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### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

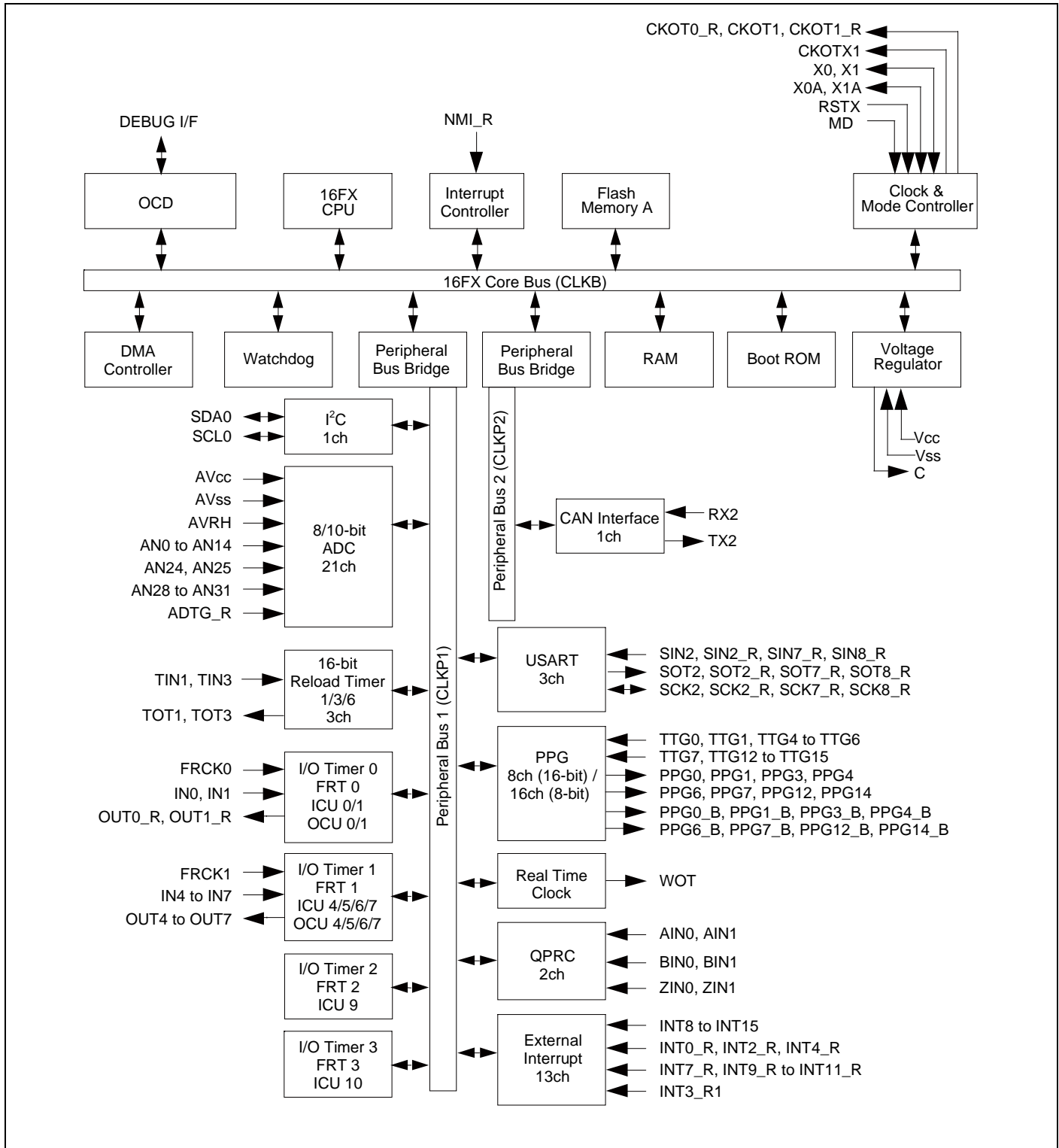
### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Obsolete
Core Processor	F <sup>2</sup> MC-16FX
Core Size	16-Bit
Speed	32MHz
Connectivity	CANbus, I <sup>2</sup> C, LINbus, SCI, UART/USART
Peripherals	DMA, LVD, POR, PWM, WDT
Number of I/O	52
Program Memory Size	64KB (64K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	4K x 8
Voltage - Supply (Vcc/Vdd)	2.7V ~ 5.5V
Data Converters	A/D 21x8/10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	64-LQFP
Supplier Device Package	64-LQFP (12x12)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/infineon-technologies/mb96f622rbpmc-gse1">https://www.e-xfl.com/product-detail/infineon-technologies/mb96f622rbpmc-gse1</a>

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## 2. Block Diagram



Pin no.	I/O circuit type*	Pin name
33	N	P04_5 / SCL0
34	O	DEBUG I/F
35	H	P17_0
36	C	MD
37	A	X0
38	A	X1
39	Supply	Vss
40	B	P04_0 / X0A
41	B	P04_1 / X1A
42	C	RSTX
43	J	P11_7 / SEG3 / IN0_R
44	J	P11_0 / COM0
45	J	P11_1 / COM1 / PPG0_R
46	J	P11_2 / COM2 / PPG1_R
47	J	P11_3 / COM3 / PPG2_R
48	J	P12_0 / SEG4 / IN1_R
49	J	P12_1 / SEG5 / TIN1_R / PPG0_B
50	J	P12_2 / SEG6 / TOT1_R / PPG1_B
51	J	P12_4 / SEG8
52	J	P12_5 / SEG9 / TIN2_R / PPG2_B
53	J	P12_6 / SEG10 / TOT2_R / PPG3_B
54	J	P12_7 / SEG11 / INT1_R
55	J	P01_1 / SEG21 / CKOT1
56	J	P01_3 / SEG23
57	L	P03_0 / SEG36 / V0
58	L	P03_1 / SEG37 / V1
59	L	P03_2 / SEG38 / V2
60	L	P03_3 / SEG39 / V3
61	M	P03_4 / RX0 / INT4
62	H	P03_5 / TX0
63	H	P03_6 / INT0 / NMI
64	Supply	Vcc

\*: See "I/O Circuit Type" for details on the I/O circuit types.

Vector number	Offset in vector table	Vector name	Cleared by DMA	Index in ICR to program	Description
81	2B8 <sub>H</sub>	OCU4	Yes	81	Output Compare Unit 4
82	2B4 <sub>H</sub>	OCU5	Yes	82	Output Compare Unit 5
83	2B0 <sub>H</sub>	OCU6	Yes	83	Output Compare Unit 6
84	2AC <sub>H</sub>	OCU7	Yes	84	Output Compare Unit 7
85	2A8 <sub>H</sub>	-	-	85	Reserved
86	2A4 <sub>H</sub>	-	-	86	Reserved
87	2A0 <sub>H</sub>	-	-	87	Reserved
88	29C <sub>H</sub>	-	-	88	Reserved
89	298 <sub>H</sub>	FRT0	Yes	89	Free-Running Timer 0
90	294 <sub>H</sub>	FRT1	Yes	90	Free-Running Timer 1
91	290 <sub>H</sub>	FRT2	Yes	91	Free-Running Timer 2
92	28C <sub>H</sub>	FRT3	Yes	92	Free-Running Timer 3
93	288 <sub>H</sub>	RTC0	No	93	Real Time Clock
94	284 <sub>H</sub>	CAL0	No	94	Clock Calibration Unit
95	280 <sub>H</sub>	-	-	95	Reserved
96	27C <sub>H</sub>	IIC0	Yes	96	I <sup>2</sup> C interface 0
97	278 <sub>H</sub>	-	-	97	Reserved
98	274 <sub>H</sub>	ADC0	Yes	98	A/D Converter 0
99	270 <sub>H</sub>	-	-	99	Reserved
100	26C <sub>H</sub>	-	-	100	Reserved
101	268 <sub>H</sub>	-	-	101	Reserved
102	264 <sub>H</sub>	-	-	102	Reserved
103	260 <sub>H</sub>	-	-	103	Reserved
104	25C <sub>H</sub>	-	-	104	Reserved
105	258 <sub>H</sub>	LINR2	Yes	105	LIN USART 2 RX
106	254 <sub>H</sub>	LINT2	Yes	106	LIN USART 2 TX
107	250 <sub>H</sub>	-	-	107	Reserved
108	24C <sub>H</sub>	-	-	108	Reserved
109	248 <sub>H</sub>	-	-	109	Reserved
110	244 <sub>H</sub>	-	-	110	Reserved
111	240 <sub>H</sub>	-	-	111	Reserved
112	23C <sub>H</sub>	-	-	112	Reserved
113	238 <sub>H</sub>	-	-	113	Reserved
114	234 <sub>H</sub>	-	-	114	Reserved
115	230 <sub>H</sub>	LINR7	Yes	115	LIN USART 7 RX
116	22C <sub>H</sub>	LINT7	Yes	116	LIN USART 7 TX
117	228 <sub>H</sub>	LINR8	Yes	117	LIN USART 8 RX
118	224 <sub>H</sub>	LINT8	Yes	118	LIN USART 8 TX
119	220 <sub>H</sub>	-	-	119	Reserved
120	21C <sub>H</sub>	-	-	120	Reserved
121	218 <sub>H</sub>	-	-	121	Reserved
122	214 <sub>H</sub>	-	-	122	Reserved

## 12. Handling Precautions

Any semiconductor devices have inherently a certain rate of failure. The possibility of failure is greatly affected by the conditions in which they are used (circuit conditions, environmental conditions, etc.). This page describes precautions that must be observed to minimize the chance of failure and to obtain higher reliability from your Cypress semiconductor devices.

### 12.1 Precautions for Product Design

This section describes precautions when designing electronic equipment using semiconductor devices.

#### ■ Absolute Maximum Ratings

Semiconductor devices can be permanently damaged by application of stress (voltage, current, temperature, etc.) in excess of certain established limits, called absolute maximum ratings. Do not exceed these ratings.

#### ■ Recommended Operating Conditions

Recommended operating conditions are normal operating ranges for the semiconductor device. All the device's electrical characteristics are warranted when operated within these ranges.

Always use semiconductor devices within the recommended operating conditions. Operation outside these ranges may adversely affect reliability and could result in device failure.

No warranty is made with respect to uses, operating conditions, or combinations not represented on the data sheet. Users considering application outside the listed conditions are advised to contact their sales representative beforehand.

#### ■ Processing and Protection of Pins

These precautions must be followed when handling the pins which connect semiconductor devices to power supply and input/output functions.

##### 1. Preventing Over-Voltage and Over-Current Conditions

Exposure to voltage or current levels in excess of maximum ratings at any pin is likely to cause deterioration within the device, and in extreme cases leads to permanent damage of the device. Try to prevent such overvoltage or over-current conditions at the design stage.

##### 2. Protection of Output Pins

Shorting of output pins to supply pins or other output pins, or connection to large capacitance can cause large current flows. Such conditions if present for extended periods of time can damage the device. Therefore, avoid this type of connection.

##### 3. Handling of Unused Input Pins

Unconnected input pins with very high impedance levels can adversely affect stability of operation. Such pins should be connected through an appropriate resistance to a power supply pin or ground pin.

#### ■ Latch-up

Semiconductor devices are constructed by the formation of P-type and N-type areas on a substrate. When subjected to abnormally high voltages, internal parasitic PNP junctions (called thyristor structures) may be formed, causing large current levels in excess of several hundred mA to flow continuously at the power supply pin. This condition is called latch-up.

**CAUTION:** The occurrence of latch-up not only causes loss of reliability in the semiconductor device, but can cause injury or damage from high heat, smoke or flame. To prevent this from happening, do the following:

1. Be sure that voltages applied to pins do not exceed the absolute maximum ratings. This should include attention to abnormal noise, surge levels, etc.
2. Be sure that abnormal current flows do not occur during the power-on sequence.

#### ■ Observance of Safety Regulations and Standards

Most countries in the world have established standards and regulations regarding safety, protection from electromagnetic interference, etc. Customers are requested to observe applicable regulations and standards in the design of products.

#### ■ Fail-Safe Design

Any semiconductor devices have inherently a certain rate of failure. You must protect against injury, damage or loss from such failures by incorporating safety design measures into your facility and equipment such as redundancy, fire protection, and prevention of over-current levels and other abnormal operating conditions.

#### ■ Precautions Related to Usage of Devices

Cypress semiconductor devices are intended for use in standard applications (computers, office automation and other office equipment, industrial, communications, and measurement equipment, personal or household devices, etc.).

**CAUTION:** Customers considering the use of our products in special applications where failure or abnormal operation may directly affect human lives or cause physical injury or property damage, or where extremely high levels of reliability are demanded (such as aerospace systems, atomic energy controls, sea floor repeaters, vehicle operating controls, medical devices for life support, etc.) are requested to consult with sales representatives before such use. The company will not be responsible for damages arising from such use without prior approval.

### 12.2 Precautions for Package Mounting

Package mounting may be either lead insertion type or surface mount type. In either case, for heat resistance during soldering, you should only mount under Cypress's recommended conditions. For detailed information about mount conditions, contact your sales representative.

#### ■ Lead Insertion Type

Mounting of lead insertion type packages onto printed circuit boards may be done by two methods: direct soldering on the board, or mounting by using a socket.

Direct mounting onto boards normally involves processes for inserting leads into through-holes on the board and using the flow soldering (wave soldering) method of applying liquid solder. In this case, the soldering process usually causes leads to be subjected to thermal stress in excess of the absolute ratings for storage temperature. Mounting processes should conform to Cypress recommended mounting conditions.

If socket mounting is used, differences in surface treatment of the socket contacts and IC lead surfaces can lead to contact deterioration after long periods. For this reason it is recommended that the surface treatment of socket contacts and IC leads be verified before mounting.

#### ■ Surface Mount Type

Surface mount packaging has longer and thinner leads than lead-insertion packaging, and therefore leads are more easily deformed or bent. The use of packages with higher pin counts and narrower pin pitch results in increased susceptibility to open connections caused by deformed pins, or shorting due to solder bridges.

You must use appropriate mounting techniques. Cypress recommends the solder reflow method, and has established a ranking of mounting conditions for each product. Users are advised to mount packages in accordance with Cypress ranking of recommended conditions.

#### ■ Lead-Free Packaging

**CAUTION:** When ball grid array (BGA) packages with Sn-Ag-Cu balls are mounted using Sn-Pb eutectic soldering, junction strength may be reduced under some conditions of use.

#### ■ Storage of Semiconductor Devices

Because plastic chip packages are formed from plastic resins, exposure to natural environmental conditions will cause absorption of moisture. During mounting, the application of heat to a package that has absorbed moisture can cause surfaces to peel, reducing moisture resistance and causing packages to crack. To prevent, do the following:

1. Avoid exposure to rapid temperature changes, which cause moisture to condense inside the product. Store products in locations where temperature changes are slight.
2. Use dry boxes for product storage. Products should be stored below 70% relative humidity, and at temperatures between 5°C and 30°C.  
When you open Dry Package that recommends humidity 40% to 70% relative humidity.
3. When necessary, Cypress packages semiconductor devices in highly moisture-resistant aluminum laminate bags, with a silica gel desiccant. Devices should be sealed in their aluminum laminate bags for storage.
4. Avoid storing packages where they are exposed to corrosive gases or high levels of dust.

#### ■ Baking

Packages that have absorbed moisture may be de-moisturized by baking (heat drying). Follow the Cypress recommended conditions for baking.

Condition: 125°C/24 h

## 13. Handling Devices

**Special care is required for the following when handling the device:**

- Latch-up prevention
- Unused pins handling
- External clock usage
- Notes on PLL clock mode operation
- Power supply pins ( $V_{CC}/V_{SS}$ )
- Crystal oscillator and ceramic resonator circuit
- Turn on sequence of power supply to A/D converter and analog inputs
- Pin handling when not using the A/D converter
- Notes on Power-on
- Stabilization of power supply voltage
- Serial communication
- Mode Pin (MD)

### 13.1 Latch-up prevention

CMOS IC chips may suffer latch-up under the following conditions:

- A voltage higher than  $V_{CC}$  or lower than  $V_{SS}$  is applied to an input or output pin.
- A voltage higher than the rated voltage is applied between  $V_{CC}$  pins and  $V_{SS}$  pins.
- The  $AV_{CC}$  power supply is applied before the  $V_{CC}$  voltage.

Latch-up may increase the power supply current dramatically, causing thermal damages to the device.

For the same reason, extra care is required to not let the analog power-supply voltage ( $AV_{CC}$ ,  $AVRH$ ) exceed the digital power-supply voltage.

### 13.2 Unused pins handling

Unused input pins can be left open when the input is disabled (corresponding bit of Port Input Enable register  $PIER = 0$ ).

Leaving unused input pins open when the input is enabled may result in misbehavior and possible permanent damage of the device. To prevent latch-up, they must therefore be pulled up or pulled down through resistors which should be more than  $2k\Omega$ .

Unused bidirectional pins can be set either to the output state and be then left open, or to the input state with either input disabled or external pull-up/pull-down resistor as described above.



### 13.6 Crystal oscillator and ceramic resonator circuit

Noise at X0, X1 pins or X0A, X1A pins might cause abnormal operation. It is required to provide bypass capacitors with shortest possible distance to X0, X1 pins and X0A, X1A pins, crystal oscillator (or ceramic resonator) and ground lines, and, to the utmost effort, that the lines of oscillation circuit do not cross the lines of other circuits.

It is highly recommended to provide a printed circuit board art work surrounding X0, X1 pins and X0A, X1A pins with a ground area for stabilizing the operation.

It is highly recommended to evaluate the quartz/MCU or resonator/MCU system at the quartz or resonator manufacturer, especially when using low-Q resonators at higher frequencies.

### 13.7 Turn on sequence of power supply to A/D converter and analog inputs

It is required to turn the A/D converter power supply ( $AV_{CC}$ ,  $AVRH$ ) and analog inputs ( $ANn$ ) on after turning the digital power supply ( $V_{CC}$ ) on.

It is also required to turn the digital power off after turning the A/D converter supply and analog inputs off. In this case,  $AVRH$  must not exceed  $AV_{CC}$ . Input voltage for ports shared with analog input ports also must not exceed  $AV_{CC}$  (turning the analog and digital power supplies simultaneously on or off is acceptable).

### 13.8 Pin handling when not using the A/D converter

If the A/D converter is not used, the power supply pins for A/D converter should be connected such as  $AV_{CC} = V_{CC}$ ,  $AV_{SS} = AVRH = V_{SS}$ .

### 13.9 Notes on Power-on

To prevent malfunction of the internal voltage regulator, supply voltage profile while turning the power supply on should be slower than 50 $\mu$ s from 0.2V to 2.7V.

### 13.10 Stabilization of power supply voltage

If the power supply voltage varies acutely even within the operation safety range of the  $V_{CC}$  power supply voltage, a malfunction may occur. The  $V_{CC}$  power supply voltage must therefore be stabilized. As stabilization guidelines, the power supply voltage must be stabilized in such a way that  $V_{CC}$  ripple fluctuations (peak to peak value) in the commercial frequencies (50Hz to 60Hz) fall within 10% of the standard  $V_{CC}$  power supply voltage and the transient fluctuation rate becomes 0.1V/ $\mu$ s or less in instantaneous fluctuation for power supply switching.

### 13.11 Serial communication

There is a possibility to receive wrong data due to noise or other causes on the serial communication.

Therefore, design a printed circuit board so as to avoid noise.

Consider receiving of wrong data when designing the system. For example apply a checksum and retransmit the data if an error occurs.

### 13.12 Mode Pin (MD)

Connect the mode pin directly to  $V_{CC}$  or  $V_{SS}$  pin. To prevent the device unintentionally entering test mode due to noise, lay out the printed circuit board so as to minimize the distance from the mode pin to  $V_{CC}$  or  $V_{SS}$  pin and provide a low-impedance connection.

## 14. Electrical Characteristics

### 14.1 Absolute Maximum Ratings

Parameter	Symbol	Condition	Rating		Unit	Remarks
			Min	Max		
Power supply voltage <sup>*1</sup>	V <sub>CC</sub>	-	V <sub>SS</sub> - 0.3	V <sub>SS</sub> + 6.0	V	
Analog power supply voltage <sup>*1</sup>	AV <sub>CC</sub>	-	V <sub>SS</sub> - 0.3	V <sub>SS</sub> + 6.0	V	V <sub>CC</sub> = AV <sub>CC</sub> <sup>*2</sup>
Analog reference voltage <sup>*1</sup>	AVRH	-	V <sub>SS</sub> - 0.3	V <sub>SS</sub> + 6.0	V	AV <sub>CC</sub> ≥ AVRH, AVRH ≥ AV <sub>SS</sub>
Input voltage <sup>*1</sup>	V <sub>I</sub>	-	V <sub>SS</sub> - 0.3	V <sub>SS</sub> + 6.0	V	V <sub>I</sub> ≤ V <sub>CC</sub> + 0.3V <sup>*3</sup>
Output voltage <sup>*1</sup>	V <sub>O</sub>	-	V <sub>SS</sub> - 0.3	V <sub>SS</sub> + 6.0	V	V <sub>O</sub> ≤ V <sub>CC</sub> + 0.3V <sup>*3</sup>
Maximum Clamp Current	I <sub>CLAMP</sub>	-	-4.0	+4.0	mA	Applicable to general purpose I/O pins <sup>*4</sup>
Total Maximum Clamp Current	Σ I <sub>CLAMP</sub>	-	-	17	mA	Applicable to general purpose I/O pins <sup>*4</sup>
"L" level maximum output current	I <sub>OL</sub>	-	-	15	mA	
"L" level average output current	I <sub>OLAV</sub>	-	-	4	mA	
"L" level maximum overall output current	ΣI <sub>OL</sub>	-	-	42	mA	
"L" level average overall output current	ΣI <sub>OLAV</sub>	-	-	21	mA	
"H" level maximum output current	I <sub>OH</sub>	-	-	-15	mA	
"H" level average output current	I <sub>OHAV</sub>	-	-	-4	mA	
"H" level maximum overall output current	ΣI <sub>OH</sub>	-	-	-42	mA	
"H" level average overall output current	ΣI <sub>OHAV</sub>	-	-	-21	mA	
Power consumption <sup>*5</sup>	P <sub>D</sub>	T <sub>A</sub> = +125°C	-	352 <sup>*6</sup>	mW	
Operating ambient temperature	T <sub>A</sub>	-	-40	+125 <sup>*7</sup>	°C	
Storage temperature	T <sub>STG</sub>	-	-55	+150	°C	

<sup>\*1</sup>: This parameter is based on V<sub>SS</sub> = AV<sub>SS</sub> = 0V.

<sup>\*2</sup>: AV<sub>CC</sub> and V<sub>CC</sub> must be set to the same voltage. It is required that AV<sub>CC</sub> does not exceed V<sub>CC</sub> and that the voltage at the analog inputs does not exceed AV<sub>CC</sub> when the power is switched on.

<sup>\*3</sup>: V<sub>I</sub> and V<sub>O</sub> should not exceed V<sub>CC</sub> + 0.3V. V<sub>I</sub> should also not exceed the specified ratings. However if the maximum current to/from an input is limited by some means with external components, the I<sub>CLAMP</sub> rating supersedes the V<sub>I</sub> rating. Input/Output voltages of standard ports depend on V<sub>CC</sub>.

<sup>\*4</sup>: Applicable to all general purpose I/O pins (Pnn\_m).

- Use within recommended operating conditions.
- Use at DC voltage (current).
- The +B signal should always be applied a limiting resistance placed between the +B signal and the microcontroller.
- The value of the limiting resistance should be set so that when the +B signal is applied the input current to the microcontroller pin does not exceed rated values, either instantaneously or for prolonged periods.
- Note that when the microcontroller drive current is low, such as in the power saving modes, the +B input potential may pass through the protective diode and increase the potential at the V<sub>CC</sub> pin, and this may affect other devices.
- Note that if a +B signal is input when the microcontroller power supply is off (not fixed at 0V), the power supply is provided from the pins, so that incomplete operation may result.
- Note that if the +B input is applied during power-on, the power supply is provided from the pins and the resulting supply voltage may not be sufficient to operate the Power reset.

## 14.2 Recommended Operating Conditions

( $V_{SS} = AV_{SS} = 0V$ )

Parameter	Symbol	Value			Unit	Remarks
		Min	Typ	Max		
Power supply voltage	$V_{CC}, AV_{CC}$	2.7	-	5.5	V	
		2.0	-	5.5	V	Maintains RAM data in stop mode
Smoothing capacitor at C pin	$C_S$	0.5	1.0 to 3.9	4.7	$\mu F$	1.0 $\mu F$ (Allowance within $\pm 50\%$ ) 3.9 $\mu F$ (Allowance within $\pm 20\%$ ) Please use the ceramic capacitor or the capacitor of the frequency response of this level. The smoothing capacitor at $V_{CC}$ must use the one of a capacity value that is larger than $C_S$ .

### WARNING

The recommended operating conditions are required in order to ensure the normal operation of the semiconductor device. All of the device's electrical characteristics are warranted when the device is operated within these ranges.

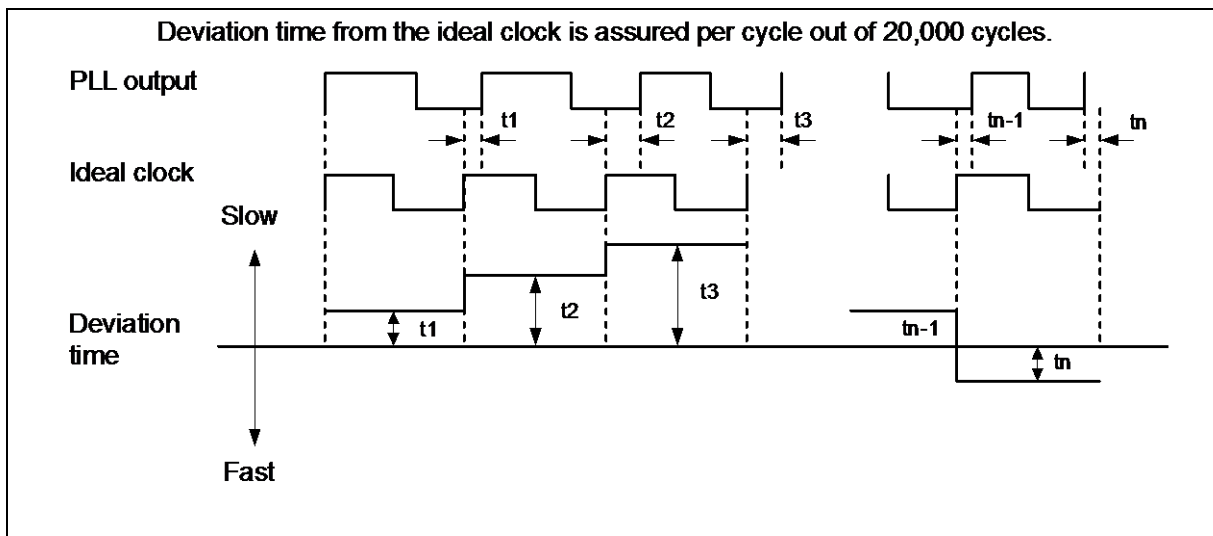
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Parameter	Symbol	Pin name	Conditions	Value			Unit	Remarks
				Min	Typ	Max		
Power supply current in Timer modes <sup>*2</sup>	I <sub>CCTPLL</sub>	V <sub>CC</sub>	PLL Timer mode with CLKPLL = 32MHz (CLKRC and CLKSC stopped)	-	1800	2245	μA	T <sub>A</sub> = +25°C
				-	-	3165	μA	T <sub>A</sub> = +105°C
				-	-	3975	μA	T <sub>A</sub> = +125°C
	I <sub>CCTMAIN</sub>		Main Timer mode with CLKMC = 4MHz, SMCR:LPMSS = 0 (CLKPLL, CLKRC and CLKSC stopped)	-	285	325	μA	T <sub>A</sub> = +25°C
				-	-	1085	μA	T <sub>A</sub> = +105°C
				-	-	1930	μA	T <sub>A</sub> = +125°C
	I <sub>CCTRCH</sub>		RC Timer mode with CLKRC = 2MHz, SMCR:LPMSS = 0 (CLKPLL, CLKMC and CLKSC stopped)	-	160	210	μA	T <sub>A</sub> = +25°C
				-	-	1025	μA	T <sub>A</sub> = +105°C
				-	-	1840	μA	T <sub>A</sub> = +125°C
	I <sub>CCTRCL</sub>		RC Timer mode with CLKRC = 100kHz (CLKPLL, CLKMC and CLKSC stopped)	-	35	75	μA	T <sub>A</sub> = +25°C
				-	-	855	μA	T <sub>A</sub> = +105°C
				-	-	1640	μA	T <sub>A</sub> = +125°C
	I <sub>CCTSUB</sub>		Sub Timer mode with CLKSC = 32kHz (CLKMC, CLKPLL and CLKRC stopped)	-	25	65	μA	T <sub>A</sub> = +25°C
				-	-	830	μA	T <sub>A</sub> = +105°C
				-	-	1620	μA	T <sub>A</sub> = +125°C

#### 14.4.5 Operating Conditions of PLL

( $V_{CC} = AV_{CC} = 2.7V$  to  $5.5V$ ,  $V_{SS} = AV_{SS} = 0V$ ,  $T_A = -40^{\circ}C$  to  $+125^{\circ}C$ )

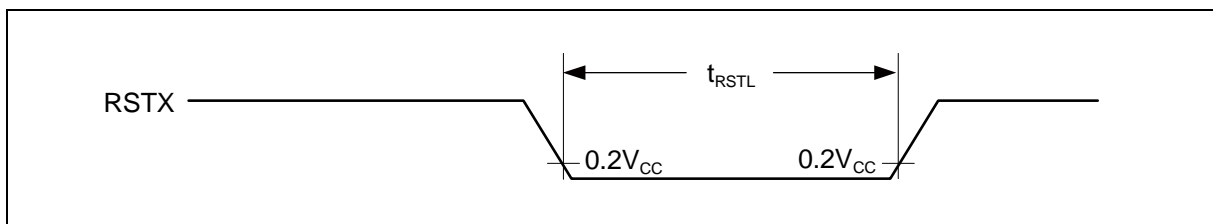
Parameter	Symbol	Value			Unit	Remarks
		Min	Typ	Max		
PLL oscillation stabilization wait time	$t_{LOCK}$	1	-	4	ms	For CLKMC = 4MHz
PLL input clock frequency	$f_{PLLI}$	4	-	8	MHz	
PLL oscillation clock frequency	$f_{CLKVCO}$	56	-	108	MHz	Permitted VCO output frequency of PLL (CLKVCO)
PLL phase jitter	$t_{PSKEW}$	-5	-	+5	ns	For CLKMC (PLL input clock) $\geq 4MHz$

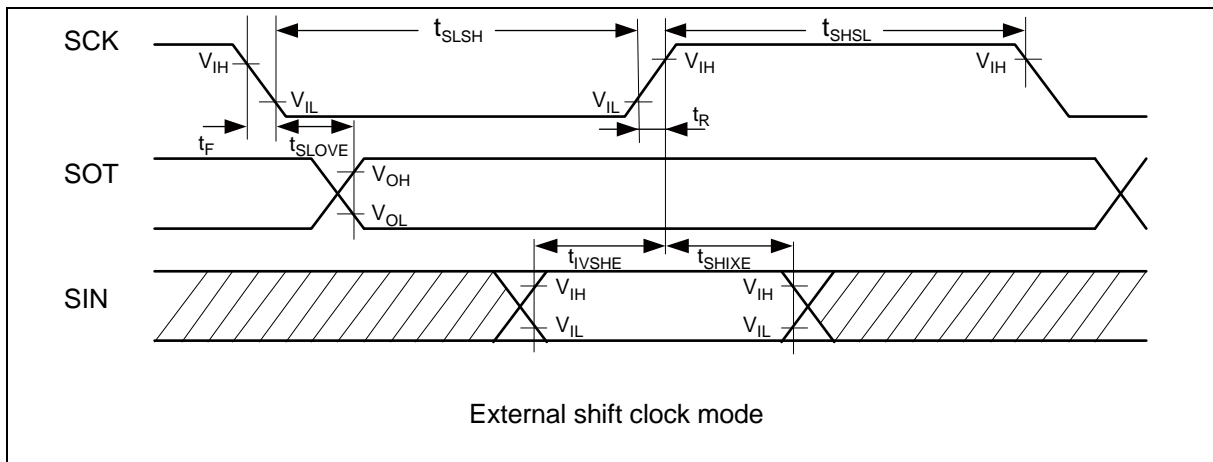
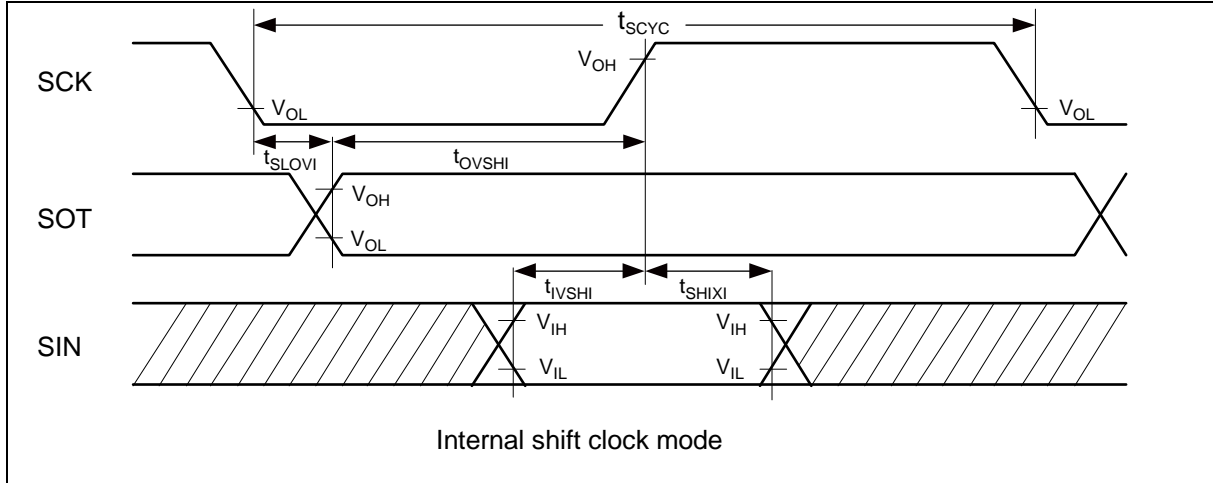


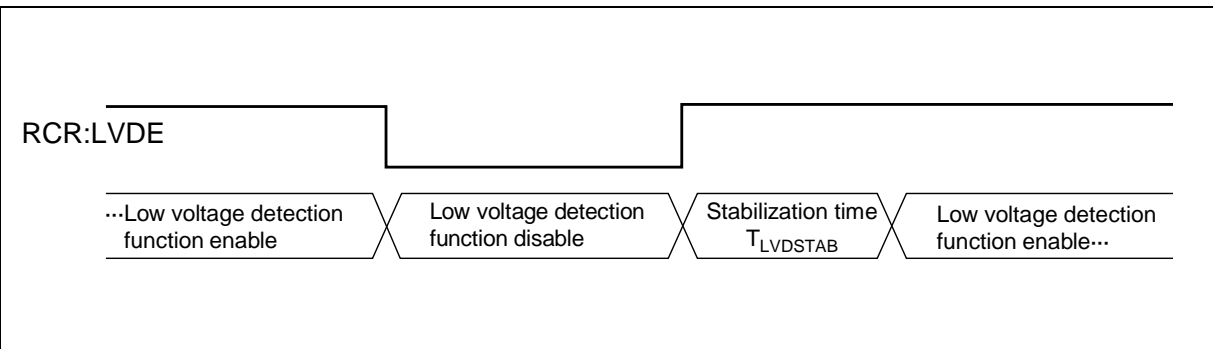
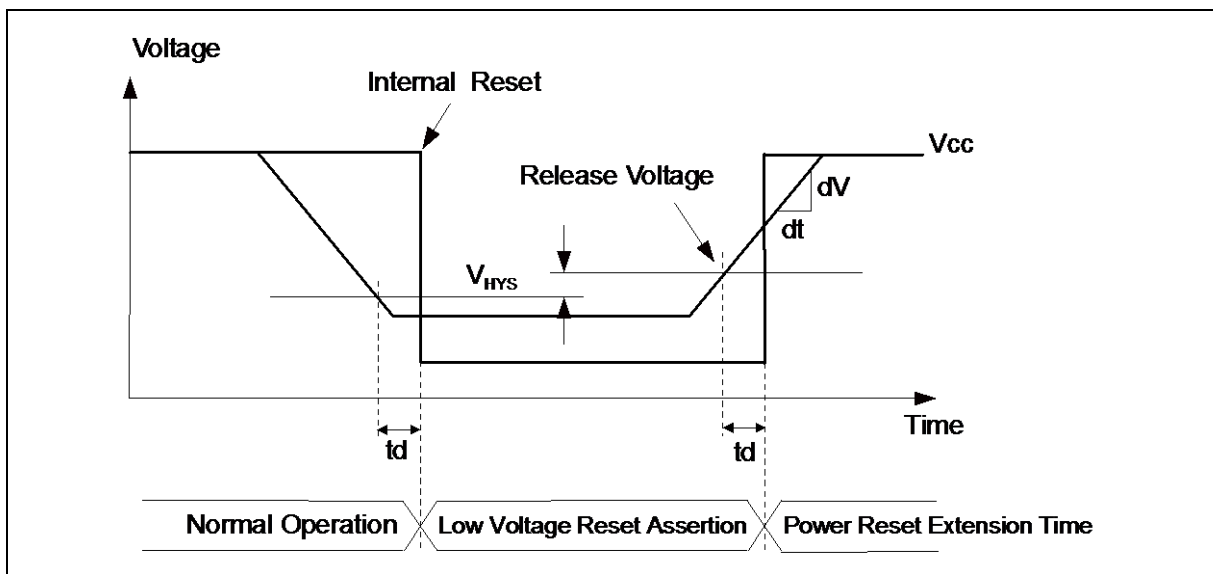
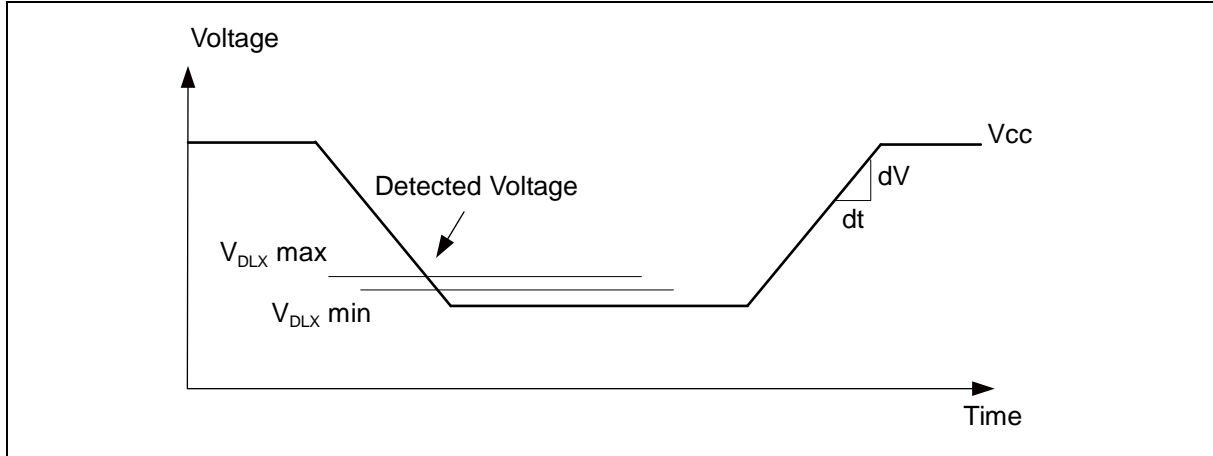
#### 14.4.6 Reset Input

( $V_{CC} = AV_{CC} = 2.7V$  to  $5.5V$ ,  $V_{SS} = AV_{SS} = 0V$ ,  $T_A = -40^{\circ}C$  to  $+125^{\circ}C$ )

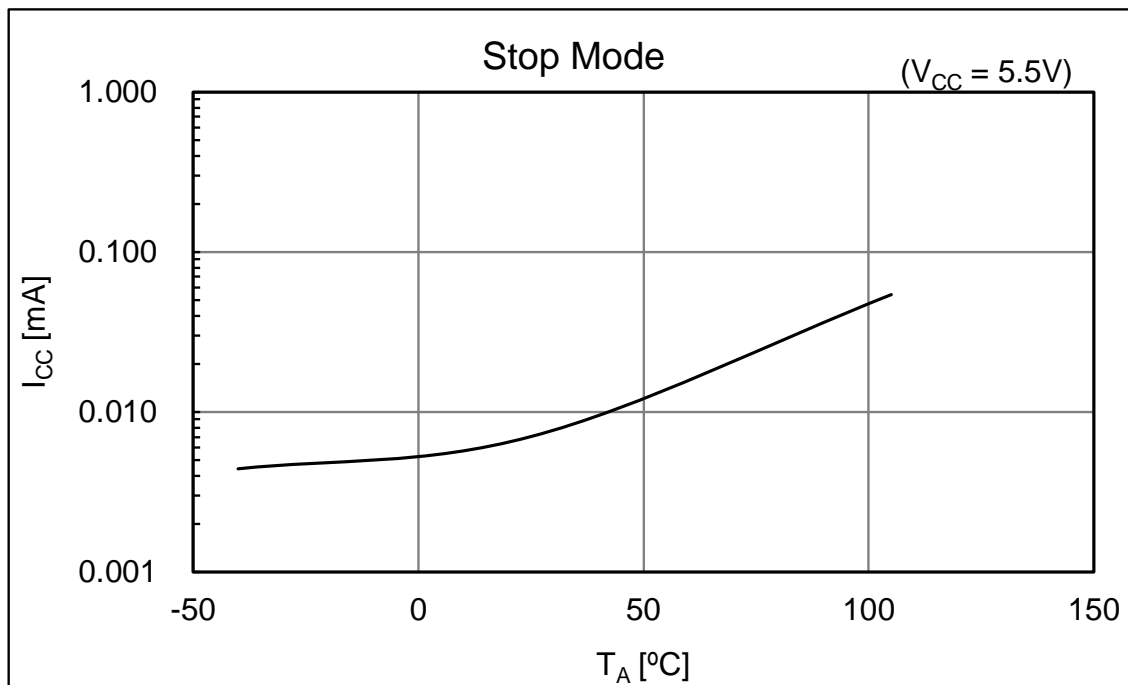
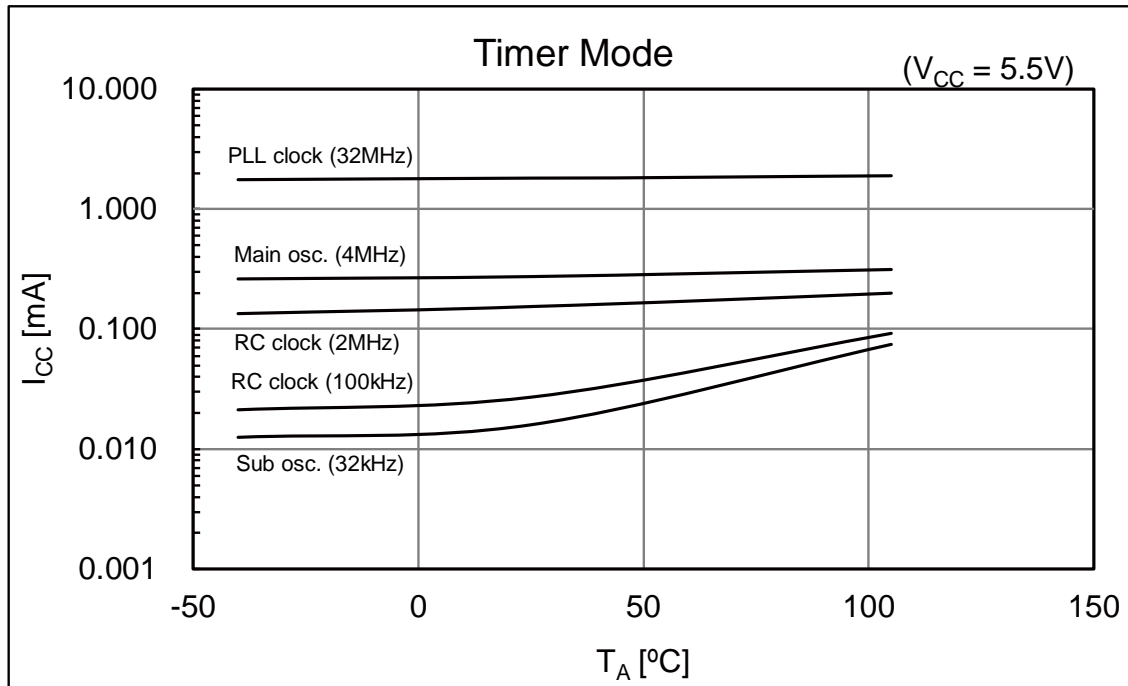
Parameter	Symbol	Pin name	Value		Unit
			Min	Max	
Reset input time	$t_{RSTL}$	RSTX	10	-	$\mu s$
Rejection of reset input time			1	-	$\mu s$







■ MB96F625

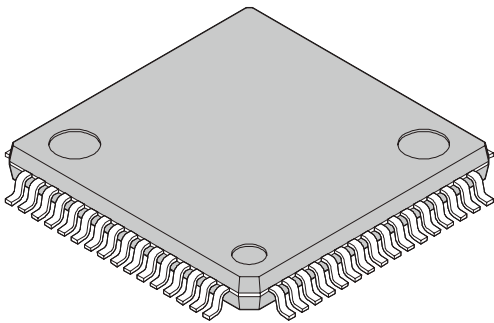


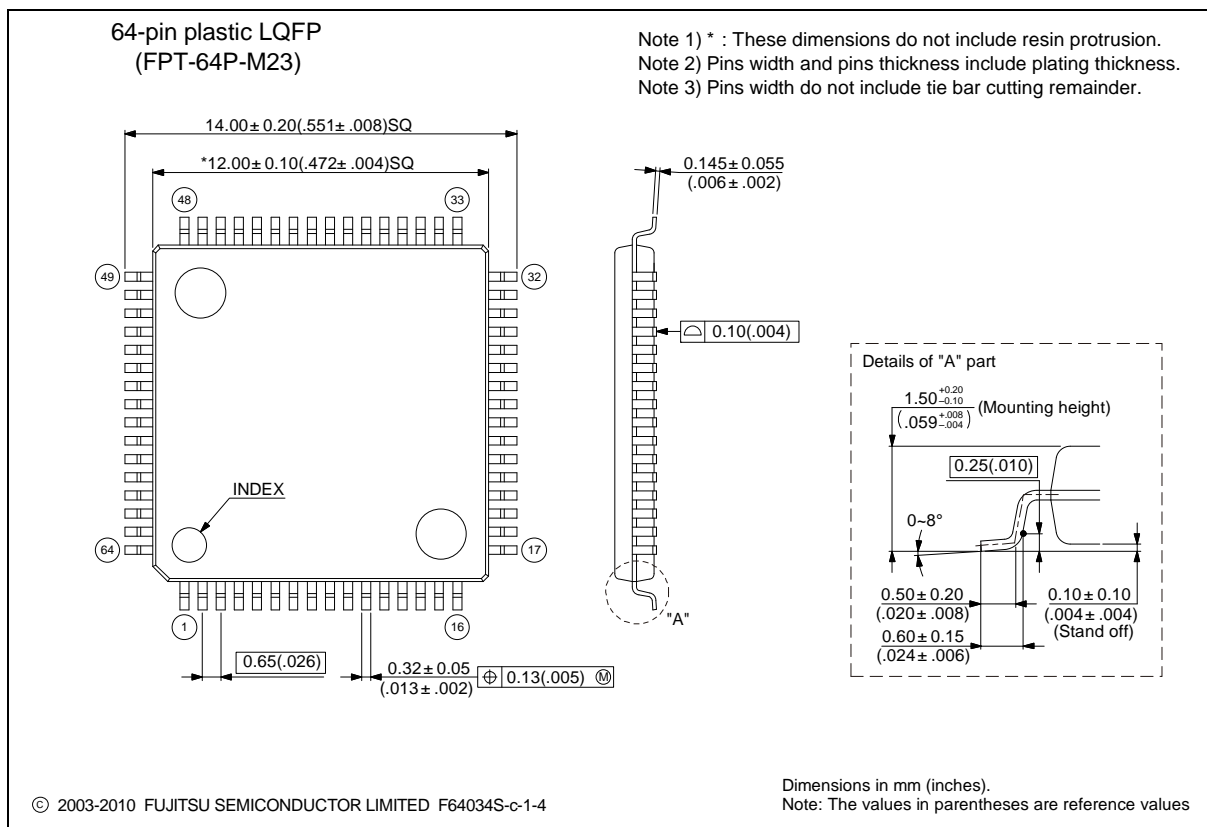


**■ Used setting**

Mode	Selected Source Clock	Clock/Regulator and FLASH Settings
Run mode	PLL	CLKS1 = CLKS2 = CLKB = CLKP1 = CLKP2 = 32MHz
	Main osc.	CLKS1 = CLKS2 = CLKB = CLKP1 = CLKP2 = 4MHz
	RC clock fast	CLKS1 = CLKS2 = CLKB = CLKP1 = CLKP2 = 2MHz
	RC clock slow	CLKS1 = CLKS2 = CLKB = CLKP1 = CLKP2 = 100kHz
	Sub osc.	CLKS1 = CLKS2 = CLKB = CLKP1 = CLKP2 = 32kHz
Sleep mode	PLL	CLKS1 = CLKS2 = CLKP1 = CLKP2 = 32MHz Regulator in High Power Mode, (CLKB is stopped in this mode)
	Main osc.	CLKS1 = CLKS2 = CLKP1 = CLKP2 = 4MHz Regulator in High Power Mode, (CLKB is stopped in this mode)
	RC clock fast	CLKS1 = CLKS2 = CLKP1 = CLKP2 = 2MHz Regulator in High Power Mode, (CLKB is stopped in this mode)
	RC clock slow	CLKS1 = CLKS2 = CLKP1 = CLKP2 = 100kHz Regulator in Low Power Mode, (CLKB is stopped in this mode)
	Sub osc.	CLKS1 = CLKS2 = CLKP1 = CLKP2 = 32kHz Regulator in Low Power Mode, (CLKB is stopped in this mode)
Timer mode	PLL	CLKMC = 4MHz, CLKPLL = 32MHz (System clocks are stopped in this mode) Regulator in High Power Mode, FLASH in Power-down / reset mode
	Main osc.	CLKMC = 4MHz (System clocks are stopped in this mode) Regulator in High Power Mode, FLASH in Power-down / reset mode
	RC clock fast	CLKMC = 2MHz (System clocks are stopped in this mode) Regulator in High Power Mode, FLASH in Power-down / reset mode
	RC clock slow	CLKMC = 100kHz (System clocks are stopped in this mode) Regulator in Low Power Mode, FLASH in Power-down / reset mode
	Sub osc.	CLKMC = 32 kHz (System clocks are stopped in this mode) Regulator in Low Power Mode, FLASH in Power-down / reset mode
Stop mode	stopped	(All clocks are stopped in this mode) Regulator in Low Power Mode, FLASH in Power-down / reset mode

## 17. Package Dimension

 <p>64-pin plastic LQFP</p> <p>(FPT-64P-M23)</p>	Lead pitch	0.65 mm
	Package width × package length	12.0 × 12.0 mm
	Lead shape	Gullwing
	Sealing method	Plastic mold
	Mounting height	1.70 mm MAX
	Weight	0.47 g
	Code (Reference)	P-LQFP64-12 × 12-0.65



Page	Section	Change Results
56	Electrical Characteristics 7. Flash Memory Write/Erase Characteristics	<p>Changed the Note</p> <p>While the Flash memory is written or erased, shutdown of the external power (<math>V_{CC}</math>) is prohibited. In the application system where the external power (<math>V_{CC}</math>) might be shut down while writing, be sure to turn the power off by using an external voltage detector.</p> <p>→</p> <p>While the Flash memory is written or erased, shutdown of the external power (<math>V_{CC}</math>) is prohibited. In the application system where the external power (<math>V_{CC}</math>) might be shut down while writing or erasing, be sure to turn the power off by using a low voltage detection function.</p>
60	Ordering Information	<p>Deleted the Part number</p> <p>MCU with CAN controller</p> <p>MB96F622RBPMC-GTE2</p> <p>MB96F622RBPMC1-GTE2</p> <p>MB96F623RBPMC-GTE2</p> <p>MB96F623RBPMC1-GTE2</p> <p>MB96F625RBPMC-GTE2</p> <p>MB96F625RBPMC1-GTE2</p> <p>MCU without CAN controller</p> <p>MB96F622ABPMC-GTE2</p> <p>MB96F622ABPMC1-GTE2</p> <p>MB96F623ABPMC-GTE2</p> <p>MB96F623ABPMC1-GTE2</p> <p>MB96F625ABPMC-GTE2</p> <p>MB96F625ABPMC1-GTE2</p>
Revision 2.1		
-	-	Company name and layout design change

**NOTE:** Please see “Document History” about later revised information.

## Document History

Document Title: MB96620 Series F<sup>2</sup>MC-16FX 16-Bit Microcontroller

Document Number: 002-04712

Revision	ECN	Orig. of Change	Submission Date	Description of Change
**	-	KSUN	01/31/2014	Migrated to Cypress and assigned document number 002-04712. No change to document contents or format.
*A	5137624	KSUN	02/17/2016	Updated to Cypress format.

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