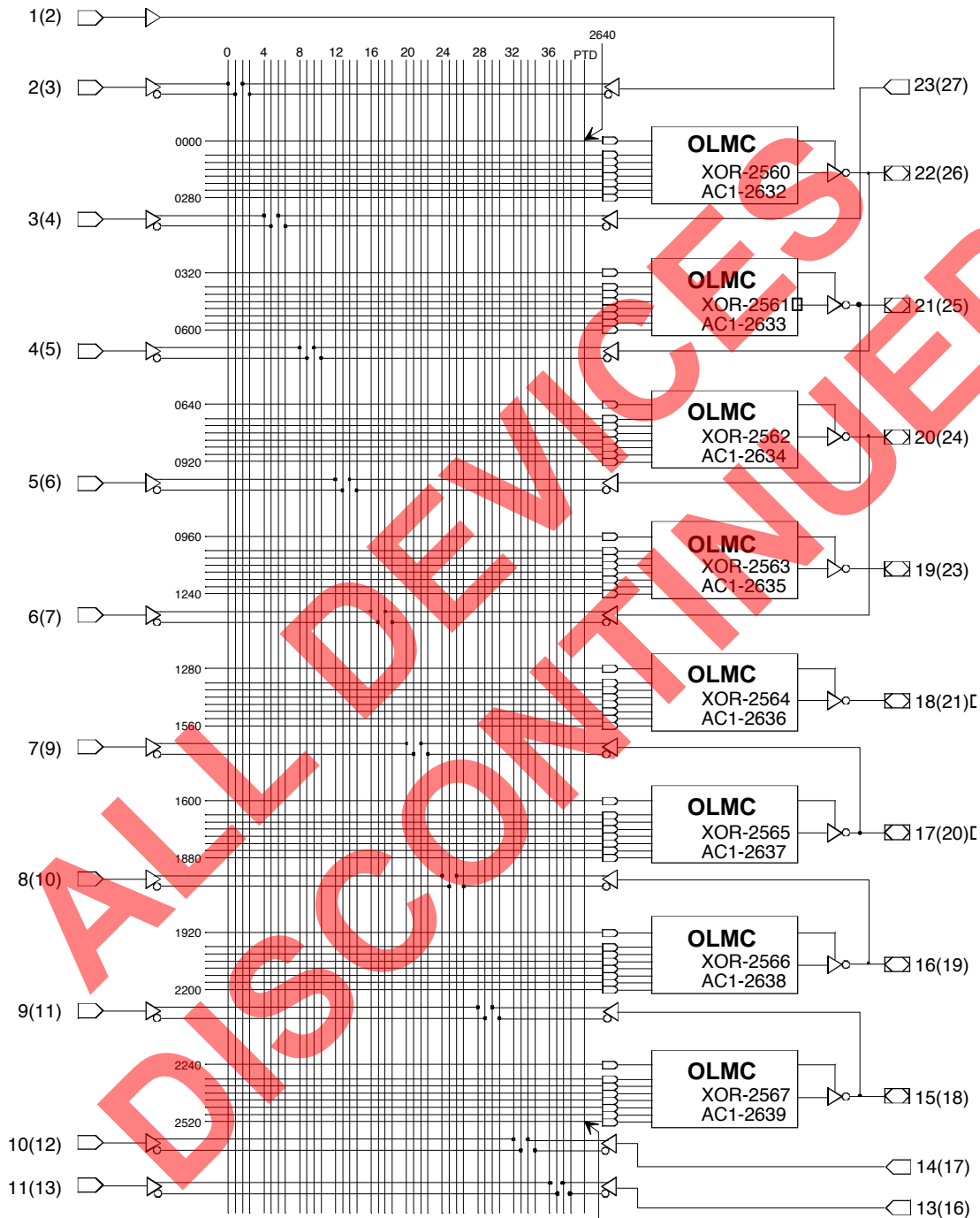
M L  
S S  
B B

SYN-2704  
AC0-2705



**Simple Mode Logic Diagram**

**DIP (PLCC) Package Pinouts**



**64-USER ELECTRONIC SIGNATURE FUSES**

2568, 2569, ....	.... 2630, 2631
Byte 7 Byte 6 ....	.... Byte 1 Byte 0
M L	
S S	
B B	

SYN-2704  
AC0-2705

## Absolute Maximum Ratings<sup>(1)</sup>

Supply voltage  $V_{CC}$  ..... -0.5 to +7V  
 Input voltage applied ..... -2.5 to  $V_{CC} + 1.0V$   
 Off-state output voltage applied ..... -2.5 to  $V_{CC} + 1.0V$   
 Storage Temperature ..... -65 to 150°C  
 Ambient Temperature with

Power Applied ..... -55 to 125°C

1. Stresses above those listed under the "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress only ratings and functional operation of the device at these or at any other conditions above those indicated in the operational sections of this specification is not implied (while programming, follow the programming specifications).

## Recommended Operating Conditions

### Commercial Devices:

Ambient Temperature ( $T_A$ ) ..... 0 to 75°C  
 Supply voltage ( $V_{CC}$ )  
 with Respect to Ground ..... +4.75 to +5.25V

### Industrial Devices:

Ambient Temperature ( $T_A$ ) ..... -40 to 85°C  
 Supply voltage ( $V_{CC}$ )  
 with Respect to Ground ..... +4.50 to +5.50V

## DC Electrical Characteristics

Over Recommended Operating Conditions (Unless Otherwise Specified)

SYMBOL	PARAMETER	CONDITION	MIN.	TYP. <sup>3</sup>	MAX.	UNITS
$V_{IL}$	Input Low Voltage		$V_{SS} - 0.5$	—	0.8	V
$V_{IH}$	Input High Voltage		2.0	—	$V_{CC} + 1$	V
$I_{IL}^1$	Input or I/O Low Leakage Current	$0V \leq V_{IN} \leq V_{IL} (MAX.)$	—	—	-100	$\mu A$
$I_{IH}$	Input or I/O High Leakage Current	$3.5V \leq V_{IN} \leq V_{CC}$	—	—	10	$\mu A$
$V_{OL}$	Output Low Voltage	$I_{OL} = MAX.$ $V_{IN} = V_{IL}$ or $V_{IH}$	—	—	0.5	V
$V_{OH}$	Output High Voltage	$I_{OH} = MAX.$ $V_{IN} = V_{IL}$ or $V_{IH}$	2.4	—	—	V
$I_{OL}$	Low Level Output Current		—	—	16	mA
$I_{OH}$	High Level Output Current		—	—	-3.2	mA
$I_{OS}^2$	Output Short Circuit Current	$V_{CC} = 5V$ $V_{OUT} = 0.5V$ $T_A = 25^\circ C$	-30	—	-150	mA

### COMMERCIAL

$I_{CC}$	Operating Power Supply Current	$V_{IL} = 0.5V$ $V_{IH} = 3.0V$ $f_{toggle} = 15MHz$ Outputs Open	L -5/-7/-10	—	75	115	mA
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### INDUSTRIAL

$I_{CC}$	Operating Power Supply Current	$V_{IL} = 0.5V$ $V_{IH} = 3.0V$ $f_{toggle} = 15MHz$ Outputs Open	L-10	—	75	130	mA
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1) The leakage current is due to the internal pull-up resistor on all pins. See **Input Buffer** section for more information.

2) One output at a time for a maximum duration of one second.  $V_{out} = 0.5V$  was selected to avoid test problems caused by tester ground degradation. Characterized but not 100% tested.

3) Typical values are at  $V_{CC} = 5V$  and  $T_A = 25^\circ C$

## AC Switching Characteristics

Over Recommended Operating Conditions

				COM		COM		COM/IND		UNITS
PARAMETER	TEST COND <sup>1</sup> .	DESCRIPTION		-5		-7		-10		
				MIN.	MAX.	MIN.	MAX.	MIN.	MAX.	
<b>t<sub>pd</sub></b>	A	Input or I/O to	8 outputs switching	1	5	3	7.5	3	10	ns
		Comb. Output	1 output switching	—	—	—	7	—	—	ns
<b>t<sub>co</sub></b>	A	Clock to Output Delay		1	4	2	5	2	7	ns
<b>t<sub>cf</sub><sup>2</sup></b>	—	Clock to Feedback Delay		—	3	—	3	—	6	ns
<b>t<sub>su</sub></b>	—	Setup Time, Input or Feedback before Clock↑		3	—	5	—	7.5	—	ns
<b>t<sub>h</sub></b>	—	Hold Time, Input or Feedback after Clock↑		0	—	0	—	0	—	ns
<b>f<sub>max</sub><sup>3</sup></b>	A	Maximum Clock Frequency with External Feedback, 1/(t <sub>su</sub> + t <sub>co</sub> )		142.8	—	100	—	66.7	—	MHz
	A	Maximum Clock Frequency with Internal Feedback, 1/(t <sub>su</sub> + t <sub>cf</sub> )		166	—	125	—	71.4	—	MHz
	A	Maximum Clock Frequency with No Feedback		166	—	125	—	83.3	—	MHz
<b>t<sub>wh</sub></b>	—	Clock Pulse Duration, High		3	—	4	—	6	—	ns
<b>t<sub>wl</sub></b>	—	Clock Pulse Duration, Low		3	—	4	—	6	—	ns
<b>t<sub>en</sub></b>	B	Input or I/O to Output Enabled		1	6	3	9	3	10	ns
	B	OE to Output Enabled		1	6	2	6	2	10	ns
<b>t<sub>dis</sub></b>	C	Input or I/O to Output Disabled		1	5	2	9	2	10	ns
	C	OE to Output Disabled		1	5	1.5	6	1.5	10	ns

1) Refer to **Switching Test Conditions** section.

2) Calculated from f<sub>max</sub> with internal feedback. Refer to **f<sub>max</sub> Descriptions** section.

3) Refer to **f<sub>max</sub> Descriptions** section. Characterized initially and after any design or process changes that may affect these parameters.

## Capacitance (T<sub>A</sub> = 25°C, f = 1.0 MHz)

SYMBOL	PARAMETER	MAXIMUM*	UNITS	TEST CONDITIONS
C <sub>I</sub>	Input Capacitance	8	pF	V <sub>CC</sub> = 5.0V, V <sub>I</sub> = 2.0V
C <sub>I/O</sub>	I/O Capacitance	8	pF	V <sub>CC</sub> = 5.0V, V <sub>I/O</sub> = 2.0V

\*Characterized but not 100% tested

## AC Switching Characteristics

Over Recommended Operating Conditions

PARAM.	TEST COND <sup>1</sup> .	DESCRIPTION		COM		COM / IND		COM / IND		IND		COM / IND		UNITS
				-7		-10		-15		-20		-25		
				MIN.	MAX.	MIN.	MAX.	MIN.	MAX.	MIN.	MAX.	MIN.	MAX.	
<b>t<sub>pd</sub></b>	A	Input or I/O to Comb. Output	8 outputs switching	3	7.5	3	10	3	15	3	20	3	25	ns
			1 output switching	—	7	—	—	—	—	—	—	—	—	ns
<b>t<sub>co</sub></b>	A	Clock to Output Delay		2	5	2	7	2	10	2	11	2	12	ns
<b>t<sub>cf</sub><sup>2</sup></b>	—	Clock to Feedback Delay		—	3	—	6	—	8	—	9	—	10	ns
<b>t<sub>su</sub></b>	—	Setup Time, Input or Fdbk before Clk↑		7	—	10	—	12	—	13	—	15	—	ns
<b>t<sub>h</sub></b>	—	Hold Time, Input or Fdbk after Clk↑		0	—	0	—	0	—	0	—	0	—	ns
<b>f<sub>max</sub><sup>3</sup></b>	A	Maximum Clock Frequency with External Feedback, 1/(t <sub>su</sub> + t <sub>co</sub> )		83.3	—	58.8	—	45.5	—	41.6	—	37	—	MHz
	A	Maximum Clock Frequency with Internal Feedback, 1/(t <sub>su</sub> + t <sub>cf</sub> )		100	—	62.5	—	50	—	45.4	—	40	—	MHz
	A	Maximum Clock Frequency with No Feedback		100	—	62.5	—	62.5	—	50	—	41.7	—	MHz
<b>t<sub>wh</sub></b>	—	Clock Pulse Duration, High		5	—	8	—	8	—	10	—	12	—	ns
<b>t<sub>wl</sub></b>	—	Clock Pulse Duration, Low		5	—	8	—	8	—	10	—	12	—	ns
<b>t<sub>en</sub></b>	B	Input or I/O to Output Enabled		3	9	3	10	—	15	—	18	—	25	ns
	B	$\overline{\text{OE}}$ to Output Enabled		2	6	2	10	—	15	—	18	—	20	ns
<b>t<sub>dis</sub></b>	C	Input or I/O to Output Disabled		2	9	2	10	—	15	—	18	—	25	ns
	C	$\overline{\text{OE}}$ to Output Disabled		1.5	6	1.5	10	—	15	—	18	—	20	ns

1) Refer to **Switching Test Conditions** section.

2) Calculated from f<sub>max</sub> with internal feedback. Refer to **f<sub>max</sub> Descriptions** section.

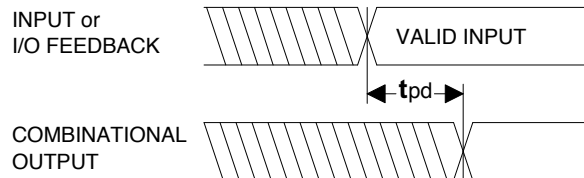
3) Refer to **f<sub>max</sub> Descriptions** section.

## Capacitance (T<sub>A</sub> = 25°C, f = 1.0 MHz)

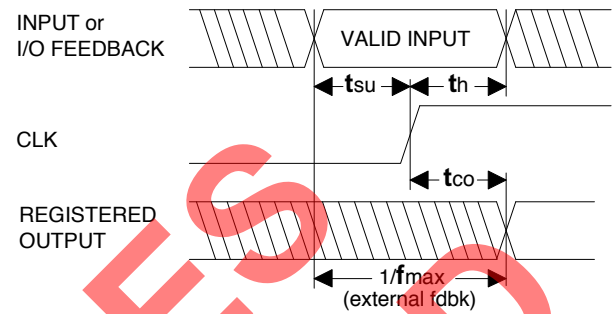
SYMBOL	PARAMETER	MAXIMUM*	UNITS	TEST CONDITIONS
C <sub>I</sub>	Input Capacitance	8	pF	V <sub>CC</sub> = 5.0V, V <sub>I</sub> = 2.0V
C <sub>I/O</sub>	I/O Capacitance	8	pF	V <sub>CC</sub> = 5.0V, V <sub>I/O</sub> = 2.0V

\*Characterized but not 100% tested.

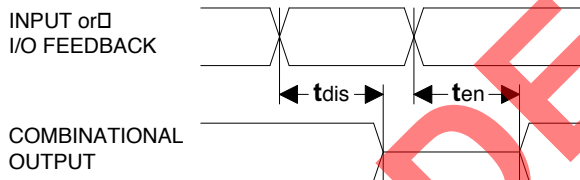
**Switching Waveforms**



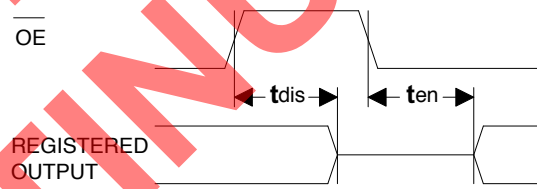
**Combinatorial Output**



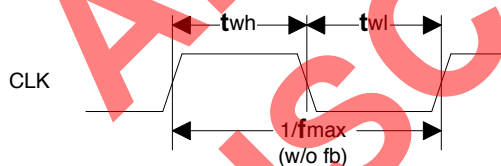
**Registered Output**



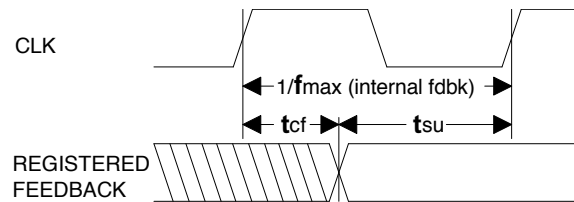
**Input or I/O to Output Enable/Disable**



**OE to Output Enable/Disable**

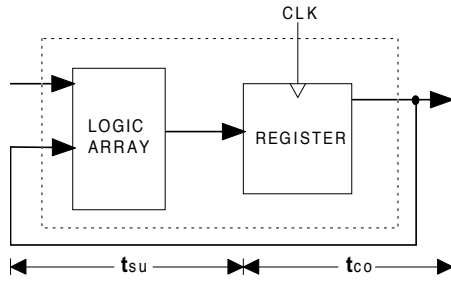


**Clock Width**



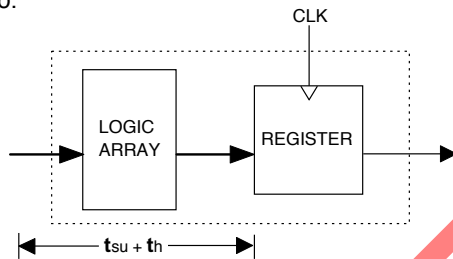
**$f_{max}$  with Feedback**

## fmax Descriptions



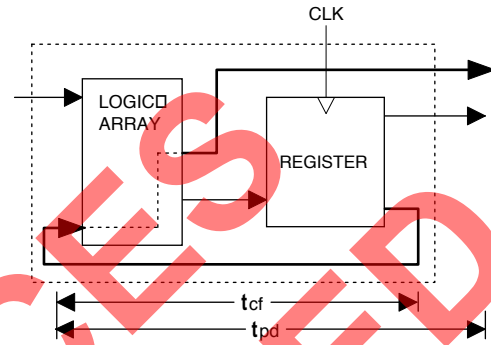
**fmax with External Feedback  $1/(tsu+tco)$**

**Note:** fmax with external feedback is calculated from measured tsu and tco.



**fmax with No Feedback**

**Note:** fmax with no feedback may be less than  $1/(twh + twl)$ . This is to allow for a clock duty cycle of other than 50%.



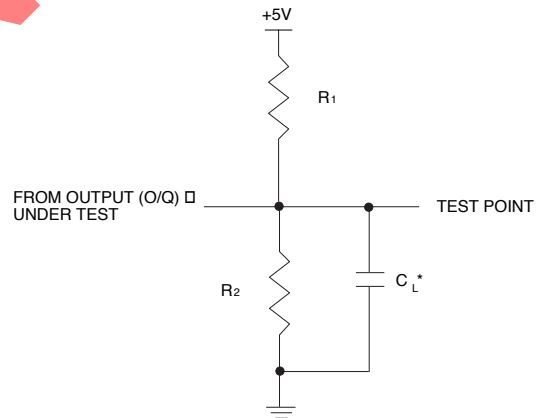
**fmax with Internal Feedback  $1/(tsu+tcf)$**

**Note:** tcf is a calculated value, derived by subtracting tsu from the period of fmax w/internal feedback ( $tcf = 1/fmax - tsu$ ). The value of tcf is used primarily when calculating the delay from clocking a register to a combinational output (through registered feedback), as shown above. For example, the timing from clock to a combinational output is equal to  $tcf + tpd$ .

## Switching Test Conditions

Input Pulse Levels		GND to 3.0V
Input Rise and Fall Times	GAL20V8B	2 – 3ns 10% – 90%
	GAL20V8C	1.5ns 10% – 90%
Input Timing Reference Levels		1.5V
Output Timing Reference Levels		1.5V
Output Load		See Figure

3-state levels are measured 0.5V from steady-state active level.



\*CL INCLUDES TEST FIXTURE AND PROBE CAPACITANCE

### GAL20V8B Output Load Conditions (see figure)

Test Condition	R1	R2	CL
A	200Ω	390Ω	50pF
B	∞	390Ω	50pF
C	200Ω	390Ω	5pF

### GAL20V8C Output Load Conditions (see figure)

Test Condition	R1	R2	CL
A	200Ω	200Ω	50pF
B	∞	200Ω	50pF
C	200Ω	200Ω	5pF

## Electronic Signature

An electronic signature is provided in every GAL20V8 device. It contains 64 bits of reprogrammable memory that can contain user defined data. Some uses include user ID codes, revision numbers, or inventory control. The signature data is always available to the user independent of the state of the security cell.

NOTE: The electronic signature is included in checksum calculations. Changing the electronic signature will alter the checksum.

## Security Cell

A security cell is provided in the GAL20V8 devices to prevent unauthorized copying of the array patterns. Once programmed, this cell prevents further read access to the functional bits in the device. This cell can only be erased by re-programming the device, so the original configuration can never be examined once this cell is programmed. The Electronic Signature is always available to the user, regardless of the state of this control cell.

## Latch-Up Protection

GAL20V8 devices are designed with an on-board charge pump to negatively bias the substrate. The negative bias minimizes the potential of latch-up caused by negative input undershoots. Additionally, outputs are designed with n-channel pull-ups instead of the traditional p-channel pull-ups in order to eliminate latch-up due to output overshoots.

## Device Programming

GAL devices are programmed using a Lattice Semiconductor-approved Logic Programmer, available from a number of manufacturers. Complete programming of the device takes only a few seconds. Erasing of the device is transparent to the user, and is done automatically as part of the programming cycle.

## Output Register Preload

When testing state machine designs, all possible states and state transitions must be verified in the design, not just those required in the normal machine operations. This is because, in system operation, certain events occur that may throw the logic into an illegal state (power-up, line voltage glitches, brown-outs, etc.). To test a design for proper treatment of these conditions, a way must be provided to break the feedback paths, and force any desired (i.e., illegal) state into the registers. Then the machine can be sequenced and the outputs tested for correct next state conditions.

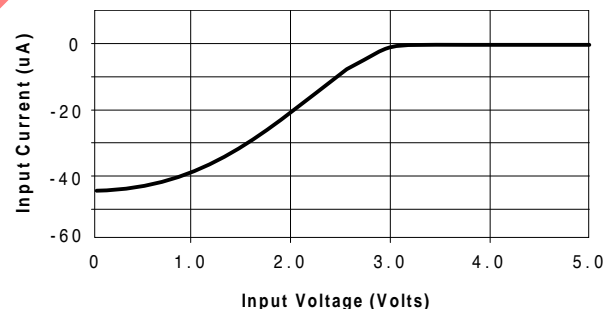
GAL20V8 devices include circuitry that allows each registered output to be synchronously set either high or low. Thus, any present state condition can be forced for test sequencing. If necessary, approved GAL programmers capable of executing test vectors perform output register preload automatically.

## Input Buffers

GAL20V8 devices are designed with TTL level compatible input buffers. These buffers have a characteristically high impedance, and present a much lighter load to the driving logic than bipolar TTL devices.

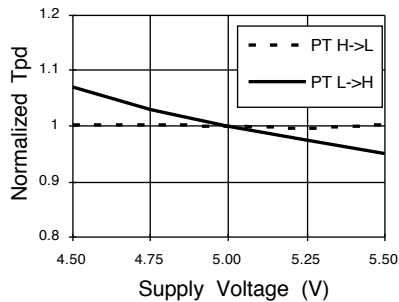
The GAL20V8 input and I/O pins have built-in active pull-ups. As a result, unused inputs and I/O's will float to a TTL "high" (logical "1"). Lattice Semiconductor recommends that all unused inputs and tri-stated I/O pins be connected to another active input, V<sub>CC</sub>, or Ground. Doing this will tend to improve noise immunity and reduce I<sub>CC</sub> for the device.

**Typical Input Pull-up Characteristic**

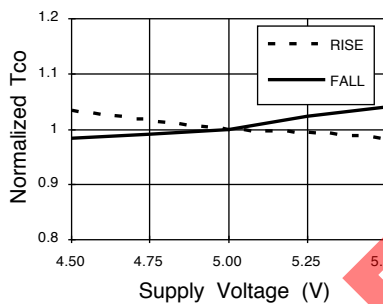


**GAL20V8C: Typical AC and DC Characteristic Diagrams**

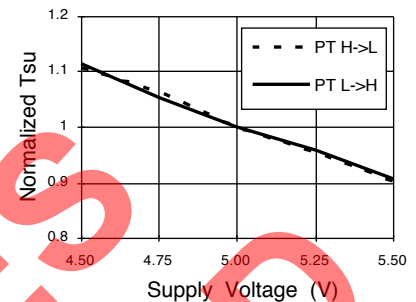
**Normalized Tpd vs Vcc**



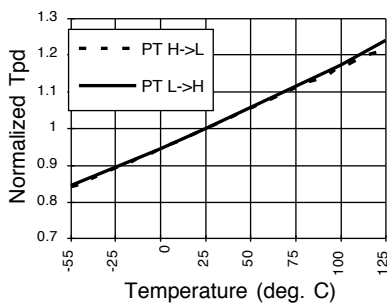
**Normalized Tco vs Vcc**



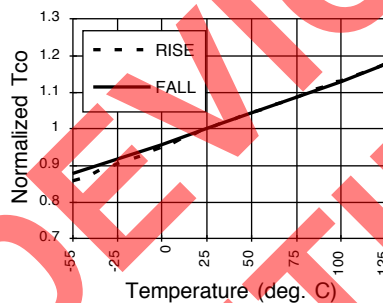
**Normalized Tsu vs Vcc**



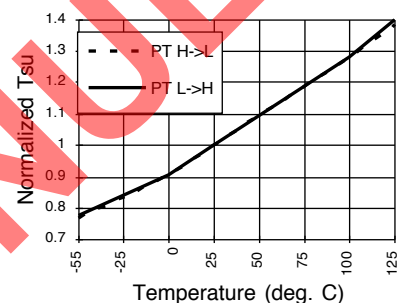
**Normalized Tpd vs Temp**



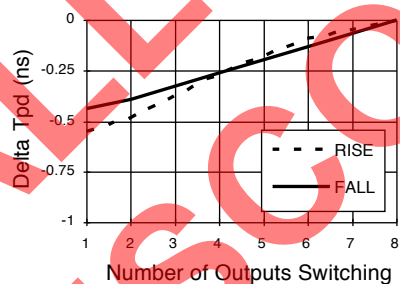
**Normalized Tco vs Temp**



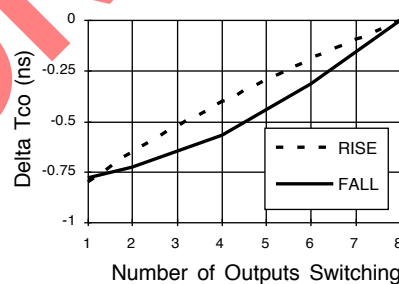
**Normalized Tsu vs Temp**



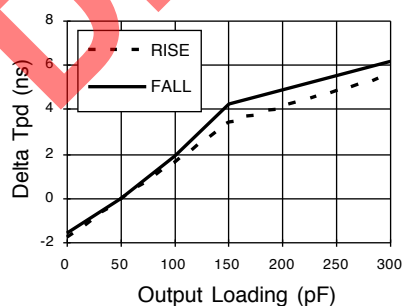
**Delta Tpd vs # of Outputs Switching**



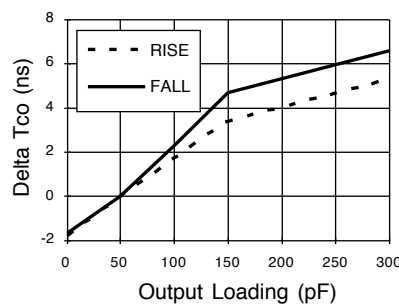
**Delta Tco vs # of Outputs Switching**



**Delta Tpd vs Output Loading**

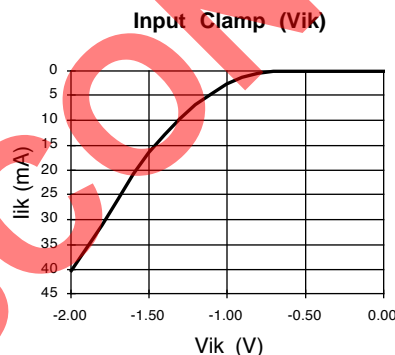
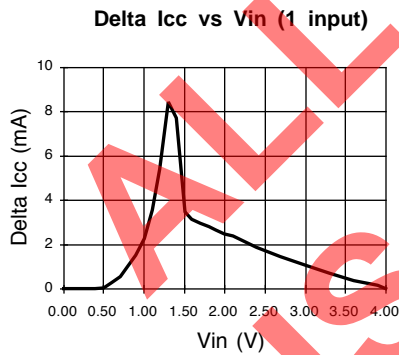
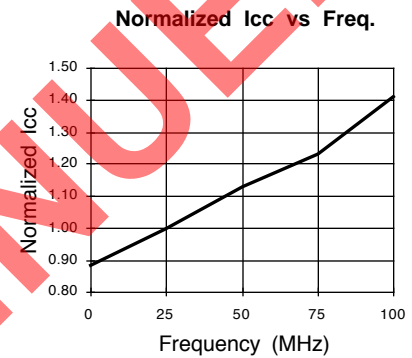
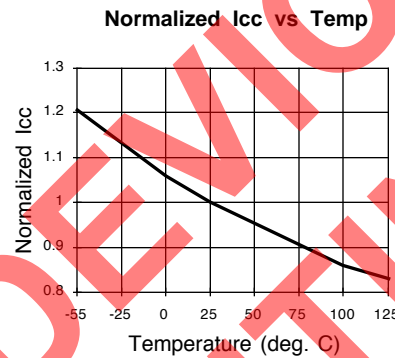
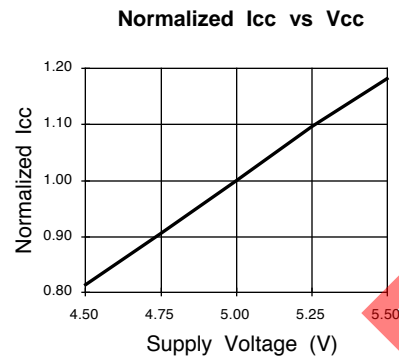
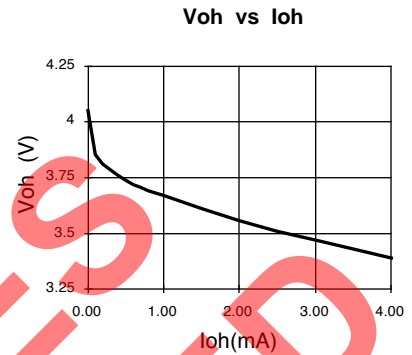
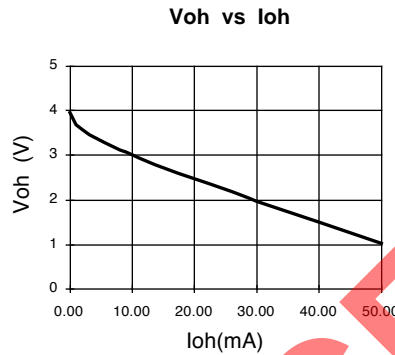
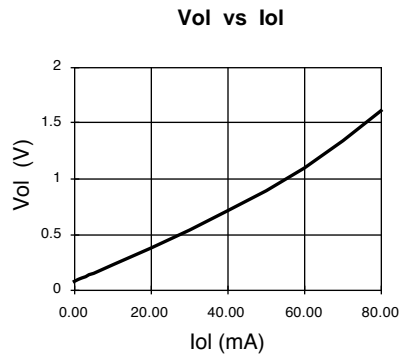


**Delta Tco vs Output Loading**



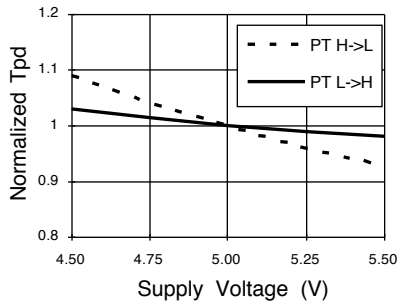


**GAL20V8C: Typical AC and DC Characteristic Diagrams**

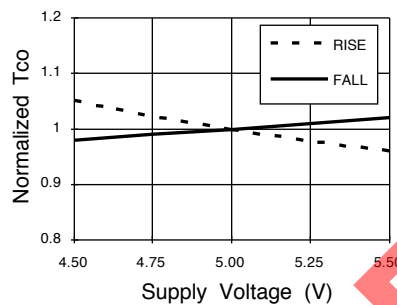


**GAL20V8B-7/-10: Typical AC and DC Characteristic Diagrams**

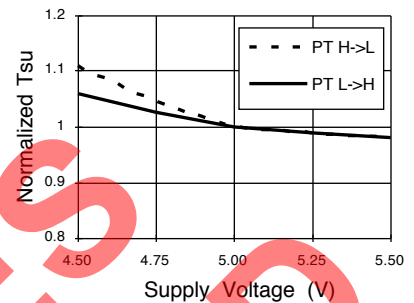
**Normalized Tpd vs Vcc**



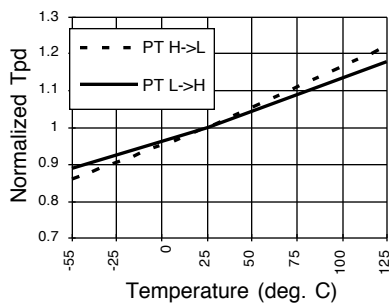
**Normalized Tco vs Vcc**



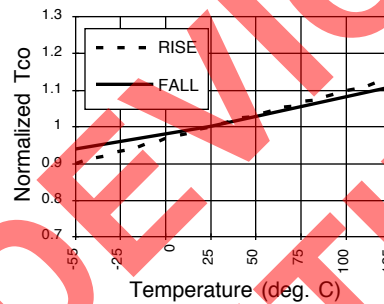
**Normalized Tsu vs Vcc**



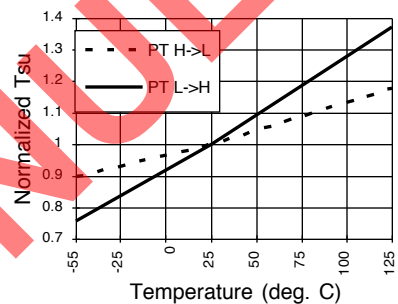
**Normalized Tpd vs Temp**



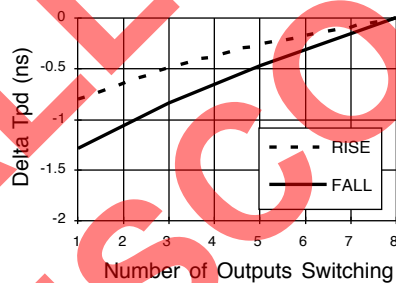
**Normalized Tco vs Temp**



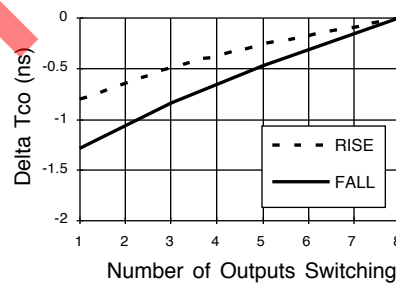
**Normalized Tsu vs Temp**



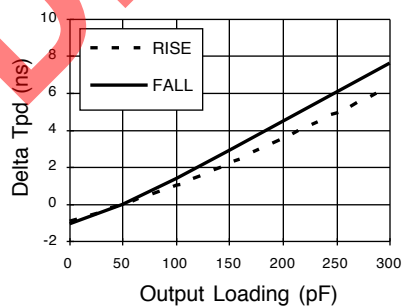
**Delta Tpd vs # of Outputs Switching**



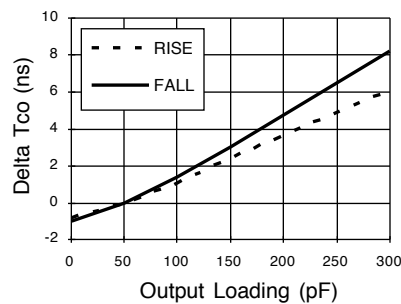
**Delta Tco vs # of Outputs Switching**



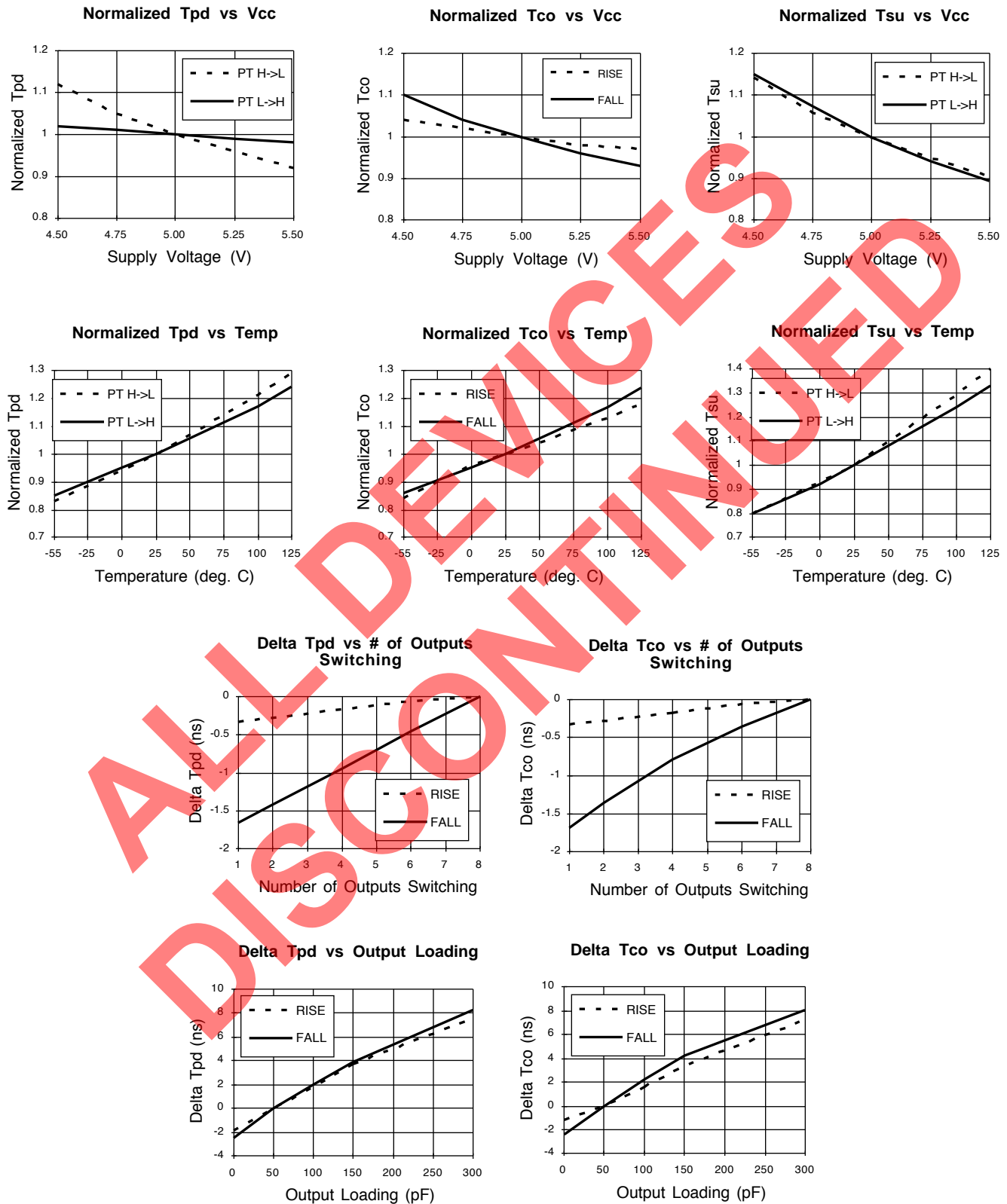
**Delta Tpd vs Output Loading**



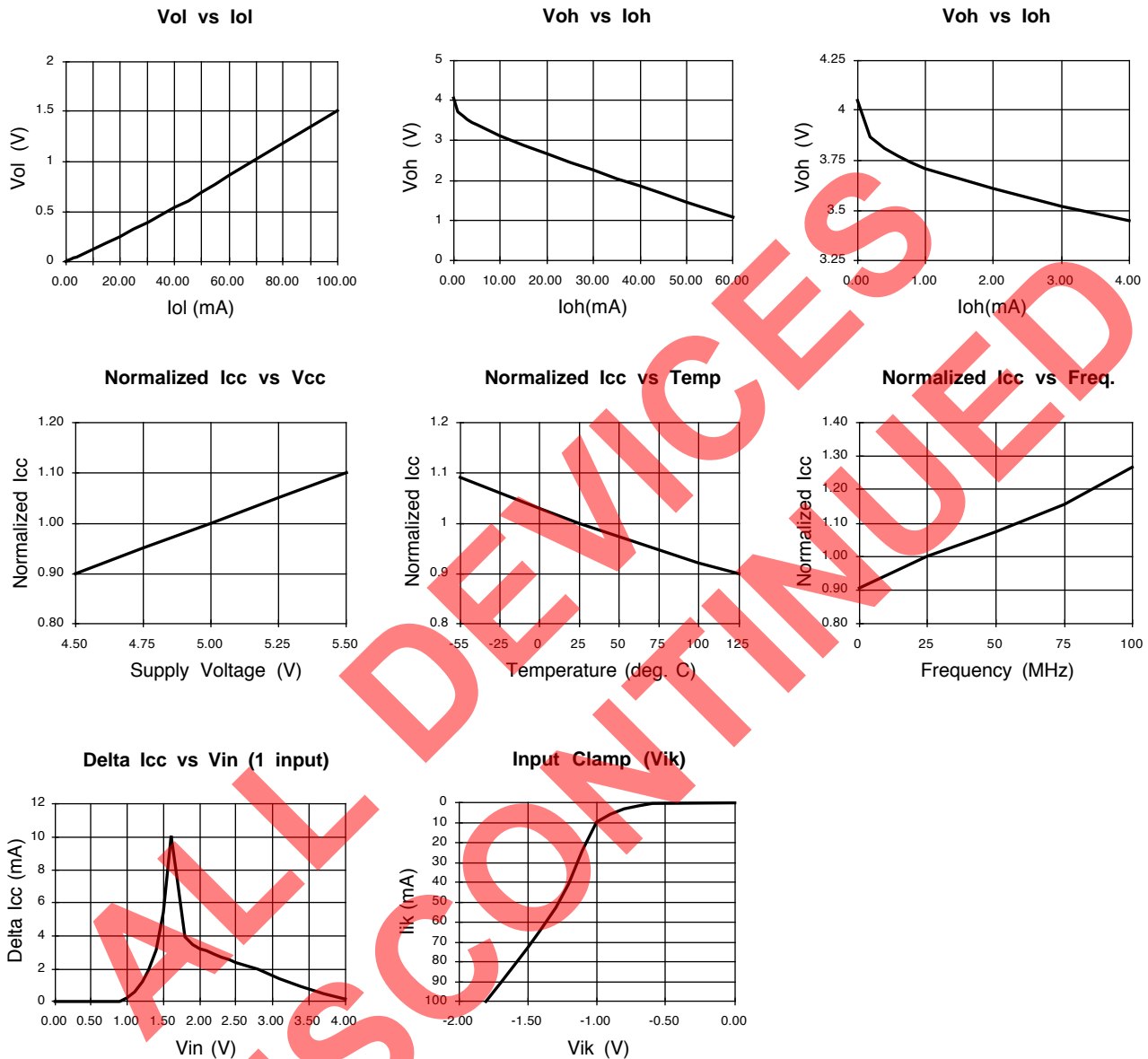
**Delta Tco vs Output Loading**



**GAL20V8B-15/-25: Typical AC and DC Characteristic Diagrams**



**GAL20V8B-15/-25: Typical AC and DC Characteristic Diagrams**



**Revision History**

Date	Version	Change Summary
-	20v8_06	Previous Lattice release.
August 2006	20v8_07	Updated for lead-free package options.

ALL DEVICES  
DISCONTINUED