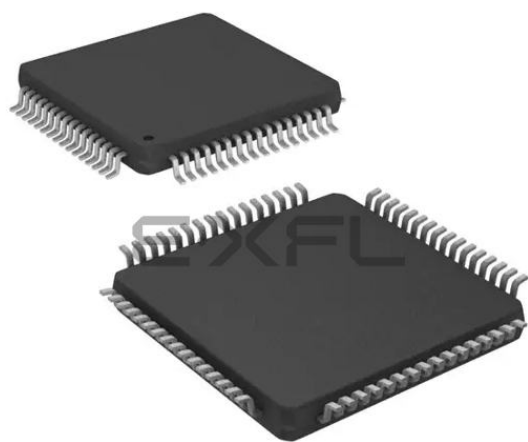




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Details

Product Status	Discontinued at Digi-Key
Core Processor	ARM® Cortex®-M0+
Core Size	32-Bit Single-Core
Speed	48MHz
Connectivity	CANbus, I ² C, IrDA, LINbus, SmartCard, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, I ² S, POR, PWM, WDT
Number of I/O	53
Program Memory Size	64KB (64K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	32K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.8V
Data Converters	A/D 12bit SAR; D/A 12bit
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TJ)
Mounting Type	Surface Mount
Package / Case	64-TQFP
Supplier Device Package	64-TQFP (10x10)
Purchase URL	https://www.e-xfl.com/product-detail/silicon-labs/efm32tg11b140f64iq64-ar

2. Ordering Information

Table 2.1. Ordering Information

Ordering Code	Flash (kB)	RAM (kB)	DC-DC Converter	LCD	GPIO	Package	Temp Range
EFM32TG11B520F128GM80-A	128	32	Yes	Yes	67	QFN80	-40 to +85°C
EFM32TG11B520F128GQ80-A	128	32	Yes	Yes	63	QFP80	-40 to +85°C
EFM32TG11B520F128IM80-A	128	32	Yes	Yes	67	QFN80	-40 to +125°C
EFM32TG11B520F128IQ80-A	128	32	Yes	Yes	63	QFP80	-40 to +125°C
EFM32TG11B540F64GM80-A	64	32	Yes	Yes	67	QFN80	-40 to +85°C
EFM32TG11B540F64GQ80-A	64	32	Yes	Yes	63	QFP80	-40 to +85°C
EFM32TG11B540F64IM80-A	64	32	Yes	Yes	67	QFN80	-40 to +125°C
EFM32TG11B540F64IQ80-A	64	32	Yes	Yes	63	QFP80	-40 to +125°C
EFM32TG11B520F128GM64-A	128	32	Yes	Yes	53	QFN64	-40 to +85°C
EFM32TG11B520F128GQ64-A	128	32	Yes	Yes	50	QFP64	-40 to +85°C
EFM32TG11B520F128IM64-A	128	32	Yes	Yes	53	QFN64	-40 to +125°C
EFM32TG11B520F128IQ64-A	128	32	Yes	Yes	50	QFP64	-40 to +125°C
EFM32TG11B540F64GM64-A	64	32	Yes	Yes	53	QFN64	-40 to +85°C
EFM32TG11B540F64GQ64-A	64	32	Yes	Yes	50	QFP64	-40 to +85°C
EFM32TG11B540F64IM64-A	64	32	Yes	Yes	53	QFN64	-40 to +125°C
EFM32TG11B540F64IQ64-A	64	32	Yes	Yes	50	QFP64	-40 to +125°C
EFM32TG11B520F128GQ48-A	128	32	Yes	Yes	34	QFP48	-40 to +85°C
EFM32TG11B520F128IQ48-A	128	32	Yes	Yes	34	QFP48	-40 to +125°C
EFM32TG11B540F64GQ48-A	64	32	Yes	Yes	34	QFP48	-40 to +85°C
EFM32TG11B540F64IQ48-A	64	32	Yes	Yes	34	QFP48	-40 to +125°C
EFM32TG11B520F128GM32-A	128	32	Yes	Yes	22	QFN32	-40 to +85°C
EFM32TG11B520F128IM32-A	128	32	Yes	Yes	22	QFN32	-40 to +125°C
EFM32TG11B540F64GM32-A	64	32	Yes	Yes	22	QFN32	-40 to +85°C
EFM32TG11B540F64IM32-A	64	32	Yes	Yes	22	QFN32	-40 to +125°C
EFM32TG11B320F128GM64-A	128	32	No	Yes	56	QFN64	-40 to +85°C
EFM32TG11B320F128GQ64-A	128	32	No	Yes	53	QFP64	-40 to +85°C
EFM32TG11B320F128IM64-A	128	32	No	Yes	56	QFN64	-40 to +125°C
EFM32TG11B320F128IQ64-A	128	32	No	Yes	53	QFP64	-40 to +125°C
EFM32TG11B340F64GM64-A	64	32	No	Yes	56	QFN64	-40 to +85°C
EFM32TG11B340F64GQ64-A	64	32	No	Yes	53	QFP64	-40 to +85°C
EFM32TG11B340F64IM64-A	64	32	No	Yes	56	QFN64	-40 to +125°C
EFM32TG11B340F64IQ64-A	64	32	No	Yes	53	QFP64	-40 to +125°C

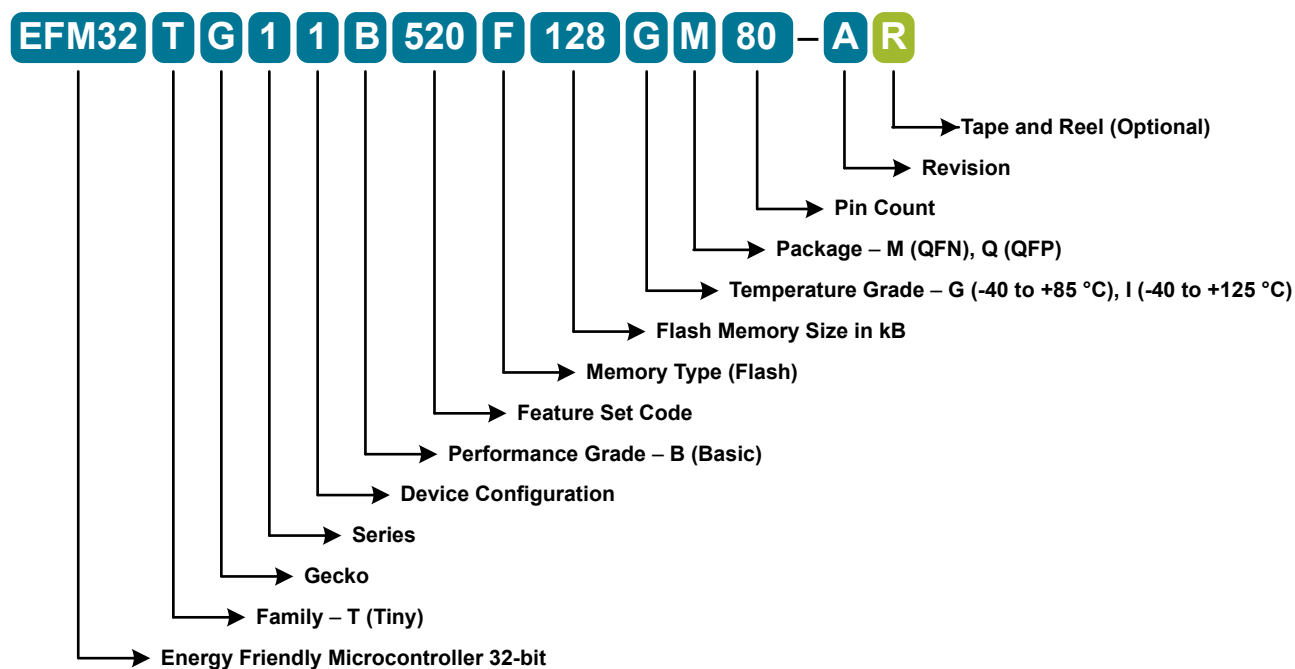


Figure 2.1. Ordering Code Key

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Max load current	I _{LOAD_MAX}	Low noise (LN) mode, Heavy Drive ² , T ≤ 85 °C	—	—	200	mA
		Low noise (LN) mode, Heavy Drive ² , T > 85 °C	—	—	100	mA
		Low noise (LN) mode, Medium Drive ²	—	—	100	mA
		Low noise (LN) mode, Light Drive ²	—	—	50	mA
		Low power (LP) mode, LPCMPBIASEMxx ³ = 0	—	—	75	μA
		Low power (LP) mode, LPCMPBIASEMxx ³ = 3	—	—	10	mA
DCDC nominal output capacitor ⁵	C _{DCDC}	25% tolerance	1	4.7	4.7	μF
DCDC nominal output inductor	L _{DCDC}	20% tolerance	4.7	4.7	4.7	μH
Resistance in Bypass mode	R _{BYP}		—	1.2	TBD	Ω

Note:

1. Due to internal dropout, the DC-DC output will never be able to reach its input voltage, V_{VREGVDD}.
2. Drive levels are defined by configuration of the PFETCNT and NFETCNT registers. Light Drive: PFETCNT=NFETCNT=3; Medium Drive: PFETCNT=NFETCNT=7; Heavy Drive: PFETCNT=NFETCNT=15.
3. LPCMPBIASEMxx refers to either LPCMPBIASEM234H in the EMU_DCDCMISCCTRL register or LPCMPBIASEM01 in the EMU_DCDCLOEM01CFG register, depending on the energy mode.
4. LP mode controller is a hysteretic controller that maintains the output voltage within the specified limits.
5. Output voltage under/over-shoot and regulation are specified with C_{DCDC} 4.7 μF. Different settings for DCDCLNCOMPCTRL must be used if C_{DCDC} is lower than 4.7 μF. See Application Note AN0948 for details.

4.1.5 Backup Supply Domain

Table 4.5. Backup Supply Domain

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Backup supply voltage range	V _{BU_VIN}		TBD	—	3.8	V
PWRRES resistor	R _{PWRRES}	EMU_BUCTRL_PWRRES = RES0	TBD	3900	TBD	Ω
		EMU_BUCTRL_PWRRES = RES1	TBD	1800	TBD	Ω
		EMU_BUCTRL_PWRRES = RES2	TBD	1330	TBD	Ω
		EMU_BUCTRL_PWRRES = RES3	TBD	815	TBD	Ω
Output impedance between BU_VIN and BU_VOUT ²	R _{BU_VOUT}	EMU_BUCTRL_VOUTRES = STRONG	TBD	110	TBD	Ω
		EMU_BUCTRL_VOUTRES = MED	TBD	775	TBD	Ω
		EMU_BUCTRL_VOUTRES = WEAK	TBD	6500	TBD	Ω
Supply current	I _{BU_VIN}	BU_VIN not powering backup domain	—	10	TBD	nA
		BU_VIN powering backup domain ¹	—	450	TBD	nA

Note:
1. Additional current required by backup circuitry when backup is active. Includes supply current of backup switches and backup regulator. Does not include supply current required for backed-up circuitry.
2. BU_VOUT and BU_STAT signals are not available in all package configurations. Check the device pinout for availability.

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Note: 1. ACMPVDD is a supply chosen by the setting in ACMPn_CTRL_PWRSEL and may be IOVDD, AVDD or DVDD. 2. The total ACMP current is the sum of the contributions from the ACMP and its internal voltage reference. $I_{ACMPTOTAL} = I_{ACMP} + I_{ACMPREF}$. 3. ± 100 mV differential drive. 4. In ACMPn_CTRL register. 5. In ACMPn_HYSTERESIS registers. 6. In ACMPn_INPUTSEL register.						

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Note: 1. Supply current specifications are for VDAC circuitry operating with static output only and do not include current required to drive the load. 2. In differential mode, the output is defined as the difference between two single-ended outputs. Absolute voltage on each output is limited to the single-ended range. 3. Entire range is monotonic and has no missing codes. 4. Current from HUPERCLK is dependent on HUPERCLK frequency. This current contributes to the total supply current used when the clock to the DAC module is enabled in the CMU. 5. Gain is calculated by measuring the slope from 10% to 90% of full scale. Offset is calculated by comparing actual VDAC output at 10% of full scale to ideal VDAC output at 10% of full scale with the measured gain. 6. PSRR calculated as $20 * \log_{10}(\Delta V_{DD} / \Delta V_{OUT})$, VDAC output at 90% of full scale						

4.1.16 Capacitive Sense (CSEN)

Table 4.23. Capacitive Sense (CSEN)

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Single conversion time (1x accumulation)	t_{CNV}	12-bit SAR Conversions	—	20.2	—	μs
		16-bit SAR Conversions	—	26.4	—	μs
		Delta Modulation Conversion (single comparison)	—	1.55	—	μs
Maximum external capacitive load	C_{EXTMAX}	CS0CG=7 (Gain = 1x), including routing parasitics	—	68	—	pF
		CS0CG=0 (Gain = 10x), including routing parasitics	—	680	—	pF
Maximum external series impedance	R_{EXTMAX}		—	1	—	k Ω
Supply current, EM2 bonded conversions, WARMUP-MODE=NORMAL, WARMUPCNT=0	I_{CSEN_BOND}	12-bit SAR conversions, 20 ms conversion rate, CS0CG=7 (Gain = 1x), 10 channels bonded (total capacitance of 330 pF) ¹	—	326	—	nA
		Delta Modulation conversions, 20 ms conversion rate, CS0CG=7 (Gain = 1x), 10 channels bonded (total capacitance of 330 pF) ¹	—	226	—	nA
		12-bit SAR conversions, 200 ms conversion rate, CS0CG=7 (Gain = 1x), 10 channels bonded (total capacitance of 330 pF) ¹	—	33	—	nA
		Delta Modulation conversions, 200 ms conversion rate, CS0CG=7 (Gain = 1x), 10 channels bonded (total capacitance of 330 pF) ¹	—	25	—	nA
Supply current, EM2 scan conversions, WARMUP-MODE=NORMAL, WARMUPCNT=0	I_{CSEN_EM2}	12-bit SAR conversions, 20 ms scan rate, CS0CG=0 (Gain = 10x), 8 samples per scan ¹	—	690	—	nA
		Delta Modulation conversions, 20 ms scan rate, 8 comparisons per sample (DMCR = 1, DMR = 2), CS0CG=0 (Gain = 10x), 8 samples per scan ¹	—	515	—	nA
		12-bit SAR conversions, 200 ms scan rate, CS0CG=0 (Gain = 10x), 8 samples per scan ¹	—	79	—	nA
		Delta Modulation conversions, 200 ms scan rate, 8 comparisons per sample (DMCR = 1, DMR = 2), CS0CG=0 (Gain = 10x), 8 samples per scan ¹	—	57	—	nA

4.1.21 I2C

4.1.21.1 I2C Standard-mode (Sm)¹

Table 4.28. I2C Standard-mode (Sm)¹

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
SCL clock frequency ²	f _{SCL}		0	—	100	kHz
SCL clock low time	t _{LOW}		4.7	—	—	μs
SCL clock high time	t _{HIGH}		4	—	—	μs
SDA set-up time	t _{SU_DAT}		250	—	—	ns
SDA hold time ³	t _{HD_DAT}		100	—	3450	ns
Repeated START condition set-up time	t _{SU_STA}		4.7	—	—	μs
(Repeated) START condition hold time	t _{HD_STA}		4	—	—	μs
STOP condition set-up time	t _{SU_STO}		4	—	—	μs
Bus free time between a STOP and START condition	t _{BUF}		4.7	—	—	μs

Note:

1. For CLHR set to 0 in the I2Cn_CTRL register.
2. For the minimum HPERCLK frequency required in Standard-mode, refer to the I2C chapter in the reference manual.
3. The maximum SDA hold time (t_{HD_DAT}) needs to be met only when the device does not stretch the low time of SCL (t_{LOW}).

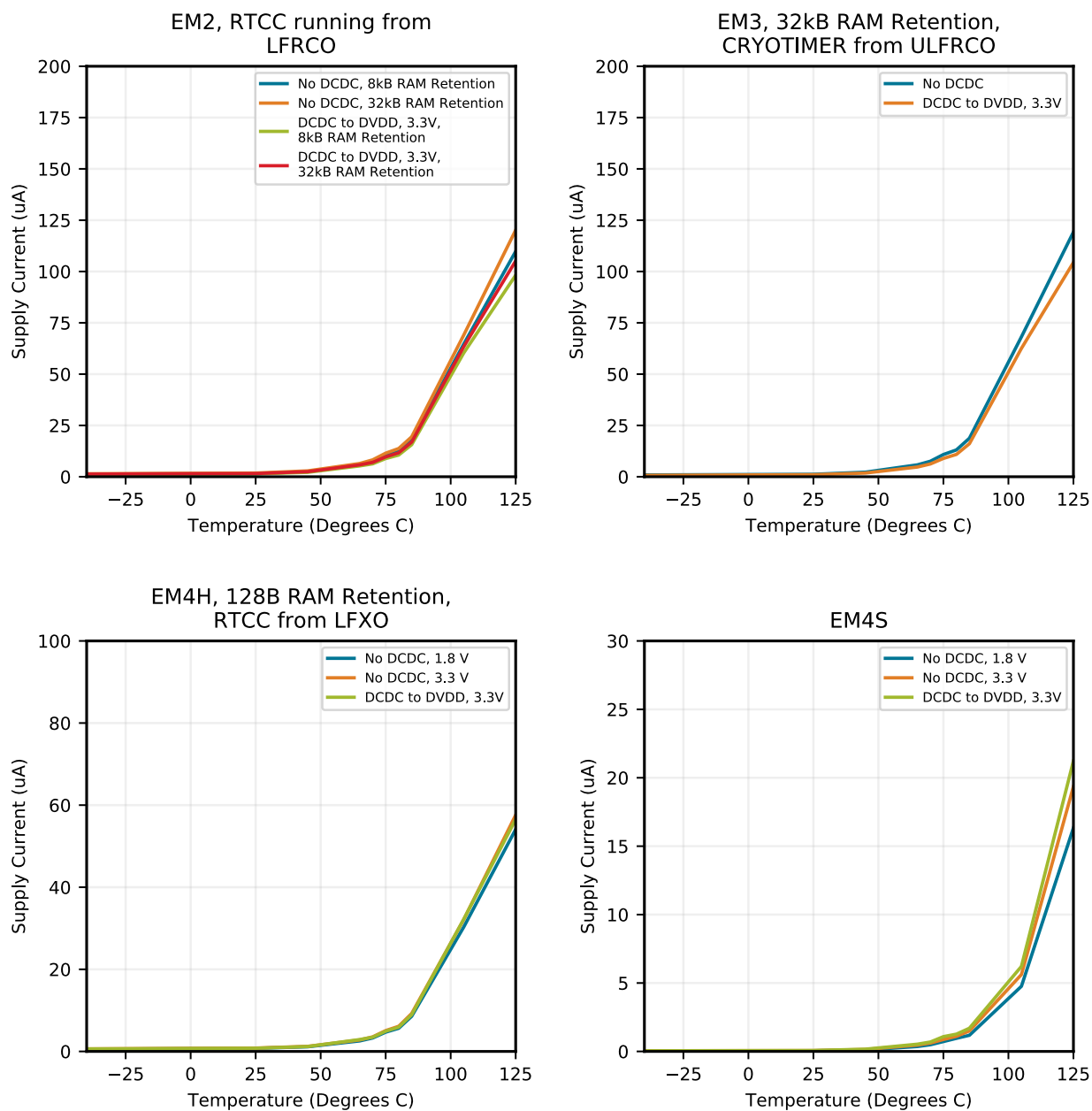


Figure 4.5. EM2, EM3, EM4H and EM4S Typical Supply Current vs. Temperature

5.2 EFM32TG11B5xx in QFN80 Device Pinout

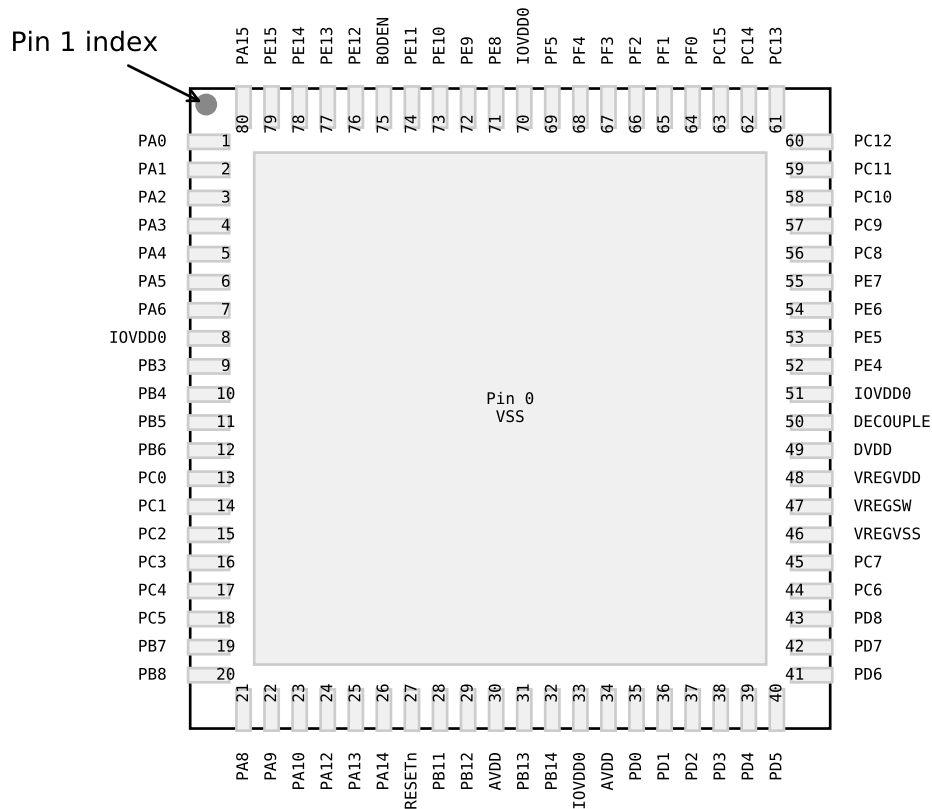


Figure 5.2. EFM32TG11B5xx in QFN80 Device Pinout

The following table provides package pin connections and general descriptions of pin functionality. For detailed information on the supported features for each GPIO pin, see [5.14 GPIO Functionality Table](#) or [5.15 Alternate Functionality Overview](#).

Table 5.2. EFM32TG11B5xx in QFN80 Device Pinout

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
VREGVSS	0 46	Voltage regulator VSS	PA0	1	GPIO
PA1	2	GPIO	PA2	3	GPIO
PA3	4	GPIO	PA4	5	GPIO
PA5	6	GPIO	PA6	7	GPIO
IOVDD0	8 33 51 70	Digital IO power supply 0.	PB3	9	GPIO

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
PC4	13	GPIO	PC5	14	GPIO
PB7	15	GPIO	PB8	16	GPIO
PA8	17	GPIO	PA12	18	GPIO
PA14	19	GPIO	RESETn	20	Reset input, active low. To apply an external reset source to this pin, it is required to only drive this pin low during reset, and let the internal pull-up ensure that reset is released.
PB11	21	GPIO	PB12	22	GPIO
AVDD	24 28	Analog power supply.	PB13	25	GPIO
PB14	26	GPIO	PD0	29	GPIO (5V)
PD1	30	GPIO	PD3	31	GPIO
PD4	32	GPIO	PD5	33	GPIO
PD6	34	GPIO	PD7	35	GPIO
PD8	36	GPIO	PC7	37	GPIO
VREGVSS	38	Voltage regulator VSS	VREGSW	39	DCDC regulator switching node
VREGVDD	40	Voltage regulator VDD input	DVDD	41	Digital power supply.
DECOUPLE	42	Decouple output for on-chip voltage regulator. An external decoupling capacitor is required at this pin.	PE4	43	GPIO
PE5	44	GPIO	PE6	45	GPIO
PE7	46	GPIO	PC12	47	GPIO (5V)
PC13	48	GPIO (5V)	PF0	49	GPIO (5V)
PF1	50	GPIO (5V)	PF2	51	GPIO
PF3	52	GPIO	PF4	53	GPIO
PF5	54	GPIO	PE8	57	GPIO
PE9	58	GPIO	PE10	59	GPIO
PE11	60	GPIO	PE12	61	GPIO
PE13	62	GPIO	PE14	63	GPIO
PE15	64	GPIO			

Note:

1. GPIO with 5V tolerance are indicated by (5V).

5.4 EFM32TG11B3xx in QFP64 Device Pinout

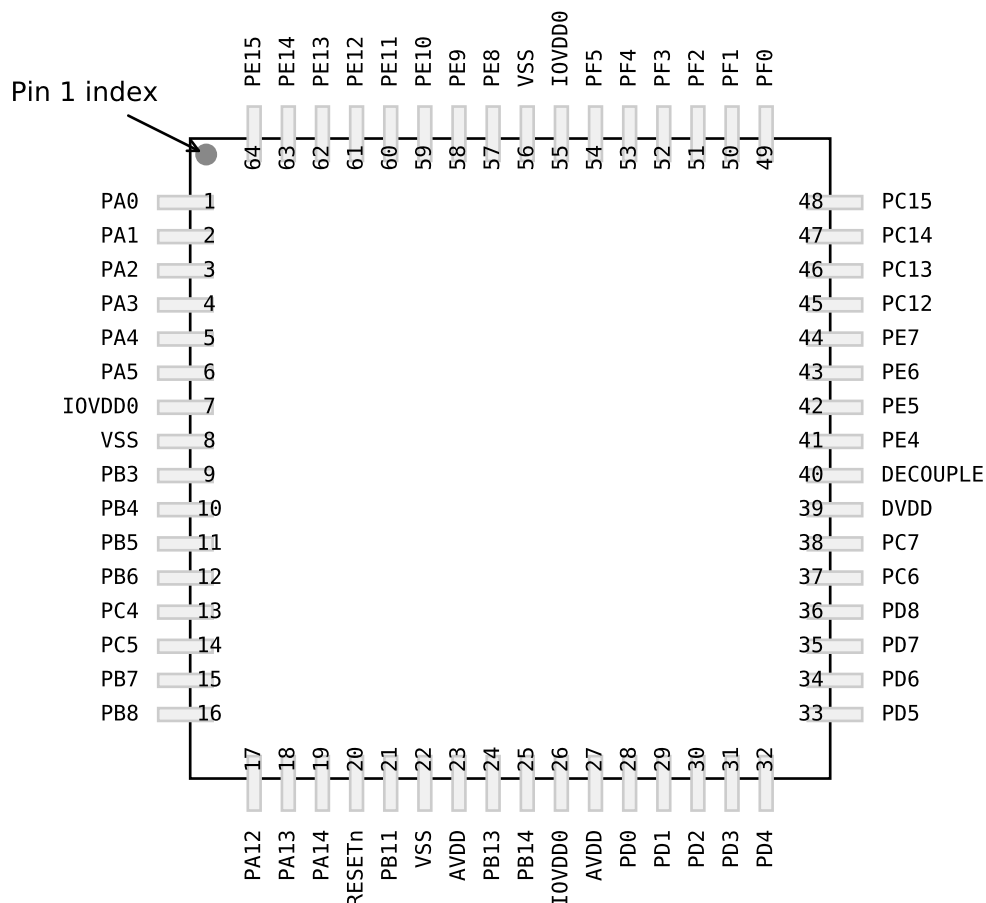


Figure 5.4. EFM32TG11B3xx in QFP64 Device Pinout

The following table provides package pin connections and general descriptions of pin functionality. For detailed information on the supported features for each GPIO pin, see [5.14 GPIO Functionality Table](#) or [5.15 Alternate Functionality Overview](#).

Table 5.4. EFM32TG11B3xx in QFP64 Device Pinout

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
PA0	1	GPIO	PA1	2	GPIO
PA2	3	GPIO	PA3	4	GPIO
PA4	5	GPIO	PA5	6	GPIO
IOVDD0	7 26 55	Digital IO power supply 0.	VSS	8 22 56	Ground
PB3	9	GPIO	PB4	10	GPIO
PB5	11	GPIO	PB6	12	GPIO

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
PC4	13	GPIO	PC5	14	GPIO
PB7	15	GPIO	PB8	16	GPIO
PA8	17	GPIO	PA9	18	GPIO
PA10	19	GPIO	RESETn	20	Reset input, active low. To apply an external reset source to this pin, it is required to only drive this pin low during reset, and let the internal pull-up ensure that reset is released.
PB11	21	GPIO	AVDD	23 27	Analog power supply.
PB13	24	GPIO	PB14	25	GPIO
PD0	28	GPIO (5V)	PD1	29	GPIO
PD2	30	GPIO (5V)	PD3	31	GPIO
PD4	32	GPIO	PD5	33	GPIO
PD6	34	GPIO	PD7	35	GPIO
PD8	36	GPIO	PC6	37	GPIO
PC7	38	GPIO	DVDD	39	Digital power supply.
DECOUPLE	40	Decouple output for on-chip voltage regulator. An external decoupling capacitor is required at this pin.	PC8	41	GPIO
PC9	42	GPIO	PC10	43	GPIO (5V)
PC11	44	GPIO (5V)	PC12	45	GPIO (5V)
PC13	46	GPIO (5V)	PC14	47	GPIO (5V)
PC15	48	GPIO (5V)	PF0	49	GPIO (5V)
PF1	50	GPIO (5V)	PF2	51	GPIO
PF3	52	GPIO	PF4	53	GPIO
PF5	54	GPIO	PE8	57	GPIO
PE9	58	GPIO	PE10	59	GPIO
PE11	60	GPIO	PE12	61	GPIO
PE13	62	GPIO	PE14	63	GPIO
PE15	64	GPIO			

Note:

1. GPIO with 5V tolerance are indicated by (5V).

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
PB4	10	GPIO	PB5	11	GPIO
PB6	12	GPIO	PC4	13	GPIO
PC5	14	GPIO	PB7	15	GPIO
PB8	16	GPIO	PA8	17	GPIO
PA12	18	GPIO	PA13	19	GPIO (5V)
PA14	20	GPIO	RESETn	21	Reset input, active low. To apply an external reset source to this pin, it is required to only drive this pin low during reset, and let the internal pull-up ensure that reset is released.
PB11	22	GPIO	PB12	23	GPIO
AVDD	24 28	Analog power supply.	PB13	25	GPIO
PB14	26	GPIO	PD0	29	GPIO (5V)
PD1	30	GPIO	PD3	31	GPIO
PD4	32	GPIO	PD5	33	GPIO
PD6	34	GPIO	PD7	35	GPIO
PD8	36	GPIO	PC7	37	GPIO
VREGSW	39	DCDC regulator switching node	VREGVDD	40	Voltage regulator VDD input
DVDD	41	Digital power supply.	DECOUPLE	42	Decouple output for on-chip voltage regulator. An external decoupling capacitor is required at this pin.
PE4	43	GPIO	PE5	44	GPIO
PE6	45	GPIO	PE7	46	GPIO
PC12	47	GPIO (5V)	PC13	48	GPIO (5V)
PF0	49	GPIO (5V)	PF1	50	GPIO (5V)
PF2	51	GPIO	PF3	52	GPIO
PF4	53	GPIO	PF5	54	GPIO
PE8	56	GPIO	PE9	57	GPIO
PE10	58	GPIO	PE11	59	GPIO
PE12	60	GPIO	PE13	61	GPIO
PE14	62	GPIO	PE15	63	GPIO
PA15	64	GPIO			

Note:

1. GPIO with 5V tolerance are indicated by (5V).

5.7 EFM32TG11B3xx in QFN64 Device Pinout

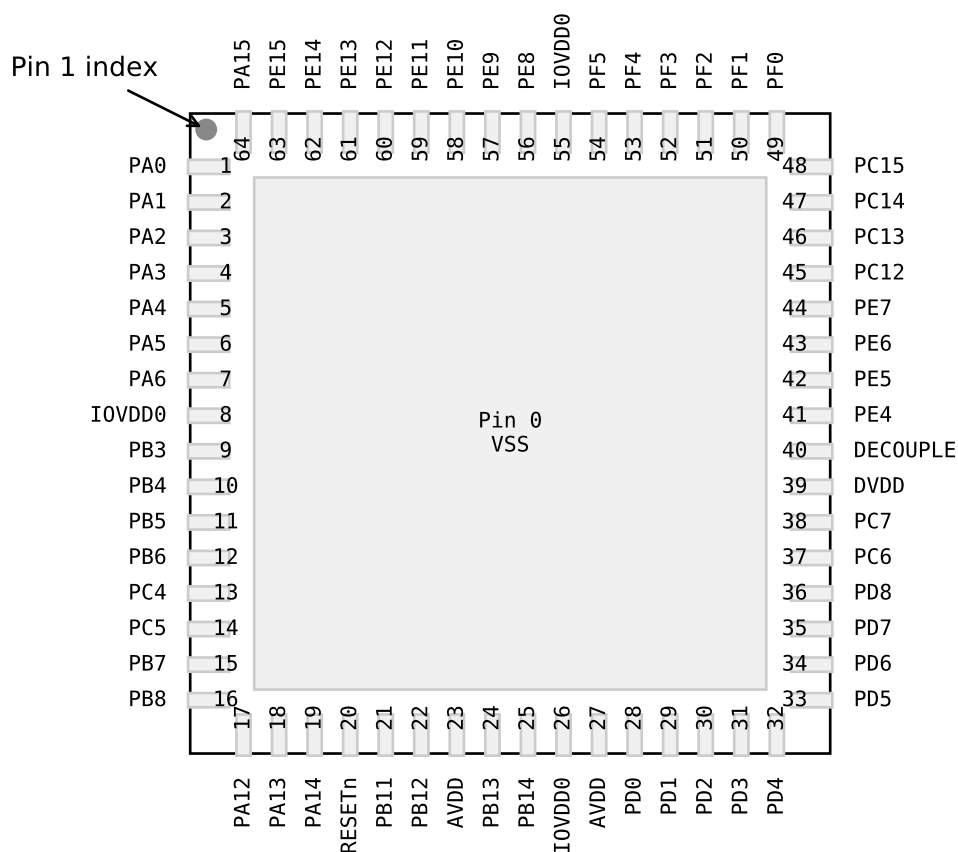


Figure 5.7. EFM32TG11B3xx in QFN64 Device Pinout

The following table provides package pin connections and general descriptions of pin functionality. For detailed information on the supported features for each GPIO pin, see [5.14 GPIO Functionality Table](#) or [5.15 Alternate Functionality Overview](#).

Table 5.7. EFM32TG11B3xx in QFN64 Device Pinout

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
VREGVSS	0	Voltage regulator VSS	PA0	1	GPIO
PA1	2	GPIO	PA2	3	GPIO
PA3	4	GPIO	PA4	5	GPIO
PA5	6	GPIO	PA6	7	GPIO
IOVDD0	8 26 55	Digital IO power supply 0.	PB3	9	GPIO
PB4	10	GPIO	PB5	11	GPIO

Alternate	LOCATION		
Functionality	0 - 3	4 - 7	Description
LES_CH4	0: PC4		LESENSE channel 4.
LES_CH5	0: PC5		LESENSE channel 5.
LES_CH6	0: PC6		LESENSE channel 6.
LES_CH7	0: PC7		LESENSE channel 7.
LES_CH8	0: PC8		LESENSE channel 8.
LES_CH9	0: PC9		LESENSE channel 9.
LES_CH10	0: PC10		LESENSE channel 10.
LES_CH11	0: PC11		LESENSE channel 11.
LES_CH12	0: PC12		LESENSE channel 12.
LES_CH13	0: PC13		LESENSE channel 13.
LES_CH14	0: PC14		LESENSE channel 14.
LES_CH15	0: PC15		LESENSE channel 15.
LETIM0_OUT0	0: PD6 1: PB11 2: PF0 3: PC4	4: PE12 5: PC14 6: PA8	Low Energy Timer LETIM0, output channel 0.

Alternate	LOCATION		
Functionality	0 - 3	4 - 7	Description
U0_TX	2: PA3 3: PC14	4: PC4 5: PF1 6: PD7	UART0 Transmit output. Also used as receive input in half duplex communication.
US0_CLK	0: PE12 1: PE5 2: PC9 3: PC15	4: PB13 5: PA12	USART0 clock input / output.
US0_CS	0: PE13 1: PE4 2: PC8 3: PC14	4: PB14 5: PA13	USART0 chip select input / output.
US0_CTS	0: PE14 2: PC7 3: PC13	4: PB6 5: PB11	USART0 Clear To Send hardware flow control input.
US0_RTS	0: PE15 2: PC6 3: PC12	4: PB5 5: PD6	USART0 Request To Send hardware flow control output.
US0_RX	0: PE11 1: PE6 2: PC10 3: PE12	4: PB8 5: PC1	USART0 Asynchronous Receive. USART0 Synchronous mode Master Input / Slave Output (MISO).
US0_TX	0: PE10 1: PE7 2: PC11 3: PE13	4: PB7 5: PC0	USART0 Asynchronous Transmit. Also used as receive input in half duplex communication. USART0 Synchronous mode Master Output / Slave Input (MOSI).
US1_CLK	0: PB7 1: PD2 2: PF0 3: PC15	4: PC3 5: PB11 6: PE5	USART1 clock input / output.
US1_CS	0: PB8 1: PD3 2: PF1 3: PC14	4: PC0 5: PE4	USART1 chip select input / output.
US1_CTS	1: PD4 2: PF3 3: PC6	4: PC12 5: PB13	USART1 Clear To Send hardware flow control input.
US1_RTS	1: PD5 2: PF4 3: PC7	4: PC13 5: PB14	USART1 Request To Send hardware flow control output.
US1_RX	0: PC1 1: PD1 2: PD6	4: PC2 5: PA0 6: PA2	USART1 Asynchronous Receive. USART1 Synchronous mode Master Input / Slave Output (MISO).
US1_TX	0: PC0 1: PD0 2: PD7	4: PC1 5: PF2 6: PA14	USART1 Asynchronous Transmit. Also used as receive input in half duplex communication. USART1 Synchronous mode Master Output / Slave Input (MOSI).

Alternate	LOCATION		
Functionality	0 - 3	4 - 7	Description
WTIM1_CC3	0: PD1 1: PD5 2: PC6	4: PE6	Wide timer 1 Capture Compare input / output channel 3.

Table 5.19. CSEN Bus and Pin Mapping

[illegible]

Port	Bus	CH31	CH30	CH29	CH28	CH27	CH26	CH25	CH24	CH23	CH22	CH21	CH20	CH19	CH18	CH17	CH16	CH15	CH14	CH13	CH12	CH11	CH10	CH9	CH8	CH7	CH6	CH5	CH4	CH3	CH2	CH1	CH0
OPA2_OUT																																	
APORT1Y	APORT2Y	APORT3Y	APORT4Y	BUSDY	BUSCY	BUSBY	BUSAY																										
												</																					