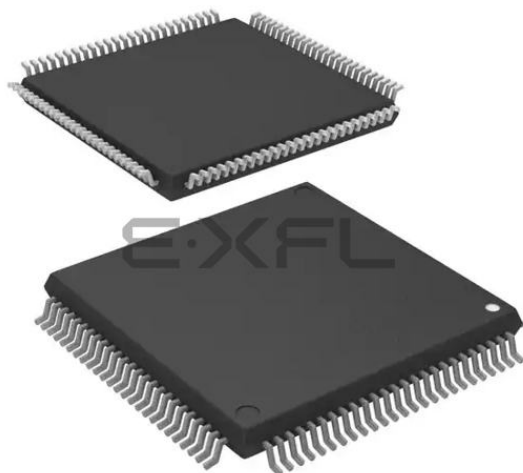




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What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Obsolete
Core Processor	R32C/100
Core Size	16/32-Bit
Speed	50MHz
Connectivity	CANbus, EBI/EMI, I ² C, IEBus, UART/USART
Peripherals	DMA, LVD, PWM, WDT
Number of I/O	84
Program Memory Size	640KB (640K x 8)
Program Memory Type	FLASH
EEPROM Size	8K x 8
RAM Size	48K x 8
Voltage - Supply (Vcc/Vdd)	3V ~ 5.5V
Data Converters	A/D 26x10b; D/A 2x8b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	100-LQFP
Supplier Device Package	100-LFQFP (14x14)
Purchase URL	https://www.e-xfl.com/product-detail/renesas-electronics-america/r5f64177dfb-ub

Table 1.2 Performance Overview for the 144-pin Package (2/2)

Unit	Function	Explanation
Timer	Timer A	16-bit timer × 5 Timer mode, event counter mode, one-shot timer mode, pulse-width modulation (PWM) mode Two-phase pulse signal processing in event counter mode (two-phase encoder input) × 3
	Timer B	16-bit timer × 6 Timer mode, event counter mode, pulse frequency measurement mode, pulse-width measurement mode
	Three-phase motor control timer	Three-phase motor control timer × 1 (timers A1, A2, A4, and B2 used) 8-bit programmable dead time timer
Serial Interface	UART0 to UART8	Asynchronous/synchronous serial interface × 9 channels • I ² C-bus (UART0 to UART6) • Special mode 2 (UART0 to UART6) • IEBus (optional ⁽¹⁾) (UART0 to UART6)
A/D Converter		10-bit resolution × 34 channels Sample and hold functionality integrated
D/A Converter		8-bit resolution × 2
CRC Calculator		CRC-CCITT ($X^{16} + X^{12} + X^5 + 1$)
X-Y Converter		16 bits × 16 bits
Intelligent I/O		Time measurement (input capture): 16 bits × 16 Waveform generation (output compare): 16 bits × 24 Serial interface: Variable-length synchronous serial I/O mode, IEBus mode (optional ⁽¹⁾)
Multi-master I ² C-bus Interface		1 channel
CAN Module		1 channel CAN functionality compliant with ISO 11898-1 32 mailboxes
Flash Memory		Programming and erasure supply voltage: VCC = 3.0 to 5.5 V Minimum endurance: 1,000 program/erase cycles Security protection: ROM code protect, ID code protect Debugging: On-chip debug, on-board flash programming
Operating Frequency/Supply Voltage		64 MHz (high speed version)/VCC = 3.0 to 5.5 V 50 MHz (normal speed version)/VCC = 3.0 to 5.5 V
Operating Temperature		-20°C to 85°C (N version) -40°C to 85°C (D version) -40°C to 85°C (P version)
Current Consumption		45 mA (VCC = 5.0 V, f(CPU) = 64 MHz) 35 mA (VCC = 5.0 V, f(CPU) = 50 MHz) 8 µA (VCC = 3.3 V, f(XCIN) = 32.768 kHz, in wait mode)
Package		144-pin plastic molded LQFP (PLQP0144KA-A)

Note:

1. Contact a Renesas Electronics sales office to use the optional features.

Table 1.3 Performance Overview for the 100-pin Package (1/2)

Unit	Function	Explanation
CPU	Central processing unit	R32C/100 Series CPU Core • Basic instructions: 108 • Minimum instruction execution time: 15.625 ns ($f(\text{CPU}) = 64 \text{ MHz}$) • Multiplier: 32-bit $\times$ 32-bit $\rightarrow$ 64-bit • Multiply-accumulate unit: 32-bit $\times$ 32-bit + 64-bit $\rightarrow$ 64-bit • IEEE-754 compatible FPU: Single precision • 32-bit barrel shifter • Operating mode: Single-chip mode, memory expansion mode, microprocessor mode (optional ⁽¹⁾)
Memory		Flash memory: 128 Kbytes to 1 Mbyte RAM: 20 K/40 K/48 K/63 Kbytes Data flash: 4 Kbytes $\times$ 2 blocks Refer to Table 1.5 for each product's memory size
Voltage Detector	Low voltage detector	Optional ⁽¹⁾ Low voltage detection interrupt
Clock	Clock generator	• 4 circuits (main clock, sub clock, PLL, on-chip oscillator) • Oscillation stop detector: Main clock oscillator stop/restart detection • Frequency divide circuit: Divide-by-2 to divide-by-24 selectable • Low power modes: Wait mode, stop mode
External Bus Expansion	Bus and memory expansion	• Address space: 4 Gbytes (of which up to 64 Mbytes is user accessible) • External bus Interface: Support for wait-state insertion, 4 chip select outputs • Bus format: Separate bus/Multiplexed bus selectable, data bus width selectable (8/16 bits)
Interrupts		Interrupt vectors: 261 External interrupt inputs: $\overline{\text{NMI}}$, $\overline{\text{INT}} \times 6$, key input $\times 4$ Interrupt priority levels: 7
Watchdog Timer		15 bits $\times$ 1 (selectable input frequency from prescaler output)
DMA	DMAC	4 channels • Cycle-steal transfer mode • Request sources: 51 • 2 transfer modes: Single transfer, repeat transfer
	DMAC II	• Triggered by an interrupt request of any peripheral • 3 characteristic transfer functions: Immediate data transfer, calculation result transfer, chain transfer
I/O Ports	Programmable I/O ports	• 2 input-only ports • 84 CMOS I/O ports (of which 32 are 5 V tolerant) • A pull-up resistor is selectable for every 4 input ports (except 5 V tolerant inputs)

Note:

1. Contact a Renesas Electronics sales office to use the optional features.

1.4 Pin Assignments

Figures 1.3 and 1.4 show the pin assignments (top view) and Tables 1.7 to 1.13 list the pin characteristics.

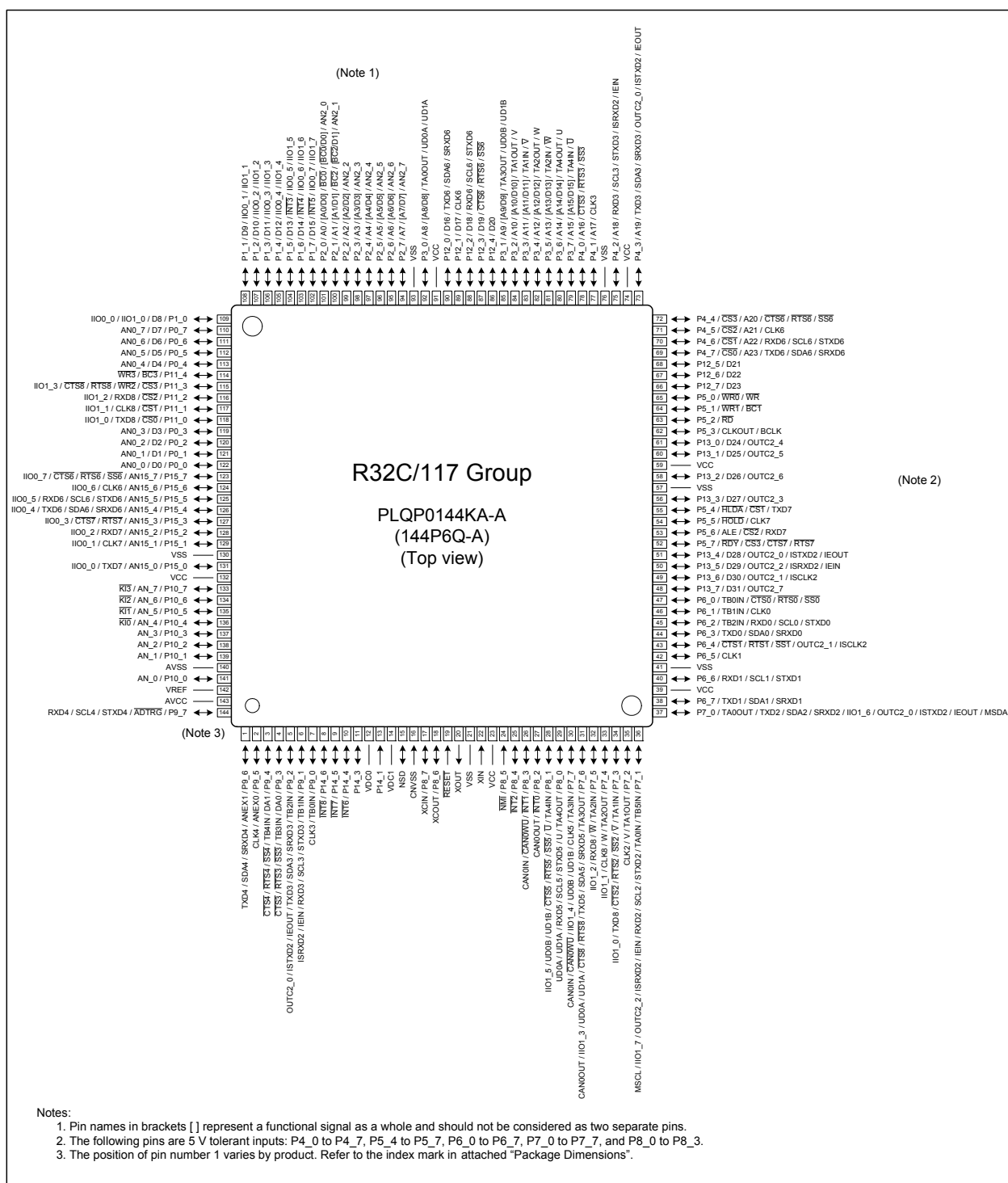


Figure 1.3 Pin Assignment for the 144-pin Package (top view)

Table 1.8 Pin Characteristics for the 144-pin Package (2/4)

Pin No.	Control Pin	Port	Interrupt Pin	Timer Pin	UART/CAN Module Pin	Intelligent I/O Pin	Analog Pin	Bus Control Pin
37		P7_0		TA0OUT	TXD2/SDA2/SRXD2/ MSDA	IIO1_6/OUTC2_0/ ISTXD2/IEOUT		
38		P6_7			TXD1/SDA1/SRXD1			
39	VCC							
40		P6_6			RXD1/SCL1/STXD1			
41	VSS							
42		P6_5			CLK1			
43		P6_4			CTS1/RTS1/SS1	OUTC2_1/ISCLK2		
44		P6_3			TXD0/SDA0/SRXD0			
45		P6_2		TB2IN	RXD0/SCL0/STXD0			
46		P6_1		TB1IN	CLK0			
47		P6_0		TB0IN	CTS0/RTS0/SS0			
48		P13_7				OUTC2_7		D31
49		P13_6				OUTC2_1/ISCLK2		D30
50		P13_5				OUTC2_2/ISRXD2/ IEIN		D29
51		P13_4				OUTC2_0/ISTXD2/ IEOUT		D28
52		P5_7			CTS7/RTS7			RDY/CS3
53		P5_6			RXD7			ALE/CS2
54		P5_5			CLK7			HOLD
55		P5_4			TXD7			HLDA/CS1
56		P13_3				OUTC2_3		D27
57	VSS							
58		P13_2				OUTC2_6		D26
59	VCC							
60		P13_1				OUTC2_5		D25
61		P13_0				OUTC2_4		D24
62		P5_3						CLKOUT/ BCLK
63		P5_2						RD
64		P5_1						WR1/BC1
65		P5_0						WR0/WR
66		P12_7						D23
67		P12_6						D22
68		P12_5						D21
69		P4_7			TXD6/SDA6/SRXD6			CS0/A23
70		P4_6			RXD6/SCL6/STXD6			CS1/A22
71		P4_5			CLK6			CS2/A21
72		P4_4			CTS6/RTS6/SS6			CS3/A20
73		P4_3			TXD3/SDA3/SRXD3	OUTC2_0/ISTXD2/ IEOUT		A19
74	VCC							

Table 1.9 Pin Characteristics for the 144-pin Package (3/4)

Pin No.	Control Pin	Port	Interrupt Pin	Timer Pin	UART/CAN Module Pin	Intelligent I/O Pin	Analog Pin	Bus Control Pin
75		P4_2			RXD3/SCL3/STXD3	ISRXD2/IEIN		A18
76	VSS							
77		P4_1			CLK3			A17
78		P4_0			CTS3/RTS3/SS3			A16
79		P3_7		TA4IN/U				A15(/D15)
80		P3_6		TA4OUT/U				A14(/D14)
81		P3_5		TA2IN/W				A13(/D13)
82		P3_4		TA2OUT/W				A12(/D12)
83		P3_3		TA1IN/V				A11(/D11)
84		P3_2		TA1OUT/V				A10(/D10)
85		P3_1		TA3OUT		UD0B/UD1B		A9(/D9)
86		P12_4						D20
87		P12_3			CTS6/RTS6/SS6			D19
88		P12_2			RXD6/SCL6/STXD6			D18
89		P12_1			CLK6			D17
90		P12_0			TXD6/SDA6/SRXD6			D16
91	VCC							
92		P3_0		TA0OUT		UD0A/UD1A		A8(/D8)
93	VSS							
94		P2_7					AN2_7	A7(/D7)
95		P2_6					AN2_6	A6(/D6)
96		P2_5					AN2_5	A5(/D5)
97		P2_4					AN2_4	A4(/D4)
98		P2_3					AN2_3	A3(/D3)
99		P2_2					AN2_2	A2(/D2)
100		P2_1					AN2_1	A1(/D1)/ BC2(/D1)
101		P2_0					AN2_0	A0(/D0)/ BC0(/D0)
102		P1_7	INT5			IIO0_7/IIO1_7		D15
103		P1_6	INT4			IIO0_6/IIO1_6		D14
104		P1_5	INT3			IIO0_5/IIO1_5		D13
105		P1_4				IIO0_4/IIO1_4		D12
106		P1_3				IIO0_3/IIO1_3		D11
107		P1_2				IIO0_2/IIO1_2		D10
108		P1_1				IIO0_1/IIO1_1		D9
109		P1_0				IIO0_0/IIO1_0		D8
110		P0_7					AN0_7	D7
111		P0_6					AN0_6	D6
112		P0_5					AN0_5	D5
113		P0_4					AN0_4	D4
114		P11_4						BC3/WR3

Table 1.13 Pin Characteristics for the 100-pin Package (3/3)

Pin No.	Control Pin	Port	Interrupt Pin	Timer Pin	UART/CAN Module Pin	Intelligent I/O Pin	Analog Pin	Bus Control Pin
76		P1_2				IIO0_2/IIO1_2		D10
77		P1_1				IIO0_1/IIO1_1		D9
78		P1_0				IIO0_0/IIO1_0		D8
79		P0_7					AN0_7	D7
80		P0_6					AN0_6	D6
81		P0_5					AN0_5	D5
82		P0_4					AN0_4	D4
83		P0_3					AN0_3	D3
84		P0_2					AN0_2	D2
85		P0_1					AN0_1	D1
86		P0_0					AN0_0	D0
87		P10_7	KI3				AN_7	
88		P10_6	KI2				AN_6	
89		P10_5	KI1				AN_5	
90		P10_4	KI0				AN_4	
91		P10_3					AN_3	
92		P10_2					AN_2	
93		P10_1					AN_1	
94	AVSS							
95		P10_0					AN_0	
96	VREF							
97	AVCC							
98		P9_7			RXD4/SCL4/STXD4		ADTRG	
99		P9_6			TXD4/SDA4/SRXD4		ANEX1	
100		P9_5			CLK4		ANEX0	

2.1 General Purpose Registers

2.1.1 Data Registers (R2R0, R3R1, R6R4, and R7R5)

These 32-bit registers are primarily used for transfers and arithmetic/logic operations.

Each of the registers can be divided into upper and lower 16-bit registers, e.g. R2R0 can be divided into R2 and R0, R3R1 can be divided into R3 and R1, etc.

Moreover, data registers R2R0 and R3R1 can be divided into four 8-bit data registers: upper (R2H and R3H), mid-upper (R2L and R3L), mid-lower (R0H and R1H), and lower (R0L and R1L).

2.1.2 Address Registers (A0, A1, A2, and A3)

These 32-bit registers have functions similar to data registers. They are also used for address register indirect addressing and address register relative addressing.

2.1.3 Static Base Register (SB)

This 32-bit register is used for SB relative addressing.

2.1.4 Frame Base Register (FB)

This 32-bit register is used for FB relative addressing.

2.1.5 Program Counter (PC)

This 32-bit counter indicates the address of the instruction to be executed next.

2.1.6 Interrupt Vector Table Base Register (INTB)

This 32-bit register indicates the start address of a relocatable vector table.

2.1.7 User Stack Pointer (USP) and Interrupt Stack Pointer (ISP)

Two types of 32-bit stack pointers (SPs) are provided: user stack pointer (USP) and interrupt stack pointer (ISP).

Use the stack pointer select flag (U flag) to select either the user stack pointer (USP) or the interrupt stack pointer (ISP). The U flag is bit 7 in the flag register (FLG). Refer to 2.1.8 "Flag Register (FLG)" for details.

To minimize the overhead of interrupt sequence due to less memory access, set the user stack pointer (USP) or the interrupt stack pointer (ISP) to a multiple of 4.

2.1.8 Flag Register (FLG)

This 32-bit register indicates the CPU status.

2.1.8.1 Carry Flag (C flag)

This flag retains a carry, borrow, or shifted-out bit generated by the arithmetic logic unit (ALU).

2.1.8.2 Debug Flag (D flag)

This flag is only for debugging. Only set this bit to 0.

2.1.8.3 Zero Flag (Z flag)

This flag becomes 1 when the result of an operation is 0; otherwise it is 0.

2.1.8.4 Sign Flag (S flag)

This flag becomes 1 when the result of an operation is a negative value; otherwise it is 0.

4. Special Function Registers (SFRs)

SFRs are memory-mapped peripheral registers that control the operation of peripherals. Table 4.1 SFR List (1) to Table 4.39 SFR List (39) list the SFR details.

Table 4.1 SFR List (1)

Address	Register	Symbol	Reset Value
000000h			
000001h			
000002h			
000003h			
000004h	Clock Control Register	CCR	0001 1000b
000005h			
000006h	Flash Memory Control Register	FMCR	0000 0001b
000007h	Protect Release Register	PRR	00h
000008h			
000009h			
00000Ah			
00000Bh			
00000Ch			
00000Dh			
00000Eh			
00000Fh			
000010h	External Bus Control Register 3/Flash Memory Rewrite Bus	EBC3/FEBC3	0000h
000011h	Control Register 3		
000012h	Chip Selects 2 and 3 Boundary Setting Register	CB23	00h
000013h			
000014h	External Bus Control Register 2	EBC2	0000h
000015h			
000016h	Chip Selects 1 and 2 Boundary Setting Register	CB12	00h
000017h			
000018h	External Bus Control Register 1	EBC1	0000h
000019h			
00001Ah	Chip Selects 0 and 1 Boundary Setting Register	CB01	00h
00001Bh			
00001Ch	External Bus Control Register 0/Flash Memory Rewrite Bus	EBC0/FEBC0	0000h
00001Dh	Control Register 0		
00001Eh	Peripheral Bus Control Register	PBC	0504h
00001Fh			
000020h to 00005Fh			

X: Undefined

Blanks are reserved. No access is allowed.

Table 4.19 SFR List (19)

Address	Register	Symbol	Reset Value
040030h to 04003Fh			
040040h			
040041h			
040042h			
040043h			
040044h	Processor Mode Register 0 ⁽¹⁾	PM0	1000 0000b (CNVSS pin = Low) 0000 0011b (CNVSS pin = High)
040045h			
040046h	System Clock Control Register 0	CM0	0000 1000b
040047h	System Clock Control Register 1	CM1	0010 0000b
040048h	Processor Mode Register 3	PM3	00h
040049h			
04004Ah	Protect Register	PRCR	XXXX X000b
04004Bh			
04004Ch	Protect Register 3	PRCR3	0000 0000b
04004Dh	Oscillator Stop Detection Register	CM2	00h
04004Eh			
04004Fh			
040050h			
040051h			
040052h			
040053h	Processor Mode Register 2	PM2	00h
040054h	Chip Select Output Pin Setting Register 0	CSOP0	1000 XXXXb
040055h	Chip Select Output Pin Setting Register 1	CSOP1	01X0 XXXXb
040056h	Chip Select Output Pin Setting Register 2	CSOP2	XXXX 0000b
040057h			
040058h			
040059h			
04005Ah	Low Speed Mode Clock Control Register	CM3	XXXX XX00b
04005Bh			
04005Ch			
04005Dh			
04005Eh			
04005Fh			
040060h	Voltage Regulator Control Register	VRCR	0000 0000b
040061h			
040062h	Low Voltage Detector Control Register	LVDC	0000 XX00b
040063h			
040064h	Detection Voltage Configuration Register	DVCR	0000 XXXXb
040065h			
040066h			
040067h			
040068h to 040093h			

X: Undefined

Blanks are reserved. No access is allowed.

Note:

1. The value in the PM0 register is retained even after a software reset or watchdog timer reset.

Table 4.21 SFR List (21)

Address	Register	Symbol	Reset Value
0400C0h	Port P4_0 Function Select Register	P4_0S	X0XX X000b
0400C1h	Port P5_0 Function Select Register	P5_0S	XXXX X000b
0400C2h	Port P4_1 Function Select Register	P4_1S	X0XX X000b
0400C3h	Port P5_1 Function Select Register	P5_1S	XXXX X000b
0400C4h	Port P4_2 Function Select Register	P4_2S	X0XX X000b
0400C5h	Port P5_2 Function Select Register	P5_2S	XXXX X000b
0400C6h	Port P4_3 Function Select Register	P4_3S	X0XX X000b
0400C7h	Port P5_3 Function Select Register	P5_3S	XXXX X000b
0400C8h	Port P4_4 Function Select Register	P4_4S	X0XX X000b
0400C9h	Port P5_4 Function Select Register	P5_4S	X0XX X000b
0400CAh	Port P4_5 Function Select Register	P4_5S	X0XX X000b
0400CBh	Port P5_5 Function Select Register	P5_5S	X0XX X000b
0400CCh	Port P4_6 Function Select Register	P4_6S	X0XX X000b
0400CDh	Port P5_6 Function Select Register	P5_6S	X0XX X000b
0400CEh	Port P4_7 Function Select Register	P4_7S	X0XX X000b
0400CFh	Port P5_7 Function Select Register	P5_7S	X0XX X000b
0400D0h	Port P6_0 Function Select Register	P6_0S	X0XX X000b
0400D1h	Port P7_0 Function Select Register	P7_0S	X0XX X000b
0400D2h	Port P6_1 Function Select Register	P6_1S	X0XX X000b
0400D3h	Port P7_1 Function Select Register	P7_1S	X0XX X000b
0400D4h	Port P6_2 Function Select Register	P6_2S	X0XX X000b
0400D5h	Port P7_2 Function Select Register	P7_2S	X0XX X000b
0400D6h	Port P6_3 Function Select Register	P6_3S	X0XX X000b
0400D7h	Port P7_3 Function Select Register	P7_3S	X0XX X000b
0400D8h	Port P6_4 Function Select Register	P6_4S	X0XX X000b
0400D9h	Port P7_4 Function Select Register	P7_4S	X0XX X000b
0400DAh	Port P6_5 Function Select Register	P6_5S	X0XX X000b
0400DBh	Port P7_5 Function Select Register	P7_5S	X0XX X000b
0400DCh	Port P6_6 Function Select Register	P6_6S	X0XX X000b
0400DDh	Port P7_6 Function Select Register	P7_6S	X0XX X000b
0400DEh	Port P6_7 Function Select Register	P6_7S	X0XX X000b
0400DFh	Port P7_7 Function Select Register	P7_7S	X0XX X000b
0400E0h	Port P8_0 Function Select Register	P8_0S	X0XX X000b
0400E1h	Port P9_0 Function Select Register	P9_0S	X0XX X000b
0400E2h	Port P8_1 Function Select Register	P8_1S	X0XX X000b
0400E3h	Port P9_1 Function Select Register	P9_1S	X0XX X000b
0400E4h	Port P8_2 Function Select Register	P8_2S	X0XX X000b
0400E5h	Port P9_2 Function Select Register	P9_2S	X0XX X000b
0400E6h	Port P8_3 Function Select Register	P8_3S	X0XX X000b
0400E7h	Port P9_3 Function Select Register	P9_3S	00XX X000b
0400E8h	Port P8_4 Function Select Register	P8_4S	XXXX X000b
0400E9h	Port P9_4 Function Select Register	P9_4S	00XX X000b
0400EAh			
0400EBh	Port P9_5 Function Select Register	P9_5S	00XX X000b
0400ECh	Port P8_6 Function Select Register	P8_6S	XXXX X000b
0400EDh	Port P9_6 Function Select Register	P9_6S	00XX X000b
0400EEh	Port P8_7 Function Select Register	P8_7S	XXXX X000b
0400EFh	Port P9_7 Function Select Register	P9_7S	X0XX X000b

X: Undefined

Blanks are reserved. No access is allowed.

Table 4.30 SFR List (30)

Address	Register	Symbol	Reset Value
047CC0h	CAN0 Mailbox 12: Message Identifier	C0MB12	XXXX XXXXh
047CC1h			
047CC2h			
047CC3h			
047CC4h			
047CC5h	CAN0 Mailbox 12: Data Length		XXh
047CC6h	CAN0 Mailbox 12: Data Field		XXXX XXXX XXXX XXXXh
047CC7h			
047CC8h			
047CC9h			
047CCAh			
047CCBh			
047CCCh			
047CCDh			
047CCEh	CAN0 Mailbox 12: Time Stamp		XXXXh
047CCFh			
047CD0h	CAN0 Mailbox 13: Message Identifier	C0MB13	XXXX XXXXh
047CD1h			
047CD2h			
047CD3h			
047CD4h			
047CD5h	CAN0 Mailbox 13: Data Length		XXh
047CD6h	CAN0 Mailbox 13: Data Field		XXXX XXXX XXXX XXXXh
047CD7h			
047CD8h			
047CD9h			
047CDAh			
047CDBh			
047CDCh			
047CDDh			
047CDEh	CAN0 Mailbox 13: Time Stamp		XXXXh
047CDFh			
047CE0h	CAN0 Mailbox 14: Message Identifier	C0MB14	XXXX XXXXh
047CE1h			
047CE2h			
047CE3h			
047CE4h			
047CE5h	CAN0 Mailbox 14: Data Length		XXh
047CE6h	CAN0 Mailbox 14: Data Field		XXXX XXXX XXXX XXXXh
047CE7h			
047CE8h			
047CE9h			
047CEAh			
047CEBh			
047CECh			
047CEDh			
047CEEh	CAN0 Mailbox 14: Time Stamp		XXXXh
047CEFh			

X: Undefined

Blanks are reserved. No access is allowed.

Table 4.35 SFR List (35)

Address	Register	Symbol	Reset Value
047DB0h	CAN0 Mailbox 27: Message Identifier	C0MB27	XXXX XXXXh
047DB1h			
047DB2h			
047DB3h			
047DB4h			
047DB5h	CAN0 Mailbox 27: Data Length		XXh
047DB6h	CAN0 Mailbox 27: Data Field		XXXX XXXX XXXX XXXXh
047DB7h			
047DB8h			
047DB9h			
047DBAh			
047DBBh			
047DBCh			
047DBDh			
047DBEh	CAN0 Mailbox 27: Time Stamp		XXXXh
047DBFh			
047DC0h	CAN0 Mailbox 28: Message Identifier	C0MB28	XXXX XXXXh
047DC1h			
047DC2h			
047DC3h			
047DC4h			
047DC5h	CAN0 Mailbox 28: Data Length		XXh
047DC6h	CAN0 Mailbox 28: Data Field		XXXX XXXX XXXX XXXXh
047DC7h			
047DC8h			
047DC9h			
047DCAh			
047DCBh			
047DCCCh			
047DCDh			
047DCEh	CAN0 Mailbox 28: Time Stamp		XXXXh
047DCFh			
047DD0h	CAN0 Mailbox 29: Message Identifier	C0MB29	XXXX XXXXh
047DD1h			
047DD2h			
047DD3h			
047DD4h			
047DD5h	CAN0 Mailbox 29: Data Length		XXh
047DD6h	CAN0 Mailbox 29: Data Field		XXXX XXXX XXXX XXXXh
047DD7h			
047DD8h			
047DD9h			
047DDAh			
047DDBh			
047DDCh			
047DDDh			
047DDEh	CAN0 Mailbox 29: Time Stamp		XXXXh
047DDFh			

X: Undefined

Blanks are reserved. No access is allowed.

Table 4.37 SFR List (37)

Address	Register	Symbol	Reset Value
047E10h	CAN0 Mask Register 4	C0MKR4	XXXX XXXXh
047E11h			
047E12h			
047E13h			
047E14h	CAN0 Mask Register 5	C0MKR5	XXXX XXXXh
047E15h			
047E16h			
047E17h			
047E18h	CAN0 Mask Register 6	C0MKR6	XXXX XXXXh
047E19h			
047E1Ah			
047E1Bh			
047E1Ch	CAN0 Mask Register 7	C0MKR7	XXXX XXXXh
047E1Dh			
047E1Eh			
047E1Fh			
047E20h	CAN0 FIFO Receive ID Compare Register 0	C0FIDCR0	XXXX XXXXh
047E21h			
047E22h			
047E23h			
047E24h	CAN0 FIFO Receive ID Compare Register 1	C0FIDCR1	XXXX XXXXh
047E25h			
047E26h			
047E27h			
047E28h	CAN0 Mask Invalid Register	C0MKIVLR	XXXX XXXXh
047E29h			
047E2Ah			
047E2Bh			
047E2Ch	CAN0 Mailbox Interrupt Enable Register	C0MIER	XXXX XXXXh
047E2Dh			
047E2Eh			
047E2Fh			
047E30h			
047E31h			
047E32h			
047E33h			
047E34h			
047E35h			
047E36h			
047E37h			
047E38h			
047E39h			
047E3Ah			
047E3Bh			
047E3Ch			
047E3Dh			
047E3Eh			
047E3Fh			
047E40h to 047F1Fh			

X: Undefined

Blanks are reserved. No access is allowed.

Table 5.12 Electrical Characteristics of Oscillator
($V_{CC} = 3.0$ to 5.5 V, $V_{SS} = 0$ V, and $T_a = T_{opr}$, unless otherwise noted)

Symbol	Characteristics	Measurement Condition	Value			Unit
			Min.	Typ.	Max.	
$f_{SO(PLL)}$	PLL clock self-oscillation frequency		35	50	65	MHz
$t_{LOCK(PLL)}$	PLL lock time ⁽¹⁾				1	ms
$t_{jitter(p-p)}$	PLL jitter period (p-p)				2.0	ns
$f_{(OCO)}$	On-chip oscillator frequency		62.5	125	250	kHz

Note:

1. This value is applicable only when the main clock oscillation is stable.

Table 5.13 Electrical Characteristics of Clock Circuitry
($V_{CC} = 3.0$ to 5.5 V, $V_{SS} = 0$ V, and $T_a = T_{opr}$, unless otherwise noted)

Symbol	Characteristics	Measurement Condition	Value			Unit
			Min.	Typ.	Max.	
$t_{rec(WAIT)}$	Recovery time from wait mode to low power mode				225	μ s
$t_{rec(STOP)}$	Recovery time from stop mode ⁽¹⁾				225	μ s

Note:

1. The recovery time from stop mode does not include the main clock oscillation stabilization time. The CPU starts operating before the oscillator is stabilized.

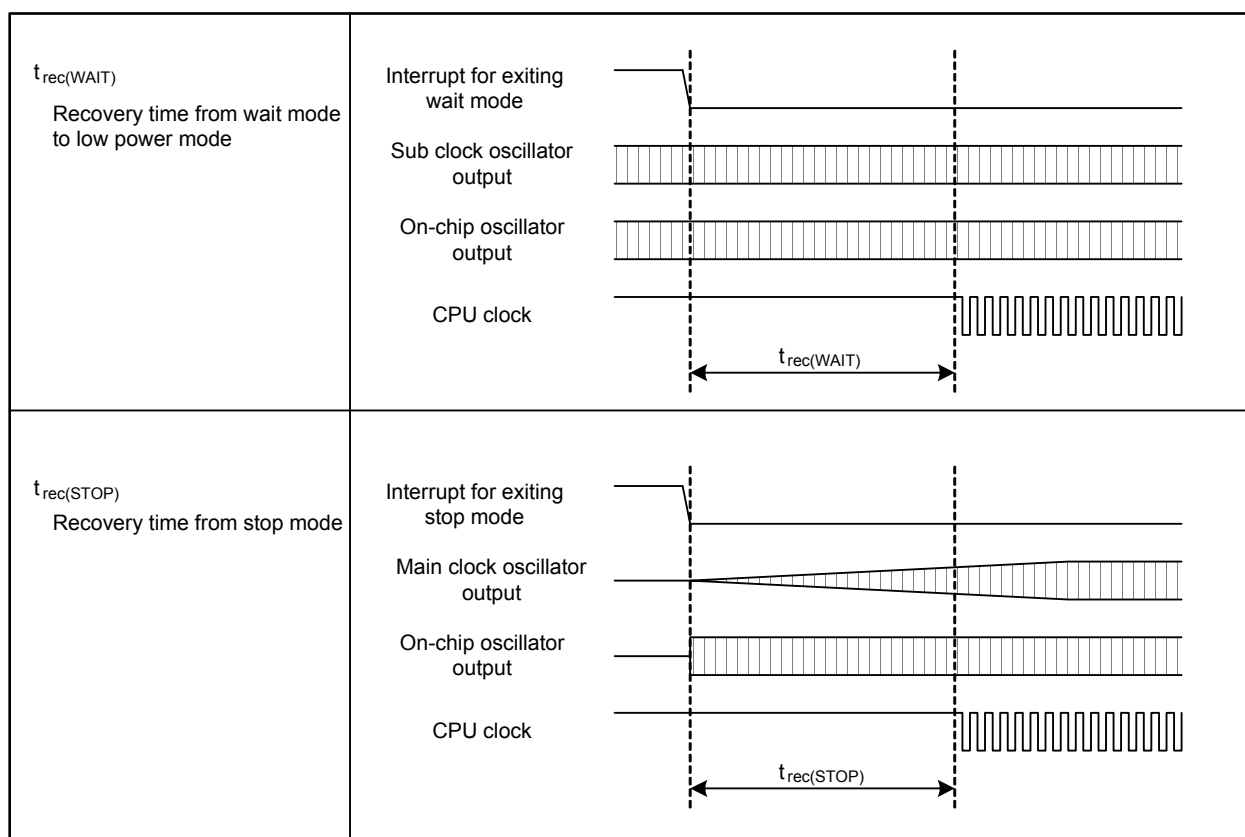


Figure 5.4 Clock Circuit Timing

$$V_{CC} = 5 \text{ V}$$

Table 5.18 A/D Conversion Characteristics ($V_{CC} = AV_{CC} = V_{REF} = 4.2 \text{ to } 5.5 \text{ V}$, $V_{SS} = AV_{SS} = 0 \text{ V}$, $T_a = T_{opr}$, and $f_{(BCLK)} = 32 \text{ MHz}$, unless otherwise noted)

Symbol	Characteristic	Measurement Condition	Value			Unit
			Min.	Typ.	Max.	
—	Resolution	$V_{REF} = V_{CC}$			10	Bits
—	Absolute error	$V_{REF} = V_{CC} = 5 \text{ V}$			± 3	LSB
		AN_0 to AN_7, AN0_0 to AN0_7, AN2_0 to AN2_7, AN15_0 to AN15_7, ANEX0, ANEX1 ⁽¹⁾ External op-amp connection mode			± 7	LSB
INL	Integral non-linearity error	$V_{REF} = V_{CC} = 5 \text{ V}$			± 3	LSB
		AN_0 to AN_7, AN0_0 to AN0_7, AN2_0 to AN2_7, AN15_0 to AN15_7, ANEX0, ANEX1 ⁽¹⁾ External op-amp connection mode			± 7	LSB
DNL	Differential non-linearity error				± 1	LSB
—	Offset error				± 3	LSB
—	Gain error				± 3	LSB
R_{LADDER}	Resistor ladder	$V_{REF} = V_{CC}$	4		20	k Ω
t_{CONV}	Conversion time (10 bits)	$\phi_{AD} = 16 \text{ MHz}$, with sample and hold function	2.06			μs
		$\phi_{AD} = 16 \text{ MHz}$, without sample and hold function	3.69			μs
t_{CONV}	Conversion time (8 bits)	$\phi_{AD} = 16 \text{ MHz}$, with sample and hold function	1.75			μs
		$\phi_{AD} = 16 \text{ MHz}$, without sample and hold function	3.06			μs
t_{SAMP}	Sampling time	$\phi_{AD} = 16 \text{ MHz}$	0.188			μs
V_{IA}	Analog input voltage		0		V_{REF}	V
ϕ_{AD}	Operating clock frequency	Without sample and hold function	0.25		16	MHz
		With sample and hold function	1		16	MHz

Note:

1. Pins AN15_0 to AN15_7 are available in the 144-pin package only.

$$V_{CC} = 5 \text{ V}$$

Timing Requirements ($V_{CC} = 4.2$ to 5.5 V , $V_{SS} = 0 \text{ V}$, and $T_a = T_{opr}$, unless otherwise noted)

Table 5.34 Multi-master I²C-bus Interface

Symbol	Characteristic	Value				Unit
		Standard-mode		Fast-mode		
		Min.	Max.	Min.	Max.	
t _{w(SCLH)}	MSCL input high level pulse width	600		600		ns
t _{w(SCLL)}	MSCL input low level pulse width	600		600		ns
t _{r(SCL)}	MSCL input rise time		1000		300	ns
t _{f(SCL)}	MSCL input fall time		300		300	ns
t _{r(SDA)}	MSDA input rise time		1000		300	ns
t _{f(SDA)}	MSDA input fall time		300		300	ns
t _{h(SDA-SCL)S}	MSCL high level hold time after START condition/repeated START condition	(1)		2 × t _{c(φIIC)} + 40		ns
t _{su(SCL-SDA)P}	MSCL high level setup time for repeated START condition/STOP condition	(1)		2 × t _{c(φIIC)} + 40		ns
t _{w(SDAH)P}	MSDA high level pulse width after STOP condition	(1)		4 × t _{c(φIIC)} + 40		ns
t _{su(SDA-SCL)}	MSDA input setup time	100		100		ns
t _{h(SCL-SDA)}	MSDA input hold time	0		0		ns

Note:

- The value is calculated by the following formulas based on a value SSC by setting bits SSC4 to SSC0 in the I2CSSCR register:

$$t_{h(SDA-SCL)S} = SSC \div 2 \times t_{c(\phi IIC)} + 40 \text{ [ns]}$$

$$t_{su(SCL-SDA)P} = (SSC \div 2 + 1) \times t_{c(\phi IIC)} + 40 \text{ [ns]}$$

$$t_{w(SDAH)P} = (SSC + 1) \times t_{c(\phi IIC)} + 40 \text{ [ns]}$$

$$V_{CC} = 5 \text{ V}$$

Switching Characteristics ($V_{CC} = 4.2$ to 5.5 V , $V_{SS} = 0 \text{ V}$, and $T_a = T_{opr}$, unless otherwise noted)

Table 5.35 External Bus Timing (separate bus)

Symbol	Characteristic	Measurement Condition	Value		Unit
			Min.	Max.	
$t_{su(S-R)}$	Chip-select setup time before read	Refer to Figure 5.6	(1)		ns
$t_{h(R-S)}$	Chip-select hold time after read		$t_{c(Base)} - 15$		ns
$t_{su(A-R)}$	Address setup time before read		(1)		ns
$t_{h(R-A)}$	Address hold time after read		$t_{c(Base)} - 15$		ns
$t_{w(R)}$	Read pulse width		(1)		ns
$t_{su(S-W)}$	Chip-select setup time before write		(1)		ns
$t_{h(W-S)}$	Chip-select hold time after write		$1.5 \times t_{c(Base)} - 15$		ns
$t_{su(A-W)}$	Address setup time before write		(1)		ns
$t_{h(W-A)}$	Address hold time after write		$1.5 \times t_{c(Base)} - 15$		ns
$t_{w(W)}$	Write pulse width		(1)		ns
$t_{su(D-W)}$	Data setup time before write		(1)		ns
$t_{h(W-D)}$	Data hold time after write		0		ns

Note:

- The value is calculated using the formulas below based on the base clock cycles ($t_{c(Base)}$) and respective cycles of $T_{su(A-R)}$, $T_{w(R)}$, $T_{su(A-W)}$, and $T_{w(W)}$ set by registers EBC0 to EBC3. If the calculation results in a negative value, modify the value to be set. For details on how to set values, refer to the User's manual.

$$t_{su(S-R)} = t_{su(A-R)} = T_{su(A-R)} \times t_{c(Base)} - 15 \text{ [ns]}$$

$$t_{w(R)} = T_{w(R)} \times t_{c(Base)} - 10 \text{ [ns]}$$

$$t_{su(S-W)} = t_{su(A-W)} = T_{su(A-W)} \times t_{c(Base)} - 15 \text{ [ns]}$$

$$t_{w(W)} = t_{su(D-W)} = T_{w(W)} \times t_{c(Base)} - 10 \text{ [ns]}$$

$$V_{CC} = 5\text{ V}$$

Switching Characteristics ($V_{CC} = 4.2$ to 5.5 V , $V_{SS} = 0\text{ V}$, and $T_a = T_{opr}$, unless otherwise noted)

Table 5.37 Serial Interface

Symbol	Characteristic	Measurement Condition	Value		Unit
			Min.	Max.	
$t_{d(C-Q)}$	TXDi output delay time	Refer to Figure 5.6		80	ns
$t_{h(C-Q)}$	TXDi output hold time		0		ns

Table 5.38 Intelligent I/O

Symbol	Characteristic	Measurement Condition	Value		Unit
			Min.	Max.	
$t_{d(ISCLK2-TXD)}$	ISTXD2 output delay time	Refer to Figure 5.6		180	ns
$t_{h(ISCLK2-RXD)}$	ISTXD2 output hold time		0		ns

Table 5.39 Multi-master I²C-bus Interface (standard-mode)

Symbol	Characteristic	Measurement Condition	Value		Unit
			Min.	Max.	
$t_{f(SCL)}$	MSCL output fall time	Refer to Figure 5.6	2		ns
$t_{f(SDA)}$	MSDA output fall time		2		ns
$t_{d(SDA-SCL)S}$	MSCL output delay time after START condition/repeated START condition		$20 \times t_{C(\phi IIC)} - 120$	$52 \times t_{C(\phi IIC)} - 40$	ns
$t_{d(SCL-SDA)P}$	Repeated START condition/STOP condition output delay time after MSCL becomes high		$20 \times t_{C(\phi IIC)} + 40$	$52 \times t_{C(\phi IIC)} + 120$	ns
$t_{d(SCL-SDA)}$	MSDA output delay time		$2 \times t_{C(\phi IIC)} + 40$	$3 \times t_{C(\phi IIC)} + 120$	ns

Table 5.40 Multi-master I²C-bus Interface (fast-mode)

Symbol	Characteristic	Measurement Condition	Value		Unit
			Min.	Max.	
$t_{f(SCL)}$	MSCL output fall time	Refer to Figure 5.6	2 (1)		ns
$t_{f(SDA)}$	MSDA output fall time		2 (1)		ns
$t_{d(SDA-SCL)S}$	MSCL output delay time after START condition/repeated START condition		$10 \times t_{C(\phi IIC)} - 120$	$26 \times t_{C(\phi IIC)} - 40$	ns
$t_{d(SCL-SDA)P}$	Repeated START condition/STOP condition output delay time after MSCL becomes high		$10 \times t_{C(\phi IIC)} + 40$	$26 \times t_{C(\phi IIC)} + 120$	ns
$t_{d(SCL-SDA)}$	MSDA output delay time		$2 \times t_{C(\phi IIC)} + 40$	$3 \times t_{C(\phi IIC)} + 120$	ns

Note:

1. External circuits are required to satisfy the I²C-bus specification.

$$V_{CC} = 3.3 \text{ V}$$

Timing Requirements ($V_{CC} = 3.0$ to 3.6 V , $V_{SS} = 0 \text{ V}$, and $T_a = T_{opr}$, unless otherwise noted)

Table 5.46 External Clock Input

Symbol	Characteristic	Value		Unit
		Min.	Max.	
$t_{C(X)}$	External clock input period	62.5	250	ns
$t_{W(XH)}$	External clock input high level pulse width	25		ns
$t_{W(XL)}$	External clock input low level pulse width	25		ns
$t_{r(X)}$	External clock input rise time		5	ns
$t_{f(X)}$	External clock input fall time		5	ns
t_W / t_C	External clock input duty	40	60	%

Table 5.47 External Bus Timing

Symbol	Characteristic	Value		Unit
		Min.	Max.	
$t_{su(D-R)}$	Data setup time before read	40		ns
$t_{h(R-D)}$	Data hold time after read	0		ns
$t_{dis(R-D)}$	Data disable time after read		$0.5 \times t_{C(Base)} + 10$	ns

$$V_{CC} = 3.3 \text{ V}$$

Switching Characteristics ($V_{CC} = 3.0$ to 3.6 V , $V_{SS} = 0 \text{ V}$, and $T_a = T_{opr}$, unless otherwise noted)

Table 5.63 Serial Interface

Symbol	Characteristic	Measurement Condition	Value		Unit
			Min.	Max.	
$t_{d(C-Q)}$	TXDi output delay time	Refer to Figure 5.6		80	ns
$t_{h(C-Q)}$	TXDi output hold time		0		ns

Table 5.64 Intelligent I/O

Symbol	Characteristic	Measurement Condition	Value		Unit
			Min.	Max.	
$t_{d(ISTXK2-TXD)}$	ISTXD2 output delay time	Refer to Figure 5.6		180	ns
$t_{h(ISTXK2-RXD)}$	ISTXD2 output hold time		0		ns

Table 5.65 Multi-master I²C-bus Interface (Standard-mode)

Symbol	Characteristic	Measurement Condition	Value		Unit
			Min.	Max.	
$t_{f(SCL)}$	MSCL output fall time	Refer to Figure 5.6	2		ns
$t_{f(SDA)}$	MSDA output fall time		2		ns
$t_{d(SDA-SCL)S}$	MSCL output delay time after START condition/repeated START condition		$20 \times t_{c(\phi IIC)} - 120$	$52 \times t_{c(\phi IIC)} - 40$	ns
$t_{d(SCL-SDA)P}$	Repeated START condition/STOP condition output delay time after MSCL becomes high		$20 \times t_{c(\phi IIC)} + 40$	$52 \times t_{c(\phi IIC)} + 120$	ns
$t_{d(SCL-SDA)}$	MSDA output delay time		$2 \times t_{c(\phi IIC)} + 40$	$3 \times t_{c(\phi IIC)} + 120$	ns

Table 5.66 Multi-master I²C-bus Interface (Fast-mode)

Symbol	Characteristic	Measurement Condition	Value		Unit
			Min.	Max.	
$t_{f(SCL)}$	MSCL output fall time	Refer to Figure 5.6	2 (1)		ns
$t_{f(SDA)}$	MSDA output fall time		2 (1)		ns
$t_{d(SDA-SCL)S}$	MSCL output delay time after START condition/repeated START condition		$10 \times t_{c(\phi IIC)} - 120$	$26 \times t_{c(\phi IIC)} - 40$	ns
$t_{d(SCL-SDA)P}$	Repeated START condition/STOP condition output delay time after MSCL becomes high		$10 \times t_{c(\phi IIC)} + 40$	$26 \times t_{c(\phi IIC)} + 120$	ns
$t_{d(SCL-SDA)}$	MSDA output delay time		$2 \times t_{c(\phi IIC)} + 40$	$3 \times t_{c(\phi IIC)} + 120$	ns

Note:

1. External circuits are required to satisfy the I²C-bus specification.