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Details

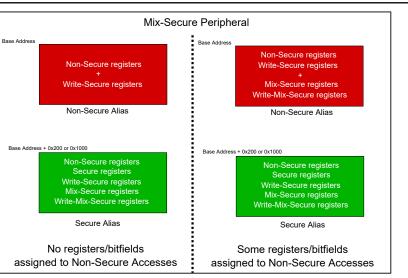
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Product Status	Active
Core Processor	ARM® Cortex®-M23
Core Size	32-Bit Single-Core
Speed	32MHz
Connectivity	I ² C, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, POR, PWM, WDT
Number of I/O	17
Program Memory Size	16KB (16K x 8)
Program Memory Type	FLASH
EEPROM Size	2K x 8
RAM Size	8K x 8
Voltage - Supply (Vcc/Vdd)	1.62V ~ 3.63V
Data Converters	A/D 5x12b; D/A 1x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	24-VFQFN Exposed Pad
Supplier Device Package	24-VQFN (4x4)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/atsaml11d14a-mut

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SAM L10/L11 Family SAM L11 Security Features



Mix-Secure peripherals have always the following registers:

- NONSEC register is a generic register that tells the Non-Secure application which resources inside a Mix-Secure peripheral can be used
- NSCHK register is a register allowing the Non-Secure application to be notified when the security configuration of a Mix-Secure peripheral is being modified during application execution

Important: It is recommended that the Non-Secure application first copy the content of NONSEC register inside NSCHK register, and then enable the NSCHK interrupt flags. Once done, any changes to the NONSEC register by the Secure application will trigger an interrupt so that Non-Secure application can take appropriate actions. This mechanism allows the Secure application to dynamically change the security attribution of a Mix-Secure peripheral and avoid illegal accesses from the Non-Secure application. The interrupt handler should always copy the NONSEC register to NSCHK register before exiting it.

Mix-Secure peripherals can have five type of registers:

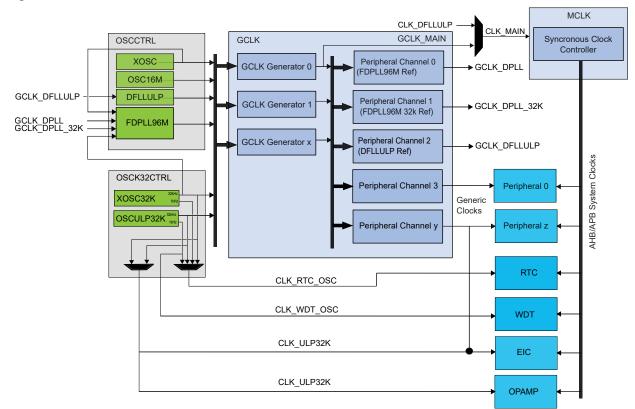
- Non-Secure: these registers will always be available in both the Secure and Non-Secure aliases
- Secure: these registers will never be available in the Non-Secure alias and always available in the Secure alias
- Write-Secure: these are registers than can:
 - Be written or read by the Secure application only in the Secure alias
 - Only read by the Non-Secure application in Non-Secure alias. Write is forbidden.
- **Mix-Secure** registers : these ones are used when a resource can be allocated to either the Secure and Non-Secure alias
 - Note that, in some cases, the Mix-Secure properties apply to a bitfield only (like one I/O bit in the PORT peripheral register)
- Write-Mix-Secure registers (NVMCTRL peripheral only): these are Mix-Secure registers, which:
 - can be written or read by the Secure application only in the Secure alias
 - can only be read by the Non-Secure application in Non-Secure alias <u>except</u> if Non-Secure writes are authorized in NVMCTRL.NONSEC register

17. Clock System

This chapter summarizes the clock distribution and terminology in the SAM L10/L11 device. This document will not explain every detail of its configuration, hence for in-depth details, refer to the respective peripherals descriptions and the *Generic Clock* documentation.

17.1 Clock Distribution

Figure 17-1. Clock Distribution



The SAM L10/L11 clock system consists of these features:

- Clock sources, that is oscillators controlled by OSCCTRL and OSC32KCTRL
 - A clock source provides a time base that is used by other components, such as Generic Clock Generators. Example clock sources are the internal 16MHz oscillator (OSC16M), external crystal oscillator (XOSC) and the Fractional Digital Phase Locked Loop (FDPLL96M).
- *Generic Clock Controller (GCLK),* which generates, controls and distributes the asynchronous clock consisting of:
 - Generic Clock Generators: These are programmable prescalers that can use any of the system clock sources as a time base. The Generic Clock Generator 0 generates the clock signal GCLK_MAIN, which is used by the Power Manager and the Main Clock (MCLK) module, which in turn generates synchronous clocks.
 - Generic Clocks: These are clock signals generated by Generic Clock Generators and output by the Peripheral Channels, and serve as clocks for the peripherals of the system. Multiple instances of a peripheral will typically have a separate Generic Clock for each instance.

After enabling OSC16M, the OSC16M clock is output as soon as the oscillator is ready (STATUS.OSC16MRDY=1). User must ensure that the OSC16M is fully disabled before enabling it by reading STATUS.OSC16MRDY=0.

After reset, OSC16M is enabled and serves as the default clock source at 4MHz.

OSC16M will behave differently in different sleep modes based on the settings of OSC16MCTRL.RUNSTDBY, OSC16MCTRL.ONDEMAND, and OSC16MCTRL.ENABLE. If OSC16MCTRL.ENABLE=0, the OSC16M will be always stopped. For OSC16MCTRL.ENABLE=1, this table is valid:

CPU Mode	OSC16MCTRL.RUN STDBY	OSC16MCTRL.OND EMAND	Sleep Behavior
Active or Idle	-	0	Always run
Active or Idle	-	1	Run if requested by peripheral
Standby	1	0	Always run
Standby	1	1	Run if requested by peripheral
Standby	0	-	Run if requested by peripheral

Table 23-2. OSC16M Sleep Behavior

OSC16M is used as a clock source for the generic clock generators. This is configured by the Generic Clock Generator Controller.

Related Links

18. GCLK - Generic Clock Controller

23.6.5 Ultra Low-Power Digital Frequency Locked Loop (DFLLULP) Operation

The Ultra Low-Power Digital Frequency Locked Loop (DFLLULP) is an internal oscillator that can output a selectable frequency based on user inputs. The frequency is a multiplication ratio relative to a given reference clock using the tuning feature. The oscillator has to be enabled for the tuner to work.

Figure 23-2. Block Diagram

23.6.5.1 Basic Operation

23.6.5.1.1 Initialization

The following bits are enable-protected, meaning that they can only be written when the DFLLULP is disabled (DFLLULPCTRL.ENABLE is zero):

- Binary Search Enable bit in Control register (DFLLULPCTRL.BINSE)
- Safe Mode bit in Control register (DFLLULPCTRL.SAFE)
- Dither Mode bit in Control register (DFLLULPCTRL.DITHER)
- Division Factor bits in Control register (DFLLULPCTRL.DIV)

The following registers are enable-protected:

- Dither Control register (DFLLULPDITHER)
- Target Ratio register (DFLLULPRATIO)

Enable-protected bits in the DFLLULPCTRL register can be written at the same time as DFLLULPCTRL.ENABLE is written to one, but not at the same time as DFLLULPCTRL.ENABLE is written to zero.

SAM L10/L11 Family OSC32KCTRL – 32KHz Oscillators Controller

	Name: Offset: Reset: Property:	INTFLAG 0x08 0x00000000 -						
Bit	31	30	29	28	27	26	25	24
Access								
Reset								
Bit	23	22	21	20	19	18	17	16
Access								
Reset								
Bit	15	14	13	12	11	10	9	8
Access								
Reset								
Bit	7	6	5	4	3	2	1	0
						CLKFAIL		XOSC32KRDY
Access						R/W		R/W
Reset						0		0

24.8.3 Interrupt Flag Status and Clear

Bit 2 – CLKFAIL XOSC32K Clock Failure Detection

This flag is cleared by writing a '1' to it.

This flag is set on a zero-to-one transition of the XOSC32K Clock Failure Detection bit in the Status register (STATUS.CLKFAIL) and will generate an interrupt request if INTENSET.CLKFAIL is '1'.

Writing a '0' to this bit has no effect.

Writing a '1' to this bit will clear the XOSC32K Clock Failure Detection flag.

Bit 0 – XOSC32KRDY XOSC32K Ready

This flag is cleared by writing a '1' to it.

This flag is set by a zero-to-one transition of the XOSC32K Ready bit in the Status register (STATUS.XOSC32KRDY), and will generate an interrupt request if INTENSET.XOSC32KRDY=1.

Writing a '0' to this bit has no effect.

Writing a '1' to this bit clears the XOSC32K Ready interrupt flag.

25.8.1 Interrupt Enable Clear

Name:	INTENCLR
Offset:	0x00
Reset:	0x0000000
Property:	PAC Write-Protection

This register allows the user to disable an interrupt without doing a read-modify-write operation. Changes in this register will also be reflected in the Interrupt Enable Set register (INTENSET).

Bit	31	30	29	28	27	26	25	24
Access								
Reset								
Bit	23	22	21	20	19	18	17	16
Access								
Reset								
Bit	15	14	13	12	11	10	9	8
					ULPVREFRDY	VCORERDY		VREGRDY
Access					R/W	R/W		R/W
Reset					0	0		0
Bit	7	6	5	4	3	2	1	0
						B33SRDY	BOD33DET	BOD33RDY
Access	-					R/W	R/W	R/W
Reset						0	0	0

Bit 11 – ULPVREFRDY Low Power Voltage Reference Ready Interrupt Enable Writing a '0' to this bit has no effect.

The ULPVREFRDY bit will clear on a zero-to-one transition of the Low Power Voltage Reference Ready bit in the Status register (STATUS.ULPVREFRDY).

Value	Description
0	The Low Power Ready interrupt is disabled.
1	The Low Power Ready interrupt is enabled and an interrupt request will be generated when the ULPVREFRDY Interrupt Flag is set.

Bit 10 – VCORERDY VDDCORE Voltage Ready Interrupt Enable

Writing a '0' to this bit has no effect.

Writing a '1' to this bit will clear the VDDCORE Ready Interrupt Enable bit, which disables the VDDCORE Ready interrupt.

Value	Description
0	The VDDCORE Ready interrupt is disabled.
1	The VDDCORE Ready interrupt is enabled and an interrupt request will be generated when the VCORERDY Interrupt Flag is set.

26.8.2 Configuration

Name:	CONFIG
Offset:	0x01
Reset:	x initially determined from NVM User Row after reset
Property:	PAC Write-Protection

Bit	7	6	5	4	3	2	1	0
	WINDOW[3:0]			PER[3:0]				
Access	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Reset	х	x	x	x	х	x	x	x

Bits 7:4 – WINDOW[3:0] Window Mode Time-Out Period

In Window mode, these bits determine the watchdog closed window period as a number of cycles of the 1.024kHz CLK_WDT_OSC clock.

These bits are loaded from NVM User Row at start-up.

Value	Name	Description
0x0	CYC8	8 clock cycles
0x1	CYC16	16 clock cycles
0x2	CYC32	32 clock cycles
0x3	CYC64	64 clock cycles
0x4	CYC128	128 clock cycles
0x5	CYC256	256 clock cycles
0x6	CYC512	512 clock cycles
0x7	CYC1024	1024 clock cycles
0x8	CYC2048	2048 clock cycles
0x9	CYC4096	4096 clock cycles
0xA	CYC8192	8192 clock cycles
0xB	CYC16384	16384 clock cycles
0xC-0xF	Reserved	Reserved

Bits 3:0 – PER[3:0] Time-Out Period

These bits determine the watchdog time-out period as a number of 1.024kHz CLK_WDTOSC clock cycles. In Window mode operation, these bits define the open window period.

These bits are loaded from NVM User Row at startup.

Value	Name	Description
0x0	CYC8	8 clock cycles
0x1	CYC16	16 clock cycles
0x2	CYC32	32 clock cycles
0x3	CYC64	64 clock cycles
0x4	CYC128	128 clock cycles
0x5	CYC256	256 clock cycles
0x6	CYC512	512 clock cycles
0x7	CYC1024	1024 clock cycles
0x8	CYC2048	2048 clock cycles

27.6.8 Additional Features

27.6.8.1 Periodic Intervals

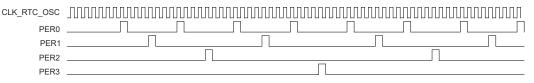
The RTC prescaler can generate interrupts and events at periodic intervals, allowing flexible system tick creation. Any of the upper eight bits of the prescaler (bits 2 to 9) can be the source of an interrupt/event. When one of the eight Periodic Event Output bits in the Event Control register (EVCTRL.PEREO[n=0..7]) is '1', an event is generated on the 0-to-1 transition of the related bit in the prescaler, resulting in a periodic event frequency of:

$$f_{\text{PERIODIC}(n)} = \frac{f_{\text{CLK}_{\text{RTC}_{\text{OSC}}}}}{2^{n+3}}$$

 $f_{CLK_RTC_OSC}$ is the frequency of the internal prescaler clock CLK_RTC_OSC, and n is the position of the EVCTRL.PEREOn bit. For example, PER0 will generate an event every eight CLK_RTC_OSC cycles, PER1 every 16 cycles, etc. This is shown in the figure below.

Periodic events are independent of the prescaler setting used by the RTC counter, except if CTRLA.PRESCALER is zero. Then, no periodic events will be generated.

Figure 27-5. Example Periodic Events



27.6.8.2 Frequency Correction

The RTC Frequency Correction module employs periodic counter corrections to compensate for a tooslow or too-fast oscillator. Frequency correction requires that CTRLA.PRESCALER is greater than 1.

The digital correction circuit adds or subtracts cycles from the RTC prescaler to adjust the frequency in approximately 1ppm steps. Digital correction is achieved by adding or skipping a single count in the prescaler once every 8192 CLK_RTC_OSC cycles. The Value bit group in the Frequency Correction register (FREQCORR.VALUE) determines the number of times the adjustment is applied over 128 of these periods. The resulting correction is as follows:

Correction in ppm $= \frac{\text{FREQCORR.VALUE}}{8192 \cdot 128} \cdot 10^6 \text{ppm}$

This results in a resolution of 0.95367ppm.

The Sign bit in the Frequency Correction register (FREQCORR.SIGN) determines the direction of the correction. A positive value will add counts and increase the period (reducing the frequency), and a negative value will reduce counts per period (speeding up the frequency).

Digital correction also affects the generation of the periodic events from the prescaler. When the correction is applied at the end of the correction cycle period, the interval between the previous periodic event and the next occurrence may also be shortened or lengthened depending on the correction value.

27.6.8.3 General Purpose Registers

The RTC includes four General Purpose registers (GPn). These registers are reset only when the RTC is reset or when tamper detection occurs while CTRLA.GPTRST=1, and remain powered while the RTC is powered. They can be used to store user-defined values while other parts of the system are powered off.

The general purpose registers 2*n and 2*n+1 are enabled by writing a '1' to the General Purpose Enable bit n in the Control B register (CTRLB.GPnEN).

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SAM L10/L11 Family

RTC – Real-Time Counter

	Name: Offset: Reset: Property:	INTFLAG 0x0C 0x0000 -						
Bit	15	14	13	12	11	10	9	8
	OVF	TAMPER						ALARM0
Access	R/W	R/W						R/W
Reset	0	0						0
Bit	7	6	5	4	3	2	1	0
	PER7	PER6	PER5	PER4	PER3	PER2	PER1	PER0
Access	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Reset	0	0	0	0	0	0	0	0

27.12.6 Interrupt Flag Status and Clear in Clock/Calendar mode (CTRLA.MODE=2)

Bit 15 – OVF Overflow

This flag is cleared by writing a '1' to the flag.

This flag is set on the next CLK_RTC_CNT cycle after an overflow condition occurs, and an interrupt request will be generated if INTENCLR/SET.OVF is '1'.

Writing a '0' to this bit has no effect.

Writing a '1' to this bit clears the Overflow interrupt flag.

Bit 14 – TAMPER Tamper

This flag is set after a tamper condition occurs, and an interrupt request will be generated if INTENCLR.TAMPER/INTENSET.TAMPER is '1'. Writing a '0' to this bit has no effect. Writing a '1' to this bit clears the Tamper interrupt flag.

Bit 8 – ALARM0 Alarm 0

This flag is cleared by writing a '1' to the flag.

This flag is set on the next CLK_RTC_CNT cycle after a match with the compare condition, and an interrupt request will be generated if INTENCLR/SET.ALARM0 is one.

Writing a '0' to this bit has no effect.

Writing a '1' to this bit clears the Alarm 0 interrupt flag.

Bits 0, 1, 2, 3, 4, 5, 6, 7 – PERn Periodic Interval n [n = 7..0]

This flag is cleared by writing a '1' to the flag.

This flag is set on the 0-to-1 transition of prescaler bit [n+2], and an interrupt request will be generated if INTENCLR/SET.PERx is '1'.

Writing a '0' to this bit has no effect.

Writing a '1' to this bit clears the Periodic Interval n interrupt flag.

- The transfer descriptor must be made valid by writing a one to the Valid bit in the Block Transfer Control register (BTCTRL.VALID)
- Number of beats in the block transfer must be selected by writing the Block Transfer Count (BTCNT) register
- Source address for the block transfer must be selected by writing the Block Transfer Source Address (SRCADDR) register
- Destination address for the block transfer must be selected by writing the Block Transfer Destination Address (DSTADDR) register

If CRC calculation is needed, the CRC engine must be configured before it is enabled, as outlined by the following steps:

- The CRC input source must selected by writing the CRC Input Source bit group in the CRC Control register (CRCCTRL.CRCSRC)
- The type of CRC calculation must be selected by writing the CRC Polynomial Type bit group in the CRC Control register (CRCCTRL.CRCPOLY)
- If I/O is selected as input source, the beat size must be selected by writing the CRC Beat Size bit group in the CRC Control register (CRCCTRL.CRCBEATSIZE)

28.6.2.2 Enabling, Disabling, and Resetting

The DMAC is enabled by writing the DMA Enable bit in the Control register (CTRL.DMAENABLE) to '1'. The DMAC is disabled by writing a '0' to CTRL.DMAENABLE.

A DMA channel is enabled by writing the Enable bit in the Channel Control A register (CHCTRLA.ENABLE) to '1', after writing the corresponding channel id to the Channel ID bit group in the Channel ID register (CHID.ID). A DMA channel is disabled by writing a '0' to CHCTRLA.ENABLE.

The CRC is enabled by writing a '1' to the CRC Enable bit in the Control register (CTRL.CRCENABLE). The CRC is disabled by writing a '0' to CTRL.CRCENABLE.

The DMAC is reset by writing a '1' to the Software Reset bit in the Control register (CTRL.SWRST) while the DMAC and CRC are disabled. All registers in the DMAC except DBGCTRL will be reset to their initial state.

A DMA channel is reset by writing a '1' to the Software Reset bit in the Channel Control A register (CHCTRLA.SWRST), after writing the corresponding channel id to the Channel ID bit group in the Channel ID register (CHID.ID). The channel registers will be reset to their initial state. The corresponding DMA channel must be disabled in order for the reset to take effect.

28.6.2.3 Transfer Descriptors

Together with the channel configurations the transfer descriptors decides how a block transfer should be executed. Before a DMA channel is enabled (CHCTRLA.ENABLE is written to one), and receives a transfer trigger, its first transfer descriptor has to be initialized and valid (BTCTRL.VALID). The first transfer descriptor describes the first block transfer of a transaction.

All transfer descriptors must reside in SRAM. The addresses stored in the Descriptor Memory Section Base Address (BASEADDR) and Write-Back Memory Section Base Address (WRBADDR) registers tell the DMAC where to find the descriptor memory section and the write-back memory section.

The descriptor memory section is where the DMAC expects to find the first transfer descriptors for all DMA channels. As BASEADDR points only to the first transfer descriptor of channel 0 (see figure below), all first transfer descriptors must be stored in a contiguous memory section, where the transfer descriptors must be ordered according to their channel number. For further details on linked descriptors, refer to 28.6.3.1 Linked Descriptors.

29.8.14 Security Attribution Check

Name:	NSCHK
Offset:	0x3C
Reset:	0x0000000
Property:	PAC Write-Protection

This register allows the user to select one or more external pins to check their security attribution as nonsecured.

	>	Important:	This register i	s only availab	ble for SAM L	11 and has no	o effect for S /	AM L10.
Bit	31	30	29	28	27	26	25	24
	NMI							
Access	RW/RW/RW							
Reset	0							
Bit	23	22	21	20	19	18	17	16
Access								
Reset								
Bit	15	14	13	12	11	10	9	8
ы.	10	14	13	12	11	10	9	0
Access								
Reset								
110301								
Bit	7	6	5	4	3	2	1	0
[EXTIN	NT[7:0]			
Access	RW/RW/RW	RW/RW/RW	RW/RW/RW	RW/RW/RW	RW/RW/RW	RW/RW/RW	RW/RW/RW	RW/RW/RW
Reset	0	0	0	0	0	0	0	0

Bit 31 – NMI Non-Maskable Interrupt Security Attribution Check

This bit selects the Non-Maskable Interrupt pin for security attribution check. If the NMI bit in NONSECNMI is set to the opposite value, then the NSCHK interrupt flag will be set.

Value	Description
0	0-to-1 transition will be detected on corresponding NONSEC bit.
1	1-to-0 transition will be detected on corresponding NONSEC bit.

Bits 7:0 – EXTINT[7:0] External Interrupts Security Attribution Check

These bits select the individual pins for security attribution check. If any pin selected in NSCHK has the corresponding bit in NONSEC set to the opposite value, then the NSCHK interrupt flag will be set.

30.8.13 Data Scramble Control

Name:	DSCC
Offset:	0x30
Reset:	0x0000000
Property:	PAC Write-Protection, Secure, Enable-Protected



Important: This register is only available for SAM L11 and has no effect for SAM L10.

Bit	31	30	29	28	27	26	25	24
					DSCKE	Y[29:24]		
Access			W/-/W	W/-/W	W/-/W	W/-/W	W/-/W	W/-/W
Reset			0	0	0	0	0	0
Bit	23	22	21	20	19	18	17	16
[DSCKE	Y[23:16]			
Access	W/-/W	W/-/W	W/-/W	W/-/W	W/-/W	W/-/W	W/-/W	W/-/W
Reset	0	0	0	0	0	0	0	0
Bit	15	14	13	12	11	10	9	8
[DSCKE	Y[15:8]			
Access	W/-/W	W/-/W	W/-/W	W/-/W	W/-/W	W/-/W	W/-/W	W/-/W
Reset	0	0	0	0	0	0	0	0
Bit	7	6	5	4	3	2	1	0
[DSCK	EY[7:0]			
Access	W/-/W	W/-/W	W/-/W	W/-/W	W/-/W	W/-/W	W/-/W	W/-/W
Reset	0	0	0	0	0	0	0	0

Bits 29:0 – DSCKEY[29:0] Data Scramble Key

This key value is used for data scrambling of the Secure Data Flash. After reset the key is 0. When written, the new value in the register is an XOR of the value written and the previous value of DSCC.DSCKEY.

This register is write only and will always read back as zero.

This register is Enable-Protected with SECCTRL.DSCEN meaning that it can't be modified when DSCEN=1 otherwise a PAC error is generated.

Updated DSCC.DSCKEY contents <- DSCC.DSCKEY XOR value written.

31.8.8 Permutation Write

Name:PERMWOffset:0x010Reset:0x00Property:PAC Write-Protected

Bit	7	6	5	4	3	2	1	0
							DATA[2:0]	
Access						W	W	W
Reset						0	0	0

Bits 2:0 – DATA[2:0] Permutation Write Data Data is the input value for the scrambler permutation function:

PERMR.DATA = Permutate(PERMW.DATA, DSCC.DSCKEY)

These bits will always return zero when read.

32.8.7 Data Output Value Set

Name:	OUTSET
Offset:	0x18
Reset:	0x0000000
Property:	PAC Write-Protection, Mix-Secure



Important: For **SAM L11 Non-Secure** accesses, read and write accesses (RW*) are allowed only if the security attribution for the corresponding I/O pin is set as Non-Secured in the NONSEC register.

This register allows the user to set one or more output I/O pin drive levels high, without doing a readmodify-write operation. Changes in this register will also be reflected in the Data Output Value (OUT), Data Output Value Toggle (OUTTGL) and Data Output Value Clear (OUTCLR) registers.



Tip: The I/O pins are assembled in pin groups ("PORT groups") with up to 32 pins. Group 0 consists of the PA pins, group 1 is for the PB pins, etc. Each pin group has its own PORT registers, with a 0x80 address spacing. For example, the register address offset for the Data Direction (DIR) register for group 0 (PA00 to PA31) is 0x00, and the register address offset for the DIR register for group 1 (PB00 to PB31) is 0x80.

Bit	31	30	29	28	27	26	25	24
Dir I	01		20		T[31:24]	20	20	
Access	RW/RW*/RW							
Reset	0	0	0	0	0	0	0	0
	-	-	-	-	-	-	-	-
Bit	23	22	21	20	19	18	17	16
				OUTSE	T[23:16]			
Access	RW/RW*/RW							
Reset	0	0	0	0	0	0	0	0
Bit	15	14	13	12	11	10	9	8
				OUTSE	T[15:8]			
Access	RW/RW*/RW							
Reset	0	0	0	0	0	0	0	0
Bit	7	6	5	4	3	2	1	0
				OUTS	ET[7:0]			
Access	RW/RW*/RW							
Reset	0	0	0	0	0	0	0	0

Bits 31:0 – OUTSET[31:0] PORT Data Output Value Set

Writing '0' to a bit has no effect.

Bits 17:16 – TXPO[1:0] Transmit Data Pinout

These bits define the transmit data (TxD) and XCK pin configurations.

This bit is not synchronized.

ТХРО	TxD Pin Location	XCK Pin Location (When Applicable)	RTS/TE	стѕ
0x0	SERCOM PAD[0]	SERCOM PAD[1]	N/A	N/A
0x1	SERCOM PAD[2]	SERCOM PAD[3]	N/A	N/A
0x2	SERCOM PAD[0]	N/A	SERCOM PAD[2]	SERCOM PAD[3]
0x3	SERCOM_PAD[0]	SERCOM_PAD[1]	SERCOM_PAD[2]	N/A

Bits 15:13 – SAMPR[2:0] Sample Rate

These bits select the sample rate.

These bits are not synchronized.

SAMPR[2:0]	Description
0x0	16x over-sampling using arithmetic baud rate generation.
0x1	16x over-sampling using fractional baud rate generation.
0x2	8x over-sampling using arithmetic baud rate generation.
0x3	8x over-sampling using fractional baud rate generation.
0x4	3x over-sampling using arithmetic baud rate generation.
0x5-0x7	Reserved

Bit 10 - RXINV Receive Data Invert

This bit controls whether the receive data (RxD) is inverted or not.

Note: Start, parity and stop bit(s) are unchanged. When enabled, parity is calculated on the inverted data.

Value	Description
0	RxD is not inverted.
1	RxD is inverted.

Bit 9 – TXINV Transmit Data Invert

This bit controls whether the transmit data (TxD) is inverted or not.

Note: Start, parity and stop bit(s) are unchanged. When enabled, parity is calculated on the inverted data.

Value	Description
0	TxD is not inverted.
1	TxD is inverted.

Bit 8 – IBON Immediate Buffer Overflow Notification

This bit controls when the buffer overflow status bit (STATUS.BUFOVF) is asserted when a buffer overflow occurs.

This bit has no effect when input capture operation is enabled.

Value	Description				
0	The CCBUFx and PERBUF buffer registers value are copied into CCx and PER registers on				
	hardware update condition.				
1	The CCBUFx and PERBUF buffer registers value are not copied into CCx and PER registers				
	on hardware update condition.				

Bit 0 – DIR Counter Direction

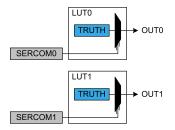
This bit is used to change the direction of the counter.

Writing a '0' to this bit has no effect

Writing a '1' to this bit will clear the bit and make the counter count up.

Value	Description				
0	The timer/counter is counting up (incrementing).				
1	The timer/counter is counting down (decrementing).				

Figure 40-11. SERCOM Input Selection



Related Links

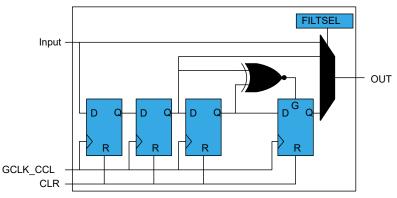
- 32. PORT I/O Pin Controller
- 18. GCLK Generic Clock Controller
- 42. AC Analog Comparators
- 38. TC Timer/Counter
- 34. SERCOM Serial Communication Interface

40.6.2.5 Filter

By default, the LUT output is a combinatorial function of the LUT inputs. This may cause some short glitches when the inputs change value. These glitches can be removed by clocking through filters, if demanded by application needs.

The Filter Selection bits in LUT Control register (LUTCTRLx.FILTSEL) define the synchronizer or digital filter options. When a filter is enabled, the OUT output will be delayed by two to five GCLK cycles. One APB clock after the corresponding LUT is disabled, all internal filter logic is cleared. **Note:** Events used as LUT input will also be filtered, if the filter is enabled.

Figure 40-12. Filter



40.6.2.6 Edge Detector

The edge detector can be used to generate a pulse when detecting a rising edge on its input. To detect a falling edge, the TRUTH table should be inverted.

The edge detector is enabled by writing '1' to the Edge Selection bit in LUT Control register (LUTCTRLx.EDGESEL). In order to avoid unpredictable behavior, either the filter or synchronizer must be enabled.

Edge detection is disabled by writing a '0' to LUTCTRLx.EDGESEL. After disabling a LUT, the corresponding internal Edge Detector logic is cleared one APB clock cycle later.

(OFFSETCORR). The offset correction value is subtracted from the converted data before writing the Result register (RESULT).

The gain error is defined as the deviation of the last output step's midpoint from the ideal straight line, after compensating for offset error. The gain error cancellation is handled by the Gain Correction register (GAINCORR).

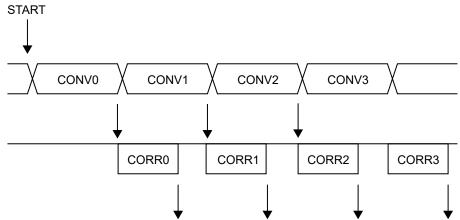
To correct these two errors, the Digital Correction Logic Enabled bit in the Control C register (CTRLC.CORREN) must be set.

Offset and gain error compensation results are both calculated according to:

Result = $(Conversion value + - OFFSETCORR) \cdot GAINCORR$

The correction will introduce a latency of 13 CLK_ADC clock cycles. In free running mode this latency is introduced on the first conversion only, since its duration is always less than the propagation delay. In single conversion mode this latency is introduced for each conversion.

Figure 41-8. ADC Timing Correction Enabled



41.6.2.15 Reference Buffer Compensation Offset

A hardware compensation using a reference buffer can be used.

When the REFCTRL.REFCOMP bit is set, the offset of the reference buffer is sensed during the ADC sampling phase. This offset will be then cancelled during the conversion phase. This feature allows to decrease the overall gain error of the ADC.

There is also a digital gain correction (refer to Offset and gain correction chapter) but contrary to that digital gain correction, the hardware compensation won't introduce any latency.

41.6.3 Additional Features

41.6.3.1 Double Buffering

The following registers are double buffered:

- Input Control (INPUTCTRL)
- Control C (CTRLC)
- Average Control (AVGCTRL)
- Sampling Time Control (SAMPCTRL)
- Window Monitor Lower Threshold (WINLT)
- Window Monitor Upper Threshold (WINUT)

42.8.1 Control A

Name:CTRLAOffset:0x00Reset:0x00Property:PAC Write-Protection, Write-Synchronized

Bit	7	6	5	4	3	2	1	0
							ENABLE	SWRST
Access							R/W	W
Reset							0	0

Bit 1 – ENABLE Enable

Due to synchronization, there is delay from updating the register until the peripheral is enabled/disabled. The value written to CTRL.ENABLE will read back immediately and the corresponding bit in the Synchronization Busy register (SYNCBUSY.ENABLE) will be set. SYNCBUSY.ENABLE is cleared when the peripheral is enabled/disabled.

Value	Description
0	The AC is disabled.
1	The AC is enabled. Each comparator must also be enabled individually by the Enable bit in
	the Comparator Control register (COMPCTRLn.ENABLE).

Bit 0 – SWRST Software Reset

Writing a '0' to this bit has no effect.

Writing a '1' to this bit resets all registers in the AC to their initial state, and the AC will be disabled.

Writing a '1' to CTRLA.SWRST will always take precedence, meaning that all other writes in the same write-operation will be discarded.

Due to synchronization, there is a delay from writing CTRLA.SWRST until the reset is complete. CTRLA.SWRST and SYNCBUSY.SWRST will both be cleared when the reset is complete.

Value	Description
0	There is no reset operation ongoing.
1	The reset operation is ongoing.

43.8.6 Interrupt Flag Status and Clear

Name:INTFLAGOffset:0x06Reset:0x00Property:PAC Write-Protection

Bit	7	6	5	4	3	2	1	0
							EMPTY	UNDERRUN
Access							R/W	R/W
Reset							0	0

Bit 1 – EMPTY Data Buffer Empty

This flag is cleared by writing a '1' to it or by writing new data to DATABUF.

This flag is set when data is transferred from DATABUF to DATA, and the DAC is ready to receive new data in DATABUF, and will generate an interrupt request if INTENCLR/SET.EMPTY is one.

Writing a '0' to this bit has no effect.

Writing a '1' to this bit will clear the Data Buffer Empty interrupt flag.

Bit 0 – UNDERRUN Underrun

This flag is cleared by writing a '1' to it.

This flag is set when a start conversion event occurs when DATABUF is empty, and will generate an interrupt request if INTENCLR/SET.UNDERRUN is one.

Writing a '0' to this bit has no effect.

Writing a '1' to this bit will clear the Underrun interrupt flag.

52. Acronyms and Abbreviations

The below table contains acronyms and abbreviations used in this document.

Table 52-1. Acronyms and Abbreviations

Abbreviation	Description			
AC	Analog Comparator			
ADC	Analog-to-Digital Converter			
ADDR	Address			
AES	Advanced Encryption Standard			
АНВ	Advanced High-performance Bus			
AMBA	Advanced Microcontroller Bus Architecture			
APB	AMBA Advanced Peripheral Bus			
AREF	Analog Reference Voltage			
BOD	Brown-out Detector			
CAL	Calibration			
CC	Compare/Capture			
CCL	Configurable Custom Logic			
CLK	Clock			
CRC	Cyclic Redundancy Check			
CTRL	Control			
DAC	Digital-to-Analog Converter			
DAP	Debug Access Port			
DFLL	Digital Frequency Locked Loop			
DPLL	Digital Phase Locked Loop			
DMAC	DMA (Direct Memory Access) Controller			
DSU	Device Service Unit			
EEPROM	Electrically Erasable Programmable Read-Only Memory			
EIC	External Interrupt Controller			
EVSYS	Event System			
FDPLL	Fractional Digital Phase Locked Loop, also DPLL			
FREQM	Frequency Meter			
GCLK	Generic Clock Controller			
GND Ground				