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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

#### Applications of "[Embedded - Microcontrollers](#)"

##### Details

Product Status	Obsolete
Core Processor	CIP-51 8051
Core Size	8-Bit
Speed	25MHz
Connectivity	SMBus (2-Wire/I <sup>2</sup> C), SPI, UART/USART
Peripherals	Brown-out Detect/Reset, POR, PWM, Temp Sensor, WDT
Number of I/O	17
Program Memory Size	8KB (8K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	512 x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.6V
Data Converters	A/D 10x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	24-SSOP (0.154", 3.90mm Width)
Supplier Device Package	24-QSOP
Purchase URL	<a href="https://www.e-xfl.com/product-detail/silicon-labs/c8051f986-gu">https://www.e-xfl.com/product-detail/silicon-labs/c8051f986-gu</a>

# C8051F99x-C8051F98x

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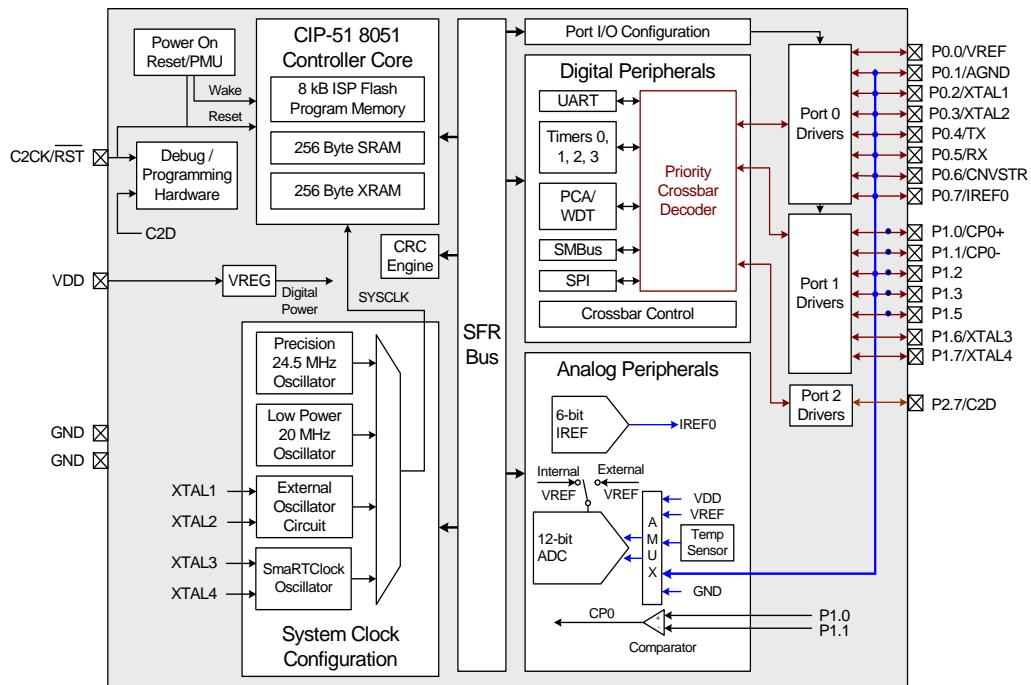


Figure 1.1. C8051F980 Block Diagram

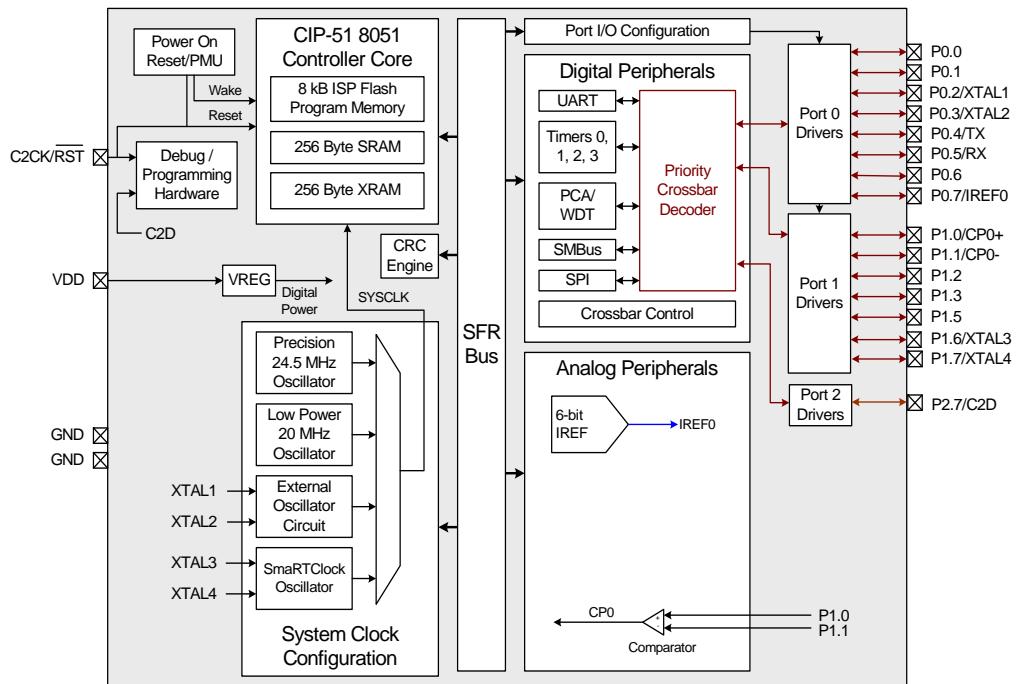
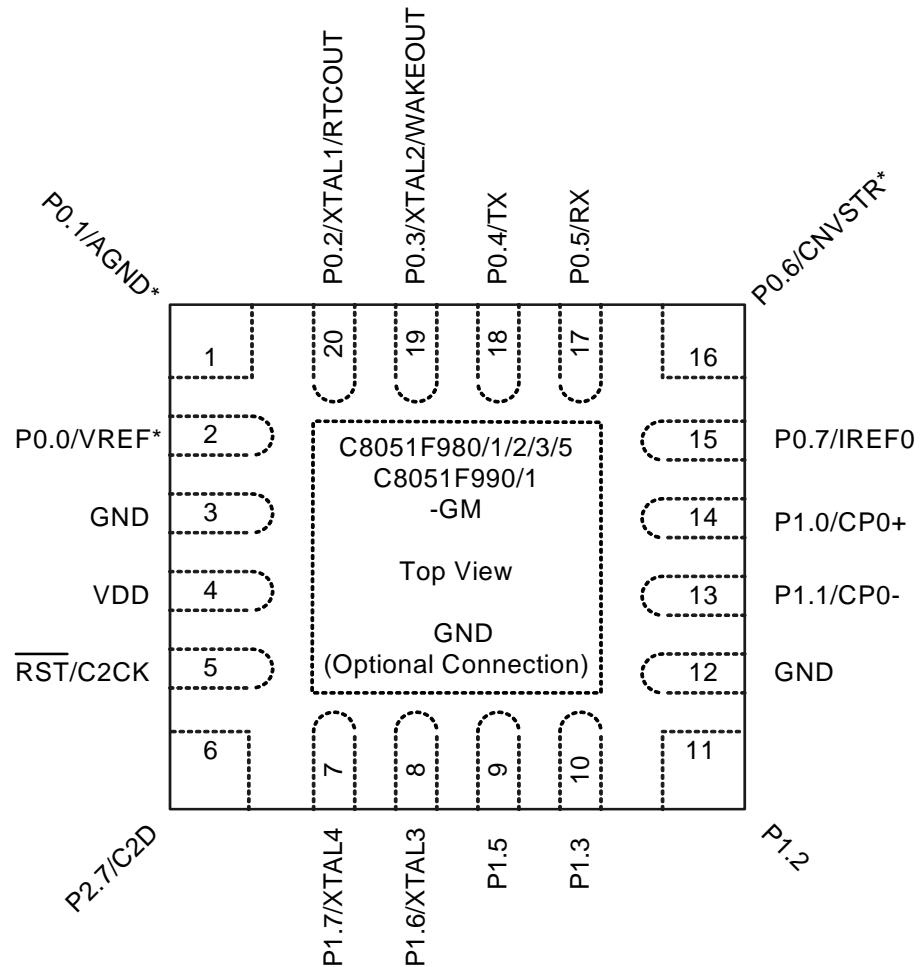


Figure 1.2. C8051F981 Block Diagram

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\*Note: Signal only available on 'F980, 'F982 and 'F990 devices.

**Figure 3.1. QFN-20 Pinout Diagram (Top View)**

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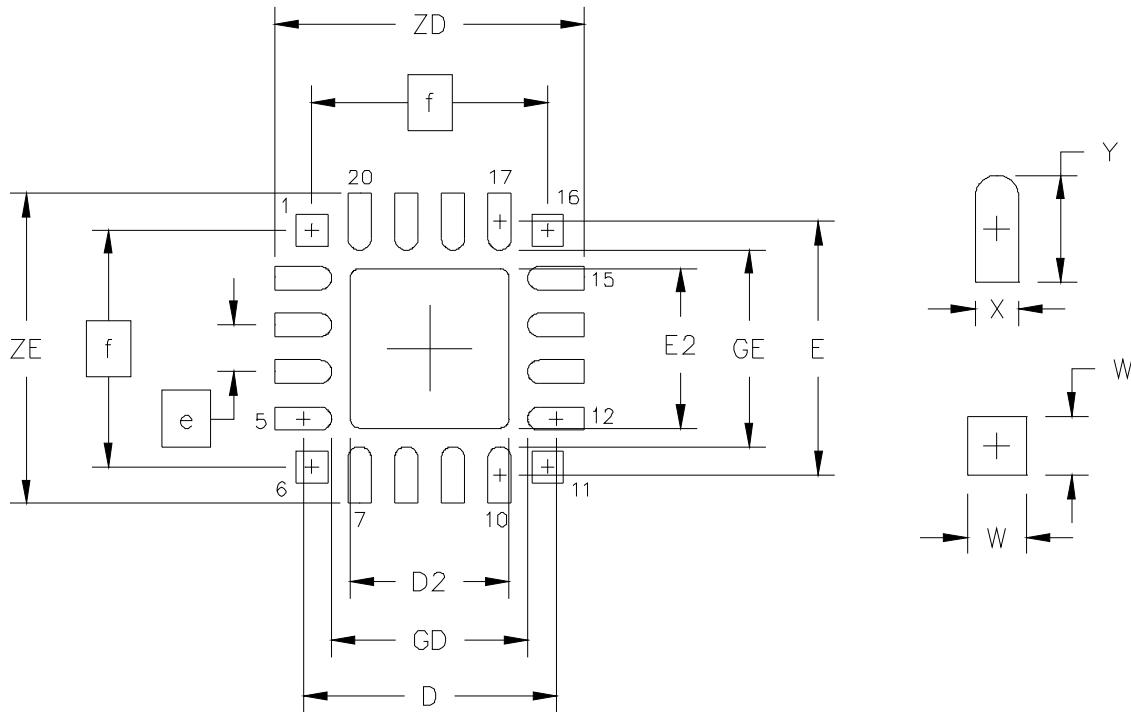


Figure 3.8. Typical QFN-20 Landing Diagram

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## SFR Definition 5.3. ADC0AC: ADC0 Accumulator Configuration

---

Bit	7	6	5	4	3	2	1	0
<b>Name</b>	AD012BE	AD0AE	AD0SJST[2:0]				AD0RPT[2:0]	
<b>Type</b>	R/W	W	R/W				R/W	
<b>Reset</b>	0	0	0	0	0	0	0	0

SFR Page = 0x0; SFR Address = 0xBA

Bit	Name	Function
7	AD012BE	<b>ADC0 12-Bit Mode Enable.</b> Enables 12-bit Mode on C8051F980/6 and C8051F990/6 devices. 0: 12-bit Mode Disabled. 1: 12-bit Mode Enabled.
6	AD0AE	<b>ADC0 Accumulate Enable.</b> Enables multiple conversions to be accumulated when burst mode is disabled. 0: ADC0H:ADC0L contain the result of the latest conversion when Burst Mode is disabled. 1: ADC0H:ADC0L contain the accumulated conversion results when Burst Mode is disabled. Software must write 0x0000 to ADC0H:ADC0L to clear the accumulated result. This bit is write-only. Always reads 0b.
5:3	AD0SJST[2:0]	<b>ADC0 Accumulator Shift and Justify.</b> Specifies the format of data read from ADC0H:ADC0L. 000: Right justified. No shifting applied. 001: Right justified. Shifted right by 1 bit. 010: Right justified. Shifted right by 2 bits. 011: Right justified. Shifted right by 3 bits. 100: Left justified. No shifting applied. All remaining bit combinations are reserved.
2:0	AD0RPT[2:0]	<b>ADC0 Repeat Count.</b> Selects the number of conversions to perform and accumulate in Burst Mode. This bit field must be set to 000 if Burst Mode is disabled. 000: Perform and Accumulate 1 conversion. 001: Perform and Accumulate 4 conversions. 010: Perform and Accumulate 8 conversions. 011: Perform and Accumulate 16 conversions. 100: Perform and Accumulate 32 conversions. 101: Perform and Accumulate 64 conversions. All remaining bit combinations are reserved.

# C8051F99x-C8051F98x

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## SFR Definition 5.15. REF0CN: Voltage Reference Control

---

Bit	7	6	5	4	3	2	1	0
Name			REFGND	REFSL	TEMPE			
Type	R	R	R/W	R/W	R/W	R/W	R	R
Reset	0	0	0	1	1	0	0	0

SFR Page = 0x0; SFR Address = 0xD1

Bit	Name	Function
7:6	Unused	Read = 00b; Write = Don't Care.
5	REFGND	<b>Analog Ground Reference.</b> Selects the ADC0 ground reference. 0: The ADC0 ground reference is the GND pin. 1: The ADC0 ground reference is the P0.1/AGND pin.
4:3	REFSL	<b>Voltage Reference Select.</b> Selects the ADC0 voltage reference. 00: The ADC0 voltage reference is the P0.0/VREF pin. 01: The ADC0 voltage reference is the VDD pin. 10: The ADC0 voltage reference is the internal 1.8 V digital supply voltage. 11: The ADC0 voltage reference is the internal 1.65 V high speed voltage reference.
2	TEMPE	<b>Temperature Sensor Enable.</b> Enables/Disables the internal temperature sensor. 0: Temperature Sensor Disabled. 1: Temperature Sensor Enabled.
1:0	Unused	Read = 00b; Write = Don't Care.

## 5.14. Voltage Reference Electrical Specifications

See Table 4.12 on page 61 for detailed Voltage Reference Electrical Specifications.

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## SFR Definition 8.3. CS0DH: Capacitive Sense Data High Byte

---

Bit	7	6	5	4	3	2	1	0
<b>Name</b>	CS0DH[7:0]							
<b>Type</b>	R	R	R	R	R	R	R	R
<b>Reset</b>	0	0	0	0	0	0	0	0

SFR Page = 0x0; SFR Address = 0xEE

Bit	Name	Description
7:0	CS0DH	<b>CS0 Data High Byte.</b> Stores the high byte of the last completed 16-bit Capacitive Sense conversion.

---

## SFR Definition 8.4. CS0DL: Capacitive Sense Data Low Byte

---

Bit	7	6	5	4	3	2	1	0
<b>Name</b>	CS0DL[7:0]							
<b>Type</b>	R	R	R	R	R	R	R	R
<b>Reset</b>	0	0	0	0	0	0	0	0

SFR Page = 0x0; SFR Address = 0xED

Bit	Name	Description
7:0	CS0DL	<b>CS0 Data Low Byte.</b> Stores the low byte of the last completed 16-bit Capacitive Sense conversion.

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---

## SFR Definition 8.9. CS0THH: Capacitive Sense Comparator Threshold High Byte

---

Bit	7	6	5	4	3	2	1	0
<b>Name</b>	CS0THH[7:0]							
<b>Type</b>	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
<b>Reset</b>	0	0	0	0	0	0	0	0

SFR Page = 0x0; SFR Address = 0xFE

Bit	Name	Description
7:0	CS0THH[7:0]	<b>CS0 Comparator Threshold High Byte.</b> High byte of the 16-bit value compared to the Capacitive Sense conversion result.

---

## SFR Definition 8.10. CS0THL: Capacitive Sense Comparator Threshold Low Byte

---

Bit	7	6	5	4	3	2	1	0
<b>Name</b>	CS0THL[7:0]							
<b>Type</b>	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
<b>Reset</b>	0	0	0	0	0	0	0	0

SFR Page = 0x0; SFR Address = 0xFD

Bit	Name	Description
7:0	CS0THL[7:0]	<b>CS0 Comparator Threshold Low Byte.</b> Low byte of the 16-bit value compared to the Capacitive Sense conversion result.

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**Table 9.1. CIP-51 Instruction Set Summary (Continued)**

Mnemonic	Description	Bytes	Clock Cycles
CLR A	Clear A	1	1
CPL A	Complement A	1	1
RL A	Rotate A left	1	1
RLC A	Rotate A left through Carry	1	1
RR A	Rotate A right	1	1
RRC A	Rotate A right through Carry	1	1
SWAP A	Swap nibbles of A	1	1
<b>Data Transfer</b>			
MOV A, Rn	Move Register to A	1	1
MOV A, direct	Move direct byte to A	2	2
MOV A, @Ri	Move indirect RAM to A	1	2
MOV A, #data	Move immediate to A	2	2
MOV Rn, A	Move A to Register	1	1
MOV Rn, direct	Move direct byte to Register	2	2
MOV Rn, #data	Move immediate to Register	2	2
MOV direct, A	Move A to direct byte	2	2
MOV direct, Rn	Move Register to direct byte	2	2
MOV direct, direct	Move direct byte to direct byte	3	3
MOV direct, @Ri	Move indirect RAM to direct byte	2	2
MOV direct, #data	Move immediate to direct byte	3	3
MOV @Ri, A	Move A to indirect RAM	1	2
MOV @Ri, direct	Move direct byte to indirect RAM	2	2
MOV @Ri, #data	Move immediate to indirect RAM	2	2
MOV DPTR, #data16	Load DPTR with 16-bit constant	3	3
MOVC A, @A+DPTR	Move code byte relative DPTR to A	1	3
MOVC A, @A+PC	Move code byte relative PC to A	1	3
MOVX A, @Ri	Move external data (8-bit address) to A	1	3
MOVX @Ri, A	Move A to external data (8-bit address)	1	3
MOVX A, @DPTR	Move external data (16-bit address) to A	1	3
MOVX @DPTR, A	Move A to external data (16-bit address)	1	3
PUSH direct	Push direct byte onto stack	2	2
POP direct	Pop direct byte from stack	2	2
XCH A, Rn	Exchange Register with A	1	1
XCH A, direct	Exchange direct byte with A	2	2
XCH A, @Ri	Exchange indirect RAM with A	1	2
XCHD A, @Ri	Exchange low nibble of indirect RAM with A	1	2
<b>Boolean Manipulation</b>			
CLR C	Clear Carry	1	1
CLR bit	Clear direct bit	2	2
SETB C	Set Carry	1	1
SETB bit	Set direct bit	2	2
CPL C	Complement Carry	1	1
CPL bit	Complement direct bit	2	2
ANL C, bit	AND direct bit to Carry	2	2

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**Table 9.1. CIP-51 Instruction Set Summary (Continued)**

Mnemonic	Description	Bytes	Clock Cycles
ANL C, /bit	AND complement of direct bit to Carry	2	2
ORL C, bit	OR direct bit to carry	2	2
ORL C, /bit	OR complement of direct bit to Carry	2	2
MOV C, bit	Move direct bit to Carry	2	2
MOV bit, C	Move Carry to direct bit	2	2
JC rel	Jump if Carry is set	2	2/3
JNC rel	Jump if Carry is not set	2	2/3
JB bit, rel	Jump if direct bit is set	3	3/4
JNB bit, rel	Jump if direct bit is not set	3	3/4
JBC bit, rel	Jump if direct bit is set and clear bit	3	3/4
<b>Program Branching</b>			
ACALL addr11	Absolute subroutine call	2	3
LCALL addr16	Long subroutine call	3	4
RET	Return from subroutine	1	5
RETI	Return from interrupt	1	5
AJMP addr11	Absolute jump	2	3
LJMP addr16	Long jump	3	4
SJMP rel	Short jump (relative address)	2	3
JMP @A+DPTR	Jump indirect relative to DPTR	1	3
JZ rel	Jump if A equals zero	2	2/3
JNZ rel	Jump if A does not equal zero	2	2/3
CJNE A, direct, rel	Compare direct byte to A and jump if not equal	3	3/4
CJNE A, #data, rel	Compare immediate to A and jump if not equal	3	3/4
CJNE Rn, #data, rel	Compare immediate to Register and jump if not equal	3	3/4
CJNE @Ri, #data, rel	Compare immediate to indirect and jump if not equal	3	4/5
DJNZ Rn, rel	Decrement Register and jump if not zero	2	2/3
DJNZ direct, rel	Decrement direct byte and jump if not zero	3	3/4
NOP	No operation	1	1

## 12.1. SFR Paging

To accommodate more than 128 SFRs in the 0x80 to 0xFF address space, SFR paging has been implemented. By default, all SFR accesses target SFR Page 0x0 to allow access to the registers listed in Table 12.1. During device initialization, some SFRs located on SFR Page 0xF may need to be accessed. Table 12.2 lists the SFRs accessible from SFR Page 0x0F. Some SFRs are accessible from both pages, including the SFRPAGE register. SFRs only accessible from Page 0xF are in **bold**.

The following procedure should be used when accessing SFRs on Page 0xF:

1. Save the current interrupt state (EA\_save = EA).
2. Disable Interrupts (EA = 0).
3. Set SFRPAGE = 0xF.
4. Access the SFRs located on SFR Page 0xF.
5. Set SFRPAGE = 0x0.
6. Restore interrupt state (EA = EA\_save).

**Table 12.2. Special Function Register (SFR) Memory Map (Page 0xF)**

F8							
F0	B			<b>CS0MD3</b>		EIP1	EIP2
E8							
E0	ACC		<b>REVID</b>	<b>DEVICEID</b>		EIE1	EIE2
D8						<b>CS0PM</b>	
D0	<b>PSW</b>						
C8							
C0							
B8		<b>IREF0CF</b>		ADC0PWR	ADC0TK		
B0						<b>PMU0MD</b>	
A8	IE	CLKSEL					
A0	P2						<b>SFRPAGE</b>
98		<b>P0DRV</b>	CRC0CNT	<b>P1DRV</b>	CRC0FLIP	<b>P2DRV</b>	CRC0AUTO
90	P1						
88						<b>TOFFL</b>	<b>TOFFH</b>
80	P0	SP	DPL	DPH	CRC0CN	CRC0IN	CRC0DAT
	0(8)	1(9)	2(A)	3(B)	4(C)	5(D)	6(E)
	(bit addressable)						
							7(F)

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**Table 12.3. Special Function Registers (Continued)**

SFRs are listed in alphabetical order. All undefined SFR locations are reserved.

Register	Address	SFR Page	Description	Page
CS0DH	0xEE	0x0	CS0 Data High Byte	109
CS0DL	0xED	0x0	CS0 Data Low Byte	109
CS0MD1	0xAF	0x0	CS0 Mode1	113
CS0MD2	0xF3	0x0	CS0 Mode 2	114
CS0MD3	0xF3	0xF	CS0 Mode 3	115
CS0MX	0xAB	0x0	CS0 Mux Channel Select	118
CS0PM	0xDE	0xF	CS0 Power Management	116
CS0SCAN0	0xD2	0x0	CS0 Scan Channel Enable 0	110
CS0SCAN1	0xD3	0x0	CS0 Scan Channel Enable 1	110
CS0SE	0xDE	0x0	CS0 Auto-Scan End Channel	111
CS0SS	0xDD	0x0	CS0 Auto-Scan Start Channel	111
CS0THH	0xFE	0x0	CS0 Comparator Threshold High Byte	112
CS0THL	0xFD	0x0	CS0 Comparator Threshold Low Byte	112
DEVICEID	0xE3	0xF	Device ID	154
DPH	0x83	All	Data Pointer High	125
DPL	0x82	All	Data Pointer Low	125
EIE1	0xE6	All	Extended Interrupt Enable 1	144
EIE2	0xE7	All	Extended Interrupt Enable 2	146
EIP1	0xF6	All	Extended Interrupt Priority 1	145
EIP2	0xF7	All	Extended Interrupt Priority 2	147
FLKEY	0xB7	All	Flash Lock And Key	160
FLSCL	0xB6	0x0	Flash Scale Register	161
FLWR	0xE5	All	Flash Write Only Register	161
IE	0xA8	All	Interrupt Enable	142
IP	0xB8	All	Interrupt Priority	143
IREF0CF	0xB9	All	Current Reference IREF0 Configuration	92
IREF0CN	0xD6	0x0	Current Reference IREF0 Control	91
IT01CF	0xE4	0x0	INT0/INT1 Configuration	149
OSCICL	0xB3	0x0	Internal Oscillator Calibration	195
OSCICN	0xB2	0x0	Internal Oscillator Control	194
OSCXCN	0xB1	0x0	External Oscillator Control	196
P0	0x80	All	Port 0 Latch	228
P0DRV	0x99	0xF	Port 0 Drive Strength	230
P0MASK	0xC7	0x0	Port 0 Mask	225
P0MAT	0xD7	0x0	Port 0 Match	225
P0MDIN	0xF1	0x0	Port 0 Input Mode Configuration	229
P0MDOUT	0xA4	0x0	Port 0 Output Mode Configuration	229
P0SKIP	0xD4	0x0	Port 0 Skip	228
P1	0x90	All	Port 1 Latch	231
P1DRV	0x9B	0xF	Port 1 Drive Strength	233
P1MASK	0xBF	0x0	Port 1 Mask	226
P1MAT	0xCF	0x0	Port 1 Match	226
P1MDIN	0xF2	0x0	Port 1 Input Mode Configuration	232
P1MDOUT	0xA5	0x0	Port 1 Output Mode Configuration	228

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## SFR Definition 13.1. IE: Interrupt Enable

Bit	7	6	5	4	3	2	1	0
Name	EA	ESPI0	ET2	ES0	ET1	EX1	ET0	EX0
Type	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Reset	0	0	0	0	0	0	0	0

SFR Page = All; SFR Address = 0xA8; Bit-Addressable

Bit	Name	Function
7	EA	<b>Enable All Interrupts.</b> Globally enables/disables all interrupts. It overrides individual interrupt mask settings. 0: Disable all interrupt sources. 1: Enable each interrupt according to its individual mask setting.
6	ESPI0	<b>Enable Serial Peripheral Interface (SPI0) Interrupt.</b> This bit sets the masking of the SPI0 interrupts. 0: Disable all SPI0 interrupts. 1: Enable interrupt requests generated by SPI0.
5	ET2	<b>Enable Timer 2 Interrupt.</b> This bit sets the masking of the Timer 2 interrupt. 0: Disable Timer 2 interrupt. 1: Enable interrupt requests generated by the TF2L or TF2H flags.
4	ES0	<b>Enable UART0 Interrupt.</b> This bit sets the masking of the UART0 interrupt. 0: Disable UART0 interrupt. 1: Enable UART0 interrupt.
3	ET1	<b>Enable Timer 1 Interrupt.</b> This bit sets the masking of the Timer 1 interrupt. 0: Disable all Timer 1 interrupt. 1: Enable interrupt requests generated by the TF1 flag.
2	EX1	<b>Enable External Interrupt 1.</b> This bit sets the masking of External Interrupt 1. 0: Disable external interrupt 1. 1: Enable interrupt requests generated by the INT1 input.
1	ET0	<b>Enable Timer 0 Interrupt.</b> This bit sets the masking of the Timer 0 interrupt. 0: Disable all Timer 0 interrupt. 1: Enable interrupt requests generated by the TF0 flag.
0	EX0	<b>Enable External Interrupt 0.</b> This bit sets the masking of External Interrupt 0. 0: Disable external interrupt 0. 1: Enable interrupt requests generated by the INT0 input.

## SFR Definition 13.2. IP: Interrupt Priority

Bit	7	6	5	4	3	2	1	0
Name		PSPI0	PT2	PS0	PT1	PX1	PT0	PX0
Type	R	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Reset	1	0	0	0	0	0	0	0

SFR Page = All; SFR Address = 0xB8; Bit-Addressable

Bit	Name	Function
7	Unused	Read = 1b, Write = don't care.
6	PSPI0	<b>Serial Peripheral Interface (SPI0) Interrupt Priority Control.</b> This bit sets the priority of the SPI0 interrupt. 0: SPI0 interrupt set to low priority level. 1: SPI0 interrupt set to high priority level.
5	PT2	<b>Timer 2 Interrupt Priority Control.</b> This bit sets the priority of the Timer 2 interrupt. 0: Timer 2 interrupt set to low priority level. 1: Timer 2 interrupt set to high priority level.
4	PS0	<b>UART0 Interrupt Priority Control.</b> This bit sets the priority of the UART0 interrupt. 0: UART0 interrupt set to low priority level. 1: UART0 interrupt set to high priority level.
3	PT1	<b>Timer 1 Interrupt Priority Control.</b> This bit sets the priority of the Timer 1 interrupt. 0: Timer 1 interrupt set to low priority level. 1: Timer 1 interrupt set to high priority level.
2	PX1	<b>External Interrupt 1 Priority Control.</b> This bit sets the priority of the External Interrupt 1 interrupt. 0: External Interrupt 1 set to low priority level. 1: External Interrupt 1 set to high priority level.
1	PT0	<b>Timer 0 Interrupt Priority Control.</b> This bit sets the priority of the Timer 0 interrupt. 0: Timer 0 interrupt set to low priority level. 1: Timer 0 interrupt set to high priority level.
0	PX0	<b>External Interrupt 0 Priority Control.</b> This bit sets the priority of the External Interrupt 0 interrupt. 0: External Interrupt 0 set to low priority level. 1: External Interrupt 0 set to high priority level.

## 20.1. SmaRTClock Interface

The SmaRTClock Interface consists of three registers: RTC0KEY, RTC0ADR, and RTC0DAT. These interface registers are located on the CIP-51's SFR map and provide access to the SmaRTClock internal registers listed in Table 20.1. The SmaRTClock internal registers can only be accessed indirectly through the SmaRTClock Interface.

**Table 20.1. SmaRTClock Internal Registers**

SmaRTClock Address	SmaRTClock Register	Register Name	Description
0x00–0x03	CAPTUREn	SmaRTClock Capture Registers	Four Registers used for setting the 32-bit SmaRTClock timer or reading its current value.
0x04	RTC0CN	SmaRTClock Control Register	Controls the operation of the SmaRTClock State Machine.
0x05	RTC0XCN	SmaRTClock Oscillator Control Register	Controls the operation of the SmaRTClock Oscillator.
0x06	RTC0XCF	SmaRTClock Oscillator Configuration Register	Controls the value of the programmable oscillator load capacitance and enables/disables AutoStep.
0x08–0x0B	ALARMn	SmaRTClock Alarm Registers	Four registers used for setting or reading the 32-bit SmaRTClock alarm value.

### 20.1.1. SmaRTClock Lock and Key Functions

The SmaRTClock Interface has an RTC0KEY register for legacy reasons, however, all writes to this register are ignored. The SmaRTClock interface is always unlocked on C8051F99x-C8051F98x.

# C8051F99x-C8051F98x

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## SFR Definition 21.17. P1DRV: Port1 Drive Strength

---

Bit	7	6	5	4	3	2	1	0
Name	P1DRV[7:0]							
Type	R/W							
Reset	0	0	0	0	0	0	0	0

SFR Page = 0xF; SFR Address = 0x9B

Bit	Name	Function
7:0	P1DRV[7:0]	<b>Drive Strength Configuration Bits for P1.7–P1.0 (respectively).</b> Configures digital I/O Port cells to high or low output drive strength. 0: Corresponding P1.n Output has low output drive strength. 1: Corresponding P1.n Output has high output drive strength.

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## SFR Definition 21.18. P2: Port2

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Bit	7	6	5	4	3	2	1	0
Name	P2							
Type	R/W	R	R	R	R	R	R	R
Reset	1	0	0	0	0	0	0	0

SFR Page = All; SFR Address = 0xA0; Bit-Addressable

Bit	Name	Description	Read	Write	
7	P2	<b>Port 2 Data.</b> Sets the Port latch logic value or reads the Port pin logic state in Port cells configured for digital I/O.	0: Set output latch to logic LOW. 1: Set output latch to logic HIGH.	0: P2.7 Port pin is logic LOW. 1: P2.7 Port pin is logic HIGH.	
6:0	Unused	Read = 0000000b; Write = Don't Care.			

# C8051F99x-C8051F98x

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## 22.4. Using the SMBus

The SMBus can operate in both Master and Slave modes. The interface provides timing and shifting control for serial transfers; higher level protocol is determined by user software. The SMBus interface provides the following application-independent features:

- Byte-wise serial data transfers
- Clock signal generation on SCL (Master Mode only) and SDA data synchronization
- Timeout/bus error recognition, as defined by the SMB0CF configuration register
- START/STOP timing, detection, and generation
- Bus arbitration
- Interrupt generation
- Status information
- Optional hardware recognition of slave address and automatic acknowledgement of address/data

SMBus interrupts are generated for each data byte or slave address that is transferred. When hardware acknowledgement is disabled, the point at which the interrupt is generated depends on whether the hardware is acting as a data transmitter or receiver. When a transmitter (i.e. sending address/data, receiving an ACK), this interrupt is generated after the ACK cycle so that software may read the received ACK value; when receiving data (i.e., receiving address/data, sending an ACK), this interrupt is generated before the ACK cycle so that software may define the outgoing ACK value. If hardware acknowledgement is enabled, these interrupts are always generated after the ACK cycle. See Section 22.5 for more details on transmission sequences.

Interrupts are also generated to indicate the beginning of a transfer when a master (START generated), or the end of a transfer when a slave (STOP detected). Software should read the SMB0CN (SMBus Control register) to find the cause of the SMBus interrupt. The SMB0CN register is described in Section 22.4.2; Table 22.5 provides a quick SMB0CN decoding reference.

# C8051F99x-C8051F98x

## 24. Enhanced Serial Peripheral Interface (SPI0)

The Enhanced Serial Peripheral Interface (SPI0) provides access to a flexible, full-duplex synchronous serial bus. SPI0 can operate as a master or slave device in both 3-wire or 4-wire modes, and supports multiple masters and slaves on a single SPI bus. The slave-select (NSS) signal can be configured as an input to select SPI0 in slave mode, or to disable Master Mode operation in a multi-master environment, avoiding contention on the SPI bus when more than one master attempts simultaneous data transfers. NSS can also be configured as a chip-select output in master mode, or disabled for 3-wire operation. Additional general purpose port I/O pins can be used to select multiple slave devices in master mode.

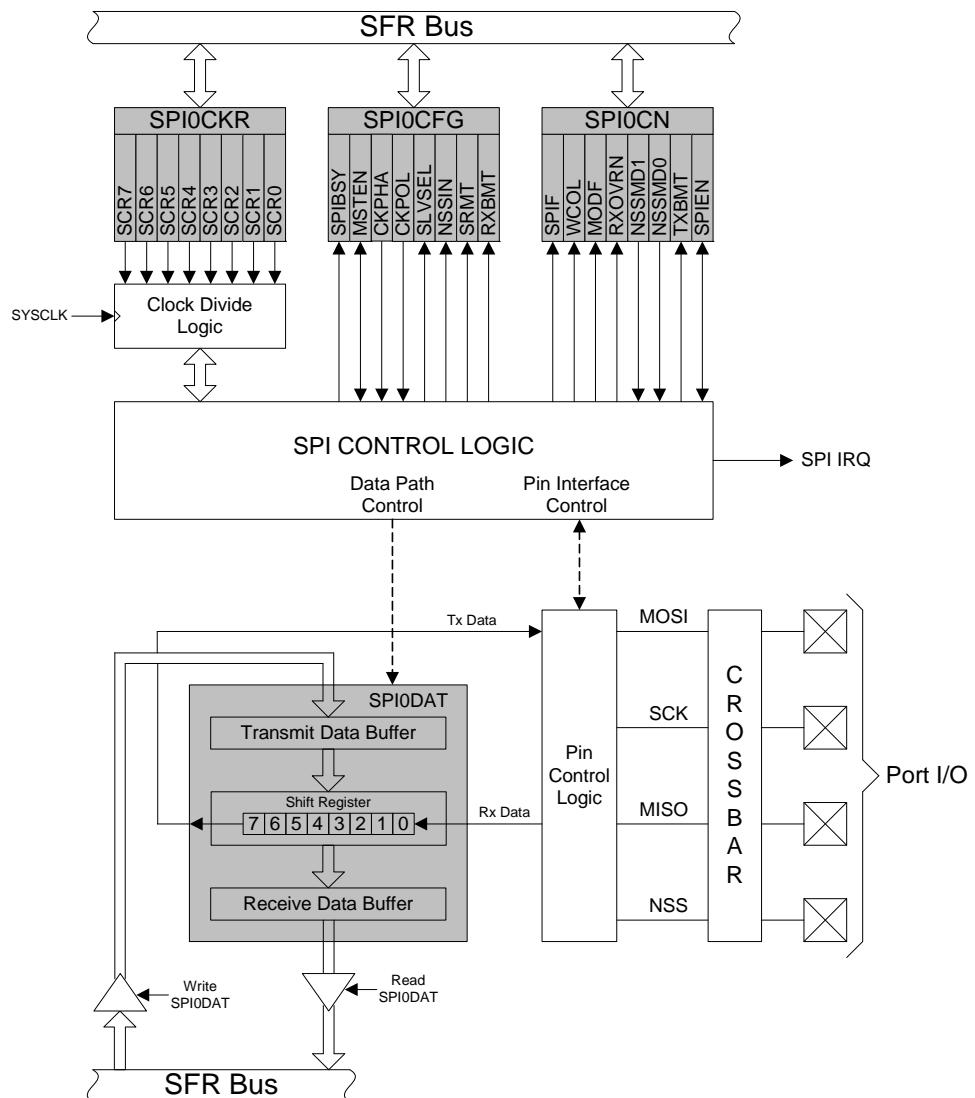


Figure 24.1. SPI Block Diagram

# C8051F99x-C8051F98x

## 26.3.1. Edge-triggered Capture Mode

In this mode, a valid transition on the CEXn pin causes the PCA to capture the value of the PCA counter/timer and load it into the corresponding module's 16-bit capture/compare register (PCA0CPLn and PCA0CPHn). The CAPPn and CAPNn bits in the PCA0CPMn register are used to select the type of transition that triggers the capture: low-to-high transition (positive edge), high-to-low transition (negative edge), or either transition (positive or negative edge). When a capture occurs, the Capture/Compare Flag (CCFn) in PCA0CN is set to logic 1. An interrupt request is generated if the CCFn interrupt for that module is enabled. The CCFn bit is not automatically cleared by hardware when the CPU vectors to the interrupt service routine, and must be cleared by software. If both CAPPn and CAPNn bits are set to logic 1, then the state of the Port pin associated with CEXn can be read directly to determine whether a rising-edge or falling-edge caused the capture.

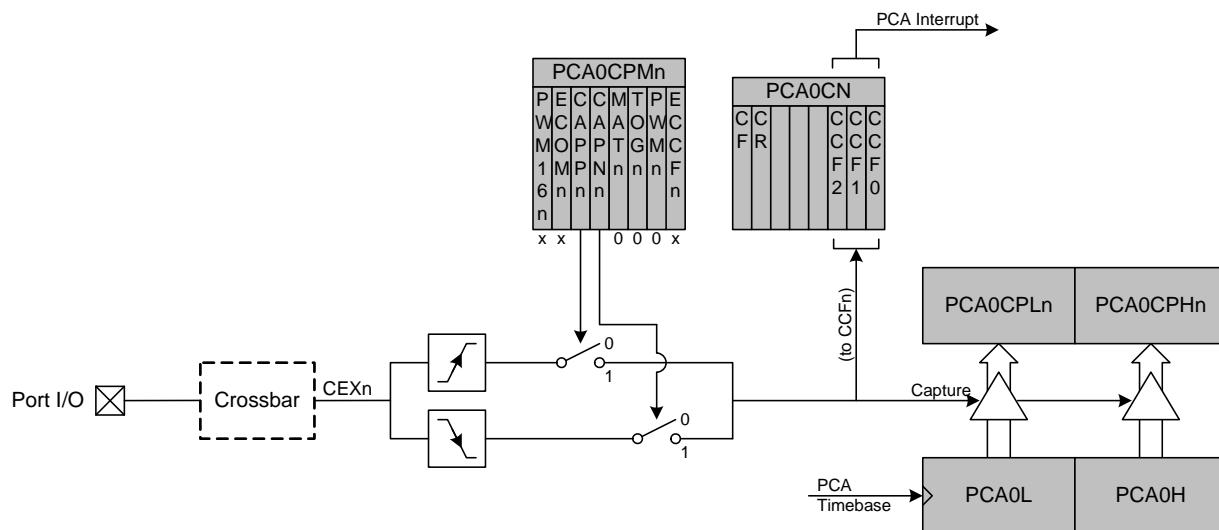


Figure 26.4. PCA Capture Mode Diagram

**Note:** The CEXn input signal must remain high or low for at least 2 system clock cycles to be recognized by the hardware.

# C8051F99x-C8051F98x

## SFR Definition 26.2. PCA0MD: PCA Mode

Bit	7	6	5	4	3	2	1	0
Name	CIDL	WDTE	WDLCK		CPS2	CPS1	CPS0	ECF
Type	R/W	R/W	R/W	R	R/W	R/W	R/W	R/W
Reset	0	1	0	0	0	0	0	0

SFR Page = 0x0; SFR Address = 0xD9

Bit	Name	Function
7	CIDL	<b>PCA Counter/Timer Idle Control.</b> Specifies PCA behavior when CPU is in Idle Mode. 0: PCA continues to function normally while the system controller is in Idle Mode. 1: PCA operation is suspended while the system controller is in Idle Mode.
6	WDTE	<b>Watchdog Timer Enable.</b> If this bit is set, PCA Module 2 is used as the watchdog timer. 0: Watchdog Timer disabled. 1: PCA Module 2 enabled as Watchdog Timer.
5	WDLCK	<b>Watchdog Timer Lock.</b> This bit locks/unlocks the Watchdog Timer Enable. When WDLCK is set, the Watchdog Timer may not be disabled until the next system reset. 0: Watchdog Timer Enable unlocked. 1: Watchdog Timer Enable locked.
4	Unused	Read = 0b, Write = don't care.
3:1	CPS[2:0]	<b>PCA Counter/Timer Pulse Select.</b> These bits select the timebase source for the PCA counter 000: System clock divided by 12 001: System clock divided by 4 010: Timer 0 overflow 011: High-to-low transitions on ECI (max rate = system clock divided by 4) 100: System clock 101: External clock divided by 8 (synchronized with the system clock) 110: SmRTClock divided by 8 (synchronized with the system clock) 111: Reserved
0	ECF	<b>PCA Counter/Timer Overflow Interrupt Enable.</b> This bit sets the masking of the PCA Counter/Timer Overflow (CF) interrupt. 0: Disable the CF interrupt. 1: Enable a PCA Counter/Timer Overflow interrupt request when CF (PCA0CN.7) is set.
<b>Note:</b> When the WDTE bit is set to 1, the other bits in the PCA0MD register cannot be modified. To change the contents of the PCA0MD register, the Watchdog Timer must first be disabled.		