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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

## Applications of "[Embedded - Microcontrollers](#)"

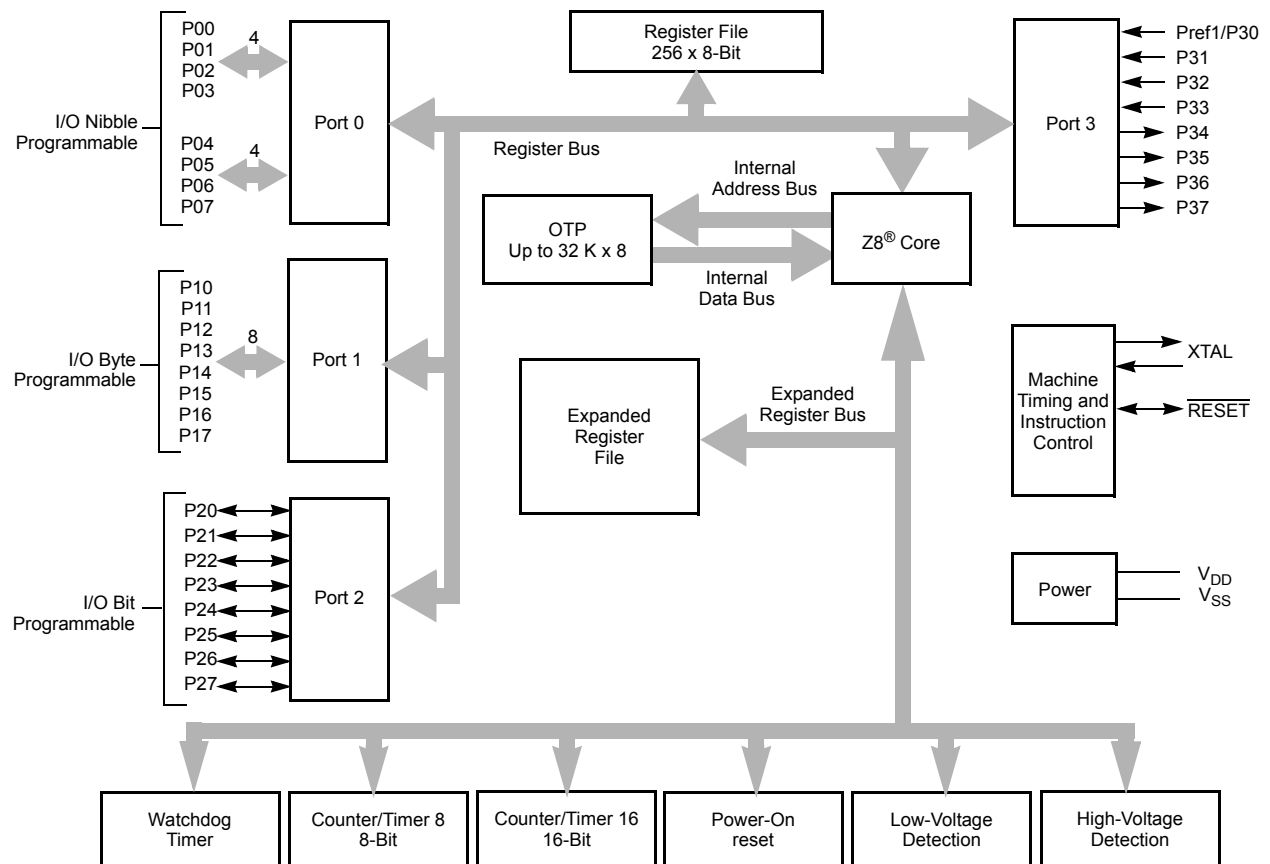
### Details

Product Status	Discontinued at Digi-Key
Core Processor	Z8
Core Size	8-Bit
Speed	8MHz
Connectivity	-
Peripherals	Brown-out Detect/Reset, HLVD, POR, WDT
Number of I/O	16
Program Memory Size	8KB (8K x 8)
Program Memory Type	OTP
EEPROM Size	-
RAM Size	237 x 8
Voltage - Supply (Vcc/Vdd)	2V ~ 3.6V
Data Converters	-
Oscillator Type	Internal
Operating Temperature	0°C ~ 70°C (TA)
Mounting Type	Through Hole
Package / Case	20-DIP (0.300", 7.62mm)
Supplier Device Package	20-PDIP
Purchase URL	<a href="https://www.e-xfl.com/product-detail/analog-devices/zlp32300p2008c">https://www.e-xfl.com/product-detail/analog-devices/zlp32300p2008c</a>

- Port 2: 0–7 pull-up transistors
- EPROM Protection
- WDT enabled at POR

## Functional Block Diagram

Figure 1 displays the Crimzon ZLP32300 MCU functional block diagram.

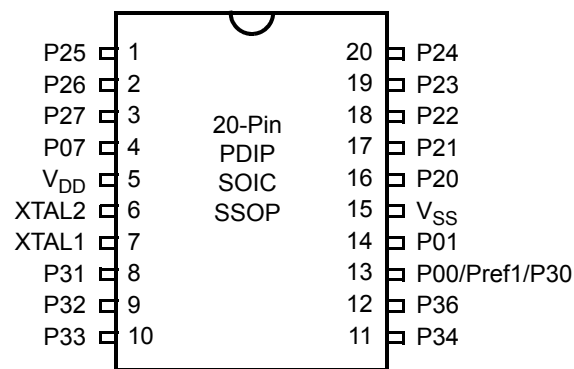


Note: Refer to the specific package for available pins.

**Figure 1. Crimzon ZLP32300 MCU Functional Block Diagram**

# Pin Description

The pin configuration for the 20-pin PDIP/SOIC/SSOP is displayed in Figure 3 and described in Table 3. The pin configuration for the 28-pin PDIP/SOIC/SSOP are depicted in Figure 4 and described in Table 4. The pin configurations for the 40-pin PDIP and 48-pin SSOP versions are displayed in Figure 5, Figure 6, and described in Table 5.



**Figure 3. 20-Pin PDIP/SOIC/SSOP Pin Configuration**

**Table 3. 20-Pin PDIP/SOIC/SSOP Pin Identification**

Pin No	Symbol	Function	Direction
1–3	P25–P27	Port 2, Bits 5,6,7	Input/Output
4	P07	Port 0, Bit 7	Input/Output
5	V <sub>DD</sub>	Power Supply	
6	XTAL2	Crystal Oscillator Clock	Output
7	XTAL1	Crystal Oscillator Clock	Input
8–10	P31–P33	Port 3, Bits 1,2,3	Input
11,12	P34, P36	Port 3, Bits 4,6	Output
13	P00/Pref1/P30	Port 0, Bit 0/Analog reference input Port 3 Bit 0	Input/Output for P00 Input for Pref1/P30
14	P01	Port 0, Bit 1	Input/Output
15	V <sub>SS</sub>	Ground	
16–20	P20–P24	Port 2, Bits 0,1,2,3,4	Input/Output

**Table 5. 40- and 48-Pin Configuration (Continued)**

40-Pin PDIP No	48-Pin SSOP No	Symbol
	14	NC
	30	NC
	36	NC

## Pin Functions

### XTAL1 Crystal 1 (Time-Based Input)

This pin connects a parallel-resonant crystal or ceramic resonator to the on-chip oscillator input. Additionally, an optional external single-phase clock can be coded to the on-chip oscillator input.

### XTAL2 Crystal 2 (Time-Based Output)

This pin connects a parallel-resonant crystal or ceramic resonator to the on-chip oscillator output.

## Input/Output Ports



**Caution:** *The CMOS input buffer for each Port 0, 1, or 2 pin is always connected to the pin, even when the pin is configured as an output. If the pin is configured as an open-drain output and no external signal is applied, a High output state can cause the CMOS input buffer to float. This might lead to excessive leakage current of more than 100  $\mu$ A. To prevent this leakage, connect the pin to an external signal with a defined logic level or ensure its output state is Low, especially during STOP mode.*

*Internal pull-ups are disabled on any given pin or group of port pins when programmed into output mode.*

*Port 0, 1, and 2 have both input and output capability. The input logic is always present no matter whether the port is configured as input or output. When doing a READ instruction, the MCU reads the actual value at the input logic but not from the output buffer. In addition, the instructions of OR, AND, and XOR have the Read-Modify-Write sequence. The MCU first reads the port, and then modifies the value and load back to the port.*

*Precaution must be taken if the port is configured as open-drain output or if the port is driving any circuit that makes the voltage different from the desired output logic. For example, pins P00–P07 are not connected to anything else. If it is configured as*

*open-drain output with output logic as ONE, it is a floating port and reads back as ZERO. The following instruction sets P00-P07 all Low.*

```
AND P0, #%F0
```

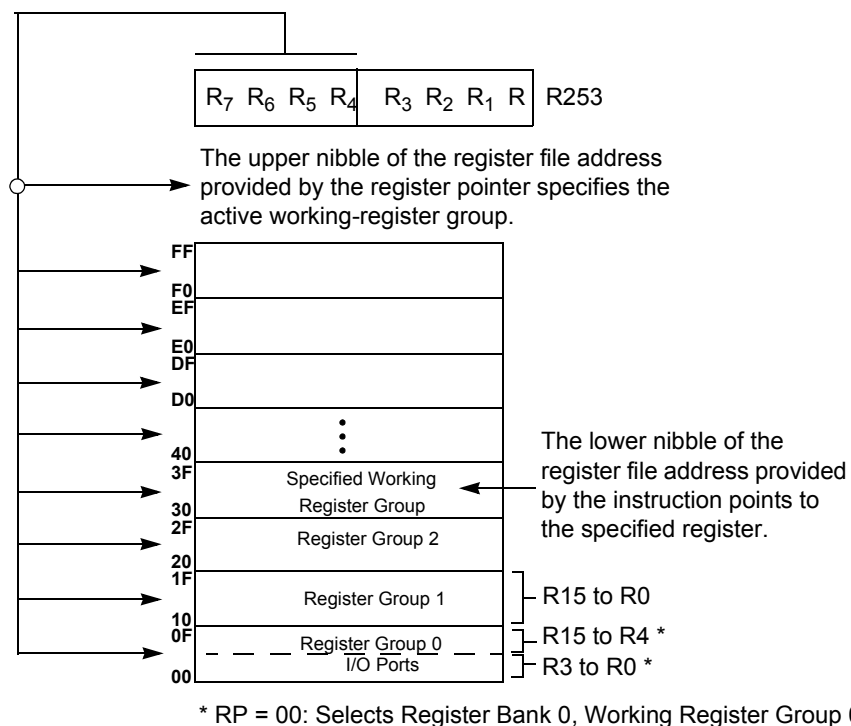
### Port 0 (P00–P07)

Port 0 is an 8-bit, bidirectional, CMOS-compatible port. These eight I/O lines are configured under software control as a nibble I/O port. The output drivers are push-pull or open-drain controlled by bit D2 in the PCON register.

If one or both nibbles are needed for I/O operation, they must be configured by writing to the Port 01 mode register (P01M). After a hardware reset or Stop Mode Recovery, Port 0 is configured as an input port.

An optional pull-up transistor is available as a OTP option bit on all Port 0 bits with nibble select.

► **Note:** *The Port 0 direction is reset to be input following an SMR.*



**Figure 15. Register Pointer—Detail**

## Stack

The internal register file is used for the stack. An 8-bit Stack Pointer SPL (R255) is used for the internal stack that resides in the general-purpose registers (R4–R239). SPH (R254) can be used as a general-purpose register.

## Timers

### T8\_Capture\_HI—HI8(D)0Bh

This register holds the captured data from the output of the 8-bit Counter/Timer0. Typically, this register holds the number of counts when the input signal is 1.

Field	Bit Position	Description
T8_Capture_HI	[7:0]	R/W Captured Data—No Effect

**Table 8. CTR1(0D)01h T8 and T16 Common Functions (Continued)**

Field	Bit Position		Value	Description
Initial_T16_Out/ Falling_Edge	-----0	R/W	0*	TRANSMIT Mode
			1	T16_OUT is 0 Initially
		R	0*	T16_OUT is 1 Initially
			1	DEMODULATION Mode
		W	0	No Falling Edge
			1	Falling Edge Detected
			0	No Effect
			1	Reset Flag to 0

\*Default at Power-On Reset

\*\*Default at Power-On Reset. Not reset with a Stop Mode Recovery.

**Mode**

If the result is 0, the counter/timers are in TRANSMIT mode; otherwise, they are in DEMODULATION mode.

**P36\_Out/Demodulator\_Input**

In TRANSMIT mode, this bit defines whether P36 is used as a normal output pin or the combined output of T8 and T16.

In DEMODULATION mode, this bit defines whether the input signal to the Counter/Timers is from P20 or P31.

If the input signal is from Port 31, a capture event may also generate an IRQ2 interrupt. To prevent generating an IRQ2, either disable the IRQ2 interrupt by clearing its IMR bit D2 or use P20 as the input.

**T8/T16\_Logic/Edge \_Detect**

In TRANSMIT mode, this field defines how the outputs of T8 and T16 are combined (AND, OR, NOR, NAND).

In DEMODULATION mode, this field defines which edge should be detected by the edge detector.

**Transmit\_Submode/Glitch Filter**

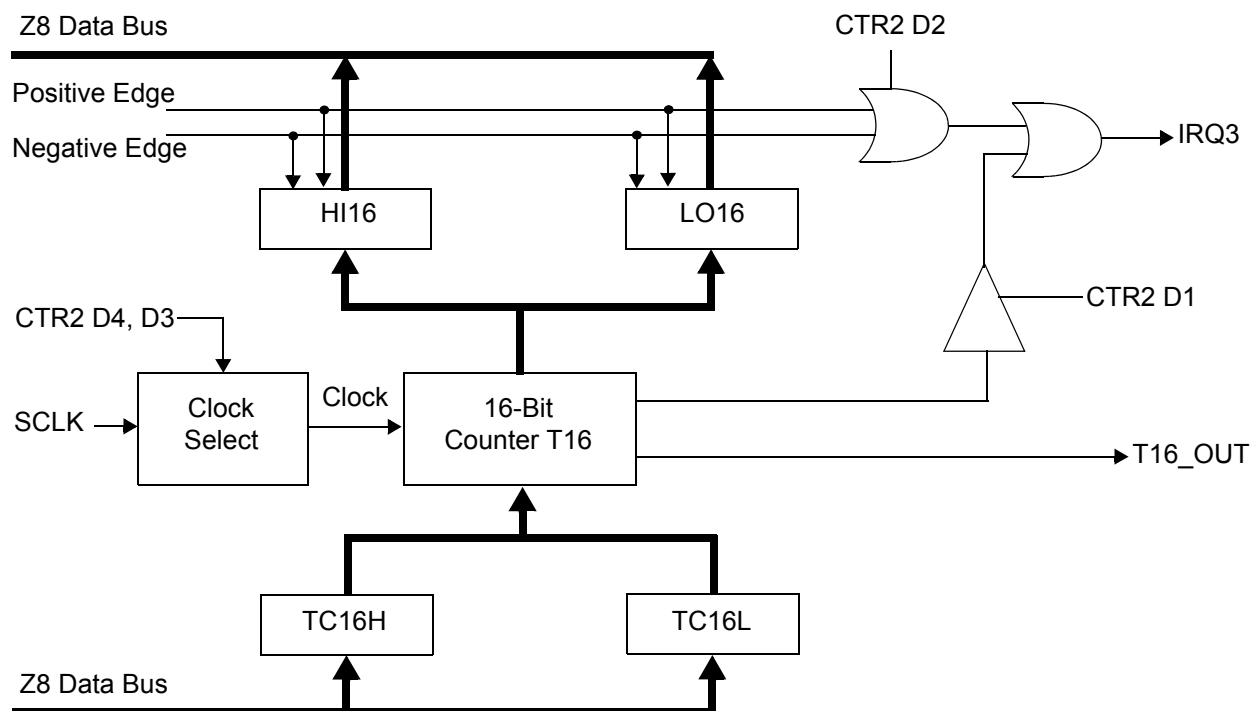
In TRANSMIT mode, this field defines whether T8 and T16 are in the PING-PONG mode or in independent normal operation mode. Setting this field to normal operation mode terminates the 'PING-PONG Mode' operation. When set to 10, T16 is immediately forced to a 0; a setting of 11 forces T16 to output a 1.

In DEMODULATION mode, this field defines the width of the glitch that must be filtered out.

### T16 TRANSMIT Mode

In NORMAL or PING-PONG mode, the output of T16 when not enabled, is dependent on CTR1, D0. If it is a 0, T16\_OUT is a 1; if it is a 1, T16\_OUT is 0. You can force the output of T16 to either a 0 or 1 whether it is enabled or not by programming CTR1 D3; D2 to a 10 or 11.

When T16 is enabled, TC16H \* 256 + TC16L is loaded, and T16\_OUT is switched to its initial value (CTR1, D0). When T16 counts down to 0, T16\_OUT is toggled (in NORMAL or PING-PONG mode), an interrupt (CTR2, D1) is generated (if enabled), and a status bit (CTR2, D5) is set, see [Figure 23](#).



**Figure 23. 16-Bit Counter/Timer Circuits**

► **Note:** *Global interrupts override this function as described in [Interrupts](#) on page 43.*

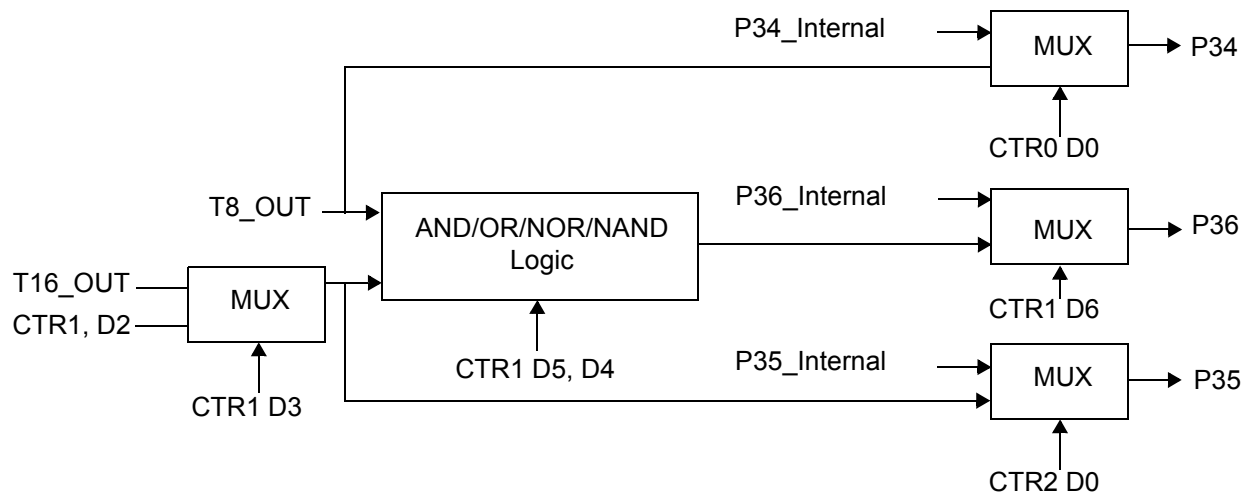
If T16 is in SINGLE-PASS mode, it is stopped at this point (see [Figure 24](#)). If it is in MODULO-N mode, it is loaded with TC16H \* 256 + TC16L, and the counting continues (see [Figure 25](#)).

You can modify the values in TC16H and TC16L at any time. The new values take effect when they are loaded.



### Initiating PING-PONG Mode

First, make sure both counter/timers are not running. Set T8 into SINGLE-PASS mode (CTR0, D6), set T16 into SINGLE-PASS mode (CTR2, D6), and set the PING-PONG mode (CTR1, D2; D3). These instructions can be in random order. Finally, start PING-PONG mode by enabling either T8 (CTR0, D7) or T16 (CTR2, D7), see [Figure 26](#).



**Figure 27. Output Circuit**

The initial value of T8 or T16 must not be 1. If you stop the timer and restart the timer, reload the initial value to avoid an unknown previous value.

### During PING-PONG Mode

The enable bits of T8 and T16 (CTR0, D7; CTR2, D7) are set and cleared alternately by hardware. The timeout bits (CTR0, D5; CTR2, D5) are set every time the counter/timers reach the terminal count.

### Timer Output

The output logic for the timers is displayed in [Figure 27](#). P34 is used to output T8-OUT when D0 of CTR0 is set. P35 is used to output the value of T16-OUT when D0 of CTR2 is set. When D6 of CTR1 is set, P36 outputs the logic combination of T8-OUT and T16-OUT determined by D5 and D4 of CTR1.

## Interrupts

The Crimzon ZLP32300 features six different interrupts (see [Table 11](#) on page 45). The interrupts are maskable and prioritized (see [Figure 28](#)). The six sources are divided as follows: three sources are claimed by Port 3 lines P33–P31, two by the

**Table 11. Interrupt Types, Sources, and Vectors**

Name	Source	Vector Location	Comments
IRQ0	P32	0,1	External (P32), Rising, Falling Edge Triggered
IRQ1	P33	2,3	External (P33), Falling Edge Triggered
IRQ2	P31, T <sub>IN</sub>	4,5	External (P31), Rising, Falling Edge Triggered
IRQ3	T16	6,7	Internal
IRQ4	T8	8,9	Internal
IRQ5	LVD	10,11	Internal

When more than one interrupt is pending, priorities are resolved by a programmable priority encoder controlled by the Interrupt Priority Register. An interrupt machine cycle activates when an interrupt request is granted. As a result, all subsequent interrupts are disabled, and the Program Counter and Status Flags are saved. The cycle then branches to the program memory vector location reserved for that interrupt. All Crimzon ZLP32300 interrupts are vectored through locations in the program memory. This memory location and the next byte contain the 16-bit address of the interrupt service routine for that particular interrupt request. To accommodate polled interrupt systems, interrupt inputs are masked, and the Interrupt Request register is polled to determine which of the interrupt requests require service.

An interrupt resulting from AN1 is mapped into IRQ2, and an interrupt from AN2 is mapped into IRQ0. Interrupts IRQ2 and IRQ0 can be rising, falling, or both edge triggered. These interrupts are programmable. The software can poll to identify the state of the pin.

Programming bits for the Interrupt Edge Select are located in the IRQ Register (R250), bits D7 and D6. The configuration is indicated in [Table 12](#).

**Table 12. IRQ Register**

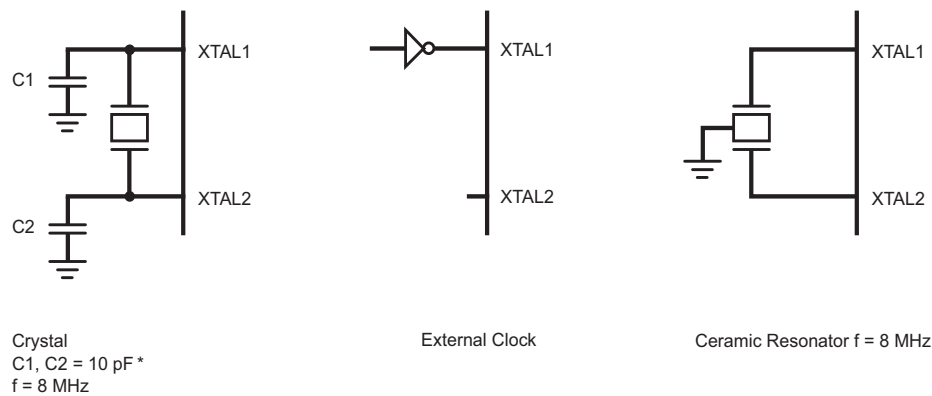
IRQ		Interrupt Edge	
D7	D6	IRQ2 (P31)	IRQ0 (P32)
0	0	F	F
0	1	F	R
1	0	R	F
1	1	R/F	R/F

**Note:** F = Falling Edge; R = Rising Edge

## Clock

The device's on-chip oscillator has a high-gain, parallel-resonant amplifier, for connection to a crystal, ceramic resonator, or any suitable external clock source (XTAL1 = Input, XTAL2 = Output). The crystal must be AT cut, 1 MHz to 8 MHz maximum, with a series resistance ( $R_S$ ) less than or equal to  $100\ \Omega$ . The on-chip oscillator can be driven with a suitable external clock source.

The crystal must be connected across XTAL1 and XTAL2 using the recommended capacitors from each pin to ground. The typical capacitor value is 10 pF for 8 MHz. Also check with the crystal supplier for the optimum capacitance.



\*Note: preliminary value.

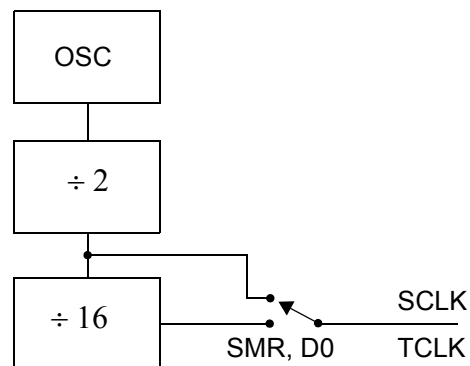
**Figure 29. Oscillator Configuration**

Zilog's IR MCU supports crystal, resonator, and oscillator. Most resonators have a frequency tolerance of less than  $\pm 0.5\%$ , which is enough for remote control application. Resonator has a very fast startup time, which is around few hundred microseconds. Most crystals have a frequency tolerance of less than 50 ppm ( $\pm 0.005\%$ ). However, crystal needs longer startup time than the resonator. The large loading capacitance slows down the oscillation startup time. Zilog® suggests not to use more than 10 pF loading capacitor for the crystal. If the stray capacitance of the PCB or the crystal is high, the loading capacitance C1 and C2 must be reduced further to ensure stable oscillation before the  $T_{POR}$  (Power-On Reset time is typically 5-6 ms, see [Table 20](#) on page 79).

For Stop Mode Recovery operation, bit 5 of SMR register allows you to select the Stop Mode Recovery delay, which is the  $T_{POR}$ . If Stop Mode Recovery delay is not selected, the MCU executes instruction immediately after it wakes up from the STOP mode. If resonator or crystal is used as a clock source then Stop Mode Recovery delay needs to be selected (bit 5 of SMR = 1).

**SCLK/TCLK Divide-by-16 Select (D0)**

D0 of the SMR controls a divide-by-16 prescaler of SCLK/TCLK (see Figure 32). This control selectively reduces device power consumption during normal processor execution (SCLK control) and/or HALT mode (where TCLK sources interrupt logic). After Stop Mode Recovery, this bit is set to a 0.

**Figure 32. SCLK Circuit****Stop Mode Recovery Source (D2, D3, and D4)**

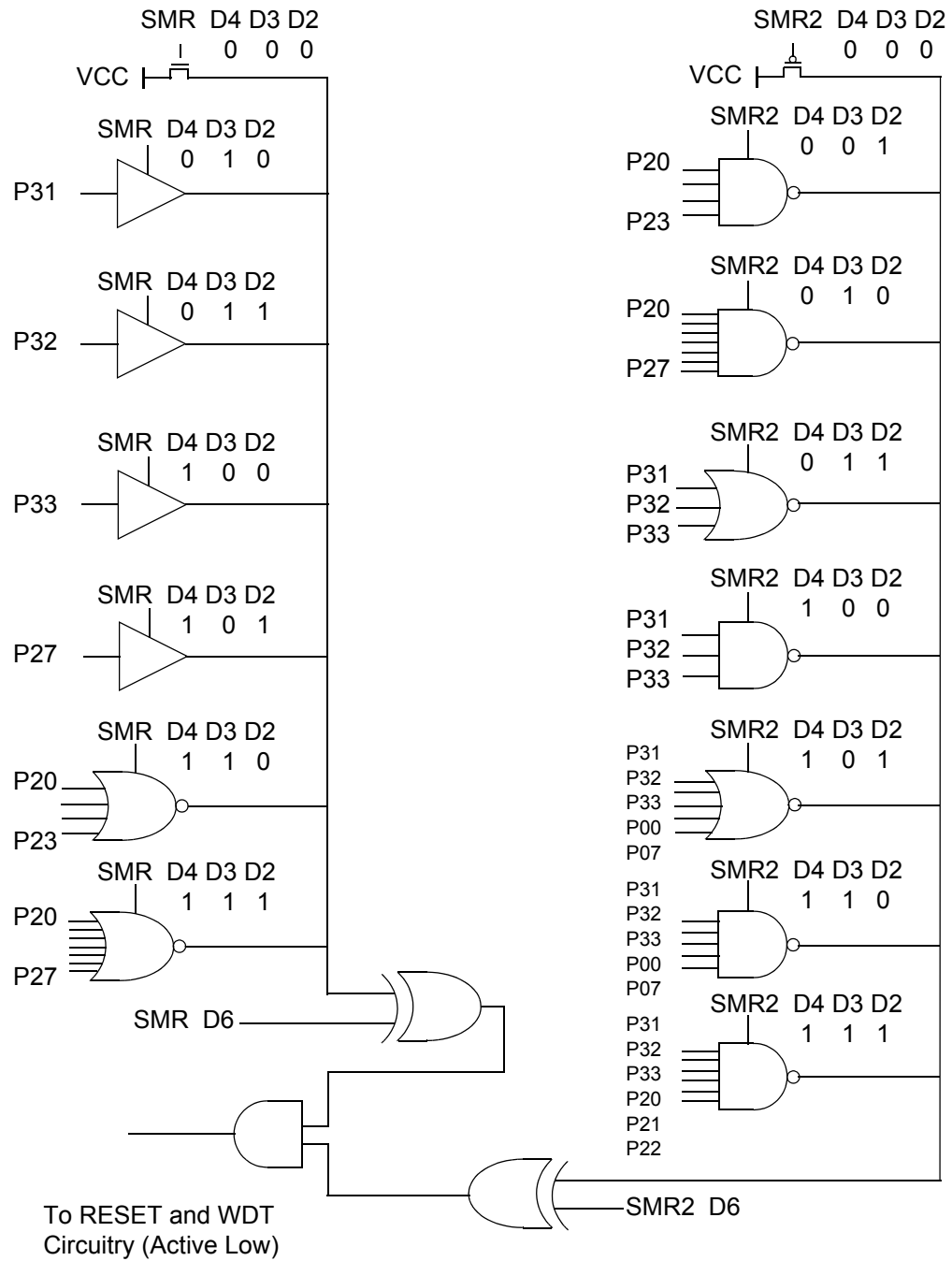
These three bits of the SMR specify the wake-up source of the Stop recovery (see Figure 33 and Table 14).

**Stop Mode Recovery Register 2—SMR2(F)0Dh**

Table 13 lists and briefly describes the fields for this register.

**Table 13. SMR2(F)0Dh:Stop Mode Recovery Register 2\***

Field	Bit Position	Value	Description
Reserved	7-----	0	Reserved (Must be 0)
Recovery Level	-6-----	W 0 <sup>†</sup> 1	Low High
Reserved	--5-----	0	Reserved (Must be 0)



**Figure 33. Stop Mode Recovery Source**

**Table 16. EPROM Selectable Options**

Port 00–03 Pull-Ups	ON/OFF
Port 04–07 Pull-Ups	ON/OFF
Port 10–13 Pull-Ups	ON/OFF
Port 14–17 Pull-Ups	ON/OFF
Port 20–27 Pull-Ups	ON/OFF
EPROM Protection	ON/OFF
Watchdog Timer at Power-On Reset	ON/OFF

**Voltage Brownout/Standby**

An on-chip Voltage Comparator checks that the  $V_{DD}$  is at the required level for correct operation of the device. Reset is globally driven when  $V_{DD}$  falls below  $V_{BO}$ . A small drop in  $V_{DD}$  causes the XTAL1 and XTAL2 circuitry to stop the crystal or resonator clock. If the  $V_{DD}$  is allowed to stay above  $V_{RAM}$ , the RAM content is preserved. When the power level is returned to above  $V_{BO}$ , the device performs a POR and functions normally.

**Low-Voltage Detection****Low-Voltage Detection Register—LVD(D)0Ch**

► **Note:** *Voltage detection does not work at STOP mode.*

Field	Bit Position	Description
LVD	76543---	Reserved No Effect
	----2--	R 1 0* HVD Flag set HVD Flag reset
	-----1-	R 1 0* LVD Flag set LVD Flag reset
	-----0	R/W 1 0* Enable VD Disable VD
*Default after POR		

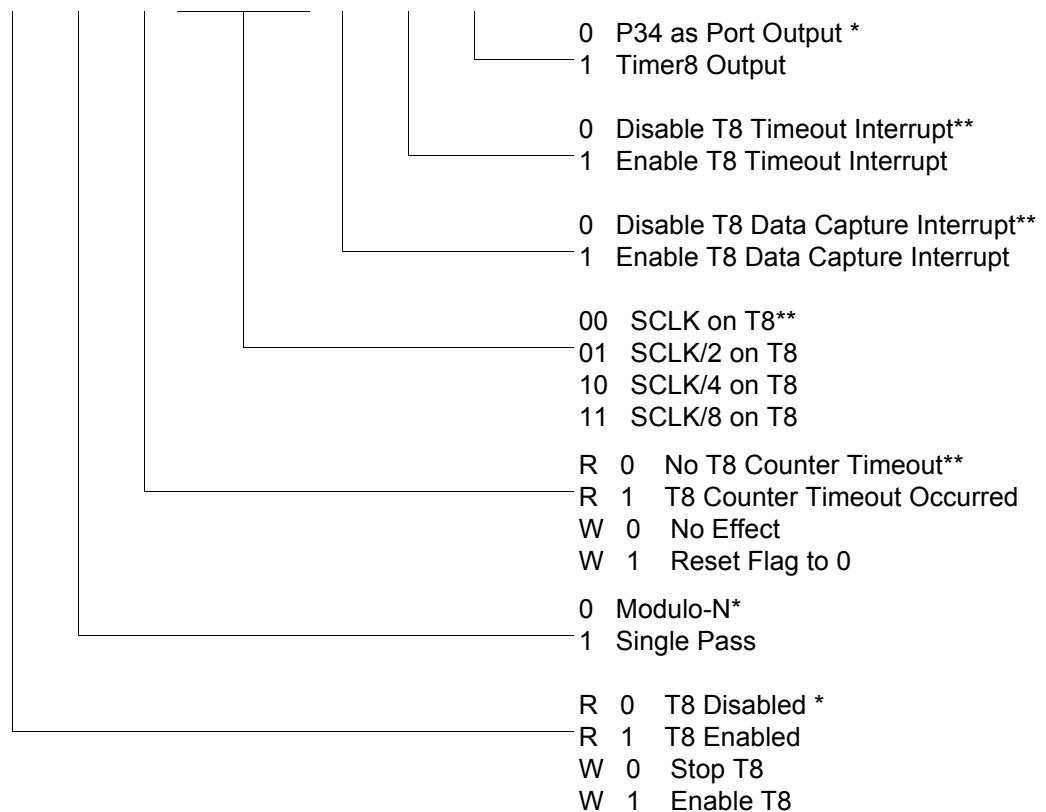
► **Note:** *Do not modify register P01M while checking a low-voltage condition. Switching noise of both Ports 0 and 1 together might trigger the LVD Flag.*

## Expanded Register File Control Registers (0D)

The expanded register file control registers (0D) are displayed in [Figure 37](#) through [Figure 41](#).

CTR0(0D)00H

D7	D6	D5	D4	D3	D2	D1	D0
----	----	----	----	----	----	----	----



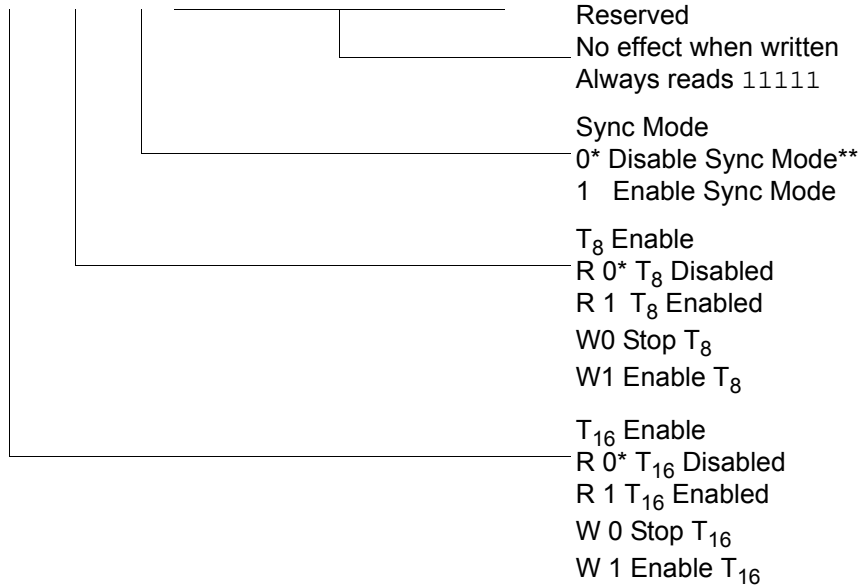
\*Default setting after reset.

\*\*Default setting after reset. Not reset with a Stop Mode Recovery.

**Figure 37. TC8 Control Register ((0D)00H: Read/Write Except Where Noted)**

CTR3(0D)03H

D7	D6	D5	D4	D3	D2	D1	D0
----	----	----	----	----	----	----	----



\*Default setting after reset.

\*\*Default setting after reset. Not reset with a Stop Mode Recovery.

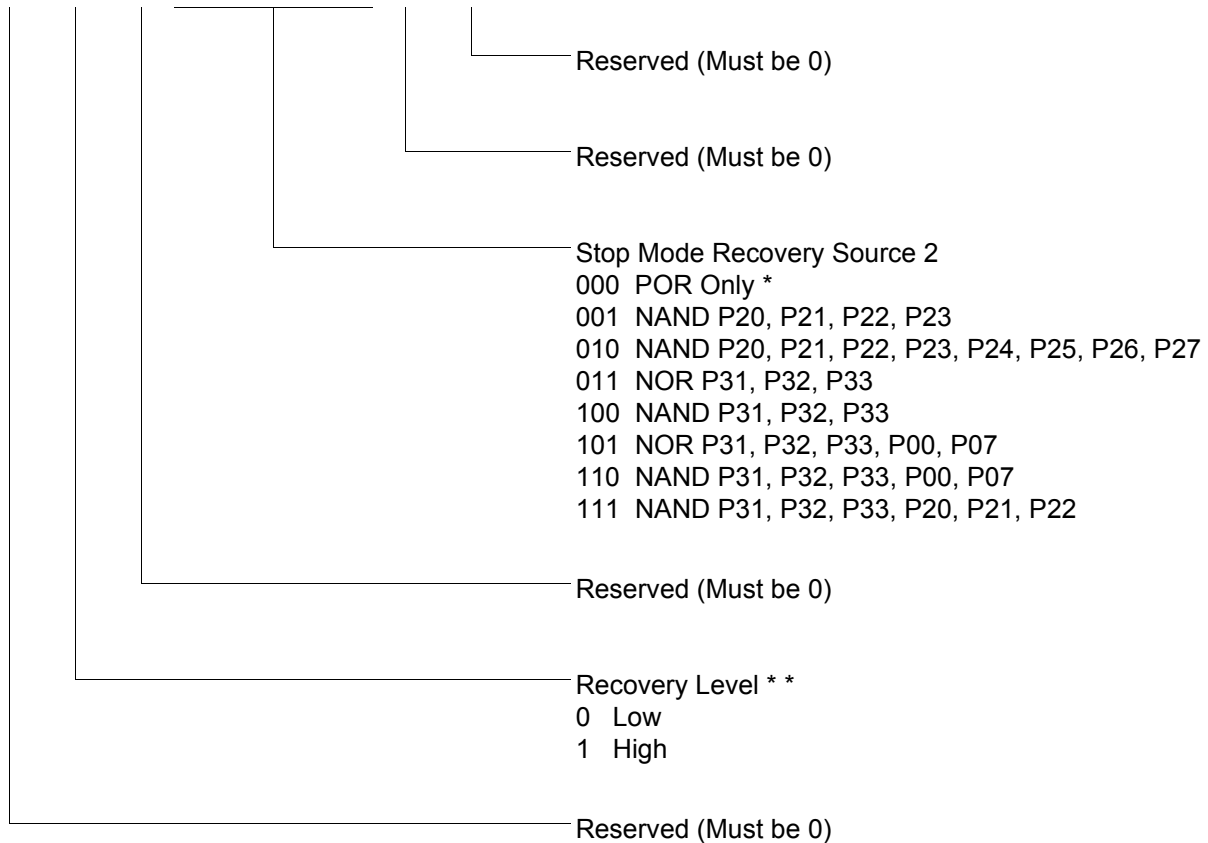
**Figure 40. T8/T16 Control Register (0D)03H: Read/Write (Except Where Noted)**

► **Note:** *If Sync Mode is enabled, the first pulse of T8 carrier is always synchronized with T16 (demodulated signal). It can always provide a full carrier pulse.*



SMR2(0F)0DH

D7	D6	D5	D4	D3	D2	D1	D0
----	----	----	----	----	----	----	----



If used in conjunction with SMR, either of the two specified events causes a Stop Mode Recovery.

\*Default setting after reset. Not Reset with a Stop Mode Recovery.

\* \*At the XOR gate input

**Figure 44. Stop Mode Recovery Register 2 ((0F)0DH:D2–D4, D6 Write Only)**

## Capacitance

Table 18 lists the capacitances.

**Table 18. Capacitance**

Parameter	Maximum
Input capacitance	12 pF
Output capacitance	12 pF
I/O capacitance	12 pF
$T_A = 25\text{ }^{\circ}\text{C}$ , $V_{CC} = \text{GND} = 0\text{ V}$ , $f = 1.0\text{ MHz}$ , unmeasured pins returned to GND	

## DC Characteristics

Table 19 describes the DC characteristics.

**Table 19. DC Characteristics**

Symbol	Parameter	$V_{CC}$	$T_A = 0\text{ }^{\circ}\text{C to } +70\text{ }^{\circ}\text{C}$			Units	Conditions	Notes
			Min	Typ <sup>(7)</sup>	Max			
$V_{CC}$	Supply Voltage		2.0		3.6	V	See Notes	5
$V_{CH}$	Clock Input High Voltage	2.0-3.6	$0.8 V_{CC}$		$V_{CC}+0.3$	V	Driven by External Clock Generator	
$V_{CL}$	Clock Input Low Voltage	2.0-3.6	$V_{SS}-0.3$		0.4	V	Driven by External Clock Generator	
$V_{IH}$	Input High Voltage	2.0-3.6	$0.7 V_{CC}$		$V_{CC}+0.3$	V		
$V_{IL}$	Input Low Voltage	2.0-3.6	$V_{SS}-0.3$		$0.2 V_{CC}$	V		
$V_{OH1}$	Output High Voltage	2.0-3.6	$V_{CC}-0.4$			V	$I_{OH} = -0.5\text{ mA}$	
$V_{OH2}$	Output High Voltage (P36, P37, P00, P01)	2.0-3.6	$V_{CC}-0.8$			V	$I_{OH} = -7\text{ mA}$	
$V_{OL1}$	Output Low Voltage	2.0-3.6			0.4	V	$I_{OL} = 4.0\text{ mA}$	
$V_{OL2}$	Output Low Voltage (P00, P01, P36, P37)	2.0-3.6			0.8	V	$I_{OL} = 10\text{ mA}$	
$V_{OFFSET}$	Comparator Input Offset Voltage	2.0-3.6			25	mV		
$V_{REF}$	Comparator Reference Voltage	2.0-3.6	0		$V_{CC}$ -1.75	V		

Table 20. AC Characteristics

T <sub>A</sub> =0 °C to +70 °C 8.0 MHz							Watchdog Timer Mode Register (D1, D0)
No	Symbol	Parameter	V <sub>CC</sub>	Minimum	Maximum	Units	
1	TpC	Input Clock Period	2.0–3.6	121	DC	ns	1
2	TrC, TfC	Clock Input Rise and Fall Times	2.0–3.6		25	ns	1
3	TwC	Input Clock Width	2.0–3.6	37		ns	1
4	TwTinL	Timer Input Low Width	2.0 3.6	100 70		ns	1
5	TwTinH	Timer Input High Width	2.0–3.6	3TpC			1
6	TpTin	Timer Input Period	2.0–3.6	8TpC			1
7	TrTin, TtTin	Timer Input Rise and Fall Timers	2.0–3.6		100	ns	1
8	TwIL	Interrupt Request Low Time	2.0 3.6	100 70		ns	1, 2
9	TwIH	Interrupt Request Input High Time	2.0–3.6	5TpC			1, 2
10	Twsm	Stop Mode Recovery Width Spec	2.0–3.6	12 10TpC		ns	3 4
11	Tost	Oscillator Start-Up Time	2.0–3.6		5TpC		4
12	Twdt	Watchdog Timer Delay Time	2.0–3.6 2.0–3.6 2.0–3.6 2.0–3.6	5 10 20 80		ms ms ms ms	0, 0 0, 1 1, 0 1, 1
13	T <sub>POR</sub>	Power-on reset	2.0–3.6	2.5	10	ms	

**Notes**

1. Timing Reference uses 0.9 V<sub>CC</sub> for a logic 1 and 0.1 V<sub>CC</sub> for a logic 0.
2. Interrupt request through Port 3 (P33–P31).
3. SMR–D5 = 1.
4. SMR–D5 = 0.

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