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Understanding <u>Embedded - FPGAs (Field</u> <u>Programmable Gate Array)</u>

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details

Product Status	Active
Number of LABs/CLBs	-
Number of Logic Elements/Cells	-
Total RAM Bits	110592
Number of I/O	119
Number of Gates	600000
Voltage - Supply	1.425V ~ 1.575V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 85°C (TJ)
Package / Case	256-LBGA
Supplier Device Package	256-FPBGA (17x17)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/afs600-1fgg256

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Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

Flash Memory Block Diagram

A simplified diagram of the flash memory block is shown in Figure 2-33.





The logic consists of the following sub-blocks:

Flash Array

Contains all stored data. The flash array contains 64 sectors, and each sector contains 33 pages of data.

Page Buffer

A page-wide volatile register. A page contains 8 blocks of data and an AUX block.

- Block Buffer
 - Contains the contents of the last block accessed. A block contains 128 data bits.
- ECC Logic

The FB stores error correction information with each block to perform single-bit error correction and double-bit error detection on all data blocks.



Figure 2-72 • Positive Current Monitor

Care must be taken when choosing the right resistor for current measurement application. Note that because of the 10× amplification, the maximum measurable difference between the AV and AC pads is V_{AREF} / 10. A larger AV-to-AC voltage drop will result in ADC saturation; that is, the digital code put out by the ADC will stay fixed at the full scale value. Therefore, the user must select the external sense resistor appropriately. Table 2-38 shows recommended resistor values for different current measurement ranges. When choosing resistor values for a system, there is a trade-off between measurement accuracy and power consumption. Choosing a large resistor will increase the voltage drop and hence increase accuracy of the measurement; however the larger voltage drop dissipates more power (P = I² × R).

The Current Monitor is a unipolar system, meaning that the differential voltage swing must be from 0 V to $V_{AREF}/10$. Therefore, the Current Monitor only supports differential voltage where $|V_{AV}-V_{AC}|$ is greater than 0 V. This results in the requirement that the potential of the AV pad must be larger than the potential of the AC pad. This is straightforward for positive voltage systems. For a negative voltage system, it means that the AV pad must be "more negative" than the AC pad. This is shown in Figure 2-73.

In this case, both the AV pad and the AC pad are configured for negative operations and the output of the differential amplifier still falls between 0 V and V_{AREF} as required.

Current Range	Recommended Minimum Resistor Value (Ohms)
> 5 mA – 10 mA	10 – 20
> 10 mA – 20 mA	5 – 10
> 20 mA – 50 mA	2.5 – 5
> 50 mA – 100 mA	1 – 2
> 100 mA – 200 mA	0.5 – 1
> 200 mA – 500 mA	0.3 – 0.5
> 500 mA – 1 A	0.1 – 0.2
> 1 A – 2 A	0.05 – 0.1
> 2 A – 4 A	0.025 – 0.05
> 4 A – 8 A	0.0125 – 0.025
> 8 A – 12 A	0.00625 – 0.02

Table 2-37 • Recommended Resistor for Different Current Range Measurement

There are several popular ADC architectures, each with advantages and limitations.

The analog-to-digital converter in Fusion devices is a switched-capacitor Successive Approximation Register (SAR) ADC. It supports 8-, 10-, and 12-bit modes of operation with a cumulative sample rate up to 600 k samples per second (ksps). Built-in bandgap circuitry offers 1% internal voltage reference accuracy or an external reference voltage can be used.

As shown in Figure 2-81, a SAR ADC contains N capacitors with binary-weighted values.



Figure 2-81 • Example SAR ADC Architecture

To begin a conversion, all of the capacitors are quickly discharged. Then VIN is applied to all the capacitors for a period of time (acquisition time) during which the capacitors are charged to a value very close to VIN. Then all of the capacitors are switched to ground, and thus –VIN is applied across the comparator. Now the conversion process begins. First, C is switched to VREF Because of the binary weighting of the capacitors, the voltage at the input of the comparator is then shown by EQ 11.

Voltage at input of comparator = -VIN + VREF / 2

EQ 11

If VIN is greater than VREF / 2, the output of the comparator is 1; otherwise, the comparator output is 0. A register is clocked to retain this value as the MSB of the result. Next, if the MSB is 0, C is switched back to ground; otherwise, it remains connected to VREF, and C / 2 is connected to VREF. The result at the comparator input is now either –VIN + VREF / 4 or –VIN + 3 VREF / 4 (depending on the state of the MSB), and the comparator output now indicates the value of the next most significant bit. This bit is likewise registered, and the process continues for each subsequent bit until a conversion is complete. The conversion process requires some acquisition time plus N + 1 ADC clock cycles to complete.



Device Architecture

Integrated Voltage Reference

The Fusion device has an integrated on-chip 2.56 V reference voltage for the ADC. The value of this reference voltage was chosen to make the prescaling and postscaling factors for the prescaler blocks change in a binary fashion. However, if desired, an external reference voltage of up to 3.3 V can be connected between the VAREF and ADCGNDREF pins. The VAREFSEL control pin is used to select the reference voltage.

Table 2-42 • VAREF Bit Function

Name	Bit	Function
VAREF	0	Reference voltage selection
		0 – Internal voltage reference selected. VAREF pin outputs 2.56 V.
		1 – Input external voltage reference from VAREF and ADCGNDREF

ADC Clock

The speed of the ADC depends on its internal clock, ADCCLK, which is not accessible to users. The ADCCLK is derived from SYSCLK. Input signal TVC[7:0], Time Divider Control, determines the speed of the ADCCLK in relationship to SYSCLK, based on EQ 15.

$$t_{ADCCLK} = 4 \times (1 + TVC) \times t_{SYSCLK}$$

EQ 15

TVC: Time Divider Control (0-255)

 t_{ADCCLK} is the period of ADCCLK, and must be between 0.5 MHz and 10 MHz t_{SYSCLK} is the period of SYSCLK

Table 2-43 • TVC Bits Function

Name	Bits	Function
TVC	[7:0]	SYSCLK divider control

The frequency of ADCCLK, f_{ADCCLK}, must be within 0.5 Hz to 10 MHz.

The inputs to the ADC are synchronized to SYSCLK. A conversion is initiated by asserting the ADCSTART signal on a rising edge of SYSCLK. Figure 2-90 on page 2-112 and Figure 2-91 on page 2-112 show the timing diagram for the ADC.

Acquisition Time or Sample Time Control

Acquisition time (t_{SAMPLE}) specifies how long an analog input signal has to charge the internal capacitor array. Figure 2-88 shows a simplified internal input sampling mechanism of a SAR ADC.



Figure 2-88 • Simplified Sample and Hold Circuitry

The internal impedance (Z_{INAD}), external source resistance (R_{SOURCE}), and sample capacitor (C_{INAD}) form a simple RC network. As a result, the accuracy of the ADC can be affected if the ADC is given insufficient time to charge the capacitor. To resolve this problem, you can either reduce the source resistance or increase the sampling time by changing the acquisition time using the STC signal.

Table 2-49 • Analog Channel Specifications (continued)Commercial Temperature Range Conditions, TJ = 85°C (unless noted otherwise),Typical: VCC33A = 3.3 V, VCC = 1.5 V

Parameter	Description	Condition	Min.	Тур.	Max.	Units
Temperature Mo	nitor Using Analog Pad	AT				
External	Resolution	8-bit ADC		4	°C	
Temperature		10-bit ADC		°C		
(external diode		12-bit ADC		°C		
2N3904, T _J = 25°C) ⁴	Systematic Offset ⁵	AFS090, AFS250, AFS600, AFS1500, uncalibrated ⁷			5	°C
		AFS090, AFS250, AFS600, AFS1500, calibrated ⁷		°C		
	Accuracy			±3	±5	°C
	External Sensor Source	High level, TMSTBx = 0		10		μA
	Current	Low level, TMSTBx = 1		100		μA
	Max Capacitance on AT pad				1.3	nF
Internal	Resolution	8-bit ADC	4			°C
Temperature		10-bit ADC	1			°C
Mornton		12-bit ADC	0.25			°C
	Systematic Offset ⁵	AFS090 ⁷			5	°C
		AFS250, AFS600, AFS1500 ⁷			11	°C
	Accuracy			±3	±5	°C
t _{TMSHI}	Strobe High time		10		105	μs
t _{TMSLO}	Strobe Low time		5			μs
t _{TMSSET}	Settling time		5			μs

Notes:

1. VRSM is the maximum voltage drop across the current sense resistor.

2. Analog inputs used as digital inputs can tolerate the same voltage limits as the corresponding analog pad. There is no reliability concern on digital inputs as long as VIND does not exceed these limits.

3. VIND is limited to VCC33A + 0.2 to allow reaching 10 MHz input frequency.

- 4. An averaging of 1,024 samples (LPF setting in Analog System Builder) is required and the maximum capacitance allowed across the AT pins is 500 pF.
- 5. The temperature offset is a fixed positive value.
- 6. The high current mode has a maximum power limit of 20 mW. Appropriate current limit resistors must be used, based on voltage on the pad.
- 7. When using SmartGen Analog System Builder, CalibIP is required to obtain specified offset. For further details on CalibIP, refer to the "Temperature, Voltage, and Current Calibration in Fusion FPGAs" chapter of the Fusion FPGA Fabric User Guide.

Table 2-68 • I/O Bank Support by Device

I/O Bank	AFS090	AFS250	AFS600	AFS1500
Standard I/O	Ν	Ν	_	-
Advanced I/O	E, W	E, W	E, W	E, W
Pro I/O	-	_	Ν	Ν
Analog Quad	S	S	S	S

Note: E = *East side of the device*

W = West side of the device

N = North side of the device

S = South side of the device

Table 2-69 • Fusion VCCI Voltages and Compatible Standards

VCCI (typical)	Compatible Standards
3.3 V	LVTTL/LVCMOS 3.3, PCI 3.3, SSTL3 (Class I and II),* GTL+ 3.3, GTL 3.3,* LVPECL
2.5 V	LVCMOS 2.5, LVCMOS 2.5/5.0, SSTL2 (Class I and II),* GTL+ 2.5,* GTL 2.5,* LVDS, BLVDS, M-LVDS
1.8 V	LVCMOS 1.8
1.5 V	LVCMOS 1.5, HSTL (Class I),* HSTL (Class II)*

Note: *I/O standard supported by Pro I/O banks.

Table 2-70 • Fusion VREF Voltages and Compatible Standards*

VREF (typical)	Compatible Standards
1.5 V	SSTL3 (Class I and II)
1.25 V	SSTL2 (Class I and II)
1.0 V	GTL+ 2.5, GTL+ 3.3
0.8 V	GTL 2.5, GTL 3.3
0.75 V	HSTL (Class I), HSTL (Class II)

Note: *I/O standards supported by Pro I/O banks.



Device Architecture

Table 2-85 • Fusion Pro I/O Attributes vs. I/O Standard Applications

I/O Standards	SLEW (output only)	OUT_DRIVE (output only)	SKEW (all macros with OE)	RES_PULL	OUT_LOAD (output only)	COMBINE_REGISTER	IN_DELAY (input only)	IN_DELAY_VAL (input only)	SCHMITT_TRIGGER (input only)	HOT_SWAPPABLE
LVTTL/LVCMOS 3.3 V	3	3	3	3	3	3	3	3	3	3
LVCMOS 2.5 V	3	3	3	3	3	3	3	3	3	3
LVCMOS 2.5/5.0 V	3	3	3	3	3	3	3	3	3	3
LVCMOS 1.8 V	3	3	3	3	3	3	3	3	3	3
LVCMOS 1.5 V	3	3	3	3	3	3	3	3	3	3
PCI (3.3 V)			3		3	3	3	3		
PCI-X (3.3 V)	3		3		3	3	3	3		
GTL+ (3.3 V)			3		3	3	3	3		3
GTL+ (2.5 V)			3		3	3	3	3		3
GTL (3.3 V)			3		3	3	3	3		3
GTL (2.5 V)			3		3	3	3	3		3
HSTL Class I			3		3	3	3	3		3
HSTL Class II			3		3	3	3	3		3
SSTL2 Class I and II			3		3	3	3	3		3
SSTL3 Class I and II			3		3	3	3	3		3
LVDS, BLVDS, M-LVDS			3			3	3	3		3
LVPECL						3	3	3		3





Figure 2-118 • Tristate Output Buffer Timing Model and Delays (example)



Detailed I/O DC Characteristics

Table 2-95 • Input Capacitance

Symbol	Definition	Conditions	Min.	Max.	Units
C _{IN}	Input capacitance	VIN = 0, f = 1.0 MHz		8	pF
C _{INCLK}	Input capacitance on the clock pin	VIN = 0, f = 1.0 MHz		8	pF

Table 2-96 • I/O Output Buffer Maximum Resistances ¹

Drive Strength	R _{PULL-DOWN} (ohms) ²	R _{PULL-UP} (ohms) ³	
4 mA	100	300	
8 mA	50	150	
12 mA	25	75	
16 mA	17	50	
24 mA	11	33	
4 mA	100	200	
8 mA	50	100	
12 mA	25	50	
16 mA	20	40	
24 mA	11	22	
2 mA	200	225	
4 mA	100	112	
6 mA	50	56	
8 mA	50	56	
12 mA	20	22	
16 mA	20	22	
2 mA	200	224	
4 mA	100	112	
6 mA	67	75	
8 mA	33	37	
12 mA	33	37	
Per PCI/PCI-X specification	25	75	
20 mA	11	-	
20 mA	14	-	
35 mA	12	-	
33 mA	15	_	
	Drive Strength 4 mA 8 mA 12 mA 16 mA 24 mA 4 mA 8 mA 12 mA 16 mA 24 mA 4 mA 8 mA 12 mA 16 mA 24 mA 6 mA 8 mA 112 mA 16 mA 2 mA 4 mA 6 mA 8 mA 12 mA 16 mA 8 mA 12 mA 12 mA 13 mA Per PCI/PCI-X specification 20 mA 35 mA 33 mA	Drive Strength "PULL-DOWN (ohms) 2" 4 mA 100 8 mA 50 12 mA 25 16 mA 17 24 mA 11 4 mA 100 8 mA 50 12 mA 25 16 mA 11 4 mA 100 8 mA 50 12 mA 25 16 mA 20 24 mA 11 2 mA 200 4 mA 100 6 mA 50 12 mA 20 16 mA 20 2 mA 200 4 mA 100 6 mA 50 12 mA 20 2 mA 200 4 mA 100 6 mA 67 8 mA 33 12 mA 33 Per PCI/PCI-X specification 25 20 mA 11 20 mA 14 <	

Notes:

 These maximum values are provided for informational reasons only. Minimum output buffer resistance values depend on VCC, drive strength selection, temperature, and process. For board design considerations and detailed output buffer resistances, use the corresponding IBIS models located on the Microsemi SoC Products Group website: http://www.microsemi.com/soc/techdocs/models/ibis.html.

2. R_(PULL-DOWN-MAX) = VOLspec / I_{OLspec}

3. R_(PULL-UP-MAX) = (VCCImax – VOHspec) / IOHspec

Microsemi.

Device Architecture

Table 2-130 • 1.5 V LVCMOS Low Slew

Commercial Temperature Range Conditions: $T_J = 70^{\circ}$ C, Worst-Case VCC = 1.425 V, Worst-Case VCCI = 1.4 V Applicable to Advanced I/Os

Drive	Speed												
Strength	Grade	t _{DOUT}	t _{DP}	t _{DIN}	t _{PY}	t _{EOUT}	t _{ZL}	t _{ZH}	t _{LZ}	t _{HZ}	t _{ZLS}	t _{zHS}	Units
2 mA	Std.	0.66	12.78	0.04	1.31	0.43	12.81	12.78	3.40	2.64	15.05	15.02	ns
	-1	0.56	10.87	0.04	1.11	0.36	10.90	10.87	2.89	2.25	12.80	12.78	ns
	-2	0.49	9.55	0.03	0.98	0.32	9.57	9.55	2.54	1.97	11.24	11.22	ns
4 mA	Std.	0.66	10.01	0.04	1.31	0.43	10.19	9.55	3.75	3.27	12.43	11.78	ns
	-1	0.56	8.51	0.04	1.11	0.36	8.67	8.12	3.19	2.78	10.57	10.02	ns
	-2	0.49	7.47	0.03	0.98	0.32	7.61	7.13	2.80	2.44	9.28	8.80	ns
8 mA	Std.	0.66	9.33	0.04	1.31	0.43	9.51	8.89	3.83	3.43	11.74	11.13	ns
	-1	0.56	7.94	0.04	1.11	0.36	8.09	7.56	3.26	2.92	9.99	9.47	ns
	-2	0.49	6.97	0.03	0.98	0.32	7.10	6.64	2.86	2.56	8.77	8.31	ns
12 mA	Std.	0.66	8.91	0.04	1.31	0.43	9.07	8.89	3.95	4.05	11.31	11.13	ns
	-1	0.56	7.58	0.04	1.11	0.36	7.72	7.57	3.36	3.44	9.62	9.47	ns
	-2	0.49	6.65	0.03	0.98	0.32	6.78	6.64	2.95	3.02	8.45	8.31	ns

Note: For the derating values at specific junction temperature and voltage supply levels, refer to Table 3-7 on page 3-9.

Table 2-131 • 1.5 V LVCMOS High Slew

Commercial Temperature Range Conditions: $T_J = 70^{\circ}$ C, Worst-Case VCC = 1.425 V, Worst-Case VCCI = 1.4 V Applicable to Advanced I/Os

Drive Strength	Speed Grade	t _{DOUT}	t _{DP}	t _{DIN}	t _{PY}	t _{EOUT}	t _{ZL}	t _{zH}	t _{LZ}	t _{HZ}	t _{zLS}	t _{zHS}	Units
2 mA	Std.	0.66	8.36	0.04	1.44	0.43	6.82	8.36	3.39	2.77	9.06	10.60	ns
	-1	0.56	7.11	0.04	1.22	0.36	5.80	7.11	2.88	2.35	7.71	9.02	ns
	-2	0.49	6.24	0.03	1.07	0.32	5.10	6.24	2.53	2.06	6.76	7.91	ns
4 mA	Std.	0.66	5.31	0.04	1.44	0.43	4.85	5.31	3.74	3.40	7.09	7.55	ns
	-1	0.56	4.52	0.04	1.22	0.36	4.13	4.52	3.18	2.89	6.03	6.42	ns
	-2	0.49	3.97	0.03	1.07	0.32	3.62	3.97	2.79	2.54	5.29	5.64	ns
8 mA	Std.	0.66	4.67	0.04	1.44	0.43	4.55	4.67	3.82	3.56	6.78	6.90	ns
	-1	0.56	3.97	0.04	1.22	0.36	3.87	3.97	3.25	3.03	5.77	5.87	ns
	-2	0.49	3.49	0.03	1.07	0.32	3.40	3.49	2.85	2.66	5.07	5.16	ns
12 mA	Std.	0.66	4.08	0.04	1.44	0.43	4.15	3.58	3.94	4.20	6.39	5.81	ns
	-1	0.56	3.47	0.04	1.22	0.36	3.53	3.04	3.36	3.58	5.44	4.95	ns
	-2	0.49	3.05	0.03	1.07	0.32	3.10	2.67	2.95	3.14	4.77	4.34	ns

Note: For the derating values at specific junction temperature and voltage supply levels, refer to Table 3-7 on page 3-9.



Differential I/O Characteristics

Configuration of the I/O modules as a differential pair is handled by the Microsemi Designer software when the user instantiates a differential I/O macro in the design.

Differential I/Os can also be used in conjunction with the embedded Input Register (InReg), Output Register (OutReg), Enable Register (EnReg), and Double Data Rate (DDR). However, there is no support for bidirectional I/Os or tristates with these standards.

LVDS

Low-Voltage Differential Signal (ANSI/TIA/EIA-644) is a high-speed differential I/O standard. It requires that one data bit be carried through two signal lines, so two pins are needed. It also requires external resistor termination.

The full implementation of the LVDS transmitter and receiver is shown in an example in Figure 2-134. The building blocks of the LVDS transmitter–receiver are one transmitter macro, one receiver macro, three board resistors at the transmitter end, and one resistor at the receiver end. The values for the three driver resistors are different from those used in the LVPECL implementation because the output standard specifications are different.



Figure 2-134 • LVDS	Circuit Diagram and	I Board-Level Implementat	ion
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Table 2-168 • I	Minimum and	Maximum	DC Input a	and Output Levels
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DC Parameter	Description	Min.	Тур.	Max.	Units
VCCI	Supply Voltage	2.375	2.5	2.625	V
VOL	Output Low Voltage	0.9	1.075	1.25	V
VOH	Input High Voltage	1.25	1.425	1.6	V
IOL ¹	Output Low Voltage	0.65	0.91	1.16	mA
IOH ¹	Output High Voltage	0.65	0.91	1.16	mA
VI	Input Voltage	0		2.925	V
IIL ^{2,3}	Input Low Voltage			10	μA
IIH ^{2,4}	Input High Voltage			10	μA
VODIFF	Differential Output Voltage	250	350	450	mV
VOCM	Output Common Mode Voltage	1.125	1.25	1.375	V
VICM	Input Common Mode Voltage	0.05	1.25	2.35	V
VIDIFF	Input Differential Voltage	100	350		mV

Notes:

- 1. IOL/IOH defined by VODIFF/(Resistor Network)
- 2. Currents are measured at 85°C junction temperature.
- 3. ILL is the input leakage current per I/O pin over recommended operation conditions where -0.3 V < VIN < VIL.
- 4. IIH is the input leakage current per I/O pin over recommended operating conditions VIH < VIN < VCCI. Input current is larger when operating outside recommended ranges.

Table 2-169 • AC Waveforms, Measuring Points, and Capacitive Loads

Input Low (V)	Input High (V)	Measuring Point* (V)	VREF (typ.) (V)
1.075	1.325	Cross point	_

Note: *Measuring point = Vtrip. See Table 2-90 on page 2-166 for a complete table of trip points.

Timing Characteristics

Table 2-170 • LVDS

Commercial Temperature Range Conditions: $T_J = 70^{\circ}$ C, Worst-Case VCC = 1.425 V, Worst-Case VCCI = 2.3 V Applicable to Pro I/Os

Speed Grade	t _{DOUT}	t _{DP}	t _{DIN}	t _{PY}	Units
Std.	0.66	2.10	0.04	1.82	ns
-1	0.56	1.79	0.04	1.55	ns
-2	0.49	1.57	0.03	1.36	ns

Note: For the derating values at specific junction temperature and voltage supply levels, refer to Table 3-7 on page 3-9.

BLVDS/M-LVDS

Bus LVDS (BLVDS) and Multipoint LVDS (M-LVDS) specifications extend the existing LVDS standard to high-performance multipoint bus applications. Multidrop and multipoint bus configurations can contain any combination of drivers, receivers, and transceivers. Microsemi LVDS drivers provide the higher drive current required by BLVDS and M-LVDS to accommodate the loading. The driver requires series terminations for better signal quality and to control voltage swing. Termination is also required at both ends of the bus, since the driver can be located anywhere on the bus. These configurations can be implemented using TRIBUF_LVDS and BIBUF_LVDS macros along with appropriate terminations. Multipoint designs using Microsemi LVDS macros can achieve up to 200 MHz with a maximum of 20 loads. A sample application is given in Figure 2-135. The input and output buffer delays are available in the LVDS section in Table 2-171.

Example: For a bus consisting of 20 equidistant loads, the following terminations provide the required differential voltage, in worst-case industrial operating conditions at the farthest receiver: $R_S = 60 \Omega$ and $R_T = 70 \Omega$, given $Z_0 = 50 \Omega$ (2") and $Z_{stub} = 50 \Omega$ (~1.5").



Figure 2-135 • BLVDS/M-LVDS Multipoint Application Using LVDS I/O Buffers





Figure	2-145 •	Output DDR	Timing	Diagram

Timing Characteristics

Table 2-182 • Output DDR Propagation Delays	
Commercial Temperature Range Conditions: T ₁ = 70°C, Worst-Case VCC = 1.425 V	

Parameter	Description	-2	-1	Std.	Units
t _{DDROCLKQ}	Clock-to-Out of DDR for Output DDR	0.70	0.80	0.94	ns
t _{DDROSUD1}	Data_F Data Setup for Output DDR	0.38	0.43	0.51	ns
t _{DDROSUD2}	Data_R Data Setup for Output DDR	0.38	0.43	0.51	ns
t _{DDROHD1}	Data_F Data Hold for Output DDR	0.00	0.00	0.00	ns
t _{DDROHD2}	Data_R Data Hold for Output DDR	0.00	0.00	0.00	ns
t _{DDROCLR2Q}	Asynchronous Clear-to-Out for Output DDR	0.80	0.91	1.07	ns
t _{DDROREMCLR}	Asynchronous Clear Removal Time for Output DDR	0.00	0.00	0.00	ns
t _{DDRORECCLR}	Asynchronous Clear Recovery Time for Output DDR	0.22	0.25	0.30	ns
t _{DDROWCLR1}	Asynchronous Clear Minimum Pulse Width for Output DDR	0.22	0.25	0.30	ns
t _{DDROCKMPWH}	Clock Minimum Pulse Width High for the Output DDR	0.36	0.41	0.48	ns
t _{DDROCKMPWL}	Clock Minimum Pulse Width Low for the Output DDR	0.32	0.37	0.43	ns
F _{DDOMAX}	Maximum Frequency for the Output DDR	1404	1232	1048	MHz

Note: For the derating values at specific junction temperature and voltage supply levels, refer to Table 3-7 on page 3-9.

XTAL2 Crystal Oscillator Circuit Input

Input to crystal oscillator circuit. Pin for connecting external crystal, ceramic resonator, RC network, or external clock input. When using an external crystal or ceramic oscillator, external capacitors are also recommended (Please refer to the crystal oscillator manufacturer for proper capacitor value).

If using external RC network or clock input, XTAL1 should be used and XTAL2 left unconnected. In the case where the Crystal Oscillator block is not used, the XTAL1 pin should be connected to GND and the XTAL2 pin should be left floating.

Security

Fusion devices have a built-in 128-bit AES decryption core. The decryption core facilitates highly secure, in-system programming of the FPGA core array fabric and the FlashROM. The FlashROM and the FPGA core fabric can be programmed independently from each other, allowing the FlashROM to be updated without the need for change to the FPGA core fabric. The AES master key is stored in on-chip nonvolatile memory (flash). The AES master key can be preloaded into parts in a security-protected programming environment (such as the Microsemi in-house programming center), and then "blank" parts can be shipped to an untrusted programming or manufacturing center for final personalization with an AES-encrypted bitstream. Late stage product changes or personalization can be implemented easily and with high level security by simply sending a STAPL file with AES-encrypted data. Highly secure remote field updates over public networks (such as the Internet) are possible by sending and programming a STAPL file with AES-encrypted data. For more information, refer to the *Fusion Security* application note.

128-Bit AES Decryption

The 128-bit AES standard (FIPS-197) block cipher is the National Institute of Standards and Technology (NIST) replacement for DES (Data Encryption Standard FIPS46-2). AES has been designed to protect sensitive government information well into the 21st century. It replaces the aging DES, which NIST adopted in 1977 as a Federal Information Processing Standard used by federal agencies to protect sensitive, unclassified information. The 128-bit AES standard has 3.4 × 10³⁸ possible 128-bit key variants, and it has been estimated that it would take 1,000 trillion years to crack 128-bit AES cipher text using exhaustive techniques. Keys are stored (protected with security) in Fusion devices in nonvolatile flash memory. All programming files sent to the device can be authenticated by the part prior to programming to ensure that bad programming data is not loaded into the part that may possibly damage it. All programming verification is performed on-chip, ensuring that the contents of Fusion devices remain as secure as possible.

AES decryption can also be used on the 1,024-bit FlashROM to allow for remote updates of the FlashROM contents. This allows for easy support of subscription model products and protects them with measures designed to provide the highest level of security available. See the application note *Fusion Security* for more details.

AES for Flash Memory

AES decryption can also be used on the flash memory blocks. This provides the best available security during update of the flash memory blocks. During runtime, the encrypted data can be clocked in via the JTAG interface. The data can be passed through the internal AES decryption engine, and the decrypted data can then be stored in the flash memory block.

Programming

Programming can be performed using various programming tools, such as Silicon Sculptor II (BP Micro Systems) or FlashPro3 (Microsemi).

The user can generate STP programming files from the Designer software and can use these files to program a device.

Fusion devices can be programmed in-system. During programming, VCCOSC is needed in order to power the internal 100 MHz oscillator. This oscillator is used as a source for the 20 MHz oscillator that is used to drive the charge pump for programming.



Symbol	Parameter ²		Commercial	Industrial	Units
Τ _J	Junction temperature		0 to +85	-40 to +100	°C
VCC	1.5 V DC core supply voltage	1.425 to 1.575	1.425 to 1.575	V	
VJTAG	JTAG DC voltage		1.4 to 3.6	1.4 to 3.6	V
VPUMP	Programming voltage	Programming mode ³	3.15 to 3.45	3.15 to 3.45	V
	Operation ⁴		0 to 3.6	0 to 3.6	V
VCCPLL	Analog power supply (PLL)		1.425 to 1.575	1.425 to 1.575	V
VCCI	1.5 V DC supply voltage		1.425 to 1.575	1.425 to 1.575	V
	1.8 V DC supply voltage		1.7 to 1.9	1.7 to 1.9	V
	2.5 V DC supply voltage		2.3 to 2.7	2.3 to 2.7	V
	3.3 V DC supply voltage		3.0 to 3.6	3.0 to 3.6	V
	LVDS differential I/O		2.375 to 2.625	2.375 to 2.625	V
	LVPECL differential I/O	3.0 to 3.6	3.0 to 3.6	V	
VCC33A	+3.3 V power supply	2.97 to 3.63	2.97 to 3.63	V	
VCC33PMP	+3.3 V power supply	2.97 to 3.63	2.97 to 3.63	V	
VAREF	Voltage reference for ADC	2.527 to 2.593	2.527 to 2.593	V	
VCC15A ⁵	Digital power supply for the analog	1.425 to 1.575	1.425 to 1.575	V	
VCCNVM	Embedded flash power supply	1.425 to 1.575	1.425 to 1.575	V	
VCCOSC	Oscillator power supply		2.97 to 3.63	2.97 to 3.63	V
AV, AC ⁶	Unpowered, ADC reset asserted or	-10.5 to 12.0	-10.5 to 11.6	V	
	Analog input (+16 V to +2 V presca	ller range)	-0.3 to 12.0	–0.3 to 11.6	V
	Analog input (+1 V to + 0.125 V pre	escaler range)	-0.3 to 3.6	-0.3 to 3.6	V
	Analog input (–16 V to –2 V presca	ler range)	-10.5 to 0.3	-10.5 to 0.3	V
	Analog input (–1 V to –0.125 V pres	scaler range)	-3.6 to 0.3	-3.6 to 0.3	V
	Analog input (direct input to ADC)		-0.3 to 3.6	-0.3 to 3.6	V
	Digital input		-0.3 to 12.0	–0.3 to 11.6	V
AG ⁶	Unpowered, ADC reset asserted or	unconfigured	-10.5 to 12.0	-10.5 to 11.6	V
	Low Current Mode (1 µA, 3 µA, 10	μΑ, 30 μΑ)	-0.3 to 12.0	–0.3 to 11.6	V
	Low Current Mode (–1 µA, –3 µA, -	–10 μA, –30 μA)	-10.5 to 0.3	-10.5 to 0.3	V
	High Current Mode ⁷		-10.5 to 12.0	-10.5 to 11.6	V
AT ⁶	Unpowered, ADC reset asserted or	unconfigured	-0.3 to 15.5	–0.3 to 14.5	V
	Analog input (+16 V, +4 V prescale	r range)	-0.3 to 15.5	–0.3 to 14.5	V
	Analog input (direct input to ADC)		-0.3 to 3.6	-0.3 to 3.6	V
	Digital input		-0.3 to 15.5	-0.3 to 14.5	V

Table 3-2 • Recommended Operating Conditions¹

Notes:

1. The ranges given here are for power supplies only. The recommended input voltage ranges specific to each I/O standard are given in Table 2-85 on page 2-157.

- 2. All parameters representing voltages are measured with respect to GND unless otherwise specified.
- 3. The programming temperature range supported is $T_{ambient} = 0^{\circ}C$ to 85°C.
- 4. VPUMP can be left floating during normal operation (not programming mode).
- 5. Violating the V_{CC15A} recommended voltage supply during an embedded flash program cycle can corrupt the page being programmed.
- 6. The input voltage may overshoot by up to 500 mV above the Recommended Maximum (150 mV in Direct mode), provided the duration of the overshoot is less than 50% of the operating lifetime of the device.
- 7. The AG pad should also conform to the limits as specified in Table 2-48 on page 2-114.



 P_{S-CELL} = N_{S-CELL} * (PAC5 + (α_1 / 2) * PAC6) * F_{CLK}

N_{S-CELL} is the number of VersaTiles used as sequential modules in the design. When a multi-tile sequential cell is used, it should be accounted for as 1.

 α_1 is the toggle rate of VersaTile outputs—guidelines are provided in Table 3-16 on page 3-27.

F_{CLK} is the global clock signal frequency.

Standby Mode and Sleep Mode

 $P_{S-CELL} = 0 W$

Combinatorial Cells Dynamic Contribution—P_{C-CELL}

Operating Mode

 $P_{C-CELL} = N_{C-CELL} * (\alpha_1 / 2) * PAC7 * F_{CLK}$

N_{C-CELL} is the number of VersaTiles used as combinatorial modules in the design.

 α_1 is the toggle rate of VersaTile outputs—guidelines are provided in Table 3-16 on page 3-27.

F_{CLK} is the global clock signal frequency.

Standby Mode and Sleep Mode

 $P_{C-CELL} = 0 W$

Routing Net Dynamic Contribution-PNET

Operating Mode

 $P_{NET} = (N_{S-CELL} + N_{C-CELL}) * (\alpha_1 / 2) * PAC8 * F_{CLK}$

N_{S-CELL} is the number VersaTiles used as sequential modules in the design.

N_{C-CELL} is the number of VersaTiles used as combinatorial modules in the design.

 α_1 is the toggle rate of VersaTile outputs—guidelines are provided in Table 3-16 on page 3-27.

F_{CLK} is the global clock signal frequency.

Standby Mode and Sleep Mode

 $P_{NET} = 0 W$

I/O Input Buffer Dynamic Contribution—PINPUTS

Operating Mode

 $P_{INPUTS} = N_{INPUTS} * (\alpha_2 / 2) * PAC9 * F_{CLK}$

N_{INPUTS} is the number of I/O input buffers used in the design.

 α_2 is the I/O buffer toggle rate—guidelines are provided in Table 3-16 on page 3-27.

F_{CLK} is the global clock signal frequency.

Standby Mode and Sleep Mode

P_{INPUTS} = 0 W

I/O Output Buffer Dynamic Contribution—POUTPUTS

Operating Mode

 $\mathsf{P}_{\mathsf{OUTPUTS}} = \mathsf{N}_{\mathsf{OUTPUTS}} * (\alpha_2 / 2) * \beta_1 * \mathsf{PAC10} * \mathsf{F}_{\mathsf{CLK}}$

N_{OUTPUTS} is the number of I/O output buffers used in the design.

 α_2 is the I/O buffer toggle rate—guidelines are provided in Table 3-16 on page 3-27.

 β_1 is the I/O buffer enable rate—guidelines are provided in Table 3-17 on page 3-27.

F_{CLK} is the global clock signal frequency.

Standby Mode and Sleep Mode

P_{OUTPUTS} = 0 W

Power Consumption

Table 3-18 • Power Consumption

Parameter	Description	Condition	Min.	Typical	Max.	Units
Crystal Oscillator						•
ISTBXTAL	Standby Current of Crystal Oscillator			10		μΑ
IDYNXTAL	Operating Current	RC		0.6		mA
		0.032–0.2		0.19		mA
		0.2–2.0		0.6		mA
		2.0–20.0		0.6		mA
RC Oscillator						
IDYNRC	Operating Current			1		mA
ACM					-	
	Operating Current (fixed clock)			200		µA/MHz
	Operating Current (user clock)			30		μΑ
NVM System						•
	NVM Array Operating Power	Idle		795		μA
		Read operation		See Table 3-15 on page 3-23.		See Table 3-15 on page 3-23.
		Erase		900		μA
		Write		900		μA
PNVMCTRL	NVM Controller Operating Power			20		µW/MHz

🌜 Microsemi.

Package Pin Assignments

FG676			FG676	FG676		
Pin Number	AFS1500 Function	Pin Number	AFS1500 Function	Pin Number	AFS1500 Function	
C9	IO07PDB0V1	D19	GBC1/IO40PDB1V2	F3	IO121NDB4V0	
C10	IO09PDB0V1	D20	GBA1/IO42PDB1V2	F4	GND	
C11	IO13NDB0V2	D21	GND	F5	IO123NDB4V0	
C12	IO13PDB0V2	D22	VCCPLB	F6	GAC2/IO123PDB4V0	
C13	IO24PDB1V0	D23	GND	F7	GAA2/IO125PDB4V0	
C14	IO26PDB1V0	D24	NC	F8	GAC0/IO03NDB0V0	
C15	IO27NDB1V1	D25	NC	F9	GAC1/IO03PDB0V0	
C16	IO27PDB1V1	D26	NC	F10	IO10NDB0V1	
C17	IO35NDB1V2	E1	GND	F11	IO10PDB0V1	
C18	IO35PDB1V2	E2	IO122NPB4V0	F12	IO14NDB0V2	
C19	GBC0/IO40NDB1V2	E3	IO121PDB4V0	F13	IO23NDB1V0	
C20	GBA0/IO42NDB1V2	E4	IO122PPB4V0	F14	IO23PDB1V0	
C21	IO43NDB1V2	E5	IO00NDB0V0	F15	IO32NPB1V1	
C22	IO43PDB1V2	E6	IO00PDB0V0	F16	IO34NDB1V1	
C23	NC	E7	VCCIB0	F17	IO34PDB1V1	
C24	GND	E8	IO05NDB0V1	F18	IO37PDB1V2	
C25	NC	E9	IO05PDB0V1	F19	GBB1/IO41PDB1V2	
C26	NC	E10	VCCIB0	F20	VCCIB2	
D1	NC	E11	IO11NDB0V1	F21	IO47PPB2V0	
D2	NC	E12	IO14PDB0V2	F22	IO44NDB2V0	
D3	NC	E13	VCCIB0	F23	GND	
D4	GND	E14	VCCIB1	F24	IO45NDB2V0	
D5	GAA0/IO01NDB0V0	E15	IO29NDB1V1	F25	VCCIB2	
D6	GND	E16	IO29PDB1V1	F26	NC	
D7	IO04NDB0V0	E17	VCCIB1	G1	NC	
D8	IO04PDB0V0	E18	IO37NDB1V2	G2	IO119PPB4V0	
D9	GND	E19	GBB0/IO41NDB1V2	G3	IO120NDB4V0	
D10	IO09NDB0V1	E20	VCCIB1	G4	IO120PDB4V0	
D11	IO11PDB0V1	E21	VCOMPLB	G5	VCCIB4	
D12	GND	E22	GBA2/IO44PDB2V0	G6	GAB2/IO124PDB4V0	
D13	IO24NDB1V0	E23	IO48PPB2V0	G7	IO125NDB4V0	
D14	IO26NDB1V0	E24	GBB2/IO45PDB2V0	G8	GND	
D15	GND	E25	NC	G9	VCCIB0	
D16	IO31NDB1V1	E26	GND	G10	IO08NDB0V1	
D17	IO31PDB1V1	F1	NC	G11	IO08PDB0V1	
D18	GND	F2	VCCIB4	G12	GND	



Datasheet Information

Revision	Changes	Page
Advance v1.0 (continued)	This change table states that in the "208-Pin PQFP" table listed under the Advance v0.8 changes, the AFS090 device had a pin change. That is incorrect. Pin 102 was updated for AFS250 and AFS600. The function name changed from $V_{CC33ACAP}$ to V_{CC33A} .	3-8
Advance v0.9 (October 2007)	In the "Package I/Os: Single-/Double-Ended (Analog)" table, the AFS1500/M7AFS1500 I/O counts were updated for the following devices: FG484: 223/109 FG676: 252/126	II
	In the "108-Pin QFN" table, the function changed from $V_{CC33ACAP}$ to V_{CC33A} for the following pin: B25	3-2
	In the "180-Pin QFN" table, the function changed from V _{CC33ACAP} to V _{CC33A} for the following pins: AFS090: B29 AFS250: B29	3-4
	In the "208-Pin PQFP" table, the function changed from V _{CC33ACAP} to V _{CC33A} for the following pins: AFS090: 102 AFS250: 102	3-8
	In the "256-Pin FBGA" table, the function changed from $V_{CC33ACAP}$ to V_{CC33A} for the following pins: AFS090: T14 AFS250: T14 AFS600: T14 AFS1500: T14	3-12
Advance v0.9 (continued)	In the "484-Pin FBGA" table, the function changed from V _{CC33ACAP} to V _{CC33A} for the following pins: AFS600: AB18 AFS1500: AB18	3-20
	In the "676-Pin FBGA" table, the function changed from V _{CC33ACAP} to V _{CC33A} for the following pins: AFS1500: AD20	3-28
Advance v0.8 (June 2007)	Figure 2-16 • Fusion Clocking Options and the "RC Oscillator" section were updated to change GND_OSC and VCC_OSC to GNDOSC and VCCOSC.	2-20, 2-21
	Figure 2-19 • Fusion CCC Options: Global Buffers with the PLL Macro was updated to change the positions of OADIVRST and OADIVHALF, and a note was added.	2-25
	The "Crystal Oscillator" section was updated to include information about controlling and enabling/disabling the crystal oscillator.	2-22
	Table 2-11 \cdot Electrical Characteristics of the Crystal Oscillator was updated to change the typical value of I _{DYNXTAL} for 0.032–0.2 MHz to 0.19.	2-24
	The "1.5 V Voltage Regulator" section was updated to add "or floating" in the paragraph stating that an external pull-down is required on TRST to power down the VR.	2-41
	The "1.5 V Voltage Regulator" section was updated to include information on powering down with the VR.	2-41

Fusion Family of Mixed Signal FPGAs

Revision	Changes	Page
Advance v0.6 (continued)	The "Analog-to-Digital Converter Block" section was updated with the following statement: "All results are MSB justified in the ADC."	2-99
	The information about the ADCSTART signal was updated in the "ADC Description" section.	2-102
	Table 2-46 · Analog Channel Specifications was updated.	2-118
	Table 2-47 · ADC Characteristics in Direct Input Mode was updated.	2-121
	Table 2-51 • ACM Address Decode Table for Analog Quad was updated.	2-127
	In Table 2-53 • Analog Quad ACM Byte Assignment, the Function and Default Setting for Bit 6 in Byte 3 was updated.	2-130
	The "Introduction" section was updated to include information about digital inputs, outputs, and bibufs.	2-133
	In Table 2-69 • Fusion Pro I/O Features, the programmable delay descriptions were updated for the following features:	2-137
	Single-ended receiver	
	Voltage-referenced differential receiver	
	The "liker I/O Naming Convention" section was undeted to include "V/" and "r"	2 150
	descriptions	2-159
	The "VCC33PMP Analog Power Supply (3.3 V)" section was updated to include information about avoiding high current draw.	2-224
	The "VCCNVM Flash Memory Block Power Supply (1.5 V)" section was updated to include information about avoiding high current draw.	2-224
	The "VMVx I/O Supply Voltage (quiet)" section was updated to include this statement: VMV and VCCI must be connected to the same power supply and V_{CCI} pins within a given I/O bank.	2-185
	The "PUB Push Button" section was updated to include information about leaving the pin floating if it is not used.	2-228
	The "PTBASE Pass Transistor Base" section was updated to include information about leaving the pin floating if it is not used.	2-228
	The "PTEM Pass Transistor Emitter" section was updated to include information about leaving the pin floating if it is not used.	2-228
	The heading was incorrect in the "208-Pin PQFP" table. It should be AFS250 and not AFS090.	3-8