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Understanding [Embedded - FPGAs \(Field Programmable Gate Array\)](#)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details

| | |
|--------------------------------|---|
| Product Status | Active |
| Number of LABs/CLBs | - |
| Number of Logic Elements/Cells | - |
| Total RAM Bits | 110592 |
| Number of I/O | 172 |
| Number of Gates | 600000 |
| Voltage - Supply | 1.425V ~ 1.575V |
| Mounting Type | Surface Mount |
| Operating Temperature | 0°C ~ 85°C (TJ) |
| Package / Case | 484-BGA |
| Supplier Device Package | 484-FPBGA (23x23) |
| Purchase URL | https://www.e-xfl.com/product-detail/microchip-technology/p1afs600-2fg484 |

Temperature Grade Offerings

| Fusion Devices | AFS090 | AFS250 | AFS600 | AFS1500 |
|-----------------------|--------|-----------------------|-----------------------|------------------------|
| ARM Cortex-M1 Devices | | M1AFS250 | M1AFS600 | M1AFS1500 |
| Pigeon Point Devices | | | P1AFS600 ³ | P1AFS1500 ³ |
| MicroBlade Devices | | U1AFS250 ⁴ | U1AFS600 ⁴ | U1AFS1500 ⁴ |
| QN108 ⁵ | C, I | – | – | – |
| QN180 ⁵ | C, I | C, I | – | – |
| PQ208 | – | C, I | C, I | – |
| FG256 | C, I | C, I | C, I | C, I |
| FG484 | – | – | C, I | C, I |
| FG676 | – | – | – | C, I |

Notes:

1. C = Commercial Temperature Range: 0°C to 85°C Junction
2. I = Industrial Temperature Range: –40°C to 100°C Junction
3. Pigeon Point devices are only offered in FG484 and FG256.
4. MicroBlade devices are only offered in FG256.
5. Package not available.

Speed Grade and Temperature Grade Matrix

| | Std. ¹ | –1 | –2 ² |
|----------------|-------------------|----|-----------------|
| C ³ | ✓ | ✓ | ✓ |
| I ⁴ | ✓ | ✓ | ✓ |

Notes:

1. MicroBlade devices are only offered in standard speed grade.
2. Pigeon Point devices are only offered in –2 speed grade.
3. C = Commercial Temperature Range: 0°C to 85°C Junction
4. I = Industrial Temperature Range: –40°C to 100°C Junction

Contact your local Microsemi SoC Products Group representative for device availability:

http://www.microsemi.com/index.php?option=com_content&id=137&lang=en&view=article.

Cortex-M1, Pigeon Point, and MicroBlade Fusion Device Information

This datasheet provides information for all Fusion (AFS), Cortex-M1 (M1), Pigeon Point (P1), and MicroBlade (U1) devices. The remainder of the document will only list the Fusion (AFS) devices. Please apply relevant information to M1, P1, and U1 devices when appropriate. Please note the following:

- Cortex-M1 devices are offered in the same speed grades and packages as basic Fusion devices.
- Pigeon Point devices are only offered in –2 speed grade and FG484 and FG256 packages.
- MicroBlade devices are only offered in standard speed grade and the FG256 package.

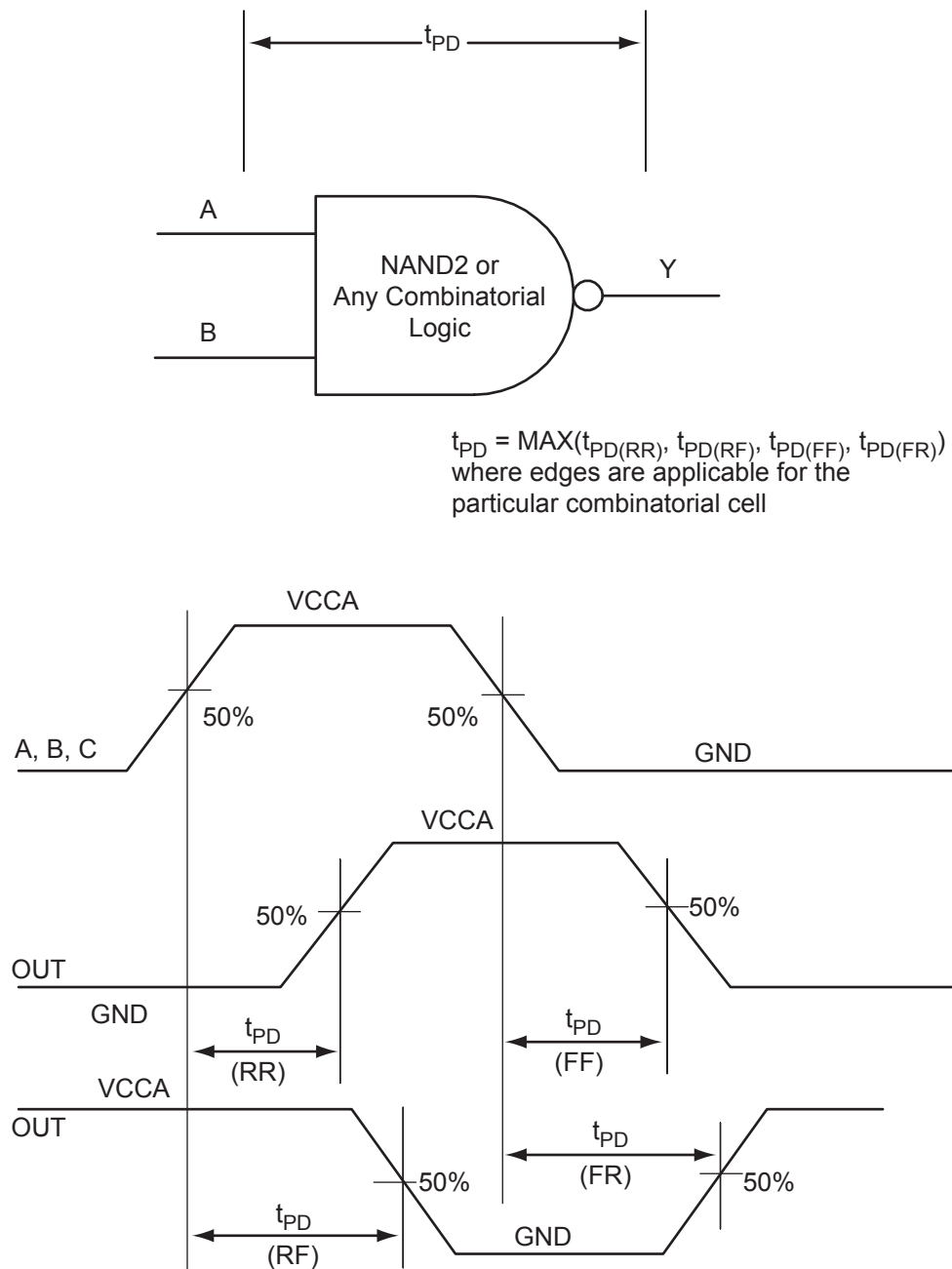


Figure 2-4 • Combinatorial Timing Model and Waveforms

Crystal Oscillator

The Crystal Oscillator (XTLOSC) is source that generates the clock from an external crystal. The output of XTLOSC CLKOUT signal can be selected as an input to the PLL. Refer to the ["Clock Conditioning Circuits" section](#) for more details. The XTLOSC can operate in normal operations and Standby mode (RTC is running and 1.5 V is not present).

In normal operation, the internal FPGA_EN signal is '1' as long as 1.5 V is present for VCC. As such, the internal enable signal, XTL_EN, for Crystal Oscillator is enabled since FPGA_EN is asserted. The XTL_MODE has the option of using MODE or RTC_MODE, depending on SELMODE.

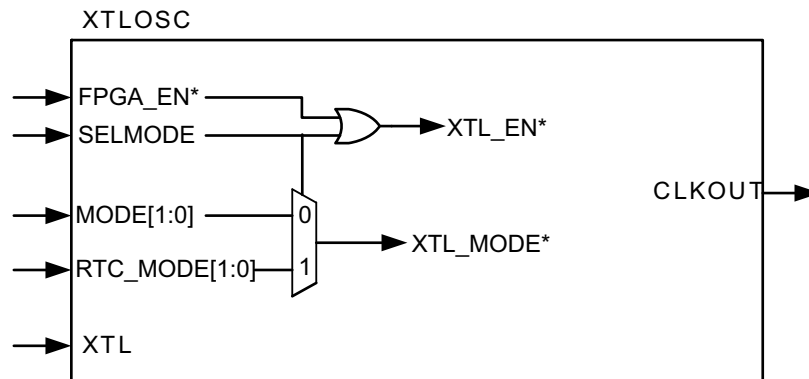
During Standby, 1.5 V is not available, as such, and FPGA_EN is '0'. SELMODE must be asserted in order for XTL_EN to be enabled; hence XTL_MODE relies on RTC_MODE. SELMODE and RTC_MODE must be connected to RTCXTLSEL and RTCXTLMODE from the AB respectively for correct operation during Standby (refer to the ["Real-Time Counter System" section on page 2-31](#) for a detailed description).

The Crystal Oscillator can be configured in one of four modes:

- RC network, 32 KHz to 4 MHz
- Low gain, 32 to 200 KHz
- Medium gain, 0.20 to 2.0 MHz
- High gain, 2.0 to 20.0 MHz

In RC network mode, the XTAL1 pin is connected to an RC circuit, as shown in [Figure 2-16 on page 2-18](#). The XTAL2 pin should be left floating. The RC value can be chosen based on [Figure 2-18](#) for any desired frequency between 32 KHz and 4 MHz. The RC network mode can also accommodate an external clock source on XTAL1 instead of an RC circuit.

In Low gain, Medium gain, and High gain, an external crystal component or ceramic resonator can be added onto XTAL1 and XTAL2, as shown in [Figure 2-16 on page 2-18](#). In the case where the Crystal Oscillator block is not used, the XTAL1 pin should be connected to GND and the XTAL2 pin should be left floating.



Note: *Internal signal—does not exist in macro.

Figure 2-17 • XTLOSC Macro

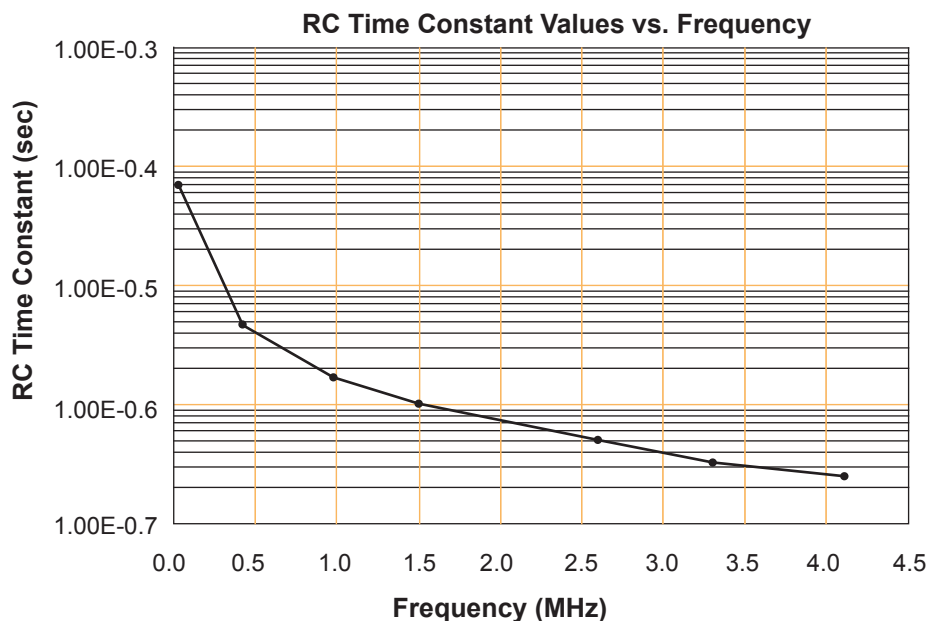


Figure 2-18 • Crystal Oscillator: RC Time Constant Values vs. Frequency (typical)

Table 2-10 • XTLOSC Signals Descriptions

| Signal Name | Width | Direction | Function | | |
|---------------|-------|-----------|---|---|-----------------|
| XTL_EN* | 1 | | Enables the crystal. Active high. | | |
| XTL_MODE* | 2 | | Settings for the crystal clock for different frequency. | | |
| | | | Value | Modes | Frequency Range |
| | | | b'00 | RC network | 32 KHz to 4 MHz |
| | | | b'01 | Low gain | 32 to 200 KHz |
| | | | b'10 | Medium gain | 0.20 to 2.0 MHz |
| | | | b'11 | High gain | 2.0 to 20.0 MHz |
| SELMODE | 1 | IN | Selects the source of XTL_MODE and also enables the XTL_EN. Connect from RTCXTLSEL from AB. | | |
| | | | 0 | For normal operation or sleep mode, XTL_EN depends on FPGA_EN, XTL_MODE depends on MODE | |
| | | | 1 | For Standby mode, XTL_EN is enabled, XTL_MODE depends on RTC_MODE | |
| RTC_MODE[1:0] | 2 | IN | Settings for the crystal clock for different frequency ranges. XTL_MODE uses RTC_MODE when SELMODE is '1'. | | |
| MODE[1:0] | 2 | IN | Settings for the crystal clock for different frequency ranges. XTL_MODE uses MODE when SELMODE is '0'. In Standby, MODE inputs will be 0's. | | |
| FPGA_EN* | 1 | IN | 0 when 1.5 V is not present for VCC 1 when 1.5 V is present for VCC | | |
| XTL | 1 | IN | Crystal Clock source | | |
| CLKOUT | 1 | OUT | Crystal Clock output | | |

Note: *Internal signal—does not exist in macro.

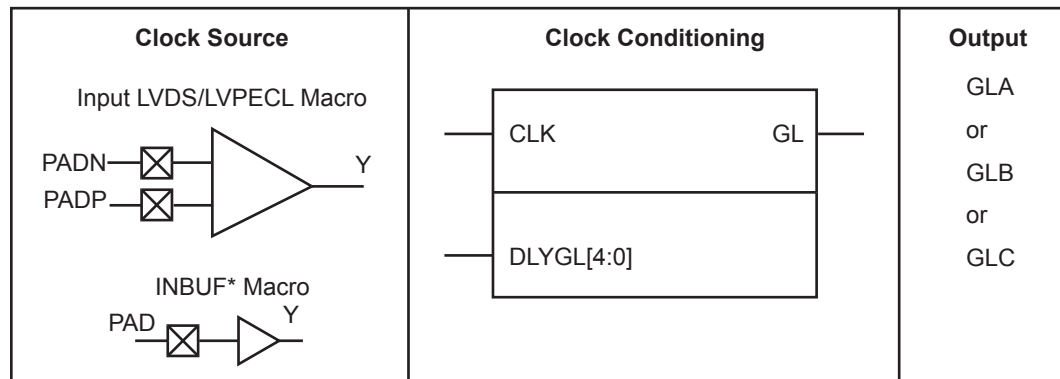
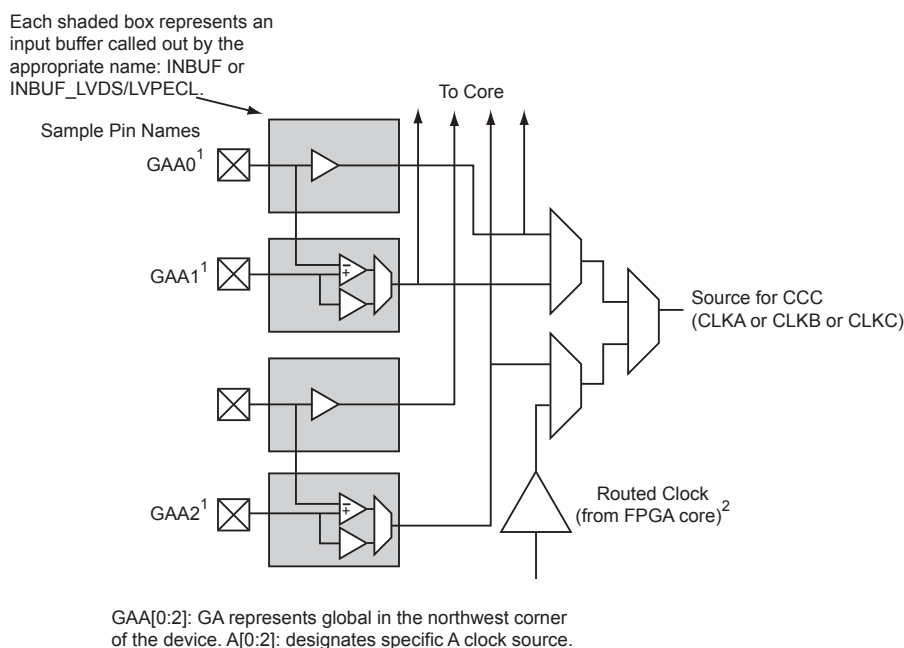


Figure 2-21 • Fusion CCC Options: Global Buffers with Programmable Delay

Global Input Selections

Each global buffer, as well as the PLL reference clock, can be driven from one of the following (Figure 2-22):

- 3 dedicated single-ended I/Os using a hardwired connection
- 2 dedicated differential I/Os using a hardwired connection
- The FPGA core



Notes:

1. Represents the global input pins. Globals have direct access to the clock conditioning block and are not routed via the FPGA fabric. Refer to the ["User I/O Naming Convention"](#) section on page 2-158 for more information.
2. Instantiate the routed clock source input as follows:
 - a) Connect the output of a logic element to the clock input of the PLL, CLKDLY, or CLKINT macro.
 - b) Do not place a clock source I/O (INBUF or INBUF_LVPECL/LVDS) in a relevant global pin location.
3. LVDS-based clock sources are available in the east and west banks on all Fusion devices.

Figure 2-22 • Clock Input Sources Including CLKBUF, CLKBUF_LVDS/LVPECL, and CLKINT

Timing Characteristics

Table 2-31 • RAM4K9

Commercial Temperature Range Conditions: $T_J = 70^\circ\text{C}$, Worst-Case $V_{CC} = 1.425\text{ V}$

| Parameter | Description | -2 | -1 | Std. | Units |
|----------------|--|------|------|------|-------|
| t_{AS} | Address setup time | 0.25 | 0.28 | 0.33 | ns |
| t_{AH} | Address hold time | 0.00 | 0.00 | 0.00 | ns |
| t_{ENS} | REN, WEN setup time | 0.14 | 0.16 | 0.19 | ns |
| t_{ENH} | REN, WEN hold time | 0.10 | 0.11 | 0.13 | ns |
| t_{BKS} | BLK setup time | 0.23 | 0.27 | 0.31 | ns |
| t_{BKH} | BL hold time | 0.02 | 0.02 | 0.02 | ns |
| t_{DS} | Input data (DIN) setup time | 0.18 | 0.21 | 0.25 | ns |
| t_{DH} | Input data (DIN) hold time | 0.00 | 0.00 | 0.00 | ns |
| t_{CKQ1} | Clock High to new data valid on DOUT (output retained, WMODE = 0) | 1.79 | 2.03 | 2.39 | ns |
| | Clock High to new data valid on DOUT (flow-through, WMODE = 1) | 2.36 | 2.68 | 3.15 | ns |
| t_{CKQ2} | Clock High to new data valid on DOUT (pipelined) | 0.89 | 1.02 | 1.20 | ns |
| t_{C2CWWH}^1 | Address collision clk-to-clk delay for reliable write after write on same address—Applicable to Rising Edge | 0.30 | 0.26 | 0.23 | ns |
| t_{C2CRWH}^1 | Address collision clk-to-clk delay for reliable read access after write on same address—Applicable to Opening Edge | 0.45 | 0.38 | 0.34 | ns |
| t_{C2CWRH}^1 | Address collision clk-to-clk delay for reliable write access after read on same address—Applicable to Opening Edge | 0.49 | 0.42 | 0.37 | ns |
| t_{RSTBQ} | RESET Low to data out Low on DOUT (flow-through) | 0.92 | 1.05 | 1.23 | ns |
| | RESET Low to Data Out Low on DOUT (pipelined) | 0.92 | 1.05 | 1.23 | ns |
| $t_{REMRSTB}$ | RESET removal | 0.29 | 0.33 | 0.38 | ns |
| $t_{RECRSTB}$ | RESET recovery | 1.50 | 1.71 | 2.01 | ns |
| $t_{MPWRSTB}$ | RESET minimum pulse width | 0.21 | 0.24 | 0.29 | ns |
| t_{CYC} | Clock cycle time | 3.23 | 3.68 | 4.32 | ns |
| F_{MAX} | Maximum frequency | 310 | 272 | 231 | MHz |

Notes:

1. For more information, refer to the application note [Simultaneous Read-Write Operations in Dual-Port SRAM for Flash-Based cSoCs and FPGAs](#).
2. For the derating values at specific junction temperature and voltage supply levels, refer to [Table 3-7 on page 3-9](#).

Gate Driver

The Fusion Analog Quad includes a Gate Driver connected to the Quad's AG pin ([Figure 2-74](#)). Designed to work with external p- or n-channel MOSFETs, the Gate driver is a configurable current sink or source and requires an external pull-up or pull-down resistor. The AG supports 4 selectable gate drive levels: 1 μA , 3 μA , 10 μA , and 30 μA ([Figure 2-75 on page 2-91](#)). The AG also supports a High Current Drive mode in which it can sink 20 mA; in this mode the switching rate is approximately 1.3 MHz with 100 ns turn-on time and 600 ns turn-off time. Modeled on an open-drain-style output, it does not output a voltage level without an appropriate pull-up or pull-down resistor. If 1 V is forced on the drain, the current sinking/sourcing will exceed the ability of the transistor, and the device could be damaged.

The AG pad is turned on via the corresponding GDONx pin in the Analog Block macro, where x is the number of the corresponding Analog Quad for the AG pad to be enabled (GDON0 to GDON9).

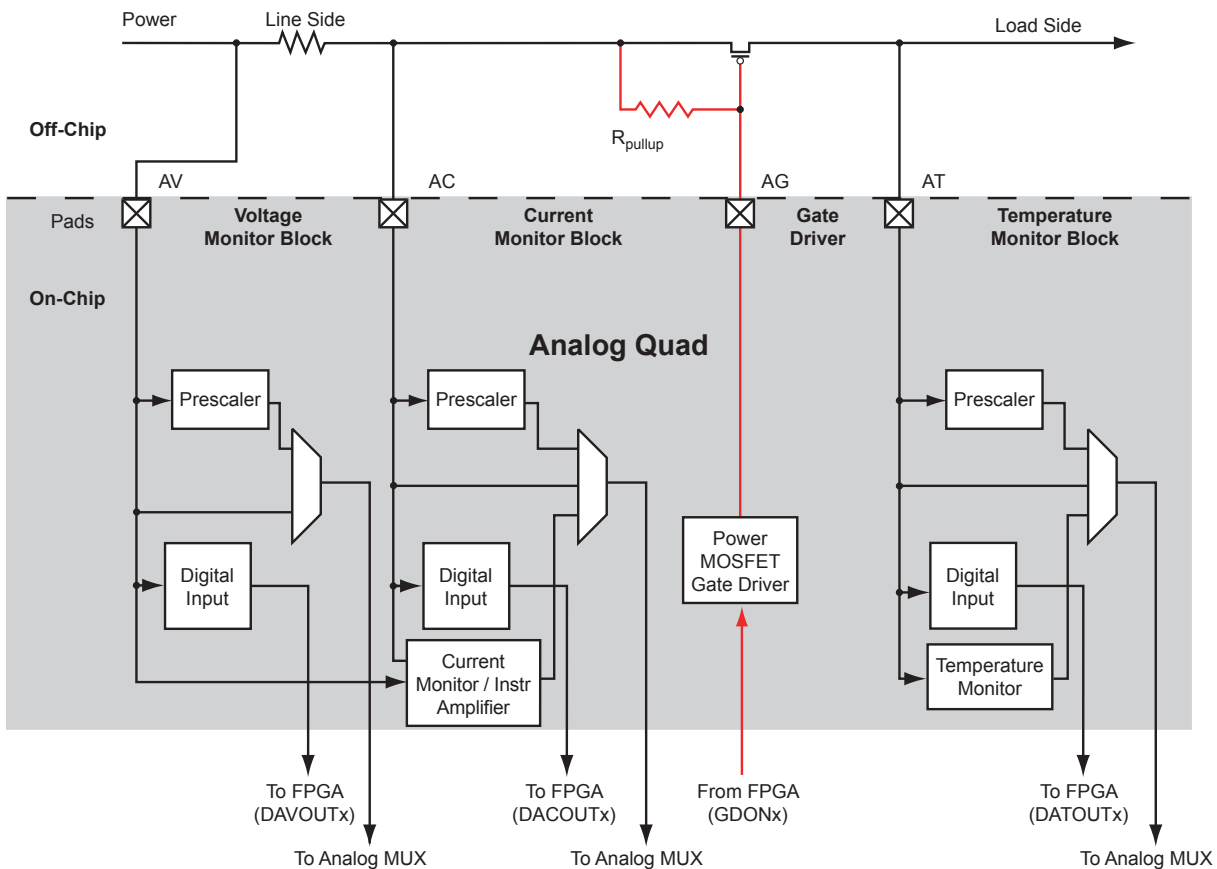


Figure 2-74 • Gate Driver

The gate-to-source voltage (V_{gs}) of the external MOSFET is limited to the programmable drive current times the external pull-up or pull-down resistor value (EQ 5).

$$V_{gs} \leq I_q \times (R_{pullup} \text{ or } R_{pulldown})$$

EQ 5

ADC Terminology

Conversion Time

Conversion time is the interval between the release of the hold state (imposed by the input circuitry of a track-and-hold) and the instant at which the voltage on the sampling capacitor settles to within one LSB of a new input value.

DNL – Differential Non-Linearity

For an ideal ADC, the analog-input levels that trigger any two successive output codes should differ by one LSB (DNL = 0). Any deviation from one LSB is defined as DNL (Figure 2-83).

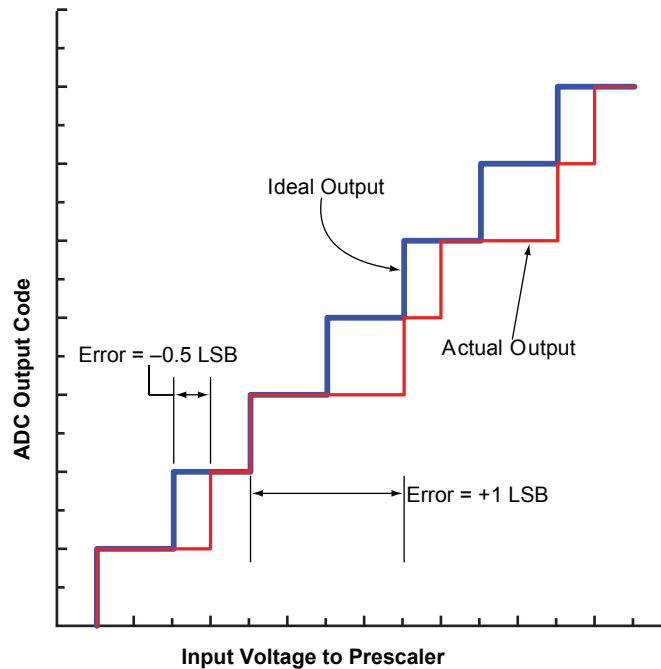


Figure 2-83 • Differential Non-Linearity (DNL)

ENOB – Effective Number of Bits

ENOB specifies the dynamic performance of an ADC at a specific input frequency and sampling rate. An ideal ADC's error consists only of quantization of noise. As the input frequency increases, the overall noise (particularly in the distortion components) also increases, thereby reducing the ENOB and SINAD (also see "Signal-to-Noise and Distortion Ratio (SINAD)"). ENOB for a full-scale, sinusoidal input waveform is computed using EQ 12.

$$ENOB = \frac{SINAD - 1.76}{6.02}$$

EQ 12

FS Error – Full-Scale Error

Full-scale error is the difference between the actual value that triggers that transition to full-scale and the ideal analog full-scale transition value. Full-scale error equals offset error plus gain error.

INL – Integral Non-Linearity

INL is the deviation of an actual transfer function from a straight line. After nullifying offset and gain errors, the straight line is either a best-fit straight line or a line drawn between the end points of the transfer function (Figure 2-85).

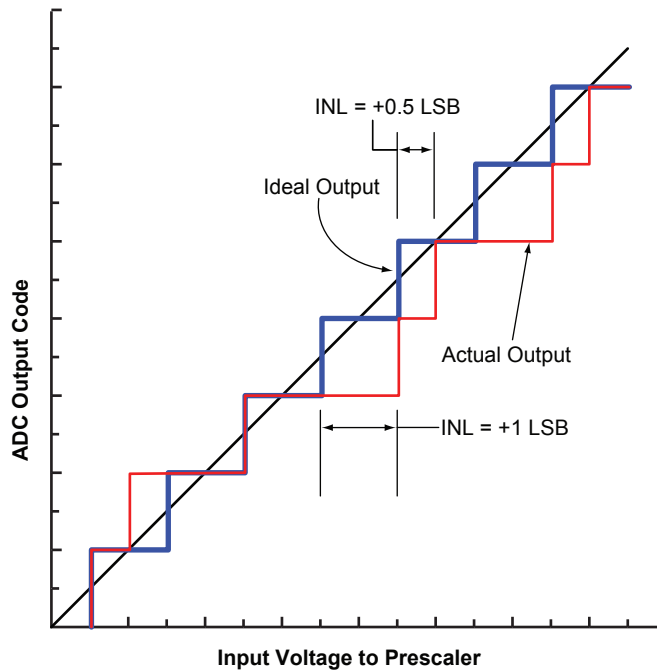


Figure 2-85 • Integral Non-Linearity (INL)

LSB – Least Significant Bit

In a binary number, the LSB is the least weighted bit in the group. Typically, the LSB is the furthest right bit. For an ADC, the weight of an LSB equals the full-scale voltage range of the converter divided by 2^N , where N is the converter's resolution.

EQ 13 shows the calculation for a 10-bit ADC with a unipolar full-scale voltage of 2.56 V:

$$1 \text{ LSB} = (2.56 \text{ V} / 2^{10}) = 2.5 \text{ mV}$$

EQ 13

No Missing Codes

An ADC has no missing codes if it produces all possible digital codes in response to a ramp signal applied to the analog input.

Table 2-50 • ADC Characteristics in Direct Input Mode
Commercial Temperature Range Conditions, $T_J = 85^{\circ}\text{C}$ (unless noted otherwise),
Typical: $V_{CC33A} = 3.3\text{ V}$, $V_{CC} = 1.5\text{ V}$

| Parameter | Description | Condition | Min. | Typ. | Max. | Units |
|--|--|--|-------|--------|---------------|----------|
| Direct Input using Analog Pad AV, AC, AT | | | | | | |
| VINADC | Input Voltage (Direct Input) | Refer to Table 3-2 on page 3-3 | | | | |
| CINADC | Input Capacitance | Channel not selected | | 7 | | pF |
| | | Channel selected but not sampling | | 8 | | pF |
| | | Channel selected and sampling | | 18 | | pF |
| ZINADC | Input Impedance | 8-bit mode | | 2 | | kΩ |
| | | 10-bit mode | | 2 | | kΩ |
| | | 12-bit mode | | 2 | | kΩ |
| Analog Reference Voltage VAREF | | | | | | |
| VAREF | Accuracy | T _J = 25°C | 2.537 | 2.56 | 2.583 | V |
| | Temperature Drift of Internal Reference | | | 65 | | ppm / °C |
| | External Reference | | 2.527 | | VCC33A + 0.05 | V |
| ADC Accuracy (using external reference) ^{1,2} | | | | | | |
| DC Accuracy | | | | | | |
| TUE | Total Unadjusted Error | 8-bit mode | 0.29 | | | LSB |
| | | 10-bit mode | 0.72 | | | LSB |
| | | 12-bit mode | 1.8 | | | LSB |
| INL | Integral Non-Linearity | 8-bit mode | | 0.20 | 0.25 | LSB |
| | | 10-bit mode | | 0.32 | 0.43 | LSB |
| | | 12-bit mode | | 1.71 | 1.80 | LSB |
| DNL | Differential Non-Linearity (no missing code) | 8-bit mode | | 0.20 | 0.24 | LSB |
| | | 10-bit mode | | 0.60 | 0.65 | LSB |
| | | 12-bit mode | | 2.40 | 2.48 | LSB |
| | Offset Error | 8-bit mode | | 0.01 | 0.17 | LSB |
| | | 10-bit mode | | 0.05 | 0.20 | LSB |
| | | 12-bit mode | | 0.20 | 0.40 | LSB |
| | Gain Error | 8-bit mode | | 0.0004 | 0.003 | LSB |
| | | 10-bit mode | | 0.002 | 0.011 | LSB |
| | | 12-bit mode | | 0.007 | 0.044 | LSB |
| | Gain Error (with internal reference) | All modes | | 2 | | % FSR |

Notes:

1. Accuracy of the external reference is $2.56\text{ V} \pm 4.6\text{ mV}$.
2. Data is based on characterization.
3. The sample rate is time-shared among active analog inputs.

Timing Characteristics

Table 2-55 • Analog Configuration Multiplexer (ACM) Timing
 Commercial Temperature Range Conditions: $T_J = 70^{\circ}\text{C}$, Worst-Case $V_{CC} = 1.425\text{ V}$

| Parameter | Description | -2 | -1 | Std. | Units |
|------------------|--|-------|-------|-------|-------|
| $t_{CLKQACM}$ | Clock-to-Q of the ACM | 19.73 | 22.48 | 26.42 | ns |
| t_{SUDACM} | Data Setup time for the ACM | 4.39 | 5.00 | 5.88 | ns |
| t_{HDACM} | Data Hold time for the ACM | 0.00 | 0.00 | 0.00 | ns |
| t_{SUAACM} | Address Setup time for the ACM | 4.73 | 5.38 | 6.33 | ns |
| t_{HAACM} | Address Hold time for the ACM | 0.00 | 0.00 | 0.00 | ns |
| t_{SUEACM} | Enable Setup time for the ACM | 3.93 | 4.48 | 5.27 | ns |
| t_{HEACM} | Enable Hold time for the ACM | 0.00 | 0.00 | 0.00 | ns |
| $t_{MPWARACM}$ | Asynchronous Reset Minimum Pulse Width for the ACM | 10.00 | 10.00 | 10.00 | ns |
| $t_{REMARACM}$ | Asynchronous Reset Removal time for the ACM | 12.98 | 14.79 | 17.38 | ns |
| $t_{RECARACM}$ | Asynchronous Reset Recovery time for the ACM | 12.98 | 14.79 | 17.38 | ns |
| $t_{MPWCLKACM}$ | Clock Minimum Pulse Width for the ACM | 45.00 | 45.00 | 45.00 | ns |
| $t_{FMAXCLKACM}$ | lock Maximum Frequency for the ACM | 10.00 | 10.00 | 10.00 | MHz |

Features Supported on Pro I/Os

Table 2-72 lists all features supported by transmitter/receiver for single-ended and differential I/Os.

Table 2-72 • Fusion Pro I/O Features

| Feature | Description |
|--|--|
| Single-ended and voltage-referenced transmitter features | • Hot insertion in every mode except PCI or 5 V input tolerant (these modes use clamp diodes and do not allow hot insertion) |
| | • Activation of hot insertion (disabling the clamp diode) is selectable by I/Os. |
| | • Weak pull-up and pull-down |
| | • Two slew rates |
| | • Skew between output buffer enable/disable time: 2 ns delay (rising edge) and 0 ns delay (falling edge); see "Selectable Skew between Output Buffer Enable/Disable Time" on page 2-149 for more information |
| | • Five drive strengths |
| | • 5 V–tolerant receiver ("5 V Input Tolerance" section on page 2-144) |
| | • LVTTTL/LVCMOS 3.3 V outputs compatible with 5 V TTL inputs ("5 V Output Tolerance" section on page 2-148) |
| | • High performance (Table 2-76 on page 2-143) |
| Single-ended receiver features | • Schmitt trigger option |
| | • ESD protection |
| | • Programmable delay: 0 ns if bypassed, 0.625 ns with '000' setting, 6.575 ns with '111' setting, 0.85-ns intermediate delay increments (at 25°C, 1.5 V) |
| | • High performance (Table 2-76 on page 2-143) |
| | • Separate ground planes, GND/GNDQ, for input buffers only to avoid output-induced noise in the input circuitry |
| Voltage-referenced differential receiver features | • Programmable Delay: 0 ns if bypassed, 0.625 ns with '000' setting, 6.575 ns with '111' setting, 0.85-ns intermediate delay increments (at 25°C, 1.5 V) |
| | • High performance (Table 2-76 on page 2-143) |
| | • Separate ground planes, GND/GNDQ, for input buffers only to avoid output-induced noise in the input circuitry |
| CMOS-style LVDS, BLVDS, M-LVDS, or LVPECL transmitter | • Two I/Os and external resistors are used to provide a CMOS-style LVDS, BLVDS, M-LVDS, or LVPECL transmitter solution. |
| | • Activation of hot insertion (disabling the clamp diode) is selectable by I/Os. |
| | • Weak pull-up and pull-down |
| | • Fast slew rate |
| LVDS/LVPECL differential receiver features | • ESD protection |
| | • High performance (Table 2-76 on page 2-143) |
| | • Programmable delay: 0.625 ns with '000' setting, 6.575 ns with '111' setting, 0.85-ns intermediate delay increments (at 25°C, 1.5 V) |
| | • Separate input buffer ground and power planes to avoid output-induced noise in the input circuitry |

Table 2-77 • Comparison Table for 5 V–Compliant Receiver Scheme

| Scheme | Board Components | Speed | Current Limitations |
|--------|--|--------------------------|--|
| 1 | Two resistors | Low to high ¹ | Limited by transmitter's drive strength |
| 2 | Resistor and Zener 3.3 V | Medium | Limited by transmitter's drive strength |
| 3 | Bus switch | High | N/A |
| 4 | Minimum resistor value ² R = 47 Ω at T _J = 70°C R = 150 Ω at T _J = 85°C R = 420 Ω at T _J = 100°C | Medium | Maximum diode current at 100% duty cycle, signal constantly at '1' 52.7 mA at T _J = 70°C / 10-year lifetime 16.5 mA at T _J = 85°C / 10-year lifetime 5.9 mA at T _J = 100°C / 10-year lifetime For duty cycles other than 100%, the currents can be increased by a factor = 1 / (duty cycle). Example: 20% duty cycle at 70°C Maximum current = (1 / 0.2) * 52.7 mA = 5 * 52.7 mA = 263.5 mA |

Notes:

1. Speed and current consumption increase as the board resistance values decrease.
2. Resistor values ensure I/O diode long-term reliability.

Table 2-81 • Fusion Pro I/O Default Attributes

| I/O Standards | SLEW (output only) | OUT_DRIVE (output only) | SKEW (tribuf and bibuf only) | RES_PULL | OUT_LOAD (output only) | COMBINE_REGISTER | IN_DELAY (input only) | IN_DELAY_VAL (input only) | SCHMITT_TRIGGER (input only) |
|----------------------|---|---|------------------------------|----------|------------------------|------------------|-----------------------|---------------------------|------------------------------|
| LVTTL/LVCMOS 3.3 V | Refer to the following tables for more information: Table 2-78 on page 2-152 Table 2-79 on page 2-152 Table 2-80 on page 2-152 | Refer to the following tables for more information: Table 2-78 on page 2-152 Table 2-79 on page 2-152 Table 2-80 on page 2-152 | Off | None | 35 pF | – | Off | 0 | Off |
| LVC MOS 2.5 V | | | Off | None | 35 pF | – | Off | 0 | Off |
| LVC MOS 2.5/5.0 V | | | Off | None | 35 pF | – | Off | 0 | Off |
| LVC MOS 1.8 V | | | Off | None | 35 pF | – | Off | 0 | Off |
| LVC MOS 1.5 V | | | Off | None | 35 pF | – | Off | 0 | Off |
| PCI (3.3 V) | | | Off | None | 10 pF | – | Off | 0 | Off |
| PCI-X (3.3 V) | | | Off | None | 10 pF | – | Off | 0 | Off |
| GTL+ (3.3 V) | | | Off | None | 10 pF | – | Off | 0 | Off |
| GTL+ (2.5 V) | | | Off | None | 10 pF | – | Off | 0 | Off |
| GTL (3.3 V) | | | Off | None | 10 pF | – | Off | 0 | Off |
| GTL (2.5 V) | | | Off | None | 10 pF | – | Off | 0 | Off |
| HSTL Class I | | | Off | None | 20 pF | – | Off | 0 | Off |
| HSTL Class II | | | Off | None | 20 pF | – | Off | 0 | Off |
| SSTL2 Class I and II | | | Off | None | 30 pF | – | Off | 0 | Off |
| SSTL3 Class I and II | | | Off | None | 30 pF | – | Off | 0 | Off |
| LVDS, BLVDS, M-LVDS | | | Off | None | 0 pF | – | Off | 0 | Off |
| LVPECL | | | Off | None | 0 pF | – | Off | 0 | Off |

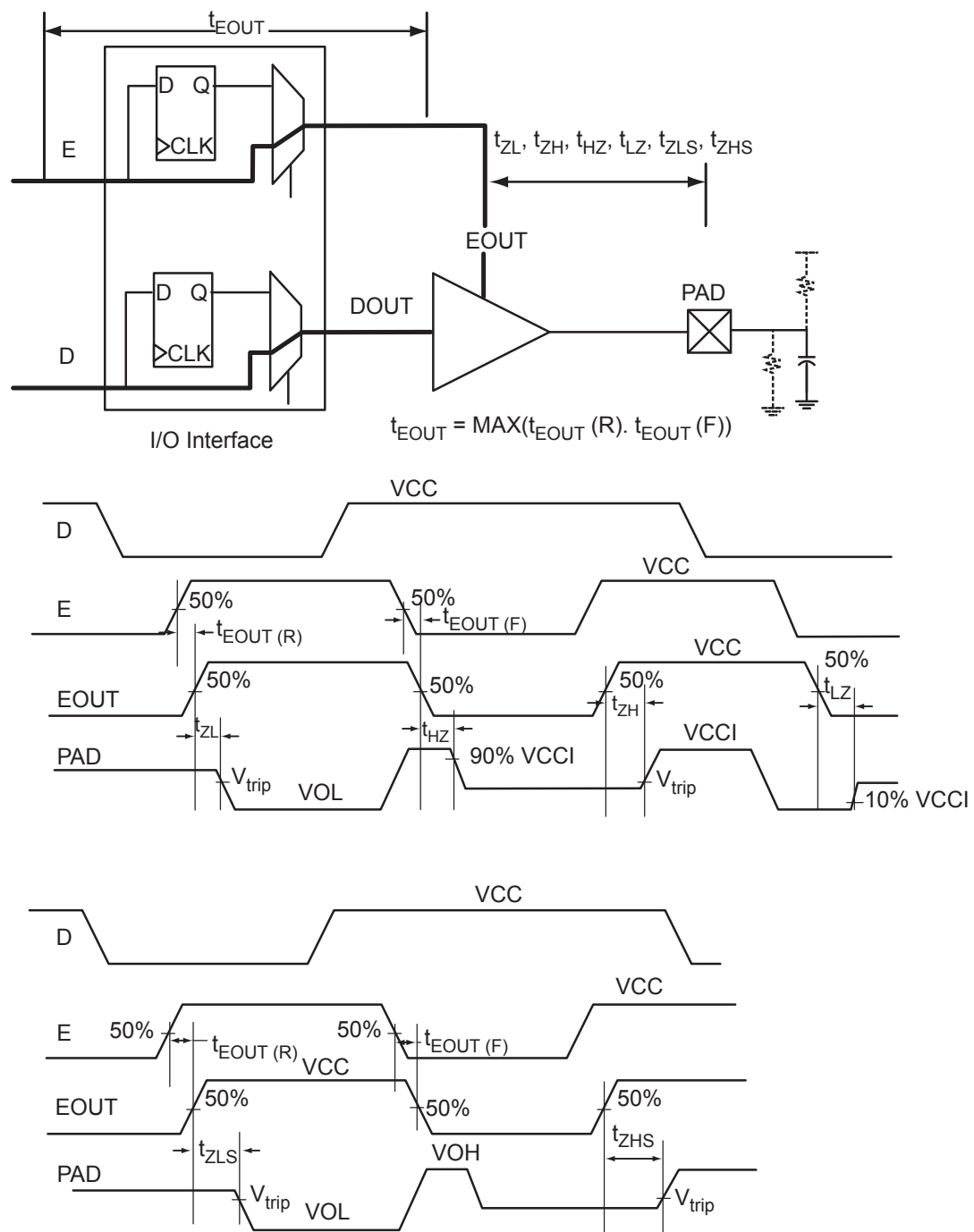


Figure 2-118 • Tristate Output Buffer Timing Model and Delays (example)

Output DDR

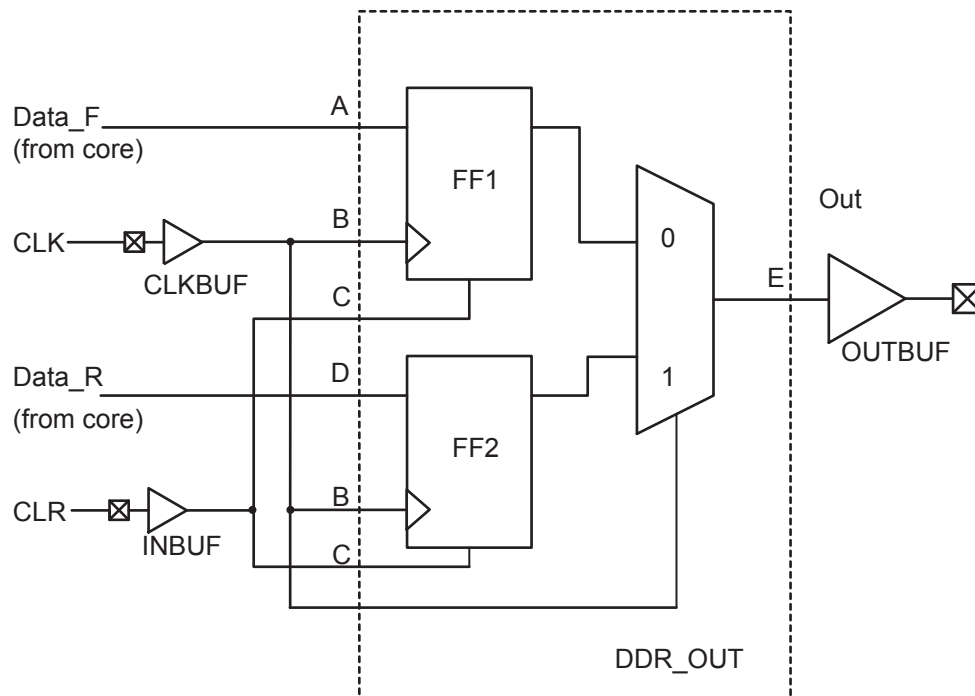


Figure 2-144 • Output DDR Timing Model

Table 2-181 • Parameter Definitions

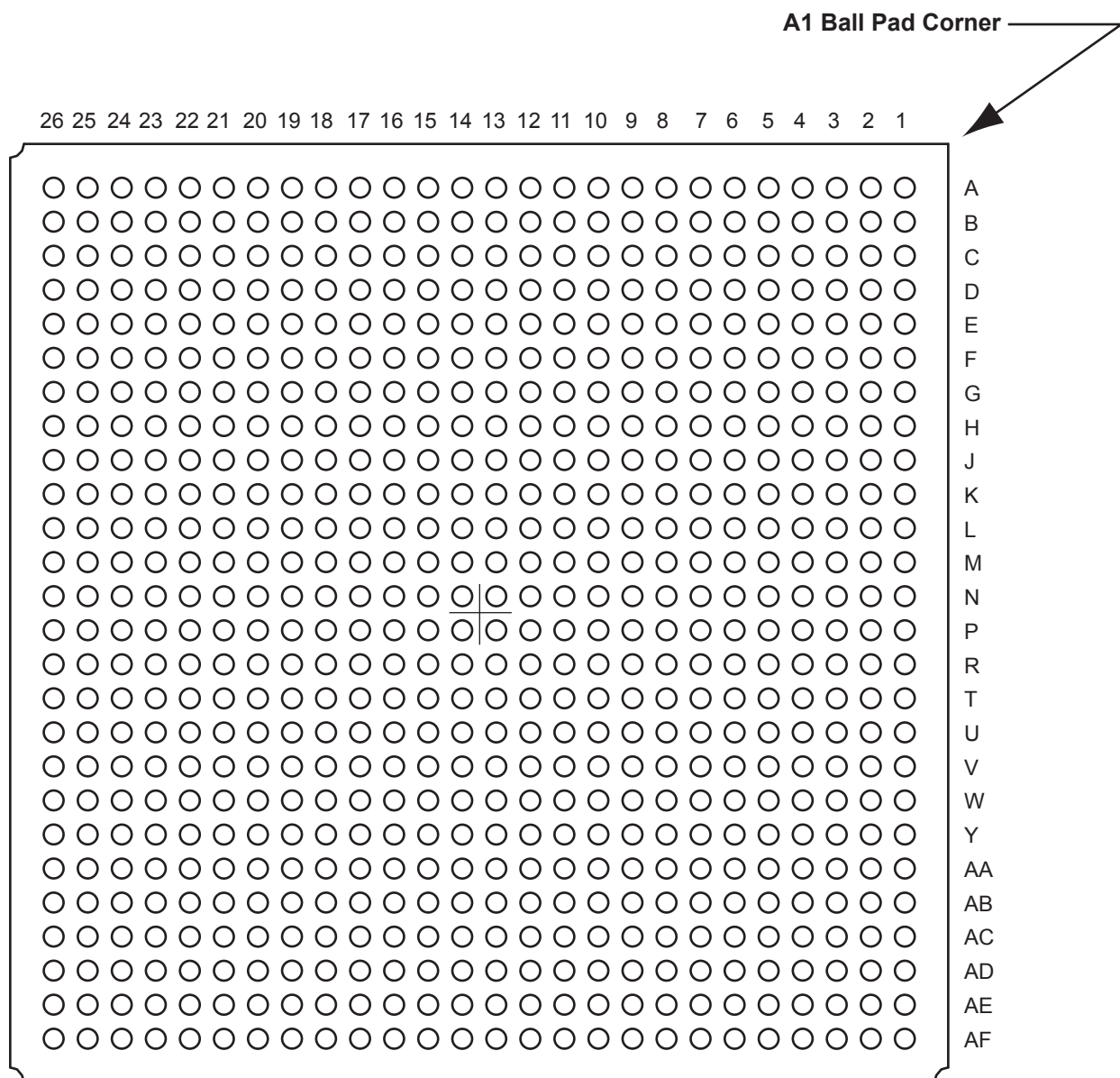
| Parameter Name | Parameter Definition | Measuring Nodes (From, To) |
|------------------|---------------------------|----------------------------|
| $t_{DDROCLKQ}$ | Clock-to-Out | B, E |
| $t_{DDROCLR2Q}$ | Asynchronous Clear-to-Out | C, E |
| $t_{DDROREMCLR}$ | Clear Removal | C, B |
| $t_{DDRORECCLR}$ | Clear Recovery | C, B |
| $t_{DDROSUD1}$ | Data Setup Data_F | A, B |
| $t_{DDROSUD2}$ | Data Setup Data_R | D, B |
| $t_{DDROHD1}$ | Data Hold Data_F | A, B |
| $t_{DDROHD2}$ | Data Hold Data_R | D, B |

| QN180 | | |
|------------|-----------------|-----------------|
| Pin Number | AFS090 Function | AFS250 Function |
| B9 | XTAL2 | XTAL2 |
| B10 | GEA0/IO44NDB3V0 | GFA0/IO66NDB3V0 |
| B11 | GEB2/IO42PDB3V0 | IO60NDB3V0 |
| B12 | VCC | VCC |
| B13 | VCCNVM | VCCNVM |
| B14 | VCC15A | VCC15A |
| B15 | NCAP | NCAP |
| B16 | VCC33N | VCC33N |
| B17 | GNDQAQ | GNDQAQ |
| B18 | AC0 | AC0 |
| B19 | AT0 | AT0 |
| B20 | AT1 | AT1 |
| B21 | AV1 | AV1 |
| B22 | AC2 | AC2 |
| B23 | ATRTN1 | ATRTN1 |
| B24 | AG3 | AG3 |
| B25 | AV3 | AV3 |
| B26 | AG4 | AG4 |
| B27 | ATRTN2 | ATRTN2 |
| B28 | NC | AC5 |
| B29 | VCC33A | VCC33A |
| B30 | VAREF | VAREF |
| B31 | PUB | PUB |
| B32 | PTEM | PTEM |
| B33 | GNDNVM | GNDNVM |
| B34 | VCC | VCC |
| B35 | TCK | TCK |
| B36 | TMS | TMS |
| B37 | TRST | TRST |
| B38 | GDB2/IO41PSB1V0 | GDA2/IO55PSB1V0 |
| B39 | GDC0/IO38NDB1V0 | GDB0/IO53NDB1V0 |
| B40 | VCCIB1 | VCCIB1 |
| B41 | GCA1/IO36PDB1V0 | GCA1/IO49PDB1V0 |
| B42 | GCC0/IO34NDB1V0 | GCC0/IO47NDB1V0 |
| B43 | GCB2/IO33PSB1V0 | GBC2/IO42PSB1V0 |
| B44 | VCC | VCC |

| QN180 | | |
|------------|-----------------|-----------------|
| Pin Number | AFS090 Function | AFS250 Function |
| B45 | GBA2/IO31PDB1V0 | GBA2/IO40PDB1V0 |
| B46 | GNDQ | GNDQ |
| B47 | GBA1/IO30RSB0V0 | GBA0/IO38RSB0V0 |
| B48 | GBB1/IO28RSB0V0 | GBC1/IO35RSB0V0 |
| B49 | VCC | VCC |
| B50 | GBC0/IO25RSB0V0 | IO31RSB0V0 |
| B51 | IO23RSB0V0 | IO28RSB0V0 |
| B52 | IO20RSB0V0 | IO25RSB0V0 |
| B53 | VCC | VCC |
| B54 | IO11RSB0V0 | IO14RSB0V0 |
| B55 | IO08RSB0V0 | IO11RSB0V0 |
| B56 | GAC1/IO05RSB0V0 | IO08RSB0V0 |
| B57 | VCCIB0 | VCCIB0 |
| B58 | GAB0/IO02RSB0V0 | GAC0/IO04RSB0V0 |
| B59 | GAA0/IO00RSB0V0 | GAA1/IO01RSB0V0 |
| B60 | VCCPLA | VCCPLA |
| C1 | NC | NC |
| C2 | NC | VCCIB3 |
| C3 | GND | GND |
| C4 | NC | GFC2/IO69PPB3V0 |
| C5 | GFC1/IO49PDB3V0 | GFC1/IO68PDB3V0 |
| C6 | GFA0/IO47NPB3V0 | GFB0/IO67NPB3V0 |
| C7 | VCCIB3 | NC |
| C8 | GND | GND |
| C9 | GEA1/IO44PDB3V0 | GFA1/IO66PDB3V0 |
| C10 | GEA2/IO42NDB3V0 | GEC2/IO60PDB3V0 |
| C11 | NC | GEA2/IO58PSB3V0 |
| C12 | NC | NC |
| C13 | GND | GND |
| C14 | NC | NC |
| C15 | NC | NC |
| C16 | GNDA | GNDA |
| C17 | NC | NC |
| C18 | NC | NC |
| C19 | NC | NC |
| C20 | NC | NC |

| FG256 | | | | |
|------------|-----------------|-----------------|-----------------|------------------|
| Pin Number | AFS090 Function | AFS250 Function | AFS600 Function | AFS1500 Function |
| K9 | VCC | VCC | VCC | VCC |
| K10 | GND | GND | GND | GND |
| K11 | NC | GDC2/IO57PPB1V0 | GDC2/IO57PPB2V0 | GDC2/IO84PPB2V0 |
| K12 | GND | GND | GND | GND |
| K13 | NC | GDA0/IO54NDB1V0 | GDA0/IO54NDB2V0 | GDA0/IO81NDB2V0 |
| K14 | NC | GDA2/IO55PPB1V0 | GDA2/IO55PPB2V0 | GDA2/IO82PPB2V0 |
| K15 | VCCIB1 | VCCIB1 | VCCIB2 | VCCIB2 |
| K16 | NC | GDB1/IO53PPB1V0 | GDB1/IO53PPB2V0 | GDB1/IO80PPB2V0 |
| L1 | NC | GEC1/IO63PDB3V0 | GEC1/IO63PDB4V0 | GEC1/IO90PDB4V0 |
| L2 | NC | GEC0/IO63NDB3V0 | GEC0/IO63NDB4V0 | GEC0/IO90NDB4V0 |
| L3 | NC | GEB1/IO62PDB3V0 | GEB1/IO62PDB4V0 | GEB1/IO89PDB4V0 |
| L4 | NC | GEB0/IO62NDB3V0 | GEB0/IO62NDB4V0 | GEB0/IO89NDB4V0 |
| L5 | NC | IO60NDB3V0 | IO60NDB4V0 | IO87NDB4V0 |
| L6 | NC | GEC2/IO60PDB3V0 | GEC2/IO60PDB4V0 | GEC2/IO87PDB4V0 |
| L7 | GNDA | GNDA | GNDA | GNDA |
| L8 | AC0 | AC0 | AC2 | AC2 |
| L9 | AV2 | AV2 | AV4 | AV4 |
| L10 | AC3 | AC3 | AC5 | AC5 |
| L11 | PTEM | PTEM | PTEM | PTEM |
| L12 | TDO | TDO | TDO | TDO |
| L13 | VJTAG | VJTAG | VJTAG | VJTAG |
| L14 | NC | IO57NPB1V0 | IO57NPB2V0 | IO84NPB2V0 |
| L15 | GDB2/IO41PPB1V0 | GDB2/IO56PPB1V0 | GDB2/IO56PPB2V0 | GDB2/IO83PPB2V0 |
| L16 | NC | IO55NPB1V0 | IO55NPB2V0 | IO82NPB2V0 |
| M1 | GND | GND | GND | GND |
| M2 | NC | GEA1/IO61PDB3V0 | GEA1/IO61PDB4V0 | GEA1/IO88PDB4V0 |
| M3 | NC | GEA0/IO61NDB3V0 | GEA0/IO61NDB4V0 | GEA0/IO88NDB4V0 |
| M4 | VCCIB3 | VCCIB3 | VCCIB4 | VCCIB4 |
| M5 | NC | IO58NPB3V0 | IO58NPB4V0 | IO85NPB4V0 |
| M6 | NC | NC | AV0 | AV0 |
| M7 | NC | NC | AC1 | AC1 |
| M8 | AG1 | AG1 | AG3 | AG3 |
| M9 | AC2 | AC2 | AC4 | AC4 |
| M10 | AC4 | AC4 | AC6 | AC6 |
| M11 | NC | AG5 | AG7 | AG7 |
| M12 | VPUMP | VPUMP | VPUMP | VPUMP |
| M13 | VCCIB1 | VCCIB1 | VCCIB2 | VCCIB2 |
| M14 | TMS | TMS | TMS | TMS |

FG676



Note

For Package Manufacturing and Environmental information, visit the Resource Center at <http://www.microsemi.com/soc/products/solutions/package/default.aspx>.

| Revision | Changes | Page |
|---------------------------------|--|-------------------|
| v2.0, Revision 1 (continued) | The data in the 2.5 V LCMOS and LVCMOS 2.5 V / 5.0 V rows were updated in Table 2-75 • Fusion Standard and Advanced I/O – Hot-Swap and 5 V Input Tolerance Capabilities . | 2-143 |
| | In Table 2-78 • Fusion Standard I/O Standards—OUT_DRIVE Settings , LVCMOS 1.5 V, for OUT_DRIVE 2, was changed from a dash to a check mark. | 2-152 |
| | The "VCC15A Analog Power Supply (1.5 V)" definition was changed from "A 1.5 V analog power supply input should be used to provide this input" to "1.5 V clean analog power supply input for use by the 1.5 V portion of the analog circuitry." | 2-223 |
| | In the "VCC33PMP Analog Power Supply (3.3 V)" pin description, the following text was changed from "VCC33PMP should be powered up before or simultaneously with VCC33A" to "VCC33PMP should be powered up simultaneously with or after VCC33A." | 2-223 |
| | The "VCCOSC Oscillator Power Supply (3.3 V)" section was updated to include information about when to power the pin. | 2-223 |
| | In the "128-Bit AES Decryption" section, FIPS-192 was incorrect and changed to FIPS-197. | 2-228 |
| | The note in Table 2-84 • Fusion Standard and Advanced I/O Attributes vs. I/O Standard Applications was updated. | 2-156 |
| | For 1.5 V LVCMOS, the VIL and VIH parameters, 0.30 * VCCI was changed to 0.35 * VCCI and 0.70 * VCCI was changed to 0.65 * VCCI in Table 2-86 • Summary of Maximum and Minimum DC Input and Output Levels Applicable to Commercial and Industrial Conditions , Table 2-87 • Summary of Maximum and Minimum DC Input and Output Levels Applicable to Commercial and Industrial Conditions , and Table 2-88 • Summary of Maximum and Minimum DC Input and Output Levels Applicable to Commercial and Industrial Conditions . In Table 2-87 • Summary of Maximum and Minimum DC Input and Output Levels Applicable to Commercial and Industrial Conditions , the VIH max column was updated. | 2-164 to 2-165 |
| | Table 2-89 • Summary of Maximum and Minimum DC Input Levels Applicable to Commercial and Industrial Conditions was updated to include notes 3 and 4. The temperature ranges were also updated in notes 1 and 2. | 2-165 |
| | The titles in Table 2-92 • Summary of I/O Timing Characteristics – Software Default Settings to Table 2-94 • Summary of I/O Timing Characteristics – Software Default Settings were updated to "VCCI = I/O Standard Dependent." | 2-167 to 2-168 |
| | Below Table 2-98 • I/O Short Currents IOSH/IOSL , the paragraph was updated to change 110°C to 100°C and three months was changed to six months. | 2-172 |
| | Table 2-99 • Short Current Event Duration before Failure was updated to remove 110°C data. | 2-174 |
| | In Table 2-101 • I/O Input Rise Time, Fall Time, and Related I/O Reliability , LVTTTL/LVCMOS rows were changed from 110°C to 100°C. | 2-174 |
| | VCC33PMP was added to Table 3-1 • Absolute Maximum Ratings . In addition, conditions for AV, AC, AG, and AT were also updated. | 3-1 |
| | VCC33PMP was added to Table 3-2 • Recommended Operating Conditions1 . In addition, conditions for AV, AC, AG, and AT were also updated. | 3-3 |
| | Table 3-5 • FPGA Programming, Storage, and Operating Limits was updated to include new data and the temperature ranges were changed. The notes were removed from the table. | 3-5 |