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Understanding Embedded - FPGAs (Field Programmable Gate Array)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details	
Product Status	Active
Number of LABs/CLBs	864
Number of Logic Elements/Cells	3888
Total RAM Bits	49152
Number of I/O	176
Number of Gates	150000
Voltage - Supply	2.375V ~ 2.625V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 85°C (TJ)
Package / Case	256-BGA
Supplier Device Package	256-FBGA (17x17)
Purchase URL	https://www.e-xfl.com/product-detail/xilinx/xc2s150-5fgg256c

Local Routing

The local routing resources, as shown in Figure 6, provide the following three types of connections:

- Interconnections among the LUTs, flip-flops, and General Routing Matrix (GRM)
- Internal CLB feedback paths that provide high-speed connections to LUTs within the same CLB, chaining them together with minimal routing delay
- Direct paths that provide high-speed connections between horizontally adjacent CLBs, eliminating the delay of the GRM

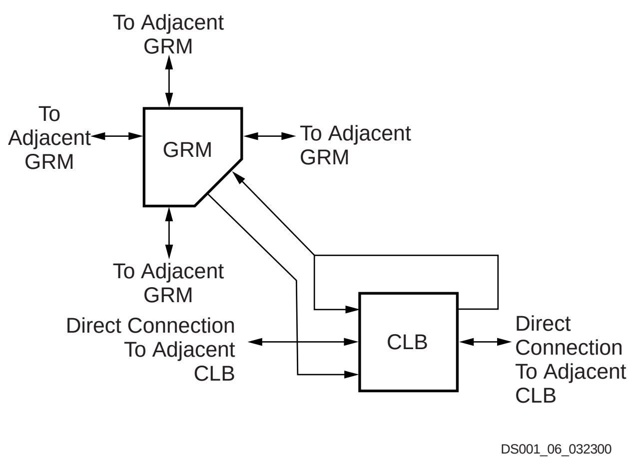


Figure 6: **Spartan-II Local Routing**

General Purpose Routing

Most Spartan-II FPGA signals are routed on the general purpose routing, and consequently, the majority of interconnect resources are associated with this level of the routing hierarchy. The general routing resources are located in horizontal and vertical routing channels associated with the rows and columns CLBs. The general-purpose routing resources are listed below.

- Adjacent to each CLB is a General Routing Matrix (GRM). The GRM is the switch matrix through which horizontal and vertical routing resources connect, and is also the means by which the CLB gains access to the general purpose routing.
- 24 single-length lines route GRM signals to adjacent GRMs in each of the four directions.
- 96 buffered Hex lines route GRM signals to other GRMs six blocks away in each one of the four directions. Organized in a staggered pattern, Hex lines may be driven only at their endpoints. Hex-line signals can be accessed either at the endpoints or at the midpoint (three blocks from the source). One third of the Hex lines are bidirectional, while the remaining ones are unidirectional.
- 12 Longlines are buffered, bidirectional wires that distribute signals across the device quickly and efficiently. Vertical Longlines span the full height of the device, and horizontal ones span the full width of the device.

I/O Routing

Spartan-II devices have additional routing resources around their periphery that form an interface between the CLB array and the IOBs. This additional routing, called the VersaRing, facilitates pin-swapping and pin-locking, such that logic redesigns can adapt to existing PCB layouts. Time-to-market is reduced, since PCBs and other system components can be manufactured while the logic design is still in progress.

Dedicated Routing

Some classes of signal require dedicated routing resources to maximize performance. In the Spartan-II architecture, dedicated routing resources are provided for two classes of signal.

- Horizontal routing resources are provided for on-chip 3-state busses. Four partitionable bus lines are provided per CLB row, permitting multiple busses within a row, as shown in Figure 7.
- Two dedicated nets per CLB propagate carry signals vertically to the adjacent CLB.

Global Routing

Global Routing resources distribute clocks and other signals with very high fanout throughout the device. Spartan-II devices include two tiers of global routing resources referred to as primary and secondary global routing resources.

- The primary global routing resources are four dedicated global nets with dedicated input pins that are designed to distribute high-fanout clock signals with minimal skew. Each global clock net can drive all CLB, IOB, and block RAM clock pins. The primary global nets may only be driven by global buffers. There are four global buffers, one for each global net.
- The secondary global routing resources consist of 24 backbone lines, 12 across the top of the chip and 12 across bottom. From these lines, up to 12 unique signals per column can be distributed via the 12 longlines in the column. These secondary resources are more flexible than the primary resources since they are not restricted to routing only to clock pins.

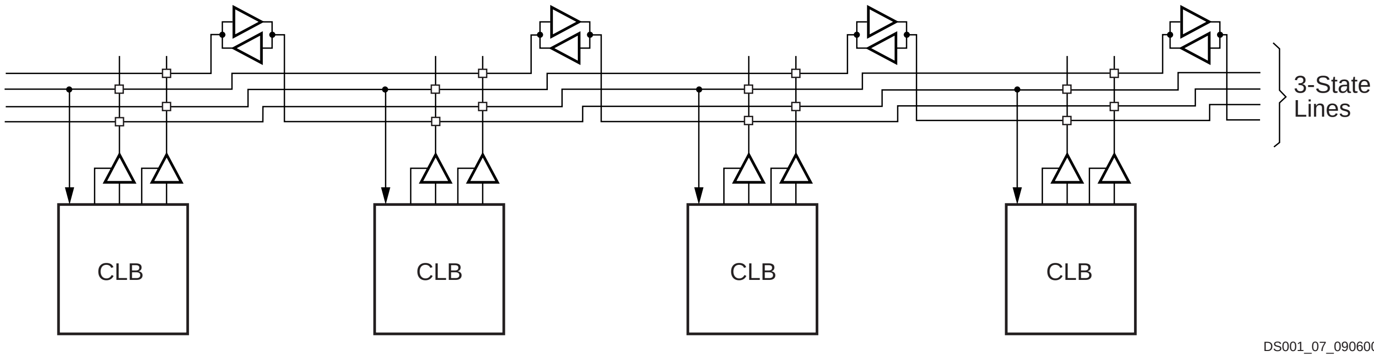


Figure 7: **BUFT Connections to Dedicated Horizontal Bus Lines**

Clock Distribution

The Spartan-II family provides high-speed, low-skew clock distribution through the primary global routing resources described above. A typical clock distribution net is shown in Figure 8.

Four global buffers are provided, two at the top center of the device and two at the bottom center. These drive the four primary global nets that in turn drive any clock pin.

Four dedicated clock pads are provided, one adjacent to each of the global buffers. The input to the global buffer is selected either from these pads or from signals in the general purpose routing. Global clock pins do not have the option for internal, weak pull-up resistors.

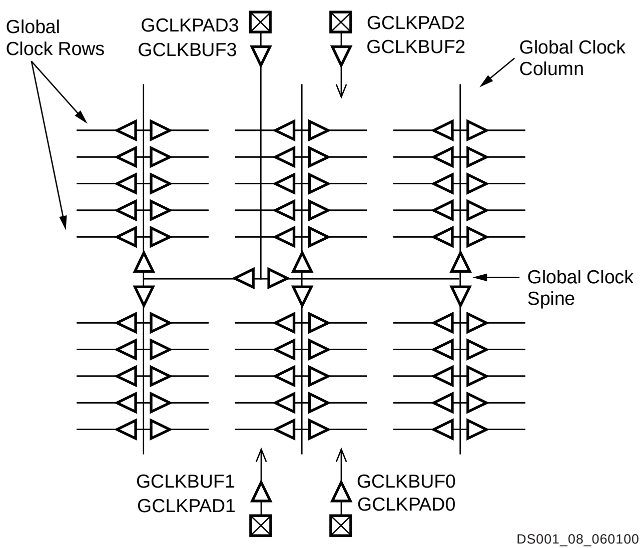


Figure 8: **Global Clock Distribution Network**

Delay-Locked Loop (DLL)

Associated with each global clock input buffer is a fully digital Delay-Locked Loop (DLL) that can eliminate skew between the clock input pad and internal clock-input pins throughout the device. Each DLL can drive two global clock networks. The DLL monitors the input clock and the distributed clock, and automatically adjusts a clock delay element. Additional delay is introduced such that clock edges reach internal flip-flops exactly one clock period after they arrive at the input. This closed-loop system effectively eliminates clock-distribution delay by ensuring that clock edges arrive at internal flip-flops in synchronism with clock edges arriving at the input.

In addition to eliminating clock-distribution delay, the DLL provides advanced control of multiple clock domains. The DLL provides four quadrature phases of the source clock, can double the clock, or divide the clock by 1.5, 2, 2.5, 3, 4, 5, 8, or 16. It has six outputs.

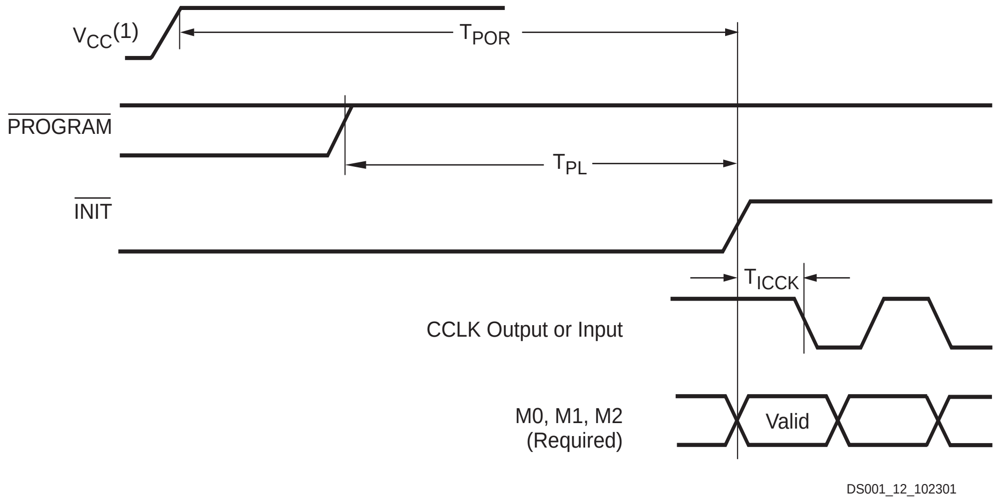
The DLL also operates as a clock mirror. By driving the output from a DLL off-chip and then back on again, the DLL can be used to deskew a board level clock among multiple Spartan-II devices.

In order to guarantee that the system clock is operating correctly prior to the FPGA starting up after configuration, the DLL can delay the completion of the configuration process until after it has achieved lock.

Boundary Scan

Spartan-II devices support all the mandatory boundary-scan instructions specified in the IEEE standard 1149.1. A Test Access Port (TAP) and registers are provided that implement the EXTEST, SAMPLE/PRELOAD, and BYPASS instructions. The TAP also supports two USERCODE instructions and internal scan chains.

The TAP uses dedicated package pins that always operate using LVTTL. For TDO to operate using LVTTL, the V_{CCO} for Bank 2 must be 3.3V. Otherwise, TDO switches rail-to-rail between ground and V_{CCO}. TDI, TMS, and TCK have a default internal weak pull-up resistor, and TDO has no default resistor. Bitstream options allow setting any of the four TAP pins to have an internal pull-up, pull-down, or neither.



Symbol	Description	Min	Max
T_{POR}	Power-on reset	-	2 ms
T_{PL}	Program latency	-	100 µs
T_{ICCK}	CCLK output delay (Master Serial mode only)	0.5 µs	4 µs
$T_{PROGRAM}$	Program pulse width	300 ns	-

Notes: (referring to waveform above:)

1. Before configuration can begin, V_{CCINT} must be greater than 1.6V and V_{CCO} Bank 2 must be greater than 1.0V.

Figure 12: **Configuration Timing on Power-Up**

Clearing Configuration Memory

The device indicates that clearing the configuration memory is in progress by driving INIT Low. At this time, the user can delay configuration by holding either PROGRAM or INIT Low, which causes the device to remain in the memory clearing phase. Note that the bidirectional INIT line is driving a Low logic level during memory clearing. To avoid contention, use an open-drain driver to keep INIT Low.

With no delay in force, the device indicates that the memory is completely clear by driving INIT High. The FPGA samples its mode pins on this Low-to-High transition.

Loading Configuration Data

Once INIT is High, the user can begin loading configuration data frames into the device. The details of loading the configuration data are discussed in the sections treating the configuration modes individually. The sequence of operations necessary to load configuration data using the serial modes is shown in Figure 14. Loading data using the Slave Parallel mode is shown in Figure 19, page 25.

CRC Error Checking

During the loading of configuration data, a CRC value embedded in the configuration file is checked against a CRC value calculated within the FPGA. If the CRC values do not match, the FPGA drives INIT Low to indicate that a frame error has occurred and configuration is aborted.

To reconfigure the device, the PROGRAM pin should be asserted to reset the configuration logic. Recycling power also resets the FPGA for configuration. See "Clearing Configuration Memory".

Start-up

The start-up sequence oversees the transition of the FPGA from the configuration state to full user operation. A match of CRC values, indicating a successful loading of the configuration data, initiates the sequence.

During start-up, the device performs four operations:

1. The assertion of DONE. The failure of DONE to go High may indicate the unsuccessful loading of configuration data.
2. The release of the Global Three State net. This activates I/Os to which signals are assigned. The remaining I/Os stay in a high-impedance state with internal weak pull-down resistors present.
3. Negates Global Set Reset (GSR). This allows all flip-flops to change state.
4. The assertion of Global Write Enable (GWE). This allows all RAMs and flip-flops to change state.

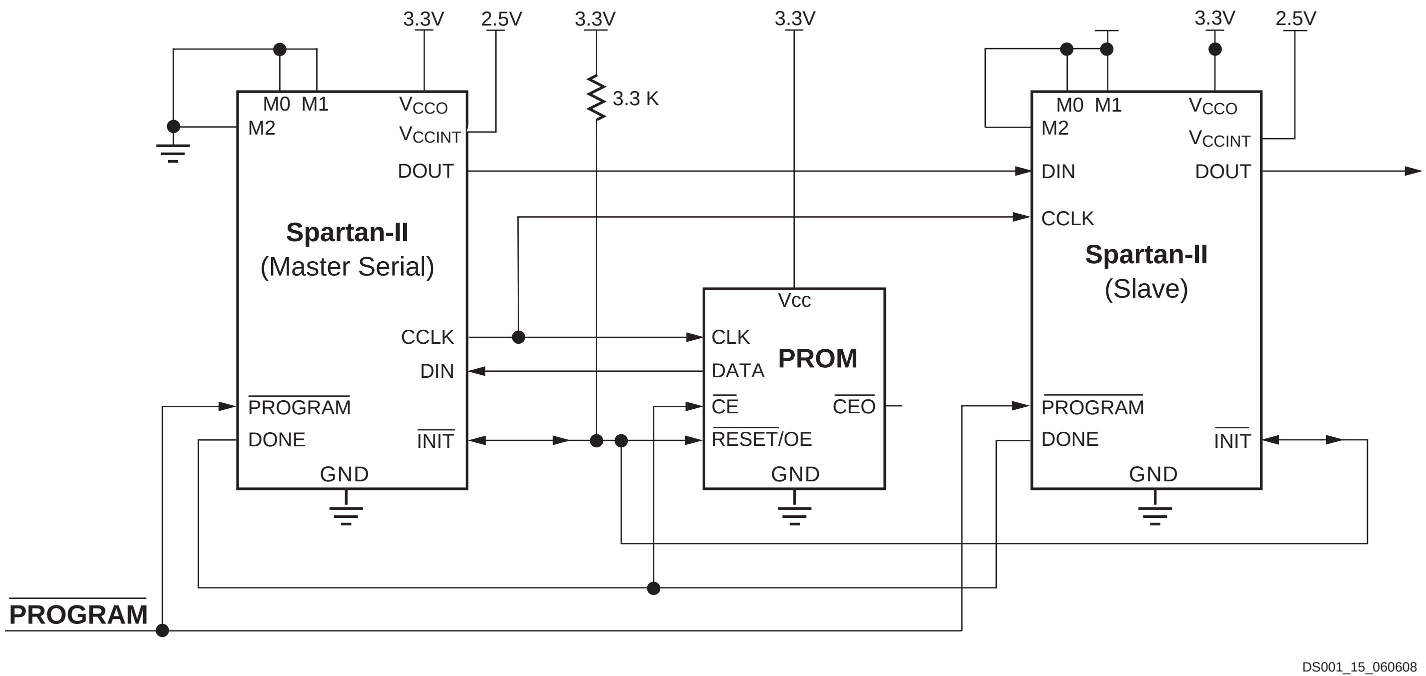
Slave Serial Mode

In Slave Serial mode, the FPGA's CCLK pin is driven by an external source, allowing FPGAs to be configured from other logic devices such as microprocessors or in a daisy-chain configuration. Figure 15 shows connections for a Master Serial FPGA configuring a Slave Serial FPGA from a PROM. A Spartan-II device in slave serial mode should be connected as shown for the third device from the left. Slave Serial mode is selected by a <11x> on the mode pins (M0, M1, M2).

Figure 16 shows the timing for Slave Serial configuration. The serial bitstream must be setup at the DIN input pin a short time before each rising edge of an externally generated CCLK.

Multiple FPGAs in Slave Serial mode can be daisy-chained for configuration from a single source. The maximum amount of data that can be sent to the DOUT pin for a serial daisy chain is 2^{20}-1 (1,048,575) 32-bit words, or 33,554,400 bits, which is approximately 25 XC2S200 bitstreams. The configuration bitstream of downstream devices is limited to this size.

After an FPGA is configured, data for the next device is routed to the DOUT pin. Data on the DOUT pin changes on the rising edge of CCLK. Configuration must be delayed until $\overline{\text{INIT}}$ pins of all daisy-chained FPGAs are High. For more information, see "Start-up," page 19.



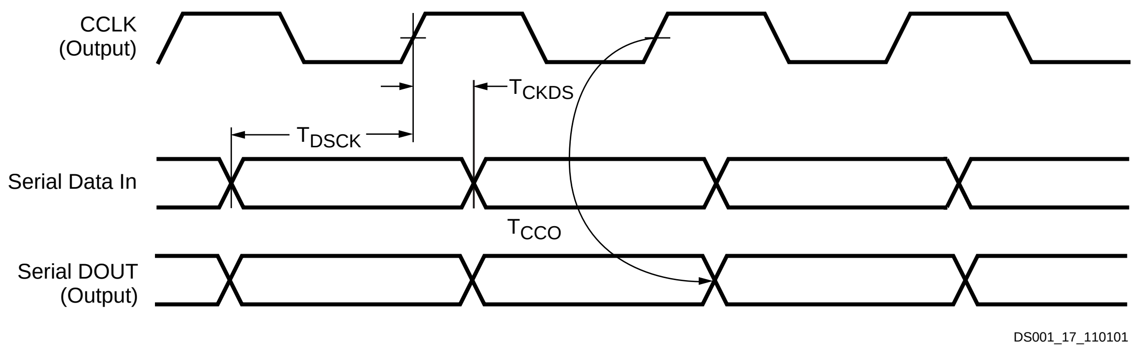
Notes:
1. If the DriveDone configuration option is not active for any of the FPGAs, pull up DONE with a 330Ω resistor.

Figure 15: **Master/Slave Serial Configuration Circuit Diagram**

Master Serial Mode

In Master Serial mode, the CCLK output of the FPGA drives a Xilinx PROM which feeds a serial stream of configuration data to the FPGA's DIN input. Figure 15 shows a Master Serial FPGA configuring a Slave Serial FPGA from a PROM. A Spartan-II device in Master Serial mode should be connected as shown for the device on the left side. Master Serial mode is selected by a <00x> on the mode pins (M0, M1, M2). The PROM RESET pin is driven by $\overline{\text{INIT}}$, and CE input is driven by DONE. The interface is identical to the slave serial mode except that an oscillator internal to the FPGA is used to generate the configuration clock (CCLK). Any of a number of different frequencies ranging from 4 to 60 MHz can be set using the ConfigRate option in the Xilinx software. On power-up, while the first 60 bytes of the configuration data are being loaded, the CCLK frequency is always 2.5 MHz. This frequency is used until the ConfigRate bits, part of the configuration file, have been loaded into the FPGA, at which point, the frequency changes to the selected ConfigRate. Unless a different frequency is specified in the design, the default ConfigRate is 4 MHz. The frequency of the CCLK signal created by the internal oscillator has a variance of +45%, –30% from the specified value.

Figure 17 shows the timing for Master Serial configuration. The FPGA accepts one bit of configuration data on each rising CCLK edge. After the FPGA has been loaded, the data for the next device in a daisy-chain is presented on the DOUT pin after the rising CCLK edge.



Symbol		Description		Units
T_{DSCK}	CCLK	DIN setup	5.0	ns, min
T_{CKDS}		DIN hold	0.0	ns, min
		Frequency tolerance with respect to nominal	+45%, –30%	-

Figure 17: **Master Serial Mode Timing**

Slave Parallel Mode

The Slave Parallel mode is the fastest configuration option. Byte-wide data is written into the FPGA. A BUSY flag is provided for controlling the flow of data at a clock frequency F_{CCNH} above 50 MHz.

Figure 18, page 24 shows the connections for two Spartan-II devices using the Slave Parallel mode. Slave Parallel mode is selected by a <011> on the mode pins (M0, M1, M2).

If a configuration file of the format .bit, .rbt, or non-swapped HEX is used for parallel programming, then the most significant bit (i.e. the left-most bit of each configuration byte, as displayed in a text editor) must be routed to the D0 input on the FPGA.

The agent controlling configuration is not shown. Typically, a processor, a microcontroller, or CPLD controls the Slave Parallel interface. The controlling agent provides byte-wide configuration data, CCLK, a Chip Select ($\overline{\text{CS}}$) signal and a Write signal ($\overline{\text{WRITE}}$). If BUSY is asserted (High) by the FPGA, the data must be held until BUSY goes Low.

After configuration, the pins of the Slave Parallel port (D0-D7) can be used as additional user I/O. Alternatively, the port may be retained to permit high-speed 8-bit readback. Then data can be read by de-asserting $\overline{\text{WRITE}}$. See "Readback," page 25.

Creating Larger RAM Structures

The block RAM columns have specialized routing to allow cascading blocks together with minimal routing delays. This achieves wider or deeper RAM structures with a smaller timing penalty than when using normal routing channels.

Location Constraints

Block RAM instances can have LOC properties attached to them to constrain the placement. The block RAM placement locations are separate from the CLB location naming convention, allowing the LOC properties to transfer easily from array to array.

The LOC properties use the following form:

LOC = RAMB4_R#C#

RAMB4_R0C0 is the upper left RAMB4 location on the device.

Conflict Resolution

The block RAM memory is a true dual-read/write port RAM that allows simultaneous access of the same memory cell from both ports. When one port writes to a given memory cell, the other port must not address that memory cell (for a write or a read) within the clock-to-clock setup window. The following lists specifics of port and memory cell write conflict resolution.

- If both ports write to the same memory cell simultaneously, violating the clock-to-clock setup requirement, consider the data stored as invalid.
- If one port attempts a read of the same memory cell the other simultaneously writes, violating the clock-to-clock setup requirement, the following occurs.
  - The write succeeds
  - The data out on the writing port accurately reflects the data written.
  - The data out on the reading port is invalid.

Conflicts do not cause any physical damage.

Single Port Timing

Figure 33 shows a timing diagram for a single port of a block RAM memory. The block RAM AC switching characteristics are specified in the data sheet. The block RAM memory is initially disabled.

At the first rising edge of the CLK pin, the ADDR, DI, EN, WE, and RST pins are sampled. The EN pin is High and the WE pin is Low indicating a read operation. The DO bus contains the contents of the memory location, 0x00, as indicated by the ADDR bus.

At the second rising edge of the CLK pin, the ADDR, DI, EN, WR, and RST pins are sampled again. The EN and WE pins are High indicating a write operation. The DO bus mirrors the DI bus. The DI bus is written to the memory location 0x0F.

At the third rising edge of the CLK pin, the ADDR, DI, EN, WR, and RST pins are sampled again. The EN pin is High and the WE pin is Low indicating a read operation. The DO bus contains the contents of the memory location 0x7E as indicated by the ADDR bus.

At the fourth rising edge of the CLK pin, the ADDR, DI, EN, WR, and RST pins are sampled again. The EN pin is Low indicating that the block RAM memory is now disabled. The DO bus retains the last value.

Dual Port Timing

Figure 34 shows a timing diagram for a true dual-port read/write block RAM memory. The clock on port A has a longer period than the clock on Port B. The timing parameter T_{BCCS}, (clock-to-clock setup) is shown on this diagram. The parameter, T_{BCCS} is violated once in the diagram. All other timing parameters are identical to the single port version shown in Figure 33.

T_{BCCS} is only of importance when the address of both ports are the same and at least one port is performing a write operation. When the clock-to-clock set-up parameter is violated for a WRITE-WRITE condition, the contents of the memory at that location will be invalid. When the clock-to-clock set-up parameter is violated for a WRITE-READ condition, the contents of the memory will be correct, but the read port will have invalid data. At the first rising edge of the CLKA, memory location 0x00 is to be written with the value 0xAAAA and is mirrored on the DOA bus. The last operation of Port B was a read to the same memory location 0x00. The DOB bus of Port B does not change with the new value on Port A, and retains the last read value. A short time later, Port B executes another read to memory location 0x00, and the DOB bus now reflects the new memory value written by Port A.

At the second rising edge of CLKA, memory location 0x7E is written with the value 0x9999 and is mirrored on the DOA bus. Port B then executes a read operation to the same memory location without violating the T_{BCCS} parameter and the DOB reflects the new memory values written by Port A.

support of a wide variety of applications, from general purpose standard applications to high-speed low-voltage memory busses.

Versatile I/O blocks also provide selectable output drive strengths and programmable slew rates for the LVTTL output buffers, as well as an optional, programmable weak pull-up, weak pull-down, or weak "keeper" circuit ideal for use in external bussing applications.

Each Input/Output Block (IOB) includes three registers, one each for the input, output, and 3-state signals within the IOB. These registers are optionally configurable as either a D-type flip-flop or as a level sensitive latch.

The input buffer has an optional delay element used to guarantee a zero hold time requirement for input signals registered within the IOB.

The Versatile I/O features also provide dedicated resources for input reference voltage (V_{REF}) and output source voltage (V_{CCO}), along with a convenient banking system that simplifies board design.

By taking advantage of the built-in features and wide variety of I/O standards supported by the Versatile I/O features, system-level design and board design can be greatly simplified and improved.

Fundamentals

Modern bus applications, pioneered by the largest and most influential companies in the digital electronics industry, are commonly introduced with a new I/O standard tailored specifically to the needs of that application. The bus I/O standards provide specifications to other vendors who create products designed to interface with these applications. Each standard often has its own specifications for current, voltage, I/O buffering, and termination techniques.

The ability to provide the flexibility and time-to-market advantages of programmable logic is increasingly dependent on the capability of the programmable logic device to support an ever increasing variety of I/O standards

The Versatile I/O resources feature highly configurable input and output buffers which provide support for a wide variety of I/O standards. As shown in Table 15, each buffer type can support a variety of voltage requirements.

Table 15: **Versatile I/O Supported Standards (Typical Values)**

I/O Standard	Input Reference Voltage (V_{REF})	Output Source Voltage (V_{CCO})	Board Termination Voltage (V_{TT})
LVTTL (2-24 mA)	N/A	3.3	N/A
LVCMOS2	N/A	2.5	N/A
PCI (3V/5V, 33 MHz/66 MHz)	N/A	3.3	N/A
GTL	0.8	N/A	1.2
GTL+	1.0	N/A	1.5
HSTL Class I	0.75	1.5	0.75
HSTL Class III	0.9	1.5	1.5
HSTL Class IV	0.9	1.5	1.5
SSTL3 Class I and II	1.5	3.3	1.5
SSTL2 Class I and II	1.25	2.5	1.25
CTT	1.5	3.3	1.5
AGP-2X	1.32	3.3	N/A

Overview of Supported I/O Standards

This section provides a brief overview of the I/O standards supported by all Spartan-II devices.

While most I/O standards specify a range of allowed voltages, this document records typical voltage values only. Detailed information on each specification may be found on the Electronic Industry Alliance JEDEC website at http://www.jedec.org. For more details on the I/O standards and termination application examples, see XAPP179, "*Using SelectIO Interfaces in Spartan-II and Spartan-IIE FPGAs.*"

LVTTL — Low-Voltage TTL

The Low-Voltage TTL (LVTTL) standard is a general purpose EIA/JESDSA standard for 3.3V applications that uses an LVTTL input buffer and a Push-Pull output buffer. This standard requires a 3.3V output source voltage (V_{CCO}), but does not require the use of a reference voltage (V_{REF}) or a termination voltage (V_{TT}).

LVCMOS2 — Low-Voltage CMOS for 2.5V

The Low-Voltage CMOS for 2.5V or lower (LVCMOS2) standard is an extension of the LVCMOS standard (JESD 8.5) used for general purpose 2.5V applications. This standard requires a 2.5V output source voltage (V_{CCO}), but does not require the use of a reference voltage (V_{REF}) or a board termination voltage (V_{TT}).

GTL

A sample circuit illustrating a valid termination technique for GTL is shown in Figure 42. Table 20 lists DC voltage specifications for the GTL standard. See "DC Specifications" in Module 3 for the actual FPGA characteristics.

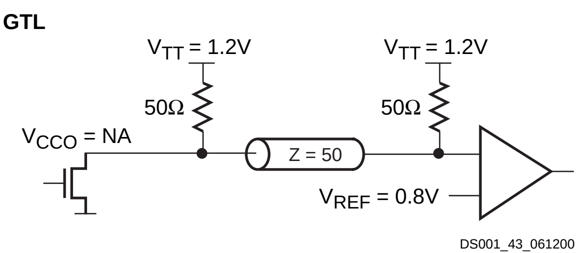


Figure 42: **Terminated GTL**

Table 20: **GTL Voltage Specifications**

Parameter	Min	Typ	Max
V_{CCO}	-	N/A	-
$V_{REF} = N \times V_{TT}$(1)	0.74	0.8	0.86
V_{TT}	1.14	1.2	1.26
$V_{IH} \geq V_{REF} + 0.05$	0.79	0.85	-
$V_{IL} \leq V_{REF} - 0.05$	-	0.75	0.81
V_{OH}	-	-	-
V_{OL}	-	0.2	0.4
I_{OH} at V_{OH} (mA)	-	-	-
I_{OL} at V_{OL} (mA) at 0.4V	32	-	-
I_{OL} at V_{OL} (mA) at 0.2V	-	-	40

Notes:
1. N must be greater than or equal to 0.653 and less than or equal to 0.68.

GTL+

A sample circuit illustrating a valid termination technique for GTL+ appears in Figure 43. DC voltage specifications appear in Table 21 for the GTL+ standard. See "DC Specifications" in Module 3 for the actual FPGA characteristics.

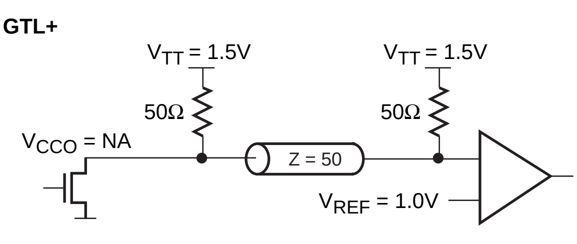


Figure 43: **Terminated GTL+**

Table 21: **GTL+ Voltage Specifications**

Parameter	Min	Typ	Max
V_{CCO}	-	-	-
$V_{REF} = N \times V_{TT}$(1)	0.88	1.0	1.12
V_{TT}	1.35	1.5	1.65
$V_{IH} \geq V_{REF} + 0.1$	0.98	1.1	-
$V_{IL} \leq V_{REF} - 0.1$	-	0.9	1.02
V_{OH}	-	-	-
V_{OL}	0.3	0.45	0.6
I_{OH} at V_{OH} (mA)	-	-	-
I_{OL} at V_{OL} (mA) at 0.6V	36	-	-
I_{OL} at V_{OL} (mA) at 0.3V	-	-	48

Notes:
1. N must be greater than or equal to 0.653 and less than or equal to 0.68.

HSTL Class I

A sample circuit illustrating a valid termination technique for HSTL_I appears in Figure 44. DC voltage specifications appear in Table 22 for the HSTL_1 standard. See "DC Specifications" in Module 3 for the actual FPGA characteristics.

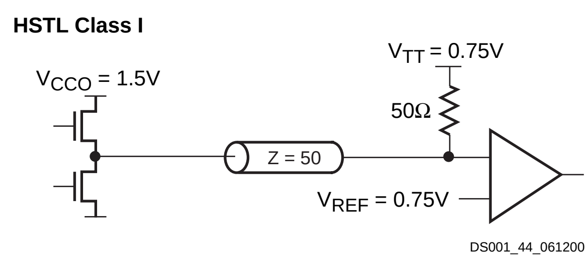


Figure 44: **Terminated HSTL Class I**

Table 22: **HSTL Class I Voltage Specification**

Parameter	Min	Typ	Max
V_{CCO}	1.40	1.50	1.60
V_{REF}	0.68	0.75	0.90
V_{TT}	-	$V_{CCO} \times 0.5$	-
V_{IH}	$V_{REF} + 0.1$	-	-
V_{IL}	-	-	$V_{REF} - 0.1$
V_{OH}	$V_{CCO} - 0.4$	-	-
V_{OL}			0.4
I_{OH} at V_{OH} (mA)	–8	-	-
I_{OL} at V_{OL} (mA)	8	-	-

HSTL Class III

A sample circuit illustrating a valid termination technique for HSTL_III appears in Figure 45. DC voltage specifications appear in Table 23 for the HSTL_III standard. See "DC Specifications" in Module 3 for the actual FPGA characteristics.

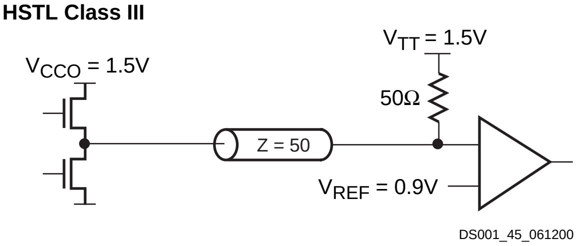


Figure 45: **Terminated HSTL Class III**

Table 23: **HSTL Class III Voltage Specification**

Parameter	Min	Typ	Max
V_{CCO}	1.40	1.50	1.60
V_{REF} (1)	-	0.90	-
V_{TT}	-	V_{CCO}	-
V_{IH}	V_{REF} + 0.1	-	-
V_{IL}	-	-	V_{REF} – 0.1
V_{OH}	V_{CCO} – 0.4	-	-
V_{OL}	-	-	0.4
I_{OH} at V_{OH} (mA)	–8	-	-
I_{OL} at V_{OL} (mA)	24	-	-

Notes:
1. Per EIA/JESD8-6, "The value of V_{REF} is to be selected by the user to provide optimum noise margin in the use conditions specified by the user."

HSTL Class IV

A sample circuit illustrating a valid termination technique for HSTL_IV appears in Figure 46.DC voltage specifications appear in Table 23 for the HSTL_IV standard. See "DC Specifications" in Module 3 for the actual FPGA characteristics

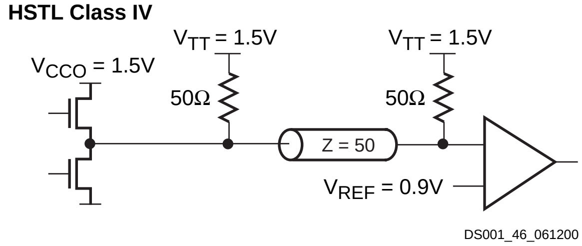


Figure 46: **Terminated HSTL Class IV**

Table 24: **HSTL Class IV Voltage Specification**

Parameter	Min	Typ	Max
V_{CCO}	1.40	1.50	1.60
V_{REF}	-	0.90	-
V_{TT}	-	V_{CCO}	-
V_{IH}	V_{REF} + 0.1	-	-
V_{IL}	-	-	V_{REF} – 0.1
V_{OH}	V_{CCO} – 0.4	-	-
V_{OL}	-	-	0.4
I_{OH} at V_{OH} (mA)	–8	-	-
I_{OL} at V_{OL} (mA)	48	-	-

Notes:
1. Per EIA/JESD8-6, "The value of V_{REF} is to be selected by the user to provide optimum noise margin in the use conditions specified by the user."

Definition of Terms

In this document, some specifications may be designated as Advance or Preliminary. These terms are defined as follows:

Advance: Initial estimates based on simulation and/or extrapolation from other speed grades, devices, or families. Values are subject to change. Use as estimates, not for production.

Preliminary: Based on preliminary characterization. Further changes are not expected.

Unmarked: Specifications not identified as either Advance or Preliminary are to be considered Final.

Except for pin-to-pin input and output parameters, the AC parameter delay specifications included in this document are derived from measuring internal test patterns. All limits are representative of worst-case supply voltage and junction temperature conditions. Typical numbers are based on measurements taken at a nominal V_{CCINT} level of 2.5V and a junction temperature of 25°C. The parameters included are common to popular designs and typical applications. **All specifications are subject to change without notice.**

DC Specifications

Absolute Maximum Ratings(1)

Symbol	Description		Min	Max	Units
V_{CCINT}	Supply voltage relative to GND(2)		–0.5	3.0	V
V_{CCO}	Supply voltage relative to GND(2)		–0.5	4.0	V
V_{REF}	Input reference voltage		–0.5	3.6	V
V_{IN}	Input voltage relative to GND(3)	5V tolerant I/O(4)	–0.5	5.5	V
		No 5V tolerance(5)	–0.5	V_{CCO} + 0.5	V
V_{TS}	Voltage applied to 3-state output	5V tolerant I/O(4)	–0.5	5.5	V
		No 5V tolerance(5)	–0.5	V_{CCO} + 0.5	V
T_{STG}	Storage temperature (ambient)		–65	+150	°C
T_J	Junction temperature		-	+125	°C

Notes:
1. Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those listed under Operating Conditions is not implied. Exposure to Absolute Maximum Ratings conditions for extended periods of time may affect device reliability.
2. Power supplies may turn on in any order.
3. V_{IN} should not exceed V_{CCO} by more than 3.6V over extended periods of time (e.g., longer than a day).
4. Spartan®-II device I/Os are 5V Tolerant whenever the LVTTL, LVCMOS2, or PCI33_5 signal standard has been selected. With 5V Tolerant I/Os selected, the Maximum DC overshoot must be limited to either +5.5V or 10 mA, and undershoot must be limited to either –0.5V or 10 mA, whichever is easier to achieve. The Maximum AC conditions are as follows: The device pins may undershoot to –2.0V or overshoot to +7.0V, provided this over/undershoot lasts no more than 11 ns with a forcing current no greater than 100 mA.
5. Without 5V Tolerant I/Os selected, the Maximum DC overshoot must be limited to either V_{CCO} + 0.5V or 10 mA, and undershoot must be limited to –0.5V or 10 mA, whichever is easier to achieve. The Maximum AC conditions are as follows: The device pins may undershoot to –2.0V or overshoot to V_{CCO} + 2.0V, provided this over/undershoot lasts no more than 11 ns with a forcing current no greater than 100 mA.
6. For soldering guidelines, see the Packaging Information on the Xilinx® web site.

Recommended Operating Conditions

Symbol	Description		Min	Max	Units
T_J	Junction temperature[(1)]	Commercial	0	85	°C
		Industrial	–40	100	°C
V_{CCINT}	Supply voltage relative to GND[(2,5)]	Commercial	2.5 – 5%	2.5 + 5%	V
		Industrial	2.5 – 5%	2.5 + 5%	V
V_{CCO}	Supply voltage relative to GND[(3,5)]	Commercial	1.4	3.6	V
		Industrial	1.4	3.6	V
T_{IN}	Input signal transition time[(4)]		-	250	ns

Notes:
1. At junction temperatures above those listed as Operating Conditions, all delay parameters increase by 0.35% per °C.
2. Functional operation is guaranteed down to a minimum V_{CCINT} of 2.25V (Nominal V_{CCINT} – 10%). For every 50 mV reduction in V_{CCINT} below 2.375V (nominal V_{CCINT} – 5%), all delay parameters increase by 3%.
3. Minimum and maximum values for V_{CCO} vary according to the I/O standard selected.
4. Input and output measurement threshold is ~50% of V_{CCO}. See "Delay Measurement Methodology," page 60 for specific levels.
5. Supply voltages may be applied in any order desired.

DC Characteristics Over Operating Conditions

Symbol	Description			Min	Typ	Max	Units
V_{DRINT}	Data Retention V_{CCINT} voltage (below which configuration data may be lost)			2.0	-	-	V
V_{DRIO}	Data Retention V_{CCO} voltage (below which configuration data may be lost)			1.2	-	-	V
I_{CCINTQ}	Quiescent V_{CCINT} supply current[(1)]	XC2S15	Commercial	-	10	30	mA
			Industrial	-	10	60	mA
		XC2S30	Commercial	-	10	30	mA
			Industrial	-	10	60	mA
		XC2S50	Commercial	-	12	50	mA
			Industrial	-	12	100	mA
		XC2S100	Commercial	-	12	50	mA
			Industrial	-	12	100	mA
		XC2S150	Commercial	-	15	50	mA
			Industrial	-	15	100	mA
		XC2S200	Commercial	-	15	75	mA
			Industrial	-	15	150	mA
I_{CCOQ}	Quiescent V_{CCO} supply current[(1)]			-	-	2	mA
I_{REF}	V_{REF} current per V_{REF} pin			-	-	20	μA
I_L	Input or output leakage current[(2)]			–10	-	+10	μA
C_{IN}	Input capacitance (sample tested)	VQ, CS, TQ, PQ, FG packages		-	-	8	pF
I_{RPU}	Pad pull-up (when selected) @ V_{IN} = 0V, V_{CCO} = 3.3V (sample tested)[(3)]			-	-	0.25	mA
I_{RPD}	Pad pull-down (when selected) @ V_{IN} = 3.6V (sample tested)[(3)]			-	-	0.15	mA

Notes:
1. With no output current loads, no active input pull-up resistors, all I/O pins 3-stated and floating.
2. The I/O leakage current specification applies only when the V_{CCINT} and V_{CCO} supply voltages have reached their respective minimum Recommended Operating Conditions.
3. Internal pull-up and pull-down resistors guarantee valid logic levels at unconnected input pins. These pull-up and pull-down resistors do not provide valid logic levels when input pins are connected to other circuits.

DLL Timing Parameters

All devices are 100 percent functionally tested. Because of the difficulty in directly measuring many internal timing parameters, those parameters are derived from benchmark timing patterns. The following guidelines reflect worst-case values across the recommended operating conditions.

Symbol	Description	Speed Grade				Units
		-6		-5		
		Min	Max	Min	Max	
$F_{CLKINHF}$	Input clock frequency (CLKDLLHF)	60	200	60	180	MHz
$F_{CLKINLF}$	Input clock frequency (CLKDLL)	25	100	25	90	MHz
$T_{DLLPWHF}$	Input clock pulse width (CLKDLLHF)	2.0	-	2.4	-	ns
$T_{DLLPWLF}$	Input clock pulse width (CLKDLL)	2.5	-	3.0	-	ns

DLL Clock Tolerance, Jitter, and Phase Information

All DLL output jitter and phase specifications were determined through statistical measurement at the package pins using a clock mirror configuration and matched drivers. Figure 52, page 63, provides definitions for various parameters in the table below.

Symbol	Description	F_{CLKIN}	CLKDLLHF		CLKDLL		Units
			Min	Max	Min	Max	
T_{IPTOL}	Input clock period tolerance		-	1.0	-	1.0	ns
T_{IJITCC}	Input clock jitter tolerance (cycle-to-cycle)		-	±150	-	±300	ps
T_{LOCK}	Time required for DLL to acquire lock	> 60 MHz	-	20	-	20	µs
		50-60 MHz	-	-	-	25	µs
		40-50 MHz	-	-	-	50	µs
		30-40 MHz	-	-	-	90	µs
		25-30 MHz	-	-	-	120	µs
T_{OJITCC}	Output jitter (cycle-to-cycle) for any DLL clock output(1)		-	±60	-	±60	ps
T_{PHIO}	Phase offset between CLKIN and CLKO(2)		-	±100	-	±100	ps
T_{PHOO}	Phase offset between clock outputs on the DLL(3)		-	±140	-	±140	ps
T_{PHIOM}	Maximum phase difference between CLKIN and CLKO(4)		-	±160	-	±160	ps
T_{PHOOM}	Maximum phase difference between clock outputs on the DLL(5)		-	±200	-	±200	ps

Notes:

1. **Output Jitter** is cycle-to-cycle jitter measured on the DLL output clock, *excluding* input clock jitter.
2. **Phase Offset between CLKIN and CLKO** is the worst-case fixed time difference between rising edges of CLKIN and CLKO, *excluding* output jitter and input clock jitter.
3. **Phase Offset between Clock Outputs on the DLL** is the worst-case fixed time difference between rising edges of any two DLL outputs, *excluding* Output Jitter and input clock jitter.
4. **Maximum Phase Difference between CLKIN an CLKO** is the sum of Output Jitter and Phase Offset between CLKIN and CLKO, or the greatest difference between CLKIN and CLKO rising edges due to DLL alone (*excluding* input clock jitter).
5. **Maximum Phase Difference between Clock Outputs on the DLL** is the sum of Output JItter and Phase Offset between any DLL clock outputs, or the greatest difference between any two DLL output rising edges due to DLL alone (*excluding* input clock jitter).

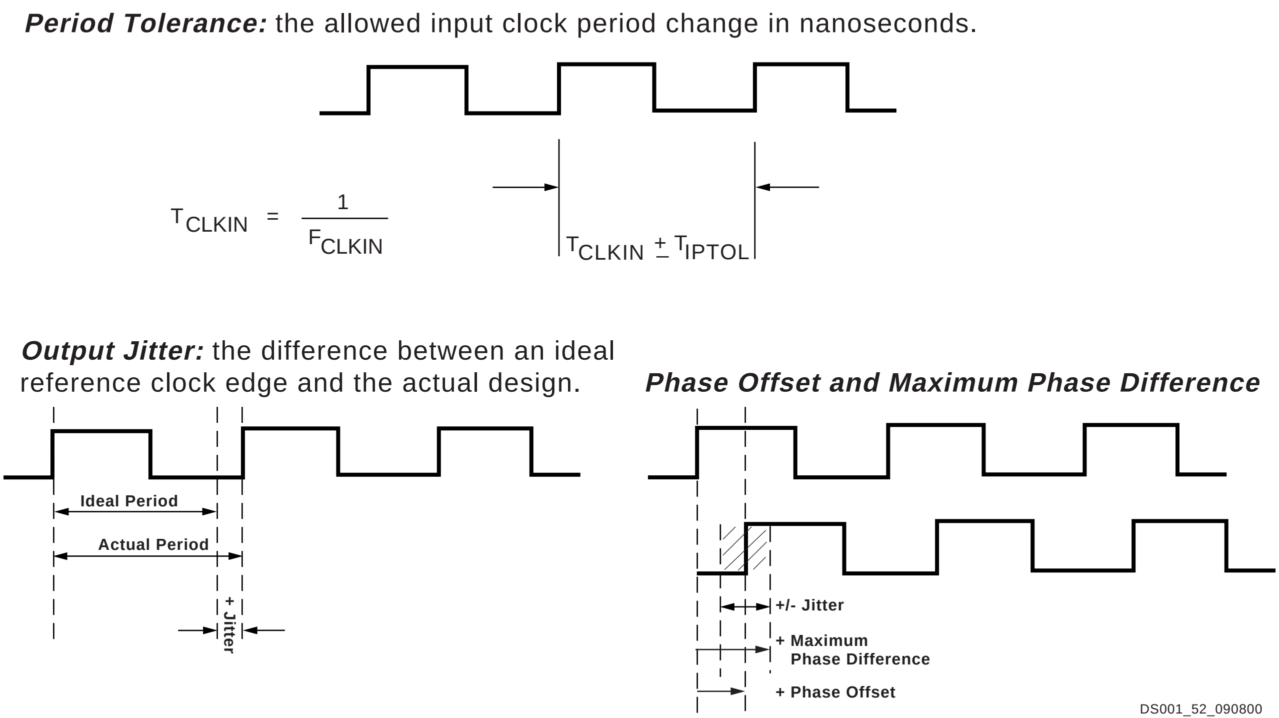


Figure 52: **Period Tolerance and Clock Jitter**

CLB Switching Characteristics

Delays originating at F/G inputs vary slightly according to the input used. The values listed below are worst-case. Precise values are provided by the timing analyzer.

Symbol	Description	Speed Grade				Units
		-6		-5		
		Min	Max	Min	Max	
Combinatorial Delays						
T_{ILO}	4-input function: F/G inputs to X/Y outputs	-	0.6	-	0.7	ns
T_{IF5}	5-input function: F/G inputs to F5 output	-	0.7	-	0.9	ns
T_{IF5X}	5-input function: F/G inputs to X output	-	0.9	-	1.1	ns
T_{IF6Y}	6-input function: F/G inputs to Y output via F6 MUX	-	1.0	-	1.1	ns
T_{F5INY}	6-input function: F5IN input to Y output	-	0.4	-	0.4	ns
T_{IFNCTL}	Incremental delay routing through transparent latch to XQ/YQ outputs	-	0.7	-	0.9	ns
T_{BYYB}	BY input to YB output	-	0.6	-	0.7	ns
Sequential Delays						
T_{CKO}	FF clock CLK to XQ/YQ outputs	-	1.1	-	1.3	ns
T_{CKLO}	Latch clock CLK to XQ/YQ outputs	-	1.2	-	1.5	ns
Setup/Hold Times with Respect to Clock CLK[(1)]						
T_{ICK} / T_{CKI}	4-input function: F/G inputs	1.3 / 0	-	1.4 / 0	-	ns
T_{IF5CK} / T_{CKIF5}	5-input function: F/G inputs	1.6 / 0	-	1.8 / 0	-	ns
T_{F5INCK} / T_{CKF5IN}	6-input function: F5IN input	1.0 / 0	-	1.1 / 0	-	ns
T_{IF6CK} / T_{CKIF6}	6-input function: F/G inputs via F6 MUX	1.6 / 0	-	1.8 / 0	-	ns
T_{DICK} / T_{CKDI}	BX/BY inputs	0.8 / 0	-	0.8 / 0	-	ns
T_{CECK} / T_{CKCE}	CE input	0.9 / 0	-	0.9 / 0	-	ns
T_{RCK} / T_{CKR}	SR/BY inputs (synchronous)	0.8 / 0	-	0.8 / 0	-	ns
Clock CLK						
T_{CH}	Minimum pulse width, High	-	1.9	-	1.9	ns
T_{CL}	Minimum pulse width, Low	-	1.9	-	1.9	ns
Set/Reset						
T_{RPW}	Minimum pulse width, SR/BY inputs	3.1	-	3.1	-	ns
T_{RQ}	Delay from SR/BY inputs to XQ/YQ outputs (asynchronous)	-	1.1	-	1.3	ns
T_{IOGSRQ}	Delay from GSR to XQ/YQ outputs	-	9.9	-	11.7	ns
F_{TOG}	Toggle frequency (for export control)	-	263	-	263	MHz

Notes:

1. A zero hold time listing indicates no hold time or a negative hold time.

XC2S15 Device Pinouts *(Continued)*

XC2S15 Pad Name					
Function	Bank	VQ100	TQ144	CS144	Bndry Scan
GND	-	-	P61	J12	-
I/O (D5)	3	P57	P60	J13	245
I/O	3	P58	P59	H10	248
I/O, V_{REF}	3	P59	P58	H11	251
I/O (D4)	3	P60	P57	H12	254
I/O	3	-	P56	H13	257
V_{CCINT}	-	P61	P55	G12	-
I/O, TRDY(1)	3	P62	P54	G13	260
V_{CCO}	3	P63	P53	G11	-
V_{CCO}	2	P63	P53	G11	-
GND	-	P64	P52	G10	-
I/O, IRDY(1)	2	P65	P51	F13	263
I/O	2	-	P50	F12	266
I/O (D3)	2	P66	P49	F11	269
I/O, V_{REF}	2	P67	P48	F10	272
I/O	2	P68	P47	E13	275
I/O (D2)	2	P69	P46	E12	278
GND	-	-	P45	E11	-
I/O (D1)	2	P70	P44	E10	281
I/O	2	P71	P43	D13	284
I/O, V_{REF}	2	P72	P41	D11	287
I/O	2	-	P40	C13	290
I/O (DIN, D0)	2	P73	P39	C12	293
I/O (DOUT, BUSY)	2	P74	P38	C11	296
CCLK	2	P75	P37	B13	299
V_{CCO}	2	P76	P36	B12	-
V_{CCO}	1	P76	P35	A13	-
TDO	2	P77	P34	A12	-
GND	-	P78	P33	B11	-
TDI	-	P79	P32	A11	-
I/O ($\overline{CS}$)	1	P80	P31	D10	0
I/O ($\overline{WRITE}$)	1	P81	P30	C10	3
I/O	1	-	P29	B10	6
I/O, V_{REF}	1	P82	P28	A10	9
I/O	1	P83	P27	D9	12
I/O	1	P84	P26	C9	15
GND	-	-	P25	B9	-
V_{CCINT}	-	P85	P24	A9	-
I/O	1	-	P23	D8	18
I/O	1	-	P22	C8	21

XC2S15 Device Pinouts *(Continued)*

XC2S15 Pad Name					
Function	Bank	VQ100	TQ144	CS144	Bndry Scan
I/O, V_{REF}	1	P86	P21	B8	24
I/O	1	-	P20	A8	27
I/O	1	P87	P19	B7	30
I, GCK2	1	P88	P18	A7	36
GND	-	P89	P17	C7	-
V_{CCO}	1	P90	P16	D7	-
V_{CCO}	0	P90	P16	D7	-
I, GCK3	0	P91	P15	A6	37
V_{CCINT}	-	P92	P14	B6	-
I/O	0	-	P13	C6	44
I/O, V_{REF}	0	P93	P12	D6	47
I/O	0	-	P11	A5	50
I/O	0	-	P10	B5	53
V_{CCINT}	-	P94	P9	C5	-
GND	-	-	P8	D5	-
I/O	0	P95	P7	A4	56
I/O	0	P96	P6	B4	59
I/O, V_{REF}	0	P97	P5	C4	62
I/O	0	-	P4	A3	65
I/O	0	P98	P3	B3	68
TCK	-	P99	P2	C3	-
V_{CCO}	0	P100	P1	A2	-
V_{CCO}	7	P100	P144	B2	-

04/18/01

Notes:
1. IRDY and TRDY can only be accessed when using Xilinx PCI cores.
2. See "VCCO Banks" for details on V_{CCO} banking.

Additional XC2S15 Package Pins

VQ100

Not Connected Pins					
P28	P29	-	-	-	-

11/02/00

TQ144

Not Connected Pins					
P42	P64	P78	P101	P104	P105
P116	P138	-	-	-	-

11/02/00

CS144

Not Connected Pins					
D3	D12	J4	K13	M3	M4
M10	N3	-	-	-	-

11/02/00

XC2S30 Device Pinouts *(Continued)*

XC2S30 Pad Name						
Function	Bank	VQ100	TQ144	CS144	PQ208	Bndry Scan
V_{CCINT}	-	P85	P24	A9	P171	-
I/O	1	-	P23	D8	P172	24
I/O	1	-	P22	C8	P173	27
I/O	1	-	-	-	P174	30
I/O	1	-	-	-	P175	33
I/O	1	-	-	-	P176	36
GND	-	-	-	-	P177	-
I/O, V_{REF}	1	P86	P21	B8	P178	39
I/O	1	-	-	-	P179	42
I/O	1	-	P20	A8	P180	45
I/O	1	P87	P19	B7	P181	48
I, GCK2	1	P88	P18	A7	P182	54
GND	-	P89	P17	C7	P183	-
V_{CCO}	1	P90	P16	D7	P184	-
V_{CCO}	0	P90	P16	D7	P184	-
I, GCK3	0	P91	P15	A6	P185	55
V_{CCINT}	-	P92	P14	B6	P186	-
I/O	0	-	P13	C6	P187	62
I/O	0	-	-	-	P188	65
I/O, V_{REF}	0	P93	P12	D6	P189	68
GND	-	-	-	-	P190	-
I/O	0	-	-	-	P191	71
I/O	0	-	-	-	P192	74
I/O	0	-	-	-	P193	77
I/O	0	-	P11	A5	P194	80
I/O	0	-	P10	B5	P195	83
V_{CCINT}	-	P94	P9	C5	P196	-
V_{CCO}	0	-	-	-	P197	-
GND	-	-	P8	D5	P198	-
I/O	0	P95	P7	A4	P199	86
I/O	0	P96	P6	B4	P200	89
I/O	0	-	-	-	P201	92

XC2S30 Device Pinouts *(Continued)*

XC2S30 Pad Name						
Function	Bank	VQ100	TQ144	CS144	PQ208	Bndry Scan
I/O, V_{REF}	0	P97	P5	C4	P203	95
I/O	0	-	-	-	P204	98
I/O	0	-	P4	A3	P205	101
I/O	0	P98	P3	B3	P206	104
TCK	-	P99	P2	C3	P207	-
V_{CCO}	0	P100	P1	A2	P208	-
V_{CCO}	7	P100	P144	B2	P208	-

04/18/01

Notes:
1. IRDY and TRDY can only be accessed when using Xilinx PCI cores.
2. See "VCCO Banks" for details on V_{CCO} banking.

Additional XC2S30 Package Pins

VQ100

Not Connected Pins					
P28	P29	-	-	-	-

11/02/00

TQ144

Not Connected Pins					
P104	P105	-	-	-	-

11/02/00

CS144

Not Connected Pins					
M3	N3	-	-	-	-

11/02/00

PQ208

Not Connected Pins					
P7	P13	P38	P44	P55	P56
P60	P97	P112	P118	P143	P149
P165	P202	-	-	-	-

11/02/00

Notes:
1. For the PQ208 package, P13, P38, P118, and P143, which are Not Connected Pins on the XC2S30, are assigned to V_{CCINT} on larger devices.

XC2S50 Device Pinouts

XC2S50 Pad Name		TQ144	PQ208	FG256	Bndry Scan
Function	Bank				
GND	-	P143	P1	GND*	-
TMS	-	P142	P2	D3	-
I/O	7	P141	P3	C2	149
I/O	7	-	-	A2	152
I/O	7	P140	P4	B1	155
I/O	7	-	-	E3	158
I/O	7	-	P5	D2	161
GND	-	-	-	GND*	-
I/O, V_{REF}	7	P139	P6	C1	164
I/O	7	-	P7	F3	167
I/O	7	-	-	E2	170
I/O	7	P138	P8	E4	173
I/O	7	P137	P9	D1	176
I/O	7	P136	P10	E1	179
GND	-	P135	P11	GND*	-
V_{CCO}	7	-	P12	V_{CCO} Bank 7*	-
V_{CCINT}	-	-	P13	V_{CCINT}*	-
I/O	7	P134	P14	F2	182
I/O	7	P133	P15	G3	185
I/O	7	-	-	F1	188
I/O	7	-	P16	F4	191
I/O	7	-	P17	F5	194
I/O	7	-	P18	G2	197
GND	-	-	P19	GND*	-
I/O, V_{REF}	7	P132	P20	H3	200
I/O	7	P131	P21	G4	203
I/O	7	-	-	H2	206
I/O	7	P130	P22	G5	209
I/O	7	-	P23	H4	212
I/O, IRDY(1)	7	P129	P24	G1	215
GND	-	P128	P25	GND*	-
V_{CCO}	7	P127	P26	V_{CCO} Bank 7*	-
V_{CCO}	6	P127	P26	V_{CCO} Bank 6*	-
I/O, TRDY(1)	6	P126	P27	J2	218
V_{CCINT}	-	P125	P28	V_{CCINT}*	-
I/O	6	P124	P29	H1	224
I/O	6	-	-	J4	227
I/O	6	P123	P30	J1	230
I/O, V_{REF}	6	P122	P31	J3	233

XC2S50 Device Pinouts *(Continued)*

XC2S50 Pad Name		TQ144	PQ208	FG256	Bndry Scan
Function	Bank				
GND	-	-	P32	GND*	-
I/O	6	-	P33	K5	236
I/O	6	-	P34	K2	239
I/O	6	-	P35	K1	242
I/O	6	-	-	K3	245
I/O	6	P121	P36	L1	248
I/O	6	P120	P37	L2	251
V_{CCINT}	-	-	P38	V_{CCINT}*	-
V_{CCO}	6	-	P39	V_{CCO} Bank 6*	-
GND	-	P119	P40	GND*	-
I/O	6	P118	P41	K4	254
I/O	6	P117	P42	M1	257
I/O	6	P116	P43	L4	260
I/O	6	-	-	M2	263
I/O	6	-	P44	L3	266
I/O, V_{REF}	6	P115	P45	N1	269
GND	-	-	-	GND*	-
I/O	6	-	P46	P1	272
I/O	6	-	-	L5	275
I/O	6	P114	P47	N2	278
I/O	6	-	-	M4	281
I/O	6	P113	P48	R1	284
I/O	6	P112	P49	M3	287
M1	-	P111	P50	P2	290
GND	-	P110	P51	GND*	-
M0	-	P109	P52	N3	291
V_{CCO}	6	P108	P53	V_{CCO} Bank 6*	-
V_{CCO}	5	P107	P53	V_{CCO} Bank 5*	-
M2	-	P106	P54	R3	292
I/O	5	-	-	N5	299
I/O	5	P103	P57	T2	302
I/O	5	-	-	P5	305
I/O	5	-	P58	T3	308
GND	-	-	-	GND*	-
I/O, V_{REF}	5	P102	P59	T4	311
I/O	5	-	P60	M6	314
I/O	5	-	-	T5	317
I/O	5	P101	P61	N6	320
I/O	5	P100	P62	R5	323

XC2S50 Device Pinouts *(Continued)*

XC2S50 Pad Name		TQ144	PQ208	FG256	Bndry Scan
Function	Bank				
I/O	0	-	-	D8	83
I/O	0	-	P188	A6	86
I/O, V_{REF}	0	P12	P189	B7	89
GND	-	-	P190	GND*	-
I/O	0	-	P191	C8	92
I/O	0	-	P192	D7	95
I/O	0	-	P193	E7	98
I/O	0	P11	P194	C7	104
I/O	0	P10	P195	B6	107
V_{CCINT}	-	P9	P196	V_{CCINT}*	-
V_{CCO}	0	-	P197	V_{CCO} Bank 0*	-
GND	-	P8	P198	GND*	-
I/O	0	P7	P199	A5	110
I/O	0	P6	P200	C6	113
I/O	0	-	P201	B5	116
I/O	0	-	-	D6	119
I/O	0	-	P202	A4	122
I/O, V_{REF}	0	P5	P203	B4	125
GND	-	-	-	GND*	-
I/O	0	-	P204	E6	128
I/O	0	-	-	D5	131
I/O	0	P4	P205	A3	134
I/O	0	-	-	C5	137
I/O	0	P3	P206	B3	140
TCK	-	P2	P207	C4	-
V_{CCO}	0	P1	P208	V_{CCO} Bank 0*	-
V_{CCO}	7	P144	P208	V_{CCO} Bank 7*	-

04/18/01

Notes:
1. IRDY and TRDY can only be accessed when using Xilinx PCI cores.
2. Pads labelled GND*, V_{CCINT}*, V_{CCO} Bank 0*, V_{CCO} Bank 1*, V_{CCO} Bank 2*, V_{CCO} Bank 3*, V_{CCO} Bank 4*, V_{CCO} Bank 5*, V_{CCO} Bank 6*, V_{CCO} Bank 7* are internally bonded to independent ground or power planes within the package.
3. See "VCCO Banks" for details on V_{CCO} banking.

Additional XC2S50 Package Pins

TQ144

Not Connected Pins					
P104	P105	-	-	-	-

11/02/00

XC2S150 Device Pinouts

XC2S150 Pad Name					
Function	Bank	PQ208	FG256	FG456	Bndry Scan
GND	-	P1	GND*	GND*	-
TMS	-	P2	D3	D3	-
I/O	7	P3	C2	B1	221
I/O	7	-	-	E4	224
I/O	7	-	-	C1	227
I/O	7	-	A2	F5	230
GND	-	-	GND*	GND*	-
I/O	7	P4	B1	D2	233
I/O	7	-	-	E3	236
I/O	7	-	-	F4	239
I/O	7	-	E3	G5	242
I/O	7	P5	D2	F3	245
GND	-	-	GND*	GND*	-
V_{CCO}	7	-	V_{CCO} Bank 7*	V_{CCO} Bank 7*	-
I/O, V_{REF}	7	P6	C1	E2	248
I/O	7	P7	F3	E1	251
I/O	7	-	-	G4	254
I/O	7	-	-	G3	257
I/O	7	-	E2	H5	260
I/O	7	P8	E4	F2	263
I/O	7	-	-	F1	266
I/O, V_{REF}	7	P9	D1	H4	269
I/O	7	P10	E1	G1	272
GND	-	P11	GND*	GND*	-
V_{CCO}	7	P12	V_{CCO} Bank 7*	V_{CCO} Bank 7*	-
V_{CCINT}	-	P13	V_{CCINT}*	V_{CCINT}*	-
I/O	7	P14	F2	H3	275
I/O	7	P15	G3	H2	278
I/O	7	-	-	H1	284
I/O	7	-	F1	J5	287
I/O	7	P16	F4	J2	290
I/O	7	-	-	J3	293
I/O	7	P17	F5	K5	299
I/O	7	P18	G2	K1	302
GND	-	P19	GND*	GND*	-
V_{CCO}	7	-	V_{CCO} Bank 7*	V_{CCO} Bank 7*	-
I/O, V_{REF}	7	P20	H3	K3	305
I/O	7	P21	G4	K4	308
I/O	7	-	H2	L6	311

XC2S150 Device Pinouts *(Continued)*

XC2S150 Pad Name					
Function	Bank	PQ208	FG256	FG456	Bndry Scan
I/O	7	P22	G5	L1	314
I/O	7	-	-	L5	317
I/O	7	P23	H4	L4	320
I/O, IRDY(1)	7	P24	G1	L3	323
GND	-	P25	GND*	GND*	-
V_{CCO}	7	P26	V_{CCO} Bank 7*	V_{CCO} Bank 7*	-
V_{CCO}	6	P26	V_{CCO} Bank 6*	V_{CCO} Bank 6*	-
I/O, TRDY(1)	6	P27	J2	M1	326
V_{CCINT}	-	P28	V_{CCINT}*	V_{CCINT}*	-
I/O	6	-	-	M6	332
I/O	6	P29	H1	M3	335
I/O	6	-	J4	M4	338
I/O	6	P30	J1	M5	341
I/O, V_{REF}	6	P31	J3	N2	344
V_{CCO}	6	-	V_{CCO} Bank 6*	V_{CCO} Bank 6*	-
GND	-	P32	GND*	GND*	-
I/O	6	P33	K5	N3	347
I/O	6	P34	K2	N4	350
I/O	6	-	-	N5	356
I/O	6	P35	K1	P2	359
I/O	6	-	K3	P4	362
I/O	6	-	-	R1	365
I/O	6	P36	L1	P3	371
I/O	6	P37	L2	R2	374
V_{CCINT}	-	P38	V_{CCINT}*	V_{CCINT}*	-
V_{CCO}	6	P39	V_{CCO} Bank 6*	V_{CCO} Bank 6*	-
GND	-	P40	GND*	GND*	-
I/O	6	P41	K4	T1	377
I/O, V_{REF}	6	P42	M1	R4	380
I/O	6	-	-	T2	383
I/O	6	P43	L4	U1	386
I/O	6	-	M2	R5	389
I/O	6	-	-	V1	392
I/O	6	-	-	T5	395
I/O	6	P44	L3	U2	398
I/O, V_{REF}	6	P45	N1	T3	401
V_{CCO}	6	-	V_{CCO} Bank 6*	V_{CCO} Bank 6*	-
GND	-	-	GND*	GND*	-

XC2S150 Device Pinouts *(Continued)*

XC2S150 Pad Name					
Function	Bank	PQ208	FG256	FG456	Bndry Scan
I/O, IRDY(1)	2	P132	H16	L20	767
I/O	2	P133	H14	L17	770
I/O	2	-	-	L18	773
I/O	2	P134	H15	L21	776
I/O	2	-	J13	L22	779
I/O (D3)	2	P135	G16	K20	782
I/O, V_{REF}	2	P136	H13	K21	785
V_{CCO}	2	-	V_{CCO} Bank 2*	V_{CCO} Bank 2*	-
GND	-	P137	GND*	GND*	-
I/O	2	P138	G14	K22	788
I/O	2	P139	G15	J21	791
I/O	2	-	-	J20	797
I/O	2	P140	G12	J18	800
I/O	2	-	F16	J22	803
I/O	2	-	-	J19	806
I/O	2	P141	G13	H19	812
I/O (D2)	2	P142	F15	H20	815
V_{CCINT}	-	P143	V_{CCINT}*	V_{CCINT}*	-
V_{CCO}	2	P144	V_{CCO} Bank 2*	V_{CCO} Bank 2*	-
GND	-	P145	GND*	GND*	-
I/O (D1)	2	P146	E16	H22	818
I/O, V_{REF}	2	P147	F14	H18	821
I/O	2	-	-	G21	824
I/O	2	P148	D16	G18	827
I/O	2	-	F12	G20	830
I/O	2	-	-	G19	833
I/O	2	-	-	F22	836
I/O	2	P149	E15	F19	839
I/O, V_{REF}	2	P150	F13	F21	842
V_{CCO}	2	-	V_{CCO} Bank 2*	V_{CCO} Bank 2*	-
GND	-	-	GND*	GND*	-
I/O	2	P151	E14	F20	845
I/O	2	-	C16	F18	848
I/O	2	-	-	E22	851
I/O	2	-	-	E21	854
I/O	2	P152	E13	D22	857
GND	-	-	GND*	GND*	-
I/O	2	-	B16	E20	860
I/O	2	-	-	D21	863

XC2S150 Device Pinouts *(Continued)*

XC2S150 Pad Name					
Function	Bank	PQ208	FG256	FG456	Bndry Scan
I/O	2	-	-	C22	866
I/O (DIN, D0)	2	P153	D14	D20	869
I/O (DOUT, BUSY)	2	P154	C15	C21	872
CCLK	2	P155	D15	B22	875
V_{CCO}	2	P156	V_{CCO} Bank 2*	V_{CCO} Bank 2*	-
V_{CCO}	1	P156	V_{CCO} Bank 1*	V_{CCO} Bank 1*	-
TDO	2	P157	B14	A21	-
GND	-	P158	GND*	GND*	-
TDI	-	P159	A15	B20	-
I/O ($\overline{CS}$)	1	P160	B13	C19	0
I/O ($\overline{WRITE}$)	1	P161	C13	A20	3
I/O	1	-	-	B19	6
I/O	1	-	-	C18	9
I/O	1	-	C12	D17	12
GND	-	-	GND*	GND*	-
I/O	1	P162	A14	A19	15
I/O	1	-	-	B18	18
I/O	1	-	-	E16	21
I/O	1	-	D12	C17	24
I/O	1	P163	B12	D16	27
GND	-	-	GND*	GND*	-
V_{CCO}	1	-	V_{CCO} Bank 1*	V_{CCO} Bank 1*	-
I/O, V_{REF}	1	P164	C11	A18	30
I/O	1	P165	A13	B17	33
I/O	1	-	-	E15	36
I/O	1	-	-	A17	39
I/O	1	-	D11	D15	42
I/O	1	P166	A12	C16	45
I/O	1	-	-	D14	48
I/O, V_{REF}	1	P167	E11	E14	51
I/O	1	P168	B11	A16	54
GND	-	P169	GND*	GND*	-
V_{CCO}	1	P170	V_{CCO} Bank 1*	V_{CCO} Bank 1*	-
V_{CCINT}	-	P171	V_{CCINT}*	V_{CCINT}*	-
I/O	1	P172	A11	C15	57
I/O	1	P173	C10	B15	60
I/O	1	-	-	A15	66
I/O	1	-	-	F12	69