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### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Active
Core Processor	dsPIC
Core Size	16-Bit
Speed	40 MIPS
Connectivity	I <sup>2</sup> C, IrDA, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, Motor Control PWM, POR, PWM, QEI, WDT
Number of I/O	35
Program Memory Size	32KB (32K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	4K x 8
Voltage - Supply (Vcc/Vdd)	3V ~ 3.6V
Data Converters	A/D 9x10b/12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	44-VQFN Exposed Pad
Supplier Device Package	44-QFN (8x8)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/microchip-technology/dspic33fj32mc304-e-ml">https://www.e-xfl.com/product-detail/microchip-technology/dspic33fj32mc304-e-ml</a>

**dsPIC33FJ32MC302/304,  
dsPIC33FJ64MCX02/X04 AND  
dsPIC33FJ128MCX02/X04 PRODUCT  
FAMILIES**

The device names, pin counts, memory sizes, and peripheral availability of each device are listed in [Table 1](#). The pages that follow show their pinout diagrams.

**TABLE 1: dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 AND dsPIC33FJ128MCX02/X04 CONTROLLER FAMILIES**

Device	Pins	Program Flash Memory (Kbyte)	RAM (Kbyte) <sup>(1)</sup>	Remappable Peripheral										RTCC	I <sup>2</sup> C™	CRC Generator	10-bit/12-bit ADC (Channels)	6-pin 16-bit DAC	Analog Comparator (2 Channels/Voltage Regulator)	8-bit Parallel Master Port (Address Lines)	I/O Pins	Packages
				Remappable Pins	16-bit Timer <sup>(2)</sup>	Input Capture	Output Compare Standard PWM	Motor Control PWM (Channels) <sup>(3)</sup>	Quadrature Encoder Interface	UART	SPI	ECAN™	External Interrupts <sup>(4)</sup>									
dsPIC33FJ128MC804	44	128	16	26	5	4	4	6, 2	2	2	2	1	3	1	1	1	9	1	1/1	11	35	QFN TQFP
dsPIC33FJ128MC802	28	128	16	16	5	4	4	6, 2	2	2	2	1	3	1	1	1	6	0	1/0	2	21	SPDIP SOIC QFN-S
dsPIC33FJ128MC204	44	128	8	26	5	4	4	6, 2	2	2	2	0	3	1	1	1	9	0	1/1	11	35	QFN TQFP
dsPIC33FJ128MC202	28	128	8	16	5	4	4	6, 2	2	2	2	0	3	1	1	1	6	0	1/0	2	21	SPDIP SOIC QFN-S
dsPIC33FJ64MC804	44	64	16	26	5	4	4	6, 2	2	2	2	1	3	1	1	1	9	1	1/1	11	35	QFN TQFP
dsPIC33FJ64MC802	28	64	16	16	5	4	4	6, 2	2	2	2	1	3	1	1	1	6	0	1/0	2	21	SPDIP SOIC QFN-S
dsPIC33FJ64MC204	44	64	8	26	5	4	4	6, 2	2	2	2	0	3	1	1	1	9	0	1/1	11	35	QFN TQFP
dsPIC33FJ64MC202	28	64	8	16	5	4	4	6, 2	2	2	2	0	3	1	1	1	6	0	1/0	2	21	SPDIP SOIC QFN-S
dsPIC33FJ32MC304	44	32	4	26	5	4	4	6, 2	2	2	2	0	3	1	1	1	9	0	1/1	11	35	QFN TQFP
dsPIC33FJ32MC302	28	32	4	16	5	4	4	6, 2	2	2	2	0	3	1	1	1	6	0	1/0	2	21	SPDIP SOIC QFN-S

- Note** 1: RAM size is inclusive of 2 Kbytes of DMA RAM for all devices except dsPIC33FJ32MC302/304, which include 1 Kbyte of DMA RAM.  
2: Only four out of five timers are remappable.  
3: Only PWM fault pins are remappable.  
4: Only two out of three interrupts are remappable.

**TABLE 4-12: I2C1 REGISTER MAP**

SFR Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
I2C1RCV	0200	—	—	—	—	—	—	—	—	Receive Register								0000
I2C1TRN	0202	—	—	—	—	—	—	—	—	Transmit Register								00FF
I2C1BRG	0204	—	—	—	—	—	—	—	Baud Rate Generator Register								0000	
I2C1CON	0206	I2CEN	—	I2CSIDL	SCLREL	IPMIEN	A10M	DISSLW	SMEN	GCEN	STREN	ACKDT	ACKEN	RCEN	PEN	RSEN	SEN	1000
I2C1STAT	0208	ACKSTAT	TRSTAT	—	—	—	BCL	GCSTAT	ADD10	IWCOL	I2COV	D_A	P	S	R_W	RBF	TBF	0000
I2C1ADD	020A	—	—	—	—	—	—	Address Register										0000
I2C1MSK	020C	—	—	—	—	—	—	Address Mask Register										0000

**Legend:** x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-13: UART1 REGISTER MAP**

SFR Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
U1MODE	0220	UARTEN	—	USIDL	IREN	RTSMD	—	UEN1	UEN0	WAKE	LPBACK	ABAUD	URXINV	BRGH	PDSEL<1:0>		STSEL	0000
U1STA	0222	UTXISEL1	UTXINV	UTXISEL0	—	UTXBRK	UTXEN	UTXBF	TRMT	URXISEL<1:0>		ADDEN	RIDLE	PERR	FERR	OERR	URXDA	0110
U1TXREG	0224	—	—	—	—	—	—	—	UTX8	UART Transmit Register								xxxx
U1RXREG	0226	—	—	—	—	—	—	—	URX8	UART Received Register								0000
U1BRG	0228	Baud Rate Generator Prescaler																0000

**Legend:** x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-14: UART2 REGISTER MAP**

SFR Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
U2MODE	0230	UARTEN	—	USIDL	IREN	RTSMD	—	UEN1	UEN0	WAKE	LPBACK	ABAUD	URXINV	BRGH	PDSEL<1:0>		STSEL	0000
U2STA	0232	UTXISEL1	UTXINV	UTXISEL0	—	UTXBRK	UTXEN	UTXBF	TRMT	URXISEL<1:0>		ADDEN	RIDLE	PERR	FERR	OERR	URXDA	0110
U2TXREG	0234	—	—	—	—	—	—	—	UTX8	UART Transmit Register								xxxx
U2RXREG	0236	—	—	—	—	—	—	—	URX8	UART Receive Register								0000
U2BRG	0238	Baud Rate Generator Prescaler																0000

**Legend:** x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

### 5.6.1 PROGRAMMING ALGORITHM FOR FLASH PROGRAM MEMORY

Programmers can program one row of program Flash memory at a time. To do this, it is necessary to erase the 8-row erase page that contains the desired row. The general process is:

1. Read eight rows of program memory (512 instructions) and store in data RAM.
2. Update the program data in RAM with the desired new data.
3. Erase the block (see [Example 5-1](#)):
  - a) Set the NVMOP bits (NVMCON<3:0>) to '0010' to configure for block erase. Set the ERASE (NVMCON<6>) and WREN (NVMCON<14>) bits.
  - b) Write the starting address of the page to be erased into the TBLPAG and W registers.
  - c) Write 0x55 to NVMKEY.
  - d) Write 0xAA to NVMKEY.
  - e) Set the WR bit (NVMCON<15>). The erase cycle begins and the CPU stalls for the duration of the erase cycle. When the erase is done, the WR bit is cleared automatically.

4. Write the first 64 instructions from data RAM into the program memory buffers (see [Example 5-2](#)).
5. Write the program block to Flash memory:
  - a) Set the NVMOP bits to '0001' to configure for row programming. Clear the ERASE bit and set the WREN bit.
  - b) Write 0x55 to NVMKEY.
  - c) Write 0xAA to NVMKEY.
  - d) Set the WR bit. The programming cycle begins and the CPU stalls for the duration of the write cycle. When the write to Flash memory is done, the WR bit is cleared automatically.
6. Repeat steps 4 and 5, using the next available 64 instructions from the block in data RAM by incrementing the value in TBLPAG, until all 512 instructions are written back to Flash memory.

For protection against accidental operations, the write initiate sequence for NVMKEY must be used to allow any erase or program operation to proceed. After the programming command has been executed, the user application must wait for the programming time until programming is complete. The two instructions following the start of the programming sequence should be NOPs, as shown in [Example 5-3](#).

#### EXAMPLE 5-1: ERASING A PROGRAM MEMORY PAGE

```
; Set up NVMCON for block erase operation
MOV    #0x4042, W0                ;
MOV    W0, NVMCON                 ; Initialize NVMCON
; Init pointer to row to be ERASED
MOV    #tblpage(PROG_ADDR), W0    ;
MOV    W0, TBLPAG                 ; Initialize PM Page Boundary SFR
MOV    #tbloffset(PROG_ADDR), W0  ; Initialize in-page EA[15:0] pointer
TBLWTL W0, [W0]                   ; Set base address of erase block
DISI    #5                         ; Block all interrupts with priority < 7
                                           ; for next 5 instructions

MOV    #0x55, W0
MOV    W0, NVMKEY                 ; Write the 55 key
MOV    #0xAA, W1
MOV    W1, NVMKEY                 ; Write the AA key
BSET   NVMCON, #WR                ; Start the erase sequence
NOP                                         ; Insert two NOPs after the erase
NOP                                         ; command is asserted
```

### 6.3 System Reset

The dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 family of devices have two types of Reset:

- Cold Reset
- Warm Reset

A cold Reset is the result of a Power-on Reset (POR) or a Brown-out Reset (BOR). On a cold Reset, the FNOSC Configuration bits in the FOSC device Configuration register selects the device clock source.

A warm Reset is the result of all other reset sources, including the `RESET` instruction. On warm Reset, the device will continue to operate from the current clock source as indicated by the Current Oscillator Selection bits (`COSC<2:0>`) in the Oscillator Control register (`OSCCON<14:12>`).

The device is kept in a Reset state until the system power supplies have stabilized at appropriate levels and the oscillator clock is ready. The description of the sequence in which this occurs is shown in [Figure 6-2](#).

**TABLE 6-1: OSCILLATOR DELAY**

Oscillator Mode	Oscillator Startup Delay	Oscillator Startup Timer	PLL Lock Time	Total Delay
FRC, FRCDIV16, FRCDIVN	TOSCD	—	—	TOSCD
FRCPLL	TOSCD	—	TLOCK	TOSCD + TLOCK
XT	TOSCD	TOST	—	TOSCD + TOST
HS	TOSCD	TOST	—	TOSCD + TOST
EC	—	—	—	—
XTPLL	TOSCD	TOST	TLOCK	TOSCD + TOST + TLOCK
HSPLL	TOSCD	TOST	TLOCK	TOSCD + TOST + TLOCK
ECPLL	—	—	TLOCK	TLOCK
SOSC	TOSCD	TOST	—	TOSCD + TOST
LPRC	TOSCD	—	—	TOSCD

- Note 1:** TOSCD = Oscillator Start-up Delay (1.1  $\mu$ s max for FRC, 70  $\mu$ s max for LPRC). Crystal Oscillator start-up times vary with crystal characteristics, load capacitance, etc.
- 2:** TOST = Oscillator Start-up Timer Delay (1024 oscillator clock period). For example, TOST = 102.4  $\mu$ s for a 10 MHz crystal and TOST = 32 ms for a 32 kHz crystal.
- 3:** TLOCK = PLL lock time (1.5 ms nominal), if PLL is enabled.

**REGISTER 7-23: IPC8: INTERRUPT PRIORITY CONTROL REGISTER 8**

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—	C1IP<2:0> <sup>(1)</sup>			—	C1RXIP<2:0> <sup>(1)</sup>		
bit 15				bit 8			

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—	SPI2IP<2:0>			—	SPI2EIP<2:0>		
bit 7				bit 0			

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15 **Unimplemented:** Read as '0'

bit 14-12 **C1IP<2:0>:** ECAN1 Event Interrupt Priority bits<sup>(1)</sup>

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

bit 11 **Unimplemented:** Read as '0'

bit 10-8 **C1RXIP<2:0>:** ECAN1 Receive Data Ready Interrupt Priority bits<sup>(1)</sup>

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

bit 7 **Unimplemented:** Read as '0'

bit 6-4 **SPI2IP<2:0>:** SPI2 Event Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

bit 3 **Unimplemented:** Read as '0'

bit 2-0 **SPI2EIP<2:0>:** SPI2 Error Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

**Note 1:** Interrupts are disabled on devices without an ECAN™ module.

## 9.4 Clock Switching Operation

Applications are free to switch among any of the four clock sources (Primary, LP, FRC and LPRC) under software control at any time. To limit the possible side effects of this flexibility, dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 devices have a safeguard lock built into the switch process.

**Note:** Primary Oscillator mode has three different submodes (XT, HS and EC), which are determined by the POSCMD<1:0> Configuration bits. While an application can switch to and from Primary Oscillator mode in software, it cannot switch among the different primary submodes without reprogramming the device.

### 9.4.1 ENABLING CLOCK SWITCHING

To enable clock switching, the FCKSM1 Configuration bit in the Configuration register must be programmed to '0'. (Refer to [Section 28.1 "Configuration Bits"](#) for further details.) If the FCKSM1 Configuration bit is unprogrammed ('1'), the clock switching function and Fail-Safe Clock Monitor function are disabled. This is the default setting.

The NOSC control bits (OSCCON<10:8>) do not control the clock selection when clock switching is disabled. However, the COSC bits (OSCCON<14:12>) reflect the clock source selected by the FNOSC Configuration bits.

The OSWEN control bit (OSCCON<0>) has no effect when clock switching is disabled. It is held at '0' at all times.

### 9.4.2 OSCILLATOR SWITCHING SEQUENCE

Performing a clock switch requires this basic sequence:

1. If desired, read the COSC bits (OSCCON<14:12>) to determine the current oscillator source.
2. Perform the unlock sequence to allow a write to the OSCCON register high byte.
3. Write the appropriate value to the NOSC control bits (OSCCON<10:8>) for the new oscillator source.
4. Perform the unlock sequence to allow a write to the OSCCON register low byte.
5. Set the OSWEN bit (OSCCON<0>) to initiate the oscillator switch.

Once the basic sequence is completed, the system clock hardware responds automatically as follows:

1. The clock switching hardware compares the COSC status bits with the new value of the NOSC control bits. If they are the same, the clock switch is a redundant operation. In this case, the OSWEN bit is cleared automatically and the clock switch is aborted.

2. If a valid clock switch has been initiated, the LOCK (OSCCON<5>) and the CF (OSCCON<3>) status bits are cleared.
3. The new oscillator is turned on by the hardware if it is not currently running. If a crystal oscillator must be turned on, the hardware waits until the Oscillator Start-up Timer (OST) expires. If the new source is using the PLL, the hardware waits until a PLL lock is detected (LOCK = 1).
4. The hardware waits for 10 clock cycles from the new clock source and then performs the clock switch.
5. The hardware clears the OSWEN bit to indicate a successful clock transition. In addition, the NOSC bit values are transferred to the COSC status bits.
6. The old clock source is turned off at this time, with the exception of LPRC (if WDT or FSCM are enabled) or LP (if LPOSCEN remains set).

**Note 1:** The processor continues to execute code throughout the clock switching sequence. Timing-sensitive code should not be executed during this time.

- 2: Direct clock switches between any primary oscillator mode with PLL and FRCPLL mode are not permitted. This applies to clock switches in either direction. In these instances, the application must switch to FRC mode as a transition clock source between the two PLL modes.
- 3: Refer to **Section 39. "Oscillator (Part III)"** (DS70216) in the *"dsPIC33F/PIC24H Family Reference Manual"* for details.

## 9.5 Fail-Safe Clock Monitor (FSCM)

The Fail-Safe Clock Monitor (FSCM) allows the device to continue to operate even in the event of an oscillator failure. The FSCM function is enabled by programming. If the FSCM function is enabled, the LPRC internal oscillator runs at all times (except during Sleep mode) and is not subject to control by the Watchdog Timer.

In the event of an oscillator failure, the FSCM generates a clock failure trap event and switches the system clock over to the FRC oscillator. Then the application program can either attempt to restart the oscillator or execute a controlled shutdown. The trap can be treated as a warm Reset by simply loading the Reset address into the oscillator fail trap vector.

If the PLL multiplier is used to scale the system clock, the internal FRC is also multiplied by the same factor on clock failure. Essentially, the device switches to FRC with PLL on a clock failure.

## 10.5 Power-Saving Resources

Many useful resources related to power-saving modes are provided on the main product page of the Microchip web site for the devices listed in this data sheet. This product page, which can be accessed using this [link](http://www.microchip.com/wwwproducts/Devices.aspx?dDocName=en532315), contains the latest updates and additional information.

<p><b>Note:</b> In the event you are not able to access the product page using the link above, enter this URL in your browser: <a href="http://www.microchip.com/wwwproducts/Devices.aspx?dDocName=en532315">http://www.microchip.com/wwwproducts/Devices.aspx?dDocName=en532315</a></p>
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### 10.5.1 KEY RESOURCES

- **Section 9. “Watchdog Timer and Power-Saving Modes”** (DS70196)
- Code Samples
- Application Notes
- Software Libraries
- Webinars
- All related dsPIC33F/PIC24H Family Reference Manuals Sections
- Development Tools

2: Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 “Memory Organization”** in this data sheet for device-specific register and bit information.

The Output Compare module has multiple operating modes:

- Active-Low One-Shot mode
- Active-High One-Shot mode
- Toggle mode
- Delayed One-Shot mode
- Continuous Pulse mode
- PWM mode without fault protection
- PWM mode with fault protection

**REGISTER 16-8: PxDTCON2: DEAD-TIME CONTROL REGISTER 2<sup>(1)</sup>**

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	DTS3A	DTS3I	DTS2A	DTS2I	DTS1A	DTS1I
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15-6      **Unimplemented:** Read as '0'
- bit 5      **DTS3A:** Dead-Time Select for PWMxH3 Signal Going Active bit  
             1 = Dead time provided from Unit B  
             0 = Dead time provided from Unit A
- bit 4      **DTS3I:** Dead-Time Select for PWMxL3 Signal Going Inactive bit  
             1 = Dead time provided from Unit B  
             0 = Dead time provided from Unit A
- bit 3      **DTS2A:** Dead-Time Select for PWMxH2 Signal Going Active bit  
             1 = Dead time provided from Unit B  
             0 = Dead time provided from Unit A
- bit 2      **DTS2I:** Dead-Time Select for PWMxL2 Signal Going Inactive bit  
             1 = Dead time provided from Unit B  
             0 = Dead time provided from Unit A
- bit 1      **DTS1A:** Dead-Time Select for PWMxH1 Signal Going Active bit  
             1 = Dead time provided from Unit B  
             0 = Dead time provided from Unit A
- bit 0      **DTS1I:** Dead-Time Select for PWMxL1 Signal Going Inactive bit  
             1 = Dead time provided from Unit B  
             0 = Dead time provided from Unit A

**Note 1:** PWM2 supports only one PWM I/O pin pair.

**REGISTER 16-10: PxOVDCON: OVERRIDE CONTROL REGISTER<sup>(1)</sup>**

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	POVD3H	POVD3L	POVD2H	POVD2L	POVD1H	POVD1L
bit 15						bit 8	

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	POUT3H	POUT3L	POUT2H	POUT2L	POUT1H	POUT1L
bit 7						bit 0	

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-14 **Unimplemented:** Read as '0'

bit 13-8 **POVDxH<3:1>:POVDxL<3:1>:** PWM Output Override bits

1 = Output on PWMx I/O pin is controlled by the PWM generator

0 = Output on PWMx I/O pin is controlled by the value in the corresponding POUTxH:POUTxL bit

bit 7-6 **Unimplemented:** Read as '0'

bit 5-0 **POUTxH<3:1>:POUTxL<3:1>:** PWM Manual Output bits

1 = PWMx I/O pin is driven active when the corresponding POVDxH:POVDxL bit is cleared

0 = PWMx I/O pin is driven inactive when the corresponding POVDxH:POVDxL bit is cleared

**Note 1:** PWM2 supports only one PWM I/O pin pair.

## 21.5 ECAN Control Registers

**REGISTER 21-1: CiCTRL1: ECAN™ CONTROL REGISTER 1**

U-0	U-0	R/W-0	R/W-0	r-0	R/W-1	R/W-0	R/W-0
—	—	CSIDL	ABAT	—	REQOP<2:0>		
bit 15						bit 8	

R-1	R-0	R-0	U-0	R/W-0	U-0	U-0	R/W-0
OPMODE<2:0>			—	CANCAP	—	—	WIN
bit 7						bit 0	

<b>Legend:</b>	r = Bit is Reserved		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

- bit 15-14     **Unimplemented:** Read as '0'
- bit 13     **CSIDL:** Stop in Idle Mode bit  
             1 = Discontinue module operation when device enters Idle mode  
             0 = Continue module operation in Idle mode
- bit 12     **ABAT:** Abort All Pending Transmissions bit  
             1 = Signal all transmit buffers to abort transmission  
             0 = Module will clear this bit when all transmissions are aborted
- bit 11     **Reserved:** Do not use
- bit 10-8     **REQOP<2:0>:** Request Operation Mode bits  
             111 = Set Listen All Messages mode  
             110 = Reserved  
             101 = Reserved  
             100 = Set Configuration mode  
             011 = Set Listen Only Mode  
             010 = Set Loopback mode  
             001 = Set Disable mode  
             000 = Set Normal Operation mode
- bit 7-5     **OPMODE<2:0>:** Operation Mode bits  
             111 = Module is in Listen All Messages mode  
             110 = Reserved  
             101 = Reserved  
             100 = Module is in Configuration mode  
             011 = Module is in Listen Only mode  
             010 = Module is in Loopback mode  
             001 = Module is in Disable mode  
             000 = Module is in Normal Operation mode
- bit 4     **Unimplemented:** Read as '0'
- bit 3     **CANCAP:** CAN Message Receive Timer Capture Event Enable bit  
             1 = Enable input capture based on CAN message receive  
             0 = Disable CAN capture
- bit 2-1     **Unimplemented:** Read as '0'
- bit 0     **WIN:** SFR Map Window Select bit  
             1 = Use filter window  
             0 = Use buffer window

**REGISTER 21-20: C<sub>i</sub>RX<sub>M</sub>nSID: ECAN™ ACCEPTANCE FILTER MASK STANDARD IDENTIFIER**  
**REGISTER n (n = 0-2)**

R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
SID10	SID9	SID8	SID7	SID6	SID5	SID4	SID3
bit 15							bit 8

R/W-x	R/W-x	R/W-x	U-0	R/W-x	U-0	R/W-x	R/W-x
SID2	SID1	SID0	—	MIDE	—	EID17	EID16
bit 7							bit 0

**Legend:**

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
-n = Value at POR                      '1' = Bit is set                      '0' = Bit is cleared                      x = Bit is unknown

- bit 15-5      **SID<10:0>**: Standard Identifier bits  
                    1 = Include bit SID<sub>x</sub> in filter comparison  
                    0 = Bit SID<sub>x</sub> is don't care in filter comparison
- bit 4      **Unimplemented**: Read as '0'
- bit 3      **MIDE**: Identifier Receive Mode bit  
                    1 = Match only message types (standard or extended address) that correspond to EXIDE bit in filter  
                    0 = Match either standard or extended address message if filters match  
                            (i.e., if (Filter SID) = (Message SID) or if (Filter SID/EID) = (Message SID/EID))
- bit 2      **Unimplemented**: Read as '0'
- bit 1-0      **EID<17:16>**: Extended Identifier bits  
                    1 = Include bit EID<sub>x</sub> in filter comparison  
                    0 = Bit EID<sub>x</sub> is don't care in filter comparison

**REGISTER 21-21: C<sub>i</sub>RX<sub>M</sub>nEID: ECAN™ ACCEPTANCE FILTER MASK EXTENDED IDENTIFIER**  
**REGISTER n (n = 0-2)**

R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
EID15	EID14	EID13	EID12	EID11	EID10	EID9	EID8
bit 15							bit 8

R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
EID7	EID6	EID5	EID4	EID3	EID2	EID1	EID0
bit 7							bit 0

**Legend:**

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
-n = Value at POR                      '1' = Bit is set                      '0' = Bit is cleared                      x = Bit is unknown

- bit 15-0      **EID<15:0>**: Extended Identifier bits  
                    1 = Include bit EID<sub>x</sub> in filter comparison  
                    0 = Bit EID<sub>x</sub> is don't care in filter comparison

## 22.6 ADC Control Registers

REGISTER 22-1: AD1CON1: ADC1 CONTROL REGISTER 1

R/W-0	U-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0	R/W-0
ADON	—	ADSIDL	ADDMABM	—	AD12B	FORM<1:0>	
bit 15							bit 8

R/W-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0	R/W-0 HC, HS	R/C-0 HC, HS
SSRC<2:0>	—	SIMSAM	ASAM	SAMP	DONE		
bit 7							bit 0

<b>Legend:</b>	HC = Cleared by hardware	HS = Set by hardware
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared
		x = Bit is unknown

- bit 15      **ADON:** ADC Operating Mode bit  
             1 = ADC module is operating  
             0 = ADC is off
- bit 14      **Unimplemented:** Read as '0'
- bit 13      **ADSIDL:** Stop in Idle Mode bit  
             1 = Discontinue module operation when device enters Idle mode  
             0 = Continue module operation in Idle mode
- bit 12      **ADDMABM:** DMA Buffer Build Mode bit  
             1 = DMA buffers are written in the order of conversion. The module provides an address to the DMA channel that is the same as the address used for the non-DMA stand-alone buffer  
             0 = DMA buffers are written in Scatter/Gather mode. The module provides a scatter/gather address to the DMA channel, based on the index of the analog input and the size of the DMA buffer
- bit 11      **Unimplemented:** Read as '0'
- bit 10      **AD12B:** 10-bit or 12-bit Operation Mode bit  
             1 = 12-bit, 1-channel ADC operation  
             0 = 10-bit, 4-channel ADC operation
- bit 9-8     **FORM<1:0>:** Data Output Format bits  
             For 10-bit operation:  
             11 = Signed fractional (DOUT = sddd dddd dd00 0000, where s = .NOT.d<9>)  
             10 = Fractional (DOUT = dddd dddd dd00 0000)  
             01 = Signed integer (DOUT = ssss sssd dddd dddd, where s = .NOT.d<9>)  
             00 = Integer (DOUT = 0000 00dd dddd dddd)  
             For 12-bit operation:  
             11 = Signed fractional (DOUT = sddd dddd dddd 0000, where s = .NOT.d<11>)  
             10 = Fractional (DOUT = dddd dddd dddd 0000)  
             01 = Signed Integer (DOUT = ssss sddd dddd dddd, where s = .NOT.d<11>)  
             00 = Integer (DOUT = 0000 dddd dddd dddd)
- bit 7-5     **SSRC<2:0>:** Sample Clock Source Select bits  
             111 = Internal counter ends sampling and starts conversion (auto-convert)  
             110 = Reserved  
             101 = Motor Control PWM2 interval ends sampling and starts conversion  
             100 = GP timer (Timer5 for ADC1) compare ends sampling and starts conversion  
             011 = Motor Control PWM1 interval ends sampling and starts conversion  
             010 = GP timer (Timer3 for ADC1) compare ends sampling and starts conversion  
             001 = Active transition on INT0 pin ends sampling and starts conversion  
             000 = Clearing sample bit ends sampling and starts conversion
- bit 4      **Unimplemented:** Read as '0'

**REGISTER 22-5: AD1CHS123: ADC1 INPUT CHANNEL 1, 2, 3 SELECT REGISTER**

U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0
—	—	—	—	—	CH123NB<1:0>		CH123SB
bit 15						bit 8	

U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0
—	—	—	—	—	CH123NA<1:0>		CH123SA
bit 7						bit 0	

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-11 **Unimplemented:** Read as '0'

bit 10-9 **CH123NB<1:0>:** Channel 1, 2, 3 Negative Input Select for Sample B bits

**dsPIC33FJ32MC302, dsPIC33FJ64MC202/802 and dsPIC33FJ128MC202/802 devices only:**

If AD12B = 1:

11 = Reserved

10 = Reserved

01 = Reserved

00 = Reserved

If AD12B = 0:

11 = Reserved

10 = Reserved

01 = CH1, CH2, CH3 negative input is VREF-

00 = CH1, CH2, CH3 negative input is VREF-

**dsPIC33FJ32MC304, dsPIC33FJ64MC204/804 and dsPIC33FJ128MC204/804 devices only:**

If AD12B = 1:

11 = Reserved

10 = Reserved

01 = Reserved

00 = Reserved

If AD12B = 0:

11 = Reserved

10 = CH1 negative input is AN6, CH2 negative input is AN7, CH3 negative input is AN8

01 = CH1, CH2, CH3 negative input is VREF-

00 = CH1, CH2, CH3 negative input is VREF-

bit 8 **CH123SB:** Channel 1, 2, 3 Positive Input Select for Sample B bit

If AD12B = 1:

1 = Reserved

0 = Reserved

If AD12B = 0:

1 = CH1 positive input is AN3, CH2 positive input is AN4, CH3 positive input is AN5

0 = CH1 positive input is AN0, CH2 positive input is AN1, CH3 positive input is AN2

bit 7-3 **Unimplemented:** Read as '0'

**REGISTER 23-3: DAC1DFLT: DAC DEFAULT DATA REGISTER**

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
DAC1DFLT<15:8>							
bit 15				bit 8			

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
DAC1DFLT<7:0>							
bit 7				bit 0			

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-0 **DAC1DFLT<15:0>**: DAC Default Value bits

**REGISTER 23-4: DAC1LDAT: DAC LEFT DATA REGISTER**

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
DAC1LDAT<15:8>							
bit 15				bit 8			

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
DAC1LDAT<7:0>							
bit 7				bit 0			

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-0 **DAC1LDAT<15:0>**: Left Channel Data Port bits

**REGISTER 23-5: DAC1RDAT: DAC RIGHT DATA REGISTER**

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
DAC1RDAT<15:8>							
bit 15				bit 8			

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
DAC1RDAT<7:0>							
bit 7				bit 0			

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-0 **DAC1RDAT<15:0>**: Right Channel Data Port bits

**REGISTER 25-2: PADCFG1: PAD CONFIGURATION CONTROL REGISTER**

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15						bit 8	

U-0	U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0
—	—	—	—	—	—	RTSECSEL <sup>(1)</sup>	PMPTTL
bit 7						bit 0	

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-2      **Unimplemented:** Read as '0'

bit 1      **RTSECSEL:** RTCC Seconds Clock Output Select bit<sup>(1)</sup>

1 = RTCC seconds clock is selected for the RTCC pin

0 = RTCC alarm pulse is selected for the RTCC pin

bit 0      **PMPTTL:** PMP Module TTL Input Buffer Select bit

1 = PMP module uses TTL input buffers

0 = PMP module uses Schmitt Trigger input buffers

**Note 1:** To enable the actual RTCC output, the RTCOE bit (RCFGCAL) needs to be set.

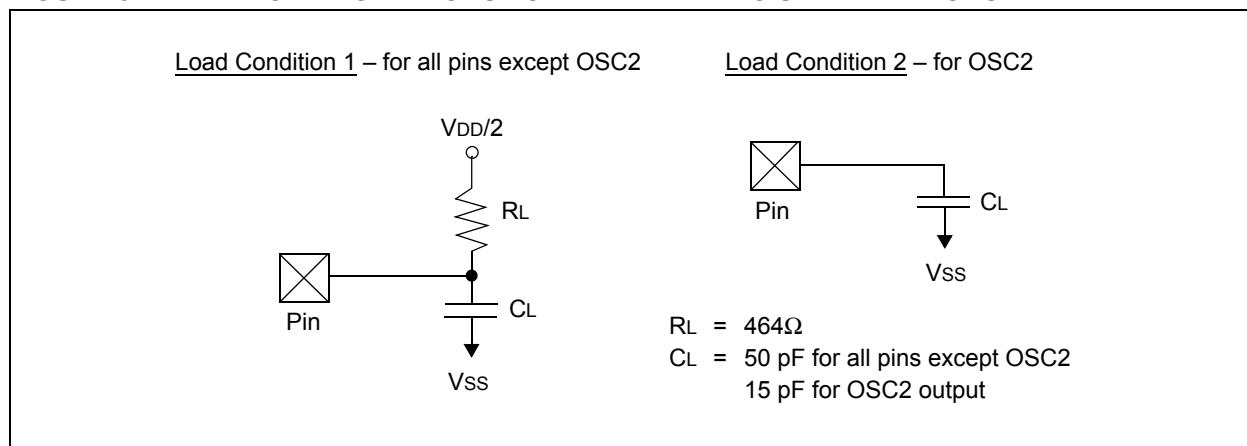
## 31.2 AC Characteristics and Timing Parameters

This section defines dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 AC characteristics and timing parameters.

**TABLE 31-14: TEMPERATURE AND VOLTAGE SPECIFICATIONS – AC**

<b>AC CHARACTERISTICS</b>	<b>Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)</b>
	Operating temperature $-40^{\circ}\text{C} \leq T_A \leq +85^{\circ}\text{C}$ for Industrial $-40^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$ for Extended Operating voltage $V_{DD}$ range as described in <a href="#">Table 31-1</a> .

**FIGURE 31-1: LOAD CONDITIONS FOR DEVICE TIMING SPECIFICATIONS**



**TABLE 31-15: CAPACITIVE LOADING REQUIREMENTS ON OUTPUT PINS**

Param No.	Symbol	Characteristic	Min	Typ	Max	Units	Conditions
DO50	Cosco	OSC2/SOSCO pin	—	—	15	pF	In XT and HS modes when external clock is used to drive OSC1
DO56	Cio	All I/O pins and OSC2	—	—	50	pF	EC mode
DO58	CB	SCLx, SDAx	—	—	400	pF	In I <sup>2</sup> C™ mode

TABLE 31-23: TIMER2 AND TIMER4 EXTERNAL CLOCK TIMING REQUIREMENTS

AC CHARACTERISTICS				Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature $-40^{\circ}\text{C} \leq T_A \leq +85^{\circ}\text{C}$ for Industrial $-40^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$ for Extended				
Param No.	Symbol	Characteristic <sup>(1)</sup>		Min	Typ	Max	Units	Conditions
TB10	TtxH	TxCK High Time	Synchronous mode	Greater of: 20 or (Tcy + 20)/N	—	—	ns	Must also meet parameter TB15 N = prescale value (1, 8, 64, 256)
TB11	TtxL	TxCK Low Time	Synchronous mode	Greater of: 20 or (Tcy + 20)/N	—	—	ns	Must also meet parameter TB15 N = prescale value (1, 8, 64, 256)
TB15	TtxP	TxCK Input Period	Synchronous mode	Greater of: 40 or (2 Tcy + 40)/N	—	—	ns	N = prescale value (1, 8, 64, 256)
TB20	TCKEXTMRL	Delay from External TxCK Clock Edge to Timer Increment		0.75 Tcy + 40	—	1.75 Tcy + 40	ns	—

**Note 1:** These parameters are characterized, but are not tested in manufacturing.

TABLE 31-24: TIMER3 AND TIMER5 EXTERNAL CLOCK TIMING REQUIREMENTS

AC CHARACTERISTICS				Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature $-40^{\circ}\text{C} \leq T_A \leq +85^{\circ}\text{C}$ for Industrial $-40^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$ for Extended				
Param No.	Symbol	Characteristic <sup>(1)</sup>		Min	Typ	Max	Units	Conditions
TC10	TtxH	TxCK High Time	Synchronous	Tcy + 20	—	—	ns	Must also meet parameter TC15
TC11	TtxL	TxCK Low Time	Synchronous	Tcy + 20	—	—	ns	Must also meet parameter TC15
TC15	TtxP	TxCK Input Period	Synchronous, with prescaler	2 Tcy + 40	—	—	ns	—
TC20	TCKEXTMRL	Delay from External TxCK Clock Edge to Timer Increment		0.75 Tcy + 40	—	1.75 Tcy + 40	ns	—

**Note 1:** These parameters are characterized, but are not tested in manufacturing.

**TABLE 31-38: SPIx SLAVE MODE (FULL-DUPLEX, CKE = 0, CKP = 1, SMP = 0) TIMING REQUIREMENTS**

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param No.	Symbol	Characteristic <sup>(1)</sup>	Min	Typ <sup>(2)</sup>	Max	Units	Conditions
SP70	TscP	Maximum SCK Input Frequency	—	—	15	MHz	See <b>Note 3</b>
SP72	TscF	SCKx Input Fall Time	—	—	—	ns	See parameter <a href="#">DO32</a> and <b>Note 4</b>
SP73	TscR	SCKx Input Rise Time	—	—	—	ns	See parameter <a href="#">DO31</a> and <b>Note 4</b>
SP30	TdoF	SDOx Data Output Fall Time	—	—	—	ns	See parameter <a href="#">DO32</a> and <b>Note 4</b>
SP31	TdoR	SDOx Data Output Rise Time	—	—	—	ns	See parameter <a href="#">DO31</a> and <b>Note 4</b>
SP35	Tsch2doV, TscL2doV	SDOx Data Output Valid after SCKx Edge	—	6	20	ns	—
SP36	TdoV2scH, TdoV2scL	SDOx Data Output Setup to First SCKx Edge	30	—	—	ns	—
SP40	TdiV2scH, TdiV2scL	Setup Time of SDIx Data Input to SCKx Edge	30	—	—	ns	—
SP41	Tsch2diL, TscL2diL	Hold Time of SDIx Data Input to SCKx Edge	30	—	—	ns	—
SP50	TssL2scH, TssL2scL	$\overline{SSx} \downarrow$ to SCKx $\uparrow$ or SCKx Input	120	—	—	ns	—
SP51	TssH2doZ	$\overline{SSx} \uparrow$ to SDOx Output High-Impedance <sup>(4)</sup>	10	—	50	ns	—
SP52	Tsch2ssH TscL2ssH	$\overline{SSx}$ after SCKx Edge	1.5 TCY + 40	—	—	ns	See <b>Note 4</b>

**Note 1:** These parameters are characterized, but are not tested in manufacturing.

**2:** Data in “Typ” column is at 3.3V, 25°C unless otherwise stated.

**3:** The minimum clock period for SCKx is 66.7 ns. Therefore, the SCK clock generated by the Master must not violate this specification.

**4:** Assumes 50 pF load on all SPIx pins.

**FIGURE 31-21: SPIx SLAVE MODE (FULL-DUPLEX, CKE = 0, CKP = 0, SMP = 0) TIMING CHARACTERISTICS**

