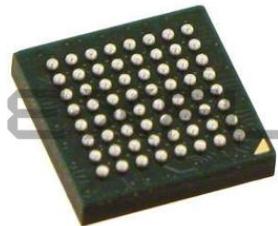


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"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details

Product Status	Active
Core Processor	ARM® Cortex®-M0+
Core Size	32-Bit Single-Core
Speed	48MHz
Connectivity	I²C, SPI, UART/USART
Peripherals	DMA, I²S, LCD, LVD, POR, PWM, WDT
Number of I/O	54
Program Memory Size	256KB (256K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	32K x 8
Voltage - Supply (Vcc/Vdd)	1.71V ~ 3.6V
Data Converters	A/D 20x16b; D/A 1x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	64-LFBGA
Supplier Device Package	64-MAPBGA (5x5)
Purchase URL	https://www.e-xfl.com/product-detail/nxp-semiconductors/mkl33z256vmp4

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Table 7. Voltage and current operating behaviors (continued)

Symbol	Description	Min.	Max.	Unit	Notes
	<ul style="list-style-type: none"> $2.7 \text{ V} \leq V_{DD} \leq 3.6 \text{ V}$, $I_{OL} = 18 \text{ mA}$ $1.71 \text{ V} \leq V_{DD} \leq 2.7 \text{ V}$, $I_{OL} = 6 \text{ mA}$ 	—	0.5	V	
I_{OLT}	Output low current total for all ports	—	100	mA	
I_{IN}	Input leakage current (per pin) for full temperature range	—	1	μA	2
I_{IN}	Input leakage current (per pin) at 25 °C	—	0.025	μA	2
I_{IN}	Input leakage current (total all pins) for full temperature range	—	64	μA	2
I_{OZ}	Hi-Z (off-state) leakage current (per pin)	—	1	μA	
R_{PU}	Internal pullup resistors	20	50	kΩ	3

1. PTB0, PTB1, PTC3, PTC4, PTD6, and PTD7 I/O have both high drive and normal drive capability selected by the associated PTx_PCRn[DSE] control bit. All other GPIOs are normal drive only.

2. Measured at $V_{DD} = 3.6 \text{ V}$

3. Measured at V_{DD} supply voltage = V_{DD} min and $V_{IN} = V_{SS}$

2.2.4 Power mode transition operating behaviors

All specifications except t_{POR} and $VLLSx \rightarrow RUN$ recovery times in the following table assume this clock configuration:

- CPU and system clocks = 48 MHz
- Bus and flash clock = 24 MHz
- HIRC clock mode

Table 8. Power mode transition operating behaviors

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
t_{POR}	After a POR event, amount of time from the point V_{DD} reaches 1.8 V to execution of the first instruction across the operating temperature range of the chip.	—	—	300	μs	1
	<ul style="list-style-type: none"> $VLLS0 \rightarrow RUN$ 	—	152	166	μs	
	<ul style="list-style-type: none"> $VLLS1 \rightarrow RUN$ 	—	152	166	μs	
	<ul style="list-style-type: none"> $VLLS3 \rightarrow RUN$ 	—	93	104	μs	
	<ul style="list-style-type: none"> $LLS \rightarrow RUN$ 	—	7.5	8	μs	

Table continues on the next page...

Table 9. Power consumption operating behaviors (continued)

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
I _{DD_RUN}	Run mode current—48M HIRC mode, running CoreMark in Flash all peripheral clock disable 12 MHz core/6 MHz flash, V _{DD} = 3.0 V <ul style="list-style-type: none"> • at 25 °C • at 105 °C 	—	2.68	3.32	mA	2
I _{DD_RUN}	Run mode current—48M HIRC mode, running CoreMark in Flash all peripheral clock enable 48 MHz core/24 MHz flash, V _{DD} = 3.0 V <ul style="list-style-type: none"> • at 25 °C • at 105 °C 	—	8.08	8.72	mA	2
I _{DD_RUN}	Run mode current—48M HIRC mode, running While(1) loop in flash all peripheral clock disable, 48 MHz core/24 MHz flash, V _{DD} = 3.0 V <ul style="list-style-type: none"> • at 25 °C • at 105 °C 	—	3.90	4.54	mA	
I _{DD_RUN}	Run mode current—48M HIRC mode, running While(1) loop in Flash all peripheral clock disable, 24 MHz core/12 MHz flash, V _{DD} = 3.0 V <ul style="list-style-type: none"> • at 25 °C • at 105 °C 	—	2.66	3.30	mA	
I _{DD_RUN}	Run mode current—48M HIRC mode, Running While(1) loop in Flash all peripheral clock disable, 12 MHz core/6 MHz flash, V _{DD} = 3.0 V <ul style="list-style-type: none"> • at 25 °C • at 105 °C 	—	2.03	2.67	mA	
I _{DD_RUN}	Run mode current—48M HIRC mode, Running While(1) loop in Flash all peripheral clock enable, 48 MHz core/24 MHz flash, V _{DD} = 3.0 V <ul style="list-style-type: none"> • at 25 °C • at 105 °C 	—	5.52	6.16	mA	
I _{DD_RUN}	Run mode current—48M HIRC mode, running While(1) loop in SRAM all peripheral clock disable, 48 MHz core/24 MHz flash, V _{DD} = 3.0 V <ul style="list-style-type: none"> • at 25 °C • at 105 °C 	—	5.29	5.93	mA	
I _{DD_RUN}	Run mode current—48M HIRC mode, running While(1) loop in SRAM all peripheral clock enable, 48 MHz core/24 MHz flash, V _{DD} = 3.0 V <ul style="list-style-type: none"> • at 25 °C • at 105 °C 	—	6.91	7.55	mA	
		—	7.19	7.91		

Table continues on the next page...

Table 9. Power consumption operating behaviors (continued)

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
I _{DD_VLPRC_O}	Very Low Power Run Core Mark in Flash in Compute Operation mode: Core@4MHz, Flash @1MHz, V _{DD} = 3.0 V • at 25 °C	—	826	907	µA	
I _{DD_VLPRC_O}	Very-low-power-run While(1) loop in SRAM in compute operation mode— 8 MHz LIRC mode, 4 MHz core / 1 MHz flash, V _{DD} = 3.0 V • at 25 °C	—	405	486	µA	
I _{DD_VLPRC_O}	Very-low-power run While(1) loop in SRAM in compute operation mode:—2 MHz LIRC mode, 2 MHz core / 0.5 MHz flash, V _{DD} = 3.0 V • at 25 °C	—	154	235	µA	
I _{DD_VLPR}	Very-low-power run mode current— 2 MHz LIRC mode, While(1) loop in flash all peripheral clock disable, 2 MHz core / 0.5 MHz flash, V _{DD} = 3.0 V • at 25 °C	—	108	189	µA	
I _{DD_VLPR}	Very-low-power run mode current— 2 MHz LIRC mode, While(1) loop in flash all peripheral clock disable, 125 kHz core / 31.25 kHz flash, V _{DD} = 3.0 V • at 25 °C	—	39	120	µA	
I _{DD_VLPR}	Very-low-power run mode current— 8 MHz LIRC mode, While(1) loop in flash all peripheral clock disable, 4 MHz core / 1 MHz flash, V _{DD} = 3.0 V • at 25 °C	—	249	330	µA	
I _{DD_VLPR}	Very-low-power run mode current— 8 MHz LIRC mode, While(1) loop in flash all peripheral clock enable, 4 MHz core / 1 MHz flash, V _{DD} = 3.0 V • at 25 °C	—	337	418	µA	
I _{DD_VLPR}	Very-low-power run mode current— 8 MHz LIRC mode, While(1) loop in SRAM in all peripheral clock disable, 4 MHz core / 1 MHz flash, V _{DD} = 3.0 V • at 25 °C	—	416	497	µA	
I _{DD_VLPR}	Very-low-power run mode current— 8 MHz LIRC mode, While(1) loop in SRAM all peripheral clock enable, 4 MHz core / 1 MHz flash, V _{DD} = 3.0 V • at 25 °C	—	494	575	µA	
I _{DD_VLPR}	Very-low-power run mode current—2 MHz LIRC mode, While(1) loop in SRAM in all peripheral clock disable, 2 MHz core / 0.5 MHz flash, V _{DD} = 3.0 V • at 25 °C	—	166	247	µA	
I _{DD_VLPR}	Very-low-power run mode current—2 MHz LIRC mode, While(1) loop in SRAM all peripheral clock disable, 125 kHz core / 31.25 kHz flash, V _{DD} = 3.0 V • at 25 °C	—	50	131	µA	

Table continues on the next page...

Table 9. Power consumption operating behaviors (continued)

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
I _{DD_VLPR}	Very-low-power run mode current—2 MHz LIRC mode, While(1) loop in SRAM all peripheral clock enable, 2 MHz core / 0.5 MHz flash, V _{DD} = 3.0 V • at 25 °C	—	208	289	µA	
I _{DD_WAIT}	Wait mode current—core disabled, 48 MHz system/24 MHz bus, flash disabled (flash doze enabled), all peripheral clocks disabled, MCG_Lite under HIRC mode, V _{DD} = 3.0 V	—	1.81	1.89	mA	
I _{DD_WAIT}	Wait mode current—core disabled, 24 MHz system/12 MHz bus, flash disabled (flash doze enabled), all peripheral clocks disabled, MCG_Lite under HIRC mode, V _{DD} = 3.0 V	—	1.22	1.39	mA	
I _{DD_VLPW}	Very-low-power wait mode current, core disabled, 4 MHz system/ 1 MHz bus and flash, all peripheral clocks disabled, V _{DD} = 3.0 V	—	172	182	µA	
I _{DD_VLPW}	Very-low-power wait mode current, core disabled, 2 MHz system/ 0.5 MHz bus and flash, all peripheral clocks disabled, V _{DD} = 3.0 V	—	69	76	µA	
I _{DD_VLPW}	Very-low-power wait mode current, core disabled, 125 kHz system/ 31.25 kHz bus and flash, all peripheral clocks disabled, V _{DD} = 3.0 V	—	36	40	µA	
I _{DD_PSTOP2}	Partial Stop 2, core and system clock disabled, 12 MHz bus and flash, V _{DD} = 3.0 V	—	1.81	2.06	mA	
I _{DD_PSTOP2}	Partial Stop 2, core and system clock disabled, flash doze enabled, 12 MHz bus, V _{DD} = 3.0 V	—	1.00	1.25	mA	
I _{DD_STOP}	Stop mode current at 3.0 V • at 25 °C and below • at 50 °C • at 85 °C • at 105 °C	— — — —	161.93 181.45 236.29 390.33	171.82 191.96 271.17 465.58	µA	
I _{DD_VLPS}	Very-low-power stop mode current at 3.0 V • at 25 °C and below • at 50 °C • at 85 °C • at 105 °C	— — — —	3.31 10.43 34.14 104.38	5.14 17.68 61.06 164.44	µA	
I _{DD_VLPS}	Very-low-power stop mode current at 1.8 V • at 25 °C and below • at 50 °C	— — —	3.21 10.26 33.49	5.22 17.62 60.19	µA	

Table continues on the next page...

Table 9. Power consumption operating behaviors (continued)

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
I _{DD_VLLS3}	Very-low-leakage stop mode 3 current with RTC current, at 1.8 V • at 25 °C and below • at 50 °C • at 70 °C • at 85 °C • at 105 °C	—	1.96	2.36	μA	3
I _{DD_VLLS1}	Very-low-leakage stop mode 1 current all peripheral disabled at 3.0 V • at 25 °C and below • at 50°C • at 70°C • at 85°C • at 105 °C	—	0.66	0.80	μA	
I _{DD_VLLS1}	Very-low-leakage stop mode 1 current RTC enabled at 3.0 V • at 25 °C and below • at 50°C • at 70°C • at 85°C • at 105 °C	—	1.26	1.40	μA	3
I _{DD_VLLS1}	Very-low-leakage stop mode 1 current RTC enabled at 1.8 V • at 25 °C and below • at 50°C • at 70°C • at 85°C • at 105 °C	—	1.16	1.30	μA	3
I _{DD_VLLS0}	Very-low-leakage stop mode 0 current all peripheral disabled (SMC_STOPCTRL[PORPO] = 0) at 3.0 V • at 25 °C and below • at 50 °C • at 70 °C • at 85 °C • at 105 °C	—	0.35	0.47	μA	
I _{DD_VLLS0}	Very-low-leakage stop mode 0 current all peripheral disabled (SMC_STOPCTRL[PORPO] = 1) at 3 V	—	1.25	1.44		
		—	2.53	3.24		
		—	4.40	5.24		
		—	16.09	19.29		

Table 9. Power consumption operating behaviors

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
	<ul style="list-style-type: none"> • at 25 °C and below • at 50 °C • at 70 °C • at 85 °C • at 105 °C 	—	0.18	0.28	μA	
		—	1.09	1.31		
		—	2.25	2.94		
		—	4.25	5.10		
		—	15.95	19.10		

1. The analog supply current is the sum of the active or disabled current for each of the analog modules on the device. See each module's specification for its supply current.
2. MCG_Lite configured for HIRC mode. CoreMark benchmark compiled using IAR 7.10 with optimization level high, optimized for balanced.
3. RTC uses external 32 kHz crystal as clock source, and the current includes ERCLK32K power consumption.

Table 10. Low power mode peripheral adders — typical value

Symbol	Description	Temperature (°C)						Unit
		-40	25	50	70	85	105	
I _{IRC8MHz}	8 MHz internal reference clock (IRC) adder. Measured by entering STOP or VLPS mode with 8 MHz IRC enabled, MCG_SC[FCRDIV]=000b, MCG_MC[LIRC_DIV2]=000b.	93	93	93	93	93	93	μA
I _{IRC2MHz}	2 MHz internal reference clock (IRC) adder. Measured by entering STOP mode with the 2 MHz IRC enabled, MCG_SC[FCRDIV]=000b, MCG_MC[LIRC_DIV2]=000b.	29	29	29	29	29	29	μA
I _{EREFSTEN4MHz}	External 4 MHz crystal clock adder. Measured by entering STOP or VLPS mode with the crystal enabled.	206	224	230	238	245	253	μA
I _{EREFSTEN32kHz}	External 32 kHz crystal clock adder by means of the OSC0_CR[EREFSTEN and EREFSTEN] bits. Measured by entering all modes with the crystal enabled. <ul style="list-style-type: none"> • VLLS1 • VLLS3 • LLS • VLPS • STOP 	440	490	540	560	570	580	nA
I _{EREFSTEN32kHz}		440	490	540	560	570	580	nA
I _{EREFSTEN32kHz}		490	490	540	560	570	680	nA
I _{EREFSTEN32kHz}		510	560	560	560	610	680	nA
I _{EREFSTEN32kHz}		510	560	560	560	610	680	nA
I _{LPTMR}	LPTMR peripheral adder measured by placing the device in VLLS1 mode with LPTMR enabled using LPO.	30	30	30	85	100	200	

Table continues on the next page...

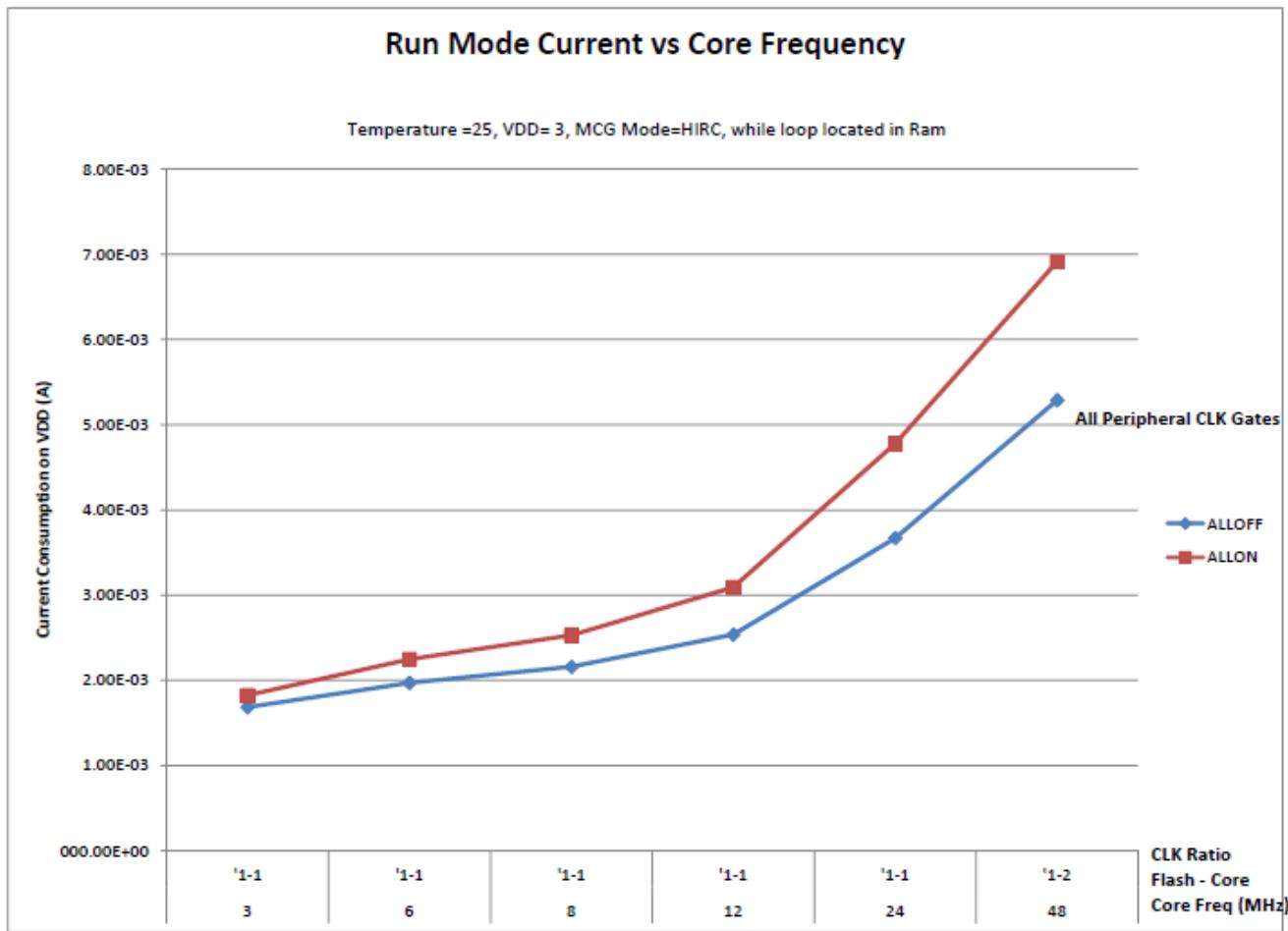


Table 13. Device clock specifications (continued)

Symbol	Description	Min.	Max.	Unit
$f_{osc_hi_2}$	Oscillator crystal or resonator frequency — high frequency mode (high range) (MCG_C2[RANGE]=1x)	—	16	MHz
f_{TPM}	TPM asynchronous clock	—	8	MHz
$f_{LPUART0/1}$	LPUART0/1 asynchronous clock	—	8	MHz

1. The maximum value of system clock, core clock, bus clock, and flash clock under normal run mode can be 3% higher than the specified maximum frequency when IRC 48MHz is used as the clock source.
2. The frequency limitations in VLPR and VLPS modes here override any frequency specification listed in the timing specification for any other module. These same frequency limits apply to VLPS, whether VLPS was entered from RUN or from VLPR.
3. The LPTMR can be clocked at this speed in VLPR or VLPS only when the source is an external pin.

2.3.2 General switching specifications

These general-purpose specifications apply to all signals configured for GPIO and UART signals.

Table 14. General switching specifications

Description	Min.	Max.	Unit	Notes
GPIO pin interrupt pulse width (digital glitch filter disabled) — Synchronous path	1.5	—	Bus clock cycles	1
External RESET and NMI pin interrupt pulse width — Asynchronous path	100	—	ns	2
GPIO pin interrupt pulse width — Asynchronous path	16	—	ns	2
Port rise and fall time	—	36	ns	3

1. The synchronous and asynchronous timing must be met.
2. This is the shortest pulse that is guaranteed to be recognized.
3. 75 pF load

2.4 Thermal specifications

2.4.1 Thermal operating requirements

Table 15. Thermal operating requirements

Symbol	Description	Min.	Max.	Unit	Notes
T_J	Die junction temperature	-40	125	°C	
T_A	Ambient temperature	-40	105	°C	1

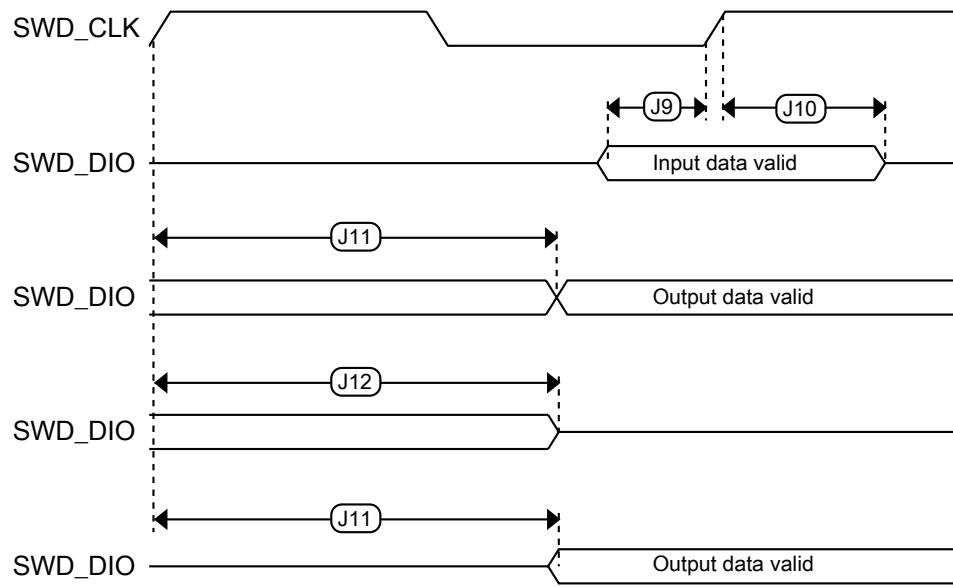


Figure 5. Serial wire data timing

3.2 System modules

There are no specifications necessary for the device's system modules.

3.3 Clock modules

3.3.1 MCG-Lite specifications

Table 18. IRC48M specification

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
I_{DD}	Supply current	—	400	500	μA	—
f_{IRC}	Output frequency	—	48	—	MHz	—
$\Delta f_{irc48m_ol_lv}$	Open loop total deviation of IRC48M frequency at low voltage ($VDD=1.71\text{V}-1.89\text{V}$) over temperature	—	± 0.5	± 1.5	% f_{irc48m}	1
$\Delta f_{irc48m_ol_hv}$	Open loop total deviation of IRC48M frequency at high voltage ($VDD=1.89\text{V}-3.6\text{V}$) over temperature	—	± 0.5	± 1.0	% f_{irc48m}	1

Table continues on the next page...

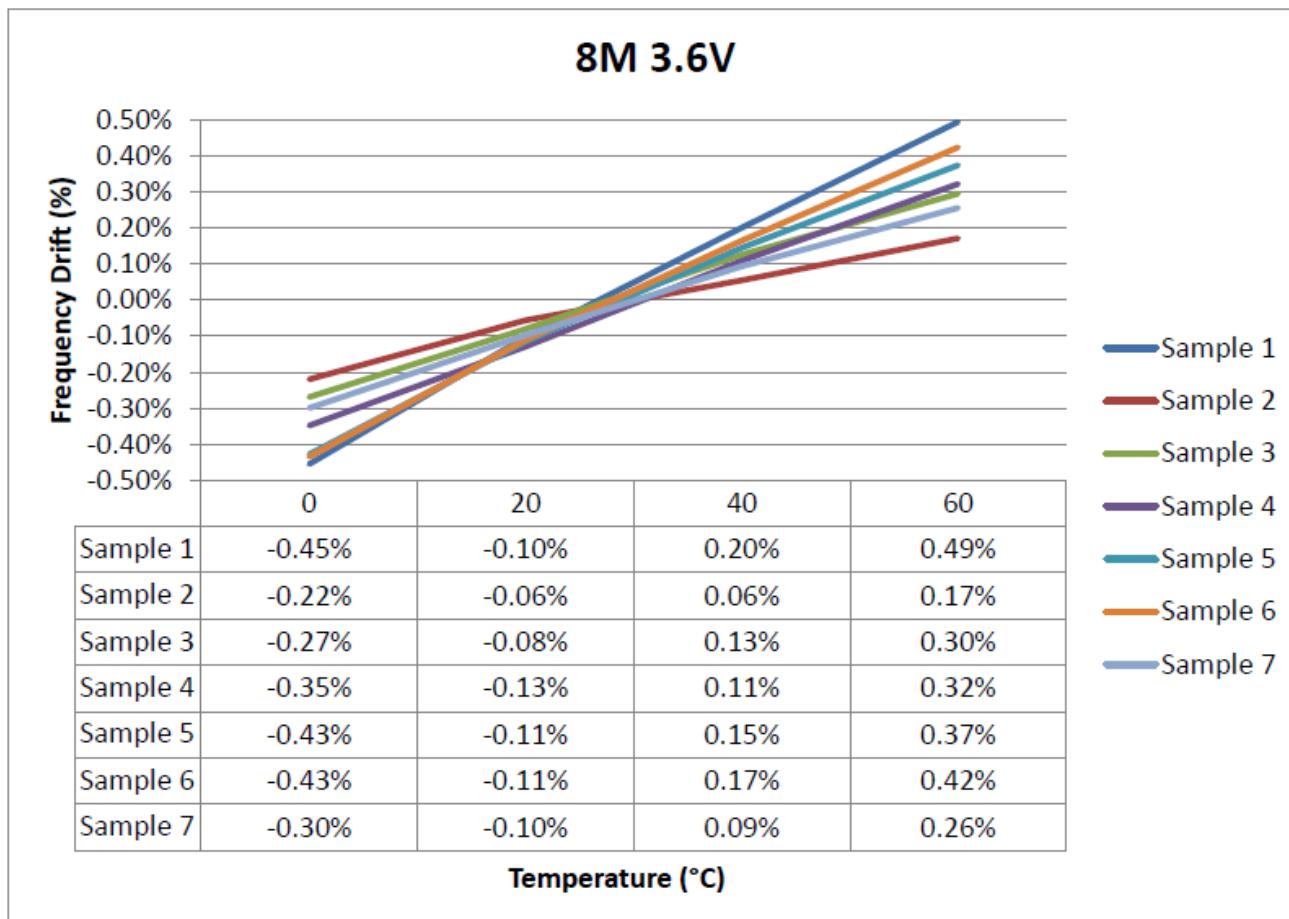


Figure 6. IRC8M Frequency Drift vs Temperature curve

3.3.2 Oscillator electrical specifications

3.3.2.1 Oscillator DC electrical specifications

Table 20. Oscillator DC electrical specifications

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
V _{DD}	Supply voltage	1.71	—	3.6	V	
I _{DDOSC}	Supply current — low-power mode (HGO=0) <ul style="list-style-type: none"> • 32 kHz • 4 MHz • 8 MHz (RANGE=01) • 16 MHz 	—	500	—	nA	1
		—	200	—	µA	
		—	300	—	µA	
		—	950	—	µA	
		—	1.2	—	mA	

Table continues on the next page...

Peripheral operating requirements and behaviors

2. Typical values assume $V_{DDA} = 3.0$ V, Temp = 25 °C, $f_{ADCK} = 2.0$ MHz unless otherwise stated. Typical values are for reference only and are not tested in production.
3. The ADC supply current depends on the ADC conversion clock speed, conversion rate and ADC_CFG1[ADLPC] (low power). For lowest power operation, ADC_CFG1[ADLPC] must be set, the ADC_CFG2[ADHSC] bit must be clear with 1 MHz ADC conversion clock speed.
4. 1 LSB = $(V_{REFH} - V_{REFL})/2^N$
5. ADC conversion clock < 16 MHz, Max hardware averaging (AVGE = %1, AVGS = %11)
6. Input data is 100 Hz sine wave. ADC conversion clock < 12 MHz.
7. Input data is 1 kHz sine wave. ADC conversion clock < 12 MHz.
8. ADC conversion clock < 3 MHz

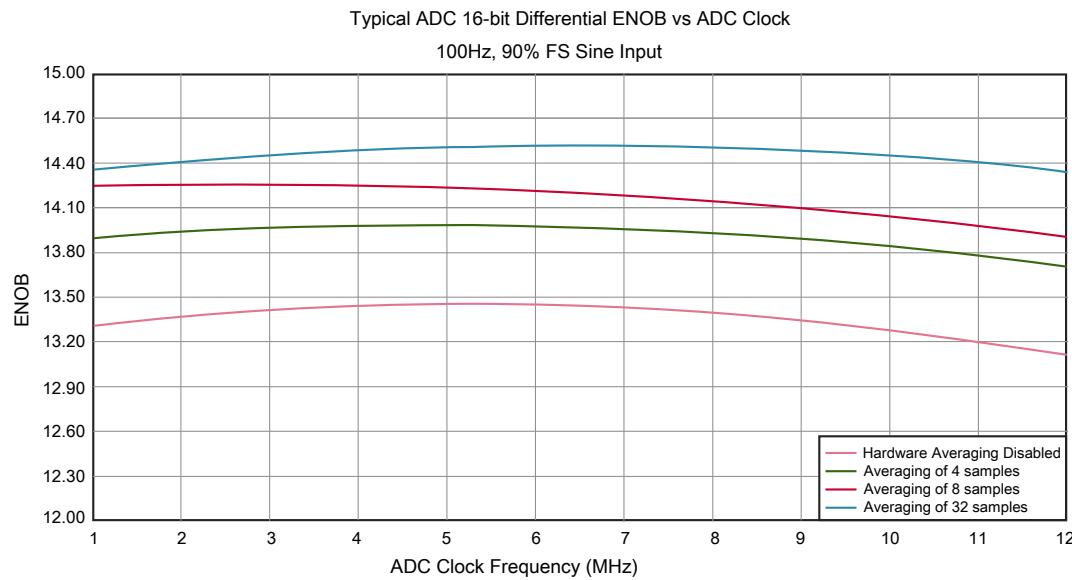


Figure 8. Typical ENOB vs. ADC_CLK for 16-bit differential mode

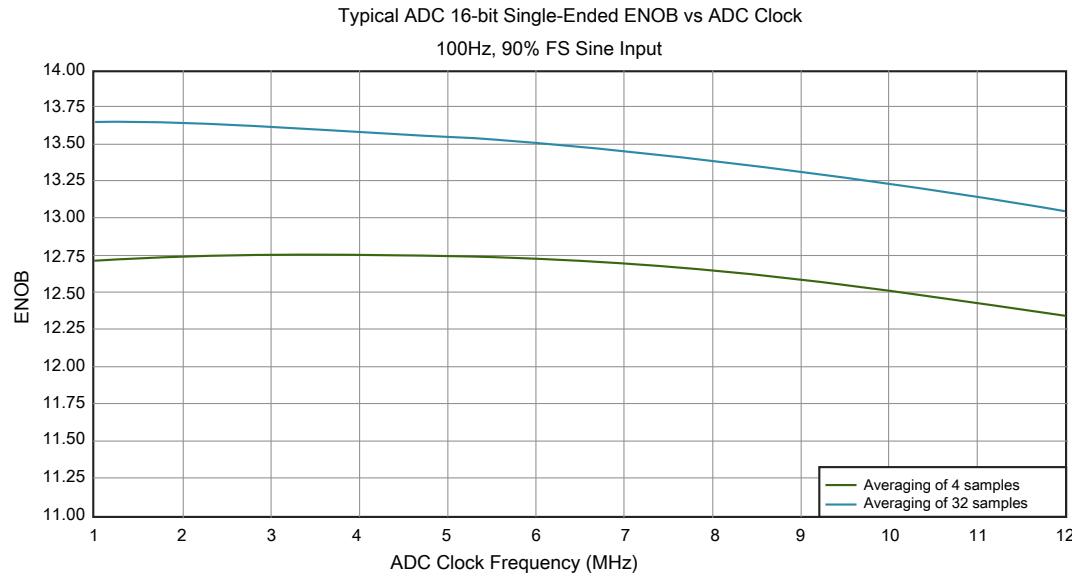


Figure 9. Typical ENOB vs. ADC_CLK for 16-bit single-ended mode

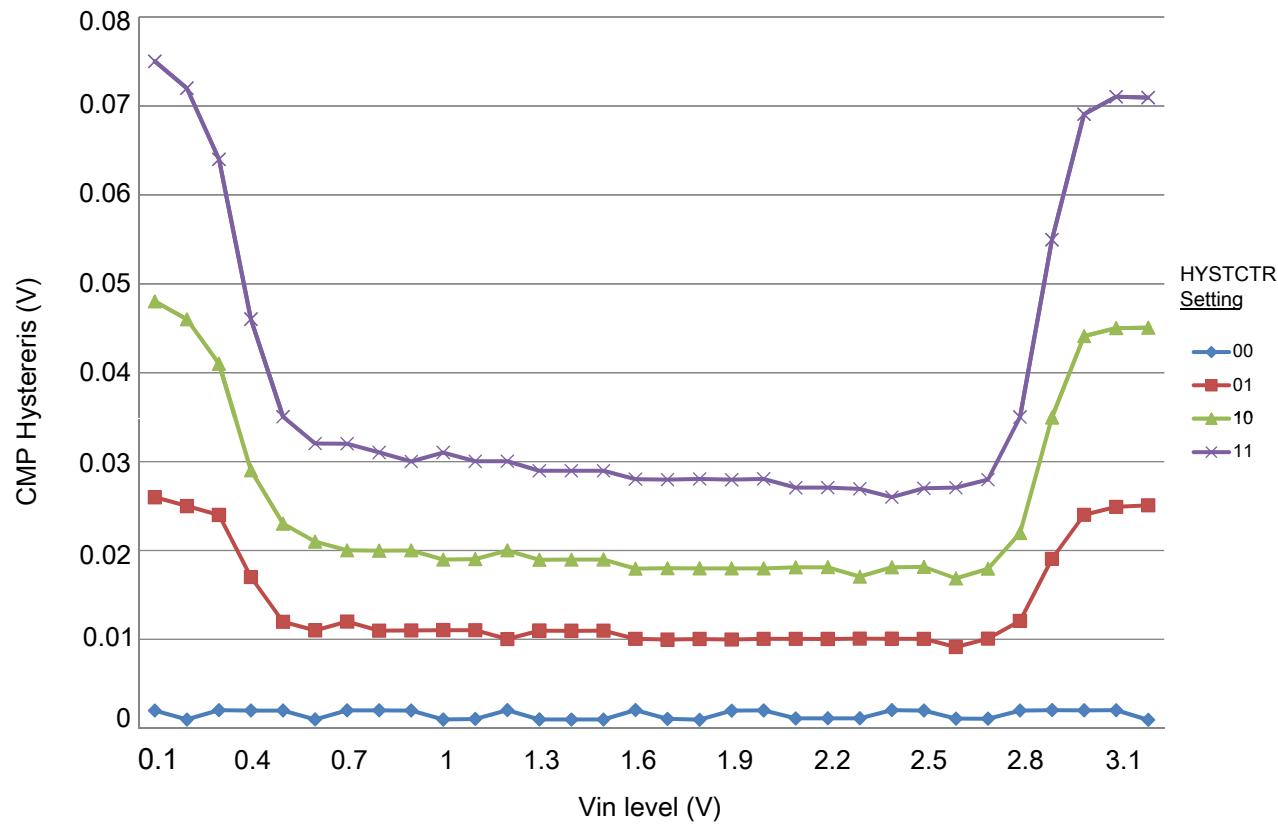


Figure 10. Typical hysteresis vs. Vin level (VDD = 3.3 V, PMODE = 0)

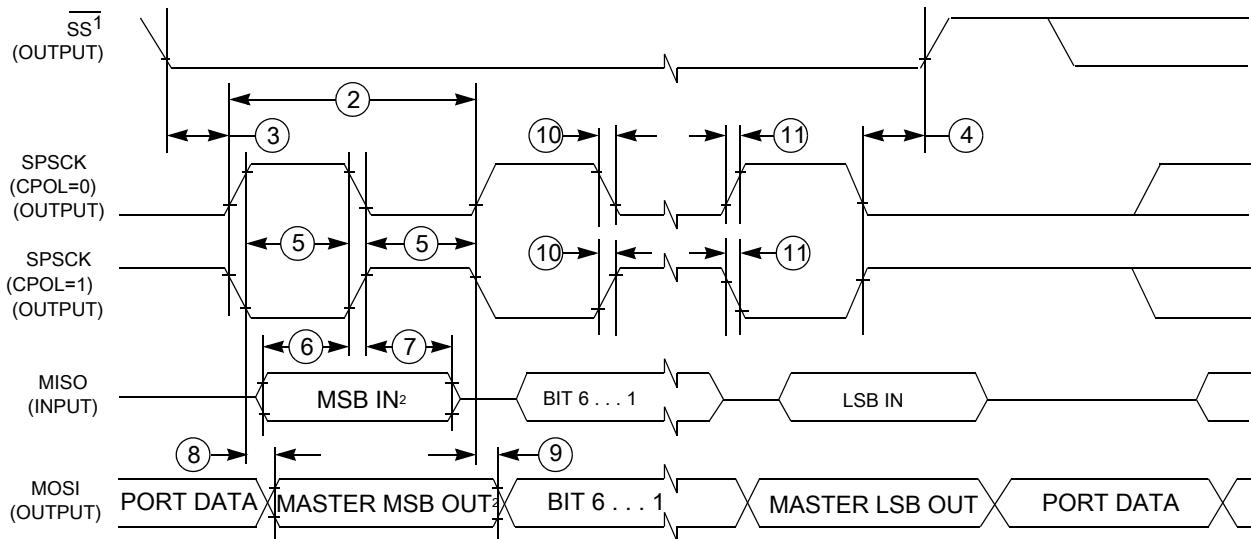


Figure 15. SPI master mode timing (CPHA = 1)

Table 37. SPI slave mode timing on slew rate disabled pads

Num.	Symbol	Description	Min.	Max.	Unit	Note
1	f_{op}	Frequency of operation	0	$f_{periph}/4$	Hz	1
2	t_{SPSCK}	SPSCK period	$4 \times t_{periph}$	—	ns	2
3	t_{Lead}	Enable lead time	1	—	t_{periph}	—
4	t_{Lag}	Enable lag time	1	—	t_{periph}	—
5	t_{WSPSCK}	Clock (SPSCK) high or low time	$t_{periph} - 30$	—	ns	—
6	t_{SU}	Data setup time (inputs)	2.5	—	ns	—
7	t_{HI}	Data hold time (inputs)	3.5	—	ns	—
8	t_a	Slave access time	—	t_{periph}	ns	3
9	t_{dis}	Slave MISO disable time	—	t_{periph}	ns	4
10	t_v	Data valid (after SPSCK edge)	—	31	ns	—
11	t_{HO}	Data hold time (outputs)	0	—	ns	—
12	t_{RI}	Rise time input	—	$t_{periph} - 25$	ns	—
	t_{FI}	Fall time input	—			
13	t_{RO}	Rise time output	—	25	ns	—
	t_{FO}	Fall time output	—			

1. For SPI0 f_{periph} is the bus clock (f_{BUS}). For SPI1 f_{periph} is the system clock (f_{SYS}).
2. $t_{periph} = 1/f_{periph}$
3. Time to data active from high-impedance state
4. Hold time to high-impedance state

Table 38. SPI slave mode timing on slew rate enabled pads

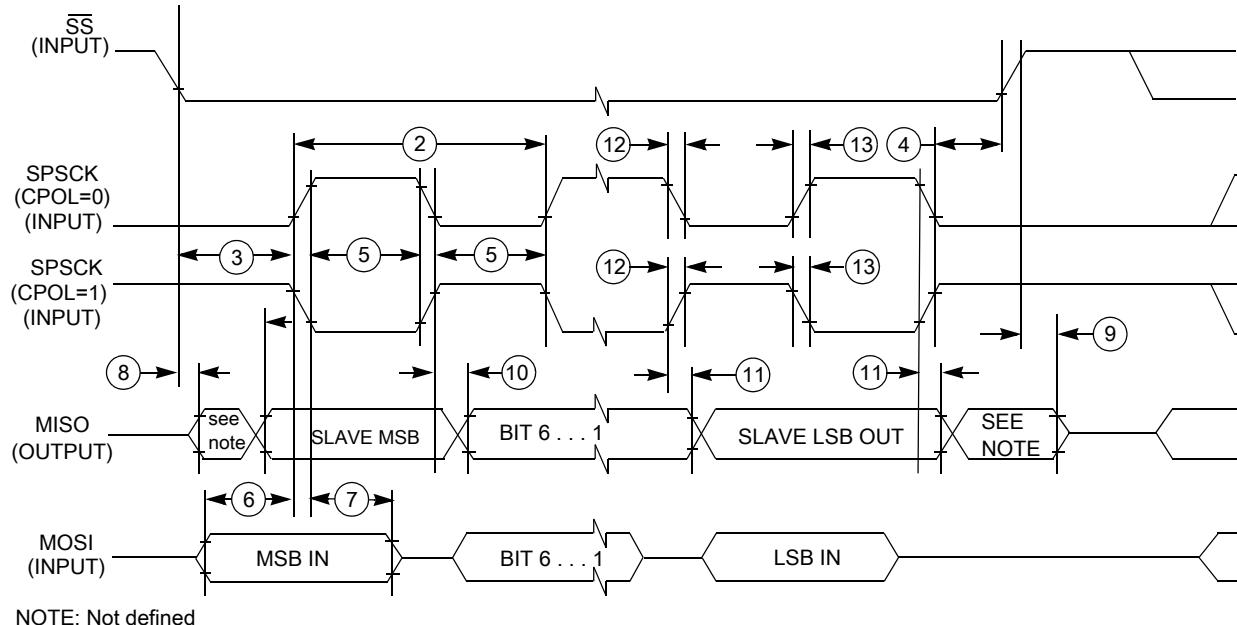
Num.	Symbol	Description	Min.	Max.	Unit	Note
1	f_{op}	Frequency of operation	0	$f_{periph}/4$	Hz	1
2	t_{SPSCK}	SPSCK period	$4 \times t_{periph}$	—	ns	2
3	t_{Lead}	Enable lead time	1	—	t_{periph}	—
4	t_{Lag}	Enable lag time	1	—	t_{periph}	—
5	t_{WPSCK}	Clock (SPSCK) high or low time	$t_{periph} - 30$	—	ns	—
6	t_{SU}	Data setup time (inputs)	2	—	ns	—
7	t_{HI}	Data hold time (inputs)	7	—	ns	—
8	t_a	Slave access time	—	t_{periph}	ns	3
9	t_{dis}	Slave MISO disable time	—	t_{periph}	ns	4
10	t_v	Data valid (after SPSCK edge)	—	122	ns	—
11	t_{HO}	Data hold time (outputs)	0	—	ns	—
12	t_{RI}	Rise time input	—	$t_{periph} - 25$	ns	—
	t_{FI}	Fall time input				
13	t_{RO}	Rise time output	—	36	ns	—
	t_{FO}	Fall time output				

1. For SPI0 f_{periph} is the bus clock (f_{BUS}). For SPI1 f_{periph} is the system clock (f_{sys}).

2. $t_{periph} = 1/f_{periph}$

3. Time to data active from high-impedance state

4. Hold time to high-impedance state

**Figure 16. SPI slave mode timing (CPHA = 0)**

1. The maximum SCL Clock Frequency in Fast mode with maximum bus loading can be achieved only when using the high drive pins across the full voltage range and when using the normal drive pins and $VDD \geq 2.7$ V.
2. The master mode I²C deasserts ACK of an address byte simultaneously with the falling edge of SCL. If no slaves acknowledge this address byte, then a negative hold time can result, depending on the edge rates of the SDA and SCL lines.
3. The maximum tHD; DAT must be met only if the device does not stretch the LOW period (t_{LOW}) of the SCL signal.
4. Input Signal Slew = 10 ns and Output Load = 50 pF
5. Set-up time in slave-transmitter mode is 1 IPBus clock period, if the TX FIFO is empty.
6. A Fast mode I²C bus device can be used in a Standard mode I²C bus system, but the requirement $t_{SU; DAT} \geq 250$ ns must then be met. This is automatically the case if the device does not stretch the LOW period of the SCL signal. If such a device does stretch the LOW period of the SCL signal, then it must output the next data bit to the SDA line $t_{rmax} + t_{SU; DAT} = 1000 + 250 = 1250$ ns (according to the Standard mode I²C bus specification) before the SCL line is released.
7. C_b = total capacitance of the one bus line in pF.

To achieve 1MHz I²C clock rates, consider the following recommendations:

- To counter the effects of clock stretching, the I²C baud Rate select bits can be configured for faster than desired baud rate.
- Use high drive pad and DSE bit should be set in PORTx_PCRn register.
- Minimize loading on the I²C SDA and SCL pins to ensure fastest rise times for the SCL line to avoid clock stretching.
- Use smaller pull up resistors on SDA and SCL to reduce the RC time constant.

Table 40. I²C 1Mbit/s timing

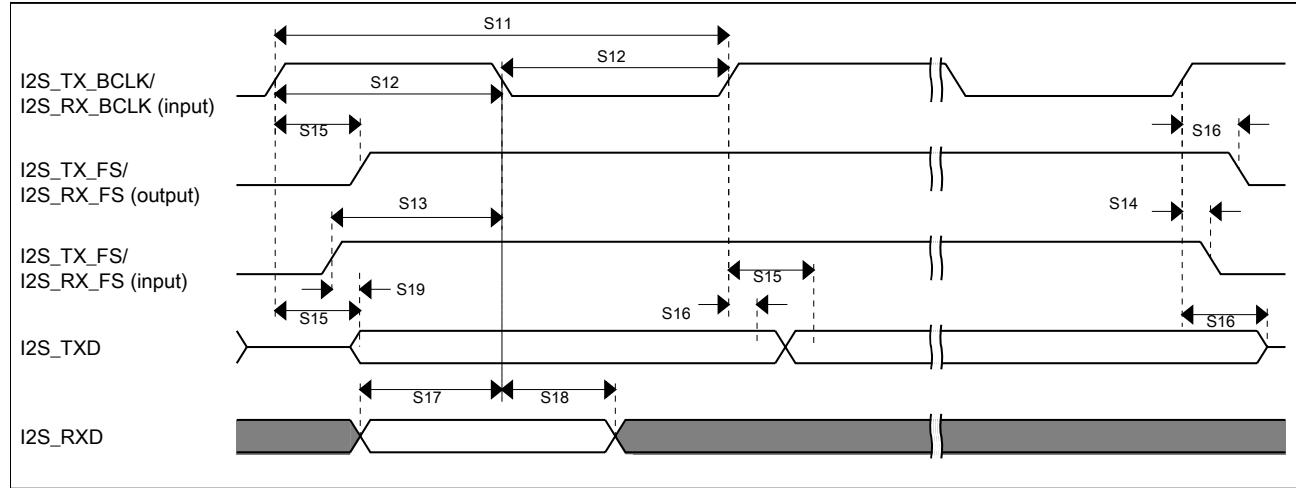
Characteristic	Symbol	Minimum	Maximum	Unit
SCL Clock Frequency	f_{SCL}	0	1 ¹	MHz
Hold time (repeated) START condition. After this period, the first clock pulse is generated.	$t_{HD; STA}$	0.26	—	μs
LOW period of the SCL clock	t_{LOW}	0.5	—	μs
HIGH period of the SCL clock	t_{HIGH}	0.26	—	μs
Set-up time for a repeated START condition	$t_{SU; STA}$	0.26	—	μs
Data hold time for I ₂ C bus devices	$t_{HD; DAT}$	0	—	μs
Data set-up time	$t_{SU; DAT}$	50	—	ns
Rise time of SDA and SCL signals	t_r	$20 + 0.1C_b$	120	ns
Fall time of SDA and SCL signals	t_f	$20 + 0.1C_b^2$	120	ns
Set-up time for STOP condition	$t_{SU; STO}$	0.26	—	μs
Bus free time between STOP and START condition	t_{BUF}	0.5	—	μs
Pulse width of spikes that must be suppressed by the input filter	t_{SP}	0	50	ns

1. The maximum SCL clock frequency of 1 Mbit/s can support maximum bus loading when using the high drive pins across the full voltage range.
2. C_b = total capacitance of the one bus line in pF.

Table 42. I2S/SAI slave mode timing (continued)

Num.	Characteristic	Min.	Max.	Unit
S18	I2S_RXD hold after I2S_RX_BCLK	2	—	ns
S19	I2S_TX_FS input assertion to I2S_TXD output valid ¹	—	28	ns

1. Applies to first bit in each frame and only if the TCR4[FSE] bit is clear

**Figure 20. I2S/SAI timing — slave modes**

3.8.4.2 VLPR, VLPW, and VLPS mode performance over the full operating voltage range

This section provides the operating performance over the full operating voltage for the device in VLPR, VLPW, and VLPS modes.

Table 43. I2S/SAI master mode timing in VLPR, VLPW, and VLPS modes (full voltage range)

Num.	Characteristic	Min.	Max.	Unit
	Operating voltage	1.71	3.6	V
S1	I2S_MCLK cycle time	62.5	—	ns
S2	I2S_MCLK pulse width high/low	45%	55%	MCLK period
S3	I2S_TX_BCLK/I2S_RX_BCLK cycle time (output)	250	—	ns
S4	I2S_TX_BCLK/I2S_RX_BCLK pulse width high/low	45%	55%	BCLK period
S5	I2S_TX_BCLK/I2S_RX_BCLK to I2S_TX_FS/I2S_RX_FS output valid	—	45	ns
S6	I2S_TX_BCLK/I2S_RX_BCLK to I2S_TX_FS/I2S_RX_FS output invalid	0	—	ns
S7	I2S_TX_BCLK to I2S_TXD valid	—	45	ns

Table continues on the next page...

Pinouts and Packaging

64 LQFP	64 MAP BGA	Pin Name	Default	ALT0	ALT1	ALT2	ALT3	ALT4	ALT5	ALT6	ALT7
33	G8	PTA19	XTAL0	XTAL0	PTA19		LPUART1_TX	TPM_CLKIN1		LPTMR0_ ALT1	
34	F8	PTA20	RESET_b		PTA20						RESET_b
35	F7	PTB0/ LLWU_P5	LCD_P0/ ADC0_SE8	LCD_P0/ ADC0_SE8	PTB0/ LLWU_P5	I2C0_SCL	TPM1_CH0				LCD_P0
36	F6	PTB1	LCD_P1/ ADC0_SE9	LCD_P1/ ADC0_SE9	PTB1	I2C0_SDA	TPM1_CH1				LCD_P1
37	E7	PTB2	LCD_P2/ ADC0_SE12	LCD_P2/ ADC0_SE12	PTB2	I2C0_SCL	TPM2_CH0				LCD_P2
38	E8	PTB3	LCD_P3/ ADC0_SE13	LCD_P3/ ADC0_SE13	PTB3	I2C0_SDA	TPM2_CH1				LCD_P3
39	E6	PTB16	LCD_P12	LCD_P12	PTB16	SPI1_MOSI	LPUART0_RX	TPM_CLKIN0	SPI1_MISO		LCD_P12
40	D7	PTB17	LCD_P13	LCD_P13	PTB17	SPI1_MISO	LPUART0_TX	TPM_CLKIN1	SPI1_MOSI		LCD_P13
41	D6	PTB18	LCD_P14	LCD_P14	PTB18		TPM2_CH0	I2S0_TX_ BCLK			LCD_P14
42	C7	PTB19	LCD_P15	LCD_P15	PTB19		TPM2_CH1	I2S0_TX_FS			LCD_P15
43	D8	PTC0	LCD_P20/ ADC0_SE14	LCD_P20/ ADC0_SE14	PTC0		EXTRG_IN	audioUSB_ SOF_OUT	CMP0_OUT	I2S0_TxD0	LCD_P20
44	C6	PTC1/ LLWU_P6/ RTC_CLKIN	LCD_P21/ ADC0_SE15	LCD_P21/ ADC0_SE15	PTC1/ LLWU_P6/ RTC_CLKIN	I2C1_SCL		TPM0_CH0		I2S0_TxD0	LCD_P21
45	B7	PTC2	LCD_P22/ ADC0_SE11	LCD_P22/ ADC0_SE11	PTC2	I2C1_SDA		TPM0_CH1		I2S0_TX_FS	LCD_P22
46	C8	PTC3/ LLWU_P7	LCD_P23	LCD_P23	PTC3/ LLWU_P7	SPI1_SCK	LPUART1_RX	TPM0_CH2	CLKOUT	I2S0_TX_ BCLK	LCD_P23
47	E3	VSS	VSS	VSS							
48	C5	VLL3	VLL3	VLL3							
49	A6	VLL2	VLL2	VLL2/ LCD_P4	PTC20						LCD_P4
50	B5	VLL1	VLL1	VLL1/ LCD_P5	PTC21						LCD_P5
51	B4	VCAP2	VCAP2	VCAP2/ LCD_P6	PTC22						LCD_P6
52	A5	VCAP1	VCAP1	VCAP1/ LCD_P39	PTC23						LCD_P39
53	B8	PTC4/ LLWU_P8	LCD_P24	LCD_P24	PTC4/ LLWU_P8	SPI0_SS	LPUART1_TX	TPM0_CH3	I2S0_MCLK		LCD_P24
54	A8	PTC5/ LLWU_P9	LCD_P25	LCD_P25	PTC5/ LLWU_P9	SPI0_SCK	LPTMR0_ ALT2	I2S0_RXD0		CMP0_OUT	LCD_P25
55	A7	PTC6/ LLWU_P10	LCD_P26/ CMP0_IN0	LCD_P26/ CMP0_IN0	PTC6/ LLWU_P10	SPI0_MOSI	EXTRG_IN	I2S0_RX_ BCLK	SPI0_MISO	I2S0_MCLK	LCD_P26
56	B6	PTC7	LCD_P27/ CMP0_IN1	LCD_P27/ CMP0_IN1	PTC7	SPI0_MISO	audioUSB_ SOF_OUT	I2S0_RX_FS	SPI0_MOSI		LCD_P27
57	C3	PTD0	LCD_P40	LCD_P40	PTD0	SPI0_SS		TPM0_CH0		FXIO0_D0	LCD_P40

7.1 Description

Part numbers for the chip have fields that identify the specific part. You can use the values of these fields to determine the specific part you have received.

7.2 Format

Part numbers for this device have the following format:

Q KL## A FFF R T PP CC N

7.3 Fields

This table lists the possible values for each field in the part number (not all combinations are valid):

Table 46. Part number fields descriptions

Field	Description	Values
Q	Qualification status	<ul style="list-style-type: none">• M = Fully qualified, general market flow• P = Prequalification
KL##	Kinetis family	<ul style="list-style-type: none">• KL33
A	Key attribute	<ul style="list-style-type: none">• Z = Cortex-M0+
FFF	Program flash memory size	
R	Silicon revision	<ul style="list-style-type: none">• (Blank) = Main• A = Revision after main
T	Temperature range (°C)	<ul style="list-style-type: none">• V = -40 to 105
PP	Package identifier	<ul style="list-style-type: none">• LH = 64 LQFP (10 mm x 10 mm)• MP = 64 MAPBGA (5 mm x 5 mm)
CC	Maximum CPU frequency (MHz)	<ul style="list-style-type: none">• 4 = 48 MHz
N	Packaging type	<ul style="list-style-type: none">• R = Tape and reel

7.4 Example

This is an example part number:

MKL33Z256VMP4

8.2 Examples

Operating rating:

Symbol	Description	Min.	Max.	Unit
V _{DD}	1.0 V core supply voltage	-0.3	1.2	V

Operating requirement:

Symbol	Description	Min.	Max.	Unit
V _{DD}	1.0 V core supply voltage	0.9	1.1	V

Operating behavior that includes a typical value:

Symbol	Description	Min.	Typ.	Max.	Unit
I _{WP}	Digital I/O weak pullup/pulldown current	10	70	130	µA

8.3 Typical-value conditions

Typical values assume you meet the following conditions (or other conditions as specified):

Symbol	Description	Value	Unit
T _A	Ambient temperature	25	°C
V _{DD}	3.3 V supply voltage	3.3	V