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Understanding <u>Embedded - FPGAs (Field</u> <u>Programmable Gate Array)</u>

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details

Product Status	Active
Number of LABs/CLBs	-
Number of Logic Elements/Cells	-
Total RAM Bits	276480
Number of I/O	223
Number of Gates	1500000
Voltage - Supply	1.425V ~ 1.575V
Mounting Type	Surface Mount
Operating Temperature	-40°C ~ 100°C (TJ)
Package / Case	484-BGA
Supplier Device Package	484-FPBGA (23x23)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/m1afs1500-1fg484i

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong



1 – Fusion Device Family Overview

Introduction

The Fusion mixed signal FPGA satisfies the demand from system architects for a device that simplifies design and unleashes their creativity. As the world's first mixed signal programmable logic family, Fusion integrates mixed signal analog, flash memory, and FPGA fabric in a monolithic device. Fusion devices enable designers to quickly move from concept to completed design and then deliver feature-rich systems to market. This new technology takes advantage of the unique properties of Microsemi flash-based FPGAs, including a high-isolation, triple-well process and the ability to support high-voltage transistors to meet the demanding requirements of mixed signal system design.

Fusion mixed signal FPGAs bring the benefits of programmable logic to many application areas, including power management, smart battery charging, clock generation and management, and motor control. Until now, these applications have only been implemented with costly and space-consuming discrete analog components or mixed signal ASIC solutions. Fusion mixed signal FPGAs present new capabilities for system development by allowing designers to integrate a wide range of functionality into a single device, while at the same time offering the flexibility of upgrades late in the manufacturing process or after the device is in the field. Fusion devices provide an excellent alternative to costly and

time-consuming mixed signal ASIC designs. In addition, when used in conjunction with the ARM Cortex-M1 processor, Fusion technology represents the definitive mixed signal FPGA platform.

Flash-based Fusion devices are Instant On. As soon as system power is applied and within normal operating specifications, Fusion devices are working. Fusion devices have a 128-bit flash-based lock and industry-leading AES decryption, used to secure programmed intellectual property (IP) and configuration data. Fusion devices are the most comprehensive single-chip analog and digital programmable logic solution available today.

To support this new ground-breaking technology, Microsemi has developed a series of major tool innovations to help maximize designer productivity. Implemented as extensions to the popular Microsemi Libero[®] System-on-Chip (SoC) software, these new tools allow designers to easily instantiate and configure peripherals within a design, establish links between peripherals, create or import building blocks or reference designs, and perform hardware verification. This tool suite will also add comprehensive hardware/software debug capability as well as a suite of utilities to simplify development of embedded soft-processor-based solutions.

General Description

The Fusion family, based on the highly successful ProASIC[®]3 and ProASIC3E flash FPGA architecture, has been designed as a high-performance, programmable, mixed signal platform. By combining an advanced flash FPGA core with flash memory blocks and analog peripherals, Fusion devices dramatically simplify system design and, as a result, dramatically reduce overall system cost and board space.

The state-of-the-art flash memory technology offers high-density integrated flash memory blocks, enabling savings in cost, power, and board area relative to external flash solutions, while providing increased flexibility and performance. The flash memory blocks and integrated analog peripherals enable true mixed-mode programmable logic designs. Two examples are using an on-chip soft processor to implement a fully functional flash MCU and using high-speed FPGA logic to offer system and power supervisory capabilities. Instant On, and capable of operating from a single 3.3 V supply, the Fusion family is ideally suited for system management and control applications.

The devices in the Fusion family are categorized by FPGA core density. Each family member contains many peripherals, including flash memory blocks, an analog-to-digital-converter (ADC), high-drive outputs, both RC and crystal oscillators, and a real-time counter (RTC). This provides the user with a high level of flexibility and integration to support a wide variety of mixed signal applications. The flash memory block capacity ranges from 2 Mbits to 8 Mbits. The integrated 12-bit ADC supports up to 30 independently configurable input channels.

Clocking Resources

The Fusion family has a robust collection of clocking peripherals, as shown in the block diagram in Figure 2-16. These on-chip resources enable the creation, manipulation, and distribution of many clock signals. The Fusion integrated RC oscillator produces a 100 MHz clock source with no external components. For systems requiring more precise clock signals, the Fusion family supports an on-chip crystal oscillator circuit. The integrated PLLs in each Fusion device can use the RC oscillator, crystal oscillator, or another on-chip clock signal as a source. These PLLs offer a variety of capabilities to modify the clock source (multiply, divide, synchronize, advance, or delay). Utilizing the CCC found in the popular ProASIC3 family, Fusion incorporates six CCC blocks. The CCCs allow access to Fusion global and local clock distribution nets, as described in the "Global Resources (VersaNets)" section on page 2-11.



Figure 2-16 • Fusion Clocking Options

Voltage Regulator and Power System Monitor (VRPSM)

The VRPSM macro controls the power-up state of the FPGA. The power-up bar (PUB) pin can turn on the voltage regulator when set to 0. TRST can enable the voltage regulator when deasserted, allowing the FPGA to power-up when user want access to JTAG ports. The inputs VRINITSTATE and RTCPSMMATCH come from the flash bits and RTC, and can also power up the FPGA.



Note: *Signals are hardwired internally and do not exist in the macro core.

Figure 2-30 • VRPSM Macro

Table 2-17 • VRPSM Signal Descriptions

Signal Name	Width	Direction	Function
VRPU	1	In	Voltage Regulator Power-Up
			0 – Voltage regulator disabled. PUB must be floated or pulled up, and the TRST pin must be grounded to disable the voltage regulator.
			1 – Voltage regulator enabled
VRINITSTATE	1	In	Voltage Regulator Initial State
			Defines the voltage Regulator status upon power-up of the 3.3 V. The signal is configured by Libero SoC when the VRPSM macro is generated.
			Tie off to 1 – Voltage regulator enables when 3.3 V is powered.
			Tie off to 0 – Voltage regulator disables when 3.3 V is powered.
RTCPSMMATCH	1	In	RTC Power System Management Match
			Connect from RTCPSMATCH signal from RTC in AB
			0 transition to 1 turns on the voltage regulator
PUB	1	In	External pin, built-in weak pull-up
			Power-Up Bar
			0 – Enables voltage regulator at all times
TRST*	1	In	External pin, JTAG Test Reset
			1 – Enables voltage regulator at all times
FPGAGOOD	1	Out	Indicator that the FPGA is powered and functional
			No need to connect if it is not used.
			1 – Indicates that the FPGA is powered up and functional.
			0 – Not possible to read by FPGA since it has already powered off.
PUCORE	1	Out	Power-Up Core
			Inverted signal of PUB. No need to connect if it is not used.
VREN*	1	Out	Voltage Regulator Enable
			Connected to 1.5 V voltage regulator in Fusion device internally.
			0 – Voltage regulator disables
			1 – Voltage regulator enables
Note: *Signals a	re hard	wired interr	ally and do not exist in the macro core.

Read Next Operation

The Read Next operation is a feature by which the next block relative to the block in the Block Buffer is read from the FB Array while performing reads from the Block Buffer. The goal is to minimize wait states during consecutive sequential Read operations.

The Read Next operation is performed in a predetermined manner because it does look-ahead reads. The general look-ahead function is as follows:

- Within a page, the next block fetched will be the next in linear address.
- When reading the last data block of a page, it will fetch the first block of the next page.
- When reading spare pages, it will read the first block of the next sector's spare page.
- Reads of the last sector will wrap around to sector 0.
- · Reads of Auxiliary blocks will read the next linear page's Auxiliary block.

When an address on the ADDR input does not agree with the predetermined look-ahead address, there is a time penalty for this access. The FB will be busy finishing the current look-ahead read before it can start the next read. The worst case is a total of nine BUSY cycles before data is delivered.

The Non-Pipe Mode and Pipe Mode waveforms for Read Next operations are illustrated in Figure 2-40 and Figure 2-41.



Figure 2-40 • Read Next Waveform (Non-Pipe Mode, 32-bit access)



Figure 2-41 • Read Next WaveForm (Pipe Mode, 32-bit access)

Table 2-36 describes each pin in the Analog Block. Each function within the Analog Block will be explained in detail in the following sections.

Table 2-36 • Analog Block Pin Description

Signal Name	Number of Bits	Direction	Function	Location of Details
VAREF	1	Input/Output	Voltage reference for ADC	ADC
ADCGNDREF	1	Input	External ground reference	ADC
MODE[3:0]	4	Input	ADC operating mode	ADC
SYSCLK	1	Input	External system clock	
TVC[7:0]	8	Input	Clock divide control	ADC
STC[7:0]	8	Input	Sample time control	ADC
ADCSTART	1	Input	Start of conversion	ADC
PWRDWN	1	Input	ADC comparator power-down if 1. When asserted, the ADC will stop functioning, and the digital portion of the analog block will continue operating. This may result in invalid status flags from the analog block. Therefore, Microsemi does not recommend asserting the PWRDWN pin.	ADC
ADCRESET	1	Input	ADC resets and disables Analog Quad – active high	ADC
BUSY	1	Output	1 – Running conversion	ADC
CALIBRATE	1	Output	1 – Power-up calibration	ADC
DATAVALID	1	Output	1 – Valid conversion result	ADC
RESULT[11:0]	12	Output	Conversion result	ADC
TMSTBINT	1	Input	Internal temp. monitor strobe	ADC
SAMPLE	1	Output	 1 – An analog signal is actively being sampled (stays high during signal acquisition only) 0 – No analog signal is being sampled 	ADC
VAREFSEL	1	Input	0 = Output internal voltage reference (2.56 V) to VAREF 1 = Input external voltage reference	ADC
	_		from VAREF and ADCGNDREF	
CHNUMBER[4:0]	5	Input	Analog input channel select	Input multiplexer
ACMCLK	1	Input	ACM clock	ACM
ACMWEN	1	Input	ACM write enable – active high	ACM
ACMRESET	1	Input	ACM reset – active low	ACM
ACMWDATA[7:0]	8	Input	ACM write data	ACM
ACMRDATA[7:0]	8	Output	ACM read data	ACM
ACMADDR[7:0]	8	Input	ACM address	ACM
CMSTB0 to CMSTB9	10	Input	Current monitor strobe – 1 per quad, active high	Analog Quad





Figure 2-73 • Negative Current Monitor

Terminology

Accuracy

The accuracy of Fusion Current Monitor is $\pm 2 \text{ mV}$ minimum plus 5% of the differential voltage at the input. The input accuracy can be translated to error at the ADC output by using EQ 4. The 10 V/V gain is the gain of the Current Monitor Circuit, as described in the "Current Monitor" section on page 2-86. For 8-bit mode, N = 8, $V_{AREF} = 2.56$ V, zero differential voltage between AV and AC, the Error (E_{ADC}) is equal to 2 LSBs.

$$E_{ADC} = (2mV + 0.05 |V_{AV} - V_{AC}|) \times (10V) / V \times \frac{2^{N}}{V_{AREF}}$$

EQ 4

where

N is the number of bits

 V_{AREF} is the Reference voltage

 V_{AV} is the voltage at AV pad

V_{AC} is the voltage at AC pad

INL – Integral Non-Linearity

INL is the deviation of an actual transfer function from a straight line. After nullifying offset and gain errors, the straight line is either a best-fit straight line or a line drawn between the end points of the transfer function (Figure 2-85).



Figure 2-85 • Integral Non-Linearity (INL)

LSB – Least Significant Bit

In a binary number, the LSB is the least weighted bit in the group. Typically, the LSB is the furthest right bit. For an ADC, the weight of an LSB equals the full-scale voltage range of the converter divided by 2^N , where N is the converter's resolution.

EQ 13 shows the calculation for a 10-bit ADC with a unipolar full-scale voltage of 2.56 V:

EQ 13

No Missing Codes

An ADC has no missing codes if it produces all possible digital codes in response to a ramp signal applied to the analog input.



Integrated Voltage Reference

The Fusion device has an integrated on-chip 2.56 V reference voltage for the ADC. The value of this reference voltage was chosen to make the prescaling and postscaling factors for the prescaler blocks change in a binary fashion. However, if desired, an external reference voltage of up to 3.3 V can be connected between the VAREF and ADCGNDREF pins. The VAREFSEL control pin is used to select the reference voltage.

Table 2-42 • VAREF Bit Function

Name	Bit	Function
VAREF	0	Reference voltage selection
		0 – Internal voltage reference selected. VAREF pin outputs 2.56 V.
		1 – Input external voltage reference from VAREF and ADCGNDREF

ADC Clock

The speed of the ADC depends on its internal clock, ADCCLK, which is not accessible to users. The ADCCLK is derived from SYSCLK. Input signal TVC[7:0], Time Divider Control, determines the speed of the ADCCLK in relationship to SYSCLK, based on EQ 15.

$$t_{ADCCLK} = 4 \times (1 + TVC) \times t_{SYSCLK}$$

EQ 15

TVC: Time Divider Control (0-255)

 t_{ADCCLK} is the period of ADCCLK, and must be between 0.5 MHz and 10 MHz t_{SYSCLK} is the period of SYSCLK

Table 2-43 • TVC Bits Function

Name	Bits	Function
TVC	[7:0]	SYSCLK divider control

The frequency of ADCCLK, f_{ADCCLK}, must be within 0.5 Hz to 10 MHz.

The inputs to the ADC are synchronized to SYSCLK. A conversion is initiated by asserting the ADCSTART signal on a rising edge of SYSCLK. Figure 2-90 on page 2-112 and Figure 2-91 on page 2-112 show the timing diagram for the ADC.

Acquisition Time or Sample Time Control

Acquisition time (t_{SAMPLE}) specifies how long an analog input signal has to charge the internal capacitor array. Figure 2-88 shows a simplified internal input sampling mechanism of a SAR ADC.



Figure 2-88 • Simplified Sample and Hold Circuitry

The internal impedance (Z_{INAD}), external source resistance (R_{SOURCE}), and sample capacitor (C_{INAD}) form a simple RC network. As a result, the accuracy of the ADC can be affected if the ADC is given insufficient time to charge the capacitor. To resolve this problem, you can either reduce the source resistance or increase the sampling time by changing the acquisition time using the STC signal.



Table 2-49 • Analog Channel Specifications (continued)

Commercial Temperature Range Conditions, $T_J = 85^{\circ}C$ (unless noted otherwise), Typical: VCC33A = 3.3 V, VCC = 1.5 V

Parameter	Description	Condition	Min.	Тур.	Max.	Units
Digital Input usi	ing Analog Pads AV, AC	and AT		1 1		
VIND ^{2,3}	Input Voltage	Refer to Table 3-2 on page 3-3				
VHYSDIN	Hysteresis			0.3		V
VIHDIN	Input High			1.2		V
VILDIN	Input Low			0.9		V
VMPWDIN	Minimum Pulse With		50			ns
F _{DIN}	Maximum Frequency				10	MHz
ISTBDIN	Input Leakage Current			2		μA
IDYNDIN	Dynamic Current			20		μA
t _{INDIN}	Input Delay			10		ns
Gate Driver Out	put Using Analog Pad A	G	•			
VG	Voltage Range	Refer to Table 3-2 on page 3-3				
IG	Output Current Drive	High Current Mode ⁶ at 1.0 V			±20	mA
		Low Current Mode: ±1 µA	0.8	1.0	1.3	μA
		Low Current Mode: ±3 µA	2.0	2.7	3.3	μA
		Low Current Mode: ± 10 µA	7.4	9.0	11.5	μA
		Low Current Mode: ± 30 µA	21.0	27.0	32.0	μA
IOFFG	Maximum Off Current				100	nA
F _G	Maximum switching rate	High Current Mode ⁶ at 1.0 V, 1 k Ω resistive load		1.3		MHz
		Low Current Mode: ±1 μA, 3 MΩ resistive load		3		KHz
		Low Current Mode: ±3 μA, 1 MΩ resistive load		7		KHz
		Low Current Mode: $\pm 10 \ \mu$ A, 300 k Ω resistive load		25		KHz
		Low Current Mode: $\pm 30 \ \mu$ A, 105 k Ω resistive load		78		KHz

Notes:

1. VRSM is the maximum voltage drop across the current sense resistor.

2. Analog inputs used as digital inputs can tolerate the same voltage limits as the corresponding analog pad. There is no reliability concern on digital inputs as long as VIND does not exceed these limits.

3. VIND is limited to VCC33A + 0.2 to allow reaching 10 MHz input frequency.

4. An averaging of 1,024 samples (LPF setting in Analog System Builder) is required and the maximum capacitance allowed across the AT pins is 500 pF.

- 5. The temperature offset is a fixed positive value.
- 6. The high current mode has a maximum power limit of 20 mW. Appropriate current limit resistors must be used, based on voltage on the pad.
- 7. When using SmartGen Analog System Builder, CalibIP is required to obtain specified offset. For further details on CalibIP, refer to the "Temperature, Voltage, and Current Calibration in Fusion FPGAs" chapter of the Fusion FPGA Fabric User Guide.





Figure 2-116 • Input Buffer Timing Model and Delays (example)

Fusion Family of Mixed Signal FPGAs

Table 2-98 • I/O Short Currents IOSH/IOSL

	Drive Strength	IOSH (mA)*	IOSL (mA)*
Applicable to Pro I/O Banks			
3.3 V LVTTL / 3.3 V LVCMOS	4 mA	25	27
	8 mA	51	54
	12 mA	103	109
	16 mA	132	127
	24 mA	268	181
2.5 V LVCMOS	4 mA	16	18
	8 mA	32	37
	12 mA	65	74
	16 mA	83	87
	24 mA	169	124
1.8 V LVCMOS	2 mA	9	11
	4 mA	17	22
	6 mA	35	44
	8 mA	45	51
	12 mA	91	74
	16 mA	91	74
1.5 V LVCMOS	2 mA	13	16
	4 mA	25	33
	6 mA	32	39
	8 mA	66	55
	12 mA	66	55
Applicable to Advanced I/O Banks			
3.3 V LVTTL / 3.3 V LVCMOS	2 mA	25	27
	4 mA	25	27
	6 mA	51	54
	8 mA	51	54
	12 mA	103	109
	16 mA	132	127
	24 mA	268	181
3.3 V LVCMOS	2 mA	25	27
	4 mA	25	27
	6 mA	51	54
	8 mA	51	54
	12 mA	103	109
	16 mA	132	127
	24 mA	268	181

Note: $^{*}T_{J} = 100^{\circ}C$



Single-Ended I/O Characteristics

3.3 V LVTTL / 3.3 V LVCMOS

Low-Voltage Transistor–Transistor Logic is a general-purpose standard (EIA/JESD) for 3.3 V applications. It uses an LVTTL input buffer and push-pull output buffer. The 3.3 V LVCMOS standard is supported as part of the 3.3 V LVTTL support.

Table 2-102	• Minimum	and Maximum	DC Input	and Output	l evels
10016 2-102	• Willing the second		DO inpui	and Output	. LEVEIJ

3.3 V LVTTL / 3.3 V LVCMOS	v	IL	v	ін	VOL	νон	IOL	ЮН	IOSL	IOSH	IIL ¹	IIH ²
Drive Strength	Min. V	Max. V	Min. V	Max. V	Max. V	Min. V	mA	mA	Max. mA ³	Max. mA ³	μA ⁴	μA ⁴
Applicable to P	ro I/O Ba	nks					•				•	
4 mA	-0.3	0.8	2	3.6	0.4	2.4	4	4	27	25	10	10
8 mA	-0.3	0.8	2	3.6	0.4	2.4	8	8	54	51	10	10
12 mA	-0.3	0.8	2	3.6	0.4	2.4	12	12	109	103	10	10
16 mA	-0.3	0.8	2	3.6	0.4	2.4	16	16	127	132	10	10
24 mA	-0.3	0.8	2	3.6	0.4	2.4	24	24	181	268	10	10
Applicable to A	dvanced	I/O Bank	s									
2 mA	-0.3	0.8	2	3.6	0.4	2.4	2	2	27	25	10	10
4 mA	-0.3	0.8	2	3.6	0.4	2.4	4	4	27	25	10	10
6 mA	-0.3	0.8	2	3.6	0.4	2.4	6	6	54	51	10	10
8 mA	-0.3	0.8	2	3.6	0.4	2.4	8	8	54	51	10	10
12 mA	-0.3	0.8	2	3.6	0.4	2.4	12	12	109	103	10	10
16 mA	-0.3	0.8	2	3.6	0.4	2.4	16	16	127	132	10	10
24 mA	-0.3	0.8	2	3.6	0.4	2.4	24	24	181	268	10	10
Applicable to S	tandard I	/O Banks										
2 mA	-0.3	0.8	2	3.6	0.4	2.4	2	2	27	25	10	10
4 mA	-0.3	0.8	2	3.6	0.4	2.4	4	4	27	25	10	10
6 mA	-0.3	0.8	2	3.6	0.4	2.4	6	6	54	51	10	10
8 mA	-0.3	0.8	2	3.6	0.4	2.4	8	8	54	51	10	10

Notes:

1. IIL is the input leakage current per I/O pin over recommended operation conditions where –0.3 V < VIN < VIL.

2. IIH is the input leakage current per I/O pin over recommended operating conditions VIH < VIN < VCCI. Input current is larger when operating outside recommended ranges.

3. Currents are measured at high temperature (100°C junction temperature) and maximum voltage.

4. Currents are measured at 85°C junction temperature.

5. Software default selection highlighted in gray.



Figure 2-119 • AC Loading



3.3 V GTL+

Gunning Transceiver Logic Plus is a high-speed bus standard (JESD8-3). It provides a differential amplifier input buffer and an open-drain output buffer. The VCCI pin should be connected to 3.3 V.

Table 2-144 • Minimum and Maximum DC Input and Output Levels

3.3 V GTL+		VIL	VIH		VOL	VOH	IOL	ЮН	IOSL	IOSH	IIL¹	IIH ²
Drive Strength	Min. V	Max. V	Min. V	Max. V	Max. V	Min. V	mA	mA	Max. mA ³	Max. mA ³	μA ⁴	μA ⁴
35 mA	-0.3	VREF – 0.1	VREF + 0.1	3.6	0.6	-	35	35	181	268	10	10

Notes:

1. IIL is the input leakage current per I/O pin over recommended operation conditions where –0.3 V < VIN < VIL.

2. IIH is the input leakage current per I/O pin over recommended operating conditions VIH < VIN < VCCI. Input current is larger when operating outside recommended ranges.

3. Currents are measured at high temperature (100°C junction temperature) and maximum voltage.

4. Currents are measured at 85°C junction temperature.



Figure 2-126 • AC Loading

Table	2-145	AC Wavef	orms. Meas	suring Poin	ts, and Ca	pacitive Loads
i ubic	2-140		ormo, mous	ournig i oni	its, and ou	

Input Low (V)	Input High (V)	Measuring Point* (V)	VREF (typ.) (V)	VTT (typ.) (V)	C _{LOAD} (pF)
VREF – 0.1	VREF + 0.1	1.0	1.0	1.5	10

Note: *Measuring point = Vtrip. See Table 2-90 on page 2-166 for a complete table of trip points.

Timing Characteristics

Table 2-146 • 3.3 V GTL+

Commercial Temperature Range Conditions: T_J = 70°C, Worst-Case VCC = 1.425 V, Worst-Case VCCI = 3.0 V, VREF = 1.0 V

Speed Grade	t _{DOUT}	t _{DP}	t _{DIN}	t _{PY}	t _{EOUT}	t _{ZL}	t _{zH}	t _{LZ}	t _{HZ}	t _{ZLS}	t _{zHS}	Units
Std.	0.66	2.06	0.04	1.59	0.43	2.09	2.06			4.33	4.29	ns
-1	0.56	1.75	0.04	1.35	0.36	1.78	1.75			3.68	3.65	ns
-2	0.49	1.53	0.03	1.19	0.32	1.56	1.53			3.23	3.20	ns

Note: For the derating values at specific junction temperature and voltage supply levels, refer to Table 3-7 on page 3-9.

SSTL3 Class II

Stub-Speed Terminated Logic for 3.3 V memory bus standard (JESD8-8). Fusion devices support Class II. This provides a differential amplifier input buffer and a push-pull output buffer.

SSTL3 Class II	VIL		VIH		VOL	VOH	IOL	IOH	IOSL	IOSH	IIL ¹	IIH ²
Drive Strength	Min. V	Max. V	Min. V	Max. V	Max. V	Min. V	mA	mA	Max. mA ³	Max. mA ³	μA ⁴	μA ⁴
21 mA	-0.3	VREF – 0.2	VREF + 0.2	3.6	0.5	VCCI – 0.9	21	21	109	103	10	10

Table 2-165 • Minimum and Maximum DC Input and Output Levels

Notes:

1. IIL is the input leakage current per I/O pin over recommended operation conditions where –0.3 V < VIN < VIL.

2. IIH is the input leakage current per I/O pin over recommended operating conditions VIH < VIN < VCCI. Input current is larger when operating outside recommended ranges.

3. Currents are measured at high temperature (100°C junction temperature) and maximum voltage.

4. Currents are measured at 85°C junction temperature.



Figure 2-133 • AC Loading

Table 2-166 • AC Waveforms, Measuring Points, and Capacitive Loads

Input Low (V)	Input High (V)	Measuring Point* (V)	VREF (typ.) (V)	VTT (typ.) (V)	C _{LOAD} (pF)
VREF – 0.2	VREF + 0.2	1.5	1.5	1.485	30

Note: *Measuring point = Vtrip. See Table 2-90 on page 2-166 for a complete table of trip points.

Timing Characteristics

Table 2-167 • SSTL3- Class II Commercial Temperature Range Conditions: T_J = 70°C, Worst-Case VCC = 1.425 V, Worst-Case VCCI = 3.0 V, VREF = 1.5 V

Speed Grade	t _{DOUT}	t _{DP}	t _{DIN}	t _{PY}	t _{EOUT}	t _{ZL}	t _{zH}	t _{LZ}	t _{HZ}	t _{ZLS}	t _{zHS}	Units
Std.	0.66	2.07	0.04	1.25	0.43	2.10	1.67			4.34	3.91	ns
-1	0.56	1.76	0.04	1.06	0.36	1.79	1.42			3.69	3.32	ns
-2	0.49	1.54	0.03	0.93	0.32	1.57	1.25			3.24	2.92	ns

Note: For the derating values at specific junction temperature and voltage supply levels, refer to Table 3-7 on page 3-9.



Table 2-174 • Parameter Definitions and Measuring Nodes

Parameter Name	Parameter Definition	Measuring Nodes (from, to)*
t _{OCLKQ}	Clock-to-Q of the Output Data Register	H, DOUT
tosud	Data Setup Time for the Output Data Register	F, H
t _{OHD}	Data Hold Time for the Output Data Register	F, H
t _{OSUE}	Enable Setup Time for the Output Data Register	G, H
t _{OHE}	Enable Hold Time for the Output Data Register	G, H
t _{OPRE2Q}	Asynchronous Preset-to-Q of the Output Data Register	L,DOUT
t _{OREMPRE}	Asynchronous Preset Removal Time for the Output Data Register	L, H
t _{ORECPRE}	Asynchronous Preset Recovery Time for the Output Data Register	L, H
t _{OECLKQ}	Clock-to-Q of the Output Enable Register	H, EOUT
t _{OESUD}	Data Setup Time for the Output Enable Register	J, H
t _{OEHD}	Data Hold Time for the Output Enable Register	J, H
t _{OESUE}	Enable Setup Time for the Output Enable Register	K, H
t _{OEHE}	Enable Hold Time for the Output Enable Register	K, H
t _{OEPRE2Q}	Asynchronous Preset-to-Q of the Output Enable Register	I, EOUT
t _{OEREMPRE}	Asynchronous Preset Removal Time for the Output Enable Register	I, H
t _{OERECPRE}	Asynchronous Preset Recovery Time for the Output Enable Register	I, H
t _{ICLKQ}	Clock-to-Q of the Input Data Register	A, E
t _{ISUD}	Data Setup Time for the Input Data Register	C, A
t _{IHD}	Data Hold Time for the Input Data Register	C, A
t _{ISUE}	Enable Setup Time for the Input Data Register	B, A
t _{IHE}	Enable Hold Time for the Input Data Register	B, A
t _{IPRE2Q}	Asynchronous Preset-to-Q of the Input Data Register	D, E
t _{IREMPRE}	Asynchronous Preset Removal Time for the Input Data Register	D, A
t _{IRECPRE}	Asynchronous Preset Recovery Time for the Input Data Register	D, A

Note: *See Figure 2-137 on page 2-212 for more information.



Pin Descriptions

Supply Pins

GND Ground

Ground supply voltage to the core, I/O outputs, and I/O logic.

GNDQ Ground (quiet)

Quiet ground supply voltage to input buffers of I/O banks. Within the package, the GNDQ plane is decoupled from the simultaneous switching noise originated from the output buffer ground domain. This minimizes the noise transfer within the package and improves input signal integrity. GNDQ needs to always be connected on the board to GND. Note: In FG256, FG484, and FG676 packages, GNDQ and GND pins are connected within the package and are labeled as GND pins in the respective package pin assignment tables.

ADCGNDREF Analog Reference Ground

Analog ground reference used by the ADC. This pad should be connected to a quiet analog ground.

GNDA Ground (analog)

Quiet ground supply voltage to the Analog Block of Fusion devices. The use of a separate analog ground helps isolate the analog functionality of the Fusion device from any digital switching noise. A 0.2 V maximum differential voltage between GND and GNDA/GNDQ should apply to system implementation.

GNDAQ Ground (analog quiet)

Quiet ground supply voltage to the analog I/O of Fusion devices. The use of a separate analog ground helps isolate the analog functionality of the Fusion device from any digital switching noise. A 0.2 V maximum differential voltage between GND and GNDA/GNDQ should apply to system implementation. Note: In FG256, FG484, and FG676 packages, GNDAQ and GNDA pins are connected within the package and are labeled as GNDA pins in the respective package pin assignment tables.

GNDNVM Flash Memory Ground

Ground supply used by the Fusion device's flash memory block module(s).

GNDOSC Oscillator Ground

Ground supply for both integrated RC oscillator and crystal oscillator circuit.

VCC15A Analog Power Supply (1.5 V)

1.5 V clean analog power supply input for use by the 1.5 V portion of the analog circuitry.

VCC33A Analog Power Supply (3.3 V)

3.3 V clean analog power supply input for use by the 3.3 V portion of the analog circuitry.

VCC33N Negative 3.3 V Output

This is the -3.3 V output from the voltage converter. A 2.2 μ F capacitor must be connected from this pin to ground.

VCC33PMP Analog Power Supply (3.3 V)

3.3 V clean analog power supply input for use by the analog charge pump. To avoid high current draw, VCC33PMP should be powered up simultaneously with or after VCC33A.

VCCNVM Flash Memory Block Power Supply (1.5 V)

1.5 V power supply input used by the Fusion device's flash memory block module(s). To avoid high current draw, VCC should be powered up before or simultaneously with VCCNVM.

VCCOSC Oscillator Power Supply (3.3 V)

Power supply for both integrated RC oscillator and crystal oscillator circuit. The internal 100 MHz oscillator, powered by the VCCOSC pin, is needed for device programming, operation of the VDDN33 pump, and eNVM operation. VCCOSC is off only when VCCA is off. VCCOSC must be powered whenever the Fusion device needs to function.



Table 3-13 • Summary of I/O Output Buffer Power (per pin)—Default I/O Software Settings¹ (continued)

	C _{LOAD} (pF)	VCCI (V)	Static Power PDC8 (mW) ²	Dynamic Power PAC10 (µW/MHz) ³
Differential				•
LVDS	-	2.5	7.74	88.92
LVPECL	_	3.3	19.54	166.52
Applicable to Standard I/O Bank	S			
Single-Ended				
3.3 V LVTTL / 3.3 V LVCMOS	35	3.3	-	431.08
2.5 V LVCMOS	35	2.5	-	247.36
1.8 V LVCMOS	35	1.8	-	128.46
1.5 V LVCMOS (JESD8-11)	35	1.5	-	89.46

Notes:

1. Dynamic power consumption is given for standard load and software-default drive strength and output slew.

2. PDC8 is the static power (where applicable) measured on VCCI.

3. PAC10 is the total dynamic power measured on VCC and VCCI.



Package Pin Assignments

	QN180		QN180					
Pin Number	AFS090 Function	AFS250 Function	Pin Number	AFS090 Function	AFS250 Function			
A1	GNDQ	GNDQ	A37	VPUMP	VPUMP			
A2	VCCIB3	VCCIB3	A38	TDI	TDI			
A3	GAB2/IO52NDB3V0	IO74NDB3V0	A39	TDO	TDO			
A4	GFA2/IO51NDB3V0	IO71NDB3V0	A40	VJTAG	VJTAG			
A5	GFC2/IO50NDB3V0	IO69NPB3V0	A41	GDB1/IO39PPB1V0	GDA1/IO54PPB1V0			
A6	VCCIB3	VCCIB3	A42	GDC1/IO38PDB1V0	GDB1/IO53PDB1V0			
A7	GFA1/IO47PPB3V0	GFB1/IO67PPB3V0	A43	VCC	VCC			
A8	GEB0/IO45NDB3V0	NC	A44	GCB0/IO35NPB1V0	GCB0/IO48NPB1V0			
A9	XTAL1	XTAL1	A45	GCC1/IO34PDB1V0	GCC1/IO47PDB1V0			
A10	GNDOSC	GNDOSC	A46	VCCIB1	VCCIB1			
A11	GEC2/IO43PPB3V0	GEA1/IO61PPB3V0	A47	GBC2/IO32PPB1V0	GBB2/IO41PPB1V0			
A12	IO43NPB3V0	GEA0/IO61NPB3V0	A48	VCCIB1	VCCIB1			
A13	NC	VCCIB3	A49	NC	NC			
A14	GNDNVM	GNDNVM	A50	GBA0/IO29RSB0V0	GBB1/IO37RSB0V0			
A15	PCAP	PCAP	A51	VCCIB0	VCCIB0			
A16	VCC33PMP	VCC33PMP	A52	GBB0/IO27RSB0V0	GBC0/IO34RSB0V0			
A17	NC	NC	A53	GBC1/IO26RSB0V0	IO33RSB0V0			
A18	AV0	AV0	A54	IO24RSB0V0	IO29RSB0V0			
A19	AG0	AG0	A55	IO21RSB0V0	IO26RSB0V0			
A20	ATRTN0	ATRTN0	A56	VCCIB0	VCCIB0			
A21	AG1	AG1	A57	IO15RSB0V0	IO21RSB0V0			
A22	AC1	AC1	A58	IO10RSB0V0	IO13RSB0V0			
A23	AV2	AV2	A59	IO07RSB0V0	IO10RSB0V0			
A24	AT2	AT2	A60	GAC0/IO04RSB0V0	IO06RSB0V0			
A25	AT3	AT3	A61	GAB1/IO03RSB0V0	GAC1/IO05RSB0V0			
A26	AC3	AC3	A62	VCC	VCC			
A27	AV4	AV4	A63	GAA1/IO01RSB0V0	GAB0/IO02RSB0V0			
A28	AC4	AC4	A64	NC	NC			
A29	AT4	AT4	B1	VCOMPLA	VCOMPLA			
A30	NC	AG5	B2	GAA2/IO52PDB3V0	GAC2/IO74PDB3V0			
A31	NC	AV5	B3	GAC2/IO51PDB3V0	GFA2/IO71PDB3V0			
A32	ADCGNDREF	ADCGNDREF	B4	GFB2/IO50PDB3V0	GFB2/IO70PSB3V0			
A33	VCC33A	VCC33A	B5	VCC	VCC			
A34	GNDA	GNDA	B6	GFC0/IO49NDB3V0	GFC0/IO68NDB3V0			
A35	PTBASE	PTBASE	B7	GEB1/IO45PDB3V0	NC			
A36	VCCNVM	VCCNVM	B8	VCCOSC	VCCOSC			



Package Pin Assignments

	FG484		FG484				
Pin Number	AFS600 Function	AFS1500 Function	Pin Number	AFS600 Function	AFS1500 Function		
L17	VCCIB2	VCCIB2	N8	GND	GND		
L18	IO46PDB2V0	IO69PDB2V0	N9	GND	GND		
L19	GCA1/IO45PDB2V0	GCA1/IO64PDB2V0	N10	VCC	VCC		
L20	VCCIB2	VCCIB2	N11	GND	GND		
L21	GCC0/IO43NDB2V0	GCC0/IO62NDB2V0	N12	VCC	VCC		
L22	GCC1/IO43PDB2V0	GCC1/IO62PDB2V0	N13	GND	GND		
M1	NC	IO103PDB4V0	N14	VCC	VCC		
M2	XTAL1	XTAL1	N15	GND	GND		
M3	VCCIB4	VCCIB4	N16	GDB2/IO56PDB2V0	GDB2/IO83PDB2V0		
M4	GNDOSC	GNDOSC	N17	NC	IO78PDB2V0		
M5	GFC0/IO72NDB4V0	GFC0/IO107NDB4V0	N18	GND	GND		
M6	VCCIB4	VCCIB4	N19	IO47NDB2V0	IO72NDB2V0		
M7	GFB0/IO71NDB4V0	GFB0/IO106NDB4V0	N20	IO47PDB2V0	IO72PDB2V0		
M8	VCCIB4	VCCIB4	N21	GND	GND		
M9	VCC	VCC	N22	IO49PDB2V0	IO71PDB2V0		
M10	GND	GND	P1	GFA1/IO70PDB4V0	GFA1/IO105PDB4V0		
M11	VCC	VCC	P2	GFA0/IO70NDB4V0	GFA0/IO105NDB4V0		
M12	GND	GND	P3	IO68NDB4V0	IO101NDB4V0		
M13	VCC	VCC	P4	IO65PDB4V0	IO96PDB4V0		
M14	GND	GND	P5	IO65NDB4V0	IO96NDB4V0		
M15	VCCIB2	VCCIB2	P6	NC	IO99NDB4V0		
M16	IO48NDB2V0	IO70NDB2V0	P7	NC	IO97NDB4V0		
M17	VCCIB2	VCCIB2	P8	VCCIB4	VCCIB4		
M18	IO46NDB2V0	IO69NDB2V0	P9	VCC	VCC		
M19	GCA0/IO45NDB2V0	GCA0/IO64NDB2V0	P10	GND	GND		
M20	VCCIB2	VCCIB2	P11	VCC	VCC		
M21	GCB0/IO44NDB2V0	GCB0/IO63NDB2V0	P12	GND	GND		
M22	GCB1/IO44PDB2V0	GCB1/IO63PDB2V0	P13	VCC	VCC		
N1	NC	IO103NDB4V0	P14	GND	GND		
N2	GND	GND	P15	VCCIB2	VCCIB2		
N3	IO68PDB4V0	IO101PDB4V0	P16	IO56NDB2V0	IO83NDB2V0		
N4	NC	IO100NPB4V0	P17	NC	IO78NDB2V0		
N5	GND	GND	P18	GDA1/IO54PDB2V0	GDA1/IO81PDB2V0		
N6	NC	IO99PDB4V0	P19	GDB1/IO53PDB2V0	GDB1/IO80PDB2V0		
N7	NC	IO97PDB4V0	P20	IO51NDB2V0	IO73NDB2V0		