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Understanding Embedded - Microprocessors

Embedded microprocessors are specialized computing chips designed to perform specific tasks within an embedded system. Unlike general-purpose microprocessors found in personal computers, embedded microprocessors are tailored for dedicated functions within larger systems, offering optimized performance, efficiency, and reliability. These microprocessors are integral to the operation of countless electronic devices, providing the computational power necessary for controlling processes, handling data, and managing communications.

Applications of Embedded - Microprocessors

Embedded microprocessors are utilized across a broad spectrum of applications, making them indispensable in

Details	
Product Status	Active
Core Processor	PowerPC e500mc
Number of Cores/Bus Width	4 Core, 32-Bit
Speed	1.5GHz
Co-Processors/DSP	-
RAM Controllers	DDR3, DDR3L
Graphics Acceleration	No
Display & Interface Controllers	-
Ethernet	10/100/1000Mbps (5), 10Gbps (1)
SATA	SATA 3Gbps (2)
USB	USB 2.0 + PHY (2)
Voltage - I/O	1.0V, 1.35V, 1.5V, 1.8V, 2.5V, 3.3V
Operating Temperature	0°C ~ 105°C (TA)
Security Features	-
Package / Case	780-BBGA, FCBGA
Supplier Device Package	780-FCPBGA (23x23)
Purchase URL	https://www.e-xfl.com/pro/item?MUrl=&PartUrl=p2041nsn1pnb

Table 1. Pin List by Bus (continued)

Signal	Signal Description	Package Pin Number	Pin Type	Power Supply	Note
MDQ29	Data	AC4	I/O	GV_{DD}	—
MDQ30	Data	AE1	I/O	GV_{DD}	—
MDQ31	Data	AE3	I/O	GV_{DD}	—
MDQ32	Data	AE16	I/O	GV_{DD}	—
MDQ33	Data	AD16	I/O	GV_{DD}	—
MDQ34	Data	AE19	I/O	GV_{DD}	—
MDQ35	Data	AD19	I/O	GV_{DD}	—
MDQ36	Data	AF15	I/O	GV_{DD}	—
MDQ37	Data	AF16	I/O	GV_{DD}	—
MDQ38	Data	AF18	I/O	GV_{DD}	—
MDQ39	Data	AF19	I/O	GV_{DD}	—
MDQ40	Data	AH23	I/O	GV_{DD}	—
MDQ41	Data	AG23	I/O	GV_{DD}	—
MDQ42	Data	AH27	I/O	GV_{DD}	—
MDQ43	Data	AG27	I/O	GV_{DD}	—
MDQ44	Data	AG21	I/O	GV_{DD}	—
MDQ45	Data	AH22	I/O	GV_{DD}	—
MDQ46	Data	AH26	I/O	GV_{DD}	—
MDQ47	Data	AG26	I/O	GV_{DD}	—
MDQ48	Data	AF21	I/O	GV_{DD}	—
MDQ49	Data	AD21	I/O	GV_{DD}	—
MDQ50	Data	AF24	I/O	GV_{DD}	—
MDQ51	Data	AD24	I/O	GV_{DD}	—
MDQ52	Data	AE20	I/O	GV_{DD}	—
MDQ53	Data	AD20	I/O	GV_{DD}	—
MDQ54	Data	AD23	I/O	GV_{DD}	—
MDQ55	Data	AE25	I/O	GV_{DD}	—
MDQ56	Data	AF26	I/O	GV_{DD}	—
MDQ57	Data	AF27	I/O	GV_{DD}	—
MDQ58	Data	AD25	I/O	GV_{DD}	—
MDQ59	Data	AD26	I/O	GV_{DD}	—
MDQ60	Data	AG28	I/O	GV_{DD}	—
MDQ61	Data	AF25	I/O	GV_{DD}	—
MDQ62	Data	AD27	I/O	GV_{DD}	—

Table 1. Pin List by Bus (continued)

Signal	Signal Description	Package Pin Number	Pin Type	Power Supply	Note
MCK0	Clock	AD14	O	GV_{DD}	—
MCK1	Clock	AE13	O	GV_{DD}	—
MCK2	Clock	AG13	O	GV_{DD}	—
MCK3	Clock	AG14	O	GV_{DD}	—
$\overline{\text{MCK0}}$	Clock Complements	AE14	O	GV_{DD}	—
$\overline{\text{MCK1}}$	Clock Complements	AD13	O	GV_{DD}	—
$\overline{\text{MCK2}}$	Clock Complements	AH13	O	GV_{DD}	—
$\overline{\text{MCK3}}$	Clock Complements	AH14	O	GV_{DD}	—
MODT0	On Die Termination	AC19	O	GV_{DD}	—
MODT1	On Die Termination	AD22	O	GV_{DD}	—
MODT2	On Die Termination	AG18	O	GV_{DD}	—
MODT3	On Die Termination	AH21	O	GV_{DD}	—
MDIC0	Driver Impedance Calibration	AG12	I/O	GV_{DD}	16
MDIC1	Driver Impedance Calibration	AE12	I/O	GV_{DD}	16
Local Bus Controller Interface					
LAD00	Muxed Data/Address	J6	I/O	BV_{DD}	3
LAD01	Muxed Data/Address	J4	I/O	BV_{DD}	3
LAD02	Muxed Data/Address	K2	I/O	BV_{DD}	3
LAD03	Muxed Data/Address	K4	I/O	BV_{DD}	3
LAD04	Muxed Data/Address	L1	I/O	BV_{DD}	3
LAD05	Muxed Data/Address	J5	I/O	BV_{DD}	3
LAD06	Muxed Data/Address	N5	I/O	BV_{DD}	3
LAD07	Muxed Data/Address	N2	I/O	BV_{DD}	3
LAD08	Muxed Data/Address	N3	I/O	BV_{DD}	3
LAD09	Muxed Data/Address	N1	I/O	BV_{DD}	3
LAD10	Muxed Data/Address	P4	I/O	BV_{DD}	3
LAD11	Muxed Data/Address	R7	I/O	BV_{DD}	3
LAD12	Muxed Data/Address	T4	I/O	BV_{DD}	3
LAD13	Muxed Data/Address	U2	I/O	BV_{DD}	3
LAD14	Muxed Data/Address	T6	I/O	BV_{DD}	3
LAD15	Muxed Data/Address	T7	I/O	BV_{DD}	3
LA16	Address	K6	I/O	BV_{DD}	31
LA17	Address	K3	I/O	BV_{DD}	31
LA18	Address	P6	I/O	BV_{DD}	31

Table 1. Pin List by Bus (continued)

Signal	Signal Description	Package Pin Number	Pin Type	Power Supply	Note
SD_RX04	Receive Data (positive)	A2	I	XV_{DD}	—
SD_RX03	Receive Data (positive)	E1	I	XV_{DD}	—
SD_RX02	Receive Data (positive)	G1	I	XV_{DD}	—
$\overline{\text{SD\_RX13}}$	Receive Data (negative)	A21	I	XV_{DD}	—
$\overline{\text{SD\_RX12}}$	Receive Data (negative)	A19	I	XV_{DD}	—
$\overline{\text{SD\_RX11}}$	Receive Data (negative)	A15	I	XV_{DD}	—
$\overline{\text{SD\_RX10}}$	Receive Data (negative)	B13	I	XV_{DD}	—
$\overline{\text{SD\_RX07}}$	Receive Data (negative)	A11	I	XV_{DD}	—
$\overline{\text{SD\_RX06}}$	Receive Data (negative)	A9	I	XV_{DD}	—
$\overline{\text{SD\_RX05}}$	Receive Data (negative)	A7	I	XV_{DD}	—
$\overline{\text{SD\_RX04}}$	Receive Data (negative)	A3	I	XV_{DD}	—
$\overline{\text{SD\_RX03}}$	Receive Data (negative)	E2	I	XV_{DD}	—
$\overline{\text{SD\_RX02}}$	Receive Data (negative)	G2	I	XV_{DD}	—
SD_REF_CLK1	SerDes Bank 1 PLL Reference Clock	D3	I	XV_{DD}	—
$\overline{\text{SD\_REF\_CLK1}}$	SerDes Bank 1 PLL Reference Clock Complement	D4	I	XV_{DD}	—
SD_REF_CLK2	SerDes Bank 2 PLL Reference Clock	E17	I	XV_{DD}	—
$\overline{\text{SD\_REF\_CLK2}}$	SerDes Bank 2 PLL Reference Clock Complement	F17	I	XV_{DD}	—
General-Purpose Input/Output					
GPIO00/$\overline{\text{SPI\_CS0}}$/SDHC_DATA4	General Purpose Input/Output	H26	I/O	CV_{DD}	—
GPIO01/$\overline{\text{SPI\_CS1}}$/SDHC_DATA5	General Purpose Input/Output	H23	I/O	CV_{DD}	—
GPIO02/$\overline{\text{SPI\_CS2}}$/SDHC_DATA6	General Purpose Input/Output	H27	I/O	CV_{DD}	—
GPIO03$\overline{\text{SPI_CS3}}$/SDHC_DATA7	General Purpose Input/Output	H24	I/O	CV_{DD}	—
GPIO08/UART1_SOUT	General Purpose Input/Output	R23	I/O	OV_{DD}	—
GPIO09/UART2_SOUT	General Purpose Input/Output	P26	I/O	OV_{DD}	—
GPIO10/UART1_SIN	General Purpose Input/Output	R26	I/O	OV_{DD}	—
GPIO11/UART2_SIN	General Purpose Input/Output	P27	I/O	OV_{DD}	—
GPIO12/$\overline{\text{UART1\_RTS}}$/UART3_SOUT	General Purpose Input/Output	P24	I/O	OV_{DD}	—
GPIO13/$\overline{\text{UART2\_RTS}}$/UART4_SOUT	General Purpose Input/Output	P25	I/O	OV_{DD}	—
GPIO14/$\overline{\text{UART1\_CTS}}$/UART3_SIN	General Purpose Input/Output	R25	I/O	OV_{DD}	—
GPIO15/$\overline{\text{UART2\_CTS}}$/UART4_SIN	General Purpose Input/Output	P23	I/O	OV_{DD}	—
GPIO16/IIC3_SCL/M1DVAL/LB_DVAL/ $\overline{\text{DMA1\_DACK0}}$/$\overline{\text{SDHC\_CD}}$	General Purpose Input/Output	AB23	I/O	OV_{DD}	—

Table 1. Pin List by Bus (continued)

Signal	Signal Description	Package Pin Number	Pin Type	Power Supply	Note
GND166	Ground	B25	—	—	—
GND165	Ground	C23	—	—	—
GND164	Ground	D23	—	—	—
GND163	Ground	D27	—	—	—
GND162	Ground	E24	—	—	—
GND161	Ground	F22	—	—	—
GND160	Ground	F27	—	—	—
GND159	Ground	G10	—	—	—
GND158	Ground	G12	—	—	—
GND157	Ground	G14	—	—	—
GND156	Ground	G16	—	—	—
GND155	Ground	G18	—	—	—
GND154	Ground	G21	—	—	—
GND153	Ground	G22	—	—	—
GND152	Ground	H3	—	—	—
GND151	Ground	H4	—	—	—
GND150	Ground	H10	—	—	—
GND149	Ground	H12	—	—	—
GND148	Ground	H14	—	—	—
GND147	Ground	H16	—	—	—
GND146	Ground	H18	—	—	—
GND145	Ground	H21	—	—	—
GND144	Ground	H25	—	—	—
GND143	Ground	J2	—	—	—
GND142	Ground	J8	—	—	—
GND141	Ground	J10	—	—	—
GND140	Ground	J12	—	—	—
GND139	Ground	J14	—	—	—
GND138	Ground	J16	—	—	—
GND137	Ground	J18	—	—	—
GND136	Ground	J21	—	—	—
GND135	Ground	K5	—	—	—
GND134	Ground	K8	—	—	—
GND133	Ground	K10	—	—	—

Table 1. Pin List by Bus (continued)

Signal	Signal Description	Package Pin Number	Pin Type	Power Supply	Note
GND030	Ground	AB10	—	—	—
GND029	Ground	AB11	—	—	—
GND028	Ground	AB12	—	—	—
GND027	Ground	AB15	—	—	—
GND026	Ground	AB22	—	—	—
GND025	Ground	AC5	—	—	—
GND024	Ground	AC17	—	—	—
GND023	Ground	AC20	—	—	—
GND022	Ground	AC26	—	—	—
GND021	Ground	AD12	—	—	—
GND020	Ground	AD15	—	—	—
GND019	Ground	AE2	—	—	—
GND018	Ground	AE5	—	—	—
GND017	Ground	AE8	—	—	—
GND016	Ground	AE11	—	—	—
GND015	Ground	AE15	—	—	—
GND014	Ground	AE18	—	—	—
GND013	Ground	AE21	—	—	—
GND012	Ground	AE24	—	—	—
GND011	Ground	AE27	—	—	—
GND010	Ground	AF13	—	—	—
GND009	Ground	AF14	—	—	—
GND008	Ground	AG4	—	—	—
GND007	Ground	AG7	—	—	—
GND006	Ground	AG10	—	—	—
GND005	Ground	AG19	—	—	—
GND004	Ground	AG22	—	—	—
GND003	Ground	AG25	—	—	—
GND002	Ground	AH12	—	—	—
GND001	Ground	AH15	—	—	—
XGND12	SerDes Transceiver GND	C5	—	—	—
XGND11	SerDes Transceiver GND	C7	—	—	—
XGND10	SerDes Transceiver GND	C11	—	—	—
XGND09	SerDes Transceiver GND	C15	—	—	—

Table 1. Pin List by Bus (continued)

Signal	Signal Description	Package Pin Number	Pin Type	Power Supply	Note
USB1_AGND01	USB1 PHY Transceiver GND	M28	—	—	—
USB2_AGND06	USB2 PHY Transceiver GND	J22	—	—	—
USB2_AGND05	USB2 PHY Transceiver GND	J24	—	—	—
USB2_AGND04	USB2 PHY Transceiver GND	J26	—	—	—
USB2_AGND03	USB2 PHY Transceiver GND	K25	—	—	—
USB2_AGND02	USB2 PHY Transceiver GND	L25	—	—	—
USB2_AGND01	USB2 PHY Transceiver GND	M26	—	—	—
OVDD06	General I/O Supply	N20	—	OV_{DD}	—
OVDD05	General I/O Supply	P20	—	OV_{DD}	—
OVDD04	General I/O Supply	R20	—	OV_{DD}	—
OVDD03	General I/O Supply	T20	—	OV_{DD}	—
OVDD02	General I/O Supply	T26	—	OV_{DD}	—
OVDD01	General I/O Supply	W26	—	OV_{DD}	—
CVDD2	eSPI and eSDHC Supply	K20	—	CV_{DD}	—
CVDD1	eSPI and eSDHC Supply	M20	—	CV_{DD}	—
GVDD17	DDR Supply	AA8	—	GV_{DD}	—
GVDD16	DDR Supply	AA9	—	GV_{DD}	—
GVDD15	DDR Supply	AA10	—	GV_{DD}	—
GVDD14	DDR Supply	AA11	—	GV_{DD}	—
GVDD13	DDR Supply	AA12	—	GV_{DD}	—
GVDD12	DDR Supply	AA13	—	GV_{DD}	—
GVDD11	DDR Supply	AA14	—	GV_{DD}	—
GVDD10	DDR Supply	AA15	—	GV_{DD}	—
GVDD09	DDR Supply	AB13	—	GV_{DD}	—
GVDD08	DDR Supply	AB14	—	GV_{DD}	—
GVDD07	DDR Supply	AC13	—	GV_{DD}	—
GVDD06	DDR Supply	AC14	—	GV_{DD}	—
GVDD05	DDR Supply	AF6	—	GV_{DD}	—
GVDD04	DDR Supply	AF9	—	GV_{DD}	—
GVDD03	DDR Supply	AF17	—	GV_{DD}	—
GVDD02	DDR Supply	AF20	—	GV_{DD}	—
GVDD01	DDR Supply	AF23	—	GV_{DD}	—
BVDD07	Local Bus Supply	J7	—	BV_{DD}	—
BVDD06	Local Bus Supply	K7	—	BV_{DD}	—

Table 1. Pin List by Bus (continued)

Signal	Signal Description	Package Pin Number	Pin Type	Power Supply	Note
SENSEVDD_CA_PL	Core Group A and Platform Vdd Sense	H8	—	—	8
SENSEVDD_CB	Core Group B Vdd Sense	AB16	—	—	8
USB1_VDD_3P3	USB1 PHY Transceiver 3.3 V Supply	M23	—	—	—
USB2_VDD_3P3	USB2 PHY Transceiver 3.3 V Supply	J23	—	—	—
USB1_VDD_1P0	USB1 PHY PLL 1.0 V Supply	L22	—	—	—
USB2_VDD_1P0	USB2 PHY PLL 1.0 V Supply	K22	—	—	—
Analog Signals					
MVREF	SSTL_1.5/1.35 Reference Voltage	W7	I	$GV_{DD}/2$	—
SD_IMP_CAL_TX	SerDes Tx Impedance Calibration	E21	I	200Ω (±1%) to XV_{DD}	21
SD_IMP_CAL_RX	SerDes Rx Impedance Calibration	F7	I	200Ω (±1%) to SV_{DD}	22
TEMP_ANODE	Temperature Diode Anode	V5	—	internal diode	9
TEMP_CATHODE	Temperature Diode Cathode	U6	—	internal diode	9
USB2_IBIAS_REXT	USB PHY2 Reference Bias Current Generation	K23	—	GND	32
USB1_IBIAS_REXT	USB PHY1 Reference Bias Current Generation	L23	—	GND	32
USB2_VDD_1P8_DECAP	USB2 PHY 1.8 V Output to External Decap	K24	—	GND	33
USB1_VDD_1P8_DECAP	USB1 PHY 1.8 V Output to External Decap	L24	—	GND	33
No Connection Pins					
NC03	No Connection	W4	—	—	11
NC04	No Connection	W3	—	—	11
NC05	No Connection	W1	—	—	11
NC06	No Connection	H7	—	—	11
NC07	No Connection	G7	—	—	11
NC08	No Connection	F20	—	—	11
NC09	No Connection	F19	—	—	11
NC10	No Connection	F18	—	—	11
NC11	No Connection	F16	—	—	11
NC12	No Connection	F13	—	—	11

While VDD is ramping, current may be supplied from VDD through the chip to GVDD. Nevertheless, GVDD from an external supply should follow the sequencing described above.

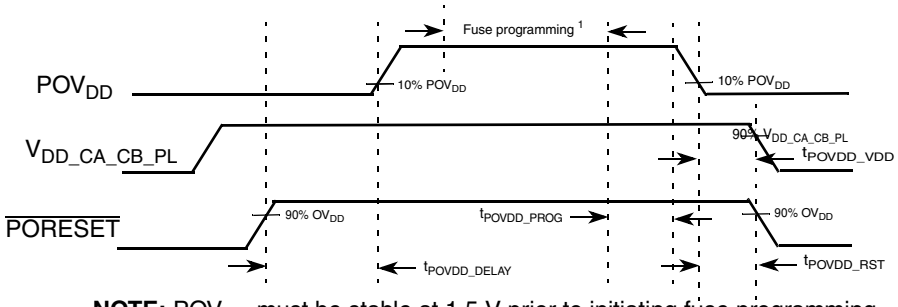
WARNING

Only 100,000 POR cycles are permitted per lifetime of a device.

All supplies must be at their stable values within 75 ms.

Items on the same line have no ordering requirement with respect to one another. Items on separate lines must be ordered sequentially such that voltage rails on a previous step must reach 90% of their value before the voltage rails on the current step reach 10% of theirs.

This figure provides the POV_{DD} timing diagram.



NOTE: POV_{DD} must be stable at 1.5 V prior to initiating fuse programming.

Figure 8. POV_{DD} Timing Diagram

This table provides information on the power-down and power-up sequence parameters for POV_{DD}.

Table 5. POV_{DD} Timing [5]

Driver Type	Min	Max	Unit	Note
t_{POVDD_DELAY}	100	—	SYSCLKs	1
t_{POVDD_PROG}	0	—	µs	2
t_{POVDD_VDD}	0	—	µs	3
t_{POVDD_RST}	0	—	µs	4

Note:

1. Delay required from the negation of $\overline{\text{PORESET}}$ to driving POV_{DD} ramp up. Delay measured from $\overline{\text{PORESET}}$ negation at 90% OV_{DD} to 10% POV_{DD} ramp up.
2. Delay required from fuse programming finished to POV_{DD} ramp down start. Fuse programming must complete while POV_{DD} is stable at 1.5 V. No activity other than that required for secure boot fuse programming is permitted while POV_{DD} driven to any voltage above GND, including the reading of the fuse block. The reading of the fuse block may only occur while POV_{DD} = GND. After fuse programming is completed, it is required to return POV_{DD} = GND.
3. Delay required from POV_{DD} ramp down complete to $V_{DD\_CA\_CB\_PL}$ ramp down start. POV_{DD} must be grounded to minimum 10% POV_{DD} before $V_{DD\_CA\_CB\_PL}$ is at 90% V_{DD}.
4. Delay required from POV_{DD} ramp down complete to $\overline{\text{PORESET}}$ assertion. POV_{DD} must be grounded to minimum 10% POV_{DD} before $\overline{\text{PORESET}}$ assertion reaches 90% OV_{DD}.
5. Only two secure boot fuse programming events are permitted per lifetime of a device.

To guarantee MCKE low during power up, the above sequencing for GV_{DD} is required. If there is no concern about any of the DDR signals being in an indeterminate state during power up, the sequencing for GV_{DD} is not required.

This table shows the estimated power dissipation on the AV_{DD} and AV_{DD_SRDS} supplies for the device PLLs, at allowable voltage levels.

Table 8. Device AV_{DD} Power Dissipation

AV_{DD}s	Typical	Maximum	Unit	Note
AV_{DD_DDR}	5	15	mW	1
AV_{DD_CC1}				
AV_{DD_CC2}				
AV_{DD_PLAT}				
AV_{DD_SRDS1}	—	36	mW	2
AV_{DD_SRDS2}				
USB_V_{DD_1P0}	—	10	mW	3

Note:

1. $V_{DD\_CA\_CB\_PL}$, T_A = 80°C, T_J = 105°C
2. SV_{DD} = 1.0 V, T_A = 80°C, T_J = 105°C
3. USB_V_{DD_1P0} = 1.0V, T_A = 80°C, T_J = 105°C

This table shows the estimated power dissipation on the POV_{DD} supply for the chip at allowable voltage levels.

Table 9. POV_{DD} Power Dissipation

Supply	Maximum	Unit	Notes
POV_{DD}	450	mW	1

Note:

1. To ensure device reliability, fuse programming must be performed within the recommended fuse programming temperature range per Table 3.

This table shows the estimated power dissipation on the V_{DD_LP} supply for the device, at allowable voltage levels.

Table 10. V_{DD_LP} Power Dissipation

Supply	Maximum	Unit	Notes
V_{DD_LP} (Device on, 105C)	1.5	mW	1
V_{DD_LP} (Device off, 70C)	195	uW	2
V_{DD_LP} (Device off, 40C)	132	uW	2

Note:

1. V_{DD_LP} = 1.0 V, T_J = 105°C.
2. When the device is off, V_{DD_LP} may be supplied by battery power to retain the Zeroizable Master Key and other Trust Architecture state. Board should implement a PMIC, which switches V_{DD_LP} to battery when the SoC is powered down. See the Trust Architecture chapter in the device reference manual for more information.

2.5 Thermal

Table 11. Package Thermal Characteristics [6]

Rating	Board	Symbol	Value	Unit	Note
Junction to ambient, natural convection	Single-layer board (1s)	$R_{\Theta JA}$	21	°C/W	1, 2
Junction to ambient, natural convection	Four-layer board (2s2p)	$R_{\Theta JA}$	15	°C/W	1, 3

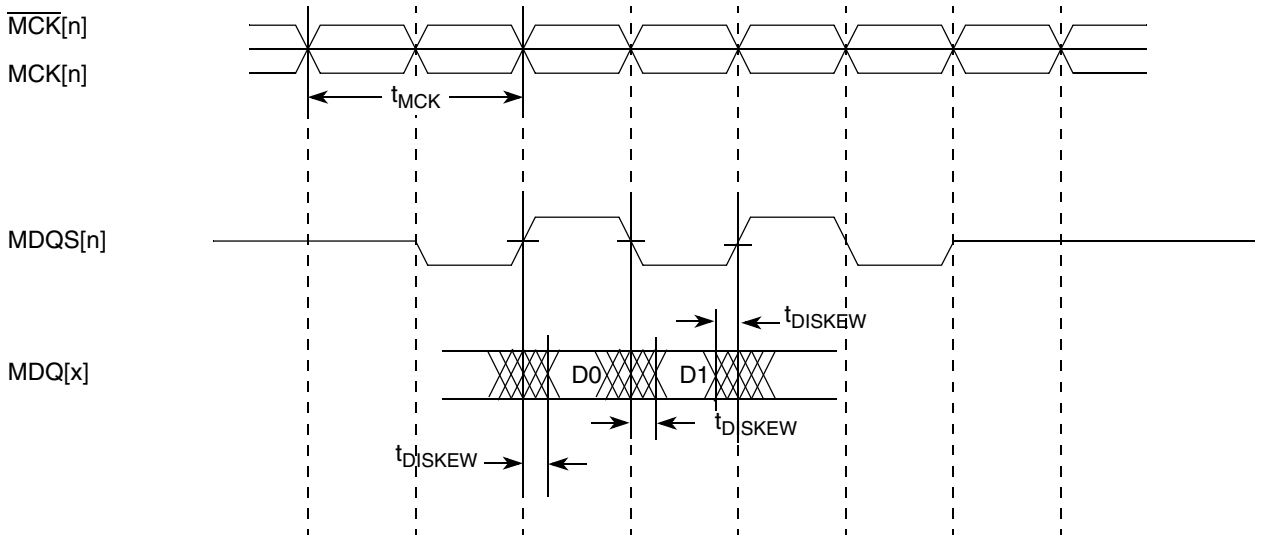


Figure 9. DDR3 and DDR3L SDRAM Interface Input Timing Diagram

2.9.2.2 DDR3 and DDDR3L SDRAM Interface Output AC Timing Specifications

This table provides the DDR3/DDR3L SDRAM output AC timing specifications.

Table 27. DDR3 and DDR3L SDRAM Interface Output AC Timing Specifications

For recommended operating conditions, see Table 3.

Parameter	Symbol[1]	Min	Max	Unit	Note
MCK[n] cycle time	t_{MCK}	1.67	2.5	ns	2
ADDR/CMD output setup with respect to MCK	t_{DDKHAS}			ns	3
1200 MT/s data rate		0.675	—		
1066 MT/s data rate		0.744	—		
800 MT/s data rate		0.917	—		
ADDR/CMD output hold with respect to MCK	t_{DDKHAX}			ns	3
1200 MT/s data rate		0.675	—		
1066 MT/s data rate		0.744	—		
800 MT/s data rate		0.917	—		
$\overline{\text{MCS}}$[n] output setup with respect to MCK	t_{DDKHCS}			ns	3
1200 MT/s data rate		0.675	—		
1066 MT/s data rate		0.744	—		
800 MT/s data rate		0.917	—		
$\overline{\text{MCS}}$[n] output hold with respect to MCK	t_{DDKHCX}			ns	3
1200 MT/s data rate		0.675	—		
1066 MT/s data rate		0.744	—		
800 MT/s data rate		0.917	—		

2.14 Enhanced Local Bus Interface

This section describes the DC and AC electrical specifications for the enhanced local bus interface.

2.14.1 Enhanced Local Bus DC Electrical Characteristics

This table provides the DC electrical characteristics for the enhanced local bus interface operating at BV_{DD} = 3.3 V.

Table 46. Enhanced Local Bus DC Electrical Characteristics (BV_{DD} = 3.3 V)

For recommended operating conditions, see Table 3.

Parameter	Symbol	Min	Max	Unit	Note
Input high voltage	V_{IH}	2	—	V	1
Input low voltage	V_{IL}	—	0.8	V	1
Input current (V_{IN} = 0 V or V_{IN} = BV_{DD})	I_{IN}	—	±40	μA	2
Output high voltage (BV_{DD} = min, I_{OH} = –2 mA)	V_{OH}	2.4	—	V	—
Output low voltage (BV_{DD} = min, I_{OL} = 2 mA)	V_{OL}	—	0.4	V	—

Note:
1. The min $V_{IL}$and max V_{IH} values are based on the respective min and max BV_{IN} values found in Table 3.
2. The symbol V_{IN}, in this case, represents the BV_{IN} symbol referenced in Section 2.1.2, “Recommended Operating Conditions.”

This table provides the DC electrical characteristics for the enhanced local bus interface operating at BV_{DD} = 2.5 V.

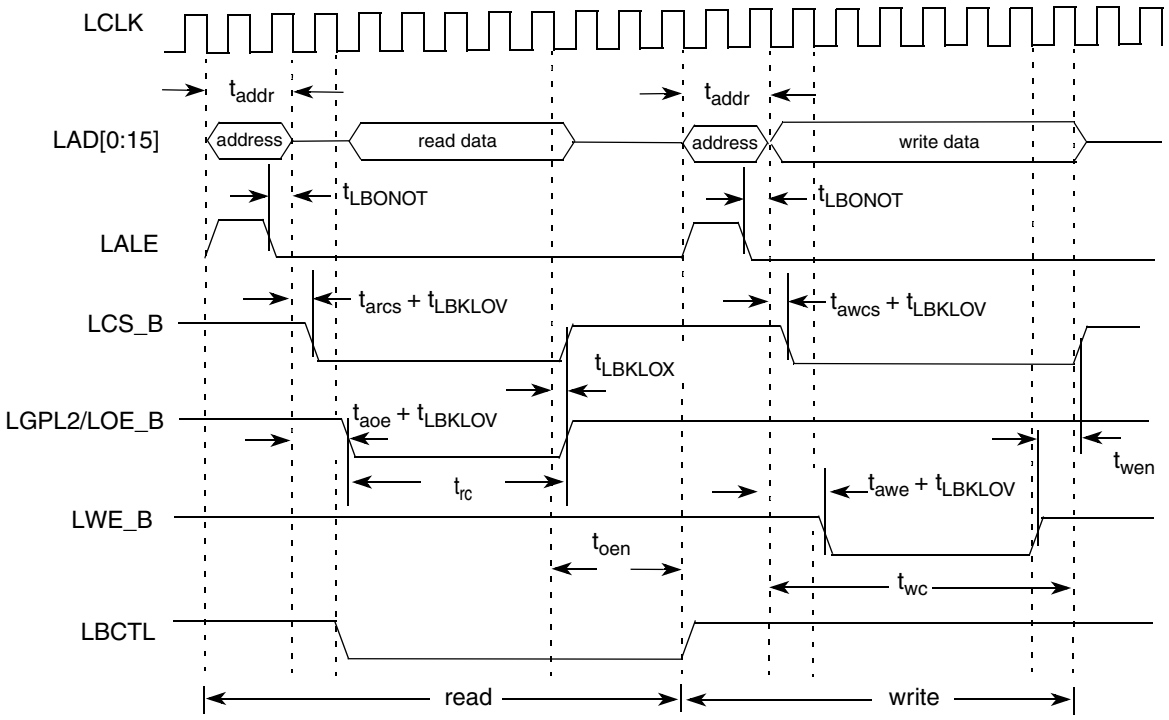
Table 47. Enhanced Local Bus DC Electrical Characteristics (BV_{DD} = 2.5 V)

For recommended operating conditions, see Table 3.

Parameter	Symbol	Min	Max	Unit	Note
Input high voltage	V_{IH}	1.7	—	V	1
Input low voltage	V_{IL}	—	0.7	V	1
Input current (V_{IN} = 0 V or V_{IN} = BV_{DD})	I_{IN}	—	±40	μA	2
Output high voltage (BV_{DD} = min, I_{OH} = –1 mA)	V_{OH}	2.0	—	V	—
Output low voltage (BV_{DD} = min, I_{OL} = 1 mA)	V_{OL}	—	0.4	V	—

Note:
1. The min $V_{IL}$and max V_{IH} values are based on the respective min and max BV_{IN} values found in Table 3
2. The symbol V_{IN}, in this case, represents the BV_{IN} symbol referenced in Section 2.1.2, “Recommended Operating Conditions.”

This figure shows how the AC timing diagram applies to GPCM. The same principle applies to UPM and FCM.



1 t_{addr} is programmable and determined by LCRR[EADC] and ORx[EAD].

2 t_{arcs}, t_{awcs}, t_{aoe}, t_{rc}, t_{oen}, t_{awe}, t_{wc}, t_{wen} are determined by ORx. See the chip reference manual.

Figure 22. GPCM Output Timing Diagram

2.15 Enhanced Secure Digital Host Controller (eSDHC)

This section describes the DC and AC electrical specifications for the eSDHC interface.

2.15.1 eSDHC DC Electrical Characteristics

This table provides the eSDHC electrical characteristics.

Table 50. eSDHC Interface DC Electrical Characteristics

For recommended operating conditions, see Table 3.

Characteristic	Symbol	Condition	Min	Max	Unit	Note
Input high voltage	V_{IH}	—	$0.625 \times CV_{DD}$	—	V	1
Input low voltage	V_{IL}	—	—	$0.25 \times CV_{DD}$	V	1
Input/output leakage current	I_{IN}/I_{OZ}	—	–50	50	μA	—
Output high voltage	V_{OH}	I_{OH} = –100 μA at CV_{DD} min	$0.75 \times CV_{DD}$	—	V	—

Table 52. MPIC DC Electrical Characteristics (OV_{DD} = 3.3 V) (continued)

For recommended operating conditions, see Table 3.

Parameter	Symbol	Min	Max	Unit	Note

Note:
1. The min $V_{IL}$and max V_{IH} values are based on the min and max OV_{IN} respective values found in Table 3.
2. The symbol OV_{IN}, in this case, represents the OV_{IN} symbol referenced in Table 3.

2.16.2 MPIC AC Timing Specifications

This table provides the MPIC input and output AC timing specifications.

Table 53. MPIC Input AC Timing Specifications

For recommended operating conditions, see Table 3.

Characteristic	Symbol	Min	Max	Unit	Note
MPIC inputs—minimum pulse width	t_{PIWID}	3	—	SYSCLKs	1
Trust inputs—minimum pulse width	t_{TIWID}	3	—	SYSCLKs	2

Note:
1. MPIC inputs and outputs are asynchronous to any visible clock. MPIC outputs must be synchronized before use by any external synchronous logic. MPIC inputs are required to be valid for at least t_{PIWID} ns to ensure proper operation when working in edge triggered mode.
2. Trust inputs are asynchronous to any visible clock. Trust inputs are required to be valid for at least t_{TIWID} ns to ensure proper operation when working in edge triggered mode. For low power trust input pin LP_TMP_DETECT, the voltage is V_{DD_LP} and see Table 3 for the voltage requirment.

2.17 JTAG Controller

This section describes the DC and AC electrical specifications for the IEEE 1149.1 (JTAG) interface.

2.17.1 JTAG DC Electrical Characteristics

This table provides the JTAG DC electrical characteristics.

Table 54. JTAG DC Electrical Characteristics (OV_{DD} = 3.3 V)

For recommended operating conditions, see Table 3.

Parameter	Symbol	Min	Max	Unit	Note
Input high voltage	V_{IH}	2	—	V	1
Input low voltage	V_{IL}	—	0.8	V	1
Input current (OV_{IN} = 0 V or OV_{IN} = OV_{DD})	I_{IN}	—	±40	μA	2
Output high voltage (OV_{DD} = min, I_{OH} = –2 mA)	V_{OH}	2.4	—	V	—
Output low voltage (OV_{DD} = min, I_{OL} = 2 mA)	V_{OL}	—	0.4	V	—

Note:
1. The min $V_{IL}$and max V_{IH} values are based on the respective min and max OV_{IN} values found in Table 3.
2. The symbol V_{IN}, in this case, represents the OV_{IN} symbol found in Table 3.

Table 65. PCI Express 2.0 (5 GT/s) Differential Receiver (Rx) Input DC Specifications (XV_{DD} = 1.5 V or 1.8 V) (continued)

Parameter	Symbol	Min	Typ	Max	Unit	Note
Electrical idle detect threshold	$V_{RX-IDLE-DET-DIFFp-p}$	65	—	175	mV	$V_{RX-IDLE-DET-DIFFp-p}$ = $2 \times \lvert V_{RX-D+} - V_{RX-D-} \rvert$ Measured at the package pins of the receiver

Note:

1. Measured at the package pins with a test load of 50 Ω to GND on each pin.
2. Impedance during all LTSSM states. When transitioning from a fundamental reset to detect (the initial state of the LTSSM) there is a 5 ms transition time before receiver termination values must be met on all unconfigured lanes of a port.
3. The Rx DC common mode impedance that exists when no power is present or fundamental reset is asserted. This helps ensure that the receiver detect circuit does not falsely assume a receiver is powered on when it is not. This term must be measured at 300 mV above the Rx ground.

2.20.4.5 PCI Express AC Physical Layer Specifications

This section contains the DC specifications for the physical layer of PCI Express on this device.

2.20.4.5.1 PCI Express AC Physical Layer Transmitter Specifications

This section discusses the PCI Express AC physical layer transmitter specifications 2.5 GT/s and 5 GT/s.

This table defines the PCI Express 2.0 (2.5 GT/s) AC specifications for the differential output at all transmitters. The parameters are specified at the component pins. The AC timing specifications do not include RefClk jitter.

Table 66. PCI Express 2.0 (2.5 GT/s) Differential Transmitter (Tx) Output AC Specifications

For recommended operating conditions, see Table 3.

Parameter	Symbol	Min	Typ	Max	Unit	Note
Unit interval	UI	399.88	400	400.12	ps	Each UI is 400 ps ± 300 ppm. UI does not account for spread spectrum clock dictated variations. See note 1.
Minimum Tx eye width	T_{TX-EYE}	0.75	—	—	UI	The maximum transmitter jitter can be derived as $T_{TX-MAX-JITTER} = 1 - T_{TX-EYE} = 0.25$ UI. Does not include spread spectrum or RefCLK jitter. Includes device random jitter at 10^{-12}. See notes 2 and 3.
Maximum time between the jitter median and maximum deviation from the median	$T_{TX-EYE-MEDIAN-to-MAX-JITTER}$	—	—	0.125	UI	Jitter is defined as the measurement variation of the crossing points ($V_{TX-DIFFp-p}$ = 0 V) in relation to a recovered Tx UI. A recovered Tx UI is calculated over 3500 consecutive unit intervals of sample data. Jitter is measured using all edges of the 250 consecutive UI in the center of the 3500 UI used for calculating the Tx UI. See notes 2 and 3.
AC coupling capacitor	C_{TX}	75	—	200	nF	All transmitters must be AC coupled. The AC coupling is required either within the media or within the transmitting component itself. See note 4.

- The use of active circuits in the receiver, often referred to as adaptive equalization.

2.20.5.3 Serial RapidIO Clocking Requirements for SD_REF_CLK*n* and SD_REF_CLK*n*

SerDes bank 1 (SD_REF_CLK1 and $\overline{\text{SD\_REF\_CLK1}}$) may be used for various SerDes Serial RapidIO configurations based on the RCW configuration field SRDS_PRTCL. Serial RapidIO is not supported on SerDes banks 2.

For more information on these specifications, see Section 2.20.2, "SerDes Reference Clocks."

2.20.5.4 DC Requirements for Serial RapidIO

This section explains the DC requirements for the Serial RapidIO interface.

2.20.5.4.1 DC Serial RapidIO Timing Transmitter Specifications

LP-Serial transmitter electrical and timing specifications are stated in the text and tables of this section.

The differential return loss, S11, of the transmitter in each case is better than the following:

- –10 dB for (Baud Frequency) ÷ 10 < Freq(f) < 625 MHz
- –10 dB + 10log(f ÷ 625 MHz) dB for 625 MHz ≤ Freq(f) ≤ Baud Frequency

The reference impedance for the differential return loss measurements is 100-Ω resistive. Differential return loss includes contributions from on-chip circuitry, chip packaging, and any off-chip components related to the driver. The output impedance requirement applies to all valid output levels.

It is recommended that the 20%–80% rise/fall time of the transmitter, as measured at the transmitter output, have a minimum value 60 ps in each case.

It is recommended that the timing skew at the output of an LP-Serial transmitter between the two signals that comprise a differential pair not exceed 20 ps at 2.50 GBaud and 15 ps at 3.125 GBaud and XX ps at 5 GBaud.

This table defines the transmitter DC specifications for Serial RapidIO operating at XV_{DD} = 1.5 V or 1.8 V.

Table 70. Serial RapidIO Transmitter DC Timing Specifications—2.5 GBaud, 3.125 GBaud, 5 GBaud

For recommended operating conditions, see Table 3.

Parameter	Symbol	Min	Typ	Max	Unit	Note
Output voltage	V_O	–0.40	—	2.30	V	1
Long-run differential output voltage	V_{DIFFPP}	800	—	1600	mV p-p	—
Short-run differential output voltage	V_{DIFFPP}	500	—	1000	mV p-p	—

Note:
1. Voltage relative to COMMON of either signal comprising a differential pair.

2.20.5.4.2 DC Serial RapidIO Receiver Specifications

LP-Serial receiver electrical and timing specifications are stated in the text and tables of this section.

Receiver input impedance results in a differential return loss better than 10 dB and a common mode return loss better than 6 dB from 100 MHz to (0.8) × (Baud Frequency). This includes contributions from on-chip circuitry, the chip package, and any off-chip components related to the receiver. AC coupling components are included in this requirement. The reference impedance for return loss measurements is 100-Ω resistive for differential return loss and 25-Ω resistive for common mode.

This table defines the receiver DC specifications for Serial RapidIO operating at XV_{DD} = 1.5 V or 1.8 V.

Table 71. Serial RapidIO Receiver DC Timing Specifications—2.5 GBaud, 3.125 GBaud, 5 GBaud

For recommended operating conditions, see Table 3.

Parameter	Symbol	Min	Typ	Max	Unit	Note
Differential input voltage	V_{IN}	200	—	1600	mV p-p	1

Note:
1. Measured at the receiver.

2.20.5.5 AC Requirements for Serial RapidIO

This section explains the AC requirements for the Serial RapidIO interface.

2.20.5.5.1 AC Requirements for Serial RapidIO Transmitter

This table defines the transmitter AC specifications for the Serial RapidIO interface. The AC timing specifications do not include RefClk jitter.

Table 72. Serial RapidIO Transmitter AC Timing Specifications

For recommended operating conditions, see Table 3.

Parameter	Symbol	Min	Typical	Max	Unit
Deterministic jitter	J_D	—	—	0.17	UI p-p
Total jitter	J_T	—	—	0.35	UI p-p
Unit interval: 2.5 GBaud	UI	400 – 100ppm	400	400 + 100ppm	ps
Unit interval: 3.125 GBaud	UI	320 – 100ppm	320	320 + 100ppm	ps

This table defines the receiver AC specifications for Serial RapidIO. The AC timing specifications do not include RefClk jitter.

Table 73. Serial RapidIO Receiver AC Timing Specifications

For recommended operating conditions, see Table 3.

Parameter	Symbol	Min	Typical	Max	Unit	Note
Deterministic jitter tolerance	J_D	0.37	—	—	UI p-p	1
Combined deterministic and random jitter tolerance	J_{DR}	0.55	—	—	UI p-p	1
Total jitter tolerance[2]	J_T	0.65	—	—	UI p-p	1
Bit error rate	BER	—	—	10^{-12}	—	—
Unit interval: 2.5 GBaud	UI	400 – 100ppm	400	400 + 100ppm	ps	—
Unit interval: 3.125 GBaud	UI	320 – 100ppm	320	320 + 100ppm	ps	—

Note:
1. Measured at receiver
2. Total jitter is composed of three components: deterministic jitter, random jitter, and single frequency sinusoidal jitter. The sinusoidal jitter may have any amplitude and frequency in the unshaded region of Figure 42. The sinusoidal jitter component is included to ensure margin for low-frequency jitter, wander, noise, crosstalk, and other variable system effects.

Table 82. SATA Reference Clock Input Requirements (continued)

For recommended operating conditions, see Table 3.

Parameter	Symbol	Min	Typ	Max	Unit	Note
SD_REF_CLK/$\overline{\text{SD\_REF\_CLK}}$ cycle-to-cycle clock jitter (period jitter)	t_{CLK_CJ}	—	—	100	ps	2
SD_REF_CLK/$\overline{\text{SD\_REF\_CLK}}$ total reference clock jitter, phase jitter (peak-peak)	t_{CLK_PJ}	–50	—	+50	ps	2, 3, 4

Note:
1. **Caution:** Only 100, 125 MHz have been tested. In-between values do not work correctly with the rest of the system.
2. At RefClk input
3. In a frequency band from 150 kHz to 15 MHz at BER of 10^{-12}
4. Total peak-to-peak deterministic jitter must be less than or equal to 50 ps.

This figure shows the reference clock timing waveform.

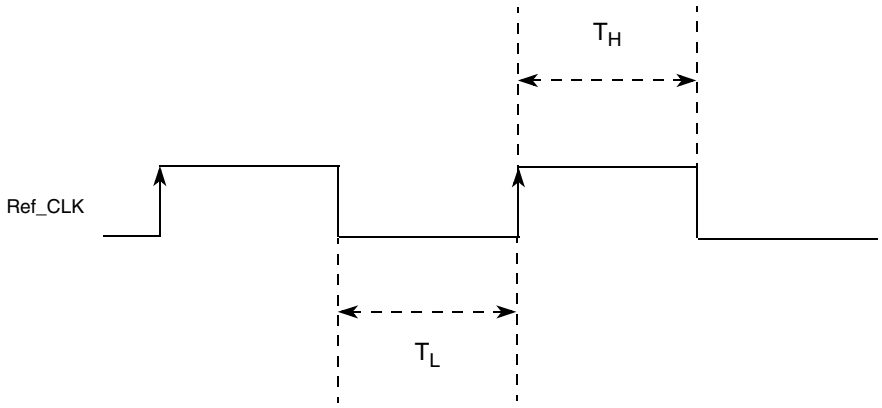


Figure 43. Reference Clock Timing Waveform

2.20.7.3 AC Transmitter Output Characteristics

This table provides the differential transmitter output AC characteristics for the SATA interface at Gen1i or 1.5 Gbits/s transmission. The AC timing specifications do not include RefClk jitter.

Table 83. Gen1i/1.5 G Transmitter (Tx) AC Specifications

For recommended operating conditions, see Table 3.

Parameter	Symbol	Min	Typ	Max	Unit	Note
Channel speed	t_{CH_SPEED}	—	1.5	—	Gbps	—
Unit Interval	T_{UI}	666.4333	666.6667	670.2333	ps	—
Total jitter data-data 5 UI	$U_{SATA\_TXTJ5UI}$	—	—	0.355	UI p-p	1
Total jitter, data-data 250 UI	$U_{SATA\_TXTJ250UI}$	—	—	0.47	UI p-p	1
Deterministic jitter, data-data 5 UI	$U_{SATA\_TXDJ5UI}$	—	—	0.175	UI p-p	1
Deterministic jitter, data-data 250 UI	$U_{SATA\_TXDJ250UI}$	—	—	0.22	UI p-p	1

This table provides the differential receiver input AC characteristics for the SATA interface at Gen2i or 3.0 Gbits/s transmission. The AC timing specifications do not include RefClk jitter.

Table 86. Gen 2i/3G Receiver (Rx) AC Specifications

For recommended operating conditions, see Table 3.

Parameter	Symbol	Min	Typical	Max	Unit	Note
Unit Interval	T_{UI}	333.2167	333.3333	335.1167	ps	—
Total jitter $f_{C3dB} = f_{BAUD} \div 10$	$U_{SATA\_TXTJfB/10}$	—	—	0.46	UI p-p	1
Total jitter $f_{C3dB} = f_{BAUD} \div 500$	$U_{SATA\_TXTJfB/500}$	—	—	0.60	UI p-p	1
Total jitter $f_{C3dB} = f_{BAUD} \div 1667$	$U_{SATA\_TXTJfB/1667}$	—	—	0.65	UI p-p	1
Deterministic jitter, $f_{C3dB} = f_{BAUD} \div 10$	$U_{SATA\_TXDJfB/10}$	—	—	0.35	UI p-p	1
Deterministic jitter, $f_{C3dB} = f_{BAUD} \div 500$	$U_{SATA\_TXDJfB/500}$	—	—	0.42	UI p-p	1
Deterministic jitter, $f_{C3dB} = f_{BAUD} \div 1667$	$U_{SATA\_TXDJfB/1667}$	—	—	0.35	UI p-p	1

Note:
1. Measured at receiver.

2.20.8 SGMII Interface

Each SGMII port features a 4-wire AC-coupled serial link from the SerDes interface of the device, as shown in Figure 44, where C_{TX} is the external (on board) AC-coupled capacitor. Each output pin of the SerDes transmitter differential pair features 50-Ω output impedance. Each input of the SerDes receiver differential pair features 50-Ω on-die termination to XGND. The reference circuit of the SerDes transmitter and receiver is shown in Figure 39.

2.20.8.0.1 SGMII Clocking Requirements for SD_REF_CLK*n* and $\overline{\text{SD\_REF\_CLK}n}$

When operating in SGMII mode, the EC_GTX_CLK125 clock is not required for this port. Instead, a SerDes reference clock is required on SD_REF_CLK[1:2] and $\overline{\text{SD\_REF\_CLK}[1:2]}$ pins. SerDes banks 1–2 may be used for SerDes SGMII configurations based on the RCW Configuration field SRDS_PRTCL.

For more information on these specifications, see Section 2.20.2, “SerDes Reference Clocks.”

2.20.8.1 SGMII DC Electrical Characteristics

This section discusses the electrical characteristics for the SGMII interface.

2.20.8.1.1 SGMII Transmit DC Timing Specifications

This table describe the SGMII SerDes transmitter and receiver AC-coupled DC electrical characteristics for 1.25 GBaud. Transmitter DC characteristics are measured at the transmitter outputs (SD_TX*n* and $\overline{\text{SD\_TX}n}$) as shown in Figure 45.

Table 87. SGMII DC Transmitter Electrical Characteristics (XV_{DD} = 1.5 V or 1.8 V)

For recommended operating conditions, see Table 3.

Parameter	Symbol	Min	Typ	Max	Unit	Note
Output high voltage	V_{OH}	—	—	1.5 x $\lvert V_{OD}\rvert_{-max}$	mV	1
Output low voltage	V_{OL}	$\lvert V_{OD}\rvert_{-min}/2$	—	—	mV	1

3.3 Power Supply Design

This section discusses the power supply design.

3.3.1 PLL Power Supply Filtering

Each of the PLLs described in Section 3.1, "System Clocking," is provided with power through independent power supply pins (AV_{DD_PLAT}, AV_{DD_CCn}, AV_{DD_DDR}, and AV_{DD_SRDSn}). AV_{DD_PLAT}, AV_{DD_CCn} and AV_{DD_DDR} voltages must be derived directly from the $V_{DD\_CA\_CB\_PL}$ source through a low frequency filter scheme. AV_{DD_SRDSn} voltages must be derived directly from the SV_{DD} source through a low frequency filter scheme.

The recommended solution for PLL filtering is to provide independent filter circuits per PLL power supply, as illustrated in Figure 50, one for each of the AV_{DD} pins. By providing independent filters to each PLL the opportunity to cause noise injection from one PLL to the other is reduced.

This circuit is intended to filter noise in the PLL's resonant frequency range from a 500-kHz to 10-MHz range.

Each circuit must be placed as close as possible to the specific AV_{DD} pin being supplied to minimize noise coupled from nearby circuits. It must be possible to route directly from the capacitors to the AV_{DD} pin, which is on the periphery of the footprint, without the inductance of vias.

Figure 50 shows the PLL power supply filter circuit.

Where:

R = 5 Ω ± 5%

C1 = 10µF ± 10%, 0603, X5R, with ESL ≤ 0.5 nH

C2 = 1.0 µF ± 10%, 0402, X5R, with ESL ≤ 0.5 nH

NOTE

A higher capacitance value for C2 may be used to improve the filter as long as the other C2 parameters do not change (0402 body, X5R, ESL ≤ 0.5 nH).

Voltage for AV_{DD} is defined at the PLL supply filter and not the pin of AV_{DD}.

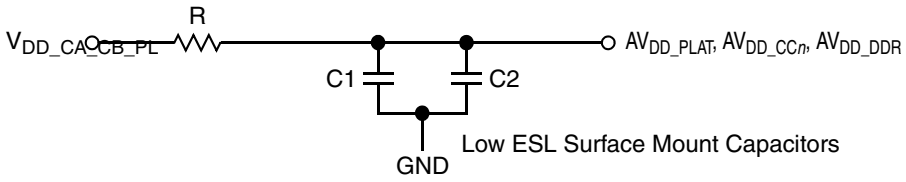
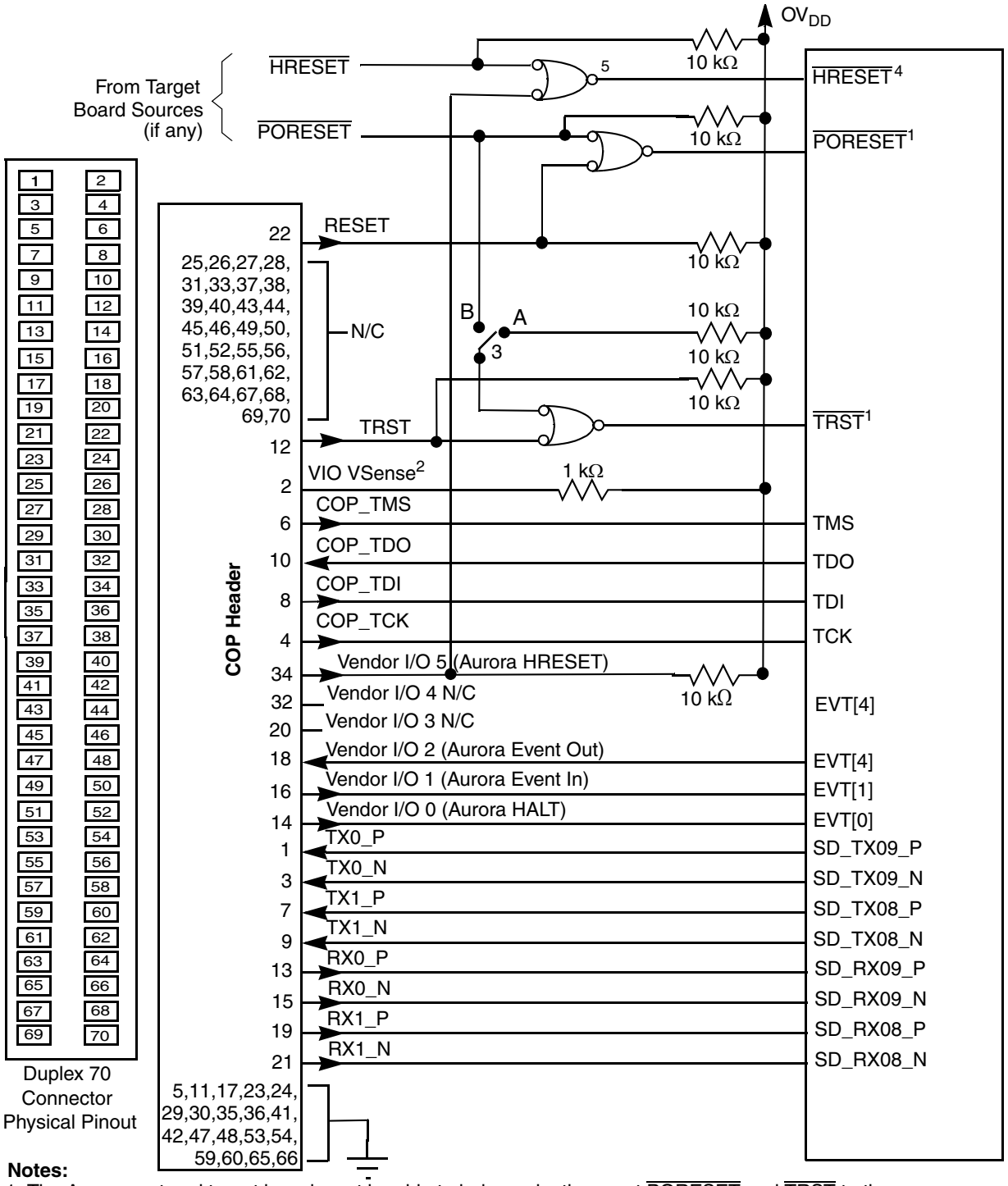


Figure 50. PLL Power Supply Filter Circuit

The AV_{DD_SRDSn} signals provides power for the analog portions of the SerDes PLL. To ensure stability of the internal clock, the power supplied to the PLL is filtered using a circuit similar to the one shown in following Figure 51. For maximum effectiveness, the filter circuit is placed as closely as possible to the AV_{DD_SRDSn} balls to ensure it filters out as much noise as possible. The ground connection must be near the AV_{DD_SRDSn} balls. The 0.003-µF capacitor is closest to the balls, followed by two 2.2-µF capacitors, and finally the 1-Ω resistor to the board supply plane. The capacitors are connected from AV_{DD_SRDSn}



Notes:

1. The Aurora port and target board must be able to independently assert $\overline{\text{PORESET}}$ and $\overline{\text{TRST}}$ to the processor in order to fully control the processor as shown here.
2. Populate this with a 1 kΩ resistor for short-circuit/current-limiting protection.
3. This switch is included as a precaution for BSDL testing. The switch must be closed to position A during BSDL testing to avoid accidentally asserting the $\overline{\text{TRST}}$ line. If BSDL testing is not being performed, this switch must be closed to position B.
4. Asserting $\overline{\text{HRESET}}$ causes a hard reset on the device.
5. This is an open-drain gate.

Figure 59. Aurora 70 Pin Connector Duplex Interface Connection