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Applications of "Embedded - Microcontrollers"

Details	
Product Status	Discontinued at Digi-Key
Core Processor	Z8
Core Size	8-Bit
Speed	8MHz
Connectivity	-
Peripherals	Brown-out Detect/Reset, HLVD, POR, WDT
Number of I/O	24
Program Memory Size	16KB (16K x 8)
Program Memory Type	OTP
EEPROM Size	-
RAM Size	237 x 8
Voltage - Supply (Vcc/Vdd)	2V ~ 3.6V
Data Converters	-
Oscillator Type	Internal
Operating Temperature	0°C ~ 70°C (TA)
Mounting Type	Surface Mount
Package / Case	28-SSOP (0.209", 5.30mm Width)
Supplier Device Package	-
Purchase URL	https://www.e-xfl.com/product-detail/zilog/zlp32300h2816c

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Pin Description

The pin configuration for the 20-pin PDIP/SOIC/SSOP is displayed in Figure 3 and described in Table 3. The pin configuration for the 28-pin PDIP/SOIC/SSOP are depicted in Figure 4 and described in Table 4. The pin configurations for the 40-pin PDIP and 48-pin SSOP versions are displayed in Figure 5, Figure 6, and described in Table 5.

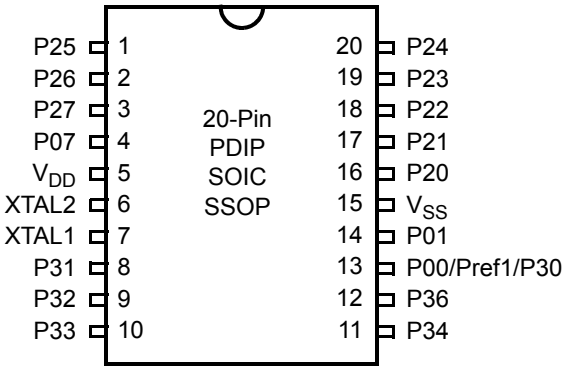


Figure 3. 20-Pin PDIP/SOIC/SSOP Pin Configuration

Table 3. 20-Pin PDIP/SOIC/SSOP Pin Identification

Pin No	Symbol	Function	Direction
1–3	P25–P27	Port 2, Bits 5,6,7	Input/Output
4	P07	Port 0, Bit 7	Input/Output
5	V_{DD}	Power Supply	
6	XTAL2	Crystal Oscillator Clock	Output
7	XTAL1	Crystal Oscillator Clock	Input
8–10	P31–P33	Port 3, Bits 1,2,3	Input
11,12	P34, P36	Port 3, Bits 4,6	Output
13	P00/Pref1/P30	Port 0, Bit 0/Analog reference input Port 3 Bit 0	Input/Output for P00 Input for Pref1/P30
14	P01	Port 0, Bit 1	Input/Output
15	V_{SS}	Ground	
16–20	P20–P24	Port 2, Bits 0,1,2,3,4	Input/Output

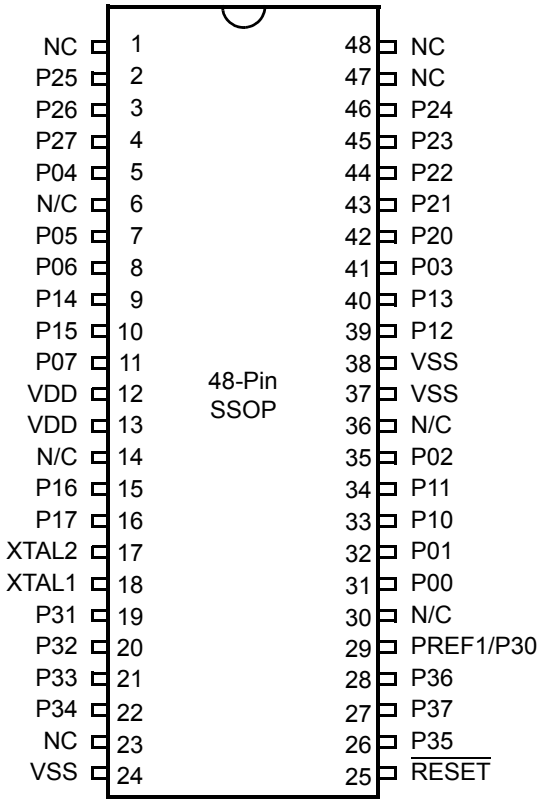


Figure 6. 48-Pin SSOP Pin Configuration

Table 5. 40- and 48-Pin Configuration

40-Pin PDIP No	48-Pin SSOP No	Symbol
26	31	P00
27	32	P01
30	35	P02
34	41	P03
5	5	P04
6	7	P05
7	8	P06
10	11	P07
28	33	P10
29	34	P11

T8_Capture_LO—L08(D)0Ah

This register holds the captured data from the output of the 8-bit Counter/Timer0. Typically, this register holds the number of counts when the input signal is 0.

Field	Bit Position		Description
T8_Capture_L0	[7:0]	R/W	Captured Data—No Effect

T16_Capture_HI—HI16(D)09h

This register holds the captured data from the output of the 16-bit Counter/Timer16. This register holds the MS-Byte of the data.

Field	Bit Position		Description
T16_Capture_HI	[7:0]	R/W	Captured Data—No Effect

T16_Capture_LO—L016(D)08h

This register holds the captured data from the output of the 16-bit Counter/Timer16. This register holds the LS-Byte of the data.

Field	Bit Position		Description
T16_Capture_LO	[7:0]	R/W	Captured Data—No Effect

Counter/Timer2 MS-Byte Hold Register—TC16H(D)07h

Field	Bit Position		Description
T16_Data_HI	[7:0]	R/W	Data

Counter/Timer2 LS-Byte Hold Register—TC16L(D)06h

Field	Bit Position		Description
T16_Data_LO	[7:0]	R/W	Data

Table 8. CTR1(0D)01h T8 and T16 Common Functions (Continued)

Field	Bit Position		Value	Description
Initial_T16_Out/ Falling_Edge	-------0			TRANSMIT Mode
		R/W	0*	T16_OUT is 0 Initially
			1	T16_OUT is 1 Initially
				DEMODULATION Mode
		R	0*	No Falling Edge
			1	Falling Edge Detected
		W	0	No Effect
			1	Reset Flag to 0

*Default at Power-On Reset
**Default at Power-On Reset. Not reset with a Stop Mode Recovery.

Mode

If the result is 0, the counter/timers are in TRANSMIT mode; otherwise, they are in DEMODULATION mode.

P36_Out/Demodulator_Input

In TRANSMIT mode, this bit defines whether P36 is used as a normal output pin or the combined output of T8 and T16.

In DEMODULATION mode, this bit defines whether the input signal to the Counter/Timers is from P20 or P31.

If the input signal is from Port 31, a capture event may also generate an IRQ2 interrupt. To prevent generating an IRQ2, either disable the IRQ2 interrupt by clearing its IMR bit D2 or use P20 as the input.

T8/T16_Logic/Edge _Detect

In TRANSMIT mode, this field defines how the outputs of T8 and T16 are combined (AND, OR, NOR, NAND).

In DEMODULATION mode, this field defines which edge should be detected by the edge detector.

Transmit_Submode/Glitch Filter

In TRANSMIT mode, this field defines whether T8 and T16 are in the PING-PONG mode or in independent normal operation mode. Setting this field to normal operation mode terminates the ‘PING-PONG Mode’ operation. When set to 10, T16 is immediately forced to a 0; a setting of 11 forces T16 to output a 1.

In DEMODULATION mode, this field defines the width of the glitch that must be filtered out.

interrupt can be generated if enabled (CTR0, D1). T8 then continues counting from FFh (see Figure 21 and Figure 22).

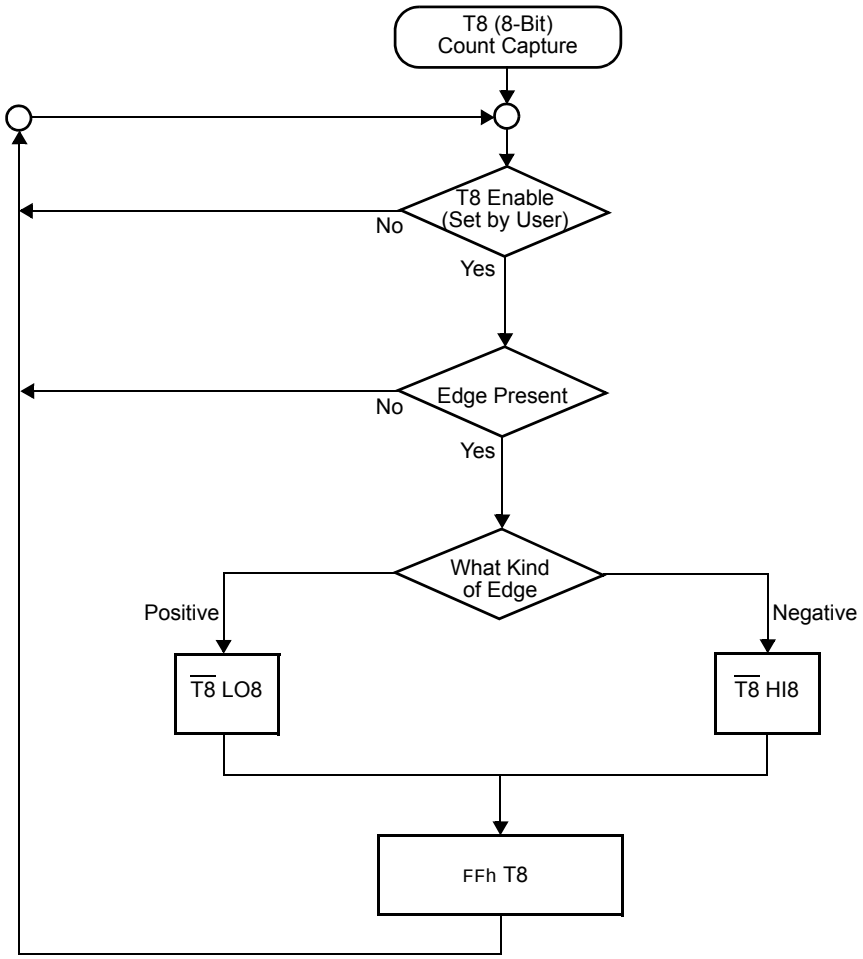


Figure 21. DEMODULATION Mode Count Capture Flowchart

T16 TRANSMIT Mode

In NORMAL or PING-PONG mode, the output of T16 when not enabled, is dependent on CTR1, D0. If it is a 0, T16_OUT is a 1; if it is a 1, T16_OUT is 0. You can force the output of T16 to either a 0 or 1 whether it is enabled or not by programming CTR1 D3; D2 to a 10 or 11.

When T16 is enabled, TC16H * 256 + TC16L is loaded, and T16_OUT is switched to its initial value (CTR1, D0). When T16 counts down to 0, T16_OUT is toggled (in NORMAL or PING-PONG mode), an interrupt (CTR2, D1) is generated (if enabled), and a status bit (CTR2, D5) is set, see Figure 23.

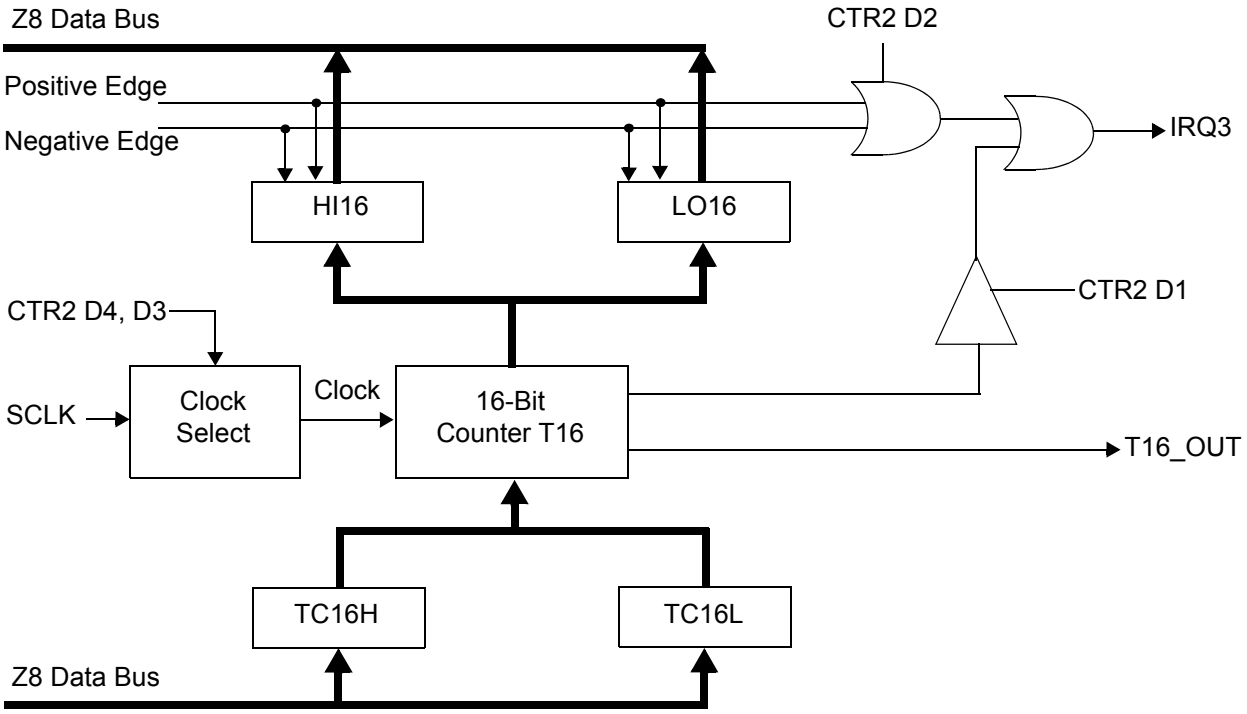


Figure 23. 16-Bit Counter/Timer Circuits

Note: *Global interrupts override this function as described in* Interrupts on page 43.

If T16 is in SINGLE-PASS mode, it is stopped at this point (see Figure 24). If it is in MODULO-N mode, it is loaded with TC16H * 256 + TC16L, and the counting continues (see Figure 25).

You can modify the values in TC16H and TC16L at any time. The new values take effect when they are loaded.

This T16 mode is generally used to measure space time, the length of time between bursts of carrier signal (marks).

If D6 of CTR2 Is 1

T16 ignores the subsequent edges in the input signal and continues counting down. A timeout of T8 causes T16 to capture its current value and generate an interrupt if enabled (CTR2, D2). In this case, T16 does not reload and continues counting. If the D6 bit of CTR2 is toggled (by writing a 0 then a 1 to it), T16 captures and reloads on the next edge (rising, falling, or both depending on CTR1, D5; D4), continuing to ignore subsequent edges.

This T16 mode generally measures mark time, the length of an active carrier signal burst.

If T16 reaches 0, T16 continues counting from FFFFh. Meanwhile, a status bit (CTR2 D5) is set, and an interrupt timeout can be generated if enabled (CTR2 D1).

PING-PONG Mode

This operation mode is only valid in TRANSMIT mode. T8 and T16 must be programmed in SINGLE-PASS mode (CTR0, D6; CTR2, D6), and PING-PONG mode must be programmed in CTR1, D3; D2. You can begin the operation by enabling either T8 or T16 (CTR0, D7 or CTR2, D7). For example, if T8 is enabled, T8_OUT is set to this initial value (CTR1, D1). According to T8_OUT's level, TC8H or TC8L is loaded into T8. After the terminal count is reached, T8 is disabled, and T16 is enabled. T16_OUT then switches to its initial value (CTR1, D0), data from TC16H and TC16L is loaded, and T16 starts to count. After T16 reaches the terminal count, it stops, T8 is enabled again, repeating the entire cycle. Interrupts can be allowed when T8 or T16 reaches terminal control (CTR0, D1; CTR2, D1). To stop the Ping-Pong operation, write 00 to bits D3 and D2 of CTR1, see Figure 26.

Note: *Enabling Ping-Pong operation while the counter/timers are running might cause intermittent counter/timer function. Disable the counter/timers and reset the status Flags before instituting this operation.*

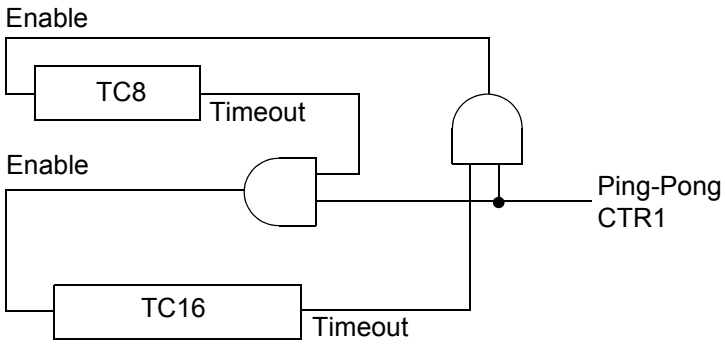


Figure 26. PING-PONG Mode Diagram

SCLK/TCLK Divide-by-16 Select (D0)

D0 of the SMR controls a divide-by-16 prescaler of SCLK/TCLK (see Figure 32). This control selectively reduces device power consumption during normal processor execution (SCLK control) and/or HALT mode (where TCLK sources interrupt logic). After Stop Mode Recovery, this bit is set to a 0.

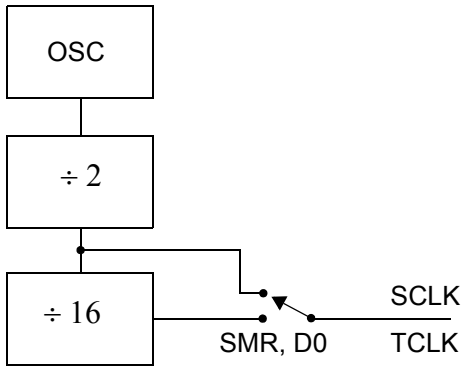


Figure 32. SCLK Circuit

Stop Mode Recovery Source (D2, D3, and D4)

These three bits of the SMR specify the wake-up source of the Stop recovery (see Figure 33 and Table 14).

Stop Mode Recovery Register 2—SMR2(F)0Dh

Table 13 lists and briefly describes the fields for this register.

Table 13. SMR2(F)0Dh:Stop Mode Recovery Register 2*

Field	Bit Position		Value	Description
Reserved	7-------		0	Reserved (Must be 0)
Recovery Level	-6------	W	0†	Low
			1	High
Reserved	--5-----		0	Reserved (Must be 0)

Table 14. Stop Mode Recovery Source

SMR:432			Operation
D4	D3	D2	Description of Action
0	0	0	POR and/or external reset recovery
0	0	1	Reserved
0	1	0	P31 transition
0	1	1	P32 transition
1	0	0	P33 transition
1	0	1	P27 transition
1	1	0	Logical NOR of P20 through P23
1	1	1	Logical NOR of P20 through P27

Note: *Any Port 2 bit defined as an output drives the corresponding input to the default state. For example, if the NOR of P23-P20 is selected as the recovery source and P20 is configured as an output, the remaining SMR pins (P23-P21) form the NOR equation. This condition allows the remaining inputs to control the AND/OR function, refer to SMR2 register* on page 54 *for other recover sources.*

Stop Mode Recovery Delay Select (D5)

This bit, if low, disables the T_{POR} delay after Stop Mode Recovery. The default configuration of this bit is 1. If the 'fast' wake up is selected, the Stop Mode Recovery source must be kept active for at least 10 TpC.

Note: *This bit must be set to 1 if a crystal or resonator clock source is used. The T_{POR} delay allows the clock source to stabilize before executing instructions.*

Stop Mode Recovery Edge Select (D6)

A 1 in this bit position indicates that a High level on any one of the recovery sources wakes the Crimzon ZLP32300 from STOP mode. A 0 indicates Low level recovery. The default is 0 on POR.

Cold or Warm Start (D7)

This bit is read only. It is set to 1 when the device is recovered from STOP mode. The bit is set to 0 when the device reset is other than Stop Mode Recovery.

WDT Time Select (D0, D1)

This bit selects the WDT time period. It is configured as indicated in Table 15.

Table 15. Watchdog Timer Time Select

D1	D0	Timeout of Internal RC-Oscillator
0	0	5 ms min
0	1	10 ms min
1	0	20 ms min
1	1	80 ms min

WDTMR During Halt (D2)

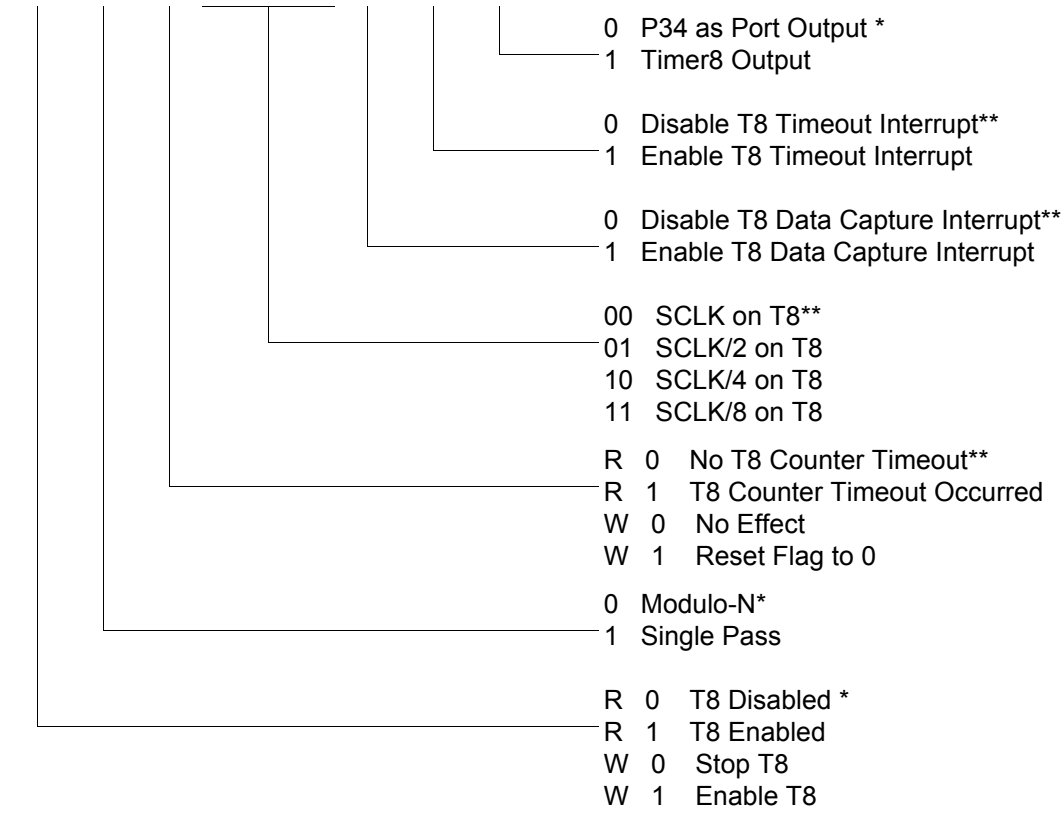
This bit determines whether or not the WDT is active during HALT mode. A 1 indicates active during HALT. The default is 1, see Figure 36.

Expanded Register File Control Registers (0D)

The expanded register file control registers (0D) are displayed in Figure 37 through Figure 41.

CTR0(0D)00H

D7	D6	D5	D4	D3	D2	D1	D0



*Default setting after reset.
**Default setting after reset. Not reset with a Stop Mode Recovery.

Figure 37. TC8 Control Register ((0D)O0H: Read/Write Except Where Noted)

Notes:

1. *Ensure to differentiate the TRANSMIT mode from DEMODULATION mode. Depending on which of these two modes is operating, the CTR1 bit has different functions.*
2. *Changing from one mode to another cannot be performed without disabling the counter/timers.*

CTR2(0D)02H

D7	D6	D5	D4	D3	D2	D1	D0

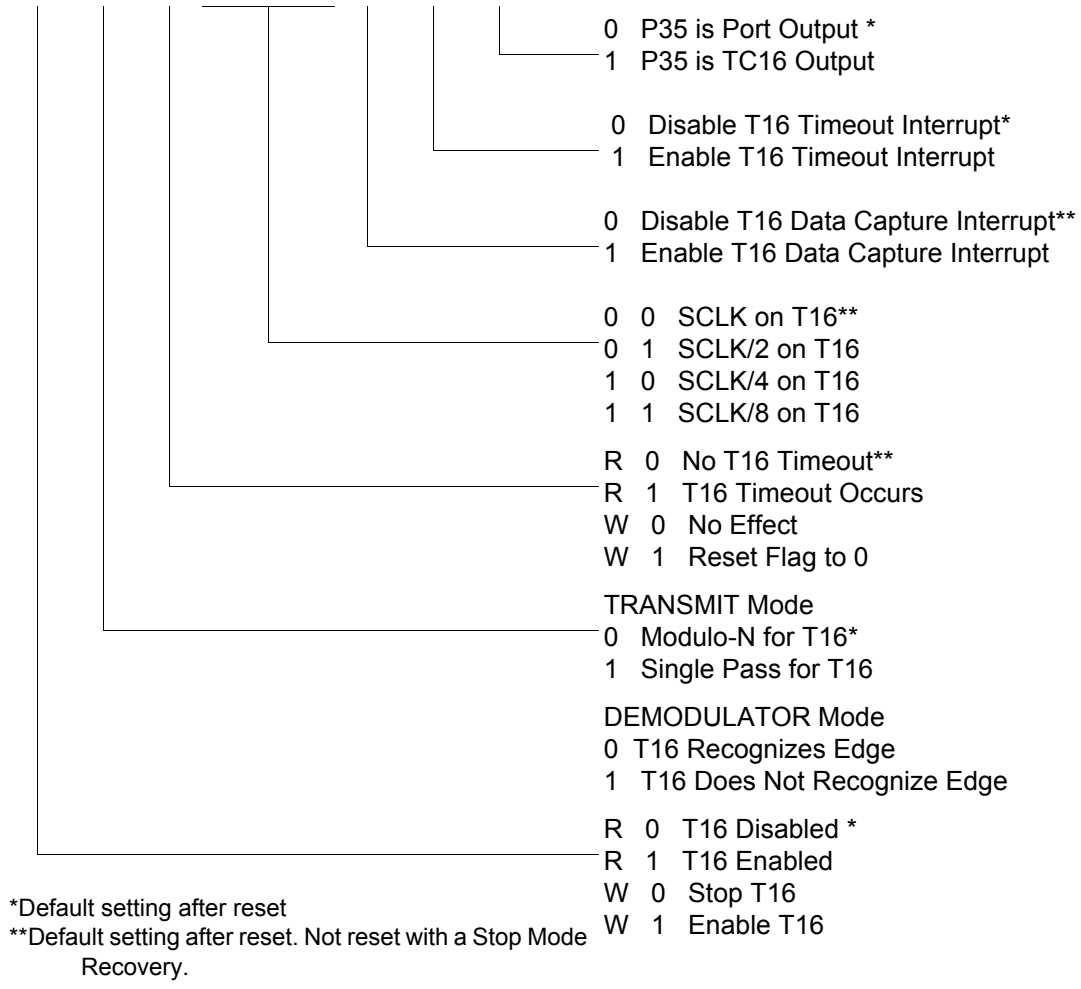
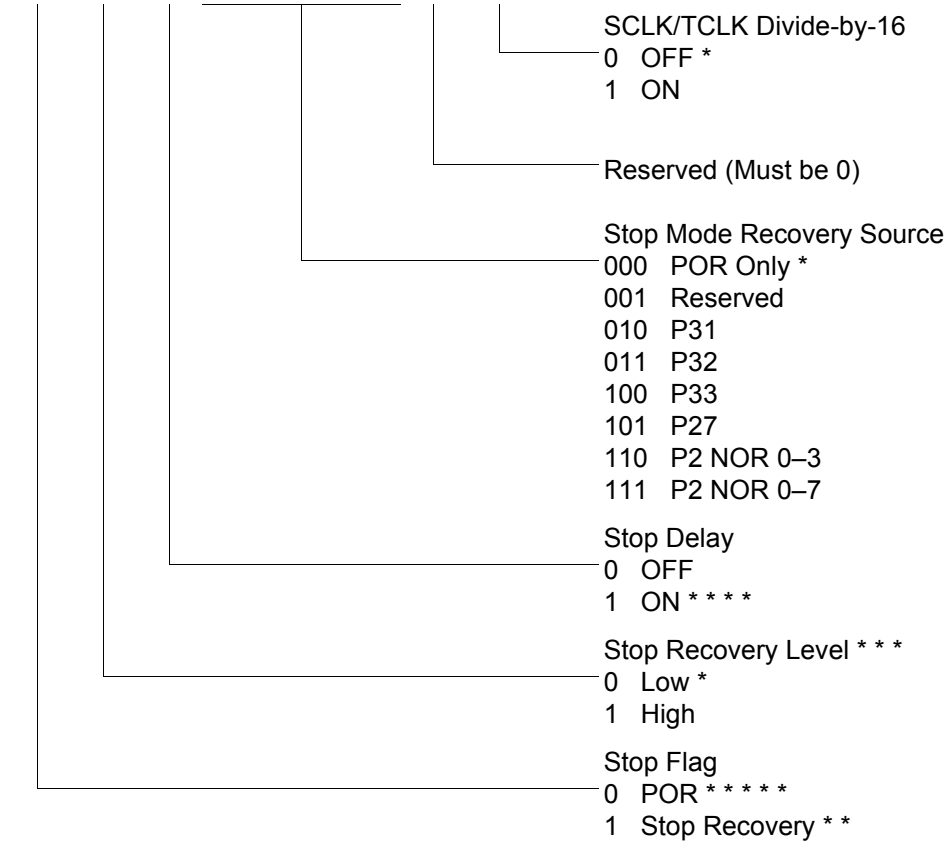


Figure 39. T16 Control Register ((0D) 2H: Read/Write Except Where Noted)

SMR(0F)0BH

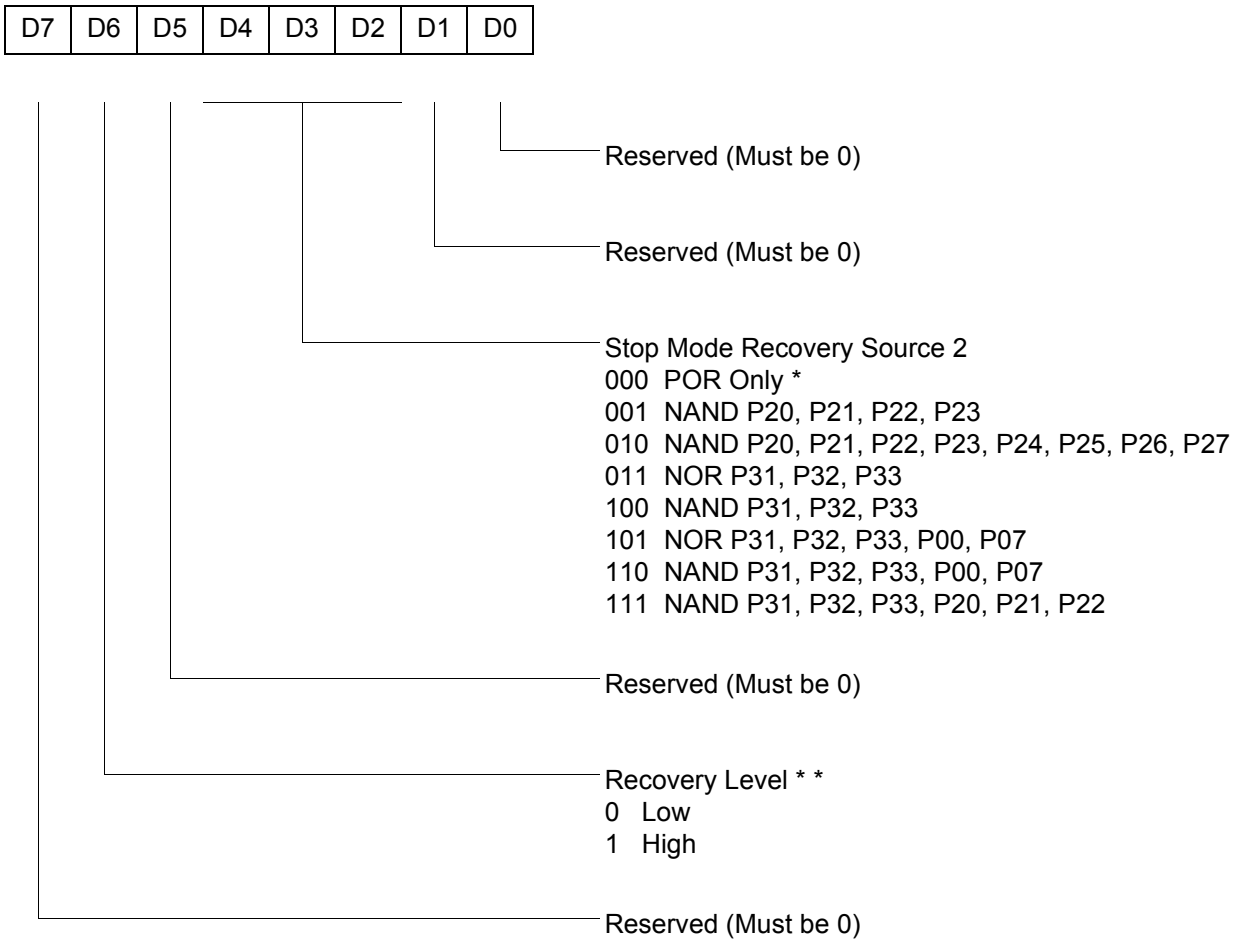
D7	D6	D5	D4	D3	D2	D1	D0



*Default setting after Reset
* *Set after Stop Mode Recovery
* * *At the XOR gate input
* * * *Default setting after Reset. Must be 1 if using a crystal or resonator clock source.
* * * * *Default setting after Power-On Reset. Not Reset with a Stop Mode Recovery.

Figure 43. Stop Mode Recovery Register ((0F)0BH: D6–D0=Write Only, D7=Read Only)

SMR2(0F)0DH



If used in conjunction with SMR, either of the two specified events causes a Stop Mode Recovery.
*Default setting after reset. Not Reset with a Stop Mode Recovery.
* *At the XOR gate input

Figure 44. Stop Mode Recovery Register 2 ((0F)0DH:D2–D4, D6 Write Only)

R250 IRQ(FAH)

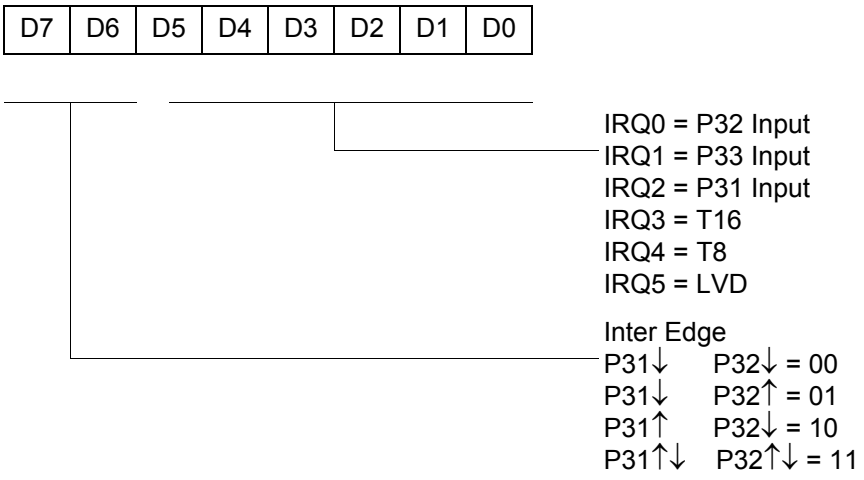
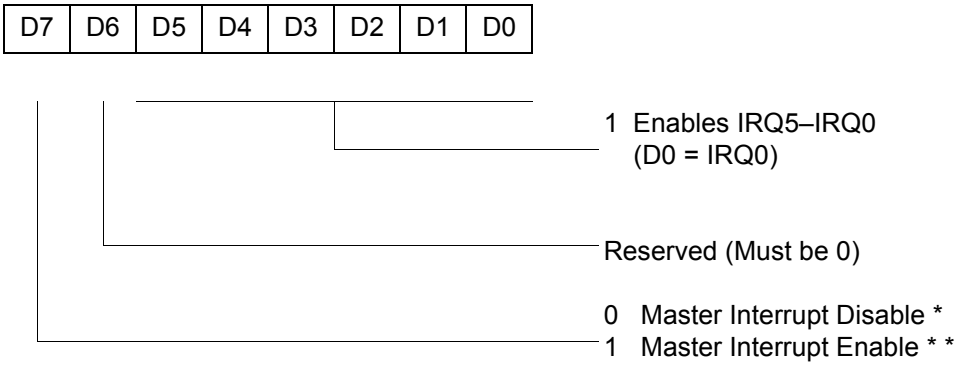


Figure 50. Interrupt Request Register (FAH: Read/Write)

R251 IMR(FBH)



*Default setting after reset
* *Only by using EI, DI instruction; DI is required before changing the IMR register

Figure 51. Interrupt Mask Register (FBH: Read/Write)

Electrical Characteristics

Absolute Maximum Ratings

Stresses greater than those listed in Table 18 might cause permanent damage to the device. This rating is a stress rating only. Functional operation of the device at any condition above those indicated in the operational sections of these specifications is not implied. Exposure to absolute maximum rating conditions for an extended period might affect device reliability.

Table 17. Absolute Maximum Ratings

Parameter	Minimum	Maximum	Units	Notes
Ambient temperature under bias	0	+70	C	
Storage temperature	–65	+150	C	
Voltage on any pin with respect to V_{SS}	–0.3	+5.5	V	1
Voltage on V_{DD} pin with respect to V_{SS}	–0.3	+3.6	V	
Maximum current on input and/or inactive output pin	–5	+5	µA	
Maximum output current from active output pin	–25	+25	mA	
Maximum current into V_{DD} or out of V_{SS}		75	mA	

[1]This voltage applies to all pins except the following: V_{DD}, P32, P33 and $\overline{\text{RESET}}$.

Standard Test Conditions

The characteristics listed in this product specification apply for standard test conditions as noted. All voltages are referenced to GND. Positive current flows into the referenced pin (see Figure 56).

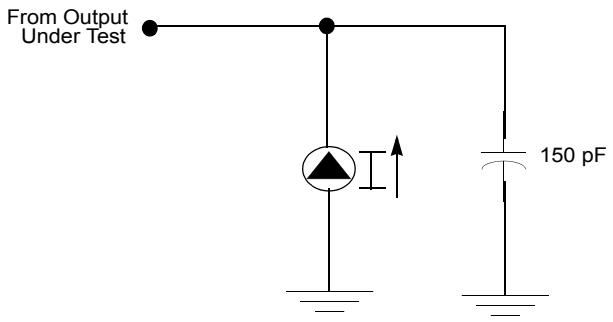
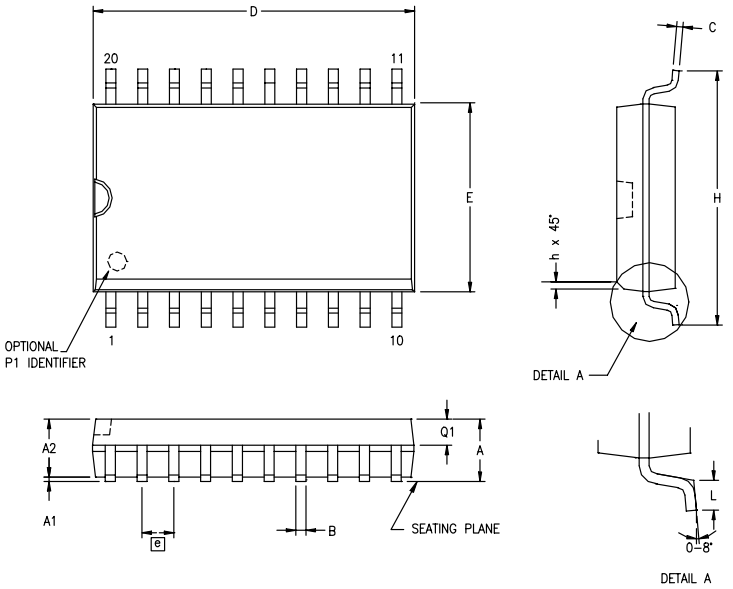


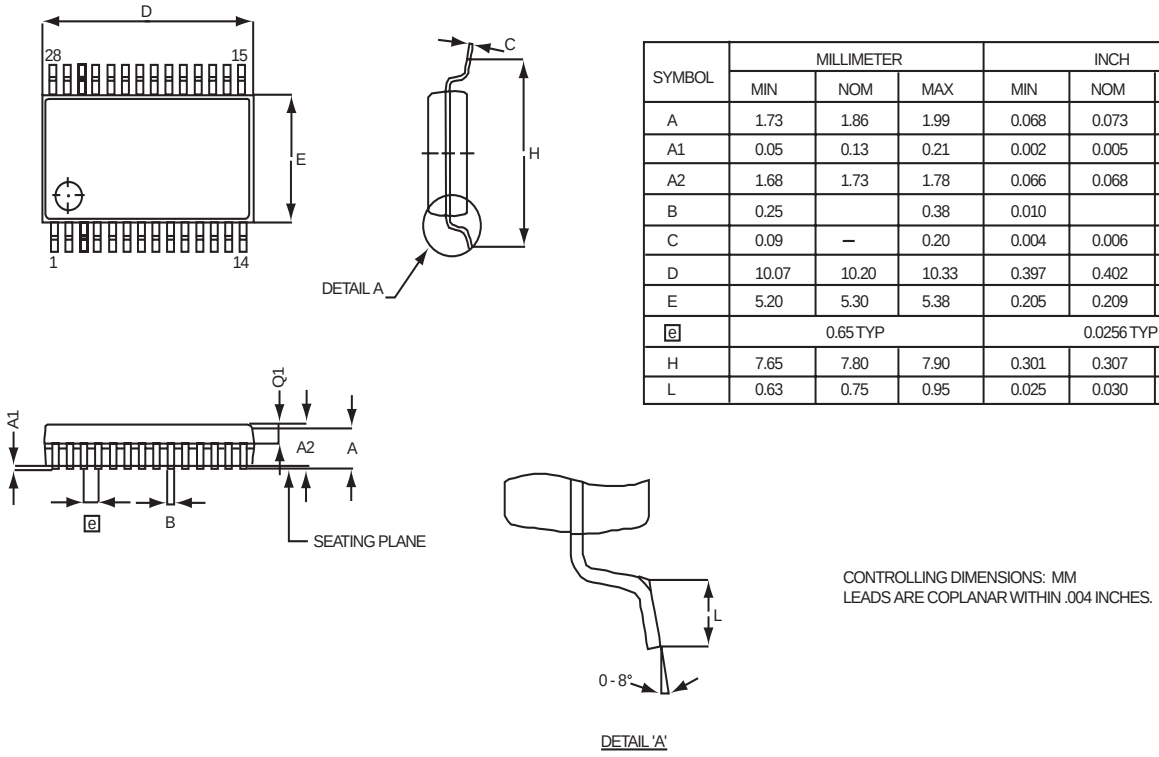
Figure 56. Test Load Diagram



SYMBOL	MILLIMETER		INCH	
	MIN	MAX	MIN	MAX
A	2.40	2.65	.094	.104
A1	0.10	0.30	.004	.012
A2	2.24	2.44	.088	.096
B	0.36	0.46	.014	.018
C	0.23	0.30	.009	.012
D	12.60	12.95	**.496**	.510
E	7.40	7.60	.291	.299
e	1.27 BSC		.050 BSC	
H	10.00	10.65	.394	.419
h	0.30	0.40	.012	.016
L	0.60	1.00	.024	.039
Q1	0.97	1.07	.038	.042

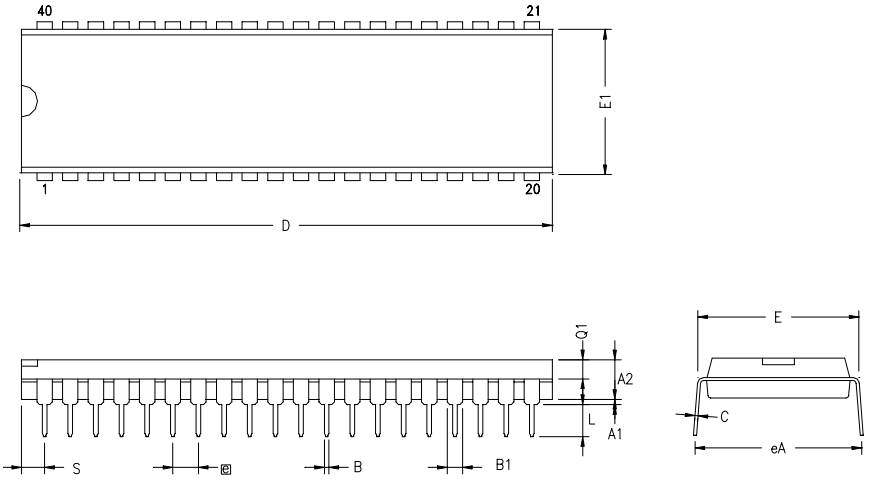
CONTROLLING DIMENSIONS : MM
LEADS ARE COPLANAR WITHIN .004 INCH.

Figure 59. 20-Pin SOIC Package Diagram



SYMBOL	MILLIMETER			INCH		
	MIN	NOM	MAX	MIN	NOM	MAX
A	1.73	1.86	1.99	0.068	0.073	0.078
A1	0.05	0.13	0.21	0.002	0.005	0.008
A2	1.68	1.73	1.78	0.066	0.068	0.070
B	0.25		0.38	0.010		0.015
C	0.09	–	0.20	0.004	0.006	0.008
D	10.07	10.20	10.33	0.397	0.402	0.407
E	5.20	5.30	5.38	0.205	0.209	0.212
e	0.65 TYP			0.0256 TYP		
H	7.65	7.80	7.90	0.301	0.307	0.311
L	0.63	0.75	0.95	0.025	0.030	0.037

Figure 63. 28-Pin SSOP Package Diagram



SYMBOL	MILLIMETER		INCH	
	MIN	MAX	MIN	MAX
A1	0.51	1.02	.020	.040
A2	3.18	3.94	.125	.155
B	0.38	0.53	.015	.021
B1	1.02	1.52	.040	.060
C	0.23	0.38	.009	.015
D	52.07	52.58	2.050	2.070
E	15.24	15.75	.600	.620
E1	13.59	14.22	.535	.560
e	2.54 TYP		.100 TYP	
eA	15.49	16.76	.610	.660
L	3.05	3.81	.120	.150
Q1	1.40	1.91	.055	.075
S	1.52	2.29	.060	.090

CONTROLLING DIMENSIONS : INCH

Figure 64. 40-Pin PDIP Package Diagram

Customer Support

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For any comments, detail technical questions, or reporting problems, please visit Zilog's Technical Support at http://support.zilog.com.