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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded - Microcontrollers</u>"

Details	
Product Status	Discontinued at Digi-Key
Core Processor	CIP-51 8051
Core Size	8-Bit
Speed	25MHz
Connectivity	EBI/EMI, I ² C, SMBus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	16
Program Memory Size	16KB (16K x 8)
Program Memory Type	FLASH
EEPROM Size	•
RAM Size	4.25K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.6V
Data Converters	A/D 15x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	24-WFQFN Exposed Pad
Supplier Device Package	24-QFN (4x4)
Purchase URL	https://www.e-xfl.com/product-detail/silicon-labs/efm8sb20f16g-a-qfn24r

3. System Overview

3.1 Introduction

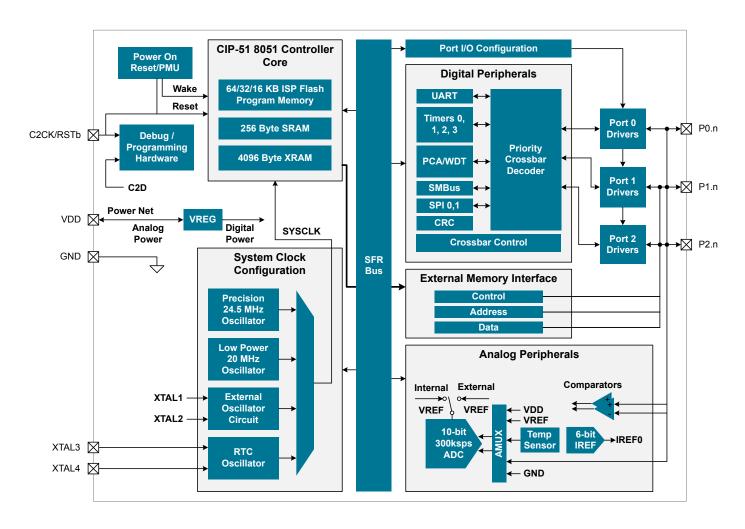


Figure 3.1. Detailed EFM8SB2 Block Diagram

3.5 Counters/Timers and PWM

Real Time Clock (RTC0)

The RTC is an ultra low power, 36 hour 32-bit independent time-keeping Real Time Clock with alarm. The RTC has a dedicated 32 kHz oscillator. No external resistor or loading capacitors are required, and a missing clock detector features alerts the system if the external crystal fails. The on-chip loading capacitors are programmable to 16 discrete levels allowing compatibility with a wide range of crystals.

The RTC module includes the following features:

- Up to 36 hours (32-bit) of independent time keeping.
- Support for external 32 kHz crystal or internal self-oscillate mode.
- Internal crystal loading capacitors with 16 levels.
- Operation in the lowest power mode and across the full supported voltage range.
- Alarm and oscillator failure events to wake from the lowest power mode or reset the device.

Programmable Counter Array (PCA0)

The programmable counter array (PCA) provides multiple channels of enhanced timer and PWM functionality while requiring less CPU intervention than standard counter/timers. The PCA consists of a dedicated 16-bit counter/timer and one 16-bit capture/compare module for each channel. The counter/timer is driven by a programmable timebase that has flexible external and internal clocking options. Each capture/compare module may be configured to operate independently in one of five modes: Edge-Triggered Capture, Software Timer, High-Speed Output, Frequency Output, or Pulse-Width Modulated (PWM) Output. Each capture/compare module has its own associated I/O line (CEXn) which is routed through the crossbar to port I/O when enabled.

- · 16-bit time base.
- Programmable clock divisor and clock source selection.
- · Up to six independently-configurable channels
- 8, 9, 10, 11 and 16-bit PWM modes (edge-aligned operation).
- · Frequency output mode.
- · Capture on rising, falling or any edge.
- · Compare function for arbitrary waveform generation.
- Software timer (internal compare) mode.
- · Integrated watchdog timer.

Timers (Timer 0, Timer 1, Timer 2, and Timer 3)

Several counter/timers are included in the device: two are 16-bit counter/timers compatible with those found in the standard 8051, and the rest are 16-bit auto-reload timers for timing peripherals or for general purpose use. These timers can be used to measure time intervals, count external events and generate periodic interrupt requests. Timer 0 and Timer 1 are nearly identical and have four primary modes of operation. The other timers offer both 16-bit and split 8-bit timer functionality with auto-reload and capture capabilities.

Timer 0 and Timer 1 include the following features:

- · Standard 8051 timers, supporting backwards-compatibility with firmware and hardware.
- · Clock sources include SYSCLK, SYSCLK divided by 12, 4, or 48, the External Clock divided by 8, or an external pin.
- · 8-bit auto-reload counter/timer mode
- · 13-bit counter/timer mode
- 16-bit counter/timer mode
- · Dual 8-bit counter/timer mode (Timer 0)

Timer 2 and Timer 3 are 16-bit timers including the following features:

- Clock sources include SYSCLK, SYSCLK divided by 12, or the External Clock divided by 8.
- 16-bit auto-reload timer mode
- · Dual 8-bit auto-reload timer mode
- Comparator 0 or RTC0 capture (Timer 2)
- · Comparator 1 or EXTCLK/8 capture (Timer 3)

Watchdog Timer (WDT0)

The device includes a programmable watchdog timer (WDT) integrated within the PCA0 peripheral. A WDT overflow forces the MCU into the reset state. To prevent the reset, the WDT must be restarted by application software before overflow. If the system experiences a software or hardware malfunction preventing the software from restarting the WDT, the WDT overflows and causes a reset. Following a reset, the WDT is automatically enabled and running with the default maximum time interval. If needed, the WDT can be disabled by system software. The state of the RSTb pin is unaffected by this reset.

The Watchdog Timer integrated in the PCA0 peripheral has the following features:

- · Programmable timeout interval
- · Runs from the selected PCA clock source
- · Automatically enabled after any system reset

3.6 Communications and Other Digital Peripherals

Universal Asynchronous Receiver/Transmitter (UART0)

UART0 is an asynchronous, full duplex serial port offering modes 1 and 3 of the standard 8051 UART. Enhanced baud rate support allows a wide range of clock sources to generate standard baud rates. Received data buffering allows UART0 to start reception of a second incoming data byte before software has finished reading the previous data byte.

The UART module provides the following features:

- · Asynchronous transmissions and receptions
- Baud rates up to SYSCLK/2 (transmit) or SYSCLK/8 (receive)
- · 8- or 9-bit data
- · Automatic start and stop generation

Serial Peripheral Interface (SPI0 and SPI1)

The serial peripheral interface (SPI) module provides access to a flexible, full-duplex synchronous serial bus. The SPI can operate as a master or slave device in both 3-wire or 4-wire modes, and supports multiple masters and slaves on a single SPI bus. The slave-select (NSS) signal can be configured as an input to select the SPI in slave mode, or to disable master mode operation in a multi-master environment, avoiding contention on the SPI bus when more than one master attempts simultaneous data transfers. NSS can also be configured as a firmware-controlled chip-select output in master mode, or disabled to reduce the number of pins required. Additional general purpose port I/O pins can be used to select multiple slave devices in master mode.

The SPI module includes the following features:

- Supports 3- or 4-wire operation in master or slave modes.
- Supports external clock frequencies up to SYSCLK / 2 in master mode and SYSCLK / 10 in slave mode.
- · Support for four clock phase and polarity options.
- 8-bit dedicated clock clock rate generator.
- · Support for multiple masters on the same data lines.

System Management Bus / I2C (SMB0)

The SMBus I/O interface is a two-wire, bi-directional serial bus. The SMBus is compliant with the System Management Bus Specification, version 1.1, and compatible with the I²C serial bus.

The SMBus module includes the following features:

- Standard (up to 100 kbps) and Fast (400 kbps) transfer speeds.
- · Support for master, slave, and multi-master modes.
- Hardware synchronization and arbitration for multi-master mode.
- · Clock low extending (clock stretching) to interface with faster masters.
- Hardware support for 7-bit slave and general call address recognition.
- · Firmware support for 10-bit slave address decoding
- · Ability to inhibit all slave states.
- · Programmable data setup/hold times.

External Memory Interface (EMIF0)

The External Memory Interface (EMIF) enables access of off-chip memories and memory-mapped devices connected to the GPIO ports. The external memory space may be accessed using the external move instruction (MOVX) with the target address specified in either 8-bit or 16-bit formats.

- · Supports multiplexed memory access.
- · Four external memory modes:
 - · Internal only.
 - · Split mode without bank select.
 - · Split mode with bank select.
 - External only
- · Configurable ALE (address latch enable) timing.
- · Configurable address setup and hold times.
- · Configurable write and read pulse widths.

16/32-bit CRC (CRC0)

The cyclic redundancy check (CRC) module performs a CRC using a 16-bit or 32-bit polynomial. CRC0 accepts a stream of 8-bit data and posts the result to an internal register. In addition to using the CRC block for data manipulation, hardware can automatically CRC the flash contents of the device.

The CRC module is designed to provide hardware calculations for flash memory verification and communications protocols. The CRC module includes the following features:

- Support for CCITT-16 polynomial (0x1021).
- Support for CRC-32 polynomial (0x04C11DB7).
- · Byte-level bit reversal.
- · Automatic CRC of flash contents on one or more 1024-byte blocks.
- Initial seed selection of 0x0000/0x00000000 or 0xFFFF/0xFFFFFFF.

3.7 Analog

Programmable Current Reference (IREF0)

The programmable current reference (IREF0) module enables current source or sink with two output current settings: Low Power Mode and High Current Mode. The maximum current output in Low Power Mode is 63 μ A (1 μ A steps) and the maximum current output in High Current Mode is 504 μ A (8 μ A steps).

The IREF module includes the following features:

- · Capable of sourcing or sinking current in programmable steps.
- Two operational modes: Low Power Mode and High Current Mode.

4. Electrical Specifications

4.1 Electrical Characteristics

All electrical parameters in all tables are specified under the conditions listed in Table 4.1 Recommended Operating Conditions on page 11, unless stated otherwise.

Table 4.1. Recommended Operating Conditions

Parameter	Symbol	Test Condition	Min	Тур	Max	Unit
Operating Supply Voltage on VDD	V_{DD}		1.8	2.4	3.6	V
Minimum RAM Data Retention	V _{RAM}	Not in Sleep Mode	_	1.4	_	V
Voltage on VDD ¹		Sleep Mode	_	0.3	0.5	V
System Clock Frequency	f _{SYSCLK}		0	_	25	MHz
Operating Ambient Temperature	T _A		-4 0	_	85	°C

Note:

1. All voltages with respect to GND.

Table 4.2. Power Consumption

Parameter	Symbol	Conditions	Min	Тур	Max	Units
Digital Supply Current						
Normal Mode supply current - Full speed with code executing from	I _{DD}	V _{DD} = 1.8–3.6 V, f _{SYSCLK} = 24.5 MHz	_	4.1	5.0	mA
flash ^{3,4,5}		V _{DD} = 1.8–3.6 V, f _{SYSCLK} = 20 MHz	_	3.5	_	mA
		V _{DD} = 1.8–3.6 V, f _{SYSCLK} = 32.768 kHz	_	90	_	μA
Normal Mode supply current frequency sensitivity ^{1, 3, 5}	I _{DDFREQ}	V _{DD} = 1.8–3.6 V, T = 25 °C, f _{SYSCLK} < 14 MHz	_	226	_	μΑ/MHz
		V _{DD} = 1.8–3.6 V, T = 25 °C, f _{SYSCLK} > 14 MHz	_	120		μA/MHz
Idle Mode supply current - Core halted with peripherals running ⁴ , ⁶	I _{DD}	V _{DD} = 1.8–3.6 V, f _{SYSCLK} = 24.5 MHz	_	2.5	3.0	mA
		V _{DD} = 1.8–3.6 V, f _{SYSCLK} = 20 MHz	_	1.8		mA
		V _{DD} = 1.8–3.6 V, f _{SYSCLK} = 32.768 kHz	_	84		μA
Idle Mode Supply Current Frequency Sensitivity ^{1,6}	I _{DDFREQ}	V _{DD} = 1.8–3.6 V, T = 25 °C	_	95		μA/MHz
Suspend Mode Supply Current	I _{DD}	V _{DD} = 1.8–3.6 V	_	77	_	μA
Sleep Mode Supply Current with	I _{DD}	1.8 V, T = 25 °C	_	0.60	_	μA
RTC running from 32.768 kHz crystal		3.6 V, T = 25 °C	_	0.85	_	μA
		1.8 V, T = 85 °C	_	1.30	_	μA
		3.6 V, T = 85 °C	_	1.90	_	μA

Parameter	Symbol	Conditions	Min	Тур	Max	Units
Sleep Mode Supply Current (RTC	I _{DD}	1.8 V, T = 25 °C	_	0.05	_	μA
off)		3.6 V, T = 25 °C	_	0.12	_	μA
		1.8 V, T = 85 °C	_	0.75	_	μA
		3.6 V, T = 85 °C	_	1.20	_	μA
V _{DD} Monitor Supply Current	I _{VMON}		_	7	_	μA
Oscillator Supply Current	I _{HFOSC0}	25 °C	_	300	_	μA
ADC0 Always-on Power Supply	I _{ADC}	300 ksps	_	800	_	μA
Current ⁷		V _{DD} = 3.0 V				
		Tracking	_	680	_	μA
		V _{DD} = 3.0 V				
Comparator 0 (CMP0) Supply Cur-	I _{CMP}	CPMD = 11	_	0.4	_	μA
rent		CPMD = 10	_	2.6	_	μA
		CPMD = 01	_	8.8	_	μA
		CPMD = 00	_	23	_	μA
Internal Fast-settling 1.65V ADC0 Reference, Always-on ⁸	I _{VREFFS}		_	200	_	μA
On-chip Precision Reference	I _{VREFP}		_	15	_	μA
Temp sensor Supply Current	I _{TSENSE}		_	35	_	μA
Programmable Current Reference (IREF0) Supply Current ⁹	I _{IREF}	Current Source, Either Power Mode, Any Output Code	_	10	_	μA
		Low Power Mode, Current Sink	_	1	_	μA
		IREF0DAT = 000001				
		Low Power Mode, Current Sink	_	11	_	μA
		IREF0DAT = 111111				
		High Current Mode, Current Sink	_	12	_	μA
		IREF0DAT = 000001				
		High Current Mode, Current Sink	_	81	_	μA
		IREF0DAT = 111111				

Parameter	Symbol	Test Condition	Min	Тур	Max	Units
Endurance (Write/Erase Cycles)	N _{WE}		1 k	30 k	_	Cycles

Note:

- 1. Does not include sequencing time before and after the write/erase operation, which may be multiple SYSCLK cycles.
- 2. Data Retention Information is published in the Quarterly Quality and Reliability Report.

Table 4.5. Power Management Timing

Parameter	Symbol	Test Condition	Min	Тур	Max	Units
Idle Mode Wake-up Time	t _{IDLEWK}		2	_	3	SYSCLKs
Suspend Mode Wake-up Time	t _{SUS-} PENDWK	CLKDIV = 0x00 Precision Osc.	_	400	_	ns
		CLKDIV = 0x00 Low Power Osc.	_	1.3	_	μs
Sleep Mode Wake-up Time	t _{SLEEPWK}		_	2	_	μs

Table 4.6. Internal Oscillators

Parameter	Symbol	Test Condition	Min	Тур	Max	Unit		
High Frequency Oscillator 0 (24.5 MHz)								
Oscillator Frequency	f _{HFOSC0}	Full Temperature and Supply Range	24	24.5	25	MHz		
Low Power Oscillator (20 MHz)								
Oscillator Frequency	f _{LPOSC}	Full Temperature and Supply Range	18	20	22	MHz		
RTC in Self-Oscillate Mode								
Oscillator Frequency	f _{LFOSC}	Bias Off	_	12 ± 5	_	kHz		
		Bias On	_	25 ± 10	_	kHz		

Table 4.7. Crystal Oscillator

Parameter	Symbol	Test Condition	Min	Тур	Max	Unit
Crystal Frequency	f _{XTAL}		0.02	-	25	MHz

Table 4.8. External Clock Input

Parameter	Symbol	Test Condition	Min	Тур	Max	Unit
External Input CMOS Clock	f _{CMOS}		0	_	25	MHz
Frequency (at EXTCLK pin)						
External Input CMOS Clock High Time	tсмоsн		18	_	_	ns
External Input CMOS Clock Low Time	t _{CMOSL}		18	_	_	ns

Parameter	Symbol	Test Condition	Min	Тур	Max	Unit
Temperature Coefficient	TC _{REFFS}		_	50	_	ppm/°C
Turn-on Time	t _{VREFFS}		_	_	1.5	μs
Power Supply Rejection	PSRR _{REF} FS		_	400	_	ppm/V
On-chip Precision Reference						
Output Voltage	V _{REFP}		1.645	1.68	1.715	V
Turn-on Time, settling to 0.5 LSB	t _{VREFP}	4.7 μF tantalum + 0.1 μF ceramic bypass on VREF pin	_	15	_	ms
		0.1 μF ceramic bypass on VREF pin	_	300	_	μs
		No bypass on VREF pin	_	25	_	μs
Load Regulation	LR _{VREFP}	Load = 0 to 200 µA to GND	_	400	_	μV / μΑ
Short-circuit current	ISC _{VREFP}		_	3.5	_	mA
Power Supply Rejection	PSRR _{VRE} FP		_	140	_	ppm/V
External Reference						
Input Voltage	V _{EXTREF}		1	_	V _{DD}	V
Input Current	I _{EXTREF}	Sample Rate = 300 ksps; VREF = 3.0 V	_	5.25	_	μА

Table 4.11. Temperature Sensor

Parameter	Symbol	Test Condition	Min	Тур	Max	Unit
Offset	V _{OFF}	T _A = 0 °C	_	940	_	mV
Offset Error ¹	E _{OFF}	T _A = 0 °C	_	18	_	mV
Slope	М		_	3.40	_	mV/°C
Slope Error ¹	E _M		_	40	_	μV/°C
Linearity			_	±1	_	°C
Turn-on Time	t _{PWR}		_	1.8	_	μs
Note:	1		-1	1	1	1

Table 4.12. Comparators

Parameter	Symbol	Test Condition	Min	Тур	Max	Unit
Response Time, CPMD = 00 (Highest Speed)	t _{RESP0}	+100 mV Differential	_	130	_	ns
		-100 mV Differential	_	200	_	ns
Response Time, CPMD = 11 (Lowest Power)	t _{RESP3}	+100 mV Differential	_	1.75	_	μs
		-100 mV Differential	_	6.2	_	μs

1. Represents one standard deviation from the mean.

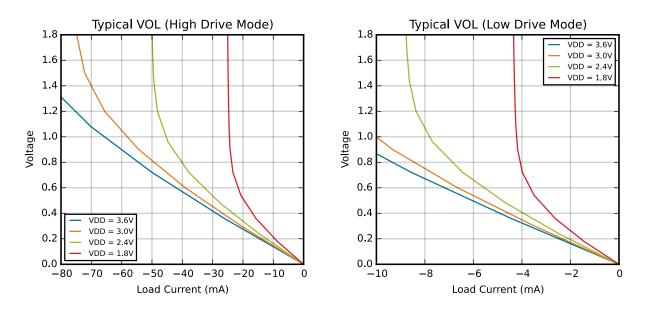


Figure 4.3. Typical V_{OL} Curves

5. Typical Connection Diagrams

5.1 Power

Figure 5.1 Power Connection Diagram on page 22 shows a typical connection diagram for the power pins of the EFM8SB2 devices.

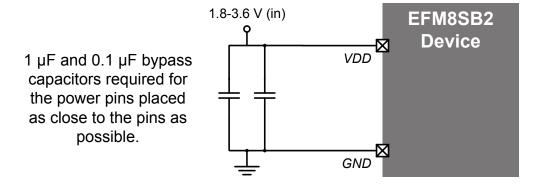


Figure 5.1. Power Connection Diagram

5.2 Other Connections

Other components or connections may be required to meet the system-level requirements. Application Note AN203: "8-bit MCU Printed Circuit Board Design Notes" contains detailed information on these connections. Application Notes can be accessed on the Silicon Labs website (www.silabs.com/8bit-appnotes).

Pin	Pin Name	Description	Crossbar Capability	Additional Digital	Analog Functions
Number				Functions	
6	RSTb /	Active-low Reset /			
	C2CK	C2 Debug Clock			
7	P2.7 /	Multifunction I/O /			
	C2D	C2 Debug Data			
8	XTAL4	RTC Crystal			XTAL4
9	XTAL3	RTC Crystal			XTAL3
10	P1.6	Multifunction I/O	Yes		ADC0.14
					CMP0P.7
					CMP1P.7
11	P1.5	Multifunction I/O	Yes	P1MAT.5	ADC0.13
					CMP0N.6
					CMP1N.6
12	P1.4	Multifunction I/O	Yes	P1MAT.4	ADC0.12
					CMP0P.6
					CMP1P.6
13	P1.3	Multifunction I/O	Yes	P1MAT.3	ADC0.11
				SPI1_NSS	CMP0N.5
					CMP1N.5
14	P1.2	Multifunction I/O	Yes	P1MAT.2	ADC0.10
				SPI1_MOSI	CMP0P.5
					CMP1P.5
15	P1.1	Multifunction I/O	Yes	P1MAT.1	ADC0.9
				SPI1_MISO	CMP0N.4
					CMP1N.4
16	P1.0	Multifunction I/O	Yes	P1MAT.0	ADC0.8
				SPI1_SCK	CMP0P.4
					CMP1P.4
17	P0.7	Multifunction I/O	Yes	P0MAT.7	ADC0.7
				INT0.7	IREF0
				INT1.7	CMP0N.3
					CMP1N.3
18	P0.6	Multifunction I/O	Yes	P0MAT.6	ADC0.6
				CNVSTR	CMP0P.3
				INT0.6	CMP1P.3
				INT1.6	

Pin Number	Pin Name	Description	Crossbar Capability	Additional Digital Functions	Analog Functions
19	P0.5	Multifunction I/O	Yes	P0MAT.5	ADC0.5
				INT0.5	CMP0N.2
				INT1.5	CMP1N.2
20	P0.4	Multifunction I/O	Yes	P0MAT.4	ADC0.4
				INT0.4	CMP0P.2
				INT1.4	CMP1P.2
21	P0.3	Multifunction I/O	Yes	P0MAT.3	ADC0.3
				EXTCLK	XTAL2
				INT0.3	CMP0N.1
				INT1.3	CMP1N.1
22	P0.2	Multifunction I/O	Yes	P0MAT.2	ADC0.2
				INT0.2	CMP0P.1
				INT1.2	CMP1P.1
					XTAL1
23	P0.1	Multifunction I/O	Yes	P0MAT.1	ADC0.1
				INT0.1	AGND
				INT1.1	CMP0N.0
					CMP1N.0
24	P0.0	Multifunction I/O	Yes	P0MAT.0	ADC0.0
				INT0.0	CMP0P.0
				INT1.0	CMP1P.0
					VREF
Center	GND	Ground			

Pin Number	Pin Name	Description	Crossbar Capability	Additional Digital Functions	Analog Functions
21	P1.3	Multifunction I/O	Yes	P1MAT.3	ADC0.11
				SPI1_NSS	CMP0N.5
				EMIF_AD3	CMP1N.5
22	P1.2	Multifunction I/O	Yes	P1MAT.2	ADC0.10
				SPI1_MOSI	CMP0P.5
				EMIF_AD2	CMP1P.5
23	P1.1	Multifunction I/O	Yes	P1MAT.1	ADC0.9
				SPI1_MISO	CMP0N.4
				EMIF_AD1	CMP1N.4
24	P1.0	Multifunction I/O	Yes	P1MAT.0	ADC0.8
				SPI1_SCK	CMP0P.4
				EMIF_AD0	CMP1P.4
25	P0.7	Multifunction I/O	Yes	P0MAT.7	ADC0.7
				INT0.7	IREF0
				INT1.7	CMP0N.3
					CMP1N.3
26	P0.6	Multifunction I/O	Yes	P0MAT.6	ADC0.6
				CNVSTR	CMP0P.3
				INT0.6	CMP1P.3
				INT1.6	
27	P0.5	Multifunction I/O	Yes	P0MAT.5	ADC0.5
				INT0.5	CMP0N.2
				INT1.5	CMP1N.2
28	P0.4	Multifunction I/O	Yes	P0MAT.4	ADC0.4
				INT0.4	CMP0P.2
				INT1.4	CMP1P.2
29	P0.3	Multifunction I/O	Yes	P0MAT.3	ADC0.3
				EXTCLK	XTAL2
				INT0.3	CMP0N.1
				INT1.3	CMP1N.1
30	P0.2	Multifunction I/O	Yes	P0MAT.2	ADC0.2
				INT0.2	CMP0P.1
				INT1.2	CMP1P.1
					XTAL1

8.2 QFN24 PCB Land Pattern

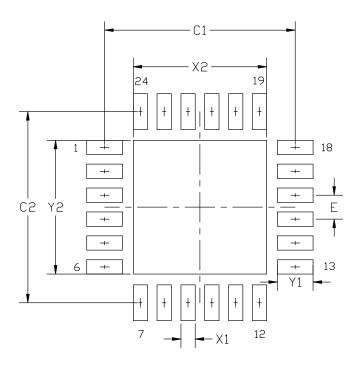


Figure 8.2. QFN24 PCB Land Pattern Drawing

Table 8.2. QFN24 PCB Land Pattern Dimensions

Dimension	Min	Max
C1	3.90	4.00
C2	3.90	4.00
E	0.50	BSC
X1	0.20	0.30
X2	2.70	2.80
Y1	0.65	0.75
Y2	2.70	2.80

9. QFP32 Package Specifications

9.1 QFP32 Package Dimensions

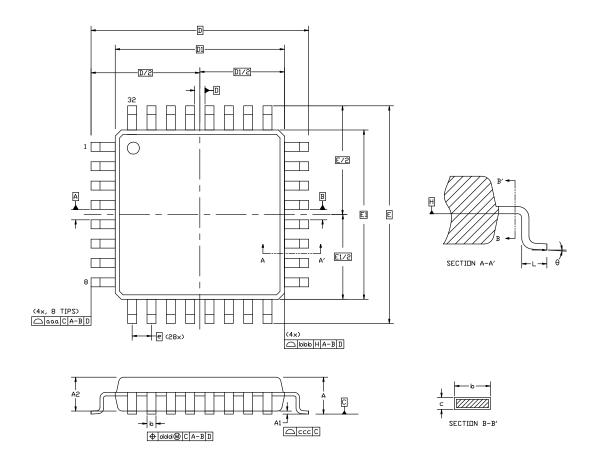


Figure 9.1. QFP32 Package Drawing

Table 9.1. QFP32 Package Dimensions

Dimension	Min	Тур	Max						
А	_	_	1.60						
A1	0.05	_	0.15						
A2	1.35	1.40	1.45						
b	0.30	0.37	0.45						
D	9.00 BSC								
D1	7.00 BSC								
е		0.80 BSC							
Е		9.00 BSC							
E1		7.00 BSC							
L	0.45	0.60	0.75						
aaa	0.20								

Dimension	Min	Тур	Max				
bbb		0.20					
ccc	0.10						
ddd		0.20					
theta	0°	3.5°	7°				

Note:

- 1. All dimensions shown are in millimeters (mm) unless otherwise noted.
- 2. Dimensioning and Tolerancing per ANSI Y14.5M-1994.
- 3. This drawing conforms to JEDEC outline MS-026, variation BBA.
- 4. Recommended card reflow profile is per the JEDEC/IPC J-STD-020C specification for Small Body Components.

9.2 QFP32 PCB Land Pattern

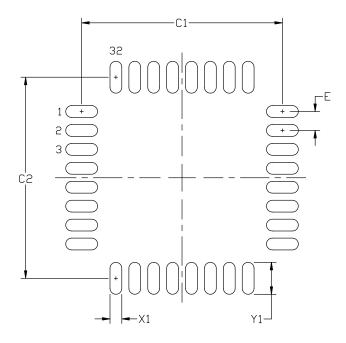


Figure 9.2. QFP32 PCB Land Pattern Drawing

Table 9.2. QFP32 PCB Land Pattern Dimensions

Dimension	Min	Max
C1	8.40	8.50
C2	8.40	8.50
Е	0.80	BSC
X1	0.40	0.50
Y1	1.25	1.35

Note:

- 1. All dimensions shown are in millimeters (mm) unless otherwise noted.
- 2. This Land Pattern Design is based on the IPC-7351 guidelines.
- 3. All metal pads are to be non-solder mask defined (NSMD). Clearance between the solder mask and the metal pad is to be $60 \mu m$ minimum, all the way around the pad.
- 4. A stainless steel, laser-cut and electro-polished stencil with trapezoidal walls should be used to assure good solder paste release.
- 5. The stencil thickness should be 0.125 mm (5 mils).
- 6. The ratio of stencil aperture to land pad size should be 1:1 for all perimeter pads.
- 7. A No-Clean, Type-3 solder paste is recommended.
- 8. The recommended card reflow profile is per the JEDEC/IPC J-STD-020C specification for Small Body Components.

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