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#### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

#### Applications of "[Embedded - Microcontrollers](#)"

##### Details

Product Status	Active
Core Processor	ARM® Cortex®-M0+
Core Size	32-Bit Single-Core
Speed	48MHz
Connectivity	I²C, LINbus, SPI, UART/USART, USB, USB OTG
Peripherals	Brown-out Detect/Reset, DMA, LVD, POR, PWM, WDT
Number of I/O	50
Program Memory Size	64KB (64K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	8K x 8
Voltage - Supply (Vcc/Vdd)	1.71V ~ 3.6V
Data Converters	A/D 14x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	64-LQFP
Supplier Device Package	64-LQFP (10x10)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/nxp-semiconductors/mkl24z64vlh4">https://www.e-xfl.com/product-detail/nxp-semiconductors/mkl24z64vlh4</a>

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# 1 Ordering parts

## 1.1 Determining valid orderable parts

Valid orderable part numbers are provided on the web. To determine the orderable part numbers for this device, go to [www.freescale.com](http://www.freescale.com) and perform a part number search for the following device numbers: PKL24 and MKL24

# 2 Part identification

## 2.1 Description

Part numbers for the chip have fields that identify the specific part. You can use the values of these fields to determine the specific part you have received.

## 2.2 Format

Part numbers for this device have the following format:

Q KL## A FFF R T PP CC N

## 2.3 Fields

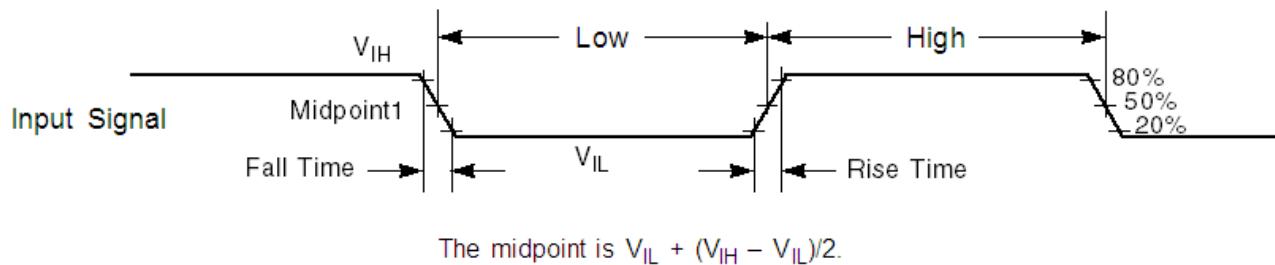
This table lists the possible values for each field in the part number (not all combinations are valid):

Field	Description	Values
Q	Qualification status	<ul style="list-style-type: none"> <li>M = Fully qualified, general market flow</li> <li>P = Prequalification</li> </ul>
KL##	Kinetis family	<ul style="list-style-type: none"> <li>KL24</li> </ul>
A	Key attribute	<ul style="list-style-type: none"> <li>Z = Cortex-M0+</li> </ul>
FFF	Program flash memory size	<ul style="list-style-type: none"> <li>32 = 32 KB</li> <li>64 = 64 KB</li> </ul>
R	Silicon revision	<ul style="list-style-type: none"> <li>(Blank) = Main</li> <li>A = Revision after main</li> </ul>
T	Temperature range (°C)	<ul style="list-style-type: none"> <li>V = -40 to 105</li> </ul>

*Table continues on the next page...*

## 5.1 AC electrical characteristics

Unless otherwise specified, propagation delays are measured from the 50% to the 50% point, and rise and fall times are measured at the 20% and 80% points, as shown in the following figure.



**Figure 1. Input signal measurement reference**

All digital I/O switching characteristics, unless otherwise specified, assumes:

1. output pins
  - have  $C_L=30\text{pF}$  loads,
  - are slew rate disabled, and
  - are normal drive strength

## 5.2 Nonswitching electrical specifications

### 5.2.1 Voltage and current operating requirements

**Table 1. Voltage and current operating requirements**

Symbol	Description	Min.	Max.	Unit	Notes
$V_{DD}$	Supply voltage	1.71	3.6	V	
$V_{DDA}$	Analog supply voltage	1.71	3.6	V	
$V_{DD} - V_{DDA}$	$V_{DD}$ -to- $V_{DDA}$ differential voltage	-0.1	0.1	V	
$V_{SS} - V_{SSA}$	$V_{SS}$ -to- $V_{SSA}$ differential voltage	-0.1	0.1	V	
$V_{IH}$	Input high voltage <ul style="list-style-type: none"> <li>• <math>2.7 \text{ V} \leq V_{DD} \leq 3.6 \text{ V}</math></li> <li>• <math>1.7 \text{ V} \leq V_{DD} \leq 2.7 \text{ V}</math></li> </ul>	$0.7 \times V_{DD}$ $0.75 \times V_{DD}$	— —	V V	
$V_{IL}$	Input low voltage <ul style="list-style-type: none"> <li>• <math>2.7 \text{ V} \leq V_{DD} \leq 3.6 \text{ V}</math></li> <li>• <math>1.7 \text{ V} \leq V_{DD} \leq 2.7 \text{ V}</math></li> </ul>	— —	$0.35 \times V_{DD}$ $0.3 \times V_{DD}$	V V	

*Table continues on the next page...*

**Table 2. V<sub>DD</sub> supply LVD and POR operating requirements (continued)**

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
V <sub>LVW1L</sub>	Low-voltage warning thresholds — low range • Level 1 falling (LVWV=00)	1.74	1.80	1.86	V	1
V <sub>LVW2L</sub>	• Level 2 falling (LVWV=01)	1.84	1.90	1.96	V	
V <sub>LVW3L</sub>	• Level 3 falling (LVWV=10)	1.94	2.00	2.06	V	
V <sub>LVW4L</sub>	• Level 4 falling (LVWV=11)	2.04	2.10	2.16	V	
V <sub>HYSL</sub>	Low-voltage inhibit reset/recover hysteresis — low range	—	±40	—	mV	
V <sub>BG</sub>	Bandgap voltage reference	0.97	1.00	1.03	V	
t <sub>LPO</sub>	Internal low power oscillator period — factory trimmed	900	1000	1100	μs	

1. Rising thresholds are falling threshold + hysteresis voltage

### 5.2.3 Voltage and current operating behaviors

**Table 3. Voltage and current operating behaviors**

Symbol	Description	Min.	Max.	Unit	Notes
V <sub>OH</sub>	Output high voltage — Normal drive pad • 2.7 V ≤ V <sub>DD</sub> ≤ 3.6 V, I <sub>OH</sub> = -5 mA • 1.71 V ≤ V <sub>DD</sub> ≤ 2.7 V, I <sub>OH</sub> = -1.5 mA	V <sub>DD</sub> – 0.5 V <sub>DD</sub> – 0.5	— —	V V	1
V <sub>OH</sub>	Output high voltage — High drive pad • 2.7 V ≤ V <sub>DD</sub> ≤ 3.6 V, I <sub>OH</sub> = -18 mA • 1.71 V ≤ V <sub>DD</sub> ≤ 2.7 V, I <sub>OH</sub> = -6 mA	V <sub>DD</sub> – 0.5 V <sub>DD</sub> – 0.5	— —	V V	1
I <sub>OHT</sub>	Output high current total for all ports	—	100	mA	
V <sub>OL</sub>	Output low voltage — Normal drive pad • 2.7 V ≤ V <sub>DD</sub> ≤ 3.6 V, I <sub>OL</sub> = 5 mA • 1.71 V ≤ V <sub>DD</sub> ≤ 2.7 V, I <sub>OL</sub> = 1.5 mA	— —	0.5 0.5	V V	1
V <sub>OL</sub>	Output low voltage — High drive pad • 2.7 V ≤ V <sub>DD</sub> ≤ 3.6 V, I <sub>OL</sub> = 18 mA • 1.71 V ≤ V <sub>DD</sub> ≤ 2.7 V, I <sub>OL</sub> = 6 mA	— —	0.5 0.5	V V	1
I <sub>OLT</sub>	Output low current total for all ports	—	100	mA	
I <sub>IN</sub>	Input leakage current (per pin) for full temperature range	—	1	μA	2
I <sub>IN</sub>	Input leakage current (per pin) at 25 °C	—	0.025	μA	2
I <sub>IN</sub>	Input leakage current (total all pins) for full temperature range	—	65	μA	2
I <sub>OZ</sub>	Hi-Z (off-state) leakage current (per pin)	—	1	μA	

Table continues on the next page...

**Table 5. Power consumption operating behaviors (continued)**

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
I <sub>DD_VLPR</sub>	Very low power run mode current - 4 MHz core / 0.8 MHz bus and flash, all peripheral clocks enabled, code of while(1) loop executing from flash • at 3.0 V	—	300	745	µA	5, 4
I <sub>DD_VLPW</sub>	Very low power wait mode current - core disabled / 4 MHz system / 0.8 MHz bus / flash disabled (flash doze enabled), all peripheral clocks disabled • at 3.0 V	—	135	496	µA	5
I <sub>DD_STOP</sub>	Stop mode current at 3.0 V at 25 °C at 50 °C at 70 °C at 85 °C at 105 °C	— — — — —	345 357 392 438 551	490 827 869 927 1065	µA	
I <sub>DD_VLPS</sub>	Very-low-power stop mode current at 3.0 V at 25 °C at 50 °C at 70 °C at 85 °C at 105 °C	— — — — —	4.4 10 20 37 81	16 35 50 112 201	µA	
I <sub>DD_LLS</sub>	Low leakage stop mode current at 3.0 V at 25 °C at 50 °C at 70 °C at 85 °C at 105 °C	— — — — —	1.9 3.6 6.5 13 30	3.7 39 43 49 69	µA	
I <sub>DD_VLLS3</sub>	Very low-leakage stop mode 3 current at 3.0 V at 25 °C at 50 °C at 70 °C at 85 °C at 105 °C	— — — — —	1.4 2.5 5.1 9.2 21	3.2 19 21 26 38	µA	
I <sub>DD_VLLS1</sub>	Very low-leakage stop mode 1 current at 3.0V at 25°C at 50°C at 70°C at 85°C at 105°C	— — — — —	0.7 1.3 2.3 5.1 13	1.4 13 14 17 25	µA	

Table continues on the next page...

**Table 5. Power consumption operating behaviors (continued)**

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
I <sub>DD_VLLS0</sub>	Very low-leakage stop mode 0 current (SMC_STOPCTRL[PORPO] = 0) at 3.0 V at 25 °C at 50 °C at 70 °C at 85 °C at 105 °C	—	381	943	nA	
		—	956	11760		
		—	2370	13260		
		—	4800	15700		
		—	12410	23480		
I <sub>DD_VLLS0</sub>	Very low-leakage stop mode 0 current (SMC_STOPCTRL[PORPO] = 1) at 3.0 V at 25 °C at 50 °C at 70 °C at 85 °C at 105 °C	—	176	860	nA	6
		—	760	3577		
		—	2120	11660		
		—	4500	18450		
		—	12130	22441		

1. The analog supply current is the sum of the active or disabled current for each of the analog modules on the device. See each module's specification for its supply current.
2. MCG configured for PEE mode. CoreMark benchmark compiled using Keil 4.54 with optimization level 3, optimized for time.
3. MCG configured for FEI mode.
4. Incremental current consumption from peripheral activity is not included.
5. MCG configured for BLPI mode.
6. No brownout

**Table 6. Low power mode peripheral adders — typical value**

Symbol	Description	Temperature (°C)						Unit
		-40	25	50	70	85	105	
I <sub>IREFSTEN4MHz</sub>	4 MHz internal reference clock (IRC) adder. Measured by entering STOP or VLPS mode with 4 MHz IRC enabled.	56	56	56	56	56	56	µA
I <sub>IREFSTEN32KHz</sub>	32 kHz internal reference clock (IRC) adder. Measured by entering STOP mode with the 32 kHz IRC enabled.	52	52	52	52	52	52	µA
I <sub>EREFSTEN4MHz</sub>	External 4MHz crystal clock adder. Measured by entering STOP or VLPS mode with the crystal enabled.	206	228	237	245	251	258	uA

*Table continues on the next page...*

2.  $V_{DD} = 3.3$  V,  $T_A = 25$  °C,  $f_{OSC} = 8$  MHz (crystal),  $f_{SYS} = 48$  MHz,  $f_{BUS} = 48$  MHz
3. Specified according to Annex D of IEC Standard 61967-2, *Measurement of Radiated Emissions—TEM Cell and Wideband TEM Cell Method*

## 5.2.7 Designing with radiated emissions in mind

To find application notes that provide guidance on designing your system to minimize interference from radiated emissions:

1. Go to [www.freescale.com](http://www.freescale.com).
2. Perform a keyword search for “EMC design.”

## 5.2.8 Capacitance attributes

**Table 8. Capacitance attributes**

Symbol	Description	Min.	Max.	Unit
$C_{IN\_A}$	Input capacitance: analog pins	—	7	pF
$C_{IN\_D}$	Input capacitance: digital pins	—	7	pF

## 5.3 Switching specifications

### 5.3.1 Device clock specifications

Symbol	Description	Min.	Max.	Unit	Notes
Normal run mode					
$f_{SYS}$	System and core clock	—	48	MHz	
$f_{BUS}$	Bus clock	—	24	MHz	
$f_{FLASH}$	Flash clock	—	24	MHz	
$f_{SYS\_USB}$	System and core clock when Full Speed USB in operation	20	—	MHz	
$f_{LPTMR}$	LPTMR clock	—	24	MHz	
VLPR mode <sup>1</sup>					
$f_{SYS}$	System and core clock	—	4	MHz	
$f_{BUS}$	Bus clock	—	1	MHz	
$f_{FLASH}$	Flash clock	—	1	MHz	
$f_{LPTMR}$	LPTMR clock	—	24	MHz	
$f_{ERCLK}$	External reference clock	—	16	MHz	
$f_{LPTMR\_pin}$	LPTMR clock	—	24	MHz	

Table continues on the next page...

## General

Symbol	Description	Min.	Max.	Unit	Notes
$f_{LPTMR\_ERCLK}$	LPTMR external reference clock	—	16	MHz	
$f_{osc\_hi\_2}$	Oscillator crystal or resonator frequency — high frequency mode (high range) (MCG_C2[RANGE]=1x)	—	16	MHz	
$f_{TPM}$	TPM asynchronous clock	—	8	MHz	
$f_{UART0}$	UART0 asynchronous clock	—	8	MHz	

1. The frequency limitations in VLPR mode here override any frequency specification listed in the timing specification for any other module.

## 5.3.2 General Switching Specifications

These general purpose specifications apply to all signals configured for GPIO, UART, and I<sup>2</sup>C signals.

Symbol	Description	Min.	Max.	Unit	Notes
	GPIO pin interrupt pulse width (digital glitch filter disabled) — Synchronous path	1.5	—	Bus clock cycles	<a href="#">1</a>
	External RESET and NMI pin interrupt pulse width — Asynchronous path	100	—	ns	<a href="#">2</a>
	GPIO pin interrupt pulse width — Asynchronous path	16	—	ns	<a href="#">2</a>
	Port rise and fall time	—	36	ns	<a href="#">3</a>

1. The greater synchronous and asynchronous timing must be met.
2. This is the shortest pulse that is guaranteed to be recognized.
3. 75 pF load

## 5.4 Thermal specifications

### 5.4.1 Thermal operating requirements

Table 9. Thermal operating requirements

Symbol	Description	Min.	Max.	Unit
$T_J$	Die junction temperature	-40	125	°C
$T_A$	Ambient temperature	-40	105	°C

## 6.2 System modules

There are no specifications necessary for the device's system modules.

## 6.3 Clock modules

### 6.3.1 MCG specifications

Table 12. MCG specifications

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
$f_{ints\_ft}$	Internal reference frequency (slow clock) — factory trimmed at nominal $V_{DD}$ and 25 °C	—	32.768	—	kHz	
$f_{ints\_t}$	Internal reference frequency (slow clock) — user trimmed	31.25	—	39.0625	kHz	
$\Delta f_{dco\_res\_t}$	Resolution of trimmed average DCO output frequency at fixed voltage and temperature — using SCTRIM and SCFTRIM	—	± 0.3	± 0.6	% $f_{dco}$	1
$\Delta f_{dco\_t}$	Total deviation of trimmed average DCO output frequency over voltage and temperature	—	+0.5/-0.7	± 3	% $f_{dco}$	1, 2
$\Delta f_{dco\_t}$	Total deviation of trimmed average DCO output frequency over fixed voltage and temperature range of 0 - 70 °C	—	± 0.4	± 1.5	% $f_{dco}$	1, 2
$f_{intf\_ft}$	Internal reference frequency (fast clock) — factory trimmed at nominal $V_{DD}$ and 25 °C	—	4	—	MHz	
$\Delta f_{intf\_ft}$	Frequency deviation of internal reference clock (fast clock) over temperature and voltage --- factory trimmed at nominal $V_{DD}$ and 25 °C	—	+1/-2	± 3	% $f_{intf\_ft}$	2
$f_{intf\_t}$	Internal reference frequency (fast clock) — user trimmed at nominal $V_{DD}$ and 25 °C	3	—	5	MHz	
$f_{loc\_low}$	Loss of external clock minimum frequency — RANGE = 00	(3/5) x $f_{ints\_t}$	—	—	kHz	
$f_{loc\_high}$	Loss of external clock minimum frequency — RANGE = 01, 10, or 11	(16/5) x $f_{ints\_t}$	—	—	kHz	
<b>FLL</b>						
$f_{fll\_ref}$	FLL reference frequency range	31.25	—	39.0625	kHz	
$f_{dco}$	DCO output frequency range	Low range (DRS = 00) 640 x $f_{fll\_ref}$	20	20.97	25	MHz 3, 4
		Mid range (DRS = 01) 1280 x $f_{fll\_ref}$	40	41.94	48	

Table continues on the next page...

**Table 13. Oscillator DC electrical specifications (continued)**

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
$R_S$	Series resistor — low-frequency, low-power mode (HGO=0)	—	—	—	kΩ	
	Series resistor — low-frequency, high-gain mode (HGO=1)	—	200	—	kΩ	
	Series resistor — high-frequency, low-power mode (HGO=0)	—	—	—	kΩ	
	Series resistor — high-frequency, high-gain mode (HGO=1)	—	0	—	kΩ	
$V_{pp}^5$	Peak-to-peak amplitude of oscillation (oscillator mode) — low-frequency, low-power mode (HGO=0)	—	0.6	—	V	
	Peak-to-peak amplitude of oscillation (oscillator mode) — low-frequency, high-gain mode (HGO=1)	—	$V_{DD}$	—	V	
	Peak-to-peak amplitude of oscillation (oscillator mode) — high-frequency, low-power mode (HGO=0)	—	0.6	—	V	
	Peak-to-peak amplitude of oscillation (oscillator mode) — high-frequency, high-gain mode (HGO=1)	—	$V_{DD}$	—	V	

1.  $V_{DD}=3.3$  V, Temperature =25 °C
2. See crystal or resonator manufacturer's recommendation
3.  $C_x, C_y$  can be provided by using the integrated capacitors when the low frequency oscillator (RANGE = 00) is used. For all other cases external capacitors must be used..
4. When low power mode is selected,  $R_F$  is integrated and must not be attached externally.
5. The EXTAL and XTAL pins should only be connected to required oscillator components and must not be connected to any other devices.

### 6.3.2.2 Oscillator frequency specifications

**Table 14. Oscillator frequency specifications**

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
$f_{osc\_lo}$	Oscillator crystal or resonator frequency — low frequency mode (MCG_C2[RANGE]=00)	32	—	40	kHz	
$f_{osc\_hi\_1}$	Oscillator crystal or resonator frequency — high frequency mode (low range) (MCG_C2[RANGE]=01)	3	—	8	MHz	
$f_{osc\_hi\_2}$	Oscillator crystal or resonator frequency — high frequency mode (high range) (MCG_C2[RANGE]=1x)	8	—	32	MHz	
$f_{ec\_extal}$	Input clock frequency (external clock mode)	—	—	48	MHz	1, 2
$t_{dc\_extal}$	Input clock duty cycle (external clock mode)	40	50	60	%	

Table continues on the next page...

**Table 14. Oscillator frequency specifications (continued)**

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
$t_{cst}$	Crystal startup time — 32 kHz low-frequency, low-power mode (HGO=0)	—	750	—	ms	3, 4
	Crystal startup time — 32 kHz low-frequency, high-gain mode (HGO=1)	—	250	—	ms	
	Crystal startup time — 8 MHz high-frequency (MCG_C2[RANGE]=01), low-power mode (HGO=0)	—	0.6	—	ms	
	Crystal startup time — 8 MHz high-frequency (MCG_C2[RANGE]=01), high-gain mode (HGO=1)	—	1	—	ms	

1. Other frequency limits may apply when external clock is being used as a reference for the FLL or PLL.
2. When transitioning from FBE to FEI mode, restrict the frequency of the input clock so that, when it is divided by FRDIV, it remains within the limits of the DCO input clock frequency.
3. Proper PC board layout procedures must be followed to achieve specifications.
4. Crystal startup time is defined as the time between the oscillator being enabled and the OSCINIT bit in the MCG\_S register being set.

## 6.4 Memories and memory interfaces

### 6.4.1 Flash electrical specifications

This section describes the electrical characteristics of the flash memory module.

#### 6.4.1.1 Flash timing specifications — program and erase

The following specifications represent the amount of time the internal charge pumps are active and do not include command overhead.

**Table 15. NVM program/erase timing specifications**

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
$t_{hvpgm4}$	Longword Program high-voltage time	—	7.5	18	μs	
$t_{hversscr}$	Sector Erase high-voltage time	—	13	113	ms	1
$t_{hversall}$	Erase All high-voltage time	—	52	452	ms	1

1. Maximum time based on expectations at cycling end-of-life.

### 6.4.1.2 Flash timing specifications — commands

Table 16. Flash command timing specifications

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
$t_{rd1sec1k}$	Read 1s Section execution time (flash sector)	—	—	60	μs	1
$t_{pgmchk}$	Program Check execution time	—	—	45	μs	1
$t_{rdrsrc}$	Read Resource execution time	—	—	30	μs	1
$t_{pgm4}$	Program Longword execution time	—	65	145	μs	
$t_{ersscr}$	Erase Flash Sector execution time	—	14	114	ms	2
$t_{rd1all}$	Read 1s All Blocks execution time	—	—	1.8	ms	
$t_{rdonce}$	Read Once execution time	—	—	25	μs	1
$t_{pgmonce}$	Program Once execution time	—	65	—	μs	
$t_{ersall}$	Erase All Blocks execution time	—	62	500	ms	2
$t_{vfykey}$	Verify Backdoor Access Key execution time	—	—	30	μs	1

- Assumes 25MHz flash clock frequency.
- Maximum times for erase parameters based on expectations at cycling end-of-life.

### 6.4.1.3 Flash high voltage current behaviors

Table 17. Flash high voltage current behaviors

Symbol	Description	Min.	Typ.	Max.	Unit
$I_{DD\_PGM}$	Average current adder during high voltage flash programming operation	—	2.5	6.0	mA
$I_{DD\_ERS}$	Average current adder during high voltage flash erase operation	—	1.5	4.0	mA

### 6.4.1.4 Reliability specifications

Table 18. NVM reliability specifications

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
Program Flash						
$t_{nvmretp10k}$	Data retention after up to 10 K cycles	5	50	—	years	
$t_{nvmretp1k}$	Data retention after up to 1 K cycles	20	100	—	years	
$n_{nvmcycp}$	Cycling endurance	10 K	50 K	—	cycles	2

- Typical data retention values are based on measured response accelerated at high temperature and derated to a constant 25°C use profile. Engineering Bulletin EB618 does not apply to this technology. Typical endurance defined in Engineering Bulletin EB619.
- Cycling endurance represents number of program/erase cycles at  $-40^{\circ}\text{C} \leq T_j \leq 125^{\circ}\text{C}$ .

**Table 20. 12-bit ADC characteristics ( $V_{REFH} = V_{DDA}$ ,  $V_{REFL} = V_{SSA}$ ) (continued)**

Symbol	Description	Conditions <sup>1</sup>	Min.	Typ. <sup>2</sup>	Max.	Unit	Notes
$E_Q$	Quantization error	• 12-bit modes	—	—	$\pm 0.5$	LSB <sup>4</sup>	
$E_{IL}$	Input leakage error			$I_{in} \times R_{AS}$		mV	$I_{in}$ = leakage current (refer to the MCU's voltage and current operating ratings)
	Temp sensor slope	Across the full temperature range of the device	—	1.715	—	mV/°C	
$V_{TEMP25}$	Temp sensor voltage	25 °C	—	719	—	mV	

1. All accuracy numbers assume the ADC is calibrated with  $V_{REFH} = V_{DDA}$
2. Typical values assume  $V_{DDA} = 3.0$  V, Temp = 25°C,  $f_{ADCK} = 2.0$  MHz unless otherwise stated. Typical values are for reference only and are not tested in production.
3. The ADC supply current depends on the ADC conversion clock speed, conversion rate and the ADLPC bit (low power). For lowest power operation the ADLPC bit must be set, the HSC bit must be clear with 1 MHz ADC conversion clock speed.
4. 1 LSB =  $(V_{REFH} - V_{REFL})/2^N$
5. ADC conversion clock < 16 MHz, Max hardware averaging (AVGE = %1, AVGS = %11)

## 6.6.2 CMP and 6-bit DAC electrical specifications

**Table 21. Comparator and 6-bit DAC electrical specifications**

Symbol	Description	Min.	Typ.	Max.	Unit
$V_{DD}$	Supply voltage	1.71	—	3.6	V
$I_{DDHS}$	Supply current, high-speed mode (EN = 1, PMODE = 1)	—	—	200	µA
$I_{DDLS}$	Supply current, low-speed mode (EN = 1, PMODE = 0)	—	—	20	µA
$V_{AIN}$	Analog input voltage	$V_{SS}$	—	$V_{DD}$	V
$V_{AIO}$	Analog input offset voltage	—	—	20	mV
$V_H$	Analog comparator hysteresis <sup>1</sup>				
	• CR0[HYSTCTR] = 00	—	5	—	mV
	• CR0[HYSTCTR] = 01	—	10	—	mV
	• CR0[HYSTCTR] = 10	—	20	—	mV
	• CR0[HYSTCTR] = 11	—	30	—	mV
$V_{CMPOh}$	Output high	$V_{DD} - 0.5$	—	—	V
$V_{CMPOl}$	Output low	—	—	0.5	V

Table continues on the next page...

## 6.7 Timers

See General switching specifications.

## 6.8 Communication interfaces

### 6.8.1 USB electrical specifications

The USB electricals for the USB On-the-Go module conform to the standards documented by the Universal Serial Bus Implementers Forum. For the most up-to-date standards, visit <http://www.usb.org>.

### 6.8.2 USB VREG electrical specifications

**Table 22. USB VREG electrical specifications**

Symbol	Description	Min.	Typ. <sup>1</sup>	Max.	Unit	Notes
VREGIN	Input supply voltage	2.7	—	5.5	V	
I <sub>DDon</sub>	Quiescent current — Run mode, load current equal zero, input supply (VREGIN) > 3.6 V	—	120	186	µA	
I <sub>DDstby</sub>	Quiescent current — Standby mode, load current equal zero	—	1.1	10	µA	
I <sub>DDoff</sub>	Quiescent current — Shutdown mode <ul style="list-style-type: none"> <li>• VREGIN = 5.0 V and temperature=25C</li> <li>• Across operating voltage and temperature</li> </ul>	—	650	—	nA	
—	—	—	4	—	µA	
I <sub>LOADrun</sub>	Maximum load current — Run mode	—	—	120	mA	
I <sub>LOADstby</sub>	Maximum load current — Standby mode	—	—	1	mA	
V <sub>Reg33out</sub>	Regulator output voltage — Input supply (VREGIN) > 3.6 V <ul style="list-style-type: none"> <li>• Run mode</li> <li>• Standby mode</li> </ul>	3 2.1	3.3 2.8	3.6 3.6	V	
V <sub>Reg33out</sub>	Regulator output voltage — Input supply (VREGIN) < 3.6 V, pass-through mode	2.1	—	3.6	V	<sup>2</sup>
C <sub>OUT</sub>	External output capacitor	1.76	2.2	8.16	µF	
ESR	External output capacitor equivalent series resistance	1	—	100	mΩ	
I <sub>LIM</sub>	Short circuit current	—	290	—	mA	

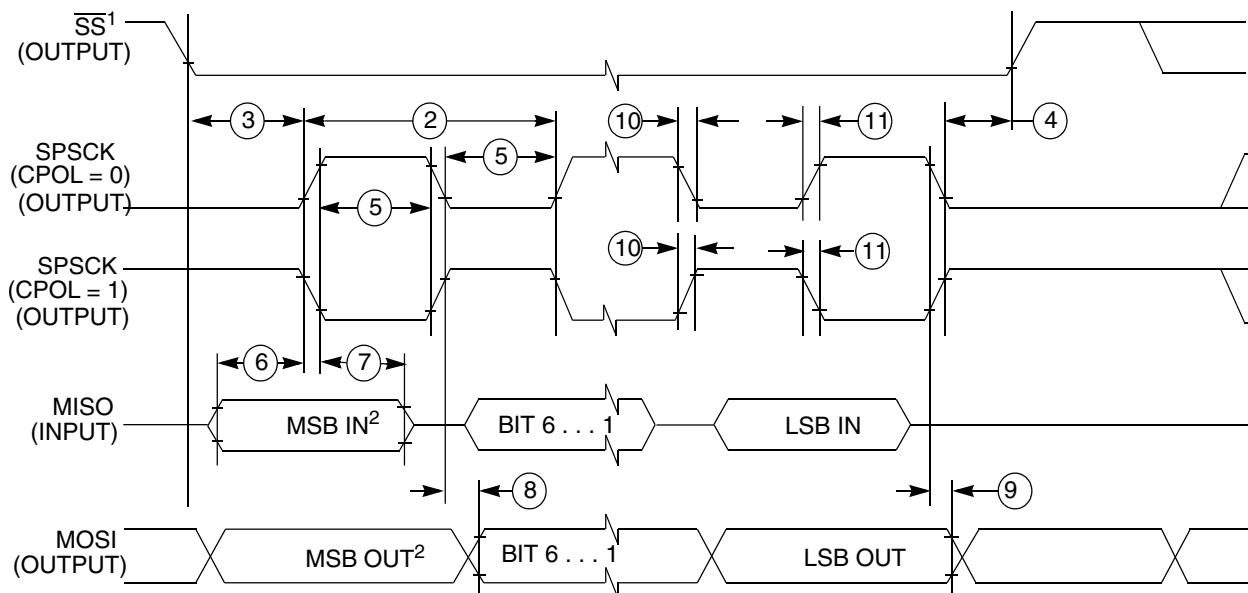
1. Typical values assume VREGIN = 5.0 V, Temp = 25 °C unless otherwise stated.
2. Operating in pass-through mode: regulator output voltage equal to the input voltage minus a drop proportional to I<sub>Load</sub>.

**Table 24. SPI master mode timing on slew rate enabled pads (continued)**

Num.	Symbol	Description	Min.	Max.	Unit	Note
7	$t_{HI}$	Data hold time (inputs)	0	—	ns	—
8	$t_V$	Data valid (after SPSCK edge)	—	52	ns	—
9	$t_{HO}$	Data hold time (outputs)	0	—	ns	—
10	$t_{RI}$	Rise time input	—	$t_{periph} - 25$	ns	—
	$t_{FI}$	Fall time input				
11	$t_{RO}$	Rise time output	—	36	ns	—
	$t_{FO}$	Fall time output				

1. For SPI0  $f_{periph}$  is the bus clock ( $f_{BUS}$ ). For SPI1  $f_{periph}$  is the system clock ( $f_{SYS}$ ).

2.  $t_{periph} = 1/f_{periph}$



1. If configured as an output.

2. LSBF = 0. For LSBF = 1, bit order is LSB, bit 1, ..., bit 6, MSB.

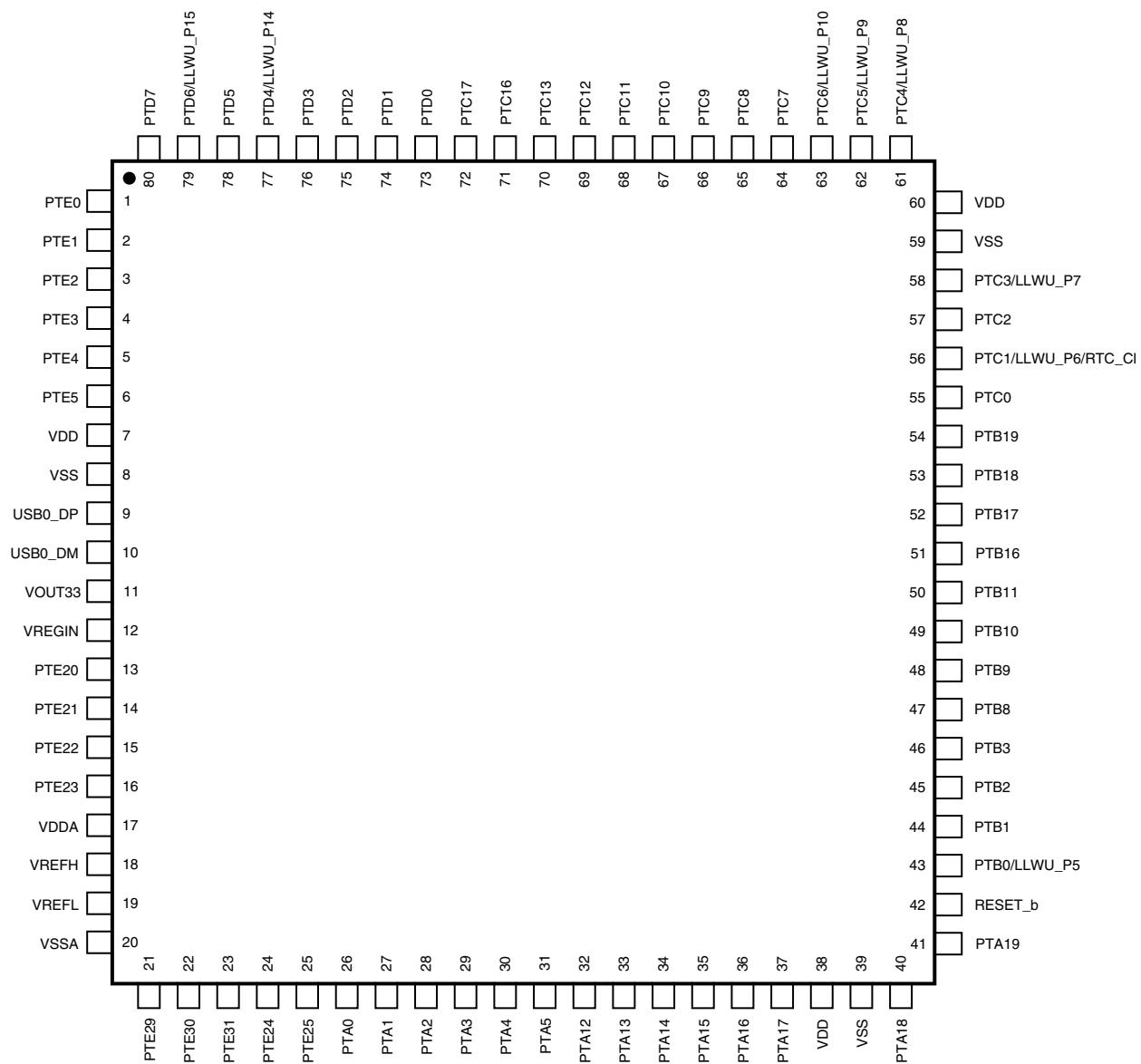
**Figure 9. SPI master mode timing (CPHA = 0)**

80 LQFP	64 LQFP	48 QFN	32 QFN	Pin Name	Default	ALT0	ALT1	ALT2	ALT3	ALT4	ALT5	ALT6	ALT7
64	52	40	28	PTC7	CMP0_IN1	CMP0_IN1	PTC7	SPI0_MISO			SPI0_MOSI		
65	53	—	—	PTC8	CMP0_IN2	CMP0_IN2	PTC8	I2C0_SCL	TPM0_CH4				
66	54	—	—	PTC9	CMP0_IN3	CMP0_IN3	PTC9	I2C0_SDA	TPM0_CH5				
67	55	—	—	PTC10	DISABLED		PTC10	I2C1_SCL					
68	56	—	—	PTC11	DISABLED		PTC11	I2C1_SDA					
69	—	—	—	PTC12	DISABLED		PTC12			TPM_CLKIN0			
70	—	—	—	PTC13	DISABLED		PTC13			TPM_CLKIN1			
71	—	—	—	PTC16	DISABLED		PTC16						
72	—	—	—	PTC17	DISABLED		PTC17						
73	57	41	—	PTD0	DISABLED		PTD0	SPI0_PCS0		TPM0_CH0			
74	58	42	—	PTD1	ADC0_SE5b	ADC0_SE5b	PTD1	SPI0_SCK		TPM0_CH1			
75	59	43	—	PTD2	DISABLED		PTD2	SPI0_MOSI	UART2_RX	TPM0_CH2	SPI0_MISO		
76	60	44	—	PTD3	DISABLED		PTD3	SPI0_MISO	UART2_TX	TPM0_CH3	SPI0_MOSI		
77	61	45	29	PTD4/ LLWU_P14	DISABLED		PTD4/ LLWU_P14	SPI1_PCS0	UART2_RX	TPM0_CH4			
78	62	46	30	PTD5	ADC0_SE6b	ADC0_SE6b	PTD5	SPI1_SCK	UART2_TX	TPM0_CH5			
79	63	47	31	PTD6/ LLWU_P15	ADC0_SE7b	ADC0_SE7b	PTD6/ LLWU_P15	SPI1_MOSI	UART0_RX		SPI1_MISO		
80	64	48	32	PTD7	DISABLED		PTD7	SPI1_MISO	UART0_TX		SPI1_MOSI		

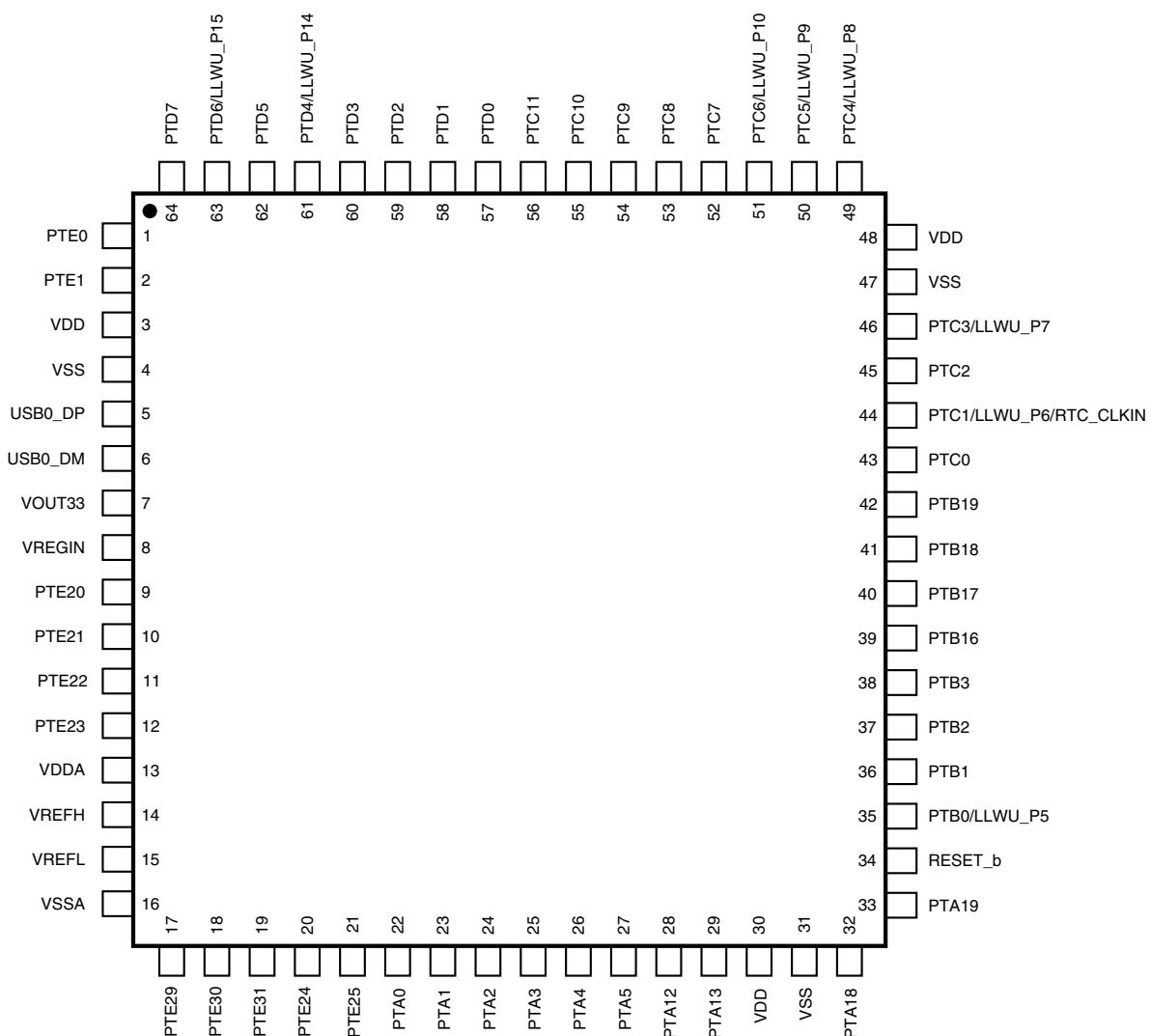
## 8.2 KL24 Pinouts

The below figures show the pinout diagrams for the devices supported by this document. Many signals may be multiplexed onto a single pin. To determine what signals can be used on which pin, see the previous section.

## Pinout

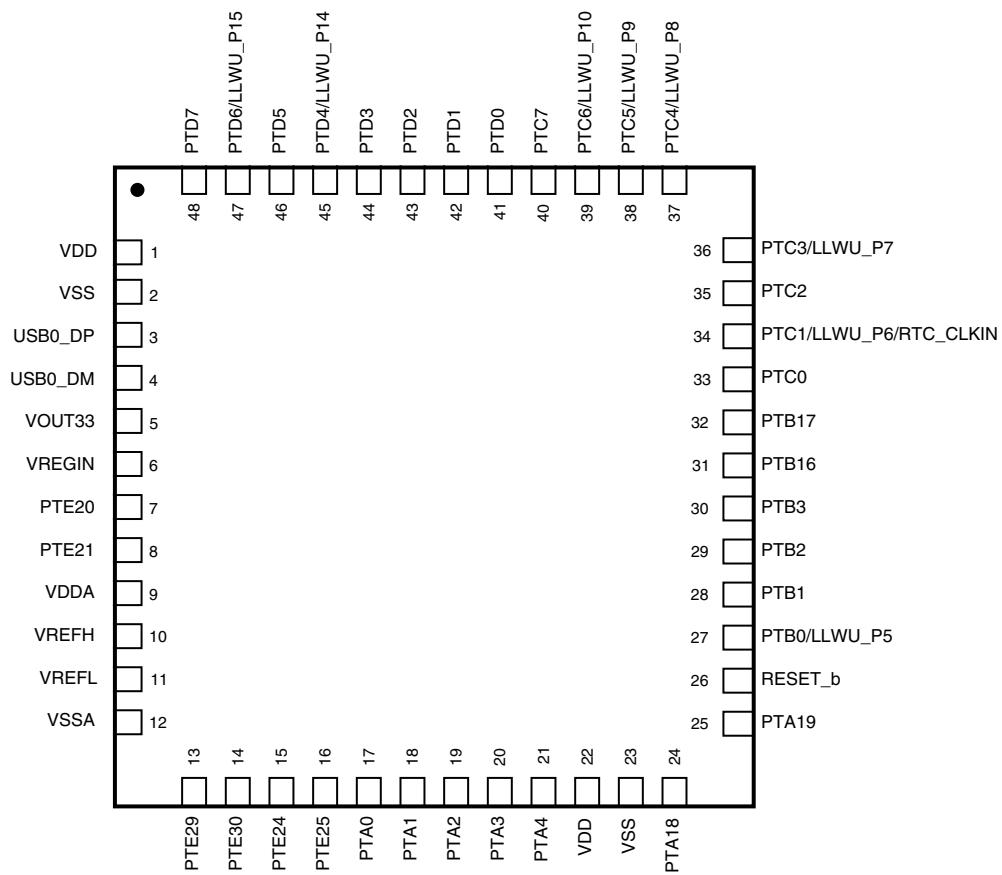


**Figure 13. KL24 80-pin LQFP pinout diagram**



**Figure 14. KL24 64-pin LQFP pinout diagram**

## Pinout



**Figure 15. KL24 48-pin QFN pinout diagram**

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