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### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Active
Core Processor	ARM® Cortex®-M0+
Core Size	32-Bit Single-Core
Speed	48MHz
Connectivity	I <sup>2</sup> C, LINbus, SPI, UART/USART, USB, USB OTG
Peripherals	Brown-out Detect/Reset, DMA, LVD, POR, PWM, WDT
Number of I/O	50
Program Memory Size	32KB (32K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	4K x 8
Voltage - Supply (Vcc/Vdd)	1.71V ~ 3.6V
Data Converters	A/D 14x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	64-LQFP
Supplier Device Package	64-LQFP (10x10)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/nxp-semiconductors/mkl24z32vlh4">https://www.e-xfl.com/product-detail/nxp-semiconductors/mkl24z32vlh4</a>

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**Table 2. V<sub>DD</sub> supply LVD and POR operating requirements (continued)**

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
V <sub>LVW1L</sub>	Low-voltage warning thresholds — low range • Level 1 falling (LVWV=00)	1.74	1.80	1.86	V	1
V <sub>LVW2L</sub>	• Level 2 falling (LVWV=01)	1.84	1.90	1.96	V	
V <sub>LVW3L</sub>	• Level 3 falling (LVWV=10)	1.94	2.00	2.06	V	
V <sub>LVW4L</sub>	• Level 4 falling (LVWV=11)	2.04	2.10	2.16	V	
V <sub>HYSL</sub>	Low-voltage inhibit reset/recover hysteresis — low range	—	±40	—	mV	
V <sub>BG</sub>	Bandgap voltage reference	0.97	1.00	1.03	V	
t <sub>LPO</sub>	Internal low power oscillator period — factory trimmed	900	1000	1100	μs	

1. Rising thresholds are falling threshold + hysteresis voltage

### 5.2.3 Voltage and current operating behaviors

**Table 3. Voltage and current operating behaviors**

Symbol	Description	Min.	Max.	Unit	Notes
V <sub>OH</sub>	Output high voltage — Normal drive pad • 2.7 V ≤ V <sub>DD</sub> ≤ 3.6 V, I <sub>OH</sub> = -5 mA • 1.71 V ≤ V <sub>DD</sub> ≤ 2.7 V, I <sub>OH</sub> = -1.5 mA	V <sub>DD</sub> - 0.5 V <sub>DD</sub> - 0.5	— —	V V	1
V <sub>OH</sub>	Output high voltage — High drive pad • 2.7 V ≤ V <sub>DD</sub> ≤ 3.6 V, I <sub>OH</sub> = -18 mA • 1.71 V ≤ V <sub>DD</sub> ≤ 2.7 V, I <sub>OH</sub> = -6 mA	V <sub>DD</sub> - 0.5 V <sub>DD</sub> - 0.5	— —	V V	1
I <sub>OHT</sub>	Output high current total for all ports	—	100	mA	
V <sub>OL</sub>	Output low voltage — Normal drive pad • 2.7 V ≤ V <sub>DD</sub> ≤ 3.6 V, I <sub>OL</sub> = 5 mA • 1.71 V ≤ V <sub>DD</sub> ≤ 2.7 V, I <sub>OL</sub> = 1.5 mA	— —	0.5 0.5	V V	1
V <sub>OL</sub>	Output low voltage — High drive pad • 2.7 V ≤ V <sub>DD</sub> ≤ 3.6 V, I <sub>OL</sub> = 18 mA • 1.71 V ≤ V <sub>DD</sub> ≤ 2.7 V, I <sub>OL</sub> = 6 mA	— —	0.5 0.5	V V	1
I <sub>OLT</sub>	Output low current total for all ports	—	100	mA	
I <sub>IN</sub>	Input leakage current (per pin) for full temperature range	—	1	μA	2
I <sub>IN</sub>	Input leakage current (per pin) at 25 °C	—	0.025	μA	2
I <sub>IN</sub>	Input leakage current (total all pins) for full temperature range	—	65	μA	2
I <sub>OZ</sub>	Hi-Z (off-state) leakage current (per pin)	—	1	μA	

Table continues on the next page...

**Table 3. Voltage and current operating behaviors (continued)**

Symbol	Description	Min.	Max.	Unit	Notes
R <sub>PU</sub>	Internal pullup resistors	20	50	kΩ	3
R <sub>PD</sub>	Internal pulldown resistors	20	50	kΩ	4

1. PTB0, PTB1, PTD6, and PTD7 I/O have both high drive and normal drive capability selected by the associated PTx\_PCRn[DSE] control bit. All other GPIOs are normal drive only.
2. Measured at V<sub>DD</sub> = 3.6 V
3. Measured at V<sub>DD</sub> supply voltage = V<sub>DD</sub> min and V<sub>input</sub> = V<sub>SS</sub>
4. Measured at V<sub>DD</sub> supply voltage = V<sub>DD</sub> min and V<sub>input</sub> = V<sub>DD</sub>

## 5.2.4 Power mode transition operating behaviors

All specifications except t<sub>POR</sub> and VLLSx→RUN recovery times in the following table assume this clock configuration:

- CPU and system clocks = 48 MHz
- Bus and flash clock = 24 MHz
- FEI clock mode

**Table 4. Power mode transition operating behaviors**

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
t <sub>POR</sub>	After a POR event, amount of time from the point V <sub>DD</sub> reaches 1.8 V to execution of the first instruction across the operating temperature range of the chip.	—	—	300	μs	
	• VLLS0 → RUN	—	95	115	μs	
	• VLLS1 → RUN	—	93	115	μs	
	• VLLS3 → RUN	—	42	53	μs	
	• LLS → RUN	—	4	4.6	μs	
	• VLPS → RUN	—	4	4.4	μs	
	• STOP → RUN	—	4	4.4	μs	

**Table 6. Low power mode peripheral adders — typical value (continued)**

Symbol	Description	Temperature (°C)						Unit
		-40	25	50	70	85	105	
I <sub>REFSTEN32KHz</sub>	External 32 kHz crystal clock adder by means of the OSC0_CR[EREFSTEN and EREFSTEN] bits. Measured by entering all modes with the crystal enabled.	440	490	540	560	570	580	nA
		440	490	540	560	570	580	
	VLLS1	490	490	540	560	570	680	
	VLLS3	510	560	560	560	610	680	
	LLS	510	560	560	560	610	680	
	VLPS							
	STOP							
I <sub>CMP</sub>	CMP peripheral adder measured by placing the device in VLLS1 mode with CMP enabled using the 6-bit DAC and a single external input for compare. Includes 6-bit DAC power consumption.	22	22	22	22	22	22	μA
I <sub>RTC</sub>	RTC peripheral adder measured by placing the device in VLLS1 mode with external 32 kHz crystal enabled by means of the RTC_CR[OSCE] bit and the RTC ALARM set for 1 minute. Includes ERCLK32K (32 kHz external crystal) power consumption.	432	357	388	475	532	810	nA
I <sub>UART</sub>	UART peripheral adder measured by placing the device in STOP or VLPS mode with selected clock source waiting for RX data at 115200 baud rate. Includes selected clock source power consumption.							
	MCGIRCLK (4MHz internal reference clock)	66	66	66	66	66	66	μA
	OSCERCLK (4MHz external crystal)	214	237	246	254	260	268	
I <sub>TPM</sub>	TPM peripheral adder measured by placing the device in STOP or VLPS mode with selected clock source configured for output compare generating 100Hz clock signal. No load is placed on the I/O generating the clock signal. Includes selected clock source and I/O switching currents.							
	MCGIRCLK (4MHz internal reference clock)	86	86	86	86	86	86	μA
	OSCERCLK (4MHz external crystal)	235	256	265	274	280	287	
I <sub>BG</sub>	Bandgap adder when BGEN bit is set and device is placed in VLPx, LLS, or VLLSx mode.	45	45	45	45	45	45	μA

Table continues on the next page...

**Table 6. Low power mode peripheral adders — typical value (continued)**

Symbol	Description	Temperature (°C)						Unit
		-40	25	50	70	85	105	
I <sub>ADC</sub>	ADC peripheral adder combining the measured values at VDD and VDDA by placing the device in STOP or VLPS mode. ADC is configured for low power mode using the internal clock and continuous conversions.	366	366	366	366	366	366	μA

### 5.2.5.1 Diagram: Typical IDD\_RUN operating behavior

The following data was measured under these conditions:

- MCG in FBE for run mode, and BLPE for VLPR mode
- USB regulator disabled
- No GPIOs toggled
- Code execution from flash with cache enabled
- For the ALLOFF curve, all peripheral clocks are disabled except FTFA

2.  $V_{DD} = 3.3\text{ V}$ ,  $T_A = 25\text{ }^\circ\text{C}$ ,  $f_{OSC} = 8\text{ MHz}$  (crystal),  $f_{SYS} = 48\text{ MHz}$ ,  $f_{BUS} = 48\text{ MHz}$
3. Specified according to Annex D of IEC Standard 61967-2, *Measurement of Radiated Emissions—TEM Cell and Wideband TEM Cell Method*

## 5.2.7 Designing with radiated emissions in mind

To find application notes that provide guidance on designing your system to minimize interference from radiated emissions:

1. Go to [www.freescale.com](http://www.freescale.com).
2. Perform a keyword search for “EMC design.”

## 5.2.8 Capacitance attributes

Table 8. Capacitance attributes

Symbol	Description	Min.	Max.	Unit
$C_{IN\_A}$	Input capacitance: analog pins	—	7	pF
$C_{IN\_D}$	Input capacitance: digital pins	—	7	pF

## 5.3 Switching specifications

### 5.3.1 Device clock specifications

Symbol	Description	Min.	Max.	Unit	Notes
Normal run mode					
$f_{SYS}$	System and core clock	—	48	MHz	
$f_{BUS}$	Bus clock	—	24	MHz	
$f_{FLASH}$	Flash clock	—	24	MHz	
$f_{SYS\_USB}$	System and core clock when Full Speed USB in operation	20	—	MHz	
$f_{LPTMR}$	LPTMR clock	—	24	MHz	
VLPR mode <sup>1</sup>					
$f_{SYS}$	System and core clock	—	4	MHz	
$f_{BUS}$	Bus clock	—	1	MHz	
$f_{FLASH}$	Flash clock	—	1	MHz	
$f_{LPTMR}$	LPTMR clock	—	24	MHz	
$f_{ERCLK}$	External reference clock	—	16	MHz	
$f_{LPTMR\_pin}$	LPTMR clock	—	24	MHz	

Table continues on the next page...

## 5.4.2 Thermal attributes

**Table 10. Thermal attributes**

Board type	Symbol	Description	80 LQFP	64 LQFP	48 QFN	32 QFN	Unit	Notes
Single-layer (1S)	$R_{\theta JA}$	Thermal resistance, junction to ambient (natural convection)	70	71	84	92	°C/W	1
Four-layer (2s2p)	$R_{\theta JA}$	Thermal resistance, junction to ambient (natural convection)	53	52	28	33	°C/W	
Single-layer (1S)	$R_{\theta JMA}$	Thermal resistance, junction to ambient (200 ft./min. air speed)	—	59	69	75	°C/W	
Four-layer (2s2p)	$R_{\theta JMA}$	Thermal resistance, junction to ambient (200 ft./min. air speed)	—	46	22	27	°C/W	
—	$R_{\theta JB}$	Thermal resistance, junction to board	34	34	10	12	°C/W	2
—	$R_{\theta JC}$	Thermal resistance, junction to case	15	20	2.0	1.8	°C/W	3
—	$\Psi_{JT}$	Thermal characterization parameter, junction to package top outside center (natural convection)	0.6	5	5.0	8	°C/W	4

1. Determined according to JEDEC Standard JESD51-2, *Integrated Circuits Thermal Test Method Environmental Conditions – Natural Convection (Still Air)*, or EIA/JEDEC Standard JESD51-6, *Integrated Circuit Thermal Test Method Environmental Conditions – Forced Convection (Moving Air)*.
2. Determined according to JEDEC Standard JESD51-8, *Integrated Circuit Thermal Test Method Environmental Conditions – Junction-to-Board*.
3. Determined according to Method 1012.1 of MIL-STD 883, *Test Method Standard, Microcircuits*, with the cold plate temperature used for the case temperature. The value includes the thermal resistance of the interface material between the top of the package and the cold plate.
4. Determined according to JEDEC Standard JESD51-2, *Integrated Circuits Thermal Test Method Environmental Conditions – Natural Convection (Still Air)*.

## 6 Peripheral operating requirements and behaviors

### 6.1 Core modules

#### 6.1.1 SWD Electricals

**Table 11. SWD full voltage range electricals**

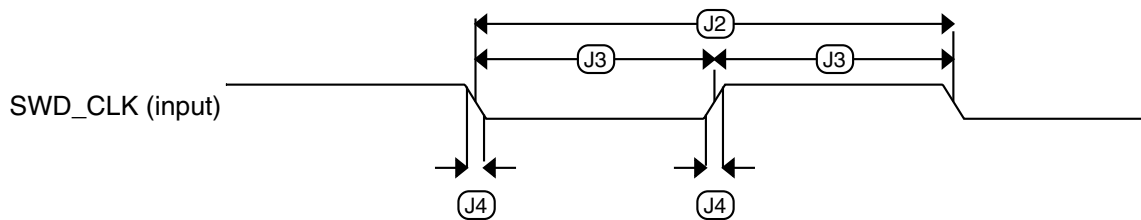
Symbol	Description	Min.	Max.	Unit
	Operating voltage	1.71	3.6	V

Table continues on the next page...

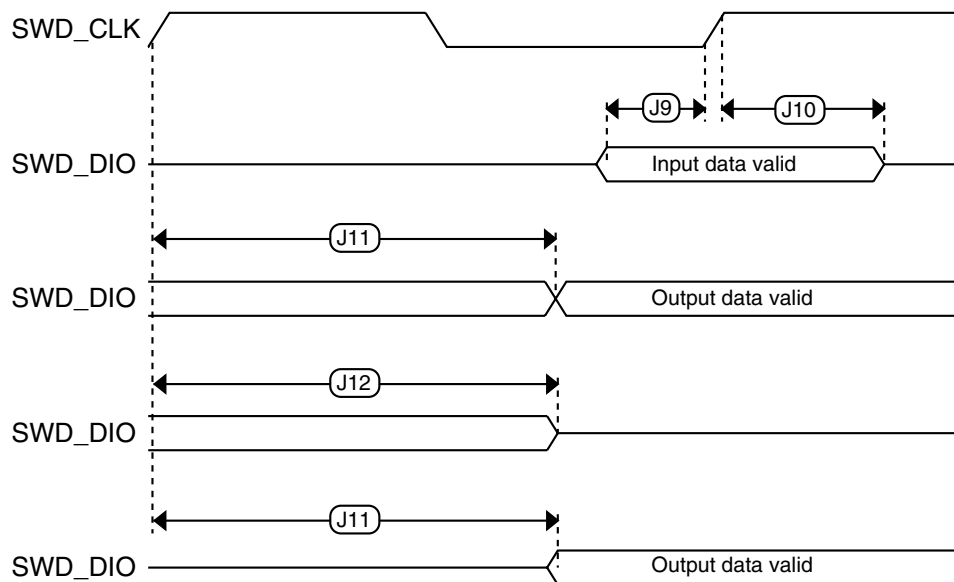


**Table 11. SWD full voltage range electricals (continued)**

Symbol	Description	Min.	Max.	Unit
J1	SWD_CLK frequency of operation <ul style="list-style-type: none"> <li>Serial wire debug</li> </ul>	0	25	MHz
J2	SWD_CLK cycle period	1/J1	—	ns
J3	SWD_CLK clock pulse width <ul style="list-style-type: none"> <li>Serial wire debug</li> </ul>	20	—	ns
J4	SWD_CLK rise and fall times	—	3	ns
J9	SWD_DIO input data setup time to SWD_CLK rise	10	—	ns
J10	SWD_DIO input data hold time after SWD_CLK rise	0	—	ns
J11	SWD_CLK high to SWD_DIO data valid	—	32	ns
J12	SWD_CLK high to SWD_DIO high-Z	5	—	ns



**Figure 4. Serial wire clock input timing**



**Figure 5. Serial wire data timing**

**Table 12. MCG specifications (continued)**

Symbol	Description	Min.	Typ.	Max.	Unit	Notes	
$f_{\text{dco\_t\_DMX32}}$	DCO output frequency	Low range (DRS = 00) $732 \times f_{\text{fil\_ref}}$	—	23.99	—	MHz	5, 6
		Mid range (DRS = 01) $1464 \times f_{\text{fil\_ref}}$	—	47.97	—	MHz	
$J_{\text{cyc\_fll}}$	FLL period jitter • $f_{\text{VCO}} = 48$ MHz	—	180	—	ps	7	
$t_{\text{fll\_acquire}}$	FLL target frequency acquisition time	—	—	1	ms	8	
PLL							
$f_{\text{vco}}$	VCO operating frequency	48.0	—	100	MHz		
$I_{\text{pll}}$	PLL operating current • PLL at 96 MHz ( $f_{\text{osc\_hi\_1}} = 8$ MHz, $f_{\text{pll\_ref}} = 2$ MHz, VDIV multiplier = 48)	—	1060	—	$\mu\text{A}$	9	
		—	600	—	$\mu\text{A}$	9	
$f_{\text{pll\_ref}}$	PLL reference frequency range	2.0	—	4.0	MHz		
$J_{\text{cyc\_pll}}$	PLL period jitter (RMS) • $f_{\text{vco}} = 48$ MHz • $f_{\text{vco}} = 100$ MHz	—	120	—	ps	10	
		—	50	—	ps		
$J_{\text{acc\_pll}}$	PLL accumulated jitter over 1 $\mu\text{s}$ (RMS) • $f_{\text{vco}} = 48$ MHz • $f_{\text{vco}} = 100$ MHz	—	1350	—	ps	10	
		—	600	—	ps		
$D_{\text{lock}}$	Lock entry frequency tolerance	$\pm 1.49$	—	$\pm 2.98$	%		
$D_{\text{unl}}$	Lock exit frequency tolerance	$\pm 4.47$	—	$\pm 5.97$	%		
$t_{\text{pll\_lock}}$	Lock detector detection time	—	—	$150 \times 10^{-6} + 1075(1/f_{\text{pll\_ref}})$	s	11	

- This parameter is measured with the internal reference (slow clock) being used as a reference to the FLL (FEI clock mode).
- The deviation is relative to the factory trimmed frequency at nominal  $V_{\text{DD}}$  and 25 °C,  $f_{\text{ints\_ft}}$ .
- These typical values listed are with the slow internal reference clock (FEI) using factory trim and DMX32 = 0.
- The resulting system clock frequencies must not exceed their maximum specified values. The DCO frequency deviation ( $\Delta f_{\text{dco\_t}}$ ) over voltage and temperature must be considered.
- These typical values listed are with the slow internal reference clock (FEI) using factory trim and DMX32 = 1.
- The resulting clock frequency must not exceed the maximum specified clock frequency of the device.
- This specification is based on standard deviation (RMS) of period or frequency.
- This specification applies to any time the FLL reference source or reference divider is changed, trim value is changed, DMX32 bit is changed, DRS bits are changed, or changing from FLL disabled (BLPE, BLPI) to FLL enabled (FEI, FEE, FBE, FBI). If a crystal/resonator is being used as the reference, this specification assumes it is already running.
- Excludes any oscillator currents that are also consuming power while PLL is in operation.
- This specification was obtained using a Freescale developed PCB. PLL jitter is dependent on the noise characteristics of each PCB and results will vary.
- This specification applies to any time the PLL VCO divider or reference divider is changed, or changing from PLL disabled (BLPE, BLPI) to PLL enabled (PBE, PEE). If a crystal/resonator is being used as the reference, this specification assumes it is already running.

## 6.3.2 Oscillator electrical specifications

This section provides the electrical characteristics of the module.

### 6.3.2.1 Oscillator DC electrical specifications

Table 13. Oscillator DC electrical specifications

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
$V_{DD}$	Supply voltage	1.71	—	3.6	V	
$I_{DDOSC}$	Supply current — low-power mode (HGO=0) <ul style="list-style-type: none"> <li>• 32 kHz</li> <li>• 4 MHz</li> <li>• 8 MHz (RANGE=01)</li> <li>• 16 MHz</li> <li>• 24 MHz</li> <li>• 32 MHz</li> </ul>	—	500	—	nA	1
		—	200	—	$\mu$ A	
		—	300	—	$\mu$ A	
		—	950	—	$\mu$ A	
		—	1.2	—	mA	
		—	1.5	—	mA	
$I_{DDOSC}$	Supply current — high gain mode (HGO=1) <ul style="list-style-type: none"> <li>• 32 kHz</li> <li>• 4 MHz</li> <li>• 8 MHz (RANGE=01)</li> <li>• 16 MHz</li> <li>• 24 MHz</li> <li>• 32 MHz</li> </ul>	—	25	—	$\mu$ A	1
		—	400	—	$\mu$ A	
		—	500	—	$\mu$ A	
		—	2.5	—	mA	
		—	3	—	mA	
		—	4	—	mA	
$C_x$	EXTAL load capacitance	—	—	—		2, 3
$C_y$	XTAL load capacitance	—	—	—		2, 3
$R_F$	Feedback resistor — low-frequency, low-power mode (HGO=0)	—	—	—	M $\Omega$	2, 4
	Feedback resistor — low-frequency, high-gain mode (HGO=1)	—	10	—	M $\Omega$	
	Feedback resistor — high-frequency, low-power mode (HGO=0)	—	—	—	M $\Omega$	
	Feedback resistor — high-frequency, high-gain mode (HGO=1)	—	1	—	M $\Omega$	

Table continues on the next page...

**Table 13. Oscillator DC electrical specifications (continued)**

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
R <sub>S</sub>	Series resistor — low-frequency, low-power mode (HGO=0)	—	—	—	kΩ	
	Series resistor — low-frequency, high-gain mode (HGO=1)	—	200	—	kΩ	
	Series resistor — high-frequency, low-power mode (HGO=0)	—	—	—	kΩ	
	Series resistor — high-frequency, high-gain mode (HGO=1)	—	0	—	kΩ	
V <sub>pp</sub> <sup>5</sup>	Peak-to-peak amplitude of oscillation (oscillator mode) — low-frequency, low-power mode (HGO=0)	—	0.6	—	V	
	Peak-to-peak amplitude of oscillation (oscillator mode) — low-frequency, high-gain mode (HGO=1)	—	V <sub>DD</sub>	—	V	
	Peak-to-peak amplitude of oscillation (oscillator mode) — high-frequency, low-power mode (HGO=0)	—	0.6	—	V	
	Peak-to-peak amplitude of oscillation (oscillator mode) — high-frequency, high-gain mode (HGO=1)	—	V <sub>DD</sub>	—	V	

1. V<sub>DD</sub>=3.3 V, Temperature =25 °C
2. See crystal or resonator manufacturer's recommendation
3. C<sub>x</sub>,C<sub>y</sub> can be provided by using the integrated capacitors when the low frequency oscillator (RANGE = 00) is used. For all other cases external capacitors must be used..
4. When low power mode is selected, R<sub>F</sub> is integrated and must not be attached externally.
5. The EXTAL and XTAL pins should only be connected to required oscillator components and must not be connected to any other devices.

### 6.3.2.2 Oscillator frequency specifications

**Table 14. Oscillator frequency specifications**

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
f <sub>osc_lo</sub>	Oscillator crystal or resonator frequency — low frequency mode (MCG_C2[RANGE]=00)	32	—	40	kHz	
f <sub>osc_hi_1</sub>	Oscillator crystal or resonator frequency — high frequency mode (low range) (MCG_C2[RANGE]=01)	3	—	8	MHz	
f <sub>osc_hi_2</sub>	Oscillator crystal or resonator frequency — high frequency mode (high range) (MCG_C2[RANGE]=1x)	8	—	32	MHz	
f <sub>ec_extal</sub>	Input clock frequency (external clock mode)	—	—	48	MHz	1, 2
t <sub>dc_extal</sub>	Input clock duty cycle (external clock mode)	40	50	60	%	

Table continues on the next page...

## 6.5 Security and integrity modules

There are no specifications necessary for the device's security and integrity modules.

## 6.6 Analog

### 6.6.1 ADC electrical specifications

All ADC channels meet the 12-bit single-ended accuracy specifications.

#### 6.6.1.1 12-bit ADC operating conditions

Table 19. 12-bit ADC operating conditions

Symbol	Description	Conditions	Min.	Typ. <sup>1</sup>	Max.	Unit	Notes
$V_{DDA}$	Supply voltage	Absolute	1.71	—	3.6	V	
$\Delta V_{DDA}$	Supply voltage	Delta to $V_{DD}$ ( $V_{DD} - V_{DDA}$ )	-100	0	+100	mV	2
$\Delta V_{SSA}$	Ground voltage	Delta to $V_{SS}$ ( $V_{SS} - V_{SSA}$ )	-100	0	+100	mV	2
$V_{REFH}$	ADC reference voltage high		1.13	$V_{DDA}$	$V_{DDA}$	V	3
$V_{REFL}$	ADC reference voltage low		$V_{SSA}$	$V_{SSA}$	$V_{SSA}$	V	3
$V_{ADIN}$	Input voltage		$V_{REFL}$	—	$V_{REFH}$	V	
$C_{ADIN}$	Input capacitance	• 8-/10-/12-bit modes	—	4	5	pF	
$R_{ADIN}$	Input resistance		—	2	5	k $\Omega$	
$R_{AS}$	Analog source resistance	12-bit modes $f_{ADCK} < 4$ MHz	—	—	5	k $\Omega$	4
$f_{ADCK}$	ADC conversion clock frequency	$\leq$ 12-bit mode	1.0	—	18.0	MHz	5
$C_{rate}$	ADC conversion rate	$\leq$ 12 bit modes No ADC hardware averaging Continuous conversions enabled, subsequent conversion time	20.000	—	818.330	Ksps	6

1. Typical values assume  $V_{DDA} = 3.0$  V, Temp = 25 °C,  $f_{ADCK} = 1.0$  MHz unless otherwise stated. Typical values are for reference only and are not tested in production.
2. DC potential difference.
3. For packages without dedicated VREFH and VREFL pins,  $V_{REFH}$  is internally tied to  $V_{DDA}$ , and  $V_{REFL}$  is internally tied to  $V_{SSA}$ .
4. This resistance is external to MCU. The analog source resistance must be kept as low as possible to achieve the best results. The results in this data sheet were derived from a system which has < 8  $\Omega$  analog source resistance. The  $R_{AS}/C_{AS}$  time constant should be kept to < 1ns.
5. To use the maximum ADC conversion clock frequency, the ADHSC bit must be set and the ADLPC bit must be clear.
6. For guidelines and examples of conversion rate calculation, download the [ADC calculator tool](#)

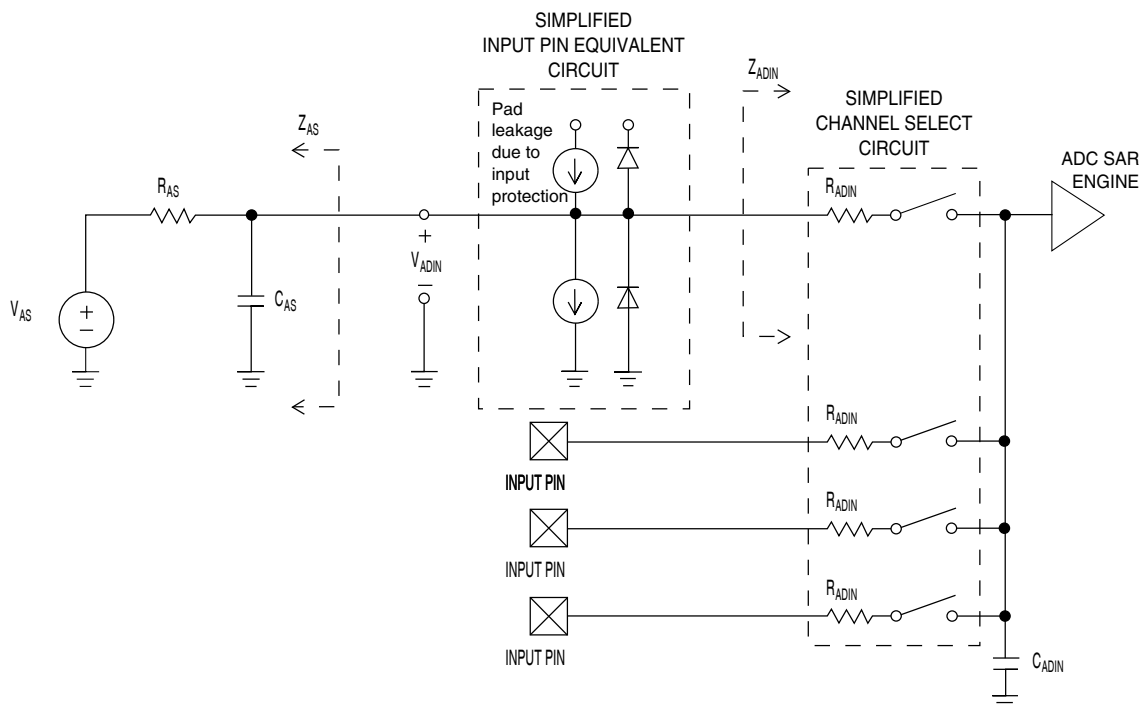


Figure 6. ADC input impedance equivalency diagram

### 6.6.1.2 12-bit ADC electrical characteristics

Table 20. 12-bit ADC characteristics ( $V_{REFH} = V_{DDA}$ ,  $V_{REFL} = V_{SSA}$ )

Symbol	Description	Conditions <sup>1</sup>	Min.	Typ. <sup>2</sup>	Max.	Unit	Notes
$I_{DDA\_ADC}$	Supply current		0.215	—	1.7	mA	3
$f_{ADACK}$	ADC asynchronous clock source	• ADLPC = 1, ADHSC = 0	1.2	2.4	3.9	MHz	$t_{ADACK} = 1/f_{ADACK}$
		• ADLPC = 1, ADHSC = 1	2.4	4.0	6.1	MHz	
		• ADLPC = 0, ADHSC = 0	3.0	5.2	7.3	MHz	
		• ADLPC = 0, ADHSC = 1	4.4	6.2	9.5	MHz	
	Sample Time	See Reference Manual chapter for sample times					
TUE	Total unadjusted error	• 12-bit modes • <12-bit modes	— —	$\pm 4$ $\pm 1.4$	$\pm 6.8$ $\pm 2.1$	LSB <sup>4</sup>	5
DNL	Differential non-linearity	• 12-bit modes • <12-bit modes	— —	$\pm 0.7$ $\pm 0.2$	-1.1 to +1.9 -0.3 to 0.5	LSB <sup>4</sup>	5
INL	Integral non-linearity	• 12-bit modes • <12-bit modes	— —	$\pm 1.0$ $\pm 0.5$	-2.7 to +1.9 -0.7 to +0.5	LSB <sup>4</sup>	5
$E_{FS}$	Full-scale error	• 12-bit modes • <12-bit modes	— —	-4 -1.4	-5.4 -1.8	LSB <sup>4</sup>	$V_{ADIN} = V_{DDA}$ 5

Table continues on the next page...

## 6.7 Timers

See General switching specifications.

## 6.8 Communication interfaces

### 6.8.1 USB electrical specifications

The USB electricals for the USB On-the-Go module conform to the standards documented by the Universal Serial Bus Implementers Forum. For the most up-to-date standards, visit <http://www.usb.org>.

### 6.8.2 USB VREG electrical specifications

Table 22. USB VREG electrical specifications

Symbol	Description	Min.	Typ. <sup>1</sup>	Max.	Unit	Notes
VREGIN	Input supply voltage	2.7	—	5.5	V	
I <sub>DDon</sub>	Quiescent current — Run mode, load current equal zero, input supply (VREGIN) > 3.6 V	—	120	186	μA	
I <sub>DDstby</sub>	Quiescent current — Standby mode, load current equal zero	—	1.1	10	μA	
I <sub>DDoff</sub>	Quiescent current — Shutdown mode <ul style="list-style-type: none"> <li>VREGIN = 5.0 V and temperature=25C</li> <li>Across operating voltage and temperature</li> </ul>	—	650	—	nA	
		—	—	4	μA	
I <sub>LOADrun</sub>	Maximum load current — Run mode	—	—	120	mA	
I <sub>LOADstby</sub>	Maximum load current — Standby mode	—	—	1	mA	
V <sub>Reg33out</sub>	Regulator output voltage — Input supply (VREGIN) > 3.6 V <ul style="list-style-type: none"> <li>Run mode</li> <li>Standby mode</li> </ul>	3	3.3	3.6	V	
		2.1	2.8	3.6	V	
V <sub>Reg33out</sub>	Regulator output voltage — Input supply (VREGIN) < 3.6 V, pass-through mode	2.1	—	3.6	V	2
C <sub>OUT</sub>	External output capacitor	1.76	2.2	8.16	μF	
ESR	External output capacitor equivalent series resistance	1	—	100	mΩ	
I <sub>LIM</sub>	Short circuit current	—	290	—	mA	

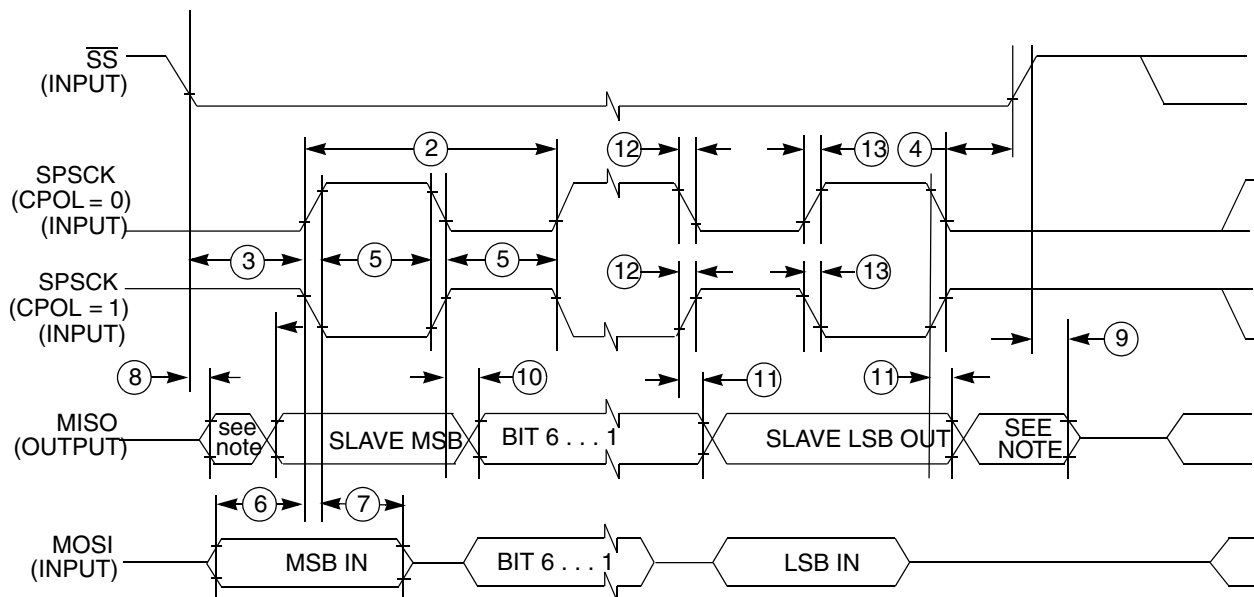
1. Typical values assume VREGIN = 5.0 V, Temp = 25 °C unless otherwise stated.

2. Operating in pass-through mode: regulator output voltage equal to the input voltage minus a drop proportional to I<sub>Load</sub>.

**Table 26. SPI slave mode timing on slew rate enabled pads (continued)**

Num.	Symbol	Description	Min.	Max.	Unit	Note
2	$t_{SPSCK}$	SPSCK period	$4 \times t_{periph}$	—	ns	2
3	$t_{Lead}$	Enable lead time	1	—	$t_{periph}$	—
4	$t_{Lag}$	Enable lag time	1	—	$t_{periph}$	—
5	$t_{WSPSCK}$	Clock (SPSCK) high or low time	$t_{periph} - 30$	—	ns	—
6	$t_{SU}$	Data setup time (inputs)	2	—	ns	—
7	$t_{HI}$	Data hold time (inputs)	7	—	ns	—
8	$t_a$	Slave access time	—	$t_{periph}$	ns	3
9	$t_{dis}$	Slave MISO disable time	—	$t_{periph}$	ns	4
10	$t_v$	Data valid (after SPSCK edge)	—	122	ns	—
11	$t_{HO}$	Data hold time (outputs)	0	—	ns	—
12	$t_{RI}$	Rise time input	—	$t_{periph} - 25$	ns	—
	$t_{FI}$	Fall time input				
13	$t_{RO}$	Rise time output	—	36	ns	—
	$t_{FO}$	Fall time output				

- For SPI0  $f_{periph}$  is the bus clock ( $f_{BUS}$ ). For SPI1  $f_{periph}$  is the system clock ( $f_{SYS}$ ).
- $t_{periph} = 1/f_{periph}$
- Time to data active from high-impedance state
- Hold time to high-impedance state



NOTE: Not defined!

**Figure 11. SPI slave mode timing (CPHA = 0)**



## 8 Pinout

### 8.1 KL24 Signal Multiplexing and Pin Assignments

The following table shows the signals available on each pin and the locations of these pins on the devices supported by this document. The Port Control Module is responsible for selecting which ALT functionality is available on each pin.

80 LQFP	64 LQFP	48 QFN	32 QFN	Pin Name	Default	ALT0	ALT1	ALT2	ALT3	ALT4	ALT5	ALT6	ALT7
1	1	—	1	PTE0	DISABLED		PTE0		UART1_TX	RTC_CLKOUT	CMPO_OUT	I2C1_SDA	
2	2	—	—	PTE1	DISABLED		PTE1	SPI1_MOSI	UART1_RX		SPI1_MISO	I2C1_SCL	
3	—	—	—	PTE2	DISABLED		PTE2	SPI1_SCK					
4	—	—	—	PTE3	DISABLED		PTE3	SPI1_MISO			SPI1_MOSI		
5	—	—	—	PTE4	DISABLED		PTE4	SPI1_PCS0					
6	—	—	—	PTE5	DISABLED		PTE5						
7	3	1	—	VDD	VDD	VDD							
8	4	2	2	VSS	VSS	VSS							
9	5	3	3	USB0_DP	USB0_DP	USB0_DP							
10	6	4	4	USB0_DM	USB0_DM	USB0_DM							
11	7	5	5	VOUT33	VOUT33	VOUT33							
12	8	6	6	VREGIN	VREGIN	VREGIN							
13	9	7	—	PTE20	ADC0_SE0	ADC0_SE0	PTE20		TPM1_CH0	UART0_TX			
14	10	8	—	PTE21	ADC0_SE4a	ADC0_SE4a	PTE21		TPM1_CH1	UART0_RX			
15	11	—	—	PTE22	ADC0_SE3	ADC0_SE3	PTE22		TPM2_CH0	UART2_TX			
16	12	—	—	PTE23	ADC0_SE7a	ADC0_SE7a	PTE23		TPM2_CH1	UART2_RX			
17	13	9	7	VDDA	VDDA	VDDA							
18	14	10	—	VREFH	VREFH	VREFH							
19	15	11	—	VREFL	VREFL	VREFL							
20	16	12	8	VSSA	VSSA	VSSA							
21	17	13	—	PTE29	CMPO_IN5/ ADC0_SE4b	CMPO_IN5/ ADC0_SE4b	PTE29		TPM0_CH2	TPM_CLKIN0			
22	18	14	9	PTE30	ADC0_SE23/ CMPO_IN4	ADC0_SE23/ CMPO_IN4	PTE30		TPM0_CH3	TPM_CLKIN1			
23	19	—	—	PTE31	DISABLED		PTE31		TPM0_CH4				
24	20	15	—	PTE24	DISABLED		PTE24		TPM0_CH0		I2C0_SCL		
25	21	16	—	PTE25	DISABLED		PTE25		TPM0_CH1		I2C0_SDA		
26	22	17	10	PTA0	SWD_CLK		PTA0		TPM0_CH5				SWD_CLK
27	23	18	11	PTA1	DISABLED		PTA1	UART0_RX	TPM2_CH0				
28	24	19	12	PTA2	DISABLED		PTA2	UART0_TX	TPM2_CH1				

80 LQFP	64 LQFP	48 QFN	32 QFN	Pin Name	Default	ALT0	ALT1	ALT2	ALT3	ALT4	ALT5	ALT6	ALT7
64	52	40	28	PTC7	CMPO_IN1	CMPO_IN1	PTC7	SPI0_MISO			SPI0_MOSI		
65	53	—	—	PTC8	CMPO_IN2	CMPO_IN2	PTC8	I2C0_SCL	TPM0_CH4				
66	54	—	—	PTC9	CMPO_IN3	CMPO_IN3	PTC9	I2C0_SDA	TPM0_CH5				
67	55	—	—	PTC10	DISABLED		PTC10	I2C1_SCL					
68	56	—	—	PTC11	DISABLED		PTC11	I2C1_SDA					
69	—	—	—	PTC12	DISABLED		PTC12			TPM_CLKIN0			
70	—	—	—	PTC13	DISABLED		PTC13			TPM_CLKIN1			
71	—	—	—	PTC16	DISABLED		PTC16						
72	—	—	—	PTC17	DISABLED		PTC17						
73	57	41	—	PTD0	DISABLED		PTD0	SPI0_PCS0		TPM0_CH0			
74	58	42	—	PTD1	ADC0_SE5b	ADC0_SE5b	PTD1	SPI0_SCK		TPM0_CH1			
75	59	43	—	PTD2	DISABLED		PTD2	SPI0_MOSI	UART2_RX	TPM0_CH2	SPI0_MISO		
76	60	44	—	PTD3	DISABLED		PTD3	SPI0_MISO	UART2_TX	TPM0_CH3	SPI0_MOSI		
77	61	45	29	PTD4/ LLWU_P14	DISABLED		PTD4/ LLWU_P14	SPI1_PCS0	UART2_RX	TPM0_CH4			
78	62	46	30	PTD5	ADC0_SE6b	ADC0_SE6b	PTD5	SPI1_SCK	UART2_TX	TPM0_CH5			
79	63	47	31	PTD6/ LLWU_P15	ADC0_SE7b	ADC0_SE7b	PTD6/ LLWU_P15	SPI1_MOSI	UART0_RX		SPI1_MISO		
80	64	48	32	PTD7	DISABLED		PTD7	SPI1_MISO	UART0_TX		SPI1_MOSI		

## 8.2 KL24 Pinouts

The below figures show the pinout diagrams for the devices supported by this document. Many signals may be multiplexed onto a single pin. To determine what signals can be used on which pin, see the previous section.

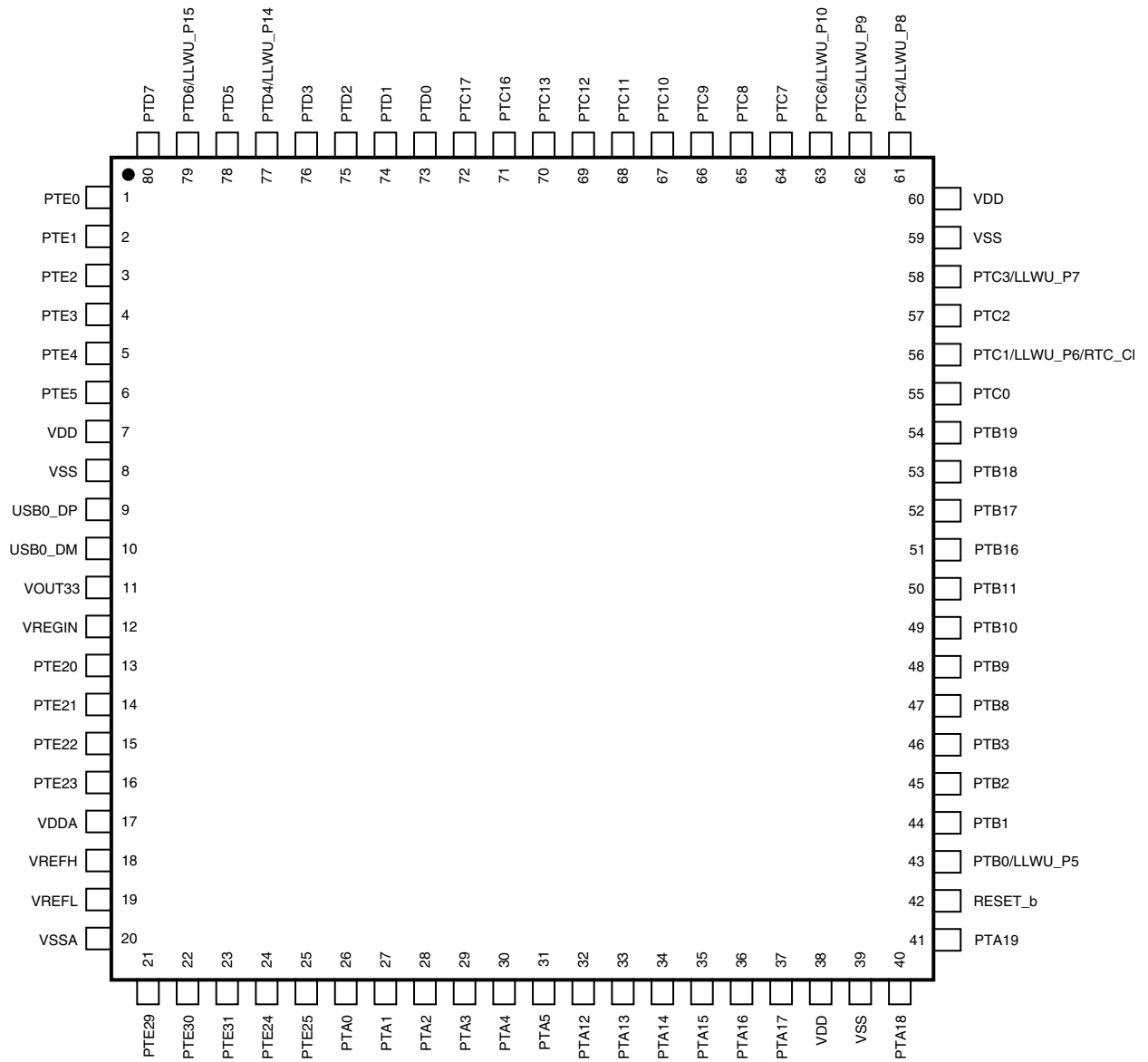


Figure 13. KL24 80-pin LQFP pinout diagram

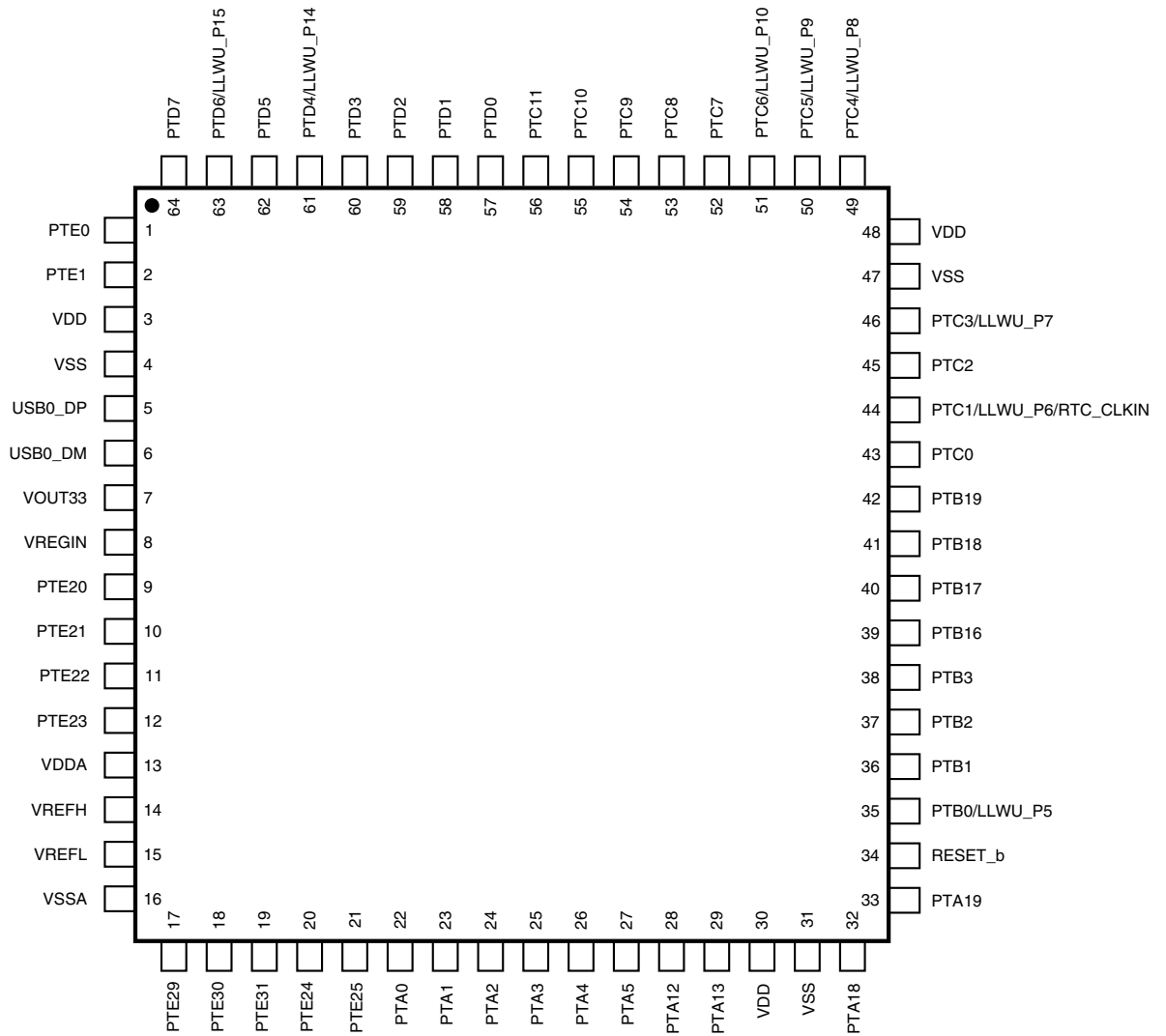


Figure 14. KL24 64-pin LQFP pinout diagram

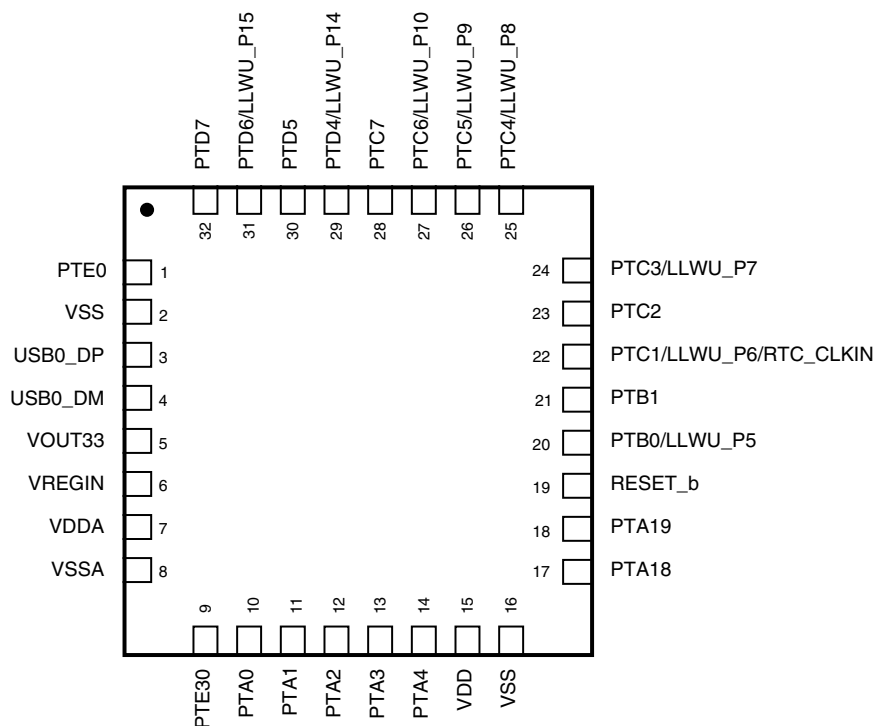


Figure 16. KL24 32-pin QFN pinout diagram

## 9 Revision History

The following table provides a revision history for this document.

**Table 27. Revision History**

Rev. No.	Date	Substantial Changes
1	7/2012	Initial NDA release.
2	9/2012	Completed all the TBDs, initial public release.
3	9/2012	Updated Signal Multiplexing and Pin Assignments table to add UART2 signals.