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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded -</u> <u>Microcontrollers</u>"

Details

Product Status	Active
Core Processor	ARM® Cortex®-M4
Core Size	32-Bit Single-Core
Speed	100MHz
Connectivity	CANbus, EBI/EMI, Ethernet, I ² C, IrDA, SD, SPI, UART/USART, USB, USB OTG
Peripherals	DMA, I ² S, LVD, POR, PWM, WDT
Number of I/O	66
Program Memory Size	512KB (512K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	128K x 8
Voltage - Supply (Vcc/Vdd)	1.71V ~ 3.6V
Data Converters	A/D 33x16b; D/A 1x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	100-LQFP
Supplier Device Package	100-LQFP (14x14)
Purchase URL	https://www.e-xfl.com/product-detail/nxp-semiconductors/mk60dn512vll10r

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong



8	Pine	
	8.1	K60 signal multiplexing and pin assignments

	8.2 K60 pinouts	77
9	Revision history	78





1 Ordering parts

1.1 Determining valid orderable parts

Valid orderable part numbers are provided on the web. To determine the orderable part numbers for this device, go to freescale.com and perform a part number search for the following device numbers: PK60 and MK60.

2 Part identification

2.1 Description

Part numbers for the chip have fields that identify the specific part. You can use the values of these fields to determine the specific part you have received.

2.2 Format

Part numbers for this device have the following format:

Q K## A M FFF R T PP CC N

2.3 Fields

This table lists the possible values for each field in the part number (not all combinations are valid):

Field	Description	Values
Q	Qualification status	 M = Fully qualified, general market flow P = Prequalification
K##	Kinetis family	• K60
A	Key attribute	 D = Cortex-M4 w/ DSP F = Cortex-M4 w/ DSP and FPU
М	Flash memory type	 N = Program flash only X = Program flash and FlexMemory

Table continues on the next page...



reminology and guidelines

Field	Description	Values
FFF	Program flash memory size	 32 = 32 KB 64 = 64 KB 128 = 128 KB 256 = 256 KB 512 = 512 KB 1M0 = 1 MB 2M0 = 2 MB
R	Silicon revision	 Z = Initial (Blank) = Main A = Revision after main
Т	Temperature range (°C)	 V = -40 to 105 C = -40 to 85
PP	Package identifier	 FM = 32 QFN (5 mm x 5 mm) FT = 48 QFN (7 mm x 7 mm) LF = 48 LQFP (7 mm x 7 mm) LH = 64 LQFP (10 mm x 10 mm) MP = 64 MAPBGA (5 mm x 5 mm) LK = 80 LQFP (12 mm x 12 mm) LL = 100 LQFP (14 mm x 14 mm) MC = 121 MAPBGA (8 mm x 8 mm) LQ = 144 LQFP (20 mm x 20 mm) MD = 144 MAPBGA (13 mm x 13 mm) MJ = 256 MAPBGA (17 mm x 17 mm)
CC	Maximum CPU frequency (MHz)	 5 = 50 MHz 7 = 72 MHz 10 = 100 MHz 12 = 120 MHz 15 = 150 MHz
N	Packaging type	 R = Tape and reel (Blank) = Trays

2.4 Example

This is an example part number:

MK60DN512ZVMD10

3 Terminology and guidelines

3.1 Definition: Operating requirement

An *operating requirement* is a specified value or range of values for a technical characteristic that you must guarantee during operation to avoid incorrect operation and possibly decreasing the useful life of the chip.



4 Ratings

4.1 Thermal handling ratings

Symbol	Description	Min.	Max.	Unit	Notes
T _{STG}	Storage temperature	-55	150	°C	1
T _{SDR}	Solder temperature, lead-free	—	260	°C	2

1. Determined according to JEDEC Standard JESD22-A103, High Temperature Storage Life.

2. Determined according to IPC/JEDEC Standard J-STD-020, Moisture/Reflow Sensitivity Classification for Nonhermetic Solid State Surface Mount Devices.

4.2 Moisture handling ratings

Symbol	Description	Min.	Max.	Unit	Notes
MSL	Moisture sensitivity level		3	—	1

1. Determined according to IPC/JEDEC Standard J-STD-020, Moisture/Reflow Sensitivity Classification for Nonhermetic Solid State Surface Mount Devices.

4.3 ESD handling ratings

Symbol	Description	Min.	Max.	Unit	Notes
V _{HBM}	Electrostatic discharge voltage, human body model	-2000	+2000	V	1
V _{CDM}	Electrostatic discharge voltage, charged-device model	-500	+500	V	2
I _{LAT}	Latch-up current at ambient temperature of 105°C	-100	+100	mA	3

1. Determined according to JEDEC Standard JESD22-A114, *Electrostatic Discharge (ESD) Sensitivity Testing Human Body Model (HBM)*.

2. Determined according to JEDEC Standard JESD22-C101, Field-Induced Charged-Device Model Test Method for Electrostatic-Discharge-Withstand Thresholds of Microelectronic Components.

3. Determined according to JEDEC Standard JESD78, IC Latch-Up Test.

4.4 Voltage and current operating ratings

\mathbf{A}		

5.2.3 Voltage and current operating behaviors Table 4. Voltage and current operating behaviors

Symbol	Description	Min.	Typ. ¹	Max.	Unit	Notes
V _{OH}	Output high voltage — high drive strength					
	• 2.7 V \leq V _{DD} \leq 3.6 V, I _{OH} = -9mA	V _{DD} – 0.5	—	—	V	
	• 1.71 V \leq V _{DD} \leq 2.7 V, I _{OH} = -3mA	V _{DD} – 0.5	—		V	
	Output high voltage — low drive strength					
	• 2.7 V \leq V _{DD} \leq 3.6 V, I _{OH} = -2mA	V _{DD} – 0.5		_	v	
	• 1.71 V \leq V _{DD} \leq 2.7 V, I _{OH} = -0.6mA	$V_{DD} - 0.5$	_	_	v	
I _{ОНТ}	Output high current total for all ports	_		100	mA	
V _{OL}	Output low voltage — high drive strength					2
	• 2.7 V \leq V _{DD} \leq 3.6 V, I _{OL} = 10mA	_	_	0.5	v	
	• 1.71 V \leq V _{DD} \leq 2.7 V, I _{OL} = 5mA	_	—	0.5	v	
	Output low voltage — low drive strength					
	• 2.7 V \leq V _{DD} \leq 3.6 V, I _{OL} = 2mA	_	_	0.5	v	
	• 1.71 V \leq V _{DD} \leq 2.7 V, I _{OL} = 1mA	_	_	0.5	v	
I _{OLT}	Output low current total for all ports	_		100	mA	
I _{INA}	Input leakage current, analog pins and digital pins configured as analog inputs					3, 4
	• $V_{SS} \le V_{IN} \le V_{DD}$					
	All pins except EXTAL32, XTAL32, EXTAL XTAL	_	0.002	0.5	μA	
	EXTAL (PTA18) and XTAL (PTA19)	—	0.004	1.5	μA	
	• EXTAL32, XTAL32	_	0.075	10	μA	
I _{IND}	Input leakage current, digital pins					4, 5
	• $V_{SS} \le V_{IN} \le V_{IL}$					
	All digital pins	_	0.002	0.5	μA	
	• Vm = Vpp					
	All digital pins except PTD7	_	0.002	0.5	μA	
	PTD7	_	0.004	1	μA	
I _{IND}	Input leakage current, digital pins					4, 5, 6
	• $V_{IL} < V_{IN} < V_{DD}$					
	• V _{DD} = 3.6 V		18	26	μA	
	• V _{DD} = 3.0 V		12	49	μA	
	• V _{DD} = 2.5 V		8	13	μA	
	• V _{DD} = 1.7 V	_	3	6	μA	

Table continues on the next page ...

K60 Sub-Family Data Sheet, Rev. 3, 6/2013.



Peripheral operating requirements and behaviors

Symbol	Description	Min.	Max.	Unit
Τ _f	Clock and data fall time	_	3	ns
Ts	Data setup	3	_	ns
Τ _h	Data hold	2	—	ns

Table 12. Debug trace operating behaviors (continued)







Figure 4. Trace data specifications

6.1.2 JTAG electricals

Table 13. JTAG limited voltage range electricals

Symbol	Description	Min.	Max.	Unit
	Operating voltage	2.7	3.6	V
J1	TCLK frequency of operation			MHz
	Boundary Scan	0	10	
	JTAG and CJTAG	0	25	
	Serial Wire Debug	0	50	
J2	TCLK cycle period	1/J1	_	ns
J3	TCLK clock pulse width			
	Boundary Scan	50	_	ns
	JTAG and CJTAG	20	—	ns
	Serial Wire Debug	10	—	ns
J4	TCLK rise and fall times	—	3	ns
J5	Boundary scan input data setup time to TCLK rise	20		ns

Table continues on the next page ...



Symbol	Description	Min.	Тур.	Max.	Unit	Notes
	Swap Control execution time					
t _{swapx01}	control code 0x01	_	200	—	μs	
t _{swapx02}	control code 0x02	_	70	150	μs	
t _{swapx04}	control code 0x04	_	70	150	μs	
t _{swapx08}	control code 0x08	_	_	30	μs	
	Program Partition for EEPROM execution time					
t _{pgmpart64k}	• 64 KB FlexNVM	_	138	—	ms	
t _{pgmpart256k}	• 256 KB FlexNVM	_	145	—	ms	
	Set FlexRAM Function execution time:					
t _{setramff}	Control Code 0xFF	_	70	_	μs	
t _{setram32k}	32 KB EEPROM backup	_	0.8	1.2	ms	
t _{setram64k}	64 KB EEPROM backup	_	1.3	1.9	ms	
t _{setram256k}	• 256 KB EEPROM backup	_	4.5	5.5	ms	
	Byte-write to FlexRAM	for EEPROM	l operation			
t _{eewr8bers}	Byte-write to erased FlexRAM location execution time	_	175	260	μs	3
	Byte-write to FlexRAM execution time:					
t _{eewr8b32k}	32 KB EEPROM backup	_	385	1800	μs	
t _{eewr8b64k}	64 KB EEPROM backup	_	475	2000	μs	
t _{eewr8b128k}	• 128 KB EEPROM backup	_	650	2400	μs	
t _{eewr8b256k}	256 KB EEPROM backup	_	1000	3200	μs	
	Word-write to FlexRAM	for EEPRON	/ operation			
t _{eewr16bers}	Word-write to erased FlexRAM location execution time		175	260	μs	
	Word-write to FlexRAM execution time:					
t _{eewr16b32k}	• 32 KB EEPROM backup	_	385	1800	μs	
t _{eewr16b64k}	• 64 KB EEPROM backup	_	475	2000	μs	
t _{eewr16b128k}	• 128 KB EEPROM backup	_	650	2400	μs	
t _{eewr16b256k}	• 256 KB EEPROM backup	_	1000	3200	μs	
	Longword-write to FlexRA	M for EEPR	OM operatior	<u>ו</u>		
t _{eewr32bers}	Longword-write to erased FlexRAM location execution time		360	540	μs	
	Longword-write to FlexRAM execution time:					
t _{eewr32b32k}	32 KB EEPROM backup	—	630	2050	μs	
t _{eewr32b64k}	64 KB EEPROM backup	_	810	2250	μs	
t _{eewr32b128k}	128 KB EEPROM backup	—	1200	2675	μs	
t _{eewr32b256k}	• 256 KB EEPROM backup	_	1900	3500	μs	

Table 21. Flash command timing specifications (continued)



rempheral operating requirements and behaviors

2. Specification is valid for all FB_AD[31:0] and FB_TA.

Table 26. Flexbus full voltage range switching specifications

Num	Description	Min.	Max.	Unit	Notes
	Operating voltage	1.71	3.6	V	
	Frequency of operation		FB_CLK	MHz	
FB1	Clock period	1/FB_CLK	_	ns	
FB2	Address, data, and control output valid	_	13.5	ns	1
FB3	Address, data, and control output hold	0	_	ns	1
FB4	Data and FB_TA input setup	13.7	_	ns	2
FB5	Data and FB_TA input hold	0.5	_	ns	2

1. Specification is valid for all FB_AD[31:0], FB_BE/BWEn, FB_CSn, FB_OE, FB_R/W, FB_TBST, FB_TSIZ[1:0], FB_ALE, and FB_TS.

2. Specification is valid for all FB_AD[31:0] and $\overline{FB_TA}$.

rempheral operating requirements and behaviors

Symbol	Description	Conditions	Min.	Typ. ¹	Max.	Unit	Notes
C _{rate}	ADC conversion	16-bit mode					5
	rate	No ADC hardware averaging	37.037	_	461.467	Ksps	
		Continuous conversions enabled, subsequent conversion time					

 Table 27.
 16-bit ADC operating conditions (continued)

- 1. Typical values assume V_{DDA} = 3.0 V, Temp = 25 °C, f_{ADCK} = 1.0 MHz, unless otherwise stated. Typical values are for reference only, and are not tested in production.
- 2. DC potential difference.
- 3. This resistance is external to MCU. To achieve the best results, the analog source resistance must be kept as low as possible. The results in this data sheet were derived from a system that had < 8 Ω analog source resistance. The R_{AS}/C_{AS} time constant should be kept to < 1 ns.
- 4. To use the maximum ADC conversion clock frequency, CFG2[ADHSC] must be set and CFG1[ADLPC] must be clear.
- 5. For guidelines and examples of conversion rate calculation, download the ADC calculator tool.



Figure 13. ADC input impedance equivalency diagram

6.6.1.2 16-bit ADC electrical characteristics Table 28. 16-bit ADC characteristics (V_{REFH} = V_{DDA}, V_{REFL} = V_{SSA})

Symbol	Description	Conditions ¹ .	Min.	Typ. ²	Max.	Unit	Notes
I _{DDA_ADC}	Supply current		0.215		1.7	mA	3

Table continues on the next page ...



Table 28.	16-bit ADC characteristics	$(V_{REFH} = V_{DC})$	_{DA} , V _{REFL} = ^v	V _{SSA}) (continued)
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Symbol	Description	Conditions ¹ .	Min.	Typ. ²	Max.	Unit	Notes
	ADC	• ADLPC = 1, ADHSC = 0	1.2	2.4	3.9	MHz	t _{ADACK} = 1/
	asynchronous clock source	• ADLPC = 1, ADHSC = 1	2.4	4.0	6.1	MHz	† _{ADACK}
† _{ADACK}		• ADLPC = 0, ADHSC = 0	3.0	5.2	7.3	MHz	
		• ADLPC = 0, ADHSC = 1	4.4	6.2	9.5	MHz	
	Sample Time	See Reference Manual chapter	for sample t	imes			
TUE	Total unadjusted	12-bit modes	_	±4	±6.8	LSB ⁴	5
	error	<12-bit modes	—	±1.4	±2.1		
DNL	Differential non-	12-bit modes		±0.7	-1.1 to +1.9	LSB ⁴	5
	linearity				-0.3 to 0.5		
		 <12-bit modes 	—	±0.2			
INL	Integral non-	12-bit modes	—	±1.0	-2.7 to +1.9	LSB ⁴	5
	linearity				-0.7 to +0.5		
		 <12-bit modes 		±0.5			
E _{FS}	Full-scale error	12-bit modes	—	-4	-5.4	LSB ⁴	V _{ADIN} =
		<12-bit modes	—	-1.4	-1.8		V DDA
E .	Quantization	16-bit modes		-1 to 0		I SB4	5
	error	 <13-bit modes 		-1100	+0.5	LOD	
					10.5		
ENOB	Effective number	16-bit differential mode					6
		• Avg = 32	12.8	14.5	_	bits	
		• Avg = 4	11.9	13.8	_	bits	
		16-bit single-ended mode					
		• Avg = 32	10.0	12.0		bito	
		• Avg = 4	12.2	10.1	_	Dits	
	Signal-to-noise		11.4	13.1		DIIS	
SINAD	plus distortion		6.02	2 × ENOB +	1.76	dB	
THD	Total harmonic	16-bit differential mode					7
	distortion	• Avg = 32	—	-94	—	dB	
		16-bit single-ended mode					
		• Avg = 32	—	-85	—	dB	
0500							_
SFDR	Spurious free dvnamic range	16-bit differential mode				15	1
		• Avg = 32	82	95		aв	
		16-bit single-ended mode	70				
		• Avg = 32	78	90		uВ	

Table continues on the next page ...



rempheral operating requirements and behaviors

Symbol	Description	Conditions ¹ .	Min.	Typ. ²	Max.	Unit	Notes
EIL	Input leakage error			$I_{In} \times R_{AS}$		mV	I _{In} = leakage current
							(refer to the MCU's voltage and current operating ratings)
	Temp sensor slope	Across the full temperature range of the device	1.55	1.62	1.69	mV/°C	
V _{TEMP25}	Temp sensor voltage	25 °C	706	716	726	mV	

Table 28. 16-bit ADC characteristics ($V_{REFH} = V_{DDA}$, $V_{REFL} = V_{SSA}$) (continued)

- 1. All accuracy numbers assume the ADC is calibrated with $V_{REFH} = V_{DDA}$
- Typical values assume V_{DDA} = 3.0 V, Temp = 25 °C, f_{ADCK} = 2.0 MHz unless otherwise stated. Typical values are for reference only and are not tested in production.
- The ADC supply current depends on the ADC conversion clock speed, conversion rate and ADC_CFG1[ADLPC] (low power). For lowest power operation, ADC_CFG1[ADLPC] must be set, the ADC_CFG2[ADHSC] bit must be clear with 1 MHz ADC conversion clock speed.
- 4. 1 LSB = $(V_{REFH} V_{REFL})/2^{N}$
- 5. ADC conversion clock < 16 MHz, Max hardware averaging (AVGE = %1, AVGS = %11)
- 6. Input data is 100 Hz sine wave. ADC conversion clock < 12 MHz.
- 7. Input data is 1 kHz sine wave. ADC conversion clock < 12 MHz.

Typical ADC 16-bit Differential ENOB vs ADC Clock 100Hz, 90% FS Sine Input









Typical ADC 16-bit Single-Ended ENOB vs ADC Clock 100Hz, 90% FS Sine Input

Figure 15. Typical ENOB vs. ADC_CLK for 16-bit single-ended mode

6.6.1.3 16-bit ADC with PGA operating conditions Table 29. 16-bit ADC with PGA operating conditions

Symbol	Description	Conditions	Min.	Typ. ¹	Max.	Unit	Notes
V _{DDA}	Supply voltage	Absolute	1.71	—	3.6	V	
V _{REFPGA}	PGA ref voltage		VREF_OU T	VREF_OU T	VREF_OU T	V	2, 3
V _{ADIN}	Input voltage		V _{SSA}	_	V _{DDA}	V	
V _{CM}	Input Common Mode range		V _{SSA}	_	V _{DDA}	V	
R _{PGAD}	Differential input	Gain = 1, 2, 4, 8	_	128	—	kΩ	IN+ to IN- ⁴
	impedance	Gain = 16, 32	—	64	—		
		Gain = 64	—	32	—		
R _{AS}	Analog source resistance		—	100	_	Ω	5
T _S	ADC sampling time		1.25	_		μs	6

Table continues on the next page...



Symbol	Description	Conditions	Min.	Typ. ¹	Max.	Unit	Notes
G	Gain ⁴	PGAG=0	0.95	1	1.05		$R_{AS} < 100\Omega$
		• PGAG=1	1.9	2	2.1		
		• PGAG=2	3.8	4	4.2		
		• PGAG=3	7.6	8	8.4		
		• PGAG=4	15.2	16	16.6		
		• PGAG=5	30.0	31.6	33.2		
		• PGAG=6	58.8	63.3	67.8		
BW	Input signal	16-bit modes	_	_	4	kHz	
	bandwidth	 < 16-bit modes 	_	_	40	kHz	
PSRR	Power supply rejection ratio	Gain=1	-	-84		dB	V _{DDA} = 3V ±100mV, f _{VDDA} = 50Hz, 60Hz
CMRR	Common mode	Gain=1	—	-84	_	dB	V _{CM} =
	rejection ratio	• Gain=64	_	-85	—	dB	500mVpp, f _{VCM} = 50Hz, 100Hz
V _{OFS}	Input offset voltage		_	0.2	—	mV	Output offset = V _{OFS} *(Gain+1)
T _{GSW}	Gain switching settling time		_	_	10	μs	5
dG/dT	Gain drift over full	Gain=1	—	6	10	ppm/°C	
	temperature range	• Gain=64	_	31	42	ppm/°C	
dG/dV _{DDA}	Gain drift over	• Gain=1	_	0.07	0.21	%/V	V _{DDA} from 1.71
	supply voltage	• Gain=64	_	0.14	0.31	%/V	to 3.6V
E _{IL}	Input leakage error	All modes		$I_{\text{ln}} \times R_{\text{AS}}$		mV	I _{In} = leakage current
							(refer to the MCU's voltage and current operating ratings)
V _{PP,DIFF}	Maximum differential input signal swing		$\left(\frac{(\min(V))}{(\min(V))}\right)$	$\frac{V_{x}V_{DDA} - V_{x}}{Gain}$	$(-0.2) \times 4$	V	6
SNR	Signal-to-noise	Gain=1	80	90		dB	16-bit
	ratio	• Gain=64	52	66	_	dB	differential mode, Average=32
THD	Total harmonic	Gain=1	85	100		dB	16-bit
	aistortion	• Gain=64	49	95	_	dB	differential mode, Average=32, f _{in} =100Hz

Table 30. 16-bit ADC with PGA characteristics (continued)

Table continues on the next page...



Symbol	Description	Min.	Тур.	Max.	Unit
V _H	Analog comparator hysteresis ¹				
	• CR0[HYSTCTR] = 00	—	5	—	mV
	 CR0[HYSTCTR] = 01 	—	10	—	mV
	• CR0[HYSTCTR] = 10		20	—	mV
	 CR0[HYSTCTR] = 11 	—	30	—	mV
V _{CMPOh}	Output high	V _{DD} – 0.5	_	—	V
V _{CMPOI}	Output low		_	0.5	V
t _{DHS}	Propagation delay, high-speed mode (EN=1, PMODE=1)	20	50	200	ns
t _{DLS}	Propagation delay, low-speed mode (EN=1, PMODE=0)	80	250	600	ns
	Analog comparator initialization delay ²	_	_	40	μs
I _{DAC6b}	6-bit DAC current adder (enabled)	_	7	—	μA
INL	6-bit DAC integral non-linearity	-0.5	_	0.5	LSB ³
DNL	6-bit DAC differential non-linearity	-0.3	_	0.3	LSB

Table 31. Comparator and 6-bit DAC electrical specifications (continued)

1. Typical hysteresis is measured with input voltage range limited to 0.6 to V_{DD} -0.6 V.

2. Comparator initialization delay is defined as the time between software writes to change control inputs (Writes to DACEN, VRSEL, PSEL, MSEL, VOSEL) and the comparator output settling to a stable level.

3. 1 LSB = $V_{reference}/64$



Peripheral operating requirements and behaviors



Figure 17. Typical hysteresis vs. Vin level (VDD=3.3V, PMODE=1)

6.6.3 12-bit DAC electrical characteristics

6.6.3.1 12-bit DAC operating requirements Table 32. 12-bit DAC operating requirements

Symbol	Desciption	Min.	Max.	Unit	Notes
V _{DDA}	Supply voltage	1.71 3.6		V	
V _{DACR}	Reference voltage	1.13 3.6		V	1
T _A	Temperature	Operating t range of t	emperature he device	°C	
CL	Output load capacitance	— 100		pF	2
١L	Output load current		1	mA	

1. The DAC reference can be selected to be V_{DDA} or the voltage output of the VREF module (VREF_OUT)

2. A small load capacitance (47 pF) can improve the bandwidth performance of the DAC



Peripheral operating requirements and behaviors



Figure 18. Typical INL error vs. digital code



Peripheral operating requirements and behaviors



Figure 21. MII receive signal timing diagram

6.8.1.2 RMII signal switching specifications

The following timing specs meet the requirements for RMII style interfaces for a range of transceiver devices.

Num	Description	Min.	Max.	Unit
—	EXTAL frequency (RMII input clock RMII_CLK)	—	50	MHz
RMII1	RMII_CLK pulse width high	35%	65%	RMII_CLK period
RMII2	RMII_CLK pulse width low	35%	65%	RMII_CLK period
RMII3	RXD[1:0], CRS_DV, RXER to RMII_CLK setup	4		ns
RMII4	RMII_CLK to RXD[1:0], CRS_DV, RXER hold	2		ns
RMII7	RMII_CLK to TXD[1:0], TXEN invalid	4	—	ns
RMII8	RMII_CLK to TXD[1:0], TXEN valid		15	ns

 Table 39.
 RMII signal switching specifications

6.8.2 USB electrical specifications

The USB electricals for the USB On-the-Go module conform to the standards documented by the Universal Serial Bus Implementers Forum. For the most up-to-date standards, visit **usb.org**.



Table 49. I2S/SAI slave mode timing in Normal Run, Wait and Stop modes (limited voltage range) (continued)

Num.	Characteristic	Min.	Max.	Unit
S16	I2S_TX_BCLK to I2S_TXD/I2S_TX_FS output invalid	0	—	ns
S17	I2S_RXD setup before I2S_RX_BCLK	4.5	—	ns
S18	I2S_RXD hold after I2S_RX_BCLK	2	—	ns
S19	I2S_TX_FS input assertion to I2S_TXD output valid ¹	—	25	ns

1. Applies to first bit in each frame and only if the TCR4[FSE] bit is clear



Figure 29. I2S/SAI timing — slave modes

6.8.11.2 Normal Run, Wait and Stop mode performance over the full operating voltage range

This section provides the operating performance over the full operating voltage for the device in Normal Run, Wait and Stop modes.

 Table 50.
 I2S/SAI master mode timing in Normal Run, Wait and Stop modes (full voltage range)

Num.	Characteristic	Min.	Max.	Unit
	Operating voltage	1.71	3.6	V
S1	I2S_MCLK cycle time	40	_	ns
S2	I2S_MCLK pulse width high/low	45%	55%	MCLK period
S3	I2S_TX_BCLK/I2S_RX_BCLK cycle time (output)	80	_	ns
S4	I2S_TX_BCLK/I2S_RX_BCLK pulse width high/low	45%	55%	BCLK period
S5	I2S_TX_BCLK/I2S_RX_BCLK to I2S_TX_FS/ I2S_RX_FS output valid	—	15	ns
S6	I2S_TX_BCLK/I2S_RX_BCLK to I2S_TX_FS/ I2S_RX_FS output invalid	-1.0	—	ns

Table continues on the next page...

K60 Sub-Family Data Sheet, Rev. 3, 6/2013.





Figure 34. K60 100 LQFP Pinout Diagram

9 Revision history

The following table provides a revision history for this document.



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