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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Discontinued at Digi-Key
Core Processor	ARM® Cortex®-M0+
Core Size	32-Bit Single-Core
Speed	48MHz
Connectivity	CANbus, I²C, IrDA, LINbus, SmartCard, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, I²S, POR, PWM, WDT
Number of I/O	37
Program Memory Size	64KB (64K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	32K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.8V
Data Converters	A/D 12bit SAR; D/A 12bit
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TJ)
Mounting Type	Surface Mount
Package / Case	48-TQFP
Supplier Device Package	48-TQFP (7x7)
Purchase URL	https://www.e-xfl.com/product-detail/silicon-labs/efm32tg11b140f64iq48-ar

- **Timers/Counters**
  - 2 × 16-bit Timer/Counter
    - 3 or 4 Compare/Capture/PWM channels (4 + 4 on one timer instance)
    - Dead-Time Insertion on one timer instance
  - 2 × 32-bit Timer/Counter
  - 32-bit Real Time Counter and Calendar (RTCC)
  - 32-bit Ultra Low Energy CRYOTIMER for periodic wakeup from any Energy Mode
  - 16-bit Low Energy Timer for waveform generation
  - 16-bit Pulse Counter with asynchronous operation
  - Watchdog Timer with dedicated RC oscillator
- **Low Energy Sensor Interface (LESENSE)**
  - Autonomous sensor monitoring in Deep Sleep Mode
  - Wide range of sensors supported, including LC sensors and capacitive buttons
  - Up to 16 inputs
- **Ultra efficient Power-on Reset and Brown-Out Detector**
- **Debug Interface**
  - 2-pin Serial Wire Debug interface
  - 4-pin JTAG interface
  - Micro Trace Buffer (MTB)
- **Pre-Programmed UART Bootloader**
- **Wide Operating Range**
  - 1.8 V to 3.8 V single power supply
  - Integrated DC-DC, down to 1.8 V output with up to 200 mA load current for system
  - Standard (-40 °C to 85 °C T_A) and Extended (-40 °C to 125 °C T_J) temperature grades available
- **Packages**
  - QFN32 (5x5 mm)
  - TQFP48 (7x7 mm)
  - QFN64 (9x9 mm)
  - TQFP64 (10x10 mm)
  - QFN80 (9x9 mm)
  - TQFP80 (12x12 mm)

2. Ordering Information

Table 2.1. Ordering Information

Ordering Code	Flash (kB)	RAM (kB)	DC-DC Con-verter	LCD	GPIO	Package	Temp Range
EFM32TG11B520F128GM80-A	128	32	Yes	Yes	67	QFN80	-40 to +85°C
EFM32TG11B520F128GQ80-A	128	32	Yes	Yes	63	QFP80	-40 to +85°C
EFM32TG11B520F128IM80-A	128	32	Yes	Yes	67	QFN80	-40 to +125°C
EFM32TG11B520F128IQ80-A	128	32	Yes	Yes	63	QFP80	-40 to +125°C
EFM32TG11B540F64GM80-A	64	32	Yes	Yes	67	QFN80	-40 to +85°C
EFM32TG11B540F64GQ80-A	64	32	Yes	Yes	63	QFP80	-40 to +85°C
EFM32TG11B540F64IM80-A	64	32	Yes	Yes	67	QFN80	-40 to +125°C
EFM32TG11B540F64IQ80-A	64	32	Yes	Yes	63	QFP80	-40 to +125°C
EFM32TG11B520F128GM64-A	128	32	Yes	Yes	53	QFN64	-40 to +85°C
EFM32TG11B520F128GQ64-A	128	32	Yes	Yes	50	QFP64	-40 to +85°C
EFM32TG11B520F128IM64-A	128	32	Yes	Yes	53	QFN64	-40 to +125°C
EFM32TG11B520F128IQ64-A	128	32	Yes	Yes	50	QFP64	-40 to +125°C
EFM32TG11B540F64GM64-A	64	32	Yes	Yes	53	QFN64	-40 to +85°C
EFM32TG11B540F64GQ64-A	64	32	Yes	Yes	50	QFP64	-40 to +85°C
EFM32TG11B540F64IM64-A	64	32	Yes	Yes	53	QFN64	-40 to +125°C
EFM32TG11B540F64IQ64-A	64	32	Yes	Yes	50	QFP64	-40 to +125°C
EFM32TG11B520F128GQ48-A	128	32	Yes	Yes	34	QFP48	-40 to +85°C
EFM32TG11B520F128IQ48-A	128	32	Yes	Yes	34	QFP48	-40 to +125°C
EFM32TG11B540F64GQ48-A	64	32	Yes	Yes	34	QFP48	-40 to +85°C
EFM32TG11B540F64IQ48-A	64	32	Yes	Yes	34	QFP48	-40 to +125°C
EFM32TG11B520F128GM32-A	128	32	Yes	Yes	22	QFN32	-40 to +85°C
EFM32TG11B520F128IM32-A	128	32	Yes	Yes	22	QFN32	-40 to +125°C
EFM32TG11B540F64GM32-A	64	32	Yes	Yes	22	QFN32	-40 to +85°C
EFM32TG11B540F64IM32-A	64	32	Yes	Yes	22	QFN32	-40 to +125°C
EFM32TG11B320F128GM64-A	128	32	No	Yes	56	QFN64	-40 to +85°C
EFM32TG11B320F128GQ64-A	128	32	No	Yes	53	QFP64	-40 to +85°C
EFM32TG11B320F128IM64-A	128	32	No	Yes	56	QFN64	-40 to +125°C
EFM32TG11B320F128IQ64-A	128	32	No	Yes	53	QFP64	-40 to +125°C
EFM32TG11B340F64GM64-A	64	32	No	Yes	56	QFN64	-40 to +85°C
EFM32TG11B340F64GQ64-A	64	32	No	Yes	53	QFP64	-40 to +85°C
EFM32TG11B340F64IM64-A	64	32	No	Yes	56	QFN64	-40 to +125°C
EFM32TG11B340F64IQ64-A	64	32	No	Yes	53	QFP64	-40 to +125°C

3.10 Core and Memory

3.10.1 Processor Core

The ARM Cortex-M processor includes a 32-bit RISC processor integrating the following features and tasks in the system:

- ARM Cortex-M0+ RISC processor
- Memory Protection Unit (MPU) supporting up to 8 memory segments
- Micro-Trace Buffer (MTB)
- Up to 128 kB flash program memory
- Up to 32 kB RAM data memory
- Configuration and event handling of all modules
- 2-pin Serial-Wire debug interface

3.10.2 Memory System Controller (MSC)

The Memory System Controller (MSC) is the program memory unit of the microcontroller. The flash memory is readable and writable from both the Cortex-M and DMA. The flash memory is divided into two blocks; the main block and the information block. Program code is normally written to the main block, whereas the information block is available for special user data and flash lock bits. There is also a read-only page in the information block containing system and device calibration data. Read and write operations are supported in energy modes EM0 Active and EM1 Sleep.

3.10.3 Linked Direct Memory Access Controller (LDMA)

The Linked Direct Memory Access (LDMA) controller allows the system to perform memory operations independently of software. This reduces both energy consumption and software workload. The LDMA allows operations to be linked together and staged, enabling sophisticated operations to be implemented.

3.10.4 Bootloader

All devices come pre-programmed with a UART bootloader. This bootloader resides in flash and can be erased if it is not needed. More information about the bootloader protocol and usage can be found in *AN0003: UART Bootloader*. Application notes can be found on the Silicon Labs website (www.silabs.com/32bit-appnotes) or within Simplicity Studio in the [**Documentation**] area.

4.1.2.1 General Operating Conditions

Table 4.2. General Operating Conditions

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Operating ambient temperature range[6]	T_A	-G temperature grade	-40	25	85	°C
		-I temperature grade	-40	25	125	°C
AVDD supply voltage[2]	V_{AVDD}		1.8	3.3	3.8	V
VREGVDD operating supply voltage[2] [1]	$V_{VREGVDD}$	DCDC in regulation	2.4	3.3	3.8	V
		DCDC in bypass, 50mA load	1.8	3.3	3.8	V
		DCDC not in use. DVDD externally shorted to VREGVDD	1.8	3.3	3.8	V
VREGVDD current	$I_{VREGVDD}$	DCDC in bypass, T ≤ 85 °C	—	—	200	mA
		DCDC in bypass, T > 85 °C	—	—	100	mA
DVDD operating supply voltage	V_{DVDD}		1.62	—	$V_{VREGVDD}$	V
IOVDD operating supply voltage	V_{IOVDD}	All IOVDD pins[5]	1.62	—	$V_{VREGVDD}$	V
DECOUPLE output capacitor[3] [4]	$C_{DECOUPLE}$		0.75	1.0	2.75	µF
HFCORECLK frequency	f_{CORE}	VSCALE2, MODE = WS1	—	—	48	MHz
		VSCALE2, MODE = WS0	—	—	25	MHz
		VSCALE0, MODE = WS1	—	—	20	MHz
		VSCALE0, MODE = WS0	—	—	10	MHz
HFCLK frequency	f_{HFCLK}	VSCALE2	—	—	48	MHz
		VSCALE0	—	—	20	MHz
HFSRCCLK frequency	$f_{HFSRCCLK}$	VSCALE2	—	—	48	MHz
		VSCALE0	—	—	20	MHz
HFBUSCLK frequency	$f_{HFBUSCLK}$	VSCALE2	—	—	48	MHz
		VSCALE0	—	—	20	MHz
HFPERCLK frequency	$f_{HFPERCLK}$	VSCALE2	—	—	48	MHz
		VSCALE0	—	—	20	MHz
HFPERBCLK frequency	$f_{HFPERBCLK}$	VSCALE2	—	—	48	MHz
		VSCALE0	—	—	20	MHz
HFPERCCLK frequency	$f_{HFPERCCLK}$	VSCALE2	—	—	48	MHz
		VSCALE0	—	—	20	MHz

4.1.6.2 Current Consumption 3.3 V using DC-DC Converter

Unless otherwise indicated, typical conditions are: VREGVDD = AVDD = IOVDD = 3.3 V, DVDD = 1.8 V DC-DC output. T = 25 °C. Minimum and maximum values in this table represent the worst conditions across supply voltage and process variation at T = 25 °C.

Table 4.7. Current Consumption 3.3 V using DC-DC Converter

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Current consumption in EM0 mode with all peripherals disabled, DCDC in Low Noise DCM mode[2]	I_{ACTIVE_DCM}	48 MHz crystal, CPU running while loop from flash	—	38	—	µA/MHz
		48 MHz HFRCO, CPU running while loop from flash	—	37	—	µA/MHz
		48 MHz HFRCO, CPU running Prime from flash	—	45	—	µA/MHz
		48 MHz HFRCO, CPU running CoreMark loop from flash	—	53	—	µA/MHz
		32 MHz HFRCO, CPU running while loop from flash	—	43	—	µA/MHz
		26 MHz HFRCO, CPU running while loop from flash	—	47	—	µA/MHz
		16 MHz HFRCO, CPU running while loop from flash	—	61	—	µA/MHz
		1 MHz HFRCO, CPU running while loop from flash	—	587	—	µA/MHz
Current consumption in EM0 mode with all peripherals disabled, DCDC in Low Noise CCM mode[1]	I_{ACTIVE_CCM}	48 MHz crystal, CPU running while loop from flash	—	49	—	µA/MHz
		48 MHz HFRCO, CPU running while loop from flash	—	48	—	µA/MHz
		48 MHz HFRCO, CPU running Prime from flash	—	55	—	µA/MHz
		48 MHz HFRCO, CPU running CoreMark loop from flash	—	63	—	µA/MHz
		32 MHz HFRCO, CPU running while loop from flash	—	60	—	µA/MHz
		26 MHz HFRCO, CPU running while loop from flash	—	68	—	µA/MHz
		16 MHz HFRCO, CPU running while loop from flash	—	96	—	µA/MHz
		1 MHz HFRCO, CPU running while loop from flash	—	1157	—	µA/MHz
Current consumption in EM0 mode with all peripherals disabled, DCDC in LP mode[3]	I_{ACTIVE_LPM}	32 MHz HFRCO, CPU running while loop from flash	—	32	—	µA/MHz
		26 MHz HFRCO, CPU running while loop from flash	—	33	—	µA/MHz
		16 MHz HFRCO, CPU running while loop from flash	—	36	—	µA/MHz
		1 MHz HFRCO, CPU running while loop from flash	—	156	—	µA/MHz

4.1.16 Capacitive Sense (CSEN)

Table 4.23. Capacitive Sense (CSEN)

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Single conversion time (1x accumulation)	t_{CNV}	12-bit SAR Conversions	—	20.2	—	µs
		16-bit SAR Conversions	—	26.4	—	µs
		Delta Modulation Conversion (single comparison)	—	1.55	—	µs
Maximum external capacitive load	C_{EXTMAX}	CS0CG=7 (Gain = 1x), including routing parasitics	—	68	—	pF
		CS0CG=0 (Gain = 10x), including routing parasitics	—	680	—	pF
Maximum external series impedance	R_{EXTMAX}		—	1	—	kΩ
Supply current, EM2 bonded conversions, WARMUPMODE=NORMAL, WARMUPCNT=0	I_{CSEN_BOND}	12-bit SAR conversions, 20 ms conversion rate, CS0CG=7 (Gain = 1x), 10 channels bonded (total capacitance of 330 pF)[1]	—	326	—	nA
		Delta Modulation conversions, 20 ms conversion rate, CS0CG=7 (Gain = 1x), 10 channels bonded (total capacitance of 330 pF)[1]	—	226	—	nA
		12-bit SAR conversions, 200 ms conversion rate, CS0CG=7 (Gain = 1x), 10 channels bonded (total capacitance of 330 pF)[1]	—	33	—	nA
		Delta Modulation conversions, 200 ms conversion rate, CS0CG=7 (Gain = 1x), 10 channels bonded (total capacitance of 330 pF)[1]	—	25	—	nA
Supply current, EM2 scan conversions, WARMUPMODE=NORMAL, WARMUPCNT=0	I_{CSEN_EM2}	12-bit SAR conversions, 20 ms scan rate, CS0CG=0 (Gain = 10x), 8 samples per scan[1]	—	690	—	nA
		Delta Modulation conversions, 20 ms scan rate, 8 comparisons per sample (DMCR = 1, DMR = 2), CS0CG=0 (Gain = 10x), 8 samples per scan[1]	—	515	—	nA
		12-bit SAR conversions, 200 ms scan rate, CS0CG=0 (Gain = 10x), 8 samples per scan[1]	—	79	—	nA
		Delta Modulation conversions, 200 ms scan rate, 8 comparisons per sample (DMCR = 1, DMR = 2), CS0CG=0 (Gain = 10x), 8 samples per scan[1]	—	57	—	nA

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Supply current, continuous conversions, WARMUPMODE=KEEPCSENWARM	I_{CSEN_ACTIVE}	SAR or Delta Modulation conversions of 33 pF capacitor, CS0CG=0 (Gain = 10x), always on	—	90.5	—	µA
HFPERCLK supply current	$I_{CSEN\_HFPERCLK}$	Current contribution from HFPERCLK when clock to CSEN block is enabled.	—	2.25	—	µA/MHz

Note:

1. Current is specified with a total external capacitance of 33 pF per channel. Average current is dependent on how long the module is actively sampling channels within the scan period, and scales with the number of samples acquired. Supply current for a specific application can be estimated by multiplying the current per sample by the total number of samples per period (total_current = single_sample_current * (number_of_channels * accumulation)).

4.1.21.2 I2C Fast-mode (Fm)[1]

Table 4.29. I2C Fast-mode (Fm)[1]

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
SCL clock frequency[2]	f_{SCL}		0	—	400	kHz
SCL clock low time	t_{LOW}		1.3	—	—	µs
SCL clock high time	t_{HIGH}		0.6	—	—	µs
SDA set-up time	t_{SU_DAT}		100	—	—	ns
SDA hold time[3]	t_{HD_DAT}		100	—	900	ns
Repeated START condition set-up time	t_{SU_STA}		0.6	—	—	µs
(Repeated) START condition hold time	t_{HD_STA}		0.6	—	—	µs
STOP condition set-up time	t_{SU_STO}		0.6	—	—	µs
Bus free time between a STOP and START condition	t_{BUF}		1.3	—	—	µs

Note:

1. For CLHR set to 1 in the I2Cn_CTRL register.
2. For the minimum HFPERCLK frequency required in Fast-mode, refer to the I2C chapter in the reference manual.
3. The maximum SDA hold time ($t_{HD,DAT}$) needs to be met only when the device does not stretch the low time of SCL (t_{LOW}).

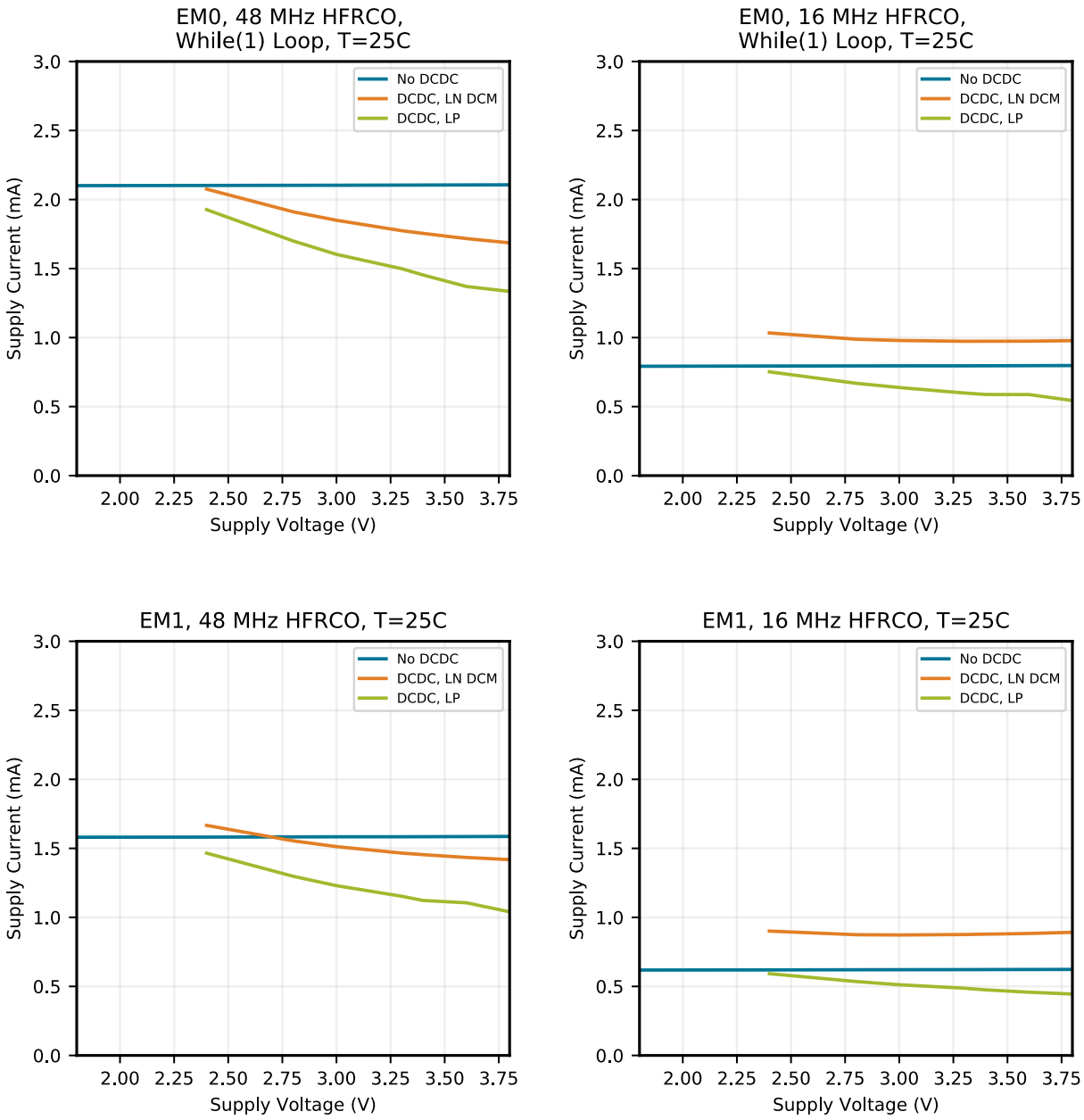


Figure 4.6. EM0 and EM1 Mode Typical Supply Current vs. Supply

Typical supply current for EM2, EM3 and EM4H using standard software libraries from Silicon Laboratories.

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
PB4	10	GPIO	PB5	11	GPIO
PB6	12	GPIO	PC0	13	GPIO (5V)
PC1	14	GPIO (5V)	PC2	15	GPIO (5V)
PC3	16	GPIO (5V)	PC4	17	GPIO
PC5	18	GPIO	PB7	19	GPIO
PB8	20	GPIO	PA8	21	GPIO
PA9	22	GPIO	PA10	23	GPIO
PA12	24	GPIO	PA13	25	GPIO (5V)
PA14	26	GPIO	RESETn	27	Reset input, active low. To apply an external reset source to this pin, it is required to only drive this pin low during reset, and let the internal pull-up ensure that reset is released.
PB11	28	GPIO	PB12	29	GPIO
AVDD	30 34	Analog power supply.	PB13	31	GPIO
PB14	32	GPIO	PD0	35	GPIO (5V)
PD1	36	GPIO	PD2	37	GPIO (5V)
PD3	38	GPIO	PD4	39	GPIO
PD5	40	GPIO	PD6	41	GPIO
PD7	42	GPIO	PD8	43	GPIO
PC6	44	GPIO	PC7	45	GPIO
VREGSW	47	DCDC regulator switching node	VREGVDD	48	Voltage regulator VDD input
DVDD	49	Digital power supply.	DECOUPLE	50	Decouple output for on-chip voltage regulator. An external decoupling capacitor is required at this pin.
PE4	52	GPIO	PE5	53	GPIO
PE6	54	GPIO	PE7	55	GPIO
PC8	56	GPIO	PC9	57	GPIO
PC10	58	GPIO (5V)	PC11	59	GPIO (5V)
PC12	60	GPIO (5V)	PC13	61	GPIO (5V)
PC14	62	GPIO (5V)	PC15	63	GPIO (5V)
PF0	64	GPIO (5V)	PF1	65	GPIO (5V)
PF2	66	GPIO	PF3	67	GPIO
PF4	68	GPIO	PF5	69	GPIO
PE8	71	GPIO	PE9	72	GPIO
PE10	73	GPIO	PE11	74	GPIO
BODEN	75	Brown-Out Detector Enable. This pin may be left disconnected or tied to AVDD.	PE12	76	GPIO
PE13	77	GPIO	PE14	78	GPIO

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
PB4	10	GPIO	PB5	11	GPIO
PB6	12	GPIO	PC4	13	GPIO
PC5	14	GPIO	PB7	15	GPIO
PB8	16	GPIO	PA8	17	GPIO
PA12	18	GPIO	PA13	19	GPIO (5V)
PA14	20	GPIO	RESETn	21	Reset input, active low. To apply an external reset source to this pin, it is required to only drive this pin low during reset, and let the internal pull-up ensure that reset is released.
PB11	22	GPIO	PB12	23	GPIO
AVDD	24 28	Analog power supply.	PB13	25	GPIO
PB14	26	GPIO	PD0	29	GPIO (5V)
PD1	30	GPIO	PD3	31	GPIO
PD4	32	GPIO	PD5	33	GPIO
PD6	34	GPIO	PD7	35	GPIO
PD8	36	GPIO	PC7	37	GPIO
VREGSW	39	DCDC regulator switching node	VREGVDD	40	Voltage regulator VDD input
DVDD	41	Digital power supply.	DECOUPLE	42	Decouple output for on-chip voltage regulator. An external decoupling capacitor is required at this pin.
PE4	43	GPIO	PE5	44	GPIO
PE6	45	GPIO	PE7	46	GPIO
PC12	47	GPIO (5V)	PC13	48	GPIO (5V)
PF0	49	GPIO (5V)	PF1	50	GPIO (5V)
PF2	51	GPIO	PF3	52	GPIO
PF4	53	GPIO	PF5	54	GPIO
PE8	56	GPIO	PE9	57	GPIO
PE10	58	GPIO	PE11	59	GPIO
PE12	60	GPIO	PE13	61	GPIO
PE14	62	GPIO	PE15	63	GPIO
PA15	64	GPIO			

Note:

1. GPIO with 5V tolerance are indicated by (5V).

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
PB6	12	GPIO	PC4	13	GPIO
PC5	14	GPIO	PB7	15	GPIO
PB8	16	GPIO	PA12	17	GPIO
PA13	18	GPIO (5V)	PA14	19	GPIO
RESETn	20	Reset input, active low. To apply an external reset source to this pin, it is required to only drive this pin low during reset, and let the internal pull-up ensure that reset is released.	PB11	21	GPIO
PB12	22	GPIO	AVDD	23 27	Analog power supply.
PB13	24	GPIO	PB14	25	GPIO
PD0	28	GPIO (5V)	PD1	29	GPIO
PD2	30	GPIO (5V)	PD3	31	GPIO
PD4	32	GPIO	PD5	33	GPIO
PD6	34	GPIO	PD7	35	GPIO
PD8	36	GPIO	PC6	37	GPIO
PC7	38	GPIO	DVDD	39	Digital power supply.
DECOUPLE	40	Decouple output for on-chip voltage regulator. An external decoupling capacitor is required at this pin.	PE4	41	GPIO
PE5	42	GPIO	PE6	43	GPIO
PE7	44	GPIO	PC12	45	GPIO (5V)
PC13	46	GPIO (5V)	PC14	47	GPIO (5V)
PC15	48	GPIO (5V)	PF0	49	GPIO (5V)
PF1	50	GPIO (5V)	PF2	51	GPIO
PF3	52	GPIO	PF4	53	GPIO
PF5	54	GPIO	PE8	56	GPIO
PE9	57	GPIO	PE10	58	GPIO
PE11	59	GPIO	PE12	60	GPIO
PE13	61	GPIO	PE14	62	GPIO
PE15	63	GPIO	PA15	64	GPIO

Note:

1. GPIO with 5V tolerance are indicated by (5V).

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
PC3	12	GPIO (5V)	PC4	13	GPIO
PC5	14	GPIO	PB7	15	GPIO
PB8	16	GPIO	PA8	17	GPIO
PA9	18	GPIO	PA10	19	GPIO
RESETn	20	Reset input, active low. To apply an external reset source to this pin, it is required to only drive this pin low during reset, and let the internal pull-up ensure that reset is released.	PB11	21	GPIO
PB12	22	GPIO	AVDD	23 27	Analog power supply.
PB13	24	GPIO	PB14	25	GPIO
PD0	28	GPIO (5V)	PD1	29	GPIO
PD2	30	GPIO (5V)	PD3	31	GPIO
PD4	32	GPIO	PD5	33	GPIO
PD6	34	GPIO	PD7	35	GPIO
PD8	36	GPIO	PC6	37	GPIO
PC7	38	GPIO	DVDD	39	Digital power supply.
DECOUPLE	40	Decouple output for on-chip voltage regulator. An external decoupling capacitor is required at this pin.	PC8	41	GPIO
PC9	42	GPIO	PC10	43	GPIO (5V)
PC11	44	GPIO (5V)	PC12	45	GPIO (5V)
PC13	46	GPIO (5V)	PC14	47	GPIO (5V)
PC15	48	GPIO (5V)	PF0	49	GPIO (5V)
PF1	50	GPIO (5V)	PF2	51	GPIO
PF3	52	GPIO	PF4	53	GPIO
PF5	54	GPIO	PE8	56	GPIO
PE9	57	GPIO	PE10	58	GPIO
PE11	59	GPIO	PE12	60	GPIO
PE13	61	GPIO	PE14	62	GPIO
PE15	63	GPIO	PA15	64	GPIO

Note:

1. GPIO with 5V tolerance are indicated by (5V).

Alternate	LOCATION		
Functionality	0 - 3	4 - 7	Description
CAN0_TX	0: PC1 1: PF2 2: PD1		CAN0 TX.
CMU_CLK0	0: PA2 1: PC12 2: PD7	4: PF2 5: PA12	Clock Management Unit, clock output number 0.
CMU_CLK1	0: PA1 1: PD8 2: PE12	4: PF3 5: PB11	Clock Management Unit, clock output number 1.
CMU_CLK2	0: PA0 1: PA3 2: PD6	4: PA3	Clock Management Unit, clock output number 2.
CMU_CLKI0	0: PD4 1: PA3 2: PB8 3: PB13	6: PE12 7: PB11	Clock Management Unit, clock input number 0.
DBG_SWCLKTCK	0: PF0		Debug-interface Serial Wire clock input and JTAG Test Clock. Note that this function is enabled to the pin out of reset, and has a built-in pull down.
DBG_SWDIOTMS	0: PF1		Debug-interface Serial Wire data input / output and JTAG Test Mode Select. Note that this function is enabled to the pin out of reset, and has a built-in pull up.
DBG_TDI	0: PF5		Debug-interface JTAG Test Data In. Note that this function becomes available after the first valid JTAG command is received, and has a built-in pull up when JTAG is active.
DBG_TDO	0: PF2		Debug-interface JTAG Test Data Out. Note that this function becomes available after the first valid JTAG command is received.
GPIO_EM4WU0	0: PA0		Pin can be used to wake the system up from EM4
GPIO_EM4WU1	0: PA6		Pin can be used to wake the system up from EM4
GPIO_EM4WU2	0: PC9		Pin can be used to wake the system up from EM4
GPIO_EM4WU3	0: PF1		Pin can be used to wake the system up from EM4

Alternate	LOCATION		
Functionality	0 - 3	4 - 7	Description
LCD_SEG9	0: PE13		LCD segment line 9.
LCD_SEG10	0: PE14		LCD segment line 10.
LCD_SEG11	0: PE15		LCD segment line 11.
LCD_SEG12	0: PA15		LCD segment line 12.
LCD_SEG13	0: PA0		LCD segment line 13.
LCD_SEG14	0: PA1		LCD segment line 14.
LCD_SEG15	0: PA2		LCD segment line 15.
LCD_SEG16	0: PA3		LCD segment line 16.
LCD_SEG17	0: PA4		LCD segment line 17.
LCD_SEG18	0: PA5		LCD segment line 18.
LCD_SEG19	0: PA6		LCD segment line 19.
LCD_SEG20 / LCD_COM4	0: PB3		LCD segment line 20. This pin may also be used as LCD COM line 4
LCD_SEG21 / LCD_COM5	0: PB4		LCD segment line 21. This pin may also be used as LCD COM line 5

Alternate	LOCATION		
Functionality	0 - 3	4 - 7	Description
LETIM0_OUT1	0: PD7 1: PB12 2: PF1 3: PC5	4: PE13 5: PC15 6: PA9	Low Energy Timer LETIM0, output channel 1.
LEU0_RX	0: PD5 1: PB14 2: PE15 3: PF1	4: PA0 5: PC15	LEUART0 Receive input.
LEU0_TX	0: PD4 1: PB13 2: PE14 3: PF0	4: PF2 5: PC14	LEUART0 Transmit output. Also used as receive input in half duplex communication.
LFXTAL_N	0: PB8		Low Frequency Crystal (typically 32.768 kHz) negative pin. Also used as an optional external clock input pin.
LFXTAL_P	0: PB7		Low Frequency Crystal (typically 32.768 kHz) positive pin.
OPA0_N	0: PC5		Operational Amplifier 0 external negative input.
OPA0_P	0: PC4		Operational Amplifier 0 external positive input.
OPA1_N	0: PD7		Operational Amplifier 1 external negative input.
OPA1_P	0: PD6		Operational Amplifier 1 external positive input.
OPA2_N	0: PD3		Operational Amplifier 2 external negative input.
OPA2_OUT	0: PD5		Operational Amplifier 2 output.
OPA2_OUTALT	0: PD0		Operational Amplifier 2 alternative output.
OPA2_P	0: PD4		Operational Amplifier 2 external positive input.

Alternate	LOCATION		
Functionality	0 - 3	4 - 7	Description
US2_CLK	0: PC4 1: PB5 2: PA9 3: PA15	5: PF2	USART2 clock input / output.
US2_CS	0: PC5 1: PB6 2: PA10 3: PB11	5: PF5	USART2 chip select input / output.
US2_CTS	0: PC1 1: PB12	4: PC12 5: PD6	USART2 Clear To Send hardware flow control input.
US2_RTS	0: PC0 2: PA12 3: PC14	4: PC13 5: PD8	USART2 Request To Send hardware flow control output.
US2_RX	0: PC3 1: PB4 2: PA8 3: PA14	5: PF1	USART2 Asynchronous Receive. USART2 Synchronous mode Master Input / Slave Output (MISO).
US2_TX	0: PC2 1: PB3 3: PA13	5: PF0	USART2 Asynchronous Transmit. Also used as receive input in half duplex communication. USART2 Synchronous mode Master Output / Slave Input (MOSI).
US3_CLK	0: PA2 1: PD7 2: PD4		USART3 clock input / output.
US3_CS	0: PA3 1: PE4 2: PC14 3: PC0		USART3 chip select input / output.
US3_CTS	0: PA4 1: PE5 2: PD6		USART3 Clear To Send hardware flow control input.
US3_RTS	0: PA5 1: PC1 2: PA14 3: PC15		USART3 Request To Send hardware flow control output.
US3_RX	0: PA1 1: PE7 2: PB7		USART3 Asynchronous Receive. USART3 Synchronous mode Master Input / Slave Output (MISO).
US3_TX	0: PA0 1: PE6 2: PB3		USART3 Asynchronous Transmit. Also used as receive input in half duplex communication. USART3 Synchronous mode Master Output / Slave Input (MOSI).
VDAC0_EXT	0: PD6		Digital to analog converter VDAC0 external reference input pin.

6.2 TQFP80 PCB Land Pattern

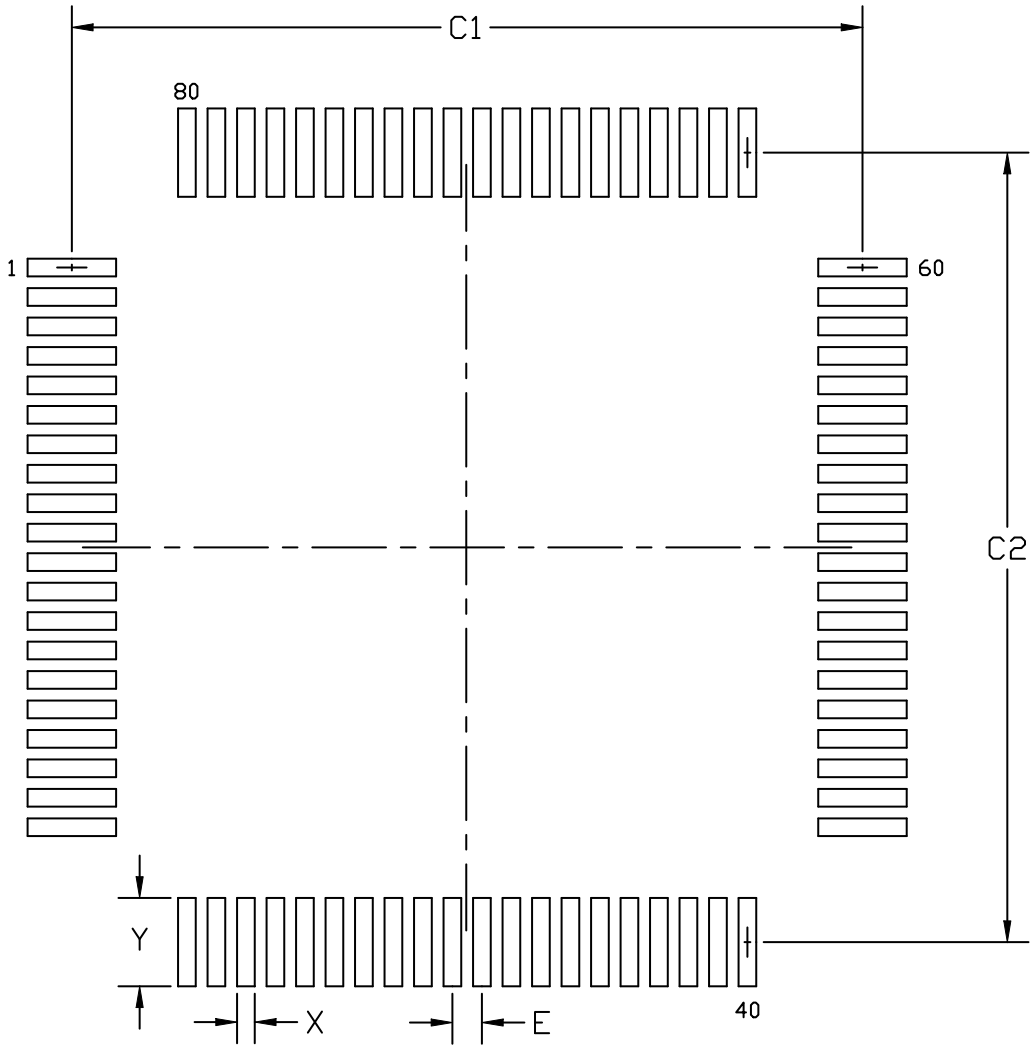


Figure 6.2. TQFP80 PCB Land Pattern Drawing

9.2 QFN64 PCB Land Pattern

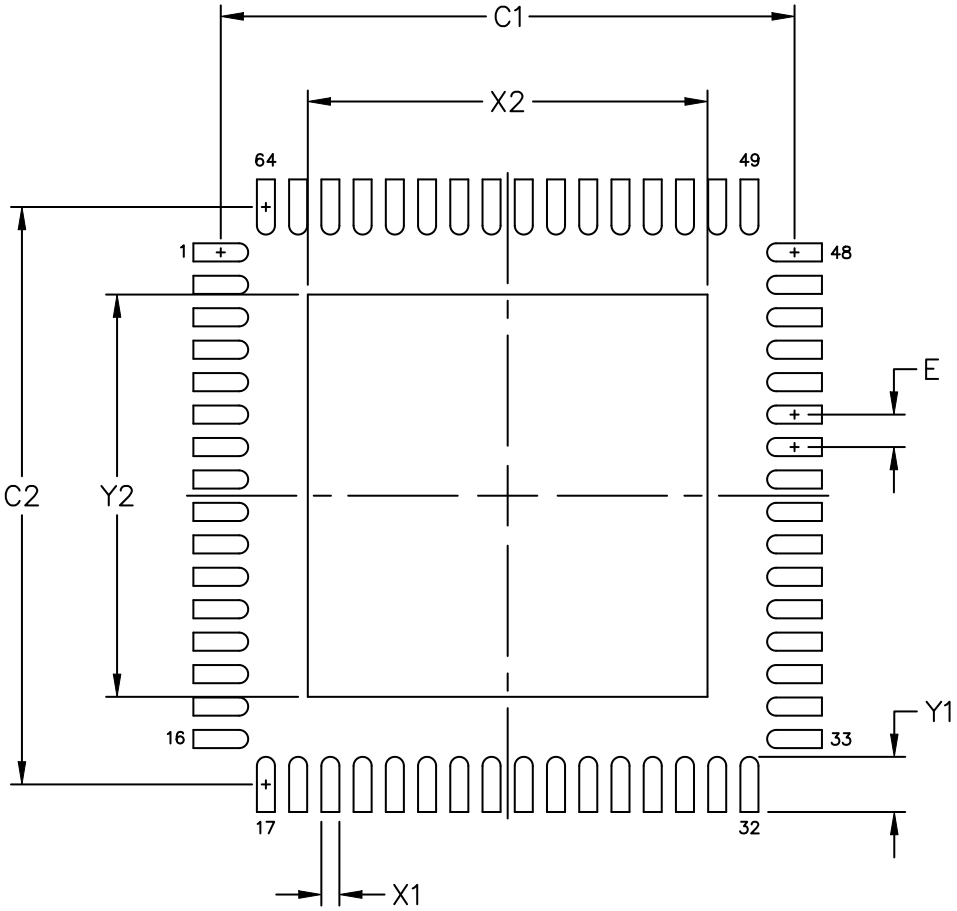
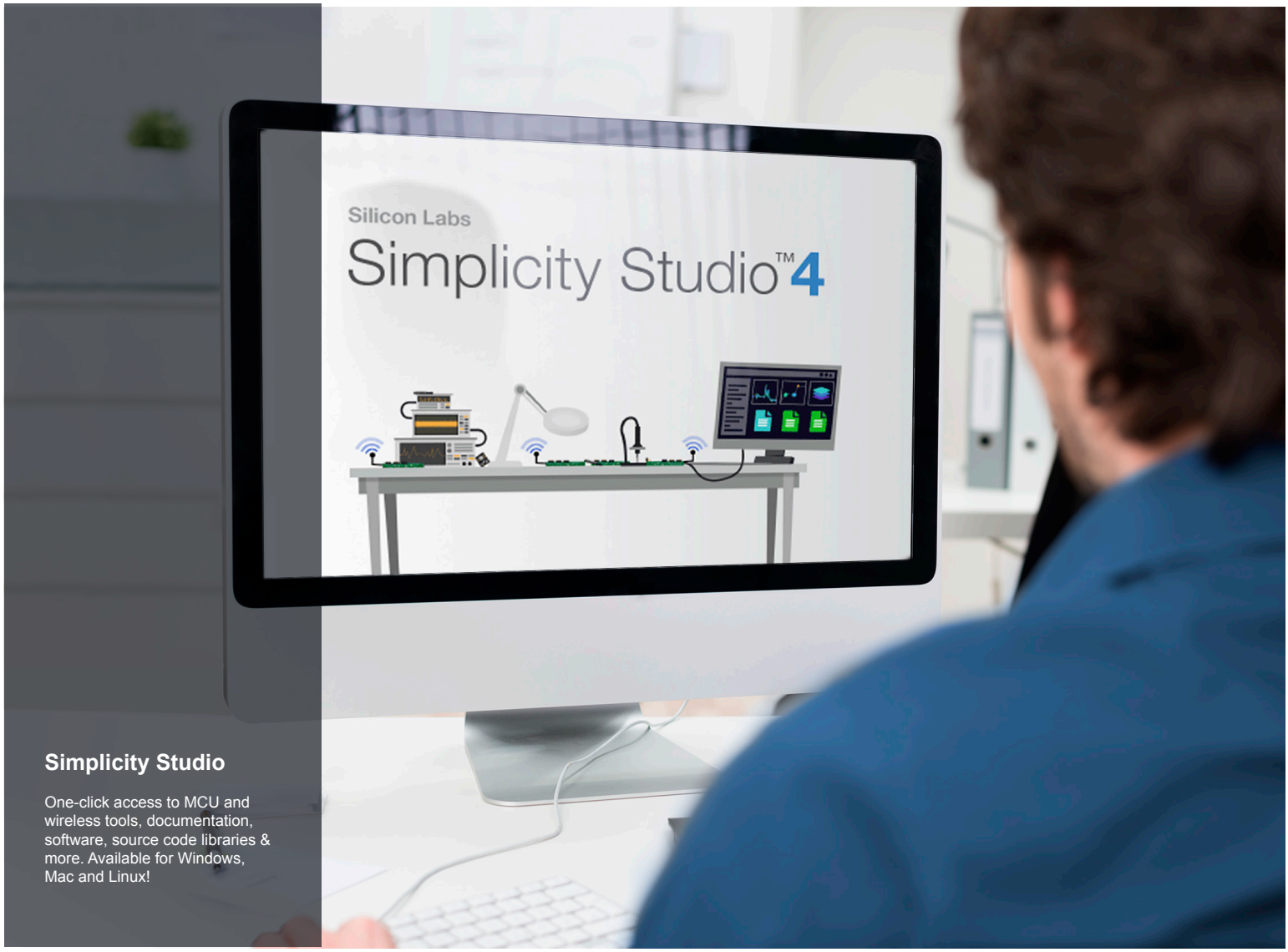


Figure 9.2. QFN64 PCB Land Pattern Drawing



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