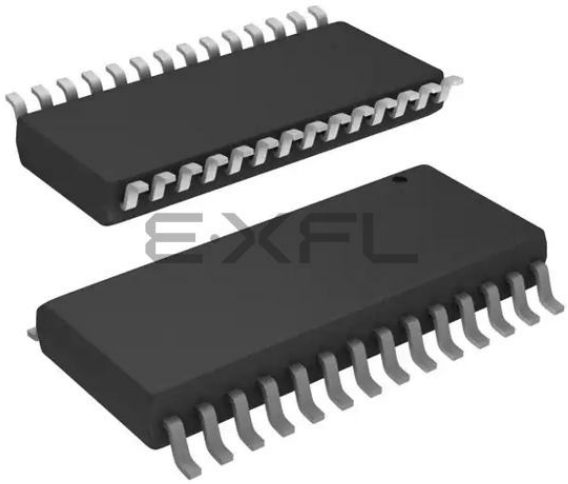

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## What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

## Applications of "Embedded - Microcontrollers"

| Details | |
|---|---|
| Product Status | Active |
| Core Processor | PIC |
| Core Size | 16-Bit |
| Speed | 32MHz |
| Connectivity | I²C, IrDA, SPI, UART/USART |
| Peripherals | Brown-out Detect/Reset, LVD, POR, PWM, WDT |
| Number of I/O | 21 |
| Program Memory Size | 32KB (11K x 24) |
| Program Memory Type | FLASH |
| EEPROM Size | - |
| RAM Size | 8K x 8 |
| Voltage - Supply (Vcc/Vdd) | 2V ~ 3.6V |
| Data Converters | A/D 10x10b |
| Oscillator Type | Internal |
| Operating Temperature | -40°C ~ 85°C (TA) |
| Mounting Type | Surface Mount |
| Package / Case | 28-SOIC (0.295", 7.50mm Width) |
| Supplier Device Package | 28-SOIC |
| Purchase URL | https://www.e-xfl.com/product-detail/microchip-technology/pic24fj32ga102-i-so |

**TABLE 1-2: PIC24FJ64GA104 FAMILY PINOUT DESCRIPTIONS (CONTINUED)**

| Function | Pin Number | | | I/O | Input Buffer | Description |
|---|---|---|---|---|---|---|
| | 28-Pin SPDIP/ SOIC/SSOP | 28-Pin QFN | 44-Pin QFN/ TQFP | | | |
| RA0 | 2 | 27 | 19 | I/O | ST | PORTA Digital I/O. |
| RA1 | 3 | 28 | 20 | I/O | ST | |
| RA2 | 9 | 6 | 30 | I/O | ST | |
| RA3 | 10 | 7 | 31 | I/O | ST | |
| RA4 | 12 | 9 | 34 | I/O | ST | |
| RA7 | — | — | 13 | I/O | ST | |
| RA8 | — | — | 32 | I/O | ST | |
| RA9 | — | — | 35 | I/O | ST | |
| RA10 | — | — | 12 | I/O | ST | |
| RB0 | 4 | 1 | 21 | I/O | ST | PORTB Digital I/O. |
| RB1 | 5 | 2 | 22 | I/O | ST | |
| RB2 | 6 | 3 | 23 | I/O | ST | |
| RB3 | 7 | 4 | 24 | I/O | ST | |
| RB4 | 11 | 8 | 33 | I/O | ST | |
| RB5 | 14 | 11 | 41 | I/O | ST | |
| RB6 | 15 | 12 | 42 | I/O | ST | |
| RB7 | 16 | 13 | 43 | I/O | ST | |
| RB8 | 17 | 14 | 44 | I/O | ST | |
| RB9 | 18 | 15 | 1 | I/O | ST | |
| RB10 | 21 | 18 | 8 | I/O | ST | |
| RB11 | 22 | 19 | 9 | I/O | ST | |
| RB12 | 23 | 20 | 10 | I/O | ST | |
| RB13 | 24 | 21 | 11 | I/O | ST | |
| RB14 | 25 | 22 | 14 | I/O | ST | |
| RB15 | 26 | 23 | 15 | I/O | ST | |
| RC0 | — | — | 25 | I/O | ST | PORTC Digital I/O. |
| RC1 | — | — | 26 | I/O | ST | |
| RC2 | — | — | 27 | I/O | ST | |
| RC3 | — | — | 36 | I/O | ST | |
| RC4 | — | — | 37 | I/O | ST | |
| RC5 | — | — | 38 | I/O | ST | |
| RC6 | — | — | 2 | I/O | ST | |
| RC7 | — | — | 3 | I/O | ST | |
| RC8 | — | — | 4 | I/O | ST | |
| RC9 | — | — | 5 | I/O | ST | |
| REFO | 24 | 21 | 11 | O | — | Reference Clock Output. |

**Legend:** TTL = TTL input buffer
ANA = Analog level input/output
ST = Schmitt Trigger input buffer
$I^2C$™ = $I^2C$/SMBus input buffer

**TABLE 3-1: CPU CORE REGISTERS**

| Register(s) Name | Description |
|---|---|
| W0 through W15 | Working Register Array |
| PC | 23-Bit Program Counter |
| SR | ALU STATUS Register |
| SPLIM | Stack Pointer Limit Value Register |
| TBLPAG | Table Memory Page Address Register |
| PSVPAG | Program Space Visibility Page Address Register |
| RCOUNT | Repeat Loop Counter Register |
| CORCON | CPU Control Register |

**FIGURE 3-2: PROGRAMMER'S MODEL**

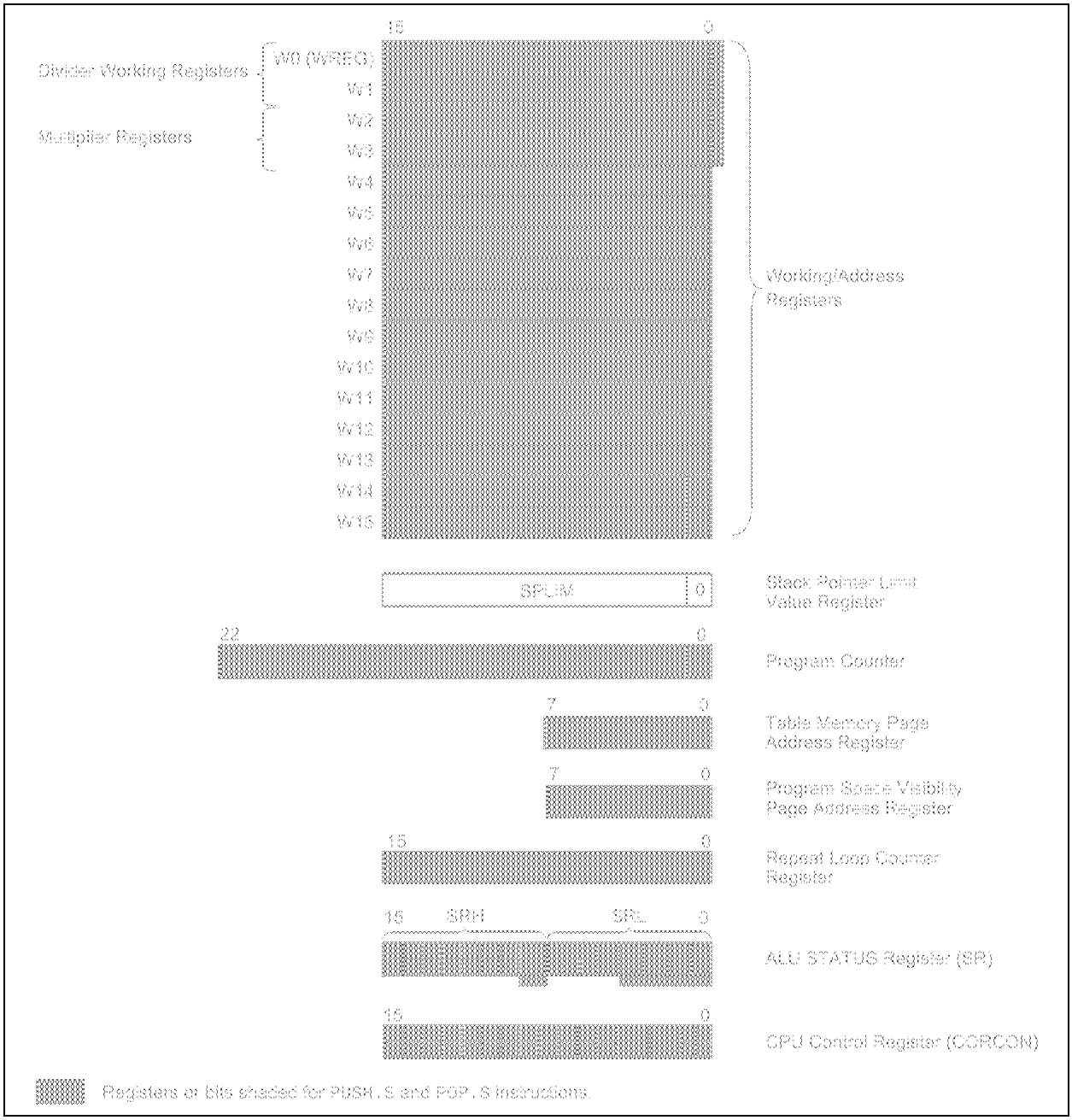


**TABLE 4-4: ICN REGISTER MAP**

| File Name | Addr | Bit 15 | Bit 14 | Bit 13 | Bit 12 | Bit 11 | Bit 10 | Bit 9 | Bit 8 | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | All Resets |
|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| CNEN1 | 0060 | CN15IE | CN14IE | CN13IE | CN12IE | CN11IE | CN10IE(1) | CN9IE(1) | CN8IE(1) | CN7IE | CN6IE | CN5IE | CN4IE | CN3IE | CN2IE | CN1IE | CN0IE | 0000 |
| CNEN2 | 0062 | — | CN30IE | CN29IE | CN28IE(1) | CN27IE | CN26IE(1) | CN25IE(1) | CN24IE | CN23IE | CN22IE | CN21IE | CN20IE(1) | CN19IE(1) | CN18IE(1) | CN17IE(1) | CN16IE | 0000 |
| CNPU1 | 0068 | CN15PUE | CN14PUE | CN13PUE | CN12PUE | CN11PUE | CN10PUE(1) | CN9PUE(1) | CN8PUE(1) | CN7PUE | CN6PUE | CN5PUE | CN4PUE | CN3PUE | CN2PUE | CN1PUE | CN0PUE | 0000 |
| CNPU2 | 006A | — | CN30PUE | CN29PUE | CN28PUE(1) | CN27PUE | CN26PUE(1) | CN25PUE(1) | CN24PUE | CN23PUE | CN22PUE | CN21PUE | CN20PUE(1) | CN19PUE(1) | CN18PUE(1) | CN17PUE(1) | CN16PUE | 0000 |

**Legend:** — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**Note 1:** Unimplemented in 28-pin devices; read as '0'.

**EXAMPLE 5-4: LOADING THE WRITE BUFFERS (C LANGUAGE CODE)**

```
// C example using MPLAB C30

    #define NUM_INSTRUCTION_PER_ROW 64
    unsigned int offset;
    unsigned int i;
    unsigned long progAddr = 0xXXXXXX;                  // Address of row to write
    unsigned int progData[2*NUM_INSTRUCTION_PER_ROW];   // Buffer of data to write

//Set up NVMCON for row programming
    NVMCON = 0x4001;                                    // Initialize NVMCON

//Set up pointer to the first memory location to be written
    TBLPAG = progAddr>>16;                              // Initialize PM Page Boundary SFR
    offset = progAddr & 0xFFFF;                         // Initialize lower word of address

//Perform TBLWT instructions to write necessary number of latches
for(i=0; i < 2*NUM_INSTRUCTION_PER_ROW; i++)
    {
        __builtin_tblwtl(offset, progData[i++]);        // Write to address low word
        __builtin_tblwth(offset, progData[i]);          // Write to upper byte
        offset = offset + 2;                            // Increment address
    }
```

**EXAMPLE 5-5: INITIATING A PROGRAMMING SEQUENCE (ASSEMBLY LANGUAGE CODE)**

```
        DISI    #5                      ; Block all interrupts with priority <7
                                        ; for next 5 instructions
        MOV     #0x55, W0
        MOV     W0, NVMKEY              ; Write the 55 key
        MOV     #0xAA, W1               ;
        MOV     W1, NVMKEY              ; Write the AA key
        BSET    NVMCON, #WR             ; Start the erase sequence
        NOP                             ;
        NOP                             ;
        BTSC    NVMCON, #15             ; and wait for it to be
        BRA     $-2                     ; completed
```

**EXAMPLE 5-6: INITIATING A PROGRAMMING SEQUENCE (C LANGUAGE CODE)**

```
// C example using MPLAB C30

asm("DISI #5");           // Block all interrupts with priority < 7
                          // for next 5 instructions

__builtin_write_NVM();    // Perform unlock sequence and set WR
```

**TABLE 7-2: IMPLEMENTED INTERRUPT VECTORS**

| Interrupt Source | Vector Number | IVT Address | AIVT Address | Interrupt Bit Locations | | |
|---|---|---|---|---|---|---|
| | | | | Flag | Enable | Priority |
| ADC1 Conversion Done | 13 | 00002Eh | 00012Eh | IFS0<13> | IEC0<13> | IPC3<6:4> |
| Comparator Event | 18 | 000038h | 000138h | IFS1<2> | IEC1<2> | IPC4<10:8> |
| CRC Generator | 67 | 00009Ah | 00019Ah | IFS4<3> | IEC4<3> | IPC16<14:12> |
| CTMU Event | 77 | 0000AEh | 0001AEh | IFS4<13> | IEC4<13> | IPC19<6:4> |
| External Interrupt 0 | 0 | 000014h | 000114h | IFS0<0> | IEC0<0> | IPC0<2:0> |
| External Interrupt 1 | 20 | 00003Ch | 00013Ch | IFS1<4> | IEC1<4> | IPC5<2:0> |
| External Interrupt 2 | 29 | 00004Eh | 00014Eh | IFS1<13> | IEC1<13> | IPC7<6:4> |
| I2C1 Master Event | 17 | 000036h | 000136h | IFS1<1> | IEC1<1> | IPC4<6:4> |
| I2C1 Slave Event | 16 | 000034h | 000134h | IFS1<0> | IEC1<0> | IPC4<2:0> |
| I2C2 Master Event | 50 | 000078h | 000178h | IFS3<2> | IEC3<2> | IPC12<10:8> |
| I2C2 Slave Event | 49 | 000076h | 000176h | IFS3<1> | IEC3<1> | IPC12<6:4> |
| Input Capture 1 | 1 | 000016h | 000116h | IFS0<1> | IEC0<1> | IPC0<6:4> |
| Input Capture 2 | 5 | 00001Eh | 00011Eh | IFS0<5> | IEC0<5> | IPC1<6:4> |
| Input Capture 3 | 37 | 00005Eh | 00015Eh | IFS2<5> | IEC2<5> | IPC9<6:4> |
| Input Capture 4 | 38 | 000060h | 000160h | IFS2<6> | IEC2<6> | IPC9<10:8> |
| Input Capture 5 | 39 | 000062h | 000162h | IFS2<7> | IEC2<7> | IPC9<14:12> |
| Input Change Notification | 19 | 00003Ah | 00013Ah | IFS1<3> | IEC1<3> | IPC4<14:12> |
| LVD Low-Voltage Detect | 72 | 0000A4h | 0001A4h | IFS4<8> | IEC4<8> | IPC18<2:0> |
| Output Compare 1 | 2 | 000018h | 000118h | IFS0<2> | IEC0<2> | IPC0<10:8> |
| Output Compare 2 | 6 | 000020h | 000120h | IFS0<6> | IEC0<6> | IPC1<10:8> |
| Output Compare 3 | 25 | 000046h | 000146h | IFS1<9> | IEC1<9> | IPC6<6:4> |
| Output Compare 4 | 26 | 000048h | 000148h | IFS1<10> | IEC1<10> | IPC6<10:8> |
| Output Compare 5 | 41 | 000066h | 000166h | IFS2<9> | IEC2<9> | IPC10<6:4> |
| Parallel Master Port | 45 | 00006Eh | 00016Eh | IFS2<13> | IEC2<13> | IPC11<6:4> |
| Real-Time Clock/Calendar | 62 | 000090h | 000190h | IFS3<14> | IEC3<14> | IPC15<10:8> |
| SPI1 Error | 9 | 000026h | 000126h | IFS0<9> | IEC0<9> | IPC2<6:4> |
| SPI1 Event | 10 | 000028h | 000128h | IFS0<10> | IEC0<10> | IPC2<10:8> |
| SPI2 Error | 32 | 000054h | 000154h | IFS2<0> | IEC2<0> | IPC8<2:0> |
| SPI2 Event | 33 | 000056h | 000156h | IFS2<1> | IEC2<1> | IPC8<6:4> |
| Timer1 | 3 | 00001Ah | 00011Ah | IFS0<3> | IEC0<3> | IPC0<14:12> |
| Timer2 | 7 | 000022h | 000122h | IFS0<7> | IEC0<7> | IPC1<14:12> |
| Timer3 | 8 | 000024h | 000124h | IFS0<8> | IEC0<8> | IPC2<2:0> |
| Timer4 | 27 | 00004Ah | 00014Ah | IFS1<11> | IEC1<11> | IPC6<14:12> |
| Timer5 | 28 | 00004Ch | 00014Ch | IFS1<12> | IEC1<12> | IPC7<2:0> |
| UART1 Error | 65 | 000096h | 000196h | IFS4<1> | IEC4<1> | IPC16<6:4> |
| UART1 Receiver | 11 | 00002Ah | 00012Ah | IFS0<11> | IEC0<11> | IPC2<14:12> |
| UART1 Transmitter | 12 | 00002Ch | 00012Ch | IFS0<12> | IEC0<12> | IPC3<2:0> |
| UART2 Error | 66 | 000098h | 000198h | IFS4<2> | IEC4<2> | IPC16<10:8> |
| UART2 Receiver | 30 | 000050h | 000150h | IFS1<14> | IEC1<14> | IPC7<10:8> |
| UART2 Transmitter | 31 | 000052h | 000152h | IFS1<15> | IEC1<15> | IPC7<14:12> |

**REGISTER 7-10: IEC0: INTERRUPT ENABLE CONTROL REGISTER 0**

| U-0 | U-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| — | — | AD1IE | U1TXIE | U1RXIE | SPI1IE | SPF1IE | T3IE |
| bit 15 | | | | | | | bit 8 |

| R/W-0 | R/W-0 | R/W-0 | U-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| T2IE | OC2IE | IC2IE | — | T1IE | OC1IE | IC1IE | INT0IE |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15-14 **Unimplemented:** Read as '0'

bit 13 **AD1IE:** A/D Conversion Complete Interrupt Enable bit
1 = Interrupt request enabled
0 = Interrupt request not enabled

bit 12 **U1TXIE:** UART1 Transmitter Interrupt Enable bit
1 = Interrupt request enabled
0 = Interrupt request not enabled

bit 11 **U1RXIE:** UART1 Receiver Interrupt Enable bit
1 = Interrupt request enabled
0 = Interrupt request not enabled

bit 10 **SPI1IE:** SPI1 Transfer Complete Interrupt Enable bit
1 = Interrupt request enabled
0 = Interrupt request not enabled

bit 9 **SPF1IE:** SPI1 Fault Interrupt Enable bit
1 = Interrupt request enabled
0 = Interrupt request not enabled

bit 8 **T3IE:** Timer3 Interrupt Enable bit
1 = Interrupt request enabled
0 = Interrupt request not enabled

bit 7 **T2IE:** Timer2 Interrupt Enable bit
1 = Interrupt request enabled
0 = Interrupt request not enabled

bit 6 **OC2IE:** Output Compare Channel 2 Interrupt Enable bit
1 = Interrupt request enabled
0 = Interrupt request not enabled

bit 5 **IC2IE:** Input Capture Channel 2 Interrupt Enable bit
1 = Interrupt request enabled
0 = Interrupt request not enabled

bit 4 **Unimplemented:** Read as '0'

bit 3 **T1IE:** Timer1 Interrupt Enable bit
1 = Interrupt request enabled
0 = Interrupt request not enabled

bit 2 **OC1IE:** Output Compare Channel 1 Interrupt Enable bit
1 = Interrupt request enabled
0 = Interrupt request not enabled

bit 1 **IC1IE:** Input Capture Channel 1 Interrupt Enable bit
1 = Interrupt request enabled
0 = Interrupt request not enabled

bit 0 **INT0IE:** External Interrupt 0 Enable bit
1 = Interrupt request enabled
0 = Interrupt request not enabled

**REGISTER 7-18: IPC3: INTERRUPT PRIORITY CONTROL REGISTER 3**

| U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | — | — | — | — | — |
| bit 15 | | | | | | | bit 8 |

| U-0 | R/W-1 | R/W-0 | R/W-0 | U-0 | R/W-1 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| — | AD1IP2 | AD1IP1 | AD1IP0 | — | U1TXIP2 | U1TXIP1 | U1TXIP0 |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15-7 **Unimplemented:** Read as '0'

bit 6-4 **AD1IP<2:0>:** A/D Conversion Complete Interrupt Priority bits
111 = Interrupt is priority 7 (highest priority interrupt)
•
•
•
001 = Interrupt is priority 1
000 = Interrupt source is disabled

bit 3 **Unimplemented:** Read as '0'

bit 2-0 **U1TXIP<2:0>:** UART1 Transmitter Interrupt Priority bits
111 = Interrupt is priority 7 (highest priority interrupt)
•
•
•
001 = Interrupt is priority 1
000 = Interrupt source is disabled

**REGISTER 7-21: IPC6: INTERRUPT PRIORITY CONTROL REGISTER 6**

| U-0 | R/W-1 | R/W-0 | R/W-0 | U-0 | R/W-1 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| — | T4IP2 | T4IP1 | T4IP0 | — | OC4IP2 | OC4IP1 | OC4IP0 |
| bit 15 | | | | | | | bit 8 |

| U-0 | R/W-1 | R/W-0 | R/W-0 | U-0 | U-0 | U-0 | U-0 |
|---|---|---|---|---|---|---|---|
| — | OC3IP2 | OC3IP1 | OC3IP0 | — | — | — | — |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15 **Unimplemented:** Read as '0'

bit 14-12 **T4IP<2:0>:** Timer4 Interrupt Priority bits
111 = Interrupt is priority 7 (highest priority interrupt)
•
•
•
001 = Interrupt is priority 1
000 = Interrupt source is disabled

bit 11 **Unimplemented:** Read as '0'

bit 10-8 **OC4IP<2:0>:** Output Compare Channel 4 Interrupt Priority bits
111 = Interrupt is priority 7 (highest priority interrupt)
•
•
•
001 = Interrupt is priority 1
000 = Interrupt source is disabled

bit 7 **Unimplemented:** Read as '0'

bit 6-4 **OC3IP<2:0>:** Output Compare Channel 3 Interrupt Priority bits
111 = Interrupt is priority 7 (highest priority interrupt)
•
•
•
001 = Interrupt is priority 1
000 = Interrupt source is disabled

bit 3-0 **Unimplemented:** Read as '0'

**REGISTER 8-1: OSCCON: OSCILLATOR CONTROL REGISTER (CONTINUED)**

bit 7 **CLKLOCK:** Clock Selection Lock Enabled bit
If FSCM is enabled (FCKSM1 = 1):
1 = Clock and PLL selections are locked
0 = Clock and PLL selections are not locked and may be modified by setting the OSWEN bit
If FSCM is disabled (FCKSM1 = 0):
Clock and PLL selections are never locked and may be modified by setting the OSWEN bit.

bit 6 **IOLOCK:** I/O Lock Enable bit(2)
1 = I/O lock is active
0 = I/O lock is not active

bit 5 **LOCK:** PLL Lock Status bit(3)
1 = PLL module is in lock or PLL module start-up timer is satisfied
0 = PLL module is out of lock, PLL start-up timer is running or PLL is disabled

bit 4 **Unimplemented:** Read as '0'

bit 3 **CF:** Clock Fail Detect bit
1 = FSCM has detected a clock failure
0 = No clock failure has been detected

bit 2 **POSCEN:** Primary Oscillator Sleep Enable bit
1 = Primary Oscillator continues to operate during Sleep mode
0 = Primary Oscillator disabled during Sleep mode

bit 1 **SOSCEN:** 32 kHz Secondary Oscillator (SOSC) Enable bit
1 = Enable Secondary Oscillator
0 = Disable Secondary Oscillator

bit 0 **OSWEN:** Oscillator Switch Enable bit
1 = Initiate an oscillator switch to clock source specified by NOSC<2:0> bits
0 = Oscillator switch is complete

**Note 1:** Reset values for these bits are determined by the FNOSC Configuration bits.
**2:** The state of the IOLOCK bit can only be changed once an unlocking sequence has been executed. In addition, if the IOL1WAY Configuration bit is '1', once the IOLOCK bit is set, it cannot be cleared.
**3:** Also resets to '0' during any valid clock switch or whenever a non-PLL clock mode is selected.

#### 9.2.4.3 Exiting Deep Sleep Mode

Deep Sleep mode exits on any one of the following events:

- POR event on VDD supply. If there is no DSBOR circuit to re-arm the VDD supply POR circuit, the external VDD supply must be lowered to the natural arming voltage of the POR circuit.
- DSWDT time-out. When the DSWDT timer times out, the device exits Deep Sleep.
- RTCC alarm (if RTCEN = 1).
- Assertion ('0') of the $\overline{\text{MCLR}}$ pin.
- Assertion of the INT0 pin (if the interrupt was enabled before Deep Sleep mode was entered). The polarity configuration is used to determine the assertion level ('0' or '1') of the pin that will cause an exit from Deep Sleep mode. Exiting from Deep Sleep mode requires a change on the INT0 pin while in Deep Sleep mode.

| **Note:** | Any interrupt pending when entering Deep Sleep mode is cleared. |
|---|---|

Exiting Deep Sleep mode generally does not retain the state of the device and is equivalent to a Power-on Reset (POR) of the device. Exceptions to this include the RTCC (if present), which remains operational through the wake-up, the DSGPRx registers and the DSWDT bit.

Wake-up events that occur from the time Deep Sleep exits, until the time that the POR sequence completes, are ignored, and are not captured in the DSWAKE register.

The sequence for exiting Deep Sleep mode is:

1. After a wake-up event, the device exits Deep Sleep and performs a POR. The DSEN bit is cleared automatically. Code execution resumes at the Reset vector.
2. To determine if the device exited Deep Sleep, read the Deep Sleep bit, DPSLP (RCON<10>). This bit will be set if there was an exit from Deep Sleep mode. If the bit is set, clear it.
3. Determine the wake-up source by reading the DSWAKE register.
4. Determine if a DSBOR event occurred during Deep Sleep mode by reading the DSBOR bit (DSCON<1>).
5. If application context data has been saved, read it back from the DSGPR0 and DSGPR1 registers.
6. Clear the RELEASE bit (DSCON<0>).

#### 9.2.4.4 Deep Sleep Wake-up Time

Since wake-up from Deep Sleep results in a POR, the wake-up time from Deep Sleep is the same as the device POR time. Also, because the internal regulator is turned off, the voltage on VCAP may drop depending on how long the device is asleep. If VCAP has dropped below 2V, then there will be additional wake-up time while the regulator charges VCAP.

Deep Sleep wake-up time is specified in **Section 28.0 "Electrical Characteristics"** as TDSWU. This specification indicates the worst-case wake-up time, including the full POR Reset time (including TPOR and TRST), as well as the time to fully charge a 10 μF capacitor on VCAP which has discharged to 0V. Wake-up may be significantly faster if VCAP has not discharged.

#### 9.2.4.5 Saving Context Data with the DSGPR0/DSGPR1 Registers

As exiting Deep Sleep mode causes a POR, most Special Function Registers reset to their default POR values. In addition, because VDDCORE power is not supplied in Deep Sleep mode, information in data RAM may be lost when exiting this mode.

Applications which require critical data to be saved prior to Deep Sleep may use the Deep Sleep General Purpose registers, DSGPR0 and DSGPR1, or data EEPROM (if available). Unlike other SFRs, the contents of these registers are preserved while the device is in Deep Sleep mode. After exiting Deep Sleep, software can restore the data by reading the registers and clearing the RELEASE bit (DSCON<0>).

#### 9.2.4.6 I/O Pins During Deep Sleep

During Deep Sleep, the general purpose I/O pins retain their previous states and the Secondary Oscillator (SOSC) will remain running, if enabled. Pins that are configured as inputs (TRIS bit is set) prior to entry into Deep Sleep remain high-impedance during Deep Sleep. Pins that are configured as outputs (TRIS bit is clear) prior to entry into Deep Sleep remain as output pins during Deep Sleep. While in this mode, they continue to drive the output level determined by their corresponding LAT bit at the time of entry into Deep Sleep.

### 14.3.1 PWM PERIOD

In edge aligned PWM mode, the period is specified by the value of OCxRS register. In center aligned PWM mode, the period of the synchronization source such as Timer's PRy specifies the period. The period in both cases can be calculated using Equation 14-1.

**EQUATION 14-1: CALCULATING THE PWM PERIOD(1)**

PWM Period = [Value + 1] x TCY x (Prescaler Value)

Where: Value = OCxRS in Edge-Aligned PWM mode and can be PRy in Center-Aligned PWM mode (If TMRy is the sync source).

**Note 1:** Based on TCY = TOSC * 2; Doze mode and PLL are disabled.

### 14.3.2 PWM DUTY CYCLE

The PWM duty cycle is specified by writing to the OCxRS and OCxR registers. The OCxRS and OCxR registers can be written to at any time, but the duty cycle value is not latched until a period is complete. This provides a double buffer for the PWM duty cycle and is essential for glitchless PWM operation.

Some important boundary parameters of the PWM duty cycle include:

- Edge-Aligned PWM
  - If OCxR and OCxRS are loaded with 0000h, the OCx pin will remain low (0% duty cycle).
  - If OCxRS is greater than OCxR, the pin will remain high (100% duty cycle).
- Center-Aligned PWM (with TMRy as the sync source)
  - If OCxR, OCxRS and PRy are all loaded with 0000h, the OCx pin will remain low (0% duty cycle).
  - If OCxRS is greater than PRy, the pin will go high (100% duty cycle).

See Example 14-1 for PWM mode timing details. Table 14-1 and Table 14-2 show example PWM frequencies and resolutions for a device operating at 4 MIPS and 10 MIPS, respectively.

**EQUATION 14-2: CALCULATION FOR MAXIMUM PWM RESOLUTION(1)**

$$\text{Maximum PWM Resolution (bits)} = \frac{\log_{10}\left(\frac{F_{CY}}{F_{PWM} \bullet (\text{Prescale Value})}\right)}{\log_{10}(2)} \text{ bits}$$

**Note 1:** Based on FCY = FOSC/2; Doze mode and PLL are disabled.

**EXAMPLE 14-1: PWM PERIOD AND DUTY CYCLE CALCULATIONS(1)**

1. Find the OCxRS register value for a desired PWM frequency of 52.08 kHz, where FOSC = 8 MHz with PLL (32 MHz device clock rate) and a prescaler setting of 1:1 using Edge-Aligned PWM mode.

   TCY = 2 * TOSC = 62.5 ns
   PWM Period = 1/PWM Frequency = 1/52.08 kHz = 19.2 µs
   PWM Period = (OCxRS + 1) • TCY • (OCx Prescale Value)
   19.2 µs = (OCxRS + 1) • 62.5 ns • 1
   OCxRS = 306

2. Find the maximum resolution of the duty cycle that can be used with a 52.08 kHz frequency and a 32 MHz device clock rate:

   PWM Resolution = $\log_{10}(F_{CY}/F_{PWM})/\log_{10}2$) bits
   = ($\log_{10}$(16 MHz/52.08 kHz)/$\log_{10}$2) bits
   = 8.3 bits

**Note 1:** Based on TCY = 2 * TOSC; Doze mode and PLL are disabled.

**REGISTER 16-1: I2CxCON: I2Cx CONTROL REGISTER (CONTINUED)**

bit 5 **ACKDT:** Acknowledge Data bit (When operating as $I^2C$ master. Applicable during master receive.)
Value that will be transmitted when the software initiates an Acknowledge sequence.
1 = Sends NACK during Acknowledge
0 = Sends ACK during Acknowledge

bit 4 **ACKEN:** Acknowledge Sequence Enable bit
(When operating as $I^2C$ master. Applicable during master receive.)
1 = Initiates Acknowledge sequence on SDAx and SCLx pins and transmits ACKDT data bit. Hardware clear at end of master Acknowledge sequence.
0 = Acknowledge sequence is not in progress

bit 3 **RCEN:** Receive Enable bit (when operating as $I^2C$ master)
1 = Enables Receive mode for $I^2C$. Hardware clear at end of eighth bit of master receive data byte.
0 = Receive sequence is not in progress

bit 2 **PEN:** Stop Condition Enable bit (when operating as $I^2C$ master)
1 = Initiates Stop condition on SDAx and SCLx pins. Hardware clear at end of master Stop sequence.
0 = Stop condition is not in progress

bit 1 **RSEN:** Repeated Start Condition Enabled bit (when operating as $I^2C$ master)
1 = Initiates Repeated Start condition on SDAx and SCLx pins. Hardware clear at end of master Repeated Start sequence.
0 = Repeated Start condition is not in progress

bit 0 **SEN:** Start Condition Enabled bit (when operating as $I^2C$ master)
1 = Initiates Start condition on SDAx and SCLx pins. Hardware clear at end of master Start sequence.
0 = Start condition is not in progress

## 17.1 UART Baud Rate Generator (BRG)

The UART module includes a dedicated 16-bit Baud Rate Generator. The UxBRG register controls the period of a free-running, 16-bit timer. Equation 17-1 shows the formula for computation of the baud rate with BRGH = 0.

**EQUATION 17-1: UART BAUD RATE WITH BRGH = 0(1,2)**

$$\text{Baud Rate} = \frac{F_{CY}}{16 \bullet (\text{UxBRG} + 1)}$$

$$\text{UxBRG} = \frac{F_{CY}}{16 \bullet \text{Baud Rate}} - 1$$

**Note 1:** FCY denotes the instruction cycle clock frequency (FOSC/2).

**2:** Based on FCY = FOSC/2, Doze mode and PLL are disabled.

Example 17-1 shows the calculation of the baud rate error for the following conditions:

- FCY = 4 MHz
- Desired Baud Rate = 9600

The maximum baud rate (BRGH = 0) possible is FCY/16 (for UxBRG = 0) and the minimum baud rate possible is FCY/(16 * 65536).

Equation 17-2 shows the formula for computation of the baud rate with BRGH = 1.

**EQUATION 17-2: UART BAUD RATE WITH BRGH = 1(1,2)**

$$\text{Baud Rate} = \frac{F_{CY}}{4 \bullet (\text{UxBRG} + 1)}$$

$$\text{UxBRG} = \frac{F_{CY}}{4 \bullet \text{Baud Rate}} - 1$$

**Note 1:** FCY denotes the instruction cycle clock frequency.

**2:** Based on FCY = FOSC/2, Doze mode and PLL are disabled.

The maximum baud rate (BRGH = 1) possible is FCY/4 (for UxBRG = 0) and the minimum baud rate possible is FCY/(4 * 65536).

Writing a new value to the UxBRG register causes the BRG timer to be reset (cleared). This ensures the BRG does not wait for a timer overflow before generating the new baud rate.

**EXAMPLE 17-1: BAUD RATE ERROR CALCULATION (BRGH = 0)(1)**

Desired Baud Rate = FCY/(16 (UxBRG + 1))

Solving for UxBRG Value:

UxBRG = ((FCY/Desired Baud Rate)/16) – 1
UxBRG = ((4000000/9600)/16) – 1
UxBRG = 25

Calculated Baud Rate = 4000000/(16 (25 + 1))
= 9615

Error = (Calculated Baud Rate – Desired Baud Rate) / Desired Baud Rate
= (9615 – 9600)/9600
= 0.16%

**Note 1:** Based on FCY = FOSC/2, Doze mode and PLL are disabled.

## 19.2 RTCC Module Registers

The RTCC module registers are organized into three categories:

- RTCC Control Registers
- RTCC Value Registers
- Alarm Value Registers

### 19.2.1 REGISTER MAPPING

To limit the register interface, the RTCC Timer and Alarm Time registers are accessed through corresponding register pointers. The RTCC Value register window (RTCVALH and RTCVALL) uses the RTCPTR bits (RCFGCAL<9:8>) to select the desired Timer register pair (see Table 19-1).

By writing to the RTCVALH byte, the RTCC Pointer value (the RTCPTR<1:0> bits) decrements by one until they reach '00'. Once they reach '00', the MINUTES and SECONDS value will be accessible through RTCVALH and RTCVALL until the pointer value is manually changed.

**TABLE 19-1: RTCVAL REGISTER MAPPING**

| RTCPTR<1:0> | RTCC Value Register Window | |
|---|---|---|
| | RTCVAL<15:8> | RTCVAL<7:0> |
| 00 | MINUTES | SECONDS |
| 01 | WEEKDAY | HOURS |
| 10 | MONTH | DAY |
| 11 | — | YEAR |

The Alarm Value register window (ALRMVALH and ALRMVALL) uses the ALRMPTR bits (ALCFGRPT<9:8>) to select the desired Alarm register pair (see Table 19-2).

By writing to the ALRMVALH byte, the Alarm Pointer value (ALRMPTR<1:0> bits) decrements by one until they reach '00'. Once they reach '00', the ALRMMIN and ALRMSEC value will be accessible through ALRMVALH and ALRMVALL until the pointer value is manually changed.

**TABLE 19-2: ALRMVAL REGISTER MAPPING**

| ALRMPTR <1:0> | Alarm Value Register Window | |
|---|---|---|
| | ALRMVAL<15:8> | ALRMVAL<7:0> |
| 00 | ALRMMIN | ALRMSEC |
| 01 | ALRMWD | ALRMHR |
| 10 | ALRMMNTH | ALRMDAY |
| 11 | — | — |

Considering that the 16-bit core does not distinguish between 8-bit and 16-bit read operations, the user must be aware that when reading either the ALRMVALH or ALRMVALL bytes, the ALRMPTR<1:0> value will be decremented. The same applies to the RTCVALH or RTCVALL bytes with the RTCPTR<1:0> being decremented.

| **Note:** | This only applies to read operations and not write operations. |
|---|---|

### 19.2.2 WRITE LOCK

To perform a write to any of the RTCC Timer registers, the RTCWREN bit (RCFGCAL<13>) must be set (refer to Example 19-1).

| **Note:** | To avoid accidental writes to the timer, it is recommended that the RTCWREN bit (RCFGCAL<13>) is kept clear at any other time. For the RTCWREN bit to be set, there is only one instruction cycle time window allowed between the 55h/AA sequence and the setting of RTCWREN; therefore, it is recommended that code follow the procedure in Example 19-1. |
|---|---|

### 19.2.3 SELECTING RTCC CLOCK SOURCE

The clock source for the RTCC module can be selected using the Flash Configuration bit, RTCOSC (CW4<5>). When the bit is set to '1', the Secondary Oscillator (SOSC) is used as the reference clock, and when the bit is '0', LPRC is used as the reference clock.

**EXAMPLE 19-1: SETTING THE RTCWREN BIT**

```
asm volatile("push w7");
asm volatile("push w8");
asm volatile("disi #5");
asm volatile("mov #0x55, w7");
asm volatile("mov w7, _NVMKEY");
asm volatile("mov #0xAA, w8");
asm volatile("mov w8, _NVMKEY");
asm volatile("bset _RCFGCAL, #13");   //set the RTCWREN bit
asm volatile("pop w8");
asm volatile("pop w7");
```

**REGISTER 22-1: CMxCON: COMPARATOR x CONTROL REGISTERS (COMPARATORS 1 THROUGH 3)**

| R/W-0 | R/W-0 | R/W-0 | U-0 | U-0 | U-0 | R/W-0 | R-0 |
|---|---|---|---|---|---|---|---|
| CEN | COE | CPOL | — | — | — | CEVT | COUT |
| bit 15 | | | | | | | bit 8 |

| R/W-0 | R/W-0 | U-0 | R/W-0 | U-0 | U-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| EVPOL1 | EVPOL0 | — | CREF | — | — | CCH1 | CCH0 |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15 **CEN:** Comparator Enable bit
1 = Comparator is enabled
0 = Comparator is disabled

bit 14 **COE:** Comparator Output Enable bit
1 = Comparator output is present on the CxOUT pin.
0 = Comparator output is internal only

bit 13 **CPOL:** Comparator Output Polarity Select bit
1 = Comparator output is inverted
0 = Comparator output is not inverted

bit 12-10 **Unimplemented:** Read as '0'

bit 9 **CEVT:** Comparator Event bit
1 = Comparator event defined by EVPOL<1:0> has occurred; subsequent triggers and interrupts are disabled until the bit is cleared
0 = Comparator event has not occurred

bit 8 **COUT:** Comparator Output bit
When CPOL = 0:
1 = VIN+ > VIN-
0 = VIN+ < VIN-
When CPOL = 1:
1 = VIN+ < VIN-
0 = VIN+ > VIN-

bit 7-6 **EVPOL<1:0>:** Trigger/Event/Interrupt Polarity Select bits
11 = Trigger/event/interrupt generated on any change of the comparator output (while CEVT = 0)
10 = Trigger/event/interrupt generated on transition of the comparator output:
If CPOL = 0 (non-inverted polarity):
High-to-low transition only.
If CPOL = 1 (inverted polarity):
Low-to-high transition only.
01 = Trigger/event/interrupt generated on transition of comparator output:
If CPOL = 0 (non-inverted polarity):
Low-to-high transition only.
If CPOL = 1 (inverted polarity):
High-to-low transition only.
00 = Trigger/event/interrupt generation is disabled

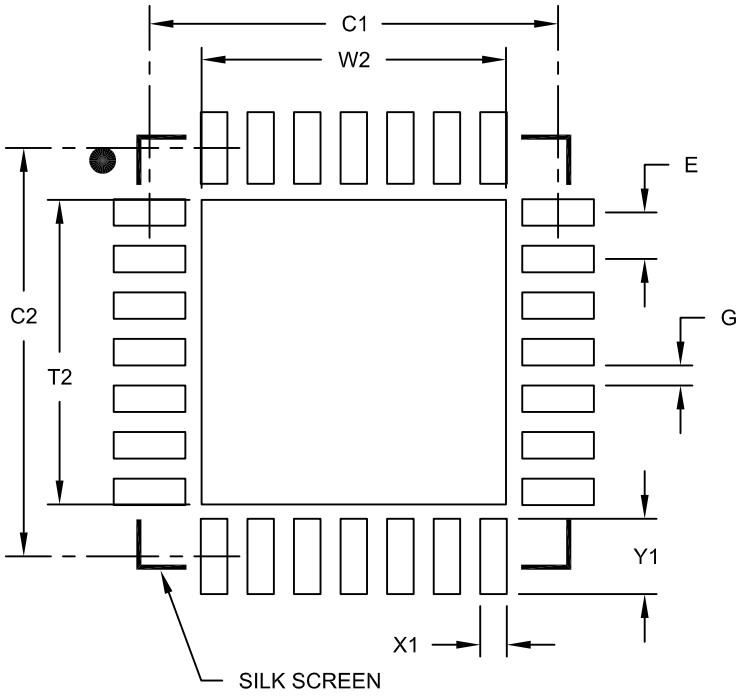
bit 5 **Unimplemented:** Read as '0'

**TABLE 27-2: INSTRUCTION SET OVERVIEW (CONTINUED)**

| Assembly Mnemonic | Assembly Syntax | | Description | # of Words | # of Cycles | Status Flags Affected |
|---|---|---|---|---|---|---|
| PWRSAV | PWRSAV | #lit1 | Go into Sleep or Idle mode | 1 | 1 | WDTO, Sleep |
| RCALL | RCALL | Expr | Relative Call | 1 | 2 | None |
| | RCALL | Wn | Computed Call | 1 | 2 | None |
| REPEAT | REPEAT | #lit14 | Repeat Next Instruction lit14 + 1 times | 1 | 1 | None |
| | REPEAT | Wn | Repeat Next Instruction (Wn) + 1 times | 1 | 1 | None |
| RESET | RESET | | Software Device Reset | 1 | 1 | None |
| RETFIE | RETFIE | | Return from Interrupt | 1 | 3 (2) | None |
| RETLW | RETLW | #lit10,Wn | Return with Literal in Wn | 1 | 3 (2) | None |
| RETURN | RETURN | | Return from Subroutine | 1 | 3 (2) | None |
| RLC | RLC | f | f = Rotate Left through Carry f | 1 | 1 | C, N, Z |
| | RLC | f,WREG | WREG = Rotate Left through Carry f | 1 | 1 | C, N, Z |
| | RLC | Ws,Wd | Wd = Rotate Left through Carry Ws | 1 | 1 | C, N, Z |
| RLNC | RLNC | f | f = Rotate Left (No Carry) f | 1 | 1 | N, Z |
| | RLNC | f,WREG | WREG = Rotate Left (No Carry) f | 1 | 1 | N, Z |
| | RLNC | Ws,Wd | Wd = Rotate Left (No Carry) Ws | 1 | 1 | N, Z |
| RRC | RRC | f | f = Rotate Right through Carry f | 1 | 1 | C, N, Z |
| | RRC | f,WREG | WREG = Rotate Right through Carry f | 1 | 1 | C, N, Z |
| | RRC | Ws,Wd | Wd = Rotate Right through Carry Ws | 1 | 1 | C, N, Z |
| RRNC | RRNC | f | f = Rotate Right (No Carry) f | 1 | 1 | N, Z |
| | RRNC | f,WREG | WREG = Rotate Right (No Carry) f | 1 | 1 | N, Z |
| | RRNC | Ws,Wd | Wd = Rotate Right (No Carry) Ws | 1 | 1 | N, Z |
| SE | SE | Ws,Wnd | Wnd = Sign-Extended Ws | 1 | 1 | C, N, Z |
| SETM | SETM | f | f = FFFFh | 1 | 1 | None |
| | SETM | WREG | WREG = FFFFh | 1 | 1 | None |
| | SETM | Ws | Ws = FFFFh | 1 | 1 | None |
| SL | SL | f | f = Left Shift f | 1 | 1 | C, N, OV, Z |
| | SL | f,WREG | WREG = Left Shift f | 1 | 1 | C, N, OV, Z |
| | SL | Ws,Wd | Wd = Left Shift Ws | 1 | 1 | C, N, OV, Z |
| | SL | Wb,Wns,Wnd | Wnd = Left Shift Wb by Wns | 1 | 1 | N, Z |
| | SL | Wb,#lit5,Wnd | Wnd = Left Shift Wb by lit5 | 1 | 1 | N, Z |
| SUB | SUB | f | f = f – WREG | 1 | 1 | C, DC, N, OV, Z |
| | SUB | f,WREG | WREG = f – WREG | 1 | 1 | C, DC, N, OV, Z |
| | SUB | #lit10,Wn | Wn = Wn – lit10 | 1 | 1 | C, DC, N, OV, Z |
| | SUB | Wb,Ws,Wd | Wd = Wb – Ws | 1 | 1 | C, DC, N, OV, Z |
| | SUB | Wb,#lit5,Wd | Wd = Wb – lit5 | 1 | 1 | C, DC, N, OV, Z |
| SUBB | SUBB | f | f = f – WREG – ($\overline{C}$) | 1 | 1 | C, DC, N, OV, Z |
| | SUBB | f,WREG | WREG = f – WREG – ($\overline{C}$) | 1 | 1 | C, DC, N, OV, Z |
| | SUBB | #lit10,Wn | Wn = Wn – lit10 – ($\overline{C}$) | 1 | 1 | C, DC, N, OV, Z |
| | SUBB | Wb,Ws,Wd | Wd = Wb – Ws – ($\overline{C}$) | 1 | 1 | C, DC, N, OV, Z |
| | SUBB | Wb,#lit5,Wd | Wd = Wb – lit5 – ($\overline{C}$) | 1 | 1 | C, DC, N, OV, Z |
| SUBR | SUBR | f | f = WREG – f | 1 | 1 | C, DC, N, OV, Z |
| | SUBR | f,WREG | WREG = WREG – f | 1 | 1 | C, DC, N, OV, Z |
| | SUBR | Wb,Ws,Wd | Wd = Ws – Wb | 1 | 1 | C, DC, N, OV, Z |
| | SUBR | Wb,#lit5,Wd | Wd = lit5 – Wb | 1 | 1 | C, DC, N, OV, Z |
| SUBBR | SUBBR | f | f = WREG – f – ($\overline{C}$) | 1 | 1 | C, DC, N, OV, Z |
| | SUBBR | f,WREG | WREG = WREG – f – ($\overline{C}$) | 1 | 1 | C, DC, N, OV, Z |
| | SUBBR | Wb,Ws,Wd | Wd = Ws – Wb – ($\overline{C}$) | 1 | 1 | C, DC, N, OV, Z |
| | SUBBR | Wb,#lit5,Wd | Wd = lit5 – Wb – ($\overline{C}$) | 1 | 1 | C, DC, N, OV, Z |
| SWAP | SWAP.b | Wn | Wn = Nibble Swap Wn | 1 | 1 | None |
| | SWAP | Wn | Wn = Byte Swap Wn | 1 | 1 | None |

### 28-Lead Plastic Quad Flat, No Lead Package (ML) – 6x6 mm Body [QFN] with 0.55 mm Contact Length

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging




RECOMMENDED LAND PATTERN

| Units | | MILLIMETERS | | |
|---|---|---|---|---|
| Dimension Limits | | MIN | NOM | MAX |
| Contact Pitch | E | | 0.65 BSC | |
| Optional Center Pad Width | W2 | | | 4.25 |
| Optional Center Pad Length | T2 | | | 4.25 |
| Contact Pad Spacing | C1 | | 5.70 | |
| Contact Pad Spacing | C2 | | 5.70 | |
| Contact Pad Width (X28) | X1 | | | 0.37 |
| Contact Pad Length (X28) | Y1 | | | 1.00 |
| Distance Between Pads | G | 0.20 | | |

Notes:

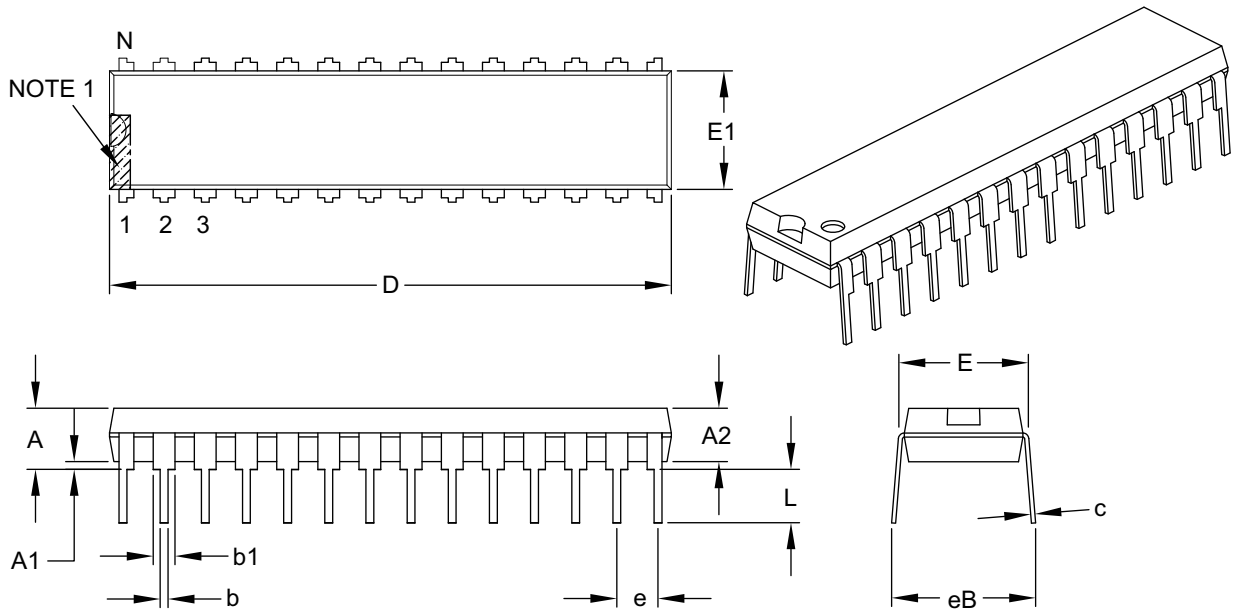
1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2105A

### 28-Lead Skinny Plastic Dual In-Line (SP) – 300 mil Body [SPDIP]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging




| Units | | INCHES | | |
|---|---|---|---|---|
| Dimension Limits | | MIN | NOM | MAX |
| Number of Pins | N | | 28 | |
| Pitch | e | | .100 BSC | |
| Top to Seating Plane | A | – | – | .200 |
| Molded Package Thickness | A2 | .120 | .135 | .150 |
| Base to Seating Plane | A1 | .015 | – | – |
| Shoulder to Shoulder Width | E | .290 | .310 | .335 |
| Molded Package Width | E1 | .240 | .285 | .295 |
| Overall Length | D | 1.345 | 1.365 | 1.400 |
| Tip to Seating Plane | L | .110 | .130 | .150 |
| Lead Thickness | c | .008 | .010 | .015 |
| Upper Lead Width | b1 | .040 | .050 | .070 |
| Lower Lead Width | b | .014 | .018 | .022 |
| Overall Row Spacing § | eB | – | – | .430 |

**Notes:**

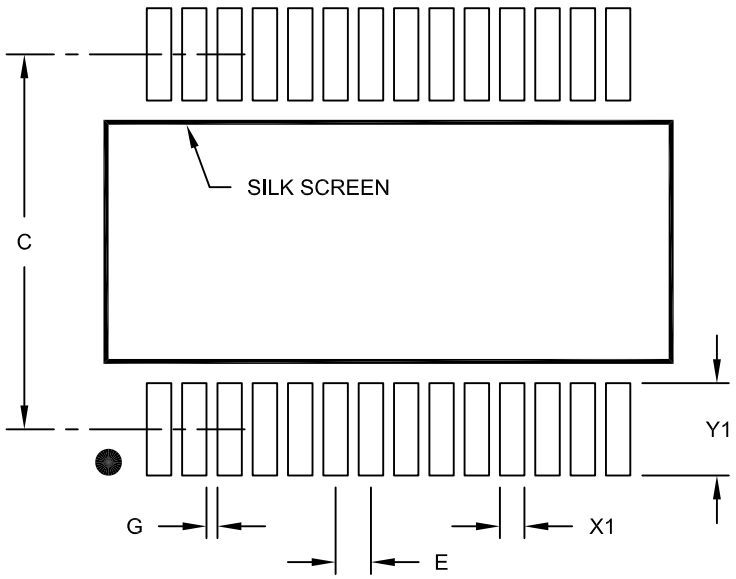
1. Pin 1 visual index feature may vary, but must be located within the hatched area.
2. § Significant Characteristic.
3. Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed .010" per side.
4. Dimensioning and tolerancing per ASME Y14.5M.

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing C04-070B

28-Lead Plastic Shrink Small Outline (SS) - 5.30 mm Body [SSOP]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging




RECOMMENDED LAND PATTERN

| Units | | MILLIMETERS | | |
|---|---|---|---|---|
| Dimension Limits | | MIN | NOM | MAX |
| Contact Pitch | E | 0.65 BSC | | |
| Contact Pad Spacing | C | | 7.20 | |
| Contact Pad Width (X28) | X1 | | | 0.45 |
| Contact Pad Length (X28) | Y1 | | | 1.75 |
| Distance Between Pads | G | 0.20 | | |

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2073A

# APPENDIX A: REVISION HISTORY

## Revision A (August 2009)

Original data sheet for the PIC24FJ64GA104 family of devices.

## Revision B (October 2009)

Corrected **Section 10.3 "Input Change Notification"** regarding the number of ICN inputs and the availability of pull-downs.

Updated **Section 10.4.2 "Available Peripherals"** by removing the Timer 1 clock input from Table 10-2.

Updated **Section 28.1 "DC Characteristics"** as follows:

- Added new specifications to Tables 29-4 and 29-5 for IDD and IIDLE at 0.5 MIPS operation.
- Updated Table 29-4 with revised maximum IDD specifications for 1 MIP and 4 MIPS.
- Renumbered the parameters for the delta IPD current (32 kHz, SOSCEL = 11) from DC62*n* to DC63*n*.

## Revision C (August 2010)

This revision includes the following updates:

Pin Diagrams

- Updated Pin 7 and Pin 14 in 28-Pin SPDIP, SOIC.
- Updated the device name, Pin13 and Pin 23, in 28-Pin QFN.

Removed IEC5, IFS5 and IPC21 rows from Table 4-5.

Updated CLKDIV bit details in Table 4-23.

Removed JTAG from Flash programming list in **Section 5.0 "Flash Program Memory"**.

Updated **Section 10.4.5 "Considerations for Peripheral Pin Selection"** as follows:

- Replaced the code in Example 10-2.
- Added the new code as Example 10-3.

Updated shaded note in **Section 20.0 "32-Bit Programmable Cyclic Redundancy Check (CRC) Generator"** and **Section 22.0 "Triple Comparator Module"**.

Updated **Section 28.1 "DC Characteristics"** as follows:

- Updated the device name in Table 28-1.
- Added the "125°C data" in Table 28-4,Table 28-5,Table 28-6 and Table 28-7.
- Updated Min and Typ columns of DC16 in Table 28-3.
- Added rows, AD08 and AD09, in Table 28-22.
- Added Figure 28-2.

Added the 28-pin SSOP package to **Section 29.0 "Packaging Information"**.