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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

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Details

Product Status	Discontinued at Digi-Key
Core Processor	ARM® Cortex®-M0+
Core Size	32-Bit Single-Core
Speed	48MHz
Connectivity	CANbus, I ² C, IrDA, LINbus, SmartCard, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, I ² S, LCD, POR, PWM, WDT
Number of I/O	53
Program Memory Size	128KB (128K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	32K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.8V
Data Converters	A/D 12bit SAR; D/A 12bit
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	64-TQFP
Supplier Device Package	64-TQFP (10x10)
Purchase URL	https://www.e-xfl.com/product-detail/silicon-labs/efm32tg11b320f128gq64-a

Ordering Code	Flash (kB)	RAM (kB)	DC-DC Converter	LCD	GPIO	Package	Temp Range
EFM32TG11B320F128GQ48-A	128	32	No	Yes	37	QFP48	-40 to +85°C
EFM32TG11B320F128IQ48-A	128	32	No	Yes	37	QFP48	-40 to +125°C
EFM32TG11B340F64GQ48-A	64	32	No	Yes	37	QFP48	-40 to +85°C
EFM32TG11B340F64IQ48-A	64	32	No	Yes	37	QFP48	-40 to +125°C
EFM32TG11B120F128GM64-A	128	32	No	No	56	QFN64	-40 to +85°C
EFM32TG11B120F128GQ64-A	128	32	No	No	53	QFP64	-40 to +85°C
EFM32TG11B120F128IM64-A	128	32	No	No	56	QFN64	-40 to +125°C
EFM32TG11B120F128IQ64-A	128	32	No	No	53	QFP64	-40 to +125°C
EFM32TG11B140F64GM64-A	64	32	No	No	56	QFN64	-40 to +85°C
EFM32TG11B140F64GQ64-A	64	32	No	No	53	QFP64	-40 to +85°C
EFM32TG11B140F64IM64-A	64	32	No	No	56	QFN64	-40 to +125°C
EFM32TG11B140F64IQ64-A	64	32	No	No	53	QFP64	-40 to +125°C
EFM32TG11B120F128GQ48-A	128	32	No	No	37	QFP48	-40 to +85°C
EFM32TG11B120F128IQ48-A	128	32	No	No	37	QFP48	-40 to +125°C
EFM32TG11B140F64GQ48-A	64	32	No	No	37	QFP48	-40 to +85°C
EFM32TG11B140F64IQ48-A	64	32	No	No	37	QFP48	-40 to +125°C
EFM32TG11B120F128GM32-A	128	32	No	No	24	QFN32	-40 to +85°C
EFM32TG11B120F128IM32-A	128	32	No	No	24	QFN32	-40 to +125°C
EFM32TG11B140F64GM32-A	64	32	No	No	24	QFN32	-40 to +85°C
EFM32TG11B140F64IM32-A	64	32	No	No	24	QFN32	-40 to +125°C

4.1.8 Brown Out Detector (BOD)

Table 4.10. Brown Out Detector (BOD)

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
DVDD BOD threshold	V _{DVddbOD}	DVDD rising	—	—	TBD	V
		DVDD falling (EM0/EM1)	TBD	—	—	V
		DVDD falling (EM2/EM3)	TBD	—	—	V
DVDD BOD hysteresis	V _{DVddbOD_HYST}		—	18	—	mV
DVDD BOD response time	t _{DVddbOD_DELAY}	Supply drops at 0.1V/μs rate	—	2.4	—	μs
AVDD BOD threshold	V _{AVddbOD}	AVDD rising	—	—	TBD	V
		AVDD falling (EM0/EM1)	TBD	—	—	V
		AVDD falling (EM2/EM3)	TBD	—	—	V
AVDD BOD hysteresis	V _{AVddbOD_HYST}		—	20	—	mV
AVDD BOD response time	t _{AVddbOD_DELAY}	Supply drops at 0.1V/μs rate	—	2.4	—	μs
EM4 BOD threshold	V _{EM4dBOD}	AVDD rising	—	—	TBD	V
		AVDD falling	TBD	—	—	V
EM4 BOD hysteresis	V _{EM4BOD_HYST}		—	25	—	mV
EM4 BOD response time	t _{EM4BOD_DELAY}	Supply drops at 0.1V/μs rate	—	300	—	μs

4.1.9.2 High-Frequency Crystal Oscillator (HFXO)

Table 4.12. High-Frequency Crystal Oscillator (HFXO)

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Crystal frequency	f_{HFXO}		4	—	48	MHz
Supported crystal equivalent series resistance (ESR)	ESR_{HFXO}	48 MHz crystal	—	—	50	Ω
		24 MHz crystal	—	—	150	Ω
		4 MHz crystal	—	—	180	Ω
Supported range of crystal load capacitance ¹	$C_{\text{HFXO_CL}}$		TBD	—	TBD	pF
Nominal on-chip tuning cap range ²	$C_{\text{HFXO_T}}$	On each of HFXTAL_N and HFXTAL_P pins	8.7	—	51.7	pF
On-chip tuning capacitance step	SS_{HFXO}		—	0.08	—	pF
Startup time	t_{HFXO}	48 MHz crystal, ESR = 50 Ohm, $C_L = 8$ pF	—	350	—	μs
		24 MHz crystal, ESR = 150 Ohm, $C_L = 6$ pF	—	700	—	μs
		4 MHz crystal, ESR = 180 Ohm, $C_L = 18$ pF	—	3	—	ms
Current consumption after startup	I_{HFXO}	48 MHz crystal	—	880	—	μA
		24 MHz crystal	—	420	—	μA
		4 MHz crystal	—	80	—	μA

Note:

1. Total load capacitance as seen by the crystal.
2. The effective load capacitance seen by the crystal will be $C_{\text{HFXO_T}}/2$. This is because each XTAL pin has a tuning cap and the two caps will be seen in series by the crystal.

4.1.9.3 Low-Frequency RC Oscillator (LFRCO)

Table 4.13. Low-Frequency RC Oscillator (LFRCO)

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Oscillation frequency	f _{LFRCO}	ENVREF ² = 1	TBD	32.768	TBD	kHz
		ENVREF ² = 1, T > 85 °C	TBD	32.768	TBD	kHz
		ENVREF ² = 0	TBD	32.768	TBD	kHz
Startup time	t _{LFRCO}		—	500	—	μs
Current consumption ¹	I _{LFRCO}	ENVREF = 1 in CMU_LFRCOCTRL	—	370	—	nA
		ENVREF = 0 in CMU_LFRCOCTRL	—	520	—	nA

Note:
1. Block is supplied by AVDD if ANASW = 0, or DVDD if ANASW=1 in EMU_PWRCTRL register.
2. In CMU_LFRCOCTRL register.

4.1.12 Voltage Monitor (VMON)

Table 4.19. Voltage Monitor (VMON)

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Supply current (including I _{SENSE})	I _{VMON}	In EM0 or EM1, 1 supply monitored, T ≤ 85 °C	—	6.3	TBD	μA
		In EM0 or EM1, 4 supplies monitored, T ≤ 85 °C	—	12.5	TBD	μA
		In EM2, EM3 or EM4, 1 supply monitored and above threshold	—	62	—	nA
		In EM2, EM3 or EM4, 1 supply monitored and below threshold	—	62	—	nA
		In EM2, EM3 or EM4, 4 supplies monitored and all above threshold	—	99	—	nA
		In EM2, EM3 or EM4, 4 supplies monitored and all below threshold	—	99	—	nA
Loading of monitored supply	I _{SENSE}	In EM0 or EM1	—	2	—	μA
		In EM2, EM3 or EM4	—	2	—	nA
Threshold range	V _{VMON_RANGE}		1.62	—	3.4	V
Threshold step size	N _{VMON_STESP}	Coarse	—	200	—	mV
		Fine	—	20	—	mV
Response time	t _{VMON_RES}	Supply drops at 1V/μs rate	—	460	—	ns
Hysteresis	V _{VMON_HYST}		—	26	—	mV

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Note: 1. Supply current specifications are for VDAC circuitry operating with static output only and do not include current required to drive the load. 2. In differential mode, the output is defined as the difference between two single-ended outputs. Absolute voltage on each output is limited to the single-ended range. 3. Entire range is monotonic and has no missing codes. 4. Current from HUPERCLK is dependent on HUPERCLK frequency. This current contributes to the total supply current used when the clock to the DAC module is enabled in the CMU. 5. Gain is calculated by measuring the slope from 10% to 90% of full scale. Offset is calculated by comparing actual VDAC output at 10% of full scale to ideal VDAC output at 10% of full scale with the measured gain. 6. PSRR calculated as $20 * \log_{10}(\Delta V_{DD} / \Delta V_{OUT})$, VDAC output at 90% of full scale						

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Open-loop gain	G _{OL}	DRIVESTRENGTH = 3	—	135	—	dB
		DRIVESTRENGTH = 2	—	137	—	dB
		DRIVESTRENGTH = 1	—	121	—	dB
		DRIVESTRENGTH = 0	—	109	—	dB
Loop unit-gain frequency ⁷	UGF	DRIVESTRENGTH = 3, Buffer connection	—	3.38	—	MHz
		DRIVESTRENGTH = 2, Buffer connection	—	0.9	—	MHz
		DRIVESTRENGTH = 1, Buffer connection	—	132	—	kHz
		DRIVESTRENGTH = 0, Buffer connection	—	34	—	kHz
		DRIVESTRENGTH = 3, 3x Gain connection	—	2.57	—	MHz
		DRIVESTRENGTH = 2, 3x Gain connection	—	0.71	—	MHz
		DRIVESTRENGTH = 1, 3x Gain connection	—	113	—	kHz
		DRIVESTRENGTH = 0, 3x Gain connection	—	28	—	kHz
Phase margin	PM	DRIVESTRENGTH = 3, Buffer connection	—	67	—	°
		DRIVESTRENGTH = 2, Buffer connection	—	69	—	°
		DRIVESTRENGTH = 1, Buffer connection	—	63	—	°
		DRIVESTRENGTH = 0, Buffer connection	—	68	—	°
Output voltage noise	N _{OUT}	DRIVESTRENGTH = 3, Buffer connection, 10 Hz - 10 MHz	—	146	—	μVrms
		DRIVESTRENGTH = 2, Buffer connection, 10 Hz - 10 MHz	—	163	—	μVrms
		DRIVESTRENGTH = 1, Buffer connection, 10 Hz - 1 MHz	—	170	—	μVrms
		DRIVESTRENGTH = 0, Buffer connection, 10 Hz - 1 MHz	—	176	—	μVrms
		DRIVESTRENGTH = 3, 3x Gain connection, 10 Hz - 10 MHz	—	313	—	μVrms
		DRIVESTRENGTH = 2, 3x Gain connection, 10 Hz - 10 MHz	—	271	—	μVrms
		DRIVESTRENGTH = 1, 3x Gain connection, 10 Hz - 1 MHz	—	247	—	μVrms
		DRIVESTRENGTH = 0, 3x Gain connection, 10 Hz - 1 MHz	—	245	—	μVrms

4.1.21 I2C

4.1.21.1 I2C Standard-mode (Sm)¹

Table 4.28. I2C Standard-mode (Sm)¹

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
SCL clock frequency ²	f_{SCL}		0	—	100	kHz
SCL clock low time	t_{LOW}		4.7	—	—	μs
SCL clock high time	t_{HIGH}		4	—	—	μs
SDA set-up time	t_{SU_DAT}		250	—	—	ns
SDA hold time ³	t_{HD_DAT}		100	—	3450	ns
Repeated START condition set-up time	t_{SU_STA}		4.7	—	—	μs
(Repeated) START condition hold time	t_{HD_STA}		4	—	—	μs
STOP condition set-up time	t_{SU_STO}		4	—	—	μs
Bus free time between a STOP and START condition	t_{BUF}		4.7	—	—	μs

Note:

1. For CLHR set to 0 in the I2Cn_CTRL register.
2. For the minimum HPERCLK frequency required in Standard-mode, refer to the I2C chapter in the reference manual.
3. The maximum SDA hold time (t_{HD_DAT}) needs to be met only when the device does not stretch the low time of SCL (t_{LOW}).

SPI Slave Timing

Table 4.32. SPI Slave Timing

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
SCLK period ^{1 3 2}	t_{SCLK}		6 * t_{HFERCLK}	—	—	ns
SCLK high time ^{1 3 2}	$t_{\text{SCLK_HI}}$		2.5 * t_{HFERCLK}	—	—	ns
SCLK low time ^{1 3 2}	$t_{\text{SCLK_LO}}$		2.5 * t_{HFERCLK}	—	—	ns
CS active to MISO ^{1 3}	$t_{\text{CS_ACT_MI}}$		20	—	70	ns
CS disable to MISO ^{1 3}	$t_{\text{CS_DIS_MI}}$		15	—	150	ns
MOSI setup time ^{1 3}	$t_{\text{SU_MO}}$		4	—	—	ns
MOSI hold time ^{1 3 2}	$t_{\text{H_MO}}$		7	—	—	ns
SCLK to MISO ^{1 3 2}	$t_{\text{SCLK_MI}}$		14 + 1.5 * t_{HFERCLK}	—	40 + 2.5 * t_{HFERCLK}	ns

Note:

1. Applies for both CLKPHA = 0 and CLKPHA = 1 (figure only shows CLKPHA = 0).
2. t_{HFERCLK} is one period of the selected HFERCLK.
3. Measurement done with 8 pF output loading at 10% and 90% of V_{DD} (figure shows 50% of V_{DD}).

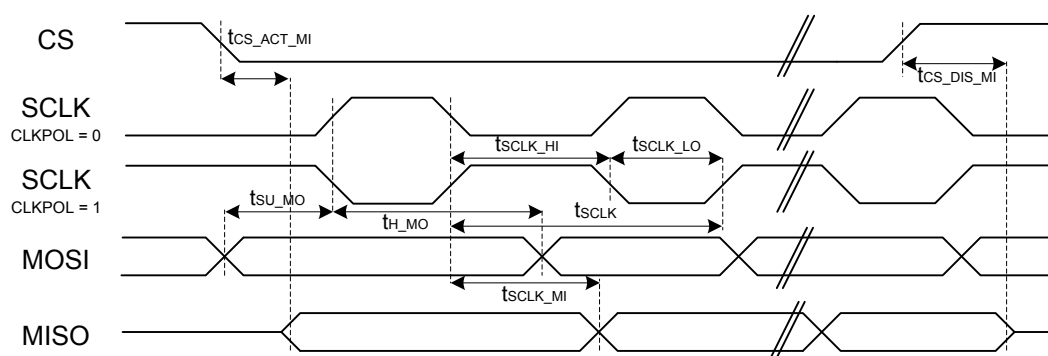


Figure 4.2. SPI Slave Timing Diagram

4.2 Typical Performance Curves

Typical performance curves indicate typical characterized performance under the stated conditions.

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
PC4	13	GPIO	PC5	14	GPIO
PB7	15	GPIO	PB8	16	GPIO
PA8	17	GPIO	PA12	18	GPIO
PA14	19	GPIO	RESETn	20	Reset input, active low. To apply an external reset source to this pin, it is required to only drive this pin low during reset, and let the internal pull-up ensure that reset is released.
PB11	21	GPIO	PB12	22	GPIO
AVDD	24 28	Analog power supply.	PB13	25	GPIO
PB14	26	GPIO	PD0	29	GPIO (5V)
PD1	30	GPIO	PD3	31	GPIO
PD4	32	GPIO	PD5	33	GPIO
PD6	34	GPIO	PD7	35	GPIO
PD8	36	GPIO	PC7	37	GPIO
VREGVSS	38	Voltage regulator VSS	VREGSW	39	DCDC regulator switching node
VREGVDD	40	Voltage regulator VDD input	DVDD	41	Digital power supply.
DECOUPLE	42	Decouple output for on-chip voltage regulator. An external decoupling capacitor is required at this pin.	PE4	43	GPIO
PE5	44	GPIO	PE6	45	GPIO
PE7	46	GPIO	PC12	47	GPIO (5V)
PC13	48	GPIO (5V)	PF0	49	GPIO (5V)
PF1	50	GPIO (5V)	PF2	51	GPIO
PF3	52	GPIO	PF4	53	GPIO
PF5	54	GPIO	PE8	57	GPIO
PE9	58	GPIO	PE10	59	GPIO
PE11	60	GPIO	PE12	61	GPIO
PE13	62	GPIO	PE14	63	GPIO
PE15	64	GPIO			

Note:

1. GPIO with 5V tolerance are indicated by (5V).

GPIO Name	Pin Alternate Functionality / Description			
	Analog	Timers	Communication	Other
PC4	BUSACMP0Y BU-SACMP0X OPA0_P LCD_SEG24	TIM0_CC0 #5 TIM0_CDTI2 #3 LE-TIM0_OUT0 #3	US2_CLK #0 U0_TX #4 I2C1_SDA #0	LES_CH4 GPIO_EM4WU6
PC5	BUSACMP0Y BU-SACMP0X OPA0_N LCD_SEG25	TIM0_CC1 #5 LE-TIM0_OUT1 #3	US2_CS #0 U0_RX #4 I2C1_SCL #0	LES_CH5
PB7	LFXTAL_P	TIM0_CDTI0 #4 TIM1_CC0 #3	US0_TX #4 US1_CLK #0 US3_RX #2 U0_CTS #4	
PB8	LFXTAL_N	TIM0_CDTI1 #4 TIM1_CC1 #3	US0_RX #4 US1_CS #0 U0_RTS #4	CMU_CLKI0 #2
PA8	BU_STAT	TIM0_CC0 #6 LE-TIM0_OUT0 #6	US2_RX #2	
PA9	BUSAY BUSBX LCD_SEG26	TIM0_CC1 #6 LE-TIM0_OUT1 #6	US2_CLK #2	
PA10	BUSBY BUSAX LCD_SEG27	TIM0_CC2 #6	US2_CS #2	
PA12	BU_VOUT	WTIM0_CDTI0 #2	US0_CLK #5 US2_RTS #2	CMU_CLK0 #5 ACMP1_O #3
PA13	BUSAY BUSBX	TIM0_CC2 #7 WTIM0_CDTI1 #2	US0_CS #5 US2_TX #3	
PA14	BUSBY BUSAX LCD_BEXT	WTIM0_CDTI2 #2	US1_TX #6 US2_RX #3 US3_RTS #2	ACMP1_O #4
PB11	BUSAY BUSBX VDAC0_OUT0 / OPA0_OUT LCD_SEG28	TIM0_CDTI2 #4 TIM1_CC2 #3 LE-TIM0_OUT0 #1 PCNT0_S1IN #7	US0_CTS #5 US1_CLK #5 US2_CS #3 I2C1_SDA #1	CMU_CLK1 #5 CMU_CLKI0 #7 ACMP0_O #3 GPIO_EM4WU7
PB12	BUSBY BUSAX VDAC0_OUT1 / OPA1_OUT LCD_SEG29	TIM1_CC3 #3 LE-TIM0_OUT1 #1 PCNT0_S0IN #7	US2_CTS #1 I2C1_SCL #1	
PB13	BUSAY BUSBX HFXTAL_P	WTIM1_CC0 #0	US0_CLK #4 US1_CTS #5 LEU0_TX #1	CMU_CLKI0 #3 PRS_CH7 #0
PB14	BUSBY BUSAX HFXTAL_N	WTIM1_CC1 #0	US0_CS #4 US1_RTS #5 LEU0_RX #1	PRS_CH6 #1
PD0	VDAC0_OUT0ALT / OPA0_OUTALT #4 OPA2_OUTALT BU-SADC0Y BUSADC0X	WTIM1_CC2 #0	CAN0_RX #2 US1_TX #1	
PD1	VDAC0_OUT1ALT / OPA1_OUTALT #4 BU-SADC0Y BUSADC0X OPA3_OUT	TIM0_CC0 #2 WTIM1_CC3 #0	CAN0_TX #2 US1_RX #1	
PD2	BUSADC0Y BUSADC0X	TIM0_CC1 #2 WTIM1_CC0 #1	US1_CLK #1	
PD3	BUSADC0Y BUSADC0X OPA2_N LCD_SEG30	TIM0_CC2 #2 WTIM1_CC1 #1	US1_CS #1	
PD4	BUSADC0Y BUSADC0X OPA2_P LCD_SEG31	WTIM0_CDTI0 #4 WTIM1_CC2 #1	US1_CTS #1 US3_CLK #2 LEU0_TX #0 I2C1_SDA #3	CMU_CLKI0 #0

Alternate	LOCATION		
Functionality	0 - 3	4 - 7	Description
LCD_SEG35	0: PC9		LCD segment line 35.
LES_ALTEX0	0: PD6		LESENSE alternate excite output 0.
LES_ALTEX1	0: PD7		LESENSE alternate excite output 1.
LES_ALTEX2	0: PA3		LESENSE alternate excite output 2.
LES_ALTEX3	0: PA4		LESENSE alternate excite output 3.
LES_ALTEX4	0: PA5		LESENSE alternate excite output 4.
LES_ALTEX5	0: PE11		LESENSE alternate excite output 5.
LES_ALTEX6	0: PE12		LESENSE alternate excite output 6.
LES_ALTEX7	0: PE13		LESENSE alternate excite output 7.
LES_CH0	0: PC0		LESENSE channel 0.
LES_CH1	0: PC1		LESENSE channel 1.
LES_CH2	0: PC2		LESENSE channel 2.
LES_CH3	0: PC3		LESENSE channel 3.

Alternate	LOCATION		
Functionality	0 - 3	4 - 7	Description
LES_CH4	0: PC4		LESENSE channel 4.
LES_CH5	0: PC5		LESENSE channel 5.
LES_CH6	0: PC6		LESENSE channel 6.
LES_CH7	0: PC7		LESENSE channel 7.
LES_CH8	0: PC8		LESENSE channel 8.
LES_CH9	0: PC9		LESENSE channel 9.
LES_CH10	0: PC10		LESENSE channel 10.
LES_CH11	0: PC11		LESENSE channel 11.
LES_CH12	0: PC12		LESENSE channel 12.
LES_CH13	0: PC13		LESENSE channel 13.
LES_CH14	0: PC14		LESENSE channel 14.
LES_CH15	0: PC15		LESENSE channel 15.
LETIM0_OUT0	0: PD6 1: PB11 2: PF0 3: PC4	4: PE12 5: PC14 6: PA8	Low Energy Timer LETIM0, output channel 0.

Alternate	LOCATION		
Functionality	0 - 3	4 - 7	Description
US2_CLK	0: PC4 1: PB5 2: PA9 3: PA15	5: PF2	USART2 clock input / output.
US2_CS	0: PC5 1: PB6 2: PA10 3: PB11	5: PF5	USART2 chip select input / output.
US2_CTS	0: PC1 1: PB12	4: PC12 5: PD6	USART2 Clear To Send hardware flow control input.
US2_RTS	0: PC0 2: PA12 3: PC14	4: PC13 5: PD8	USART2 Request To Send hardware flow control output.
US2_RX	0: PC3 1: PB4 2: PA8 3: PA14	5: PF1	USART2 Asynchronous Receive. USART2 Synchronous mode Master Input / Slave Output (MISO).
US2_TX	0: PC2 1: PB3 3: PA13	5: PF0	USART2 Asynchronous Transmit. Also used as receive input in half duplex communication. USART2 Synchronous mode Master Output / Slave Input (MOSI).
US3_CLK	0: PA2 1: PD7 2: PD4		USART3 clock input / output.
US3_CS	0: PA3 1: PE4 2: PC14 3: PC0		USART3 chip select input / output.
US3_CTS	0: PA4 1: PE5 2: PD6		USART3 Clear To Send hardware flow control input.
US3_RTS	0: PA5 1: PC1 2: PA14 3: PC15		USART3 Request To Send hardware flow control output.
US3_RX	0: PA1 1: PE7 2: PB7		USART3 Asynchronous Receive. USART3 Synchronous mode Master Input / Slave Output (MISO).
US3_TX	0: PA0 1: PE6 2: PB3		USART3 Asynchronous Transmit. Also used as receive input in half duplex communication. USART3 Synchronous mode Master Output / Slave Input (MOSI).
VDAC0_EXT	0: PD6		Digital to analog converter VDAC0 external reference input pin.

Port	Bus	CH31	CH30	CH29	CH28	CH27	CH26	CH25	CH24	CH23	CH22	CH21	CH20	CH19	CH18	CH17	CH16	CH15	CH14	CH13	CH12	CH11	CH10	CH9	CH8	CH7	CH6	CH5	CH4	CH3	CH2	CH1	CH0
OPA3_OUT																																	
APORT1Y	APORT2Y	APORT3Y	APORT4Y	BUSDY	BUSCY	BUSBY	BUSAY																										
							</																										

APORT4Y	APORT3Y	APORT2Y	APORT1Y
BUSDY	BUSCY	BUSBY	BUSAY
		PB14	
			PB13
		PB12	
			PB11
		PB6	
	PF5		PB5
PF4		PB4	
	PF3		PB3
PF2			
	PF1		
PF0			
	PE15		PA15
PE14		PA14	
	PE13		PA13
PE12			
	PE11		
PE10		PA10	
	PE9		PA9
PE8			
	PE7		
PE6		PA6	
	PE5		PA5
PE4		PA4	
			PA3
		PA2	
			PA1
		PA0	

7.2 QFN80 PCB Land Pattern

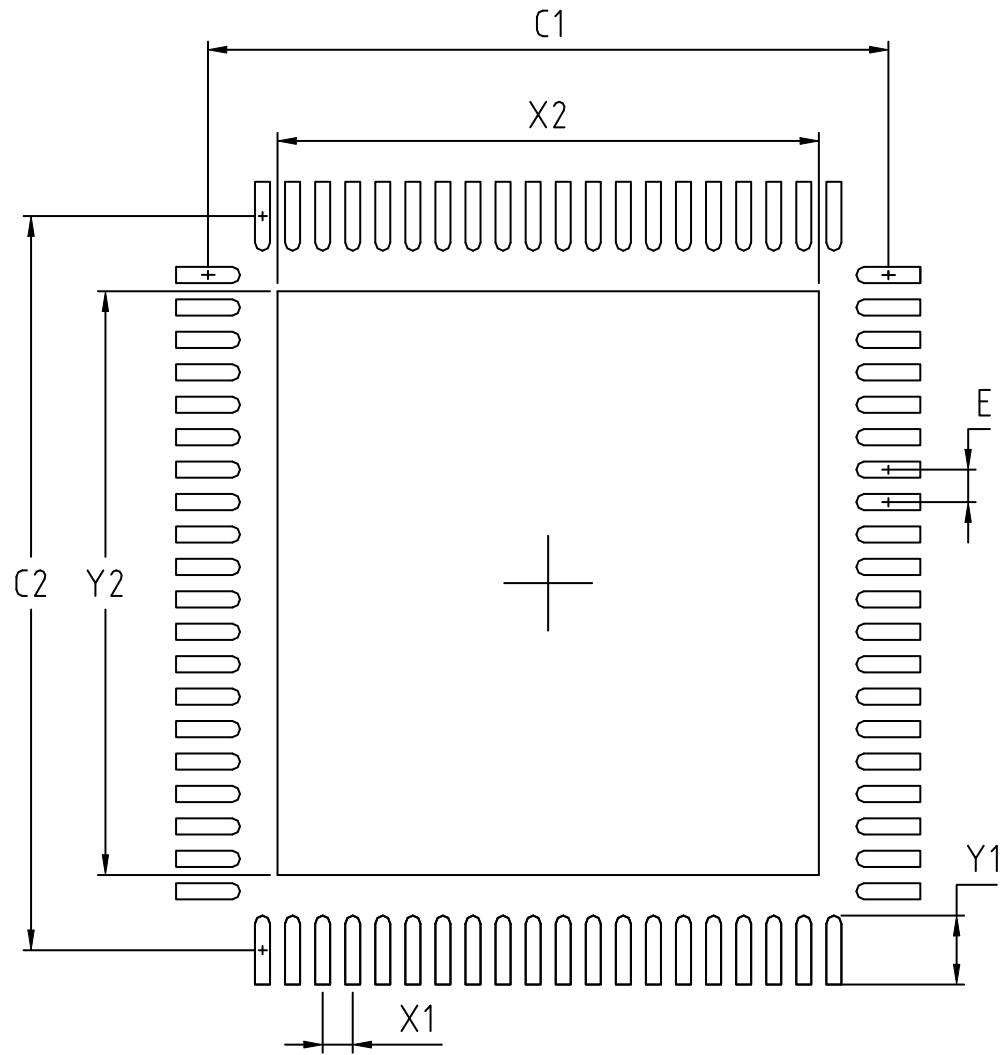


Figure 7.2. QFN80 PCB Land Pattern Drawing

Table 9.1. QFN64 Package Dimensions

Dimension	Min	Typ	Max
A	0.70	0.75	0.80
A1	0.00	—	0.05
b	0.20	0.25	0.30
A3	0.203 REF		
D	9.00 BSC		
e	0.50 BSC		
E	9.00 BSC		
D2	7.10	7.20	7.30
E2	7.10	7.20	7.30
L	0.40	0.45	0.50
L1	0.00	—	0.10
aaa	0.10		
bbb	0.10		
ccc	0.10		
ddd	0.05		
eee	0.08		

Note:

1. All dimensions shown are in millimeters (mm) unless otherwise noted.
2. Dimensioning and Tolerancing per ANSI Y14.5M-1994.
3. Recommended card reflow profile is per the JEDEC/IPC J-STD-020 specification for Small Body Components.

Table 11.1. QFN32 Package Dimensions

Dimension	Min	Typ	Max
A	0.70	0.75	0.80
A1	0.00	—	0.05
A3	0.203 REF		
b	0.20	0.25	0.30
D	5.0 BSC		
D2/E2	3.60	3.70	3.80
E	5.0 BSC		
e	0.50 BSC		
L	0.35	0.40	0.45
aaa	0.10		
bbb	0.10		
ccc	0.10		
ddd	0.05		
eee	0.08		

Note:

1. All dimensions shown are in millimeters (mm) unless otherwise noted.
2. Dimensioning and Tolerancing per ANSI Y14.5M-1994.
3. This drawing conforms to the JEDEC Solid State Outline MO-220, Variation VKKD-4.
4. Recommended card reflow profile is per the JEDEC/IPC J-STD-020 specification for Small Body Components.

11.2 QFN32 PCB Land Pattern

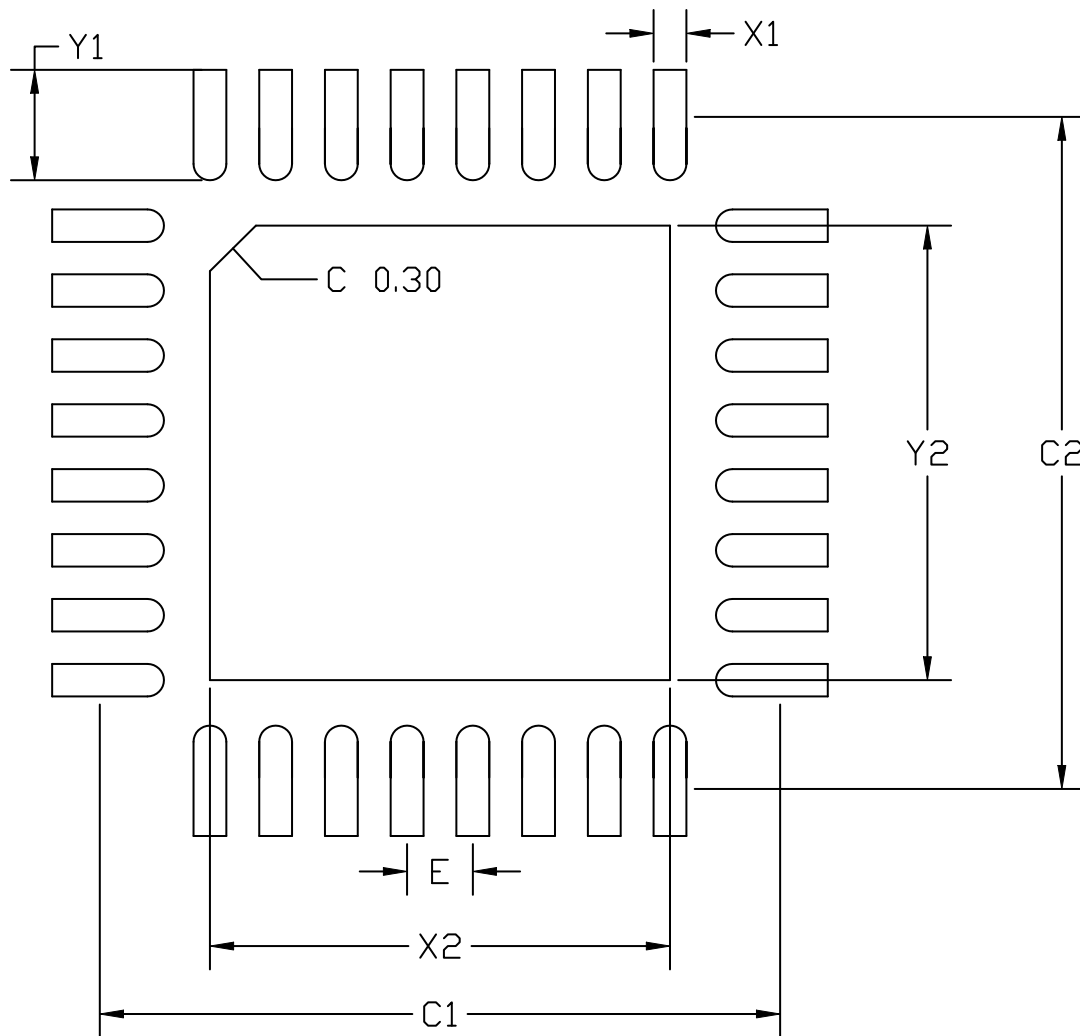


Figure 11.2. QFN32 PCB Land Pattern Drawing