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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Not For New Designs
Core Processor	M32C/80
Core Size	16/32-Bit
Speed	32MHz
Connectivity	CANbus, I²C, IEBus, SIO, UART/USART
Peripherals	DMA, WDT
Number of I/O	121
Program Memory Size	512KB (512K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	24K x 8
Voltage - Supply (Vcc/Vdd)	3V ~ 5.5V
Data Converters	A/D 34x10b; D/A 2x8b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	144-LQFP
Supplier Device Package	144-LFQFP (20x20)
Purchase URL	https://www.e-xfl.com/product-detail/renesas-electronics-america/m30855fjgp-u3

1.2 Performance Overview

Tables 1.1 and 1.2 list performance overview of the M32C/85 group (M32C/85, M32C/85T).

Table 1.1 M32C/85 Group (M32C/85, M32C/85T) Performance (144-Pin Package)

Characteristic		Performance	
		M32C/85	M32C/85T
CPU	Basic Instructions	108 instructions	
	Minimum Instruction Execution Time	31.3 ns (f(BCLK)=32 MHz, V_{CC1}=4.2 V to 5.5 V) 41.7 ns (f(BCLK)=24 MHz, V_{CC1}=3.0 V to 5.5 V)	31.3 ns (f(BCLK)=32 MHz, V_{CC1}=4.2 V to 5.5 V)
	Operating Mode	Single-chip mode, Memory expansion mode and Microprocessor mode	Single-chip mode
	Address Space	16 Mbytes	
	Memory Capacity	See Table 1.3	
Peripheral Function	I/O Port	123 I/O pins and 1 input pin	
	Multifunction Timer	Timer A: 16 bits x 5 channels, Timer B: 16 bits x 6 channels Three-phase motor control circuit	
	Intelligent I/O	Time measurement function or Waveform generating function: 16 bits x 8 channels Communication function (Clock synchronous serial I/O, Clock asynchronous serial I/O, HDLC data processing)	
	Serial I/O	5 Channels Clock synchronous serial I/O, Clock asynchronous serial I/O, IEBus(1), I^2C bus(2)	
	CAN Module	2 channels Supporting CAN 2.0B specification	
	A/D Converter	10-bit A/D converter: 1 circuit, 34 channels	
	D/A Converter	8 bits x 2 channels	
	DMAC	4 channels	
	DMAC II	Can be activated by all peripheral function interrupt sources Immediate transfer, Calculation transfer and Chain transfer functions	
	CRC Calculation Circuit	CRC-CCITT	
	X/Y Converter	16 bits x 16 bits	
	Watchdog Timer	15 bits x 1 channel (with prescaler)	
	Interrupt	39 internal and 8 external sources, 5 software sources Interrupt priority level: 7	
	Clock Generation Circuit	4 circuits Main clock oscillation circuit(*), Sub clock oscillation circuit(*), On-chip oscillator, PLL frequency synthesizer (*)Equipped with a built-in feedback resistor. Ceramic resonator or crystal oscillator must be connected externally	
	Oscillation Stop Detect Function	Main clock oscillation stop detect function	
	Voltage Detection Circuit	Available (optional)	Not available(4)
Electrical Characteristics	Supply Voltage	V_{CC1}=4.2 V to 5.5 V, V_{CC2}=3.0 V to V_{CC1} (f(BCLK)=32 MHz) V_{CC1}=3.0 V to 5.5 V, V_{CC2}=3.0 V to V_{CC1} (f(BCLK)=24 MHz)	V_{CC1}=V_{CC2}=4.2 V to 5.5 V, (f(BCLK)=32 MHz)(3)
	Power Consumption	28 mA (V_{CC1}=V_{CC2}=5 V, f(BCLK)=32 MHz) 22 mA (V_{CC1}=V_{CC2}=3.3 V, f(BCLK)=24 MHz) 10µA (V_{CC1}=V_{CC2}=5 V, f(BCLK)=32 kHz, in wait mode)	28 mA (V_{CC1}=V_{CC2}=5 V, f(BCLK)=32 MHz) 10µA (V_{CC1}=V_{CC2}=5 V, f(BCLK)=32 kHz, in wait mode)
Flash Memory	Program/Erase Supply Voltage	3.3 V ± 0.3 V or 5.0 V ± 0.5 V	5.0 V ± 0.5 V
	Program and Erase Endurance	100 times (all space)	
Operating Ambient Temperature		–20 to 85°C –40 to 85°C (optional)	–40 to 85°C (T version)
Package		144-pin plastic molded LQFP	

NOTES:
1. IEBus is a trademark of NEC Electronics Corporation.
2. I^2C bus is a trademark of Koninklijke Philips Electronics N. V.
3. The supply voltage of M32C/85T (High-reliability version) must be V_{CC1}=V_{CC2}.
4. The cold start-up/warm start-up determine function is available only at the user's option.

All options are on a request basis.

Table 1.5 Pin Characteristics for 100-Pin Package (Continued)

Package Pin No.		Control Pin	Port	Interrupt Pin	Timer Pin	UART/CAN Pin	Intelligent I/O Pin	Analog Pin	Bus Control Pin(1)
FP	GP								
51	49		$P4_3$						A_{19}
52	50		$P4_2$						A_{18}
53	51		$P4_1$						A_{17}
54	52		$P4_0$						A_{16}
55	53		$P3_7$						A_{15}(/D_{15})
56	54		$P3_6$						A_{14}(/D_{14})
57	55		$P3_5$						A_{13}(/D_{13})
58	56		$P3_4$						A_{12}(/D_{12})
59	57		$P3_3$						A_{11}(/D_{11})
60	58		$P3_2$						A_{10}(/D_{10})
61	59		$P3_1$						A_9(/D_9)
62	60	V_{CC2}							
63	61		$P3_0$						A_8(/D_8)
64	62	V_{SS}							
65	63		$P2_7$					$AN2_7$	A_7(/D_7)
66	64		$P2_6$					$AN2_6$	A_6(/D_6)
67	65		$P2_5$					$AN2_5$	A_5(/D_5)
68	66		$P2_4$					$AN2_4$	A_4(/D_4)
69	67		$P2_3$					$AN2_3$	A_3(/D_3)
70	68		$P2_2$					$AN2_2$	A_2(/D_2)
71	69		$P2_1$					$AN2_1$	A_1(/D_1)
72	70		$P2_0$					$AN2_0$	A_0(/D_0)
73	71		$P1_7$	$\overline{INT5}$					D_{15}
74	72		$P1_6$	$\overline{INT4}$					D_{14}
75	73		$P1_5$	$\overline{INT3}$					D_{13}
76	74		$P1_4$						D_{12}
77	75		$P1_3$						D_{11}
78	76		$P1_2$						D_{10}
79	77		$P1_1$						D_9
80	78		$P1_0$						D_8
81	79		$P0_7$					$AN0_7$	D_7
82	80		$P0_6$					$AN0_6$	D_6
83	81		$P0_5$					$AN0_5$	D_5
84	82		$P0_4$					$AN0_4$	D_4
85	83		$P0_3$					$AN0_3$	D_3
86	84		$P0_2$					$AN0_2$	D_2
87	85		$P0_1$					$AN0_1$	D_1
88	86		$P0_0$					$AN0_0$	D_0
89	87		$P10_7$	$\overline{KI_3}$				AN_7	
90	88		$P10_6$	$\overline{KI_2}$				AN_6	
91	89		$P10_5$	$\overline{KI_1}$				AN_5	
92	90		$P10_4$	$\overline{KI_0}$				AN_4	
93	91		$P10_3$					AN_3	
94	92		$P10_2$					AN_2	
95	93		$P10_1$					AN_1	
96	94	AV_{SS}							
97	95		$P10_0$					AN_0	
98	96	V_{REF}							
99	97	AV_{CC}							
100	98		$P9_7$			RxD4/SCL4/STxD4		$\overline{ADTRG}$	

NOTES:

1. Bus control pins in M32C/85T cannot be used.

1.6 Pin Description

Table 1.6 Pin Description (100-Pin and 144-Pin Packages)

Classsfication	Symbol	I/O Type	Supply Voltage	Function
Power Supply	V_{CC1}, V_{CC2} V_{SS}	I	–	Apply 3.0 to 5.5V to both V_{CC1} and V_{CC2} pins. Apply 0V to the V_{SS} pin. $V_{CC1} \geq V_{CC2}$(1, 2)
Analog Power Supply	AVCC AVSS	I	V_{CC1}	Supplies power to the A/D converter. Connect the AVCC pin to V_{CC1} and the AVSS pin to V_{SS}
Reset Input	$\overline{RESET}$	I	V_{CC1}	The microcomputer is in a reset state when "L" is applied to the $\overline{RESET}$ pin
CNVSS	CNVSS	I	V_{CC1}	Switches processor mode. Connect the CNVSS pin to V_{SS} to start up in single-chip mode or to V_{CC1} to start up in microprocessor mode
Input to Switch External Data Bus Width(3)	BYTE	I	V_{CC1}	Switches data bus width in external memory space 3. The data bus is 16 bits wide when the BYTE pin is held "L" and 8 bits wide when it is held "H". Set to either. Connect the BYTE pin to V_{SS} to use the microcomputer in single-chip mode
Bus Control Pins(3)	D_0 to D_7	I/O	V_{CC2}	Inputs and outputs data (D_0 to D_7) while accessing an external memory space with separate bus
	D_8 to D_{15}	I/O	V_{CC2}	Inputs and outputs data (D_8 to D_{15}) while accessing an external memory space with 16-bit separate bus
	A_0 to A_{22}	O	V_{CC2}	Outputs address bits A_0 to A_{22}
	$\overline{A_{23}}$	O	V_{CC2}	Outputs inversed address bit A_{23}
	A_0/D_0 to A_7/D_7	I/O	V_{CC2}	Inputs and outputs data (D_0 to D_7) and outputs 8 low-order address bits (A_0 to A_7) by time-sharing while accessing an external memory space with multiplexed bus
	A_8/D_8 to A_{15}/D_{15}	I/O	V_{CC2}	Inputs and outputs data (D_8 to D_{15}) and outputs 8 middle-order address bits (A_8 to A_{15}) by time-sharing while accessing an external memory space with 16-bit multiplexed bus
	$\overline{CS0}$ to $\overline{CS3}$	O	V_{CC2}	Outputs $\overline{CS0}$ to $\overline{CS3}$ that are chip-select signals specifying an external space
	$\overline{WRL}$ / $\overline{WR}$ $\overline{WRH}$ / $\overline{BHE}$ $\overline{RD}$	O	V_{CC2}	Outputs $\overline{WRL}$, $\overline{WRH}$, ($\overline{WR}$, $\overline{BHE}$) and $\overline{RD}$ signals. $\overline{WRL}$ and $\overline{WRH}$ can be switched with $\overline{WR}$ and $\overline{BHE}$ by program ■ $\overline{WRL}$, $\overline{WRH}$ and $\overline{RD}$ selected: If external data bus is 16 bits wide, data is written to an even address in external memory space when $\overline{WRL}$ is held "L". Data is written to an odd address when $\overline{WRH}$ is held "L". Data is read when $\overline{RD}$ is held "L". ■ $\overline{WR}$, $\overline{BHE}$ and $\overline{RD}$ selected: Data is written to external memory space when $\overline{WR}$ is held "L". Data in an external memory space is read when $\overline{RD}$ is held "L". An odd address is accessed when $\overline{BHE}$ is held "L". Select $\overline{WR}$, $\overline{BHE}$ and $\overline{RD}$ for external 8-bit data bus.
	ALE	O	V_{CC2}	ALE is a signal latching the address
	$\overline{HOLD}$	I	V_{CC2}	The microcomputer is placed in a hold state while the $\overline{HOLD}$ pin is held "L"
	$\overline{HLDA}$	O	V_{CC2}	Outputs an "L" signal while the microcomputer is placed in a hold state
	$\overline{RDY}$	I	V_{CC2}	Bus is placed in a wait state while the $\overline{RDY}$ pin is held "L"

I : Input O : Output I/O : Input and output

NOTES:
1. V_{CC1} is hereinafter referred to as V_{CC} unless otherwise noted.
2. Apply 4.2 to 5.5V to the V_{CC1} and V_{CC2} pins when using M32C/85T. V_{CC1}=V_{CC2}.
3. Bus control pins in M32C/85T cannot be used.

Table 1.6 Pin Description (100-Pin and 144-Pin Packages) (Continued)

Classsfication	Symbol	I/O Type	Supply Voltage	Function
Reference Voltage Input	V_{REF}	I	-	Applies reference voltage to the A/D converter and D/A converter
A/D Converter	AN_0 to AN_7 $AN0_0$ to $AN0_7$ $AN2_0$ to $AN2_7$	I	V_{CC1}	Analog input pins for the A/D converter
	$\overline{ADTRG}$	I	V_{CC1}	Input pin for an external A/D trigger
	ANEX0	I/O	V_{CC1}	Extended analog input pin for the A/D converter and output pin in external op-amp connection mode
	ANEX1	I	V_{CC1}	Extended analog input pin for the A/D converter
D/A Converter	DA0, DA1	O	V_{CC1}	Output pin for the D/A converter
Intelligent I/O	$INPC1_0$ to $INPC1_3$	I	V_{CC1}/V_{CC2}(1)	Input pins for the time measurement function
	$INPC1_4$ to $INPC1_7$		V_{CC1}	
	$OUTC1_0$ to $OUTC1_3$	O	V_{CC1}/V_{CC2}(1)	Output pins for the waveform generating function
	$OUTC1_4$ to $OUTC1_7$		V_{CC1}	($OUTC1_6$ and $OUTC1_7$ assigned to $P7_0$ and $P7_1$ are pins for the N-channel open drain output.)
	ISCLK0	I/O	V_{CC1}	Inputs and outputs the clock for the intelligent I/O communication function
	ISCLK1		V_{CC1}/V_{CC2}(1)	
	ISRXD0	I	V_{CC1}	Inputs data for the intelligent I/O communication function
	ISRXD1		V_{CC1}/V_{CC2}(1)	
	ISTXD0	O	V_{CC1}	Outputs data for the intelligent I/O communication function
	ISTXD1		V_{CC1}/V_{CC2}(1)	
	$BE1_{IN}$	I	V_{CC1}/V_{CC2}(1)	Inputs data for the intelligent I/O communication function
	$BE1_{OUT}$	O	V_{CC1}/V_{CC2}(1)	Outputs data for the intelligent I/O communication function
CAN	$CAN0_{IN}$	I	V_{CC1}	Input pin for the CAN communication function
	$CAN1_{IN}$			
	$CAN0_{OUT}$	O		Output pin for the CAN communication function
	$CAN1_{OUT}$			
	$\overline{CAN1WU}$	I		Input pin for the CAN1 wake-up interrupt
I/O Ports	$P0_0$ to $P0_7$ $P1_0$ to $P1_7$ $P2_0$ to $P2_7$ $P3_0$ to $P3_7$ $P4_0$ to $P4_7$ $P5_0$ to $P5_7$	I/O	V_{CC2}	I/O ports for CMOS. Each port can be programmed for input or output under the control of the direction register. An input port can be set, by program, for a pull-up resistor available or for no pull-up resister available in 4-bit units
	$P6_0$ to $P6_7$ $P7_0$ to $P7_7$ $P9_0$ to $P9_7$ $P10_0$ to $P10_7$	I/O	V_{CC1}	I/O ports having equivalent functions to P0 ($P7_0$ and $P7_1$ are ports for the N-channel open drain output.)
	$P8_0$ to $P8_4$ $P8_6$, $P8_7$	I/O	V_{CC1}	I/O ports having equivalent functions to P0
Input Port	$P8_5$	I	V_{CC1}	Shares a pin with $\overline{NMI}$. $\overline{NMI}$ input state can be got by reading $P8_5$

I : Input O : Output I/O : Input and output

NOTES:

1. V_{CC2} is not available in the 100-pin package. V_{CC1} only available.

Address	Register	Symbol	Value after RESET
006016			
006116			
006216			
006316			
006416			
006516			
006616			
006716			
006816	DMA0 Interrupt Control Register	DM0IC	XXXX X0002
006916	Timer B5 Interrupt Control Register	TB5IC	XXXX X0002
006A16	DMA2 Interrupt Control Register	DM2IC	XXXX X0002
006B16	UART2 Receive /ACK Interrupt Control Register	S2RIC	XXXX X0002
006C16	Timer A0 Interrupt Control Register	TA0IC	XXXX X0002
006D16	UART3 Receive /ACK Interrupt Control Register	S3RIC	XXXX X0002
006E16	Timer A2 Interrupt Control Register	TA2IC	XXXX X0002
006F16	UART4 Receive /ACK Interrupt Control Register	S4RIC	XXXX X0002
007016	Timer A4 Interrupt Control Register	TA4IC	XXXX X0002
007116	UART0/UART3 Bus Conflict Detect Interrupt Control Register	BCN0IC/BCN3IC	XXXX X0002
007216	UART0 Receive/ACK Interrupt Control Register	S0RIC	XXXX X0002
007316	A/D0 Conversion Interrupt Control Register	AD0IC	XXXX X0002
007416	UART1 Receive/ACK Interrupt Control Register	S1RIC	XXXX X0002
007516	Intelligent I/O Interrupt Control Register 0/ CAN Interrupt 3 Control Register	IIO0IC/ CAN3IC	XXXX X0002
007616	Timer B1 Interrupt Control Register	TB1IC	XXXX X0002
007716	Intelligent I/O Interrupt Control Register 2	IIO2IC	XXXX X0002
007816	Timer B3 Interrupt Control Register	TB3IC	XXXX X0002
007916	Intelligent I/O Interrupt Control Register 4	IIO4IC	XXXX X0002
007A16	INT5 Interrupt Control Register	INT5IC	XX00 X0002
007B16			
007C16	INT3 Interrupt Control Register	INT3IC	XX00 X0002
007D16	Intelligent I/O Interrupt Control Register 8	IIO8IC	XXXX X0002
007E16	INT1 Interrupt Control Register	INT1IC	XX00 X0002
007F16	Intelligent I/O Interrupt Control Register 10/ CAN Interrupt 1 Control Register	IIO10IC/ CAN1IC	XXXX X0002
008016			
008116	CAN Interrupt 2 Control Register	CAN2IC	XXXX X0002
008216			
008316			
008416			
008516			
008616			
008716			
008816	DMA1 Interrupt Control Register	DM1IC	XXXX X0002
008916	UART2 Transmit /NACK Interrupt Control Register	S2TIC	XXXX X0002
008A16	DMA3 Interrupt Control Register	DM3IC	XXXX X0002
008B16	UART3 Transmit /NACK Interrupt Control Register	S3TIC	XXXX X0002
008C16	Timer A1 Interrupt Control Register	TA1IC	XXXX X0002
008D16	UART4 Transmit /NACK Interrupt Control Register	S4TIC	XXXX X0002
008E16	Timer A3 Interrupt Control Register	TA3IC	XXXX X0002
008F16	UART2 Bus Conflict Detect Interrupt Control Register	BCN2IC	XXXX X0002

X: Indeterminate

Blank spaces are reserved. No access is allowed.

Address	Register	Symbol	Value after RESET
0150₁₆			
0151₁₆			
0152₁₆			
0153₁₆			
0154₁₆			
0155₁₆			
0156₁₆			
0157₁₆			
0158₁₆			
0159₁₆			
015A₁₆			
015B₁₆			
015C₁₆			
015D₁₆			
015E₁₆			
015F₁₆			
0160₁₆			
0161₁₆			
0162₁₆			
0163₁₆			
0164₁₆			
0165₁₆			
0166₁₆			
0167₁₆			
0168₁₆			
0169₁₆			
016A₁₆			
016B₁₆			
016C₁₆			
016D₁₆			
016E₁₆			
016F₁₆			
0170₁₆			
0171₁₆			
0172₁₆			
0173₁₆			
0174₁₆			
0175₁₆			
0176₁₆			
0177₁₆			
0178₁₆	Input Function Select Register	IPS	00₁₆
0179₁₆	Input Function Select Register A	IPSA	00₁₆
017A₁₆			
017B₁₆			
017C₁₆			
017D₁₆ to 01DF₁₆			

X: Indeterminate

Blank spaces are reserved. No access is allowed.

Address	Register	Symbol	Value after RESET
023A16	CAN0 Message Slot 10 Control Register / CAN0 Local Mask Register B Extended ID0	C0MCTL10/ C0LMBR2	0000 00002(2) XXXX 00002(2)
023B16	CAN0 Message Slot 11 Control Register / CAN0 Local Mask Register B Extended ID1	C0MCTL11/ C0LMBR3	0016(2) 0016(2)
023C16	CAN0 Message Slot 12 Control Register / CAN0 Local Mask Register B Extended ID2	C0MCTL12/ C0LMBR4	0000 00002(2) XX00 00002(2)
023D16	CAN0 Message Slot 13 Control Register	C0MCTL13	0016(2)
023E16	CAN0 Message Slot 14 Control Register	C0MCTL14	0016(2)
023F16	CAN0 Message Slot 15 Control Register	C0MCTL15	0016(2)
024016	CAN0 Slot Buffer Select Register	C0SBS	0016(2)
024116	CAN0 Control Register 1	C0CTLR1	X000 00XX2(2)
024216	CAN0 Sleep Control Register	C0SLPR	XXXX XXX02
024316			
024416 024516	CAN0 Acceptance Filter Support Register	C0AFS	0016(2) 0116(2)
024616			
024716			
024816			
024916			
024A16			
024B16			
024C16			
024D16			
024E16			
024F16			
025016	CAN1 Slot Buffer Select Register	C1SBS	0016(3)
025116	CAN1 Control Register 1	C1CTLR1	X000 00XX2(3)
025216	CAN1 Sleep Control Register	C1SLPR	XXXX XXX02
025316			
025416 025516	CAN1 Acceptance Filter Support Register	C1AFS	0016(3) 0116(3)
025616			
025716			
025816			
025916			
025A16			
025B16			
025C16			
025D16			
025E16			
025F16			

(Note 1)

X: Indeterminate

Blank spaces are reserved. No access is allowed.

NOTES:

1. The BANKSEL bit in the C0CTLR1 register switches functions for addresses 022016 to 023F16.
2. Values are obtained by setting the SLEEP bit in the C0SLPR register to "1" (sleep mode exited) after reset and applying the clock to the CAN module.
3. Values are obtained by setting the SLEEP bit in the C1SLPR register to "1" (sleep mode exited) after reset and applying the clock to the CAN module.

Address	Register	Symbol	Value after RESET
02BA16	CAN1 Message Slot 10 Control Register / CAN1 Local Mask Register B Extended ID0	C1MCTL10/ C1LMBR2	0000 00002(2) XXXX 00002(2)
02BB16	CAN1 Message Slot 11 Control Register / CAN1 Local Mask Register B Extended ID1	C1MCTL11/ C1LMBR3	0016(2) 0016(2)
02BC16	CAN1 Message Slot 12 Control Register / CAN1 Local Mask Register B Extended ID2	C1MCTL12/ C1LMBR4	0000 00002(2) XX00 00002(2)
02BD16	CAN1 Message Slot 13 Control Register	C1MCTL13	0016(2)
02BE16	CAN1 Message Slot 14 Control Register	C1MCTL14	0016(2)
02BF16	CAN1 Message Slot 15 Control Register	C1MCTL15	0016(2)
02C016 02C116	X0 Register Y0 Register	X0R,Y0R	XX16 XX16
02C216 02C316	X1 Register Y1 Register	X1R,Y1R	XX16 XX16
02C416 02C516	X2 Register Y2 Register	X2R,Y2R	XX16 XX16
02C616 02C716	X3 Register Y3 Register	X3R,Y3R	XX16 XX16
02C816 02C916	X4 Register Y4 Register	X4R,Y4R	XX16 XX16
02CA16 02CB16	X5 Register Y5 Register	X5R,Y5R	XX16 XX16
02CC16 02CD16	X6 Register Y6 Register	X6R,Y6R	XX16 XX16
02CE16 02CF16	X7 Register Y7 Register	X7R,Y7R	XX16 XX16
02D016 02D116	X8 Register Y8 Register	X8R,Y8R	XX16 XX16
02D216 02D316	X9 Register Y9 Register	X9R,Y9R	XX16 XX16
02D416 02D516	X10 Register Y10 Register	X10R,Y10R	XX16 XX16
02D616 02D716	X11 Register Y11 Register	X11R,Y11R	XX16 XX16
02D816 02D916	X12 Register Y12 Register	X12R,Y12R	XX16 XX16
02DA16 02DB16	X13 Register Y13 Register	X13R,Y13R	XX16 XX16
02DC16 02DD16	X14 Register Y14 Register	X14R,Y14R	XX16 XX16
02DE16 02DF16	X15 Register Y15 Register	X15R,Y15R	XX16 XX16

(Note 1)

X: Indeterminate

Blank spaces are reserved. No access is allowed.

NOTES:

1. The BANKSEL bit in the C1CTLR1 register switches functions for addresses 02A016 to 02BF16.
2. Values are obtained by setting the SLEEP bit in the C1SLPR register to "1" (sleep mode exited) after reset and applying the clock to the CAN module.

Table 5.2 Recommended Operating Conditions

(V_{CC1}= V_{CC2}=3.0V to 5.5V at Topr=– 20 to 85°C unless otherwise specified)

Symbol	Parameter		Standard			Unit
			Min.	Typ.	Max.	
V_{CC1}, V_{CC2}	Supply Voltage (V_{CC1}≥ V_{CC2})		3.0	5.0	5.5	V
AVCC	Analog Supply Voltage			V_{CC1}		V
VSS	Supply Voltage			0		V
AVSS	Analog Supply Voltage			0		V
V_{IH}	Input High ("H") Voltage	$P2_0$-$P2_7$, $P3_0$-$P3_7$, $P4_0$-$P4_7$, $P5_0$-$P5_7$, $P11_0$-$P11_4$, $P12_0$-$P12_7$, $P13_0$-$P13_7$(4)	0.8V_{CC2}		V_{CC2}	V
		$P6_0$-$P6_7$, $P7_2$-$P7_7$, $P8_0$-$P8_7$(3), $P9_0$-$P9_7$, $P10_0$-$P10_7$, $P14_0$-$P14_6$, $P15_0$-$P15_7$(4), X_{IN}, $\overline{RESET}$, CNV_{SS}, BYTE	0.8V_{CC1}		V_{CC1}	
		$P7_0$, $P7_1$	0.8V_{CC1}		6.0	
		$P0_0$-$P0_7$, $P1_0$-$P1_7$ (in single-chip mode)	0.8V_{CC2}		V_{CC2}	
		$P0_0$-$P0_7$, $P1_0$-$P1_7$ (in memory expansion mode and microprocesor mode)	0.5V_{CC2}		V_{CC2}	
V_{IL}	Input Low ("L") Voltage	$P2_0$-$P2_7$, $P3_0$-$P3_7$, $P4_0$-$P4_7$, $P5_0$-$P5_7$, $P11_0$-$P11_4$, $P12_0$-$P12_7$, $P13_0$-$P13_7$(4)	0		0.2V_{CC2}	V
		$P6_0$-$P6_7$, $P7_0$-$P7_7$, $P8_0$-$P8_7$(3), $P9_0$-$P9_7$, $P10_0$-$P10_7$, $P14_0$-$P14_6$, $P15_0$-$P15_7$(4), X_{IN}, $\overline{RESET}$, CNV_{SS}, BYTE	0		0.2V_{CC1}	
		$P0_0$-$P0_7$, $P1_0$-$P1_7$ (in single-chip mode)	0		0.2V_{CC2}	
		$P0_0$-$P0_7$, $P1_0$-$P1_7$ (in memory expansion mode and microprocesor mode)	0		0.16V_{CC2}	
$I_{OH(peak)}$	Peak Output High ("H") Current(2)	$P0_0$-$P0_7$, $P1_0$-$P1_7$, $P2_0$-$P2_7$, $P3_0$-$P3_7$, $P4_0$-$P4_7$, $P5_0$-$P5_7$, $P6_0$-$P6_7$, $P7_2$-$P7_7$, $P8_0$-$P8_4$, $P8_6$, $P8_7$, $P9_0$-$P9_7$, $P10_0$-$P10_7$, $P11_0$-$P11_4$, $P12_0$-$P12_7$, $P13_0$-$P13_7$, $P14_0$-$P14_6$, $P15_0$-$P15_7$(4)			-10.0	mA
$I_{OH(avg)}$	Average Output High ("H") Current(1)	$P0_0$-$P0_7$, $P1_0$-$P1_7$, $P2_0$-$P2_7$, $P3_0$-$P3_7$, $P4_0$-$P4_7$, $P5_0$-$P5_7$, $P6_0$-$P6_7$, $P7_2$-$P7_7$, $P8_0$-$P8_4$, $P8_6$, $P8_7$, $P9_0$-$P9_7$, $P10_0$-$P10_7$, $P11_0$-$P11_4$, $P12_0$-$P12_7$, $P13_0$-$P13_7$, $P14_0$-$P14_6$, $P15_0$-$P15_7$(4)			-5.0	mA
$I_{OL(peak)}$	Peak Output Low ("L") Current(2)	$P0_0$-$P0_7$, $P1_0$-$P1_7$, $P2_0$-$P2_7$, $P3_0$-$P3_7$, $P4_0$-$P4_7$, $P5_0$-$P5_7$, $P6_0$-$P6_7$, $P7_0$-$P7_7$, $P8_0$-$P8_4$, $P8_6$, $P8_7$, $P9_0$-$P9_7$, $P10_0$-$P10_7$, $P11_0$-$P11_4$, $P12_0$-$P12_7$, $P13_0$-$P13_7$, $P14_0$-$P14_6$, $P15_0$-$P15_7$(4)			10.0	mA
$I_{OL(avg)}$	Average Output Low ("L") Current(1)	$P0_0$-$P0_7$, $P1_0$-$P1_7$, $P2_0$-$P2_7$, $P3_0$-$P3_7$, $P4_0$-$P4_7$, $P5_0$-$P5_7$, $P6_0$-$P6_7$, $P7_0$-$P7_7$, $P8_0$-$P8_4$, $P8_6$, $P8_7$, $P9_0$-$P9_7$, $P10_0$-$P10_7$, $P11_0$-$P11_4$, $P12_0$-$P12_7$, $P13_0$-$P13_7$, $P14_0$-$P14_6$, $P15_0$-$P15_7$(4)			5.0	mA

NOTES:

1. Typical values when average output current is 100ms.
2. Total $I_{OL(peak)}$ for P0, P1, P2, $P8_6$, $P8_7$, P9, P10, P11, P14 and P15 must be 80mA or less.
   Total $I_{OL(peak)}$ for P3, P4, P5, P6, P7, $P8_0$ to $P8_4$, P12 and P13 must be 80mA or less.
   Total $I_{OH(peak)}$ for P0, P1, P2, and P11 must be -40mA or less.
   Total $I_{OH(peak)}$ for $P8_6$, $P8_7$, P9, P10, P14 and P15 must be -40mA or less.
   Total $I_{OH(peak)}$ for P3, P4, P5, P12 and P13 must be -40mA or less.
   Total $I_{OH(peak)}$ for P6, P7, and $P8_0$ to $P8_4$ must be -40mA or less.
3. V_{IH} and V_{IL} reference for $P8_7$ applies when $P8_7$ is used as a programmable input port.
   It does not apply when $P8_7$ is used as X_{CIN}.
4. P11 to P15 are provided in the 144-pin package only.

$V_{CC1}=V_{CC2}=5V$

Timing Requirements

($V_{CC1}=V_{CC2}=4.2$ to 5.5V, $V_{SS}=0V$ at Topr=–20 to 85°C unless otherwise specified)

Table 5.11 Timer A Input (Count Source Input in Event Counter Mode)

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{c(TA)}$	TAiIN Input Cycle Time	100		ns
$t_{w(TAH)}$	TAiIN Input High ("H") Width	40		ns
$t_{w(TAL)}$	TAiIN Input Low ("L") Width	40		ns

Table 5.12 Timer A Input (Gate Input in Timer Mode)

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{c(TA)}$	TAiIN Input Cycle Time	400		ns
$t_{w(TAH)}$	TAiIN Input High ("H") Width	200		ns
$t_{w(TAL)}$	TAiIN Input Low ("L") Width	200		ns

Table 5.13 Timer A Input (External Trigger Input in One-Shot Timer Mode)

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{c(TA)}$	TAiIN Input Cycle Time	200		ns
$t_{w(TAH)}$	TAiIN Input High ("H") Width	100		ns
$t_{w(TAL)}$	TAiIN Input Low ("L") Width	100		ns

Table 5.14 Timer A Input (External Trigger Input in Pulse Width Modulation Mode)

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{w(TAH)}$	TAiIN Input High ("H") Width	100		ns
$t_{w(TAL)}$	TAiIN Input Low ("L") Width	100		ns

Table 5.15 Timer A Input (Counter Increment/Decrement Input in Event Counter Mode)

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{c(UP)}$	TAiOUT Input Cycle Time	2000		ns
$t_{w(UPH)}$	TAiOUT Input High ("H") Width	1000		ns
$t_{w(UPL)}$	TAiOUT Input Low ("L") Width	1000		ns
$t_{su(UP-TIN)}$	TAiOUT Input Setup Time	400		ns
$t_{h(TIN-UP)}$	TAiOUT Input Hold Time	400		ns

$V_{CC1}=V_{CC2}=5V$

Timing Requirements

(V_{CC1} = V_{CC2} = 4.2 to 5.5V, V_{SS} = 0V at Topr = –20 to 85°C unless otherwise specified)

Table 5.16 Timer B Input (Count Source Input in Event Counter Mode)

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{c(TB)}$	TBi_{IN} Input Cycle Time (counted on one edge)	100		ns
$t_{w(TBH)}$	TBi_{IN} Input High ("H") Width (counted on one edge)	40		ns
$t_{w(TBL)}$	TBi_{IN} Input Low ("L") Width (counted on one edge)	40		ns
$t_{c(TB)}$	TBi_{IN} Input Cycle Time (counted on both edges)	200		ns
$t_{w(TBH)}$	TBi_{IN} Input High ("H") Width (counted on both edges)	80		ns
$t_{w(TBL)}$	TBi_{IN} Input Low ("L") Width (counted on both edges)	80		ns

Table 5.17 Timer B Input (Pulse Period Measurement Mode)

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{c(TB)}$	TBi_{IN} Input Cycle Time	400		ns
$t_{w(TBH)}$	TBi_{IN} Input High ("H") Width	200		ns
$t_{w(TBL)}$	TBi_{IN} Input Low ("L") Width	200		ns

Table 5.18 Timer B Input (Pulse Width Measurement Mode)

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{c(TB)}$	TBi_{IN} Input Cycle Time	400		ns
$t_{w(TBH)}$	TBi_{IN} Input High ("H") Width	200		ns
$t_{w(TBL)}$	TBi_{IN} Input Low ("L") Width	200		ns

Table 5.19 A/D Trigger Input

Symbol	Parameter	Standard		Unit
		Min.	Max	
$t_{c(AD)}$	$\overline{ADTRG}$ Input Cycle Time (required for trigger)	1000		ns
$t_{w(ADL)}$	$\overline{ADTRG}$ Input Low ("L") Width	125		ns

Table 5.20 Serial I/O

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{c(CK)}$	CLKi Input Cycle Time	200		ns
$t_{w(CKH)}$	CLKi Input High ("H") Width	100		ns
$t_{w(CKL)}$	CLKi Input Low ("L") Width	100		ns
$t_{d(C-Q)}$	TxDi Output Delay Time		80	ns
$t_{h(C-Q)}$	TxDi Hold Time	0		ns
$t_{su(D-C)}$	RxDi Input Setup Time	30		ns
$t_{h(C-Q)}$	RxDi Input Hold Time	90		ns

Table 5.21 External Interrupt $\overline{INTi}$ Input

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{w(INH)}$	$\overline{INTi}$ Input High ("H") Width	250		ns
$t_{w(INL)}$	$\overline{INTi}$ Input Low ("L") Width	250		ns

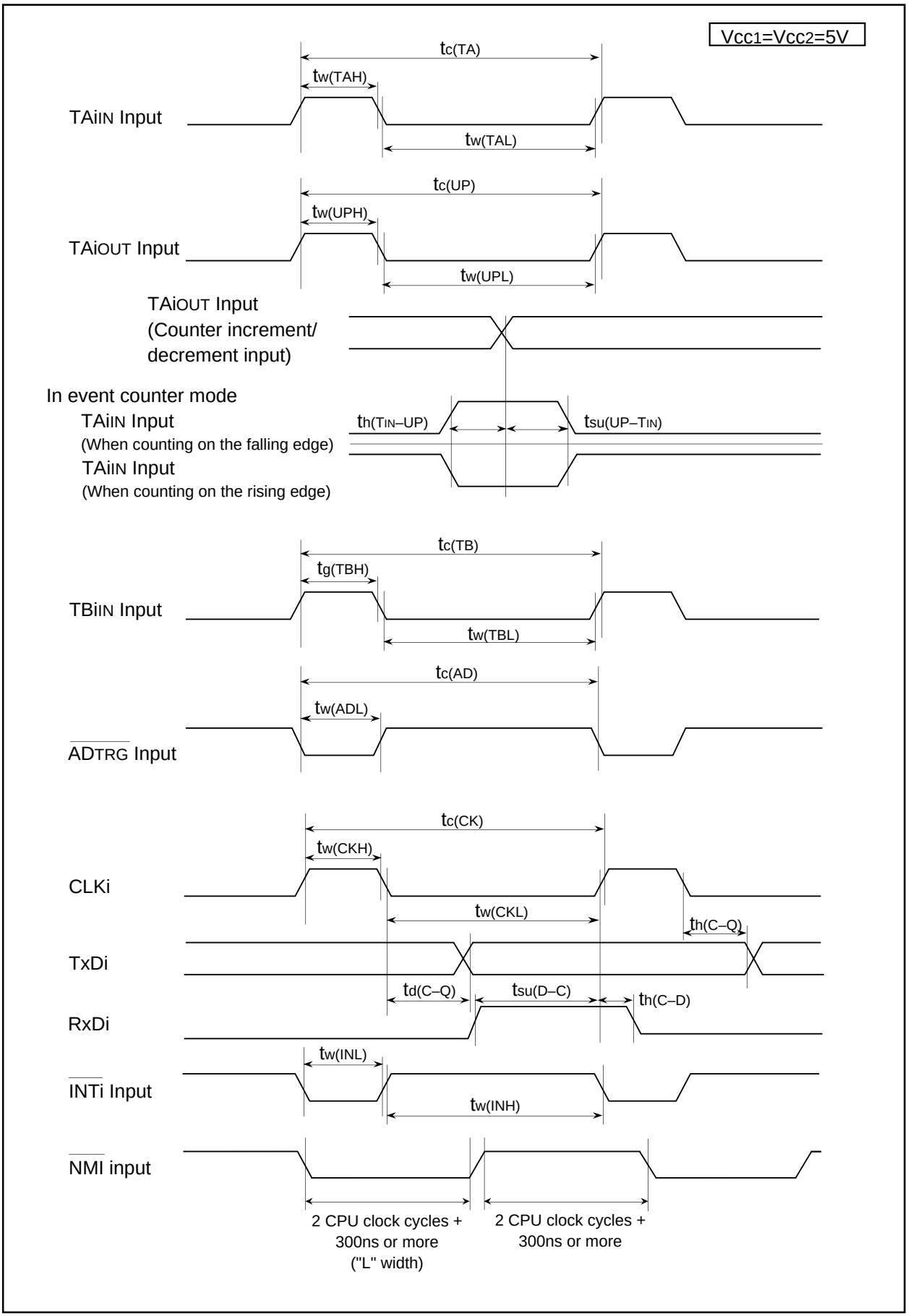


Figure 5.5 Vcc1=Vcc2=5V Timing Diagram (3)

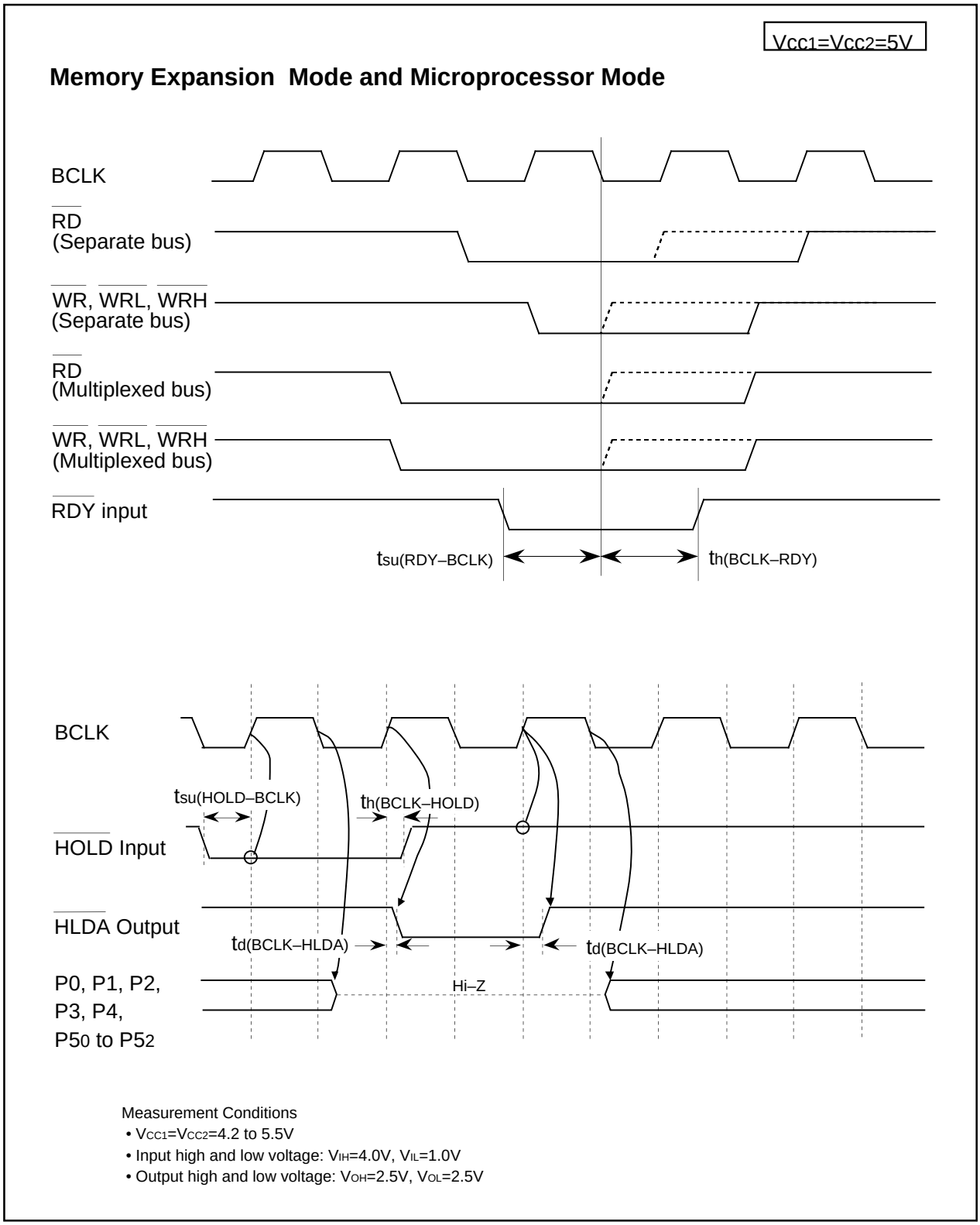


Figure 5.6 Vcc1=Vcc2=5V Timing Diagram (4)

$V_{CC1}=V_{CC2}=3.3V$

Table 5.24 Electrical Characteristics ($V_{CC1}=V_{CC2}=3.0$ to $3.6V$, $V_{SS}=0V$ at Topr = –20 to 85°C, f(BCLK)=24MHz unless otherwise specified)

Symbol	Parameter		Condition		Standard			Unit
					Min.	Typ.	Max.	
V_{OH}	Output High ("H") Voltage	$P0_0$-$P0_7$, $P1_0$-$P1_7$, $P2_0$-$P2_7$, $P3_0$-$P3_7$, $P4_0$-$P4_7$, $P5_0$-$P5_7$, $P11_0$-$P11_4$, $P12_0$-$P12_7$, $P13_0$-$P13_7$	I_{OH}=-1mA		V_{CC2}-0.6		V_{CC2}	V
		$P6_0$-$P6_7$, $P7_2$-$P7_7$, $P8_0$-$P8_4$, $P8_6$, $P8_7$, $P9_0$-$P9_7$, $P10_0$-$P10_7$, $P14_0$-$P14_6$, $P15_0$-$P15_7$(1)			V_{CC1}-0.6		V_{CC1}	V
		X_{OUT}	I_{OH}=-0.1mA		2.7		V_{CC1}	V
		X_{COUT} High Power	No load applied			2.5		V
		X_{COUT} Low Power	No load applied			1.6		V
V_{OL}	Output Low ("L") Voltage	$P0_0$-$P0_7$, $P1_0$-$P1_7$, $P2_0$-$P2_7$, $P3_0$-$P3_7$, $P4_0$-$P4_7$, $P5_0$-$P5_7$, $P6_0$-$P6_7$, $P7_0$-$P7_7$, $P8_0$-$P8_4$, $P8_6$, $P8_7$, $P9_0$-$P9_7$, $P10_0$-$P10_7$, $P11_0$-$P11_4$, $P12_0$-$P12_7$, $P13_0$-$P13_7$, $P14_0$-$P14_6$, $P15_0$-$P15_7$(1)	I_{OL}=1mA				0.5	V
		X_{OUT}	I_{OL}=0.1mA				0.5	V
		X_{COUT} High Power	No load applied			0		V
		X_{COUT} Low Power	No load applied			0		V
V_{T+}-V_{T-}	Hysteresis	$\overline{HOLD}$, $\overline{RDY}$, $TA0_{IN}$-$TA4_{IN}$, $TB0_{IN}$-$TB5_{IN}$, $\overline{INT0}$-$\overline{INT5}$, $\overline{ADTRG}$, $\overline{CTS0}$-$\overline{CTS4}$, CLK0-CLK4, $TA0_{OUT}$-$TA4_{OUT}$, $\overline{NMI}$, $\overline{KI0}$-$\overline{KI3}$, RxD0-RxD4, SCL0-SCL4, SDA0-SDA4			0.2		1.0	V
		$\overline{RESET}$			0.2		1.8	V
I_{IH}	Input High ("H") Current	$P0_0$-$P0_7$, $P1_0$-$P1_7$, $P2_0$-$P2_7$, $P3_0$-$P3_7$, $P4_0$-$P4_7$, $P5_0$-$P5_7$, $P6_0$-$P6_7$, $P7_0$-$P7_7$, $P8_0$-$P8_7$, $P9_0$-$P9_7$, $P10_0$-$P10_7$, $P11_0$-$P11_4$, $P12_0$-$P12_7$, $P13_0$-$P13_7$, $P14_0$-$P14_6$, $P15_0$-$P15_7$(1), X_{IN}, $\overline{RESET}$, CNV_{SS}, BYTE	V_I=3V				4.0	µA
I_{IL}	Input Low ("L") Current	$P0_0$-$P0_7$, $P1_0$-$P1_7$, $P2_0$-$P2_7$, $P3_0$-$P3_7$, $P4_0$-$P4_7$, $P5_0$-$P5_7$, $P6_0$-$P6_7$, $P7_0$-$P7_7$, $P8_0$-$P8_7$, $P9_0$-$P9_7$, $P10_0$-$P10_7$, $P11_0$-$P11_4$, $P12_0$-$P12_7$, $P13_0$-$P13_7$, $P14_0$-$P14_6$, $P15_0$-$P15_7$(1), X_{IN}, $\overline{RESET}$, CNV_{SS}, BYTE	V_I=0V				-4.0	µA
R_{PULLUP}	Pull-up Resistance	$P0_0$-$P0_7$, $P1_0$-$P1_7$, $P2_0$-$P2_7$, $P3_0$-$P3_7$, $P4_0$-$P4_7$, $P5_0$-$P5_7$, $P6_0$-$P6_7$, $P7_2$-$P7_7$, $P8_0$-$P8_4$, $P8_6$, $P8_7$, $P9_0$-$P9_7$, $P10_0$-$P10_7$, $P11_0$-$P11_4$, $P12_0$-$P12_7$, $P13_0$-$P13_7$, $P14_0$-$P14_6$, $P15_0$-$P15_7$(1)	V_I=0V	Flash Memory	66	120	500	kΩ
				Masked ROM	40	70	500	kΩ
R_{fXIN}	Feedback Resistance	X_{IN}				3.0		MΩ
R_{fXCIN}	Feedback Resistance	X_{CIN}				20.0		MΩ
V_{RAM}	RAM Standby Voltage	in stop mode			2.0			V
I_{CC}	Power Supply Current	Measurement condition: In single-chip mode, output pins are left open and other pins are connected to V_{SS}.	f(BCLK)=24 MHz, Square wave, No division			22	35	mA
			f(BCLK)=32 kHz, In wait mode, Topr=25° C			10		µA
			While clock stops, Topr=25° C			0.8	5	µA
			While clock stops, Topr=85° C				50	µA

NOTES:

1. P11 to P15 are provided in the 144-pin package only.

$V_{CC1}=V_{CC2}=3.3V$

Table 5.25 A/D Conversion Characteristics ($V_{CC1}=V_{CC2}=AV_{CC}=V_{REF}$= 3.0 to 3.6V, $V_{SS}=AV_{SS}$=0V at Topr = –20 to 85°C, f(BCLK) = 24MHz unless otherwise specified)

Symbol	Parameter		Measurement Condition	Standard			Unit
				Min.	Typ.	Max.	
-	Resolution		$V_{REF}=V_{CC1}$			10	Bits
INL	Integral Nonlinearity Error	No S&H (8-bit)	$V_{CC1}=V_{CC2}=V_{REF}$=3.3V			±2	LSB
DNL	Differential Nonlinearity Error	No S&H (8-bit)				±1	LSB
-	Offset Error	No S&H (8-bit)				±2	LSB
-	Gain Error	No S&H (8-bit)				±2	LSB
R_{LADDER}	Resistor Ladder		$V_{REF}=V_{CC1}$	8		40	kΩ
t_{CONV}	8-bit Conversion Time(1, 2)			6.1			µs
V_{REF}	Reference Voltage			3		V_{CC1}	V
V_{IA}	Analog Input Voltage			0		V_{REF}	V

S&H: Sample and Hold

NOTES:
1. Divide f(X_{IN}), if exceeding 10 MHz, to keep ϕAD frequency at 10 MHz or less.
2. S&H not available.

Table 5.26 D/A Conversion Characteristics ($V_{CC1}=V_{CC2}=V_{REF}$=3.0 to 3.6V, $V_{SS}=AV_{SS}$=0V at Topr = –20 to 85°C, f(BCLK) = 24MHz unless otherwise specified)

Symbol	Parameter	Measurement Condition	Standard			Unit
			Min.	Typ.	Max.	
-	Resolution				8	Bits
-	Absolute Accuracy				1.0	%
t_{SU}	Setup Time				3	µs
R_O	Output Resistance		4	10	20	kΩ
I_{VREF}	Reference Power Supply Input Current	(Note 1)			1.0	mA

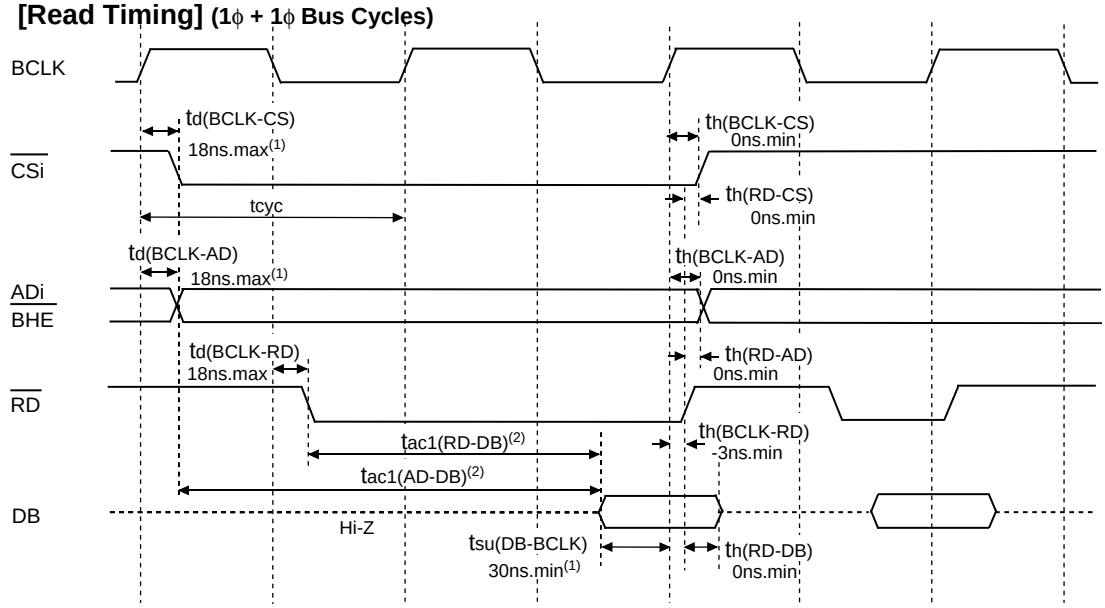
NOTES:
1. Measurement results when using one D/A converter. The DAi register (i=0, 1) of the D/A converter, not being used, is set to "00_{16}". The resistor ladder in the A/D converter is excluded.
I_{VREF} flows even if the VCUT bit in the AD0CON1 register is set to "0" (no V_{REF} connection).

Vcc1=Vcc2=3.3V

Memory Expansion Mode and Microprocessor Mode

(when accessing an external memory space)

[Read Timing] (1φ + 1φ Bus Cycles)



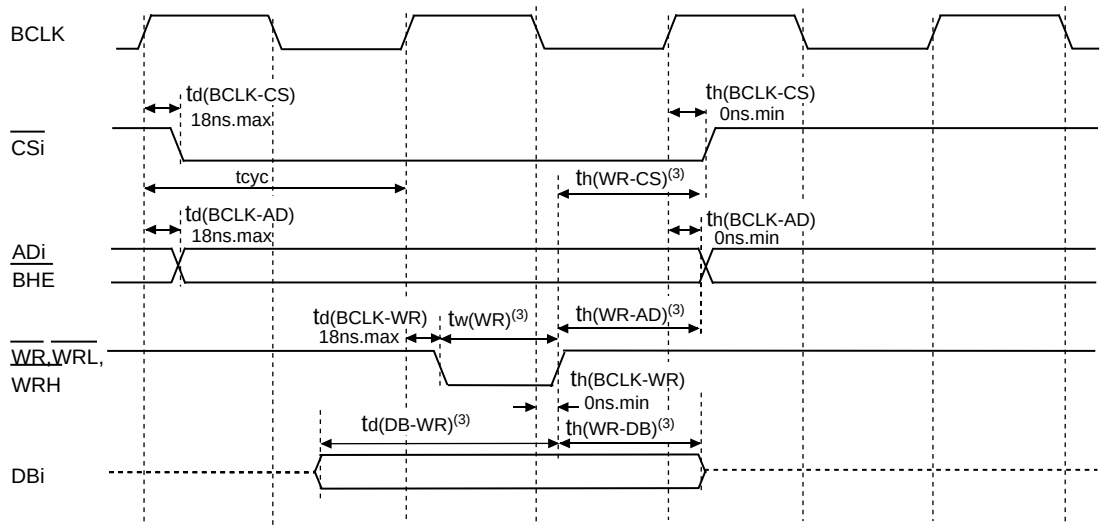
NOTES:

1. Values guaranteed only when the microcomputer is used independently.
   A maximum of 35ns is guaranteed for $t_{d(BCLK-AD)}+t_{su(DB-BCLK)}$.
2. Varies with operation frequency.

   $t_{ac1(RD-DB)}$=(tcyc/2 x m-35)ns.max (if external bus cycle is aφ + bφ, m=(b x 2) + 1)

   $t_{ac1(AD-DB)}$=(tcyc x n-35)ns.max (if external bus cycle is aφ + bφ, n = a + b)

[Write Timing] (1φ + 1φ Bus Cycles)



NOTES:

3. Varies with operation frequency.

   $t_{d(DB-WR)}$=(tcyc x m-20)ns.min

   (if external bus cycle is aφ + bφ, m=b)

   $t_{h(WR-DB)}$=(tcyc/2-20)ns.min

   $t_{h(WR-AD)}$=(tcyc/2-10)ns.min

   $t_{h(WR-CS)}$=(tcyc/2-10)ns.min

   $t_{w(WR)}$=(tcyc/2 x n-15)ns.min

   (if external bus cycle is aφ + bφ, n=(bx2)-1)

Measurement Conditions

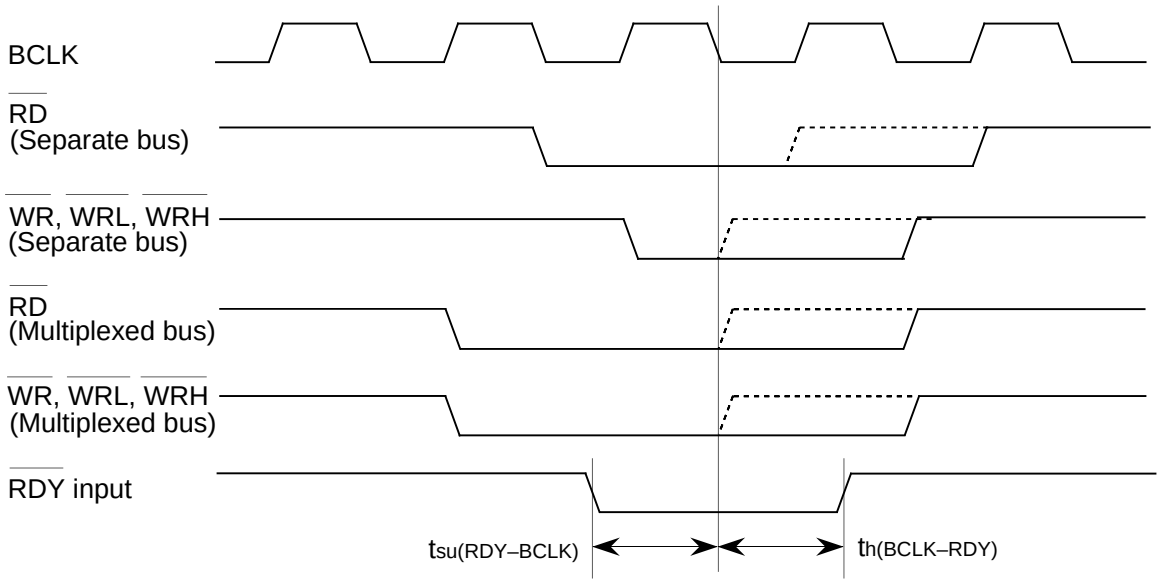
- V_{CC1}=V_{CC2}=3.0 to 3.6V
- Input high and low voltage: V_{IH}=1.5V, V_{IL}=0.5V
- Output high and low voltage: V_{OH}=1.5V, V_{OL}=1.5V

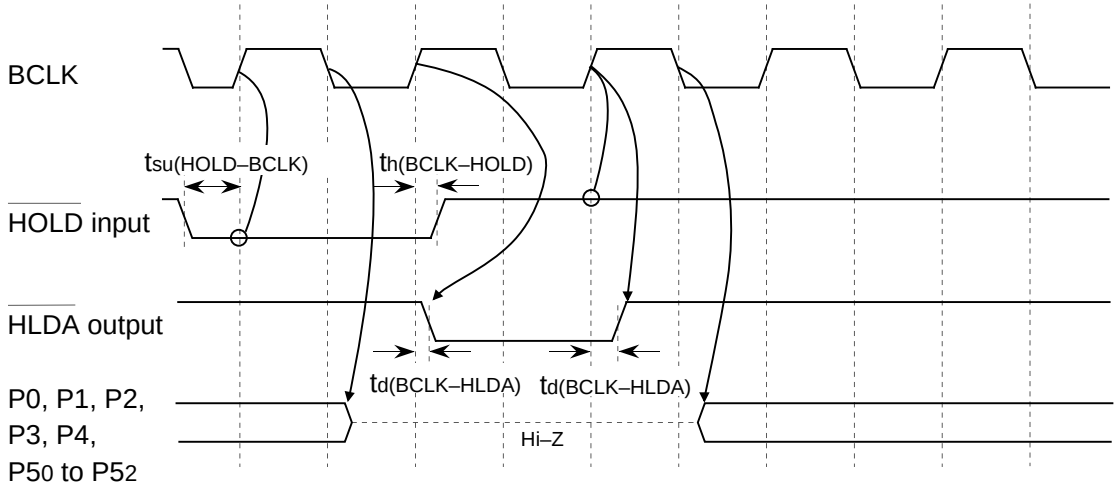
$$tcyc = \frac{10^9}{f(BCLK)}$$

Figure 5.7 V_{CC1}=V_{CC2}=3.3V Timing Diagram (1)

$V_{CC1}=V_{CC2}=3.3V$

Memory Expansion Mode and Microprocessor Mode





Measurement Conditions:
- $V_{CC1}=V_{CC2}=3.0$ to 3.6V
- Input high and low voltage: $V_{IH}=2.4V$, $V_{IL}=0.6V$
- Output high and low voltage: $V_{OH}=1.5V$, $V_{OL}=1.5V$

Figure 5.10 $V_{CC1}=V_{CC2}=3.3V$ Timing Diagram (4)

$V_{CC1}=V_{CC2}=5V$

Table 5.45 A/D Conversion Characteristics ($V_{CC1}=V_{CC2}=4.2$ to 5.5V, $V_{SS}=0V$ at Topr= -40 to 85°C (T version), f(BCLK)=32MHz unless otherwise specified)

Symbol	Parameter	Measurement Condition		Standard			Unit
				Min.	Typ.	Max.	
-	Resolution	$V_{REF}=V_{CC1}$				10	Bits
INL	Integral Nonlinearity Error	$V_{REF}=V_{CC1}=V_{CC2}=5V$	AN_0 to AN_7, $AN0_0$ to $AN0_7$, $AN2_0$ to $AN2_7$, $AN15_0$ to $AN15_7$, ANEX0, ANEX1			±3	LSB
							LSB
			External op-amp connection mode			±7	LSB
							LSB
DNL	Differential Nonlinearity Error					±1	LSB
-	Offset Error					±3	LSB
-	Gain Error					±3	LSB
R_{LADDER}	Resistor Ladder	$V_{REF}=V_{CC1}$		8		40	kΩ
t_{CONV}	10-bit Conversion Time(1, 2)			2.06			µs
t_{CONV}	8-bit Conversion Time(1, 2)			1.75			µs
t_{SAMP}	Sampling Time(1)			0.188			µs
V_{REF}	Reference Voltage			2		V_{CC1}	V
V_{IA}	Analog Input Voltage			0		V_{REF}	V

NOTES:
1. Divide f(X_{IN}), if exceeding 16 MHz, to keep ϕAD frequency at 16 MHz or less.
2. With using the sample and hold function.

Table 5.46 D/A Conversion Characteristics ($V_{CC1}=V_{CC2}=4.2$ to 5.5V, $V_{SS}=0V$ at Topr= -40 to 85°C (T version), f(BCLK)=32MHz unless otherwise specified)

Symbol	Parameter	Measurement Condition	Standard			Unit
			Min.	Typ.	Max.	
-	Resolution				8	Bits
-	Absolute Accuracy				1.0	%
t_{SU}	Setup Time				3	µs
R_O	Output Resistance		4	10	20	kΩ
I_{VREF}	Reference Power Supply Input Current	(Note 1)			1.5	mA

NOTES:
1. Measurement when using one D/A converter. The DAi register (i=0, 1) of the D/A converter, not being used, is set to "00_{16}". The resistor ladder in the A/D converter is excluded.
I_{VREF} flows even if the VCUT bit in the AD0CON1 register is set to "0" (no V_{REF} connection).

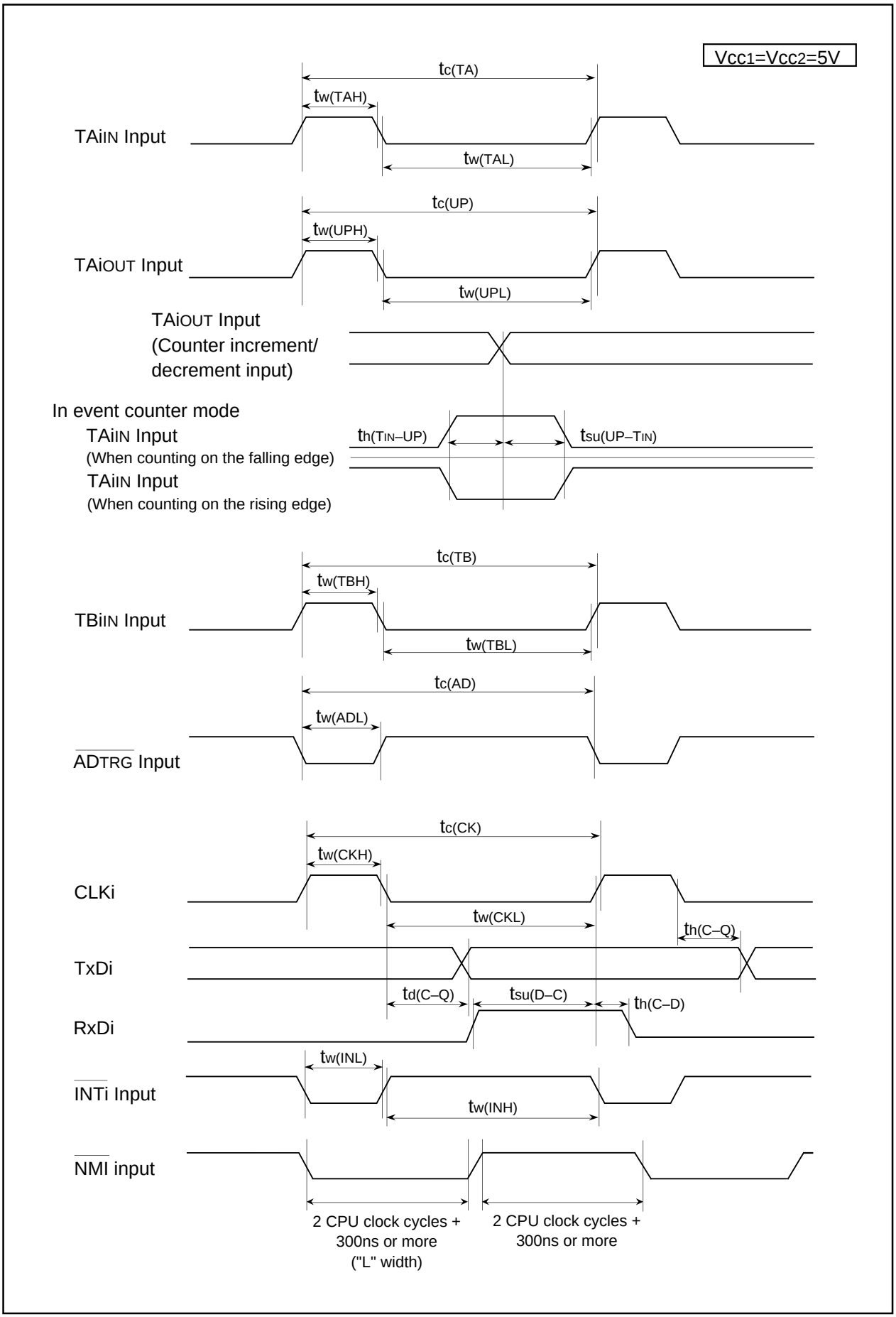
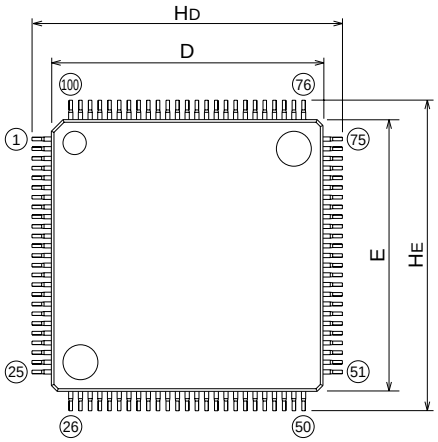


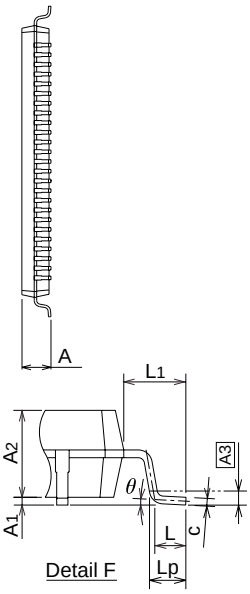
Figure 5.13 Vcc1=Vcc2=5V Timing Diagram

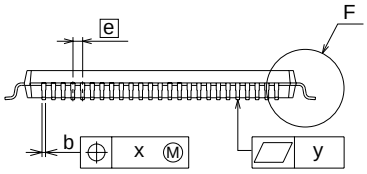
PLQP0100KB-A (100P6Q-A)

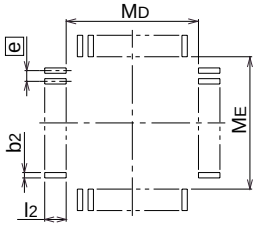
Plastic 100pin 14×14mm body LQFP

JEITA Package Code	RENESAS Code	Previous Code	Mass[Typ.]
P-LQFP100-14x14-0.50	PLQP0100KB-A	100P6Q-A	0.6g









Recommended Mount Pad

Symbol	Dimension in Millimeters		
	Min	Nom	Max
A	–	–	1.7
A1	0	0.1	0.2
A2	–	1.4	–
b	0.13	0.18	0.28
c	0.105	0.125	0.175
D	13.9	14.0	14.1
E	13.9	14.0	14.1
e	–	0.5	–
HD	15.8	16.0	16.2
HE	15.8	16.0	16.2
L	0.3	0.5	0.7
L1	–	1.0	–
Lp	0.45	0.6	0.75
A3	–	0.25	–
x	–	–	0.08
y	–	–	0.1
θ	0°	–	10°
b2	–	0.225	–
l2	0.9	–	–
MD	–	14.4	–
ME	–	14.4	–