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### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Not For New Designs
Core Processor	CIP-51 8051
Core Size	8-Bit
Speed	50MHz
Connectivity	I <sup>2</sup> C, SMBus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	29
Program Memory Size	32KB (32K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	2.25K x 8
Voltage - Supply (Vcc/Vdd)	2.2V ~ 3.6V
Data Converters	A/D 20x10/12b SAR; D/A 2x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	32-WFQFN Exposed Pad
Supplier Device Package	32-QFN (5x5)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/silicon-labs/efm8bb31f32i-b-5qfn32">https://www.e-xfl.com/product-detail/silicon-labs/efm8bb31f32i-b-5qfn32</a>

## 1. Feature List

The EFM8BB3 device family are fully integrated, mixed-signal system-on-a-chip MCUs. Highlighted features are listed below.

- Core:
  - Pipelined CIP-51 Core
  - Fully compatible with standard 8051 instruction set
  - 70% of instructions execute in 1-2 clock cycles
  - 50 MHz maximum operating frequency
- Memory:
  - Up to 64 kB flash memory (63 kB user-accessible), in-system re-programmable from firmware in 512-byte sectors
  - Up to 4352 bytes RAM (including 256 bytes standard 8051 RAM and 4096 bytes on-chip XRAM)
- Power:
  - Internal LDO regulator for CPU core voltage
  - Power-on reset circuit and brownout detectors
- I/O: Up to 29 total multifunction I/O pins:
  - Up to 25 pins 5 V tolerant under bias
  - Selectable state retention through reset events
  - Flexible peripheral crossbar for peripheral routing
  - 5 mA source, 12.5 mA sink allows direct drive of LEDs
- Clock Sources:
  - Internal 49 MHz oscillator with accuracy of  $\pm 2\%$
  - Internal 24.5 MHz oscillator with  $\pm 2\%$  accuracy
  - Internal 80 kHz low-frequency oscillator
  - External CMOS clock option
  - External crystal/RC Oscillator (up to 25 MHz)
- Analog:
  - 12/10-Bit Analog-to-Digital Converter (ADC)
  - Internal temperature sensor
  - 4 x 12-Bit Digital-to-Analog Converters (DAC)
  - 2 x Low-current analog comparators with adjustable reference
- Communications and Digital Peripherals:
  - 2 x UART, up to 3 Mbaud
  - SPI™ Master / Slave, up to 12 Mbps
  - SMBus™/I2C™ Master / Slave, up to 400 kbps
  - I2C High-Speed Slave, up to 3.4 Mbps
  - 16-bit CRC unit, supporting automatic CRC of flash at 256-byte boundaries
  - 4 Configurable Logic Units
- Timers/Counters and PWM:
  - 6-channel programmable counter array (PCA) supporting PWM, capture/compare, and frequency output modes
  - 6 x 16-bit general-purpose timers
  - Independent watchdog timer, clocked from the low frequency oscillator
- On-Chip, Non-Intrusive Debugging
  - Full memory and register inspection
  - Four hardware breakpoints, single-stepping
- Pre-programmed UART bootloader
- Temperature range -40 to 85 °C or -40 to 125 °C

With on-chip power-on reset, voltage supply monitor, watchdog timer, and clock oscillator, the EFM8BB3 devices are truly standalone system-on-a-chip solutions. The flash memory is reprogrammable in-circuit, providing nonvolatile data storage and allowing field upgrades of the firmware. The on-chip debugging interface (C2) allows non-intrusive (uses no on-chip resources), full speed, in-circuit debugging using the production MCU installed in the final application. This debug logic supports inspection and modification of memory and registers, setting breakpoints, single stepping, and run and halt commands. All analog and digital peripherals are fully functional while debugging. Device operation is specified from 2.2 V up to a 3.6 V supply. Devices are AEC-Q100 qualified and available in 4x4 mm 32-pin QFN, 3x3 mm 24-pin QFN, 32-pin QFP, or 24-pin QSOP packages. All package options are lead-free and RoHS compliant.

### 3.4 Clocking

The CPU core and peripheral subsystem may be clocked by both internal and external oscillator resources. By default, the system clock comes up running from the 24.5 MHz oscillator divided by 8.

The clock control system offers the following features:

- Provides clock to core and peripherals.
- 24.5 MHz internal oscillator (HFOSC0), accurate to  $\pm 2\%$  over supply and temperature corners.
- 49 MHz internal oscillator (HFOSC1), accurate to  $\pm 2\%$  over supply and temperature corners.
- 80 kHz low-frequency oscillator (LFOSC0).
- External RC, CMOS, and high-frequency crystal clock options (EXTCLK).
- Clock divider with eight settings for flexible clock scaling:
  - Divide the selected clock source by 1, 2, 4, 8, 16, 32, 64, or 128.
  - HFOSC0 and HFOSC1 include 1.5x pre-scalers for further flexibility.

### 3.5 Counters/Timers and PWM

#### Programmable Counter Array (PCA0)

The programmable counter array (PCA) provides multiple channels of enhanced timer and PWM functionality while requiring less CPU intervention than standard counter/timers. The PCA consists of a dedicated 16-bit counter/timer and one 16-bit capture/compare module for each channel. The counter/timer is driven by a programmable timebase that has flexible external and internal clocking options. Each capture/compare module may be configured to operate independently in one of five modes: Edge-Triggered Capture, Software Timer, High-Speed Output, Frequency Output, or Pulse-Width Modulated (PWM) Output. Each capture/compare module has its own associated I/O line (CEXn) which is routed through the crossbar to port I/O when enabled.

- 16-bit time base
- Programmable clock divisor and clock source selection
- Up to six independently-configurable channels
- 8, 9, 10, 11 and 16-bit PWM modes (center or edge-aligned operation)
- Output polarity control
- Frequency output mode
- Capture on rising, falling or any edge
- Compare function for arbitrary waveform generation
- Software timer (internal compare) mode
- Can accept hardware “kill” signal from comparator 0 or comparator 1

## I2C Slave (I2CSLAVE0)

The I2C Slave interface is a 2-wire, bidirectional serial bus that is compatible with the I2C Bus Specification 3.0. It is capable of transferring in high-speed mode (HS-mode) at speeds of up to 3.4 Mbps. Firmware can write to the I2C interface, and the I2C interface can autonomously control the serial transfer of data. The interface also supports clock stretching for cases where the core may be temporarily prohibited from transmitting a byte or processing a received byte during an I2C transaction. This module operates only as an I2C slave device.

The I2C module includes the following features:

- Standard (up to 100 kbps), Fast (400 kbps), Fast Plus (1 Mbps), and High-speed (3.4 Mbps) transfer speeds
- Support for slave mode only
- Clock low extending (clock stretching) to interface with faster masters
- Hardware support for 7-bit slave address recognition
- Transmit and receive FIFOs (two byte) to help increase throughput in faster applications
- Hardware support for multiple slave addresses with the option to save the matching address in the receive FIFO

## 16-bit CRC (CRC0)

The cyclic redundancy check (CRC) module performs a CRC using a 16-bit polynomial. CRC0 accepts a stream of 8-bit data and posts the 16-bit result to an internal register. In addition to using the CRC block for data manipulation, hardware can automatically CRC the flash contents of the device.

The CRC module is designed to provide hardware calculations for flash memory verification and communications protocols. The CRC module supports the standard CCITT-16 16-bit polynomial (0x1021), and includes the following features:

- Support for CCITT-16 polynomial
- Byte-level bit reversal
- Automatic CRC of flash contents on one or more 256-byte blocks
- Initial seed selection of 0x0000 or 0xFFFF

## Configurable Logic Units (CLU0, CLU1, CLU2, and CLU3)

The Configurable Logic block consists of multiple Configurable Logic Units (CLUs). CLUs are flexible logic functions which may be used for a variety of digital functions, such as replacing system glue logic, aiding in the generation of special waveforms, or synchronizing system event triggers.

- Four configurable logic units (CLUs), with direct-pin and internal logic connections
- Each unit supports 256 different combinatorial logic functions (AND, OR, XOR, muxing, etc.) and includes a clocked flip-flop for synchronous operations
- Units may be operated synchronously or asynchronously
- May be cascaded together to perform more complicated logic functions
- Can operate in conjunction with serial peripherals such as UART and SPI or timing peripherals such as timers and PCA channels
- Can be used to synchronize and trigger multiple on-chip resources (ADC, DAC, Timers, etc.)
- Asynchronous output may be used to wake from low-power states

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Stop Mode—Core halted and all clocks stopped, Internal LDO On, Supply monitor off.	$I_{DD}$		—	120	740	$\mu A$
Shutdown Mode—Core halted and all clocks stopped, Internal LDO Off, Supply monitor off.	$I_{DD}$		—	0.2	4.5	$\mu A$
<b>Analog Peripheral Supply Currents (-40 °C to +125 °C)</b>						
High-Frequency Oscillator 0	$I_{HFOSC0}$	Operating at 24.5 MHz, $T_A = 25\text{ °C}$	—	120	135	$\mu A$
High-Frequency Oscillator 1	$I_{HFOSC1}$	Operating at 49 MHz, $T_A = 25\text{ °C}$	—	770	1200	$\mu A$
Low-Frequency Oscillator	$I_{LFOSC}$	Operating at 80 kHz, $T_A = 25\text{ °C}$	—	3.7	6	$\mu A$
ADC0 <sup>4</sup>	$I_{ADC}$	High Speed Mode 1 Msps, 10-bit conversions Normal bias settings $V_{DD} = 3.0\text{ V}$	—	1210	1600	$\mu A$
		Low Power Mode 350 ksps, 12-bit conversions Low power bias settings $V_{DD} = 3.0\text{ V}$	—	415	560	$\mu A$
Internal ADC0 Reference <sup>5</sup>	$I_{VREFFS}$	High Speed Mode	—	700	790	$\mu A$
		Low Power Mode	—	170	210	$\mu A$
On-chip Precision Reference	$I_{VREFP}$		—	75	—	$\mu A$
Temperature Sensor	$I_{TSENSE}$		—	68	120	$\mu A$
Digital-to-Analog Converters (DAC0, DAC1, DAC2, DAC3) <sup>6</sup>	$I_{DAC}$		—	125	—	$\mu A$
Comparators (CMP0, CMP1)	$I_{CMP}$	CPMD = 11	—	0.5	—	$\mu A$
		CPMD = 10	—	3	—	$\mu A$
		CPMD = 01	—	10	—	$\mu A$
		CPMD = 00	—	25	—	$\mu A$
Comparator Reference	$I_{CPREF}$		—	24	—	$\mu A$
Voltage Supply Monitor (VMON0)	$I_{VMON}$		—	15	20	$\mu A$

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
<b>Note:</b> <ol style="list-style-type: none"> <li>1. Currents are additive. For example, where <math>I_{DD}</math> is specified and the mode is not mutually exclusive, enabling the functions increases supply current by the specified amount.</li> <li>2. Includes supply current from internal LDO regulator, supply monitor, and High Frequency Oscillator.</li> <li>3. Includes supply current from internal LDO regulator, supply monitor, and Low Frequency Oscillator.</li> <li>4. ADC0 power excludes internal reference supply current.</li> <li>5. The internal reference is enabled as-needed when operating the ADC in low power mode. Total ADC + Reference current will depend on sampling rate.</li> <li>6. DAC supply current for each enabled DA and not including external load on pin.</li> </ol>						

#### 4.1.3 Reset and Supply Monitor

**Table 4.3. Reset and Supply Monitor**

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
VDD Supply Monitor Threshold	$V_{VDDM}$		1.95	2.05	2.15	V
Power-On Reset (POR) Threshold	$V_{POR}$	Rising Voltage on VDD	—	1.4	—	V
		Falling Voltage on VDD	0.75	—	1.36	V
VDD Ramp Time	$t_{RMP}$	Time to $V_{DD} > 2.2$ V	10	—	—	$\mu$ s
Reset Delay from POR	$t_{POR}$	Relative to $V_{DD} > V_{POR}$	3	10	31	ms
Reset Delay from non-POR source	$t_{RST}$	Time between release of reset source and code execution	—	50	—	$\mu$ s
RST Low Time to Generate Reset	$t_{RSTL}$		15	—	—	$\mu$ s
Missing Clock Detector Response Time (final rising edge to reset)	$t_{MCD}$	$F_{SYSCLK} > 1$ MHz	—	0.625	1.2	ms
Missing Clock Detector Trigger Frequency	$F_{MCD}$		—	7.5	13.5	kHz
VDD Supply Monitor Turn-On Time	$t_{MON}$		—	2	—	$\mu$ s

## 4.1.9 ADC

Table 4.9. ADC

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Resolution	N <sub>bits</sub>	12 Bit Mode	12			Bits
		10 Bit Mode	10			Bits
Throughput Rate (High Speed Mode)	f <sub>S</sub>	10 Bit Mode	—	—	1.125	Msp/s
Throughput Rate (Low Power Mode)	f <sub>S</sub>	12 Bit Mode	—	—	340	ksps
		10 Bit Mode	—	—	360	ksps
Tracking Time	t <sub>TRK</sub>	High Speed Mode	230	—	—	ns
		Low Power Mode	450	—	—	ns
Power-On Time	t <sub>PWR</sub>		1.2	—	—	μs
SAR Clock Frequency	f <sub>SAR</sub>	High Speed Mode	—	—	18	MHz
		Low Power Mode	—	—	12.25	MHz
Conversion Time <sup>1</sup>	t <sub>CNV</sub>	12-Bit Conversion, SAR Clock = 6.125 MHz, System Clock = 49 MHz	2.0			μs
		10-Bit Conversion, SAR Clock = 16.33 MHz, System Clock = 49 MHz	0.658			μs
Sample/Hold Capacitor	C <sub>SAR</sub>	Gain = 1	—	5.2	—	pF
		Gain = 0.75	—	3.9	—	pF
		Gain = 0.5	—	2.6	—	pF
		Gain = 0.25	—	1.3	—	pF
Input Pin Capacitance	C <sub>IN</sub>		—	20	—	pF
Input Mux Impedance	R <sub>MUX</sub>		—	550	—	Ω
Voltage Reference Range	V <sub>REF</sub>		1	—	V <sub>IO</sub>	V
Input Voltage Range <sup>2</sup>	V <sub>IN</sub>		0	—	V <sub>REF</sub> / Gain	V
Power Supply Rejection Ratio	PSRR <sub>ADC</sub>	At 1 kHz	—	66	—	dB
		At 1 MHz	—	43	—	dB
DC Performance						

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Integral Nonlinearity	INL	12 Bit Mode	-1.9	-0.35 / +1	1.9	LSB
		10 Bit Mode	-0.6	±0.2	0.6	LSB
		T <sub>A</sub> = -40 °C to 85 °C				
		10 Bit Mode	-0.7	±0.2	0.7	LSB
		T <sub>A</sub> = -40 °C to 125 °C (I-grade parts only)				
Differential Nonlinearity (Guaranteed Monotonic)	DNL	12 Bit Mode	-0.9	±0.3	0.9	LSB
		T <sub>A</sub> = -40 °C to 85 °C				
		12 Bit Mode	-1.02	±0.3	1.02	LSB
		T <sub>A</sub> = -40 °C to 125 °C (I-grade parts only)				
		10 Bit Mode	-0.5	±0.2	0.5	LSB
Offset Error <sup>3</sup>	E <sub>OFF</sub>	12 Bit Mode	-2	0	2	LSB
		T <sub>A</sub> = -40 °C to 85 °C				
		12 Bit Mode	-3	0	3	LSB
		T <sub>A</sub> = -40 °C to 125 °C (I-grade parts only)				
		10 Bit Mode	-1	0	1	LSB
		T <sub>A</sub> = -40 °C to 85 °C				
		10 Bit Mode	-1	0	1.3	LSB
		T <sub>A</sub> = -40 °C to 125 °C (I-grade parts only)				
Offset Temperature Coefficient	TC <sub>OFF</sub>		—	0.011	—	LSB/°C
Slope Error	E <sub>M</sub>	12 Bit Mode	-2.5	—	2.5	LSB
		T <sub>A</sub> = -40 °C to 85 °C				
		12 Bit Mode	-2.6	—	2.6	LSB
		T <sub>A</sub> = -40 °C to 125 °C (I-grade parts only)				
		10 Bit Mode	-1.1	—	1.1	LSB
Dynamic Performance 10 kHz Sine Wave Input 1 dB below full scale, Max throughput, using AGND pin						
Signal-to-Noise	SNR	12 Bit Mode	64	68	—	dB
		10 Bit Mode	59	61	—	dB
Signal-to-Noise Plus Distortion	SNDR	12 Bit Mode	64	68	—	dB
		10 Bit Mode	59	61	—	dB
Total Harmonic Distortion (Up to 5th Harmonic)	THD	12 Bit Mode	—	-72	—	dB
		10 Bit Mode	—	-69	—	dB
Spurious-Free Dynamic Range	SFDR	12 Bit Mode	—	74	—	dB
		10 Bit Mode	—	71	—	dB



#### 4.1.12 DACs

Table 4.12. DACs

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Resolution	N <sub>bits</sub>		12			Bits
Throughput Rate	f <sub>S</sub>		—	—	200	ksps
Integral Nonlinearity	INL	DAC0 and DAC2 T <sub>A</sub> = -40 °C to 125 °C (I-grade parts only)	-11.5	-1.77 / 1.56	11.5	LSB
		DAC0 and DAC3 T <sub>A</sub> = -40 °C to 125 °C (I-grade parts only)	-13.5	-2.73 / 1.11	13.5	LSB
Differential Nonlinearity	DNL		-1	—	1	LSB
Output Noise	V <sub>REF</sub> = 2.4 V f <sub>S</sub> = 0.1 Hz to 300 kHz		—	110	—	μV <sub>RMS</sub>
Slew Rate	SLEW		—	±1	—	V/μs
Output Settling Time to 1% Full-scale	t <sub>SETTLE</sub>	V <sub>OUT</sub> change between 25% and 75% Full Scale	—	2.6	5	μs
Power-on Time	t <sub>PWR</sub>		—	—	10	μs
Voltage Reference Range	V <sub>REF</sub>		1.15	—	V <sub>DD</sub>	V
Power Supply Rejection Ratio	PSRR	DC, V <sub>OUT</sub> = 50% Full Scale	—	78	—	dB
Total Harmonic Distortion	THD	V <sub>OUT</sub> = 10 kHz sine wave, 10% to 90%	54	—	—	dB
Offset Error	E <sub>OFF</sub>	V <sub>REF</sub> = 2.4 V	-8	0	8	LSB
Full-Scale Error	E <sub>FS</sub>	V <sub>REF</sub> = 2.4 V	-13	±5	13	LSB
External Load Impedance	R <sub>LOAD</sub>		2	—	—	kΩ
External Load Capacitance <sup>1</sup>	C <sub>LOAD</sub>		—	—	100	pF

**Note:**

1. No minimum external load capacitance is required. However, under low loading conditions, it is possible for the DAC output to glitch during start-up. If smooth start-up is required, the minimum loading capacitance at the pin should be a minimum of 10 pF.

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Negative Hysteresis Mode 3 (CPMD = 11)	HYS <sub>CP-</sub>	CPHYN = 00	—	-1.5	—	mV
		CPHYN = 01	—	-4	—	mV
		CPHYN = 10	—	-8	—	mV
		CPHYN = 11	—	-16	—	mV
Input Range (CP+ or CP-)	V <sub>IN</sub>		-0.25	—	V <sub>IO</sub> +0.25	V
Input Pin Capacitance	C <sub>CP</sub>		—	7.5	—	pF
Internal Reference DAC Resolution	N <sub>bits</sub>		6			bits
Common-Mode Rejection Ratio	CMRR <sub>CP</sub>		—	70	—	dB
Power Supply Rejection Ratio	PSRR <sub>CP</sub>		—	72	—	dB
Input Offset Voltage	V <sub>OFF</sub>	T <sub>A</sub> = 25 °C	-10	0	10	mV
Input Offset Tempco	TC <sub>OFF</sub>		—	3.5	—	μV/°

#### 4.1.14 Configurable Logic

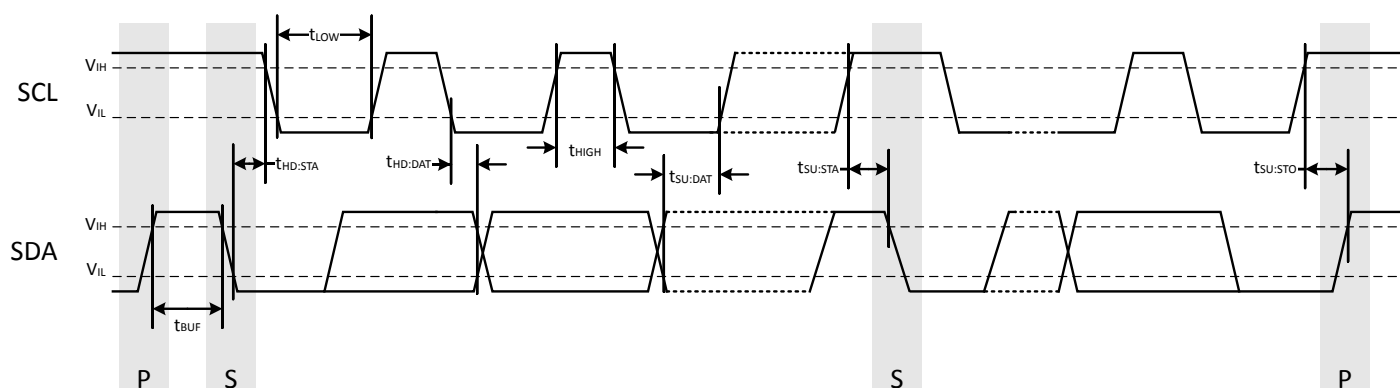
**Table 4.14. Configurable Logic**

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Propagation Delay	t <sub>DLY</sub>	Through single CLU Using an external pin	—	—	35.3	ns
		Through single CLU Using an internal connection	—	3	—	ns
Clocking Frequency	F <sub>CLK</sub>	1 or 2 CLUs Cascaded	—	—	73.5	MHz
		3 or 4 CLUs Cascaded	—	—	36.75	MHz

**Table 4.17. SMBus Peripheral Timing Formulas (Master Mode)**

Parameter	Symbol	Clocks
SMBus Operating Frequency	$f_{\text{SMB}}$	$f_{\text{CSO}} / 3$
Bus Free Time Between STOP and START Conditions	$t_{\text{BUF}}$	$2 / f_{\text{CSO}}$
Hold Time After (Repeated) START Condition	$t_{\text{HD:STA}}$	$1 / f_{\text{CSO}}$
Repeated START Condition Setup Time	$t_{\text{SU:STA}}$	$2 / f_{\text{CSO}}$
STOP Condition Setup Time	$t_{\text{SU:STO}}$	$2 / f_{\text{CSO}}$
Clock Low Period	$t_{\text{LOW}}$	$1 / f_{\text{CSO}}$
Clock High Period	$t_{\text{HIGH}}$	$2 / f_{\text{CSO}}$

**Note:**  
1.  $f_{\text{CSO}}$  is the SMBus peripheral clock source overflow frequency.



**Figure 4.1. SMBus Peripheral Timing Diagram (Master Mode)**

## 4.2 Thermal Conditions

**Table 4.18. Thermal Conditions**

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Thermal Resistance	$\theta_{\text{JA}}$	QFN24 Packages	—	30	—	°C/W
		QFN32 Packages	—	26	—	°C/W
		QFP32 Packages	—	80	—	°C/W
		QSOP24 Packages	—	65	—	°C/W

**Note:**  
1. Thermal resistance assumes a multi-layer PCB with any exposed pad soldered to a PCB pad.

### 4.3 Absolute Maximum Ratings

Stresses above those listed in [Table 4.19 Absolute Maximum Ratings on page 32](#) may cause permanent damage to the device. This is a stress rating only and functional operation of the devices at those or any other conditions above those indicated in the operation listings of this specification is not implied. Exposure to maximum rating conditions for extended periods may affect device reliability. For more information on the available quality and reliability data, see the Quality and Reliability Monitor Report at <http://www.silabs.com/support/quality/pages/default.aspx>.

**Table 4.19. Absolute Maximum Ratings**

Parameter	Symbol	Test Condition	Min	Max	Unit
Ambient Temperature Under Bias	$T_{BIAS}$		-55	125	°C
Storage Temperature	$T_{STG}$		-65	150	°C
Voltage on VDD	$V_{DD}$		GND-0.3	4.2	V
Voltage on VIO <sup>2</sup>	$V_{IO}$		GND-0.3	$V_{DD}+0.3$	V
Voltage on I/O pins or RSTb, excluding P2.0-P2.3 (QFN24 and QSOP24) or P3.0-P3.3 (QFN32 and QFP32)	$V_{IN}$	$V_{IO} > 3.3\text{ V}$	GND-0.3	5.8	V
		$V_{IO} < 3.3\text{ V}$	GND-0.3	$V_{IO}+2.5$	V
Voltage on P2.0-P2.3 (QFN24 and QSOP24) or P3.0-P3.3 (QFN32 and QFP32)	$V_{IN}$		GND-0.3	$V_{DD}+0.3$	V
Total Current Sunk into Supply Pin	$I_{VDD}$		—	200	mA
Total Current Sourced out of Ground Pin	$I_{GND}$		200	—	mA
Current Sourced or Sunk by any I/O Pin or RSTb	$I_{IO}$		-100	100	mA
Operating Junction Temperature	$T_J$	$T_A = -40\text{ °C to }85\text{ °C}$	-40	105	°C
		$T_A = -40\text{ °C to }125\text{ °C}$ (I-grade parts only)	-40	130	°C

**Note:**

1. Exposure to maximum rating conditions for extended periods may affect device reliability.
2. In certain package configurations, the VIO and VDD supplies are bonded to the same pin.

Pin Number	Pin Name	Description	Crossbar Capability	Additional Digital Functions	Analog Functions
15	P2.2	Multifunction I/O	Yes	P2MAT.2 CLU2OUT CLU1A.15 CLU2B.14 CLU3A.14	ADC0.15 CMP1P.4 CMP1N.4
16	P2.1	Multifunction I/O	Yes	P2MAT.1 I2C0_SCL CLU1B.14 CLU2A.15 CLU3B.15	ADC0.14 CMP1P.3 CMP1N.3
17	P2.0	Multifunction I/O	Yes	P2MAT.0 I2C0_SDA CLU1A.14 CLU2A.14 CLU3B.14	CMP1P.2 CMP1N.2
18	P1.7	Multifunction I/O	Yes	P1MAT.7 CLU0B.15 CLU1B.13 CLU2A.13	ADC0.13 CMP0P.9 CMP0N.9
19	P1.6	Multifunction I/O	Yes	P1MAT.6 CLU0A.15 CLU1B.12 CLU2A.12	ADC0.12
20	P1.5	Multifunction I/O	Yes	P1MAT.5 CLU0B.14 CLU1A.13 CLU2B.13	ADC0.11
21	P1.4	Multifunction I/O	Yes	P1MAT.4 CLU0A.14 CLU1A.12 CLU2B.12	ADC0.10
22	P1.3	Multifunction I/O	Yes	P1MAT.3 CLU0B.13 CLU1B.11 CLU2B.11 CLU3A.13	ADC0.9

Pin Number	Pin Name	Description	Crossbar Capability	Additional Digital Functions	Analog Functions
29	P0.4	Multifunction I/O	Yes	P0MAT.4 INT0.4 INT1.4 UART0_TX CLU0A.10 CLU1A.8 CLU3B.10	ADC0.2 CMP0P.2 CMP0N.2
30	P0.3	Multifunction I/O	Yes	P0MAT.3 EXTCLK INT0.3 INT1.3 CLU0B.9 CLU2B.9 CLU3A.9	XTAL2
31	P0.2	Multifunction I/O	Yes	P0MAT.2 INT0.2 INT1.2 CLU0OUT CLU0A.9 CLU2B.8 CLU3A.8	XTAL1 ADC0.1 CMP0P.1 CMP0N.1
32	P0.1	Multifunction I/O	Yes	P0MAT.1 INT0.1 INT1.1 CLU0B.8 CLU2A.9 CLU3B.9	ADC0.0 CMP0P.0 CMP0N.0 AGND
Center	GND	Ground			

Pin Number	Pin Name	Description	Crossbar Capability	Additional Digital Functions	Analog Functions
25	P1.0	Multifunction I/O	Yes	P1MAT.0 CLU1OUT CLU0A.12 CLU1A.10 CLU2A.10 CLU3B.12	ADC0.6 CMP0P.6 CMP0N.6 CMP1P.1 CMP1N.1
26	P0.7	Multifunction I/O	Yes	P0MAT.7 INT0.7 INT1.7 CLU0B.11 CLU1B.9 CLU3A.11	ADC0.5 CMP0P.5 CMP0N.5 CMP1P.0 CMP1N.0
27	P0.6	Multifunction I/O	Yes	P0MAT.6 CNVSTR INT0.6 INT1.6 CLU0A.11 CLU1B.8 CLU3A.10	ADC0.4 CMP0P.4 CMP0N.4
28	P0.5	Multifunction I/O	Yes	P0MAT.5 INT0.5 INT1.5 UART0_RX CLU0B.10 CLU1A.9 CLU3B.11	ADC0.3 CMP0P.3 CMP0N.3
29	P0.4	Multifunction I/O	Yes	P0MAT.4 INT0.4 INT1.4 UART0_TX CLU0A.10 CLU1A.8 CLU3B.10	ADC0.2 CMP0P.2 CMP0N.2

## 6.4 EFM8BB3x-QSOP24 Pin Definitions

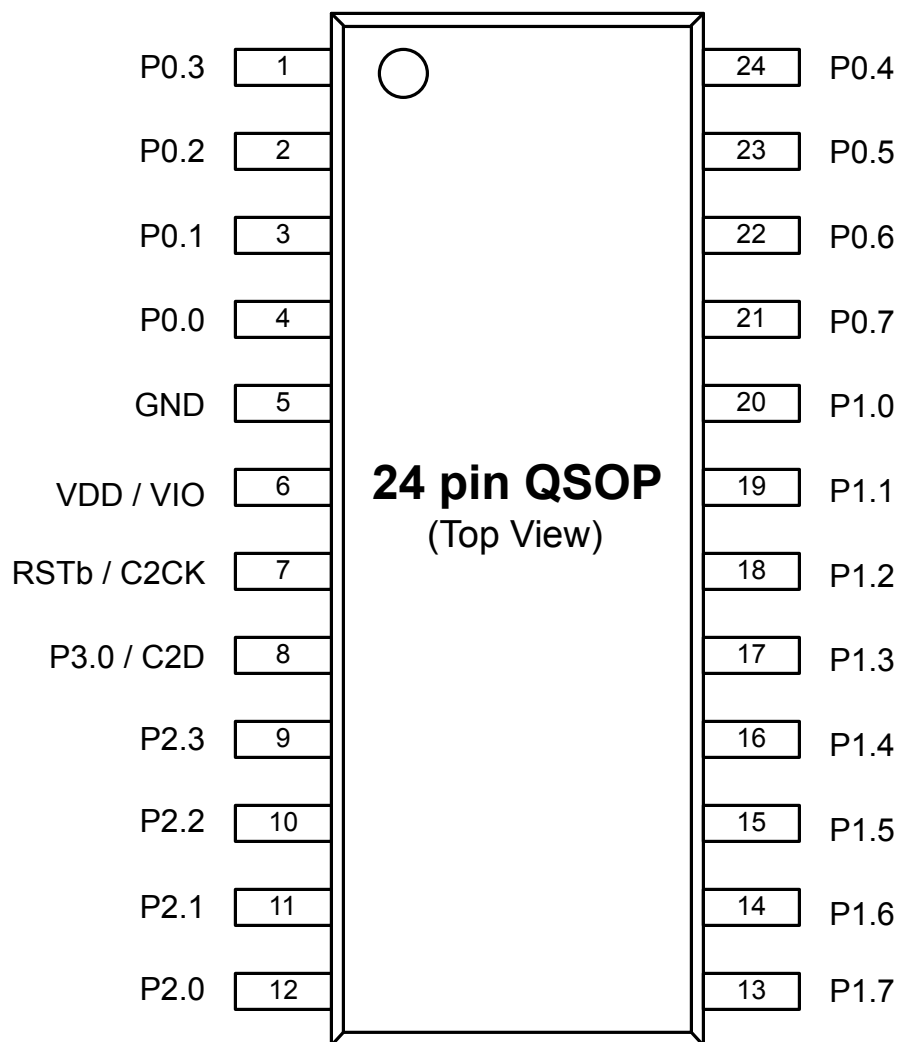


Figure 6.4. EFM8BB3x-QSOP24 Pinout

Table 6.4. Pin Definitions for EFM8BB3x-QSOP24

Pin Number	Pin Name	Description	Crossbar Capability	Additional Digital Functions	Analog Functions
1	P0.3	Multifunction I/O	Yes	P0MAT.3 EXTCLK INT0.3 INT1.3 CLU0B.9 CLU2B.9 CLU3A.9	XTAL2



Pin Number	Pin Name	Description	Crossbar Capability	Additional Digital Functions	Analog Functions
18	P1.2	Multifunction I/O	Yes	P1MAT.2 CLU0A.13 CLU1A.11 CLU2B.10 CLU3A.12	ADC0.8
19	P1.1	Multifunction I/O	Yes	P1MAT.1 CLU0B.12 CLU1B.10 CLU2A.11 CLU3B.13	ADC0.7
20	P1.0	Multifunction I/O	Yes	P1MAT.0 CLU0A.12 CLU1A.10 CLU2A.10 CLU3B.12	ADC0.6
21	P0.7	Multifunction I/O	Yes	P0MAT.7 INT0.7 INT1.7 CLU1OUT CLU0B.11 CLU1B.9 CLU3A.11	ADC0.5 CMP0P.5 CMP0N.5 CMP1P.1 CMP1N.1
22	P0.6	Multifunction I/O	Yes	P0MAT.6 CNVSTR INT0.6 INT1.6 CLU0A.11 CLU1B.8 CLU3A.10	ADC0.4 CMP0P.4 CMP0N.4 CMP1P.0 CMP1N.0
23	P0.5	Multifunction I/O	Yes	P0MAT.5 INT0.5 INT1.5 UART0_RX CLU0B.10 CLU1A.9 CLU3B.11	ADC0.3 CMP0P.3 CMP0N.3

## 8. QFP32 Package Specifications

### 8.1 QFP32 Package Dimensions

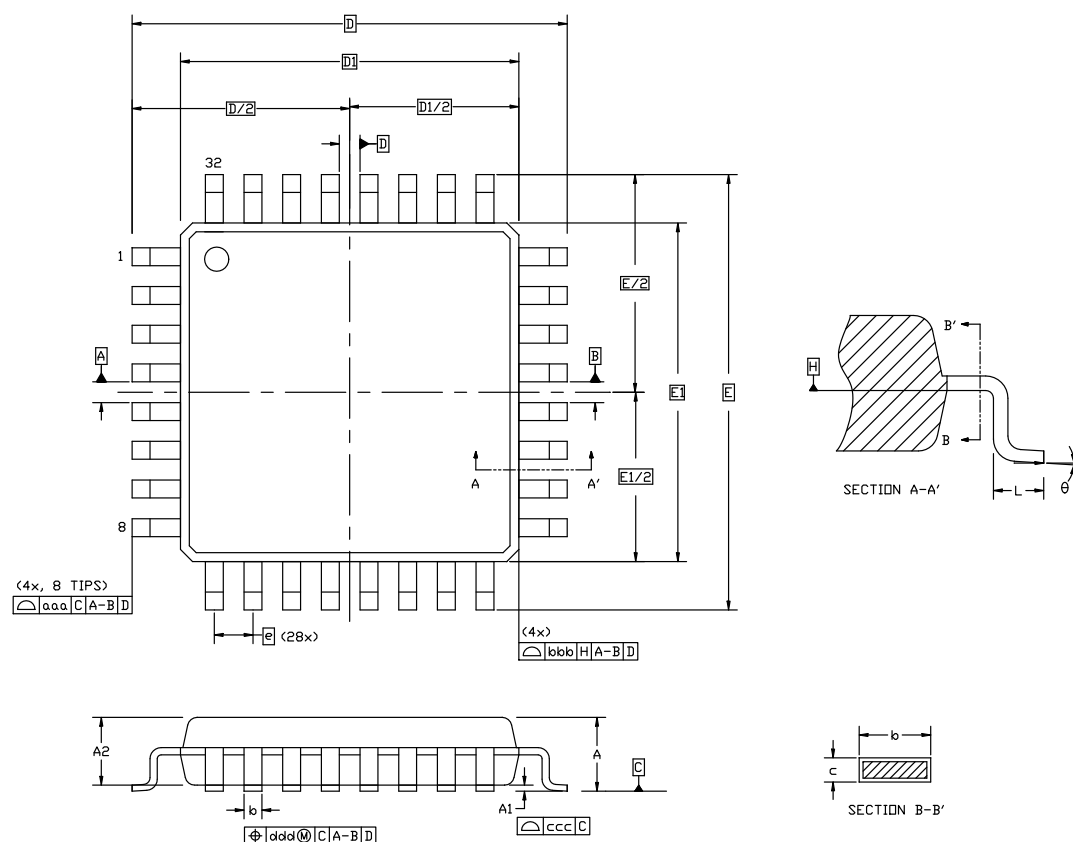


Figure 8.1. QFP32 Package Drawing

Table 8.1. QFP32 Package Dimensions

Dimension	Min	Typ	Max
A	—	—	1.20
A1	0.05	—	0.15
A2	0.95	1.00	1.05
b	0.30	0.37	0.45
c	0.09	—	0.20
D	9.00 BSC		
D1	7.00 BSC		
e	0.80 BSC		
E	9.00 BSC		
E1	7.00 BSC		
L	0.50	0.60	0.70

### 8.3 QFP32 Package Marking

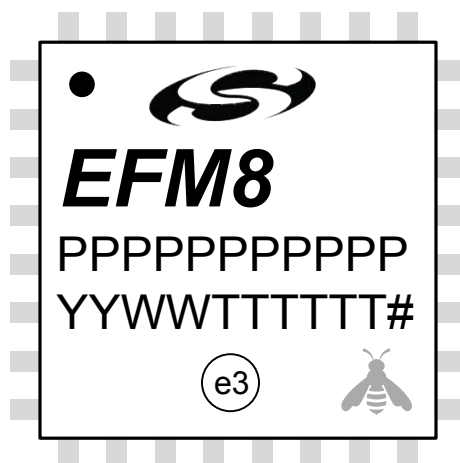


Figure 8.3. QFP32 Package Marking

The package marking consists of:

- P P P P P P P P – The part number designation.
- T T T T T T – A trace or manufacturing code.
- Y Y – The last 2 digits of the assembly year.
- W W – The 2-digit workweek when the device was assembled.
- # – The device revision (A, B, etc.).

## 9.2 QFN24 PCB Land Pattern

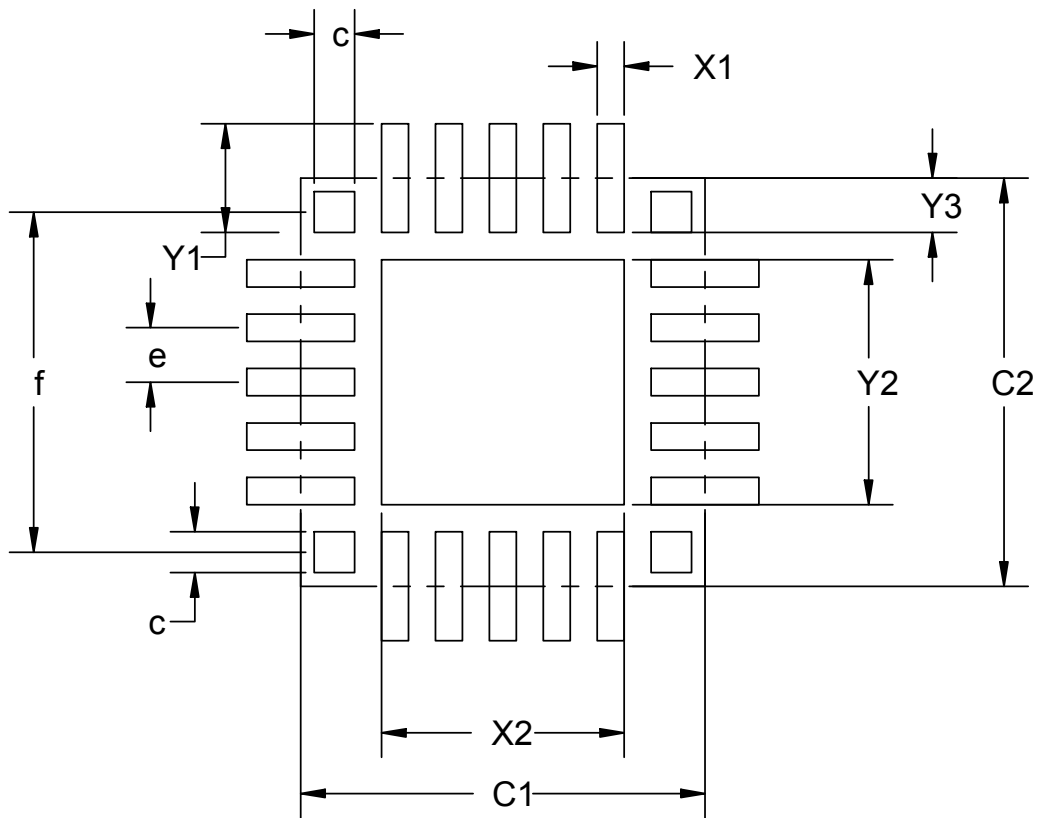


Figure 9.2. QFN24 PCB Land Pattern Drawing

Table 9.2. QFN24 PCB Land Pattern Dimensions

Dimension	Min	Max
C1		3.00
C2		3.00
e		0.4 REF
X1		0.20
X2		1.80
Y1		0.80
Y2		1.80
Y3		0.4
f		2.50 REF
c	0.25	0.35

Dimension	Min	Max
<b>Note:</b> <ol style="list-style-type: none"> <li>1. All dimensions shown are in millimeters (mm) unless otherwise noted.</li> <li>2. Dimensioning and Tolerancing is per the ANSI Y14.5M-1994 specification.</li> <li>3. This Land Pattern Design is based on the IPC-SM-782 guidelines.</li> <li>4. All metal pads are to be non-solder mask defined (NSMD). Clearance between the solder mask and the metal pad is to be 60 µm minimum, all the way around the pad.</li> <li>5. A stainless steel, laser-cut and electro-polished stencil with trapezoidal walls should be used to assure good solder paste release.</li> <li>6. The stencil thickness should be 0.125 mm (5 mils).</li> <li>7. The ratio of stencil aperture to land pad size should be 1:1 for all perimeter pads.</li> <li>8. A 2 x 1 array of 0.7 mm x 1.6 mm openings on a 0.9 mm pitch should be used for the center pad.</li> <li>9. A No-Clean, Type-3 solder paste is recommended.</li> <li>10. The recommended card reflow profile is per the JEDEC/IPC J-STD-020 specification for Small Body Components.</li> </ol>		

### 9.3 QFN24 Package Marking

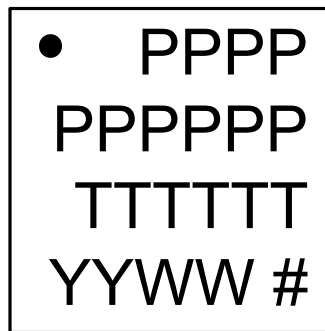


Figure 9.3. QFN24 Package Marking

The package marking consists of:

- P P P P P P P P – The part number designation.
- T T T T T T – A trace or manufacturing code.
- Y Y – The last 2 digits of the assembly year.
- W W – The 2-digit workweek when the device was assembled.
- # – The device revision (A, B, etc.).