Microsemi Corporation - A2F060M3E-TQ144 Datasheet

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Embedded - System On Chip (SoC): The Heart of Modern Embedded Systems

Embedded - System On Chip (SoC) refers to an integrated circuit that consolidates all the essential components of a computer system into a single chip. This includes a microprocessor, memory, and other peripherals, all packed into one compact and efficient package. SoCs are designed to provide a complete computing solution, optimizing both space and power consumption, making them ideal for a wide range of embedded applications.

What are Embedded - System On Chip (SoC)?

System On Chip (SoC) integrates multiple functions of a computer or electronic system onto a single chip. Unlike traditional multi-chip solutions, SoCs combine a central

Details	
Product Status	Obsolete
Architecture	MCU, FPGA
Core Processor	ARM® Cortex®-M3
Flash Size	128KB
RAM Size	16KB
Peripherals	DMA, POR, WDT
Connectivity	EBI/EMI, I²C, SPI, UART/USART
Speed	80MHz
Primary Attributes	ProASIC®3 FPGA, 60K Gates, 1536D-Flip-Flops
Operating Temperature	0°C ~ 85°C (TJ)
Package / Case	144-LQFP
Supplier Device Package	144-TQFP (20x20)
Purchase URL	https://www.e-xfl.com/product-detail/microsemi/a2f060m3e-tq144

ProASIC3 FPGA Fabric

The SmartFusion cSoC family, based on the proven, low power, firm-error immune ProASIC®3 flash FPGA architecture, benefits from the advantages only flash-based devices offer:

Reduced Cost of Ownership

Advantages to the designer extend beyond low unit cost, high performance, and ease of use. Flash-based SmartFusion cSoCs are Instant On and do not need to be loaded from an external boot PROM at each power-up. On-board security mechanisms prevent access to the programming information and enable secure remote updates of the FPGA logic. Designers can perform secure remote in-system programming (ISP) to support future design iterations and critical field upgrades, with confidence that valuable IP cannot be compromised or copied. Secure ISP can be performed using the industry standard AES algorithm with MAC data authentication on the device.

Low Power

Flash-based SmartFusion cSoCs exhibit power characteristics similar to those of an ASIC, making them an ideal choice for power-sensitive applications. With SmartFusion cSoCs, there is no power-on current and no high current transition, both of which are common with SRAM-based FPGAs.

SmartFusion cSoCs also have low dynamic power consumption and support very low power time-keeping mode, offering further power savings.

Security

As the nonvolatile, flash-based SmartFusion cSoC family requires no boot PROM, there is no vulnerable external bitstream. SmartFusion cSoCs incorporate FlashLock®, which provides a unique combination of reprogrammability and design security without external overhead, advantages that only a device with nonvolatile flash programming can offer.

SmartFusion cSoCs utilize a 128-bit flash-based key lock and a separate AES key to provide security for programmed IP and configuration data. The FlashROM data in Fusion devices can also be encrypted prior to loading. Additionally, the flash memory blocks can be programmed during runtime using the AES-128 block cipher encryption standard (FIPS Publication 192).

SmartFusion cSoCs with AES-based security are designed to provide protection for remote field updates over public networks, such as the Internet, and help to ensure that valuable IP remains out of the hands of system overbuilders, system cloners, and IP thieves. As an additional security measure, the FPGA configuration data of a programmed Fusion device cannot be read back, although secure design verification is possible. During design, the user controls and defines both internal and external access to the flash memory blocks.

Security, built into the FPGA fabric, is an inherent component of the SmartFusion cSoC family. The flash cells are located beneath seven metal layers, and many device design and layout techniques have been used to make invasive attacks extremely difficult. SmartFusion cSoCs, with FlashLock and AES security, are unique in being highly resistant to both invasive and noninvasive attacks. Your valuable IP is protected with industry standard security measures, making remote ISP feasible. A SmartFusion cSoC provides the highest security available for programmable logic designs.

Single Chip

Flash-based FPGAs store their configuration information in on-chip flash cells. Once programmed, the configuration data is an inherent part of the FPGA structure, and no external configuration data needs to be loaded at system power-up (unlike SRAM-based FPGAs). Therefore, flash-based SmartFusion cSoCs do not require system configuration components such as electrically erasable programmable read-only memories (EEPROMs) or microcontrollers to load device configuration data during power-up. This reduces bill-of-materials costs and PCB area, and increases system security and reliability.

Instant On

Flash-based SmartFusion cSoCs are Instant On. Instant On SmartFusion cSoCs greatly simplify total system design and reduce total system cost by eliminating the need for complex programmable logic devices (CPLDs). SmartFusion Instant On clocking (PLLs) replace off-chip clocking resources. In addition, glitches and brownouts in system power will not corrupt the SmartFusion flash configuration. Unlike SRAM-based FPGAs, the device will not have to be reloaded when system power is restored.

Thermal Characteristics

Introduction

The temperature variable in the SoC Products Group Designer software refers to the junction temperature, not the ambient, case, or board temperatures. This is an important distinction because dynamic and static power consumption will cause the chip's junction temperature to be higher than the ambient, case, or board temperatures. EQ 1 through EQ 3 give the relationship between thermal resistance, temperature gradient, and power.

$$\theta_{JA} = \frac{T_J - \theta_A}{P}$$

EQ 1

$$\theta_{JB} = \frac{T_J - T_B}{P}$$

EQ 2

$$\theta_{JC} = \frac{T_J - T_C}{P}$$

EQ 3

where

θ_{JA} = Junction-to-air thermal resistance
θ_{JB} = Junction-to-board thermal resistance
θ_{JC} = Junction-to-case thermal resistance
T_J = Junction temperature
T_A = Ambient temperature
T_B = Board temperature (measured 1.0 mm away from the package edge)
T_C = Case temperature
P = Total power dissipated by the device

Table 2-6 • **Package Thermal Resistance**

Product	θ_{JA}			θ_{JC}	θ_{JB}	Units
	Still Air	1.0 m/s	2.5 m/s			
A2F200M3F-FG256	33.7	30.0	28.3	9.3	24.8	°C/W
A2F200M3F-FG484	21.8	18.2	16.7	7.7	16.8	°C/W
A2F200M3F-CS288	26.6	20.2	18.1	7.3	9.4	°C/W
A2F200M3F-PQG208I	38.5	34.6	33.1	0.7	31.6	°C/W

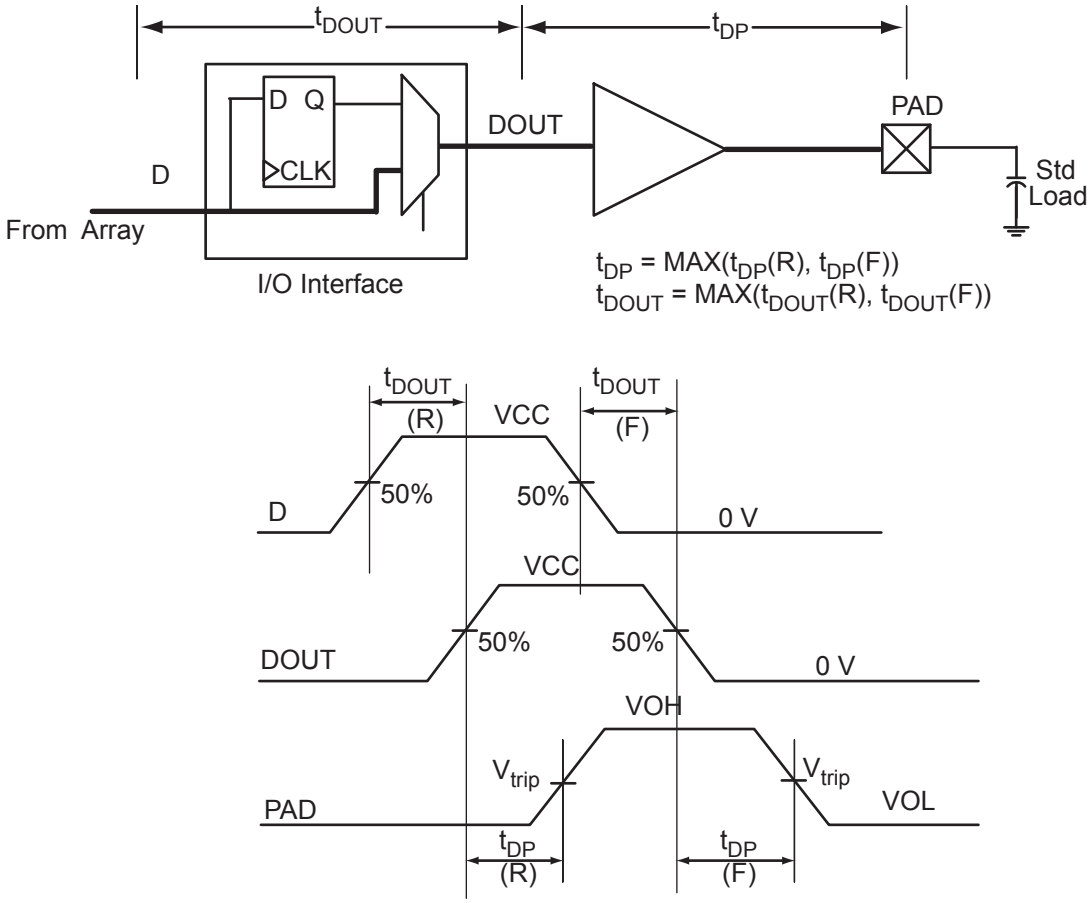


Figure 2-4 • **Output Buffer Model and Delays (example)**

Overview of I/O Performance

Summary of I/O DC Input and Output Levels – Default I/O Software Settings

Table 2-19 • Summary of Maximum and Minimum DC Input and Output Levels Applicable to Commercial Conditions—Software Default Settings Applicable to FPGA I/O Banks

I/O Standard	Drive Strgth.	Slew Rate	VIL		VIH		VOL	VOH	I_{OL}[1]	I_{OH}[1]
			Min. V	Max. V	Min. V	Max. V	Max. V	Min. V	mA	mA
3.3 V LVTTL / 3.3 V LVCMOS	12 mA	High	–0.3	0.8	2	3.6	0.4	2.4	12	12
2.5 V LVCMOS	12 mA	High	–0.3	0.7	1.7	3.6	0.7	1.7	12	12
1.8 V LVCMOS	12 mA	High	–0.3	0.35 * VCCxxxxIOBx	0.65* VCCxxxxIOBx	3.6	0.45	VCCxxxxIOBx – 0.45	12	12
1.5 V LVCMOS	12 mA	High	–0.3	0.35 * VCCxxxxIOBx	0.65* VCCxxxxIOBx	3.6	0.25 * VCCxxxxIOBx	0.75* VCCxxxxIOBx	12	12
3.3 V PCI	Per PCI specifications									
3.3 V PCI-X	Per PCI-X specifications									

Notes:

1. *Currents are measured at 85°C junction temperature.*
2. *Output slew rate can be extracted by the IBIS Models.*

Table 2-20 • Summary of Maximum and Minimum DC Input and Output Levels Applicable to Commercial Conditions—Software Default Settings Applicable to MSS I/O Banks

I/O Standard	Drive Strgth.	Slew Rate	VIL		VIH		VOL	VOH	I_{OL}[1]	I_{OH}[1]
			Min. V	Max. V	Min. V	Max. V	Max. V	Min. V	mA	mA
3.3 V LVTTL / 3.3 V LVCMOS	8 mA	High	–0.3	0.8	2	3.6	0.4	2.4	8	8
2.5 V LVCMOS	8 mA	High	–0.3	0.7	1.7	3.6	0.7	1.7	8	8
1.8 V LVCMOS	4 mA	High	–0.3	0.35* VCCxxxxIOBx	0.65* VCCxxxxIOBx	3.6	0.45	VCCxxxxIOBx – 0.45	4	4
1.5 V LVCMOS	2 mA	High	–0.3	0.35* VCCxxxxIOBx	0.65* VCCxxxxIOBx	3.6	0.25* VCCxxxxIOBx	0.75* VCCxxxxIOBx	2	2

Notes:

1. *Currents are measured at 85°C junction temperature.*
2. *Output slew rate can be extracted by the IBIS Models.*

Differential I/O Characteristics

Physical Implementation

Configuration of the I/O modules as a differential pair is handled by SoC Products Group Designer software when the user instantiates a differential I/O macro in the design.

Differential I/Os can also be used in conjunction with the embedded Input Register (InReg), Output Register (OutReg), Enable Register (EnReg), and Double Data Rate (DDR). However, there is no support for bidirectional I/Os or tristates with the LVPECL standards.

LVDS

Low-Voltage Differential Signaling (ANSI/TIA/EIA-644) is a high-speed, differential I/O standard. It requires that one data bit be carried through two signal lines, so two pins are needed. It also requires external resistor termination.

The full implementation of the LVDS transmitter and receiver is shown in an example in Figure 2-11. The building blocks of the LVDS transmitter-receiver are one transmitter macro, one receiver macro, three board resistors at the transmitter end, and one resistor at the receiver end. The values for the three driver resistors are different from those used in the LVPECL implementation because the output standard specifications are different.

Along with LVDS I/O, SmartFusion cSoCs also support bus LVDS structure and multipoint LVDS (M-LVDS) configuration (up to 40 nodes).

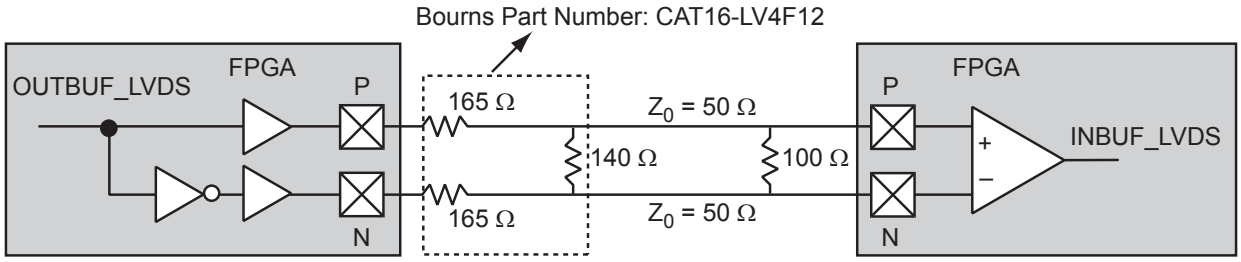


Figure 2-11 • **LVDS Circuit Diagram and Board-Level Implementation**

Timing Characteristics

Table 2-78 • Combinatorial Cell Propagation Delays
Worst Commercial-Case Conditions: T_J = 85°C, Worst-Case VCC = 1.425 V

Combinatorial Cell	Equation	Parameter	–1	Std.	Units
INV	Y = !A	t_{PD}	0.41	0.49	ns
AND2	Y = A · B	t_{PD}	0.48	0.57	ns
NAND2	Y = !(A · B)	t_{PD}	0.48	0.57	ns
OR2	Y = A + B	t_{PD}	0.49	0.59	ns
NOR2	Y = !(A + B)	t_{PD}	0.49	0.59	ns
XOR2	Y = A ⊕ B	t_{PD}	0.75	0.90	ns
MAJ3	Y = MAJ(A, B, C)	t_{PD}	0.71	0.85	ns
XOR3	Y = A ⊕ B ⊕ C	t_{PD}	0.89	1.07	ns
MUX2	Y = A !S + B S	t_{PD}	0.51	0.62	ns
AND3	Y = A · B · C	t_{PD}	0.57	0.68	ns

Note: For specific junction temperature and voltage supply levels, refer to Table 2-7 on page 2-9 for derating values.

VersaTile Specifications as a Sequential Module

The SmartFusion library offers a wide variety of sequential cells, including flip-flops and latches. Each has a data input and optional enable, clear, or preset. In this section, timing characteristics are presented for a representative sample from the library. For more details, refer to the *IGLOO/e, Fusion, ProASIC3/E, and SmartFusion Macro Library Guide*.

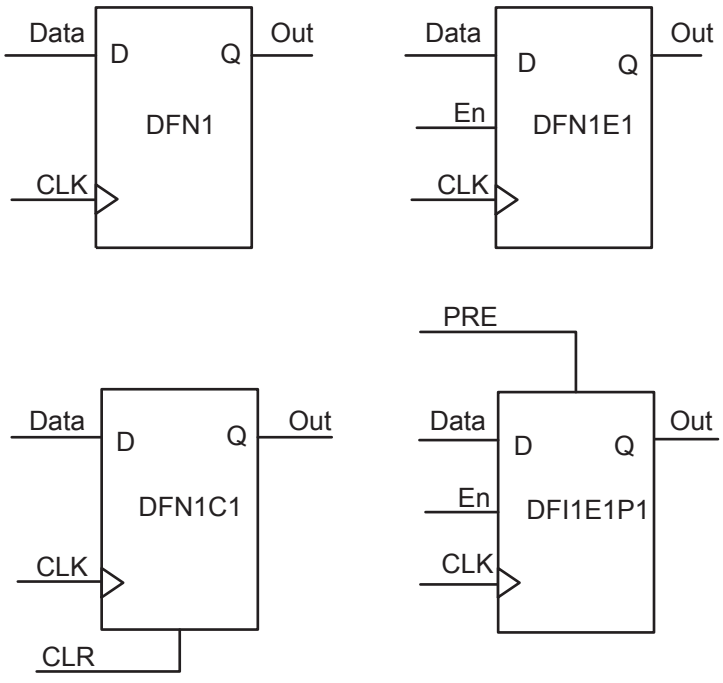


Figure 2-25 • Sample of Sequential Cells

Programmable Analog Specifications

Current Monitor

Unless otherwise noted, current monitor performance is specified at 25°C with nominal power supply voltages, with the output measured using the internal voltage reference with the internal ADC in 12-bit mode and 91 Ksps, after digital compensation. All results are based on averaging over 16 samples.

***Table 2-93* • Current Monitor Performance Specification**

Specification	Test Conditions	Min.	Typical	Max.	Units
Input voltage range (for driving ADC over full range)		0 – 48	0 – 50	1 – 51	mV
Analog gain	From the differential voltage across the input pads to the ADC input		50		V/V
Input referred offset voltage	Input referred offset voltage	0	0.1	0.5	mV
	–40ºC to +100ºC	0	0.1	0.5	mV
Gain error	Slope of BFSL vs. 50 V/V		±0.1	±0.5	% nom.
	–40ºC to +100ºC			±0.5	% nom.
Overall Accuracy	Peak error from ideal transfer function, 25°C		±(0.1 + 0.25%)	±(0.4 + 1.5%)	mV plus % reading
Input referred noise	0 VDC input (no output averaging)	0.3	0.4	0.5	mVrms
Common-mode rejection ratio	0 V to 12 VDC common-mode voltage	–86	–87		dB
Analog settling time	To 0.1% of final value (with ADC load)				
	From CM_STB (High)	5			µs
	From ADC_START (High)	5		200	µs
Input capacitance			8		pF
Input biased current	CM[n] or TM[n] pad, –40°C to +100°C over maximum input voltage range (plus is into pad)				
	Strobe = 0; IBIAS on CM[n]		0		µA
	Strobe = 1; IBIAS on CM[n]		1		µA
	Strobe = 0; IBIAS on TM[n]		2		µA
	Strobe = 1; IBIAS on TM[n]		1		µA
Power supply rejection ratio	DC (0 – 10 KHz)	41	42		dB
Incremental operational current monitor power supply current requirements (per current monitor instance, not including ADC or VAREFx)	VCC33A		150		µA
	VCC33AP		140		µA
	VCC15A		50		µA

Note: Under no condition should the TM pad ever be greater than 10 mV above the CM pad. This restriction is applicable only if current monitor is used.

4 – SmartFusion Programming

SmartFusion cSoCs have three separate flash areas that can be programmed:

1. The FPGA fabric
2. The embedded nonvolatile memories (eNVMs)
3. The embedded flash ROM (eFROM)

There are essentially three methodologies for programming these areas:

1. In-system programming (ISP)
2. In-application programming (IAP)
   a. A2F060 and A2F500: The FPGA fabric, eNVM, and eFROM
   b. A2F200: Only the FPGA fabric and the eNVM
3. Pre-programming (non-ISP)

Programming, whether ISP or IAP methodologies are employed, can be done in two ways:

1. Securely using the on chip AES decryption logic
2. In plain text

In-System Programming

In-System Programming is performed with the aid of external JTAG programming hardware. Table 4-1 describes the JTAG programming hardware that will program a SmartFusion cSoC and Table 4-2 defines the JTAG pins that provide the interface for the programming hardware.

***Table 4-1* • Supported JTAG Programming Hardware**

Dongle	Source	JTAG	SWD[1]	SWV[2]	Program FPGA	Program eFROM	Program eNVM
FlashPro3/4	SoC Products Group	Yes	No	No	Yes	Yes	Yes
ULINK Pro	Keil	Yes	Yes	Yes	Yes[3]	Yes[3]	Yes
ULINK2	Keil	Yes	Yes	Yes	Yes[3]	Yes[3]	Yes
IAR J-Link	IAR	Yes	Yes	Yes	Yes[3]	Yes[3]	Yes

Notes:

1. *SWD = ARM Serial Wire Debug*
2. *SWV = ARM Serial Wire Viewer*
3. *Planned support*

***Table 4-2* • JTAG Pin Descriptions**

Pin Name	Description
JTAGSEL	ARM Cortex-M3 or FPGA test access port (TAP) controller selection
TRSTB	Test reset bar
TCK	Test clock
TMS	Test mode select
TDI	Test data input
TDO	Test data output

The JTAGSEL pin selects the FPGA TAP controller or the Cortex-M3 debug logic. When JTAGSEL is asserted, the FPGA TAP controller is selected and the TRSTB input into the Cortex-M3 is held in a reset state (logic 0), as depicted in Figure 4-1. Users should tie the JTAGSEL pin high externally.

Microsemi's free Eclipse-based IDE, SoftConsole, has the ability to control the JTAGSEL pin directly with the FlashPro4 programmer. Manual jumpers are provided on the evaluation and development kits to allow manual selection of this function for the J-Link and ULINK debuggers.

Note: Standard ARM JTAG connectors do not have access to the JTAGSEL pin. SoftConsole automatically selects the appropriate TAP controller using the CTXSELECT JTAG command. When using SoftConsole, the state of JTAGSEL is a "don't care."

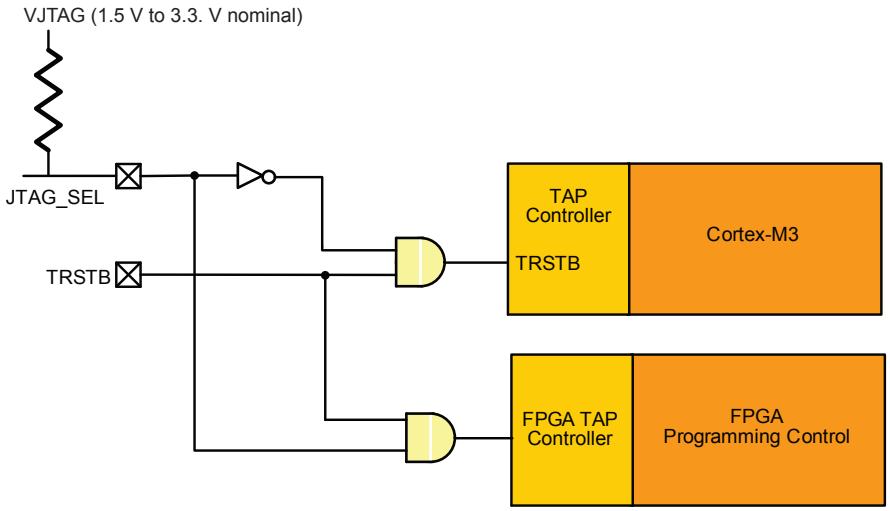


Figure 4-1 • **TRSTB Logic**

In-Application Programming

In-application programming refers to the ability to reprogram the various flash areas under direct supervision of the Cortex-M3.

Reprogramming the FPGA Fabric Using the Cortex-M3

In this mode, the Cortex-M3 is executing the programming algorithm on-chip. The IAP driver can be incorporated into the design project and executed from eNVM or eSRAM. The SoC Products Group provides working example projects for SoftConsole, IAR, and Keil development environments. These can be downloaded via the SoC Products Group Firmware Catalog. The new bitstream to be programmed into the FPGA can reside on the user's printed circuit board (PCB) in a separate SPI flash memory. Alternately, the user can modify the existing projects supplied by the SoC Products Group and, via custom handshaking software, throttle the download of the new image and program the FPGA a piece at a time in real time. A cost-effective and reliable approach would be to store the bitstream in an external SPI flash. Another option is storing a redundant bitstream image in an external SPI flash and loading the newest version into the FPGA only when receiving an IAP command. Since the FPGA I/Os are tristated or held at predefined or last known state during FPGA programming, the user must use MSS I/Os to interface to external memories. Since there are two SPI controllers in the MSS, the user can dedicate one to an SPI flash and the other to the particulars of an application. The amount of flash memory required to program the FPGA always exceeds the size of the eNVM block that is on-chip. The external memory controller (EMC) cannot be used as an interface to a memory device for storage of a bitstream because its I/O pads are FPGA I/Os; hence they are tristated when the FPGA is in a programming state.

The MSS resets itself after IAP of the FPGA fabric. This reset is internally asserted on MSS_RESETN by the power supply monitor (PSM) and reset controller of the MSS.

Special Function Pins

Name	Type	Polarity/Bus Size	Description
NC			No connect This pin is not connected to circuitry within the device. These pins can be driven to any voltage or can be left floating with no effect on the operation of the device.
DC			Do not connect. This pin should not be connected to any signals on the PCB. These pins should be left unconnected.
LPXIN	In	1	Low power 32 KHz crystal oscillator. Input from the 32 KHz oscillator. Pin for connecting a low power 32 KHz watch crystal. If not used, the LPXIN pin can be left floating. For more information, see the PLLs, Clock Conditioning Circuitry, and On-Chip Crystal Oscillators section in the *SmartFusion Microcontroller Subsystem User's Guide*.
LPXOUT	In	1	Low power 32 KHz crystal oscillator. Output to the 32 KHz oscillator. Pin for connecting a low power 32 KHz watch crystal. If not used, the LPXOUT pin can be left floating. For more information, see the PLLs, Clock Conditioning Circuitry, and On-Chip Crystal Oscillators section in the *SmartFusion Microcontroller Subsystem User's Guide*.
MAINXIN	In	1	Main crystal oscillator circuit. Input to the crystal oscillator circuit. Pin for connecting an external crystal, ceramic resonator, or RC network. When using an external crystal or ceramic oscillator, external capacitors are also recommended. Refer to documentation from the crystal oscillator manufacturer for proper capacitor value. If an external RC network or clock input is used, the RC components are connected to the MAINXIN pin, with MAINXOUT left floating. When the main crystal oscillator is not being used, MAINXIN and MAINXOUT pins can be left floating. For more information, see the PLLs, Clock Conditioning Circuitry, and On-Chip Crystal Oscillators section in the *SmartFusion Microcontroller Subsystem User's Guide*.
MAINXOUT	Out	1	Main crystal oscillator circuit. Output from the crystal oscillator circuit. Pin for connecting external crystal or ceramic resonator. When using an external crystal or ceramic oscillator, external capacitors are also recommended. Refer to documentation from the crystal oscillator manufacturer for proper capacitor value. If an external RC network or clock input is used, the RC components are connected to the MAINXIN pin, with MAINXOUT left floating. When the main crystal oscillator is not being used, MAINXIN and MAINXOUT pins can be left floating. For more information, see the PLLs, Clock Conditioning Circuitry, and On-Chip Crystal Oscillators section in the *SmartFusion Microcontroller Subsystem User's Guide*.

Name	Type	Polarity/Bus Size	Description
NCAP		1	Negative capacitor connection. This is the negative terminal of the charge pump. A capacitor, with a 2.2 µF recommended value, is required to connect between PCAP and NCAP. Analog charge pump capacitors are not needed if none of the analog SCB features are used and none of the SDDs are used. In that case it should be left unconnected.
PCAP		1	Positive Capacitor connection. This is the positive terminal of the charge pump. A capacitor, with a 2.2 µF recommended value, is required to connect between PCAP and NCAP. If this pin is not used, it must be left unconnected/floating. In this case, no capacitor is needed. Analog charge pump capacitors are not needed if none of the analog SCB features are used, and none of the SDDs are used.
PTBASE		1	Pass transistor base connection This is the control signal of the voltage regulator. This pin should be connected to the base of an external pass transistor used with the 1.5 V internal voltage regulator and can be floating if not used.
PTEM		1	Pass transistor emitter connection. This is the feedback input of the voltage regulator. This pin should be connected to the emitter of an external pass transistor used with the 1.5 V internal voltage regulator and can be floating if not used.
MSS_RESET_N		Low	Low Reset signal which can be used as an external reset and can also be used as a system level reset under control of the Cortex-M3 processor. MSS_RESET_N is an output asserted low after power-on reset. The direction of MSS_RESET_N changes during the execution of the Microsemi System Boot when chip-level reset is enabled. The Microsemi System Boot reconfigures MSS_RESET_N to become a reset input signal when chip-level reset is enabled. It has an internal pull-up so it can be left floating. In the current software, the MSS_RESET_N is modeled as an external input signal only.
PU_N	In	Low	Push-button is the connection for the external momentary switch used to turn on the 1.5 V voltage regulator and can be floating if not used.

Name	Type	Polarity/ Bus Size	Description
SPI_1_DO	Out	1	Data output. Second SPI. Can also be used as an MSS GPIO (see "GPIO_x" on page 5-6).
SPI_1_SS	Out	1	Slave select (chip select). Second SPI. Can also be used as an MSS GPIO (see "GPIO_x" on page 5-6).
Universal Asynchronous Receiver/Transmitter (UART) Peripherals			
UART_0_RXD	In	1	Receive data. First UART. Can also be used as an MSS GPIO (see "GPIO_x" on page 5-6).
UART_0_TXD	Out	1	Transmit data. First UART. Can also be used as an MSS GPIO (see "GPIO_x" on page 5-6).
UART_1_RXD	In	1	Receive data. Second UART. Can also be used as an MSS GPIO (see "GPIO_x" on page 5-6).
UART_1_TXD	Out	1	Transmit data. Second UART. Can also be used as an MSS GPIO (see "GPIO_x" on page 5-6).
Ethernet MAC			
MAC_CLK	In	Rise	Receive clock. 50 MHz ± 50 ppm clock source received from RMII PHY. Can be left floating when unused.
MAC_CRSDV	In	High	Carrier sense/receive data valid for RMII PHY Can also be used as an FPGA User IO (see "IO" on page 5-6).
MAC_MDC	Out	Rise	RMII management clock Can also be used as an FPGA User IO (see "IO" on page 5-6).
MAC_MDIO	In/Out	1	RMII management data input/output Can also be used as an FPGA User IO (see "IO" on page 5-6).
MAC_RXDx	In	2	Ethernet MAC receive data. Data recovered and decoded by PHY. The RXD[0] signal is the least significant bit. Can also be used as an FPGA User I/O (see "IO" on page 5-6).
MAC_RXER	In	HIGH	Ethernet MAC receive error. If MACRX_ER is asserted during reception, the frame is received and status of the frame is updated with MACRX_ER. Can also be used as an FPGA user I/O (see "IO" on page 5-6).
MAC_TXDx	Out	2	Ethernet MAC transmit data. The TXD[0] signal is the least significant bit. Can also be used as an FPGA user I/O (see "IO" on page 5-6).
MAC_TXEN	Out	HIGH	Ethernet MAC transmit enable. When asserted, indicates valid data for the PHY on the TXD port. Can also be used as an FPGA User I/O (see "IO" on page 5-6).

Name	Type	Description	Associated With	
			ADC/SDD	SCB
TM0	In	SCB 0 / low side of current monitor / comparator Negative input / high side of temperature monitor. See the Temperature Monitor section.	ADC0	SCB0
TM1	In	SCB 1 / low side of current monitor / comparator. Negative input / high side of temperature monitor.	ADC0	SCB1
TM2	In	SCB 2 / low side of current monitor / comparator. Negative input / high side of temperature monitor.	ADC1	SCB2
TM3	In	SCB 3 low side of current monitor / comparator. Negative input / high side of temperature monitor.	ADC1	SCB3
TM4	In	SCB 4 low side of current monitor / comparator. Negative input / high side of temperature monitor.	ADC2	SCB4
SDD0	Out	Output of SDD0 See the Sigma-Delta Digital-to-Analog Converter (DAC) section in the *SmartFusion Programmable Analog User's Guide*.	SDD0	N/A
SDD1	Out	Output of SDD1	SDD1	N/A
SDD2	Out	Output of SDD2	SDD2	N/A

Note: Unused analog inputs should be grounded. This aids in shielding and prevents an undesired coupling path.

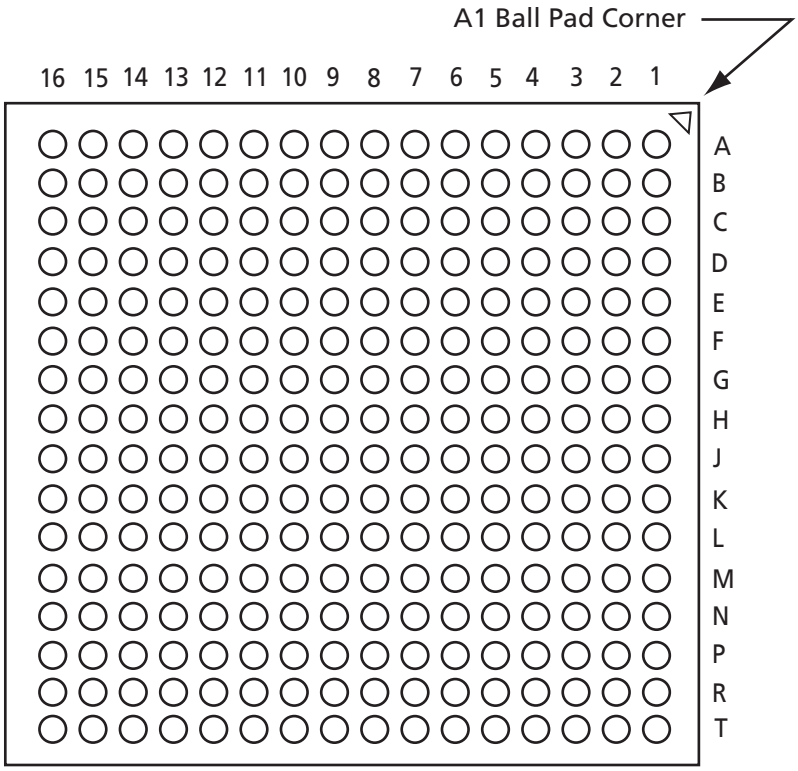
TQ144	
Pin Number	**A2F060 Function**
1	VCCPLL0
2	VCOMPLA0
3	GNDQ
4	GFA2/IO42PDB5V0
5	GFB2/IO42NDB5V0
6	GFC2/IO41PDB5V0
7	IO41NDB5V0
8	VCC
9	GND
10	VCCFPGAIOB5
11	IO38PDB5V0
12	IO38NDB5V0
13	IO36PDB5V0
14	IO36NDB5V0
15	GND
16	GNDRCOSC
17	VCCRCOSC
18	MSS_RESET_N
19	GPIO_0/IO33RSB4V0
20	GPIO_1/IO32RSB4V0
21	GPIO_2/IO31RSB4V0
22	GPIO_3/IO30RSB4V0
23	GPIO_4/IO29RSB4V0
24	GND
25	VCCMSSIOB4
26	VCC
27	GPIO_5/IO28RSB4V0
28	GPIO_6/IO27RSB4V0
29	GPIO_7/IO26RSB4V0
30	GPIO_8/IO25RSB4V0
31	VCCESRAM
32	GNDSDD0
33	VCC33SDD0
34	VCC15A
35	PCAP
36	NCAP

Pin No.	CS288		
	A2F060 Function	A2F200 Function	A2F500 Function
P19	VCCMSSIOB2	VCCMSSIOB2	VCCMSSIOB2
P21	GND	GND	GND
R1	GPIO_2/IO31RSB4V0	MAC_MDIO/IO49RSB4V0	MAC_MDIO/IO58RSB4V0
R3	GPIO_1/IO32RSB4V0	MAC_TXEN/IO52RSB4V0	MAC_TXEN/IO61RSB4V0
R5	GPIO_3/IO30RSB4V0	MAC_TXD[0]/IO56RSB4V0	MAC_TXD[0]/IO65RSB4V0
R6	GPIO_10/IO35RSB4V0	MAC_CRSDV/IO51RSB4V0	MAC_CRSDV/IO60RSB4V0
R9	GNDA	GNDA	GNDA
R13	GNDA	GNDA	GNDA
R16	UART_1_RXD/GPIO_29	UART_1_RXD/GPIO_29	UART_1_RXD/GPIO_29
R17	UART_1_TXD/GPIO_28	UART_1_TXD/GPIO_28	UART_1_TXD/GPIO_28
R19	I2C_0_SDA/GPIO_22	I2C_0_SDA/GPIO_22	I2C_0_SDA/GPIO_22
R21	I2C_1_SDA/GPIO_30	I2C_1_SDA/GPIO_30	I2C_1_SDA/GPIO_30
T1	GND	GND	GND
T3	NC	MAC_TXD[1]/IO55RSB4V0	MAC_TXD[1]/IO64RSB4V0
T5	NC	MAC_RXD[1]/IO53RSB4V0	MAC_RXD[1]/IO62RSB4V0
T6	GPIO_11/IO34RSB4V0	MAC_RXER/IO50RSB4V0	MAC_RXER/IO59RSB4V0
T7	NC	CM1	CM1
T8	NC	ADC1	ADC1
T9	NC	GND33ADC0	GND33ADC0
T10	NC	VCC15ADC0	VCC15ADC0
T11	GND33ADC0	GND33ADC1	GND33ADC1
T12	VAREF0	VAREF1	VAREF1
T13	ADC7	ADC4	ADC4
T14	TM0	TM3	TM3
T15	SPI_1_SS/GPIO_27	SPI_1_SS/GPIO_27	SPI_1_SS/GPIO_27
T16	VCCMSSIOB2	VCCMSSIOB2	VCCMSSIOB2
T17	UART_0_RXD/GPIO_21	UART_0_RXD/GPIO_21	UART_0_RXD/GPIO_21
T19	UART_0_TXD/GPIO_20	UART_0_TXD/GPIO_20	UART_0_TXD/GPIO_20
T21	I2C_1_SCL/GPIO_31	I2C_1_SCL/GPIO_31	I2C_1_SCL/GPIO_31
U1	NC	MAC_RXD[0]/IO54RSB4V0	MAC_RXD[0]/IO63RSB4V0
U3	VCCMSSIOB4	VCCMSSIOB4	VCCMSSIOB4

Notes:

1. *Shading denotes pins that do not have completely identical functions from density to density. For example, the bank assignment can be different for an I/O, or the function might be available only on a larger density device.*
2. **: Indicates that the signal assigned to the pins as a CLKBUF/CLKBUF_LVPECL/CLKBUF_LVDS goes through a glitchless mux. In order for the glitchless mux to operate correctly, the signal must be a free-running clock signal. Refer to the 'Glitchless MUX' section in the SmartFusion Microcontroller Subsystem User's Guide for more details.*

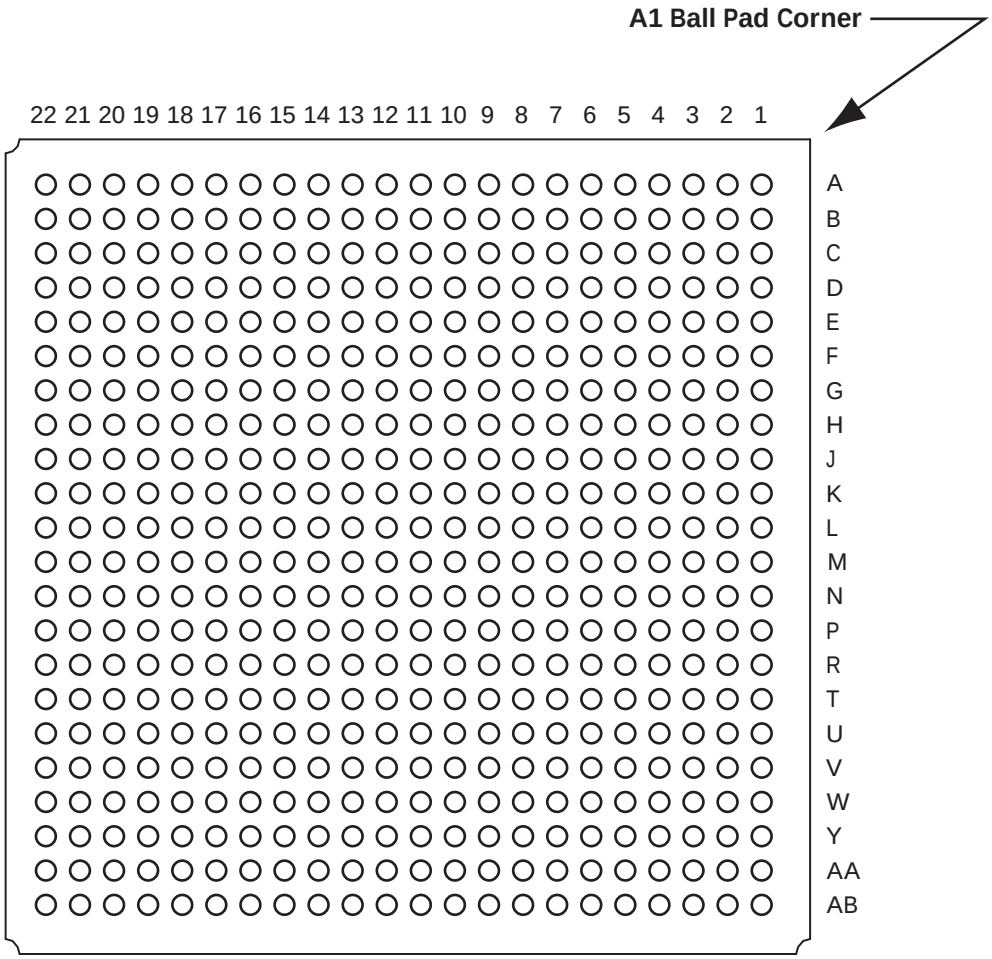
FG256



Note

For Package Manufacturing and Environmental information, visit the Resource Center at http://www.microsemi.com/soc/products/solutions/package/docs.aspx.

FG484



Note

For Package Manufacturing and Environmental information, visit the Resource Center at http://www.microsemi.com/soc/products/solutions/package/docs.aspx.

Pin Number	FG484	
	A2F200 Function	A2F500 Function
B3	NC	NC
B4	NC	NC
B5	VCCFPGAIOB0	VCCFPGAIOB0
B6	EMC_RW_N/GAA1/IO00PDB0V0	EMC_RW_N/GAA1/IO02PDB0V0
B7	NC	IO04PPB0V0
B8	VCCFPGAIOB0	VCCFPGAIOB0
B9	EMC_BYTEN[0]/GAC0/IO02NDB0V0	EMC_BYTEN[0]/GAC0/IO07NDB0V0
B10	EMC_AB[2]/IO05NDB0V0	EMC_AB[2]/IO09NDB0V0
B11	EMC_AB[3]/IO05PDB0V0	EMC_AB[3]/IO09PDB0V0
B12	EMC_AB[6]/IO07NDB0V0	EMC_AB[6]/IO12NDB0V0
B13	EMC_AB[14]/IO11NDB0V0	EMC_AB[14]/IO15NDB0V0
B14	EMC_AB[15]/IO11PDB0V0	EMC_AB[15]/IO15PDB0V0
B15	VCCFPGAIOB0	VCCFPGAIOB0
B16	EMC_AB[18]/IO13NDB0V0	EMC_AB[18]/IO18NDB0V0
B17	EMC_AB[19]/IO13PDB0V0	EMC_AB[19]/IO18PDB0V0
B18	VCCFPGAIOB0	VCCFPGAIOB0
B19	GBB0/IO18NDB0V0	GBB0/IO24NDB0V0
B20	GBB1/IO18PDB0V0	GBB1/IO24PDB0V0
B21	GND	GND
B22	GBA2/IO20PDB1V0	GBA2/IO27PDB1V0
C1	EMC_DB[14]/GAB2/IO71NDB5V0	EMC_DB[14]/GAB2/IO88NDB5V0
C2	NC	NC
C3	NC	NC
C4	NC	IO01NDB0V0
C5	NC	IO01PDB0V0
C6	EMC_CLK/GAA0/IO00NDB0V0	EMC_CLK/GAA0/IO02NDB0V0
C7	NC	IO03PPB0V0
C8	NC	IO04NPB0V0
C9	EMC_BYTEN[1]/GAC1/IO02PDB0V0	EMC_BYTEN[1]/GAC1/IO07PDB0V0
C10	EMC_OEN1_N/IO03PDB0V0	EMC_OEN1_N/IO08PDB0V0
C11	GND	GND
C12	VCCFPGAIOB0	VCCFPGAIOB0
C13	EMC_AB[8]/IO08NDB0V0	EMC_AB[8]/IO13NDB0V0
C14	EMC_AB[16]/IO12NDB0V0	EMC_AB[16]/IO17NDB0V0

Notes:

1. *Shading denotes pins that do not have completely identical functions from density to density. For example, the bank assignment can be different for an I/O, or the function might be available only on a larger density device.*
2. **: Indicates that the signal assigned to the pins as a CLKBUF/CLKBUF_LVPECL/CLKBUF_LVDS goes through a glitchless mux. In order for the glitchless mux to operate correctly, the signal must be a free-running clock signal. Refer to the 'Glitchless MUX' section in the SmartFusion Microcontroller Subsystem User's Guide for more details.*

Revision	Changes	Page
Revision 8 (continued)	The description of "In-application programming (IAP)" methodology was changed to state the difference for A2F060 and A2F500 compared to A2F200 (SAR 37808).	4-7
	The "Global I/O Naming Conventions" section is new (SARs 28996, 31147). The description for IO "User Pins" was revised accordingly and moved out of the table and into a new section: "User I/O Naming Conventions".	5-6, 5-6
	The descriptions for "MAINXIN" and "MAINXOUT" were revised to state how they should be handled if using an external RC network or clock input (SAR 32594).	5-8
	The description and type was revised for the "MSS_RESET_N" pin (SAR 34133).	5-9
	The "TQ144" section and pin table for A2F060 are new (SAR 36246).	5-18
Revision 7 (August 2011)	The title of the datasheet was changed from SmartFusion Intelligent Mixed Signal FPGAs to SmartFusion Customizable System-on-Chip (cSoC). Terminology throughout was changed accordingly. The term cSoC defines a category of devices that include at least FPGA fabric and a processor subsystem of some sort. It can also include any of the following: analog, SerDes, ASIC blocks, customer specific IP, or application-specific IP. SmartFusion is Microsemi's first cSoC (SAR 33071).	N/A
	The "SmartFusion cSoC Family Product Table" was revised to remove the note stating that the A2F060 device is under definition and subject to change (SAR 33070). A note was added for EMC, stating that it is not available on A2F500 for the PQ208 package (SAR 33041).	II
	The "SmartFusion cSoC Device Status" table was revised. The status for A2F060 CS288 and FG256 moved from Advance to Preliminary. A2F200 PQ208 and A2F500 PQ208 moved from Advance to Production (SAR 33069).	III
	The "Package I/Os: MSS + FPGA I/Os" table was revised. The number of direct analog inputs for A2F060 packages increased from 6 to 11. The number of MSS I/Os for the A2F060 FG256 package increased from 25 to 26 (SAR 33070). A note was added stating that EMC is not available for the A2F500 PQ208 package (SAR 33041).	III
	The note associated with the "SmartFusion cSoC System Architecture" diagram was corrected from "Architecture for A2F500" to "Architecture for A2F200" (SAR 32578).	V
	The Licensed DPA Logo was added to the "Product Ordering Codes" section. The trademarked Licensed DPA Logo identifies that a product is covered by a DPA counter-measures license from Cryptography Research (SAR 32151).	VI
	The "Security" section and "Secure Programming" section were updated to clarify that although no existing security measures can give an absolute guarantee, SmartFusion cSoCs implement the best security available in the industry (SAR 32865).	1-2, 4-9
	Storage temperature, T_{STG}, and junction temperature, T_J, were added to Table 2-1 • Absolute Maximum Ratings (SAR 30863).	2-1
	AC/DC characteristics for A2F060 were added to the "SmartFusion DC and Switching Characteristics" chapter (SAR 33132). The following tables were updated: Table 2-14 • Different Components Contributing to Dynamic Power Consumption in SmartFusion cSoCs Table 2-15 • Different Components Contributing to the Static Power Consumption in SmartFusion cSoCs Table 2-90 • eNVM Block Timing, Worst Commercial Case Conditions: T_J = 85°C, VCC = 1.425 V Table 2-98 • Analog Sigma-Delta DAC Table 2-100 • SPI Characteristics	 2-12 2-13 2-76 2-85 2-89

Microsemi Corporate Headquarters
One Enterprise, Aliso Viejo,
CA 92656 USA

Within the USA: +1 (800) 713-4113
Outside the USA: +1 (949) 380-6100
Sales: +1 (949) 380-6136
Fax: +1 (949) 215-4996

E-mail: sales.support@microsemi.com

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