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What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Obsolete
Core Processor	F ² MC-16FX
Core Size	16-Bit
Speed	32MHz
Connectivity	I ² C, LINbus, SCI, UART/USART
Peripherals	DMA, LVD, POR, PWM, WDT
Number of I/O	52
Program Memory Size	160KB (160K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	10K x 8
Voltage - Supply (Vcc/Vdd)	2.7V ~ 5.5V
Data Converters	A/D 21x8/10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	64-LQFP
Supplier Device Package	64-LQFP (10x10)
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/mb96f625abpmc1-gse1

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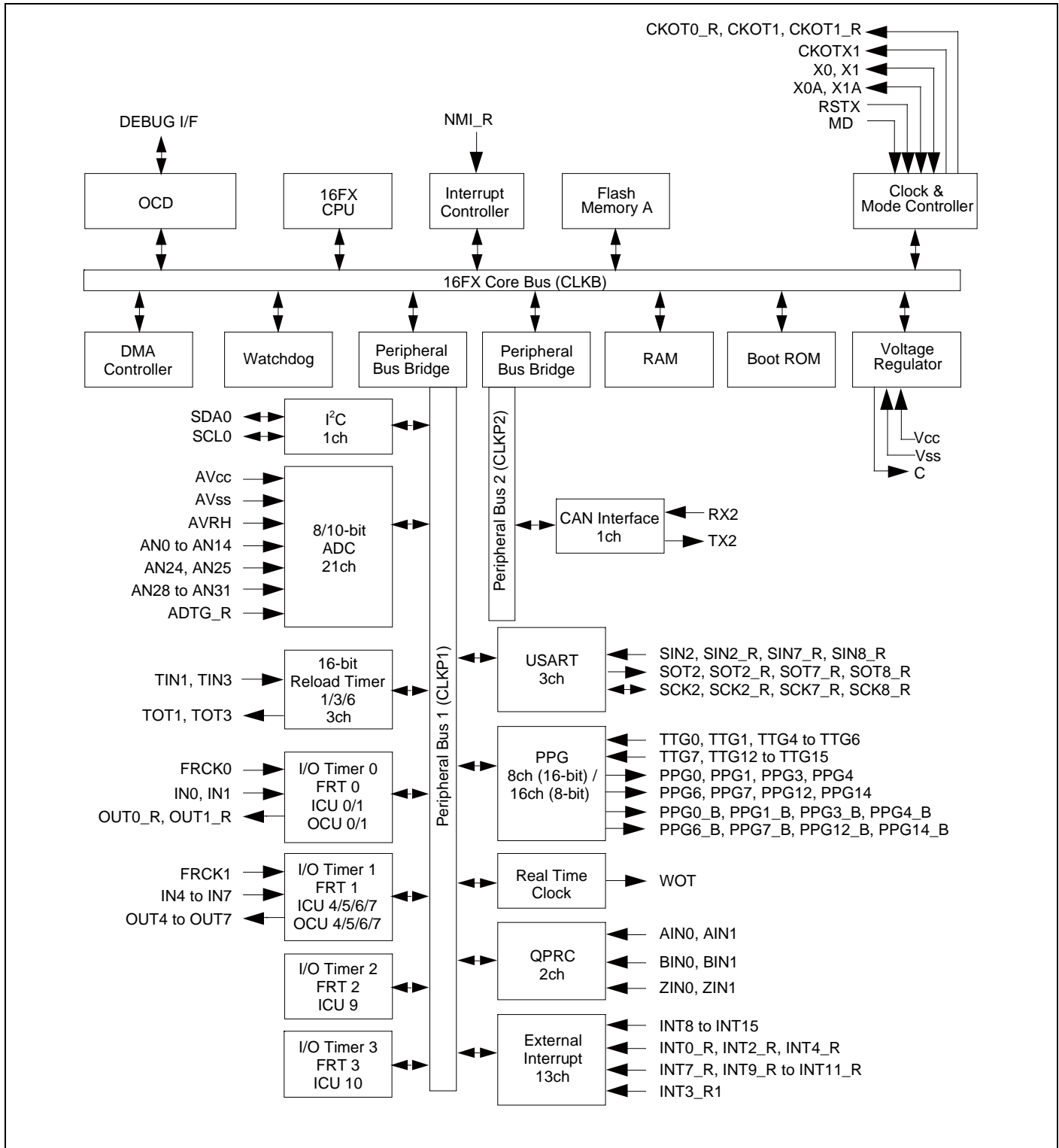
1. Product Lineup

Features		MB96620	Remark
Product Type		Flash Memory Product	
Subclock		Subclock can be set by software	
Dual Operation Flash Memory	RAM	-	
32.5KB + 32KB	4KB	MB96F622R, MB96F622A	Product Options R: MCU with CAN A: MCU without CAN
64.5KB + 32KB	10KB	MB96F623R, MB96F623A	
128.5KB + 32KB	10KB	MB96F625R, MB96F625A	
Package		LQFP-64 FPT-64P-M23/M24	
DMA		2ch	
USART		3ch	LIN-USART 2/7/8
	with automatic LIN-Header transmission/reception	Yes (only 1ch)	LIN-USART 2
	with 16 byte RX- and TX-FIFO	No	
I ² C		1ch	I ² C 0
8/10-bit A/D Converter		21ch	AN 0 to 14/24/25/28 to 31
	with Data Buffer	No	
	with Range Comparator	Yes	
	with Scan Disable	No	
	with ADC Pulse Detection	No	
16-bit Reload Timer (RLT)		3ch	RLT 1/3/6
16-bit Free-Running Timer (FRT)		4ch	FRT 0 to 3 FRT 2/3 does not have external clock input pin
16-bit Input Capture Unit (ICU)		8ch (2 channels for LIN-USART)	ICU 0/1/4 to 7/9/10 (ICU 9/10 for LIN-USART)
16-bit Output Compare Unit (OCU)		6ch	OCU 0/1/4 to 7
8/16-bit Programmable Pulse Generator (PPG)		8ch (16-bit) / 16ch (8-bit)	PPG 0/1/3/4/6/7/12/14
	with Timing point capture	Yes	
	with Start delay	No	
	with Ramp	No	
Quadrature Position/Revolution Counter (QPRC)		2ch	QPRC 0/1
CAN Interface		1ch	CAN 2 32 Message Buffers
External Interrupts (INT)		13ch	INT 0/2/3/4/7 to 15
Non-Maskable Interrupt (NMI)		1ch	
Real Time Clock (RTC)		1ch	
I/O Ports		50 (Dual clock mode) 52 (Single clock mode)	
Clock Calibration Unit (CAL)		1ch	
Clock Output Function		2ch	
Low Voltage Detection Function		Yes	Low voltage detection function can be disabled by software
Hardware Watchdog Timer		Yes	
On-chip RC-oscillator		Yes	
On-chip Debugger		Yes	

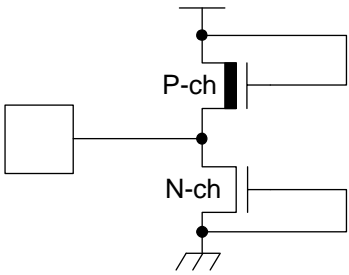
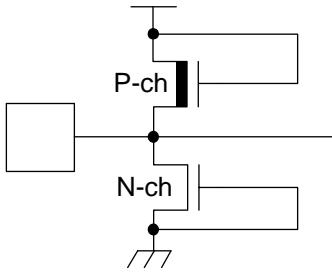
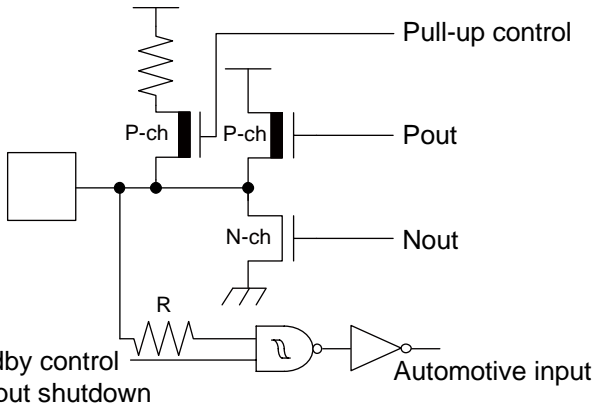
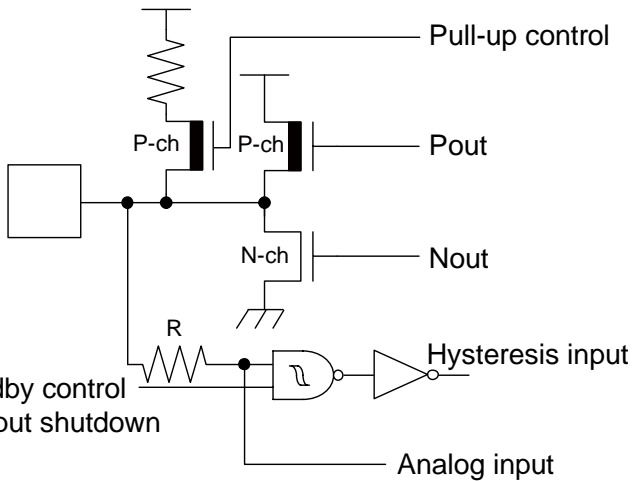
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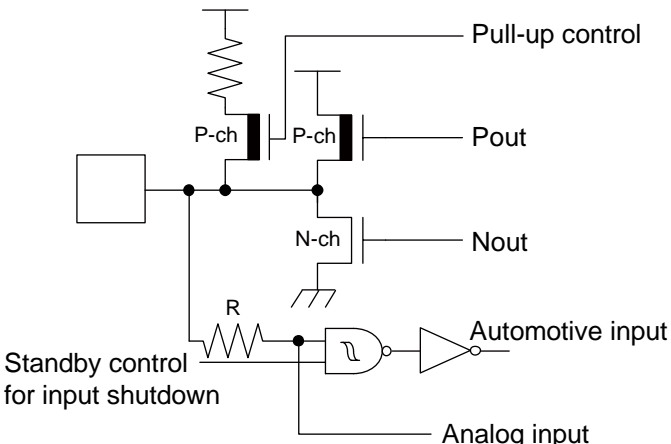
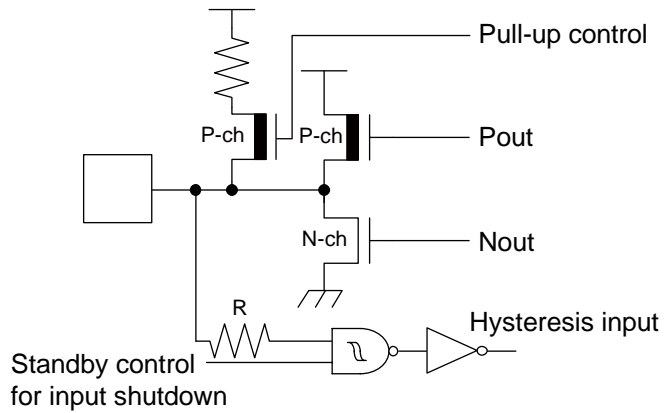
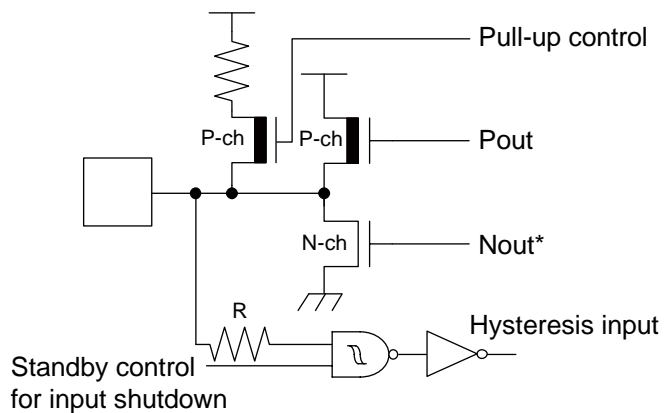
All signals of the peripheral function in each product cannot be allocated by limiting the pins of package.
It is necessary to use the port relocate function of the general I/O port according to your function use.

2. Block Diagram



Pin name	Feature	Description
WOT	RTC	Real Time clock output pin
X0	Clock	Oscillator input pin
X0A	Clock	Subclock Oscillator input pin
X1	Clock	Oscillator output pin
X1A	Clock	Subclock Oscillator output pin
ZINn	QPRC	Quadrature Position/Revolution Counter Unit n input pin

Type	Circuit	Remarks
F		Power supply input protection circuit
G		<ul style="list-style-type: none"> A/D converter ref+ (AVRH) power supply input pin with protection circuit Without protection circuit against V_{CC} for pins AVRH
H		<ul style="list-style-type: none"> CMOS level output ($I_{OL} = 4mA$, $I_{OH} = -4mA$) Automotive input with input shutdown function Programmable pull-up resistor
I		<ul style="list-style-type: none"> CMOS level output ($I_{OL} = 4mA$, $I_{OH} = -4mA$) CMOS hysteresis input with input shutdown function Programmable pull-up resistor Analog input

Type	Circuit	Remarks
K	 <p>Pull-up control</p> <p>P-ch</p> <p>Pout</p> <p>N-ch</p> <p>Nout</p> <p>R</p> <p>Standby control for input shutdown</p> <p>Automotive input</p> <p>Analog input</p>	<ul style="list-style-type: none"> • CMOS level output ($I_{OL} = 4\text{mA}$, $I_{OH} = -4\text{mA}$) • Automotive input with input shutdown function • Programmable pull-up resistor • Analog input
M	 <p>Pull-up control</p> <p>P-ch</p> <p>Pout</p> <p>N-ch</p> <p>Nout</p> <p>R</p> <p>Standby control for input shutdown</p> <p>Hysteresis input</p>	<ul style="list-style-type: none"> • CMOS level output ($I_{OL} = 4\text{mA}$, $I_{OH} = -4\text{mA}$) • CMOS hysteresis input with input shutdown function • Programmable pull-up resistor
N	 <p>Pull-up control</p> <p>P-ch</p> <p>Pout</p> <p>N-ch</p> <p>Nout*</p> <p>R</p> <p>Standby control for input shutdown</p> <p>Hysteresis input</p>	<ul style="list-style-type: none"> • CMOS level output ($I_{OL} = 3\text{mA}$, $I_{OH} = -3\text{mA}$) • CMOS hysteresis input with input shutdown function • Programmable pull-up resistor <p>*: N-channel transistor has slew rate control according to I²C spec, irrespective of usage.</p>

8. RAMSTART Addresses

Devices	Bank 0 RAM size	RAMSTART0
MB96F622	4KB	00:7200 _H
MB96F623 MB96F625	10KB	00:5A00 _H

11. Interrupt Vector Table

Vector number	Offset in vector table	Vector name	Cleared by DMA	Index in ICR to program	Description
0	3FC _H	CALLV0	No	-	CALLV instruction
1	3F8 _H	CALLV1	No	-	CALLV instruction
2	3F4 _H	CALLV2	No	-	CALLV instruction
3	3F0 _H	CALLV3	No	-	CALLV instruction
4	3EC _H	CALLV4	No	-	CALLV instruction
5	3E8 _H	CALLV5	No	-	CALLV instruction
6	3E4 _H	CALLV6	No	-	CALLV instruction
7	3E0 _H	CALLV7	No	-	CALLV instruction
8	3DC _H	RESET	No	-	Reset vector
9	3D8 _H	INT9	No	-	INT9 instruction
10	3D4 _H	EXCEPTION	No	-	Undefined instruction execution
11	3D0 _H	NMI	No	-	Non-Maskable Interrupt
12	3CC _H	DLY	No	12	Delayed Interrupt
13	3C8 _H	RC_TIMER	No	13	RC Clock Timer
14	3C4 _H	MC_TIMER	No	14	Main Clock Timer
15	3C0 _H	SC_TIMER	No	15	Sub Clock Timer
16	3BC _H	LVDI	No	16	Low Voltage Detector
17	3B8 _H	EXTINT0	Yes	17	External Interrupt 0
18	3B4 _H	-	-	18	Reserved
19	3B0 _H	EXTINT2	Yes	19	External Interrupt 2
20	3AC _H	EXTINT3	Yes	20	External Interrupt 3
21	3A8 _H	EXTINT4	Yes	21	External Interrupt 4
22	3A4 _H	-	-	22	Reserved
23	3A0 _H	-	-	23	Reserved
24	39C _H	EXTINT7	Yes	24	External Interrupt 7
25	398 _H	EXTINT8	Yes	25	External Interrupt 8
26	394 _H	EXTINT9	Yes	26	External Interrupt 9
27	390 _H	EXTINT10	Yes	27	External Interrupt 10
28	38C _H	EXTINT11	Yes	28	External Interrupt 11
29	388 _H	EXTINT12	Yes	29	External Interrupt 12
30	384 _H	EXTINT13	Yes	30	External Interrupt 13
31	380 _H	EXTINT14	Yes	31	External Interrupt 14
32	37C _H	EXTINT15	Yes	32	External Interrupt 15
33	378 _H	-	-	33	Reserved
34	374 _H	-	-	34	Reserved
35	370 _H	CAN2	No	35	CAN Controller 2
36	36C _H	-	-	36	Reserved
37	368 _H	-	-	37	Reserved
38	364 _H	PPG0	Yes	38	Programmable Pulse Generator 0
39	360 _H	PPG1	Yes	39	Programmable Pulse Generator 1

Vector number	Offset in vector table	Vector name	Cleared by DMA	Index in ICR to program	Description
40	35C _H	-	-	40	Reserved
41	358H	PPG3	Yes	41	Programmable Pulse Generator 3
42	354H	PPG4	Yes	42	Programmable Pulse Generator 4
43	350H	-	-	43	Reserved
44	34CH	PPG6	Yes	44	Programmable Pulse Generator 6
45	348H	PPG7	Yes	45	Programmable Pulse Generator 7
46	344H	-	-	46	Reserved
47	340H	-	-	47	Reserved
48	33CH	-	-	48	Reserved
49	338H	-	-	49	Reserved
50	334H	PPG12	Yes	50	Programmable Pulse Generator 12
51	330H	-	-	51	Reserved
52	32CH	PPG14	Yes	52	Programmable Pulse Generator 14
53	328H	-	-	53	Reserved
54	324H	-	-	54	Reserved
55	320H	-	-	55	Reserved
56	31CH	-	-	56	Reserved
57	318H	-	-	57	Reserved
58	314H	-	-	58	Reserved
59	310H	RLT1	Yes	59	Reload Timer 1
60	30CH	-	-	60	Reserved
61	308H	RLT3	Yes	61	Reload Timer 3
62	304H	-	-	62	Reserved
63	300H	-	-	63	Reserved
64	2FCH	RLT6	Yes	64	Reload Timer 6
65	2F8H	ICU0	Yes	65	Input Capture Unit 0
66	2F4H	ICU1	Yes	66	Input Capture Unit 1
67	2F0H	-	-	67	Reserved
68	2ECH	-	-	68	Reserved
69	2E8H	ICU4	Yes	69	Input Capture Unit 4
70	2E4H	ICU5	Yes	70	Input Capture Unit 5
71	2E0H	ICU6	Yes	71	Input Capture Unit 6
72	2DCH	ICU7	Yes	72	Input Capture Unit 7
73	2D8H	-	-	73	Reserved
74	2D4H	ICU9	Yes	74	Input Capture Unit 9
75	2D0H	ICU10	Yes	75	Input Capture Unit 10
76	2CCH	-	-	76	Reserved
77	2C8H	OCU0	Yes	77	Output Compare Unit 0
78	2C4H	OCU1	Yes	78	Output Compare Unit 1
79	2C0H	-	-	79	Reserved
80	2BCH	-	-	80	Reserved

Vector number	Offset in vector table	Vector name	Cleared by DMA	Index in ICR to program	Description
81	2B8 _H	OCU4	Yes	81	Output Compare Unit 4
82	2B4 _H	OCU5	Yes	82	Output Compare Unit 5
83	2B0 _H	OCU6	Yes	83	Output Compare Unit 6
84	2AC _H	OCU7	Yes	84	Output Compare Unit 7
85	2A8 _H	-	-	85	Reserved
86	2A4 _H	-	-	86	Reserved
87	2A0 _H	-	-	87	Reserved
88	29C _H	-	-	88	Reserved
89	298 _H	FRT0	Yes	89	Free-Running Timer 0
90	294 _H	FRT1	Yes	90	Free-Running Timer 1
91	290 _H	FRT2	Yes	91	Free-Running Timer 2
92	28C _H	FRT3	Yes	92	Free-Running Timer 3
93	288 _H	RTC0	No	93	Real Time Clock
94	284 _H	CAL0	No	94	Clock Calibration Unit
95	280 _H	-	-	95	Reserved
96	27C _H	IIC0	Yes	96	I ² C interface 0
97	278 _H	-	-	97	Reserved
98	274 _H	ADC0	Yes	98	A/D Converter 0
99	270 _H	-	-	99	Reserved
100	26C _H	-	-	100	Reserved
101	268 _H	-	-	101	Reserved
102	264 _H	-	-	102	Reserved
103	260 _H	-	-	103	Reserved
104	25C _H	-	-	104	Reserved
105	258 _H	LINR2	Yes	105	LIN USART 2 RX
106	254 _H	LINT2	Yes	106	LIN USART 2 TX
107	250 _H	-	-	107	Reserved
108	24C _H	-	-	108	Reserved
109	248 _H	-	-	109	Reserved
110	244 _H	-	-	110	Reserved
111	240 _H	-	-	111	Reserved
112	23C _H	-	-	112	Reserved
113	238 _H	-	-	113	Reserved
114	234 _H	-	-	114	Reserved
115	230 _H	LINR7	Yes	115	LIN USART 7 RX
116	22C _H	LINT7	Yes	116	LIN USART 7 TX
117	228 _H	LINR8	Yes	117	LIN USART 8 RX
118	224 _H	LINT8	Yes	118	LIN USART 8 TX
119	220 _H	-	-	119	Reserved
120	21C _H	-	-	120	Reserved
121	218 _H	-	-	121	Reserved
122	214 _H	-	-	122	Reserved

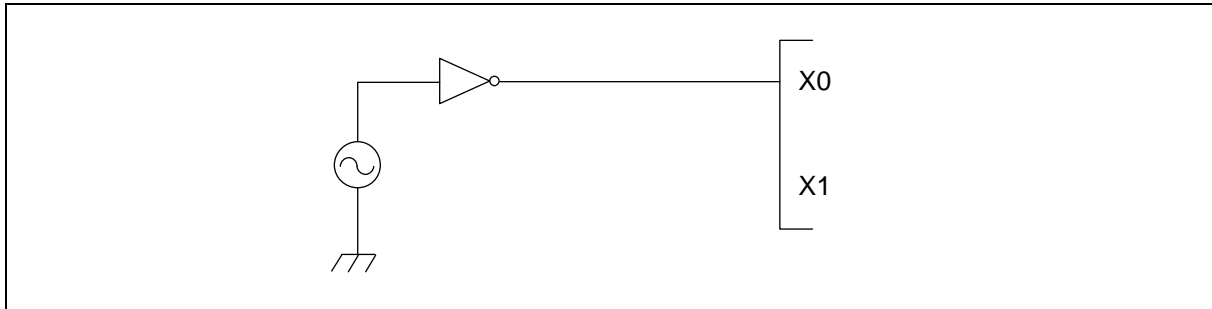
13.3 External clock usage

The permitted frequency range of an external clock depends on the oscillator type and configuration.

See AC Characteristics for detailed modes and frequency limits. Single and opposite phase external clocks must be connected as follows:

13.3.1 Single phase external clock for Main oscillator

When using a single phase external clock for the Main oscillator, X0 pin must be driven and X1 pin left open. And supply 1.8V power to the external clock.

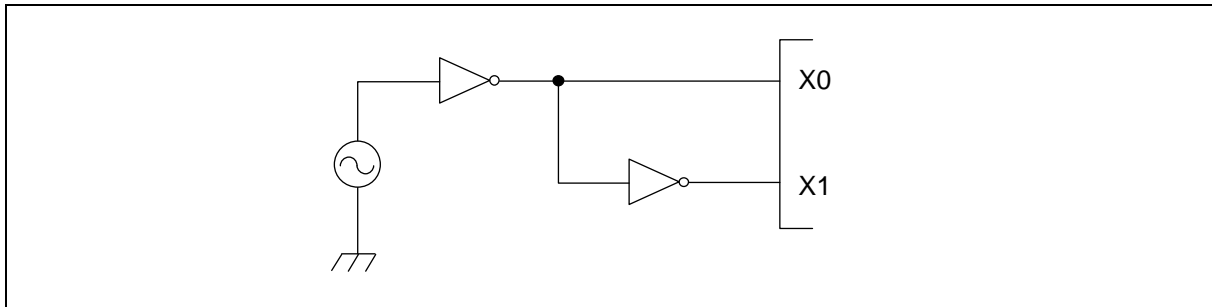


13.3.2 Single phase external clock for Sub oscillator

When using a single phase external clock for the Sub oscillator, "External clock mode" must be selected and X0A/P04_0 pin must be driven. X1A/P04_1 pin can be configured as GPIO.

13.3.3 Opposite phase external clock

When using an opposite phase external clock, X1 (X1A) pins must be supplied with a clock signal which has the opposite phase to the X0 (X0A) pins. Supply level on X0 and X1 pins must be 1.8V.



13.4 Notes on PLL clock mode operation

If the microcontroller is operated with PLL clock mode and no external oscillator is operating or no external clock is supplied, the microcontroller attempts to work with the free oscillating PLL. Performance of this operation, however, cannot be guaranteed.

13.5 Power supply pins (V_{CC}/V_{SS})

It is required that all V_{CC} -level as well as all V_{SS} -level power supply pins are at the same potential. If there is more than one V_{CC} or V_{SS} level, the device may operate incorrectly or be damaged even within the guaranteed operating range.

V_{CC} and V_{SS} pins must be connected to the device from the power supply with lowest possible impedance.

The smoothing capacitor at V_{CC} pin must use the one of a capacity value that is larger than C_s .

Besides this, as a measure against power supply noise, it is required to connect a bypass capacitor of about $0.1\mu F$ between V_{CC} and V_{SS} pins as close as possible to V_{CC} and V_{SS} pins.

14. Electrical Characteristics

14.1 Absolute Maximum Ratings

Parameter	Symbol	Condition	Rating		Unit	Remarks
			Min	Max		
Power supply voltage ^{*1}	V _{CC}	-	V _{SS} - 0.3	V _{SS} + 6.0	V	
Analog power supply voltage ^{*1}	AV _{CC}	-	V _{SS} - 0.3	V _{SS} + 6.0	V	V _{CC} = AV _{CC} ^{*2}
Analog reference voltage ^{*1}	AVRH	-	V _{SS} - 0.3	V _{SS} + 6.0	V	AV _{CC} ≥ AVRH, AVRH ≥ AV _{SS}
Input voltage ^{*1}	V _I	-	V _{SS} - 0.3	V _{SS} + 6.0	V	V _I ≤ V _{CC} + 0.3V ^{*3}
Output voltage ^{*1}	V _O	-	V _{SS} - 0.3	V _{SS} + 6.0	V	V _O ≤ V _{CC} + 0.3V ^{*3}
Maximum Clamp Current	I _{CLAMP}	-	-4.0	+4.0	mA	Applicable to general purpose I/O pins ^{*4}
Total Maximum Clamp Current	Σ I _{CLAMP}	-	-	17	mA	Applicable to general purpose I/O pins ^{*4}
"L" level maximum output current	I _{OL}	-	-	15	mA	
"L" level average output current	I _{OLAV}	-	-	4	mA	
"L" level maximum overall output current	ΣI _{OL}	-	-	42	mA	
"L" level average overall output current	ΣI _{OLAV}	-	-	21	mA	
"H" level maximum output current	I _{OH}	-	-	-15	mA	
"H" level average output current	I _{OHAV}	-	-	-4	mA	
"H" level maximum overall output current	ΣI _{OH}	-	-	-42	mA	
"H" level average overall output current	ΣI _{OHAV}	-	-	-21	mA	
Power consumption ^{*5}	P _D	T _A = +125°C	-	352 ^{*6}	mW	
Operating ambient temperature	T _A	-	-40	+125 ^{*7}	°C	
Storage temperature	T _{STG}	-	-55	+150	°C	

^{*1}: This parameter is based on V_{SS} = AV_{SS} = 0V.

^{*2}: AV_{CC} and V_{CC} must be set to the same voltage. It is required that AV_{CC} does not exceed V_{CC} and that the voltage at the analog inputs does not exceed AV_{CC} when the power is switched on.

^{*3}: V_I and V_O should not exceed V_{CC} + 0.3V. V_I should also not exceed the specified ratings. However if the maximum current to/from an input is limited by some means with external components, the I_{CLAMP} rating supersedes the V_I rating. Input/Output voltages of standard ports depend on V_{CC}.

^{*4}: Applicable to all general purpose I/O pins (Pnn_m).

- Use within recommended operating conditions.
- Use at DC voltage (current).
- The +B signal should always be applied a limiting resistance placed between the +B signal and the microcontroller.
- The value of the limiting resistance should be set so that when the +B signal is applied the input current to the microcontroller pin does not exceed rated values, either instantaneously or for prolonged periods.
- Note that when the microcontroller drive current is low, such as in the power saving modes, the +B input potential may pass through the protective diode and increase the potential at the V_{CC} pin, and this may affect other devices.
- Note that if a +B signal is input when the microcontroller power supply is off (not fixed at 0V), the power supply is provided from the pins, so that incomplete operation may result.
- Note that if the +B input is applied during power-on, the power supply is provided from the pins and the resulting supply voltage may not be sufficient to operate the Power reset.

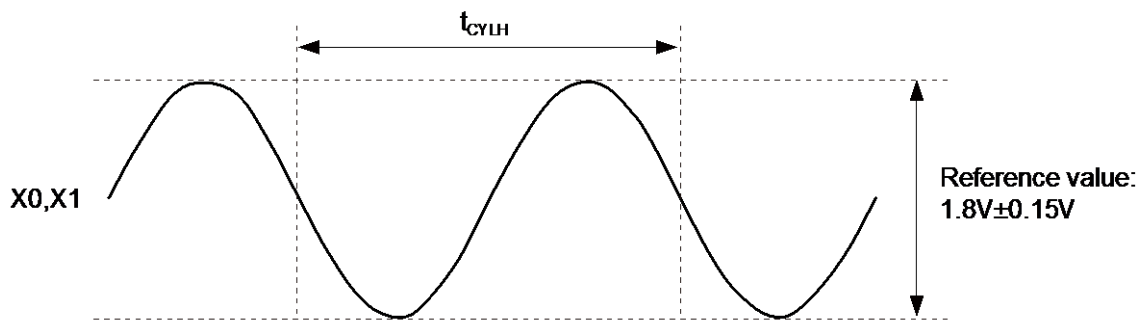
14.4 AC Characteristics

14.4.1 Main Clock Input Characteristics

($V_{CC} = AV_{CC} = 2.7V$ to $5.5V$, $V_D = 1.8V \pm 0.15V$, $V_{SS} = AV_{SS} = 0V$, $T_A = -40^\circ C$ to $+125^\circ C$)

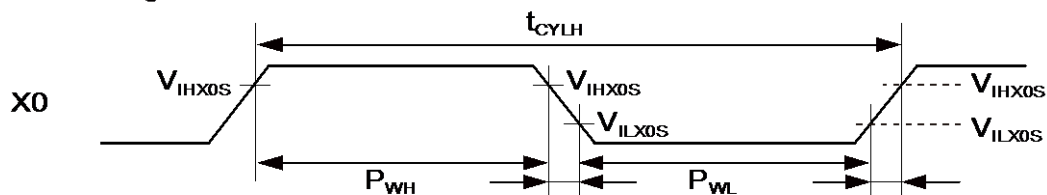
Parameter	Symbol	Pin name	Value			Unit	Remarks
			Min	Typ	Max		
Input frequency	f_c	X0, X1	4	-	8	MHz	When using a crystal oscillator, PLL off
			-	-	8	MHz	When using an opposite phase external clock, PLL off
			4	-	8	MHz	When using a crystal oscillator or opposite phase external clock, PLL on
Input frequency	f_{FCI}	X0	-	-	8	MHz	When using a single phase external clock in "Fast Clock Input mode", PLL off
			4	-	8	MHz	When using a single phase external clock in "Fast Clock Input mode", PLL on
Input clock cycle	t_{CYLH}	-	125	-	-	ns	
Input clock pulse width	P_{WH}, P_{WL}	-	55	-	-	ns	

When using the crystal oscillator



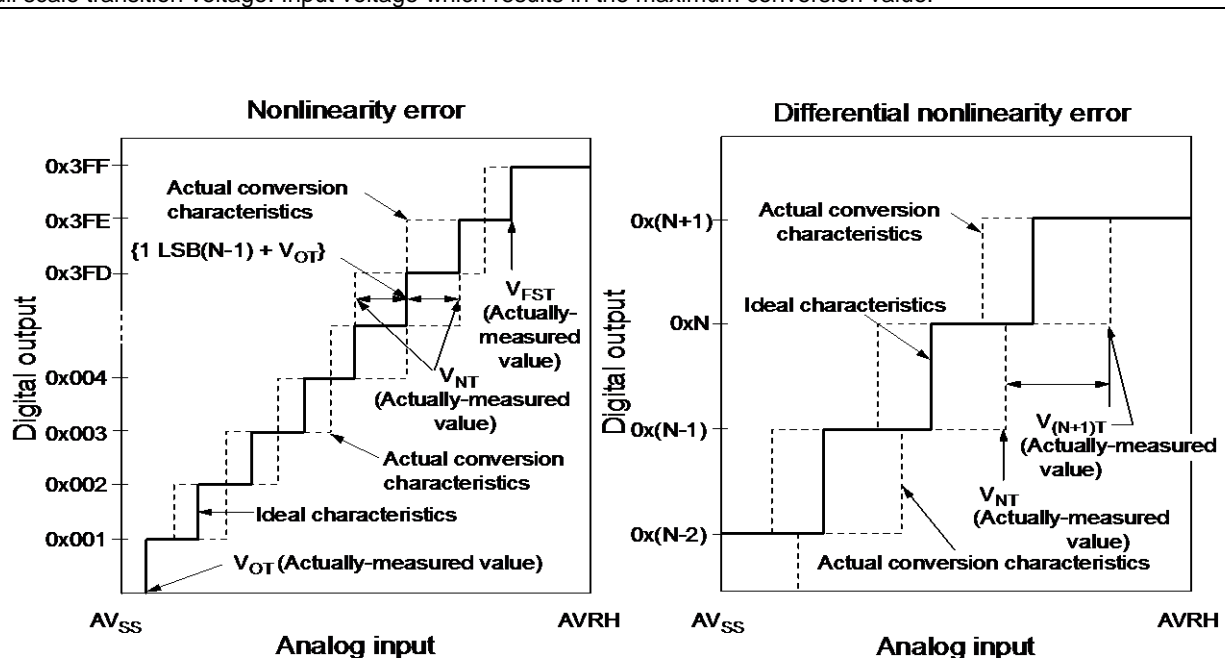
The amplitude changes by resistance, capacity which added outside or the difference of the device.

When using the external clock



14.5.3 Definition of A/D Converter Terms

- Resolution : Analog variation that is recognized by an A/D converter.
- Nonlinearity error : Deviation of the actual conversion characteristics from a straight line that connects the zero transition point (0b0000000000 \longleftrightarrow 0b0000000001) to the full-scale transition point (0b1111111110 \longleftrightarrow 0b1111111111).
- Differential nonlinearity error : Deviation from the ideal value of the input voltage that is required to change the output code by 1LSB.
- Total error : Difference between the actual value and the theoretical value. The total error includes zero transition error, full-scale transition error and nonlinearity error.
- Zero transition voltage : Input voltage which results in the minimum conversion value.
- Full scale transition voltage: Input voltage which results in the maximum conversion value.



$$\text{Nonlinearity error of digital output } N = \frac{V_{NT} - \{1\text{LSB} \times (N - 1) + V_{OT}\}}{1\text{LSB}} \text{ [LSB]}$$

$$\text{Differential nonlinearity error of digital output } N = \frac{V_{(N+1)T} - V_{NT}}{1\text{LSB}} - 1 \text{ [LSB]}$$

$$1\text{LSB} = \frac{V_{FST} - V_{OT}}{1022}$$

- N : A/D converter digital output value.
- V_{OT} : Voltage at which the digital output changes from 0x000 to 0x001.
- V_{FST} : Voltage at which the digital output changes from 0x3FE to 0x3FF.
- V_{NT} : Voltage at which the digital output changes from 0x(N - 1) to 0xN.

14.6 Low Voltage Detection Function Characteristics

($V_{CC} = AV_{CC} = 2.7V$ to $5.5V$, $V_{SS} = AV_{SS} = 0V$, $T_A = -40^{\circ}C$ to $+125^{\circ}C$)

Parameter	Symbol	Conditions	Value			Unit
			Min	Typ	Max	
Detected voltage ^{*1}	V_{DL0}	CILCR:LVL = 0000 _B	2.70	2.90	3.10	V
	V_{DL1}	CILCR:LVL = 0001 _B	2.79	3.00	3.21	V
	V_{DL2}	CILCR:LVL = 0010 _B	2.98	3.20	3.42	V
	V_{DL3}	CILCR:LVL = 0011 _B	3.26	3.50	3.74	V
	V_{DL4}	CILCR:LVL = 0100 _B	3.45	3.70	3.95	V
	V_{DL5}	CILCR:LVL = 0111 _B	3.73	4.00	4.27	V
	V_{DL6}	CILCR:LVL = 1001 _B	3.91	4.20	4.49	V
Power supply voltage change rate ^{*2}	dV/dt	-	- 0.004	-	+ 0.004	V/ μ s
Hysteresis width	V_{HYS}	CILCR:LVHYS=0	-	-	50	mV
		CILCR:LVHYS=1	80	100	120	mV
Stabilization time	$T_{LVDSTAB}$	-	-	-	75	μ s
Detection delay time	t_d	-	-	-	30	μ s

^{*1}: If the power supply voltage fluctuates within the time less than the detection delay time (t_d), there is a possibility that the low voltage detection will occur or stop after the power supply voltage passes the detection range.

^{*2}: In order to perform the low voltage detection at the detection voltage (V_{DLX}), be sure to suppress fluctuation of the power supply voltage within the limits of the change ration of power supply voltage.

14.7 Flash Memory Write/Erase Characteristics

($V_{CC} = AV_{CC} = 2.7V$ to $5.5V$, $V_{SS} = AV_{SS} = 0V$, $T_A = -40^{\circ}C$ to $+125^{\circ}C$)

Parameter		Conditions	Value			Unit	Remarks
			Min	Typ	Max		
Sector erase time	Large Sector	$T_A \leq +105^{\circ}C$	-	1.6	7.5	s	Includes write time prior to internal erase.
	Small Sector	-	-	0.4	2.1	s	
	Security Sector	-	-	0.31	1.65	s	
Word (16-bit) write time	Large Sector	$T_A \leq +105^{\circ}C$	-	25	400	μs	Not including system-level overhead time.
	Small Sector	-	-	25	400	μs	
Chip erase time		$T_A \leq +105^{\circ}C$	-	5.11	25.05	s	Includes write time prior to internal erase.

Note:

While the Flash memory is written or erased, shutdown of the external power (V_{CC}) is prohibited. In the application system where the external power (V_{CC}) might be shut down while writing or erasing, be sure to turn the power off by using a low voltage detection function.

To put it concrete, change the external power in the range of change ration of power supply voltage ($-0.004V/\mu s$ to $+0.004V/\mu s$) after the external power falls below the detection voltage (V_{DLX})^{*1}.

Write/Erase cycles and data hold time

Write/Erase cycles (cycle)	Data hold time (year)
1,000	20^{*2}
10,000	10^{*2}
100,000	5^{*2}

*1: See "Low Voltage Detection Function Characteristics".

*2: This value comes from the technology qualification (using Arrhenius equation to translate high temperature measurements into normalized value at $+85^{\circ}C$).

■ Used setting

Mode	Selected Source Clock	Clock/Regulator and FLASH Settings
Run mode	PLL	CLKS1 = CLKS2 = CLKB = CLKP1 = CLKP2 = 32MHz
	Main osc.	CLKS1 = CLKS2 = CLKB = CLKP1 = CLKP2 = 4MHz
	RC clock fast	CLKS1 = CLKS2 = CLKB = CLKP1 = CLKP2 = 2MHz
	RC clock slow	CLKS1 = CLKS2 = CLKB = CLKP1 = CLKP2 = 100kHz
	Sub osc.	CLKS1 = CLKS2 = CLKB = CLKP1 = CLKP2 = 32kHz
Sleep mode	PLL	CLKS1 = CLKS2 = CLKP1 = CLKP2 = 32MHz Regulator in High Power Mode, (CLKB is stopped in this mode)
	Main osc.	CLKS1 = CLKS2 = CLKP1 = CLKP2 = 4MHz Regulator in High Power Mode, (CLKB is stopped in this mode)
	RC clock fast	CLKS1 = CLKS2 = CLKP1 = CLKP2 = 2MHz Regulator in High Power Mode, (CLKB is stopped in this mode)
	RC clock slow	CLKS1 = CLKS2 = CLKP1 = CLKP2 = 100kHz Regulator in Low Power Mode, (CLKB is stopped in this mode)
	Sub osc.	CLKS1 = CLKS2 = CLKP1 = CLKP2 = 32kHz Regulator in Low Power Mode, (CLKB is stopped in this mode)
Timer mode	PLL	CLKMC = 4MHz, CLKPLL = 32MHz (System clocks are stopped in this mode) Regulator in High Power Mode, FLASH in Power-down / reset mode
	Main osc.	CLKMC = 4MHz (System clocks are stopped in this mode) Regulator in High Power Mode, FLASH in Power-down / reset mode
	RC clock fast	CLKMC = 2MHz (System clocks are stopped in this mode) Regulator in High Power Mode, FLASH in Power-down / reset mode
	RC clock slow	CLKMC = 100kHz (System clocks are stopped in this mode) Regulator in Low Power Mode, FLASH in Power-down / reset mode
	Sub osc.	CLKMC = 32 kHz (System clocks are stopped in this mode) Regulator in Low Power Mode, FLASH in Power-down / reset mode
Stop mode	stopped	(All clocks are stopped in this mode) Regulator in Low Power Mode, FLASH in Power-down / reset mode

16. Ordering Information

MCU with CAN controller

Part number	Flash memory	Package*
MB96F622RBPMC-GSE1	Flash A (64.5KB)	64-pin plastic LQFP (FPT-64P-M23)
MB96F622RBPMC-GSE2		
MB96F622RBPMC-GTE1		64-pin plastic LQFP (FPT-64P-M24)
MB96F622RBPMC1-GSE1		
MB96F622RBPMC1-GSE2		
MB96F622RBPMC1-GTE1		
MB96F623RBPMC-GSE1	Flash A (96.5KB)	64-pin plastic LQFP (FPT-64P-M23)
MB96F623RBPMC-GSE2		
MB96F623RBPMC-GTE1		64-pin plastic LQFP (FPT-64P-M24)
MB96F623RBPMC1-GSE1		
MB96F623RBPMC1-GSE2		
MB96F623RBPMC1-GTE1		
MB96F625RBPMC-GSE1	Flash A (160.5KB)	64-pin plastic LQFP (FPT-64P-M23)
MB96F625RBPMC-GSE2		
MB96F625RBPMC-GTE1		64-pin plastic LQFP (FPT-64P-M24)
MB96F625RBPMC1-GSE1		
MB96F625RBPMC1-GSE2		
MB96F625RBPMC1-GTE1		

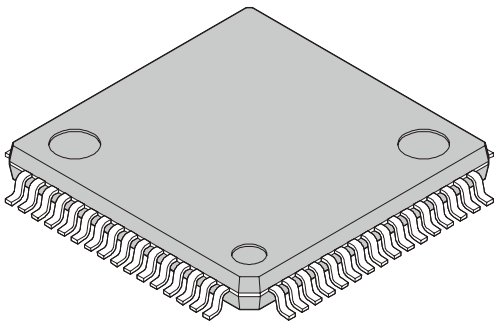
*: For details about package, see "PACKAGE DIMENSION".

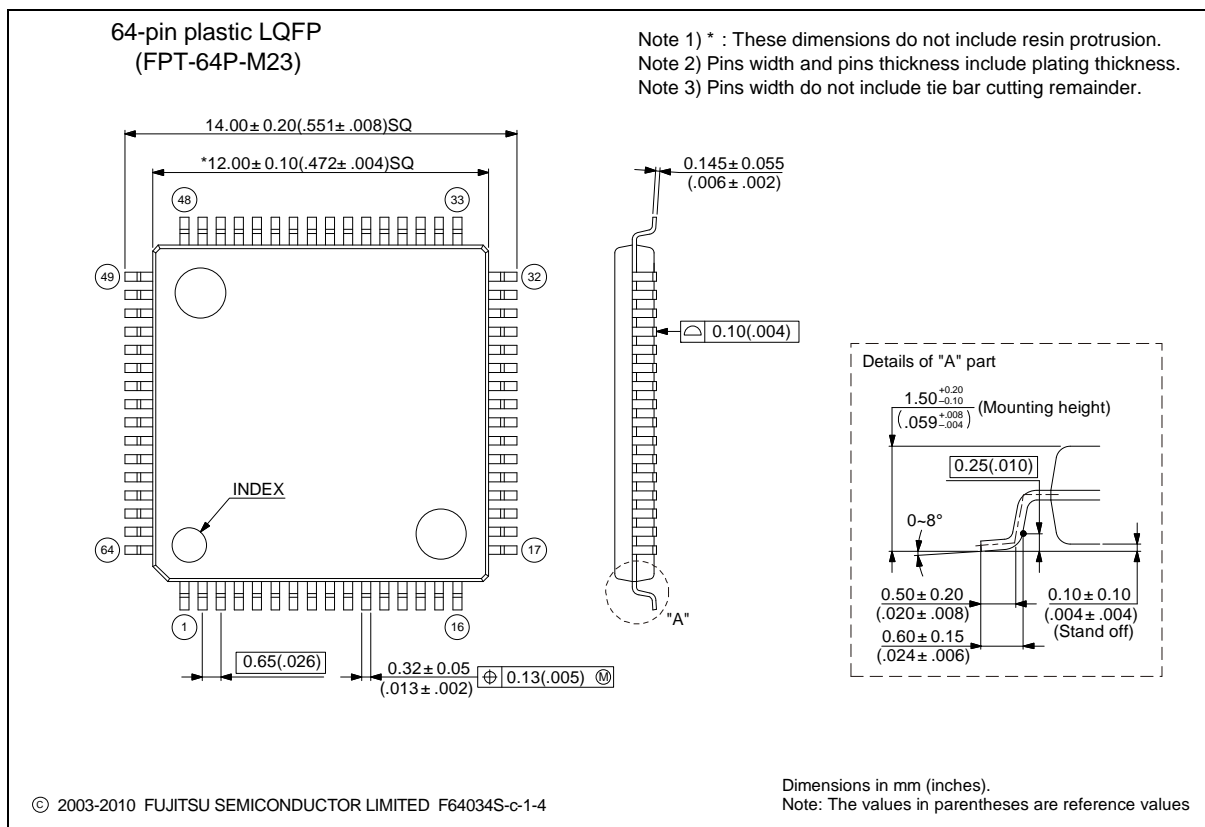
MCU without CAN controller

Part number	Flash memory	Package*
MB96F622ABPMC-GSE1	Flash A (64.5KB)	64-pin plastic LQFP (FPT-64P-M23)
MB96F622ABPMC-GSE2		
MB96F622ABPMC-GTE1		64-pin plastic LQFP (FPT-64P-M24)
MB96F622ABPMC1-GSE1		
MB96F622ABPMC1-GSE2		
MB96F622ABPMC1-GTE1		
MB96F623ABPMC-GSE1	Flash A (96.5KB)	64-pin plastic LQFP (FPT-64P-M23)
MB96F623ABPMC-GSE2		
MB96F623ABPMC-GTE1		64-pin plastic LQFP (FPT-64P-M24)
MB96F623ABPMC1-GSE1		
MB96F623ABPMC1-GSE2		
MB96F623ABPMC1-GTE1		
MB96F625ABPMC-GSE1	Flash A (160.5KB)	64-pin plastic LQFP (FPT-64P-M23)
MB96F625ABPMC-GSE2		
MB96F625ABPMC-GTE1		64-pin plastic LQFP (FPT-64P-M24)
MB96F625ABPMC1-GSE1		
MB96F625ABPMC1-GSE2		
MB96F625ABPMC1-GTE1		

*: For details about package, see "PACKAGE DIMENSION".

17. Package Dimension

 <p>64-pin plastic LQFP</p> <p>(FPT-64P-M23)</p>	Lead pitch	0.65 mm
	Package width × package length	12.0 × 12.0 mm
	Lead shape	Gullwing
	Sealing method	Plastic mold
	Mounting height	1.70 mm MAX
	Weight	0.47 g
	Code (Reference)	P-LQFP64-12 × 12-0.65



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