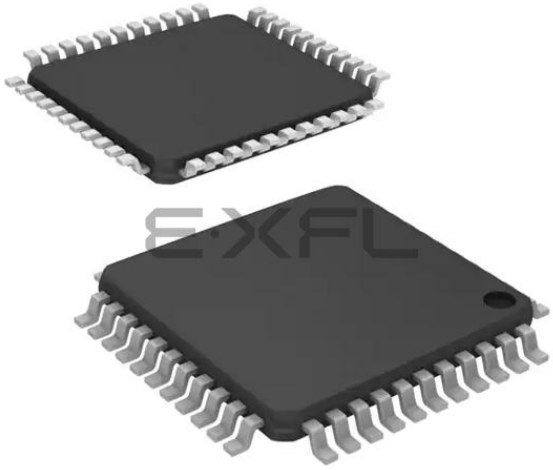

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Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	32MHz
Connectivity	I²C, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	36
Program Memory Size	14KB (8K x 14)
Program Memory Type	FLASH
EEPROM Size	128 x 8
RAM Size	1K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.6V
Data Converters	A/D 28x10b; D/A 4x5b, 4x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	44-TQFP
Supplier Device Package	44-TQFP (10x10)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic16lf1777t-i-pt

1.1 Register and Bit naming conventions

1.1.1 REGISTER NAMES

When there are multiple instances of the same peripheral in a device, the peripheral control registers will be depicted as the concatenation of a peripheral identifier, peripheral instance, and control identifier. The control registers section will show just one instance of all the register names with an 'x' in the place of the peripheral instance number. This naming convention may also be applied to peripherals when there is only one instance of that peripheral in the device to maintain compatibility with other devices in the family that contain more than one.

1.1.2 BIT NAMES

There are two variants for bit names:

- Short name: Bit function abbreviation
- Long name: Peripheral abbreviation + short name

1.1.2.1 Short Bit Names

Short bit names are an abbreviation for the bit function. For example, some peripherals are enabled with the EN bit. The bit names shown in the registers are the short name variant.

Short bit names are useful when accessing bits in C programs. The general format for accessing bits by the short name is *RegisterName*bits.*ShortName*. For example, the enable bit, EN, in the COG1CON0 register can be set in C programs with the instruction `COG1CON0bits.EN = 1`.

Short names are generally not useful in assembly programs because the same name may be used by different peripherals in different bit positions. When this occurs, during the include file generation, all instances of that short bit name are appended with an underscore plus the name of the register in which the bit resides to avoid naming contentions.

1.1.2.2 Long Bit Names

Long bit names are constructed by adding a peripheral abbreviation prefix to the short name. The prefix is unique to the peripheral, thereby making every long bit name unique. The long bit name for the COG1 enable bit is the COG1 prefix, G1, appended with the enable bit short name, EN, resulting in the unique bit name G1EN.

Long bit names are useful in both C and assembly programs. For example, in C the COG1CON0 enable bit can be set with the `G1EN = 1` instruction. In assembly, this bit can be set with the `BSF COG1CON0,G1EN` instruction.

1.1.2.3 Bit Fields

Bit fields are two or more adjacent bits in the same register. Bit fields adhere only to the short bit naming convention. For example, the three Least Significant bits of the COG1CON0 register contain the mode control bits. The short name for this field is MD. There is no long bit name variant. Bit field access is only possible in C programs. The following example demonstrates a C program instruction for setting the COG1 to the Push-Pull mode:

```
COG1CON0bits.MD = 0x5;
```

Individual bits in a bit field can also be accessed with long and short bit names. Each bit is the field name appended with the number of the bit position within the field. For example, the Most Significant mode bit has the short bit name MD2 and the long bit name is G1MD2. The following two examples demonstrate assembly program sequences for setting the COG1 to the Push-Pull mode:

EXAMPLE 1-1:

```
MOVLW  ~(1<<G1MD1)
ANDWF  COG1CON0,F
MOVLW  1<<G1MD2 | 1<<G1MD0
IORWF  COG1CON0,F
```

EXAMPLE 1-2:

```
BSF    COG1CON0,G1MD2
BCF    COG1CON0,G1MD1
BSF    COG1CON0,G1MD0
```

1.1.3 REGISTER AND BIT NAMING EXCEPTIONS

1.1.3.1 Status, Interrupt, and Mirror Bits

Status, interrupt enables, interrupt flags, and mirror bits are contained in registers that span more than one peripheral. In these cases, the bit name shown is unique so there is no prefix or short name variant.

1.1.3.2 Legacy Peripherals

There are some peripherals that do not strictly adhere to these naming conventions. Peripherals that have existed for many years and are present in almost every device are the exceptions. These exceptions were necessary to limit the adverse impact of the new conventions on legacy code. Peripherals that do adhere to the new convention will include a table in the registers section indicating the long name prefix for each peripheral instance. Peripherals that fall into the exception category will not have this table. These peripherals include, but are not limited to, the following:

- EUSART
- MSSP

TABLE 1-4: PERIPHERAL CONNECTION MATRIX

	Peripheral Input																							
Peripheral Output	**ADC Trigger**	**COG Clock**	**COG Rising/Falling**	**COG Shutdown**	**10-bit DAC**	**5-bit DAC**	**PRG Analog Input**	**PRG Rising/Falling**	**Comparator +**	**Comparator -**	**CLC**	**DSM CH**	**DSM CL**	**DSM Mod**	**Op Amp +**	**Op Amp -**	**Op Amp Override**	**10-bit PWM**	**16-bit PWM**	**CCP Capture**	**CCP Clock**	**Timer2/4/6/8 Clock**	**Timer2/4/6/8 Reset**	**Timer1/3/5 Gate**	**Timer0 Clock**
FVR					●	●	●		●	●					●	●									
ZCD											●						●					●			
PRG									●						●	●									
10-bit DAC							●		●						●	●									
5-bit DAC							●		●						●	●									
CCP	●		●					●			●	●	●	●			●						●		
Comparator (sync)	●							●			●						●			●			●	●	
Comparator (async)			●	●										●											
CLC	●		●	●							●	●	●	●			●			●		●	●		
DSM																									
COG																	●								
EUSART TX/CK											●			●											
EUSART DT											●			●											
MSSP SCK/SCL											●			●											
MSSP SDO/SDA											●			●											
Op Amp							●																		
10-bit PWM	●		●					●			●	●	●	●			●						●		
16-bit PWM	●		●					●			●	●	●	●			●						●		
Timer0 overflow	●										●													●	
Timer2 = T2PR				●							●							●			●		●		
Timer4 = T4PR				●							●							●			●		●		
Timer6 = T6PR				●							●							●			●		●		
Timer8 = T8PR				●							●							●			●		●		
Timer2 Postscale	●			●							●							●			●		●		
Timer4 Postscale	●			●							●							●			●		●		
Timer6 Postscale	●			●							●							●			●		●		
Timer8 Postscale	●			●							●							●			●		●		
Timer1 overflow	●										●							●			●				
Timer3 overflow	●										●							●			●				
Timer5 overflow	●										●							●			●				
SOSC																			●			●			
FOSC/4		●																				●			
FOSC		●									●	●	●						●			●			
HFINTOSC		●									●	●	●						●			●			
LFINTOSC											●								●			●			
MFINTOSC																						●			
IOCIF											●									●	●				
PPS Input pin			●	●				●				●	●	●						●	●	●	●	●	●

3.3 Data Memory Organization

The data memory is partitioned in 32 memory banks with 128 bytes in a bank. Each bank consists of (Figure 3-3):

- 12 core registers
- 20 Special Function Registers (SFR)
- Up to 80 bytes of General Purpose RAM (GPR)
- 16 bytes of common RAM

The active bank is selected by writing the bank number into the Bank Select Register (BSR). Unimplemented memory will read as '0'. All data memory can be accessed either directly (via instructions that use the file registers) or indirectly via the two File Select Registers (FSR). See **Section 3.7 "Indirect Addressing"** for more information.

Data memory uses a 12-bit address. The upper five bits of the address define the Bank address and the lower seven bits select the registers/RAM in that bank.

3.3.1 CORE REGISTERS

The core registers contain the registers that directly affect the basic operation. The core registers occupy the first 12 addresses of every data memory bank (addresses x00h/x08h through x0Bh/x8Bh). These registers are listed below in Table 3-2. For detailed information, see Table 3-17.

TABLE 3-2: CORE REGISTERS

Addresses	BANKx
x00h or x80h	INDF0
x01h or x81h	INDF1
x02h or x82h	PCL
x03h or x83h	STATUS
x04h or x84h	FSR0L
x05h or x85h	FSR0H
x06h or x86h	FSR1L
x07h or x87h	FSR1H
x08h or x88h	BSR
x09h or x89h	WREG
x0Ah or x8Ah	PCLATH
x0Bh or x8Bh	INTCON

3.3.1.1 STATUS Register

The STATUS register, shown in Register 3-1, contains:

- the arithmetic status of the ALU
- the Reset status

The STATUS register can be the destination for any instruction, like any other register. If the STATUS register is the destination for an instruction that affects the Z, DC or C bits, then the write to these three bits is disabled. These bits are set or cleared according to the device logic. Furthermore, the $\overline{TO}$ and $\overline{PD}$ bits are not writable. Therefore, the result of an instruction with the STATUS register as destination may be different than intended.

For example, `CLRF STATUS` will clear the upper three bits and set the Z bit. This leaves the STATUS register as '`000u u1uu`' (where u = unchanged).

It is recommended, therefore, that only `BCF`, `BSF`, `SWAPF` and `MOVWF` instructions are used to alter the STATUS register, because these instructions do not affect any Status bits. For other instructions not affecting any Status bits (Refer to **Section 35.0 "Instruction Set Summary"**).

Note:	The C and DC bits operate as $\overline{\text{Borrow}}$ and $\overline{\text{Digit Borrow}}$ out bits, respectively, in subtraction.

TABLE 3-9: PIC16(L)F1777 MEMORY MAP, BANK 16-23

BANK 16		BANK 17		BANK 18		BANK 19		BANK 20		BANK 21		BANK 22		BANK 23	
800h	Core Registers (Table 3-2)	880h	Core Registers (Table 3-2)	900h	Core Registers (Table 3-2)	980h	Core Registers (Table 3-2)	A00h	Core Registers (Table 3-2)	A80h	Core Registers (Table 3-2)	B00h	Core Registers (Table 3-2)	B80h	Core Registers (Table 3-2)
80Bh		88Bh		90Bh		98Bh		A0Bh		A8Bh		B0Bh		B8Bh	
80Ch	—	88Ch	—	90Ch	CM4CON0	98Ch	Unimplemented Read as '0'	A0Ch	Unimplemented Read as '0'	A8Ch	Unimplemented Read as '0'	B0Ch	Unimplemented Read as '0'	B8Ch	Unimplemented Read as '0'
80Dh	COG3PHR		COG4PHR	90Dh	CM4CON1										
80Eh	COG3PHF		COG4PHF	90Eh	CM4NSEL										
80Fh	COG3BLKR		COG4BLKR	90Fh	CM4PSEL										
810h	COG3BLKF		COG4BLKF	910h	CM5CON0										
811h	COG3DBR		COG4DBR	911h	CM5CON1										
812h	COG3DBF		COG4DBF	912h	CM5NSEL										
813h	COG3CON0		COG4CON0	913h	CM5PSEL										
814h	COG3CON1		COG4CON1	914h	CM6CON0										
815h	COG3RIS0		COG4RIS0	915h	CM6CON1										
816h	COG3RIS1		COG4RIS1	916h	CM6NSEL										
817h	COG3RSIM0		COG4RSIM0	917h	CM6PSEL										
818h	COG3RSIM1		COG4RSIM1	918h	CM7CON0										
819h	COG3FIS0		COG4FIS0		CM7CON1										
81Ah	COG3FIS1		COG4FIS1		CM7NSEL										
81Bh	COG3FSIM0		COG4FSIM0		CM7PSEL										
81Ch	COG3FSIM1		COG4FSIM1		CM8CON0										
81Dh	COG3ASD0		COG4ASD0		CM8CON1										
81Eh	COG3ASD1		COG4ASD1		CM8NSEL										
81Fh	COG3STR	89Fh	COG4STR	91Fh	CM8PSEL										
820h	Unimplemented Read as '0'	8A0h	Unimplemented Read as '0'	920h	Unimplemented Read as '0'										
86Fh		8EFh		96Fh		9EFh		A6Fh		AEFh		B6Fh		BEFh	
870h	Accesses 70h – 7Fh	8F0h	Accesses 70h – 7Fh	970h	Accesses 70h – 7Fh	9F0h	Accesses 70h – 7Fh	A70h	Accesses 70h – 7Fh	AF0h	Accesses 70h – 7Fh	B70h	Accesses 70h – 7Fh	BF0h	Accesses 70h – 7Fh
87Fh		8FFh		97Fh		9FFh		A7Fh		AFFh		B7Fh		BFFh	

Legend: = Unimplemented data memory locations, read as '0'.

TABLE 3-18: SPECIAL FUNCTION REGISTER SUMMARY (CONTINUED)

Addr	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR, BOR	Value on all other Resets
Bank 13											
68Ch	—	Unimplemented								—	—
68Dh	COG1PHR	—	—	COG Rising Edge Phase Delay Count Register						--00 0000	--00 0000
68Eh	COG1PHF	—	—	COG Falling Edge Phase Delay Count Register						--00 0000	--00 0000
68Fh	COG1BLKR	—	—	COG Rising Edge Blanking Count Register						--00 0000	--00 0000
690h	COG1BLKF	—	—	COG Falling Edge Blanking Count Register						--00 0000	--00 0000
691h	COG1DBR	—	—	COG Rising Edge Dead-band Count Register						--00 0000	--00 0000
692h	COG1DBF	—	—	COG Falling Edge Dead-band Count Register						--00 0000	--00 0000
693h	COG1CON0	EN	LD	—	CS<1:0>		MD<2:0>			00-0 0000	00-0 0000
694h	COG1CON1	RDBS	FDBS	—	—	POLD	POLC	POLB	POLA	00-- 0000	00-- 0000
695h	COG1RIS0	RIS7	RIS6	RIS5	RIS4	RIS3	RIS2	RIS1	RIS0	0000 0000	0000 0000
696h	COG1RIS1	RIS15	RIS14	RIS13	RIS12	RIS11	RIS10	RIS9	RIS8	0000 0000	0000 0000
697h	COG1RSIM0	RSIM7	RSIM6	RSIM5	RSIM4	RSIM3	RSIM2	RSIM1	RSIM0	0000 0000	0000 0000
698h	COG1RSIM1	RSIM15	RSIM14	RSIM13	RSIM12	RSIM11	RSIM10	RSIM9	RSIM8	0000 0000	0000 0000
699h	COG1FIS0	FIS7	FIS6	FIS5	FIS4	FIS3	FIS2	FIS1	FIS0	0000 0000	0000 0000
69Ah	COG1FIS1	FIS15	FIS14	FIS13	FIS12	FIS11	FIS10	FIS9	FIS8	0000 0000	0000 0000
69Bh	COG1FSIM0	FSIM7	FSIM6	FSIM5	FSIM4	FSIM3	FSIM2	FSIM1	FSIM0	0000 0000	0000 0000
69Ch	COG1FSIM1	FSIM15	FSIM14	FSIM13	FSIM12	FSIM11	FSIM10	FSIM9	FSIM8	0000 0000	0000 0000
69Dh	COG1ASD0	ASE	ARSEN	ASDBD<1:0>		ASDAC<1:0>		—	—	0001 01--	0001 01--
69Eh	COG1ASD1	AS7E	AS6E	AS5E	AS4E	AS3E	AS2E	AS1E	AS0E	0000 0000	0000 0000
69Fh	COG1STR	SDATD	SDATC	SDATB	SDATA	STRD	STRC	STRB	STRA	0000 0000	0000 0000

Legend: x = unknown, u = unchanged, q = value depends on condition, - = unimplemented, read as '0', r = reserved.
Shaded locations are unimplemented, read as '0'.

Note 1: Unimplemented, read as '1'.
2: Unimplemented on PIC16LF1777/8/9.
3: Unimplemented on PIC16(L)F1778.

TABLE 3-18: SPECIAL FUNCTION REGISTER SUMMARY (CONTINUED)

Addr	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR, BOR	Value on all other Resets
Bank 26											
D0Ch — D1Ah	—	Unimplemented								—	—
D1Bh	MD4CON0(3)	EN	—	OUT	OPOL	—	—	—	BIT	0-00 ---0	0-00 ---0
D1Ch	MD4CON1(3)	—	—	CHPOL	CHSYNC	—	—	CLPOL	CLSYNC	--00 --00	--00 --00
D1Dh	MD4SRC(3)	—	—	—	MS<4:0>					---0 0000	---0 0000
D1Eh	MD4CARL(3)	—	—	—	CL<4:0>					---0 0000	---0 0000
D1Fh	MD4CARH(3)	—	—	—	CH<4:0>					---0 0000	---0 0000

Legend: x = unknown, u = unchanged, q = value depends on condition, - = unimplemented, read as '0', r = reserved.
Shaded locations are unimplemented, read as '0'.

Note 1: Unimplemented, read as '1'.
2: Unimplemented on PIC16LF1777/8/9.
3: Unimplemented on PIC16(L)F1778.

5.4 Two-Speed Clock Start-up Mode

Two-Speed Start-up mode provides additional power savings by minimizing the latency between external oscillator start-up and code execution. In applications that make heavy use of the Sleep mode, Two-Speed Start-up will remove the external oscillator start-up time from the time spent awake and can reduce the overall power consumption of the device. This mode allows the application to wake-up from Sleep, perform a few instructions using the INTOSC internal oscillator block as the clock source and go back to Sleep without waiting for the external oscillator to become stable.

Two-Speed Start-up provides benefits when the oscillator module is configured for LP, XT or HS modes. The Oscillator Start-up Timer (OST) is enabled for these modes and must count 1024 oscillations before the oscillator can be used as the system clock source.

If the oscillator module is configured for any mode other than LP, XT or HS mode, then Two-Speed Start-up is disabled. This is because the external clock oscillator does not require any stabilization time after POR or an exit from Sleep.

If the OST count reaches 1024 before the device enters Sleep mode, the OSTS bit of the OSCSTAT register is set and program execution switches to the external oscillator. However, the system may never operate from the external oscillator if the time spent awake is very short.

Note:	Executing a SLEEP instruction will abort the oscillator start-up time and will cause the OSTS bit of the OSCSTAT register to remain clear.

5.4.1 TWO-SPEED START-UP MODE CONFIGURATION

Two-Speed Start-up mode is configured by the following settings:

- IESO (of the Configuration Words) = 1; Internal/External Switchover bit (Two-Speed Start-up mode enabled).
- SCS (of the OSCCON register) = 00.
- FOSC<2:0> bits in the Configuration Words configured for LP, XT or HS mode.

Two-Speed Start-up mode is entered after:

- Power-on Reset (POR) and, if enabled, after Power-up Timer (PWRT) has expired, or
- Wake-up from Sleep.

TABLE 5-1: OSCILLATOR SWITCHING DELAYS

Switch From	Switch To	Frequency	Oscillator Delay
Sleep	LFINTOSC(1) MFINTOSC(1) HFINTOSC(1)	31 kHz 31.25 kHz-500 kHz 31.25 kHz-16 MHz	Oscillator Warm-up Delay (TWARM)(2)
Sleep/POR	EC, RC(1)	DC – 32 MHz	2 cycles
LFINTOSC	EC, RC(1)	DC – 32 MHz	1 cycle of each
Sleep/POR	Secondary Oscillator LP, XT, HS(1)	32 kHz-20 MHz	1024 Clock Cycles (OST)
Any clock source	MFINTOSC(1) HFINTOSC(1)	31.25 kHz-500 kHz 31.25 kHz-16 MHz	2 μs (approx.)
Any clock source	LFINTOSC(1)	31 kHz	1 cycle of each
Any clock source	Secondary Oscillator	32 kHz	1024 Clock Cycles (OST)
PLL inactive	PLL active	16-32 MHz	2 ms (approx.)

Note 1: PLL inactive.

2: See **Section 36.0 “Electrical Specifications”**.

8.2 Low-Power Sleep Mode

The PIC16F1773/6 devices contain an internal Low Dropout (LDO) voltage regulator, which allows the device I/O pins to operate at voltages up to 5.5V while the internal device logic operates at a lower voltage. The LDO and its associated reference circuitry must remain active when the device is in Sleep mode. The PIC16F1773/6 allow the user to optimize the operating current in Sleep, depending on the application requirements.

A Low-Power Sleep mode can be selected by setting the VREGPM bit of the VREGCON register. With this bit set, the LDO and reference circuitry are placed in a low-power state when the device is in Sleep.

8.2.1 SLEEP CURRENT VS. WAKE-UP TIME

In the Default Operating mode, the LDO and reference circuitry remain in the normal configuration while in Sleep. The device is able to exit Sleep mode quickly since all circuits remain active. In Low-Power Sleep mode, when waking up from Sleep, an extra delay time is required for these circuits to return to the normal configuration and stabilize.

The Low-Power Sleep mode is beneficial for applications that stay in Sleep mode for long periods of time. The Normal mode is beneficial for applications that need to wake from Sleep quickly and frequently.

8.2.2 PERIPHERAL USAGE IN SLEEP

Some peripherals that can operate in Sleep mode will not operate properly with the Low-Power Sleep mode selected. The Low-Power Sleep mode is intended for use with the following peripherals only:

- Brown-out Reset (BOR)
- Watchdog Timer (WDT)
- External interrupt pin/interrupt-on-change pins
- Timer1 (with external clock source < 100 kHz)

Note:	The PIC16LF1777/8/9 do not have a configurable Low-Power Sleep mode. PIC16LF1777/8/9 are unregulated devices and are always in the lowest power state when in Sleep, with no wake-up time penalty. These devices have a lower maximum V_{DD} and I/O voltage than the PIC16F1777/8/9. See **Section 36.0 "Electrical Specifications"** for more information.

EXAMPLE 10-2: ERASING ONE ROW OF PROGRAM MEMORY

```
; This row erase routine assumes the following:
; 1. A valid address within the erase row is loaded in ADDRH:ADDRL
; 2. ADDRH and ADDRL are located in shared data memory 0x70 - 0x7F (common RAM)


        BCF         INTCON,GIE      ; Disable ints so required sequences will execute properly
        BANKSEL     PMADRL
        MOVF        ADDRL,W         ; Load lower 8 bits of erase address boundary
        MOVWF       PMADRL
        MOVF        ADDRH,W         ; Load upper 6 bits of erase address boundary
        MOVWF       PMADRH
        BCF         PMCON1,CFGS     ; Not configuration space
        BSF         PMCON1,FREE     ; Specify an erase operation
        BSF         PMCON1,WREN     ; Enable writes

Required
Sequence
        MOVLW       55h             ; Start of required sequence to initiate erase
        MOVWF       PMCON2          ; Write 55h
        MOVLW       0AAh            ;
        MOVWF       PMCON2          ; Write AAh
        BSF         PMCON1,WR       ; Set WR bit to begin erase
        NOP                         ; NOP instructions are forced as processor starts
        NOP                         ; row erase of program memory.
                                    ;
                                    ; The processor stalls until the erase process is complete
                                    ; after erase processor continues with 3rd instruction

        BCF         PMCON1,WREN     ; Disable writes
        BSF         INTCON,GIE      ; Enable interrupts
```

18.7 Register Definitions: DAC Control

Long bit name prefixes for the 10-bit DAC peripherals are shown in Table 18-2. Refer to **Section 1.1 "Register and Bit naming conventions"** for more information

TABLE 18-2:

Peripheral	Bit Name Prefix
DAC1	DAC1
DAC2	DAC2
DAC5	DAC5
DAC6(1)	DAC6

Note 1: PIC16(L)F1777/9 only.

REGISTER 18-1: DACxCON0: DAC CONTROL REGISTER 0

R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
EN	FM	OE1	OE2	PSS<1:0>		NSS<1:0>	
bit 7							bit 0

Legend:		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7 **EN:** DAC Enable bit
- 1 = DACx is enabled
- 0 = DACx is disabled

bit 6 **FM:** DAC Reference Format bit
- 1 = DACx reference selection is left justified
- 0 = DACx reference selection is right justified

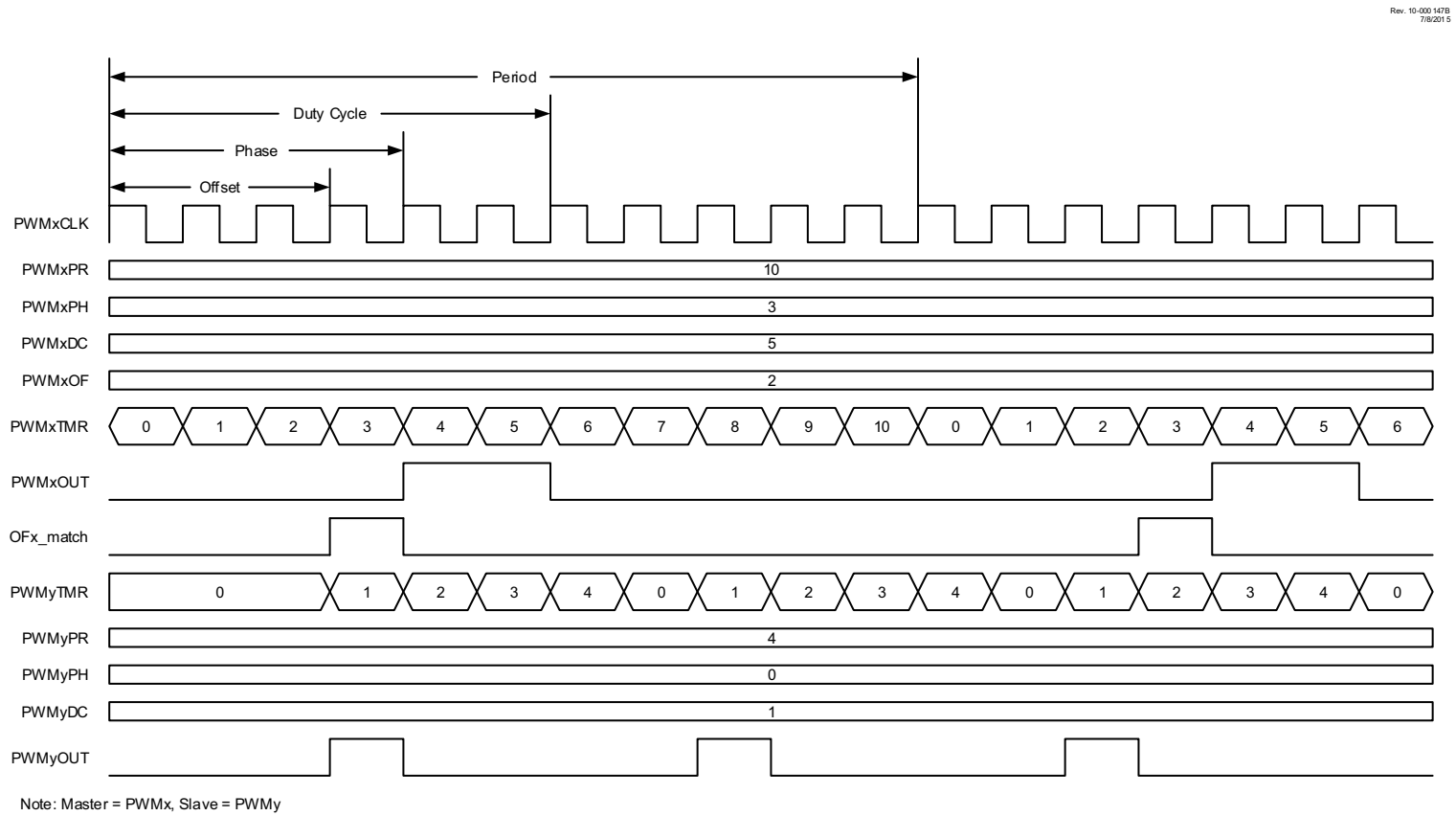
bit 5 **OE1:** DAC Voltage Output Enable bit
- 1 = DACx voltage level is also an output on the DACxOUT1 pin
- 0 = DACx voltage level is disconnected from the DACxOUT1 pin

bit 4 **OE2:** DAC Voltage Output Enable bit
- 1 = DACx voltage level is also an output on the DACxOUT2 pin
- 0 = DACx voltage level is disconnected from the DACxOUT2 pin

bit 3-2 **PSS<1:0>:** DAC Positive Source Select bits
- 11 = DACxREF1+ (DAC5/6) or Reserved (DAC1/2)
- 10 = FVR_buffer2
- 01 = DACxREF0+
- 00 = V_{DD}

bit 1-0 **NSS<1:0>:** DAC Negative Source Select bit
- 11 = Reserved. Do not use.
- 10 = DACxREF1- (DAC5/6) or Reserved (DAC1/2)
- 01 = DACxREF0-
- 00 = A_{GND} (AV_{SS})

FIGURE 26-9: SLAVE RUN MODE WITH SYNC START TIMING DIAGRAM



27.3 Modes of Operation

27.3.1 STEERED PWM MODES

In Steered PWM mode, the PWM signal derived from the input event sources is output as a single phase PWM which can be steered to any combination of the four COG outputs. Output steering takes effect on the instruction cycle following the write to the COGxSTR register.

Synchronous Steered PWM mode is identical to the Steered PWM mode except that changes to the output steering take effect on the first rising event after the COGxSTR register write. Static output data is not synchronized.

Steering mode configurations are shown in Figure 27-2 and Figure 27-3.

Steered PWM and Synchronous Steered PWM modes are selected by setting the MD<2:0> bits of the COGxCON0 register (Register 27-1) to '000' and '001', respectively.

27.3.2 FULL-BRIDGE MODES

In both Forward and Reverse Full-Bridge modes, two of the four COG outputs are active and the other two are inactive. Of the two active outputs, one is modulated by the PWM input signal and the other is on at 100% duty cycle. When the direction is changed, the dead-band time is inserted to delay the modulated output. This gives the unmodulated driver time to shut down, thereby, preventing shoot-through current in the series connected power devices.

In Forward Full-Bridge mode, the PWM input modulates the COGxD output and drives the COGA output at 100%.

In Reverse Full-Bridge mode, the PWM input modulates the COGxB output and drives the COGxC output at 100%.

The full-bridge configuration is shown in Figure 27-4. Typical full-bridge waveforms are shown in Figure 27-12 and Figure 27-13.

Full-Bridge Forward and Full-Bridge Reverse modes are selected by setting the MD<2:0> bits of the COGxCON0 register to '010' and '011', respectively.

FIGURE 27-1: EXAMPLE OF FULL-BRIDGE APPLICATION

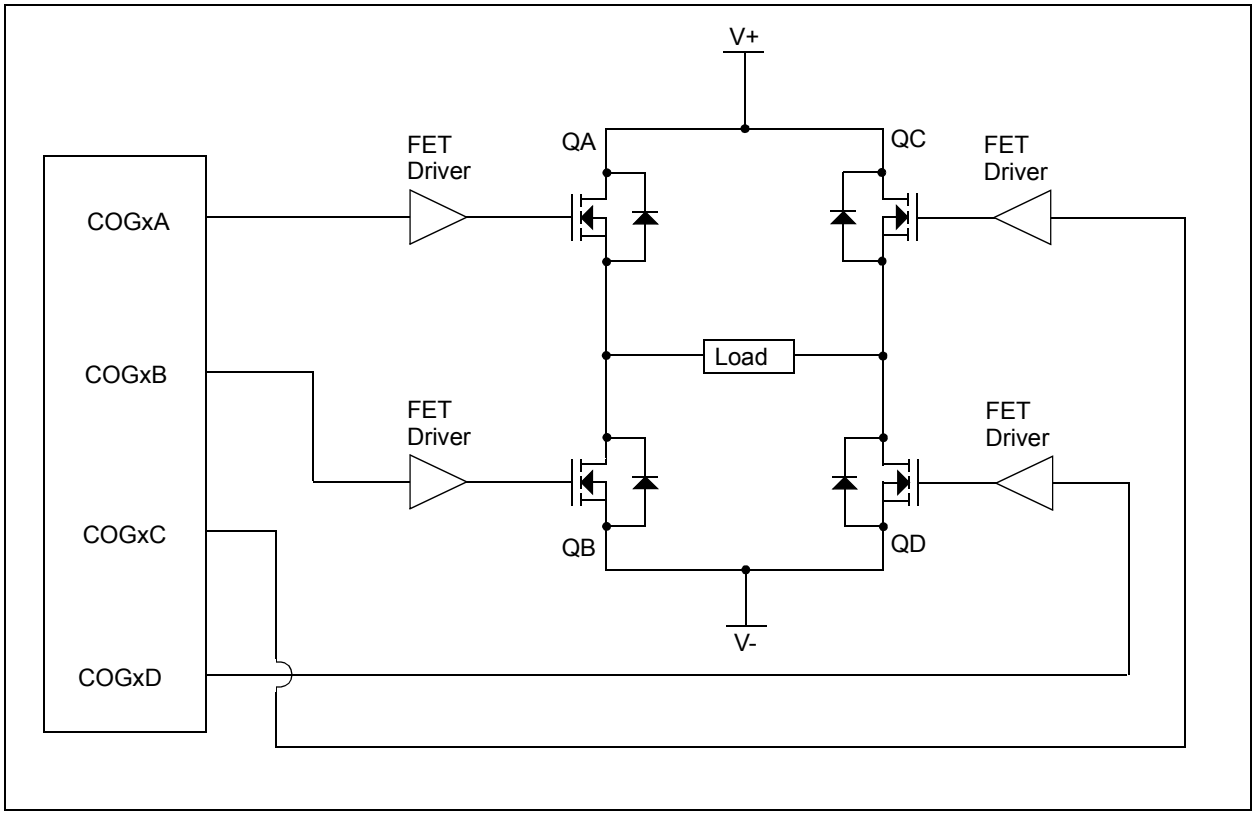
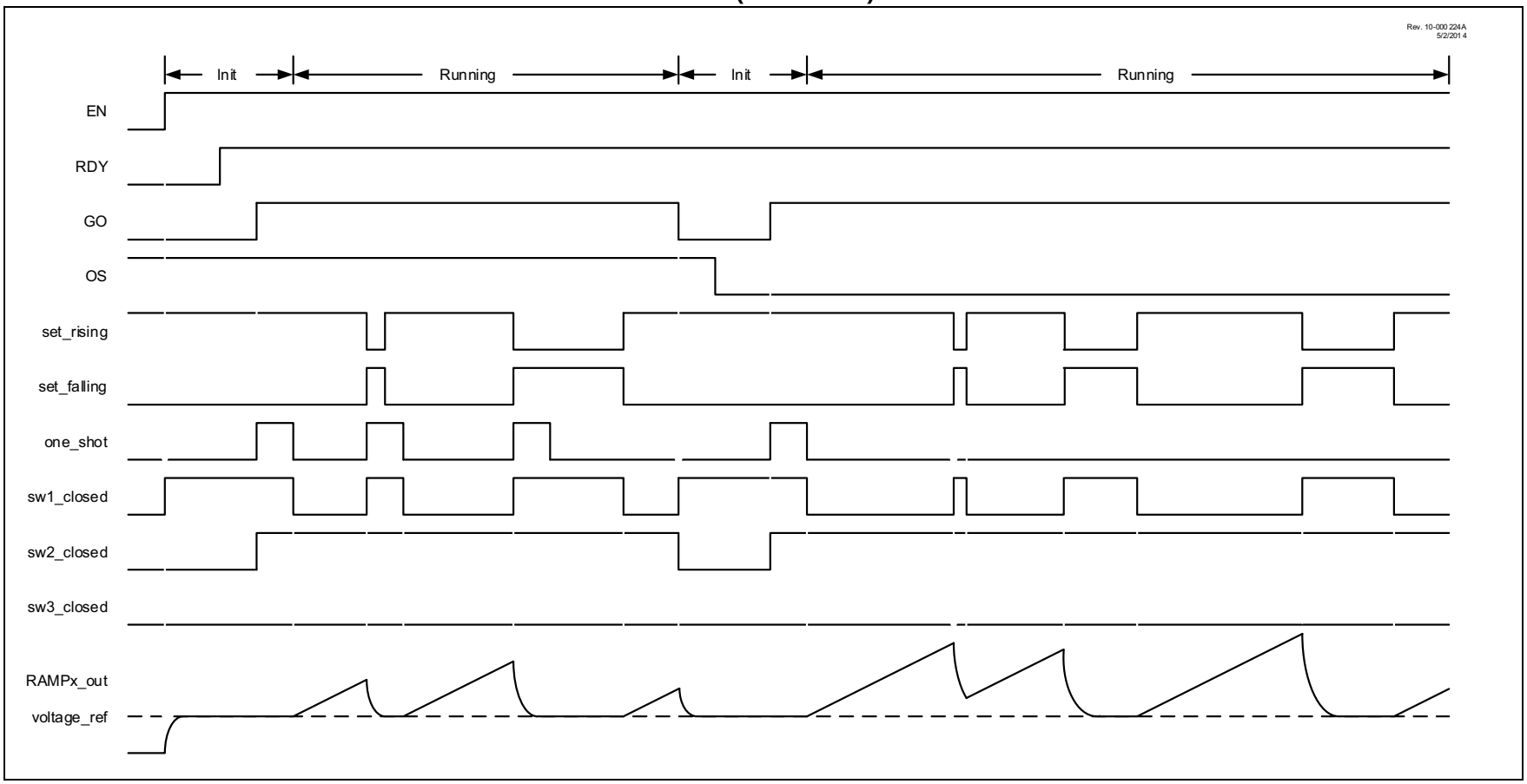


TABLE 29-6: SUMMARY OF REGISTERS ASSOCIATED WITH OP AMPS

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register on Page
ANSELB	---	---	ANSB5	ANSB4	ANSB3	ANSB2	ANSB1	ANSB0	182
ANSELC	ANSC7	ANSC6	ANSC5	ANSC4	ANSC3	ANSC2	—	—	187
DAC1CON0	EN	FM	OE1	OE2	PSS<1:0>		NSS<1:0>		249
DAC2CON0	EN	FM	OE1	OE2	PSS<1:0>		NSS<1:0>		249
DAC5CON0	EN	FM	OE1	OE2	PSS<1:0>		NSS<1:0>		249
DAC3CON0	EN	—	OE1	OE2	PSS<1:0>		NSS<1:0>		244
DAC4CON0	EN	—	OE1	OE2	PSS<1:0>		NSS<1:0>		244
DAC7CON0	EN	—	OE1	OE2	PSS<1:0>		NSS<1:0>		244
DAC3REF	---	---	---	REF<4:0>					245
DAC4REF	---	---	---	REF<4:0>					245
DAC7REF	---	---	---	REF<4:0>					245
DAC1REFH	REF<9:x> (x Depends on FM bit)								250
DAC2REFH	REF<9:x> (x Depends on FM bit)								250
DAC5REFH	REF<9:x> (x Depends on FM bit)								250
FVRCON	FVREN	FVRRDY	TSEN	TSRNG	CDAFVR<1:0>		ADFVR<1:0>		223
OPAxCON	EN	—	—	UG	—	ORPOL	ORM<1:0>		408
OPAxNCHS	—	—	—	—	NCH<3:0>				410
OPAxPCHS	—	—	—	—	PCH<3:0>				411
OPAxORS	—	—	—	ORS<4:0>					409
TRISB	TRISB7	TRISB6	TRISB5	TRISB4	TRISB3	TRISB2	TRISB1	TRISB0	181
TRISC	TRISC7	TRISC6	TRISC5	TRISC4	TRISC3	TRISC2	TRISC1	TRISC0	186

Legend: — = unimplemented location, read as '0'. Shaded cells are not used by op amps.

FIGURE 30-5: RISING RAMP GENERATION TIMING DIAGRAM (MODE = 10)



REGISTER 30-4: PRGxCON2: PROGRAMMABLE RAMP GENERATOR CONTROL 2 REGISTER

U-0	U-0	U-0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
—	—	—	ISET<4:0>				
bit 7							bit 0

Legend:		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as ‘0’
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
‘1’ = Bit is set	‘0’ = Bit is cleared	q = value depends on configuration bits

bit 7-5 **Unimplemented:** Read as ‘0’

bit 4-0 **ISET<4:0>:** PRG Current Source/Sink Set bits
Current source/sink setting and slope rate. See Table 30-4.

TABLE 30-4: PROGRAMMABLE RAMP GENERATOR CURRENT SETTINGS

ISET<4:0>	Current Setting (uA)	Slope Rate (V/us)	ISET<4:0>	Current Setting (uA)	Slope Rate (V/us)
0h	2	0.2	10h	10	1.0
1h	2.5	0.25	11h	11	1.1
2h	3	0.3	12h	12	1.2
3h	3.5	0.35	13h	13	1.3
4h	4	0.4	14h	14	1.4
5h	4.5	0.45	15h	15	1.5
6h	5	0.5	16h	16	1.6
7h	5.5	0.55	17h	17	1.7
8h	6	0.6	18h	18	1.8
9h	6.5	0.65	19h	19	1.9
Ah	7	0.7	1Ah	20	2.0
Bh	7.5	0.75	1Bh	21	2.1
Ch	8	0.8	1Ch	22	2.2
Dh	8.5	0.85	1Dh	23	2.3
Eh	9	0.9	1Eh	24	2.4
Fh	9.5	0.95	1Fh	25	2.5

TABLE 30-5: PROGRAMMABLE RAMP GENERATOR TIMING SOURCES

RTSS<3:0>/ FTSS<3:0>	PRG1 Timing Source	PRG2 Timing Source	PRG3 Timing Source	PRG4 Timing Source(2)
1111	Reserved	Reserved	PWM12_output(2)	PWM12_output
1110	Reserved	Reserved	PWM11_output	PWM11_output
1101	LC2_out	LC2_out	PWM6_output	PWM6_output
1100	LC1_out	LC1_out	PWM5_output	PWM5_output
1011	PWM10_output(2)	PWM10_output(2)	Reserved	Reserved
1010	PWM9_output	PWM9_output	Reserved	Reserved
1001	PWM4_output	PWM4_output	LC4_out(2)	LC4_out
1000	PWM3_output	PWM3_output	LC3_out	LC3_out
0111	PRGxR/PRGxF Pin(1)	PRGxR/PRGxF Pin(1)	PRGxR/PRGxF Pin(1)	PRGxR/PRGxF Pin(1)
0110	Reserved	Reserved	sync_C7OUT(2)	sync_C7OUT
0101	Reserved	Reserved	sync_C6OUT	sync_C6OUT
0100	Reserved	Reserved	sync_C5OUT	sync_C5OUT
0011	sync_C4OUT	sync_C4OUT	Reserved	Reserved
0010	sync_C3OUT	sync_C3OUT	Reserved	Reserved
0001	sync_C2OUT	sync_C2OUT	Reserved	Reserved
0000	sync_C1OUT	sync_C1OUT	Reserved	Reserved

Note 1: Input pin is selected with the PRGxRPPS or PRGxFPPS register.
2: PIC16(L)F1777/9 only.

REGISTER 31-2: MDxCON1: MODULATION CONTROL REGISTER 1

U-0	U-0	R/W-0/0	R/W-0/0	U-0	U-0	R/W-0/0	R/W-0/0
—	—	CHPOL	CHSYNC	—	—	CLPOL	CLSYNC
bit 7							bit 0

Legend:		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as ‘0’
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
‘1’ = Bit is set	‘0’ = Bit is cleared	

bit 7-6 **Unimplemented:** Read as ‘0’

bit 5 **CHPOL:** Modulation High Carrier Polarity Select bit
1 = Selected high carrier source is inverted
0 = Selected high carrier source is not inverted

bit 4 **CHSYNC:** Modulation High Carrier Synchronization Enable bit
1 = Modulator waits for a low edge on the high carrier before allowing a switch to the low carrier
0 = Modulator output is not synchronized to the high carrier(1)

bit 3-2 **Unimplemented:** Read as ‘0’

bit 1 **CLPOL:** Modulation Low Carrier Polarity Select bit
1 = Selected low carrier source is inverted
0 = Selected low carrier source is not inverted

bit 0 **CLSYNC:** Modulation Low Carrier Synchronization Enable bit
1 = Modulator waits for a low edge on the low carrier before allowing a switch to the high carrier
0 = Modulator output is not synchronized to the low carrier(1)

Note 1: Narrowed carrier pulse widths or spurs may occur in the signal stream if the carrier is not synchronized.

REGISTER 31-3: MDxSRC: MODULATION SOURCE CONTROL REGISTER

U-0	U-0	U-0	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u
—	—	—	MS<4:0>				
bit 7							bit 0

Legend:		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as ‘0’
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
‘1’ = Bit is set	‘0’ = Bit is cleared	

bit 7-5 **Unimplemented:** Read as ‘0’

bit 4-0 **MS<4:0>** Modulation Source Selection bits
See Table 31-4 or Table 31-5.

FIGURE 32-20: I²C SLAVE, 10-BIT ADDRESS, RECEPTION (SEN = 1, AHEN = 0, DHEN = 0)

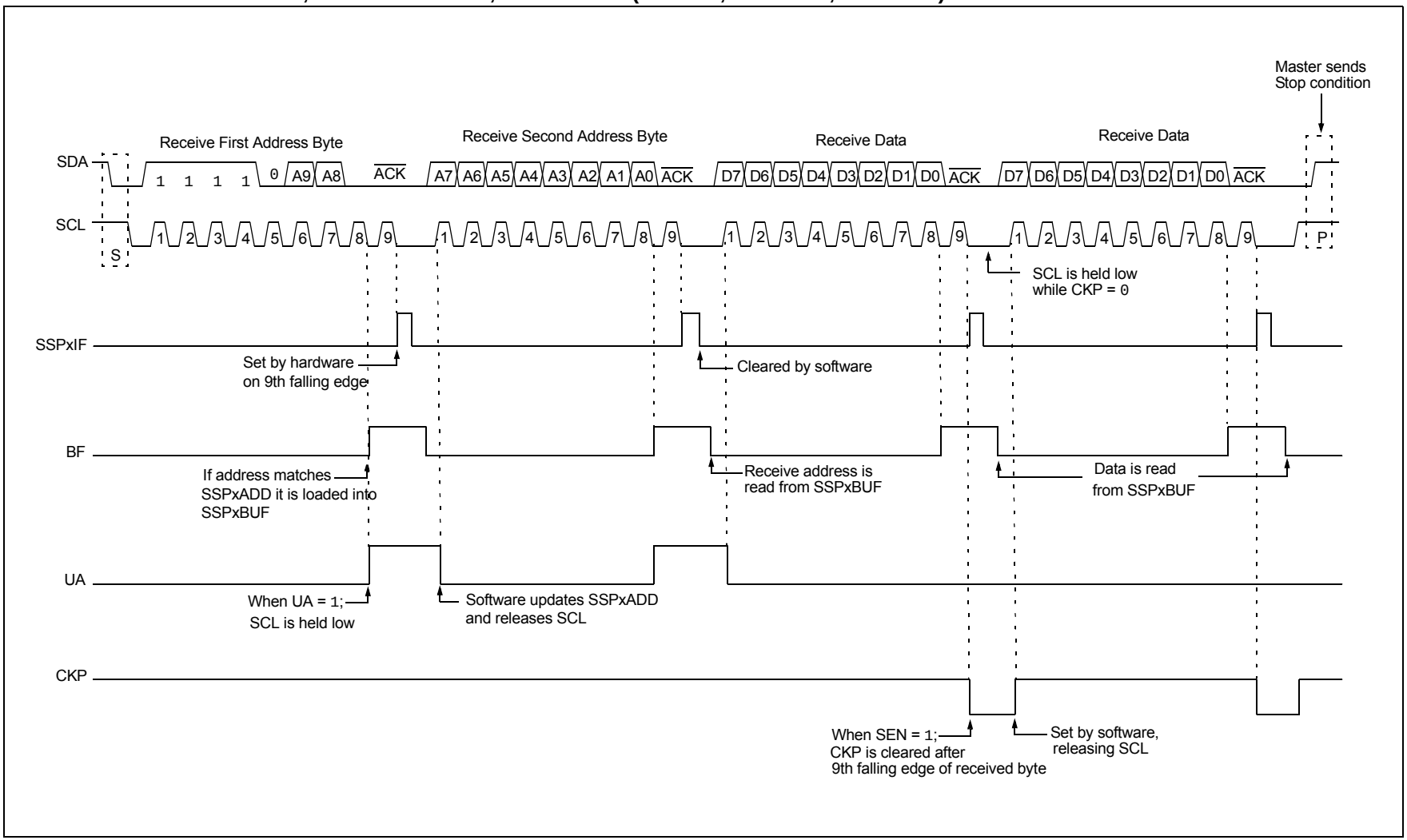


TABLE 36-27: I^2C BUS DATA REQUIREMENTS

Standard Operating Conditions (unless otherwise stated)							
Param. No.	**Symbol**	**Characteristic**		**Min.**	**Max.**	**Units**	**Conditions**
SP100*	THIGH	Clock high time	100 kHz mode	4.0	—	μs	Device must operate at a minimum of 1.5 MHz
			400 kHz mode	0.6	—	μs	Device must operate at a minimum of 10 MHz
			SSP module	1.5TCY	—		
SP101*	TLOW	Clock low time	100 kHz mode	4.7	—	μs	Device must operate at a minimum of 1.5 MHz
			400 kHz mode	1.3	—	μs	Device must operate at a minimum of 10 MHz
			SSP module	1.5TCY	—		
SP102*	TR	SDA and SCL rise time	100 kHz mode	—	1000	ns	
			400 kHz mode	20 + 0.1CB	300	ns	CB is specified to be from 10-400 pF
SP103*	TF	SDA and SCL fall time	100 kHz mode	—	250	ns	
			400 kHz mode	20 + 0.1CB	250	ns	CB is specified to be from 10-400 pF
SP106*	THD:DAT	Data input hold time	100 kHz mode	0	—	ns	
			400 kHz mode	0	0.9	μs	
SP107*	TSU:DAT	Data input setup time	100 kHz mode	250	—	ns	**(Note 2)**
			400 kHz mode	100	—	ns	
SP109*	TAA	Output valid from clock	100 kHz mode	—	3500	ns	**(Note 1)**
			400 kHz mode	—	—	ns	
SP110*	TBUF	Bus free time	100 kHz mode	4.7	—	μs	Time the bus must be free before a new transmission can start
			400 kHz mode	1.3	—	μs	
SP111	CB	Bus capacitive loading		—	400	pF	

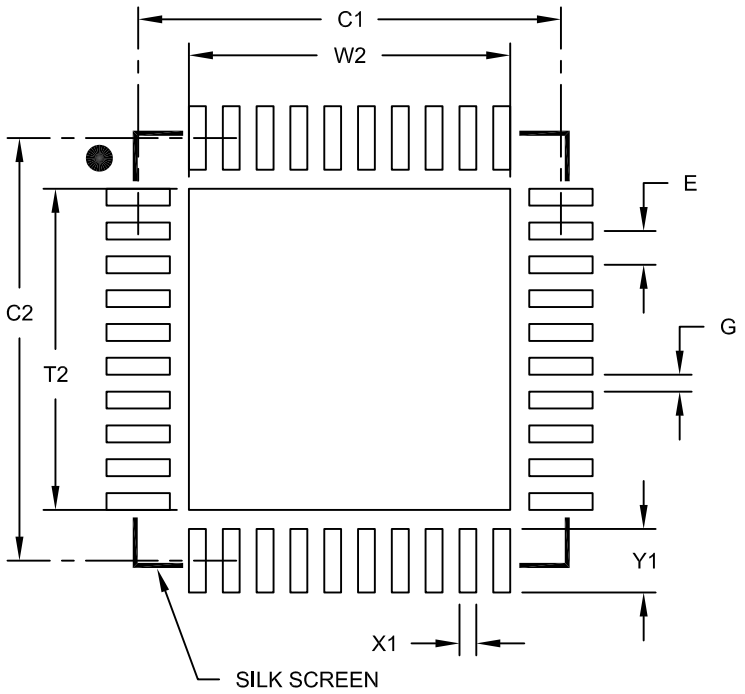
* These parameters are characterized but not tested.

Note 1: As a transmitter, the device must provide this internal minimum delay time to bridge the undefined region (min. 300 ns) of the falling edge of SCL to avoid unintended generation of Start or Stop conditions.

2: A Fast mode (400 kHz) I^2C bus device can be used in a Standard mode (100 kHz) I^2C bus system, but the requirement $T_{SU:DAT} \geq 250$ ns must then be met. This will automatically be the case if the device does not stretch the low period of the SCL signal. If such a device does stretch the low period of the SCL signal, it must output the next data bit to the SDA line T_R max. + $T_{SU:DAT}$ = 1000 + 250 = 1250 ns (according to the Standard mode I^2C bus specification), before the SCL line is released.

40-Lead Plastic Ultra Thin Quad Flat, No Lead Package (MV) - 5x5 mm Body [UQFN]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



RECOMMENDED LAND PATTERN

Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Contact Pitch	E		0.40 BSC	
Optional Center Pad Width	W2			3.80
Optional Center Pad Length	T2			3.80
Contact Pad Spacing	C1		5.00	
Contact Pad Spacing	C2		5.00	
Contact Pad Width (X40)	X1			0.20
Contact Pad Length (X40)	Y1			0.75
Distance Between Pads	G	0.20		

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2156B