Renesas Electronics America Inc - UPD78F0536AGK-GAJ-AX Datasheet

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Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	78K/0
Core Size	8-Bit
Speed	20MHz
Connectivity	3-Wire SIO, I²C, LINbus, UART/USART
Peripherals	LVD, POR, PWM, WDT
Number of I/O	55
Program Memory Size	96KB (96K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	5K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 5.5V
Data Converters	A/D 8x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	64-LQFP
Supplier Device Package	-
Purchase URL	https://www.e-xfl.com/product-detail/renesas-electronics-america/upd78f0536agk-gaj-ax

Related Documents The related documents indicated in this publication may include preliminary versions. However, preliminary versions are not marked as such.

Documents Related to Devices

Document Name	Document No.
78K0/Kx2 User's Manual	This manual
78K/0 Series Instructions User's Manual	U12326E
78K0/Kx2 Flash Memory Programming (Programmer) Application Note	U17739E
78K0/Kx2 Flash Memory Self Programming User's Manual	U17516E
78K0/Kx2 EEPROM™ Emulation Application Note	U17517E
78K0 Microcontrollers Self Programming Library Type01 User's Manual	U18274E
78K0 Microcontrollers EEPROM Emulation Library Type01 User's Manual	U18275E

Documents Related to Flash Memory Programming

Document Name	Document No.
PG-FP5 Flash Memory Programmer User's Manual	U18865E
PG-FP4 Flash Memory Programmer User's Manual	U15260E

Documents Related to Development Tools (Hardware)

Document Name	Document No.
QB-78K0KX2 In-Circuit Emulator User's Manual	U17341E
QB-MINI2 On-Chip Debug Emulator with Programming Function User's Manual	U18371E

Caution The related documents listed above are subject to change without notice. Be sure to use the latest version of each document when designing.

1.1.3 Time Instruction cycle, peripheral hardware clock frequency, external main system clock frequency, external main system clock input high-level width, and external main system clock input low-level width (AC characteristics)

(1) Conventional-specification products (μPD78F05xx and 78F05xxD)

Parameter	Symbol	Conditions		MIN.	TYP.	MAX.	Unit
Instruction cycle (minimum instruction execution time)	T_{CY}	Main system clock (f_{XP}) operation	4.0 V ≤ V_{DD} ≤ 5.5 V	0.1		32	μs
			2.7 V ≤ V_{DD} < 4.0 V	0.2		32	μs
			1.8 V ≤ V_{DD} < 2.7 V Note 1	0.4 Note 3		32	μs
		Subsystem clock (f_{SUB}) operation Note 2		114	122	125	μs
Peripheral hardware clock frequency	f_{PRS}	f_{PRS} = f_{XH} (XSEL = 1)	4.0 V ≤ V_{DD} ≤ 5.5 V			20	MHz
			2.7 V ≤ V_{DD} < 4.0 V			10	MHz
			1.8 V ≤ V_{DD} < 2.7 V Note 1			5	MHz
		f_{PRS} = f_{RH} (XSEL = 0)	2.7 V ≤ V_{DD} ≤ 5.5 V	7.6		8.4	MHz
			1.8 V ≤ V_{DD} < 2.7 V Notes 1, 5	7.6		10.4	MHz
External main system clock frequency	f_{EXCLK}	4.0 V ≤ V_{DD} ≤ 5.5 V		1.0 Note 6		20.0	MHz
		2.7 V ≤ V_{DD} < 4.0 V		1.0 Note 6		10.0	MHz
		1.8 V ≤ V_{DD} < 2.7 V Note 1		1.0		5.0	MHz
External main system clock input high-level width, low-level width	t_{EXCLKH}, t_{EXCLKL}	4.0 V ≤ V_{DD} ≤ 5.5 V		24			ns
		2.7 V ≤ V_{DD} < 4.0 V		48			ns
		1.8 V ≤ V_{DD} < 2.7 V Note 1		96			ns

(2) Expanded-specification products (μPD78F05xxA and 78F05xxDA)

Parameter	Symbol	Conditions		MIN.	TYP.	MAX.	Unit
Instruction cycle (minimum instruction execution time)	T_{CY}	Main system clock (f_{XP}) operation	2.7 V ≤ V_{DD} ≤ 5.5 V	0.1		32	μs
			1.8 V ≤ V_{DD} < 2.7 V Note 1	0.4 Note 3		32	μs
		Subsystem clock (f_{SUB}) operation Note 2		114	122	125	μs
Peripheral hardware clock frequency	f_{PRS}	f_{PRS} = f_{XH} (XSEL = 1)	4.0 V ≤ V_{DD} ≤ 5.5 V			20	MHz
			2.7 V ≤ V_{DD} < 4.0 V Note 4			20	MHz
			1.8 V ≤ V_{DD} < 2.7 V Note 1			5	MHz
		f_{PRS} = f_{RH} (XSEL = 0)	2.7 V ≤ V_{DD} ≤ 5.5 V	7.6		8.4	MHz
			1.8 V ≤ V_{DD} < 2.7 V Notes 1, 5	7.6		10.4	MHz
External main system clock frequency	f_{EXCLK}	2.7 V ≤ V_{DD} ≤ 5.5 V		1.0 Note 6		20.0	MHz
		1.8 V ≤ V_{DD} < 2.7 V Note 1		1.0		5.0	MHz
External main system clock input high-level width, low-level width	t_{EXCLKH}, t_{EXCLKL}	2.7 V ≤ V_{DD} ≤ 5.5 V		24			ns
		1.8 V ≤ V_{DD} < 2.7 V Note 1		96			ns

Notes 1. Standard and (A) grade products only

2. The 78K0/KB2 is not provided with a subsystem clock.

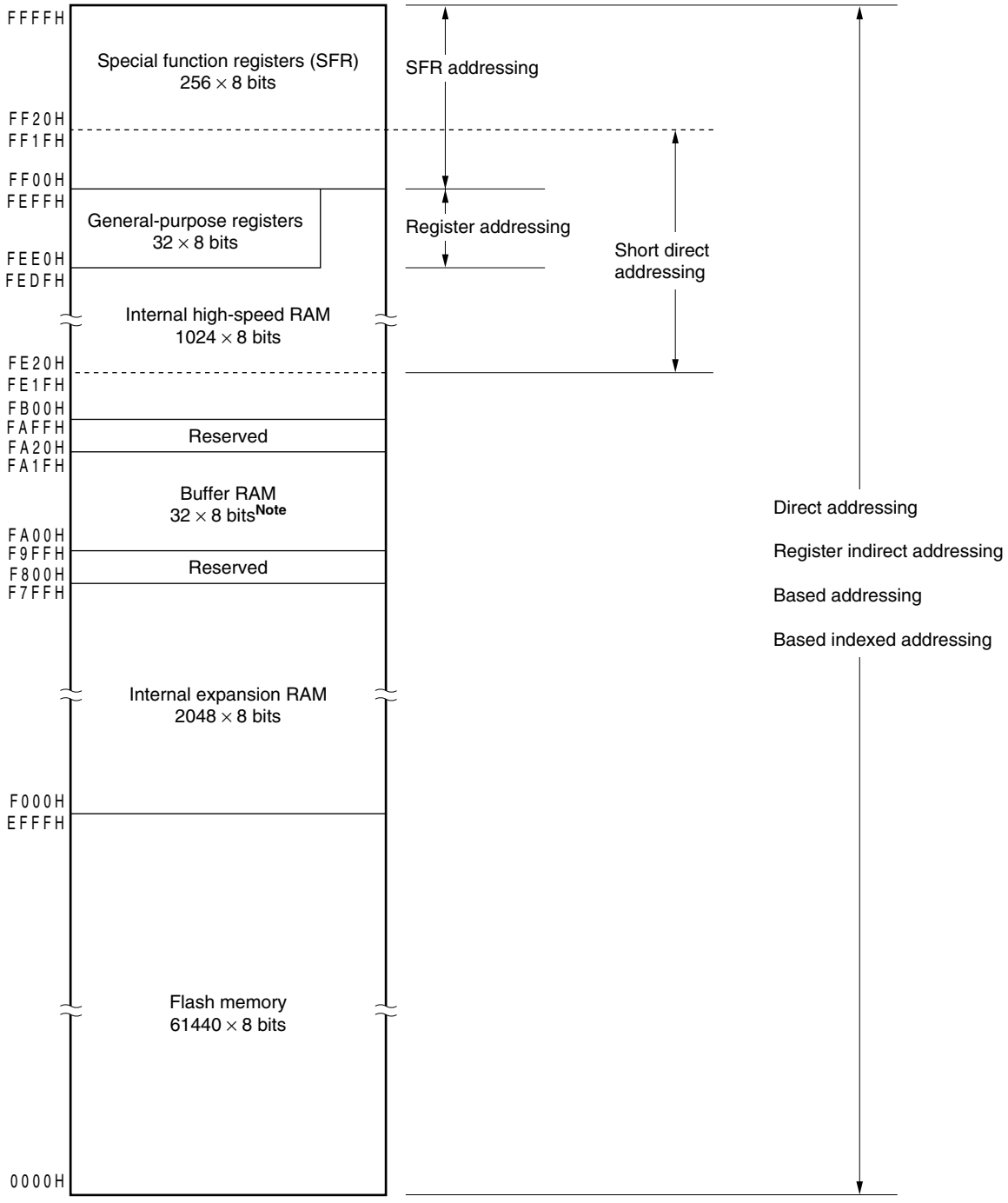
3. 0.38 μs when operating with the 8 MHz internal oscillator.

4. Characteristics of the main system clock frequency. Set the division clock to be set by a peripheral function to f_{XH}/2 (10 MHz) or less. The multiplier/divider, however, can operate on f_{XH} (20 MHz).

5. Characteristics of the main system clock frequency. Set the division clock to be set by a peripheral function to f_{RH}/2 or less.

6. 2.0 MHz (MIN.) when using UART6 during on-board programming.

Figure 3-17. Correspondence Between Data Memory and Addressing (μPD78F0515, 78F0515A, 78F0525, 78F0525A, 78F0535, 78F0535A, 78F0545, 78F0545A, 78F0515D and 78F0515DA)



Note The buffer RAM is incorporated only in the μPD78F0545 and 78F0545A (78K0/KF2). The area from FA00H to FA1FH cannot be used with the μPD78F0515, 78F0515A, 78F0525, 78F0525A, 78F0535, 78F0535A, 78F0515D, and 78F0515DA.

Remark Note the following points to use the memory bank select function efficiently.

- Allocate a routine that is used often in the common area.
- If a value that is planned to be referenced is placed in RAM, it can be referenced from all of the areas.
- If the reference destination and the branch destination of the routine placed in a memory bank are placed in the same memory bank, then the code size and processing are more efficient.
- Allocate interrupt servicing that requires a quick response in the common area.

5.2.7 Port 6

	78K0/KB2	78K0/KC2	78K0/KD2	78K0/KE2		78K0/KF2
				Products whose flash memory is less than 32 KB	Products whose flash memory is at least 48 KB	
P60/SCL0	√	√				√
P61/SDA0	√	√				√
P62/EXSCL0	–	√				√
P63	–	√				√
P64	–	–				√
P65	–	–				√
P66	–	–				√
P67	–	–				√

Remark √: Mounted, –: Not mounted

Port 6 is an I/O port with an output latch. Port 6 can be set to the input mode or output mode in 1-bit units using port mode register 6 (PM6). When the P64 to P67 pins are used as an input port, use of an on-chip pull-up resistor can be specified in 1-bit units by pull-up resistor option register 6 (PU6).

The output of the P60 to P63 pins is N-ch open-drain output (6 V tolerance).

This port can also be used for serial interface data I/O, clock I/O, and external clock input.

Reset signal generation sets port 6 to input mode.

Figures 5-17 to 5-20 show block diagrams of port 6.

Remark When using P62/EXSCL0 as an external clock input pin of the serial interface, input a clock of 6.4 MHz to it.

Figure 5-42. Format of Pull-up Resistor Option Register (78K0/KE2)

Symbol	7	6	5	4	3	2	1	0	Address	After reset	R/W
PU0	0	PU06	PU05	PU04	PU03	PU02	PU01	PU00	FF30H	00H	R/W
PU1	PU17	PU16	PU15	PU14	PU13	PU12	PU11	PU10	FF31H	00H	R/W
PU3	0	0	0	0	PU33	PU32	PU31	PU30	FF33H	00H	R/W
PU4	0	0	0	0	PU43	PU42	PU41	PU40	FF34H	00H	R/W
PU5	0	0	0	0	PU53	PU52	PU51	PU50	FF35H	00H	R/W
PU7	PU77	PU76	PU75	PU74	PU73	PU72	PU71	PU70	FF37H	00H	R/W
PU12	0	0	0	0	0	0	0	PU120	FF3CH	00H	R/W
PU14	0	0	0	0	0	0	PU141	PU140	FF3EH	00H	R/W

PUmn	Pmn pin on-chip pull-up resistor selection (m = 0, 1, 3 to 5, 7, 12, 14; n = 0 to 7)
0	On-chip pull-up resistor not connected
1	On-chip pull-up resistor connected

6.4.3 When subsystem clock is not used

If it is not necessary to use the subsystem clock[Note] for low power consumption operations, or if not using the subsystem clock as an I/O port, set the XT1 and XT2 pins to I/O mode (OSCSELS = 0) and connect them as follows.

Note The 78K0/KB2 is not provided with a subsystem clock.

Input (PM123/PM124 = 1): Independently connect to V_{DD} or V_{SS} via a resistor.
Output (PM123/PM124 = 0): Leave open.

Remark OSCSELS: Bit 4 of clock operation mode select register (OSCCTL)
PM123, PM124: Bits 3 and 4 of port mode register 12 (PM12)

6.4.4 Internal high-speed oscillator

The internal high-speed oscillator is incorporated in the 78K0/Kx2 microcontrollers. Oscillation can be controlled by the internal oscillation mode register (RCM).

After a reset release, the internal high-speed oscillator automatically starts oscillation (8 MHz (TYP.)).

6.4.5 Internal low-speed oscillator

The internal low-speed oscillator is incorporated in the 78K0/Kx2 microcontrollers.

The internal low-speed oscillation clock is only used as the watchdog timer and the clock of 8-bit timer H1. The internal low-speed oscillation clock cannot be used as the CPU clock.

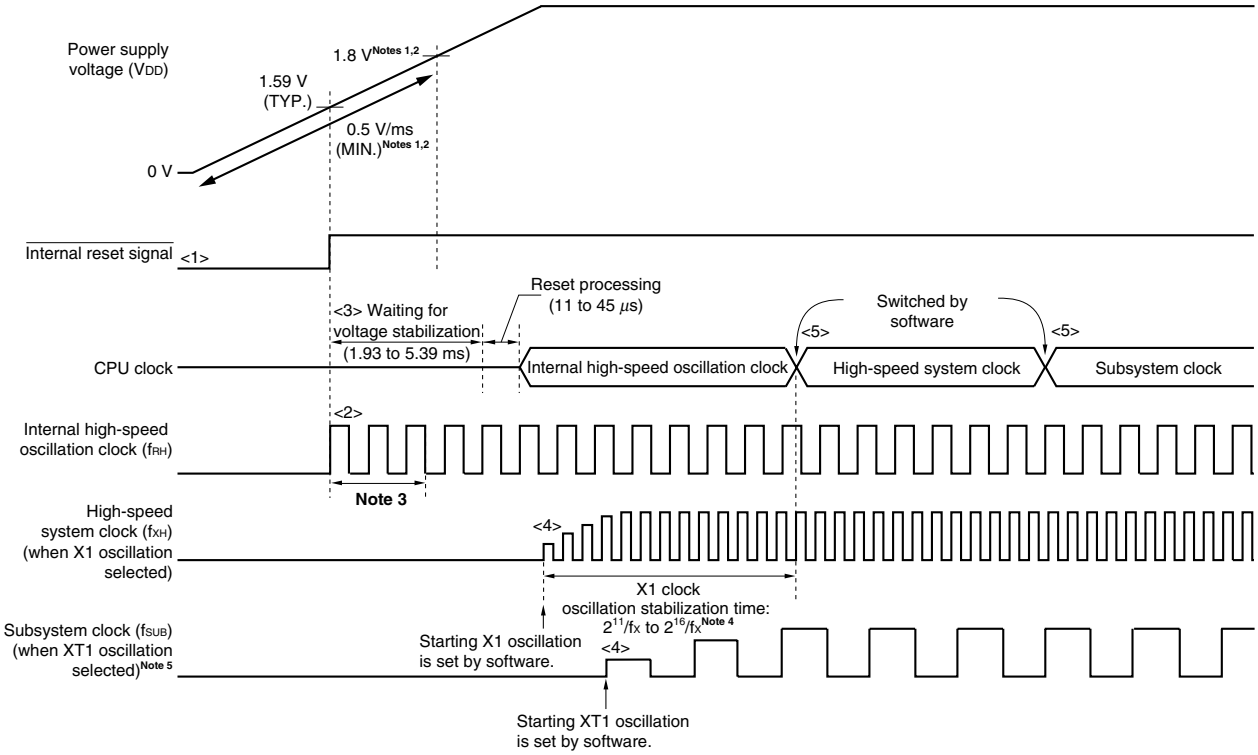
“Can be stopped by software” or “Cannot be stopped” can be selected by the option byte. When “Can be stopped by software” is set, oscillation can be controlled by the internal oscillation mode register (RCM).

After a reset release, the internal low-speed oscillator automatically starts oscillation, and the watchdog timer is driven (240 kHz (TYP.)) if the watchdog timer operation is enabled using the option byte.

6.4.6 Prescaler

The prescaler generates the CPU clock by dividing the main system clock when the main system clock is selected as the clock to be supplied to the CPU.

Figure 6-15. Clock Generator Operation When Power Supply Voltage Is Turned On (When 1.59 V POC Mode Is Set (Option Byte: POCMODE = 0))



<1> When the power is turned on, an internal reset signal is generated by the power-on-clear (POC) circuit.

<2> When the power supply voltage exceeds 1.59 V (TYP.), the reset is released and the internal high-speed oscillator automatically starts oscillation.

<3> When the power supply voltage rises with a slope of 0.5 V/ms (MIN.), the CPU starts operation on the internal high-speed oscillation clock after the reset is released and after the stabilization times for the voltage of the power supply and regulator have elapsed, and then reset processing is performed.

<4> Set the start of oscillation of the X1 or XT1 clock via software (see **(1)** in **6.6.1 Example of controlling high-speed system clock** and **(1)** in **6.6.3 Example of controlling subsystem clock)**.

<5> When switching the CPU clock to the X1 or XT1 clock, wait for the clock oscillation to stabilize, and then set switching via software (see **(3)** in **6.6.1 Example of controlling high-speed system clock** and **(3)** in **6.6.3 Example of controlling subsystem clock**).

Notes 1. With standard and (A) grade products, if the voltage rises with a slope of less than 0.5 V/ms (MIN.) from power application until the voltage reaches 1.8 V, input a low level to the $\overline{\text{RESET}}$ pin from power application until the voltage reaches 1.8 V, or set the 2.7 V/1.59 V POC mode by using the option byte (POCMODE = 1) (see **Figure 6-16**). When a low level has been input to the $\overline{\text{RESET}}$ pin until the voltage reaches 1.8 V, the CPU operates with the same timing as <2> and thereafter in Figure 6-15, after the reset has been released by the $\overline{\text{RESET}}$ pin.

2. With (A2) grade products, if the voltage rises with a slope of less than 0.75 V/ms (MIN.) from power application until the voltage reaches 2.7 V, input a low level to the $\overline{\text{RESET}}$ pin from power application until the voltage reaches 2.7 V. When a low level has been input to the $\overline{\text{RESET}}$ pin until the voltage reaches 2.7 V, the CPU operates with the same timing as <2> and thereafter in Figure 6-15, after the reset has been released by the $\overline{\text{RESET}}$ pin.

3. The internal voltage stabilization time includes the oscillation accuracy stabilization time of the internal high-speed oscillation clock.

Figure 7-7. Format of 16-Bit Timer Mode Control Register 01 (TMC01)

Address: FFB6H After reset: 00H R/W

Symbol	7	6	5	4	3	2	1	<0>
TMC01	0	0	0	0	TMC013	TMC012	TMC011	OVF01

TMC013	TMC012	Operation enable of 16-bit timer/event counter 01
0	0	Disables 16-bit timer/event counter 01 operation. Stops supplying operating clock. Clears 16-bit timer counter 01 (TM01).
0	1	Free-running timer mode
1	0	Clear & start mode entered by TI001 pin valid edge input[Note]
1	1	Clear & start mode entered upon a match between TM01 and CR001

TMC011	Condition to reverse timer output (TO01)
0	• Match between TM01 and CR001 or match between TM01 and CR011
1	• Match between TM01 and CR001 or match between TM01 and CR011 • Trigger input of TI001 pin valid edge

OVF01	TM01 overflow flag
Clear (0)	Clears OVF01 to 0 or TMC013 and TMC012 = 00
Set (1)	Overflow occurs.
OVF01 is set to 1 when the value of TM01 changes from FFFFH to 0000H in all the operation modes (free-running timer mode, clear & start mode entered by TI001 pin valid edge input, and clear & start mode entered upon a match between TM01 and CR001). It can also be set to 1 by writing 1 to OVF01.	

Note The TI001 pin valid edge is set by bits 5 and 4 (ES011, ES010) of prescaler mode register 01 (PRM01).

(7) 8-bit A/D conversion result register (ADCRH)

The A/D conversion result is loaded from the successive approximation register to this register each time A/D conversion is completed, and the ADCRH register stores the higher 8 bits of the A/D conversion result.

Caution When data is read from ADCR and ADCRH, a wait cycle is generated. Do not read data from ADCR and ADCRH when the peripheral hardware clock (f_{PRS}) is stopped. For details, see CHAPTER 36 CAUTIONS FOR WAIT.

(8) Controller

This circuit controls the conversion time of an input analog signal that is to be converted into a digital signal, as well as starting and stopping of the conversion operation. When A/D conversion has been completed, this controller generates INTAD.

(9) AV_{REF} pin

This pin inputs an analog power/reference voltage to the A/D converter. Make this pin the same potential as the V_{DD} pin when port 2 is used as a digital port.

The signal input to ANI0 to ANI7 is converted into a digital signal, based on the voltage applied across AV_{REF} and AV_{SS}.

(10) AV_{SS} pin

This is the ground potential pin of the A/D converter. Always use this pin at the same potential as that of the V_{SS} pin even when the A/D converter is not used.

(11) A/D converter mode register (ADM)

This register is used to set the conversion time of the analog input signal to be converted, and to start or stop the conversion operation.

(12) A/D port configuration register (ADPC)

This register switches the ANI0/P20 to ANI7/P27 pins to analog input of A/D converter or digital I/O of port.

(13) Analog input channel specification register (ADS)

This register is used to specify the port that inputs the analog voltage to be converted into a digital signal.

(14) Port mode register 2 (PM2)

This register switches the ANI0/P20 to ANI7/P27 pins to input or output.

Remark ANI0 to ANI3: 78K0/KB2
ANI0 to ANI5: 38-pin products of the 78K0/KC2
ANI0 to ANI7: Products other than above

(2) Asynchronous serial interface reception error status register 0 (ASIS0)

This register indicates an error status on completion of reception by serial interface UART0. It includes three error flag bits (PE0, FE0, OVE0).

This register is read-only by an 8-bit memory manipulation instruction.

Reset signal generation, or clearing bit 7 (POWER0) or bit 5 (RXE0) of ASIM0 to 0 clears this register to 00H. 00H is read when this register is read. If a reception error occurs, read ASIS0 and then read receive buffer register 0 (RXB0) to clear the error flag.

Figure 14-3. Format of Asynchronous Serial Interface Reception Error Status Register 0 (ASIS0)

Address: FF73H After reset: 00H R

Symbol	7	6	5	4	3	2	1	0
ASIS0	0	0	0	0	0	PE0	FE0	OVE0

PE0	Status flag indicating parity error
0	If POWER0 = 0 or RXE0 = 0, or if ASIS0 register is read.
1	If the parity of transmit data does not match the parity bit on completion of reception.

FE0	Status flag indicating framing error
0	If POWER0 = 0 or RXE0 = 0, or if ASIS0 register is read.
1	If the stop bit is not detected on completion of reception.

OVE0	Status flag indicating overrun error
0	If POWER0 = 0 and RXE0 = 0, or if ASIS0 register is read.
1	If receive data is set to the RXB0 register and the next reception operation is completed before the data is read.

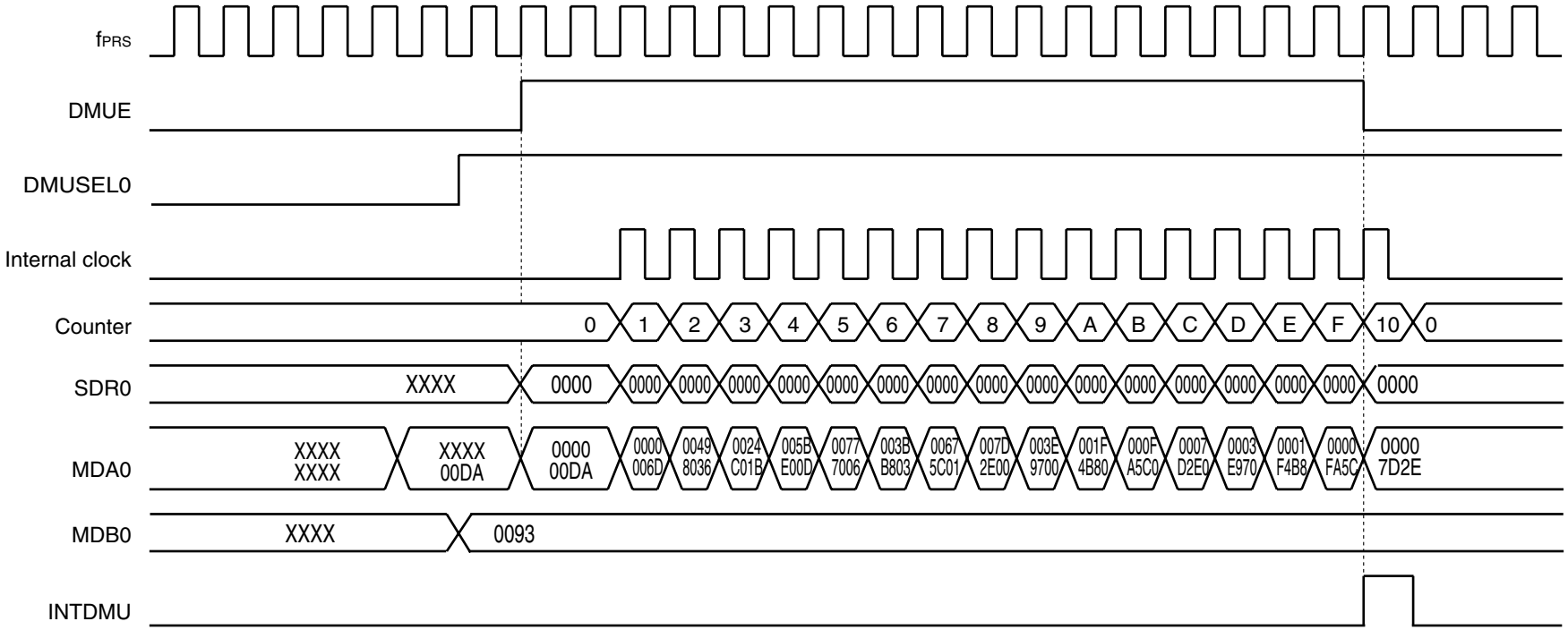
Cautions 1. The operation of the PE0 bit differs depending on the set values of the PS01 and PS00 bits of asynchronous serial interface operation mode register 0 (ASIM0).

2. Only the first bit of the receive data is checked as the stop bit, regardless of the number of stop bits.

3. If an overrun error occurs, the next receive data is not written to receive buffer register 0 (RXB0) but discarded.

4. If data is read from ASIS0, a wait cycle is generated. Do not read data from ASIS0 when the peripheral hardware clock (f_{PRS}) is stopped. For details, see CHAPTER 36 CAUTIONS FOR WAIT.

Figure 19-6. Timing Chart of Multiplication Operation (00DAH × 0093H)



Cautions 1. To use the peripheral hardware that stops operation in the STOP mode, and the peripheral hardware for which the clock that stops oscillating in the STOP mode after the STOP mode is released, restart the peripheral hardware.

2. Even if "internal low-speed oscillator can be stopped by software" is selected by the option byte, the internal low-speed oscillation clock continues in the STOP mode in the status before the STOP mode is set. To stop the internal low-speed oscillator's oscillation in the STOP mode, stop it by software and then execute the STOP instruction.

3. To shorten oscillation stabilization time after the STOP mode is released when the CPU operates with the high-speed system clock (X1 oscillation), switch the CPU clock to the internal high-speed oscillation clock before the execution of the STOP instruction using the following procedure.

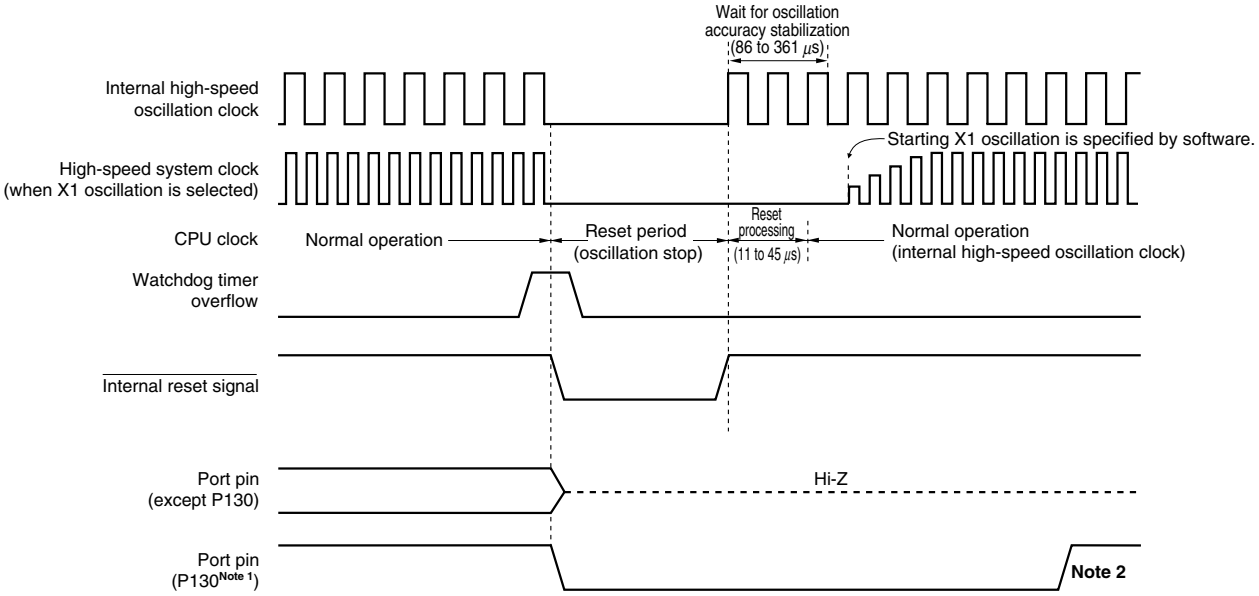
<1> Set RSTOP to 0 (starting oscillation of the internal high-speed oscillator) → <2> Set MCM0 to 0 (switching the CPU from X1 oscillation to internal high-speed oscillation) → <3> Check that MCS is 0 (checking the CPU clock) → <4> Check that RSTS is 1 (checking internal high-speed oscillation operation) → <5> Execute the STOP instruction

Before changing the CPU clock from the internal high-speed oscillation clock to the high-speed system clock (X1 oscillation) after the STOP mode is released, check the oscillation stabilization time with the oscillation stabilization time counter status register (OSTC).

4. If the STOP instruction is executed when AMPH = 1, supply of the CPU clock is stopped for 4.06 to 16.12 μs after the STOP mode is released when the internal high-speed oscillation clock is selected as the CPU clock, or for the duration of 160 external clocks when the high-speed system clock (external clock input) is selected as the CPU clock.

5. Execute the STOP instruction after having confirmed that the internal high-speed oscillator is operating stably (RSTS = 1).

Figure 23-3. Timing of Reset Due to Watchdog Timer Overflow



Notes 1. P130 pin is not mounted onto 78K0/KB2, and 38-pin and 44-pin products of the 78K0/KC2.

2. Set P130 to high-level output by software.

Caution A watchdog timer internal reset resets the watchdog timer.

Remark When reset is effected, P130 outputs a low level. If P130 is set to output a high level before reset is effected, the output signal of P130 can be dummy-output as the CPU reset signal.

Table 27-12. Processing Time for Each Command When PG-FP4 or PG-FP5 Is Used (Reference) (2/2)

(3) Products with internal ROMs of the 128 KB

Command of PG-FP4	Port: CSI-Internal-OSC (Internal high-speed oscillation clock (f_{RH})), Speed: 2.5 MHz	Port: UART-Ext-FP4CK (External main system clock (f_{EXCLK})), Speed: 115,200 bps	
		Frequency: 2.0 MHz	Frequency: 20 MHz
Signature	0.5 s (TYP.)	0.5 s (TYP.)	0.5 s (TYP.)
Blankcheck	1 s (TYP.)	1 s (TYP.)	1 s (TYP.)
Erase	1.5 s (TYP.)	1.5 s (TYP.)	1.5 s (TYP.)
Program	9.5 s (TYP.)	18 s (TYP.)	18 s (TYP.)
Verify	4.5 s (TYP.)	13.5 s (TYP.)	13.5 s (TYP.)
E.P.V	11 s (TYP.)	19.5 s (TYP.)	19.5 s (TYP.)
Checksum	1 s (TYP.)	1 s (TYP.)	1 s (TYP.)
Security	0.5 s (TYP.)	0.5 s (TYP.)	0.5 s (TYP.)

Caution When executing boot swapping, do not use the E.P.V. command with the dedicated flash memory programmer.

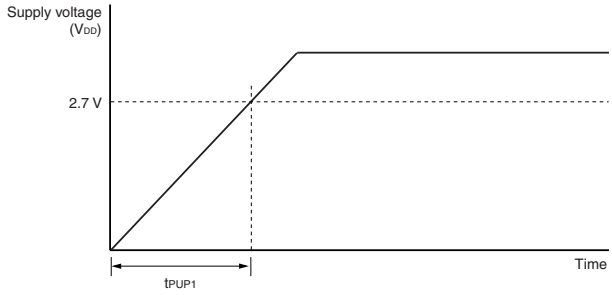
Caution The pins mounted depend on the product. Refer to Caution at the beginning of this chapter.

Supply Voltage Rise Time (T_A = –40 to +110°C, V_{SS} = EV_{SS} = 0 V)

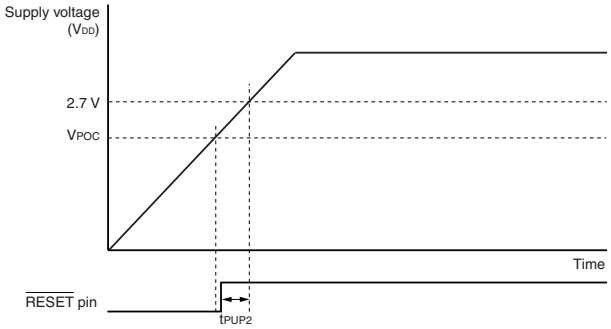
Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Maximum time to rise to 2.7 V (V_{DD} (MIN.)) (V_{DD}: 0 V → 2.7 V)	t_{PUP1}	POCMODE (option byte) = 0, when $\overline{RESET}$ input is not used			3.6	ms
Maximum time to rise to 2.7 V (V_{DD} (MIN.)) (releasing $\overline{RESET}$ input → V_{DD}: 2.7 V)	t_{PUP2}	POCMODE (option byte) = 0, when $\overline{RESET}$ input is used			1.9	ms

Supply Voltage Rise Time Timing

• When $\overline{RESET}$ pin input is not used



• When $\overline{RESET}$ pin input is used



Caution The pins mounted depend on the product. Refer to Caution at the beginning of this chapter.

2.7 V POC Circuit Characteristics (T_A = –40 to +125°C, V_{SS} = EV_{SS} = 0 V)

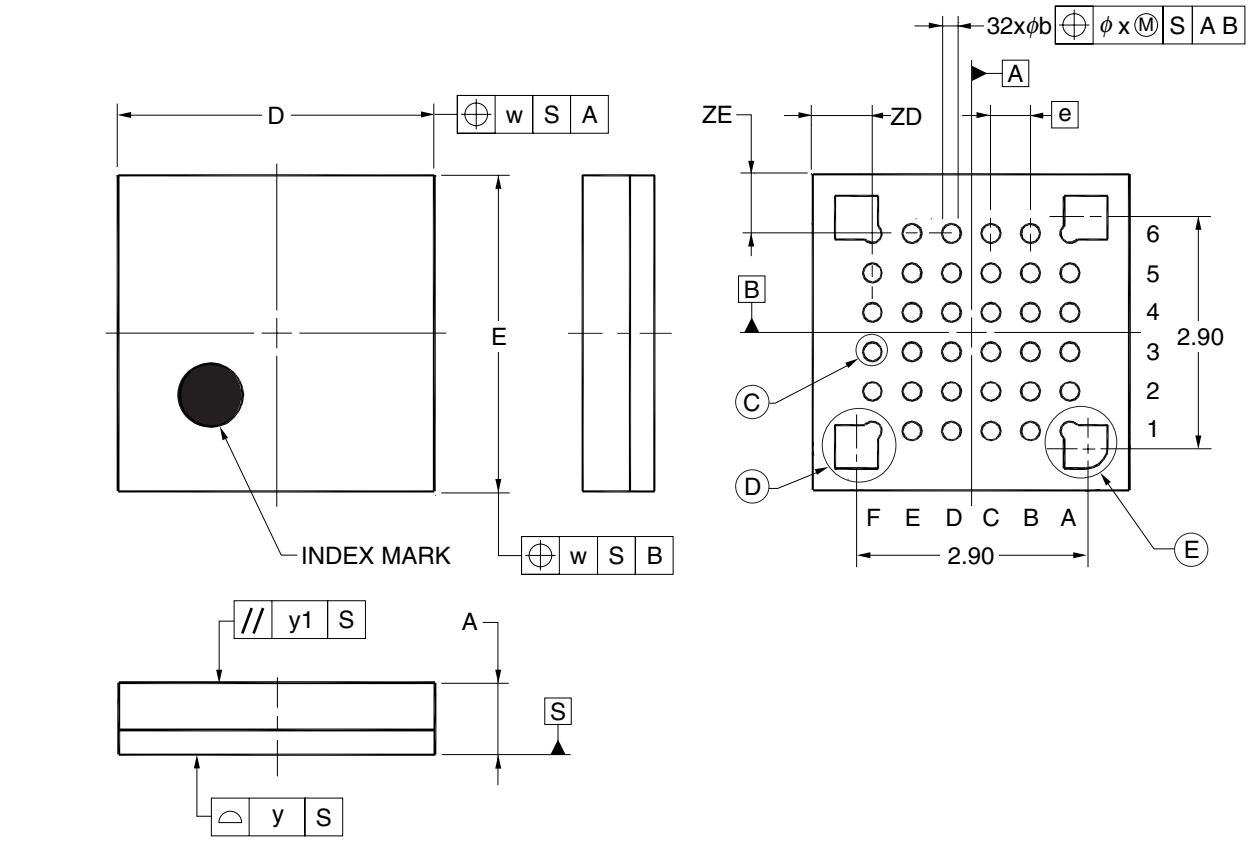
Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Detection voltage on application of supply voltage	V_{DDPOC}	POCMODE (option bye) = 1	2.50	2.70	2.90	V

Remark The operations of the POC circuit are as described below, depending on the POCMODE (option byte) setting.

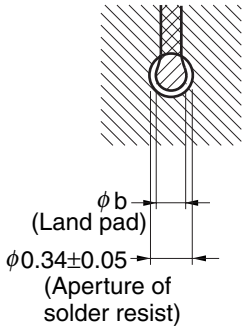
Option Byte Setting	POC Mode	Operation
POCMODE = 0	1.59 V mode operation	A reset state is retained until V_{POC} = 1.59 V (TYP.) is reached after the power is turned on, and the reset is released when V_{POC} is exceeded. After that, POC detection is performed at V_{POC}, similarly as when the power was turned on. The power supply voltage must be raised at a time of t_{PUP1} or t_{PUP2} when POCMODE is 0.
POCMODE = 1	2.7 V/1.59 V mode operation	A reset state is retained until V_{DDPOC} = 2.7 V (TYP.) is reached after the power is turned on, and the reset is released when V_{DDPOC} is exceeded. After that, POC detection is performed at V_{POC} = 1.59 V (TYP.) and not at V_{DDPOC}. The use of the 2.7 V/1.59 V POC mode is recommended when the rise of the voltage, after the power is turned on and until the voltage reaches 1.8 V, is more relaxed than t_{PTH}.

- μPD78F0500FC-AA3-A, 78F0501FC-AA3-A, 78F0502FC-AA3-A, 78F0503FC-AA3-A, 78F0503DFC-AA3-A
- μPD78F0500AFC-AA3-A, 78F0501AFC-AA3-A, 78F0502AFC-AA3-A, 78F0503AFC-AA3-A, 78F0503DAFC-AA3-A

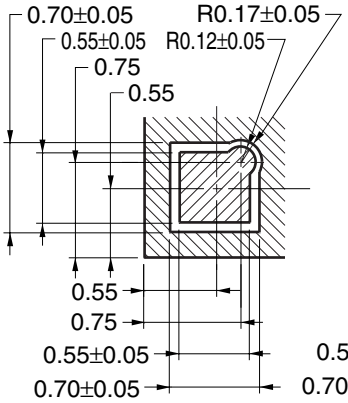
36-PIN PLASTIC FLGA (4x4)



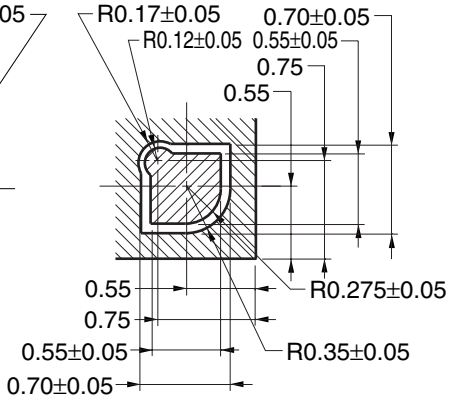
DETAIL OF Ⓒ PART



DETAIL OF Ⓓ PART



DETAIL OF Ⓔ PART

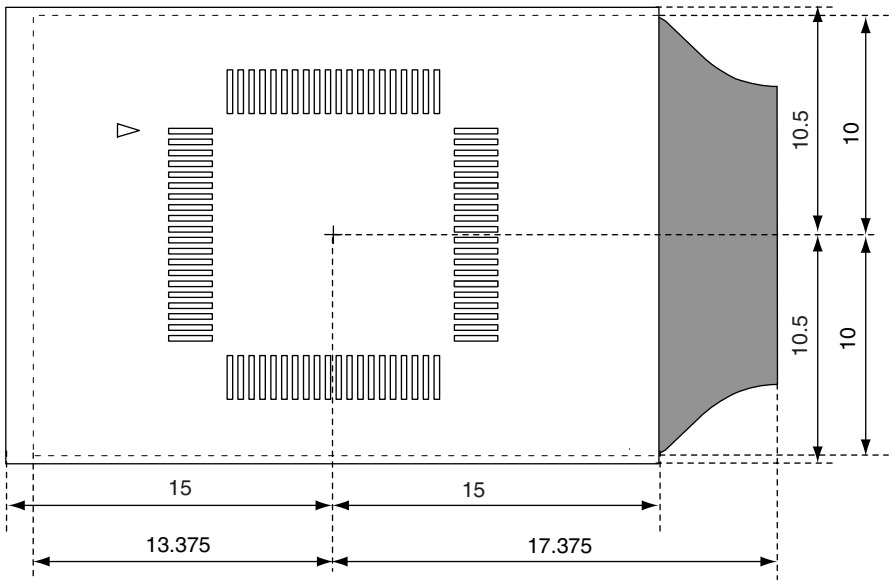


(UNIT:mm)

ITEM	DIMENSIONS
D	4.00±0.10
E	4.00±0.10
w	0.20
e	0.50
A	0.91±0.07
b	0.24±0.05
x	0.05
y	0.08
y1	0.20
ZD	0.75
ZE	0.75

P36FC-50-AA3-2

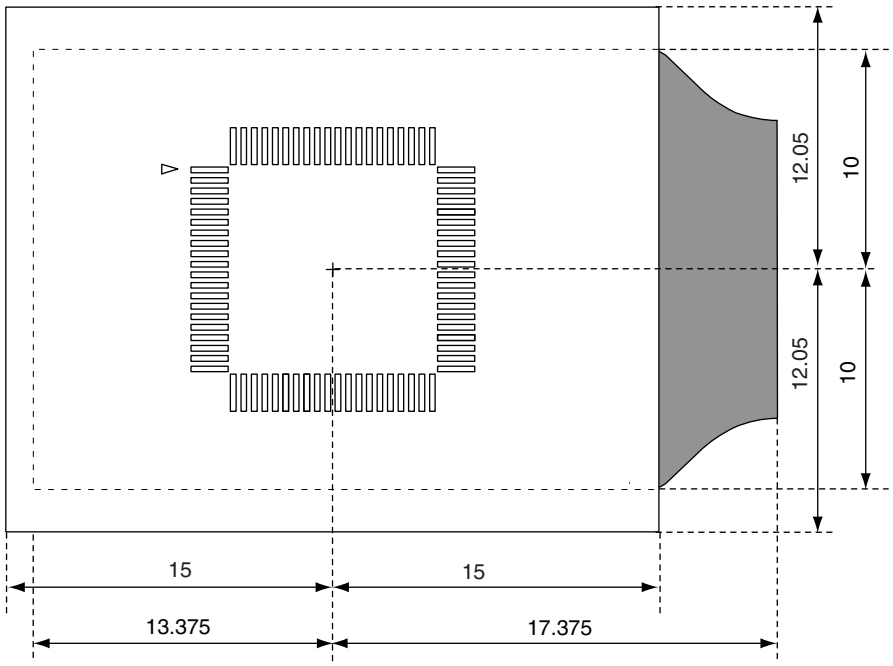
Figure B-10. For 64-Pin GK Package



□ : Exchange adapter area: Components up to 17.45 mm in height can be mounted[Note]
■ : Emulation probe tip area: Components up to 24.45 mm in height can be mounted[Note]

Note Height can be adjusted by using space adapters (each adds 2.4 mm)

Figure B-11. For 80-Pin GC Package



□ : Exchange adapter area: Components up to 17.45 mm in height can be mounted[Note]
■ : Emulation probe tip area: Components up to 24.45 mm in height can be mounted[Note]

Note Height can be adjusted by using space adapters (each adds 2.4 mm)

(4/4)

Edition	Description	Chapter
3rd Edition	Revision of this chapter	**CHAPTER 30 ELECTRICAL SPECIFICATIONS (STANDARD PRODUCTS)**
	Revision of this chapter	**CHAPTER 31 ELECTRICAL SPECIFICATIONS ((A) GRADE PRODUCTS)**
	Addition of this chapter	**CHAPTER 32 ELECTRICAL SPECIFICATIONS ((A2) GRADE PRODUCTS: T_A = –40 to +110°C)**
	Addition of this chapter	**CHAPTER 33 ELECTRICAL SPECIFICATIONS ((A2) GRADE PRODUCTS: T_A = –40 to +125°C)**
	Revision of this chapter	**CHAPTER 35 RECOMMENDED SOLDERING CONDITIONS**
	Revision of this chapter	**APPENDIX A DEVELOPMENT TOOLS**
	Addition of this chapter	**APPENDIX E REVISION HISTORY**