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Details

Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	32MHz
Connectivity	I ² C, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	44
Program Memory Size	28KB (16K x 14)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	2K x 8
Voltage - Supply (Vcc/Vdd)	2.3V ~ 5.5V
Data Converters	A/D 43x10b; D/A 1x5b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	48-TQFP
Supplier Device Package	48-TQFP (7x7)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic16f15386t-i-pt

PIC16(L)F15356/75/76/85/86

TABLE 1-2: PIC16(L)F15356 PINOUT DESCRIPTION

Name	Function	Input Type	Output Type	Description
RA0/ANA0/C1IN0-/C2IN0-/CLCIN0 ⁽¹⁾ /IOCA0	RA0	TTL/ST	CMOS/OD	General purpose I/O.
	ANA0	AN	—	ADC Channel A0 input.
	C1IN0-	AN	—	Comparator 1 negative input.
	C2IN0-	AN	—	Comparator 2 negative input.
	CLCIN0 ⁽¹⁾	TTL/ST	—	Configurable Logic Cell source input.
	IOCA0	TTL/ST	—	Interrupt-on-change input.
RA1/ANA1/C1IN1-/C2IN1-/CLCIN1 ⁽¹⁾ /IOCA1	RA1	TTL/ST	CMOS/OD	General purpose I/O.
	ANA1	AN	—	ADC Channel A1 input.
	C1IN1-	AN	—	Comparator 1 negative input.
	C2IN1-	AN	—	Comparator 2 negative input.
	CLCIN1 ⁽¹⁾	TTL/ST	—	Configurable Logic Cell source input.
	IOCA1	TTL/ST	—	Interrupt-on-change input.
RA2/ANA2/C1IN0+/C2IN0+/DAC1OUT1/IOCA2	RA2	TTL/ST	CMOS/OD	General purpose I/O.
	ANA2	AN	—	ADC Channel A2 input.
	C1IN0+	AN	—	Comparator 2 positive input.
	C2IN0+	AN	—	Comparator 2 positive input.
	DAC1OUT1	—	AN	Digital-to-Analog Converter output.
	IOCA2	TTL/ST	—	Interrupt-on-change input.
RA3/ANA3/C1IN1+/VREF+/IOCA3/DAC1REF+	RA3	TTL/ST	CMOS/OD	General purpose I/O.
	ANA3	AN	—	ADC Channel A3 input.
	C1IN1+	AN	—	Comparator 1 positive input.
	VREF+	AN	—	External ADC and/or DAC positive reference input.
	IOCA3	TTL/ST	—	Interrupt-on-change input.
	DAC1REF+	TTL/ST	AN	DAC positive reference.
RA4/ANA4/T0CKI ⁽¹⁾ /IOCA4	RA4	TTL/ST	CMOS/OD	General purpose I/O.
	ANA4	AN	—	ADC Channel A4 input.
	T0CKI ⁽¹⁾	TTL/ST	—	Timer0 clock input.
	IOCA4	TTL/ST	—	Interrupt-on-change input.
RA5/ANA5/SS1 ⁽¹⁾ /IOCA5	RA5	TTL/ST	CMOS/OD	General purpose I/O.
	ANA5	AN	—	ADC Channel A5 input.
	SS1 ⁽¹⁾	TTL/ST	—	MSSP1 SPI slave select input.
	IOCA5	TTL/ST	—	Interrupt-on-change input.

Legend: AN = Analog input or output CMOS = CMOS compatible input or output OD = Open-Drain
TTL = TTL compatible input ST = Schmitt Trigger input with CMOS levels I²C = Schmitt Trigger input with I²C
HV = High Voltage XTAL = Crystal levels

- Note**
- 1: This is a PPS remappable input signal. The input function may be moved from the default location shown to one of several other PORTx pins. Refer to Table 15-4 for details on which PORT pins may be used for this signal.
 - 2: All output signals shown in this row are PPS remappable. These signals may be mapped to output onto one of several PORTx pin options as described in Table 15-3.
 - 3: This is a bidirectional signal. For normal module operation, the firmware should map this signal to the same pin in both the PPS input and PPS output registers.
 - 4: These pins are configured for I²C logic levels. The SCLx/SDAx signals may be assigned to any of the RB1/RB2/RC3/RC4 pins. PPS assignments to the other pins (e.g., RA5) will operate, but input logic levels will be standard TTL/ST, as selected by the INLVL register, instead of the I²C specific or SMBus input buffer thresholds.

PIC16(L)F15356/75/76/85/86

TABLE 1-4: PIC16(L)F15385/86 PINOUT DESCRIPTION

Name	Function	Input Type	Output Type	Description
RA0/ANA0/C1IN0-/C2IN0-/CLCIN0 ⁽¹⁾ /IOCA0	RA0	TTL/ST	CMOS/OD	General purpose I/O.
	ANA0	AN	—	ADC Channel A0 input.
	C1IN0-	AN	—	Comparator negative input.
	C2IN0-	AN	—	Comparator negative input.
	CLCIN0 ⁽¹⁾	TTL/ST	—	Configurable Logic Cell source input.
	IOCA0	TTL/ST	—	Interrupt-on-change input.
RA1/ANA1/C1IN1-/C2IN1-/CLCIN1 ⁽¹⁾ /IOCA1	RA1	TTL/ST	CMOS/OD	General purpose I/O.
	ANA1	AN	—	ADC Channel A1 input.
	C1IN1-	AN	—	Comparator negative input.
	C2IN1-	AN	—	Comparator negative input.
	CLCIN1 ⁽¹⁾	TTL/ST	—	Configurable Logic Cell source input.
	IOCA1	TTL/ST	—	Interrupt-on-change input.
RA2/ANA2/C1IN0+/C2IN0+/DAC1OUT1/IOCA2	RA2	TTL/ST	CMOS/OD	General purpose I/O.
	ANA2	AN	—	ADC Channel A2 input.
	C1IN0+	AN	—	Comparator positive input.
	C2IN0+	AN	—	Comparator positive input.
	DAC1OUT1	—	AN	Digital-to-Analog Converter output.
	IOCA2	TTL/ST	—	Interrupt-on-change input.
RA3/ANA3/C1IN1+/VREF+/DACREF+/IOCA3	RA3	TTL/ST	CMOS/OD	General purpose I/O.
	ANA3	AN	—	ADC Channel A3 input.
	C1IN1+	AN	—	Comparator positive input.
	VREF+	AN	—	External ADC and/or DAC positive reference input.
	IOCA3	TTL/ST	—	Interrupt-on-change input.
RA4/ANA4/C1IN1-/T0CKI ⁽¹⁾ /IOCA4	RA4	TTL/ST	CMOS/OD	General purpose I/O.
	ANA4	AN	—	ADC Channel A4 input.
	C1IN1-	AN	—	Comparator negative input.
	T0CKI ⁽¹⁾	TTL/ST	—	Timer0 clock input.
	IOCA4	TTL/ST	—	Interrupt-on-change input.
RA5/ANA5/ $\overline{SS1}$ ⁽¹⁾ /T1G ⁽¹⁾ /IOCA5	RA5	TTL/ST	CMOS/OD	General purpose I/O.
	ANA5	AN	—	ADC Channel A5 input.
	$\overline{SS1}$ ⁽¹⁾	TTL/ST	—	MSSP1 SPI slave select input.
	T1G ⁽¹⁾	TTL/ST	—	Timer1 gate input.
	IOCA5	TTL/ST	—	Interrupt-on-change input.

Legend: AN = Analog input or output CMOS = CMOS compatible input or output OD = Open-Drain
TTL = TTL compatible input ST = Schmitt Trigger input with CMOS levels I²C = Schmitt Trigger input with I²C
HV = High Voltage XTAL = Crystal levels

- Note** 1: This is a PPS remappable input signal. The input function may be moved from the default location shown to one of several other PORTx pins. Refer to Table 15-4 for details on which PORT pins may be used for this signal.
- 2: All output signals shown in this row are PPS remappable. These signals may be mapped to output onto one of several PORTx pin options as described in Table 15-5, Table 15-6 and Table 15-7.
- 3: This is a bidirectional signal. For normal module operation, the firmware should map this signal to the same pin in both the PPS input and PPS output registers.
- 4: These pins are configured for I²C logic levels. The SCLx/SDAx signals may be assigned to any of the RB1/RB2/RC3/RC4 pins. PPS assignments to the other pins (e.g., RA5) will operate, but input logic levels will be standard TTL/ST, as selected by the INLVL register, instead of the I²C specific or SMBus input buffer thresholds.

4.3.2.1 STATUS Register

The STATUS register, shown in Register 4-1, contains:

- the arithmetic status of the ALU
- the Reset status

The STATUS register can be the destination for any instruction, like any other register. If the STATUS register is the destination for an instruction that affects the Z, DC or C bits, then the write to these three bits is disabled. These bits are set or cleared according to the device logic. Furthermore, the $\overline{\text{TO}}$ and $\overline{\text{PD}}$ bits are not writable. Therefore, the result of an instruction with the STATUS register as destination may be different than intended.

For example, `CLRF STATUS` will clear bits <4:3> and <1:0>, and set the Z bit. This leaves the STATUS register as '000u u1uu' (where u = unchanged).

It is recommended, therefore, that only `BCF`, `BSF`, `SWAPF` and `MOVWF` instructions are used to alter the STATUS register, because these instructions do not affect any Status bits. For other instructions not affecting any Status bits, refer to **Section 36.0 "Instruction Set Summary"**.

Note 1: The $\overline{\text{C}}$ and $\overline{\text{DC}}$ bits operate as Borrow and Digit Borrow out bits, respectively, in subtraction.

REGISTER 4-1: STATUS: STATUS REGISTER

U-0	U-0	U-0	R-1/q	R-1/q	R/W-0/u	R/W-0/u	R/W-0/u
—	—	—	$\overline{\text{TO}}$	$\overline{\text{PD}}$	Z	$\overline{\text{DC}}^{(1)}$	$\overline{\text{C}}^{(1)}$
bit 7							
							bit 0

Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	q = Value depends on condition

bit 7-5 **Unimplemented:** Read as '0'

bit 4 **$\overline{\text{TO}}$:** Time-Out bit

1 = After power-up, `CLRWDT` instruction or `SLEEP` instruction
0 = A WDT time-out occurred

bit 3 **$\overline{\text{PD}}$:** Power-Down bit

1 = After power-up or by the `CLRWDT` instruction
0 = By execution of the `SLEEP` instruction

bit 2 **Z:** Zero bit

1 = The result of an arithmetic or logic operation is zero
0 = The result of an arithmetic or logic operation is not zero

bit 1 **$\overline{\text{DC}}$:** Digit Carry/Digit Borrow bit (`ADDWF`, `ADDLW`, `SUBLW`, `SUBWF` instructions)⁽¹⁾

1 = A carry-out from the 4th low-order bit of the result occurred
0 = No carry-out from the 4th low-order bit of the result

bit 0 **$\overline{\text{C}}$:** Carry/Borrow bit⁽¹⁾ (`ADDWF`, `ADDLW`, `SUBLW`, `SUBWF` instructions)⁽¹⁾

1 = A carry-out from the Most Significant bit of the result occurred
0 = No carry-out from the Most Significant bit of the result occurred

Note 1: For $\overline{\text{Borrow}}$, the polarity is reversed. A subtraction is executed by adding the two's complement of the second operand. For rotate (`RRF`, `RLF`) instructions, this bit is loaded with either the high-order or low-order bit of the source register.

TABLE 4-11: SPECIAL FUNCTION REGISTER SUMMARY BANKS 0-63 (CONTINUED)

Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on: POR, BOR	Value on: MCLR	
Bank 17												
CPU CORE REGISTERS; see Table 4-3 for specifics												
88Ch	CPUDOZE	IDLEN	DOZEN	ROI	DOE	—	DOZE2	DOZE1	DOZE0	0000 -000	u000 -000	
88Dh	OSCCON1	—	NOSC<2:0>			NDIV<3:0>				-q qq 0000	-q qq 0000	
88Eh	OSCCON2	—	COSC<2:0>			CDIV<3:0>				-q qq qq qq	-q qq qq qq	
88Fh	OSCCON3	CSWHOLD	SOSCPWR	—	ORDY	NOSCR	—	—	—	00-0 0---	00-0 0---	
890h	OSCSTAT	EXTOR	HFOR	MFOR	LFOR	SOR	ADOR	—	PLL	q000 qq-0	qq qq qq-q	
891h	OSCEN	EXTOEN	HFOEN	MFOEN	LFOEN	SOSCEN	ADOEN	—	—	0000 00--	0000 00--	
892h	OSCTUNE	—	—	HFTUN<5:0>						--10 0000	--10 0000	
893h	OSCFRQ	—	—	—	—	—	HFFRQ<2:0>			---- -qqq	---- -qqq	
894h	—	Unimplemented								—	—	
895h	CLKRCON	CLKREN	—	—	CLKRDC<1:0>		CLKRDIV<2:0>			0--x xxxx	0--u uuuu	
896h	CLKRCLK	—	—	—	—	CLKRCLK<3:0>					---- 0000	---- 0000
897h — 89Fh	—	Unimplemented								—	—	

Legend: x = unknown, u = unchanged, q = depends on condition, - = unimplemented, read as '0', r = reserved. Shaded locations unimplemented, read as '0'.

13.3.3 NVMREG ERASE OF PFM

Before writing to PFM, the word(s) to be written must be erased or previously unwritten. PFM can only be erased one row at a time. No automatic erase occurs upon the initiation of the write to PFM.

To erase a PFM row:

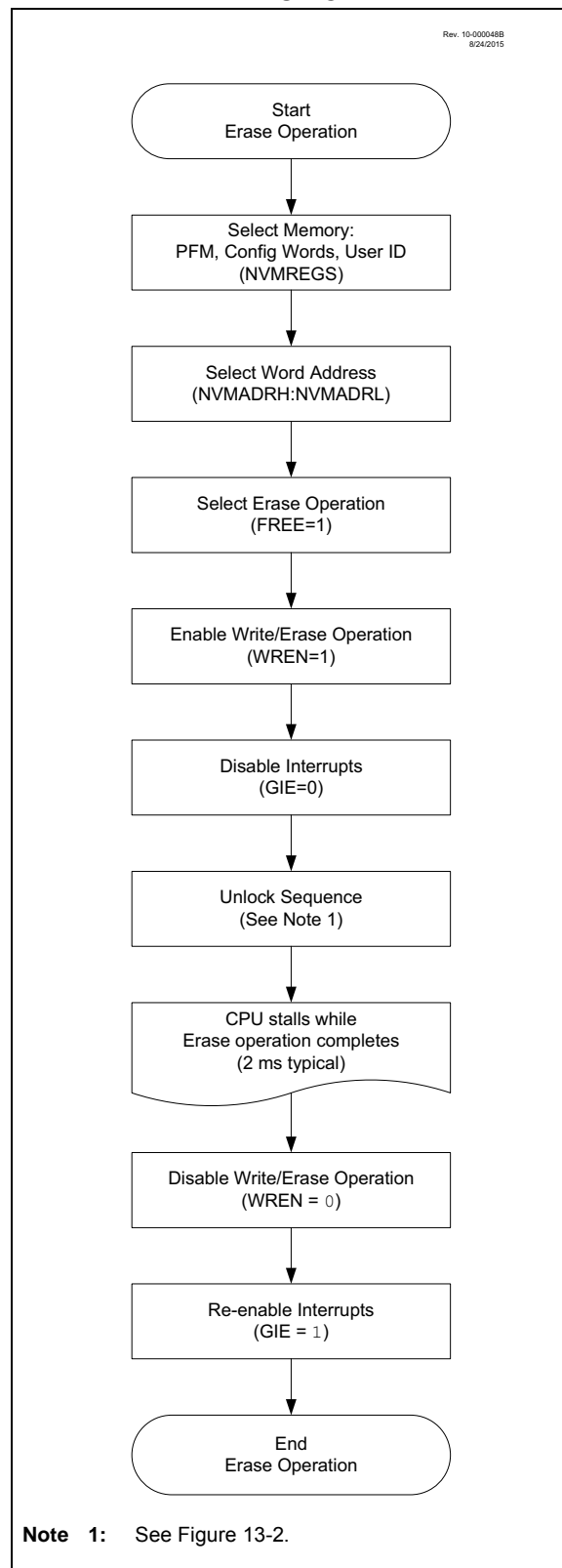
1. Clear the NVMREGS bit of the NVMCON1 register to erase PFM locations, or set the NMVREGS bit to erase User ID locations.
2. Write the desired address into the NVMADRH:NVMADRL register pair (Table 13-2).
3. Set the FREE and WREN bits of the NVMCON1 register.
4. Perform the unlock sequence as described in **Section 13.3.2 “NVM Unlock Sequence”**.

If the PFM address is write-protected, the WR bit will be cleared and the erase operation will not take place.

While erasing PFM, CPU operation is suspended, and resumes when the operation is complete. Upon completion, the NVMIF is set, and an interrupt will occur if the NVMIE bit is also set.

Write latch data is not affected by erase operations, and WREN will remain unchanged.

FIGURE 13-3: NVM ERASE FLOWCHART



14.5 Register Definitions: PORTB

REGISTER 14-9: PORTB: PORTB REGISTER

R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u
RB7	RB6	RB5	RB4	RB3	RB2	RB1	RB0
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

u = Bit is unchanged

x = Bit is unknown

-n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set

'0' = Bit is cleared

bit 7-0 **RB<7:0>**: PORTB I/O Value bits⁽¹⁾

1 = Port pin is $\geq V_{IH}$

0 = Port pin is $\leq V_{IL}$

Note 1: Writes to PORTB are actually written to corresponding LATB register. The actual I/O pin values are read from the PORTB register.

REGISTER 14-10: TRISB: PORTB TRI-STATE REGISTER

R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1
TRISB7	TRISB6	TRISB5	TRISB4	TRISB3	TRISB2	TRISB1	TRISB0
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

u = Bit is unchanged

x = Bit is unknown

-n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set

'0' = Bit is cleared

bit 7-0 **TRISB<7:0>**: PORTB Tri-State Control bit

1 = PORTB pin configured as an input (tri-stated)

0 = PORTB pin configured as an output

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TABLE 15-2: PPS INPUT SIGNAL ROUTING OPTIONS (PIC16(L)F15375/76)

INPUT SIGNAL NAME	Input Register Name	Default Location at POR	Reset Value (xxxPPS<4:0>)	Remappable to Pins of PORTx			
				PIC16(L)F15375/76			
				PORTA	PORTB	PORTC	PORTD
INT	INTPPS	RB0	01000	•	•		
T0CKI	T0CKIPPS	RA4	00100	•	•		
T1CKI	T1CKIPSS	RC0	10000	•		•	
T1G	T1GPPS	RB5	01101		•	•	
T2IN	T2INPPS	RC3	10011	•		•	
CCP1	CCP1PPS	RC2	10010		•	•	
CCP2	CCP2PPS	RC1	10001		•	•	
CWG1IN	CWG1INPPS	RB0	01000		•		•
CLCIN0	CLCIN0PPS	RA0	00000	•		•	
CLCIN1	CLCIN1PPS	RA1	00001	•		•	
CLCIN2	CLCIN2PPS	RB6	01110		•		•
CLCIN3	CLCIN3PPS	RB7	01111		•		•
ADACT	ADACTPPS	RB4	01100		•		•
SCK1/SCL1	SSP1CLKPPS	RC3	10011		•	•	
SDI1/SDA1	SSP1DATPPS	RC4	10100		•	•	
SS1	SSP1SS1PPS	RA5	00101	•			•
SCK2/SCL2	SSP2CLKPPS	RB1	01001		•		•
SDI2/SDA2	SSP2DATPPS	RB2	01010		•		•
SS2	SSP2SSPPS	RB0	01000		•		•
RX1/DT1	RX1PPS	RC7	10111		•	•	
CK1	TX1PPS	RC6	10110		•	•	
RX2/DT2	RX2PPS	RB7	01111		•		•
CK2	TX2PPS	RB6	01110		•		•

19.0 TEMPERATURE INDICATOR MODULE

This family of devices is equipped with a temperature circuit designed to measure the operating temperature of the silicon die. The main purpose of the temperature indicator module is to provide a temperature-dependent voltage that can be measured by the Analog-to-Digital Converter.

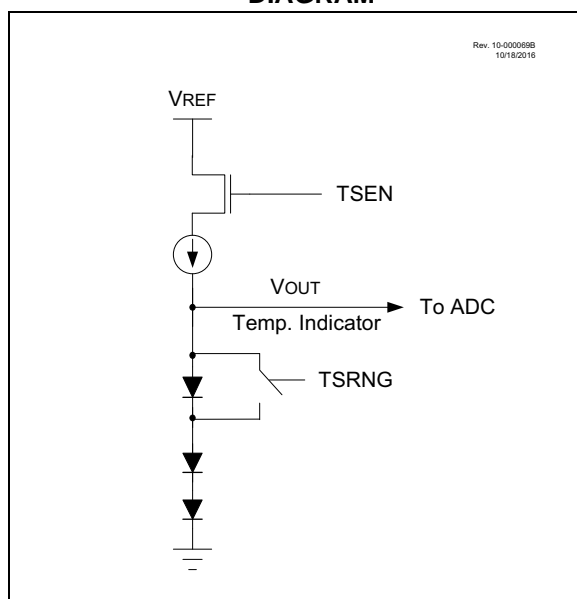
The circuit's range of operating temperature falls between -40°C and +125°C. The circuit may be used as a temperature threshold detector or a more accurate temperature indicator, depending on the level of calibration performed. A one-point calibration allows the circuit to indicate a temperature closely surrounding that point. A two-point calibration allows the circuit to sense the entire range of temperature more accurately.

19.1 Module Operation

The temperature indicator module consists of a temperature-sensing circuit that provides a voltage to the device ADC. The analog voltage output, VTSENSE, is measured and the corresponding temperature is determined. Equation 19-1 provides an estimate for the die temperature based on the VTSENSE value.

Figure 19-1 shows a simplified block diagram of the temperature indicator module.

FIGURE 19-1: TEMPERATURE INDICATOR BLOCK DIAGRAM



The output of the circuit is measured using the internal Analog-to-Digital Converter. A channel is reserved for the temperature circuit output. Refer to **Section 20.0 “Analog-to-Digital Converter (ADC) Module”** for detailed information.

The ON/OFF bit for the module is located in the FVRCON register. See **Section 18.0 “Fixed Voltage Reference (FVR)”** for more information. The circuit is enabled by setting the TSEN bit of the FVRCON register. When the module is disabled, the circuit draws no current.

The circuit operates in either High or Low range. Refer to **Section 19.5 “Temperature Indicator Range”** for more details on the range settings.

19.2 Estimation of Temperature

This section describes how the sensor voltage can be used to estimate the temperature of the module. To use the sensor, the output voltage, VTSENSE, is measured and the corresponding temperature is determined. Equation 19-1 provides an estimate for the die temperature based on the VTSENSE value.

EQUATION 19-1: SENSOR TEMPERATURE

$$T_{SENSE} = V_{TSENSE} \times (-Mt) + T_{OFFSET}$$

Where:

Mt = 1/Mv, where Mv = sensor voltage sensitivity (V/°C).

TOFFSET is the temperature difference between the theoretical temperature and the actual temperature.

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20.4 Register Definitions: ADC Control

REGISTER 20-1: ADCON0: ADC CONTROL REGISTER 0

R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
CHS<5:0>						GO/DONE	ADON
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

u = Bit is unchanged

x = Bit is unknown

-n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set

'0' = Bit is cleared

bit 7-2

CHS<5:0>: Analog Channel Select bits

111111 = FVR Buffer 2 reference voltage⁽²⁾
 111110 = FVR 1 Buffer 1 reference voltage⁽²⁾
 111101 = DAC1 output voltage⁽¹⁾
 111100 = Temperature sensor output⁽³⁾
 111011 = AVss (Analog Ground)
 111010-100000 = Reserved. No channel connected
 101111 = RF7
 101110 = RF6
 101101 = RF5
 101100 = RF4
 101011 = RF3
 101010 = RF2
 101001 = RF1
 101000 = RF0
 100010 = RE2
 100001 = RE1
 100000 = RE0
 011111 = RD7
 011110 = RD6
 011101 = RD5
 011100 = RD4
 011011 = RD3
 011010 = RD2
 011001 = RD1
 011000 = RD0
 010111 = RC7⁽⁴⁾
 010110 = RC6⁽⁴⁾
 010101 = RC5
 010100 = RC4
 010011 = RC3
 010010 = RC2
 010001 = RC1
 010000 = RC0
 001111 = RB7⁽⁴⁾
 001110 = RB6⁽⁴⁾
 001101 = RB5⁽⁴⁾
 001100 = RB4⁽⁴⁾
 001011-000110 = Reserved
 000101 = RA5
 000100 = RA4
 000011 = RA3
 000010 = RA2
 000001 = RA1
 000000 = RA0

bit 1

GO/DONE: ADC Conversion Status bit

1 = ADC conversion cycle in progress. Setting this bit starts an ADC conversion cycle.

This bit is automatically cleared by hardware when the ADC conversion has completed.

0 = ADC conversion completed/not in progress

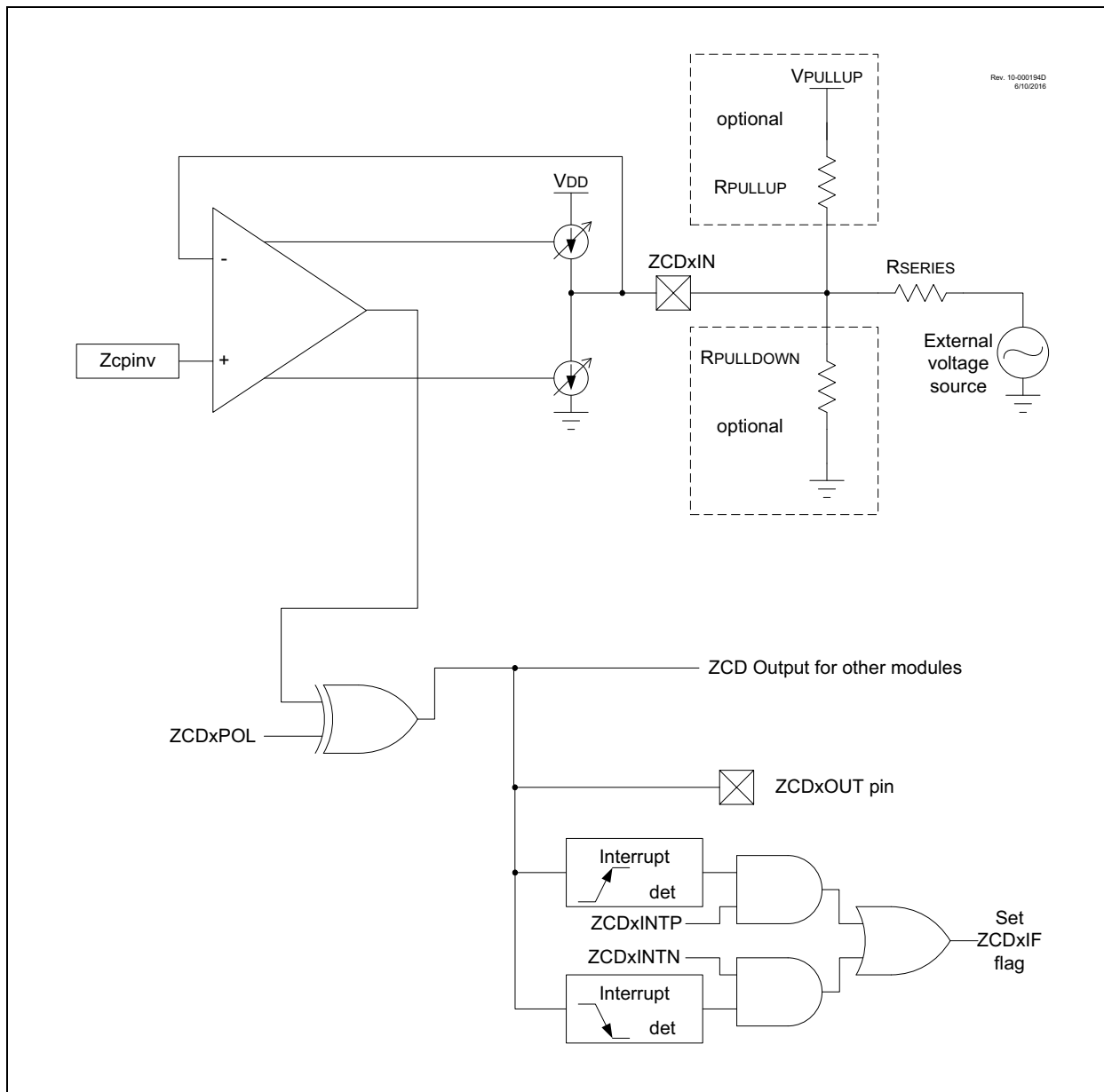
PIC16(L)F15356/75/76/85/86

TABLE 21-1: SUMMARY OF REGISTERS ASSOCIATED WITH THE DAC1 MODULE

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register on page
DAC1CON0	DAC1EN	—	DAC1OE1	DAC1OE2	DAC1PSS<1:0>		—	DAC1NSS	287
DAC1CON1	—	—	—	DAC1R<4:0>					287
CM1PSEL	—	—	—	—	—	PCH<2:0>			307
CM2PSEL	—	—	—	—	—	PCH<2:0>			307

Legend: — = Unimplemented location, read as '0'. Shaded cells are not used with the DAC module.

FIGURE 24-2: SIMPLIFIED ZCD BLOCK DIAGRAM



25.0 TIMER0 MODULE

The Timer0 module is an 8/16-bit timer/counter with the following features:

- 16-bit timer/counter
- 8-bit timer/counter with programmable period
- Synchronous or asynchronous operation
- Selectable clock sources
- Programmable prescaler (independent of Watchdog Timer)
- Programmable postscaler
- Operation during Sleep mode
- Interrupt on match or overflow
- Output on I/O pin (via PPS) or to other peripherals

25.1 Timer0 Operation

Timer0 can operate as either an 8-bit timer/counter or a 16-bit timer/counter. The mode is selected with the T016BIT bit of the T0CON register.

25.1.1 16-BIT MODE

In normal operation, TMR0 increments on the rising edge of the clock source. A 15-bit prescaler on the clock input gives several prescale options (see prescaler control bits, T0CKPS<3:0> in the T0CON1 register).

25.1.1.1 Timer0 Reads and Writes in 16-Bit Mode

TMR0H is not the actual high byte of Timer0 in 16-bit mode. It is actually a buffered version of the real high byte of Timer0, which is neither directly readable nor writable (see Figure 25-1). TMR0H is updated with the contents of the high byte of Timer0 during a read of TMR0L. This provides the ability to read all 16 bits of Timer0 without having to verify that the read of the high and low byte was valid, due to a rollover between successive reads of the high and low byte.

Similarly, a write to the high byte of Timer0 must also take place through the TMR0H Buffer register. The high byte is updated with the contents of TMR0H when a write occurs to TMR0L. This allows all 16 bits of Timer0 to be updated at once.

25.1.2 8-BIT MODE

In normal operation, TMR0 increments on the rising edge of the clock source. A 15-bit prescaler on the clock input gives several prescale options (see prescaler control bits, T0CKPS<3:0> in the T0CON1 register).

The value of TMR0L is compared to that of the Period buffer, a copy of TMR0H, on each clock cycle. When the two values match, the following events happen:

- TMR0_out goes high for one prescaled clock period
- TMR0L is reset
- The contents of TMR0H are copied to the period buffer

In 8-bit mode, the TMR0L and TMR0H registers are both directly readable and writable. The TMR0L register is cleared on any device Reset, while the TMR0H register initializes at FFh.

Both the prescaler and postscaler counters are cleared on the following events:

- A write to the TMR0L register
- A write to either the T0CON0 or T0CON1 registers
- Any device Reset – Power-on Reset (POR), MCLR Reset, Watchdog Timer Reset (WDTR) or Brown-out Reset (BOR)

25.1.3 COUNTER MODE

In Counter mode, the prescaler is normally disabled by setting the T0CKPS bits of the T0CON1 register to '0000'. Each rising edge of the clock input (or the output of the prescaler if the prescaler is used) increments the counter by '1'.

25.1.4 TIMER MODE

In Timer mode, the Timer0 module will increment every instruction cycle as long as there is a valid clock signal and the T0CKPS bits of the T0CON1 register (Register 25-2) are set to '0000'. When a prescaler is added, the timer will increment at the rate based on the prescaler value.

25.1.5 ASYNCHRONOUS MODE

When the T0ASYNC bit of the T0CON1 register is set (T0ASYNC = '1'), the counter increments with each rising edge of the input source (or output of the prescaler, if used). Asynchronous mode allows the counter to continue operation during Sleep mode provided that the clock also continues to operate during Sleep.

25.1.6 SYNCHRONOUS MODE

When the T0ASYNC bit of the T0CON1 register is clear (T0ASYNC = 0), the counter clock is synchronized to the system oscillator (Fosc/4). When operating in Synchronous mode, the counter clock frequency cannot exceed Fosc/4.

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REGISTER 26-4: T1GATE TIMER1 GATE SELECT REGISTER

U-0	U-0	U-0	R/W-0/u	R/W-0/u	R/W-0/u	R/W-0/u	R/W-0/u
—	—	—	GSS<4:0>				
bit 7			bit 0				

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

u = Bit is unchanged

x = Bit is unknown

-n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set

'0' = Bit is cleared

HC = Bit is cleared by hardware

bit 7-5 **Unimplemented:** Read as '0'

bit 4-0 **GSS<4:0>:** Timer1 Gate Select bits

11111-10001 = Reserved

10000 = LC4_out

01111 = LC3_out

01110 = LC2_out

01101 = LC1_out

00100 = ZCD1_output

01011 = C2OUT_sync

01010 = C1OUT_sync

01001 = NCO1_out

01000 = PWM6_out

00111 = PWM5_out

00110 = PWM4_out

00101 = PWM3_out

00100 = CCP2_out

00011 = CCP1_out

00010 = TMR2_postscaled

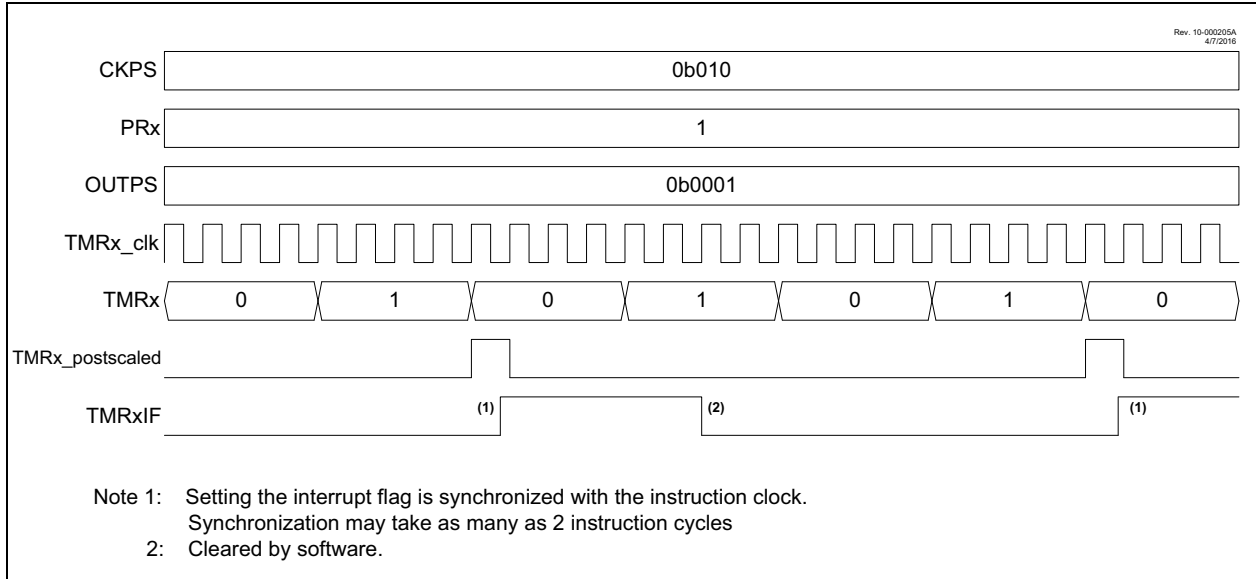
00001 = Timer0 overflow output

00000 = T1GPPS

27.4 Timer2 Interrupt

Timer2 can also generate a device interrupt. The interrupt is generated when the postscaler counter matches one of 16 postscale options (from 1:1 through 1:16), which are selected with the postscaler control bits, OUTPS<3:0> of the T2CON register. The interrupt is enabled by setting the TMR2IE interrupt enable bit of the PIE4 register. Interrupt timing is illustrated in Figure 27-3.

FIGURE 27-3: TIMER2 PRESCALER, POSTSCALER, AND INTERRUPT TIMING DIAGRAM



27.5.7 EDGE-TRIGGERED HARDWARE LIMIT ONE-SHOT MODE

In Edge-Triggered Hardware Limit One-Shot modes the timer starts on the first external signal edge after the ON bit is set and resets on all subsequent edges. Only the first edge after the ON bit is set is needed to start the timer. The counter will resume counting automatically two clocks after all subsequent external Reset edges. Edge triggers are as follows:

- Rising edge start and Reset
(MODE<4:0> = 01100)
- Falling edge start and Reset
(MODE<4:0> = 01101)

The timer resets and clears the ON bit when the timer value matches the PRx period value. External signal edges will have no effect until after software sets the ON bit. Figure 27-10 illustrates the rising edge hardware limit one-shot operation.

When this mode is used in conjunction with the CCP then the first starting edge trigger, and all subsequent Reset edges, will activate the PWM drive. The PWM drive will deactivate when the timer matches the CCPRx pulse-width value and stay deactivated until the timer halts at the PRx period match unless an external signal edge resets the timer before the match occurs.

27.6 Timer2 Operation During Sleep

When PSYNC = 1, Timer2 cannot be operated while the processor is in Sleep mode. The contents of the TMR2 and T2PR registers will remain unchanged while processor is in Sleep mode.

When PSYNC = 0, Timer2 will operate in Sleep as long as the clock source selected is also still running. Selecting the LFINTOSC, MFINTOSC, or HFINTOSC oscillator as the timer clock source will keep the selected oscillator running during Sleep.

32.2.3 SPI MASTER MODE

The master can initiate the data transfer at any time because it controls the SCK line. The master determines when the slave (Processor 2, Figure 32-5) is to broadcast data by the software protocol.

In Master mode, the data is transmitted/received as soon as the SSPxBUF register is written to. If the SPI is only going to receive, the SDO output could be disabled (programmed as an input). The SSPxSR register will continue to shift in the signal present on the SDI pin at the programmed clock rate. As each byte is received, it will be loaded into the SSPxBUF register as if a normal received byte (interrupts and Status bits appropriately set).

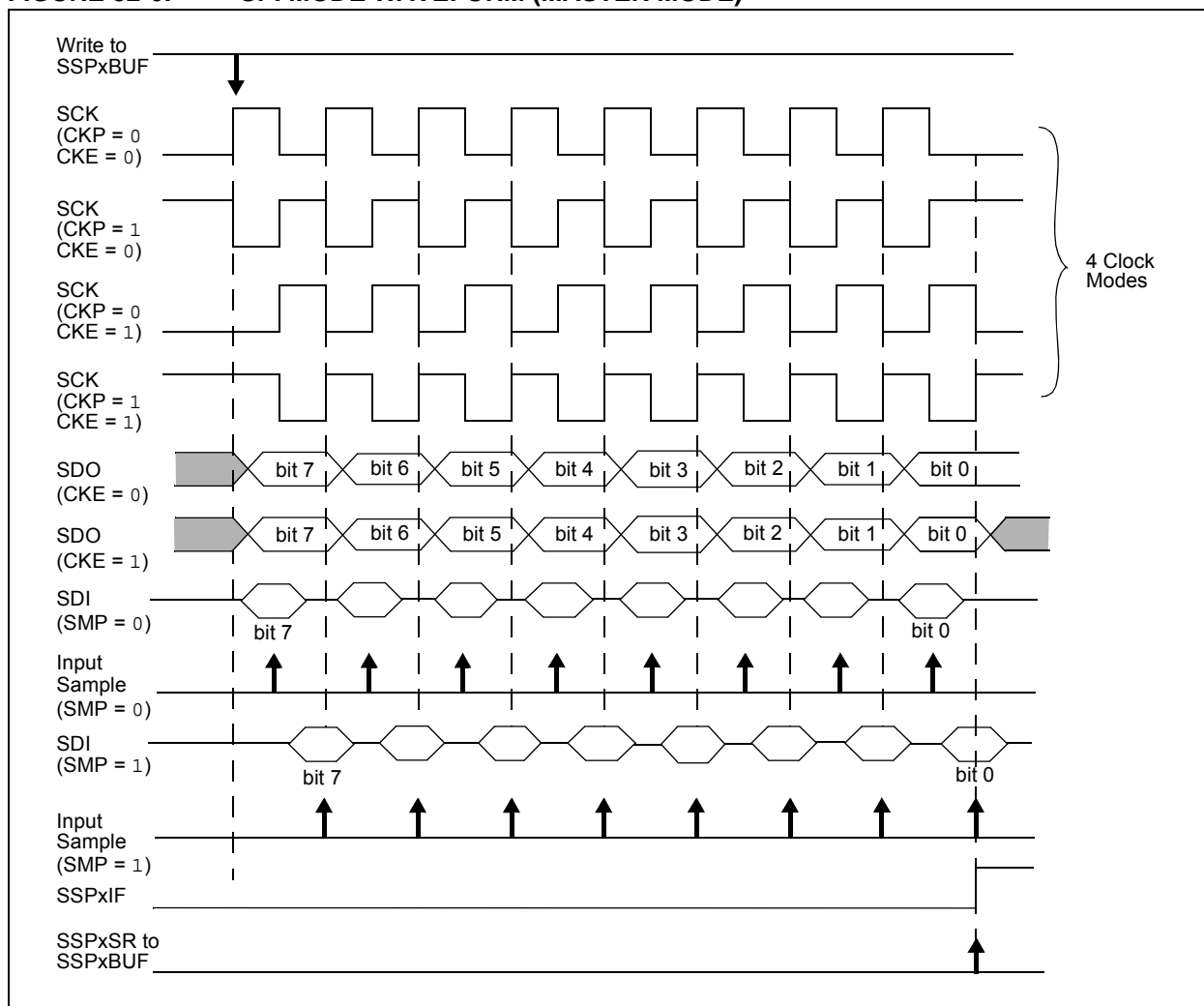
The clock polarity is selected by appropriately programming the CKP bit of the SSPxCON1 register and the CKE bit of the SSPxSTAT register. This then, would give waveforms for SPI communication as shown in Figure 32-6, Figure 32-8, Figure 32-9 and Figure 32-10, where the MSB is transmitted first. In Master mode, the SPI clock rate (bit rate) is user programmable to be one of the following:

- $F_{osc}/4$ (or T_{CY})
- $F_{osc}/16$ (or $4 * T_{CY}$)
- $F_{osc}/64$ (or $16 * T_{CY}$)
- Timer2 output/2
- $F_{osc}/(4 * (SSPxADD + 1))$

Figure 32-6 shows the waveforms for Master mode.

When the CKE bit is set, the SDO data is valid before there is a clock edge on SCK. The change of the input sample is shown based on the state of the SMP bit. The time when the SSPxBUF is loaded with the received data is shown.

FIGURE 32-6: SPI MODE WAVEFORM (MASTER MODE)



32.6 I²C Master Mode

Master mode is enabled by setting and clearing the appropriate SSPM bits in the SSPxCON1 register and by setting the SSPEN bit. In Master mode, the SDA and SCK pins must be configured as inputs. The MSSP peripheral hardware will override the output driver TRIS controls when necessary to drive the pins low.

Master mode of operation is supported by interrupt generation on the detection of the Start and Stop conditions. The Stop (P) and Start (S) bits are cleared from a Reset or when the MSSP module is disabled. Control of the I²C bus may be taken when the P bit is set, or the bus is Idle.

In Firmware Controlled Master mode, user code conducts all I²C bus operations based on Start and Stop bit condition detection. Start and Stop condition detection is the only active circuitry in this mode. All other communication is done by the user software directly manipulating the SDA and SCL lines.

The following events will cause the SSP Interrupt Flag bit, SSPxIF, to be set (SSP interrupt, if enabled):

- Start condition generated
- Stop condition generated
- Data transfer byte transmitted/received
- Acknowledge transmitted/received
- Repeated Start generated

Note 1: The MSSP module, when configured in I²C Master mode, does not allow queuing of events. For instance, the user is not allowed to initiate a Start condition and immediately write the SSPxBUF register to initiate transmission before the Start condition is complete. In this case, the SSPxBUF will not be written to and the WCOL bit will be set, indicating that a write to the SSPxBUF did not occur

2: When in Master mode, Start/Stop detection is masked and an interrupt is generated when the SEN/PEN bit is cleared and the generation is complete.

32.6.1 I²C MASTER MODE OPERATION

The master device generates all of the serial clock pulses and the Start and Stop conditions. A transfer is ended with a Stop condition or with a Repeated Start condition. Since the Repeated Start condition is also the beginning of the next serial transfer, the I²C bus will not be released.

In Master Transmitter mode, serial data is output through SDA, while SCL outputs the serial clock. The first byte transmitted contains the slave address of the receiving device (7 bits) and the Read/Write (R/W) bit. In this case, the R/W bit will be logic '0'. Serial data is transmitted eight bits at a time. After each byte is transmitted, an Acknowledge bit is received. Start and Stop conditions are output to indicate the beginning and the end of a serial transfer.

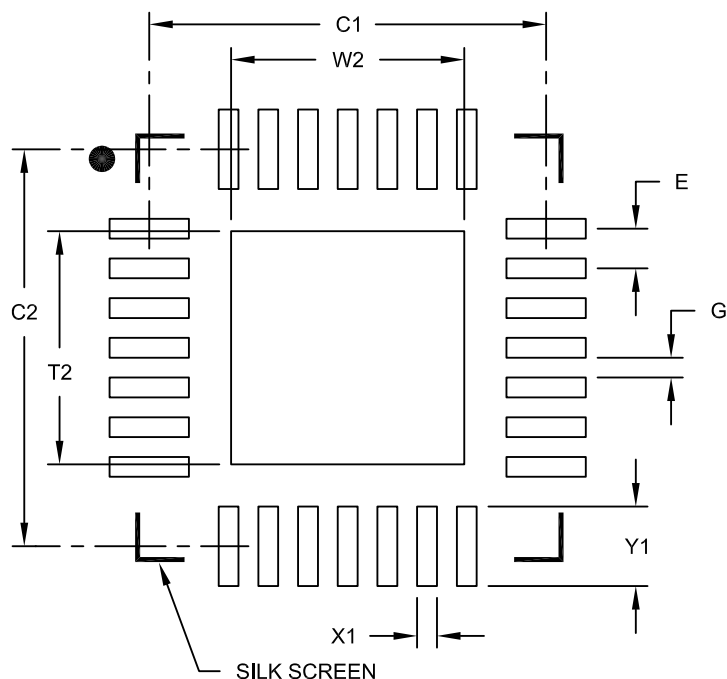
In Master Receive mode, the first byte transmitted contains the slave address of the transmitting device (7 bits) and the R/W bit. In this case, the R/W bit will be logic '1'. Thus, the first byte transmitted is a 7-bit slave address followed by a '1' to indicate the receive bit. Serial data is received via SDA, while SCL outputs the serial clock. Serial data is received eight bits at a time. After each byte is received, an Acknowledge bit is transmitted. Start and Stop conditions indicate the beginning and end of transmission.

A Baud Rate Generator is used to set the clock frequency output on SCL. See **Section 32.7 "Baud Rate Generator"** for more detail.

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28-Lead Ultra Thin Plastic Quad Flat, No Lead Package (MV) - 4x4 mm Body [UQFN]
With 0.40 mm Contact Length

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



RECOMMENDED LAND PATTERN

Dimension Limits	Units	MILLIMETERS		
		MIN	NOM	MAX
Contact Pitch	E	0.40 BSC		
Optional Center Pad Width	W2			2.35
Optional Center Pad Length	T2			2.35
Contact Pad Spacing	C1		4.00	
Contact Pad Spacing	C2		4.00	
Contact Pad Width (X28)	X1			0.20
Contact Pad Length (X28)	Y1			0.80
Distance Between Pads	G	0.20		

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

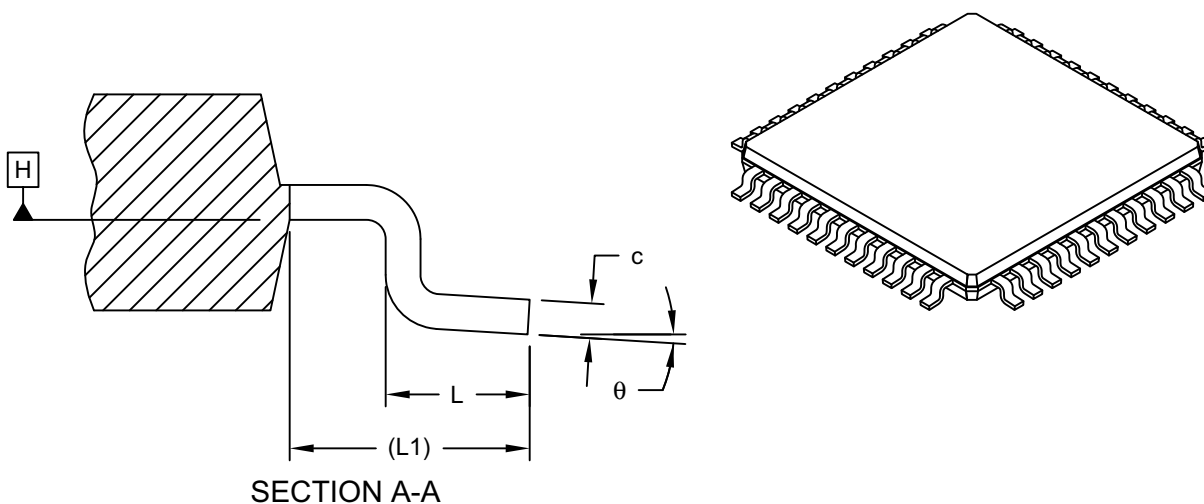
BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2152A

PIC16(L)F15356/75/76/85/86

44-Lead Plastic Thin Quad Flatpack (PT) - 10x10x1.0 mm Body [TQFP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Dimension	Units	MILLIMETERS		
		MIN	NOM	MAX
Number of Leads	N	44		
Lead Pitch	e	0.80 BSC		
Overall Height	A	-	-	1.20
Standoff	A1	0.05	-	0.15
Molded Package Thickness	A2	0.95	1.00	1.05
Overall Width	E	12.00 BSC		
Molded Package Width	E1	10.00 BSC		
Overall Length	D	12.00 BSC		
Molded Package Length	D1	10.00 BSC		
Lead Width	b	0.30	0.37	0.45
Lead Thickness	c	0.09	-	0.20
Lead Length	L	0.45	0.60	0.75
Footprint	L1	1.00 REF		
Foot Angle	θ	0°	3.5°	7°

Notes:

- Pin 1 visual index feature may vary, but must be located within the hatched area.
- Exact shape of each corner is optional.
- Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-076C Sheet 2 of 2