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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Discontinued at Digi-Key
Core Processor	Z8
Core Size	8-Bit
Speed	8MHz
Connectivity	-
Peripherals	Brown-out Detect/Reset, HLVD, POR, WDT
Number of I/O	32
Program Memory Size	32KB (32K x 8)
Program Memory Type	OTP
EEPROM Size	-
RAM Size	237 x 8
Voltage - Supply (Vcc/Vdd)	2V ~ 3.6V
Data Converters	-
Oscillator Type	Internal
Operating Temperature	0°C ~ 70°C (TA)
Mounting Type	Surface Mount
Package / Case	48-BSSOP (0.295", 7.50mm Width)
Supplier Device Package	-
Purchase URL	https://www.e-xfl.com/product-detail/zilog/zlp32300h4832c

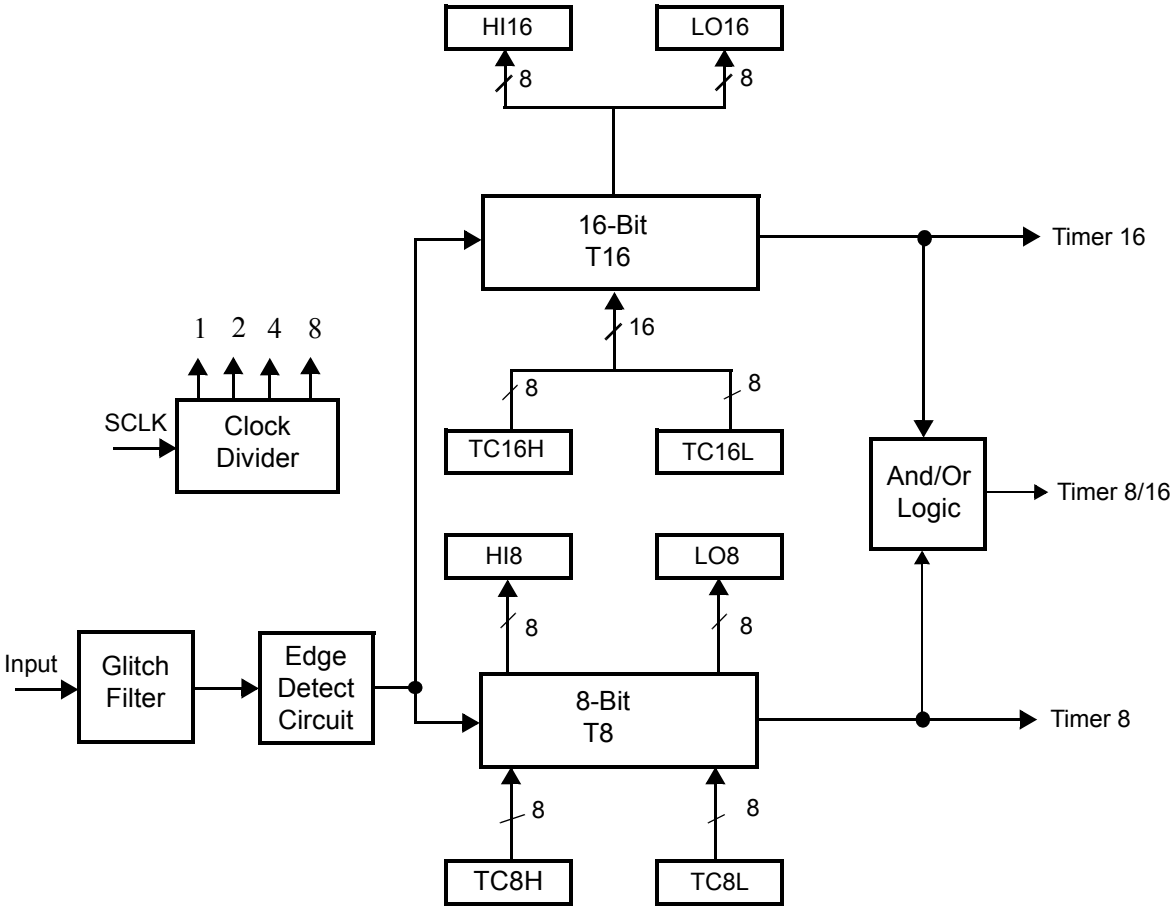


Figure 2. Counter/Timers Diagram

Table 5. 40- and 48-Pin Configuration (Continued)

40-Pin PDIP No	48-Pin SSOP No	Symbol
	14	NC
	30	NC
	36	NC

Pin Functions

XTAL1 Crystal 1 (Time-Based Input)

This pin connects a parallel-resonant crystal or ceramic resonator to the on-chip oscillator input. Additionally, an optional external single-phase clock can be coded to the on-chip oscillator input.

XTAL2 Crystal 2 (Time-Based Output)

This pin connects a parallel-resonant crystal or ceramic resonant to the on-chip oscillator output.

Input/Output Ports

Caution: *The CMOS input buffer for each Port 0, 1, or 2 pin is always connected to the pin, even when the pin is configured as an output. If the pin is configured as an open-drain output and no external signal is applied, a High output state can cause the CMOS input buffer to float. This might lead to excessive leakage current of more than 100 µA. To prevent this leakage, connect the pin to an external signal with a defined logic level or ensure its output state is Low, especially during STOP mode.*

Internal pull-ups are disabled on any given pin or group of port pins when programmed into output mode.

Port 0, 1, and 2 have both input and output capability. The input logic is always present no matter whether the port is configured as input or output. When doing a READ instruction, the MCU reads the actual value at the input logic but not from the output buffer. In addition, the instructions of OR, AND, and XOR have the Read-Modify-Write sequence. The MCU first reads the port, and then modifies the value and load back to the port.

Precaution must be taken if the port is configured as open-drain output or if the port is driving any circuit that makes the voltage different from the desired output logic. For example, pins P00–P07 are not connected to anything else. If it is configured as

```
LD                      R1, 2                   ; CTR2→CTR1

LD                      RP, #0Dh                ; Select ERF D
for access to bank D
                                                ; (working
register group 0)
LD                      RP, #7Dh                ; Select
expanded register bank D and working            ; register
group 7 of bank 0 for access.
LD                      71h, 2
; CTRL2→register 71h
LD                      R1, 2
; CTRL2→register 71h
```

Register File

The register file (bank 0) consists of 4 I/O port registers, 237 general-purpose registers, 16 control and status registers (R0–R3, R4–R239, and R240–R255, respectively), and two expanded registers groups in Banks D (see Table 7 on page 27) and F. Instructions can access registers directly or indirectly through an 8-bit address field, thereby allowing a short, 4-bit register address to use the Register Pointer (see Figure 15). In the 4-bit mode, the register file is divided into 16 working register groups, each occupying 16 continuous locations. The Register Pointer addresses the starting location of the active working register group.

Note: *Working register group E0–EF can only be accessed through working registers and indirect addressing modes.*

Table 8. CTR1(0D)01h T8 and T16 Common Functions

Field	Bit Position		Value	Description
Mode	7-------	R/W	0*	TRANSMIT Mode
			1	DEMODULATION Mode
P36_Out/ Demodulator_Input	-6------	R/W		TRANSMIT Mode
			0*	Port Output
			1	T8/T16 Output
				DEMODULATION Mode
			0*	P31
			1	P20
T8/T16_Logic/ Edge _Detect	--54----	R/W		TRANSMIT Mode
			00**	AND
			01	OR
			10	NOR
			11	NAND
				DEMODULATION Mode
			00**	Falling Edge
			01	Rising Edge
			10	Both Edges
			11	Reserved
Transmit_Submode/ Glitch_Filter	----32--	R/W		TRANSMIT Mode
			00*	Normal Operation
			01	PING-PONG Mode
			10	T16_Out = 0
			11	T16_Out = 1
				DEMODULATION Mode
			00*	No Filter
			01	4 SCLK Cycle
			10	8 SCLK Cycle
			11	Reserved
Initial_T8_Out/ Rising Edge	------1-			TRANSMIT Mode
		R/W	0*	T8_OUT is 0 Initially
			1	T8_OUT is 1 Initially
				DEMODULATION Mode
		R	0*	No Rising Edge
			1	Rising Edge Detected
		W	0	No Effect
			1	Reset Flag to 0

Initial_T8_Out/Rising_Edge

In TRANSMIT mode, if 0, the output of T8 is set to 0 when it starts to count. If 1, the output of T8 is set to 1 when it starts to count. When the counter is not enabled and this bit is set to 1 or 0, T8_OUT is set to the opposite state of this bit. This ensures that when the clock is enabled, a transition occurs to the initial state set by CTR1, D1.

In DEMODULATION mode, this bit is set to 1 when a rising edge is detected in the input signal. In order to reset the mode, a 1 should be written to this location.

Initial_T16 Out/Falling _Edge

In TRANSMIT mode, if it is 0, the output of T16 is set to 0 when it starts to count. If it is 1, the output of T16 is set to 1 when it starts to count. This bit is effective only in Normal or PING-PONG mode (CTR1, D3; D2). When the counter is not enabled and this bit is set, T16_OUT is set to the opposite state of this bit. This ensures that when the clock is enabled, a transition occurs to the initial state set by CTR1, D0.

In DEMODULATION mode, this bit is set to 1 when a falling edge is detected in the input signal. In order to reset it, a 1 should be written to this location.

Note: *Modifying CTR1 (D1 or D0) while the counters are enabled causes unpredictable output from T8/16_OUT.*

CTR2 Counter/Timer 16 Control Register—CTR2(D)02h

Table 9 lists and briefly describes the fields for this register.

Table 9. CTR2(D)02h: Counter/Timer16 Control Register

Field	Bit Position		Value	Description
T16_Enable	7-------	R	0*	Counter Disabled
			1	Counter Enabled
		W	0	Stop Counter
			1	Enable Counter
Single/Modulo-N	-6------	R/W		TRANSMIT Mode
			0*	Modulo-N
			1	Single Pass
				DEMODULATION Mode
			0	T16 Recognizes Edge
			1	T16 Does Not Recognize Edge
Time_Out	--5-----	R	0*	No Counter Timeout
			1	Counter Timeout Occurred
		W	0	No Effect
			1	Reset Flag to 0

Caution: *Using the same instructions for stopping the counter/timers and setting the status bits is not recommended.*

Two successive commands are necessary. First, the counter/timers must be stopped. Second, the status bits must be reset. These commands are required because it takes one counter/timer clock interval for the initiated event to actually occur, see Figure 19 and Figure 20.

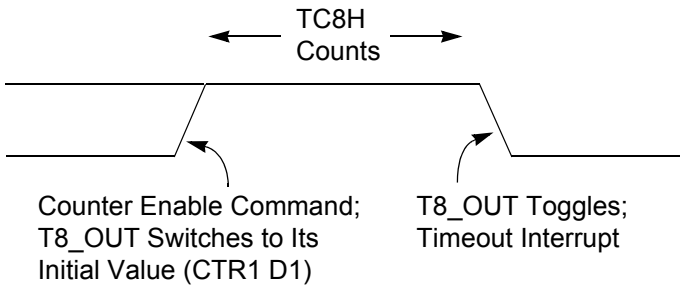


Figure 19. T8_OUT in SINGLE-PASS Mode

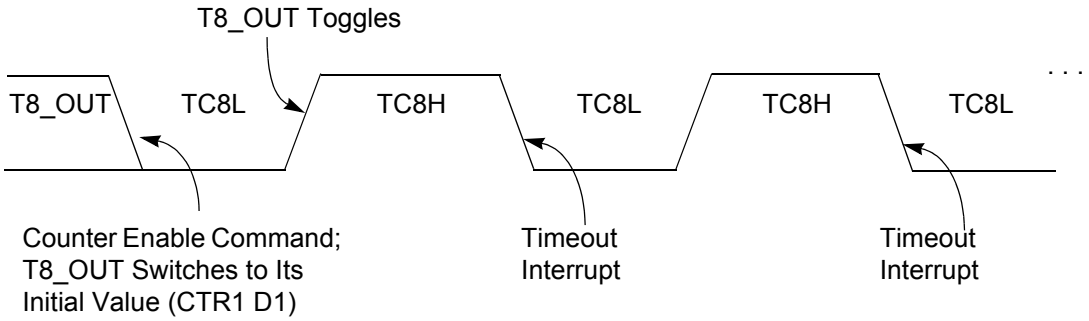


Figure 20. T8_OUT in MODULO-N Mode

T8 DEMODULATION Mode

You must program TC8L and TC8H to FFh. After T8 is enabled, when the first edge (rising, falling, or both depending on CTR1, D5; D4) is detected, it starts to count down. When a subsequent edge (rising, falling, or both depending on CTR1, D5; D4) is detected during counting, the current value of T8 is complemented and put into one of the capture registers. If it is a positive edge, data is put into LO8; if it is a negative edge, data is put into HI8. From that point, one of the edge detect status bits (CTR1, D1; D0) is set, and an interrupt can be generated if enabled (CTR0, D2). Meanwhile, T8 is loaded with FFh and starts counting again. If T8 reaches 0, the time-out status bit (CTR0, D5) is set, and an

Caution: *Do not load these registers at the time the values are to be loaded into the counter/timer to ensure known operation. An initial count of 1 is not allowed. An initial count of 0 causes T16 to count from 0 to* FFFFh *to* FFFEh. *Transition from 0 to* FFFFh *is not a timeout condition.*

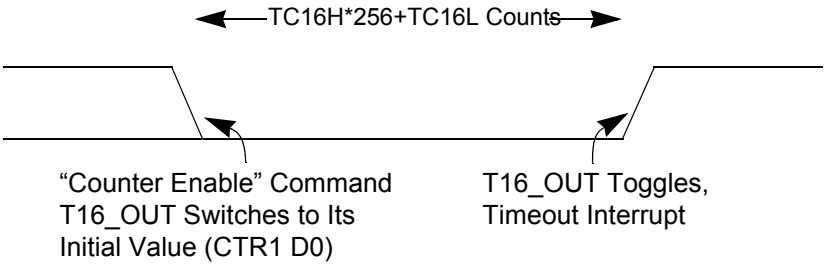


Figure 24. T16_OUT in SINGLE-PASS Mode

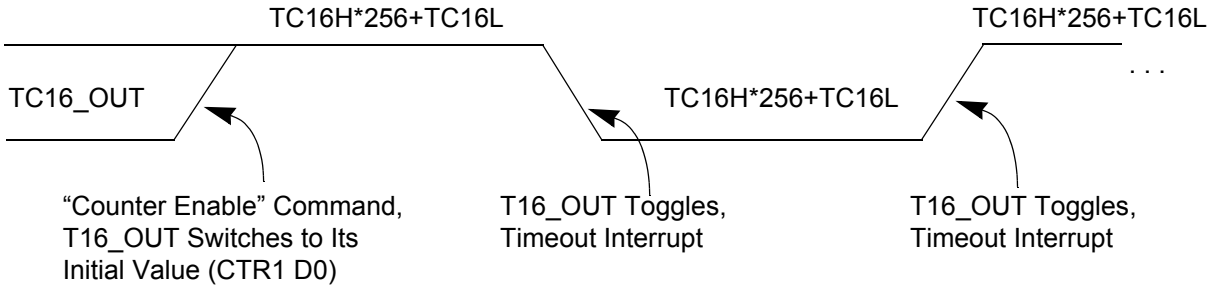


Figure 25. T16_OUT in MODULO-N Mode

T16 DEMODULATION Mode

You must program TC16L and TC16H to FFh. After T16 is enabled, and the first edge (rising, falling, or both depending on CTR1 D5; D4) is detected, T16 captures HI16 and LO16, reloads, and begins counting.

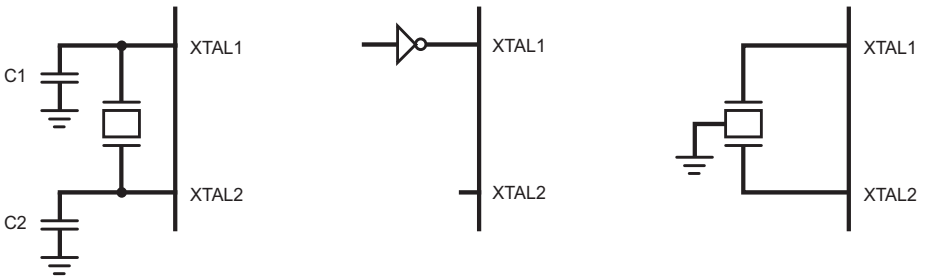
If D6 of CTR2 Is 0

When a subsequent edge (rising, falling, or both depending on CTR1, D5; D4) is detected during counting, the current count in T16 is complemented and put into HI16 and LO16. When data is captured, one of the edge detect status bits (CTR1, D1; D0) is set, and an interrupt is generated if enabled (CTR2, D2). T16 is loaded with FFFFh and starts again.

Clock

The device's on-chip oscillator has a high-gain, parallel-resonant amplifier, for connection to a crystal, ceramic resonator, or any suitable external clock source (XTAL1 = Input, XTAL2 = Output). The crystal must be AT cut, 1 MHz to 8 MHz maximum, with a series resistance (RS) less than or equal to 100 Ω. The on-chip oscillator can be driven with a suitable external clock source.

The crystal must be connected across XTAL1 and XTAL2 using the recommended capacitors from each pin to ground. The typical capacitor value is 10 pF for 8 MHz. Also check with the crystal supplier for the optimum capacitance.



Crystal
C1, C2 = 10 pF *
f = 8 MHz

External Clock

Ceramic Resonator f = 8 MHz

*Note: preliminary value.

Figure 29. Oscillator Configuration

Zilog's IR MCU supports crystal, resonator, and oscillator. Most resonators have a frequency tolerance of less than ±0.5%, which is enough for remote control application. Resonator has a very fast startup time, which is around few hundred microseconds. Most crystals have a frequency tolerance of less than 50 ppm (±0.005%). However, crystal needs longer startup time than the resonator. The large loading capacitance slows down the oscillation startup time. Zilog® suggests not to use more than 10 pF loading capacitor for the crystal. If the stray capacitance of the PCB or the crystal is high, the loading capacitance C1 and C2 must be reduced further to ensure stable oscillation before the T_{POR} (Power-On Reset time is typically 5-6 ms, see Table 20 on page 79).

For Stop Mode Recovery operation, bit 5 of SMR register allows you to select the Stop Mode Recovery delay, which is the T_{POR}. If Stop Mode Recovery delay is not selected, the MCU executes instruction immediately after it wakes up from the STOP mode. If resonator or crystal is used as a clock source then Stop Mode Recovery delay needs to be selected (bit 5 of SMR = 1).

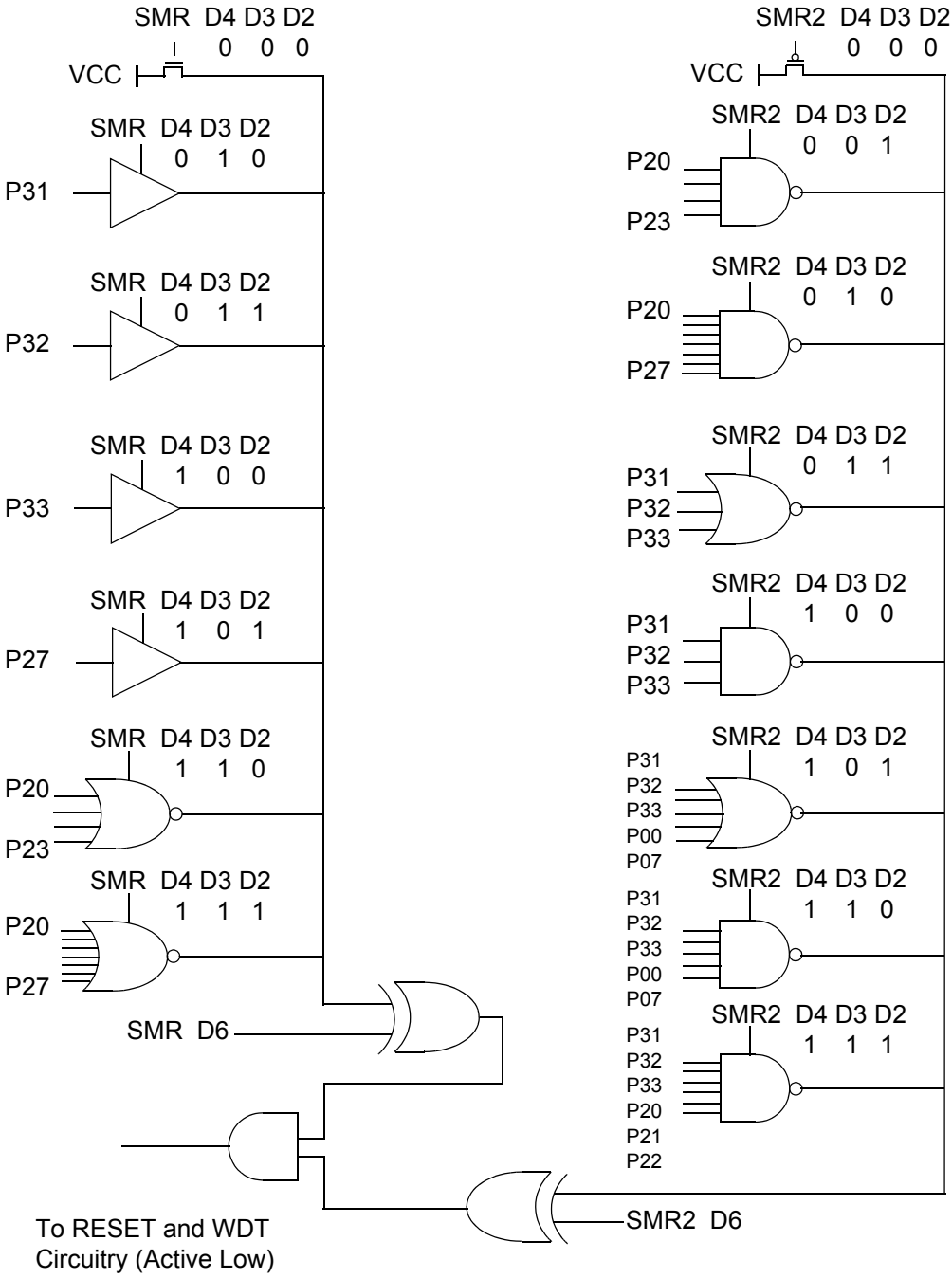


Figure 33. Stop Mode Recovery Source

Notes:

1. *Ensure to differentiate the TRANSMIT mode from DEMODULATION mode. Depending on which of these two modes is operating, the CTR1 bit has different functions.*
2. *Changing from one mode to another cannot be performed without disabling the counter/timers.*

CTR2(0D)02H

D7	D6	D5	D4	D3	D2	D1	D0

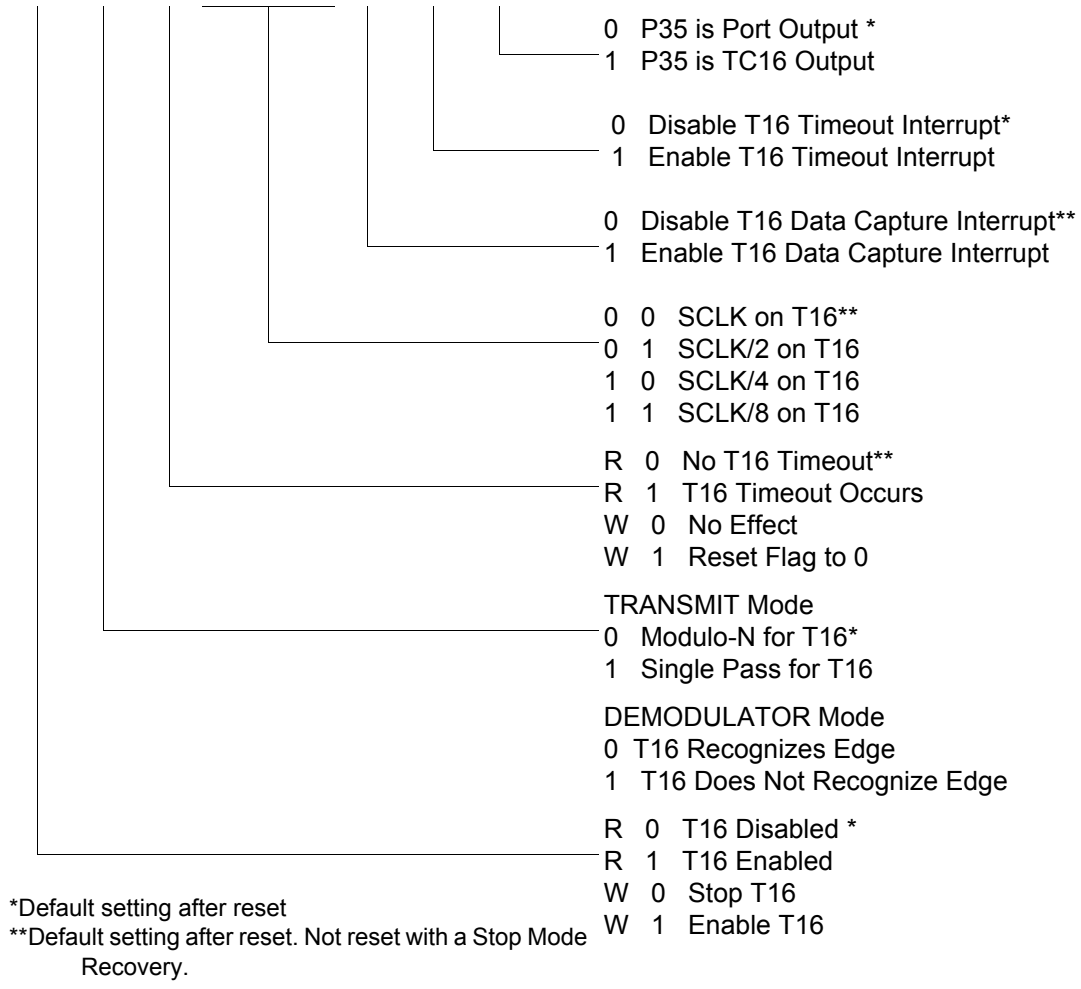
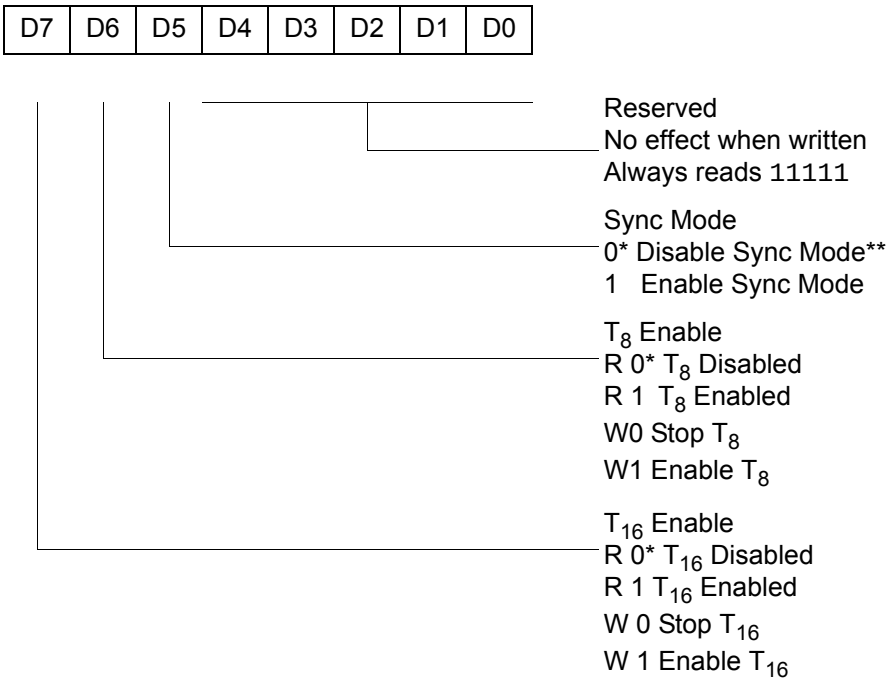


Figure 39. T16 Control Register ((0D) 2H: Read/Write Except Where Noted)

CTR3(0D)03H



*Default setting after reset.
**Default setting after reset. Not reset with a Stop Mode Recovery.

Figure 40. T8/T16 Control Register (0D)03H: Read/Write (Except Where Noted)

Note: *If Sync Mode is enabled, the first pulse of T8 carrier is always synchronized with T16 (demodulated signal). It can always provide a full carrier pulse.*

Standard Control Registers

The standard control registers are displayed in Figure 46 through Figure 55 on page 74.

R246 P2M(F6H)

D7	D6	D5	D4	D3	D2	D1	D0

P27–P20 I/O Definition
0 Defines bit as OUTPUT
1 Defines bit as INPUT *

*Default setting after reset. Not Reset with a Stop Mode Recovery.

Figure 46. Port 2 Mode Register (F6H: Write Only)

R247 P3M(F7H)

D7	D6	D5	D4	D3	D2	D1	D0

0: Port 2 Open Drain *
1: Port 2 Push-Pull

0= P31, P32 DIGITAL Mode*
1= P31, P32 ANALOG Mode

Reserved (Must be 0)

*Default setting after reset. Not Reset with a Stop Mode Recovery.

Figure 47. Port 3 Mode Register (F7H: Write Only)

R250 IRQ(FAH)

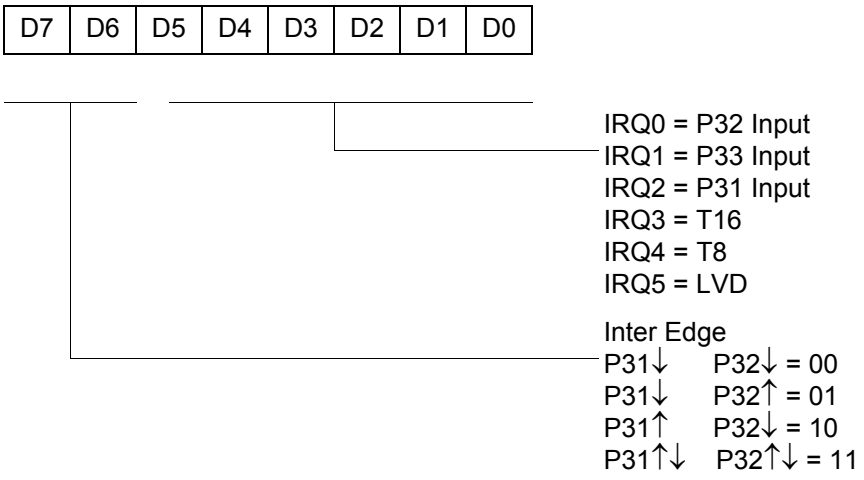
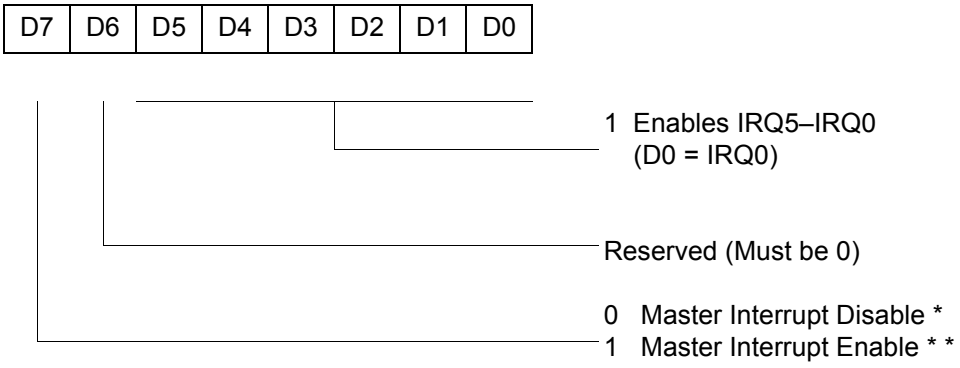


Figure 50. Interrupt Request Register (FAH: Read/Write)

R251 IMR(FBH)



*Default setting after reset
* *Only by using EI, DI instruction; DI is required before changing the IMR register

Figure 51. Interrupt Mask Register (FBH: Read/Write)

R254 SPH(FEH)

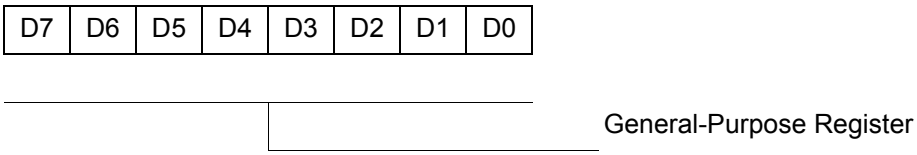


Figure 54. Stack Pointer High (FEH: Read/Write)

R255 SPL(FFH)

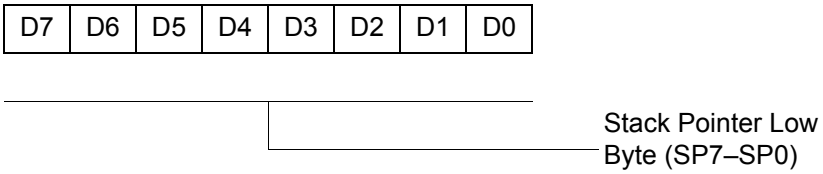


Figure 55. Stack Pointer Low (FFH: Read/Write)

Electrical Characteristics

Absolute Maximum Ratings

Stresses greater than those listed in Table 18 might cause permanent damage to the device. This rating is a stress rating only. Functional operation of the device at any condition above those indicated in the operational sections of these specifications is not implied. Exposure to absolute maximum rating conditions for an extended period might affect device reliability.

Table 17. Absolute Maximum Ratings

Parameter	Minimum	Maximum	Units	Notes
Ambient temperature under bias	0	+70	C	
Storage temperature	–65	+150	C	
Voltage on any pin with respect to V_{SS}	–0.3	+5.5	V	1
Voltage on V_{DD} pin with respect to V_{SS}	–0.3	+3.6	V	
Maximum current on input and/or inactive output pin	–5	+5	µA	
Maximum output current from active output pin	–25	+25	mA	
Maximum current into V_{DD} or out of V_{SS}		75	mA	

[1]This voltage applies to all pins except the following: V_{DD}, P32, P33 and $\overline{\text{RESET}}$.

Standard Test Conditions

The characteristics listed in this product specification apply for standard test conditions as noted. All voltages are referenced to GND. Positive current flows into the referenced pin (see Figure 56).

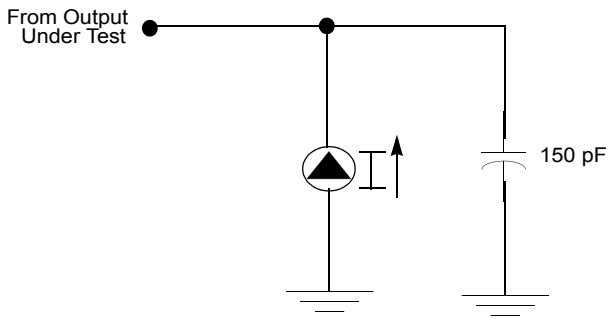
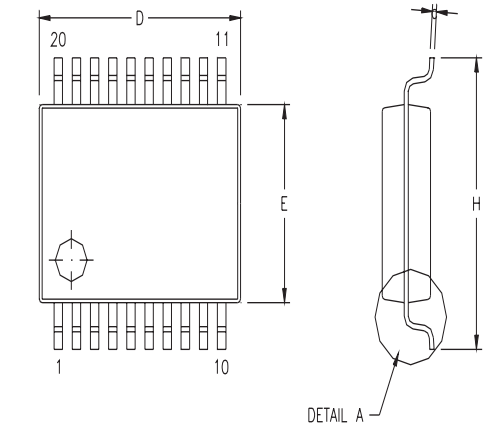


Figure 56. Test Load Diagram

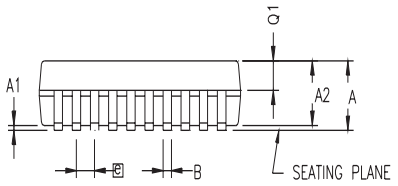
Table 20. AC Characteristics

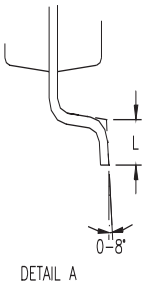
			T_A=0 °C to +70 °C 8.0 MHz					Watchdog Timer Mode Register (D1, D0)
No	**Symbol**	**Parameter**	**V_{CC}**	**Minimum**	**Maximum**	**Units**	**Notes**	
1	TpC	Input Clock Period	2.0–3.6	121	DC	ns	1	
2	TrC,TfC	Clock Input Rise and Fall Times	2.0–3.6		25	ns	1	
3	TwC	Input Clock Width	2.0–3.6	37		ns	1	
4	TwTinL	Timer Input Low Width	2.0 3.6	100 70		ns	1	
5	TwTinH	Timer Input High Width	2.0–3.6	3TpC			1	
6	TpTin	Timer Input Period	2.0–3.6	8TpC			1	
7	TrTin,TfTin	Timer Input Rise and Fall Timers	2.0–3.6		100	ns	1	
8	TwIL	Interrupt Request Low Time	2.0 3.6	100 70		ns	1, 2	
9	TwIH	Interrupt Request Input High Time	2.0–3.6	5TpC			1, 2	
10	Twsm	Stop Mode Recovery Width Spec	2.0–3.6	12 10TpC		ns	3 4	
11	Tost	Oscillator Start-Up Time	2.0–3.6		5TpC		4	
12	Twdt	Watchdog Timer Delay Time	2.0–3.6 2.0–3.6 2.0–3.6 2.0–3.6	5 10 20 80		ms ms ms ms		0, 0 0, 1 1, 0 1, 1
13	T_{POR}	Power-on reset	2.0–3.6	2.5	10	ms		

Notes
1. Timing Reference uses 0.9 V_{CC} for a logic 1 and 0.1 V_{CC} for a logic 0.
2. Interrupt request through Port 3 (P33–P31).
3. SMR–D5 = 1.
4. SMR–D5 = 0.



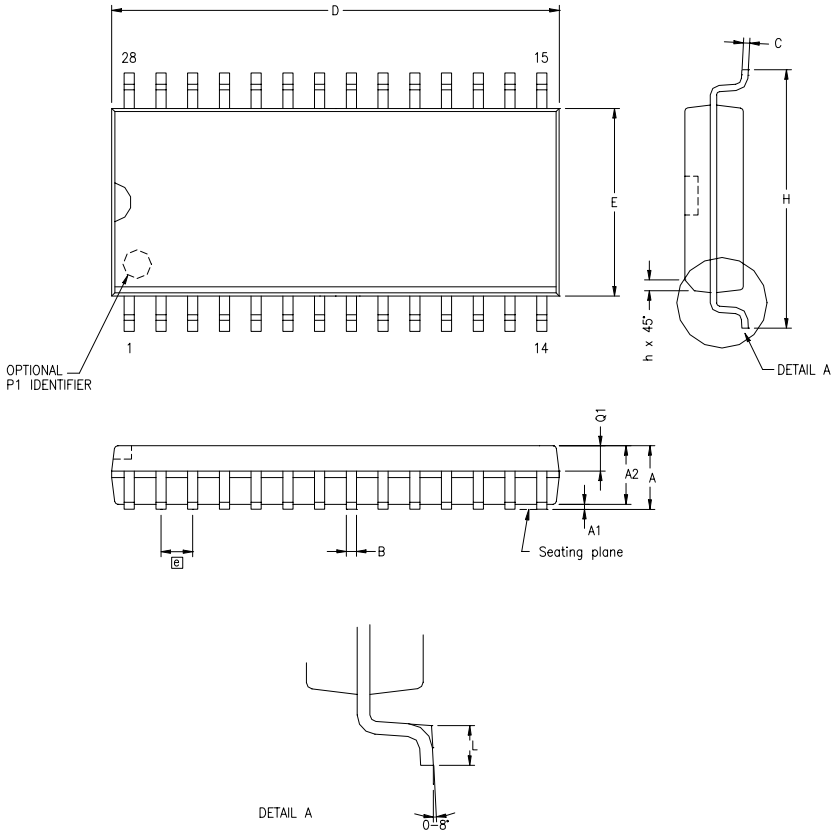
SYMBOL	MILLIMETER			INCH		
	MIN	NOM	MAX	MIN	NOM	MAX
A	1.73	1.85	1.98	0.068	0.073	0.078
A1	0.05	0.13	0.21	0.002	0.005	0.008
A2	1.68	1.73	1.83	0.066	0.068	0.072
B	0.25	0.30	0.38	0.010	0.012	0.015
C	0.13	0.15	0.22	0.005	0.006	0.009
D	7.07	7.20	7.33	0.278	0.283	0.289
E	5.20	5.30	5.38	0.205	0.209	0.212
e	0.65 BSC			0.0256 BSC		
H	7.65	7.80	7.90	0.301	0.307	0.311
L	0.56	0.75	0.94	0.022	0.030	0.037
Q1	0.74	0.78	0.82	0.029	0.031	0.032





CONTROLLING DIMENSIONS : MM
LEADS ARE COPLANAR WITHIN .004 INCH.

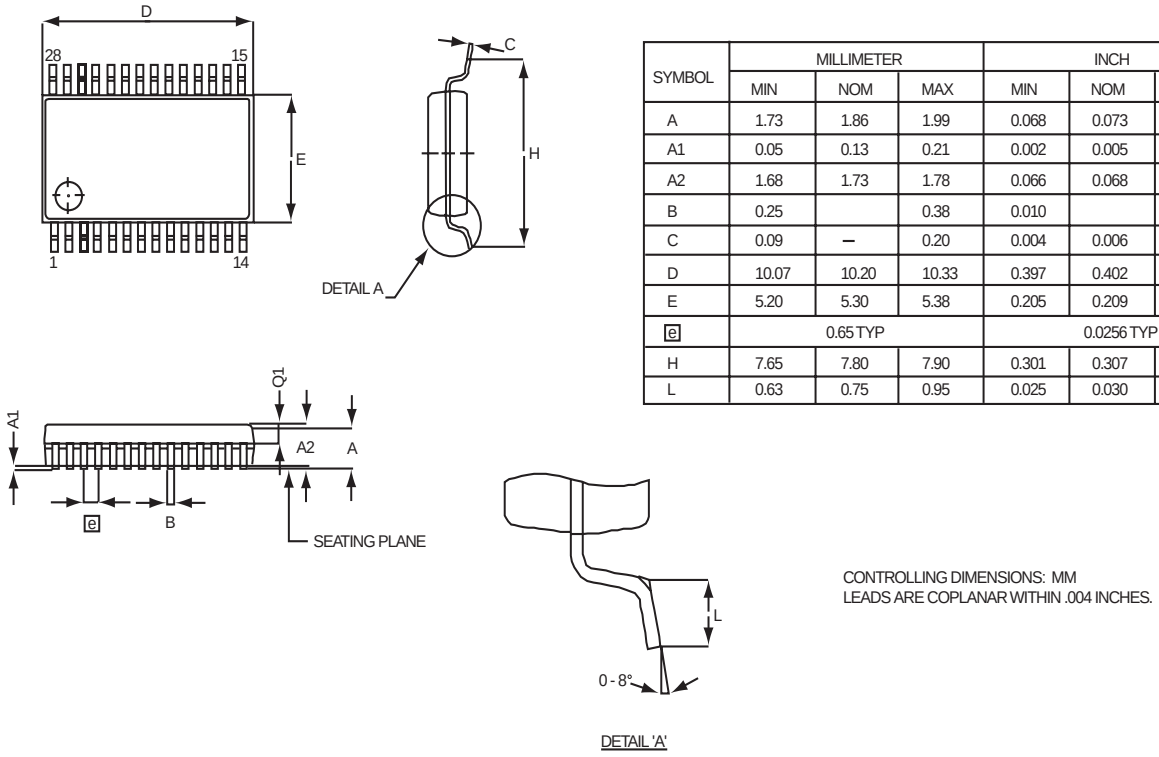
Figure 60. 20-Pin SSOP Package Diagram



SYMBOL	MILLIMETER		INCH	
	MIN	MAX	MIN	MAX
A	2.40	2.64	.094	.104
A1	0.10	0.30	.004	.012
A2	2.24	2.44	.088	.096
B	0.36	0.46	.014	.018
C	0.23	0.30	.009	.012
D	17.78	18.00	.700	.710
E	7.40	7.60	.291	.299
e	1.27 BSC		.050 BSC	
H	10.00	10.65	.394	.419
h	0.30	0.71	.012	.028
L	0.61	1.00	.024	.039
Q1	0.97	1.09	.038	.043

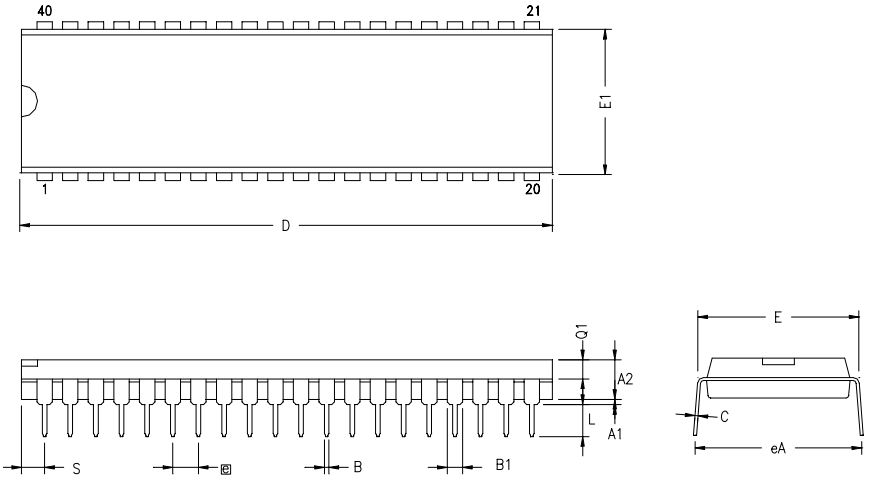
CONTROLLING DIMENSIONS : MM
LEADS ARE COPLANAR WITHIN .004 INCH.

Figure 61. 28-Pin SOIC Package Diagram



SYMBOL	MILLIMETER			INCH		
	MIN	NOM	MAX	MIN	NOM	MAX
A	1.73	1.86	1.99	0.068	0.073	0.078
A1	0.05	0.13	0.21	0.002	0.005	0.008
A2	1.68	1.73	1.78	0.066	0.068	0.070
B	0.25		0.38	0.010		0.015
C	0.09	–	0.20	0.004	0.006	0.008
D	10.07	10.20	10.33	0.397	0.402	0.407
E	5.20	5.30	5.38	0.205	0.209	0.212
e	0.65 TYP			0.0256 TYP		
H	7.65	7.80	7.90	0.301	0.307	0.311
L	0.63	0.75	0.95	0.025	0.030	0.037

Figure 63. 28-Pin SSOP Package Diagram



SYMBOL	MILLIMETER		INCH	
	MIN	MAX	MIN	MAX
A1	0.51	1.02	.020	.040
A2	3.18	3.94	.125	.155
B	0.38	0.53	.015	.021
B1	1.02	1.52	.040	.060
C	0.23	0.38	.009	.015
D	52.07	52.58	2.050	2.070
E	15.24	15.75	.600	.620
E1	13.59	14.22	.535	.560
e	2.54 TYP		.100 TYP	
eA	15.49	16.76	.610	.660
L	3.05	3.81	.120	.150
Q1	1.40	1.91	.055	.075
S	1.52	2.29	.060	.090

CONTROLLING DIMENSIONS : INCH

Figure 64. 40-Pin PDIP Package Diagram