

Welcome to E-XFL.COM

What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

| | |
|----------------------------|---|
| Product Status | Active |
| Core Processor | PIC |
| Core Size | 16-Bit |
| Speed | 32MHz |
| Connectivity | I ² C, IrDA, SPI, UART/USART |
| Peripherals | Brown-out Detect/Reset, LVD, POR, PWM, WDT |
| Number of I/O | 21 |
| Program Memory Size | 64KB (22K x 24) |
| Program Memory Type | FLASH |
| EEPROM Size | - |
| RAM Size | 8K x 8 |
| Voltage - Supply (Vcc/Vdd) | 2V ~ 3.6V |
| Data Converters | A/D 10x10b |
| Oscillator Type | Internal |
| Operating Temperature | -40°C ~ 85°C (TA) |
| Mounting Type | Surface Mount |
| Package / Case | 28-SOIC (0.295", 7.50mm Width) |
| Supplier Device Package | 28-SOIC |
| Purchase URL | https://www.e-xfl.com/product-detail/microchip-technology/pic24fj64ga102-i-so |

TABLE 4-8: OUTPUT COMPARE REGISTER MAP

| File Name | Addr | Bit 15 | Bit 14 | Bit 13 | Bit 12 | Bit 11 | Bit 10 | Bit 9 | Bit 8 | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | All Resets |
|-----------|------|-------------------------------------|--------|----------|---------|---------|---------|--------|--------|--------|----------|--------|----------|----------|----------|----------|----------|------------|
| OC1CON1 | 0190 | — | — | OCSIDL | OCTSEL2 | OCTSEL1 | OCTSEL0 | ENFLT2 | ENFLT1 | ENFLT0 | OCFLT2 | OCFLT1 | OCFLT0 | TRIGMODE | OCM2 | OCM1 | OCM0 | 0000 |
| OC1CON2 | 0192 | FLTMD | FLTOUT | FLTTRIEN | OCINV | — | DCB1 | DCB0 | OC32 | OCTRIG | TRIGSTAT | OCTRIS | SYNCSEL4 | SYNCSEL3 | SYNCSEL2 | SYNCSEL1 | SYNCSEL0 | 000C |
| OC1RS | 0194 | Output Compare 1 Secondary Register | | | | | | | | | | | | | | | | 0000 |
| OC1R | 0196 | Output Compare 1 Register | | | | | | | | | | | | | | | | 0000 |
| OC1TMR | 0198 | Timer Value 1 Register | | | | | | | | | | | | | | | | xxxx |
| OC2CON1 | 019A | — | — | OCSIDL | OCTSEL2 | OCTSEL1 | OCTSEL0 | ENFLT2 | ENFLT1 | ENFLT0 | OCFLT2 | OCFLT1 | OCFLT0 | TRIGMODE | OCM2 | OCM1 | OCM0 | 0000 |
| OC2CON2 | 019C | FLTMD | FLTOUT | FLTTRIEN | OCINV | — | DCB1 | DCB0 | OC32 | OCTRIG | TRIGSTAT | OCTRIS | SYNCSEL4 | SYNCSEL3 | SYNCSEL2 | SYNCSEL1 | SYNCSEL0 | 000C |
| OC2RS | 019E | Output Compare 2 Secondary Register | | | | | | | | | | | | | | | | 0000 |
| OC2R | 01A0 | Output Compare 2 Register | | | | | | | | | | | | | | | | 0000 |
| OC2TMR | 01A2 | Timer Value 2 Register | | | | | | | | | | | | | | | | xxxx |
| OC3CON1 | 01A4 | — | — | OCSIDL | OCTSEL2 | OCTSEL1 | OCTSEL0 | ENFLT2 | ENFLT1 | ENFLT0 | OCFLT2 | OCFLT1 | OCFLT0 | TRIGMODE | OCM2 | OCM1 | OCM0 | 0000 |
| OC3CON2 | 01A6 | FLTMD | FLTOUT | FLTTRIEN | OCINV | — | DCB1 | DCB0 | OC32 | OCTRIG | TRIGSTAT | OCTRIS | SYNCSEL4 | SYNCSEL3 | SYNCSEL2 | SYNCSEL1 | SYNCSEL0 | 000C |
| OC3RS | 01A8 | Output Compare 3 Secondary Register | | | | | | | | | | | | | | | | 0000 |
| OC3R | 01AA | Output Compare 3 Register | | | | | | | | | | | | | | | | 0000 |
| OC3TMR | 01AC | Timer Value 3 Register | | | | | | | | | | | | | | | | xxxx |
| OC4CON1 | 01AE | — | — | OCSIDL | OCTSEL2 | OCTSEL1 | OCTSEL0 | ENFLT2 | ENFLT1 | ENFLT0 | OCFLT2 | OCFLT1 | OCFLT0 | TRIGMODE | OCM2 | OCM1 | OCM0 | 0000 |
| OC4CON2 | 01B0 | FLTMD | FLTOUT | FLTTRIEN | OCINV | — | DCB1 | DCB0 | OC32 | OCTRIG | TRIGSTAT | OCTRIS | SYNCSEL4 | SYNCSEL3 | SYNCSEL2 | SYNCSEL1 | SYNCSEL0 | 000C |
| OC4RS | 01B2 | Output Compare 4 Secondary Register | | | | | | | | | | | | | | | | 0000 |
| OC4R | 01B4 | Output Compare 4 Register | | | | | | | | | | | | | | | | 0000 |
| OC4TMR | 01B6 | Timer Value 4 Register | | | | | | | | | | | | | | | | xxxx |
| OC5CON1 | 01B8 | — | — | OCSIDL | OCTSEL2 | OCTSEL1 | OCTSEL0 | ENFLT2 | ENFLT1 | ENFLT0 | OCFLT2 | OCFLT1 | OCFLT0 | TRIGMODE | OCM2 | OCM1 | OCM0 | 0000 |
| OC5CON2 | 01BA | FLTMD | FLTOUT | FLTTRIEN | OCINV | — | DCB1 | DCB0 | OC32 | OCTRIG | TRIGSTAT | OCTRIS | SYNCSEL4 | SYNCSEL3 | SYNCSEL2 | SYNCSEL1 | SYNCSEL0 | 000C |
| OC5RS | 01BC | Output Compare 5 Secondary Register | | | | | | | | | | | | | | | | 0000 |
| OC5R | 01BE | Output Compare 5 Register | | | | | | | | | | | | | | | | 0000 |
| OC5TMR | 01C0 | Timer Value 5 Register | | | | | | | | | | | | | | | | xxxx |

Legend: — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

TABLE 4-23: SYSTEM REGISTER MAP

| File Name | Addr | Bit 15 | Bit 14 | Bit 13 | Bit 12 | Bit 11 | Bit 10 | Bit 9 | Bit 8 | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | All Resets |
|-----------|------|--------|--------|--------|--------|--------|--------|--------|--------|---------|-------|--------|-------|-------|--------|--------|-------|---------------|
| RCON | 0740 | TRAPR | IOPUWR | — | — | — | DPSLP | CM | PMSLP | EXTR | SWR | SWDTEN | WDTO | SLEEP | IDLE | BOR | POR | Note 1 |
| OSCCON | 0742 | — | COSC2 | COSC1 | COSC0 | — | NOSC2 | NOSC1 | NOSC0 | CLKLOCK | IOLCK | LOCK | — | CF | POSCEN | SOSCEN | OSWEN | Note 2 |
| CLKDIV | 0744 | ROI | DOZE2 | DOZE1 | DOZE0 | DOZEN | RCDIV2 | RCDIV1 | RCDIV0 | — | — | — | — | — | — | — | — | 0100 |
| OSCTUN | 0748 | — | — | — | — | — | — | — | — | — | — | TUN5 | TUN4 | TUN3 | TUN2 | TUN1 | TUN0 | 0000 |
| REFOCON | 074E | ROEN | — | ROSSLP | ROSEL | RODIV3 | RODIV2 | RODIV1 | RODIV0 | — | — | — | — | — | — | — | — | 0000 |

Legend: — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

Note 1: The Reset value of the RCON register is dependent on the type of Reset event. See **Section 6.0 “Resets”** for more information.

2: The Reset value of the OSCCON register is dependent on both the type of Reset event and the device configuration. See **Section 8.0 “Oscillator Configuration”** for more information.

TABLE 4-24: DEEP SLEEP REGISTER MAP

| File Name | Addr | Bit 15 | Bit 14 | Bit 13 | Bit 12 | Bit 11 | Bit 10 | Bit 9 | Bit 8 | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | All Resets ⁽¹⁾ |
|-----------|------|---------------------------------------|--------|--------|--------|--------|--------|-------|--------|-------|-------|-------|-------|-------|--------|-------|---------|---------------------------|
| DSCON | 758 | DSEN | — | — | — | — | — | — | — | — | — | — | — | — | — | DSBOR | RELEASE | 0000 |
| DSWAKE | 075A | — | — | — | — | — | — | — | DSINT0 | DSFLT | — | — | DSWDT | DSRTC | DSMCLR | — | DSPOR | 0001 |
| DSGPR0 | 075C | Deep Sleep General Purpose Register 0 | | | | | | | | | | | | | | | | 0000 |
| DSGPR1 | 075E | Deep Sleep General Purpose Register 1 | | | | | | | | | | | | | | | | 0000 |

Legend: — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

Note 1: The Deep Sleep registers are only reset on a VDD POR event.

TABLE 4-25: NVM REGISTER MAP

| File Name | Addr | Bit 15 | Bit 14 | Bit 13 | Bit 12 | Bit 11 | Bit 10 | Bit 9 | Bit 8 | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | All Resets |
|-----------|------|--------|--------|--------|--------|--------|--------|-------|-------|-------|----------------------|-------|-------|--------|--------|--------|--------|---------------------|
| NVMCON | 0760 | WR | WREN | WRERR | — | — | — | — | — | — | ERASE | — | — | NVMOP3 | NVMOP2 | NVMOP1 | NVMOP0 | 0000 ⁽¹⁾ |
| NVMKEY | 0766 | — | — | — | — | — | — | — | — | — | NVMKEY Register<7:0> | | | | | | | 0000 |

Legend: — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

Note 1: Reset value shown is for POR only. Value on other Reset states is dependent on the state of memory write or erase operations at the time of Reset.

TABLE 4-26: PMD REGISTER MAP

| File Name | Addr | Bit 15 | Bit 14 | Bit 13 | Bit 12 | Bit 11 | Bit 10 | Bit 9 | Bit 8 | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | All Resets |
|-----------|------|--------|--------|--------|--------|--------|--------|--------|-------|--------|-------|-------|--------|--------|--------|--------|--------|------------|
| PMD1 | 0770 | T5MD | T4MD | T3MD | T2MD | T1MD | — | — | — | I2C1MD | U2MD | U1MD | SPI2MD | SPI1MD | — | — | ADC1MD | 0000 |
| PMD2 | 0772 | — | — | — | IC5MD | IC4MD | IC3MD | IC2MD | IC1MD | — | — | — | OC5MD | OC4MD | OC3MD | OC2MD | OC1MD | 0000 |
| PMD3 | 0774 | — | — | — | — | — | CMPMD | RTCCMD | PMPMD | CRCMD | — | — | — | — | — | I2C2MD | — | 0000 |
| PMD4 | 0776 | — | — | — | — | — | — | — | — | — | — | — | — | REFOMD | CTMUMD | LVDMD | — | 0000 |

Legend: — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

PIC24FJ64GA104 FAMILY

EXAMPLE 5-2: ERASING A PROGRAM MEMORY BLOCK (C LANGUAGE CODE)

```
// C example using MPLAB C30
unsigned long progAddr = 0XXXXXXX;    // Address of row to write
unsigned int offset;

//Set up pointer to the first memory location to be written
TBLPAG = progAddr>>16;                // Initialize PM Page Boundary SFR
offset = progAddr & 0xFFFF;           // Initialize lower word of address

__builtin_tblwtl(offset, 0x0000);      // Set base address of erase block
                                        // with dummy latch write

NVMCON = 0x4042;                      // Initialize NVMCON

asm("DISI #5");                        // Block all interrupts with priority <7
                                        // for next 5 instructions
__builtin_write_NVM();                 // C30 function to perform unlock
                                        // sequence and set WR
```

EXAMPLE 5-3: LOADING THE WRITE BUFFERS (ASSEMBLY LANGUAGE CODE)

```
; Set up NVMCON for row programming operations
MOV    #0x4001, W0                    ;
MOV    W0, NVMCON                     ; Initialize NVMCON
; Set up a pointer to the first program memory location to be written
; program memory selected, and writes enabled
MOV    #0x0000, W0                    ;
MOV    W0, TBLPAG                     ; Initialize PM Page Boundary SFR
MOV    #0x6000, W0                    ; An example program memory address
; Perform the TBLWT instructions to write the latches
; 0th_program_word
MOV    #LOW_WORD_0, W2                ;
MOV    #HIGH_BYTE_0, W3               ;
TBLWTL W2, [W0]                       ; Write PM low word into program latch
TBLWTH W3, [W0++]                     ; Write PM high byte into program latch
; 1st_program_word
MOV    #LOW_WORD_1, W2                ;
MOV    #HIGH_BYTE_1, W3               ;
TBLWTL W2, [W0]                       ; Write PM low word into program latch
TBLWTH W3, [W0++]                     ; Write PM high byte into program latch
; 2nd_program_word
MOV    #LOW_WORD_2, W2                ;
MOV    #HIGH_BYTE_2, W3               ;
TBLWTL W2, [W0]                       ; Write PM low word into program latch
TBLWTH W3, [W0++]                     ; Write PM high byte into program latch
.
.
.
; 63rd_program_word
MOV    #LOW_WORD_31, W2               ;
MOV    #HIGH_BYTE_31, W3              ;
TBLWTL W2, [W0]                       ; Write PM low word into program latch
TBLWTH W3, [W0]                       ; Write PM high byte into program latch
```


PIC24FJ64GA104 FAMILY

REGISTER 7-5: IFS0: INTERRUPT FLAG STATUS REGISTER 0

| | | | | | | | |
|--------|-----|-------|--------|--------|--------|--------|-------|
| U-0 | U-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
| — | — | AD1IF | U1TXIF | U1RXIF | SPI1IF | SPF1IF | T3IF |
| bit 15 | | | | | | | bit 8 |

| | | | | | | | |
|-------|-------|-------|-----|-------|-------|-------|--------|
| R/W-0 | R/W-0 | R/W-0 | U-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
| T2IF | OC2IF | IC2IF | — | T1IF | OC1IF | IC1IF | INT0IF |
| bit 7 | | | | | | | bit 0 |

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15-14 **Unimplemented:** Read as '0'
- bit 13 **AD1IF:** A/D Conversion Complete Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred
- bit 12 **U1TXIF:** UART1 Transmitter Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred
- bit 11 **U1RXIF:** UART1 Receiver Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred
- bit 10 **SPI1IF:** SPI1 Event Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred
- bit 9 **SPF1IF:** SPI1 Fault Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred
- bit 8 **T3IF:** Timer3 Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred
- bit 7 **T2IF:** Timer2 Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred
- bit 6 **OC2IF:** Output Compare Channel 2 Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred
- bit 5 **IC2IF:** Input Capture Channel 2 Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred
- bit 4 **Unimplemented:** Read as '0'
- bit 3 **T1IF:** Timer1 Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred
- bit 2 **OC1IF:** Output Compare Channel 1 Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred
- bit 1 **IC1IF:** Input Capture Channel 1 Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred
- bit 0 **INT0IF:** External Interrupt 0 Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred

PIC24FJ64GA104 FAMILY

REGISTER 7-18: IPC3: INTERRUPT PRIORITY CONTROL REGISTER 3

| | | | | | | | |
|--------|-----|-----|-----|-----|-----|-----|-------|
| U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 |
| — | — | — | — | — | — | — | — |
| bit 15 | | | | | | | bit 8 |

| | | | | | | | |
|-------|--------|--------|--------|-----|---------|---------|---------|
| U-0 | R/W-1 | R/W-0 | R/W-0 | U-0 | R/W-1 | R/W-0 | R/W-0 |
| — | AD1IP2 | AD1IP1 | AD1IP0 | — | U1TXIP2 | U1TXIP1 | U1TXIP0 |
| bit 7 | | | | | | | bit 0 |

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-7 **Unimplemented:** Read as '0'

bit 6-4 **AD1IP<2:0>:** A/D Conversion Complete Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•
•
•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

bit 3 **Unimplemented:** Read as '0'

bit 2-0 **U1TXIP<2:0>:** UART1 Transmitter Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•
•
•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

PIC24FJ64GA104 FAMILY

REGISTER 7-20: IPC5: INTERRUPT PRIORITY CONTROL REGISTER 5

| | | | | | | | |
|--------|-----|-----|-----|-----|-----|-----|-------|
| U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 |
| — | — | — | — | — | — | — | — |
| bit 15 | | | | | | | bit 8 |

| | | | | | | | |
|-------|-----|-----|-----|-----|---------|---------|---------|
| U-0 | U-0 | U-0 | U-0 | U-0 | R/W-1 | R/W-0 | R/W-0 |
| — | — | — | — | — | INT1IP2 | INT1IP1 | INT1IP0 |
| bit 7 | | | | | | | bit 0 |

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-3

Unimplemented: Read as '0'

bit 2-0

INT1IP<2:0>: External Interrupt 1 Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•
•
•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

PIC24FJ64GA104 FAMILY

REGISTER 7-26: IPC11: INTERRUPT PRIORITY CONTROL REGISTER 11

| | | | | | | | |
|--------|-----|-----|-----|-----|-----|-----|-------|
| U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 |
| — | — | — | — | — | — | — | — |
| bit 15 | | | | | | | bit 8 |

| | | | | | | | |
|-------|--------|--------|--------|-----|-----|-----|-------|
| U-0 | R/W-1 | R/W-0 | R/W-0 | U-0 | U-0 | U-0 | U-0 |
| — | PMPIP2 | PMPIP1 | PMPIP0 | — | — | — | — |
| bit 7 | | | | | | | bit 0 |

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-7 **Unimplemented:** Read as '0'

bit 6-4 **PMPIP<2:0>:** Parallel Master Port Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•
•
•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

bit 3-0 **Unimplemented:** Read as '0'

PIC24FJ64GA104 FAMILY

REGISTER 7-32: INTTREG: INTERRUPT CONTROL AND STATUS REGISTER

| | | | | | | | |
|--------|-----|-------|-----|------|------|------|-------|
| R-0 | U-0 | R/W-0 | U-0 | R-0 | R-0 | R-0 | R-0 |
| CPUIRQ | — | VHOLD | — | ILR3 | ILR2 | ILR1 | ILR0 |
| bit 15 | | | | | | | bit 8 |

| | | | | | | | |
|-------|---------|---------|---------|---------|---------|---------|---------|
| U-0 | R-0 | R-0 | R-0 | R-0 | R-0 | R-0 | R-0 |
| — | VECNUM6 | VECNUM5 | VECNUM4 | VECNUM3 | VECNUM2 | VECNUM1 | VECNUM0 |
| bit 7 | | | | | | | bit 0 |

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15 **CPUIRQ:** Interrupt Request from Interrupt Controller CPU bit
1 = An interrupt request has occurred but has not yet been Acknowledged by the CPU; this happens when the CPU priority is higher than the interrupt priority
0 = No interrupt request is unacknowledged
- bit 14 Unimplemented: Read as '0'
- bit 13 **VHOLD:** Vector Number Capture Configuration bit
1 = The VECNUM bits contain the value of the highest priority pending interrupt
0 = The VECNUM bits contain the value of the last Acknowledged interrupt (i.e., the last interrupt that has occurred with higher priority than the CPU, even if other interrupts are pending)
- bit 12 Unimplemented: Read as '0'
- bit 11-8 **ILR<3:0>:** New CPU Interrupt Priority Level bits
1111 = CPU Interrupt Priority Level is 15
•
•
•
0001 = CPU Interrupt Priority Level is 1
0000 = CPU Interrupt Priority Level is 0
- bit 7 Unimplemented: Read as '0'
- bit 6-0 **VECNUM<6:0>:** Pending Interrupt Vector ID bits (pending vector number is VECNUM + 8)
0111111 = Interrupt Vector pending is number 135
•
•
•
0000001 = Interrupt Vector pending is number 9
0000000 = Interrupt Vector pending is number 8

9.0 POWER-SAVING FEATURES

Note: This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the “PIC24F Family Reference Manual”, **Section 39. “Power-Saving Features with Deep Sleep”** (DS39727).

The PIC24FJ64GA104 family of devices provides the ability to manage power consumption by selectively managing clocking to the CPU and the peripherals. In general, a lower clock frequency and a reduction in the number of circuits being clocked constitutes lower consumed power. All PIC24F devices manage power consumption in four different ways:

- Clock Frequency
- Instruction-Based Sleep, Idle and Deep Sleep modes
- Software Controlled Doze mode
- Selective Peripheral Control in Software

Combinations of these methods can be used to selectively tailor an application’s power consumption, while still maintaining critical application features, such as timing-sensitive communications.

9.1 Clock Frequency and Clock Switching

PIC24F devices allow for a wide range of clock frequencies to be selected under application control. If the system clock configuration is not locked, users can choose low-power or high-precision oscillators by simply changing the NOSC bits. The process of changing a system clock during operation, as well as limitations to the process, are discussed in more detail in **Section 8.0 “Oscillator Configuration”**.

9.2 Instruction-Based Power-Saving Modes

PIC24F devices have two special power-saving modes that are entered through the execution of a special `PWRSV` instruction. Sleep mode stops clock operation and halts all code execution; Idle mode halts the CPU and code execution, but allows peripheral modules to continue operation. Deep Sleep mode stops clock operation, code execution and all peripherals except RTCC and DSWDT. It also freezes I/O states and removes power to SRAM and Flash memory.

The assembly syntax of the `PWRSV` instruction is shown in Example 9-1.

Note: `SLEEP_MODE` and `IDLE_MODE` are constants defined in the assembler include file for the selected device.

Sleep and Idle modes can be exited as a result of an enabled interrupt, WDT time-out or a device Reset. When the device exits these modes, it is said to “wake-up”.

9.2.1 SLEEP MODE

Sleep mode has these features:

- The system clock source is shut down. If an on-chip oscillator is used, it is turned off.
- The device current consumption will be reduced to a minimum provided that no I/O pin is sourcing current.
- The I/O pin directions and states are frozen.
- The Fail-Safe Clock Monitor does not operate during Sleep mode since the system clock source is disabled.
- The LPRC clock will continue to run in Sleep mode if the WDT or RTCC with LPRC as clock source is enabled.
- The WDT, if enabled, is automatically cleared prior to entering Sleep mode.
- Some device features or peripherals may continue to operate in Sleep mode. This includes items, such as the input change notification on the I/O ports, or peripherals that use an external clock input. Any peripheral that requires the system clock source for its operation will be disabled in Sleep mode.

The device will wake-up from Sleep mode on any of these events:

- On any interrupt source that is individually enabled
- On any form of device Reset
- On a WDT time-out

On wake-up from Sleep, the processor will restart with the same clock source that was active when Sleep mode was entered.

EXAMPLE 9-1: PWRSV INSTRUCTION SYNTAX

```
PWRSV    #SLEEP_MODE    ; Put the device into SLEEP mode
PWRSV    #IDLE_MODE     ; Put the device into IDLE mode
BSET     DCON, #DSEN    ; Enable Deep Sleep
PWRSV    #SLEEP_MODE    ; Put the device into Deep SLEEP mode
```


PIC24FJ64GA104 FAMILY

9.2.4.10 Power-on Resets (PORs)

VDD voltage is monitored to produce PORs. Since exiting from Deep Sleep functionally looks like a POR, the technique described in **Section 9.2.4.9 “Checking and Clearing the Status of Deep Sleep”** should be used to distinguish between Deep Sleep and a true POR event.

When a true POR occurs, the entire device, including all Deep Sleep logic (Deep Sleep registers, RTCC, DSWDT, etc.) is reset.

9.2.4.11 Summary of Deep Sleep Sequence

To review, these are the necessary steps involved in invoking and exiting Deep Sleep mode:

1. Device exits Reset and begins to execute its application code.
2. If DSWDT functionality is required, program the appropriate Configuration bit.
3. Select the appropriate clock(s) for the DSWDT and RTCC (optional).
4. Enable and configure the RTCC (optional).
5. Write context data to the DSGPRx registers (optional).
6. Enable the INT0 interrupt (optional).
7. Set the DSEN bit in the DSCON register.
8. Enter Deep Sleep by issuing a `PWRSV #SLEEP_MODE` command.
9. Device exits Deep Sleep when a wake-up event occurs.
10. The DSEN bit is automatically cleared.
11. Read and clear the DPSLP status bit in RCON, and the DSWAKE status bits.
12. Read the DSGPRx registers (optional).
13. Once all state related configurations are complete, clear the RELEASE bit.
14. Application resumes normal operation.

PIC24FJ64GA104 FAMILY

REGISTER 9-1: DSCON: DEEP SLEEP CONTROL REGISTER

| | | | | | | | |
|---------------------|-----|-----|-----|-----|-----|-----|-------|
| R/W-0, HC | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 |
| DSEN ⁽¹⁾ | — | — | — | — | — | — | — |
| bit 15 | | | | | | | bit 8 |

| | | | | | | | |
|-------|-----|-----|-----|-----|-----|--------------------------|--------------------------|
| U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | R/W-0, HCS | R/C-0, HS |
| — | — | — | — | — | — | DSBOR ^(1,2,3) | RELEASE ^(1,2) |
| bit 7 | | | | | | | bit 0 |

Legend:

| | | | |
|-----------------------------|----------------------------|---------------------------------------|--------------------------------|
| R = Readable bit | W = Writable bit | C = Clearable bit | U = Unimplemented, read as '0' |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |
| HC = Hardware Clearable bit | HS = Hardware Settable bit | HCS = Hardware Clearable/Settable bit | |

bit 15 **DSEN:** Deep Sleep Enable bit⁽¹⁾

- 1 = Device enters Deep Sleep when PWRSAV #0 is executed in the next instruction
- 0 = Device enters normal Sleep when PWRSAV #0 is executed

bit 14-2 **Unimplemented:** Read as '0'

bit 1 **DSBOR:** Deep Sleep BOR Event Status bit^(1,2,3)

- 1 = The DSBOR was active and a BOR event was detected during Deep Sleep
- 0 = The DSBOR was disabled or was active and did not detect a BOR event during Deep Sleep

bit 0 **RELEASE:** I/O Pin State Deep Sleep Release bit^(1,2)

- 1 = I/O pins and SOSC maintain their states following exit from Deep Sleep, regardless of their LAT and TRIS configuration
- 0 = I/O pins and SOSC are released from their Deep Sleep states. The pin state is controlled by the LAT and TRIS configurations, and the SOSCEN bit.

Note 1: These bits are reset only in the case of a POR event outside of Deep Sleep mode.

2: Reset value is '0' for initial power-on POR only and '1' for Deep Sleep POR.

3: This is a status bit only; a DSBOR event will NOT cause a wake-up from Deep Sleep.

PIC24FJ64GA104 FAMILY

FIGURE 15-5: SPI MASTER, FRAME MASTER CONNECTION DIAGRAM

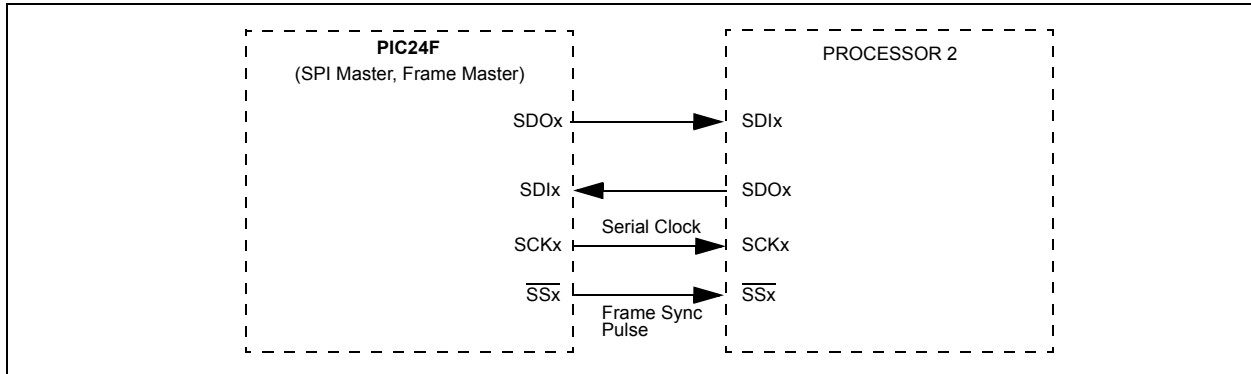


FIGURE 15-6: SPI MASTER, FRAME SLAVE CONNECTION DIAGRAM

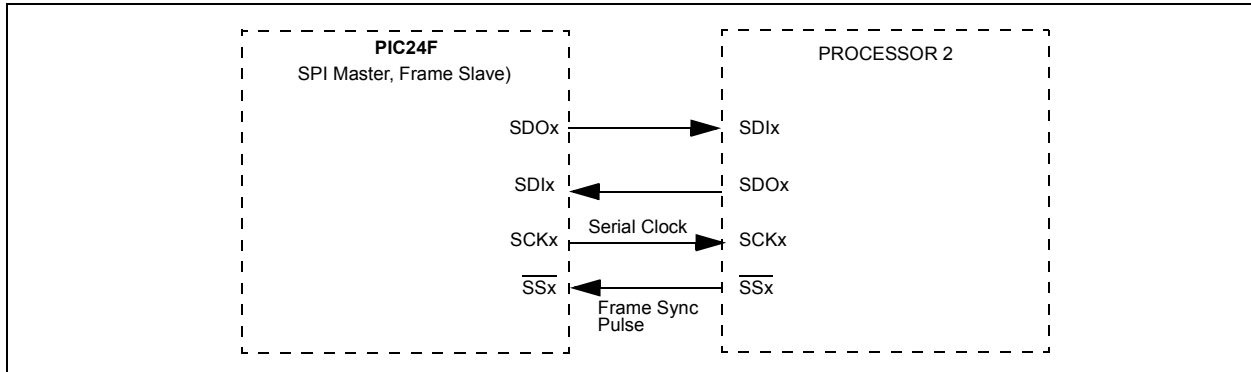


FIGURE 15-7: SPI SLAVE, FRAME MASTER CONNECTION DIAGRAM

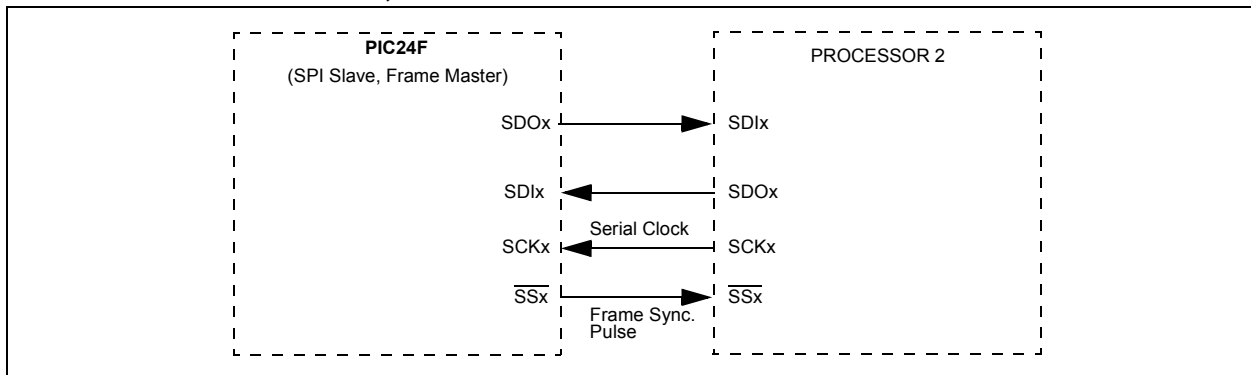
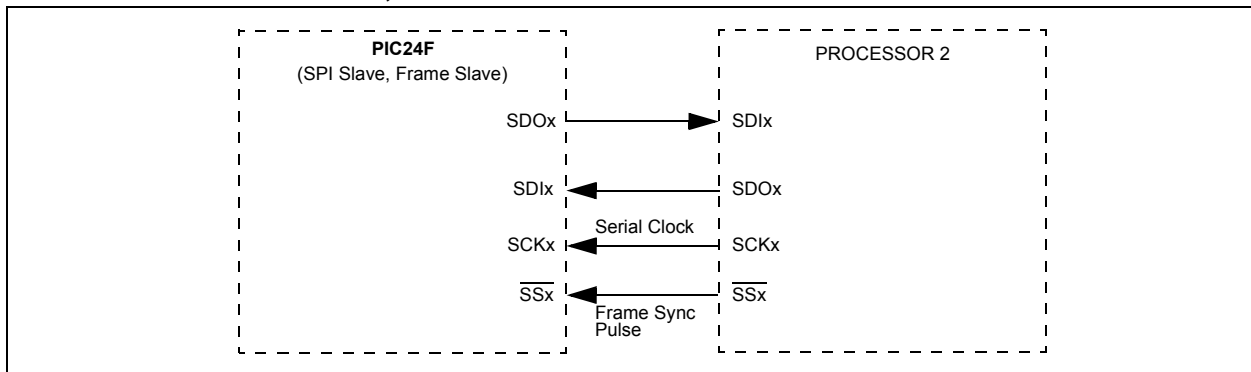


FIGURE 15-8: SPI SLAVE, FRAME SLAVE CONNECTION DIAGRAM



PIC24FJ64GA104 FAMILY

REGISTER 16-1: I2CxCON: I2Cx CONTROL REGISTER (CONTINUED)

- bit 5 **ACKDT:** Acknowledge Data bit (When operating as I²C master. Applicable during master receive.)
Value that will be transmitted when the software initiates an Acknowledge sequence.
1 = Sends NACK during Acknowledge
0 = Sends ACK during Acknowledge
- bit 4 **ACKEN:** Acknowledge Sequence Enable bit
(When operating as I²C master. Applicable during master receive.)
1 = Initiates Acknowledge sequence on SDAx and SCLx pins and transmits ACKDT data bit. Hardware clear at end of master Acknowledge sequence.
0 = Acknowledge sequence is not in progress
- bit 3 **RCEN:** Receive Enable bit (when operating as I²C master)
1 = Enables Receive mode for I²C. Hardware clear at end of eighth bit of master receive data byte.
0 = Receive sequence is not in progress
- bit 2 **PEN:** Stop Condition Enable bit (when operating as I²C master)
1 = Initiates Stop condition on SDAx and SCLx pins. Hardware clear at end of master Stop sequence.
0 = Stop condition is not in progress
- bit 1 **RSEN:** Repeated Start Condition Enabled bit (when operating as I²C master)
1 = Initiates Repeated Start condition on SDAx and SCLx pins. Hardware clear at end of master Repeated Start sequence.
0 = Repeated Start condition is not in progress
- bit 0 **SEN:** Start Condition Enabled bit (when operating as I²C master)
1 = Initiates Start condition on SDAx and SCLx pins. Hardware clear at end of master Start sequence.
0 = Start condition is not in progress

17.2 Transmitting in 8-Bit Data Mode

1. Set up the UART:
 - a) Write appropriate values for data, parity and Stop bits.
 - b) Write appropriate baud rate value to the UxBRG register.
 - c) Set up transmit and receive interrupt enable and priority bits.
2. Enable the UART.
3. Set the UTXEN bit (causes a transmit interrupt two cycles after being set).
4. Write data byte to the lower byte of the UxTXREG word. The value will be immediately transferred to the Transmit Shift Register (TSR) and the serial bit stream will start shifting out with the next rising edge of the baud clock.
5. Alternately, the data byte may be transferred while UTXEN = 0, and then the user may set UTXEN. This will cause the serial bit stream to begin immediately because the baud clock will start from a cleared state.
6. A transmit interrupt will be generated as per interrupt control bit, UTXISELx.

17.3 Transmitting in 9-Bit Data Mode

1. Set up the UART (as described in **Section 17.2 “Transmitting in 8-Bit Data Mode”**).
2. Enable the UART.
3. Set the UTXEN bit (causes a transmit interrupt).
4. Write UxTXREG as a 16-bit value only.
5. A word write to UxTXREG triggers the transfer of the 9-bit data to the TSR. The serial bit stream will start shifting out with the first rising edge of the baud clock.
6. A transmit interrupt will be generated as per the setting of control bit, UTXISELx.

17.4 Break and Sync Transmit Sequence

The following sequence will send a message frame header made up of a Break, followed by an Auto-Baud Sync byte.

1. Configure the UART for the desired mode.
2. Set UTXEN and UTXBRK to set up the Break character.
3. Load the UxTXREG with a dummy character to initiate transmission (value is ignored).
4. Write '55h' to UxTXREG; this loads the Sync character into the transmit FIFO.
5. After the Break has been sent, the UTXBRK bit is reset by hardware. The Sync character now transmits.

17.5 Receiving in 8-Bit or 9-Bit Data Mode

1. Set up the UART (as described in **Section 17.2 “Transmitting in 8-Bit Data Mode”**).
2. Enable the UART.
3. A receive interrupt will be generated when one or more data characters have been received as per interrupt control bit, URXISELx.
4. Read the OERR bit to determine if an overrun error has occurred. The OERR bit must be reset in software.
5. Read UxRXREG.

The act of reading the UxRXREG character will move the next character to the top of the receive FIFO, including a new set of PERR and FERR values.

17.6 Operation of $\overline{\text{UxCTS}}$ and $\overline{\text{UxRTS}}$ Control Pins

UARTx Clear to Send ($\overline{\text{UxCTS}}$) and Request to Send ($\overline{\text{UxRTS}}$) are the two hardware-controlled pins that are associated with the UART module. These two pins allow the UART to operate in Simplex and Flow Control modes. They are implemented to control the transmission and reception between the Data Terminal Equipment (DTE). The UEN<1:0> bits in the UxMODE register configure these pins.

17.7 Infrared Support

The UART module provides two types of infrared UART support: one is the IrDA clock output to support the external IrDA encoder and decoder device (legacy module support), and the other is the full implementation of the IrDA encoder and decoder. Note that because the IrDA modes require a 16x baud clock, they will only work when the BRGH bit (UxMODE<3>) is '0'.

17.7.1 IRDA CLOCK OUTPUT FOR EXTERNAL IRDA SUPPORT

To support external IrDA encoder and decoder devices, the BCLKx pin (same as the UxRTS pin) can be configured to generate the 16x baud clock. When UEN<1:0> = 11, the BCLKx pin will output the 16x baud clock if the UART module is enabled. It can be used to support the IrDA codec chip.

17.7.2 BUILT-IN IRDA ENCODER AND DECODER

The UART has full implementation of the IrDA encoder and decoder as part of the UART module. The built-in IrDA encoder and decoder functionality is enabled using the IREN bit (UxMODE<12>). When enabled (IREN = 1), the receive pin (UxRX) acts as the input from the infrared receiver. The transmit pin (UxTX) acts as the output to the infrared transmitter.

PIC24FJ64GA104 FAMILY

19.3 Calibration

The real-time crystal input can be calibrated using the periodic auto-adjust feature. When properly calibrated, the RTCC can provide an error of less than 3 seconds per month. This is accomplished by finding the number of error clock pulses and storing the value into the lower half of the RCFGAL register. The 8-bit signed value loaded into the lower half of RCFGAL is multiplied by four and will either be added or subtracted from the RTCC timer, once every minute. Refer to the steps below for RTCC calibration:

1. Using another timer resource on the device; the user must find the error of the 32.768 kHz crystal.
2. Once the error is known, it must be converted to the number of error clock pulses per minute.
3.
 - a) If the oscillator is faster than ideal (negative result from step 2), the RCFGAL register value must be negative. This causes the specified number of clock pulses to be subtracted from the timer counter, once every minute.
 - b) If the oscillator is slower than ideal (positive result from step 2), the RCFGAL register value must be positive. This causes the specified number of clock pulses to be subtracted from the timer counter, once every minute.

Divide the number of error clocks per minute by 4 to get the correct calibration value and load the RCFGAL register with the correct value. (Each 1-bit increment in the calibration adds or subtracts 4 pulses.)

EQUATION 19-1:

$$(\text{Ideal Frequency} \uparrow - \text{Measured Frequency}) * 60 = \text{Clocks per Minute}$$

$$\uparrow \text{ Ideal Frequency} = 32,768 \text{ Hz}$$

Writes to the lower half of the RCFGAL register should only occur when the timer is turned off or immediately after the rising edge of the seconds pulse.

Note: It is up to the user to include, in the error value, the initial error of the crystal drift due to temperature and drift due to crystal aging.

19.4 Alarm

- Configurable from half second to one year
- Enabled using the ALRMEN bit (ALCFGRPT<15>)
- One-time alarm and repeat alarm options are available

19.4.1 CONFIGURING THE ALARM

The alarm feature is enabled using the ALRMEN bit. This bit is cleared when an alarm is issued. Writes to ALRMVAL should only take place when ALRMEN = 0.

As displayed in Figure 19-2, the interval selection of the alarm is configured through the AMASK bits (ALCFGRPT<13:10>). These bits determine which and how many digits of the alarm must match the clock value for the alarm to occur.

The alarm can also be configured to repeat based on a preconfigured interval. The amount of times this occurs, once the alarm is enabled, is stored in the ARPT<7:0> bits (ALCFGRPT<7:0>). When the value of the ARPT bits equals 00h and the CHIME bit (ALCFGRPT<14>) is cleared, the repeat function is disabled and only a single alarm will occur. The alarm can be repeated up to 255 times by loading ARPT<7:0> with FFh.

After each alarm is issued, the value of the ARPT bits is decremented by one. Once the value has reached 00h, the alarm will be issued one last time, after which, the ALRMEN bit will be cleared automatically and the alarm will turn off.

Indefinite repetition of the alarm can occur if the CHIME bit = 1. Instead of the alarm being disabled when the value of the ARPT bits reaches 00h, it rolls over to FFh and continues counting indefinitely while CHIME is set.

19.4.2 ALARM INTERRUPT

At every alarm event, an interrupt is generated. In addition, an alarm pulse output is provided that operates at half the frequency of the alarm. This output is completely synchronous to the RTCC clock and can be used as a trigger clock to other peripherals.

Note: Changing any of the registers, other than the RCFGAL and ALCFGRPT registers, and the CHIME bit while the alarm is enabled (ALRMEN = 1), can result in a false alarm event leading to a false alarm interrupt. To avoid a false alarm event, the timer and alarm values should only be changed while the alarm is disabled (ALRMEN = 0). It is recommended that the ALCFGRPT register and CHIME bit be changed when RTCSYNC = 0.

PIC24FJ64GA104 FAMILY

REGISTER 21-2: AD1CON2: A/D CONTROL REGISTER 2

| | | | | | | | |
|--------|-------|-------|-----|-----|-------|-------|-----|
| R/W-0 | R/W-0 | R/W-0 | r-0 | U-0 | R/W-0 | U-0 | U-0 |
| VCFG2 | VCFG1 | VCFG0 | r | — | CSCNA | — | — |
| bit 15 | | | | | | bit 8 | |

| | | | | | | | |
|-------|-----|-------|-------|-------|-------|-------|-------|
| R-0 | U-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
| BUFS | — | SMPI3 | SMPI2 | SMPI1 | SMPI0 | BUFM | ALTS |
| bit 7 | | | | | | bit 0 | |

Legend: r = Reserved bit
R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'
-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 15-13 **VCFG<2:0>:** Voltage Reference Configuration bits

| VCFG<2:0> | Vr+ | Vr- |
|-----------|--------------------|--------------------|
| 000 | AVDD | AVSS |
| 001 | External VREF+ pin | AVSS |
| 010 | AVDD | External VREF- pin |
| 011 | External VREF+ pin | External VREF- pin |
| 1xx | AVDD | AVSS |

bit 12 **Reserved:** Maintain as '0'

bit 11 **Unimplemented:** Read as '0'

bit 10 **CSCNA:** Scan Input Selections for CH0+ S/H Input for MUX A Input Multiplexer Setting bit

1 = Scan inputs
0 = Do not scan inputs

bit 9-8 **Unimplemented:** Read as '0'

bit 7 **BUFS:** Buffer Fill Status bit (valid only when BUFM = 1)

1 = A/D is currently filling buffer 08-0F; user should access data in 00-07
0 = A/D is currently filling buffer 00-07; user should access data in 08-0F

bit 6 **Unimplemented:** Read as '0'

bit 5-2 **SMPI<3:0>:** Sample/Convert Sequences Per Interrupt Selection bits

1111 = Interrupts at the completion of conversion for each 16th sample/convert sequence
1110 = Interrupts at the completion of conversion for each 15th sample/convert sequence
.....
0001 = Interrupts at the completion of conversion for each 2nd sample/convert sequence
0000 = Interrupts at the completion of conversion for each sample/convert sequence

bit 1 **BUFM:** Buffer Mode Select bit

1 = Buffer is configured as two 8-word buffers (ADC1BUF<n<15:8> and ADC1BUF<n<7:0>)
0 = Buffer is configured as one 16-word buffer (ADC1BUF<n<15:0>)

bit 0 **ALTS:** Alternate Input Sample Mode Select bit

1 = Uses MUX A input multiplexer settings for first sample, then alternates between MUX B and MUX A input multiplexer settings for all subsequent samples
0 = Always uses MUX A input multiplexer settings

PIC24FJ64GA104 FAMILY

REGISTER 23-1: CVRCON: COMPARATOR VOLTAGE REFERENCE CONTROL REGISTER

| | | | | | | | |
|--------|-----|-----|-----|-----|--------|---------|---------|
| U-0 | U-0 | U-0 | U-0 | U-0 | R/W-0 | R/W-0 | R/W-0 |
| — | — | — | — | — | CVREFP | CVREFM1 | CVREFM0 |
| bit 15 | | | | | | bit 8 | |

| | | | | | | | |
|-------|-------|-------|-------|-------|-------|-------|-------|
| R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
| CVREN | CVROE | CVRR | CVRSS | CVR3 | CVR2 | CVR1 | CVR0 |
| bit 7 | | | | | | | bit 0 |

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-11 **Unimplemented:** Read as '0'

bit 10 **CVREFP:** CVREF+ Reference Output Select bit

1 = Use VREF+ input pin as CVREF+ reference output to comparators

0 = Use comparator voltage reference module's generated output as CVREF+ reference output to comparators

bit 9-8 **CVREFM<1:0>:** CVREF- Reference Output Select bits

11 = Use VREF+ input pin as CVREF- reference output to comparators

10 = Use VBG/6 as CVREF- reference output to comparators

01 = Use VBG as CVREF- reference output to comparators

00 = Use VBG/2 as CVREF- reference output to comparators

bit 7 **CVREN:** Comparator Voltage Reference Enable bit

1 = CVREF circuit is powered on

0 = CVREF circuit is powered down

bit 6 **CVROE:** Comparator VREF Output Enable bit

1 = CVREF voltage level is output on CVREF pin

0 = CVREF voltage level is disconnected from CVREF pin

bit 5 **CVRR:** Comparator VREF Range Selection bit

1 = CVRSRC range should be 0 to 0.625 CVRSRC with CVRSRC/24 step size

0 = CVRSRC range should be 0.25 to 0.719 CVRSRC with CVRSRC/32 step size

bit 4 **CVRSS:** Comparator VREF Source Selection bit

1 = Comparator reference source, CVRSRC = VREF+ – VREF-

0 = Comparator reference source, CVRSRC = AVDD – AVSS

bit 3-0 **CVR<3:0>:** Comparator VREF Value Selection ($0 \leq \text{CVR}<3:0> \leq 15$) bits

When CVRR = 1:

$\text{CVREF} = (\text{CVR}<3:0>/24) \cdot (\text{CVRSRC})$

When CVRR = 0:

$\text{CVREF} = 1/4 \cdot (\text{CVRSRC}) + (\text{CVR}<3:0>/32) \cdot (\text{CVRSRC})$

PIC24FJ64GA104 FAMILY

REGISTER 25-4: CW4: FLASH CONFIGURATION WORD 4

| | | | | | | | |
|--------|-----|-----|-----|-----|-----|-----|--------|
| U-1 | U-1 | U-1 | U-1 | U-1 | U-1 | U-1 | U-1 |
| — | — | — | — | — | — | — | — |
| bit 23 | | | | | | | bit 16 |

| | | | | | | | |
|--------|-----|-----|-----|-----|-----|-----|-------|
| U-1 | U-1 | U-1 | U-1 | U-1 | U-1 | U-1 | U-1 |
| — | — | — | — | — | — | — | — |
| bit 15 | | | | | | | bit 8 |

| | | | | | | | |
|---------|---------|--------|----------|----------|----------|----------|----------|
| R/PO-1 | R/PO-1 | R/PO-1 | R/PO-1 | R/PO-1 | R/PO-1 | R/PO-1 | R/PO-1 |
| DSWDTEN | DSBOREN | RTCOSC | DSWDTOSC | DSWDTPS3 | DSWDTPS2 | DSWDTPS1 | DSWDTPS0 |
| bit 7 | | | | | | | bit 0 |

Legend:

R = Readable bit PO = Program Once bit U = Unimplemented bit, read as '0'
 -n = Value when device is unprogrammed '1' = Bit is set '0' = Bit is cleared

- bit 23-8 **Unimplemented:** Read as '1'
- bit 7 **DSWDTEN:** Deep Sleep Watchdog Timer Enable bit
 1 = DSWDT is enabled
 0 = DSWDT is disabled
- bit 6 **DSBOREN:** Deep Sleep BOR Enable bit
 1 = BOR is enabled in Deep Sleep
 0 = BOR is disabled in Deep Sleep (does not affect Sleep mode)
- bit 5 **RTCOSC:** RTCC Reference Clock Select bit
 1 = RTCC uses SOSC as reference clock
 0 = RTCC uses LPRC as reference clock
- bit 4 **DSWDTOSC:** DSWDT Reference Clock Select bit
 1 = DSWDT uses LPRC as reference clock
 0 = DSWDT uses SOSC as reference clock
- bit 3-0 **DSWDTPS<3:0>:** DSWDT Postscale select bits
 The DSWDT prescaler is 32; this creates an approximate base time unit of 1 ms.
 1111 = 1:2,147,483,648 (25.7 days)
 1110 = 1:536,870,912 (6.4 days)
 1101 = 1:134,217,728 (38.5 hours)
 1100 = 1:33,554,432 (9.6 hours)
 1011 = 1:8,388,608 (2.4 hours)
 1010 = 1:2,097,152 (36 minutes)
 1001 = 1:524,288 (9 minutes)
 1000 = 1:131,072 (135 seconds)
 0111 = 1:32,768 (34 seconds)
 0110 = 1:8,192 (8.5 seconds)
 0101 = 1:2,048 (2.1 seconds)
 0100 = 1:512 (528 ms)
 0011 = 1:128 (132 ms)
 0010 = 1:32 (33 ms)
 0001 = 1:8 (8.3 ms)
 0000 = 1:2 (2.1 ms)

PIC24FJ64GA104 FAMILY

28.2 AC Characteristics and Timing Parameters

The information contained in this section defines the PIC24FJ64GA104 family AC characteristics and timing parameters.

TABLE 28-14: TEMPERATURE AND VOLTAGE SPECIFICATIONS – AC

| | |
|---------------------------|--|
| AC CHARACTERISTICS | Standard Operating Conditions: 2.0V to 3.6V (unless otherwise stated) |
| | Operating temperature $-40^{\circ}\text{C} \leq T_A \leq +85^{\circ}\text{C}$ for Industrial and |
| | $-40^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$ for Extended |
| | Operating voltage V_{DD} range as described in Section 28.1 “DC Characteristics” . |

FIGURE 28-3: LOAD CONDITIONS FOR DEVICE TIMING SPECIFICATIONS

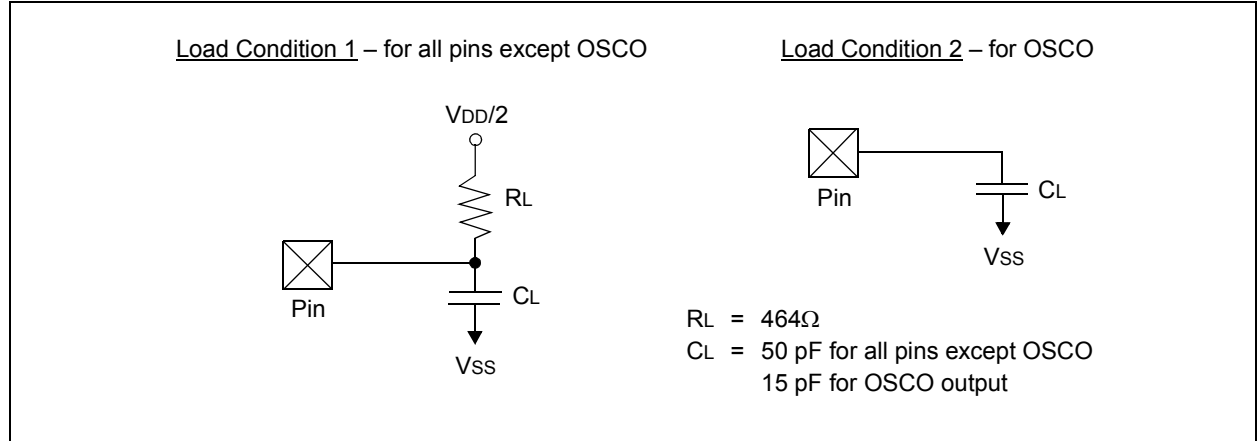


TABLE 28-15: CAPACITIVE LOADING REQUIREMENTS ON OUTPUT PINS

| Param No. | Symbol | Characteristic | Min | Typ ⁽¹⁾ | Max | Units | Conditions |
|-----------|--------|-----------------------|-----|--------------------|-----|-------|---|
| DO50 | Cosc2 | OSCO/CLKO Pin | — | — | 15 | pF | In XT and HS modes when external clock is used to drive OSCI. |
| DO56 | Cio | All I/O Pins and OSCO | — | — | 50 | pF | EC mode. |
| DO58 | Cb | SCLx, SDAx | — | — | 400 | pF | In I ² C™ mode. |

Note 1: Data in “Typ” column is at 3.3V, 25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

PIC24FJ64GA104 FAMILY

NOTES: