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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded - Microcontrollers</u>"

Details	
Product Status	Discontinued at Digi-Key
Core Processor	CIP-51 8051
Core Size	8-Bit
Speed	50MHz
Connectivity	I ² C, SMBus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	20
Program Memory Size	32KB (32K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	2.25K x 8
Voltage - Supply (Vcc/Vdd)	2.2V ~ 3.6V
Data Converters	A/D 12x10/12b SAR; D/A 2x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	24-VFQFN Exposed Pad
Supplier Device Package	24-QFN (3x3)
Purchase URL	https://www.e-xfl.com/product-detail/silicon-labs/efm8bb31f32g-b-qfn24r

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1. Feature List

The EFM8BB3 device family are fully integrated, mixed-signal system-on-a-chip MCUs. Highlighted features are listed below.

- · Core:
 - · Pipelined CIP-51 Core
 - · Fully compatible with standard 8051 instruction set
 - · 70% of instructions execute in 1-2 clock cycles
 - · 50 MHz maximum operating frequency
- · Memory:
 - Up to 64 kB flash memory (63 kB user-accessible), in-system re-programmable from firmware in 512-byte sectors
 - Up to 4352 bytes RAM (including 256 bytes standard 8051 RAM and 4096 bytes on-chip XRAM)
- · Power:
 - · Internal LDO regulator for CPU core voltage
 - · Power-on reset circuit and brownout detectors
- I/O: Up to 29 total multifunction I/O pins:
 - · Up to 25 pins 5 V tolerant under bias
 - · Selectable state retention through reset events
 - · Flexible peripheral crossbar for peripheral routing
 - 5 mA source, 12.5 mA sink allows direct drive of LEDs
- · Clock Sources:
 - Internal 49 MHz oscillator with accuracy of ±2%
 - Internal 24.5 MHz oscillator with ±2% accuracy
 - Internal 80 kHz low-frequency oscillator
 - · External CMOS clock option
 - · External crystal/RC Oscillator (up to 25 MHz)

- · Analog:
 - 12/10-Bit Analog-to-Digital Converter (ADC)
 - · Internal temperature sensor
 - 4 x 12-Bit Digital-to-Analog Converters (DAC)
 - 2 x Low-current analog comparators with adjustable reference
- · Communications and Digital Peripherals:
 - 2 x UART, up to 3 Mbaud
 - SPI™ Master / Slave, up to 12 Mbps
 - SMBus™/I2C™ Master / Slave, up to 400 kbps
 - I²C High-Speed Slave, up to 3.4 Mbps
 - 16-bit CRC unit, supporting automatic CRC of flash at 256byte boundaries
 - · 4 Configurable Logic Units
- · Timers/Counters and PWM:
 - 6-channel programmable counter array (PCA) supporting PWM, capture/compare, and frequency output modes
 - 6 x 16-bit general-purpose timers
 - Independent watchdog timer, clocked from the low frequency oscillator
- · On-Chip, Non-Intrusive Debugging
 - · Full memory and register inspection
 - · Four hardware breakpoints, single-stepping
- · Pre-programmed UART bootloader
- Temperature range -40 to 85 °C or -40 to 125 °C

With on-chip power-on reset, voltage supply monitor, watchdog timer, and clock oscillator, the EFM8BB3 devices are truly standalone system-on-a-chip solutions. The flash memory is reprogrammable in-circuit, providing nonvolatile data storage and allowing field upgrades of the firmware. The on-chip debugging interface (C2) allows non-intrusive (uses no on-chip resources), full speed, in-circuit debugging using the production MCU installed in the final application. This debug logic supports inspection and modification of memory and registers, setting breakpoints, single stepping, and run and halt commands. All analog and digital peripherals are fully functional while debugging. Device operation is specified from 2.2 V up to a 3.6 V supply. Devices are AEC-Q100 qualified and available in 4x4 mm 32-pin QFN, 3x3 mm 24-pin QFN, 32-pin QFP, or 24-pin QSOP packages. All package options are lead-free and RoHS compliant.

3.2 Power

All internal circuitry draws power from the VDD supply pin. External I/O pins are powered from the VIO supply voltage (or VDD on devices without a separate VIO connection), while most of the internal circuitry is supplied by an on-chip LDO regulator. Control over the device power can be achieved by enabling/disabling individual peripherals as needed. Each analog peripheral can be disabled when not in use and placed in low power mode. Digital peripherals, such as timers and serial buses, have their clocks gated off and draw little power when they are not in use.

Table 3.1. Power Modes

Power Mode	Details	Mode Entry	Wake-Up Sources
Normal	Core and all peripherals clocked and fully operational		
Idle	Core halted All peripherals clocked and fully operational Code resumes execution on wake event	Set IDLE bit in PCON0	Any interrupt
Suspend	Core and peripheral clocks halted HFOSC0 and HFOSC1 oscillators stopped Regulator in normal bias mode for fast wake Timer 3 and 4 may clock from LFOSC0 Code resumes execution on wake event	1. Switch SYSCLK to HFOSC0 2. Set SUSPEND bit in PCON1	Timer 4 Event SPI0 Activity I2C0 Slave Activity Port Match Event Comparator 0 Falling Edge CLUn Interrupt-Enabled Event
Stop	 All internal power nets shut down Pins retain state Exit on any reset source	1. Clear STOPCF bit in REG0CN 2. Set STOP bit in PCON0	Any reset source
Snooze	 Core and peripheral clocks halted HFOSC0 and HFOSC1 oscillators stopped Regulator in low bias current mode for energy savings Timer 3 and 4 may clock from LFOSC0 Code resumes execution on wake event 	1. Switch SYSCLK to HFOSC0 2. Set SNOOZE bit in PCON1	Timer 4 Event SPI0 Activity I2C0 Slave Activity Port Match Event Comparator 0 Falling Edge CLUn Interrupt-Enabled Event
Shutdown	All internal power nets shut downPins retain stateExit on pin or power-on reset	1. Set STOPCF bit in REG0CN 2. Set STOP bit in PCON0	RSTb pin reset Power-on reset

3.3 I/O

Digital and analog resources are externally available on the device's multi-purpose I/O pins. Port pins P0.0-P2.3 can be defined as general-purpose I/O (GPIO), assigned to one of the internal digital resources through the crossbar or dedicated channels, or assigned to an analog function. Port pins P2.4 to P3.7 can be used as GPIO. Additionally, the C2 Interface Data signal (C2D) is shared with P3.0 or P3.7, depending on the package option.

The port control block offers the following features:

- Up to 29 multi-functions I/O pins, supporting digital and analog functions.
- · Flexible priority crossbar decoder for digital peripheral assignment.
- · Two drive strength settings for each port.
- State retention feature allows pins to retain configuration through most reset sources.
- Two direct-pin interrupt sources with dedicated interrupt vectors (INT0 and INT1).
- · Up to 24 direct-pin interrupt sources with shared interrupt vector (Port Match).

Low Current Comparators (CMP0, CMP1)

An analog comparator is used to compare the voltage of two analog inputs, with a digital output indicating which input voltage is higher. External input connections to device I/O pins and internal connections are available through separate multiplexers on the positive and negative inputs. Hysteresis, response time, and current consumption may be programmed to suit the specific needs of the application.

The comparator includes the following features:

- Up to 10 (CMP0) or 9 (CMP1) external positive inputs
- Up to 10 (CMP0) or 9 (CMP1) external negative inputs
- · Additional input options:
 - · Internal connection to LDO output
 - · Direct connection to GND
 - · Direct connection to VDD
 - · Dedicated 6-bit reference DAC
- · Synchronous and asynchronous outputs can be routed to pins via crossbar
- Programmable hysteresis between 0 and ±20 mV
- Programmable response time
- · Interrupts generated on rising, falling, or both edges
- · PWM output kill feature

3.8 Reset Sources

Reset circuitry allows the controller to be easily placed in a predefined default condition. On entry to this reset state, the following occur:

- The core halts program execution.
- Module registers are initialized to their defined reset values unless the bits reset only with a power-on reset.
- External port pins are forced to a known state.
- · Interrupts and timers are disabled.

All registers are reset to the predefined values noted in the register descriptions unless the bits only reset with a power-on reset. The contents of RAM are unaffected during a reset; any previously stored data is preserved as long as power is not lost. By default, the Port I/O latches are reset to 1 in open-drain mode, with weak pullups enabled during and after the reset. Optionally, firmware may configure the port I/O, DAC outputs, and precision reference to maintain state through system resets other than power-on resets. For Supply Monitor and power-on resets, the RSTb pin is driven low until the device exits the reset state. On exit from the reset state, the program counter (PC) is reset, and the system clock defaults to an internal oscillator. The Watchdog Timer is enabled, and program execution begins at location 0x0000.

Reset sources on the device include the following:

- Power-on reset
- · External reset pin
- Comparator reset
- · Software-triggered reset
- · Supply monitor reset (monitors VDD supply)
- · Watchdog timer reset
- · Missing clock detector reset
- · Flash error reset

3.9 Debugging

The EFM8BB3 devices include an on-chip Silicon Labs 2-Wire (C2) debug interface to allow flash programming and in-system debugging with the production part installed in the end application. The C2 interface uses a clock signal (C2CK) and a bi-directional C2 data signal (C2D) to transfer information between the device and a host system. See the C2 Interface Specification for details on the C2 protocol.

4. Electrical Specifications

4.1 Electrical Characteristics

All electrical parameters in all tables are specified under the conditions listed in Table 4.1 Recommended Operating Conditions on page 14, unless stated otherwise.

4.1.1 Recommended Operating Conditions

Table 4.1. Recommended Operating Conditions

Parameter	Symbol	Test Condition	Min	Тур	Max	Unit
Operating Supply Voltage on VDD	V_{DD}		2.2	_	3.6	V
Operating Supply Voltage on VIO ^{2,}	V _{IO}		2.2	_	V _{DD}	V
System Clock Frequency	f _{SYSCLK}		0	_	50	MHz
Operating Ambient Temperature	T _A	G-grade devices	-40	_	85	°C
		I-grade devices	-40	_	125	°C

Note:

- 1. All voltages with respect to GND
- 2. In certain package configurations, the VIO and VDD supplies are bonded to the same pin.
- 3. GPIO levels are undefined whenever VIO is less than 1 V.

4.1.2 Power Consumption

Table 4.2. Power Consumption

Parameter	Symbol	Test Condition	Min	Тур	Max	Unit
Digital Core Supply Current (G-gr	ade device	s, -40 °C to +85 °C)				
Normal Mode-Full speed with code	I _{DD}	F _{SYSCLK} = 49 MHz (HFOSC1) ²	_	5	14.4	mA
executing from flash		F _{SYSCLK} = 24.5 MHz (HFOSC0) ²	_	4.2	5	mA
		F _{SYSCLK} = 1.53 MHz (HFOSC0) ²	_	625	820	μA
		F _{SYSCLK} = 80 kHz ³	_	155	310	μA
Idle Mode-Core halted with periph-	I _{DD}	F _{SYSCLK} = 49 MHz (HFOSC1) ²	_	3.8	11.8	mA
erals running		F _{SYSCLK} = 24.5 MHz (HFOSC0) ²	_	3.14	3.8	mA
		F _{SYSCLK} = 1.53 MHz (HFOSC0) ²	_	520	725	μA
		F _{SYSCLK} = 80 kHz ³	_	135	315	μA
Suspend Mode-Core halted and	I _{DD}	LFO Running	_	125	320	μA
high frequency clocks stopped, Supply monitor off.		LFO Stopped	_	120	300	μA
Snooze Mode-Core halted and	I _{DD}	LFO Running	_	23	190	μA
high frequency clocks stopped. Regulator in low-power state, Sup- ply monitor off.		LFO Stopped	_	19	186	μA
Stop Mode—Core halted and all clocks stopped,Internal LDO On, Supply monitor off.	I _{DD}		_	120	300	μA
Shutdown Mode—Core halted and all clocks stopped,Internal LDO Off, Supply monitor off.	I _{DD}		_	0.2	0.91	μA
Digital Core Supply Current (I-gra	de devices	, -40 °C to +125 °C)				
Normal Mode-Full speed with code	I _{DD}	F _{SYSCLK} = 49 MHz (HFOSC1) ²	_	5	14.4	mA
executing from flash		F _{SYSCLK} = 24.5 MHz (HFOSC0) ²	_	4.2	5.2	mA
		F _{SYSCLK} = 1.53 MHz (HFOSC0) ²	_	625	1280	μA
		F _{SYSCLK} = 80 kHz ³	_	155	765	μA
Idle Mode-Core halted with periph-	I _{DD}	F _{SYSCLK} = 49 MHz (HFOSC1) ²	_	3.8	11.8	mA
erals running		F _{SYSCLK} = 24.5 MHz (HFOSC0) ²	_	3.14	4.1	mA
		F _{SYSCLK} = 1.53 MHz (HFOSC0) ²	_	520	1175	μA
		F _{SYSCLK} = 80 kHz ³	_	135	750	μA
Suspend Mode-Core halted and	I _{DD}	LFO Running	_	125	775	μA
high frequency clocks stopped, Supply monitor off.		LFO Stopped	_	120	755	μA
Snooze Mode-Core halted and	I _{DD}	LFO Running	_	23	615	μA
high frequency clocks stopped. Regulator in low-power state, Sup- ply monitor off.		LFO Stopped	_	19	610	μA

4.1.4 Flash Memory

Table 4.4. Flash Memory

Parameter	Symbol	Test Condition	Min	Тур	Max	Units
Write Time ¹ , ²	t _{WRITE}	One Byte,	19	20	21	μs
		F _{SYSCLK} = 24.5 MHz				
Erase Time ^{1,2}	t _{ERASE}	One Page,	5.2	5.35	5.5	ms
		F _{SYSCLK} = 24.5 MHz				
V _{DD} Voltage During Programming ³	V _{PROG}		2.2	_	3.6	V
Endurance (Write/Erase Cycles)	N _{WE}		20k	100k	_	Cycles
CRC Calculation Time	t _{CRC}	One 256-Byte Block	_	5.5	_	μs
		SYSCLK = 49 MHz				

Note:

- 1. Does not include sequencing time before and after the write/erase operation, which may be multiple SYSCLK cycles.
- 2. The internal High-Frequency Oscillator 0 has a programmable output frequency, which is factory programmed to 24.5 MHz. If user firmware adjusts the oscillator speed, it must be between 22 and 25 MHz during any flash write or erase operation. It is recommended to write the HFO0CAL register back to its reset value when writing or erasing flash.
- 3. Flash can be safely programmed at any voltage above the supply monitor threshold (V_{VDDM}).
- 4. Data Retention Information is published in the Quarterly Quality and Reliability Report.

4.1.5 Power Management Timing

Table 4.5. Power Management Timing

Parameter	Symbol	Test Condition	Min	Тур	Max	Units
Idle Mode Wake-up Time	t _{IDLEWK}		2	_	3	SYSCLKs
Suspend Mode Wake-up Time	t _{SUS-}	SYSCLK = HFOSC0	_	170	_	ns
	PENDWK	CLKDIV = 0x00				
Snooze Mode Wake-up Time	tSLEEPWK	SYSCLK = HFOSC0	_	12	_	μs
		CLKDIV = 0x00				

4.1.8 Crystal Oscillator

Table 4.8. Crystal Oscillator

Parameter	Symbol	Test Condition	Min	Тур	Max	Unit
Crystal Frequency	f _{XTAL}		0.02	_	25	MHz
Crystal Drive Current	I _{XTAL}	XFCN = 0	_	0.5	_	μΑ
		XFCN = 1	_	1.5	_	μΑ
		XFCN = 2	_	4.8	_	μΑ
		XFCN = 3	_	14	_	μΑ
		XFCN = 4	_	40	_	μΑ
		XFCN = 5	_	120	_	μΑ
		XFCN = 6	_	550	_	μΑ
		XFCN = 7	_	2.6	_	mA

4.1.9 ADC

Table 4.9. ADC

Parameter	Symbol	Test Condition	Min	Тур	Max	Unit
Resolution	N _{bits}	12 Bit Mode		12		Bits
		10 Bit Mode		10		Bits
Throughput Rate	f _S	10 Bit Mode	_	_	1.125	Msps
(High Speed Mode)						
Throughput Rate	f _S	12 Bit Mode	_	_	340	ksps
(Low Power Mode)		10 Bit Mode	_	_	360	ksps
Tracking Time	t _{TRK}	High Speed Mode	230	_	_	ns
		Low Power Mode	450	_	_	ns
Power-On Time	t _{PWR}		1.2	_	_	μs
SAR Clock Frequency	f _{SAR}	High Speed Mode	_	_	18	MHz
		Low Power Mode	_	_	12.25	MHz
Conversion Time ¹	t _{CNV}	12-Bit Conversion,	2.0			μs
		SAR Clock = 6.125 MHz,				
		System Clock = 49 MHz				
		10-Bit Conversion,		0.658		μs
		SAR Clock = 16.33 MHz,				
		System Clock = 49 MHz				
Sample/Hold Capacitor	C _{SAR}	Gain = 1	_	5.2	_	pF
		Gain = 0.75	_	3.9	_	pF
		Gain = 0.5	_	2.6	_	pF
		Gain = 0.25	_	1.3	_	pF
Input Pin Capacitance	C _{IN}		_	20	_	pF
Input Mux Impedance	R _{MUX}		_	550	_	Ω
Voltage Reference Range	V _{REF}		1	_	V _{IO}	V
Input Voltage Range ²	V _{IN}		0	_	V _{REF} / Gain	V
Power Supply Rejection Ratio	PSRR _{ADC}	At 1 kHz	_	66	_	dB
		At 1 MHz	_	43	_	dB
DC Performance		At 1 MHz		43	_	

Parameter	Symbol	Test Condition	Min	Тур	Max	Unit
Integral Nonlinearity	INL	12 Bit Mode	-1.9	-0.35 / +1	1.9	LSB
		10 Bit Mode	-0.6	±0.2	0.6	LSB
		T _A = -40 °C to 85 °C				
		10 Bit Mode	-0.7	±0.2	0.7	LSB
		T _A = -40 °C to 125 °C (I-grade parts only)				
Differential Nonlinearity (Guaran-	DNL	12 Bit Mode	-0.9	±0.3	0.9	LSB
teed Monotonic)		T _A = -40 °C to 85 °C				
		12 Bit Mode	-1.02	±0.3	1.02	LSB
		T_A = -40 °C to 125 °C (I-grade parts only)				
		10 Bit Mode	-0.5	±0.2	0.5	LSB
Offset Error ³	E _{OFF}	12 Bit Mode	-2	0	2	LSB
		T _A = -40 °C to 85 °C				
		12 Bit Mode	-3	0	3	LSB
		T _A = -40 °C to 125 °C (I-grade parts only)				
		10 Bit Mode	-1	0	1	LSB
		T _A = -40 °C to 85 °C				
		10 Bit Mode	-1	0	1.3	LSB
		T_A = -40 °C to 125 °C (I-grade parts only)				
Offset Temperature Coefficient	TC _{OFF}		_	0.011	_	LSB/°C
Slope Error	E _M	12 Bit Mode	-2.5	_	2.5	LSB
		T _A = -40 °C to 85 °C				
		12 Bit Mode	-2.6	_	2.6	LSB
		T _A = -40 °C to 125 °C (I-grade parts only)				
		10 Bit Mode	-1.1	_	1.1	LSB
Dynamic Performance 10 kHz Si	ne Wave In	out 1 dB below full scale, Max throu	ghput, using	g AGND pin		1
Signal-to-Noise	SNR	12 Bit Mode	64	68	_	dB
		10 Bit Mode	59	61	_	dB
Signal-to-Noise Plus Distortion	SNDR	12 Bit Mode	64	68	_	dB
		10 Bit Mode	59	61		dB
Total Harmonic Distortion (Up to	THD	12 Bit Mode	_	-72	_	dB
5th Harmonic)		10 Bit Mode	_	-69		dB
Spurious-Free Dynamic Range	SFDR	12 Bit Mode		74		dB
		10 Bit Mode	_	71		dB

Parameter	Symbol	Test Condition	Min	Тур	Max	Unit
Negative Hysteresis	HYS _{CP}	CPHYN = 00	_	-1.5	_	mV
Mode 3 (CPMD = 11)		CPHYN = 01	_	-4	_	mV
		CPHYN = 10	_	-8	_	mV
		CPHYN = 11	_	-16	_	mV
Input Range (CP+ or CP-)	V _{IN}		-0.25	_	V _{IO} +0.25	V
Input Pin Capacitance	C _{CP}		_	7.5	_	pF
Internal Reference DAC Resolution	N _{bits}			6		bits
Common-Mode Rejection Ratio	CMRR _{CP}		_	70	_	dB
Power Supply Rejection Ratio	PSRR _{CP}		_	72	_	dB
Input Offset Voltage	V _{OFF}	T _A = 25 °C	-10	0	10	mV
Input Offset Tempco	TC _{OFF}		_	3.5	_	μV/°

4.1.14 Configurable Logic

Table 4.14. Configurable Logic

Parameter	Symbol	Test Condition	Min	Тур	Max	Unit
Propagation Delay	t _{DLY}	Through single CLU	_	_	35.3	ns
		Using an external pin				
		Through single CLU	_	3	_	ns
		Using an internal connection				
Clocking Frequency	F _{CLK}	1 or 2 CLUs Cascaded	_	_	73.5	MHz
		3 or 4 CLUs Cascaded	_	_	36.75	MHz

4.1.16 SMBus

Table 4.16. SMBus Peripheral Timing Performance (Master Mode)

Parameter	Symbol	Test Condition	Min	Тур	Max	Unit
Standard Mode (100 kHz Class)						
I2C Operating Frequency	f _{I2C}		0	_	70 ²	kHz
SMBus Operating Frequency	f _{SMB}		40 ¹	_	70 ²	kHz
Bus Free Time Between STOP and START Conditions	t _{BUF}		9.4	_	_	μs
Hold Time After (Repeated) START Condition	t _{HD:STA}		4.7	_	_	μs
Repeated START Condition Setup Time	t _{SU:STA}		9.4	_	_	μs
STOP Condition Setup Time	t _{SU:STO}		9.4	_	_	μs
Data Hold Time	t _{HD:DAT}		0	_	_	μs
Data Setup Time	t _{SU:DAT}		4.7	_	_	μs
Detect Clock Low Timeout	t _{TIMEOUT}		25	_	_	ms
Clock Low Period	t _{LOW}		4.7	_	_	μs
Clock High Period	t _{HIGH}		9.4	_	50 ³	μs
Fast Mode (400 kHz Class)						
I2C Operating Frequency	f _{I2C}		0	_	256 ²	kHz
SMBus Operating Frequency	f _{SMB}		40 ¹	_	256 ²	kHz
Bus Free Time Between STOP and START Conditions	t _{BUF}		2.6	_	_	μs
Hold Time After (Repeated) START Condition	t _{HD:STA}		1.3	_	_	μs
Repeated START Condition Setup Time	t _{SU:STA}		2.6	_	_	μs
STOP Condition Setup Time	t _{SU:STO}		2.6	_	_	μs
Data Hold Time	t _{HD:DAT}		0	_	_	μs
Data Setup Time	t _{SU:DAT}		1.3	_	_	μs
Detect Clock Low Timeout	t _{TIMEOUT}		25	_	_	ms
Clock Low Period	t _{LOW}		1.3	_	_	μs
Clock High Period	t _{HIGH}		2.6	_	50 ³	μs

Note

- 1. The minimum SMBus frequency is limited by the maximum Clock High Period requirement of the SMBus specification.
- 2. The maximum I2C and SMBus frequencies are limited by the minimum Clock Low Period requirements of their respective specifications.
- 3. SMBus has a maximum requirement of 50 μ s for Clock High Period. Operating frequencies lower than 40 kHz will be longer than 50 μ s. I2C can support periods longer than 50 μ s.

6. Pin Definitions

6.1 EFM8BB3x-QFN32 Pin Definitions

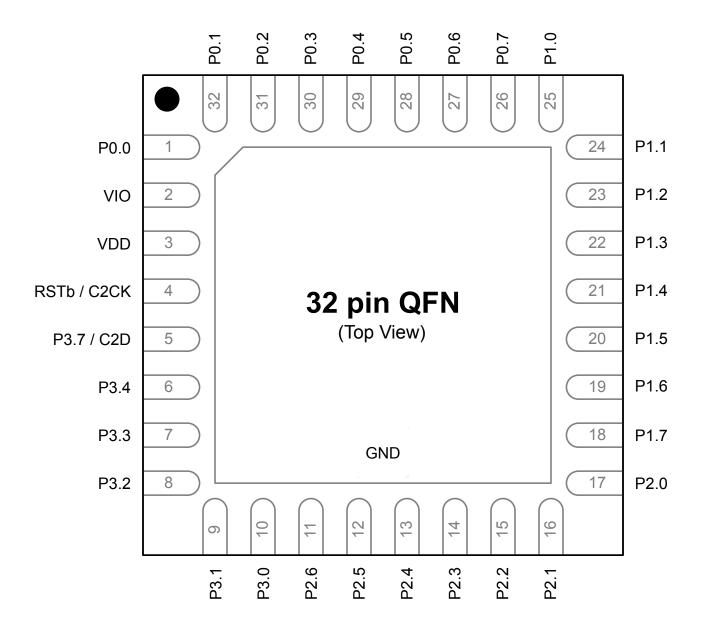


Figure 6.1. EFM8BB3x-QFN32 Pinout

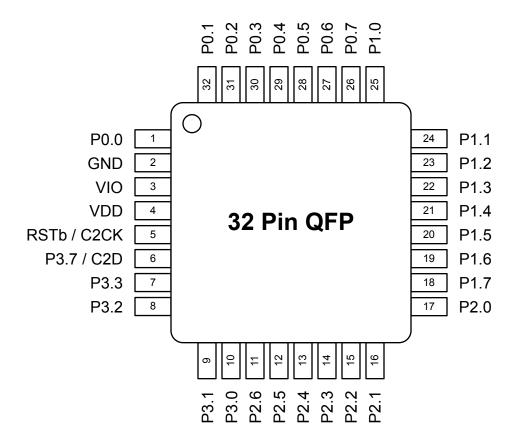


Figure 6.2. EFM8BB3x-QFP32 Pinout

Table 6.2. Pin Definitions for EFM8BB3x-QFP32

Pin Number	Pin Name	Description	Crossbar Capability	Crossbar Capability Additional Digital Functions					
1	P0.0	Multifunction I/O	Yes	P0MAT.0	VREF				
				INT0.0					
				INT1.0					
				CLU0A.8					
				CLU2A.8					
				CLU3B.8					
2	GND	Ground							
3	VIO	I/O Supply Power Input							
4	VDD	Supply Power Input							
5	RSTb /	Active-low Reset /							
	C2CK	C2 Debug Clock							

Pin	Pin Name	Description	Description Crossbar Capability		Analog Functions
Number				Functions	
18	P1.7	Multifunction I/O	Yes	P1MAT.7	ADC0.13
				CLU0B.15	CMP0P.9
				CLU1B.13	CMP0N.9
				CLU2A.13	
19	P1.6	Multifunction I/O	Yes	P1MAT.6	ADC0.12
				CLU0A.15	
				CLU1B.12	
				CLU2A.12	
20	P1.5	Multifunction I/O	Yes	P1MAT.5	ADC0.11
				CLU0B.14	
				CLU1A.13	
				CLU2B.13	
21	P1.4	Multifunction I/O	Yes	P1MAT.4	ADC0.10
				CLU0A.14	
				CLU1A.12	
				CLU2B.12	
22	P1.3	Multifunction I/O	Yes	P1MAT.3	ADC0.9
				CLU0B.13	
				CLU1B.11	
				CLU2B.11	
				CLU3A.13	
23	P1.2	Multifunction I/O	Yes	P1MAT.2	ADC0.8
				CLU0A.13	CMP0P.8
				CLU1A.11	CMP0N.8
				CLU2B.10	
				CLU3A.12	
24	P1.1	Multifunction I/O	Yes	P1MAT.1	ADC0.7
				CLU0B.12	CMP0P.7
				CLU1B.10	CMP0N.7
				CLU2A.11	
				CLU3B.13	

Pin Number	Pin Name	Description	Crossbar Capability	Additional Digital Functions	Analog Functions
2	P0.0	Multifunction I/O	Yes	P0MAT.0	VREF
				INT0.0	
				INT1.0	
				CLU0A.8	
				CLU2A.8	
				CLU3B.8	
3	GND	Ground			
4	VDD / VIO	Supply Power Input			
5	RSTb /	Active-low Reset /			
	C2CK	C2 Debug Clock			
6	P3.0 /	Multifunction I/O /			
	C2D	C2 Debug Data			
7	P2.3	Multifunction I/O	Yes	P2MAT.3	DAC3
				CLU1B.15	
				CLU2B.15	
				CLU3A.15	
8	P2.2	Multifunction I/O	Yes	P2MAT.2	DAC2
				CLU1A.15	
				CLU2B.14	
				CLU3A.14	
9	P2.1	Multifunction I/O	Yes	P2MAT.1	DAC1
				CLU1B.14	
				CLU2A.15	
				CLU3B.15	
10	P2.0	Multifunction I/O	Yes	P2MAT.0	DAC0
				CLU1A.14	
				CLU2A.14	
				CLU3B.14	
11	P1.6	Multifunction I/O	Yes	P1MAT.6	ADC0.11
				CLU3OUT	CMP1P.5
				CLU0A.15	CMP1N.5
				CLU1B.12	
				CLU2A.12	

7. QFN32 Package Specifications

7.1 QFN32 Package Dimensions

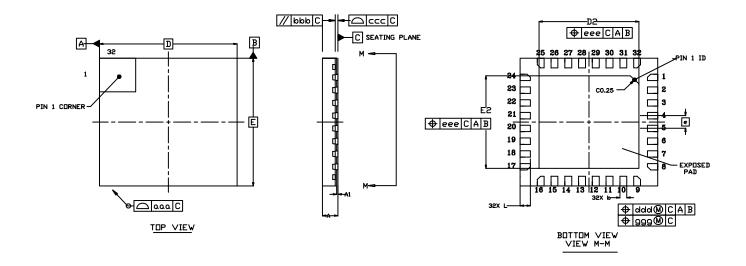


Figure 7.1. QFN32 Package Drawing

Table 7.1. QFN32 Package Dimensions

Dimension	Min	Тур	Max						
Α	0.45	0.50	0.55						
A1	0.00	0.035	0.05						
b	0.15	0.20	0.25						
D		4.00 BSC.							
D2	2.80	2.90	3.00						
е	0.40 BSC.								
Е	4.00 BSC.								
E2	2.80	2.90	3.00						
L	0.20	0.30	0.40						
aaa	_	_	0.10						
bbb	_	_	0.10						
ссс	_	_	0.08						
ddd	_	_	0.10						
eee	_	_	0.10						
999	_	_	0.05						

8. QFP32 Package Specifications

8.1 QFP32 Package Dimensions

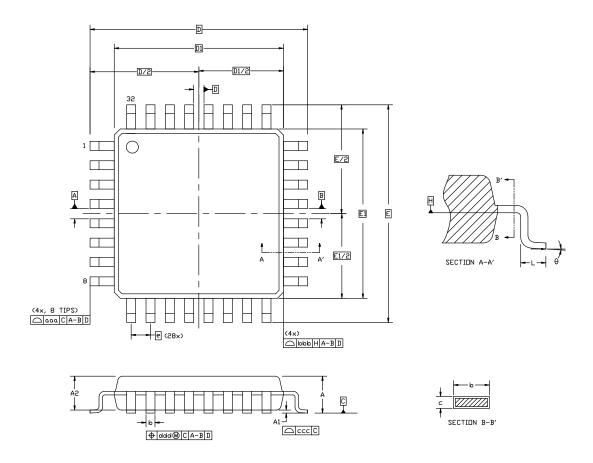


Figure 8.1. QFP32 Package Drawing

Table 8.1. QFP32 Package Dimensions

Dimension	Min	Тур	Max					
А	_	_	1.20					
A1	0.05	_	0.15					
A2	0.95	1.00	1.05					
b	0.30	0.37	0.45					
С	0.09	_	0.20					
D	9.00 BSC							
D1	7.00 BSC							
е		0.80 BSC						
Е		9.00 BSC						
E1		7.00 BSC						
L	0.50	0.60	0.70					

9. QFN24 Package Specifications

9.1 QFN24 Package Dimensions

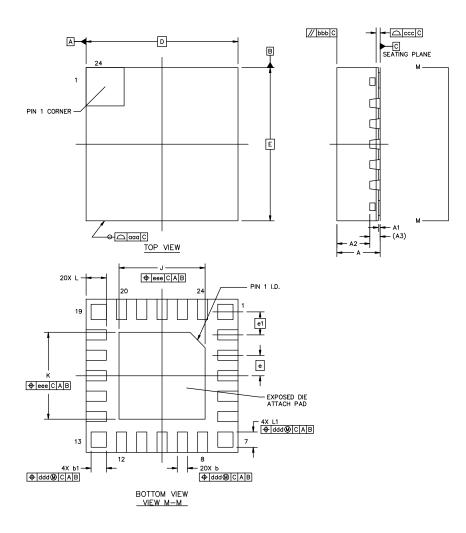


Figure 9.1. QFN24 Package Drawing

Table 9.1. QFN24 Package Dimensions

Dimension	Min	Тур	Max						
А	0.8	0.85	0.9						
A1	0.00	_	0.05						
A2	_	0.65	_						
A3	0.203 REF								
b	0.15	0.2	0.25						
b1	0.25	0.25 0.3							
D	3.00 BSC								
Е	3.00 BSC								

10. QSOP24 Package Specifications

10.1 QSOP24 Package Dimensions

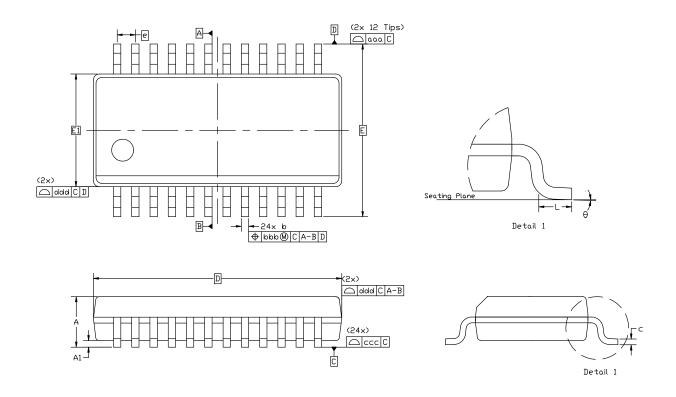


Figure 10.1. QSOP24 Package Drawing

Table 10.1. QSOP24 Package Dimensions

Dimension	Min	Тур	Max						
Α	_	_	1.75						
A1	0.10	_	0.25						
b	0.20	_	0.30						
С	0.10	_	0.25						
D	8.65 BSC								
Е	6.00 BSC								
E1	3.90 BSC								
е	0.635 BSC								
L	0.40	_	1.27						
theta	0°	_	8°						

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