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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Active
Core Processor	ARM® Cortex®-M3
Core Size	32-Bit Single-Core
Speed	120MHz
Connectivity	CANbus, I²C, IrDA, LINbus, MMC, SPI, UART/USART, USB OTG
Peripherals	Brown-out Detect/Reset, DMA, I²S, LCD, POR, PWM, WDT
Number of I/O	114
Program Memory Size	512KB (512K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	132K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.6V
Data Converters	A/D 24x12b; D/A 2x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	144-LQFP
Supplier Device Package	144-LQFP (20x20)
Purchase URL	https://www.e-xfl.com/product-detail/stmicroelectronics/stm32f215zet6

3.14 Power supply schemes

- $V_{DD} = 1.8$ to 3.6 V: external power supply for I/Os and the internal regulator (when enabled), provided externally through V_{DD} pins.
- $V_{SSA}, V_{DDA} = 1.8$ to 3.6 V: external analog power supplies for ADC, DAC, Reset blocks, RCs and PLL. V_{DDA} and V_{SSA} must be connected to V_{DD} and V_{SS} , respectively.
- $V_{BAT} = 1.65$ to 3.6 V: power supply for RTC, external clock, 32 kHz oscillator and backup registers (through power switch) when V_{DD} is not present.

Refer to [Figure 17: Power supply scheme](#) for more details.

3.15 Power supply supervisor

The devices have an integrated power-on reset (POR) / power-down reset (PDR) circuitry coupled with a Brownout reset (BOR) circuitry.

At power-on, POR/PDR is always active and ensures proper operation starting from 1.8 V. After the 1.8 V POR threshold level is reached, the option byte loading process starts, either to confirm or modify default BOR threshold levels, or to disable BOR permanently. Three BOR thresholds are available through option bytes.

The device remains in reset mode when V_{DD} is below a specified threshold, $V_{POR/PDR}$ or V_{BOR} , without the need for an external reset circuit.

The devices also feature an embedded programmable voltage detector (PWD) that monitors the V_{DD}/V_{DDA} power supply and compares it to the V_{PWD} threshold. An interrupt can be generated when V_{DD}/V_{DDA} drops below the V_{PWD} threshold and/or when V_{DD}/V_{DDA} is higher than the V_{PWD} threshold. The interrupt service routine can then generate a warning message and/or put the MCU into a safe state. The PWD is enabled by software.

3.16 Voltage regulator

The regulator has four operating modes:

- Regulator ON
 - Main regulator mode (MR)
 - Low-power regulator (LPR)
 - Power-down
- Regulator OFF
 - Regulator OFF/internal reset ON

3.16.1 Regulator ON

The regulator ON modes are activated by default on LQFP packages. On UFBGA176 package, they are activated by connecting REGOFF to V_{SS} .

V_{DD} minimum value is 1.8 V.

Table 4. Timer feature comparison (continued)

Timer type	Timer	Counter resolution	Counter type	Prescaler factor	DMA request generation	Capture/compare channels	Complementary output	Max interface clock	Max timer clock
General purpose	TIM2, TIM5	32-bit	Up, Down, Up/down	Any integer between 1 and 65536	Yes	4	No	30 MHz	60 MHz
	TIM3, TIM4	16-bit	Up, Down, Up/down	Any integer between 1 and 65536	Yes	4	No	30 MHz	60 MHz
Basic	TIM6, TIM7	16-bit	Up	Any integer between 1 and 65536	Yes	0	No	30 MHz	60 MHz
General purpose	TIM9	16-bit	Up	Any integer between 1 and 65536	No	2	No	60 MHz	120 MHz
	TIM10, TIM11	16-bit	Up	Any integer between 1 and 65536	No	1	No	60 MHz	120 MHz
	TIM12	16-bit	Up	Any integer between 1 and 65536	No	2	No	30 MHz	60 MHz
	TIM13, TIM14	16-bit	Up	Any integer between 1 and 65536	No	1	No	30 MHz	60 MHz

3.20.1 Advanced-control timers (TIM1, TIM8)

The advanced-control timers (TIM1, TIM8) can be seen as three-phase PWM generators multiplexed on 6 channels. They have complementary PWM outputs with programmable inserted dead times. They can also be considered as complete general-purpose timers.

Their 4 independent channels can be used for:

- Input capture
- Output compare
- PWM generation (edge- or center-aligned modes)
- One-pulse mode output

If configured as standard 16-bit timers, they have the same features as the general-purpose TIMx timers. If configured as 16-bit PWM generators, they have full modulation capability (0–100%).

The TIM1 and TIM8 counters can be frozen in debug mode. Many of the advanced-control timer features are shared with those of the standard TIMx timers which have the same architecture. The advanced-control timer can therefore work together with the TIMx timers via the Timer Link feature for synchronization or event chaining.

Table 7. STM32F21x pin and ball definitions (continued)

Pins					Pin name (function after reset) ⁽¹⁾	Pin type	I/O structure	Note	Alternate functions	Additional functions
LQFP64	LQFP100	LQFP144	LQFP176	UFBGA176						
22	31	42	52	P3	PA6	I/O	FT	(4)	SPI1_MISO, TIM8_BKIN, TIM13_CH1, DCMI_PIXCLK, TIM3_CH1, TIM1_BKIN, EVENTOUT	ADC12_IN6
23	32	43	53	R3	PA7	I/O	FT	(4)	SPI1_MOSI, TIM8_CH1N, TIM14_CH1, TIM3_CH2, ETH_MII_RX_DV, TIM1_CH1N, ETH_RMII_CRS_DV, EVENTOUT	ADC12_IN7
24	33	44	54	N5	PC4	I/O	FT	(4)	ETH_RMII_RXD0,/ ETH_MII_RXD0, EVENTOUT	ADC12_IN14
25	34	45	55	P5	PC5	I/O	FT	(4)	ETH_RMII_RXD1, ETH_MII_RXD1, EVENTOUT	ADC12_IN15
26	35	46	56	R5	PB0	I/O	FT	(4)	TIM3_CH3, TIM8_CH2N, OTG_HS_ULPI_D1, ETH_MII_RXD2, TIM1_CH2N, EVENTOUT	ADC12_IN8
27	36	47	57	R4	PB1	I/O	FT	(4)	TIM3_CH4, TIM8_CH3N, OTG_HS_ULPI_D2, ETH_MII_RXD3, TIM1_CH3N, EVENTOUT	ADC12_IN9
28	37	48	58	M6	PB2/BOOT1 (PB2)	I/O	FT	-	EVENTOUT	-
-	-	49	59	R6	PF11	I/O	FT	-	DCMI_D12, EVENTOUT	-
-	-	50	60	P6	PF12	I/O	FT	-	FSMC_A6, EVENTOUT	-
-	-	51	61	M8	V _{SS}	S	-	-	-	-
-	-	52	62	N8	V _{DD}	S	-	-	-	-
-	-	53	63	N6	PF13	I/O	FT	-	FSMC_A7, EVENTOUT	-
-	-	54	64	R7	PF14	I/O	FT	-	FSMC_A8, EVENTOUT	-
-	-	55	65	P7	PF15	I/O	FT	-	FSMC_A9, EVENTOUT	-
-	-	56	66	N7	PG0	I/O	FT	-	FSMC_A10, EVENTOUT	-
-	-	57	67	M7	PG1	I/O	FT	-	FSMC_A11, EVENTOUT	-
-	38	58	68	R8	PE7	I/O	FT	-	FSMC_D4, TIM1_ETR, EVENTOUT	-

Table 7. STM32F21x pin and ball definitions (continued)

Pins					Pin name (function after reset) ⁽¹⁾	Pin type	I/O structure	Note	Alternate functions	Additional functions
LQFP64	LQFP100	LQFP144	LQFP176	UFBGA176						
-	-	-	85	M12	PH8	I/O	FT	-	I2C3_SDA, DCMI_HSYNC, EVENTOUT	-
-	-	-	86	M13	PH9	I/O	FT	-	I2C3_SMBA, TIM12_CH2, DCMI_D0, EVENTOUT	-
-	-	-	87	L13	PH10	I/O	FT	-	TIM5_CH1, DCMI_D1, EVENTOUT	-
-	-	-	88	L12	PH11	I/O	FT	-	TIM5_CH2, DCMI_D2, EVENTOUT	-
-	-	-	89	K12	PH12	I/O	FT	-	TIM5_CH3, DCMI_D3, EVENTOUT	-
-	-	-	90	H12	V _{SS}	S	-	-	-	-
-	-	-	91	J12	V _{DD}	S	-	-	-	-
33	51	73	92	P12	PB12	I/O	FT	-	SPI2_NSS,I2S2_WS, I2C2_SMBA, USART3_CK, TIM1_BKIN, CAN2_RX, OTG_HS_ULPI_D5, ETH_RMII_TXD0, ETH_MII_TXD0, OTG_HS_ID, EVENTOUT	-
34	52	74	93	P13	PB13	I/O	FT	-	SPI2_SCK, I2S2_SCK, USART3_CTS, TIM1_CH1N,CAN2_TX, OTG_HS_ULPI_D6, ETH_RMII_TXD1, ETH_MII_TXD1, EVENTOUT	OTG_HS_VBUS
35	53	75	94	R14	PB14	I/O	FT	-	SPI2_MISO, TIM1_CH2N, TIM12_CH1, OTG_HS_DM USART3_RTS, TIM8_CH2N, EVENTOUT	-
36	54	76	95	R15	PB15	I/O	FT	-	SPI2_MOSI, I2S2_SD, TIM1_CH3N, TIM8_CH3N, TIM12_CH2, OTG_HS_DP, RTC_50Hz, EVENTOUT	-
-	55	77	96	P15	PD8	I/O	FT	-	FSMC_D13, USART3_TX, EVENTOUT	-
-	56	78	97	P14	PD9	I/O	FT	-	FSMC_D14, USART3_RX, EVENTOUT	-

Table 7. STM32F21x pin and ball definitions (continued)

Pins					Pin name (function after reset) ⁽¹⁾	Pin type	I/O structure	Note	Alternate functions	Additional functions
LQFP64	LQFP100	LQFP144	LQFP176	UFBGA176						
54	83	116	144	D12	PD2	I/O	FT	-	TIM3_ETR,UART5_RX, SDIO_CMD, DCMI_D11, EVENTOUT	-
-	84	117	145	D11	PD3	I/O	FT	-	FSMC_CLK,USART2_CTS, EVENTOUT	-
-	85	118	146	D10	PD4	I/O	FT	-	FSMC_NOE,USART2_RTS, EVENTOUT	-
-	86	119	147	C11	PD5	I/O	FT	-	FSMC_NWE,USART2_TX, EVENTOUT	-
-	-	120	148	D8	V _{SS}	S		-	-	-
-	-	121	149	C8	V _{DD}	S		-	-	-
-	87	122	150	B11	PD6	I/O	FT	-	FSMC_NWAIT,USART2_RX, EVENTOUT	-
-	88	123	151	A11	PD7	I/O	FT	-	USART2_CK,FSMC_NE1, FSMC_NCE2, EVENTOUT	-
-	-	124	152	C10	PG9	I/O	FT	-	USART6_RX, FSMC_NE2,FSMC_NCE3, EVENTOUT	-
-	-	125	153	B10	PG10	I/O	FT	-	FSMC_NCE4_1, FSMC_NE3, EVENTOUT	-
-	-	126	154	B9	PG11	I/O	FT	-	FSMC_NCE4_2, ETH_MII_TX_EN, ETH_RMII_TX_EN, EVENTOUT	-
-	-	127	155	B8	PG12	I/O	FT	-	FSMC_NE4, USART6_RTS, EVENTOUT	-
-	-	128	156	A8	PG13	I/O	FT	-	FSMC_A24, USART6_CTS, ETH_MII_TXD0, ETH_RMII_TXD0, EVENTOUT	-
-	-	129	157	A7	PG14	I/O	FT	-	FSMC_A25, USART6_TX, ETH_MII_TXD1, ETH_RMII_TXD1, EVENTOUT	-
-	-	130	158	D7	V _{SS}	S	-	-	-	-
-	-	131	159	C7	V _{DD}	S	-	-	-	-

Table 9. Alternate function mapping (continued)

Port	AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	AF014	AF15
	SYS	TIM1/2	TIM3/4/5	TIM8/9/10/11	I2C1/I2C2/I2C3	SPI1/SPI2/I2S2	SPI3/I2S3	USART1/2/3	UART4/5/ USART6	CAN1/CAN2/ TIM12/13/14	OTG_FS/ OTG_HS	ETH	FSMC/SDIO/ OTG_HS	DCMI		
Port F	PF0	-	-	-	-	I2C2_SDA	-	-	-	-	-	-	FSMC_A0	-	-	EVENTOUT
	PF1	-	-	-	-	I2C2_SCL	-	-	-	-	-	-	FSMC_A1	-	-	EVENTOUT
	PF2	-	-	-	-	I2C2_SMBA	-	-	-	-	-	-	FSMC_A2	-	-	EVENTOUT
	PF3	-	-	-	-	-	-	-	-	-	-	-	FSMC_A3	-	-	EVENTOUT
	PF4	-	-	-	-	-	-	-	-	-	-	-	FSMC_A4	-	-	EVENTOUT
	PF5	-	-	-	-	-	-	-	-	-	-	-	FSMC_A5	-	-	EVENTOUT
	PF6	-	-	-	TIM10_CH1	-	-	-	-	-	-	-	FSMC_NIORD	-	-	EVENTOUT
	PF7	-	-	-	TIM11_CH1	-	-	-	-	-	-	-	FSMC_NREG	-	-	EVENTOUT
	PF8	-	-	-	-	-	-	-	-	TIM13_CH1	-	-	FSMC_NIOWR	-	-	EVENTOUT
	PF9	-	-	-	-	-	-	-	-	TIM14_CH1	-	-	FSMC_CD	-	-	EVENTOUT
	PF10	-	-	-	-	-	-	-	-	-	-	-	FSMC_INTR	-	-	EVENTOUT
	PF11	-	-	-	-	-	-	-	-	-	-	-	DCMI_D12	-	-	EVENTOUT
	PF12	-	-	-	-	-	-	-	-	-	-	-	FSMC_A6	-	-	EVENTOUT
	PF13	-	-	-	-	-	-	-	-	-	-	-	FSMC_A7	-	-	EVENTOUT
	PF14	-	-	-	-	-	-	-	-	-	-	-	FSMC_A8	-	-	EVENTOUT
	PF15	-	-	-	-	-	-	-	-	-	-	-	FSMC_A9	-	-	EVENTOUT
Port G	PG0	-	-	-	-	-	-	-	-	-	-	-	FSMC_A10	-	-	EVENTOUT
	PG1	-	-	-	-	-	-	-	-	-	-	-	FSMC_A11	-	-	EVENTOUT
	PG2	-	-	-	-	-	-	-	-	-	-	-	FSMC_A12	-	-	EVENTOUT
	PG3	-	-	-	-	-	-	-	-	-	-	-	FSMC_A13	-	-	EVENTOUT
	PG4	-	-	-	-	-	-	-	-	-	-	-	FSMC_A14	-	-	EVENTOUT
	PG5	-	-	-	-	-	-	-	-	-	-	-	FSMC_A15	-	-	EVENTOUT
	PG6	-	-	-	-	-	-	-	-	-	-	-	FSMC_INT2	-	-	EVENTOUT
	PG7	-	-	-	-	-	-	-	-	USART6_CK	-	-	FSMC_INT3	-	-	EVENTOUT
	PG8	-	-	-	-	-	-	-	-	USART6 RTS	-	-	ETH_PPS_OUT	-	-	EVENTOUT
	PG9	-	-	-	-	-	-	-	-	USART6_RX	-	-	FSMC_NE2/ FSMC_NCE3	-	-	EVENTOUT
	PG10	-	-	-	-	-	-	-	-	-	-	-	FSMC_NCE4_1/ FSMC_NE3	-	-	EVENTOUT
	PG11	-	-	-	-	-	-	-	-	-	-	-	ETH_MII_TX_EN ETH_RMII_TXD0	FSMC_NCE4_2	-	EVENTOUT
	PG12	-	-	-	-	-	-	-	-	USART6 RTS	-	-	-	FSMC_NE4	-	EVENTOUT
	PG13	-	-	-	-	-	-	-	-	UART6_CTS	-	-	ETH_MII_TXD0 ETH_RMII_TXD0	FSMC_A24	-	EVENTOUT
	PG14	-	-	-	-	-	-	-	-	USART6 TX	-	-	ETH_MII_TXD1 ETH_RMII_TXD1	FSMC_A25	-	EVENTOUT
	PG15	-	-	-	-	-	-	-	-	USART6 CTS	-	-	-	DCMI_D13	-	EVENTOUT

Figure 21. Typical current consumption vs. temperature, Run mode, code with data processing running from RAM, and peripherals ON

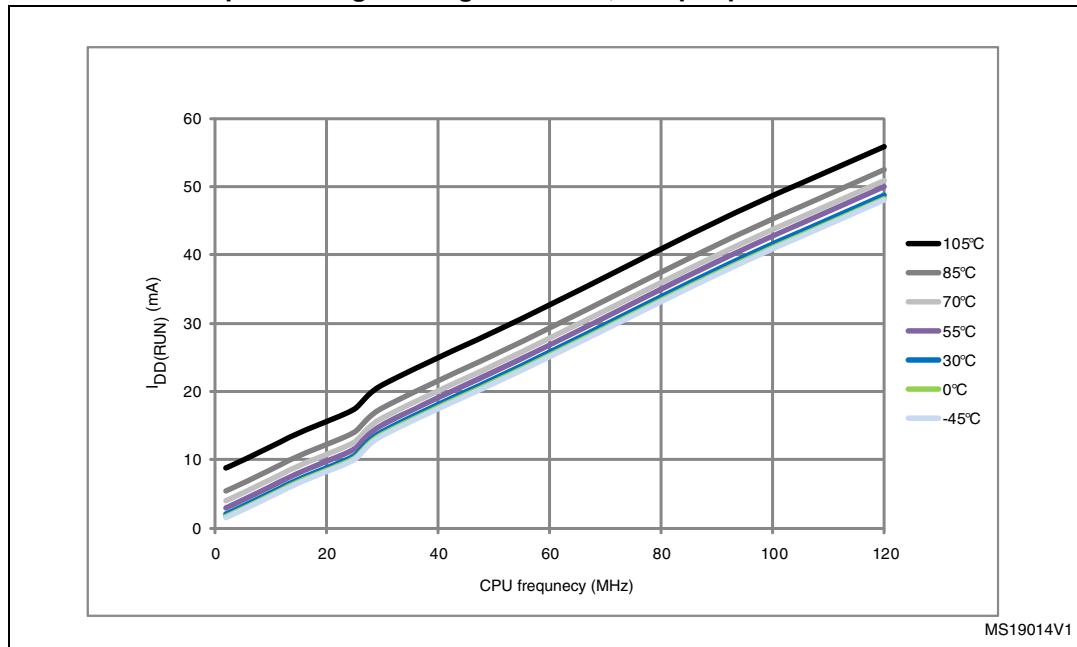
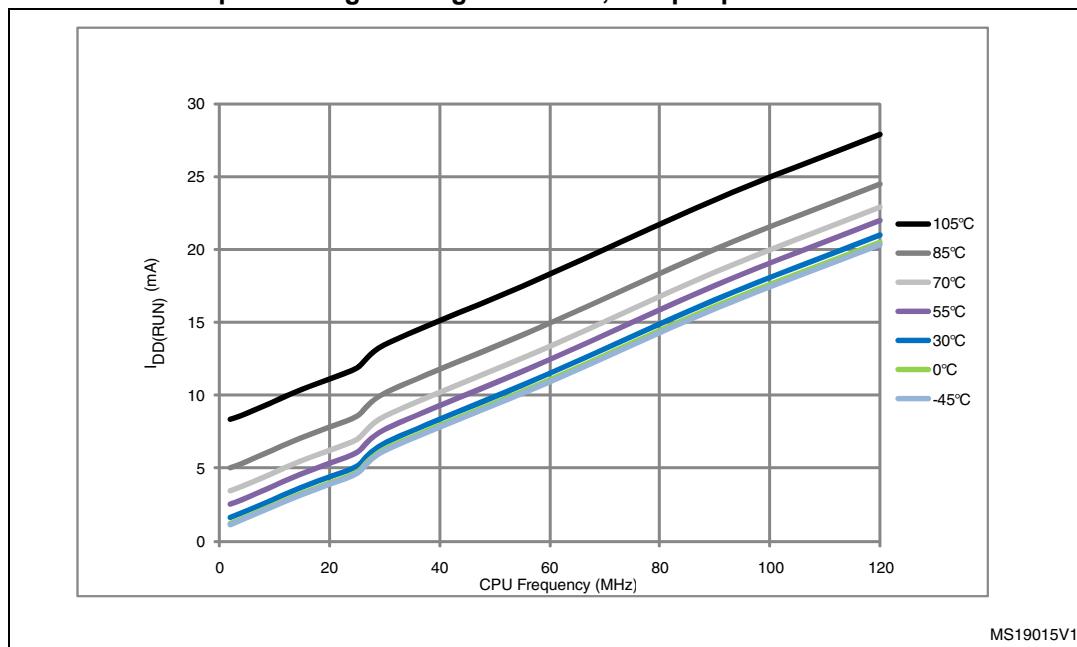


Figure 22. Typical current consumption vs. temperature, Run mode, code with data processing running from RAM, and peripherals OFF



Static latch-up

Two complementary static tests are required on six parts to assess the latch-up performance:

- A supply overvoltage is applied to each power supply pin
- A current injection is applied to each input, output and configurable I/O pin

These tests are compliant with EIA/JESD 78A IC latch-up standard.

Table 43. Electrical sensitivities

Symbol	Parameter	Conditions	Class
LU	Static latch-up class	$T_A = +105^\circ\text{C}$ conforming to JESD78A	II level A

6.3.15 I/O current injection characteristics

As a general rule, current injection to the I/O pins, due to external voltage below V_{SS} or above V_{DD} (for standard, 3 V-capable I/O pins) should be avoided during normal product operation. However, in order to give an indication of the robustness of the microcontroller in cases when abnormal injection accidentally happens, susceptibility tests are performed on a sample basis during device characterization.

Functional susceptibility to I/O current injection

While a simple application is executed on the device, the device is stressed by injecting current into the I/O pins programmed in floating input mode. While current is injected into the I/O pin, one at a time, the device is checked for functional failures.

The failure is indicated by an out of range parameter: ADC error above a certain limit (>5 LSB TUE), out of spec current injection on adjacent pins or other functional failure (for example reset, oscillator frequency deviation).

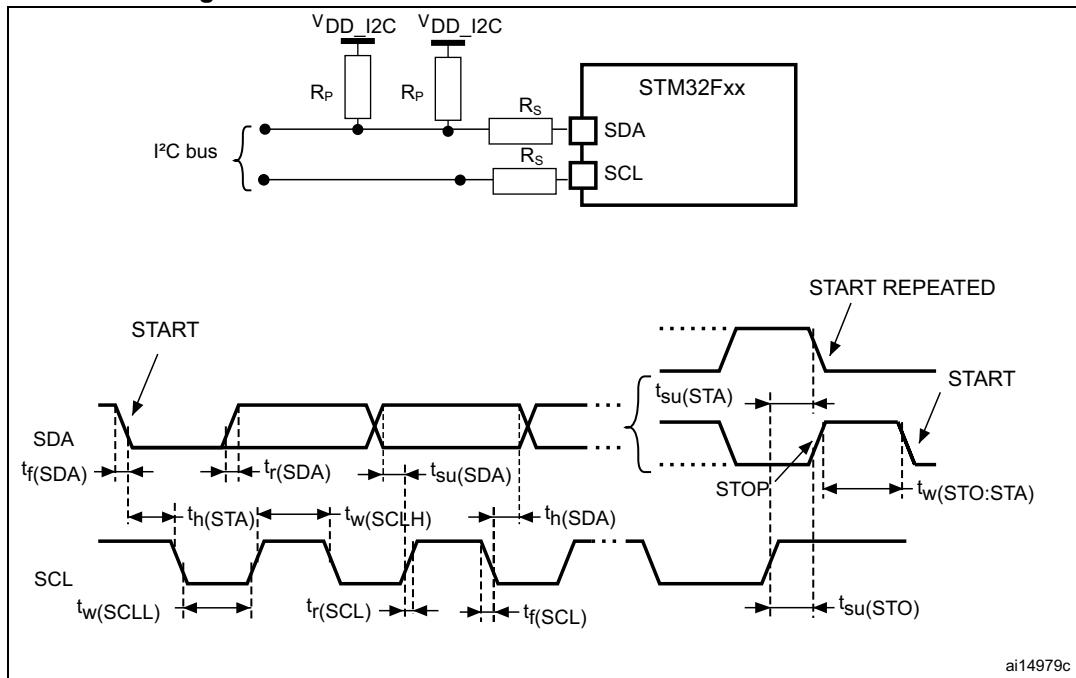
The test results are given in [Table 44](#).

Table 44. I/O current injection susceptibility⁽¹⁾

Symbol	Description	Functional susceptibility		Unit
		Negative injection	Positive injection	
I_{INJ}	Injected current on BOOT0 pin	-0	NA	mA
	Injected current on NRST pin	-0	NA	
	Injected current on TTa pins: PA4 and PA5	-0	+5	
	Injected current on all FT pins	-5	NA	

1. NA stands for "not applicable".

Note: It is recommended to add a Schottky diode (pin to ground) to analog pins which may potentially inject negative currents.

Figure 39. I²C bus AC waveforms and measurement circuit

1. R_S = series protection resistor.
2. R_P = external pull-up resistor.
3. V_{DD_I2C} is the I²C bus power supply.

Table 52. SCL frequency ($f_{PCLK1} = 30 \text{ MHz.}, V_{DD} = 3.3 \text{ V}$)⁽¹⁾⁽²⁾

$f_{SCL} (\text{kHz})$	I2C_CCR value
	$R_P = 4.7 \text{ k}\Omega$
400	0x8019
300	0x8021
200	0x8032
100	0x0096
50	0x012C
20	0x02EE

1. R_P = External pull-up resistance, f_{SCL} = I²C speed,
2. For speeds around 200 kHz, the tolerance on the achieved speed is of $\pm 5\%$. For other speed ranges, the tolerance on the achieved speed $\pm 2\%$. These variations depend on the accuracy of the external components used to design the application.

Table 67. DAC characteristics (continued)

Symbol	Parameter	Min	Typ	Max	Unit	Comments
DAC_OUT_min ⁽¹⁾	Lower DAC_OUT voltage with buffer OFF	-	0.5	-	mV	
DAC_OUT_max ⁽¹⁾	Higher DAC_OUT voltage with buffer OFF	-	-	$V_{REF+} - 1LSB$	V	It gives the maximum output excursion of the DAC.
$I_{VREF+}^{(3)}$	DAC DC V_{REF} current consumption in quiescent mode (Standby mode)	-	170	240	μA	With no load, worst code (0x800) at $V_{REF+} = 3.6$ V in terms of DC consumption on the inputs
		-	50	75		With no load, worst code (0xF1C) at $V_{REF+} = 3.6$ V in terms of DC consumption on the inputs
$I_{DDA}^{(3)}$	DAC DC V_{DDA} current consumption in quiescent mode ⁽²⁾	-	280	380	μA	With no load, middle code (0x800) on the inputs
		-	475	625	μA	With no load, worst code (0xF1C) at $V_{REF+} = 3.6$ V in terms of DC consumption on the inputs
DNL ⁽³⁾	Differential non linearity Difference between two consecutive code-1LSB)	-	-	± 0.5	LSB	Given for the DAC in 10-bit configuration.
		-	-	± 2	LSB	Given for the DAC in 12-bit configuration.
INL ⁽³⁾	Integral non linearity (difference between measured value at Code i and the value at Code i on a line drawn between Code 0 and last Code 1023)	-	-	± 1	LSB	Given for the DAC in 10-bit configuration.
		-	-	± 4	LSB	Given for the DAC in 12-bit configuration.
Offset ⁽³⁾	Offset error (difference between measured value at Code (0x800) and the ideal value = $V_{REF+}/2$)	-	-	± 10	mV	-
		-	-	± 3	LSB	Given for the DAC in 10-bit at $V_{REF+} = 3.6$ V
		-	-	± 12	LSB	Given for the DAC in 12-bit at $V_{REF+} = 3.6$ V
Gain error ⁽³⁾	Gain error	-	-	± 0.5	%	Given for the DAC in 12-bit configuration
$t_{SETTLING}^{(3)}$	Settling time (full scale: for a 10-bit input code transition between the lowest and the highest input codes when DAC_OUT reaches final value ± 4 LSB	-	3	6	μs	$C_{LOAD} \leq 50$ pF, $R_{LOAD} \geq 5$ k Ω
THD ⁽³⁾	Total Harmonic Distortion Buffer ON	-	-	-	dB	$C_{LOAD} \leq 50$ pF, $R_{LOAD} \geq 5$ k Ω

Table 74. Asynchronous multiplexed PSRAM/NOR write timings⁽¹⁾⁽²⁾ (continued)

Symbol	Parameter	Min	Max	Unit
$t_{h(A_NWE)}$	Address hold time after FSMC_NWE high	$T_{HCLK}-0.5$	-	ns
$t_{h(BL_NWE)}$	FSMC_BL hold time after FSMC_NWE high	$T_{HCLK}-1$	-	ns
$t_{v(BL_NE)}$	FSMC_NEx low to FSMC_BL valid	-	0.5	ns
$t_{v(Data_NADV)}$	FSMC_NADV high to Data valid	-	$T_{HCLK}+2$	ns
$t_{h(Data_NWE)}$	Data hold time after FSMC_NWE high	$T_{HCLK}-0.5$	-	ns

1. $C_L = 30 \text{ pF}$.

2. Guaranteed by characterization results, not tested in production.

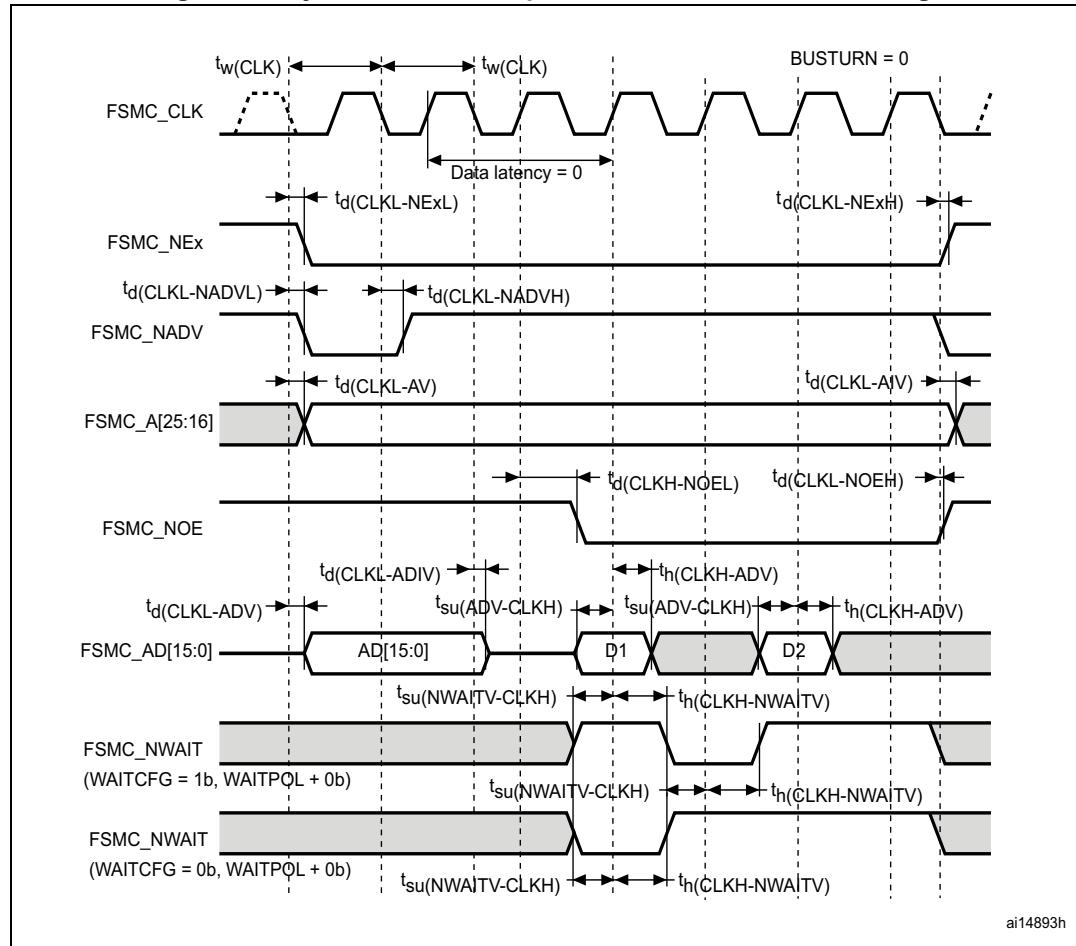
Synchronous waveforms and timings

Figure 59 through *Figure 62* represent synchronous waveforms, and *Table 76* through *Table 78* provide the corresponding timings. The results shown in these tables are obtained with the following FSMC configuration:

- `BurstAccessMode = FSMC_BurstAccessMode_Enable;`
- `MemoryType = FSMC_MemoryType_CRAM;`
- `WriteBurst = FSMC_WriteBurst_Enable;`
- `CLKDivision = 1;` (0 is not supported, see the STM32F20xxx/21xxx reference manual)
- `DataLatency = 1` for NOR Flash; `DataLatency = 0` for PSRAM

In all timing tables, the T_{HCLK} is the HCLK clock period.

Figure 59. Synchronous multiplexed NOR/PSRAM read timings

Table 75. Synchronous multiplexed NOR/PSRAM read timings⁽¹⁾⁽²⁾

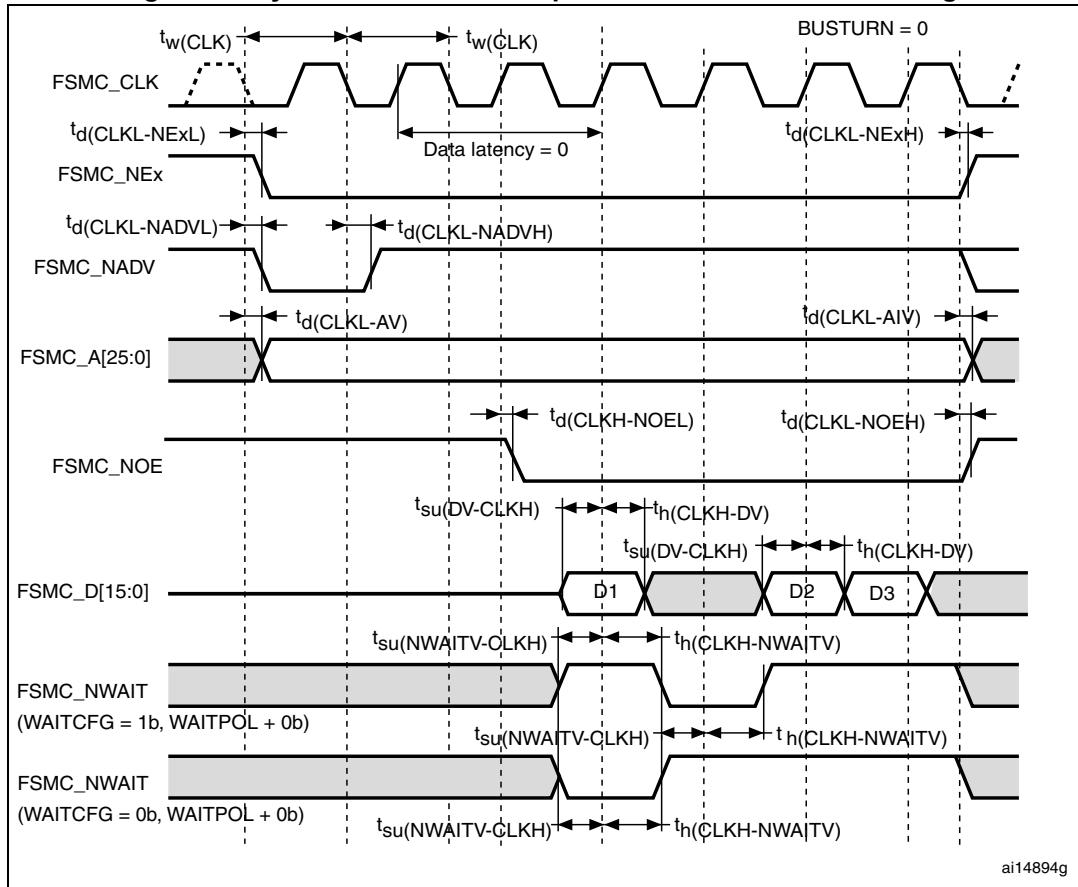
Symbol	Parameter	Min	Max	Unit
$t_w(\text{CLK})$	FSMC_CLK period	$2T_{\text{HCLK}}$	-	ns
$t_d(\text{CLKL-NExL})$	FSMC_CLK low to FSMC_NEx low ($x=0..2$)	-	0	ns
$t_d(\text{CLKL-NExH})$	FSMC_CLK low to FSMC_NEx high ($x=0..2$)	1	-	ns
$t_d(\text{CLKL-NADVL})$	FSMC_CLK low to FSMC_NADV low	-	1.5	ns
$t_d(\text{CLKL-NADVH})$	FSMC_CLK low to FSMC_NADV high	2.5	-	ns
$t_d(\text{CLKL-AV})$	FSMC_CLK low to FSMC_Ax valid ($x=16..25$)	-	0	ns
$t_d(\text{CLKL-AIV})$	FSMC_CLK low to FSMC_Ax invalid ($x=16..25$)	0	-	ns
$t_d(\text{CLKH-NOEL})$	FSMC_CLK high to FSMC_NOE low	-	1	ns
$t_d(\text{CLKL-NOEH})$	FSMC_CLK low to FSMC_NOE high	1	-	ns
$t_d(\text{CLKL-ADV})$	FSMC_CLK low to FSMC_AD[15:0] valid	-	3	ns
$t_d(\text{CLKL-ADIV})$	FSMC_CLK low to FSMC_AD[15:0] invalid	0	-	ns

Table 76. Synchronous multiplexed PSRAM write timings⁽¹⁾⁽²⁾ (continued)

Symbol	Parameter	Min	Max	Unit
$t_d(CLKL-NWEL)$	FSMC_CLK low to FSMC_NWE low	-	1	ns
$t_d(CLKL-NWEH)$	FSMC_CLK low to FSMC_NWE high	0	-	ns
$t_d(CLKL-ADIV)$	FSMC_CLK low to FSMC_AD[15:0] invalid	0	-	ns
$t_d(CLKL-DATA)$	FSMC_A/D[15:0] valid data after FSMC_CLK low	-	2	ns
$t_d(CLKL-NBLH)$	FSMC_CLK low to FSMC_NBL high	0.5	-	ns

1. $C_L = 30 \text{ pF}$.

2. Guaranteed by characterization results, not tested in production.

Figure 61. Synchronous non-multiplexed NOR/PSRAM read timings**Table 77. Synchronous non-multiplexed NOR/PSRAM read timings⁽¹⁾⁽²⁾**

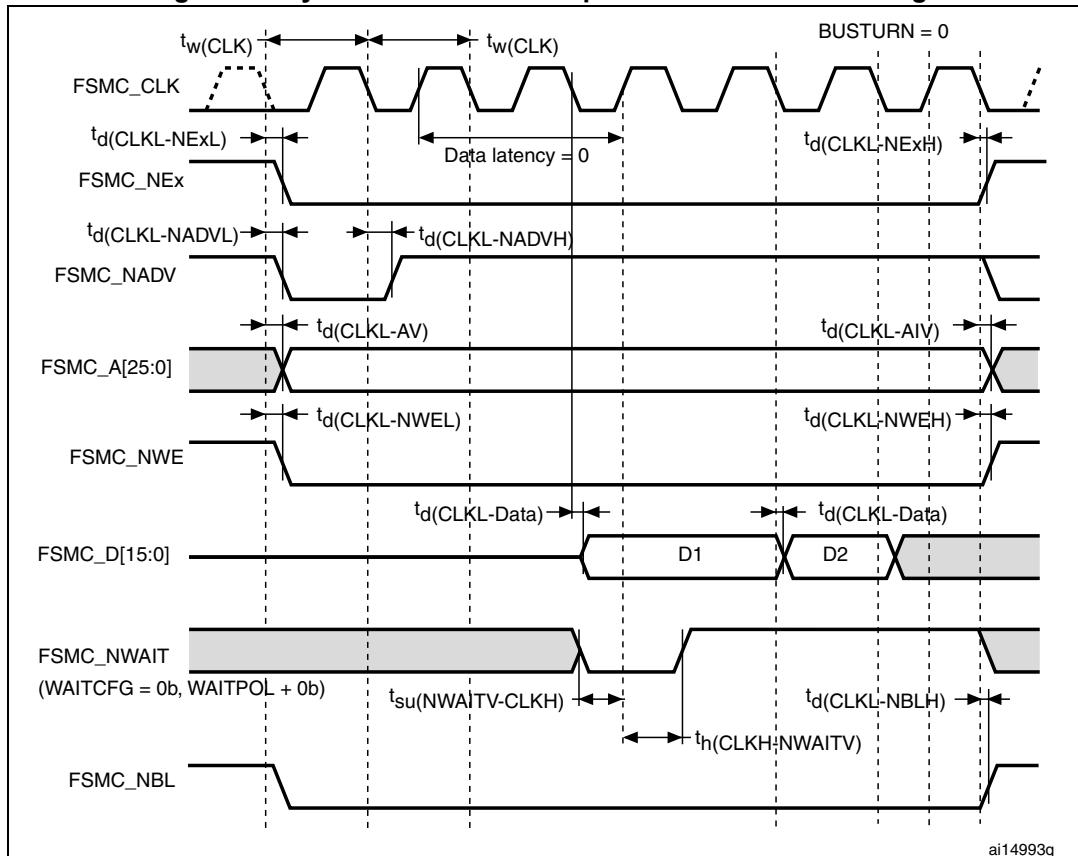
Symbol	Parameter	Min	Max	Unit
$t_w(CLK)$	FSMC_CLK period	$2T_{HCLK}$	-	ns
$t_d(CLKL-NExL)$	FSMC_CLK low to FSMC_NEx low ($x=0..2$)	-	0	ns
$t_d(CLKL-NExH)$	FSMC_CLK low to FSMC_NEx high ($x=0..2$)	1	-	ns
$t_d(CLKL-NADV)$	FSMC_CLK low to FSMC_NADV low	-	2.5	ns

Table 77. Synchronous non-multiplexed NOR/PSRAM read timings⁽¹⁾⁽²⁾ (continued)

Symbol	Parameter	Min	Max	Unit
$t_d(CLKL-NADVH)$	FSMC_CLK low to FSMC_NADV high	4	-	ns
$t_d(CLKL-AV)$	FSMC_CLK low to FSMC_Ax valid (x=16...25)	-	0	ns
$t_d(CLKL-AIV)$	FSMC_CLK low to FSMC_Ax invalid (x=16...25)	3	-	ns
$t_d(CLKH-NOEL)$	FSMC_CLK high to FSMC_NOE low	-	1	ns
$t_d(CLKL-NOEH)$	FSMC_CLK low to FSMC_NOE high	1.5	-	ns
$t_{su}(DV-CLKH)$	FSMC_D[15:0] valid data before FSMC_CLK high	8	-	ns
$t_h(CLKH-DV)$	FSMC_D[15:0] valid data after FSMC_CLK high	0	-	ns

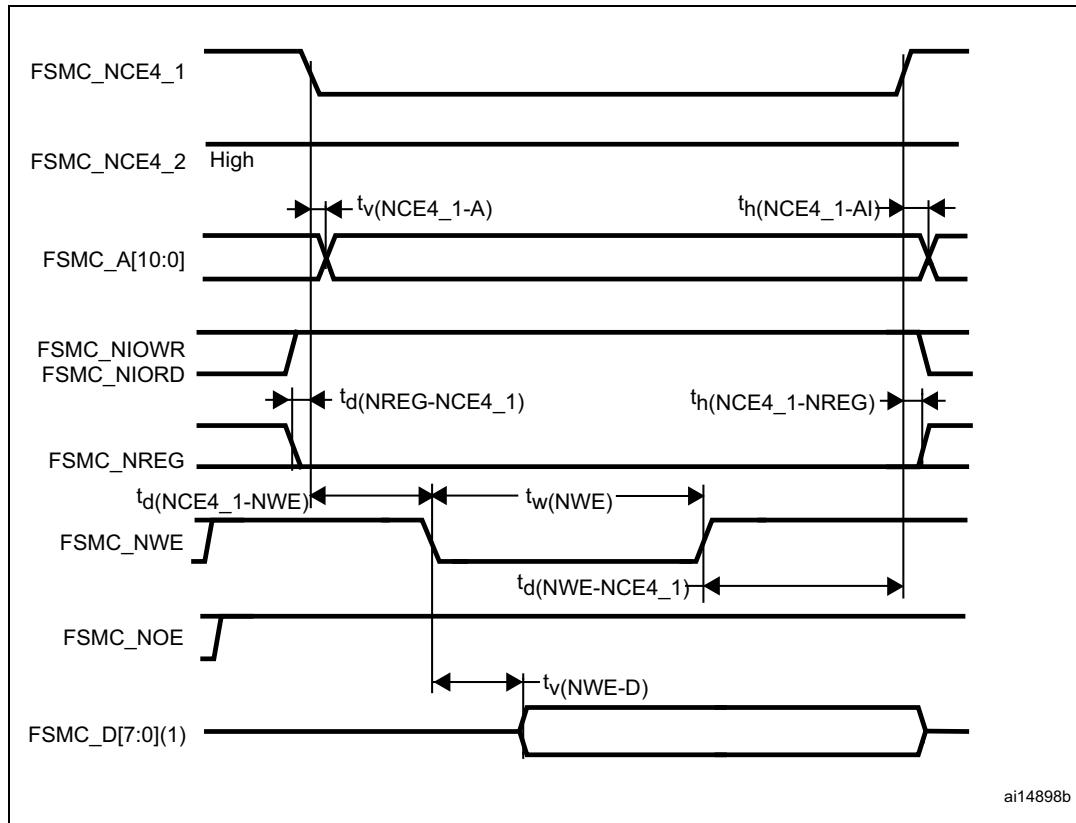
1. $C_L = 30 \text{ pF}$.

2. Guaranteed by characterization results, not tested in production.

Figure 62. Synchronous non-multiplexed PSRAM write timings**Table 78. Synchronous non-multiplexed PSRAM write timings⁽¹⁾⁽²⁾**

Symbol	Parameter	Min	Max	Unit
$t_w(CLK)$	FSMC_CLK period	$2T_{HCLK}-1$	-	ns
$t_d(CLKL-NExL)$	FSMC_CLK low to FSMC_NEx low (x=0..2)	-	1	ns
$t_d(CLKL-NExH)$	FSMC_CLK low to FSMC_NEx high (x= 0..2)	1	-	ns

Figure 66. PC Card/CompactFlash controller waveforms for attribute memory write access



1. Only data bits 0...7 are driven (bits 8...15 remains Hi-Z).

Figure 67. PC Card/CompactFlash controller waveforms for I/O space read access

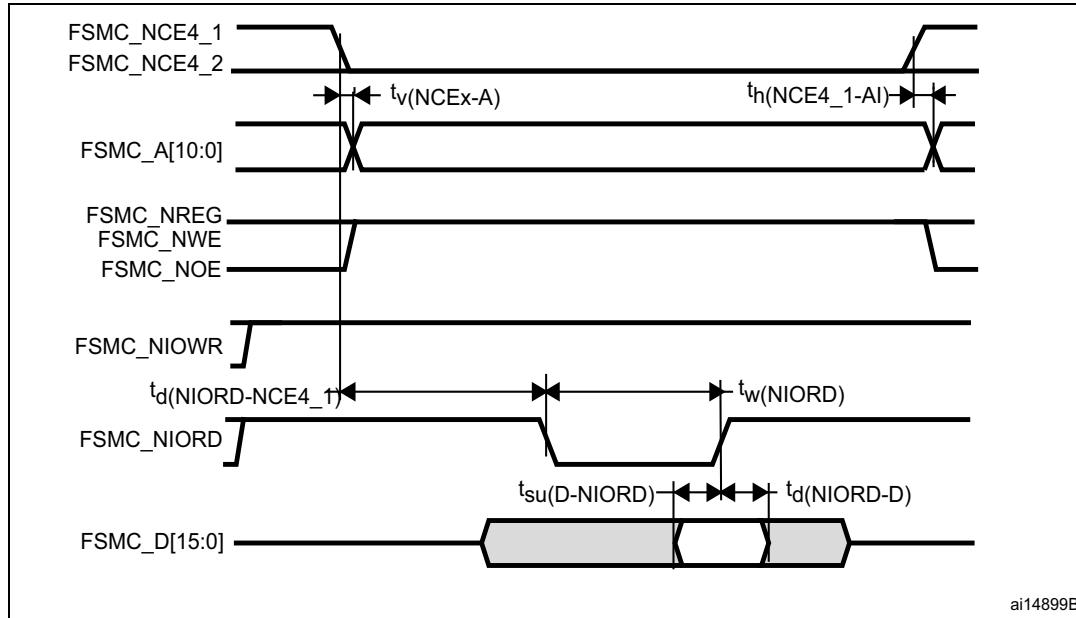
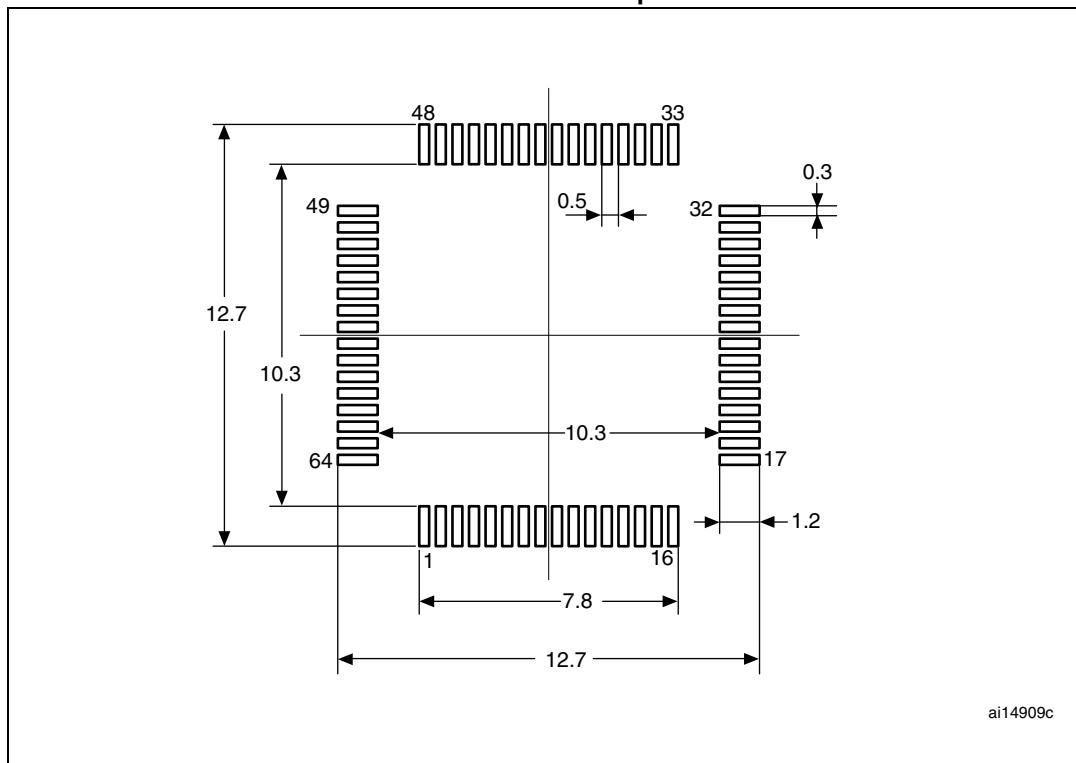


Table 86. LQFP64 - 64-pin, 10 x 10 mm low-profile quad flat package mechanical data (continued)

Symbol	millimeters			inches ⁽¹⁾		
	Min	Typ	Max	Min	Typ	Max
c	0.090	-	0.200	0.0035	-	0.0079
D	-	12.000	-	-	0.4724	-
D1	-	10.000	-	-	0.3937	-
D3	-	7.500	-	-	0.2953	-
E	-	12.000	-	-	0.4724	-
E1	-	10.000	-	-	0.3937	-
E3	-	7.500	-	-	0.2953	-
e	-	0.500	-	-	0.0197	-
K	0°	3.5°	7°	0°	3.5°	7°
L	0.450	0.600	0.750	0.0177	0.0236	0.0295
L1	-	1.000	-	-	0.0394	-
ccc	-	-	0.080	-	-	0.0031

1. Values in inches are converted from mm and rounded to 4 decimal digits.

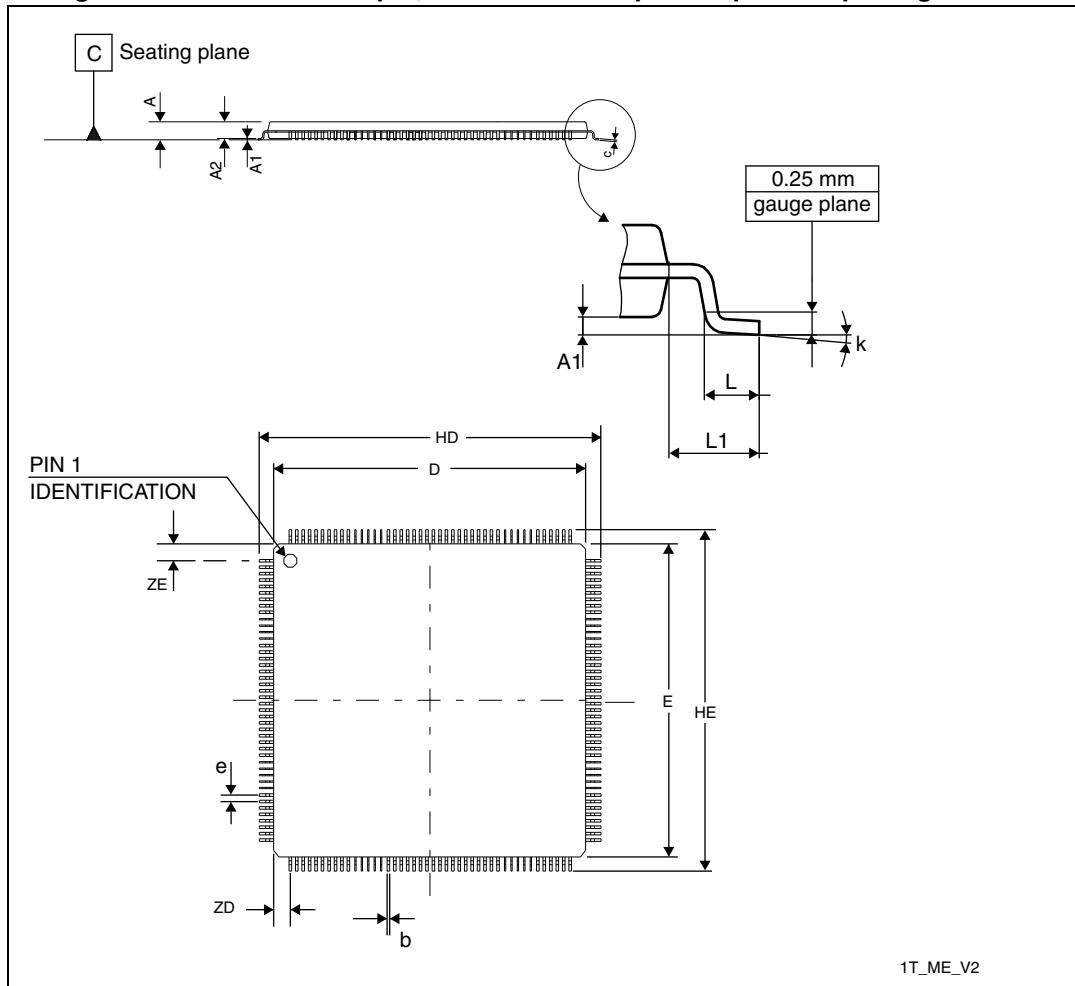
Figure 76. LQFP64 - 64-pin, 10 x 10 mm low-profile quad flat package recommended footprint



1. Dimensions are expressed in millimeters.

7.4 LQFP176 package information

Figure 83. LQFP176 - 176-pin, 24 x 24 mm low profile quad flat package outline

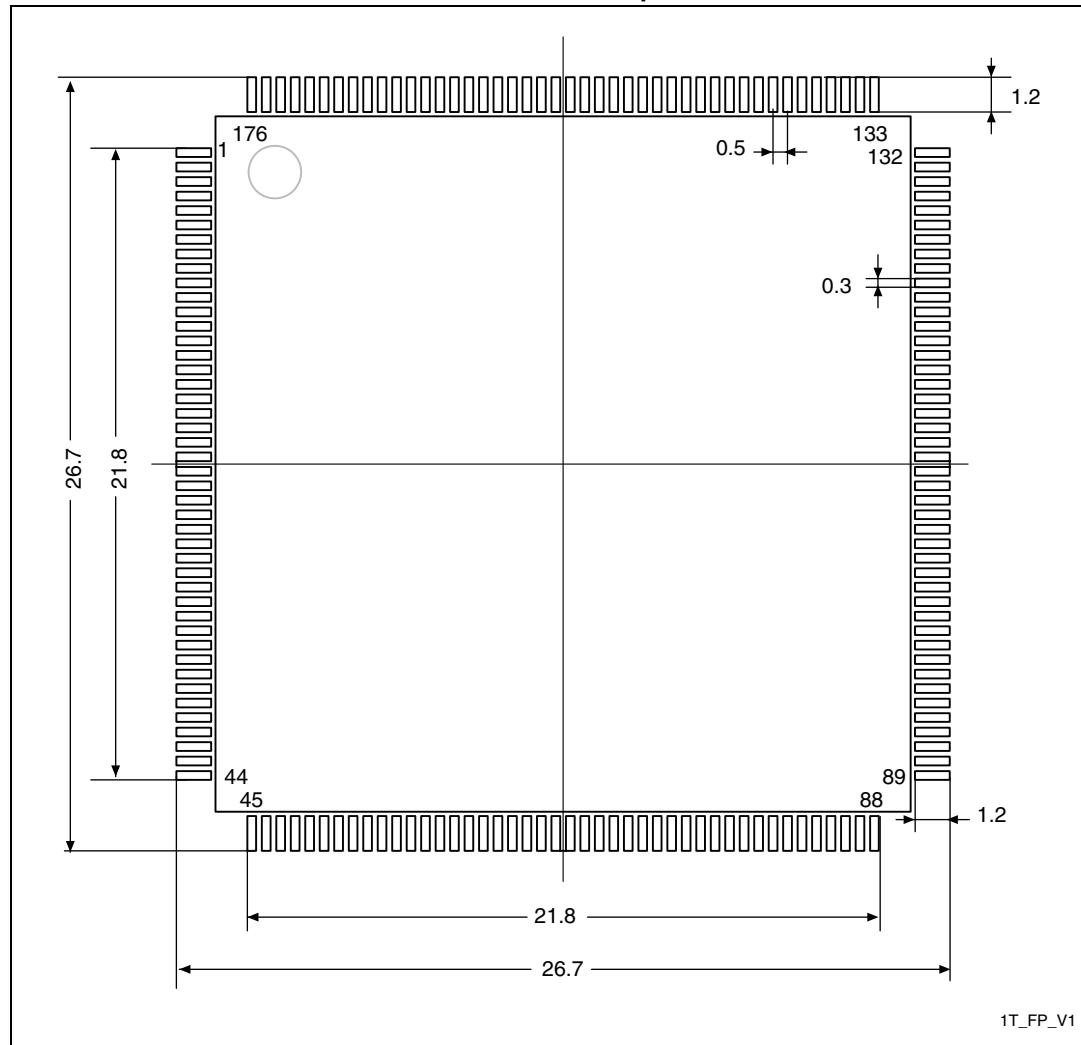


1. Drawing is not to scale.

Table 89. LQFP176 - 176-pin, 24 x 24 mm low profile quad flat package mechanical data

Symbol	Dimensions					
	millimeters			inches ⁽¹⁾		
	Min	Typ	Max	Min	Typ	Max
A	-	-	1.600	-	-	0.0630
A1	0.050	-	0.150	0.0020	-	0.0059
A2	1.350	-	1.450	0.0531	-	0.0571
b	0.170	-	0.270	0.0067	-	0.0106
c	0.090	-	0.200	0.0035	-	0.0079
D	23.900	-	24.100	0.9409	-	0.9488

Figure 84. LQFP176 - 176-pin, 24 x 24 mm low profile quad flat package recommended footprint



1. Dimensions are expressed in millimeters.

7.6 Thermal characteristics

The maximum chip-junction temperature, T_J max, in degrees Celsius, may be calculated using the following equation:

$$T_J \text{ max} = T_A \text{ max} + (P_D \text{ max} \times \Theta_{JA})$$

Where:

- T_A max is the maximum ambient temperature in °C,
- Θ_{JA} is the package junction-to-ambient thermal resistance, in °C/W,
- P_D max is the sum of P_{INT} max and $P_{I/O}$ max (P_D max = P_{INT} max + $P_{I/O}$ max),
- P_{INT} max is the product of I_{DD} and V_{DD} , expressed in Watts. This is the maximum chip internal power.

$P_{I/O}$ max represents the maximum power dissipation on output pins where:

$$P_{I/O} \text{ max} = \sum (V_{OL} \times I_{OL}) + \sum ((V_{DD} - V_{OH}) \times I_{OH}),$$

taking into account the actual V_{OL} / I_{OL} and V_{OH} / I_{OH} of the I/Os at low and high level in the application.

Table 92. Package thermal characteristics

Symbol	Parameter	Value	Unit
Θ_{JA}	Thermal resistance junction-ambient LQFP 64 - 10 × 10 mm / 0.5 mm pitch	45	°C/W
	Thermal resistance junction-ambient LQFP100 - 14 × 14 mm / 0.5 mm pitch	46	
	Thermal resistance junction-ambient LQFP144 - 20 × 20 mm / 0.5 mm pitch	40	
	Thermal resistance junction-ambient LQFP176 - 24 × 24 mm / 0.5 mm pitch	38	
	Thermal resistance junction-ambient UFBGA176 - 10× 10 mm / 0.5 mm pitch	39	

Reference document

JESD51-2 Integrated Circuits Thermal Test Method Environment Conditions - Natural Convection (Still Air). Available from www.jedec.org.

Table 94. Document revision history (continued)

Date	Revision	Changes
29-Oct-2012	8 (continued)	<p>Added Figure 84: LQFP176 recommended footprint.</p> <p>Added Note 2 below Figure 86: Regulator OFF/internal reset ON.</p> <p>Updated device subfamily in Table 93: Ordering information scheme.</p> <p>Remove reference to note 2 for USB IOTG FS in Table 93: Main applications versus package for STM32F2xxx microcontrollers.</p>
04-Nov-2013	9	<p>Updated Section 3.14: Power supply schemes, Section 3.15: Power supply supervisor, Section 3.16.1: Regulator ON and Section 3.16.2: Regulator OFF. Added Section 3.16.3: Regulator ON/OFF and internal reset ON/OFF availability.</p> <p>Restructured RTC features and added reference clock detection in Section 3.17: Real-time clock (RTC), backup SRAM and backup registers.</p> <p>Added note indicating the package view below Figure 9: STM32F21x LQFP64 pinout, Figure 10: STM32F21x LQFP100 pinout, Figure 11: STM32F21x LQFP144 pinout, and Figure 12: STM32F21x LQFP176 pinout.</p> <p>Added Table 6: Legend/abbreviations used in the pinout table.</p> <p>Table 7: STM32F21x pin and ball definitions: content reformatted, removed indexes on V_{SS} and V_{DD}, updated PA4, PA5, PA6, PC4, BOOT0; replaced DCMI_12 by DCMI_D12, ETH_MII_RX_D0 by ETH_MII_RXD0, ETH_MII_RX_D1 by ETH_MII_RXD1, ETH_RMII_RX_D0 by ETH_RMII_RXD0, and ETH_RMII_RX_D1 by ETH_RMII_RXD1 in .</p> <p>Table 9: Alternate function mapping: replaced FSMC_BLN1 by FSMC_NBL1, added EVENTOUT as AF15 alternated function for PC13, PC14, PC15, PH0, PH1, and PI8.</p> <p>Updated Figure 15: Pin loading conditions and Figure 16: Pin input voltage.</p> <p>Added V_{IN} in Table 13: General operating conditions.</p> <p>Removed note applying to V_{POR/PDR} minimum value in Table 18: Embedded reset and power control block characteristics.</p> <p>Updated notes related to C_{L1} and C_{L2} in Section : Low-speed external clock generated from a crystal/ceramic resonator.</p> <p>Updated conditions in Table 40: EMS characteristics. Updated Table 41: EMI characteristics. Updated V_{IL}, V_{IH} and V_{Hys} in Table 45: I/O static characteristics. Added Section : Output driving current and updated Figure 37: I/O AC characteristics definition.</p> <p>Updated V_{IL(NRST)} and V_{IH(NRST)} in Table 48: NRST pin characteristics, updated Figure 37: I/O AC characteristics definition.</p> <p>Removed tests conditions in Section : I2C interface characteristics.</p> <p>Updated Table 51: I2C characteristics and Figure 39: I2C bus AC waveforms and measurement circuit.</p> <p>Updated I_{VREF+} and I_{VDDA} in Table 65: ADC characteristics.</p> <p>Updated Offset comments in Table 67: DAC characteristics.</p> <p>Updated minimum t_{h(CLKH-DV)} value in Table 77: Synchronous non-multiplexed NOR/PSRAM read timings.</p>