Microchip Technology - M1AFS600-FGG256 Datasheet

Welcome to E-XFL.COM

Understanding Embedded - FPGAs (Field Programmable Gate Array)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications,

Details	
Product Status	Active
Number of LABs/CLBs	-
Number of Logic Elements/Cells	-
Total RAM Bits	110592
Number of I/O	119
Number of Gates	600000
Voltage - Supply	1.425V ~ 1.575V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 85°C (TJ)
Package / Case	256-LBGA
Supplier Device Package	256-FPBGA (17x17)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/m1afs600-fgg256

Clock Aggregation

Clock aggregation allows for multi-spine clock domains. A MUX tree provides the necessary flexibility to allow long lines or I/Os to access domains of one, two, or four global spines. Signal access to the clock aggregation system is achieved through long-line resources in the central rib, and also through local resources in the north and south ribs, allowing I/Os to feed directly into the clock system. As Figure 2-14 indicates, this access system is contiguous.

There is no break in the middle of the chip for north and south I/O VersaNet access. This is different from the quadrant clocks, located in these ribs, which only reach the middle of the rib. Refer to the *Using Global Resources in Actel Fusion Devices* application note.

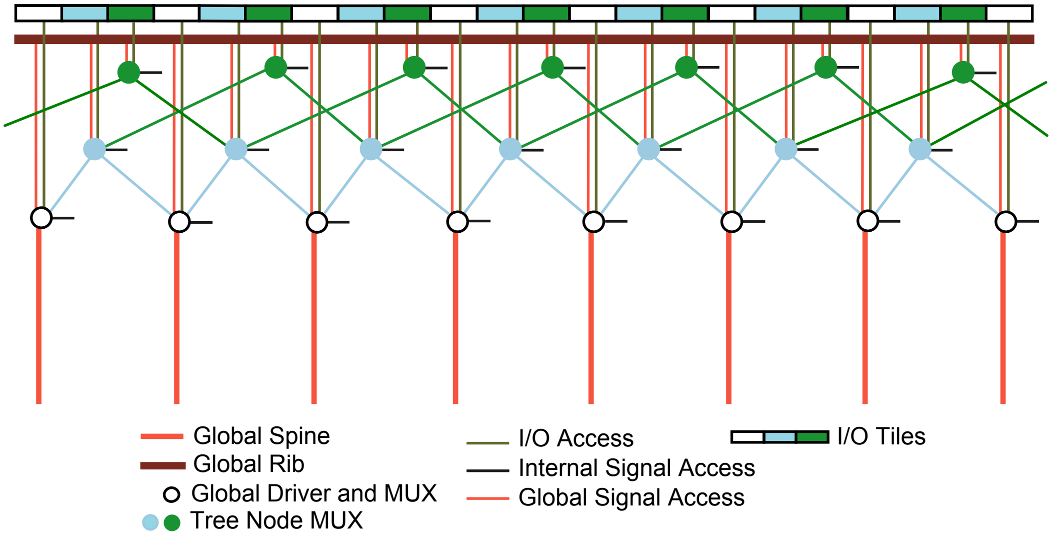


***Figure 2-14* • Clock Aggregation Tree Architecture**

Global Resource Characteristics

AFS600 VersaNet Topology

Clock delays are device-specific. Figure 2-15 is an example of a global tree used for clock routing. The global tree presented in Figure 2-15 is driven by a CCC located on the west side of the AFS600 device. It is used to drive all D-flip-flops in the device.

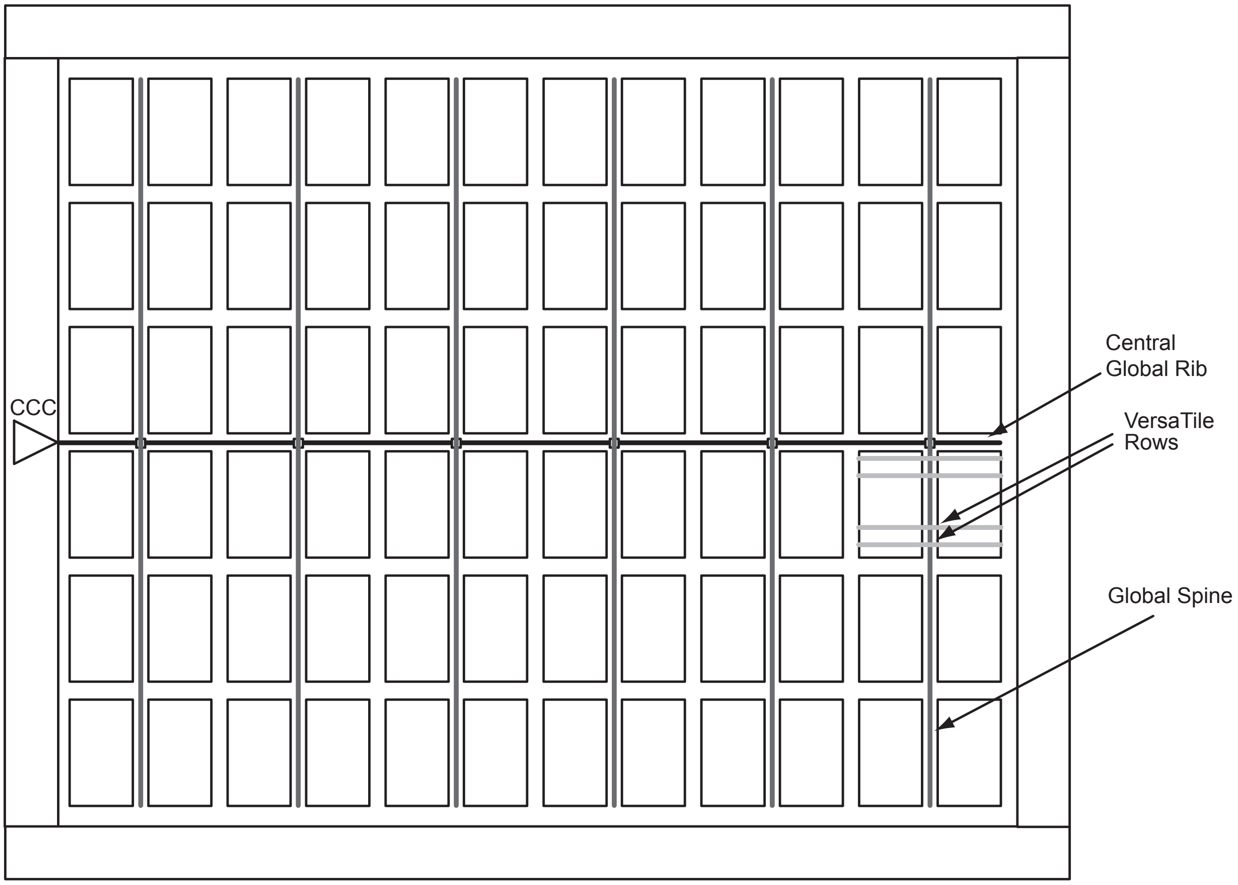


Figure 2-15 • **Example of Global Tree Use in an AFS600 Device for Clock Routing**

Table 2-7 • **AFS250 Global Resource Timing**
Commercial Temperature Range Conditions: T_J = 70°C, Worst-Case VCC = 1.425 V

Parameter	Description	–2		–1		Std.		Units
		Min.[1]	Max.[2]	Min.[1]	Max.[2]	Min.[1]	Max.[2]	
t_{RCKL}	Input Low Delay for Global Clock	0.89	1.12	1.02	1.27	1.20	1.50	ns
t_{RCKH}	Input High Delay for Global Clock	0.88	1.14	1.00	1.30	1.17	1.53	ns
$t_{RCKMPWH}$	Minimum Pulse Width High for Global Clock							ns
$t_{RCKMPWL}$	Minimum Pulse Width Low for Global Clock							ns
t_{RCKSW}	Maximum Skew for Global Clock		0.26		0.30		0.35	ns

Notes:

1. *Value reflects minimum load. The delay is measured from the CCC output to the clock pin of a sequential element located in a lightly loaded row (single element is connected to the global net).*
2. *Value reflects maximum load. The delay is measured on the clock pin of the farthest sequential element located in a fully loaded row (all available flip-flops are connected to the global net in the row).*
3. *For the derating values at specific junction temperature and voltage supply levels, refer to Table 3-7 on page 3-9.*

Table 2-8 • **AFS090 Global Resource Timing**
Commercial Temperature Range Conditions: T_J = 70°C, Worst-Case VCC = 1.425 V

Parameter	Description	–2		–1		Std.		Units
		Min.[1]	Max.[2]	Min.[1]	Max.[2]	Min.[1]	Max.[2]	
t_{RCKL}	Input Low Delay for Global Clock	0.84	1.07	0.96	1.21	1.13	1.43	ns
t_{RCKH}	Input High Delay for Global Clock	0.83	1.10	0.95	1.25	1.12	1.47	ns
$t_{RCKMPWH}$	Minimum Pulse Width High for Global Clock							ns
$t_{RCKMPWL}$	Minimum Pulse Width Low for Global Clock							ns
t_{RCKSW}	Maximum Skew for Global Clock		0.27		0.30		0.36	ns

Notes:

1. *Value reflects minimum load. The delay is measured from the CCC output to the clock pin of a sequential element located in a lightly loaded row (single element is connected to the global net).*
2. *Value reflects maximum load. The delay is measured on the clock pin of the farthest sequential element located in a fully loaded row (all available flip-flops are connected to the global net in the row).*
3. *For the derating values at specific junction temperature and voltage supply levels, refer to Table 3-7 on page 3-9.*

Crystal Oscillator

The Crystal Oscillator (XTLOSC) is source that generates the clock from an external crystal. The output of XTLOSC CLKOUT signal can be selected as an input to the PLL. Refer to the "Clock Conditioning Circuits" section for more details. The XTLOSC can operate in normal operations and Standby mode (RTC is running and 1.5 V is not present).

In normal operation, the internal FPGA_EN signal is '1' as long as 1.5 V is present for VCC. As such, the internal enable signal, XTL_EN, for Crystal Oscillator is enabled since FPGA_EN is asserted. The XTL_MODE has the option of using MODE or RTC_MODE, depending on SELMODE.

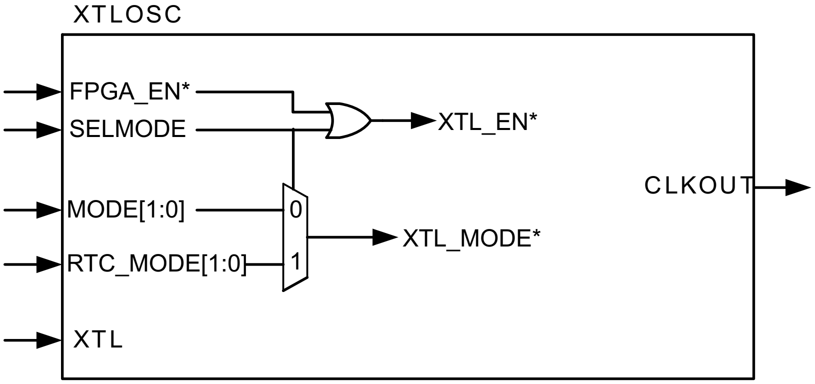
During Standby, 1.5 V is not available, as such, and FPGA_EN is '0'. SELMODE must be asserted in order for XTL_EN to be enabled; hence XTL_MODE relies on RTC_MODE. SELMODE and RTC_MODE must be connected to RTCXTLSEL and RTCXTLMODE from the AB respectively for correct operation during Standby (refer to the "Real-Time Counter System" section on page 2-31 for a detailed description).

The Crystal Oscillator can be configured in one of four modes:

- RC network, 32 KHz to 4 MHz
- Low gain, 32 to 200 KHz
- Medium gain, 0.20 to 2.0 MHz
- High gain, 2.0 to 20.0 MHz

In RC network mode, the XTAL1 pin is connected to an RC circuit, as shown in Figure 2-16 on page 2-18. The XTAL2 pin should be left floating. The RC value can be chosen based on Figure 2-18 for any desired frequency between 32 KHz and 4 MHz. The RC network mode can also accommodate an external clock source on XTAL1 instead of an RC circuit.

In Low gain, Medium gain, and High gain, an external crystal component or ceramic resonator can be added onto XTAL1 and XTAL2, as shown in Figure 2-16 on page 2-18. In the case where the Crystal Oscillator block is not used, the XTAL1 pin should be connected to GND and the XTAL2 pin should be left floating.



Note: **Internal signal—does not exist in macro.*

***Figure 2-17* • XTLOSC Macro**

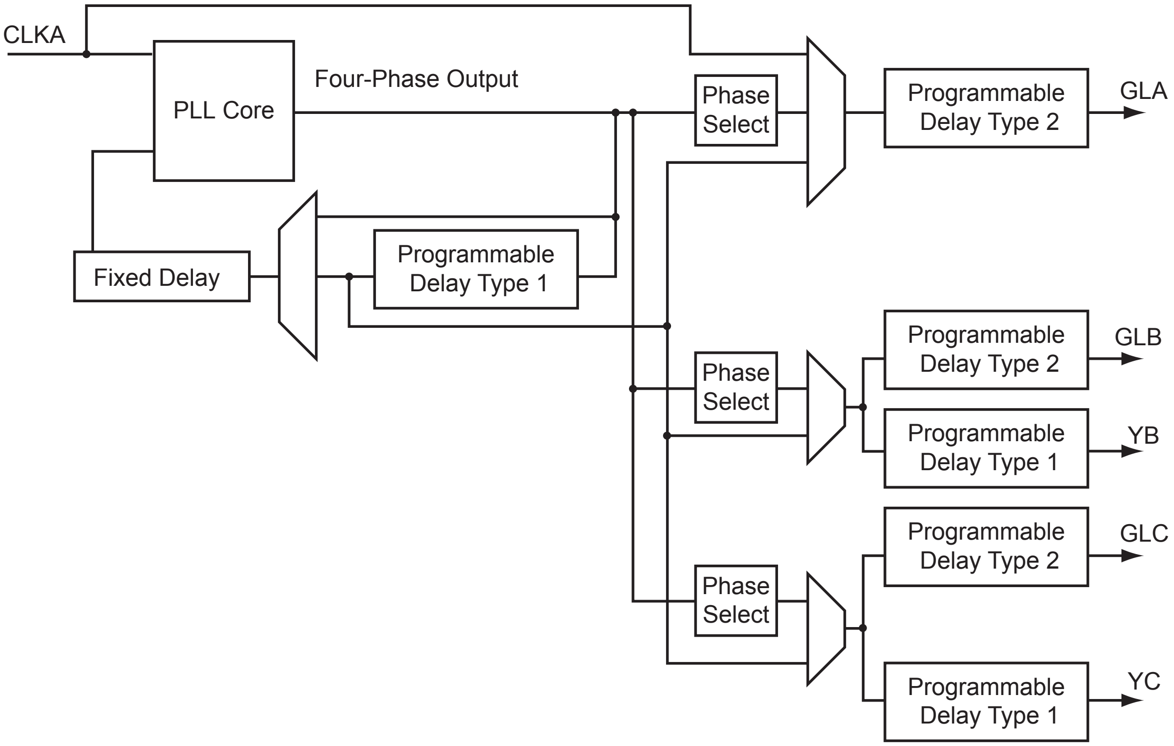
CCC Physical Implementation

The CCC circuit is composed of the following (Figure 2-23):

- PLL core
- 3 phase selectors
- 6 programmable delays and 1 fixed delay
- 5 programmable frequency dividers that provide frequency multiplication/division (not shown in Figure 2-23 because they are automatically configured based on the user's required frequencies)
- 1 dynamic shift register that provides CCC dynamic reconfiguration capability (not shown)

CCC Programming

The CCC block is fully configurable. It is configured via static flash configuration bits in the array, set by the user in the programming bitstream, or configured through an asynchronous dedicated shift register, dynamically accessible from inside the Fusion device. The dedicated shift register permits changes of parameters such as PLL divide ratios and delays during device operation. This latter mode allows the user to dynamically reconfigure the PLL without the need for core programming. The register file is accessed through a simple serial interface.



Note: *Clock divider and multiplier blocks are not shown in this figure or in SmartGen. They are automatically configured based on the user's required frequencies.*

***Figure 2-23* • PLL Block**

CCC and PLL Characteristics

Timing Characteristics

***Table 2-12* • Fusion CCC/PLL Specification**

Parameter		Min.	Typ.	Max.	Unit
Clock Conditioning Circuitry Input Frequency f_{IN_CCC}		1.5		350	MHz
Clock Conditioning Circuitry Output Frequency f_{OUT_CCC}		0.75		350	MHz
Delay Increments in Programmable Delay Blocks[1, 2]			160[3]		ps
Number of Programmable Values in Each Programmable Delay Block				32	
Input Period Jitter				1.5	ns
CCC Output Peak-to-Peak Period Jitter F_{CCC_OUT}		Max Peak-to-Peak Period Jitter			
		1 Global Network Used		3 Global Networks Used	
0.75 MHz to 24 MHz		1.00%		1.00%	
24 MHz to 100 MHz		1.50%		1.50%	
100 MHz to 250 MHz		2.25%		2.25%	
250 MHz to 350 MHz		3.50%		3.50%	
Acquisition Time	LockControl = 0			300	µs
	LockControl = 1			6.0	ms
Tracking Jitter[4]	LockControl = 0			1.6	ns
	LockControl = 1			0.8	ns
Output Duty Cycle		48.5		51.5	%
Delay Range in Block: Programmable Delay 1 [1, 2]		0.6		5.56	ns
Delay Range in Block: Programmable Delay 2 [1, 2]		0.025		5.56	ns
Delay Range in Block: Fixed Delay [1, 2]			2.2		ns

Notes:

1. *This delay is a function of voltage and temperature. See Table 3-7 on page 3-9 for deratings.*
2. *T_J = 25°C, VCC = 1.5 V*
3. *When the CCC/PLL core is generated by Microsemi core generator software, not all delay values of the specified delay increments are available. Refer to the Libero SoC Online Help associated with the core for more information.*
4. *Tracking jitter is defined as the variation in clock edge position of PLL outputs with reference to PLL input clock edge. Tracking jitter does not measure the variation in PLL output period, which is covered by period jitter parameter.*

Example: Calculation for Match Count

To put the Fusion device on standby for one hour using an external crystal of 32.768 KHz:

The period of the crystal oscillator is $T_{crystal}$:

$T_{crystal}$ = 1 / 32.768 KHz = 30.518 µs

The period of the counter is $T_{counter}$:

$T_{counter}$ = 30.518 us X 128 = 3.90625 ms

The Match Count for 1 hour is Δtmatch:

Δtmatch / $T_{counter}$ = (1 hr X 60 min/hr X 60 sec/min) / 3.90625 ms = 921600 or 0xE1000

Using a 32.768 KHz crystal, the maximum standby time of the 40-bit counter is 4,294,967,296 seconds, which is 136 years.

Table 2-15 • **Memory Map for RTC in ACM Register and Description**

ACMADDR	Register Name	Description	Use	Default Value
0x40	COUNTER0	Counter bits 7:0	Used to preload the counter to a specified start point.	0x00
0x41	COUNTER1	Counter bits 15:8		0x00
0x42	COUNTER2	Counter bits 23:16		0x00
0x43	COUNTER3	Counter bits 31:24		0x00
0x44	COUNTER4	Counter bits 39:32		0x00
0x48	MATCHREG0	Match register bits 7:0	The RTC comparison bits	0x00
0x49	MATCHREG1	Match register bits 15:8		0x00
0x4A	MATCHREG2	Match register bits 23:16		0x00
0x4B	MATCHREG3	Match register bits 31:24		0x00
0x4C	MATCHREG4	Match register bits 39:32		0x00
0x50	MATCHBIT0	Individual match bits 7:0	The output of the XNOR gates 0 – Not matched 1 – Matched	0x00
0x51	MATCHBIT1	Individual match bits 15:8		0x00
0x52	MATCHBIT2	Individual match bits 23:16		0x00
0x53	MATCHBIT3	Individual match bits 31:24		0x00
0x54	MATCHBIT4	Individual match bits 29:32		0x00
0x58	CTRL_STAT	Control (write/read) / Status (read only) register bits	Refer to Table 2-16 on page 2-35 for details.	0x00

Data operations are performed in widths of 1 to 4 bytes. A write to a location in a page that is not already in the Page Buffer will cause the page to be read from the FB Array and stored in the Page Buffer. The block that was addressed during the write will be put into the Block Buffer, and the data written by WD will overwrite the data in the Block Buffer. After the data is written to the Block Buffer, the Block Buffer is then written to the Page Buffer to keep both buffers in sync. Subsequent writes to the same block will overwrite the Block Buffer and the Page Buffer. A write to another block in the page will cause the addressed block to be loaded from the Page Buffer, and the write will be performed as described previously.

The data width can be selected dynamically via the DATAWIDTH input bus. The truth table for the data width settings is detailed in Table 2-21. The minimum resolvable address is one 8-bit byte. For data widths greater than 8 bits, the corresponding address bits are ignored—when DATAWIDTH = 0 (2 bytes), ADDR[0] is ignored, and when DATAWIDTH = '10' or '11' (4 bytes), ADDR[1:0] are ignored. Data pins are LSB-oriented and unused WD data pins must be grounded.

***Table 2-21* • Data Width Settings**

DATAWIDTH[1:0]	Data Width
00	1 byte [7:0]
01	2 byte [15:0]
10, 11	4 bytes [31:0]

Flash Memory Block Protection

Page Loss Protection

When the PAGELOSSPROTECT pin is set to logic 1, it prevents writes to any page other than the current page in the Page Buffer until the page is either discarded or programmed.

A write to another page while the current page is Page Loss Protected will return a STATUS of '11'.

Overwrite Protection

Any page that is Overwrite Protected will result in the STATUS being set to '01' when an attempt is made to either write, program, or erase it. To set the Overwrite Protection state for a page, set the OVERWRITEPROTECT pin when a Program operation is undertaken. To clear the Overwrite Protect state for a given page, an Unprotect Page operation must be performed on the page, and then the page must be programmed with the OVERWRITEPROTECT pin cleared to save the new page.

LOCKREQUEST

The LOCKREQUEST signal is used to give the user interface control over simultaneous access of the FB from both the User and JTAG interfaces. When LOCKREQUEST is asserted, the JTAG interface will hold off any access attempts until LOCKREQUEST is deasserted.

Flash Memory Block Operations

FB Operation Priority

The FB provides for priority of operations when multiple actions are requested simultaneously. Table 2-22 shows the priority order (priority 0 is the highest).

***Table 2-22* • FB Operation Priority**

Operation	Priority
System Initialization	0
FB Reset	1
Read	2
Write	3
Erase Page	4
Program	5
Unprotect Page	6
Discard Page	7

The following error indications are possible for Read operations:

1. STATUS = '01' when a single-bit data error was detected and corrected within the block addressed.
2. STATUS = '10' when a double-bit error was detected in the block addressed (note that the error is uncorrected).

In addition to data reads, users can read the status of any page in the FB by asserting PAGESTATUS along with REN. The format of the data returned by a page status read is shown in Table 2-23, and the definition of the page status bits is shown in Table 2-24.

Table 2-23 **• Page Status Read Data Format**

31	8	7	4	3	2	1	0
Write Count		Reserved		Over Threshold	Read Protected	Write Protected	Overwrite Protected

Table 2-24 **• Page Status Bit Definition**

Page Status Bit(s)	Definition
31–8	The number of times the page addressed has been programmed/erased
7–4	Reserved; read as 0
3	Over Threshold indicator (see the"Program Operation" section on page 2-46)
2	Read Protected; read protect bit for page, which is set via the JTAG interface and only affects JTAG operations. This bit can be overridden by using the correct user key value.
1	Write Protected; write protect bit for page, which is set via the JTAG interface and only affects JTAG operations. This bit can be overridden by using the correct user key value.
0	Overwrite Protected; designates that the user has set the OVERWRITEPROTECT bit on the interface while doing a Program operation. The page cannot be written without first performing an Unprotect Page operation.

RAM4K9 Description

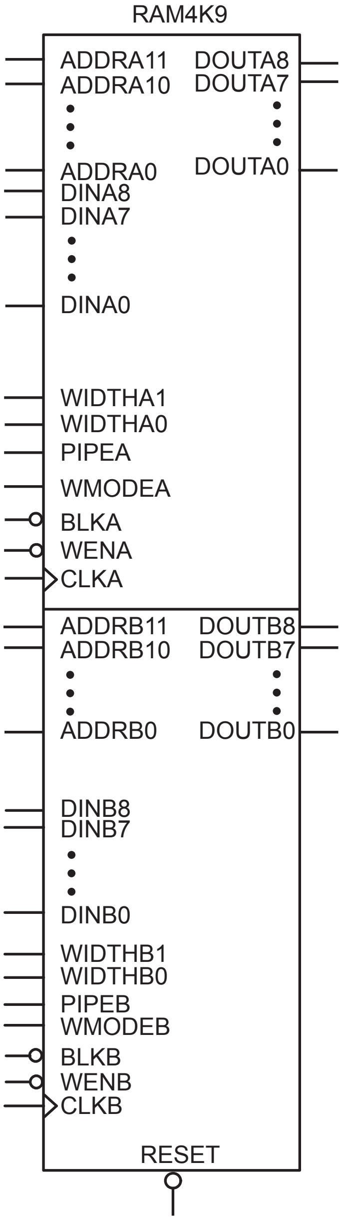


Figure 2-48 • **RAM4K9**

Timing Characteristics

Table 2-31 • **RAM4K9**
Commercial Temperature Range Conditions: T_J = 70°C, Worst-Case VCC = 1.425 V

Parameter	Description	–2	–1	Std.	Units
t_{AS}	Address setup time	0.25	0.28	0.33	ns
t_{AH}	Address hold time	0.00	0.00	0.00	ns
t_{ENS}	REN, WEN setup time	0.14	0.16	0.19	ns
t_{ENH}	REN, WEN hold time	0.10	0.11	0.13	ns
t_{BKS}	BLK setup time	0.23	0.27	0.31	ns
t_{BKH}	BL hold time	0.02	0.02	0.02	ns
t_{DS}	Input data (DIN) setup time	0.18	0.21	0.25	ns
t_{DH}	Input data (DIN) hold time	0.00	0.00	0.00	ns
t_{CKQ1}	Clock High to new data valid on DOUT (output retained, WMODE = 0)	1.79	2.03	2.39	ns
	Clock High to new data valid on DOUT (flow-through, WMODE = 1)	2.36	2.68	3.15	ns
t_{CKQ2}	Clock High to new data valid on DOUT (pipelined)	0.89	1.02	1.20	ns
t_{C2CWWH}[1]	Address collision clk-to-clk delay for reliable write after write on same address—Applicable to Rising Edge	0.30	0.26	0.23	ns
t_{C2CRWH}[1]	Address collision clk-to-clk delay for reliable read access after write on same address—Applicable to Opening Edge	0.45	0.38	0.34	ns
t_{C2CWRH}[1]	Address collision clk-to-clk delay for reliable write access after read on same address— Applicable to Opening Edge	0.49	0.42	0.37	ns
t_{RSTBQ}	RESET Low to data out Low on DOUT (flow-through)	0.92	1.05	1.23	ns
	RESET Low to Data Out Low on DOUT (pipelined)	0.92	1.05	1.23	ns
$t_{REMRSTB}$	RESET removal	0.29	0.33	0.38	ns
$t_{RECRSTB}$	RESET recovery	1.50	1.71	2.01	ns
$t_{MPWRSTB}$	RESET minimum pulse width	0.21	0.24	0.29	ns
t_{CYC}	Clock cycle time	3.23	3.68	4.32	ns
F_{MAX}	Maximum frequency	310	272	231	MHz

Notes:

1. *For more information, refer to the application note* Simultaneous Read-Write Operations in Dual-Port SRAM for Flash-Based cSoCs and FPGAs*.*
2. *For the derating values at specific junction temperature and voltage supply levels, refer to* *Table 3-7 on page 3-9*.

Intra-Conversion

Performing a conversion during power-up calibration is possible but should be avoided, since the performance is not guaranteed, as shown in Table 2-49 on page 2-117. This is described as intra-conversion. Figure 2-92 on page 2-113 shows intra-conversion, (conversion that starts during power-up calibration).

Injected Conversion

A conversion can be interrupted by another conversion. Before the current conversion is finished, a second conversion can be started by issuing a pulse on signal ADCSTART. When a second conversion is issued before the current conversion is completed, the current conversion would be dropped and the ADC would start the second conversion on the rising edge of the SYSCLK. This is known as injected conversion. Since the ADC is synchronous, the minimum time to issue a second conversion is two clock cycles of SYSCLK after the previous one. Figure 2-93 on page 2-113 shows injected conversion, (conversion that starts before a previously started conversion is finished). The total time for calibration still remains 3,840 ADCCLK cycles.

ADC Example

This example shows how to choose the correct settings to achieve the fastest sample time in 10-bit mode for a system that runs at 66 MHz. Assume the acquisition times defined in Table 2-44 on page 2-108 for 10-bit mode, which gives 0.549 µs as a minimum hold time.

The period of SYSCLK: $t_{SYSCLK} = 1/66\text{ MHz} = 0.015\ \mu s$

Choosing TVC between 1 and 33 will meet the maximum and minimum period for the ADCCLK requirement. A higher TVC leads to a higher ADCCLK period.

The minimum TVC is chosen so that $t_{distrib}$ and $t_{post\text{-}cal}$ can be run faster. The period of ADCCLK with a TVC of 1 can be computed by EQ 24.

$$t_{ADCCLK} = 4 \times (1 + TVC) \times t_{SYSCLK} = 4 \times (1 + 1) \times 0.015\ \mu s = 0.12\ \mu s$$

EQ 24

The STC value can now be computed by using the minimum sample/hold time from Table 2-44 on page 2-108, as shown in EQ 25.

$$STC = \frac{t_{sample}}{t_{ADCCLK}} - 2 = \frac{0.549\ \mu s}{0.12\ \mu s} - 2 = 4.575 - 2 = 2.575$$

EQ 25

You must round up to 3 to accommodate the minimum sample time requirement. The actual sample time, t_{sample}, with an STC of 3, is now equal to 0.6 µs, as shown in EQ 26

$$t_{sample} = (2 + STC) \times t_{ADCCLK} = (2 + 3) \times t_{ADCCLK} = 5 \times 0.12\ \mu s = 0.6\ \mu s$$

EQ 26

Microsemi recommends post-calibration for temperature drift over time, so post-calibration is enabled.

The post-calibration time, $t_{post\text{-}cal}$, can be computed by EQ 27. The post-calibration time is 0.24 µs.

$$t_{post\text{-}cal} = 2 \times t_{ADCCLK} = 0.24\ \mu s$$

EQ 27

The distribution time, $t_{distrib}$, is equal to 1.2 µs and can be computed as shown in EQ 28 (N is number of bits, referring back to EQ 8 on page 2-94).

$$t_{distrib} = N \times t_{ADCCLK} = 10 \times 0.12 = 1.2\ \mu s$$

EQ 28

The total conversion time can now be summated, as shown in EQ 29 (referring to EQ 23 on page 2-109).

$$t_{sync\_read} + t_{sample} + t_{distrib} + t_{post\text{-}cal} + tsync\_write = (0.015 + 0.60 + 1.2 + 0.24 + 0.015)\ \mu s = 2.07\ \mu s$$

EQ 29

Timing Characteristics

***Table 2-55* • Analog Configuration Multiplexer (ACM) Timing**
Commercial Temperature Range Conditions: T_J = 70°C, Worst-Case VCC = 1.425 V

Parameter	Description	–2	–1	Std.	Units
$t_{CLKQACM}$	Clock-to-Q of the ACM	19.73	22.48	26.42	ns
t_{SUDACM}	Data Setup time for the ACM	4.39	5.00	5.88	ns
t_{HDACM}	Data Hold time for the ACM	0.00	0.00	0.00	ns
t_{SUAACM}	Address Setup time for the ACM	4.73	5.38	6.33	ns
t_{HAACM}	Address Hold time for the ACM	0.00	0.00	0.00	ns
t_{SUEACM}	Enable Setup time for the ACM	3.93	4.48	5.27	ns
t_{HEACM}	Enable Hold time for the ACM	0.00	0.00	0.00	ns
$t_{MPWARACM}$	Asynchronous Reset Minimum Pulse Width for the ACM	10.00	10.00	10.00	ns
$t_{REMARACM}$	Asynchronous Reset Removal time for the ACM	12.98	14.79	17.38	ns
$t_{RECARACM}$	Asynchronous Reset Recovery time for the ACM	12.98	14.79	17.38	ns
$t_{MPWCLKACM}$	Clock Minimum Pulse Width for the ACM	45.00	45.00	45.00	ns
$t_{FMAXCLKACM}$	lock Maximum Frequency for the ACM	10.00	10.00	10.00	MHz

Table 2-85 • Fusion Pro I/O Attributes vs. I/O Standard Applications

I/O Standards	SLEW (output only)	OUT_DRIVE (output only)	SKEW (all macros with OE)	RES_PULL	OUT_LOAD (output only)	COMBINE_REGISTER	IN_DELAY (input only)	IN_DELAY_VAL (input only)	SCHMITT_TRIGGER (input only)	HOT_SWAPPABLE
LVTTL/LVCMOS 3.3 V	3	3	3	3	3	3	3	3	3	3
LVCMOS 2.5 V	3	3	3	3	3	3	3	3	3	3
LVCMOS 2.5/5.0 V	3	3	3	3	3	3	3	3	3	3
LVCMOS 1.8 V	3	3	3	3	3	3	3	3	3	3
LVCMOS 1.5 V	3	3	3	3	3	3	3	3	3	3
PCI (3.3 V)			3		3	3	3	3		
PCI-X (3.3 V)	3		3		3	3	3	3		
GTL+ (3.3 V)			3		3	3	3	3		3
GTL+ (2.5 V)			3		3	3	3	3		3
GTL (3.3 V)			3		3	3	3	3		3
GTL (2.5 V)			3		3	3	3	3		3
HSTL Class I			3		3	3	3	3		3
HSTL Class II			3		3	3	3	3		3
SSTL2 Class I and II			3		3	3	3	3		3
SSTL3 Class I and II			3		3	3	3	3		3
LVDS, BLVDS, M-LVDS			3			3	3	3		3
LVPECL						3	3	3		3

Voltage Referenced I/O Characteristics

3.3 V GTL

Gunning Transceiver Logic is a high-speed bus standard (JESD8-3). It provides a differential amplifier input buffer and an open-drain output buffer. The VCCI pin should be connected to 3.3 V.

Table 2-138 **• Minimum and Maximum DC Input and Output Levels**

3.3 V GTL	VIL		VIH		VOL	VOH	IOL	IOH	IOSL	IOSH	IIL[1]	IIH[2]
Drive Strength	Min. V	Max. V	Min. V	Max. V	Max. V	Min. V	mA	mA	Max. mA[3]	Max. mA[3]	µA[4]	µA[4]
20 mA[3]	–0.3	VREF – 0.05	VREF + 0.05	3.6	0.4	–	20	20	181	268	10	10

Notes:

1. *IIL is the input leakage current per I/O pin over recommended operation conditions where –0.3 V < VIN < VIL.*
2. *IIH is the input leakage current per I/O pin over recommended operating conditions VIH < VIN < VCCI. Input current is larger when operating outside recommended ranges.*
3. *Currents are measured at high temperature (100°C junction temperature) and maximum voltage.*
4. *Currents are measured at 85°C junction temperature.*

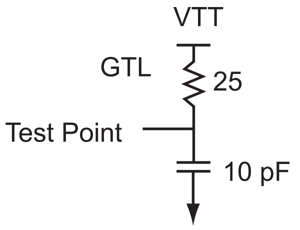


Figure 2-124 **• AC Loading**

Table 2-139 **• AC Waveforms, Measuring Points, and Capacitive Loads**

Input Low (V)	Input High (V)	Measuring Point* (V)	VREF (typ.) (V)	VTT (typ.) (V)	C_{LOAD} (pF)
VREF – 0.05	VREF + 0.05	0.8	0.8	1.2	10

*Note: *Measuring point = Vtrip. See Table 2-90 on page 2-166 for a complete table of trip points.*

Timing Characteristics

Table 2-140 **• 3.3 V GTL**
Commercial Temperature Range Conditions: T_J = 70°C, Worst-Case VCC = 1.425 V,
Worst-Case VCCI = 3.0 V, VREF = 0.8 V

Speed Grade	t_{DOUT}	t_{DP}	t_{DIN}	t_{PY}	t_{EOUT}	t_{ZL}	t_{ZH}	t_{LZ}	t_{HZ}	t_{ZLS}	t_{ZHS}	Units
Std.	0.66	2.08	0.04	2.93	0.43	2.04	2.08			4.27	4.31	ns
–1	0.56	1.77	0.04	2.50	0.36	1.73	1.77			3.63	3.67	ns
–2	0.49	1.55	0.03	2.19	0.32	1.52	1.55			3.19	3.22	ns

Note: For the derating values at specific junction temperature and voltage supply levels, refer to Table 3-7 on page 3-9.

HSTL Class II

High-Speed Transceiver Logic is a general-purpose high-speed 1.5 V bus standard (EIA/JESD8-6). Fusion devices support Class II. This provides a differential amplifier input buffer and a push-pull output buffer.

***Table 2-153* • Minimum and Maximum DC Input and Output Levels**

HSTL Class II	VIL		VIH		VOL	VOH	IOL	IOH	IOSL	IOSH	IIL[1]	IIH[2]
Drive Strength	**Min. V**	**Max. V**	**Min. V**	**Max. V**	**Max. V**	**Min. V**	**mA**	**mA**	**Max. mA[3]**	**Max. mA[3]**	**µA[4]**	**µA[4]**
15 mA[3]	–0.3	VREF – 0.1	VREF + 0.1	3.6	0.4	VCCI – 0.4	15	15	55	66	10	10

Note:

1. *IIL is the input leakage current per I/O pin over recommended operation conditions where –0.3 V < VIN < VIL.*
2. *IIH is the input leakage current per I/O pin over recommended operating conditions VIH < VIN < VCCI. Input current is larger when operating outside recommended ranges.*
3. *Currents are measured at high temperature (100°C junction temperature) and maximum voltage.*
4. *Currents are measured at 85°C junction temperature.*
5. *Output drive strength is below JEDEC specification.*

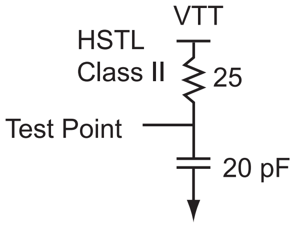


***Figure 2-129* • AC Loading**

***Table 2-154* • AC Waveforms, Measuring Points, and Capacitive Loads**

Input Low (V)	Input High (V)	Measuring Point* (V)	VREF (typ.) (V)	VTT (typ.) (V)	C_{LOAD} (pF)
VREF – 0.1	VREF + 0.1	0.75	0.75	0.75	20

*Note: *Measuring point = Vtrip. See Table 2-90 on page 2-166 for a complete table of trip points.*

Timing Characteristics

***Table 2-155* • HSTL Class II**
Commercial Temperature Range Conditions: T_J = 70°C, Worst-Case VCC = 1.425 V, Worst-Case VCCI = 1.4 V, VREF = 0.75 V

Speed Grade	t_{DOUT}	t_{DP}	t_{DIN}	t_{PY}	t_{EOUT}	t_{ZL}	t_{ZH}	t_{LZ}	t_{HZ}	t_{ZLS}	t_{ZHS}	Units
Std.	0.66	3.02	0.04	2.12	0.43	3.08	2.71			5.32	4.95	ns
–1	0.56	2.57	0.04	1.81	0.36	2.62	2.31			4.52	4.21	ns
–2	0.49	2.26	0.03	1.59	0.32	2.30	2.03			3.97	3.70	ns

Note: For the derating values at specific junction temperature and voltage supply levels, refer to Table 3-7 on page 3-9.

Differential I/O Characteristics

Configuration of the I/O modules as a differential pair is handled by the Microsemi Designer software when the user instantiates a differential I/O macro in the design.

Differential I/Os can also be used in conjunction with the embedded Input Register (InReg), Output Register (OutReg), Enable Register (EnReg), and Double Data Rate (DDR). However, there is no support for bidirectional I/Os or tristates with these standards.

LVDS

Low-Voltage Differential Signal (ANSI/TIA/EIA-644) is a high-speed differential I/O standard. It requires that one data bit be carried through two signal lines, so two pins are needed. It also requires external resistor termination.

The full implementation of the LVDS transmitter and receiver is shown in an example in Figure 2-134. The building blocks of the LVDS transmitter–receiver are one transmitter macro, one receiver macro, three board resistors at the transmitter end, and one resistor at the receiver end. The values for the three driver resistors are different from those used in the LVPECL implementation because the output standard specifications are different.

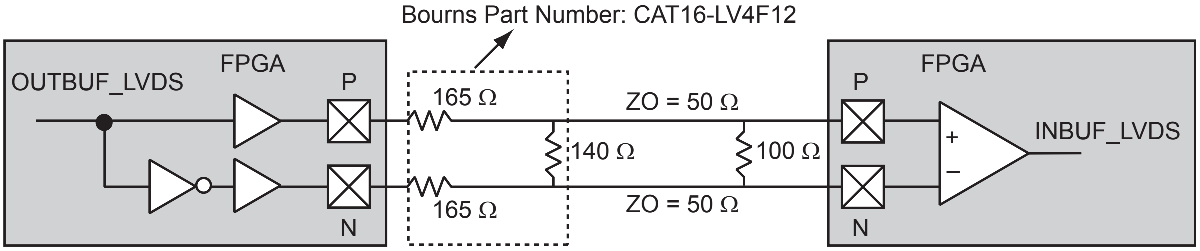


***Figure 2-134* • LVDS Circuit Diagram and Board-Level Implementation**

***Table 2-168* • Minimum and Maximum DC Input and Output Levels**

DC Parameter	Description	Min.	Typ.	Max.	Units
VCCI	Supply Voltage	2.375	2.5	2.625	V
VOL	Output Low Voltage	0.9	1.075	1.25	V
VOH	Input High Voltage	1.25	1.425	1.6	V
IOL [1]	Output Low Voltage	0.65	0.91	1.16	mA
IOH [1]	Output High Voltage	0.65	0.91	1.16	mA
VI	Input Voltage	0		2.925	V
IIL [2,3]	Input Low Voltage			10	µA
IIH [2,4]	Input High Voltage			10	µA
VODIFF	Differential Output Voltage	250	350	450	mV
VOCM	Output Common Mode Voltage	1.125	1.25	1.375	V
VICM	Input Common Mode Voltage	0.05	1.25	2.35	V
VIDIFF	Input Differential Voltage	100	350		mV

Notes:

1. *IOL/IOH defined by VODIFF/(Resistor Network)*
2. *Currents are measured at 85°C junction temperature.*
3. *IIL is the input leakage current per I/O pin over recommended operation conditions where –0.3 V < VIN < VIL.*
4. *IIH is the input leakage current per I/O pin over recommended operating conditions VIH < VIN < VCCI. Input current is larger when operating outside recommended ranges.*

Revision	Changes	Page
Revision 2 (continued)	A note was added to Figure 2-27 • Real-Time Counter System (not all the signals are shown for the AB macro) stating that the user is only required to instantiate the VRPSM macro if the user wishes to specify PUPO behavior of the voltage regulator to be different from the default, or employ user logic to shut the voltage regulator off (SAR 21773).	2-31
	VPUMP was incorrectly represented as VPP in several places. This was corrected to VPUMP in the "Standby and Sleep Mode Circuit Implementation" section and Table 3-8 • AFS1500 Quiescent Supply Current Characteristics through Table 3-11 • AFS090 Quiescent Supply Current Characteristics (21963).	2-32, 3-10
	Additional information was added to the Flash Memory Block "Write Operation" section, including an explanation of the fact that a copy-page operation takes no less than 55 cycles (SAR 26338).	2-45
	The "FlashROM" section was revised to refer to Figure 2-46 • FlashROM Timing Diagram and Table 2-26 • FlashROM Access Time rather than stating 20 MHz as the maximum FlashROM access clock and 10 ns as the time interval for D0 to become valid or invalid (SAR 22105).	2-53, 2-54
	The following figures were deleted (SAR 29991). Reference was made to a new application note, *Simultaneous Read-Write Operations in Dual-Port SRAM for Flash-Based cSoCs and FPGAs,* which covers these cases in detail (SAR 34862). Figure 2-55 • Write Access after Write onto Same Address Figure 2-56 • Read Access after Write onto Same Address Figure 2-57 • Write Access after Read onto Same Address The port names in the SRAM "Timing Waveforms", "Timing Characteristics", SRAM tables, Figure 2-55 • RAM Reset. Applicable to both RAM4K9 and RAM512x18., and the FIFO "Timing Characteristics" tables were revised to ensure consistency with the software names (SAR 35753).	2-63, 2-66, 2-65, 2-75
	In several places throughout the datasheet, GNDREF was corrected to ADCGNDREF (SAR 20783): Figure 2-64 • Analog Block Macro Table 2-36 • Analog Block Pin Description "ADC Operation" section	2-77 2-78 2-104
	The following note was added below Figure 2-78 • Timing Diagram for the Temperature Monitor Strobe Signal: When the IEEE 1149.1 Boundary Scan EXTEST instruction is executed, the AG pad drive strength ceases and becomes a 1 µA sink into the Fusion device. (SAR 24796).	2-93
	The "Analog-to-Digital Converter Block" section was extensively revised, reorganizing the information and adding the "ADC Theory of Operation" section and "Acquisition Time or Sample Time Control" section. The "ADC Example" section was reworked and corrected (SAR 20577).	2-96
	Table 2-49 • Analog Channel Specifications was modified to include calibrated and uncalibrated values for offset (AFS090 and AFS250) for the external and internal temperature monitors. The "Offset" section was revised accordingly and now references Table 2-49 • Analog Channel Specifications (SARs 22647, 27015).	2-95, 2-117
	The "Intra-Conversion" section and "Injected Conversion" section had definitions incorrectly interchanged and have been corrected. Figure 2-92 • Intra-Conversion Timing Diagram and Figure 2-93 • Injected Conversion Timing Diagram were also incorrectly interchanged and have been replaced correctly. Reference in the figure notes to EQ 10 has been corrected to EQ 23 (SAR 20547).	2-110, 2-113, 2-113

Revision	Changes	Page
Advance v1.5 (continued)	This bullet was added to the "Integrated A/D Converter (ADC) and Analog I/O" section: ADC Accuracy is Better than 1%	I
	In the "Integrated Analog Blocks and Analog I/Os" section, ±4 LSB was changed to 0.72. The following sentence was deleted: The input range for voltage signals is from –12 V to +12 V with full-scale output values from 0.125 V to 16 V. In addition, 2°C was changed to 3°C: "One analog input in each quad can be connected to an external temperature monitor diode and achieves detection accuracy of ±3ºC." The following sentence was deleted: The input range for voltage signals is from –12 V to +12 V with full-scale output values from 0.125 V to 16 V.	1-4
	The title of the datasheet changed from Actel Programmable System Chips to Actel Fusion Mixed Signal FPGAs. In addition, all instances of programmable system chip were changed to mixed signal FPGA.	N/A
Advance v1.4 (July 2008)	In Table 3-8 · Quiescent Supply Current Characteristics (IDDQ)1, footnote references were updated for I_{DC2} and I_{DC3}. Footnote 3 and 4 were updated and footnote 5 is new.	3-11
Advance v1.3 (July 2008)	The "ADC Description" section was significantly updated. Please review carefully.	2-102
Advance v1.2 (May 2008)	Table 2-25 • Flash Memory Block Timing was significantly updated.	2-55
	The "V_{AREF} Analog Reference Voltage" pin description section was significantly update. Please review it carefully.	2-226
	Table 2-45 • ADC Interface Timing was significantly updated.	2-110
	Table 2-56 • Direct Analog Input Switch Control Truth Table—AV (x = 0), AC (x = 1), and AT (x = 3) was significantly updated.	2-131
	The following sentence was deleted from the "Voltage Monitor" section: The Analog Quad inputs are tolerant up to 12 V + 10%.	2-86
	The "180-Pin QFN" figure was updated. D1 to D4 are new and the figure was changed to bottom view. The note below the figure is new.	3-3
Advance v1.1 (May 2008)	The following text was incorrect and therefore deleted: **VCC33A** **Analog Power Filter** Analog power pin for the analog power supply low-pass filter. An external 100 pF capacitor should be connected between this pin and ground. There is still a description of V_{CC33A} on page 2-224.	2-204

Revision	Changes	Page
Advance v0.8 (continued)	This sentence was updated in the "No-Glitch MUX (NGMUX)" section to delete GLA: The GLMUXCFG[1:0] configuration bits determine the source of the CLK inputs (i.e., internal signal or GLC).	2-32
	In Table 2-13 • NGMUX Configuration and Selection Table, 10 and 11 were deleted.	2-32
	The method to enable sleep mode was updated for bit 0 in Table 2-16 • RTC Control/Status Register.	2-38
	S2 was changed to D2 in Figure 2-39 • Read Waveform (Pipe Mode, 32-bit access) for RD[31:0] was updated.	2-51
	The definitions for bits 2 and 3 were updated in Table 2-24 • Page Status Bit Definition.	2-52
	Figure 2-46 • FlashROM Timing Diagram was updated.	2-58
	Table 2-26 • FlashROM Access Time is new.	2-58
	Figure 2-55 • Write Access After Write onto Same Address, Figure 2-56 • Read Access After Write onto Same Address, and Figure 2-57 • Write Access After Read onto Same Address are new.	2-68–2-70
	Table 2-31 • RAM4K9 and Table 2-32 • RAM512X18 were updated.	2-71, 2-72
	The VAREF and SAMPLE functions were updated in Table 2-36 • Analog Block Pin Description.	2-82
	The title of Figure 2-72 • Timing Diagram for Current Monitor Strobe was updated to add the word "positive."	2-91
	The "Gate Driver" section was updated to give information about the switching rate in High Current Drive mode.	2-94
	The "ADC Description" section was updated to include information about the SAMPLE and BUSY signals and the maximum frequencies for SYSCLK and ADCCLK. EQ 2 was updated to add parentheses around the entire expression in the denominator.	2-102
	Table 2-46 · Analog Channel Specifications and Table 2-47 · ADC Characteristics in Direct Input Mode were updated.	2-118, 2-121
	The note was removed from Table 2-55 • Analog Multiplexer Truth Table—AV (x = 0), AC (x = 1), and AT (x = 3).	2-131
	Table 2-63 • Internal Temperature Monitor Control Truth Table is new.	2-132
	The "Cold-Sparing Support" section was updated to add information about cases where current draw can occur.	2-143
	Figure 2-104 • Solution 4 was updated.	2-147
	Table 2-75 • Fusion Standard I/O Standards—OUT_DRIVE Settings was updated.	2-153
	The "GNDA Ground (analog)" section and "GNDAQ Ground (analog quiet)" section were updated to add information about maximum differential voltage.	2-224
	The "V_{AREF} Analog Reference Voltage" section and "VPUMP Programming Supply Voltage" section were updated.	2-226
	The "$V_{CCPLA/B}$ PLL Supply Voltage" section was updated to include information about the east and west PLLs.	2-225
	The V_{COMPLF} pin description was deleted.	N/A
	The "Axy Analog Input/Output" section was updated with information about grounding and floating the pin.	2-226