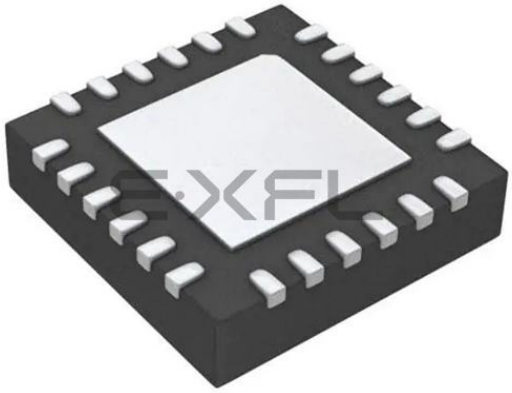

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"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Obsolete
Core Processor	CIP-51 8051
Core Size	8-Bit
Speed	48MHz
Connectivity	I²C, SMBus, SPI, UART/USART, USB
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	17
Program Memory Size	40KB (40K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	3.25K x 8
Voltage - Supply (Vcc/Vdd)	1.71V ~ 5.5V
Data Converters	A/D 16x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	24-WFQFN Exposed Pad
Supplier Device Package	24-QFN (4x4)
Purchase URL	https://www.e-xfl.com/product-detail/silicon-labs/efm8ub31f40g-a-qfn24r

3.2 Power

Control over the device power consumption can be achieved by enabling/disabling individual peripherals as needed. Each analog peripheral can be disabled when not in use and placed in low power mode. Digital peripherals, such as timers and serial buses, have their clocks gated off and draw little power when they are not in use.

Table 3.1. Power Modes

Power Mode	Details	Mode Entry	Wake-Up Sources
Normal	Core and all peripherals clocked and fully operational	—	—
Idle	• Core halted • All peripherals clocked and fully operational • Code resumes execution on wake event	Set IDLE bit in PCON0	Any interrupt
Suspend	• Core and peripheral clocks halted • HFOSC0 and HFOSC1 oscillators stopped • Regulators in normal bias mode for fast wake • Timer 3 and 4 may clock from LFOSC0 • Code resumes execution on wake event	1. Switch SYSCLK to HFOSC0 2. Set SUSPEND bit in PCON1	• USB0 Bus Activity • Timer 4 Event • SPI0 Activity • Port Match Event • Comparator 0 Falling Edge • CLUn Interrupt-Enabled Event
Stop	• All internal power nets shut down • 5V regulator remains active (if enabled) • Internal 1.8 V LDO on • Pins retain state • Exit on any reset source	1. Clear STOPCF bit in REG0CN 2. Set STOP bit in PCON0	Any reset source
Snooze	• Core and peripheral clocks halted • HFOSC0 and HFOSC1 oscillators stopped • Regulators in low bias current mode for energy savings • Timer 3 and 4 may clock from LFOSC0 • Code resumes execution on wake event	1. Switch SYSCLK to HFOSC0 2. Set SNOOZE bit in PCON1	• USB0 Bus Activity • Timer 4 Event • SPI0 Activity • Port Match Event • Comparator 0 Falling Edge • CLUn Interrupt-Enabled Event
Shutdown	• All internal power nets shut down • 5V regulator remains active (if enabled) • Internal 1.8 V LDO off to save energy • Pins retain state • Exit on pin or power-on reset	1. Set STOPCF bit in REG0CN 2. Set STOP bit in PCON0	• RSTb pin reset • Power-on reset

3.3 I/O

Digital and analog resources are externally available on the device's multi-purpose I/O pins. Port pins P0.0-P1.6 can be defined as general-purpose I/O (GPIO), assigned to one of the internal digital resources through the crossbar or dedicated channels, or assigned to an analog function. Port pins P2.0 and P2.1 can be used as GPIO. Additionally, the C2 Interface Data signal (C2D) is shared with P2.0.

The port control block offers the following features:

- Up to 17 multi-functions I/O pins, supporting digital and analog functions.
- Flexible priority crossbar decoder for digital peripheral assignment.
- Two drive strength settings for each port.
- Two direct-pin interrupt sources with dedicated interrupt vectors (INT0 and INT1).
- Up to 17 direct-pin interrupt sources with shared interrupt vector (Port Match).

3.6 Communications and Other Digital Peripherals

Universal Serial Bus (USB0)

The USB0 peripheral provides a full-speed USB 2.0 compliant device controller and PHY with additional Low Energy USB features. The device supports both full-speed (12MBit/s) and low speed (1.5MBit/s) operation, and includes a dedicated USB oscillator with clock recovery mechanism for crystal-free operation. No external components are required. The USB function controller (USB0) consists of a Serial Interface Engine (SIE), USB transceiver (including matching resistors and configurable pull-up resistors), and 1 KB FIFO block. The Low Energy Mode ensures the current consumption is optimized and enables USB communication on a strict power budget.

The USB0 module includes the following features:

- Full and Low Speed functionality.
- Implements 4 bidirectional endpoints.
- Low Energy Mode to reduce active supply current based on bus bandwidth.
- USB 2.0 compliant USB peripheral support (no host capability).
- Direct module access to 1 KB of RAM for FIFO memory.
- Clock recovery to meet USB clocking requirements with no external components.
- Charger detection circuitry with automatic detection of SDP, CDP, and DCP interfaces.
- D+ and D- can be routed to ADC input to support ACM and proprietary charger architectures.

Universal Asynchronous Receiver/Transmitter (UART1)

UART1 is an asynchronous, full duplex serial port offering a variety of data formatting options. A dedicated baud rate generator with a 16-bit timer and selectable prescaler is included, which can generate a wide range of baud rates. A received data FIFO allows UART1 to receive multiple bytes before data is lost and an overflow occurs.

UART1 provides the following features:

- Asynchronous transmissions and receptions.
- Dedicated baud rate generator supports baud rates up to SYSCLK/2 (transmit) or SYSCLK/8 (receive).
- 5, 6, 7, 8, or 9 bit data.
- Automatic start and stop generation.
- Automatic parity generation and checking.
- Four byte FIFO on transmit and receive.
- Auto-baud detection.
- LIN break and sync field detection.
- CTS / RTS hardware flow control.

Serial Peripheral Interface (SPI0)

The serial peripheral interface (SPI) module provides access to a flexible, full-duplex synchronous serial bus. The SPI can operate as a master or slave device in both 3-wire or 4-wire modes, and supports multiple masters and slaves on a single SPI bus. The slave-select (NSS) signal can be configured as an input to select the SPI in slave mode, or to disable master mode operation in a multi-master environment, avoiding contention on the SPI bus when more than one master attempts simultaneous data transfers. NSS can also be configured as a firmware-controlled chip-select output in master mode, or disabled to reduce the number of pins required. Additional general purpose port I/O pins can be used to select multiple slave devices in master mode.

- Supports 3- or 4-wire master or slave modes.
- Supports external clock frequencies up to 12 Mbps in master or slave mode.
- Support for all clock phase and polarity modes.
- 8-bit programmable clock rate (master).
- Programmable receive timeout (slave).
- Two byte FIFO on transmit and receive.
- Can operate in suspend or snooze modes and wake the CPU on reception of a byte.
- Support for multiple masters on the same data lines.

System Management Bus / I2C (SMB0)

The SMBus I/O interface is a two-wire, bi-directional serial bus. The SMBus is compliant with the System Management Bus Specification, version 1.1, and compatible with the I^2C serial bus.

The SMBus module includes the following features:

- Standard (up to 100 kbps), Fast (400 kbps), and Fast Mode Plus (1 Mbps) transfer speeds
- Support for master, slave, and multi-master modes
- Hardware synchronization and arbitration for multi-master mode
- Clock low extending (clock stretching) to interface with faster masters
- Hardware support for 7-bit slave and general call address recognition
- Firmware support for 10-bit slave address decoding
- Ability to inhibit all slave states
- Programmable data setup/hold times
- Transmit and receive FIFOs (two-byte) to help increase throughput in faster applications

16-bit CRC (CRC0)

The cyclic redundancy check (CRC) module performs a CRC using a 16-bit polynomial. CRC0 accepts a stream of 8-bit data and posts the 16-bit result to an internal register. In addition to using the CRC block for data manipulation, hardware can automatically CRC the flash contents of the device.

The CRC module is designed to provide hardware calculations for flash memory verification and communications protocols. The CRC module supports the standard CCITT-16 16-bit polynomial (0x1021), and includes the following features:

- Support for CCITT-16 polynomial
- Byte-level bit reversal
- Automatic CRC of flash contents on one or more 256-byte blocks
- Initial seed selection of 0x0000 or 0xFFFF

Configurable Logic Units (CLU0, CLU1, CLU2, and CLU3)

The Configurable Logic block consists of multiple Configurable Logic Units (CLUs). CLUs are flexible logic functions which may be used for a variety of digital functions, such as replacing system glue logic, aiding in the generation of special waveforms, or synchronizing system event triggers.

- Four configurable logic units (CLUs), with direct-pin and internal logic connections
- Each unit supports 256 different combinatorial logic functions (AND, OR, XOR, muxing, etc.) and includes a clocked flip-flop for synchronous operations
- Units may be operated synchronously or asynchronously
- May be cascaded together to perform more complicated logic functions
- Can operate in conjunction with serial peripherals such as UART and SPI or timing peripherals such as timers and PCA channels
- Can be used to synchronize and trigger multiple on-chip resources (ADC, Timers, etc.)
- Asynchronous output may be used to wake from low-power states

4.1.4 Flash Memory

Table 4.4. Flash Memory

Parameter	Symbol	Test Condition	Min	Typ	Max	Units
Write Time[1, 2]	t_{WRITE}	One Byte, F_{SYSCLK} = 24.5 MHz	19	20	21	µs
Erase Time[1, 2]	t_{ERASE}	One Page, F_{SYSCLK} = 24.5 MHz	5.2	5.35	5.5	ms
V_{DD} Voltage During Programming [3]	V_{PROG}	5 V Voltage Regulator used	2.7	—	5.5	V
		5 V Voltage Regulator bypassed	2.3	—	3.6	V
Endurance (Write/Erase Cycles)	N_{WE}		20k	100k	—	Cycles
CRC Calculation Time	t_{CRC}	One 256-Byte Block SYSCLK = 48 MHz	—	5.5	—	µs

Note:

1. Does not include sequencing time before and after the write/erase operation, which may be multiple SYSCLK cycles.
2. The internal High-Frequency Oscillator 0 has a programmable output frequency, which is factory programmed to 24.5 MHz. If user firmware adjusts the oscillator speed, it must be between 22 and 25 MHz during any flash write or erase operation. It is recommended to write the HFO0CAL register back to its reset value when writing or erasing flash.
3. Flash can be safely programmed at any voltage above the supply monitor threshold (V_{VDDM}).
4. Data Retention Information is published in the Quarterly Quality and Reliability Report.

4.1.5 Power Management Timing

Table 4.5. Power Management Timing

Parameter	Symbol	Test Condition	Min	Typ	Max	Units
Idle Mode Wake-up Time	t_{IDLEWK}		2	—	3	SYSCLKs
Suspend Mode Wake-up Time	$t_{SUSPENDWK}$	SYSCLK = HFOSC0 CLKDIV = 0x00	—	170	—	ns
Snooze Mode Wake-up Time	$t_{SLEEPWK}$	SYSCLK = HFOSC0 CLKDIV = 0x00	—	12	—	µs

4.1.6 Internal Oscillators

Table 4.6. Internal Oscillators

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
High Frequency Oscillator 0 (24.5 MHz)						
Oscillator Frequency	f_{HFOSC0}	Full Temperature and Supply Range	24	24.5	25	MHz
Power Supply Sensitivity	PSS_{HFOSC0}	T_A = 25 °C	—	0.5	—	%/V
Temperature Sensitivity	TS_{HFOSC0}	V_{DD} = 3.0 V	—	40	—	ppm/°C
High Frequency Oscillator 1 (48 MHz)						
Oscillator Frequency	f_{HFOSC1}	Full Temperature and Supply Range	47.3	48	48.7	MHz
Power Supply Sensitivity	PSS_{HFOSC1}	T_A = 25 °C	—	0.02	—	%/V
Temperature Sensitivity	TS_{HFOSC1}	V_{DD} = 3.0 V	—	45	—	ppm/°C
Low Frequency Oscillator (80 kHz)						
Oscillator Frequency	f_{LFOSC}	Full Temperature and Supply Range	75	80	85	kHz
Power Supply Sensitivity	PSS_{LFOSC}	T_A = 25 °C	—	0.05	—	%/V
Temperature Sensitivity	TS_{LFOSC}	V_{DD} = 3.0 V	—	65	—	ppm/°C

4.1.7 External Clock Input

Table 4.7. External Clock Input

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
External Input CMOS Clock Frequency (at EXTCLK pin)	f_{CMOS}		0	—	48	MHz
External Input CMOS Clock High Time	t_{CMOSH}		9	—	—	ns
External Input CMOS Clock Low Time	t_{CMOSL}		9	—	—	ns

4.1.8 ADC

Table 4.8. ADC

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Resolution	N_{bits}	12 Bit Mode		12		Bits
		10 Bit Mode		10		Bits
Throughput Rate (High Speed Mode)	f_S	12 Bit Mode	—	—	200	ksps
		10 Bit Mode	—	—	800	ksps
Throughput Rate (Low Power Mode)	f_S	12 Bit Mode	—	—	62.5	ksps
		10 Bit Mode	—	—	250	ksps
Tracking Time	t_{TRK}	High Speed Mode	230	—	—	ns
		Low Power Mode	450	—	—	ns
Power-On Time	t_{PWR}		1.2	—	—	µs
SAR Clock Frequency	f_{SAR}	High Speed Mode, Reference is 2.4 V internal	—	—	6.25	MHz
		High Speed Mode, Reference is not 2.4 V internal	—	—	12.5	MHz
		Low Power Mode	—	—	4	MHz
Conversion Time	t_{CNV}	10-Bit Conversion, SAR Clock = 12.25 MHz, System Clock = 24.5 MHz.		1.1		µs
Sample/Hold Capacitor	C_{SAR}	Gain = 1	—	5	—	pF
		Gain = 0.5	—	2.5	—	pF
Input Pin Capacitance	C_{IN}		—	20	—	pF
Input Mux Impedance	R_{MUX}		—	550	—	Ω
Voltage Reference Range	V_{REF}		1	—	V_{DD}	V
Input Voltage Range [1]	V_{IN}	Gain = 1	0	—	V_{REF}	V
		Gain = 0.5	0	—	$2xV_{REF}$	V
Power Supply Rejection Ratio	$PSRR_{ADC}$		—	70	—	dB
DC Performance						
Integral Nonlinearity	INL	12 Bit Mode	—	±1	±2.3	LSB
		10 Bit Mode	—	±0.2	±0.6	LSB
Differential Nonlinearity (Guaranteed Monotonic)	DNL	12 Bit Mode	-1	±0.7	1.9	LSB
		10 Bit Mode	—	±0.2	±0.6	LSB
Offset Error	E_{OFF}	12 Bit Mode, VREF = 1.65 V	-3	0	3	LSB
		10 Bit Mode, VREF = 1.65 V	-2	0	2	LSB
Offset Temperature Coefficient	TC_{OFF}		—	0.004	—	LSB/°C

4.1.10 Temperature Sensor

Table 4.10. Temperature Sensor

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Offset	V_{OFF}	T_A = 0 °C	—	757	—	mV
Offset Error [1]	E_{OFF}	T_A = 0 °C	—	17	—	mV
Slope	M		—	2.85	—	mV/°C
Slope Error [1]	E_M		—	70	—	µV/°
Linearity			—	0.5	—	°C
Turn-on Time			—	1.8	—	µs

Note:
1. Represents one standard deviation from the mean.

4.1.11 5 V Voltage Regulator

Table 4.11. 5V Voltage Regulator

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Input Voltage Range [1]	V_{REGIN}	USB in use	3.7	—	5.5	V
		USB not in use	3.0	—	5.5	V
Output Voltage on VDD [2]	V_{REGOUT}	Regulation range (VREGIN ≥ 4.1V)	3.1	3.4	3.6	V
		Dropout range (VREGIN < 4.1V)	—	V_{REGIN} – $V_{DROPOUT}$	—	V
Output Current [2]	I_{REGOUT}		—	—	100	mA
Dropout Voltage	$V_{DROPOUT}$	Output Current = 100 mA	—	—	0.7	V

Note:
1. Input range to meet the Output Voltage on VDD specification. If the 5 V voltage regulator is not used, VREGIN should be tied to VDD.
2. Output current is total regulator output, including any current required by the device.

4.1.12 1.8 V Internal LDO Voltage Regulator

Table 4.12. 1.8V Internal LDO Voltage Regulator

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Output Voltage	$V_{OUT\_1.8V}$		1.77	1.84	1.92	V

4.1.13 Comparators

Table 4.13. Comparators

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Response Time, CPMD = 00 (Highest Speed)	t_{RESP0}	+100 mV Differential, V_{CM} = 1.65 V	—	250	—	ns
		-100 mV Differential, V_{CM} = 1.65 V	—	213	—	ns
Response Time, CPMD = 11 (Lowest Power)	t_{RESP3}	+100 mV Differential, V_{CM} = 1.65 V	—	1.06	—	µs
		-100 mV Differential, V_{CM} = 1.65 V	—	3.4	—	µs
Positive Hysteresis Mode 0 (CPMD = 00)	HYS_{CP+}	CPHYP = 00	—	0.3	—	mV
		CPHYP = 01	—	8.55	—	mV
		CPHYP = 10	—	17.1	—	mV
		CPHYP = 11	—	33.6	—	mV
Negative Hysteresis Mode 0 (CPMD = 00)	HYS_{CP-}	CPHYN = 00	—	-0.3	—	mV
		CPHYN = 01	—	-8.55	—	mV
		CPHYN = 10	—	-17.1	—	mV
		CPHYN = 11	—	-34.2	—	mV
Positive Hysteresis Mode 3 (CPMD = 11)	HYS_{CP+}	CPHYP = 00	—	1.2	—	mV
		CPHYP = 01	—	4.9	—	mV
		CPHYP = 10	—	10.4	—	mV
		CPHYP = 11	—	20.8	—	mV
Negative Hysteresis Mode 3 (CPMD = 11)	HYS_{CP-}	CPHYN = 00	—	-1.2	—	mV
		CPHYN = 01	—	-4.9	—	mV
		CPHYN = 10	—	-10	—	mV
		CPHYN = 11	—	-20.8	—	mV
Input Range (CP+ or CP-)	V_{IN}	Direct comparator input	-0.25	—	V_{DD}+0.25	V
		Reference DAC input	1.2		V_{DD}	V
Reference DAC Resolution	N_{bits}			6		bits
Reference DAC Input Impedance	R_{CPREF}		—	2.75	—	MΩ
Input Pin Capacitance	C_{CP}		—	7.5	—	pF
Common-Mode Rejection Ratio	$CMRR_{CP}$		—	68.5	—	dB
Power Supply Rejection Ratio	$PSRR_{CP}$		—	65	—	dB
Input Offset Voltage	V_{OFF}	T_A = 25 °C	-11	-1.8	10	mV
Input Offset Tempco	TC_{OFF}		—	3.5	—	µV/°

4.1.14 Configurable Logic

Table 4.14. Configurable Logic

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Propagation Delay through LUT	t_{DLY_LUT}	Through single CLU Using an external pin	—	—	38.7	ns
		Through single CLU Using an internal connection	—	1.6	5.0	ns
Propagation Delay through D flip-flop clock	t_{DLY_DFF}	Through single CLU Using an external pin	—	—	38.7	ns
		Through single CLU Using an internal connection	—	1.4	5.6	ns
Clocking Frequency	F_{CLK}	1 or 2 CLUs Cascaded	—	—	48	MHz
		3 or 4 CLUs Cascaded	—	—	48	MHz

Table 4.18. SMBus Peripheral Timing Formulas (Master Mode)

Parameter	Symbol	Clocks
SMBus Operating Frequency	f_{SMB}	f_{CSO} / 3
Bus Free Time Between STOP and START Conditions	t_{BUF}	2 / f_{CSO}
Hold Time After (Repeated) START Condition	$t_{HD:STA}$	1 / f_{CSO}
Repeated START Condition Setup Time	$t_{SU:STA}$	2 / f_{CSO}
STOP Condition Setup Time	$t_{SU:STO}$	2 / f_{CSO}
Clock Low Period	t_{LOW}	1 / f_{CSO}
Clock High Period	t_{HIGH}	2 / f_{CSO}

Note:
1. f_{CSO} is the SMBus peripheral clock source overflow frequency.

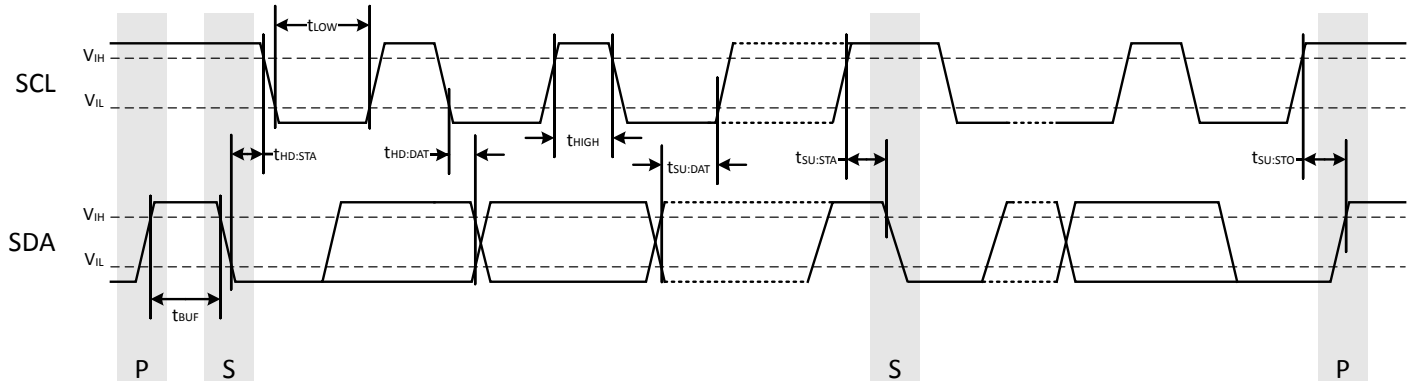

Figure 4.1. SMBus Peripheral Timing Diagram (Master Mode)

4.2 Thermal Conditions

Table 4.19. Thermal Conditions

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Thermal Resistance	θ_{JA}	QFN20 Packages	—	60	—	°C/W
		QFN24 Packages	—	30	—	°C/W
		QSOP24 Packages	—	65	—	°C/W
		QFN32 Packages	—	26	—	°C/W

Note:
1. Thermal resistance assumes a multi-layer PCB with any exposed pad soldered to a PCB pad.

The figure below shows a typical connection diagram for the power pins of the EFM8UB3 devices when the internal regulator used and USB is connected (self-powered).

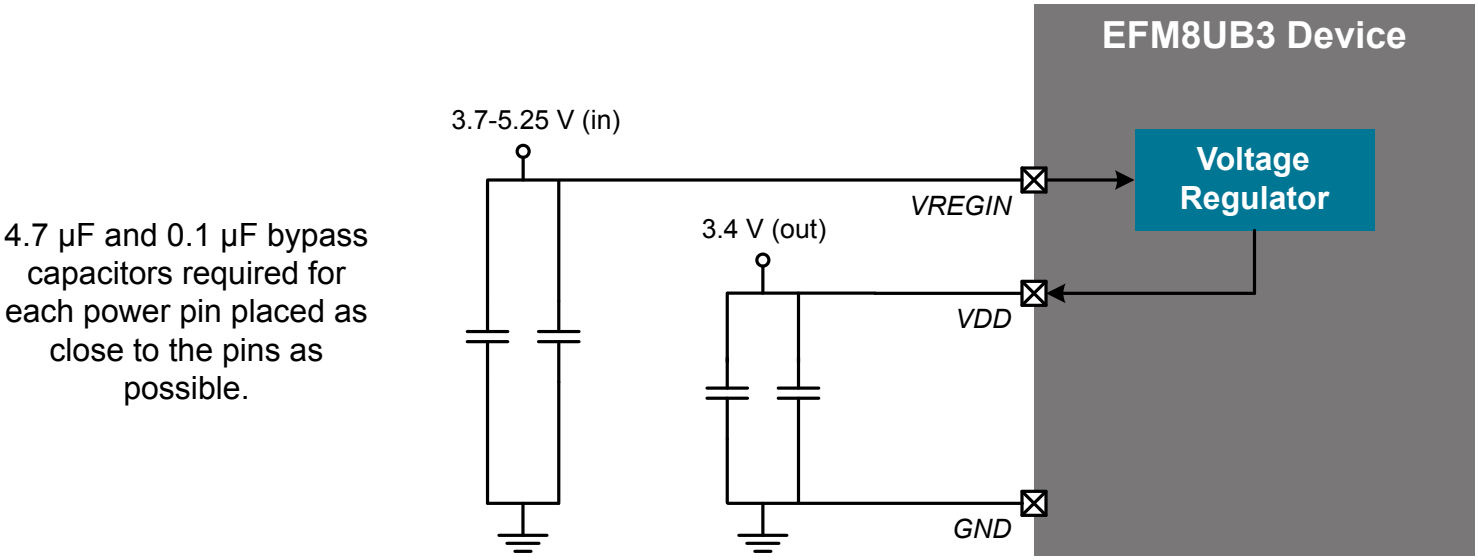

Figure 5.2. Connection Diagram with Voltage Regulator Used and USB Connected (Self-Powered)

The figure below shows a typical connection diagram for the power pins of the EFM8UB3 devices when the internal 5 V-to-3.3 V regulator is not used.

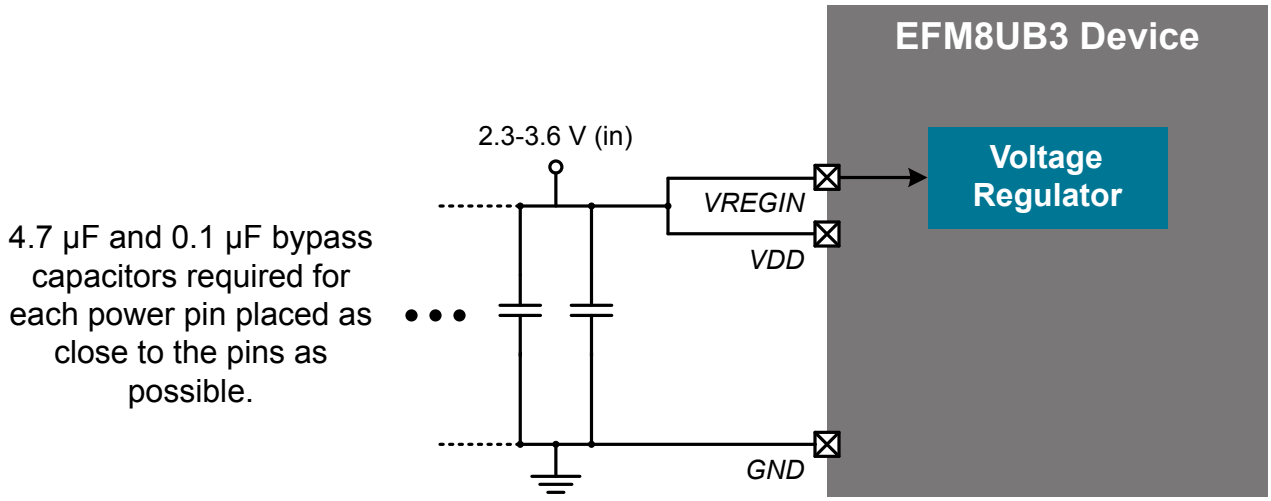

Figure 5.3. Connection Diagram with Voltage Regulator Not Used (Self-Powered)

6. Pin Definitions

6.1 EFM8UB3x-QSOP24 Pin Definitions

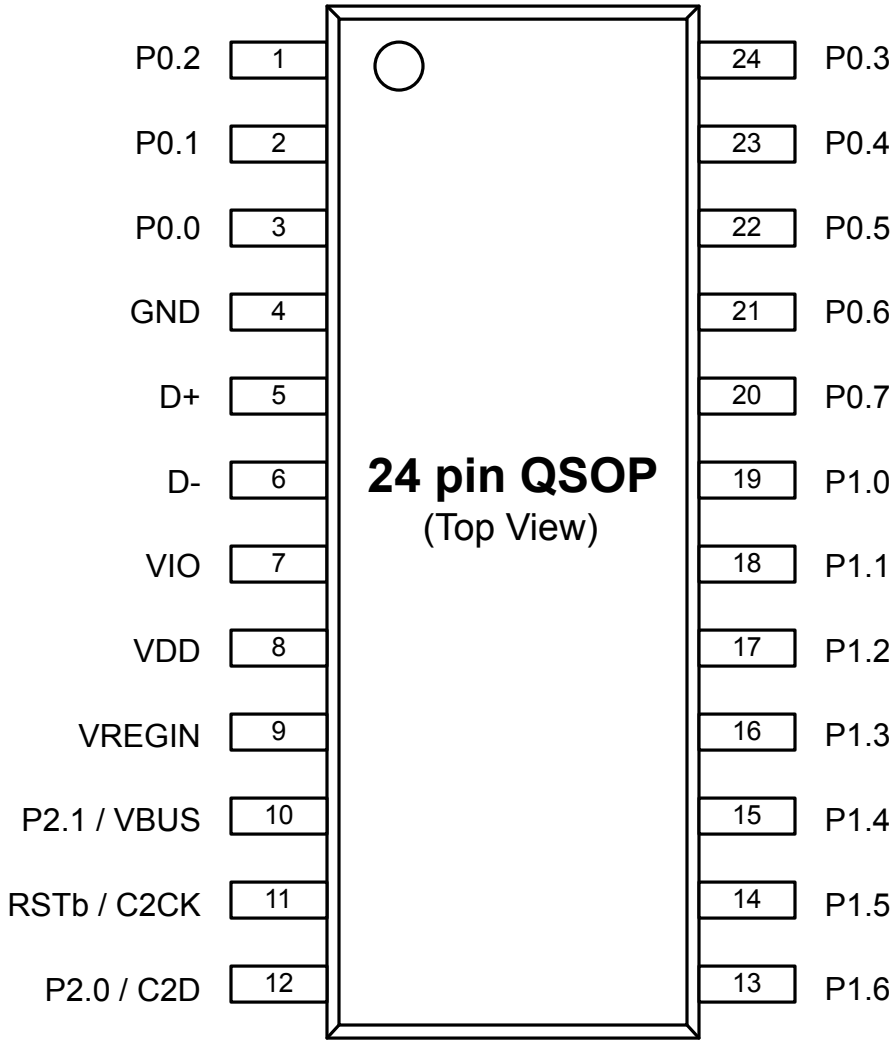

Figure 6.1. EFM8UB3x-QSOP24 Pinout

Pin Number	Pin Name	Description	Crossbar Capability	Additional Digital Functions	Analog Functions
12	P1.5	Multifunction I/O	Yes		ADC0.13 CMP1P.5 CMP1N.5
15	P1.4	Multifunction I/O	Yes	P1MAT.4	ADC0.12 CMP1P.4 CMP1N.4
16	P1.3	Multifunction I/O	Yes	P1MAT.3	ADC0.11 CMP1P.3 CMP1N.3
17	P1.2	Multifunction I/O	Yes	P1MAT.2	ADC0.10 CMP1P.2 CMP1N.2
18	P1.1	Multifunction I/O	Yes	P1MAT.1	ADC0.9 CMP1P.1 CMP1N.1
19	P1.0	Multifunction I/O	Yes	P1MAT.0 CLU0B.6 CLU2A.7 CLU3OUT	ADC0.8 CMP1P.0 CMP1N.0
20	P0.7	Multifunction I/O	Yes	P0MAT.7 INT0.7 INT1.7 CLU1A.7 CLU3A.6	ADC0.7 CMP0P.7 CMP0N.7
21	P0.6	Multifunction I/O	Yes	P0MAT.6 CNVSTR INT0.6 INT1.6 CLU1B.6 CLU2OUT	ADC0.6 CMP0P.6 CMP0N.6
22	P0.5	Multifunction I/O	Yes	P0MAT.5 INT0.5 INT1.5 UART1_RX CLU1B.7 CLU2A.6	ADC0.5 CMP0P.5 CMP0N.5

6.3 EFM8UB3x-QFN20

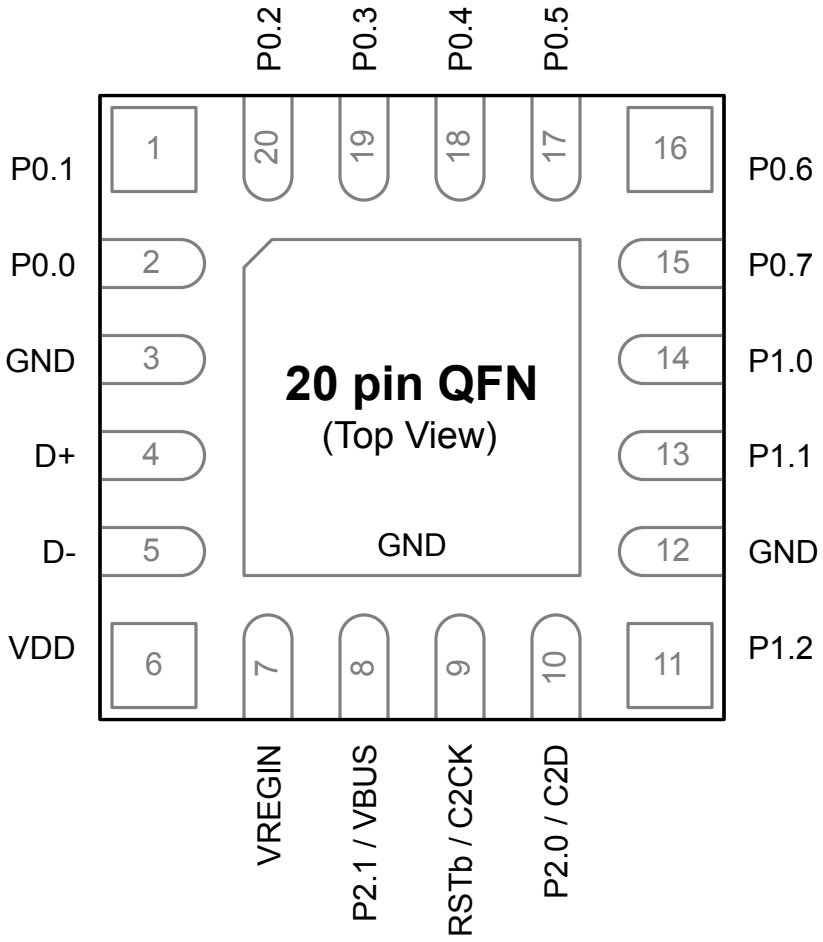

Figure 6.3. EFM8UB3x-QFN20 Pinout

Table 6.3. Pin Definitions for EFM8UB3x-QFN20

Pin Number	Pin Name	Description	Crossbar Capability	Additional Digital Functions	Analog Functions
1	P0.1	Multifunction I/O	Yes	P0MAT.1 INT0.1 INT1.1 CLU0A.6 CLU3A.7	ADC0.1 CMP0P.1 CMP0N.1 AGND

8. QSOP24 Package Specifications

8.1 Package Dimensions

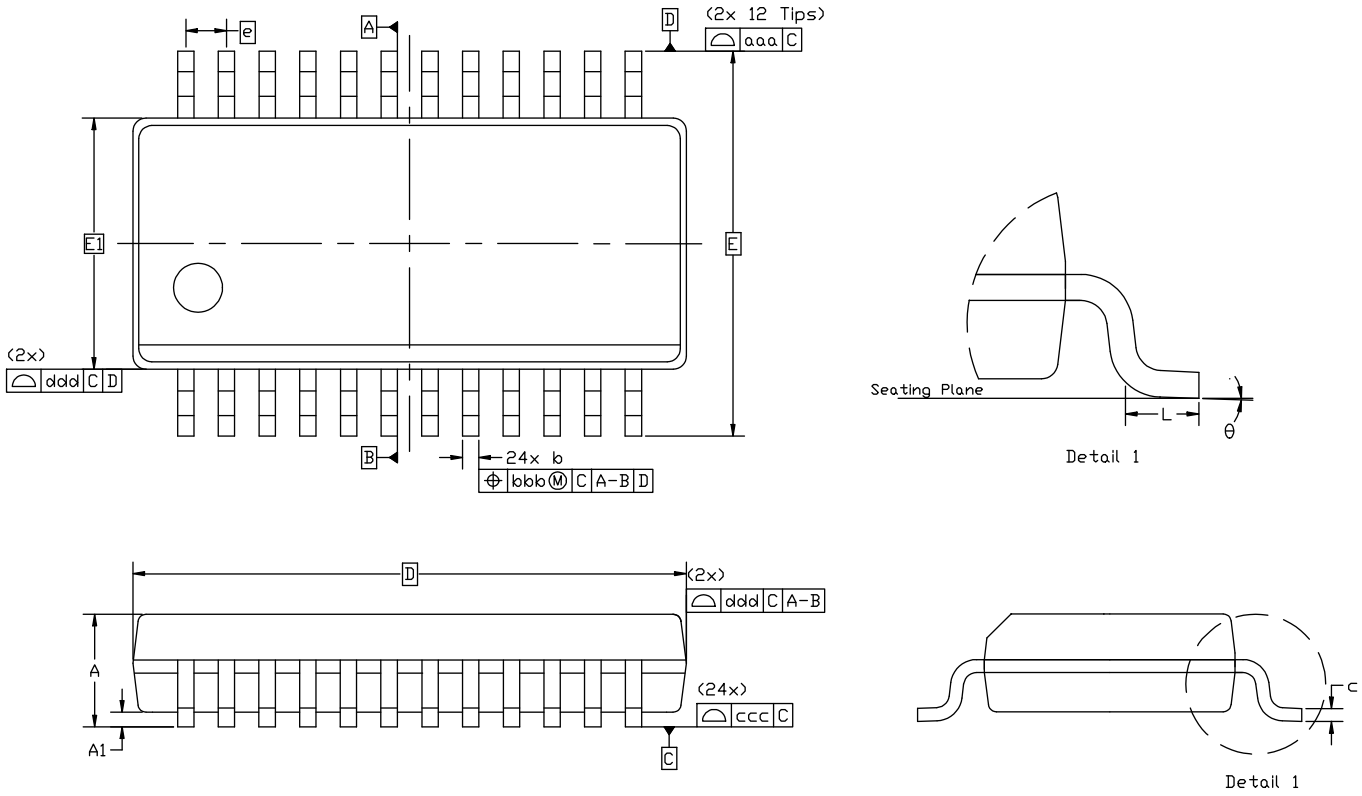

Figure 8.1. Package Drawing

Table 8.1. Package Dimensions

Dimension	Min	Typ	Max
A	—	—	1.75
A1	0.10	—	0.25
b	0.20	—	0.30
c	0.10	—	0.25
D	8.65 BSC		
E	6.00 BSC		
E1	3.90 BSC		
e	0.635 BSC		
L	0.40	—	1.27

Dimension	Min	Typ	Max
theta	0º	—	8º
aaa		0.20	
bbb		0.18	
ccc		0.10	
ddd		0.10	

Note:

1. All dimensions shown are in millimeters (mm) unless otherwise noted.
2. Dimensioning and Tolerancing per ANSI Y14.5M-1994.
3. This drawing conforms to JEDEC outline MO-137, variation AE.
4. Recommended card reflow profile is per the JEDEC/IPC J-STD-020 specification for Small Body Components.

9. QFN20 Package Specifications

9.1 QFN20 Package Dimensions

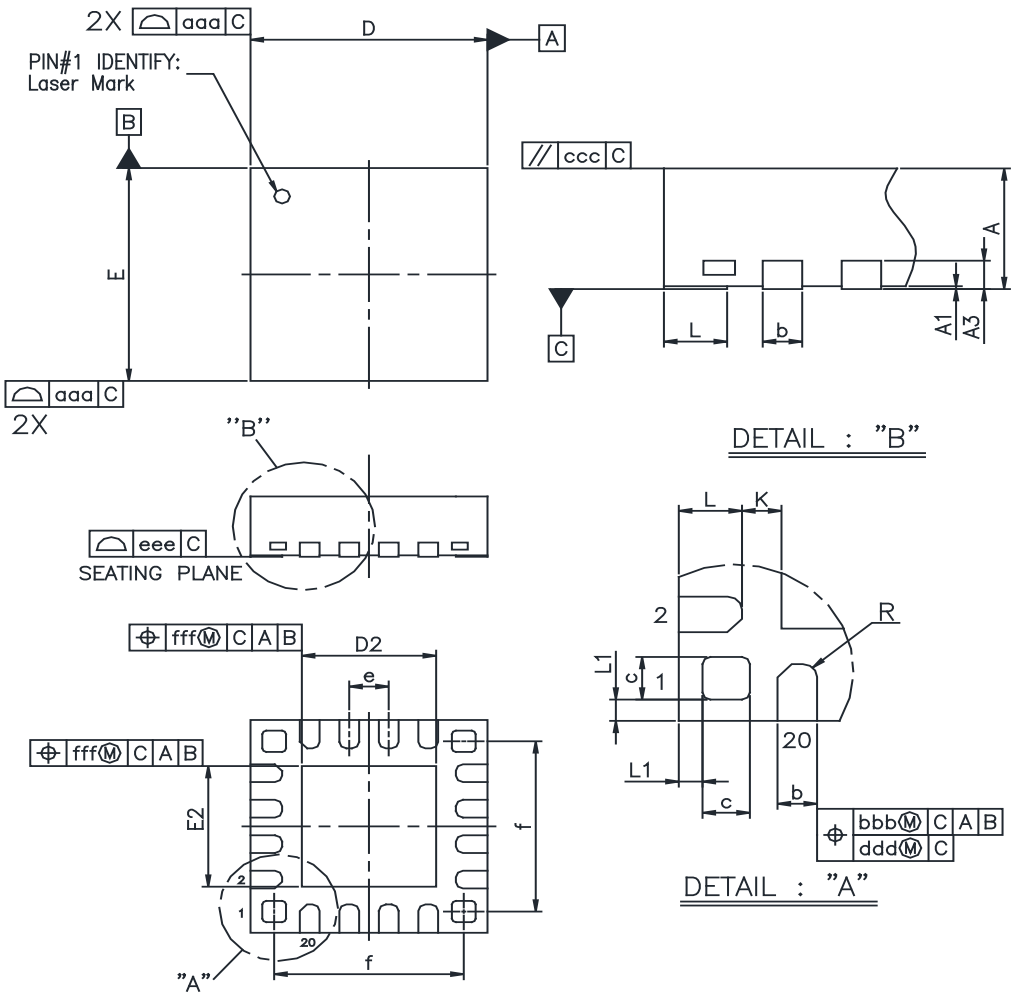

Figure 9.1. QFN20 Package Drawing

Table 9.1. QFN20 Package Dimensions

Dimension	Min	Typ	Max
A	0.70	0.75	0.80
A1	0.00	0.02	0.05
A3		0.20 REF	
b	0.18	0.25	0.30
c	0.25	0.30	0.35
D		3.00 BSC	
D2	1.6	1.70	1.80
e		0.50 BSC	
E		3.00 BSC	

Dimension	Min	Max

Note:

1. All dimensions shown are in millimeters (mm) unless otherwise noted.
2. Dimensioning and Tolerancing is per the ANSI Y14.5M-1994 specification.
3. This Land Pattern Design is based on the IPC-7351 guidelines.
4. All metal pads are to be non-solder mask defined (NSMD). Clearance between the solder mask and the metal pad is to be 60 µm minimum, all the way around the pad.
5. A stainless steel, laser-cut and electro-polished stencil with trapezoidal walls should be used to assure good solder paste release.
6. The stencil thickness should be 0.125 mm (5 mils).
7. The ratio of stencil aperture to land pad size should be 1:1 for the perimeter pads.
8. A 2 x 2 array of 0.75 mm openings on a 0.95 mm pitch should be used for the center pad to assure proper paste volume.
9. A No-Clean, Type-3 solder paste is recommended.
10. The recommended card reflow profile is per the JEDEC/IPC J-STD-020 specification for Small Body Components.

9.3 QFN20 Package Marking

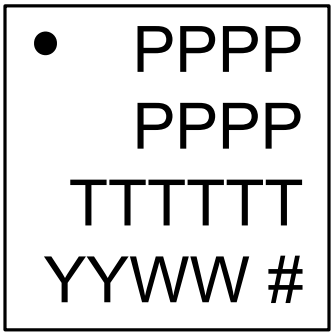

Figure 9.3. QFN20 Package Marking

The package marking consists of:

- PPPPPPPP – The part number designation.
- TTTTTT – A trace or manufacturing code.
- YY – The last 2 digits of the assembly year.
- WW – The 2-digit workweek when the device was assembled.
- # – The device revision (A, B, etc.).

10. Revision History

Revision 1.1

October 20th, 2017

- Updated the front page diagram to indicate USB and SPI are available in Snooze mode.
- Updated the front page and 1. Feature List to refer to two analog comparators.
- Corrected the number of I/O mentioned on the front page.
- Added "Pre-programmed USB Bootloader" to 1. Feature List.
- Updated I/O tolerance range to V_{IO} + 2.5 V in 1. Feature List.
- Updated 3.1 Introduction to mention all device documentation.
- Updated 3.2 Power to remove mention of the I2C Slave peripheral.
- Added bootloader pinout information to 3.10 Bootloader.
- Corrected the application note number for *AN124: Pin Sharing Techniques for the C2 Interface* in 5.3 Debug.
- Added a note to Table 4.2 Power Consumption on page 17 providing more information about the Comparator Reference specification.
- Added maximum specifications to 4.1.14 Configurable Logic Propagation Delay through LUT (internal connection) and Propagation Delay through D flip-flop clock (internal connection).
- Updated 4.1.15 Port I/O to refer to V_{IO} instead of V_{DD} for I/O specifications. Also added a note that V_{IO} = V_{DD} on devices without a VIO pin.
- Added specifications for 4.1.17 SMBus.
- Updated 4.3 Absolute Maximum Ratings to correct the GPIO pin associated with VBUS and update the maximum specfications to be relative to VIO, not VDD.
- Added a VIO specification to 4.3 Absolute Maximum Ratings.
- Updated text and figures in 5.1 Power to remove mention of the VBUS pin.
- Updated the title of Figure 5.3 Connection Diagram with Voltage Regulator Not Used (Self-Powered) on page 34 to include "Self-Powered".
- Updated to show a resistor divider on VBUS in Figure 5.5 Self-Powered Connection Diagram for USB Pins on page 36. Also added two notes regarding VBUS.
- Updated the revision history format.

Revision 1.0

July 20th, 2017

- Initial release.