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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded -</u> <u>Microcontrollers</u>"

Details

Product Status	Active
Core Processor	ARM® Cortex®-M23
Core Size	32-Bit Single-Core
Speed	32MHz
Connectivity	I ² C, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, POR, PWM, WDT
Number of I/O	25
Program Memory Size	64KB (64K x 8)
Program Memory Type	FLASH
EEPROM Size	2K x 8
RAM Size	16K x 8
Voltage - Supply (Vcc/Vdd)	1.62V ~ 3.63V
Data Converters	A/D 10x12b; D/A 1x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	32-VFQFN Exposed Pad
Supplier Device Package	32-VQFN (5x5)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/atsaml10e16a-mft

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

Signal Descriptions List

Signal Name	Function	Туре				
External Interrupt Controller - EIC	External Interrupt Controller - EIC					
EXTINT[7:0]	External Interrupts Pins	Digital Input				
NMI	Non-Maskable Interrupt Pin	Digital Input				
General Purpose I/O - PORT						
PA11-PA00 / PA19-PA14 / PA25-PA22 / PA27 / PA31-PA30	General Purpose I/O Pin in Port A	Digital I/O				
Reset Controller - RSTC						
RESET	External Reset Pin (Active Level: LOW)	Digital Input				
Debug Service Unit - DSU						
SWCLK	Serial Wire Clock	Digital Input				
SWDIO	Serial Wire Bidirectional Data Pin	Digital I/O				

1. VREFA is shared between the ADC and DAC peripherals.

16.12.10 Configuration

	Name: Offset: Reset: Property:	CFG 0x001C 0x0000000 PAC Write-Pr	otection					
Bit	31	30	29	28	27	26	25	24
Access								
Reset								
Bit	23	22	21	20	19	18	17	16
Access								
Reset								
Bit	15	14	13	12	11	10	9	8
A								
Access								
Reset								
Bit	7	6	5	4	3	2	1	0
					DCCDMALEVEL[1:0] LQOS[1:0		S[1:0]	
Access					RW	RW	RW	RW
Reset					0	0	0	2

Bits 3:2 - DCCDMALEVEL[1:0] DMA TriggerLevel

0x0X: DCC1 trigger is the image of STATUSB.DCC1D, this signals to the DMA that a data is available for read, this is the correct configuration for a channel that reads DCC1.

0x1X: DCC1 trigger is the image of STATUSB.DCC1D inverted, this signals to the DMA that DCC1 is ready for write, this is the correct configuration for a channel that writes DCC1

0xX0: DCC0 trigger is the image of STATUSB.DCC0D, this signals to the DMA that a data is available for read, this is the correct configuration for a channel that reads DCC0.

0xX1: DCC0 trigger is the image of STATUSB.DCC0D inverted, this signals to the DMA that DCC0 is ready for write, this is the correct configuration for a channel that writes DCC0

Bits 1:0 - LQOS[1:0] Latency Quality Of Service

Defines the latency quality of service required when accessing the RAM:

- 0: Background Transfers
- 1: Bandwidth Sensitive
- 2: Latency sensitive
- 3: Latency critical

19.8.1 Control A

Name:	CTRLA
Offset:	0x00
Reset:	0x00
Property:	PAC Write-Protection

Bit	7	6	5	4	3	2	1	0
						CKSEL		
Access						R/W		
Reset						0		

Bit 2 – CKSEL Main Clock Select

Value	Description
0	The GCLKMAIN clock is selected for the main clock.
1	The DFLLULP clock is selected for the main clock.

OSCCTRL – Oscillators Controller

Table 23-4. CLK_DPLL Behavior after First Edge Detection

LBYPASS	CLK_DPLL Behavior
0	Normal Mode: the CLK_DPLL is turned off when lock signal is low.
1	Lock Bypass Mode: the CLK_DPLL is always running, lock is irrelevant.

Figure 23-5. CK and CLK_DPLL Output from DPLL Off Mode to Running Mode



23.6.7.1.2 Reference Clock Switching

When a software operation requires reference clock switching, the recommended procedure is to turn the DPLL into the standby mode, modify the DPLLCTRLB.REFCLK to select the desired reference source, and activate the DPLL again.

23.6.7.1.3 Output Clock Prescaler

The DPLL controller includes an output prescaler. This prescaler provides three selectable output clocks CK, CKDIV2 and CKDIV4. The Prescaler bit field in the DPLL Prescaler register (DPLLPRESC.PRESC) is used to select a new output clock prescaler. When the prescaler field is modified, the DPLLSYNCBUSY.DPLLPRESC bit is set. It will be cleared by hardware when the synchronization is over.

Figure 23-6. Output Clock Switching Operation



23.6.7.1.4 Loop Divider Ratio Updates

The DPLL Controller supports on-the-fly update of the DPLL Ratio Control (DPLLRATIO) register, allowing to modify the loop divider ratio and the loop divider ratio fractional part when the DPLL is enabled.

This flag is set on 0-to-1 transition of the DPLL Lock Fall bit in the Status register (STATUS.DPLLLCKF) and will generate an interrupt request if INTENSET.DPLLLCKF is '1'.

Writing '0' to this bit has no effect.

Writing '1' to this bit clears the DPLL Lock Fall interrupt flag.

Bit 16 – DPLLLCKR DPLL Lock Rise

This flag is cleared by writing '1' to it.

This flag is set on 0-to-1 transition of the DPLL Lock Rise bit in the Status register (STATUS.DPLLLCKR) and will generate an interrupt request if INTENSET.DPLLLCKR is '1'.

Writing '0' to this bit has no effect.

Writing '1' to this bit clears the DPLL Lock Rise interrupt flag.

Bit 10 – DFLLULPNOLOCK DFLLULP No Lock

This flag is cleared by writing '1' to it.

This flag is set on 0-to-1 transition of the DFLLULP No Lock bit in the Status register (STATUS.DFLLULPNOLOCK) and will generate an interrupt request if INTENSET.DFLLULPNOLOCK is '1'.

Writing '0' to this bit has no effect.

Writing '1' to this bit clears the DFLLULP No Lock interrupt flag.

Bit 9 – DFLLULPLOCK DFLLULP Lock

This flag is cleared by writing '1' to it.

This flag is set on 0-to-1 transition of the DFLLULP Lock bit in the Status register (STATUS.DFLLULPLOCK) and will generate an interrupt request if INTENSET.DFLLULPLOCK is '1'.

Writing '0' to this bit has no effect.

Writing '1' to this bit clears the DFLLULP Lock interrupt flag.

Bit 8 – DFLLULPRDY DFLLULP Ready

This flag is cleared by writing '1' to it.

This flag is set on 0-to-1 transition of the DFLLULP Ready bit in the Status register (STATUS.DFLLULPREADY) and will generate an interrupt request if INTENSET.DFLLULPREADY is '1'.

Writing '0' to this bit has no effect.

Writing '1' to this bit clears the DFLLULP Ready interrupt flag.

Bit 4 – OSC16MRDY OSC16M Ready

This flag is cleared by writing '1' to it.

This flag is set on 0-to-1 transition of the OSC16M Ready bit in the Status register (STATUS.OSC16MRDY) and will generate an interrupt request if INTENSET.OSC16MRDY is '1'.

Writing '0' to this bit has no effect.

Writing '1' to this bit clears the OSC16M Ready interrupt flag.

28.8.20 Channel Interrupt Enable Clear

Name:CHINTENCLROffset:0x4CReset:0x00Property:PAC Write-Protection

This register allows the user to disable an interrupt without doing a read-modify-write operation. Changes in this register will also be reflected in the Channel Interrupt Enable Set (CHINTENSET) register. This register affects the DMA channel that is selected in the Channel ID register (CHID.ID).

Bit	7	6	5	4	3	2	1	0
						SUSP	TCMPL	TERR
Access						R/W	R/W	R/W
Reset						0	0	0

Bit 2 – SUSP Channel Suspend Interrupt Enable

Writing a '0' to this bit has no effect.

Writing a '1' to this bit will clear the Channel Suspend Interrupt Enable bit, which disables the Channel Suspend interrupt.

Value	Description
0	The Channel Suspend interrupt is disabled.
1	The Channel Suspend interrupt is enabled.

Bit 1 – TCMPL Channel Transfer Complete Interrupt Enable

Writing a '0' to this bit has no effect.

Writing a '1' to this bit will clear the Channel Transfer Complete Interrupt Enable bit, which disables the Channel Transfer Complete interrupt.

Value	Description
0	The Channel Transfer Complete interrupt is disabled. When block action is set to none, the
	TCMPL flag will not be set when a block transfer is completed.
1	The Channel Transfer Complete interrupt is enabled.

Bit 0 – TERR Channel Transfer Error Interrupt Enable

Writing a '0' to this bit has no effect.

Writing a '1' to this bit will clear the Channel Transfer Error Interrupt Enable bit, which disables the Channel Transfer Error interrupt.

Value	Description
0	The Channel Transfer Error interrupt is disabled.
1	The Channel Transfer Error interrupt is enabled.

30.8.15 Secure Boot Configuration

Name:	SCFGB
Offset:	0x38
Reset:	0x0000003
Property:	PAC Write-Protection, Write-Secure

This register is loaded from BOCOR at boot.

Bit	31	30	29	28	27	26	25	24
Access								
Reset								
Bit	23	22	21	20	19	18	17	16
Access								
Reset								
Bit	15	14	13	12	11	10	9	8
Access								
Reset								
Bit	7	6	5	4	3	2	1	0
							BCWEN	BCREN
Access							RW/R/RW	RW/R/RW
Reset							1	1

Bit 1 – BCWEN Boot Configuration Row Write Enable

Value	Description
0	BOCOR is not writable.
1	BOCOR is writable.

Bit 0 – BCREN Boot Configuration Row Read Enable

Value	Description
0	BOCOR is not readable.
1	BOCOR is readable.

The tamper full erase routine operates at the highest priority. If a remanence routine executing when a tamper full erase occurs, the remanence routine is immediately terminated. If the CPU attempts to write a new scramble key at the same time the tamper key erase routine is active, the CPU data is ignored, but no bus error will occur. If a CPU security routine access is requested during a tamper full erase, the CPU transaction will be ignored and treated as a bus error similar to accessing the module during a software reset.



Important: In STANDBY low power mode, it is mandatory to enable the dynamic power gating feature (STDBYCFG.DPGPDSW) to ensure TrustRAM erasing when the power domain PDSW is in a retention state.

31.6.3 Interrupts

The TRAM has the following interrupt sources:

- Data Remanence Prevention (DRP): Indicates that the data remanence prevention routine has ended.
- Data Read Error (ERR): Indicates when there is a RAM readout error.

Each interrupt source has an interrupt flag associated with it. The interrupt flag in the Interrupt Flag Status and Clear (INTFLAG) register is set when the interrupt condition occurs. Each interrupt can be individually enabled by writing a one to the corresponding bit in the Interrupt Enable Set (INTENSET) register, and disabled by writing a one to the corresponding bit in the Interrupt Enable Clear (INTENCLR) register.

An interrupt request is generated when the interrupt flag is set and the corresponding interrupt is enabled. The interrupt request remains active until the interrupt flag is cleared, the interrupt is disabled, or the TRAM is reset. See 22.8.6 INTFLAG for details on how to clear interrupt flags. All interrupt requests from the peripheral are ORed together on system level to generate one combined interrupt request to the NVIC. Refer to *Nested Vector Interrupt Controller* for details. The user must read the INTFLAG register to determine which interrupt condition is present.

Note that interrupts must be globally enabled for interrupt requests to be generated. Refer to *Nested Vector Interrupt Controller* for details.

31.6.4 Sleep Mode Operation

The TRAM continues to operate during sleep. When it receives events from the Event System, it will request its own clock in order to perform the requested operation.

An interrupt request will be generated after the wake-up if the Interrupt Controller is configured accordingly. Otherwise the CPU will wake up directly, without triggering an interrupt. In this case, the CPU will continue executing from the instruction following the entry into sleep.

The periodic events can also wake up the CPU through the interrupt function of the Event System. In this case, the event must be enabled and connected to an event channel with its interrupt enabled. See *EVSYS – Event System* for more information.

31.6.5 Synchronization

Due to the asynchronicity between event sources and CLK_TRAM_APB some registers must be synchronized when accessed. A register can require:

Synchronization when written

TRAM - TrustRAM

Offset	Name	Bit Pos.							
	RAM40	7:0			DATA	\ [7:0]			
		15:8			DATA	[15:8]			
0x01A0		23:16			DATA[23:16]			
		31:24	DATA[31:24]						
		7:0	DATA[7:0]						
0.0144	DAMAA	15:8	DATA[15:8]						
0X01A4	RAM41	23:16	DATA[23:16]						
		31:24	DATA[31:24]						
		7:0			DATA	A[7:0]			
0,0149	DAM42	15:8			DATA	[15:8]			
UXUTAO	KAW42	23:16			DATA[23:16]			
		31:24			DATA[31:24]			
		7:0			DATA	A[7:0]			
0×0140	DAM43	15:8			DATA	[15:8]			
UNUTAC	TAM45	23:16			DATA[23:16]			
		31:24			DATA[31:24]			
		7:0			DATA	\ [7:0]			
0v01B0	PAM44	15:8	DATA[15:8]						
0.0100	RAIVI44	23:16	DATA[23:16]						
		31:24	DATA[31:24]						
	RAM45	7:0			DATA	\ [7:0]			
0v01B4		15:8			DATA	[15:8]			
0,0104		23:16			DATA[23:16]			
		31:24	DATA[31:24]						
	RAM46	7:0			DATA	A[7:0]			
0x01B8		15:8	DATA[15:8]						
0.0120		23:16	 DATA[23:16]						
		31:24	DATA[31:24]						
		7:0			DATA	\ [7:0]			
0x01BC	RAM47	15:8	DATA[15:8]						
	, iounit	23:16	DATA[23:16]						
		31:24			DATA[31:24]			
		7:0			DATA	\ [7:0]			
0x01C0	RAM48	15:8			DATA	[15:8]			
		23:16			DATA[23:16]			
		31:24			DATA[31:24]			
		7:0			DATA	A[7:0]			
0x01C4	RAM49	15:8			DATA	[15:8]			
		23:16			DATA[23:16]			
		31:24			DATA[31:24]			
		7:0			DATA	A[7:0]			
0x01C8	RAM50	15:8			DATA	[15:8]			
		23:16			DATA[23:16]			
		31:24			DATA[31:24]			
0x01CC	RAM51	7:0			DATA	4[7:0]			
		15:8			DATA	[15:8]			

32.8.11 Write Configuration

Name:	WRCONFIG
Offset:	0x28
Reset:	0x0000000
Property:	PAC Write-Protection, Mix-Secure



Important: For **SAM L11 Non-Secure** accesses, write accesses (W*) are allowed only if the security attribution for the corresponding I/O pin is set as Non-Secured in the NONSEC register.



Tip: The I/O pins are assembled in pin groups ("PORT groups") with up to 32 pins. Group 0 consists of the PA pins, group 1 is for the PB pins, etc. Each pin group has its own PORT registers, with a 0x80 address spacing. For example, the register address offset for the Data Direction (DIR) register for group 0 (PA00 to PA31) is 0x00, and the register address offset for the DIR register for group 1 (PB00 to PB31) is 0x80.

This write-only register is used to configure several pins simultaneously with the same configuration and/or peripheral multiplexing.

In order to avoid side effect of non-atomic access, 8-bit or 16-bit writes to this register will have no effect. Reading this register always returns zero.

Bit	31	30	29	28	27	26	25	24
Γ	HWSEL	WRPINCFG		WRPMUX		PMU	X[3:0]	
Access	W/W*/W	W/W*/W	•	W/W*/W	W/W*/W	W/W*/W	W/W*/W	W/W*/W
Reset	0	0		0	0	0	0	0
Bit	23	22	21	20	19	18	17	16
Γ		DRVSTR				PULLEN	INEN	PMUXEN
Access		W/W*/W				W/W*/W	W/W*/W	W/W*/W
Reset		0				0	0	0
Bit	15	14	13	12	11	10	9	8
				PINMAS	SK[15:8]			
Access	W/W*/W	W/W*/W	W/W*/W	W/W*/W	W/W*/W	W/W*/W	W/W*/W	W/W*/W
Reset	0	0	0	0	0	0	0	0
Bit	7	6	5	4	3	2	1	0
Γ				PINMA	SK[7:0]			
Access	W/W*/W	W/W*/W	W/W*/W	W/W*/W	W/W*/W	W/W*/W	W/W*/W	W/W*/W
Reset	0	0	0	0	0	0	0	0

Bit 31 – HWSEL Half-Word Select

This bit selects the half-word field of a 32-PORT group to be reconfigured in the atomic write operation.

PORT - I/O Pin Controller

PMUXO[3:0] Name		Description
0x8 I		Peripheral function I selected
0x9-0xF	-	Reserved

Bits 3:0 – PMUXE[3:0] Peripheral Multiplexing for Even-Numbered Pin

These bits select the peripheral function for even-numbered pins (2*n) of a PORT group, if the corresponding PINCFGy.PMUXEN bit is '1'.

Not all possible values for this selection may be valid. For more details, refer to the *I/O Multiplexing and Considerations.*

PMUXE[3:0]	Name	Description		
0x0	А	Peripheral function A selected		
0x1	В	Peripheral function B selected		
0x2	С	Peripheral function C selected		
0x3	D	Peripheral function D selected		
0x4 E		Peripheral function E selected		
0x5	-	Reserved		
0x6	G	Peripheral function G selected		
0x7 H		Peripheral function H selected		
0x8 I		Peripheral function I selected		
0x9-0xF	-	Reserved		

34. SERCOM – Serial Communication Interface

34.1 Overview

There are up to three instances of the serial communication interface (SERCOM) peripheral.

A SERCOM can be configured to support a number of modes: I²C, SPI, and USART. When an instance of SERCOM is configured and enabled, all of the resources of that SERCOM instance will be dedicated to the selected mode.

The SERCOM serial engine consists of a transmitter and receiver, baud-rate generator and address matching functionality. It can use the internal generic clock or an external clock. Using an external clock allows the SERCOM to be operated in all Sleep modes.

Related Links

- 35. SERCOM USART SERCOM Synchronous and Asynchronous Receiver and Transmitter
- 36. SERCOM SPI SERCOM Serial Peripheral Interface
- 37. SERCOM I2C SERCOM Inter-Integrated Circuit

34.2 Features

- Interface for configuring into one of the following:
 - Inter-Integrated Circuit (I²C) Two-wire Serial Interface
 - System Management Bus (SMBus[™]) compatible
 - Serial Peripheral Interface (SPI)
 - Universal Synchronous/Asynchronous Receiver/Transmitter (USART)
- Single transmit buffer and double receive buffer
- Baud-rate generator
- Address match/mask logic
- Operational in all Sleep modes with an external clock source
- Can be used with DMA

See the Related Links for full feature lists of the interface configurations.

Related Links

- 35. SERCOM USART SERCOM Synchronous and Asynchronous Receiver and Transmitter
- 36. SERCOM SPI SERCOM Serial Peripheral Interface
- 37. SERCOM I2C SERCOM Inter-Integrated Circuit

SERCOM SPI – SERCOM Serial Peripheral Interface

AMODE[1:0]	Name	Description
0x0	MASK	ADDRMASK is used as a mask to the ADDR register
0x1	2_ADDRS	The slave responds to the two unique addresses in ADDR and ADDRMASK
0x2	RANGE	The slave responds to the range of addresses between and including ADDR and ADDRMASK. ADDR is the upper limit
0x3	-	Reserved

Bit 13 – MSSEN Master Slave Select Enable

This bit enables hardware slave select (\overline{SS}) control.

Value	Description
0	Hardware SS control is disabled.
1	Hardware \overline{SS} control is enabled.

Bit 9 – SSDE Slave Select Low Detect Enable

This bit enables wake up when the slave select (\overline{SS}) pin transitions from high to low.

Value	Description
0	SS low detector is disabled.
1	SS low detector is enabled.

Bit 6 – PLOADEN Slave Data Preload Enable

Setting this bit will enable preloading of the slave shift register when there is no transfer in progress. If the SS line is high when DATA is written, it will be transferred immediately to the shift register.

Bits 2:0 – CHSIZE[2:0] Character Size

CHSIZE[2:0]	Name	Description
0x0	8BIT	8 bits
0x1	9BIT	9 bits
0x2-0x7	-	Reserved

37.8.5 Interrupt Flag Status and Clear

Name:	INTFLAG
Offset:	0x18
Reset:	0x00
Property:	-

Bit	7	6	5	4	3	2	1	0
	ERROR					DRDY	AMATCH	PREC
Access	R/W					R/W	R/W	R/W
Reset	0					0	0	0

Bit 7 – ERROR Error

This bit is set when any error is detected. Errors that will set this flag have corresponding status flags in the STATUS register. The corresponding bits in STATUS are SEXTTOUT, LOWTOUT, COLL, and BUSERR.

Writing '0' to this bit has no effect.

Writing '1' to this bit will clear the flag.

Bit 2 – DRDY Data Ready

This flag is set when a I²C slave byte transmission is successfully completed.

The flag is cleared by hardware when either:

- Writing to the DATA register.
- Reading the DATA register with smart mode enabled.
- Writing a valid command to the CMD register.

Writing '0' to this bit has no effect.

Writing '1' to this bit will clear the Data Ready interrupt flag.

Bit 1 - AMATCH Address Match

This flag is set when the I²C slave address match logic detects that a valid address has been received.

The flag is cleared by hardware when CTRL.CMD is written.

Writing '0' to this bit has no effect.

Writing '1' to this bit will clear the Address Match interrupt flag. When cleared, an ACK/NACK will be sent according to CTRLB.ACKACT.

Bit 0 – PREC Stop Received

This flag is set when a stop condition is detected for a transaction being processed. A stop condition detected between a bus master and another slave will not set this flag, unless the PMBus Group Command is enabled in the Control B register (CTRLB.GCMD=1).

This flag is cleared by hardware after a command is issued on the next address match.

Writing '0' to this bit has no effect.

Writing '1' to this bit will clear the Stop Received interrupt flag.

37.10.6 Interrupt Flag Status and Clear

Name:INTFLACOffset:0x18Reset:0x00Property:-		INTFLAG 0x18 0x00 -						
Bit	7	6	5	4	3	2	1	0
	ERROR						SB	MB
Access	R/W						R/W	R/W
Reset	0						0	0

Bit 7 – ERROR Error

This flag is cleared by writing '1' to it.

This bit is set when any error is detected. Errors that will set this flag have corresponding status bits in the STATUS register. These status bits are LENERR, SEXTTOUT, MEXTTOUT, LOWTOUT, ARBLOST, and BUSERR.

Writing '0' to this bit has no effect.

Writing '1' to this bit will clear the flag.

Bit 1 – SB Slave on Bus

The Slave on Bus flag (SB) is set when a byte is successfully received in master read mode, i.e., no arbitration lost or bus error occurred during the operation. When this flag is set, the master forces the SCL line low, stretching the I²C clock period. The SCL line will be released and SB will be cleared on one of the following actions:

- Writing to ADDR.ADDR
- Writing to DATA.DATA
- Reading DATA.DATA when smart mode is enabled (CTRLB.SMEN)
- Writing a valid command to CTRLB.CMD

Writing '1' to this bit location will clear the SB flag. The transaction will not continue or be terminated until one of the above actions is performed.

Writing '0' to this bit has no effect.

Bit 0 – MB Master on Bus

This flag is set when a byte is transmitted in master write mode. The flag is set regardless of the occurrence of a bus error or an arbitration lost condition. MB is also set when arbitration is lost during sending of NACK in master read mode, or when issuing a start condition if the bus state is unknown. When this flag is set and arbitration is not lost, the master forces the SCL line low, stretching the I²C clock period. The SCL line will be released and MB will be cleared on one of the following actions:

- Writing to ADDR.ADDR
- Writing to DATA.DATA
- Reading DATA.DATA when smart mode is enabled (CTRLB.SMEN)
- Writing a valid command to CTRLB.CMD

38.7.1.1 Control A

Name:	CTRLA
Offset:	0x00
Reset:	0x0000000
Property:	PAC Write-Protection, Write-Synchronized, Enable-Protected

Bit	31	30	29	28	27	26	25	24
Access						·		
Reset								
D ''	00	00	04	00	40	40	47	10
Bit	23	22	21	20	19	18	17	16
			COPEN1	COPEN0			CAPTEN1	CAPTEN0
Access			R/W	R/W			R/W	R/W
Reset			0	0			0	0
Bit	15	14	13	12	11	10	9	8
					ALOCK	F	PRESCALER[2:0)]
Access					R/W	R/W	R/W	R/W
Reset					0	0	0	0
Bit	7	6	5	4	3	2	1	0
	ONDEMAND	RUNSTDBY	PRESCS	SYNC[1:0]	MODE[1:0]		ENABLE	SWRST
Access	R/W	R/W	R/W	R/W	R/W	R/W	R/W	W
Reset	0	0	0	0	0	0	0	0

Bits 20, 21 – COPENx Capture On Pin x Enable

Bit x of COPEN[1:0] selects the trigger source for capture operation, either events or I/O pin input.

Value	Description
0	Event from Event System is selected as trigger source for capture operation on channel x.
1	I/O pin is selected as trigger source for capture operation on channel x.

Bits 16, 17 – CAPTENx Capture Channel x Enable

Bit x of CAPTEN[1:0] selects whether channel x is a capture or a compare channel.

These bits are not synchronized.

Value	Description
0	CAPTEN disables capture on channel x.
1	CAPTEN enables capture on channel x.

Bit 11 – ALOCK Auto Lock

When this bit is set, Lock bit update (LUPD) is set to '1' on each overflow/underflow or re-trigger event.

This bit is not synchronized.

41.8.18 Debug Control

Name:DBGCTRLOffset:0x1CReset:0x00Property:PAC Write-Protection

Bit	7	6	5	4	3	2	1	0
								DBGRUN
Access								R/W
Reset								0

Bit 0 – DBGRUN Debug Run

This bit is not reset by a software reset.

This bit controls the functionality when the CPU is halted by an external debugger.

This bit should be written only while a conversion is not ongoing.

Value	Description
0	The ADC is halted when the CPU is halted by an external debugger.
1	The ADC continues normal operation when the CPU is halted by an external debugger.

For 12-bit accuracy:

 $t_{\text{samplehold}} \ge (R_{\text{sample}} + R_{\text{source}}) \times (C_{\text{sample}}) \times 9.7$ where $t_{\text{samplehold}} = \frac{1}{2 \times f_{\text{ADC}}}$.

47.4.3 Digital-to-Analog Converter (DAC) Characteristics Table 47-10. Operating Conditions ⁽¹⁾

Symbol	Parameters	Conditions	Min	Тур	Мах	Unit
AVREF	External reference voltage		1	-	VDDANA-0.6	V
	Internal reference voltage 1		-	1	-	V
	Internal reference voltage 2		-	VDDANA	-	V
	Linear output voltage range		0.05	-	VDDANA-0.05	V
	Minimum resistive load		5	-	-	kOhm
	Maximum capacitance load		-	-	100	pF
IDD	DC supply current ⁽²⁾	Voltage pump disabled	-	175	270	μA

Note:

- 1. The values in this table are based on specifications otherwise noted.
- 2. These values are based on characterization. These values are not covered in test limits in production.

Table 47-11. Clock and Timing ⁽¹⁾

Symbol	Parameter	Conditions	Min.	Тур.	Max.	Units	
	Conversion rate	Cload=100pF Rload > 5 kOhm	Normal mode	-	-	350	ksps
			For DDATA=+/-1	-	-	1000	
	Startup time	VDDANA > 2.6V	VDDANA > 2.6V	-	-	2.85	μs
		VDDANA < 2.6V	VDDANA < 2.6V	-	-	10	μs

Note:

1. These values are based on simulation. These values are not covered by test limits in production or characterization.

Table 47-12. Accuracy Characteristics ⁽¹⁾

Symbol	Parameter	Conditions		Min.	Тур.	Max.	Units
RES	Input resolution			-	-	10	Bits
INL	Integral non-linearity	VREF= Ext 1.0V	VDD = 1.62V	+/-0,2	+/-0,5	+/-1.4	LSB
			VDD = 3.63V	+/-0,2	+/-0,4	+/-1,2	
		VREF = VDDANA	VDD = 1.62V	+/-0,2	+/-0,6	+/-2.1	
			VDD = 3.63V	+/-0,2	+/-0,5	+/-1,9	

125°C Electrical Characteristics

Symbol	Parameter	Conditions		Min.	Тур.	Max.	Units
tSCKF	SCK fall time ⁽²⁾	Master		-	0,25*tSCK	-	
tMIS	MIS MISO setup to SCK	Master, VDD>2,70V		43.8	-	-	
		Master, VDD>1,62V		54.1	-	-	
tMIH	MISO hold	Master, VDD>2,70V		0	-	-	ns
	after SCK	Master, VDD>1,62V		0	-	-	
tMOV	MOSI output	Master, VDD>2,70V		-	-	17.5	
	valid after SCK	Master, VDD>1,62V		-	-	21.2	
tMOH	MOSI hold after SCK	Master, VDD>2,70V		6.32	-	-	
		Master, VDD>1,62V		6.32	-	-	
tSSCK	Slave SCK Period when tMIS=0 on the master side	Slave	Reception	2*(tSIS +tMASTER_OUT) (5)	-	-	
		Slave	Transmission	2*(tSOV +tMASTER_IN) ⁽⁶⁾	-	-	
tSSCKW	SCK high/low width	Slave		-	0,5*tSCK	-	
tSSCKR	SCK rise time ⁽²⁾	Slave		-	0,25*tSCK	-	
tSSCKF	SCK fall time ⁽²⁾	Slave		-	0,25*tSCK	-	
tSIS	MOSI setup to	Slave, VDD>2,70V		10.7	-	-	ns
	SCK	Slave, VDD>1,62V		11.4	-	-	
tSIH	MOSI hold after SCK	Slave, VDD>2,70V		6.4	-	-	
		Slave, VDD>1,62V		7.1	-	-	
tSSS	SS setup to SCK	Slave	PRELOADEN=1	tSOSS+tEXT_MIS +2*tAPBC ^{(8) (9)}	-	-	
			PRELOADEN=0	tSOSS+tEXT_MIS	-	-	
tSSH	SS hold after SCK	Slave		0.5*tSSCK	-	-	
tSOV	MISO output valid after SCK	Slave, VDD>2,70V		-	-	36.1	
		Slave, VDD>1,62V		-	-	46.4	
tSOH	MISO hold after SCK	Slave, VDD>2,70V		13.4	-	-	

2. Decoupling capacitor should be placed close to the device for each supply pin pair in the signal group.

50.4 External Reset Circuit

The external Reset circuit is connected to the RESET pin when the external Reset function is used. The circuit is not necessary when the RESET pin is not driven LOW externally by the application circuitry.

The reset switch can also be removed, if a manual reset is not desired. The RESET pin itself has an internal pull-up resistor, hence it is optional to add any external pull-up resistor.

Figure 50-5. External Reset Circuit Schematic



A pull-up resistor makes sure that the reset does not go low and unintentionally causing a device reset. An additional resistor has been added in series with the switch to safely discharge the filtering capacitor, i.e. preventing a current surge when shorting the filtering capacitor which again can cause a noise spike that can have a negative effect on the system.

Table 50-3. Reset Circuit Connec

Signal Name	Recommended Pin Connection	Description
RESET	Reset low level threshold voltage V_{DDIO} = 1.62V - 2.0V: Below 0.33 * V_{DDIO}	Reset pin
	V _{DDIO} = 2.7V - 3.63V: Below 0.36 * V _{DDIO}	
	Decoupling/filter capacitor 100pF ⁽¹⁾	
	Pull-up resistor 2.2k $\Omega^{(1,2)}$	
	Resistor in series with the switch $330\Omega^{(1)}$	

1. These values are only given as a typical example.

2. The SAM L10/L11 features an internal pull-up resistor on the RESET pin, hence an external pull-up is optional.