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Embedded - System On Chip (SoC): The Heart of Modern Embedded Systems

Embedded - System On Chip (SoC) refers to an integrated circuit that consolidates all the essential components of a computer system into a single chip. This includes a microprocessor, memory, and other peripherals, all packed into one compact and efficient package. SoCs are designed to provide a complete computing solution, optimizing both space and power consumption, making them ideal for a wide range of embedded applications.

What are Embedded - System On Chip (SoC)?

System On Chip (SoC) integrates multiple functions of a computer or electronic system onto a single chip. Unlike traditional multi-chip solutions, SoCs combine a central

Details	
Product Status	Obsolete
Architecture	MCU, FPGA
Core Processor	ARM® Cortex®-M3
Flash Size	128KB
RAM Size	16KB
Peripherals	DMA, POR, WDT
Connectivity	EBI/EMI, I²C, SPI, UART/USART
Speed	80MHz
Primary Attributes	ProASIC®3 FPGA, 60K Gates, 1536D-Flip-Flops
Operating Temperature	-40°C ~ 100°C (TJ)
Package / Case	288-TFBGA, CSPBGA
Supplier Device Package	288-CSP (11x11)
Purchase URL	https://www.e-xfl.com/product-detail/microsemi/a2f060m3e-csg288i

Table 2-4 • FPGA and Embedded Flash Programming, Storage and Operating Limits

Product Grade	Storage Temperature	Element	Grade Programming Cycles	Retention
Commercial	Min. T_J = 0°C Max. T_J = 85°C	FPGA/FlashROM	500	20 years
		Embedded Flash	< 1,000	20 years
			< 10,000	10 years
			< 15,000	5 years
Industrial	Min. T_J = –40°C Max. T_J = 100°C	FPGA/FlashROM	500	20 years
		Embedded Flash	< 1,000	20 years
			< 10,000	10 years
			< 15,000	5 years

Table 2-5 • Overshoot and Undershoot Limits [1]

VCCxxxxIOBx	Average VCCxxxxIOBx–GND Overshoot or Undershoot Duration as a Percentage of Clock Cycle[2]	Maximum Overshoot/ Undershoot[2]
2.7 V or less	10%	1.4 V
	5%	1.49 V
3 V	10%	1.1 V
	5%	1.19 V
3.3 V	10%	0.79 V
	5%	0.88 V
3.6 V	10%	0.45 V
	5%	0.54 V

Notes:

1. *Based on reliability requirements at 85°C.*
2. *The duration is allowed at one out of six clock cycles. If the overshoot/undershoot occurs at one out of two cycles, the maximum overshoot/undershoot has to be reduced by 0.15 V.*
3. *This table does not provide PCI overshoot/undershoot limits.*

Power Supply Sequencing Requirement

SmartFusion cSoCs have an on-chip 1.5 V regulator, but usage of an external 1.5 V supply is also allowed while the on-chip regulator is disabled. In that case, the 3.3 V supplies (VCC33A, etc.) should be powered before 1.5 V (VCC, etc.) supplies. The 1.5 V supplies should be enabled only after 3.3 V supplies reach a value higher than 2.7 V.

I/O Power-Up and Supply Voltage Thresholds for Power-On Reset (Commercial and Industrial)

Sophisticated power-up management circuitry is designed into every SmartFusion cSoC. These circuits ensure easy transition from the powered-off state to the powered-up state of the device. In addition, the I/O will be in a known state through the power-up sequence. The basic principle is shown in Figure 2-1 on page 2-6.

There are five regions to consider during power-up.

SmartFusion I/Os are activated only if ALL of the following three conditions are met:

1. VCC and VCCxxxxIOBx are above the minimum specified trip points (Figure 2-1 on page 2-6).
2. VCCxxxxIOBx > VCC – 0.75 V (typical)
3. Chip is in the SoC Mode.

Table 2-11 • Summary of I/O Input Buffer Power (per pin) – Default I/O Software Settings Applicable to MSS I/O Banks

	VCCMSSIOBx (V)	Static Power PDC7 (mW)	Dynamic Power PAC9 (µW/MHz)
Single-Ended			
3.3 V LVTTL / 3.3 V LVCMOS	3.3	–	17.21
3.3 V LVCMOS / 3.3 V LVCMOS – Schmitt trigger	3.3	–	20.00
2.5 V LVCMOS	2.5	–	5.55
2.5 V LVCMOS – Schmitt trigger	2.5	–	7.03
1.8 V LVCMOS	1.8	–	2.61
1.8 V LVCMOS – Schmitt trigger	1.8	–	2.72
1.5 V LVCMOS (JESD8-11)	1.5	–	1.98
1.5 V LVCMOS (JESD8-11) – Schmitt trigger	1.5	–	1.93

Table 2-12 • Summary of I/O Output Buffer Power (per pin) – Default I/O Software Settings* Applicable to FPGA I/O Banks, I/O Assigned to EMC I/O Pins

	C_{LOAD} (pF)	VCCFPGAIOBx (V)	Static Power PDC8 (mW)	Dynamic Power PAC10 (µW/MHz)
Single-Ended				
3.3 V LVTTL / 3.3 V LVCMOS	35	3.3	–	475.66
2.5 V LVCMOS	35	2.5	–	270.50
1.8 V LVCMOS	35	1.8	–	152.17
1.5 V LVCMOS (JESD8-11)	35	1.5	–	104.44
3.3 V PCI	10	3.3	–	202.69
3.3 V PCI-X	10	3.3	–	202.69
Differential				
LVDS	–	2.5	7.74	88.26
LVPECL	–	3.3	19.54	164.99

*Note: *Dynamic power consumption is given for standard load and software default drive strength and output slew.*

Table 2-13 • Summary of I/O Output Buffer Power (per pin) – Default I/O Software Settings Applicable to MSS I/O Banks

	C_{LOAD} (pF)	VCCMSSIOBx (V)	Static Power PDC8 (mW)[2]	Dynamic Power PAC10 (µW/MHz)[3]
Single-Ended				
3.3 V LVTTL / 3.3 V LVCMOS	10	3.3	–	155.65
2.5 V LVCMOS	10	2.5	–	88.23
1.8 V LVCMOS	10	1.8	–	45.03
1.5 V LVCMOS (JESD8-11)	10	1.5	–	31.01

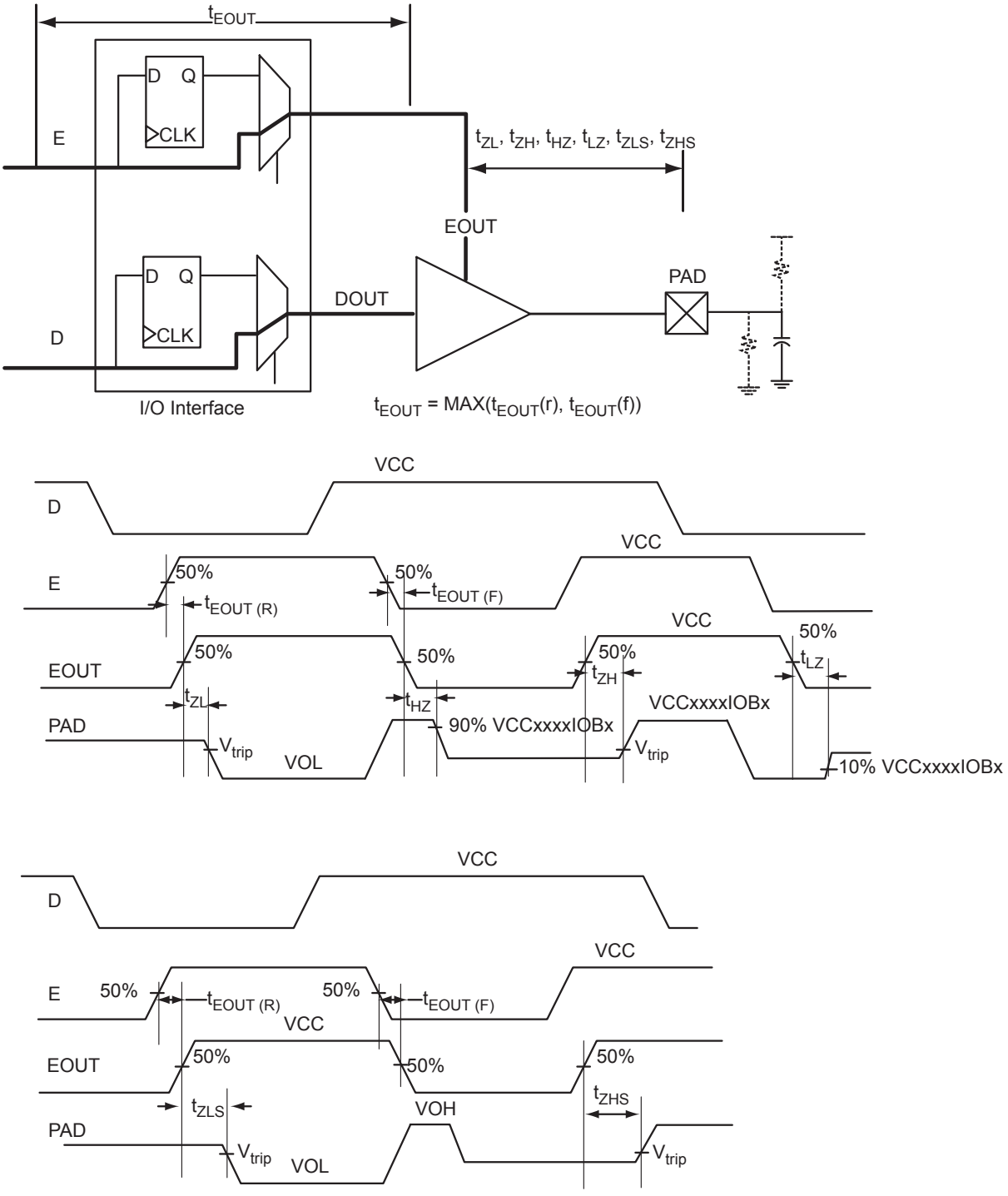

Figure 2-5 • **Tristate Output Buffer Timing Model and Delays (example)**

Timing Characteristics

Table 2-50 • 1.8 V LVCMOS High Slew
Worst Commercial-Case Conditions: T_J = 85°C, Worst-Case VCC = 1.425 V,
Worst-Case VCCxxxxIOBx = 1.7 V
Applicable to FPGA I/O Banks, I/O Assigned to EMC I/O Pins

Drive Strength	Speed Grade	t_{DOUT}	t_{DP}	t_{DIN}	t_{PY}	t_{EOUT}	t_{ZL}	t_{ZH}	t_{LZ}	t_{HZ}	t_{ZLS}	t_{ZHS}	Units
2 mA	Std.	0.60	11.06	0.04	1.14	0.39	8.61	11.06	2.61	1.59	10.67	13.12	ns
	–1	0.50	9.22	0.03	0.95	0.32	7.17	9.22	2.18	1.33	8.89	10.93	ns
4 mA	Std.	0.60	6.46	0.04	1.14	0.39	5.53	6.46	3.04	2.66	7.59	8.51	ns
	–1	0.50	5.38	0.03	0.95	0.32	4.61	5.38	2.54	2.22	6.33	7.10	ns
6 mA	Std.	0.60	4.16	0.04	1.14	0.39	3.99	4.16	3.34	3.18	6.05	6.22	ns
	–1	0.50	3.47	0.03	0.95	0.32	3.32	3.47	2.78	2.65	5.04	5.18	ns
8 mA	Std.	0.60	3.69	0.04	1.14	0.39	3.76	3.67	3.40	3.31	5.81	5.73	ns
	–1	0.50	3.07	0.03	0.95	0.32	3.13	3.06	2.84	2.76	4.85	4.78	ns
12 mA	Std.	0.60	3.38	0.04	1.14	0.39	3.44	2.86	3.50	3.82	5.50	4.91	ns
	–1	0.50	2.81	0.03	0.95	0.32	2.87	2.38	2.92	3.18	4.58	4.10	ns
16 mA	Std.	0.60	3.38	0.04	1.14	0.39	3.44	2.86	3.50	3.82	5.50	4.91	ns
	–1	0.50	2.81	0.03	0.95	0.32	2.87	2.38	2.92	3.18	4.58	4.10	ns

Notes:

1. *Software default selection highlighted in gray.*
2. *For specific junction temperature and voltage supply levels, refer to Table 2-7 on page 2-9 for derating values.*

Table 2-51 • 1.8 V LVCMOS Low Slew
Worst Commercial-Case Conditions: T_J = 85°C, Worst-Case VCC = 1.425 V,
Worst-Case VCCxxxxIOBx = 1.7 V
Applicable to FPGA I/O Banks, I/O Assigned to EMC I/O Pins

Drive Strength	Speed Grade	t_{DOUT}	t_{DP}	t_{DIN}	t_{PY}	t_{EOUT}	t_{ZL}	t_{ZH}	t_{LZ}	t_{HZ}	t_{ZLS}	t_{ZHS}	Units
2 mA	Std.	0.60	14.24	0.04	1.14	0.39	13.47	14.24	2.62	1.54	15.53	16.30	ns
	–1	0.50	11.87	0.03	0.95	0.32	11.23	11.87	2.18	1.28	12.94	13.59	ns
4 mA	Std.	0.60	9.74	0.04	1.14	0.39	9.92	9.62	3.05	2.57	11.98	11.68	ns
	–1	0.50	8.11	0.03	0.95	0.32	8.26	8.02	2.54	2.14	9.98	9.74	ns
6 mA	Std.	0.60	7.67	0.04	1.14	0.39	7.81	7.24	3.34	3.08	9.87	9.30	ns
	–1	0.50	6.39	0.03	0.95	0.32	6.51	6.03	2.79	2.56	8.23	7.75	ns
8 mA	Std.	0.60	7.15	0.04	1.14	0.39	7.29	6.75	3.41	3.21	9.34	8.80	ns
	–1	0.50	5.96	0.03	0.95	0.32	6.07	5.62	2.84	2.68	7.79	7.34	ns
12 mA	Std.	0.60	6.76	0.04	1.14	0.39	6.89	6.75	3.50	3.70	8.95	8.81	ns
	–1	0.50	5.64	0.03	0.95	0.32	5.74	5.62	2.92	3.08	7.46	7.34	ns
16 mA	Std.	0.60	6.76	0.04	1.14	0.39	6.89	6.75	3.50	3.70	8.95	8.81	ns
	–1	0.50	5.64	0.03	0.95	0.32	5.74	5.62	2.92	3.08	7.46	7.34	ns

Note: For specific junction temperature and voltage supply levels, refer to Table 2-7 on page 2-9 for derating values.

Table 2-52 • 1.8 V LVCMOS High Slew
Worst Commercial-Case Conditions: T_J = 85°C, Worst-Case VCC = 1.425 V,
Worst-Case VCCxxxxIOBx = 1.7 V
Applicable to MSS I/O Banks

Drive Strength	Speed Grade	t_{DOUT}	t_{DP}	t_{DIN}	t_{PY}	t_{PYS}	t_{EOUT}	t_{ZL}	t_{ZH}	t_{LZ}	t_{HZ}	Units
4 mA	Std.	0.22	2.77	0.09	1.09	1.64	0.22	2.82	2.72	2.21	2.25	ns
	–1	0.18	2.31	0.07	0.91	1.37	0.18	2.35	2.27	1.84	1.87	ns

Notes:

1. *Software default selection highlighted in gray.*
2. *For specific junction temperature and voltage supply levels, refer to Table 2-7 on page 2-9 for derating values.*

Fully Registered I/O Buffers with Synchronous Enable and Asynchronous Clear

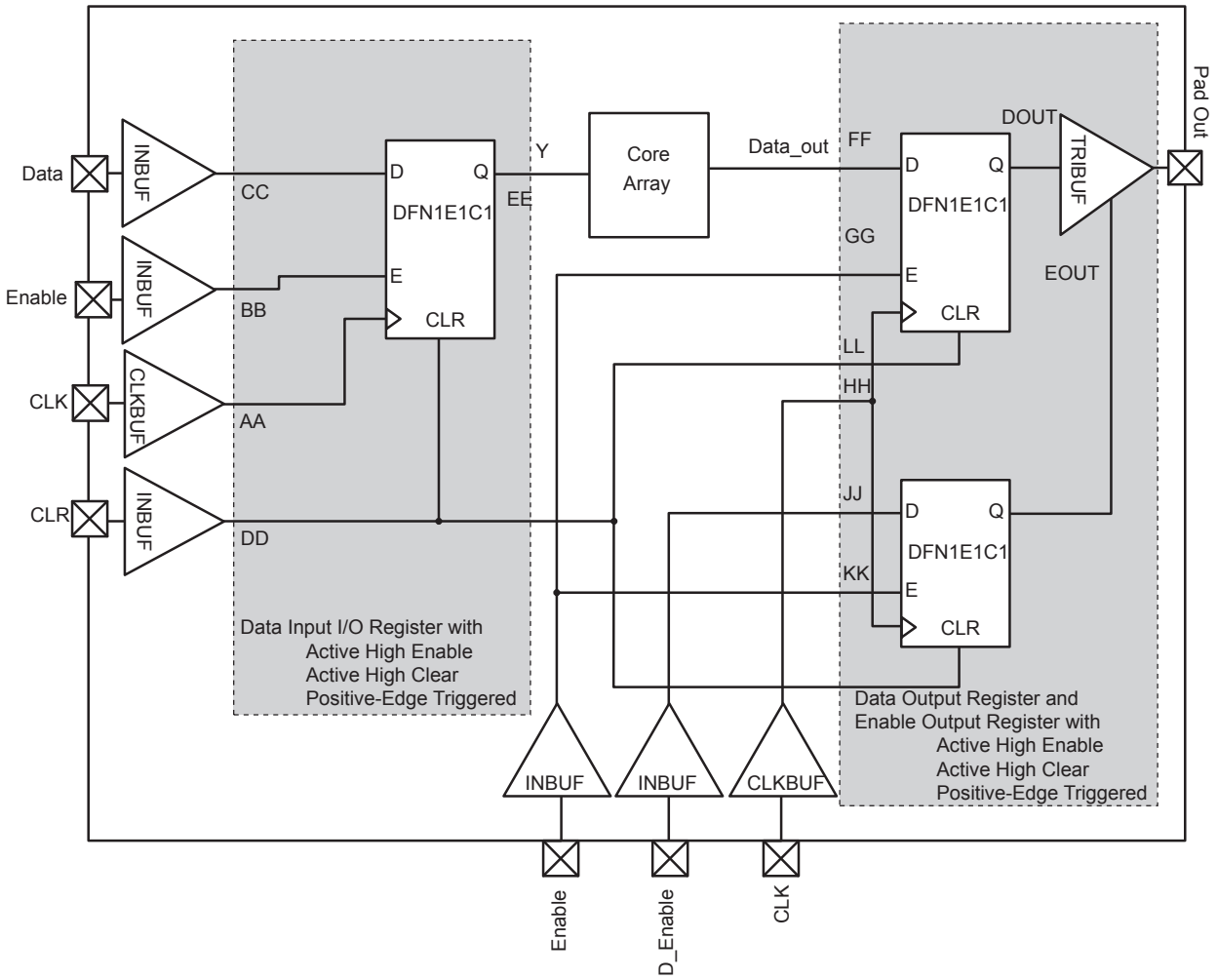

Figure 2-15 • **Timing Model of the Registered I/O Buffers with Synchronous Enable and Asynchronous Clear**

Input Register

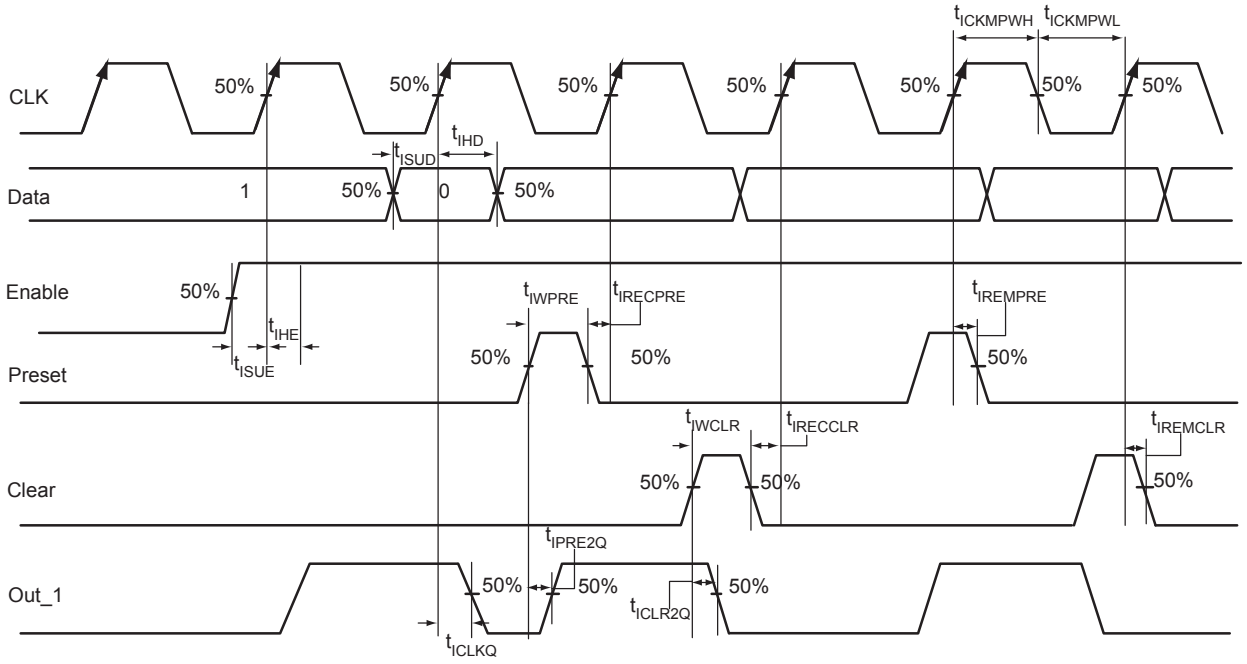

Figure 2-16 • **Input Register Timing Diagram**

Timing Characteristics

Table 2-71 • **Input Data Register Propagation Delays**
Worst Commercial-Case Conditions: T_J = 85°C, Worst-Case VCC = 1.425 V

Parameter	Description	–1	Std.	Units
t_{ICLKQ}	Clock-to-Q of the Input Data Register	0.24	0.29	ns
t_{ISUD}	Data Setup Time for the Input Data Register	0.27	0.32	ns
t_{IHD}	Data Hold Time for the Input Data Register	0.00	0.00	ns
t_{ISUE}	Enable Setup Time for the Input Data Register	0.38	0.45	ns
t_{IHE}	Enable Hold Time for the Input Data Register	0.00	0.00	ns
t_{ICLR2Q}	Asynchronous Clear-to-Q of the Input Data Register	0.46	0.55	ns
t_{IPRE2Q}	Asynchronous Preset-to-Q of the Input Data Register	0.46	0.55	ns
$t_{IREMCLR}$	Asynchronous Clear Removal Time for the Input Data Register	0.00	0.00	ns
$t_{IRECCLR}$	Asynchronous Clear Recovery Time for the Input Data Register	0.23	0.27	ns
$t_{IREMPRE}$	Asynchronous Preset Removal Time for the Input Data Register	0.00	0.00	ns
$t_{IRECPRE}$	Asynchronous Preset Recovery Time for the Input Data Register	0.23	0.27	ns
t_{IWCLR}	Asynchronous Clear Minimum Pulse Width for the Input Data Register	0.22	0.22	ns
t_{IWPRE}	Asynchronous Preset Minimum Pulse Width for the Input Data Register	0.22	0.22	ns
$t_{ICKMPWH}$	Clock Minimum Pulse Width High for the Input Data Register	0.36	0.36	ns
$t_{ICKMPWL}$	Clock Minimum Pulse Width Low for the Input Data Register	0.32	0.32	ns

Note: For the derating values at specific junction temperature and voltage supply levels, refer to Table 2-7 on page 2-9 for derating values.

Output Enable Register

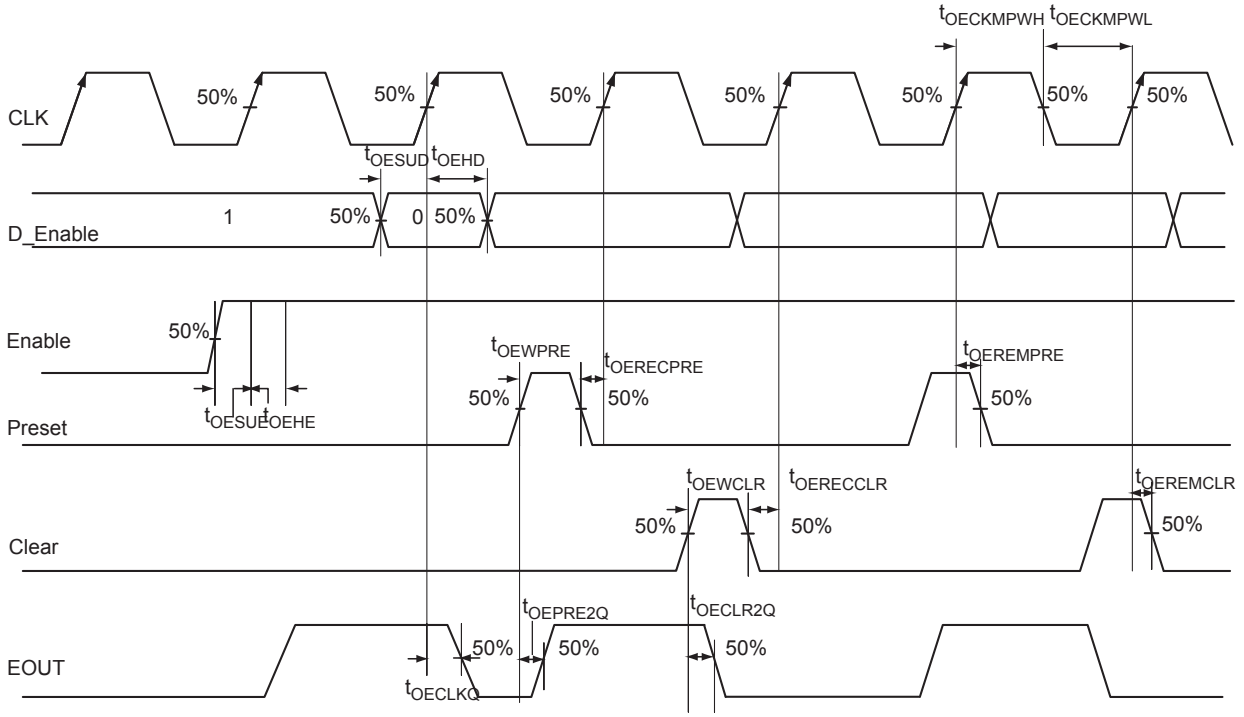

Figure 2-18 • **Output Enable Register Timing Diagram**

Timing Characteristics

Table 2-73 • **Output Enable Register Propagation Delays**
Worst Commercial-Case Conditions: T_J = 85°C, Worst-Case VCC = 1.425 V

Parameter	Description	–1	Std.	Units
t_{OECLKQ}	Clock-to-Q of the Output Enable Register	0.45	0.54	ns
t_{OESUD}	Data Setup Time for the Output Enable Register	0.32	0.38	ns
t_{OEHD}	Data Hold Time for the Output Enable Register	0.00	0.00	ns
t_{OESUE}	Enable Setup Time for the Output Enable Register	0.44	0.53	ns
t_{OEHE}	Enable Hold Time for the Output Enable Register	0.00	0.00	ns
$t_{OECLR2Q}$	Asynchronous Clear-to-Q of the Output Enable Register	0.68	0.81	ns
$t_{OEPRE2Q}$	Asynchronous Preset-to-Q of the Output Enable Register	0.68	0.81	ns
$t_{OEREMCLR}$	Asynchronous Clear Removal Time for the Output Enable Register	0.00	0.00	ns
$t_{ORECCLR}$	Asynchronous Clear Recovery Time for the Output Enable Register	0.23	0.27	ns
$t_{OEREMPRE}$	Asynchronous Preset Removal Time for the Output Enable Register	0.00	0.00	ns
$t_{ORECPRE}$	Asynchronous Preset Recovery Time for the Output Enable Register	0.23	0.27	ns
t_{OEWCLR}	Asynchronous Clear Minimum Pulse Width for the Output Enable Register	0.22	0.22	ns
t_{OEWPRE}	Asynchronous Preset Minimum Pulse Width for the Output Enable Register	0.22	0.22	ns
$t_{OECKMPWH}$	Clock Minimum Pulse Width High for the Output Enable Register	0.36	0.36	ns
$t_{OECKMPWL}$	Clock Minimum Pulse Width Low for the Output Enable Register	0.32	0.32	ns

Note: For specific junction temperature and voltage supply levels, refer to Table 2-7 on page 2-9 for derating values.

VersaTile Characteristics

VersaTile Specifications as a Combinatorial Module

The SmartFusion library offers all combinations of LUT-3 combinatorial functions. In this section, timing characteristics are presented for a sample of the library. For more details, refer to the *IGLOO/e, Fusion, ProASIC3/E, and SmartFusion Macro Library Guide*.

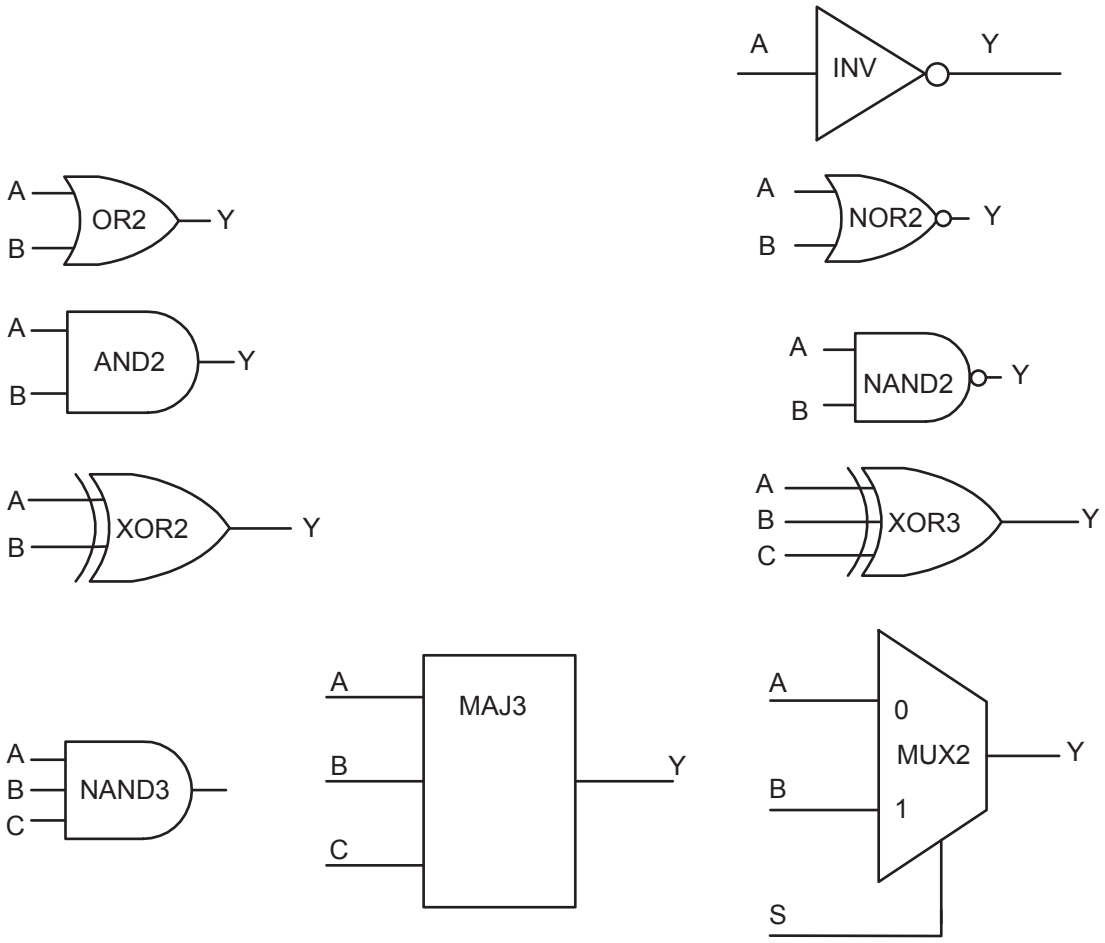

Figure 2-23 • **Sample of Combinatorial Cells**

Timing Characteristics

Table 2-87 • RAM4K9
Worst Commercial-Case Conditions: T_J = 85°C, Worst-Case VCC = 1.425 V

Parameter	Description	–1	Std.	Units
t_{AS}	Address setup time	0.25	0.30	ns
t_{AH}	Address hold time	0.00	0.00	ns
t_{ENS}	REN, WEN setup time	0.15	0.17	ns
t_{ENH}	REN, WEN hold time	0.10	0.12	ns
t_{BKS}	BLK setup time	0.24	0.28	ns
t_{BKH}	BLK hold time	0.02	0.02	ns
t_{DS}	Input data (DIN) setup time	0.19	0.22	ns
t_{DH}	Input data (DIN) hold time	0.00	0.00	ns
t_{CKQ1}	Clock High to new data valid on DOUT (output retained, WMODE = 0)	1.81	2.18	ns
	Clock High to new data valid on DOUT (flow-through, WMODE = 1)	2.39	2.87	ns
t_{CKQ2}	Clock High to new data valid on DOUT (pipelined)	0.91	1.09	ns
t_{C2CWWH}[1]	Address collision clk-to-clk delay for reliable write after write on same address—applicable to rising edge	0.23	0.26	ns
t_{C2CRWH}[1]	Address collision clk-to-clk delay for reliable read access after write on same address—applicable to opening edge	0.34	0.38	ns
t_{C2CWRH}[1]	Address collision clk-to-clk delay for reliable write access after read on same address— applicable to opening edge	0.37	0.42	ns
t_{RSTBQ}	RESET Low to data out Low on DOUT (flow-through)	0.94	1.12	ns
	RESET Low to Data Out Low on DOUT (pipelined)	0.94	1.12	ns
$t_{REMRSTB}$	RESET removal	0.29	0.35	ns
$t_{RECRSTB}$	RESET recovery	1.52	1.83	ns
$t_{MPWRSTB}$	RESET minimum pulse width	0.22	0.22	ns
t_{CYC}	Clock cycle time	3.28	3.28	ns
F_{MAX}	Maximum clock frequency	305	305	MHz

Notes:

1. *For more information, refer to the Simultaneous Read-Write Operations in Dual-Port SRAM for Flash-Based cSoCs and FPGAs application note.*
2. *For the derating values at specific junction temperature and voltage supply levels, refer to Table 2-7 on page 2-9 for derating values.*

Table 2-88 • RAM512X18
Worst Commercial-Case Conditions: T_J = 85°C, Worst-Case VCC = 1.425 V

Parameter	Description	–1	Std.	Units
t_{AS}	Address setup time	0.25	0.30	ns
t_{AH}	Address hold time	0.00	0.00	ns
t_{ENS}	REN, WEN setup time	0.09	0.11	ns
t_{ENH}	REN, WEN hold time	0.06	0.07	ns
t_{DS}	Input data (WD) setup time	0.19	0.22	ns
t_{DH}	Input data (WD) hold time	0.00	0.00	ns
t_{CKQ1}	Clock High to new data valid on RD (output retained, WMODE = 0)	2.19	2.63	ns
t_{CKQ2}	Clock High to new data valid on RD (pipelined)	0.91	1.09	ns
t_{C2CRWH} [1]	Address collision clk-to-clk delay for reliable read access after write on same address—applicable to opening edge	0.38	0.43	ns
t_{C2CWRH} [1]	Address collision clk-to-clk delay for reliable write access after read on same address—applicable to opening edge	0.44	0.50	ns
t_{RSTBQ}	RESET Low to data out Low on RD (flow-through)	0.94	1.12	ns
	RESET Low to data out Low on RD (pipelined)	0.94	1.12	ns
$t_{REMRSTB}$	RESET removal	0.29	0.35	ns
$t_{RECRSTB}$	RESET recovery	1.52	1.83	ns
$t_{MPWRSTB}$	RESET minimum pulse width	0.22	0.22	ns
t_{CYC}	Clock cycle time	3.28	3.28	ns
F_{MAX}	Maximum clock frequency	305	305	MHz

Notes:

1. *For more information, refer to the Simultaneous Read-Write Operations in Dual-Port SRAM for Flash-Based cSoCs and FPGAs application note.*
2. *For the derating values at specific junction temperature and voltage supply levels, refer to Table 2-7 on page 2-9 for derating values.*

Programmable Analog Specifications

Current Monitor

Unless otherwise noted, current monitor performance is specified at 25°C with nominal power supply voltages, with the output measured using the internal voltage reference with the internal ADC in 12-bit mode and 91 Ksps, after digital compensation. All results are based on averaging over 16 samples.

***Table 2-93* • Current Monitor Performance Specification**

Specification	Test Conditions	Min.	Typical	Max.	Units
Input voltage range (for driving ADC over full range)		0 – 48	0 – 50	1 – 51	mV
Analog gain	From the differential voltage across the input pads to the ADC input		50		V/V
Input referred offset voltage	Input referred offset voltage	0	0.1	0.5	mV
	–40ºC to +100ºC	0	0.1	0.5	mV
Gain error	Slope of BFSL vs. 50 V/V		±0.1	±0.5	% nom.
	–40ºC to +100ºC			±0.5	% nom.
Overall Accuracy	Peak error from ideal transfer function, 25°C		±(0.1 + 0.25%)	±(0.4 + 1.5%)	mV plus % reading
Input referred noise	0 VDC input (no output averaging)	0.3	0.4	0.5	mVrms
Common-mode rejection ratio	0 V to 12 VDC common-mode voltage	–86	–87		dB
Analog settling time	To 0.1% of final value (with ADC load)				
	From CM_STB (High)	5			µs
	From ADC_START (High)	5		200	µs
Input capacitance			8		pF
Input biased current	CM[n] or TM[n] pad, –40°C to +100°C over maximum input voltage range (plus is into pad)				
	Strobe = 0; IBIAS on CM[n]		0		µA
	Strobe = 1; IBIAS on CM[n]		1		µA
	Strobe = 0; IBIAS on TM[n]		2		µA
	Strobe = 1; IBIAS on TM[n]		1		µA
Power supply rejection ratio	DC (0 – 10 KHz)	41	42		dB
Incremental operational current monitor power supply current requirements (per current monitor instance, not including ADC or VAREFx)	VCC33A		150		µA
	VCC33AP		140		µA
	VCC15A		50		µA

Note: Under no condition should the TM pad ever be greater than 10 mV above the CM pad. This restriction is applicable only if current monitor is used.

Compile and Debug

Microsemi's SoftConsole is a free Eclipse-based IDE that enables the rapid production of C and C++ executables for Microsemi FPGA and cSoCs using Cortex-M3, Cortex-M1 and Core8051s. For SmartFusion support, SoftConsole includes the GNU C/C++ compiler and GDB debugger. Additional examples can be found on the SoftConsole page:

- Using UART with SmartFusion: SoftConsole Standalone Flow Tutorial
  - Design Files
- Displaying POT Level with LEDs: Libero SoC and SoftConsole Flow Tutorial for SmartFusion
  - Design Files

IAR Embedded Workbench® for ARM/Cortex is an integrated development environment for building and debugging embedded ARM applications using assembler, C and C++. It includes a project manager, editor, build and debugger tools with support for RTOS-aware debugging on hardware or in a simulator.

- Designing SmartFusion cSoC with IAR Systems
- IAR Embedded Workbench IDE User Guide for ARM
- Download Evaluation or Kickstart version of IAR Embedded Workbench for ARM

Keil's Microcontroller Development Kit comes in two editions: MDK-ARM and MDK Basic. Both editions feature µVision®, the ARM Compiler, MicroLib, and RTX, but the MDK Basic edition is limited to 256K so that small applications are more affordable.

- Designing SmartFusion cSoC with Keil
- Using Keil µVision and Microsemi SmartFusion cSoC
  - Programming file for use with this tutorial
- Keil Microcontroller Development Kit for ARM Product Manuals
- Download Evaluation version of Keil MDK-ARM

CMSIS COMPLIANT ARM® Cortex™ Microcontroller Software Interface Standard	Microsemi	KEIL™ An ARM® Company	IAR SYSTEMS
Software IDE	**SoftConsole**	**Vision IDE**	**Embedded Workbench**
Website	www.microsemi.com/soc	www.keil.com	www.iar.com
Free versions from SoC Products Group	Free with Libero SoC	32 K code limited	32 K code limited
Available from Vendor	N/A	Full version	Full version
Compiler	GNU GCC	RealView C/C++	IAR ARM Compiler
Debugger	GDB debug	Vision Debugger	C-SPY Debugger
Instruction Set Simulator	No	Vision Simulator	Yes
Debug Hardware	FlashPro4	ULINK2 or ULINK-ME	J-LINK or J-LINK Lite

Operating Systems

FreeRTOS™ is a portable, open source, royalty free, mini real-time kernel (a free-to-download and free-to-deploy RTOS that can be used in commercial applications without any requirement to expose your proprietary source code). FreeRTOS is scalable and designed specifically for small embedded systems. This FreeRTOS version ported by Microsemi is 6.0.1. For more information, visit the FreeRTOS website: www.freertos.org

- SmartFusion Webserver Demo Using uIP and FreeRTOS
- SmartFusion cSoC: Running Webserver, TFTP on lwIP TCP/IP Stack Application Note

Name	Type	Polarity/Bus Size	Description
NCAP		1	Negative capacitor connection. This is the negative terminal of the charge pump. A capacitor, with a 2.2 µF recommended value, is required to connect between PCAP and NCAP. Analog charge pump capacitors are not needed if none of the analog SCB features are used and none of the SDDs are used. In that case it should be left unconnected.
PCAP		1	Positive Capacitor connection. This is the positive terminal of the charge pump. A capacitor, with a 2.2 µF recommended value, is required to connect between PCAP and NCAP. If this pin is not used, it must be left unconnected/floating. In this case, no capacitor is needed. Analog charge pump capacitors are not needed if none of the analog SCB features are used, and none of the SDDs are used.
PTBASE		1	Pass transistor base connection This is the control signal of the voltage regulator. This pin should be connected to the base of an external pass transistor used with the 1.5 V internal voltage regulator and can be floating if not used.
PTEM		1	Pass transistor emitter connection. This is the feedback input of the voltage regulator. This pin should be connected to the emitter of an external pass transistor used with the 1.5 V internal voltage regulator and can be floating if not used.
MSS_RESET_N		Low	Low Reset signal which can be used as an external reset and can also be used as a system level reset under control of the Cortex-M3 processor. MSS_RESET_N is an output asserted low after power-on reset. The direction of MSS_RESET_N changes during the execution of the Microsemi System Boot when chip-level reset is enabled. The Microsemi System Boot reconfigures MSS_RESET_N to become a reset input signal when chip-level reset is enabled. It has an internal pull-up so it can be left floating. In the current software, the MSS_RESET_N is modeled as an external input signal only.
PU_N	In	Low	Push-button is the connection for the external momentary switch used to turn on the 1.5 V voltage regulator and can be floating if not used.

Analog Front-End (AFE)

Name	Type	Description	Associated With	
			ADC/SDD	SCB
ABPS0	In	SCB 0 / active bipolar prescaler input 1. See the Active Bipolar Prescaler (ABPS) section in the *SmartFusion Programmable Analog User's Guide*.	ADC0	SCB0
ABPS1	In	SCB 0 / active bipolar prescaler Input 2	ADC0	SCB0
ABPS2	In	SCB 1 / active bipolar prescaler Input 1	ADC0	SCB1
ABPS3	In	SCB 1 / active bipolar prescaler Input 2	ADC0	SCB1
ABPS4	In	SCB 2 / active bipolar prescaler Input 1	ADC1	SCB2
ABPS5	In	SCB 2 / active bipolar prescaler Input 2	ADC1	SCB2
ABPS6	In	SCB 3 / active bipolar prescaler Input 1	ADC1	SCB3
ABPS7	In	SCB 3 / active bipolar prescaler input 2	ADC1	SCB3
ABPS8	In	SCB 4 / active bipolar prescaler input 1	ADC2	SCB4
ABPS9	In	SCB 4 / active bipolar prescaler input 2	ADC2	SCB4
ADC0	In	ADC 0 direct input 0 / FPGA Input. See the "Sigma-Delta Digital-to-Analog Converter (DAC)" section in the *SmartFusion Programmable Analog User's Guide*.	ADC0	SCB0
ADC1	In	ADC 0 direct input 1 / FPGA input	ADC0	SCB0
ADC2	In	ADC 0 direct input 2 / FPGA input	ADC0	SCB1
ADC3	In	ADC 0 direct input 3 / FPGA input	ADC0	SCB1
ADC4	In	ADC 1 direct input 0 / FPGA input	ADC1	SCB2
ADC5	In	ADC 1 direct input 1 / FPGA input	ADC1	SCB2
ADC6	In	ADC 1 direct input 2 / FPGA input	ADC1	SCB3
ADC7	In	ADC 1 direct input 3 / FPGA input	ADC1	SCB3
ADC8	In	ADC 2 direct input 0 / FPGA input	ADC2	SCB4
ADC9	In	ADC 2 direct input 1 / FPGA input	ADC2	SCB4
ADC10	In	ADC 2 direct input 2 / FPGA input	ADC2	N/A
ADC11	In	ADC 2 direct input 3 / FPGA input	ADC2	N/A
CM0	In	SCB 0 / high side of current monitor / comparator Positive input. See the Current Monitor section in the *SmartFusion Programmable Analog User's Guide*.	ADC0	SCB0
CM1	In	SCB 1 / high side of current monitor / comparator. Positive input.	ADC0	SCB1
CM2	In	SCB 2 / high side of current monitor / comparator. Positive input.	ADC1	SCB2
CM3	In	SCB 3 / high side of current monitor / comparator. Positive input.	ADC1	SCB3
CM4	In	SCB 4 / high side of current monitor / comparator. Positive input.	ADC2	SCB4

Note: Unused analog inputs should be grounded. This aids in shielding and prevents an undesired coupling path.

TQ144	
Pin Number	**A2F060 Function**
1	VCCPLL0
2	VCOMPLA0
3	GNDQ
4	GFA2/IO42PDB5V0
5	GFB2/IO42NDB5V0
6	GFC2/IO41PDB5V0
7	IO41NDB5V0
8	VCC
9	GND
10	VCCFPGAIOB5
11	IO38PDB5V0
12	IO38NDB5V0
13	IO36PDB5V0
14	IO36NDB5V0
15	GND
16	GNDRCOSC
17	VCCRCOSC
18	MSS_RESET_N
19	GPIO_0/IO33RSB4V0
20	GPIO_1/IO32RSB4V0
21	GPIO_2/IO31RSB4V0
22	GPIO_3/IO30RSB4V0
23	GPIO_4/IO29RSB4V0
24	GND
25	VCCMSSIOB4
26	VCC
27	GPIO_5/IO28RSB4V0
28	GPIO_6/IO27RSB4V0
29	GPIO_7/IO26RSB4V0
30	GPIO_8/IO25RSB4V0
31	VCCESRAM
32	GNDSDD0
33	VCC33SDD0
34	VCC15A
35	PCAP
36	NCAP

TQ144	
Pin Number	**A2F060 Function**
73	VCC33A
74	PTEM
75	PTBASE
76	SPI_0_DO/GPIO_16
77	SPI_0_DI/GPIO_17
78	SPI_0_CLK/GPIO_18
79	SPI_0_SS/GPIO_19
80	UART_0_RXD/GPIO_21
81	UART_0_TXD/GPIO_20
82	UART_1_RXD/GPIO_29
83	UART_1_TXD/GPIO_28
84	VCC
85	VCCMSSIOB2
86	GND
87	I2C_1_SDA/GPIO_30
88	I2C_1_SCL/GPIO_31
89	I2C_0_SDA/GPIO_22
90	I2C_0_SCL/GPIO_23
91	GNDENVM
92	VCCENVM
93	JTAGSEL
94	TCK
95	TDI
96	TMS
97	TDO
98	TRSTB
99	VJTAG
100	VDDBAT
101	VCCLPXTAL
102	LPXOUT
103	LPXIN
104	GNDLPXTAL
105	GNDMAINXTAL
106	MAINXOUT
107	MAINXIN
108	VCCMAINXTAL

Pin No.	CS288		
	A2F060 Function	A2F200 Function	A2F500 Function
P19	VCCMSSIOB2	VCCMSSIOB2	VCCMSSIOB2
P21	GND	GND	GND
R1	GPIO_2/IO31RSB4V0	MAC_MDIO/IO49RSB4V0	MAC_MDIO/IO58RSB4V0
R3	GPIO_1/IO32RSB4V0	MAC_TXEN/IO52RSB4V0	MAC_TXEN/IO61RSB4V0
R5	GPIO_3/IO30RSB4V0	MAC_TXD[0]/IO56RSB4V0	MAC_TXD[0]/IO65RSB4V0
R6	GPIO_10/IO35RSB4V0	MAC_CRSDV/IO51RSB4V0	MAC_CRSDV/IO60RSB4V0
R9	GNDA	GNDA	GNDA
R13	GNDA	GNDA	GNDA
R16	UART_1_RXD/GPIO_29	UART_1_RXD/GPIO_29	UART_1_RXD/GPIO_29
R17	UART_1_TXD/GPIO_28	UART_1_TXD/GPIO_28	UART_1_TXD/GPIO_28
R19	I2C_0_SDA/GPIO_22	I2C_0_SDA/GPIO_22	I2C_0_SDA/GPIO_22
R21	I2C_1_SDA/GPIO_30	I2C_1_SDA/GPIO_30	I2C_1_SDA/GPIO_30
T1	GND	GND	GND
T3	NC	MAC_TXD[1]/IO55RSB4V0	MAC_TXD[1]/IO64RSB4V0
T5	NC	MAC_RXD[1]/IO53RSB4V0	MAC_RXD[1]/IO62RSB4V0
T6	GPIO_11/IO34RSB4V0	MAC_RXER/IO50RSB4V0	MAC_RXER/IO59RSB4V0
T7	NC	CM1	CM1
T8	NC	ADC1	ADC1
T9	NC	GND33ADC0	GND33ADC0
T10	NC	VCC15ADC0	VCC15ADC0
T11	GND33ADC0	GND33ADC1	GND33ADC1
T12	VAREF0	VAREF1	VAREF1
T13	ADC7	ADC4	ADC4
T14	TM0	TM3	TM3
T15	SPI_1_SS/GPIO_27	SPI_1_SS/GPIO_27	SPI_1_SS/GPIO_27
T16	VCCMSSIOB2	VCCMSSIOB2	VCCMSSIOB2
T17	UART_0_RXD/GPIO_21	UART_0_RXD/GPIO_21	UART_0_RXD/GPIO_21
T19	UART_0_TXD/GPIO_20	UART_0_TXD/GPIO_20	UART_0_TXD/GPIO_20
T21	I2C_1_SCL/GPIO_31	I2C_1_SCL/GPIO_31	I2C_1_SCL/GPIO_31
U1	NC	MAC_RXD[0]/IO54RSB4V0	MAC_RXD[0]/IO63RSB4V0
U3	VCCMSSIOB4	VCCMSSIOB4	VCCMSSIOB4

Notes:

1. *Shading denotes pins that do not have completely identical functions from density to density. For example, the bank assignment can be different for an I/O, or the function might be available only on a larger density device.*
2. **: Indicates that the signal assigned to the pins as a CLKBUF/CLKBUF_LVPECL/CLKBUF_LVDS goes through a glitchless mux. In order for the glitchless mux to operate correctly, the signal must be a free-running clock signal. Refer to the 'Glitchless MUX' section in the SmartFusion Microcontroller Subsystem User's Guide for more details.*

Pin No.	FG256		
	A2F060 Function	A2F200 Function	A2F500 Function
B16	GNDQ	GNDQ	GNDQ
C1	EMC_DB[14]/IO45NDB5V0	EMC_DB[14]/GAB2/IO71NDB5V0	EMC_DB[14]/GAB2/IO88NDB5V0
C2	VCCPLL0	VCCPLL	VCCPLL0
C3	EMC_BYTEN[0]/IO02NDB0V0	EMC_BYTEN[0]/GAC0/IO02NDB0V0	EMC_BYTEN[0]/GAC0/IO07NDB0V0
C4	VCCFPGAIOB0	VCCFPGAIOB0	VCCFPGAIOB0
C5	EMC_CS0_N/IO01NDB0V0	EMC_CS0_N/GAB0/IO01NDB0V0	EMC_CS0_N/GAB0/IO05NDB0V0
C6	EMC_CS1_N/IO01PDB0V0	EMC_CS1_N/GAB1/IO01PDB0V0	EMC_CS1_N/GAB1/IO05PDB0V0
C7	GND	GND	GND
C8	EMC_AB[8]/IO08NDB0V0	EMC_AB[8]/IO08NDB0V0	EMC_AB[8]/IO13NDB0V0
C9	EMC_AB[11]/IO09PDB0V0	EMC_AB[11]/IO09PDB0V0	EMC_AB[11]/IO11PDB0V0
C10	VCCFPGAIOB0	VCCFPGAIOB0	VCCFPGAIOB0
C11	EMC_AB[17]/IO12PDB0V0	EMC_AB[17]/IO12PDB0V0	EMC_AB[17]/IO17PDB0V0
C12	EMC_AB[19]/IO13PDB0V0	EMC_AB[19]/IO13PDB0V0	EMC_AB[19]/IO18PDB0V0
C13	GND	GND	GND
C14	GCC0/IO18NPB0V0	GBA2/IO20PPB1V0	GBA2/IO27PPB1V0
C15	GCB0/IO19NDB0V0	GCA2/IO23PDB1V0	GCA2/IO28PDB1V0 *
C16	GCB1/IO19PDB0V0	IO23NDB1V0	IO28NDB1V0
D1	VCCFPGAIOB5	VCCFPGAIOB5	VCCFPGAIOB5
D2	VCOMPLA0	VCOMPLA	VCOMPLA0
D3	GND	GND	GND
D4	GNDQ	GNDQ	GNDQ
D5	EMC_CLK/IO00NDB0V0	EMC_CLK/GAA0/IO00NDB0V0	EMC_CLK/GAA0/IO02NDB0V0
D6	EMC_RW_N/IO00PDB0V0	EMC_RW_N/GAA1/IO00PDB0V0	EMC_RW_N/GAA1/IO02PDB0V0
D7	EMC_AB[6]/IO07NDB0V0	EMC_AB[6]/IO07NDB0V0	EMC_AB[6]/IO12NDB0V0
D8	EMC_AB[7]/IO07PDB0V0	EMC_AB[7]/IO07PDB0V0	EMC_AB[7]/IO12PDB0V0
D9	EMC_AB[10]/IO09NDB0V0	EMC_AB[10]/IO09NDB0V0	EMC_AB[10]/IO11NDB0V0
D10	EMC_AB[22]/IO15NDB0V0	EMC_AB[22]/IO15NDB0V0	EMC_AB[22]/IO19NDB0V0
D11	EMC_AB[23]/IO15PDB0V0	EMC_AB[23]/IO15PDB0V0	EMC_AB[23]/IO19PDB0V0
D12	GNDQ	GNDQ	GNDQ
D13	GCC1/IO18PPB0V0	GBB2/IO20NPB1V0	GBB2/IO27NPB1V0
D14	GCA0/IO20NDB0V0	GCB2/IO24PDB1V0	GCB2/IO33PDB1V0

Notes:

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2. **: Indicates that the signal assigned to the pins as a CLKBUF/CLKBUF_LVPECL/CLKBUF_LVDS goes through a glitchless mux. In order for the glitchless mux to operate correctly, the signal must be a free-running clock signal. Refer to the 'Glitchless MUX' section in the SmartFusion Microcontroller Subsystem User's Guide for more details.*

Pin No.	FG256		
	A2F060 Function	A2F200 Function	A2F500 Function
K12	UART_0_RXD/GPIO_21	UART_0_RXD/GPIO_21	UART_0_RXD/GPIO_21
K13	GND	GND	GND
K14	UART_1_TXD/GPIO_28	UART_1_TXD/GPIO_28	UART_1_TXD/GPIO_28
K15	UART_1_RXD/GPIO_29	UART_1_RXD/GPIO_29	UART_1_RXD/GPIO_29
K16	UART_0_TXD/GPIO_20	UART_0_TXD/GPIO_20	UART_0_TXD/GPIO_20
L1	GND	GND	GND
L2	GPIO_2/IO31RSB4V0	MAC_TXEN/IO52RSB4V0	MAC_TXEN/IO61RSB4V0
L3	GPIO_3/IO30RSB4V0	MAC_CRSDV/IO51RSB4V0	MAC_CRSDV/IO60RSB4V0
L4	GPIO_4/IO29RSB4V0	MAC_RXER/IO50RSB4V0	MAC_RXER/IO59RSB4V0
L5	GPIO_9/IO24RSB4V0	MAC_CLK	MAC_CLK
L6	GND	GND	GND
L7	VCC	VCC	VCC
L8	GND	GND	GND
L9	VCC	VCC	VCC
L10	GND	GND	GND
L11	VCCMSSIOB2	VCCMSSIOB2	VCCMSSIOB2
L12	SPI_1_DO/GPIO_24	SPI_1_DO/GPIO_24	SPI_1_DO/GPIO_24
L13	SPI_1_SS/GPIO_27	SPI_1_SS/GPIO_27	SPI_1_SS/GPIO_27
L14	SPI_1_CLK/GPIO_26	SPI_1_CLK/GPIO_26	SPI_1_CLK/GPIO_26
L15	SPI_1_DI/GPIO_25	SPI_1_DI/GPIO_25	SPI_1_DI/GPIO_25
L16	GND	GND	GND
M1	GPIO_5/IO28RSB4V0	MAC_TXD[0]/IO56RSB4V0	MAC_TXD[0]/IO65RSB4V0
M2	GPIO_6/IO27RSB4V0	MAC_TXD[1]/IO55RSB4V0	MAC_TXD[1]/IO64RSB4V0
M3	GPIO_7/IO26RSB4V0	MAC_RXD[0]/IO54RSB4V0	MAC_RXD[0]/IO63RSB4V0
M4	GND	GND	GND
M5	NC	ADC3	ADC3
M6	NC	GND15ADC0	GND15ADC0
M7	GND33ADC0	GND33ADC1	GND33ADC1
M8	GND33ADC0	GND33ADC1	GND33ADC1
M9	ADC7	ADC4	ADC4
M10	GNDTM0	GNDTM1	GNDTM1

Notes:

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2. **: Indicates that the signal assigned to the pins as a CLKBUF/CLKBUF_LVPECL/CLKBUF_LVDS goes through a glitchless mux. In order for the glitchless mux to operate correctly, the signal must be a free-running clock signal. Refer to the 'Glitchless MUX' section in the SmartFusion Microcontroller Subsystem User's Guide for more details.*