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#### What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

#### Applications of "Embedded - Microcontrollers"

##### Details

Product Status	Active
Core Processor	dsPIC
Core Size	16-Bit
Speed	40 MIPS
Connectivity	CANbus, I <sup>2</sup> C, IrDA, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, Motor Control PWM, POR, PWM, QEI, WDT
Number of I/O	21
Program Memory Size	128KB (128K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	16K x 8
Voltage - Supply (Vcc/Vdd)	3V ~ 3.6V
Data Converters	A/D 6x10b/12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	28-SOIC (0.295", 7.50mm Width)
Supplier Device Package	28-SOIC
Purchase URL	<a href="https://www.e-xfl.com/product-detail/microchip-technology/dspic33fj128mc802-e-so">https://www.e-xfl.com/product-detail/microchip-technology/dspic33fj128mc802-e-so</a>

**REGISTER 3-1: SR: CPU STATUS REGISTER (CONTINUED)**

bit 7-5	<b>IPL&lt;2:0&gt;</b> : CPU Interrupt Priority Level Status bits <sup>(2)</sup> 111 = CPU Interrupt Priority Level is 7 (15), user interrupts disabled 110 = CPU Interrupt Priority Level is 6 (14) 101 = CPU Interrupt Priority Level is 5 (13) 100 = CPU Interrupt Priority Level is 4 (12) 011 = CPU Interrupt Priority Level is 3 (11) 010 = CPU Interrupt Priority Level is 2 (10) 001 = CPU Interrupt Priority Level is 1 (9) 000 = CPU Interrupt Priority Level is 0 (8)
bit 4	<b>RA</b> : REPEAT Loop Active bit 1 = REPEAT loop in progress 0 = REPEAT loop not in progress
bit 3	<b>N</b> : MCU ALU Negative bit 1 = Result was negative 0 = Result was non-negative (zero or positive)
bit 2	<b>OV</b> : MCU ALU Overflow bit This bit is used for signed arithmetic (two's complement). It indicates an overflow of a magnitude that causes the sign bit to change state. 1 = Overflow occurred for signed arithmetic (in this arithmetic operation) 0 = No overflow occurred
bit 1	<b>Z</b> : MCU ALU Zero bit 1 = An operation that affects the Z bit has set it at some time in the past 0 = The most recent operation that affects the Z bit has cleared it (i.e., a non-zero result)
bit 0	<b>C</b> : MCU ALU Carry/Borrow bit 1 = A carry-out from the Most Significant bit of the result occurred 0 = No carry-out from the Most Significant bit of the result occurred

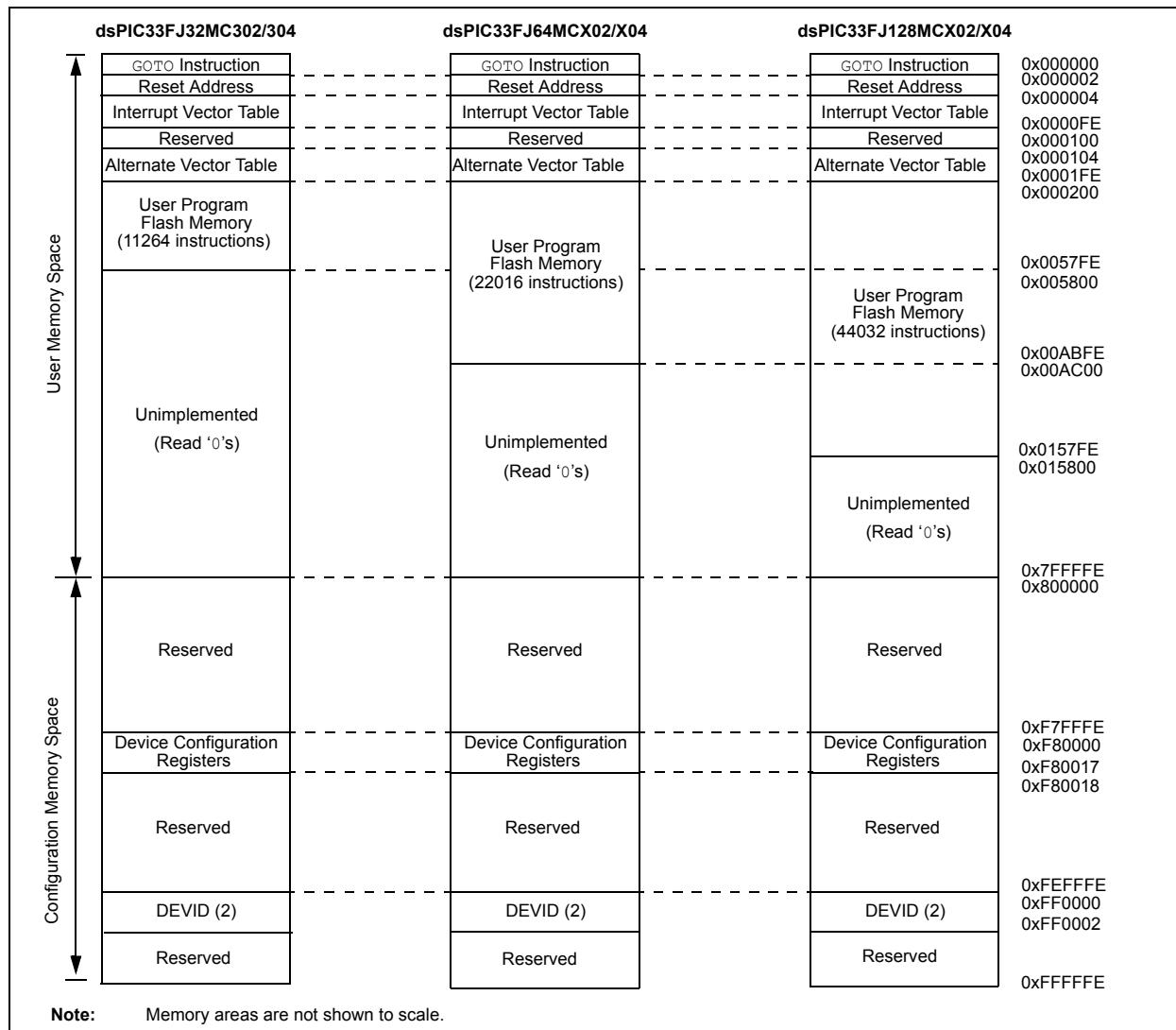
- Note 1:** This bit can be read or cleared (not set).
- 2:** The IPL<2:0> bits are concatenated with the IPL<3> bit (CORCON<3>) to form the CPU Interrupt Priority Level. The value in parentheses indicates the IPL if IPL<3> = 1. User interrupts are disabled when IPL<3> = 1.
- 3:** The IPL<2:0> Status bits are read only when the NSTDIS bit (INTCON1<15>) = 1.
- 4:** This bit can be read or cleared (not set). Clearing this bit clears SA and SB.

## 4.0 MEMORY ORGANIZATION

**Note:** This data sheet summarizes the features of the dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 4. "Program Memory"** (DS70203) of the "*dsPIC33F/PIC24H Family Reference Manual*", which is available from the Microchip web site ([www.microchip.com](http://www.microchip.com)).

The dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 architecture features separate program and data memory spaces and buses. This architecture also allows the direct access to program memory from the data space during code execution.

**FIGURE 4-1: PROGRAM MEMORY MAP FOR dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 AND dsPIC33FJ128MCX02/X04 DEVICES**



## 4.1 Program Address Space

The program address memory space of the dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 devices is 4M instructions. The space is addressable by a 24-bit value derived either from the 23-bit Program Counter (PC) during program execution, or from table operation or data space remapping as described in **Section 4.8 "Interfacing Program and Data Memory Spaces"**.

User application access to the program memory space is restricted to the lower half of the address range (0x000000 to 0x7FFFFFF). The exception is the use of TBLRD/TBLWT operations, which use TBLPAG<7> to permit access to the Configuration bits and Device ID sections of the configuration memory space.

The memory map for the dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 devices is shown in [Figure 4-1](#).

**TABLE 4-20: DMA REGISTER MAP**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
DMA0CON	0380	CHEN	SIZE	DIR	HALF	NULLW	—	—	—	—	—	AMODE<1:0>	—	—	—	MODE<1:0>	0000	
DMA0REQ	0382	FORCE	—	—	—	—	—	—	—	—	—	—	—	—	—	IRQSEL<6:0>	0000	
DMA0STA	0384	—	—	—	—	—	—	—	—	—	—	STA<15:0>	—	—	—	—	0000	
DMA0STB	0386	—	—	—	—	—	—	—	—	—	—	STB<15:0>	—	—	—	—	0000	
DMA0PAD	0388	—	—	—	—	—	—	—	—	—	—	PAD<15:0>	—	—	—	—	0000	
DMA0CNT	038A	—	—	—	—	—	—	—	—	—	—	CNT<9:0>	—	—	—	—	0000	
DMA1CON	038C	CHEN	SIZE	DIR	HALF	NULLW	—	—	—	—	—	AMODE<1:0>	—	—	—	MODE<1:0>	0000	
DMA1REQ	038E	FORCE	—	—	—	—	—	—	—	—	—	—	—	—	—	IRQSEL<6:0>	0000	
DMA1STA	0390	—	—	—	—	—	—	—	—	—	—	STA<15:0>	—	—	—	—	0000	
DMA1STB	0392	—	—	—	—	—	—	—	—	—	—	STB<15:0>	—	—	—	—	0000	
DMA1PAD	0394	—	—	—	—	—	—	—	—	—	—	PAD<15:0>	—	—	—	—	0000	
DMA1CNT	0396	—	—	—	—	—	—	—	—	—	—	CNT<9:0>	—	—	—	—	0000	
DMA2CON	0398	CHEN	SIZE	DIR	HALF	NULLW	—	—	—	—	—	AMODE<1:0>	—	—	—	MODE<1:0>	0000	
DMA2REQ	039A	FORCE	—	—	—	—	—	—	—	—	—	—	—	—	—	IRQSEL<6:0>	0000	
DMA2STA	039C	—	—	—	—	—	—	—	—	—	—	STA<15:0>	—	—	—	—	0000	
DMA2STB	039E	—	—	—	—	—	—	—	—	—	—	STB<15:0>	—	—	—	—	0000	
DMA2PAD	03A0	—	—	—	—	—	—	—	—	—	—	PAD<15:0>	—	—	—	—	0000	
DMA2CNT	03A2	—	—	—	—	—	—	—	—	—	—	CNT<9:0>	—	—	—	—	0000	
DMA3CON	03A4	CHEN	SIZE	DIR	HALF	NULLW	—	—	—	—	—	AMODE<1:0>	—	—	—	MODE<1:0>	0000	
DMA3REQ	03A6	FORCE	—	—	—	—	—	—	—	—	—	—	—	—	—	IRQSEL<6:0>	0000	
DMA3STA	03A8	—	—	—	—	—	—	—	—	—	—	STA<15:0>	—	—	—	—	0000	
DMA3STB	03AA	—	—	—	—	—	—	—	—	—	—	STB<15:0>	—	—	—	—	0000	
DMA3PAD	03AC	—	—	—	—	—	—	—	—	—	—	PAD<15:0>	—	—	—	—	0000	
DMA3CNT	03AE	—	—	—	—	—	—	—	—	—	—	CNT<9:0>	—	—	—	—	0000	
DMA4CON	03B0	CHEN	SIZE	DIR	HALF	NULLW	—	—	—	—	—	AMODE<1:0>	—	—	—	MODE<1:0>	0000	
DMA4REQ	03B2	FORCE	—	—	—	—	—	—	—	—	—	—	—	—	—	IRQSEL<6:0>	0000	
DMA4STA	03B4	—	—	—	—	—	—	—	—	—	—	STA<15:0>	—	—	—	—	0000	
DMA4STB	03B6	—	—	—	—	—	—	—	—	—	—	STB<15:0>	—	—	—	—	0000	
DMA4PAD	03B8	—	—	—	—	—	—	—	—	—	—	PAD<15:0>	—	—	—	—	0000	
DMA4CNT	03BA	—	—	—	—	—	—	—	—	—	—	CNT<9:0>	—	—	—	—	0000	
DMA5CON	03BC	CHEN	SIZE	DIR	HALF	NULLW	—	—	—	—	—	AMODE<1:0>	—	—	—	MODE<1:0>	0000	
DMA5REQ	03BE	FORCE	—	—	—	—	—	—	—	—	—	—	—	—	—	IRQSEL<6:0>	0000	
DMA5STA	03C0	—	—	—	—	—	—	—	—	—	—	STA<15:0>	—	—	—	—	0000	
DMA5STB	03C2	—	—	—	—	—	—	—	—	—	—	STB<15:0>	—	—	—	—	0000	

Legend: — = unimplemented, read as '0'.

**TABLE 7-1: INTERRUPT VECTORS**

<b>Vector Number</b>	<b>IVT Address</b>	<b>AVT Address</b>	<b>Interrupt Source</b>
0	0x000004	0x000104	Reserved
1	0x000006	0x000106	Oscillator Failure
2	0x000008	0x000108	Address Error
3	0x00000A	0x00010A	Stack Error
4	0x00000C	0x00010C	Math Error
5	0x00000E	0x00010E	DMA Error
6-7	0x000010-0x000012	0x000110-0x000112	Reserved
8	0x000014	0x000114	INT0 – External Interrupt 0
9	0x000016	0x000116	IC1 – Input Capture 1
10	0x000018	0x000118	OC1 – Output Compare 1
11	0x00001A	0x00011A	T1 – Timer1
12	0x00001C	0x00011C	DMA0 – DMA Channel 0
13	0x00001E	0x00011E	IC2 – Input Capture 2
14	0x000020	0x000120	OC2 – Output Compare 2
15	0x000022	0x000122	T2 – Timer2
16	0x000024	0x000124	T3 – Timer3
17	0x000026	0x000126	SPI1E – SPI1 Error
18	0x000028	0x000128	SPI1 – SPI1 Transfer Done
19	0x00002A	0x00012A	U1RX – UART1 Receiver
20	0x00002C	0x00012C	U1TX – UART1 Transmitter
21	0x00002E	0x00012E	ADC1 – ADC 1
22	0x000030	0x000130	DMA1 – DMA Channel 1
23	0x000032	0x000132	Reserved
24	0x000034	0x000134	SI2C1 – I2C1 Slave Events
25	0x000036	0x000136	MI2C1 – I2C1 Master Events
26	0x000038	0x000138	CM – Comparator Interrupt
27	0x00003A	0x00013A	Change Notification Interrupt
28	0x00003C	0x00013C	INT1 – External Interrupt 1
29	0x00003E	0x00013E	Reserved
30	0x000040	0x000140	IC7 – Input Capture 7
31	0x000042	0x000142	IC8 – Input Capture 8
32	0x000044	0x000144	DMA2 – DMA Channel 2
33	0x000046	0x000146	OC3 – Output Compare 3
34	0x000048	0x000148	OC4 – Output Compare 4
35	0x00004A	0x00014A	T4 – Timer4
36	0x00004C	0x00014C	T5 – Timer5
37	0x00004E	0x00014E	INT2 – External Interrupt 2
38	0x000050	0x000150	U2RX – UART2 Receiver
39	0x000052	0x000152	U2TX – UART2 Transmitter
40	0x000054	0x000154	SPI2E – SPI2 Error
41	0x000056	0x000156	SPI2 – SPI2 Transfer Done
42	0x000058	0x000158	C1RX – ECAN1 RX Data Ready
43	0x00005A	0x00015A	C1 – ECAN1 Event
44	0x00005C	0x00015C	DMA3 – DMA Channel 3
45-52	0x00005E-0x00006C	0x00015E-0x00016C	Reserved
53	0x00006E	0x00016E	PMP – Parallel Master Port
54	0x000070	0x000170	DMA – DMA Channel 4

**REGISTER 7-10: IEC0: INTERRUPT ENABLE CONTROL REGISTER 0 (CONTINUED)**

- bit 2           **OC1IE:** Output Compare Channel 1 Interrupt Enable bit  
          1 = Interrupt request enabled  
          0 = Interrupt request not enabled
- bit 1           **IC1IE:** Input Capture Channel 1 Interrupt Enable bit  
          1 = Interrupt request enabled  
          0 = Interrupt request not enabled
- bit 0           **INT0IE:** External Interrupt 0 Flag Status bit  
          1 = Interrupt request enabled  
          0 = Interrupt request not enabled

**REGISTER 7-17: IPC2: INTERRUPT PRIORITY CONTROL REGISTER 2**

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—		U1RXIP<2:0>		—		SPI1IP<2:0>	
bit 15							bit 8

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—		SPI1EIP<2:0>		—		T3IP<2:0>	
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15      **Unimplemented:** Read as '0'

bit 14-12    **U1RXIP<2:0>:** UART1 Receiver Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1  
000 = Interrupt source is disabled

bit 11      **Unimplemented:** Read as '0'

bit 10-8     **SPI1IP<2:0>:** SPI1 Event Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1  
000 = Interrupt source is disabled

bit 7        **Unimplemented:** Read as '0'

bit 6-4      **SPI1EIP<2:0>:** SPI1 Error Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1  
000 = Interrupt source is disabled

bit 3        **Unimplemented:** Read as '0'

bit 2-0      **T3IP<2:0>:** Timer3 Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1  
000 = Interrupt source is disabled

## 8.1 DMA Resources

Many useful resources related to DMA are provided on the main product page of the Microchip web site for the devices listed in this data sheet. This product page, which can be accessed using this [link](#), contains the latest updates and additional information.

**Note:** In the event you are not able to access the product page using the link above, enter this URL in your browser:  
<http://www.microchip.com/wwwproducts/Devices.aspx?dDocName=en532315>

### 8.1.1 KEY RESOURCES

- **Section 38. “Direct Memory Access (Part III)”** (DS70215)
- Code Samples
- Application Notes
- Software Libraries
- Webinars
- All related dsPIC33F/PIC24H Family Reference Manuals Sections
- Development Tools

## 8.2 DMAC Registers

Each DMAC Channel x (x = 0, 1, 2, 3, 4, 5, 6 or 7) contains the following registers:

- A 16-bit DMA Channel Control register (DMAxCON)
- A 16-bit DMA Channel IRQ Select register (DMAxREQ)
- A 16-bit DMA RAM Primary Start Address register (DMAxSTA)
- A 16-bit DMA RAM Secondary Start Address register (DMAxSTB)
- A 16-bit DMA Peripheral Address register (DMAxPAD)
- A 10-bit DMA Transfer Count register (DMAxCNT)

An additional pair of status registers, DMACS0 and DMACS1, are common to all DMAC channels. DMACS0 contains the DMA RAM and SFR write collision flags, XWCOLx and PWCOLx, respectively. DMACS1 indicates DMA channel and Ping-Pong mode status.

The DMAxCON, DMAxREQ, DMAxPAD and DMAxCNT are all conventional read/write registers. Reads of DMAxSTA or DMAxSTB reads the contents of the DMA RAM Address register. Writes to DMAxSTA or DMAxSTB write to the registers. This allows the user to determine the DMA buffer pointer value (address) at any time.

The interrupt flags (DMAxIF) are located in an IFSx register in the interrupt controller. The corresponding interrupt enable control bits (DMAxIE) are located in an IECx register in the interrupt controller, and the corresponding interrupt priority control bits (DMAxIP) are located in an IPCx register in the interrupt controller.

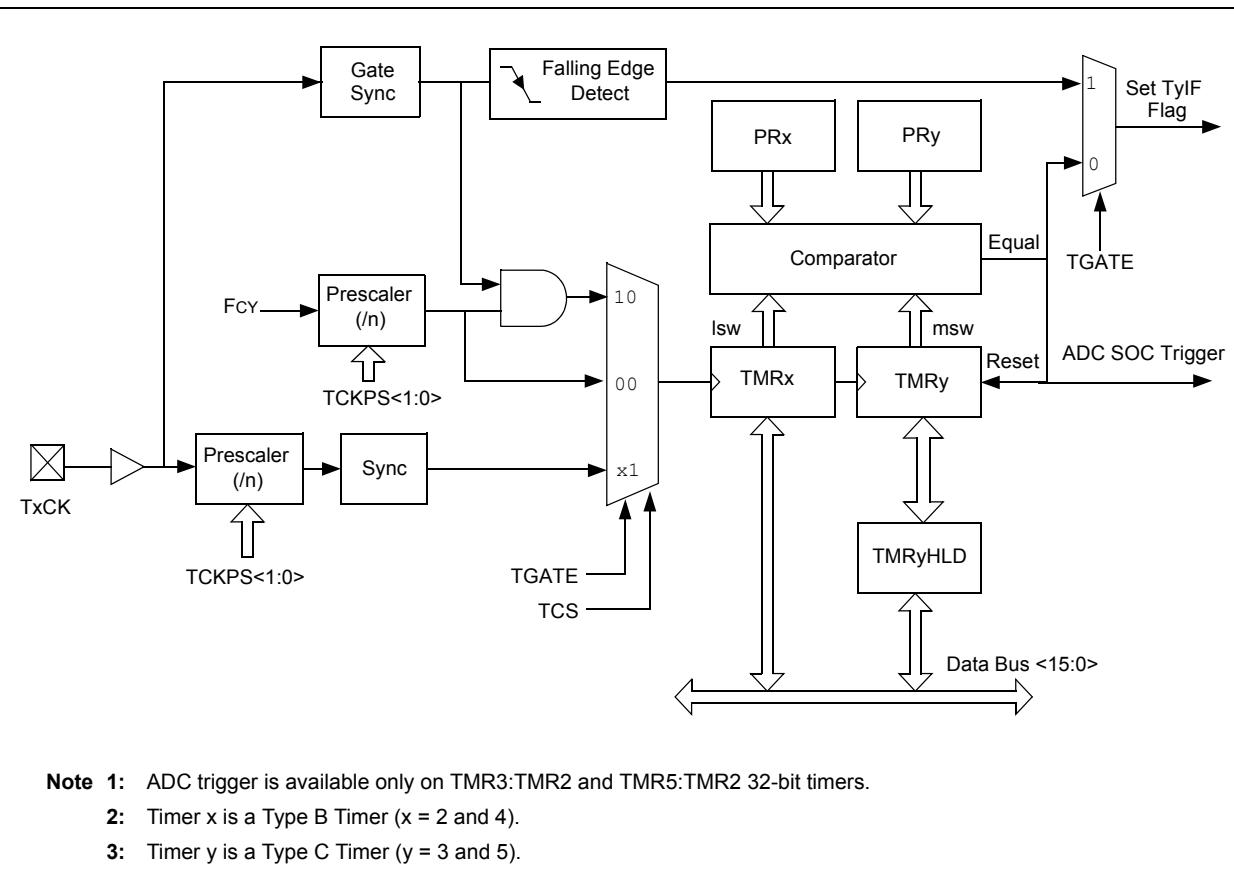
## **10.5 Power-Saving Resources**

Many useful resources related to power-saving modes are provided on the main product page of the Microchip web site for the devices listed in this data sheet. This product page, which can be accessed using this [link](#), contains the latest updates and additional information.

**Note:** In the event you are not able to access the product page using the link above, enter this URL in your browser:  
<http://www.microchip.com/wwwproducts/Devices.aspx?dDocName=en532315>

### **10.5.1 KEY RESOURCES**

- **Section 9. “Watchdog Timer and Power-Saving Modes” (DS70196)**
- Code Samples
- Application Notes
- Software Libraries
- Webinars
- All related dsPIC33F/PIC24H Family Reference Manuals Sections
- Development Tools

**FIGURE 13-3: 32-BIT TIMER BLOCK DIAGRAM**

### 13.3 Timer Resources

Many useful resources related to Timers are provided on the main product page of the Microchip web site for the devices listed in this data sheet. This product page, which can be accessed using this [link](#), contains the latest updates and additional information.

**Note:** In the event you are not able to access the product page using the link above, enter this URL in your browser:  
<http://www.microchip.com/wwwproducts/Devices.aspx?dDocName=en532315>

#### 13.3.1 KEY RESOURCES

- **Section 11. “Timers”** (DS70205)
- Code Samples
- Application Notes
- Software Libraries
- Webinars
- All related dsPIC33F/PIC24H Family Reference Manuals Sections
- Development Tools

**REGISTER 16-4: PxSECMP: SPECIAL EVENT COMPARE REGISTER**

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
SEVTDIR <sup>(1)</sup>	SEVTCMP<14:8> <sup>(2)</sup>						
bit 15	bit 8						

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
SEVTCMP<7:0> <sup>(2)</sup>							
bit 7	bit 0						

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

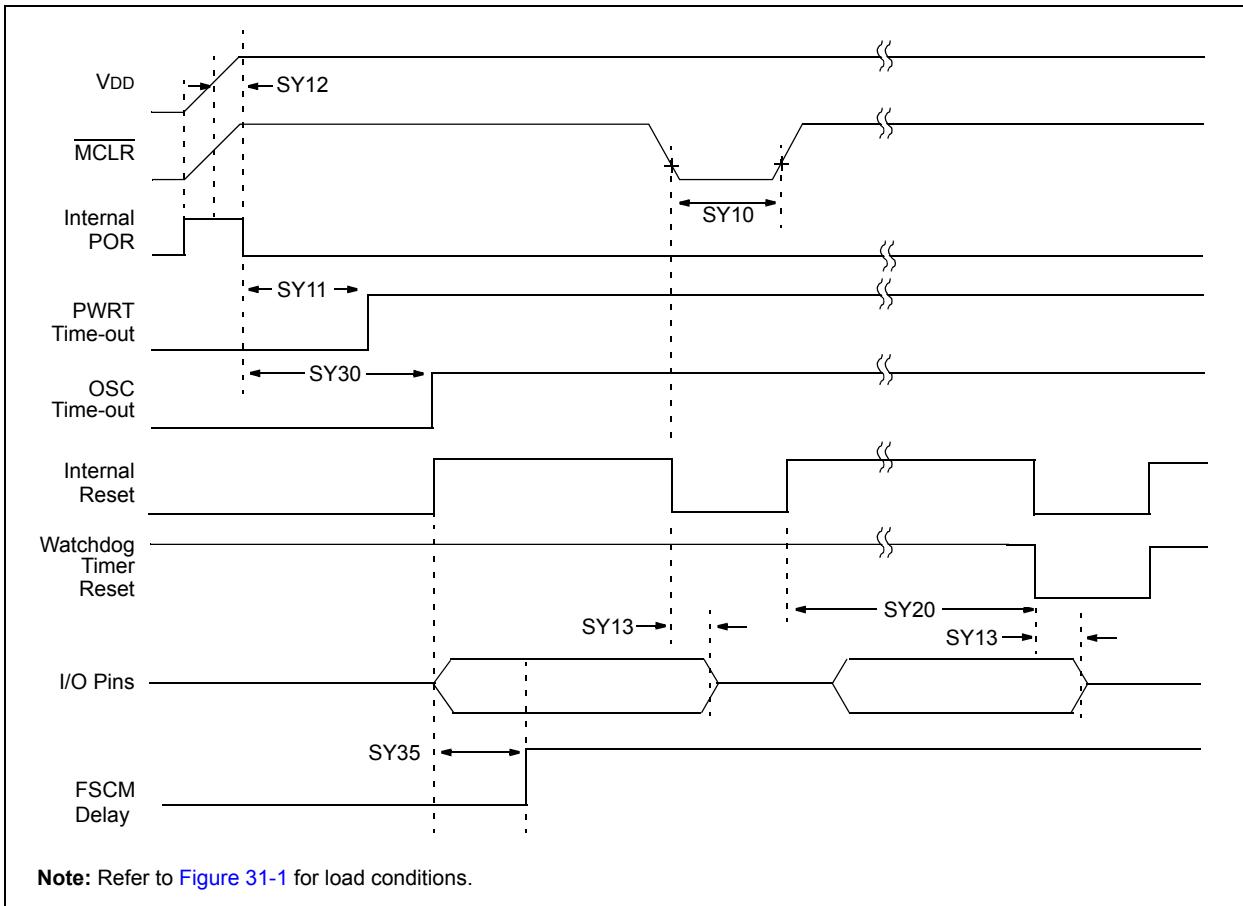
x = Bit is unknown

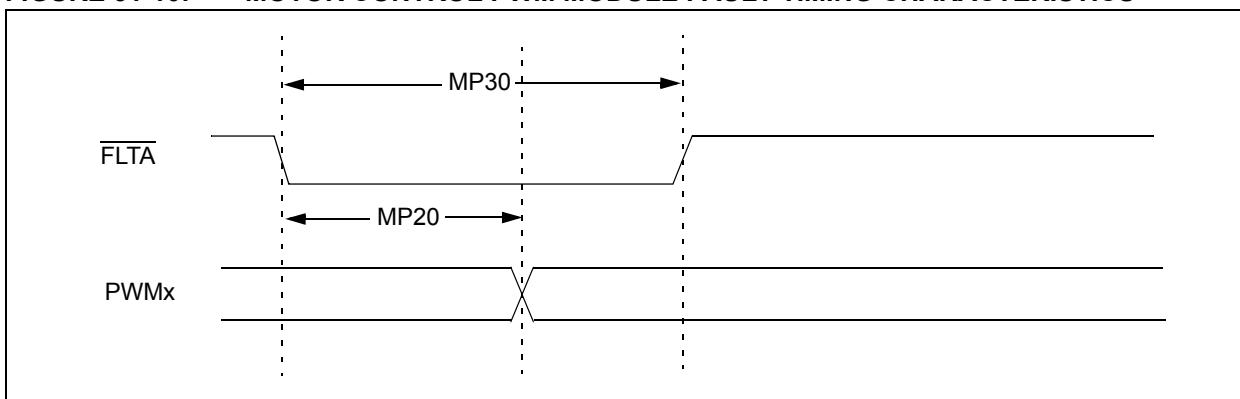
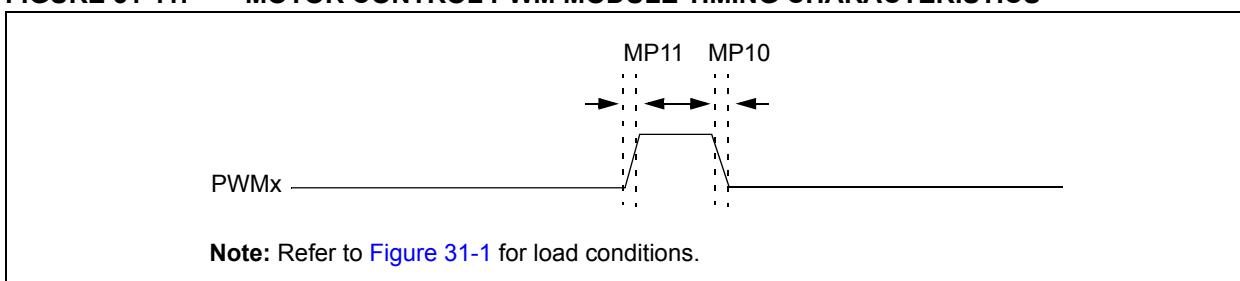
bit 15      **SEVTDIR:** Special Event Trigger Time Base Direction bit<sup>(1)</sup>1 = A Special Event Trigger occurs when the PWM time base is counting downward  
0 = A Special Event Trigger occurs when the PWM time base is counting upwardbit 14-0      **SEVTCMP<14:0>:** Special Event Compare Value bits<sup>(2)</sup>**Note 1:** This bit is compared with the PTDIR bit (PxTMR<15>) to generate the Special Event Trigger.**2:** The PxSECMP<14:0> bits are compared with the PxTMR<14:0> bits to generate the Special Event Trigger.

**TABLE 29-2: INSTRUCTION SET OVERVIEW (CONTINUED)**

Base Instr #	Assembly Mnemonic	Assembly Syntax	Description	# of Words	# of Cycles	Status Flags Affected
66	RRNC	RRNC f	f = Rotate Right (No Carry) f	1	1	N,Z
		RRNC f, WREG	WREG = Rotate Right (No Carry) f	1	1	N,Z
		RRNC Ws, Wd	Wd = Rotate Right (No Carry) Ws	1	1	N,Z
67	SAC	SAC Acc, #Slit4, Wdo	Store Accumulator	1	1	None
		SAC.R Acc, #Slit4, Wdo	Store Rounded Accumulator	1	1	None
68	SE	SE Ws, Wnd	Wnd = sign-extended Ws	1	1	C,N,Z
69	SETM	SETM f	f = 0xFFFF	1	1	None
		SETM WREG	WREG = 0xFFFF	1	1	None
		SETM Ws	Ws = 0xFFFF	1	1	None
70	SFTAC	SFTAC Acc, Wn	Arithmetic Shift Accumulator by (Wn)	1	1	OA,OB,OAB, SA,SB,SAB
		SFTAC Acc, #Slit6	Arithmetic Shift Accumulator by Slit6	1	1	OA,OB,OAB, SA,SB,SAB
71	SL	SL f	f = Left Shift f	1	1	C,N,OV,Z
		SL f, WREG	WREG = Left Shift f	1	1	C,N,OV,Z
		SL Ws, Wd	Wd = Left Shift Ws	1	1	C,N,OV,Z
		SL Wb, Wns, Wnd	Wnd = Left Shift Wb by Wns	1	1	N,Z
		SL Wb, #lit5, Wnd	Wnd = Left Shift Wb by lit5	1	1	N,Z
72	SUB	SUB Acc	Subtract Accumulators	1	1	OA,OB,OAB, SA,SB,SAB
		SUB f	f = f - WREG	1	1	C,DC,N,OV,Z
		SUB f, WREG	WREG = f - WREG	1	1	C,DC,N,OV,Z
		SUB #lit10, Wn	Wn = Wn - lit10	1	1	C,DC,N,OV,Z
		SUB Wb, Ws, Wd	Wd = Wb - Ws	1	1	C,DC,N,OV,Z
		SUB Wb, #lit5, Wd	Wd = Wb - lit5	1	1	C,DC,N,OV,Z
73	SUBB	SUBB f	f = f - WREG - ( $\bar{C}$ )	1	1	C,DC,N,OV,Z
		SUBB f, WREG	WREG = f - WREG - ( $\bar{C}$ )	1	1	C,DC,N,OV,Z
		SUBB #lit10, Wn	Wn = Wn - lit10 - ( $\bar{C}$ )	1	1	C,DC,N,OV,Z
		SUBB Wb, Ws, Wd	Wd = Wb - Ws - ( $\bar{C}$ )	1	1	C,DC,N,OV,Z
		SUBB Wb, #lit5, Wd	Wd = Wb - lit5 - ( $\bar{C}$ )	1	1	C,DC,N,OV,Z
74	SUBR	SUBR f	f = WREG - f	1	1	C,DC,N,OV,Z
		SUBR f, WREG	WREG = WREG - f	1	1	C,DC,N,OV,Z
		SUBR Wb, Ws, Wd	Wd = Ws - Wb	1	1	C,DC,N,OV,Z
		SUBR Wb, #lit5, Wd	Wd = lit5 - Wb	1	1	C,DC,N,OV,Z
75	SUBBR	SUBBR f	f = WREG - f - ( $\bar{C}$ )	1	1	C,DC,N,OV,Z
		SUBBR f, WREG	WREG = WREG - f - ( $\bar{C}$ )	1	1	C,DC,N,OV,Z
		SUBBR Wb, Ws, Wd	Wd = Ws - Wb - ( $\bar{C}$ )	1	1	C,DC,N,OV,Z
		SUBBR Wb, #lit5, Wd	Wd = lit5 - Wb - ( $\bar{C}$ )	1	1	C,DC,N,OV,Z
76	SWAP	SWAP.b Wn	Wn = nibble swap Wn	1	1	None
		SWAP Wn	Wn = byte swap Wn	1	1	None
77	TBLRDH	TBLRDH Ws, Wd	Read Prog<23:16> to Wd<7:0>	1	2	None
78	TBLRDL	TBLRDL Ws, Wd	Read Prog<15:0> to Wd	1	2	None
79	TBLWTH	TBLWTH Ws, Wd	Write Ws<7:0> to Prog<23:16>	1	2	None
80	TBLWTL	TBLWTL Ws, Wd	Write Ws to Prog<15:0>	1	2	None
81	ULNK	ULNK	Unlink Frame Pointer	1	1	None
82	XOR	XOR f	f = f .XOR. WREG	1	1	N,Z
		XOR f, WREG	WREG = f .XOR. WREG	1	1	N,Z
		XOR #lit10, Wn	Wd = lit10 .XOR. Wd	1	1	N,Z
		XOR Wb, Ws, Wd	Wd = Wb .XOR. Ws	1	1	N,Z
		XOR Wb, #lit5, Wd	Wd = Wb .XOR. lit5	1	1	N,Z
83	ZE	ZE Ws, Wnd	Wnd = Zero-extend Ws	1	1	C,Z,N

**FIGURE 31-4: RESET, WATCHDOG TIMER, OSCILLATOR START-UP TIMER AND POWER-UP TIMER TIMING CHARACTERISTICS**



**FIGURE 31-10: MOTOR CONTROL PWM MODULE FAULT TIMING CHARACTERISTICS****FIGURE 31-11: MOTOR CONTROL PWM MODULE TIMING CHARACTERISTICS****TABLE 31-29: MOTOR CONTROL PWM MODULE TIMING REQUIREMENTS**

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)				
Param No.	Symbol	Characteristic <sup>(1)</sup>	Min	Typ	Max	Units	Conditions
MP10	TFPWM	PWM Output Fall Time	—	—	—	ns	See parameter DO32
MP11	TRPWM	PWM Output Rise Time	—	—	—	ns	See parameter DO31
MP20	TFD	Fault Input ↓ to PWM I/O Change	—	—	50	ns	—
MP30	TFH	Minimum Pulse Width	50	—	—	ns	—

**Note 1:** These parameters are characterized but not tested in manufacturing.

**TABLE 31-49: COMPARATOR TIMING SPECIFICATIONS**

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)				
Param No.	Symbol	Characteristic	Min	Typ	Max	Units	Conditions
300	TRESP	Response Time <sup>(1,2)</sup>	—	150	400	ns	—
301	TMC2OV	Comparator Mode Change to Output Valid <sup>(1)</sup>	—	—	10	μs	—

**Note 1:** Parameters are characterized but not tested.

**2:** Response time measured with one comparator input at  $(VDD - 1.5)/2$ , while the other input transitions from Vss to Vdd.

**TABLE 31-50: COMPARATOR MODULE SPECIFICATIONS**

DC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)				
Param No.	Symbol	Characteristic	Min	Typ	Max	Units	Conditions
D300	VIOFF	Input Offset Voltage <sup>(1)</sup>	—	±10	—	mV	—
D301	VICM	Input Common Mode Voltage <sup>(1)</sup>	0	—	AVDD-1.5V	V	—
D302	CMRR	Common Mode Rejection Ratio <sup>(1)</sup>	-54	—	—	dB	—

**Note 1:** Parameters are characterized but not tested.

**TABLE 32-7: DC CHARACTERISTICS: PROGRAM MEMORY**

DC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +150°C for High Temperature				
Param No.	Symbol	Characteristic <sup>(1)</sup>	Min	Typ	Max	Units	Conditions
HD130	EP	<b>Program Flash Memory</b> Cell Endurance	10,000	—	—	E/W	-40°C to +150°C <sup>(2)</sup>
HD134	TRETD	Characteristic Retention	20	—	—	Year	1000 E/W cycles or less and no other specifications are violated

**Note 1:** These parameters are assured by design, but are not characterized or tested in manufacturing.

**2:** Programming of the Flash memory is allowed up to 150°C.

**TABLE 32-10: SPI<sub>x</sub> MASTER MODE (CKE = 0) TIMING REQUIREMENTS**

AC CHARACTERISTICS		Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +150°C for High Temperature					
Param No.	Symbol	Characteristic <sup>(1)</sup>	Min	Typ	Max	Units	Conditions
HSP35	TscH2doV, TscL2doV	SDOx Data Output Valid after SCKx Edge	—	10	25	ns	—
HSP40	TdiV2scH, TdiV2scL	Setup Time of SDIx Data Input to SCKx Edge	28	—	—	ns	—
HSP41	TscH2diL, TscL2diL	Hold Time of SDIx Data Input to SCKx Edge	35	—	—	ns	—

**Note 1:** These parameters are characterized but not tested in manufacturing.

**TABLE 32-11: SPI<sub>x</sub> MODULE MASTER MODE (CKE = 1) TIMING REQUIREMENTS**

AC CHARACTERISTICS		Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +150°C for High Temperature					
Param No.	Symbol	Characteristic <sup>(1)</sup>	Min	Typ	Max	Units	Conditions
HSP35	TscH2doV, TscL2doV	SDOx Data Output Valid after SCKx Edge	—	10	25	ns	—
HSP36	TdoV2sc, TdoV2scL	SDOx Data Output Setup to First SCKx Edge	35	—	—	ns	—
HSP40	TdiV2scH, TdiV2scL	Setup Time of SDIx Data Input to SCKx Edge	28	—	—	ns	—
HSP41	TscH2diL, TscL2diL	Hold Time of SDIx Data Input to SCKx Edge	35	—	—	ns	—

**Note 1:** These parameters are characterized but not tested in manufacturing.

FIGURE 32-13: TYPICAL FRC FREQUENCY @ VDD = 3.3V

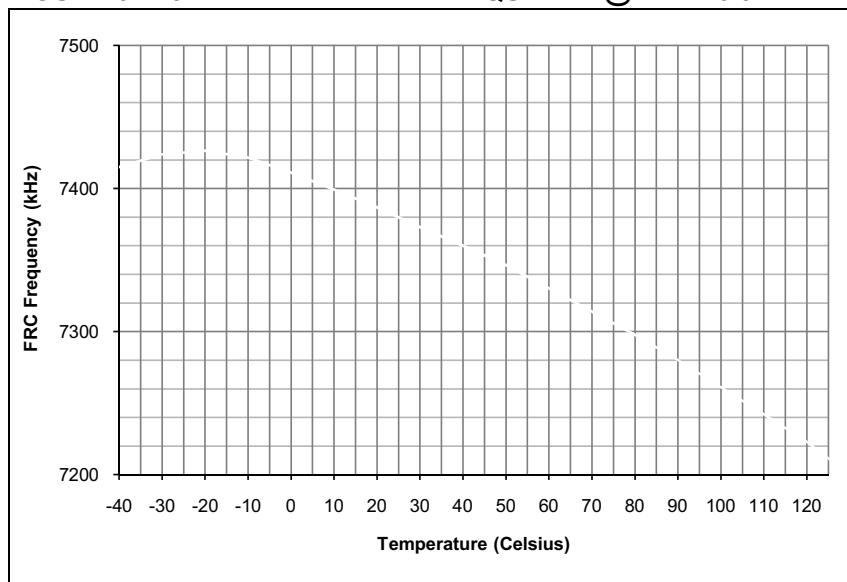
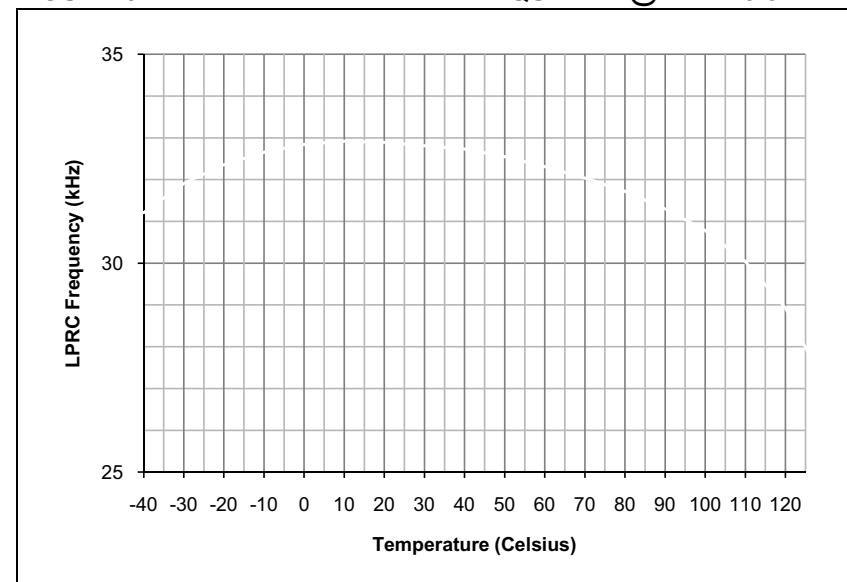


FIGURE 32-14: TYPICAL LPRC FREQUENCY @ VDD = 3.3V



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