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Applications of "<u>Embedded -</u> <u>Microcontrollers</u>"

#### Details

Product Status	Discontinued at Digi-Key
Core Processor	ARM® Cortex®-M0+
Core Size	32-Bit Single-Core
Speed	48MHz
Connectivity	CANbus, I <sup>2</sup> C, IrDA, LINbus, SmartCard, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, I <sup>2</sup> S, LCD, POR, PWM, WDT
Number of I/O	34
Program Memory Size	64KB (64K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	32K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.8V
Data Converters	A/D 12bit SAR; D/A 12bit
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	48-TQFP
Supplier Device Package	48-TQFP (7x7)
Purchase URL	https://www.e-xfl.com/product-detail/silicon-labs/efm32tg11b540f64gq48-a

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

# 2. Ordering Information

# Table 2.1. Ordering Information

	Flash	RAM	DC-DC Con-				
Ordering Code	(kB)	(kB)	verter	LCD	GPIO	Package	Temp Range
EFM32TG11B520F128GM80-A	128	32	Yes	Yes	67	QFN80	-40 to +85°C
EFM32TG11B520F128GQ80-A	128	32	Yes	Yes	63	QFP80	-40 to +85°C
EFM32TG11B520F128IM80-A	128	32	Yes	Yes	67	QFN80	-40 to +125°C
EFM32TG11B520F128IQ80-A	128	32	Yes	Yes	63	QFP80	-40 to +125°C
EFM32TG11B540F64GM80-A	64	32	Yes	Yes	67	QFN80	-40 to +85°C
EFM32TG11B540F64GQ80-A	64	32	Yes	Yes	63	QFP80	-40 to +85°C
EFM32TG11B540F64IM80-A	64	32	Yes	Yes	67	QFN80	-40 to +125°C
EFM32TG11B540F64IQ80-A	64	32	Yes	Yes	63	QFP80	-40 to +125°C
EFM32TG11B520F128GM64-A	128	32	Yes	Yes	53	QFN64	-40 to +85°C
EFM32TG11B520F128GQ64-A	128	32	Yes	Yes	50	QFP64	-40 to +85°C
EFM32TG11B520F128IM64-A	128	32	Yes	Yes	53	QFN64	-40 to +125°C
EFM32TG11B520F128IQ64-A	128	32	Yes	Yes	50	QFP64	-40 to +125°C
EFM32TG11B540F64GM64-A	64	32	Yes	Yes	53	QFN64	-40 to +85°C
EFM32TG11B540F64GQ64-A	64	32	Yes	Yes	50	QFP64	-40 to +85°C
EFM32TG11B540F64IM64-A	64	32	Yes	Yes	53	QFN64	-40 to +125°C
EFM32TG11B540F64IQ64-A	64	32	Yes	Yes	50	QFP64	-40 to +125°C
EFM32TG11B520F128GQ48-A	128	32	Yes	Yes	34	QFP48	-40 to +85°C
EFM32TG11B520F128IQ48-A	128	32	Yes	Yes	34	QFP48	-40 to +125°C
EFM32TG11B540F64GQ48-A	64	32	Yes	Yes	34	QFP48	-40 to +85°C
EFM32TG11B540F64IQ48-A	64	32	Yes	Yes	34	QFP48	-40 to +125°C
EFM32TG11B520F128GM32-A	128	32	Yes	Yes	22	QFN32	-40 to +85°C
EFM32TG11B520F128IM32-A	128	32	Yes	Yes	22	QFN32	-40 to +125°C
EFM32TG11B540F64GM32-A	64	32	Yes	Yes	22	QFN32	-40 to +85°C
EFM32TG11B540F64IM32-A	64	32	Yes	Yes	22	QFN32	-40 to +125°C
EFM32TG11B320F128GM64-A	128	32	No	Yes	56	QFN64	-40 to +85°C
EFM32TG11B320F128GQ64-A	128	32	No	Yes	53	QFP64	-40 to +85°C
EFM32TG11B320F128IM64-A	128	32	No	Yes	56	QFN64	-40 to +125°C
EFM32TG11B320F128IQ64-A	128	32	No	Yes	53	QFP64	-40 to +125°C
EFM32TG11B340F64GM64-A	64	32	No	Yes	56	QFN64	-40 to +85°C
EFM32TG11B340F64GQ64-A	64	32	No	Yes	53	QFP64	-40 to +85°C
EFM32TG11B340F64IM64-A	64	32	No	Yes	56	QFN64	-40 to +125°C
EFM32TG11B340F64IQ64-A	64	32	No	Yes	53	QFP64	-40 to +125°C

# 3. System Overview

### 3.1 Introduction

The Tiny Gecko Series 1 product family is well suited for any battery operated application as well as other systems requiring high performance and low energy consumption. This section gives a short introduction to the MCU system. The detailed functional description can be found in the Tiny Gecko Series 1 Reference Manual. Any behavior that does not conform to the specifications in this data sheet or the functional descriptions in the Tiny Gecko Series 1 Reference Manual are detailed in the EFM32TG11 Errata document.

A block diagram of the Tiny Gecko Series 1 family is shown in Figure 3.1 Detailed EFM32TG11 Block Diagram on page 10. The diagram shows a superset of features available on the family, which vary by OPN. For more information about specific device features, consult Ordering Information.

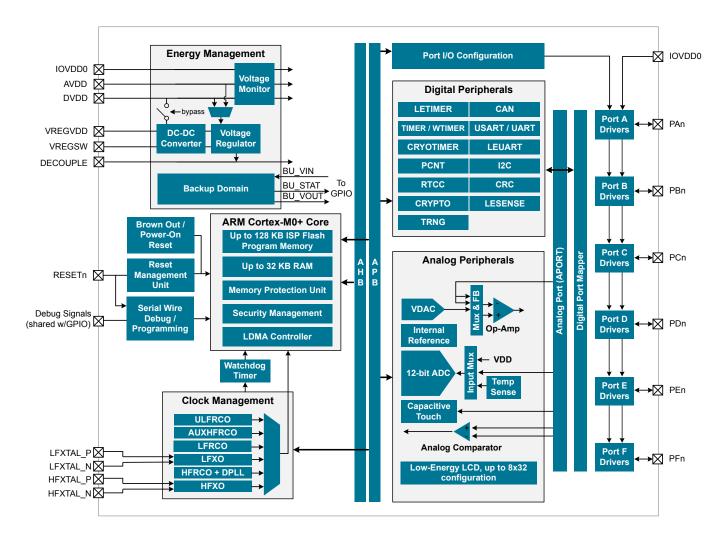


Figure 3.1. Detailed EFM32TG11 Block Diagram

#### 3.8.1 Analog Port (APORT)

The Analog Port (APORT) is an analog interconnect matrix allowing access to many analog modules on a flexible selection of pins. Each APORT bus consists of analog switches connected to a common wire. Since many clients can operate differentially, buses are grouped by X/Y pairs.

#### 3.8.2 Analog Comparator (ACMP)

The Analog Comparator is used to compare the voltage of two analog inputs, with a digital output indicating which input voltage is higher. Inputs are selected from among internal references and external pins. The tradeoff between response time and current consumption is configurable by software. Two 6-bit reference dividers allow for a wide range of internally-programmable reference sources. The ACMP can also be used to monitor the supply voltage. An interrupt can be generated when the supply falls below or rises above the programmable threshold.

#### 3.8.3 Analog to Digital Converter (ADC)

The ADC is a Successive Approximation Register (SAR) architecture, with a resolution of up to 12 bits at up to 1 Msps. The output sample resolution is configurable and additional resolution is possible using integrated hardware for averaging over multiple samples. The ADC includes integrated voltage references and an integrated temperature sensor. Inputs are selectable from a wide range of sources, including pins configurable as either single-ended or differential.

#### 3.8.4 Capacitive Sense (CSEN)

The CSEN module is a dedicated Capacitive Sensing block for implementing touch-sensitive user interface elements such a switches and sliders. The CSEN module uses a charge ramping measurement technique, which provides robust sensing even in adverse conditions including radiated noise and moisture. The module can be configured to take measurements on a single port pin or scan through multiple pins and store results to memory through DMA. Several channels can also be shorted together to measure the combined capacitance or implement wake-on-touch from very low energy modes. Hardware includes a digital accumulator and an averaging filter, as well as digital threshold comparators to reduce software overhead.

#### 3.8.5 Digital to Analog Converter (VDAC)

The Digital to Analog Converter (VDAC) can convert a digital value to an analog output voltage. The VDAC is a fully differential, 500 ksps, 12-bit converter. The opamps are used in conjunction with the VDAC, to provide output buffering. One opamp is used per singleended channel, or two opamps are used to provide differential outputs. The VDAC may be used for a number of different applications such as sensor interfaces or sound output. The VDAC can generate high-resolution analog signals while the MCU is operating at low frequencies and with low total power consumption. Using DMA and a timer, the VDAC can be used to generate waveforms without any CPU intervention. The VDAC is available in all energy modes down to and including EM3.

#### 3.8.6 Operational Amplifiers

The opamps are low power amplifiers with a high degree of flexibility targeting a wide variety of standard opamp application areas, and are available down to EM3. With flexible built-in programming for gain and interconnection they can be configured to support multiple common opamp functions. All pins are also available externally for filter configurations. Each opamp has a rail to rail input and a rail to rail output. They can be used in conjunction with the VDAC module or in stand-alone configurations. The opamps save energy, PCB space, and cost as compared with standalone opamps because they are integrated on-chip.

#### 3.8.7 Liquid Crystal Display Driver (LCD)

The LCD driver is capable of driving a segmented LCD display with up to 8x32 segments. A voltage boost function enables it to provide the LCD display with higher voltage than the supply voltage for the device. A patented charge redistribution driver can reduce the LCD module supply current by up to 40%. In addition, an animation feature can run custom animations on the LCD display without any CPU intervention. The LCD driver can also remain active even in Energy Mode 2 and provides a Frame Counter interrupt that can wake-up the device on a regular basis for updating data.

#### 3.9 Reset Management Unit (RMU)

The RMU is responsible for handling reset of the EFM32TG11. A wide range of reset sources are available, including several power supply monitors, pin reset, software controlled reset, core lockup reset, and watchdog reset.

# 4.1.2.1 General Operating Conditions

Parameter	Symbol	Test Condition	Min	Тур	Мах	Unit
Operating ambient tempera-	T <sub>A</sub>	-G temperature grade	-40	25	85	°C
ture range <sup>6</sup>		-I temperature grade	-40	25	125	°C
AVDD supply voltage <sup>2</sup>	V <sub>AVDD</sub>		1.8	3.3	3.8	V
VREGVDD operating supply	V <sub>VREGVDD</sub>	DCDC in regulation	2.4	3.3	3.8	V
voltage <sup>2 1</sup>		DCDC in bypass, 50mA load	1.8	3.3	3.8	V
		DCDC not in use. DVDD external- ly shorted to VREGVDD	1.8	3.3	3.8	V
VREGVDD current	I <sub>VREGVDD</sub>	DCDC in bypass, T ≤ 85 °C	_	_	200	mA
		DCDC in bypass, T > 85 °C	_	_	100	mA
DVDD operating supply volt- age	V <sub>DVDD</sub>		1.62	_	V <sub>VREGVDD</sub>	V
IOVDD operating supply volt- age	VIOVDD	All IOVDD pins <sup>5</sup>	1.62	_	V <sub>VREGVDD</sub>	V
DECOUPLE output capaci- tor <sup>3 4</sup>	C <sub>DECOUPLE</sub>		0.75	1.0	2.75	μF
HFCORECLK frequency	f <sub>CORE</sub>	VSCALE2, MODE = WS1	_	_	48	MHz
		VSCALE2, MODE = WS0	_	_	25	MHz
		VSCALE0, MODE = WS1	_	_	20	MHz
		VSCALE0, MODE = WS0	_	_	10	MHz
HFCLK frequency	f <sub>HFCLK</sub>	VSCALE2	_	_	48	MHz
		VSCALE0	_	_	20	MHz
HFSRCCLK frequency	f <sub>HFSRCCLK</sub>	VSCALE2	_	_	48	MHz
		VSCALE0	_	_	20	MHz
HFBUSCLK frequency	f <sub>HFBUSCLK</sub>	VSCALE2	_	_	48	MHz
		VSCALE0		_	20	MHz
HFPERCLK frequency	f <sub>HFPERCLK</sub>	VSCALE2	_	_	48	MHz
		VSCALE0	_	_	20	MHz
HFPERBCLK frequency	f <sub>HFPERBCLK</sub>	VSCALE2	_	_	48	MHz
		VSCALE0	_	_	20	MHz
HFPERCCLK frequency	fHFPERCCLK	VSCALE2	_	—	48	MHz
		VSCALE0	_	_	20	MHz

# Table 4.2. General Operating Conditions

## 4.1.5 Backup Supply Domain

Parameter	Symbol	Test Condition	Min	Тур	Max	Unit
Backup supply voltage range	V <sub>BU_VIN</sub>		TBD	—	3.8	V
PWRRES resistor	R <sub>PWRRES</sub>	EMU_BUCTRL_PWRRES = RES0	TBD	3900	TBD	Ω
		EMU_BUCTRL_PWRRES = RES1	TBD	1800	TBD	Ω
		EMU_BUCTRL_PWRRES = RES2	TBD	1330	TBD	Ω
		EMU_BUCTRL_PWRRES = RES3	TBD	815	TBD	Ω
Output impedance between BU_VIN and BU_VOUT <sup>2</sup>	R <sub>BU_VOUT</sub>	EMU_BUCTRL_VOUTRES = STRONG	TBD	110	TBD	Ω
		EMU_BUCTRL_VOUTRES = MED	TBD	775	TBD	Ω
		EMU_BUCTRL_VOUTRES = WEAK	TBD	6500	TBD	Ω
Supply current	I <sub>BU_VIN</sub>	BU_VIN not powering backup do- main	_	10	TBD	nA
		BU_VIN powering backup do- main <sup>1</sup>		450	TBD	nA

## Table 4.5. Backup Supply Domain

# Note:

1. Additional current required by backup circuitry when backup is active. Includes supply current of backup switches and backup regulator. Does not include supply current required for backed-up circuitry.

2. BU\_VOUT and BU\_STAT signals are not available in all package configurations. Check the device pinout for availability.

Parameter	Symbol	Test Condition	Min	Тур	Max	Unit
Current consumption in EM4H mode, with voltage	I <sub>EM4H_VS</sub>	128 byte RAM retention, RTCC running from LFXO	—	0.82		μA
scaling enabled		128 byte RAM retention, CRYO- TIMER running from ULFRCO	—	0.45	_	μA
		128 byte RAM retention, no RTCC	—	0.45	TBD	μA
Current consumption in EM4S mode	I <sub>EM4S</sub>	No RAM retention, no RTCC	—	0.07	TBD	μA
Current consumption of pe- ripheral power domain 1, with voltage scaling enabled	IPD1_VS	Additional current consumption in EM2/3 when any peripherals on power domain 1 are enabled <sup>1</sup>	_	0.18	_	μA
Current consumption of pe- ripheral power domain 2, with voltage scaling enabled	IPD2_VS	Additional current consumption in EM2/3 when any peripherals on power domain 2 are enabled <sup>1</sup>	_	0.18	_	μA

Note:

1. Extra current consumed by power domain. Does not include current associated with the enabled peripherals. See 3.2.3 EM2 and EM3 Power Domains for a list of the peripherals in each power domain.

2. CMU\_LFRCOCTRL\_ENVREF = 1, CMU\_LFRCOCTRL\_VREFUPDATE = 1

Parameter	Symbol	Test Condition	Min	Тур	Max	Unit
Wake up time from EM1	t <sub>EM1_WU</sub>		_	3	_	AHB Clocks
Wake up from EM2	t <sub>EM2_WU</sub>	Code execution from flash		10.1	_	μs
		Code execution from RAM		3.1	_	μs
Wake up from EM3	t <sub>EM3_WU</sub>	Code execution from flash	_	10.1	_	μs
		Code execution from RAM	_	3.1	_	μs
Wake up from EM4H <sup>1</sup>	t <sub>EM4H_WU</sub>	Executing from flash	—	88	—	μs
Wake up from EM4S <sup>1</sup>	t <sub>EM4S_WU</sub>	Executing from flash	_	282	_	μs
Time from release of reset	t <sub>RESET</sub>	Soft Pin Reset released	_	50	_	μs
source to first instruction ex- ecution		Any other reset released	_	352	_	μs
Power mode scaling time	t <sub>SCALE</sub>	VSCALE0 to VSCALE2, HFCLK = 19 MHz <sup>4 2</sup>	_	31.8	_	μs
		VSCALE2 to VSCALE0, HFCLK = 19 MHz <sup>3</sup>	_	4.3	_	μs

## Table 4.9. Wake Up Times

# Note:

1. Time from wake up request until first instruction is executed. Wakeup results in device reset.

2. VSCALE0 to VSCALE2 voltage change transitions occur at a rate of 10 mV/μs for approximately 20 μs. During this transition, peak currents will be dependent on the value of the DECOUPLE output capacitor, from 35 mA (with a 1 μF capacitor) to 70 mA (with a 2.7 μF capacitor).

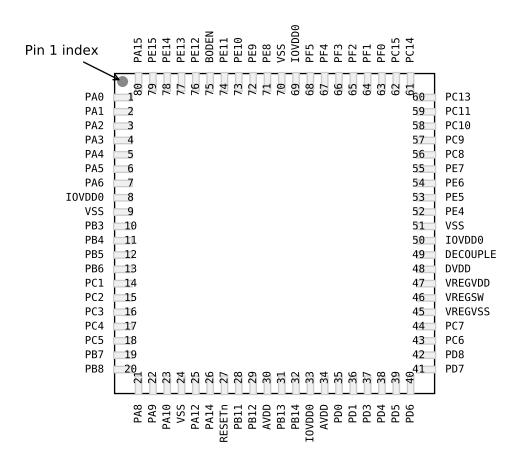
3. Scaling down from VSCALE2 to VSCALE0 requires approximately 2.8 µs + 29 HFCLKs.

4. Scaling up from VSCALE0 to VSCALE2 requires approximately 30.3 µs + 28 HFCLKs.

Parameter	Symbol	Test Condition	Min	Тур	Max	Unit
	the sum of the e. Gregisters.	etting in ACMPn_CTRL_PWRS ne contributions from the ACMP	-			ACMP +

# 5. Pin Definitions

# 5.1 EFM32TG11B5xx in QFP80 Device Pinout



#### Figure 5.1. EFM32TG11B5xx in QFP80 Device Pinout

The following table provides package pin connections and general descriptions of pin functionality. For detailed information on the supported features for each GPIO pin, see 5.14 GPIO Functionality Table or 5.15 Alternate Functionality Overview.

Table 5.1.	EFM32TG11B5xx in QFP80 Device Pinout

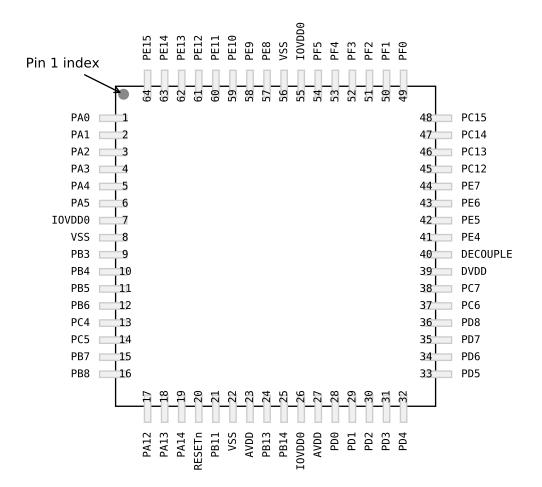
Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
PA0	1	GPIO	PA1	2	GPIO
PA2	3	GPIO	PA3	4	GPIO
PA4	5	GPIO	PA5	6	GPIO
PA6	7	GPIO	IOVDD0	8 33 50 69	Digital IO power supply 0.

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
PE12	76	GPIO	PE13	77	GPIO
PE14	78	GPIO	PE15	79	GPIO
PA15	80	GPIO			

Note:

1. GPIO with 5V tolerance are indicated by (5V).

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description		
PE15	79	GPIO	PA15	80	GPIO		
Note: 1. GPIO with	Note: 1. GPIO with 5V tolerance are indicated by (5V).						

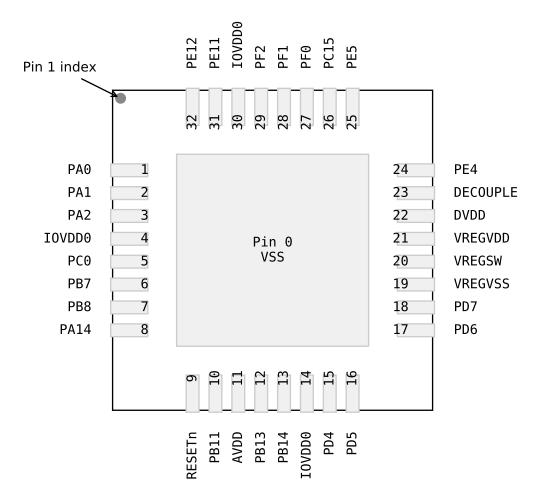


## Figure 5.4. EFM32TG11B3xx in QFP64 Device Pinout

The following table provides package pin connections and general descriptions of pin functionality. For detailed information on the supported features for each GPIO pin, see 5.14 GPIO Functionality Table or 5.15 Alternate Functionality Overview.

Table 5.4. EFM32TG11B3xx in QFP64 Device Pir	າout
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Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
PA0	1	GPIO	PA1	2	GPIO
PA2	3	GPIO	PA3	4	GPIO
PA4	5	GPIO	PA5	6	GPIO
IOVDD0	7 26 55	Digital IO power supply 0.	VSS	8 22 56	Ground
PB3	9	GPIO	PB4	10	GPIO
PB5	11	GPIO	PB6	12	GPIO



## Figure 5.12. EFM32TG11B5xx in QFN32 Device Pinout

The following table provides package pin connections and general descriptions of pin functionality. For detailed information on the supported features for each GPIO pin, see 5.14 GPIO Functionality Table or 5.15 Alternate Functionality Overview.

Table 5.12. EFM32TG11B5xx in QFN32 Device Pinout
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Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
VREGVSS	0 19	Voltage regulator VSS	PA0	1	GPIO
PA1	2	GPIO	PA2	3	GPIO
IOVDD0	4 14 30	Digital IO power supply 0.	PC0	5	GPIO (5V)
PB7	6	GPIO	PB8	7	GPIO

GPIO Name	Pin Alternate Functionality / Description					
	Analog	Timers	Communication	Other		
PC15	VDAC0_OUT1ALT / OPA1_OUTALT #3 BU- SACMP1Y BUSACMP1X	TIM0_CDTI2 #1 TIM1_CC2 #0 WTIM0_CC0 #4 LE- TIM0_OUT1 #5	US0_CLK #3 US1_CLK #3 US3_RTS #3 U0_RX #3 LEU0_RX #5	LES_CH15 PRS_CH1 #2		
PF0	BUSDY BUSCX	TIM0_CC0 #4 WTIM0_CC1 #4 LE- TIM0_OUT0 #2	CAN0_RX #1 US1_CLK #2 US2_TX #5 LEU0_TX #3 I2C0_SDA #5	DBG_SWCLKTCK BOOT_TX		
PF1	BUSCY BUSDX	TIM0_CC1 #4 WTIM0_CC2 #4 LE- TIM0_OUT1 #2	US1_CS #2 US2_RX #5 U0_TX #5 LEU0_RX #3 I2C0_SCL #5	PRS_CH4 #2 DBG_SWDIOTMS GPIO_EM4WU3 BOOT_RX		
PF2	BUSDY BUSCX LCD_SEG0	TIM0_CC2 #4 TIM1_CC0 #5	CAN0_TX #1 US1_TX #5 US2_CLK #5 U0_RX #5 LEU0_TX #4 I2C1_SCL #4	CMU_CLK0 #4 PRS_CH0 #3 ACMP1_O #0 DBG_TDO GPIO_EM4WU4		
PF3	BUSCY BUSDX LCD_SEG1	TIM0_CDTI0 #2 TIM1_CC1 #5	US1_CTS #2	CMU_CLK1 #4 PRS_CH0 #1		
PF4	BUSDY BUSCX LCD_SEG2	TIM0_CDTI1 #2 TIM1_CC2 #5	US1_RTS #2	PRS_CH1 #1		
PF5	BUSCY BUSDX LCD_SEG3	TIM0_CDTI2 #2 TIM1_CC3 #6	US2_CS #5	PRS_CH2 #1 DBG_TDI		
PE8	BUSDY BUSCX LCD_SEG4			PRS_CH3 #1		
PE9	BUSCY BUSDX LCD_SEG5					
PE10	BUSDY BUSCX LCD_SEG6	TIM1_CC0 #1 WTIM0_CDTI0 #0	US0_TX #0	PRS_CH2 #2 GPIO_EM4WU9		
PE11	BUSCY BUSDX LCD_SEG7	TIM1_CC1 #1 WTIM0_CDTI1 #0	US0_RX #0	LES_ALTEX5 PRS_CH3 #2		
PE12	BUSDY BUSCX LCD_SEG8	TIM1_CC2 #1 WTIM0_CDTI2 #0 LE- TIM0_OUT0 #4	US0_RX #3 US0_CLK #0 I2C0_SDA #6	CMU_CLK1 #2 CMU_CLKI0 #6 LES_AL- TEX6 PRS_CH1 #3		
PE13	BUSCY BUSDX LCD_SEG9	TIM1_CC3 #1 LE- TIM0_OUT1 #4	US0_TX #3 US0_CS #0 I2C0_SCL #6	LES_ALTEX7 PRS_CH2 #3 ACMP0_O #0 GPIO_EM4WU5		
PE14	BUSDY BUSCX LCD_SEG10		US0_CTS #0 LEU0_TX #2			
PE15	BUSCY BUSDX LCD_SEG11		US0_RTS #0 LEU0_RX #2			
PA15	BUSAY BUSBX LCD_SEG12		US2_CLK #3			

Alternate	LOCATION				
Functionality	0 - 3	4 - 7	Description		
CAN0_TX	0: PC1 1: PF2 2: PD1		CAN0 TX.		
CMU_CLK0	0: PA2 1: PC12 2: PD7	4: PF2 5: PA12	Clock Management Unit, clock output number 0.		
CMU_CLK1	0: PA1 1: PD8 2: PE12	4: PF3 5: PB11	Clock Management Unit, clock output number 1.		
CMU_CLK2	0: PA0 1: PA3 2: PD6	4: PA3	Clock Management Unit, clock output number 2.		
CMU_CLKI0	0: PD4 1: PA3 2: PB8 3: PB13	6: PE12 7: PB11	Clock Management Unit, clock input number 0.		
DBG_SWCLKTCK	0: PF0		Debug-interface Serial Wire clock input and JTAG Test Clock. Note that this function is enabled to the pin out of reset, and has a built-in pull down.		
DBG_SWDIOTMS	0: PF1		Debug-interface Serial Wire data input / output and JTAG Test Mode Select. Note that this function is enabled to the pin out of reset, and has a built-in pull up.		
DBG_TDI	0: PF5		Debug-interface JTAG Test Data In. Note that this function becomes available after the first valid JTAG command is re- ceived, and has a built-in pull up when JTAG is active.		
DBG_TDO	0: PF2		Debug-interface JTAG Test Data Out. Note that this function becomes available after the first valid JTAG command is re- ceived.		
GPIO_EM4WU0	0: PA0		Pin can be used to wake the system up from EM4		
GPIO_EM4WU1	0: PA6		Pin can be used to wake the system up from EM4		
GPIO_EM4WU2	0: PC9		Pin can be used to wake the system up from EM4		
GPIO_EM4WU3	0: PF1		Pin can be used to wake the system up from EM4		

Alternate	LOCA	TION	
Functionality	0 - 3	4 - 7	Description
LCD_COM0	0: PE4		LCD driver common line number 0.
LCD_COM1	0: PE5		LCD driver common line number 1.
LCD_COM2	0: PE6		LCD driver common line number 2.
LCD_COM3	0: PE7		LCD driver common line number 3.
LCD_SEG0	0: PF2		LCD segment line 0.
LCD_SEG1	0: PF3		LCD segment line 1.
LCD_SEG2	0: PF4		LCD segment line 2.
LCD_SEG3	0: PF5		LCD segment line 3.
LCD_SEG4	0: PE8		LCD segment line 4.
LCD_SEG5	0: PE9		LCD segment line 5.
LCD_SEG6	0: PE10		LCD segment line 6.
LCD_SEG7	0: PE11		LCD segment line 7.
LCD_SEG8	0: PE12		LCD segment line 8.

## 9.2 QFN64 PCB Land Pattern

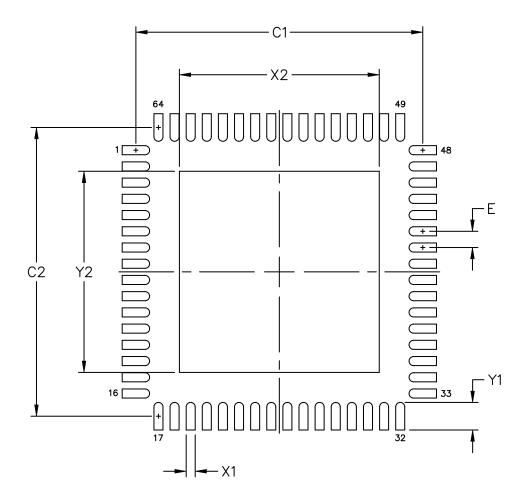


Figure 9.2. QFN64 PCB Land Pattern Drawing



Figure 9.3. QFN64 Package Marking

The package marking consists of:

- PPPPPPPPP The part number designation.
- TTTTTT A trace or manufacturing code. The first letter is the device revision.
- YY The last 2 digits of the assembly year.
- WW The 2-digit workweek when the device was assembled.

Dimension	Min	Тур	Мах			
A	0.70	0.75	0.80			
A1	0.00	_	0.05			
A3	0.203 REF					
b	0.20	0.25	0.30			
D	5.0 BSC					
D2/E2	3.60	3.70	3.80			
E	5.0 BSC					
е	0.50 BSC					
L	0.35	0.35 0.40 0.45				
ааа	0.10					
bbb	0.10					
ссс	0.10					
ddd	0.05					
eee	0.08					
•• •						

## Table 11.1. QFN32 Package Dimensions

Note:

1. All dimensions shown are in millimeters (mm) unless otherwise noted.

2. Dimensioning and Tolerancing per ANSI Y14.5M-1994.

3. This drawing conforms to the JEDEC Solid State Outline MO-220, Variation VKKD-4.

4. Recommended card reflow profile is per the JEDEC/IPC J-STD-020 specification for Small Body Components.





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