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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

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Details

Product Status	Discontinued at Digi-Key
Core Processor	ARM® Cortex®-M0+
Core Size	32-Bit Single-Core
Speed	48MHz
Connectivity	CANbus, I ² C, IrDA, LINbus, SmartCard, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, I ² S, LCD, POR, PWM, WDT
Number of I/O	63
Program Memory Size	128KB (128K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	32K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.8V
Data Converters	A/D 12bit SAR; D/A 12bit
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	80-TQFP
Supplier Device Package	80-TQFP (12x12)
Purchase URL	https://www.e-xfl.com/product-detail/silicon-labs/efm32tg11b520f128gq80-ar

- **Timers/Counters**
 - 2 × 16-bit Timer/Counter
 - 3 or 4 Compare/Capture/PWM channels (4 + 4 on one timer instance)
 - Dead-Time Insertion on one timer instance
 - 2 × 32-bit Timer/Counter
 - 32-bit Real Time Counter and Calendar (RTCC)
 - 32-bit Ultra Low Energy CRYOTIMER for periodic wakeup from any Energy Mode
 - 16-bit Low Energy Timer for waveform generation
 - 16-bit Pulse Counter with asynchronous operation
 - Watchdog Timer with dedicated RC oscillator
- **Low Energy Sensor Interface (LESENSE)**
 - Autonomous sensor monitoring in Deep Sleep Mode
 - Wide range of sensors supported, including LC sensors and capacitive buttons
 - Up to 16 inputs
- **Ultra efficient Power-on Reset and Brown-Out Detector**
- **Debug Interface**
 - 2-pin Serial Wire Debug interface
 - 4-pin JTAG interface
 - Micro Trace Buffer (MTB)
- **Pre-Programmed UART Bootloader**
- **Wide Operating Range**
 - 1.8 V to 3.8 V single power supply
 - Integrated DC-DC, down to 1.8 V output with up to 200 mA load current for system
 - Standard (-40 °C to 85 °C T_A) and Extended (-40 °C to 125 °C T_J) temperature grades available
- **Packages**
 - QFN32 (5x5 mm)
 - TQFP48 (7x7 mm)
 - QFN64 (9x9 mm)
 - TQFP64 (10x10 mm)
 - QFN80 (9x9 mm)
 - TQFP80 (12x12 mm)

3.2 Power

The EFM32TG11 has an Energy Management Unit (EMU) and efficient integrated regulators to generate internal supply voltages. Only a single external supply voltage is required, from which all internal voltages are created. An optional integrated DC-DC buck regulator can be utilized to further reduce the current consumption. The DC-DC regulator requires one external inductor and one external capacitor.

The EFM32TG11 device family includes support for internal supply voltage scaling, as well as two different power domain groups for peripherals. These enhancements allow for further supply current reductions and lower overall power consumption.

AVDD and VREGVDD need to be 1.8 V or higher for the MCU to operate across all conditions; however the rest of the system will operate down to 1.62 V, including the digital supply and I/O. This means that the device is fully compatible with 1.8 V components. Running from a sufficiently high supply, the device can use the DC-DC to regulate voltage not only for itself, but also for other PCB components, supplying up to a total of 200 mA.

3.2.1 Energy Management Unit (EMU)

The Energy Management Unit manages transitions of energy modes in the device. Each energy mode defines which peripherals and features are available and the amount of current the device consumes. The EMU can also be used to turn off the power to unused RAM blocks, and it contains control registers for the DC-DC regulator and the Voltage Monitor (VMON). The VMON is used to monitor multiple supply voltages. It has multiple channels which can be programmed individually by the user to determine if a sensed supply has fallen below a chosen threshold.

3.2.2 DC-DC Converter

The DC-DC buck converter covers a wide range of load currents and provides up to 90% efficiency in energy modes EM0, EM1, EM2 and EM3, and can supply up to 200 mA to the device and surrounding PCB components. Protection features include programmable current limiting, short-circuit protection, and dead-time protection. The DC-DC converter may also enter bypass mode when the input voltage is too low for efficient operation. In bypass mode, the DC-DC input supply is internally connected directly to its output through a low resistance switch. Bypass mode also supports in-rush current limiting to prevent input supply voltage droops due to excessive output current transients.

3.2.3 EM2 and EM3 Power Domains

The EFM32TG11 has three independent peripheral power domains for use in EM2 and EM3. Two of these domains are dynamic and can be shut down to save energy. Peripherals associated with the two dynamic power domains are listed in [Table 3.1 EM2 and EM3 Peripheral Power Subdomains on page 11](#). If all of the peripherals in a peripheral power domain are unused, the power domain for that group will be powered off in EM2 and EM3, reducing the overall current consumption of the device. Other EM2, EM3, and EM4-capable peripherals and functions not listed in the table below reside on the primary power domain, which is always on in EM2 and EM3.

Table 3.1. EM2 and EM3 Peripheral Power Subdomains

Peripheral Power Domain 1	Peripheral Power Domain 2
ACMP0	ACMP1
PCNT0	CSEN
ADC0	VDAC0
LETIMER0	LEUART0
LESENSE	I2C0
APORT	I2C1
-	IDAC
-	LCD

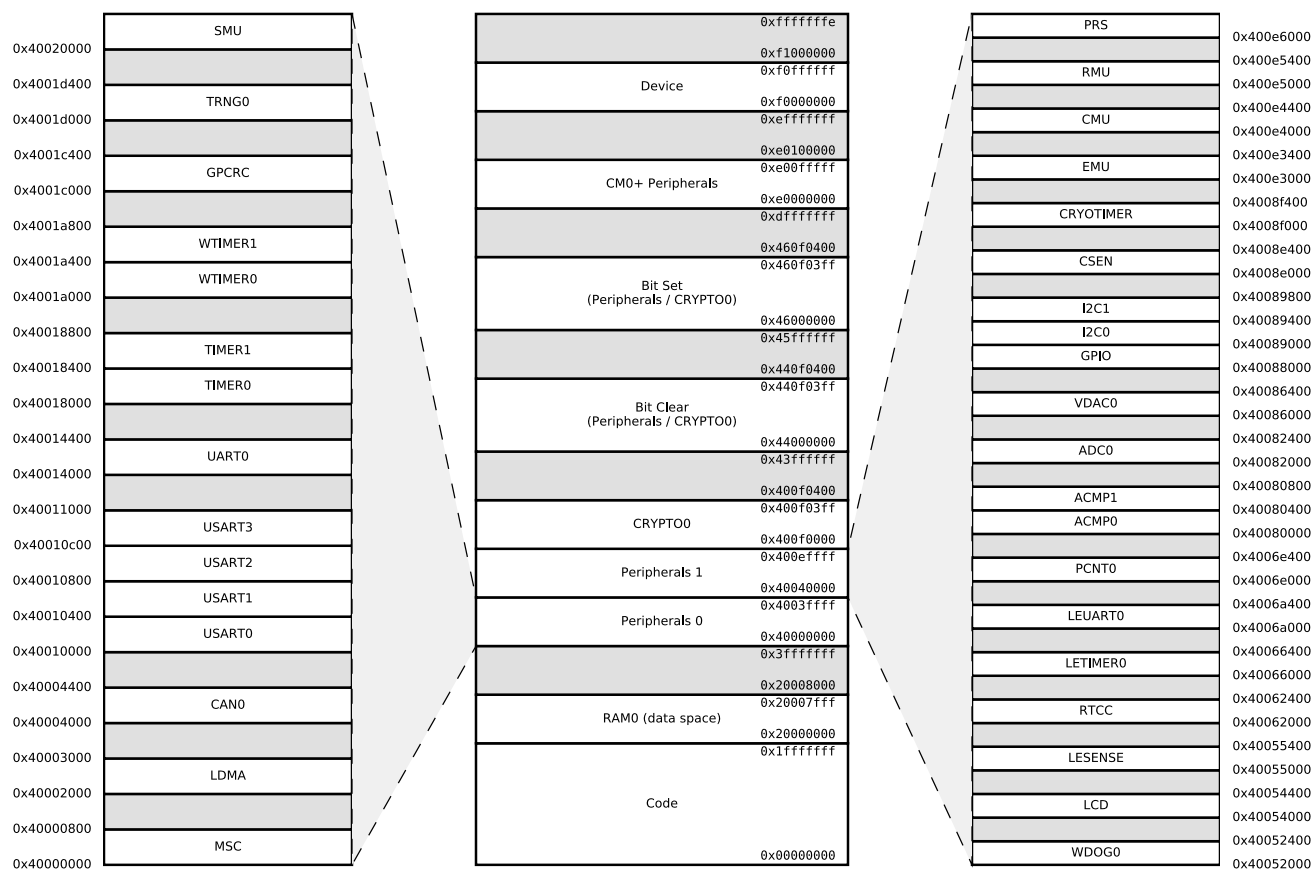


Figure 3.3. EFM32TG11 Memory Map — Peripherals

3.12 Configuration Summary

The features of the EFM32TG11 are a subset of the feature set described in the device reference manual. The table below describes device specific implementation of the features. Remaining modules support full configuration.

Table 3.2. Configuration Summary

Module	Configuration	Pin Connections
USART0	IrDA, SmartCard	US0_TX, US0_RX, US0_CLK, US0_CS
USART1	I ² S, SmartCard	US1_TX, US1_RX, US1_CLK, US1_CS
USART2	IrDA, SmartCard, High-Speed	US2_TX, US2_RX, US2_CLK, US2_CS
USART3	I ² S, SmartCard	US3_TX, US3_RX, US3_CLK, US3_CS
TIMER0	with DTI	TIM0_CC[2:0], TIM0_CDTI[2:0]
TIMER1	-	TIM1_CC[3:0]
WTIMER0	with DTI	WTIM0_CC[2:0], WTIM0_CDTI[2:0]
WTIMER1	-	WTIM1_CC[3:0]

4.1.4 DC-DC Converter

Test conditions: L_DCDC=4.7 μ H (Murata LQH3NPN4R7MM0L), C_DCDC=4.7 μ F (Samsung CL10B475KQ8NQNC), V_DCDC_I=3.3 V, V_DCDC_O=1.8 V, I_DCDC_LOAD=50 mA, Heavy Drive configuration, F_DCDC_LN=7 MHz, unless otherwise indicated.

Table 4.4. DC-DC Converter

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Input voltage range	V _{DCDC_I}	Bypass mode, I _{DCDC_LOAD} = 50 mA	1.8	—	V _{VREGVDD_MAX}	V
		Low noise (LN) mode, 1.8 V output, I _{DCDC_LOAD} = 100 mA, or Low power (LP) mode, 1.8 V output, I _{DCDC_LOAD} = 10 mA	2.4	—	V _{VREGVDD_MAX}	V
		Low noise (LN) mode, 1.8 V output, I _{DCDC_LOAD} = 200 mA	2.6	—	V _{VREGVDD_MAX}	V
Output voltage programmable range ¹	V _{DCDC_O}		1.8	—	V _{VREGVDD}	V
Regulation DC accuracy	ACC _{DC}	Low Noise (LN) mode, 1.8 V target output	TBD	—	TBD	V
Regulation window ⁴	WIN _{REG}	Low Power (LP) mode, LPCMPBIASEMxx ³ = 0, 1.8 V target output, I _{DCDC_LOAD} ≤ 75 μ A	TBD	—	TBD	V
		Low Power (LP) mode, LPCMPBIASEMxx ³ = 3, 1.8 V target output, I _{DCDC_LOAD} ≤ 10 mA	TBD	—	TBD	V
Steady-state output ripple	V _R		—	3	—	mVpp
Output voltage under/overshoot	V _{OV}	CCM Mode (LNFORCECCM ³ = 1), Load changes between 0 mA and 100 mA	—	25	TBD	mV
		DCM Mode (LNFORCECCM ³ = 0), Load changes between 0 mA and 10 mA	—	45	TBD	mV
		Overshoot during LP to LN CCM/DCM mode transitions compared to DC level in LN mode	—	200	—	mV
		Undershoot during BYP/LP to LN CCM (LNFORCECCM ³ = 1) mode transitions compared to DC level in LN mode	—	40	—	mV
		Undershoot during BYP/LP to LN DCM (LNFORCECCM ³ = 0) mode transitions compared to DC level in LN mode	—	100	—	mV
DC line regulation	V _{REG}	Input changes between V _{VREGVDD_MAX} and 2.4 V	—	0.1	—	%
DC load regulation	I _{REG}	Load changes between 0 mA and 100 mA in CCM mode	—	0.1	—	%

4.1.6 Current Consumption

4.1.6.1 Current Consumption 3.3 V without DC-DC Converter

Unless otherwise indicated, typical conditions are: VREGVDD = AVDD = DVDD = 3.3 V. T = 25 °C. DCDC is off. Minimum and maximum values in this table represent the worst conditions across supply voltage and process variation at T = 25 °C.

Table 4.6. Current Consumption 3.3 V without DC-DC Converter

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Current consumption in EM0 mode with all peripherals disabled	I _{ACTIVE}	48 MHz crystal, CPU running while loop from flash	—	45	—	μA/MHz
		48 MHz HFRCO, CPU running while loop from flash	—	44	TBD	μA/MHz
		48 MHz HFRCO, CPU running Prime from flash	—	57	—	μA/MHz
		48 MHz HFRCO, CPU running CoreMark loop from flash	—	71	—	μA/MHz
		32 MHz HFRCO, CPU running while loop from flash	—	45	—	μA/MHz
		26 MHz HFRCO, CPU running while loop from flash	—	46	TBD	μA/MHz
		16 MHz HFRCO, CPU running while loop from flash	—	50	—	μA/MHz
		1 MHz HFRCO, CPU running while loop from flash	—	161	TBD	μA/MHz
Current consumption in EM0 mode with all peripherals disabled and voltage scaling enabled	I _{ACTIVE_VS}	19 MHz HFRCO, CPU running while loop from flash	—	41	—	μA/MHz
		1 MHz HFRCO, CPU running while loop from flash	—	145	—	μA/MHz
Current consumption in EM1 mode with all peripherals disabled	I _{EM1}	48 MHz crystal	—	34	—	μA/MHz
		48 MHz HFRCO	—	33	TBD	μA/MHz
		32 MHz HFRCO	—	34	—	μA/MHz
		26 MHz HFRCO	—	35	TBD	μA/MHz
		16 MHz HFRCO	—	39	—	μA/MHz
		1 MHz HFRCO	—	150	TBD	μA/MHz
Current consumption in EM1 mode with all peripherals disabled and voltage scaling enabled	I _{EM1_VS}	19 MHz HFRCO	—	32	—	μA/MHz
		1 MHz HFRCO	—	136	—	μA/MHz
Current consumption in EM2 mode, with voltage scaling enabled	I _{EM2_VS}	Full 32 kB RAM retention and RTCC running from LFXO	—	1.48	—	μA
		Full 32 kB RAM retention and RTCC running from LFRCO	—	1.86	—	μA
		8 kB (1 bank) RAM retention and RTCC running from LFRCO ²	—	1.59	TBD	μA
Current consumption in EM3 mode, with voltage scaling enabled	I _{EM3_VS}	Full 32 kB RAM retention and CRYOTIMER running from ULFR-CO	—	1.23	TBD	μA

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Current consumption in EM4H mode, with voltage scaling enabled	I _{EM4H_VS}	128 byte RAM retention, RTCC running from LFXO	—	0.82	—	μA
		128 byte RAM retention, CRYO-TIMER running from ULFRCO	—	0.45	—	μA
		128 byte RAM retention, no RTCC	—	0.45	TBD	μA
Current consumption in EM4S mode	I _{EM4S}	No RAM retention, no RTCC	—	0.07	TBD	μA
Current consumption of peripheral power domain 1, with voltage scaling enabled	I _{PD1_VS}	Additional current consumption in EM2/3 when any peripherals on power domain 1 are enabled ¹	—	0.18	—	μA
Current consumption of peripheral power domain 2, with voltage scaling enabled	I _{PD2_VS}	Additional current consumption in EM2/3 when any peripherals on power domain 2 are enabled ¹	—	0.18	—	μA

Note:

1. Extra current consumed by power domain. Does not include current associated with the enabled peripherals. See [3.2.3 EM2 and EM3 Power Domains](#) for a list of the peripherals in each power domain.
2. CMU_LFRCOCTRL_ENVREF = 1, CMU_LFRCOCTRL_VREFUPDATE = 1

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Frequency limits	$f_{\text{HFRCO_BAND}}$	FREQRANGE = 0, FINETUNING = 0	TBD	—	TBD	MHz
		FREQRANGE = 3, FINETUNING = 0	TBD	—	TBD	MHz
		FREQRANGE = 6, FINETUNING = 0	TBD	—	TBD	MHz
		FREQRANGE = 7, FINETUNING = 0	TBD	—	TBD	MHz
		FREQRANGE = 8, FINETUNING = 0	TBD	—	TBD	MHz
		FREQRANGE = 10, FINETUNING = 0	TBD	—	TBD	MHz
		FREQRANGE = 11, FINETUNING = 0	TBD	—	TBD	MHz
		FREQRANGE = 12, FINETUNING = 0	TBD	—	TBD	MHz
		FREQRANGE = 13, FINETUNING = 0	TBD	—	TBD	MHz

4.1.14 Analog Comparator (ACMP)

Table 4.21. Analog Comparator (ACMP)

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Input voltage range	V_{ACMPIN}	ACMPVDD = ACMPn_CTRL_PWRSEL ¹	—	—	$V_{ACMPVDD}$	V
Supply voltage	$V_{ACMPVDD}$	BIASPROG ⁴ ≤ 0x10 or FULL- BIAS ⁴ = 0	1.8	—	$V_{VREGVDD_MAX}$	V
		0x10 < BIASPROG ⁴ ≤ 0x20 and FULLBIAS ⁴ = 1	2.1	—	$V_{VREGVDD_MAX}$	V
Active current not including voltage reference ²	I_{ACMP}	BIASPROG ⁴ = 1, FULLBIAS ⁴ = 0	—	50	—	nA
		BIASPROG ⁴ = 0x10, FULLBIAS ⁴ = 0	—	306	—	nA
		BIASPROG ⁴ = 0x02, FULLBIAS ⁴ = 1	—	6.5	—	μA
		BIASPROG ⁴ = 0x20, FULLBIAS ⁴ = 1	—	74	TBD	μA
Current consumption of inter- nal voltage reference ²	$I_{ACMPREF}$	VLP selected as input using 2.5 V Reference / 4 (0.625 V)	—	50	—	nA
		VLP selected as input using VDD	—	20	—	nA
		VBDIV selected as input using 1.25 V reference / 1	—	4.1	—	μA
		VADIV selected as input using VDD/1	—	2.4	—	μA

4.1.15 Digital to Analog Converter (VDAC)

DRIVESTRENGTH = 2 unless otherwise specified. Primary VDAC output.

Table 4.22. Digital to Analog Converter (VDAC)

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Output voltage	V_{DACOUT}	Single-Ended	0	—	V_{VREF}	V
		Differential ²	$-V_{VREF}$	—	V_{VREF}	V
Current consumption including references (2 channels) ¹	I_{DAC}	500 ksps, 12-bit, DRIVESTRENGTH = 2, REFSEL = 4	—	396	—	μA
		44.1 ksps, 12-bit, DRIVESTRENGTH = 1, REFSEL = 4	—	72	—	μA
		200 Hz refresh rate, 12-bit Sample-Off mode in EM2, DRIVESTRENGTH = 2, BGRREQTIME = 1, EM2REFENTIME = 9, REFSEL = 4, SETTLETIME = 0x0A, WARMUPTIME = 0x02	—	2	—	μA
Current from HFPERCLK ⁴	I_{DAC_CLK}		—	5.8	—	$\mu A/MHz$
Sample rate	SR_{DAC}		—	—	500	ksps
DAC clock frequency	f_{DAC}		—	—	1	MHz
Conversion time	$t_{DACCONV}$	$f_{DAC} = 1MHz$	2	—	—	μs
Settling time	$t_{DACSETTLE}$	50% fs step settling to 5 LSB	—	2.5	—	μs
Startup time	$t_{DACSTARTUP}$	Enable to 90% fs output, settling to 10 LSB	—	—	12	μs
Output impedance	R_{OUT}	DRIVESTRENGTH = 2, $0.4 V \leq V_{OUT} \leq V_{OPA} - 0.4 V$, $-8 mA < I_{OUT} < 8 mA$, Full supply range	—	2	—	Ω
		DRIVESTRENGTH = 0 or 1, $0.4 V \leq V_{OUT} \leq V_{OPA} - 0.4 V$, $-400 \mu A < I_{OUT} < 400 \mu A$, Full supply range	—	2	—	Ω
		DRIVESTRENGTH = 2, $0.1 V \leq V_{OUT} \leq V_{OPA} - 0.1 V$, $-2 mA < I_{OUT} < 2 mA$, Full supply range	—	2	—	Ω
		DRIVESTRENGTH = 0 or 1, $0.1 V \leq V_{OUT} \leq V_{OPA} - 0.1 V$, $-100 \mu A < I_{OUT} < 100 \mu A$, Full supply range	—	2	—	Ω
Power supply rejection ratio ⁶	PSRR	$V_{out} = 50\% fs$, DC	—	65.5	—	dB

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Supply current, continuous conversions, WARMUP-MODE=KEEPCSENWARM	I _{CSEN_ACTIVE}	SAR or Delta Modulation conversions of 33 pF capacitor, CS0CG=0 (Gain = 10x), always on	—	90.5	—	μA
HFPERCLK supply current	I _{CSEN_HFPERCLK}	Current contribution from HFPERCLK when clock to CSEN block is enabled.	—	2.25	—	μA/MHz

Note:

1. Current is specified with a total external capacitance of 33 pF per channel. Average current is dependent on how long the module is actively sampling channels within the scan period, and scales with the number of samples acquired. Supply current for a specific application can be estimated by multiplying the current per sample by the total number of samples per period (total_current = single_sample_current * (number_of_channels * accumulation)).

4.1.21.2 I2C Fast-mode (Fm)¹

Table 4.29. I2C Fast-mode (Fm)¹

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
SCL clock frequency ²	f _{SCL}		0	—	400	kHz
SCL clock low time	t _{LOW}		1.3	—	—	μs
SCL clock high time	t _{HIGH}		0.6	—	—	μs
SDA set-up time	t _{SU_DAT}		100	—	—	ns
SDA hold time ³	t _{HD_DAT}		100	—	900	ns
Repeated START condition set-up time	t _{SU_STA}		0.6	—	—	μs
(Repeated) START condition hold time	t _{HD_STA}		0.6	—	—	μs
STOP condition set-up time	t _{SU_STO}		0.6	—	—	μs
Bus free time between a STOP and START condition	t _{BUF}		1.3	—	—	μs

Note:

1. For CLHR set to 1 in the I2Cn_CTRL register.
2. For the minimum HPERCLK frequency required in Fast-mode, refer to the I2C chapter in the reference manual.
3. The maximum SDA hold time (t_{HD,DAT}) needs to be met only when the device does not stretch the low time of SCL (t_{LOW}).

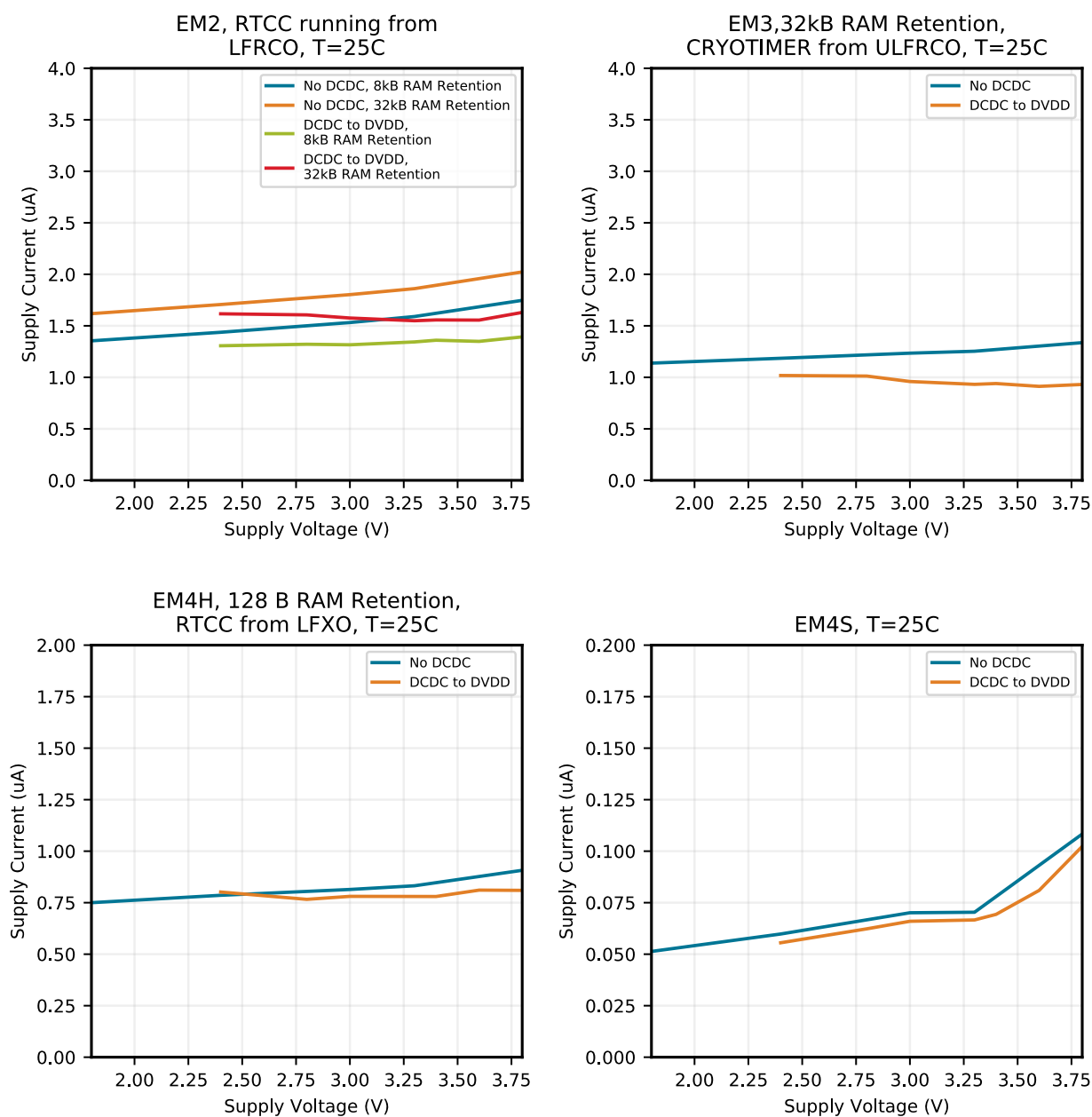


Figure 4.7. EM2, EM3, EM4H and EM4S Typical Supply Current vs. Supply

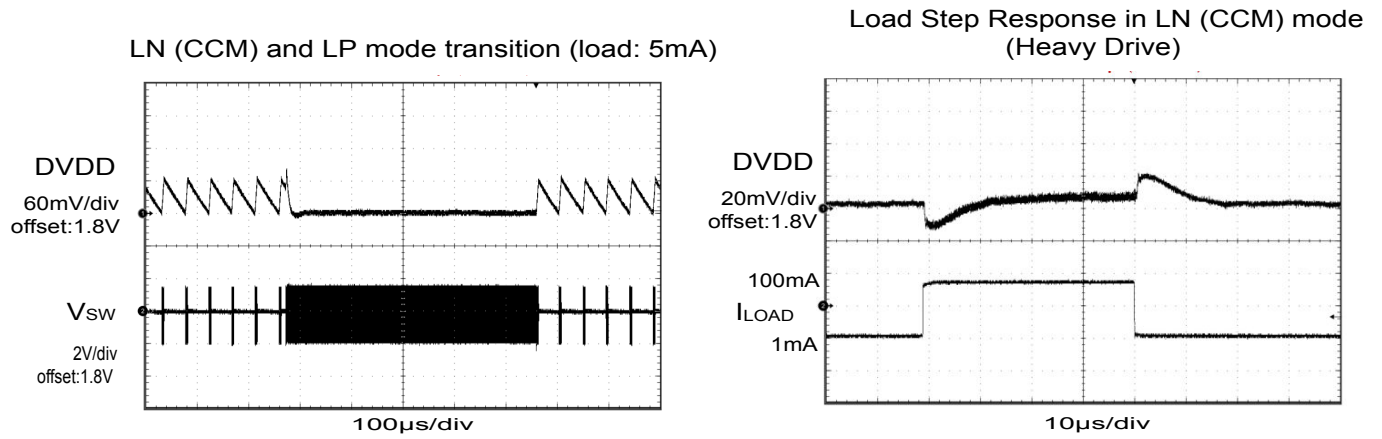


Figure 4.9. DC-DC Converter Transition Waveforms

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
PC4	13	GPIO	PC5	14	GPIO
PB7	15	GPIO	PB8	16	GPIO
PA8	17	GPIO	PA9	18	GPIO
PA10	19	GPIO	RESETn	20	Reset input, active low. To apply an external reset source to this pin, it is required to only drive this pin low during reset, and let the internal pull-up ensure that reset is released.
PB11	21	GPIO	AVDD	23 27	Analog power supply.
PB13	24	GPIO	PB14	25	GPIO
PD0	28	GPIO (5V)	PD1	29	GPIO
PD2	30	GPIO (5V)	PD3	31	GPIO
PD4	32	GPIO	PD5	33	GPIO
PD6	34	GPIO	PD7	35	GPIO
PD8	36	GPIO	PC6	37	GPIO
PC7	38	GPIO	DVDD	39	Digital power supply.
DECOUPLE	40	Decouple output for on-chip voltage regulator. An external decoupling capacitor is required at this pin.	PC8	41	GPIO
PC9	42	GPIO	PC10	43	GPIO (5V)
PC11	44	GPIO (5V)	PC12	45	GPIO (5V)
PC13	46	GPIO (5V)	PC14	47	GPIO (5V)
PC15	48	GPIO (5V)	PF0	49	GPIO (5V)
PF1	50	GPIO (5V)	PF2	51	GPIO
PF3	52	GPIO	PF4	53	GPIO
PF5	54	GPIO	PE8	57	GPIO
PE9	58	GPIO	PE10	59	GPIO
PE11	60	GPIO	PE12	61	GPIO
PE13	62	GPIO	PE14	63	GPIO
PE15	64	GPIO			

Note:

1. GPIO with 5V tolerance are indicated by (5V).

5.12 EFM32TG11B5xx in QFN32 Device Pinout

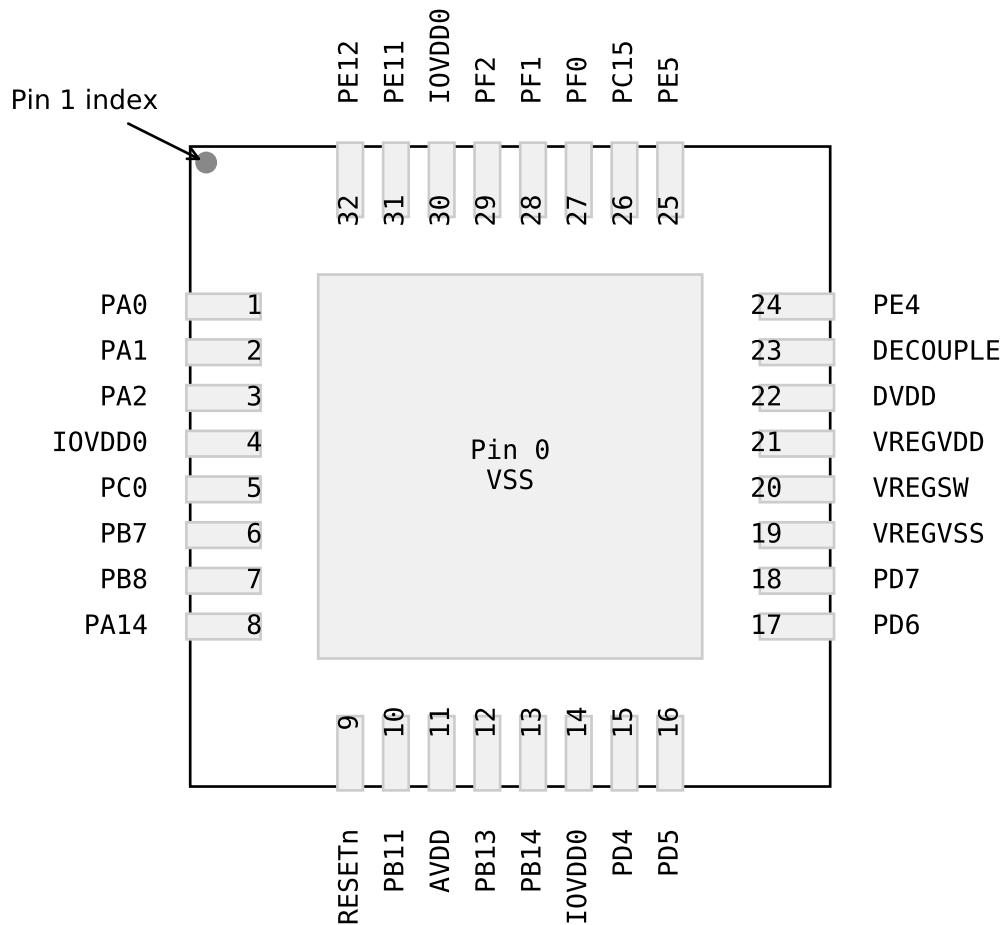


Figure 5.12. EFM32TG11B5xx in QFN32 Device Pinout

The following table provides package pin connections and general descriptions of pin functionality. For detailed information on the supported features for each GPIO pin, see [5.14 GPIO Functionality Table](#) or [5.15 Alternate Functionality Overview](#).

Table 5.12. EFM32TG11B5xx in QFN32 Device Pinout

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
VREGVSS	0 19	Voltage regulator VSS	PA0	1	GPIO
PA1	2	GPIO	PA2	3	GPIO
IOVDD0	4 14 30	Digital IO power supply 0.	PC0	5	GPIO (5V)
PB7	6	GPIO	PB8	7	GPIO

5.13 EFM32TG11B1xx in QFN32 Device Pinout

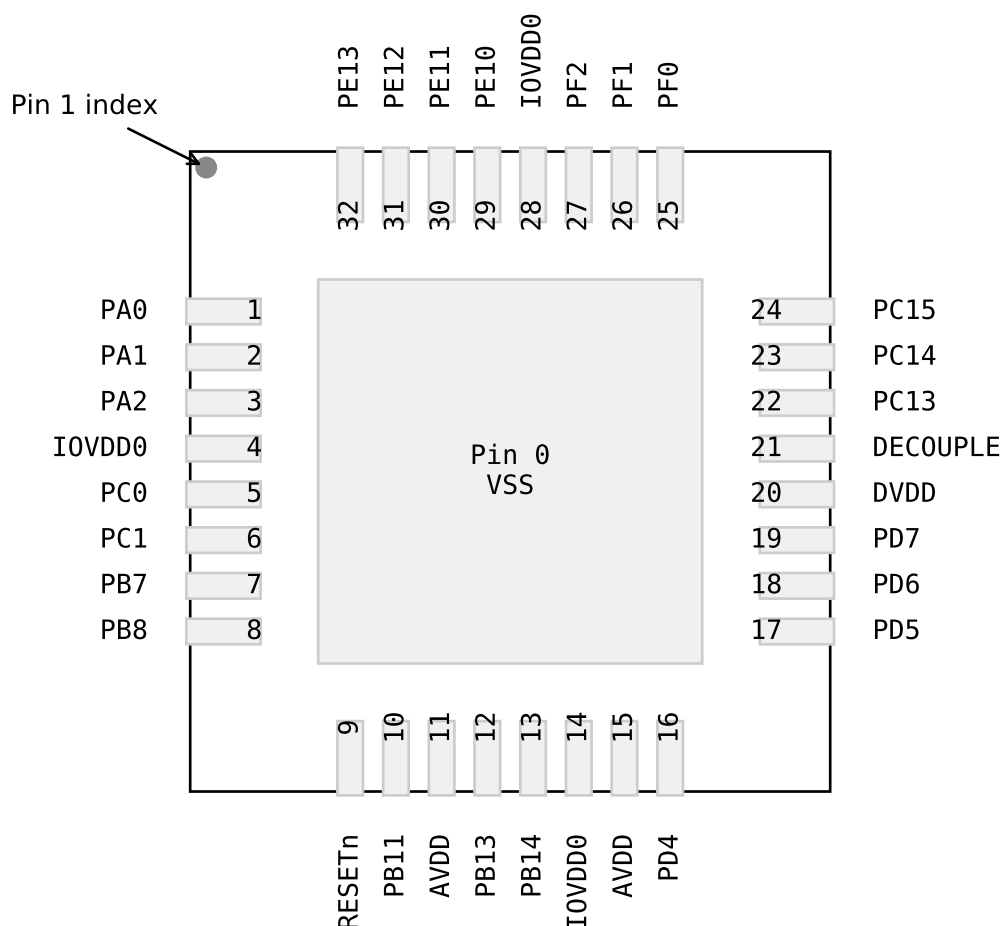


Figure 5.13. EFM32TG11B1xx in QFN32 Device Pinout

The following table provides package pin connections and general descriptions of pin functionality. For detailed information on the supported features for each GPIO pin, see [5.14 GPIO Functionality Table](#) or [5.15 Alternate Functionality Overview](#).

Table 5.13. EFM32TG11B1xx in QFN32 Device Pinout

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
VREGVSS	0	Voltage regulator VSS	PA0	1	GPIO
PA1	2	GPIO	PA2	3	GPIO
IOVDD0	4 14 28	Digital IO power supply 0.	PC0	5	GPIO (5V)
PC1	6	GPIO (5V)	PB7	7	GPIO

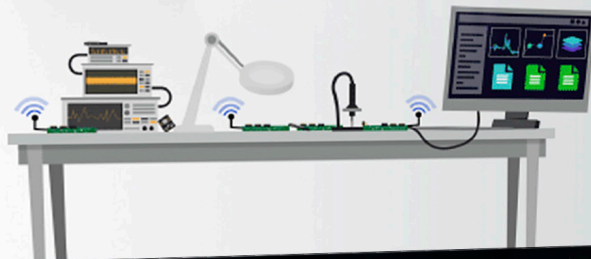
Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
PB8	8	GPIO	RESETn	9	Reset input, active low. To apply an external reset source to this pin, it is required to only drive this pin low during reset, and let the internal pull-up ensure that reset is released.
PB11	10	GPIO	AVDD	11 15	Analog power supply.
PB13	12	GPIO	PB14	13	GPIO
PD4	16	GPIO	PD5	17	GPIO
PD6	18	GPIO	PD7	19	GPIO
DVDD	20	Digital power supply.	DECOUPLE	21	Decouple output for on-chip voltage regulator. An external decoupling capacitor is required at this pin.
PC13	22	GPIO (5V)	PC14	23	GPIO (5V)
PC15	24	GPIO (5V)	PF0	25	GPIO (5V)
PF1	26	GPIO (5V)	PF2	27	GPIO
PE10	29	GPIO	PE11	30	GPIO
PE12	31	GPIO	PE13	32	GPIO
Note: 1. GPIO with 5V tolerance are indicated by (5V).					

Alternate	LOCATION		
Functionality	0 - 3	4 - 7	Description
U0_TX	2: PA3 3: PC14	4: PC4 5: PF1 6: PD7	UART0 Transmit output. Also used as receive input in half duplex communication.
US0_CLK	0: PE12 1: PE5 2: PC9 3: PC15	4: PB13 5: PA12	USART0 clock input / output.
US0_CS	0: PE13 1: PE4 2: PC8 3: PC14	4: PB14 5: PA13	USART0 chip select input / output.
US0_CTS	0: PE14 2: PC7 3: PC13	4: PB6 5: PB11	USART0 Clear To Send hardware flow control input.
US0_RTS	0: PE15 2: PC6 3: PC12	4: PB5 5: PD6	USART0 Request To Send hardware flow control output.
US0_RX	0: PE11 1: PE6 2: PC10 3: PE12	4: PB8 5: PC1	USART0 Asynchronous Receive. USART0 Synchronous mode Master Input / Slave Output (MISO).
US0_TX	0: PE10 1: PE7 2: PC11 3: PE13	4: PB7 5: PC0	USART0 Asynchronous Transmit. Also used as receive input in half duplex communication. USART0 Synchronous mode Master Output / Slave Input (MOSI).
US1_CLK	0: PB7 1: PD2 2: PF0 3: PC15	4: PC3 5: PB11 6: PE5	USART1 clock input / output.
US1_CS	0: PB8 1: PD3 2: PF1 3: PC14	4: PC0 5: PE4	USART1 chip select input / output.
US1_CTS	1: PD4 2: PF3 3: PC6	4: PC12 5: PB13	USART1 Clear To Send hardware flow control input.
US1_RTS	1: PD5 2: PF4 3: PC7	4: PC13 5: PB14	USART1 Request To Send hardware flow control output.
US1_RX	0: PC1 1: PD1 2: PD6	4: PC2 5: PA0 6: PA2	USART1 Asynchronous Receive. USART1 Synchronous mode Master Input / Slave Output (MISO).
US1_TX	0: PC0 1: PD0 2: PD7	4: PC1 5: PF2 6: PA14	USART1 Asynchronous Transmit. Also used as receive input in half duplex communication. USART1 Synchronous mode Master Output / Slave Input (MOSI).

APORT4Y	APORT3Y	APORT2Y	APORT1Y
BUSDY	BUSCY	BUSBY	BUSAY
		PB14	
			PB13
		PB12	
			PB11
		PB6	
	PF5		PB5
PF4		PB4	
	PF3		PB3
PF2			
	PF1		
PF0			
	PE15		PA15
PE14		PA14	
	PE13		PA13
PE12			
	PE11		
PE10		PA10	
	PE9		PA9
PE8			
	PE7		
PE6		PA6	
	PE5		PA5
PE4		PA4	
			PA3
		PA2	
			PA1
		PA0	

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