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#### Applications of "<u>Embedded -</u> <u>Microcontrollers</u>"

#### Details

E·XF

Product Status	Active
Core Processor	ARM® Cortex®-M0+
Core Size	32-Bit Single-Core
Speed	48MHz
Connectivity	CANbus, I <sup>2</sup> C, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, POR, WDT
Number of I/O	26
Program Memory Size	128KB (128K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	16K x 8
Voltage - Supply (Vcc/Vdd)	2.7V ~ 5.5V
Data Converters	A/D 10x12b, 1x16b; D/A 1x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	32-TQFP
Supplier Device Package	32-TQFP (7x7)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/atsamc21e17a-ant

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

Bit Position	Name	Description
59:36	TSENS OFFSET	TSENS Offset Calibration. Should be written to TSENS OFFSET register.
63:60	Reserved	

# **Related Links**

CAL GAIN OFFSET

# 9.6 Serial Number

Each device has a unique 128-bit serial number which is a concatenation of four 32-bit words contained at the following addresses:

Word 0: 0x0080A00C

Word 1: 0x0080A040

Word 2: 0x0080A044

Word 3: 0x0080A048

The uniqueness of the serial number is guaranteed only when using all 128 bits.

Peripheral Source	NVIC Line
TC6 – Timer Counter 6	
TC2 – Timer Counter 2	22
TC7 – Timer Counter 7	
TC3 – Timer Counter 3Reserved	23
TC4 – Timer Counter 4Reserved	24
ADC0 – Analog-to-Digital Converter 0	25
Reserved	26
AC – Analog Comparator	27
Reserved	28
Reserved	29
PTC – Peripheral Touch Controller	30
Reserved	31

# 10.3 Micro Trace Buffer

#### 10.3.1 Features

- Program flow tracing for the Cortex-M0+ processor
- MTB SRAM can be used for both trace and general purpose storage by the processor
- The position and size of the trace buffer in SRAM is configurable by software
- CoreSight compliant

# 10.3.2 Overview

When enabled, the MTB records changes in program flow, reported by the Cortex-M0+ processor over the execution trace interface shared between the Cortex-M0+ processor and the CoreSight MTB-M0+. This information is stored as trace packets in the SRAM by the MTB. An off-chip debugger can extract the trace information using the Debug Access Port to read the trace information from the SRAM. The debugger can then reconstruct the program flow from this information.

The MTB simultaneously stores trace information into the SRAM, and gives the processor access to the SRAM. The MTB ensures that trace write accesses have priority over processor accesses.

The execution trace packet consists of a pair of 32-bit words that the MTB generates when it detects the processor PC value changes non-sequentially. A non-sequential PC change can occur during branch instructions or during exception entry. See the CoreSight MTB-M0+ Technical Reference Manual for more details on the MTB execution trace packet format.

Tracing is enabled when the MASTER.EN bit in the Master Trace Control Register is 1. There are various ways to set the bit to 1 to start tracing, or to 0 to stop tracing. See the CoreSight Cortex-M0+ Technical Reference Manual for more details on the Trace start and stop and for a detailed description of the MTB's MASTER register. The MTB can be programmed to stop tracing automatically when the memory fills to a specified watermark level or to start or stop tracing by writing directly to the MASTER.EN bit. If the

# Name: DIVIDEND Offset: 0x08 Reset: 0x0000 Property:

Bit	31	30	29	28	27	26	25	24
				DIVIDEN	ID[31:24]			
Access	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Reset	0	0	0	0	0	0	0	0
Bit	23	22	21	20	19	18	17	16
				DIVIDEN	ID[23:16]			
Access	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Reset	0	0	0	0	0	0	0	0
Bit	15	14	13	12	11	10	9	8
				DIVIDE	ND[15:8]			
Access	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Reset	0	0	0	0	0	0	0	0
Bit	7	6	5	4	3	2	1	0
				DIVIDE	ND[7:0]			
Access	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Reset	0	0	0	0	0	0	0	0

# Bits 31:0 – DIVIDEND[31:0]: Dividend Value

Holds the 32-bit dividend for the divide operation. If the Signed bit in Control A register (CTRLA.SIGNED) is zero, DIVIDEND is unsigned. If CTRLA.SIGNED = 1, DIVIDEND is signed two's complement. Refer to Performing Division, Operand Size and Signed Division.

# 14.8.4 Divisor

Name:DIVISOROffset:0x0CReset:0x0000Property:-

PCHCTRL22, PCHCTRL23, PCHCTRL24, PCHCTRL25, PCHCTRL26, PCHCTRL27, PCHCTRL28, PCHCTRL29, PCHCTRL30, PCHCTRL31, PCHCTRL32, PCHCTRL33, PCHCTRL34, PCHCTRL35, PCHCTRL36, PCHCTRL37, PCHCTRL38, PCHCTRL39, PCHCTRL40, PCHCTRL41, PCHCTRL42, PCHCTRL43, PCHCTRL44, PCHCTRL45

#### 16.6.3.4 Configuration Lock

The peripheral clock configuration can be locked for further write accesses by setting the Write Lock bit in the Peripheral Channel Control register PCHCTRLm.WRTLOCK=1). All writing to the PCHCTRLm register will be ignored. It can only be unlocked by a Power Reset.

The Generator source of a locked Peripheral Channel will be locked, too: The corresponding GENCTRLn register is locked, and can be unlocked only by a Power Reset.

There is one exception concerning the Generator 0. As it is used as GCLK\_MAIN, it cannot be locked. It is reset by any Reset and will start up in a known configuration. The software reset (CTRLA.SWRST) can not unlock the registers.

In case of an external Reset, the Generator source will be disabled. Even if the WRTLOCK bit is written to '1' the peripheral channels are disabled (PCHCTRLm.CHEN set to '0') until the Generator source is enabled again. Then, the PCHCTRLm.CHEN are set to '1' again.

# Related Links

### CTRLA

# 16.6.4 Additional Features

#### 16.6.4.1 Peripheral Clock Enable after Reset

The Generic Clock Controller must be able to provide a generic clock to some specific peripherals after a Reset. That means that the configuration of the Generators and Peripheral Channels after Reset is device-dependent.

Refer to GENCTRLn.SRC for details on GENCTRLn reset.

Refer to PCHCTRLm.SRC for details on PCHCTRLm reset.

# 16.6.5 Sleep Mode Operation

#### 16.6.5.1 SleepWalking

The GCLK module supports the SleepWalking feature.

If the system is in a sleep mode where the Generic Clocks are stopped, a peripheral that needs its clock in order to execute a process must request it from the Generic Clock Controller.

The Generic Clock Controller receives this request, determines which Generic Clock Generator is involved and which clock source needs to be awakened. It then wakes up the respective clock source, enables the Generator and Peripheral Channel stages successively, and delivers the clock to the peripheral.

The RUNSTDBY bit in the Generator Control register controls clock output to pin during standby sleep mode. If the bit is cleared, the Generator output is not available on pin. When set, the GCLK can continuously output the generator output to GCLK\_IO. Refer to External Clock for details.

#### **Related Links**

PM – Power Manager

Value	Description
0	The AHB clock for the APBC is stopped.
1	The AHB clock for the APBC is enabled

# Bit 1 – APBB: APBB AHB Clock Enable

Value	Description
0	The AHB clock for the APBB is stopped.
1	The AHB clock for the APBB is enabled.

#### Bit 0 – APBA: APBA AHB Clock Enable

Value	Description
0	The AHB clock for the APBA is stopped.
1	The AHB clock for the APBA is enabled.

# 17.8.7 APBA Mask

Name:	APBAMASK
Offset:	0x14 [ID-00001086]
Reset:	0x00000FFF
<b>Property:</b>	PAC Write-Protection

Bit	31	30	29	28	27	26	25	24
Access					-			
Reset								
Bit	23	22	21	20	19	18	17	16
Access								
Reset								
Bit	15	14	13	12	11	10	9	8
				TSENS	FREQM	EIC	RTC	WDT
Access				R/W	R/W	R/W	R/W	R/W
Reset				0	1	1	1	1
Bit	7	6	5	4	3	2	1	0
	GCLK	SUPC	OSC32KCTRL	OSCCTRL	RSTC	MCLK	PM	PAC
Access	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Reset	1	1	1	1	1	1	1	1

# Bit 12 – TSENS: TSENS APBA Clock Enable

Value	Description
0	The APBA clock for the TSENS is stopped.
1	The APBA clock for the TSENS is enabled.

#### Bit 11 – FREQM: FREQM APBA Clock Enable

#### Figure 23-3. Window-Mode Operation



# 23.6.3 DMA Operation

Not applicable.

#### 23.6.4 Interrupts

The WDT has the following interrupt source:

- Early Warning (EW): Indicates that the counter is approaching the time-out condition.
  - This interrupt is an asynchronous wake-up source.

Each interrupt source has an interrupt flag associated with it. The interrupt flag in the Interrupt Flag Status and Clear (INTFLAG) register is set when the interrupt condition occurs.

Each interrupt can be individually enabled by writing a '1' to the corresponding bit in the Interrupt Enable Set (INTENSET) register, and disabled by writing a '1' to the corresponding bit in the Interrupt Enable Clear (INTENCLR) register.

An interrupt request is generated when the interrupt flag is set and the corresponding interrupt is enabled. The interrupt request remains active until the interrupt flag is cleared, the interrupt is disabled, or the WDT is reset. See the INTFLAG register description for details on how to clear interrupt flags. All interrupt requests from the peripheral are ORed together on system level to generate one combined interrupt request to the NVIC. The user must read the INTFLAG register to determine which interrupt condition is present.

Note: Interrupts must be globally enabled for interrupt requests to be generated.

#### **Related Links**

Nested Vector Interrupt Controller Overview Interrupt Line Mapping PM – Power Manager Sleep Mode Controller

# 23.6.5 Events

Not applicable.

# 23.6.6 Sleep Mode Operation Related Links CTRLA

# Bits 23:22 – TRIGACT[1:0]: Trigger Action

These bits define the trigger action used for a transfer.

TRIGACT[1:0]	Name	Description
0x0	BLOCK	One trigger required for each block transfer
0x1	-	Reserved
0x2	BEAT	One trigger required for each beat transfer
0x3	TRANSACTION	One trigger required for each transaction

# Bits 13:8 – TRIGSRC[5:0]: Trigger Source

These bits define the peripheral trigger which is source of the transfer. For details on trigger selection and trigger modes, refer to Transfer Triggers and Actions and CHCTRLB.TRIGACT.

#### Table 25-2. Peripheral Trigger Source

Value	Name	Description
0x00	DISABLE	Only software/event triggers
0x01	TSENS	TSENS Result Ready Trigger
0x02	SERCOM0 RX	SERCOM0 RX Trigger
0x03	SERCOM0 TX	SERCOM0TX Trigger
0x04	SERCOM1 RX	SERCOM1 RX Trigger
0x05	SERCOM1 TX	SERCOM1 TX Trigger
0x06	SERCOM2 RX	SERCOM2 RX Trigger
0x07	SERCOM2 TX	SERCOM2 TX Trigger
0x08	SERCOM3 RX	SERCOM3 RX Trigger
0x09	SERCOM3 TX	SERCOM3 TX Trigger
0x0A	SERCOM4 RX-	SERCOM4 RX TriggerReserved
0x0B	SERCOM4 TX-	SERCOM4 TX TriggerReserved
0x0C	SERCOM5 RX-	SERCOM5 RX TriggerReserved
0x0D	SERCOM5 TX-	SERCOM5 TX TriggerReserved
0x0E	CAN0 DEBUG-	CAN0 Debug TriggerReserved
0x0F	CAN1 DEBUG-	CAN1 Debug TriggerReserved
0x10	TCC0 OVF	TCC0 Overflow Trigger
0x11	TCC0 MC0	TCC0 Match/Compare 0 Trigger
0x12	TCC0 MC1	TCC0 Match/Compare 1 Trigger
0x13	TCC0 MC2	TCC0 Match/Compare 2 Trigger
0x14	TCC0 MC3	TCC0 Match/Compare 3 Trigger
0x15	TCC1 OVF	TCC1 Overflow Trigger

# SAM C20/C21

Bit	31	30	29	28	27	26	25	24
Access								
Reset								
Bit	23	22	21	20	19	18	17	16
Access								
Reset								
Bit	15	14	13	12	11	10	9	8
Access								
Reset								
Bit	7	6	5	4	3	2	1	0
							ENABLE	SWRST
Access							R	R
Reset							0	0

#### Bit 1 – ENABLE: SERCOM Enable Synchronization Busy

Enabling and disabling the SERCOM (CTRLA.ENABLE) requires synchronization. When written, the SYNCBUSY.ENABLE bit will be set until synchronization is complete.

Writes to any register (except for CTRLA.SWRST) while enable synchronization is on-going will be discarded and an APB error will be generated.

Value	Description
0	Enable synchronization is not busy.
1	Enable synchronization is busy.

#### **Bit 0 – SWRST: Software Reset Synchronization Busy**

Resetting the SERCOM (CTRLA.SWRST) requires synchronization. When written, the SYNCBUSY.SWRST bit will be set until synchronization is complete.

Writes to any register while synchronization is on-going will be discarded and an APB error will be generated.

Value	Description
0	SWRST synchronization is not busy.
1	SWRST synchronization is busy.

#### 33.8.8 Address

Name:ADDROffset:0x24 [ID-00001bb3]Reset:0x00000000Property:PAC Write-Protection, Enable-Protected

Name:DATAOffset:0x28 [ID-00001bb3]Reset:0x0000Property:Write-Synchronized, Read-Synchronized



# Bits 7:0 - DATA[7:0]: Data

The slave data register I/O location (DATA.DATA) provides access to the master transmit and receive data buffers. Reading valid data or writing data to be transmitted can be successfully done only when SCL is held low by the slave (STATUS.CLKHOLD is set). An exception occurs when reading the last data byte after the stop condition has been received.

Accessing DATA.DATA auto-triggers I<sup>2</sup>C bus operations. The operation performed depends on the state of CTRLB.ACKACT, CTRLB.SMEN and the type of access (read/write).

Writing or reading DATA.DATA when not in smart mode does not require synchronization.

# SAM C20/C21

Offset	Name	Bit Pos.								
0x2C		7:0				TOC	[7:0]			
0x2D		15:8				тос	[15:8]			
0x2E	TOCV	23:16								
0x2F	-	31:24								
0x30										
	Reserved									
0x3F										
0x40		7:0			1	TEC	[7:0]			
0x41	FCR	15:8	RP				REC[6:0]			
0x42	LOIX	23:16				CEL	.[7:0]			
0x43		31:24								
0x44		7:0	BO	EW	EP	ACT	[1:0]		LEC[2:0]	
0x45	PSR	15:8		PXE	RFDF	RBRS	RESI		DLEC[2:0]	
0x46		23:16			1		TDCV[6:0]			
0x47		31:24								
0x48		7:0					TDCF[6:0]			
0x49	TDCR	15:8					TDCO[6:0]			
0x4A		23:16								
0x4B		31:24								
0x4C										
	Reserved									
0x4F										
0x50		7:0	RF1L	RF1F	RF1W	RF1N	RF0L	RF0F	RF0W	RF0N
0x51	IR	15:8	TEFL	TEFF	TEFW	TEFN	TFE	TCF	TC	HPM
0x52		23:16	EP	ELO	BEU	BEC	DRX	TOO	MRAF	TSW
0x53		31:24			ARA	PED	PEA	WDI	BO	EW
0x54	-	7:0	RF1LE	RF1FE	RF1WE	RF1NE	RF0LE	RF0FE	RF0WE	RF0NE
0x55	IE	15:8	TEFLE	TEFFE	TEFWE	TEFNE	TFEE	TCFE	TCE	HPME
0x56	-	23:16	EPE	ELOE	BEUE	BECE	DRXE	TOOE	MRAFE	TSWE
0x57		31:24			ARAE	PEDE	PEAE	WDIE	BOE	EWE
0x58	-	7:0	RF1LL	RF1FL	RF1WL	RF1NL	RF0LL	RF0FL	RF0WL	RF0NL
0x59	ILS	15:8	TEFLL	TEFFL	TEFWL	TEFNL	TFEL	TCFL	TCL	HPML
0x5A		23:16	EPL	ELOL	BEUL	BECL	DRXL	TOOL	MRAFL	TSWL
0x5B		31:24			ARAL	PEDL	PEAL	WDIL	BOL	EWL
Ux5C	-	/:0							EININ	EININ
0x5D	ILE	15:8								
0x5E		23:10								
0x5F		31:24								
0x60	Reserved									
 0x7F	i leseiveu									
0x80		7:0				S[1:0]	ΔΝΕΙ	=[1:0]	RRES	RRFF
0x81	-	15.8						-[]		
0x82	GFC	23.16								
0x83	-	31.24								
0x84		7:0				FLSS	A[7:0]			
0x85	SIDFC	15.8				FI 89	A[15:8]			
0,00		10.0				1 1 1 3 3/				

Required read-synchronization is denoted by the "Read-Synchronized" property in the register description.

# 35.7 Register Description

Registers can be 8, 16, or 32 bits wide. Atomic 8-, 16- and 32-bit accesses are supported. In addition, the 8-bit quarters and 16-bit halves of a 32-bit register, and the 8-bit halves of a 16-bit register can be accessed directly.

Some registers are optionally write-protected by the Peripheral Access Controller (PAC). Optional PAC write-protection is denoted by the "PAC Write-Protection" property in each individual register description. For details, refer to Register Access Protection.

Some registers are synchronized when read and/or written. Synchronization is denoted by the "Write-Synchronized" or the "Read-Synchronized" property in each individual register description. For details, refer to Synchronization.

Some registers are enable-protected, meaning they can only be written when the peripheral is disabled. Enable-protection is denoted by the "Enable-Protected" property in each individual register description.

Value	Description
0	The Match or Capture Channel x interrupt is disabled.
1	The Match or Capture Channel x interrupt is enabled.

#### Bit 1 – ERR: Error Interrupt Enable

Writing a '0' to this bit has no effect.

Writing a '1' to this bit will set the Error Interrupt Enable bit, which enables the Error interrupt.

Value	Description
0	The Error interrupt is disabled.
1	The Error interrupt is enabled.

#### Bit 0 – OVF: Overflow Interrupt Enable

Writing a '0' to this bit has no effect.

Writing a '1' to this bit will set the Overflow Interrupt Enable bit, which enables the Overflow interrupt request.

Value	Description
0	The Overflow interrupt is disabled.
1	The Overflow interrupt is enabled.

#### 35.7.2.7 Interrupt Flag Status and Clear

Name:	INTFLAG
Offset:	0x0A
Reset:	0x00
Property:	-

Bit	7	6	5	4	3	2	1	0
				MCx			ERR	OVF
Access				R/W			R/W	R/W
Reset				0			0	0

#### Bit 4 – MCx: Match or Capture Channel x

This flag is set on a comparison match, or when the corresponding CCx register contains a valid capture value. This flag is set on the next CLK\_TC\_CNT cycle, and will generate an interrupt request if the corresponding Match or Capture Channel x Interrupt Enable bit in the Interrupt Enable Set register (INTENSET.MCx) is '1'.

Writing a '0' to one of these bits has no effect.

Writing a '1' to one of these bits will clear the corresponding Match or Capture Channel x interrupt flag

In capture operation, this flag is automatically cleared when CCx register is read.

# Bit 1 – ERR: Error Interrupt Flag

This flag is set when a new capture occurs on a channel while the corresponding Match or Capture Channel x interrupt flag is set, in which case there is nowhere to store the new capture.

Writing a '0' to this bit has no effect.

Writing a '1' to this bit clears the Error interrupt flag.

Name:PERBUFOffset:0x6C [ID-00002e48]Reset:0xFFFFFFFProperty:Write-Synchronized, Read-Synchronized

Bit	31	30	29	28	27	26	25	24
[								
Access		•						
Reset								
Bit	23	22	21	20	19	18	17	16
[				PERBU	F[17:10]			
Access	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Reset	1	1	1	1	1	1	1	1
Bit	15	14	13	12	11	10	9	8
[				PERBU	JF[9:2]			
Access	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Reset	1	1	1	1	1	1	1	1
Bit	7	6	5	4	3	2	1	0
[	PERB	UF[1:0]			DITHER	BUF[5:0]		
Access	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Reset	1	1	1	1	1	1	1	1

# Bits 23:6 – PERBUF[17:0]: Period Buffer Value

These bits hold the value of the period buffer register. The value is copied to PER register on UPDATE condition.

Note: When the TCC is configured as 16-bit timer/counter, the excess bits are read zero.

**Note:** This bit field occupies the MSB of the register, [23:m]. m is dependent on the Resolution bit in the Control A register (CTRLA.RESOLUTION):

CTRLA.RESOLUTION	Bits [23:m]
0x0 - NONE	23:0
0x1 - DITH4	23:4
0x2 - DITH5	23:5
0x3 - DITH6	23:6 (depicted)

#### Bits 5:0 – DITHERBUF[5:0]: Dithering Buffer Cycle Number

These bits represent the PER.DITHER bits buffer. When the double buffering is enabled, the value of this bit field is copied to the PER.DITHER bits on an UPDATE condition.

**Note:** This bit field consists of the n LSB of the register. n is dependent on the value of the Resolution bits in the Control A register (CTRLA.RESOLUTION):

# 37. CCL – Configurable Custom Logic

# 37.1 Overview

The Configurable Custom Logic (CCL) is a programmable logic peripheral which can be connected to the device pins, to events, or to other internal peripherals. This allows the user to eliminate logic gates for simple glue logic functions on the PCB.

Each LookUp Table (LUT) consists of three inputs, a truth table, an optional synchronizer/filter, and an optional edge detector. Each LUT can generate an output as a user programmable logic expression with three inputs. Inputs can be individually masked.

The output can be combinatorially generated from the inputs, and can be filtered to remove spikes. Optional sequential logic can be used. The inputs of the sequential module are individually controlled by two independent, adjacent LUT (LUT0/LUT1, LUT2/LUT3 etc.) outputs, enabling complex waveform generation.

# 37.2 Features

- Glue logic for general purpose PCB design
- Up to 4 programmable LookUp Tables (LUTs)
- Combinatorial logic functions: AND, NAND, OR, NOR, XOR, XNOR, NOT
- Sequential logic functions: Gated D Flip-Flop, JK Flip-Flop, gated D Latch, RS Latch
- Flexible LUT inputs selection:
  - I/Os
  - Events
  - Internal peripherals
  - Subsequent LUT output
- Output can be connected to the I/O pins or the Event System
- Optional synchronizer, filter, or edge detector available on each LUT output

# Table 37-4. D-Latch Characteristics

G	D	ουτ
0	Х	Hold state (no change)
1	0	Clear
1	1	Set

# **RS Latch (RS)**

When this configuration is selected, the S-input is driven by the even LUT output (LUT0 and LUT2), and the R-input is driven by the odd LUT output (LUT1 and LUT3), as shown in Figure 37-17.

# Figure 37-17. RS-Latch



When the even LUT is disabled LUTCTRL0.ENABLE=0 / LUTCTRL2.ENABLE=0), the latch output will be cleared. The R-input is forced enabled for one more APB clock cycle and S-input to zero. In all other cases, the latch output (OUT) is refreshed as shown in Table 37-5.

# Table 37-5. RS-Latch Characteristics

S	R	оит
0	0	Hold state (no change)
0	1	Clear
1	0	Set
1	1	Forbidden state

# 37.6.3 Events

The CCL can generate the following output events:

• OUTx: Lookup Table Output Value

Writing a '1' to the LUT Control Event Output Enable bit (LUTCTRL.LUTEO) enables the corresponding output event. Writing a '0' to this bit disables the corresponding output event.

The CCL can take the following actions on an input event:

• INSELx: The event is used as input for the TRUTH table. For further details refer to Events.

Writing a '1' to the LUT Control Event Input Enable bit (LUTCTRL.LUTEI) enables the corresponding action on input event. Writing a '0' to this bit disables the corresponding action on input event.

#### Analog-to-Digital Converter (ADC) Characteristics

#### 38.6.2.6 ADC Resolution

The ADC supports 8-bit, 10-bit or 12-bit resolution. Resolution can be changed by writing the Resolution bit group in the Control C register (CTRLC.RESSEL). By default, the ADC resolution is set to 12 bits. The resolution affects the propagation delay, see also Conversion Timing and Sampling Rate.

#### 38.6.2.7 Differential and Single-Ended Conversions

The ADC has two conversion options: differential and single-ended:

If the positive input is always positive, the single-ended conversion should be used in order to have full 12-bit resolution in the conversion.

If the positive input may go below the negative input, the differential mode should be used in order to get correct results.

The differential mode is enabled by setting DIFFMODE bit in the Control C register (CTRLC.DIFFMODE). Both conversion types could be run in single mode or in free-running mode. When the free-running mode is selected, an ADC input will continuously sample the input and performs a new conversion. The INTFLAG.RESRDY bit will be set at the end of each conversion.

#### 38.6.2.8 Conversion Timing and Sampling Rate

The following figure shows the ADC timing for one single conversion. A conversion starts after the software or event start are synchronized with the GCLK\_ADCx clock. The input channel is sampled in the first half CLK\_ADCx period.

#### Figure 38-3. ADC Timing for One Conversion in 12-bit Resolution



The sampling time can be increased by using the Sampling Time Length bit group in the Sampling Time Control register (SAMPCTRL.SAMPLEN). As example, the next figure is showing the timing conversion with sampling time increased to six CLK\_ADC cycles.

#### Figure 38-4. ADC Timing for One Conversion with Increased Sampling Time, 12-bit



The ADC provides also offset compensation, see the following figure. The offset compensation is enabled by the Offset Compensation bit in the Sampling Control register (SAMPCTRL.OFFCOMP).

Note: If offset compensation is used, the sampling time must be set to one cycle of CLK\_ADCx.

In free running mode, the sampling rate R<sub>S</sub> is calculated by

 $R_{S} = f_{CLK\_ADC} / (n_{SAMPLING} + n_{OFFCOMP} + n_{DATA})$ 

Here,  $n_{SAMPLING}$  is the sampling duration in CLK\_ADC cycles,  $n_{OFFCOMP}$  is the offset compensation duration in clock cycles, and  $n_{DATA}$  is the bit resolution.  $f_{CLK\_ADC}$  is the ADC clock frequency from the internal prescaler:  $f_{CLK\_ADC} = f_{GCLK\_ADC} / 2^{(1 + CTRLB.PRESCALER)}$ 

# 41.8.10 Synchronization Busy



# Bit 3 – DATABUF: Data Buffer DAC0

This bit is set when DATABUF register is written.

This bit is cleared when DATABUF synchronization is completed.

Value	Description
0	No ongoing synchronized access.
1	Synchronized access is ongoing.

# Bit 2 – DATA: Data

This bit is set when DATA register is written.

This bit is cleared when DATA synchronization is completed.

Value	Description
0	No ongoing synchronized access.
1	Synchronized access is ongoing.

# Bit 1 – ENABLE: DAC Enable Status

This bit is set when CTRLA.ENABLE bit is written.

This bit is cleared when CTRLA.ENABLE synchronization is completed.



#### Bit 1 – OVF: Sticky Count Value Overflow

This bit is cleared by writing a '1' to it.

This bit is set when an overflow condition occurs to the value counter.

Writing a '0' to this bit has no effect.

Writing a '1' to this bit will clear the OVF status.

#### Bit 0 – BUSY: FREQM Status

Value	Description
0	No ongoing frequency measurement.
1	Frequency measurement is ongoing.

#### 44.8.8 Synchronization Busy

Name:	SYNCBUSY
Offset:	0x0C [ID-00000e03]
Reset:	0x00000000
Property	:-

Bit	31	30	29	28	27	26	25	24
Access								
Reset								
Bit	23	22	21	20	19	18	17	16
Access								
Reset								
Bit	15	14	13	12	11	10	9	8
Access								
Reset								
Bit	7	6	5	4	3	2	1	0
							ENABLE	SWRST
Access							R	R
Reset							0	0

# Bit 1 – ENABLE: Enable

This bit is cleared when the synchronization of CTRLA.ENABLE is complete.

This bit is set when the synchronization of CTRLA.ENABLE is started.

# $C_{LEXT}=2$ ( $C_{L}-C_{STRAY}-C_{SHUNT}$ )

where  ${\tt C}_{\tt STRAY}$  is the capacitance of the pins and PCB and <code>CSHUNT</code> is the shunt capacitance of the <code>crystal</code>.

Symbol	Parameter	Conditions	Min.	Тур.	Мах	Units
f <sub>OUT</sub> <sup>(1)</sup>	Crystal oscillator frequency		-	32768	-	Hz
C <sub>L</sub> <sup>(1)</sup>	Crystal load capacitance		-	-	12.5	pF
C <sub>SHUNT</sub> <sup>(1)</sup>	Crystal shunt capacitance		-	-	1.75	
Cm <sup>(1)</sup>	Motional capacitance		-	1.25	-	fF
ESR	Crystal Equivalent Series Resistance - SF = 3	F = 32.768kHz, C <sub>L</sub> =12.5 pF	-	-	79	kΩ
Cxin32k	Parasitic capacitor load		-	2.9	-	pF
Cxout32k			-	3.2	-	
Tstart	Startup time	F = 32.768kHz, C <sub>L</sub> =12.5 pF	-	16	24	Kcycles

# Table 45-43. 32kHz Crystal Oscillator Characteristics

# 1. These are based on simulation. These values are not covered by test or characterization

# Table 45-44. Power Consumption<sup>(1)</sup>

Symbol	Parameters	Conditions	Та	Тур.	Max	Units
I <sub>DD</sub>	Current consumption	VDD = 5.0V	Max 85°C	1528	1720	nA
			Typ 25°C			

1. These are based on characterization.

# 45.12.3 Digital Phase Locked Loop (DPLL) Characteristics

# Table 45-45. Fractional Digital Phase Locked Loop Characteristics

Symbol	Parameter	Conditions	Min.	Тур.	Max.	Units
f <sub>IN</sub> <sup>(1)</sup>	Input frequency		32		2000	KHz
f <sub>OUT</sub> <sup>(1)</sup>	Output frequency		48		96	MHz
Jp <sup>(2)</sup>	Period jitter	f <sub>IN</sub> = 32 kHz, f <sub>OUT</sub> = 48 MHz	-	1.5	3.0	%
	(Peak-Peak value)	f <sub>IN</sub> = 32 kHz, f <sub>OUT</sub> = 96 MHz	-	2.7	8.0	
		f <sub>IN</sub> = 2 MHz, f <sub>OUT</sub> = 48 MHz	-	1.8	4.0	
		f <sub>IN</sub> = 2 MHz, f <sub>OUT</sub> = 96 MHz	-	2.5	6.0	
$t_{LOCK}^{(2)}$	Lock Time	After startup, time to get lock signal.	-	1.1	1.5	ms
		f <sub>IN</sub> = 32 kHz,				
		f <sub>OUT</sub> = 96 MHz				
		After startup, time to get lock signal.	-	25	35	μs

# 49.7.4 Calculating the Correct Crystal Decoupling Capacitor

The model shown in Figure 49-10 can be used to calculate correct load capacitor for a given crystal. This model includes internal capacitors  $C_{Ln}$ , external parasitic capacitance  $C_{ELn}$  and external load capacitance  $C_{Pn}$ .





Using this model the total capacitive load for the crystal can be calculated as shown in the equation below:

$$\sum C_{\text{tot}} = \frac{(C_{L1} + C_{P1} + C_{\text{EL1}})(C_{L2} + C_{P2} + C_{\text{EL2}})}{C_{L1} + C_{P1} + C_{\text{EL1}} + C_{L2} + C_{P2} + C_{\text{EL2}}}$$

where C<sub>tot</sub> is the total load capacitance seen by the crystal. This value should be equal to the load capacitance value found in the crystal manufacturer datasheet.

The parasitic capacitance  $C_{ELn}$  can in most applications be disregarded as these are usually very small. If accounted for, these values are dependent on the PCB material and PCB layout.

For some crystal the internal capacitive load provided by the device itself can be enough. To calculate the total load capacitance in this case.  $C_{ELn}$  and  $C_{Pn}$  are both zero,  $C_{L1} = C_{L2} = C_L$ , and the equation reduces to the following:

$$\sum C_{\rm tot} = \frac{C_L}{2}$$

See the related links for equivalent internal pin capacitance values.

# **Related Links**

**Crystal Oscillator Characteristics** 

# 49.8 **Programming and Debug Ports**

For programming and/or debugging the SAM C20/C21 the device should be connected using the Serial Wire Debug (SWD) interface. Currently the SWD interface is supported by several Microchip and third party programmers and debuggers, like the SAM-ICE, JTAGICE3 or SAM C21 Xplained Pro (SAM C21 evaluation kit) Embedded Debugger.