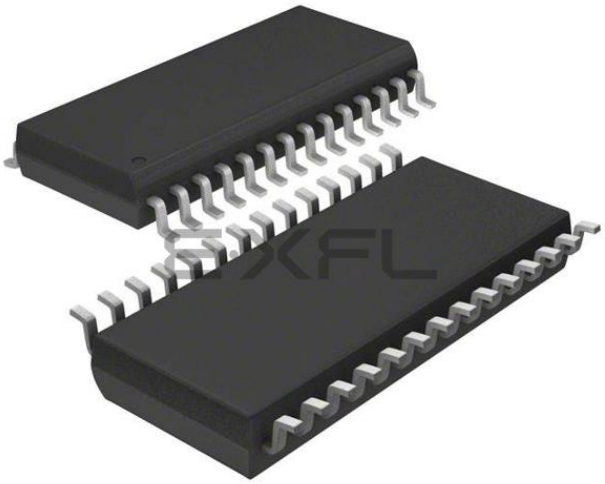

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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	M8C
Core Size	8-Bit
Speed	24MHz
Connectivity	I²C, IrDA, SPI, UART/USART
Peripherals	LVD, POR, PWM, WDT
Number of I/O	26
Program Memory Size	8KB (8K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	256 x 8
Voltage - Supply (Vcc/Vdd)	3V ~ 5.25V
Data Converters	A/D - 14bit; D/A - 8bit
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	28-SSOP (0.209", 5.30mm Width)
Supplier Device Package	28-SSOP
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/cy8c24533-24pvxi

PSoC Functional Overview

The PSoC family consists of many Mixed-Signal Array with On-Chip Controller devices. These devices are designed to replace multiple traditional MCU-based system components with one, low cost single-chip programmable device. PSoC devices include configurable blocks of analog and digital logic, and programmable interconnects. This architecture allows the user to create customized peripheral configurations that match the requirements of each individual application. Additionally, a fast CPU, Flash program memory, SRAM data memory, and configurable IO are included in a range of convenient pinouts and packages.

The PSoC architecture, as shown in the Logic Block Diagram on page 1, is comprised of four main areas: PSoC Core, Digital System, Analog System, and System Resources. Configurable global busing allows all the device resources to be combined into a complete custom system. The PSoC CY8C24x33 family can have up to three IO ports that connect to the global digital and analog interconnects, providing access to four digital blocks and four analog blocks.

PSoC Core

The PSoC Core is a powerful engine that supports a rich feature set. The core includes a CPU, memory, clocks, and configurable GPIO (General Purpose IO).

The M8C CPU core is a powerful processor with speeds up to 24 MHz, providing a four MIPS 8-bit Harvard architecture microprocessor. The CPU utilizes an interrupt controller with 11 vectors, to simplify programming of real time embedded events. Program execution is timed and protected using the included Sleep and Watch Dog Timers (WDT).

Memory encompasses 8 KB of Flash for program storage, 256 bytes of SRAM for data storage, and up to 2 KB of EEPROM emulated using the Flash. Program Flash utilizes four protection levels on blocks of 64 bytes, allowing customized software IP protection.

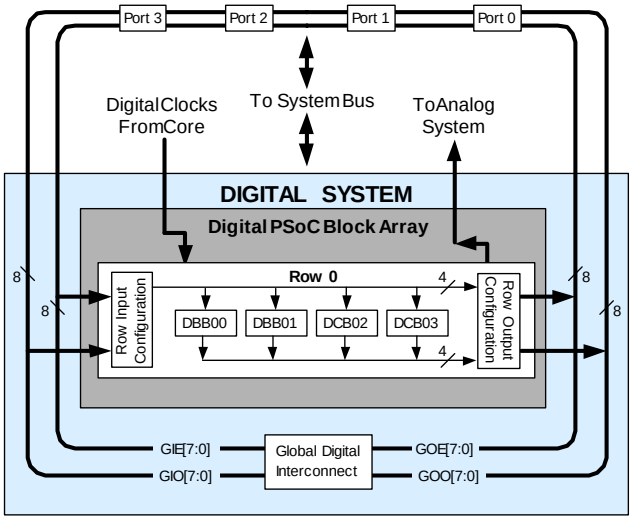
The PSoC device incorporates flexible internal clock generators, including a 24 MHz IMO (internal main oscillator) accurate to ±5% over temperature and voltage. The 24 MHz IMO can also be doubled to 48 MHz for use by the digital system. A low power 32 kHz ILO (internal low speed oscillator) is provided for the Sleep timer and WDT. If crystal accuracy is desired, the ECO (32.768 kHz external crystal oscillator) is available for use as a Real Time Clock (RTC) and can optionally generate a crystal-accurate 24 MHz system clock using a PLL. The clocks, together with programmable clock dividers (as a System Resource), provide the flexibility to integrate almost any timing requirement into the PSoC device.

PSoC GPIOs provide connection to the CPU, digital and analog resources of the device. Each pin's drive mode may be selected from eight options, allowing great flexibility in external interfacing. Every pin also has the capability to generate a system interrupt on high level, low level, and change from last read.

Digital System

The Digital System is composed of 4 digital PSoC blocks. Each block is an 8-bit resource that can be used alone or combined with other blocks to form 8, 16, 24, and 32-bit peripherals, which are called user module references.

Figure 1. Digital System Block Diagram



The digital peripheral configurations include:

- PWMs (8 to 32 bit)
- PWMs with Dead band (8 to 32 bit)
- Counters (8 to 32 bit)
- Timers (8 to 32 bit)
- UART 8 bit with selectable parity (up to 1)
- SPI master and slave (up to 1)
- I2C slave and master (one available as a System Resource)
- Cyclical Redundancy Checker/Generator (8 to 32 bit)
- IrDA (up to one)
- Pseudo Random Sequence Generators (8 to 32 bit)

The digital blocks can be connected to any GPIO through a series of global buses that can route any signal to any pin. The buses also allow for signal multiplexing and for performing logic operations. This configurability frees your designs from the constraints of a fixed peripheral controller.

Digital blocks are provided in rows of four, where the number of blocks varies by PSoC device family. This allows you the optimum choice of system resources for your application. Family resources are shown in the table titled PSoC Device Characteristics on page 4.

Analog System

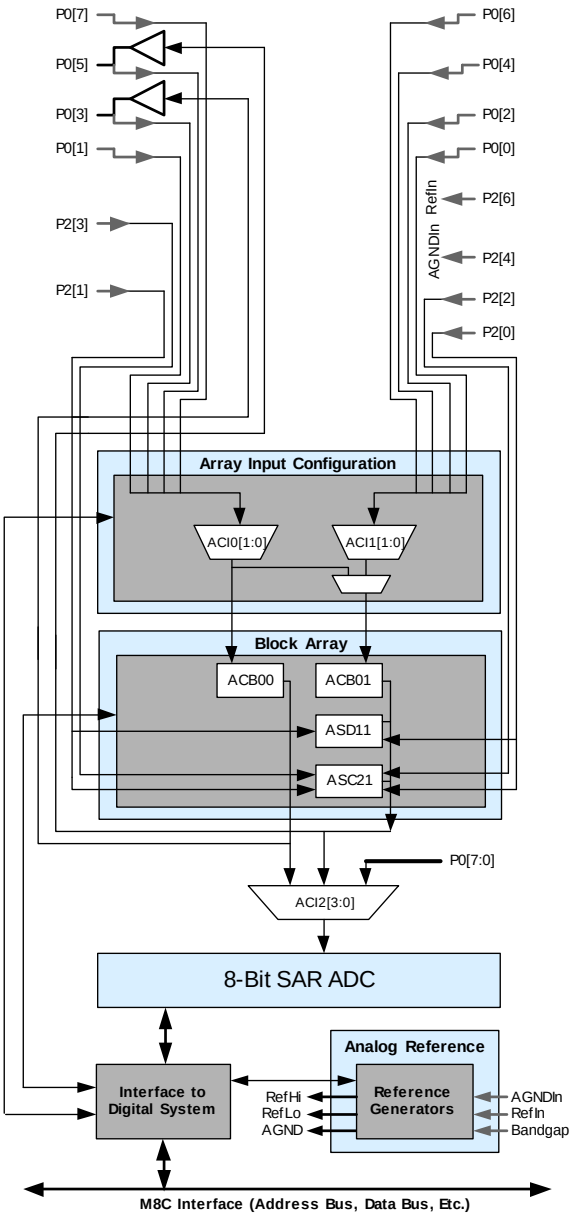
The Analog system is composed of an 8-bit SAR ADC and four configurable blocks. The programmable 8-bit SAR ADC is an optimized ADC that runs up to 300 Ksps, with monotonic guarantee. It also has the features to support a motor control application.

Each analog block is comprised of an opamp circuit allowing the creation of complex analog signal flows. Analog peripherals are very flexible and can be customized to support specific application requirements. Some of the more common PSoC analog functions (most available as user modules) are:

- Filters (2 and 4 pole band pass, low-pass, and notch)
- Amplifiers (up to 2, with selectable gain to 48x)
- Instrumentation amplifiers (1 with selectable gain to 93x)
- Comparators (up to 2, with 16 selectable thresholds)
- DACs (up to 2, with 6- to 9-bit resolution)
- Multiplying DACs (up to 2, with 6- to 9-bit resolution)
- High current output drivers (two with 30 mA drive as a Core Resource)
- 1.3V reference (as a System Resource)
- DTMF dialer
- Modulators
- Correlators
- Peak detectors
- Many other topologies possible

Analog blocks are arranged in a column of three, which includes one CT (Continuous Time) and two SC (Switched Capacitor) blocks. The Analog Column 0 contains the SAR8 ADC block rather than the standard SC blocks.

Figure 2. Analog System Block Diagram



Debugger

The PSoC Designer Debugger subsystem provides hardware in-circuit emulation, allowing the designer to test the program in a physical system while providing an internal view of the PSoC device. Debugger commands allow the designer to read and program and read and write data memory, read and write IO registers, read and write CPU registers, set and clear breakpoints, and provide program run, halt, and step control. The debugger also allows the designer to create a trace buffer of registers and memory locations of interest.

Online Help System

The online help system displays online, context-sensitive help for the user. Designed for procedural and quick reference, each functional subsystem has its own context-sensitive help. This system also provides tutorials and links to FAQs and an Online Support Forum to aid the designer in getting started.

Hardware Tools

In-Circuit Emulator

A low cost, high functionality ICE (In-Circuit Emulator) is available for development support. This hardware has the capability to program single devices.

The emulator consists of a base unit that connects to the PC by way of a USB port. The base unit is universal and operates with all PSoC devices. Emulation pods for each device family are available separately. The emulation pod takes the place of the PSoC device in the target board and performs full speed (24 MHz) operation.

Designing with User Modules

The development process for the PSoC device differs from that of a traditional fixed function microprocessor. The configurable analog and digital hardware blocks give the PSoC architecture a unique flexibility that pays dividends in managing specification change during development and by lowering inventory costs. These configurable resources, called PSoC Blocks, have the ability to implement a wide variety of user-selectable functions. Each block has several registers that determine its function and connectivity to other blocks, multiplexers, buses and to the IO pins. Iterative development cycles permit you to adapt the hardware as well as the software. This substantially lowers the risk of having to select a different part to meet the final design requirements.

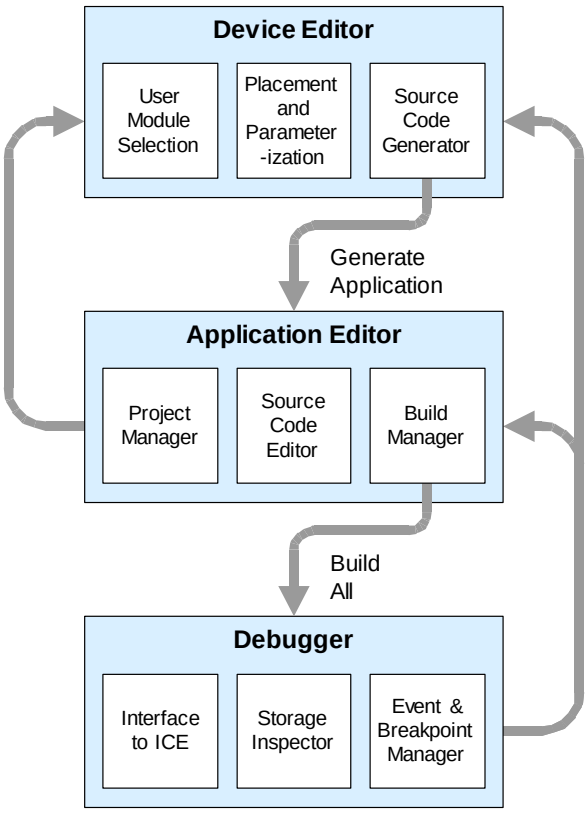
To speed the development process, the PSoC Designer Integrated Development Environment (IDE) provides a library of pre-built, pre-tested hardware peripheral functions, called “User Modules.” User modules make selecting and implementing peripheral devices simple, and come in analog, digital, and mixed signal varieties. The standard User Module library contains over 50 common peripherals such as ADCs, DACs Timers, Counters, UARTs, and other not-so common peripherals such as DTMF Generators and Bi-Quad analog filter sections.

Each user module establishes the basic register settings that implement the selected function. It also provides parameters that allow you to tailor its precise configuration to your particular application. For example, a Pulse Width Modulator User Module configures one or more digital PSoC blocks, one for each 8 bits of resolution. The user module parameters permit you to establish the pulse width and duty cycle. User modules also provide tested software to cut your development time. The user module application programming interface (API) provides high-level functions to control and respond to hardware events at run-time. The API also provides optional interrupt service routines that you can adapt as needed.

The API functions are documented in user module data sheets that are viewed directly in the PSoC Designer IDE. These data sheets explain the internal operation of the user module and provide performance specifications. Each data sheet describes the use of each user module parameter and documents the setting of each register controlled by the user module.

The development process starts when you open a new project and bring up the Device Editor, a graphical user interface (GUI) for configuring the hardware. You pick the user modules you need for your project and map them onto the PSoC blocks with point-and-click simplicity. Next, you build signal chains by interconnecting user modules to each other and the IO pins. At this stage, you also configure the clock source connections and enter parameter values directly or by selecting values from drop-down menus. When you are ready to test the hardware configuration or move on to developing code for the project, you perform the “Generate Application” step. This causes PSoC Designer to generate source code that automatically configures the device to your specification and provides the high-level user module API functions.

Figure 4. User Module/Source Code Development Flows



The next step is to write your main program, and any sub-routines using PSoC Designer's Application Editor subsystem. The Application Editor includes a Project Manager that allows you to open the project source code files (including all generated code files) from a hierarchal view. The source code editor provides syntax coloring and advanced edit features for both C and assembly language. File search capabilities include simple string searches and recursive "grep-style" patterns. A single mouse click invokes the Build Manager. It employs a professional-strength "makefile" system to automatically analyze all file dependencies and run the compiler and assembler as necessary. Project-level options control optimization strategies used by the compiler and linker. Syntax errors are displayed in a console window. Double clicking the error message takes you directly to the offending line of source code. When all is correct, the linker builds a HEX file image suitable for programming.

The last step in the development process takes place inside the PSoC Designer's Debugger subsystem. The Debugger downloads the HEX image to the In-Circuit Emulator (ICE) where it runs at full speed. Debugger capabilities rival those of systems costing many times more. In addition to traditional single-step, run-to-breakpoint and watch-variable features, the Debugger provides a large trace buffer and allows you to define complex breakpoint events that include monitoring address and data bus values, memory locations, and external signals.

Document Conventions

Acronyms Used

The following table lists the acronyms that are used in this document.

Table 2. Acronyms Used

Acronym	Description
AC	alternating current
ADC	analog-to-digital converter
API	application programming interface
CPU	central processing unit
CT	continuous time
DAC	digital-to-analog converter
DC	direct current
EEPROM	electrically erasable programmable read-only memory
FSR	full scale range
GPIO	general purpose IO
IO	input/output
IPOR	imprecise power on reset
LSb	least-significant bit
LVD	low voltage detect
MSb	most-significant bit
PC	program counter
POR	power on reset
PPOR	precision power on reset
PSoC®	Programmable System-on-Chip™

Table 2. Acronyms Used (continued)

Acronym	Description
PWM	pulse width modulator
RAM	random access memory
ROM	read only memory
SC	switched capacitor

Units of Measure

A units of measure table is located in the Electrical Specifications section. Table 6 on page 13 lists all the abbreviations used to measure the PSoC devices.

Numeric Naming

Hexadecimal numbers are represented with all letters in uppercase with an appended lowercase 'h' (for example, '14h' or '3Ah'). Hexadecimal numbers may also be represented by a '0x' prefix, the C coding convention. Binary numbers have an appended lowercase 'b' (for example, 01010100b' or '01000011b'). Numbers not indicated by an 'h' or 'b' are decimal.

Table 4. Register Map Bank 0 Table: User Space

Name	Addr (0,Hex)	Access	Name	Addr (0,Hex)	Access	Name	Addr (0,Hex)	Access	Name	Addr (0,Hex)	Access
PRT0DR	00	RW		40			80			C0	
PRT0IE	01	RW		41			81			C1	
PRT0GS	02	RW		42			82			C2	
PRT0DM2	03	RW		43			83			C3	
PRT1DR	04	RW		44		ASD11CR0	84	RW		C4	
PRT1IE	05	RW		45		ASD11CR1	85	RW		C5	
PRT1GS	06	RW		46		ASD11CR2	86	RW		C6	
PRT1DM2	07	RW		47		ASD11CR3	87	RW		C7	
PRT2DR	08	RW		48			88			C8	
PRT2IE	09	RW		49			89			C9	
PRT2GS	0A	RW		4A			8A			CA	
PRT2DM2	0B	RW		4B			8B			CB	
PRT3DR	0C	RW		4C			8C			CC	
PRT3IE	0D	RW		4D			8D			CD	
PRT3GS	0E	RW		4E			8E			CE	
PRT3DM2	0F	RW		4F			8F			CF	
	10			50			90			D0	
	11			51			91			D1	
	12			52			92			D2	
	13			53			93			D3	
	14			54		ASC21CR0	94	RW		D4	
	15			55		ASC21CR1	95	RW		D5	
	16			56		ASC21CR2	96	RW	I2C_CFG	D6	RW
	17			57		ASC21CR3	97	RW	I2C_SCR	D7	#
	18			58			98		I2C_DR	D8	RW
	19			59			99		I2C_MSCR	D9	#
	1A			5A			9A		INT_CLR0	DA	RW
	1B			5B			9B		INT_CLR1	DB	RW
	1C			5C			9C			DC	
	1D			5D			9D		INT_CLR3	DD	RW
	1E			5E			9E		INT_MSK3	DE	RW
	1F			5F			9F			DF	
DBB00DR0	20	#	AMX_IN	60	RW		A0		INT_MSK0	E0	RW
DBB00DR1	21	W		61			A1		INT_MSK1	E1	RW
DBB00DR2	22	RW		62			A2		INT_VC	E2	RC
DBB00CR0	23	#	ARF_CR	63	RW		A3		RES_WDT	E3	W
DBB01DR0	24	#	CMP_CR0	64	#		A4		DEC_DH	E4	RC
DBB01DR1	25	W	ASY_CR	65	#		A5		DEC_DL	E5	RC
DBB01DR2	26	RW	CMP_CR1	66	RW		A6		DEC_CR0	E6	RW
DBB01CR0	27	#	SARADC_DL	67	RW		A7		DEC_CR1	E7	RW
DCB02DR0	28	#		68			A8		MUL0_X	E8	W
DCB02DR1	29	W	SARADC_CR0	69	#		A9		MUL0_Y	E9	W
DCB02DR2	2A	RW	SARADC_CR1	6A	RW		AA		MUL0_DH	EA	R
DCB02CR0	2B	#		6B			AB		MUL0_DL	EB	R
DCB03DR0	2C	#	TMP_DR0	6C	RW		AC		ACC0_DR1	EC	RW
DCB03DR1	2D	W	TMP_DR1	6D	RW		AD		ACC0_DR0	ED	RW
DCB03DR2	2E	RW	TMP_DR2	6E	RW		AE		ACC0_DR3	EE	RW
DCB03CR0	2F	#	TMP_DR3	6F	RW		AF		ACC0_DR2	EF	RW
	30		ACB00CR3	70	RW	RDI0RI	B0	RW		F0	
	31		ACB00CR0	71	RW	RDI0SYN	B1	RW		F1	
	32		ACB00CR1	72	RW	RDI0IS	B2	RW		F2	
	33		ACB00CR2	73	RW	RDI0LT0	B3	RW		F3	
	34		ACB01CR3	74	RW	RDI0LT1	B4	RW		F4	
	35		ACB01CR0	75	RW	RDI0RO0	B5	RW		F5	
	36		ACB01CR1 *	76	RW	RDI0RO1	B6	RW		F6	
	37		ACB01CR2 *	77	RW		B7		CPU_F	F7	RL
	38			78			B8			F8	
	39			79			B9			F9	
	3A			7A			BA			FA	
	3B			7B			BB			FB	
	3C			7C			BC			FC	
	3D			7D			BD			FD	

Gray fields are reserved. # Access is bit specific.

Table 4. Register Map Bank 0 Table: User Space (continued)

Name	Addr (0,Hex)	Access	Name	Addr (0,Hex)	Access	Name	Addr (0,Hex)	Access	Name	Addr (0,Hex)	Access
	3E			7E			BE		CPU_SCR1	FE	#
	3F			7F			BF		CPU_SCR0	FF	#

Gray fields are reserved. # Access is bit specific.

Table 5. Register Map Bank 1 Table: Configuration Space

Name	Addr (1,Hex)	Access	Name	Addr (1,Hex)	Access	Name	Addr (1,Hex)	Access	Name	Addr (1,Hex)	Access
PRT0DM0	00	RW		40			80			C0	
PRT0DM1	01	RW		41			81			C1	
PRT0IC0	02	RW		42			82			C2	
PRT0IC1	03	RW		43			83			C3	
PRT1DM0	04	RW		44		ASD11CR0	84	RW		C4	
PRT1DM1	05	RW		45		ASD11CR1	85	RW		C5	
PRT1IC0	06	RW		46		ASD11CR2	86	RW		C6	
PRT1IC1	07	RW		47		ASD11CR3	87	RW		C7	
PRT2DM0	08	RW		48			88			C8	
PRT2DM1	09	RW		49			89			C9	
PRT2IC0	0A	RW		4A			8A			CA	
PRT2IC1	0B	RW		4B			8B			CB	
PRT3DM0	0C	RW		4C			8C			CC	
PRT3DM1	0D	RW		4D			8D			CD	
PRT3IC0	0E	RW		4E			8E			CE	
PRT3IC1	0F	RW		4F			8F			CF	
	10			50			90		GDI_O_IN	D0	RW
	11			51			91		GDI_E_IN	D1	RW
	12			52			92		GDI_O_OU	D2	RW
	13			53			93		GDI_E_OU	D3	RW
	14			54		ASC21CR0	94	RW		D4	
	15			55		ASC21CR1	95	RW		D5	
	16			56		ASC21CR2	96	RW		D6	
	17			57		ASC21CR3	97	RW		D7	
	18			58			98			D8	
	19			59			99			D9	
	1A			5A			9A			DA	
	1B			5B			9B			DB	
	1C			5C			9C			DC	
	1D			5D			9D		OSC_GO_EN	DD	RW
	1E			5E			9E		OSC_CR4	DE	RW
	1F			5F			9F		OSC_CR3	DF	RW
DBB00FN	20	RW	CLK_CR0	60	RW		A0		OSC_CR0	E0	RW
DBB00IN	21	RW	CLK_CR1	61	RW		A1		OSC_CR1	E1	RW
DBB00OU	22	RW	ABF_CR0	62	RW		A2		OSC_CR2	E2	RW
	23		AMD_CR0	63	RW		A3		VLT_CR	E3	RW
DBB01FN	24	RW		64			A4		VLT_CMP	E4	R
DBB01IN	25	RW		65			A5			E5	
DBB01OU	26	RW	AMD_CR1	66	RW		A6			E6	
	27		ALT_CR0	67	RW		A7			E7	
DCB02FN	28	RW		68		SARADC_TRS	A8	RW	IMO_TR	E8	W
DCB02IN	29	RW		69		SARADC_TRCL	A9	RW	ILO_TR	E9	W
DCB02OU	2A	RW		6A		SARADC_TRCH	AA	RW	BDG_TR	EA	RW
	2B			6B		SARADC_CR2	AB	#	ECO_TR	EB	W
DCB03FN	2C	RW	TMP_DR0	6C	RW	SARADC_LCR	AC	RW		EC	
DCB03IN	2D	RW	TMP_DR1	6D	RW		AD			ED	
DCB03OU	2E	RW	TMP_DR2	6E	RW		AE			EE	
	2F		TMP_DR3	6F	RW		AF			EF	
	30		ACB00CR3	70	RW	RDI0RI	B0	RW		F0	
	31		ACB00CR0	71	RW	RDI0SYN	B1	RW		F1	
	32		ACB00CR1	72	RW	RDI0IS	B2	RW		F2	
	33		ACB00CR2	73	RW	RDI0LT0	B3	RW		F3	
	34		ACB01CR3	74	RW	RDI0LT1	B4	RW		F4	
	35		ACB01CR0	75	RW	RDI0RO0	B5	RW		F5	
	36		ACB01CR1	76	RW	RDI0RO1	B6	RW		F6	

Gray fields are reserved. # Access is bit specific.

Electrical Specifications

This section presents the DC and AC electrical specifications of the CY8C24533 PSoC device. For the latest electrical specifications, visit http://www.cypress.com/psoc.

Specifications are valid for -40°C ≤ T_A ≤ 85°C and T_J ≤ 100°C, except where noted.

Refer to Table 21 on page 22 for the electrical specifications on the internal main oscillator (IMO) using SLIMO mode.

Figure 6. Voltage versus CPU Frequency

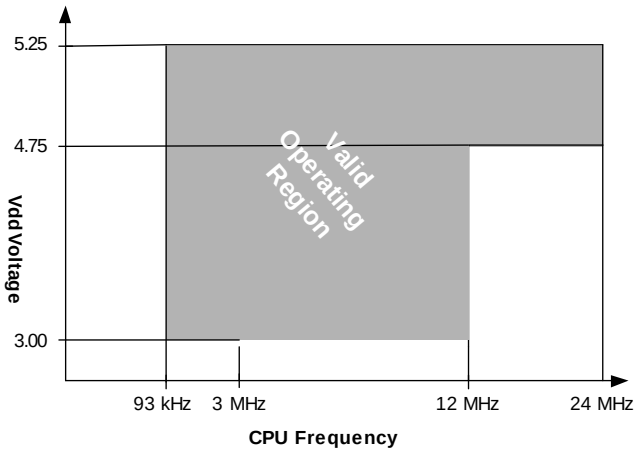
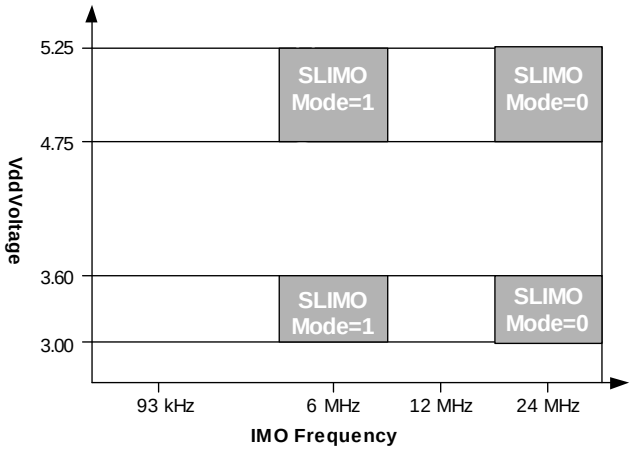


Figure 7. IMO Frequency Trim Options



The following table lists the units of measure that are used in this section.

Table 6. Units of Measure

Symbol	Unit of Measure	Symbol	Unit of Measure
°C	degree Celsius	µW	micro watts
dB	decibels	mA	milli-ampere
fF	femto farad	ms	milli-second
Hz	hertz	mV	milli-volts
KB	1024 bytes	nA	nano ampere
Kbit	1024 bits	ns	nanosecond
kHz	kilohertz	nV	nanovolts
kΩ	kilohm	W	ohm
MHz	megahertz	pA	pico ampere
MΩ	megaohm	pF	pico farad
µA	micro ampere	pp	peak-to-peak
µF	micro farad	ppm	parts per million
µH	micro henry	ps	picosecond
µs	microsecond	sps	samples per second
µV	micro volts	s	sigma: one standard deviation
µVrms	micro volts root-mean-square	V	volts

DC Electrical Characteristics

DC Chip-Level Specifications

The following table lists the guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75V to 5.25V and -40°C ≤ T_A ≤ 85°C, or 3.0V to 3.6V and -40°C ≤ T_A ≤ 85°C, respectively. Typical parameters apply to 5V and 3.3V at 25°C and are for design guidance only.

Table 9. DC Chip-Level Specifications

Symbol	Description	Min	Typ	Max	Units	Notes
Vdd	Supply Voltage	3.0	–	5.25	V	See Table 19 on page 21.
I_{DD}	Supply Current	–	5	8	mA	Conditions are Vdd = 5.0V, T_A = 25 °C, CPU = 3 MHz, SYSCLK doubler disabled, VC1 = 1.5 MHz, VC2 = 93.75 kHz, VC3 = 93.75 kHz, analog power = off. SLIMO mode = 0. IMO = 24 MHz.
I_{DD3}	Supply Current	–	3.3	6.0	mA	Conditions are Vdd = 3.3V, T_A = 25°C, CPU = 3 MHz, SYSCLK doubler disabled, VC1 = 1.5 MHz, VC2 = 93.75 kHz, VC3 = 93.75 kHz, analog power = off. SLIMO mode = 0. IMO = 24 MHz.
I_{SB}	Sleep (Mode) Current with POR, LVD, Sleep Timer, and WDT.[6]	–	3	6.5	µA	Conditions are with internal slow speed oscillator, Vdd = 3.3V, -40°C ≤ T_A ≤ 55°C, analog power = off.
I_{SBH}	Sleep (Mode) Current with POR, LVD, Sleep Timer, and WDT at high temperature.[6]	–	4	25	µA	Conditions are with internal slow speed oscillator, Vdd = 3.3V, 55°C < T_A ≤ 85°C, analog power = off.
I_{SBXTL}	Sleep (Mode) Current with POR, LVD, Sleep Timer, WDT, and external crystal.[6]	–	4	7.5	µA	Conditions are with properly loaded, 1 µW max, 32.768 kHz crystal. Vdd = 3.3V, -40°C ≤ T_A ≤ 55°C, analog power = off.
I_{SBXTLH}	Sleep (Mode) Current with POR, LVD, Sleep Timer, WDT, and external crystal at high temperature.[6]	–	5	26	µA	Conditions are with properly loaded, 1µW max, 32.768 kHz crystal. Vdd = 3.3 V, 55°C < T_A ≤ 85°C, analog power = off.
V_{REF}	Reference Voltage (Bandgap)	1.28	1.30	1.33	V	Trimmed for appropriate Vdd. Vdd > 3.0V

Note
6. Standby current includes all functions (POR, LVD, WDT, Sleep Time) needed for reliable system operation. This must be compared with devices that have similar functions enabled.

DC Operational Amplifier Specifications

The following table lists guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75V to 5.25V and -40°C ≤ T_A ≤ 85°C, or 3.0V to 3.6V and -40°C ≤ T_A ≤ 85°C, respectively. Typical parameters apply to 5V and 3.3V at 25°C and are for design guidance only.

The Operational Amplifier is a component of both the Analog Continuous Time PSoC blocks and the Analog Switched Cap PSoC blocks. The guaranteed specifications are measured in the Analog Continuous Time PSoC block. Typical parameters apply to 5V at 25°C and are for design guidance only.

Table 11. 5V DC Operational Amplifier Specifications

Symbol	Description	Min	Typ	Max	Units	Notes
V_{OSOA}	Input Offset Voltage (absolute value) Power = Low, Opamp Bias = High Power = Medium, Opamp Bias = High Power = High, Opamp Bias = High	 – – –	 1.6 1.3 1.2	 10 8 7.5	 mV mV mV	
TCV_{OSOA}	Average Input Offset Voltage Drift	–	7.0	35.0	µV/°C	
I_{EBOA}	Input Leakage Current (Port 0 Analog Pins)	–	20	–	pA	Gross tested to 1 µA
C_{INOA}	Input Capacitance (Port 0 Analog Pins)	–	4.5	9.5	pF	Package and pin dependent. Temp = 25°C
V_{CMOA}	Common Mode Voltage Range Common Mode Voltage Range (high power or high opamp bias)	0.0 0.5	– –	Vdd Vdd - 0.5	V	The common-mode input voltage range is measured through an analog output buffer. The specification includes the limitations imposed by the characteristics of the analog output buffer.
G_{OLOA}	Open Loop Gain Power = Low, Opamp Bias = High Power = Medium, Opamp Bias = High Power = High, Opamp Bias = High	 60 60 80	–	–	dB	Specification is applicable at high power. For all other bias modes (except high power, high opamp bias), minimum is 60 dB.
$V_{OHIGHOA}$	High Output Voltage Swing (internal signals) Power = Low, Opamp Bias = High Power = Medium, Opamp Bias = High Power = High, Opamp Bias = High	 Vdd - 0.2 Vdd - 0.2 Vdd - 0.5	 – – –	 – – –	 V V V	
V_{OLOWOA}	Low Output Voltage Swing (internal signals) Power = Low, Opamp Bias = High Power = Medium, Opamp Bias = High Power = High, Opamp Bias = High	 – – –	 – – –	 0.2 0.2 0.5	 V V V	
I_{SOA}	Supply Current (including associated AGND buffer) Power = Low, Opamp Bias = High Power = Medium, Opamp Bias = Low Power = Medium, Opamp Bias = High Power = High, Opamp Bias = Low Power = High, Opamp Bias = High	 – – – – –	 300 600 1200 2400 4600	 400 800 1600 3200 6400	 µA µA µA µA µA	
$PSRR_{OA}$	Supply Voltage Rejection Ratio	52	80	–	dB	Vss ≤ VIN ≤ (Vdd - 2.25) or (Vdd - 1.25V) ≤ VIN ≤ Vdd

Table 12. 3.3V DC Operational Amplifier Specifications

Symbol	Description	Min	Typ	Max	Units	Notes
V_{OSOA}	Input Offset Voltage (absolute value) Power = Low, Opamp Bias = High Power = Medium, Opamp Bias = High High Power is 5 Volts Only	 – –	 1.65 1.32	 10 8	 mV mV	
TCV_{OSOA}	Average Input Offset Voltage Drift	–	7.0	35.0	µV/°C	
I_{EBOA}	Input Leakage Current (Port 0 Analog Pins)	–	20	–	pA	Gross tested to 1 µA
C_{INOA}	Input Capacitance (Port 0 Analog Pins)	–	4.5	9.5	pF	Package and pin dependent. Temp = 25°C
V_{CMOA}	Common Mode Voltage Range	0.2	–	Vdd - 0.2	V	The common-mode input voltage range is measured through an analog output buffer. The specification includes the limitations imposed by the characteristics of the analog output buffer.
G_{OLOA}	Open Loop Gain Power = Low, Opamp Bias = Low Power = Medium, Opamp Bias = Low Power = High, Opamp Bias = Low	 60 60 80	–	–	dB	Specification is applicable at high power. For all other bias modes (except high power, high opamp bias), minimum is 60 dB.
$V_{OHIGHOA}$	High Output Voltage Swing (internal signals) Power = Low, Opamp Bias = Low Power = Medium, Opamp Bias = Low Power = High is 5V only	 Vdd - 0.2 Vdd - 0.2 Vdd - 0.2	 – – –	 – – –	 V V V	
V_{OLOWOA}	Low Output Voltage Swing (internal signals) Power = Low, Opamp Bias = Low Power = Medium, Opamp Bias = Low Power = High, Opamp Bias = Low	 – – –	 – – –	 0.2 0.2 0.2	 V V V	
I_{SOA}	Supply Current (including associated AGND buffer) Power = Low, Opamp Bias = High Power = Medium, Opamp Bias = Low Power = Medium, Opamp Bias = High Power = High, Opamp Bias = Low Power = High, Opamp Bias = High	 – – – – –	 300 600 1200 2400 4600	 400 800 1600 3200 6400	 µA µA µA µA µA	
$PSRR_{OA}$	Supply Voltage Rejection Ratio	52	80	–	dB	Vss ≤ VIN ≤ (Vdd - 2.25) or (Vdd - 1.25V) ≤ VIN ≤ Vdd

DC Low Power Comparator Specifications

The following table lists guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75V to 5.25V and -40°C ≤ T_A ≤ 85°C, or 3.0V to 3.6V and -40°C ≤ T_A ≤ 85°C, respectively. Typical parameters apply to 5V and 3.3V at 25°C and are for design guidance only.

Table 13. DC Low Power Comparator Specifications

Symbol	Description	Min	Typ	Max	Units	Notes
V_{REFLPC}	Low power comparator (LPC) reference voltage range	0.2	–	Vdd - 1	V	
I_{SLPC}	LPC supply current	–	10	40	µA	
V_{OSLPC}	LPC voltage offset	–	2.5	30	mV	

DC Analog Output Buffer Specifications

The following table lists guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75V to 5.25V and -40°C ≤ T_A ≤ 85°C, or 3.0V to 3.6V and -40°C ≤ T_A ≤ 85°C, respectively. Typical parameters apply to 5V and 3.3V at 25°C and are for design guidance only.

Table 14. 5V DC Analog Output Buffer Specifications

Symbol	Description	Min	Typ	Max	Units	Notes
V_{OSOB}	Input Offset Voltage (Absolute Value)	–	3	12	mV	
TCV_{OSOB}	Average Input Offset Voltage Drift	–	+6	–	µV/°C	
V_{CMOB}	Common-Mode Input Voltage Range	0.5	–	Vdd - 1.0	V	
R_{OUTOB}	Output Resistance Power = Low Power = High	 – –	 1 1	 – –	 W W	
$V_{OHIGHOB}$	High Output Voltage Swing (Load = 32 ohms to Vdd/2) Power = Low Power = High	 0.5 x Vdd + 1.1 0.5 x Vdd + 1.1	 – –	 – –	 V V	
V_{OLOWOB}	Low Output Voltage Swing (Load = 32 ohms to Vdd/2) Power = Low Power = High	 – –	 – –	 0.5 x Vdd - 1.3 0.5 x Vdd - 1.3	 V V	
I_{SOB}	Supply Current Including Bias Cell (No Load) Power = Low Power = High	 – –	 1.1 2.6	 5.1 8.8	 mA mA	
$PSRR_{OB}$	Supply Voltage Rejection Ratio	52	64	–	dB	V_{OUT} > (Vdd - 1.25)

Table 15. 3.3V DC Analog Output Buffer Specifications

Symbol	Description	Min	Typ	Max	Units	Notes
V_{OSOB}	Input Offset Voltage (Absolute Value)	–	3	12	mV	
TCV_{OSOB}	Average Input Offset Voltage Drift	–	+6	–	µV/°C	
V_{CMOB}	Common-Mode Input Voltage Range	0.5	-	Vdd - 1.0	V	
R_{OUTOB}	Output Resistance Power = Low Power = High	 – –	 1 1	 – –	 W W	
$V_{OHIGHOB}$	High Output Voltage Swing (Load = 1k ohms to Vdd/2) Power = Low Power = High	 0.5 x Vdd + 1.0 0.5 x Vdd + 1.0	 – –	 – –	 V V	
V_{OLOWOB}	Low Output Voltage Swing (Load = 1k ohms to Vdd/2) Power = Low Power = High	 – –	 – –	 0.5 x Vdd - 1.0 0.5 x Vdd - 1.0	 V V	
I_{SOB}	Supply Current Including Bias Cell (No Load) Power = Low Power = High	 –	 0.8 2.0	 2.0 4.3	 mA mA	
$PSRR_{OB}$	Supply Voltage Rejection Ratio	52	64	–	dB	V_{OUT} > (Vdd - 1.25)

DC Programming Specifications

The following table lists guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75V to 5.25V and -40°C ≤ T_A ≤ 85°C, or 3.0V to 3.6V and -40°C ≤ T_A ≤ 85°C, respectively. Typical parameters apply to 5V and 3.3V at 25°C and are for design guidance only.

Table 20. DC Programming Specifications

Symbol	Description	Min	Typ	Max	Units	Notes
Vdd_{IWRITE}	Supply Voltage for Flash Write Operations	3.3	–	–	V	
I_{DDP}	Supply Current During Programming or Verify	–	5	25	mA	
V_{ILP}	Input Low Voltage During Programming or Verify	–	–	0.8	V	
V_{IHP}	Input High Voltage During Programming or Verify	2.1	–	–	V	
I_{ILP}	Input Current when Applying Vilp to P1[0] or P1[1] During Programming or Verify	–	–	0.2	mA	Driving internal pull down resistor.
I_{IHP}	Input Current when Applying Vihp to P1[0] or P1[1] During Programming or Verify	–	–	1.5	mA	Driving internal pull down resistor.
V_{OLV}	Output Low Voltage During Programming or Verify	–	–	Vss + 0.75	V	
V_{OHV}	Output High Voltage During Programming or Verify	Vdd - 1.0	–	Vdd	V	
$Flash_{ENPB}$	Flash Endurance (per block)	50,000	–	–	–	Erase/write cycles per block.
$Flash_{ENT}$	Flash Endurance (total)[9]	1,800,000	–	–	–	Erase/write cycles.
$Flash_{DR}$	Flash Data Retention	10	–	–	Years	

SAR8 ADC DC Specifications

The following table lists guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75V to 5.25V and -40°C ≤ T_A ≤ 85°C, or 3.0V to 3.6V and -40°C ≤ T_A ≤ 85°C, respectively. Typical parameters apply to 5V and 3.3V at 25°C and are for design guidance only.

Table 21. SAR8 ADC DC Specifications

Symbol	Description	Min	Typ	Max	Units	Notes
$V_{ADCVREF}$	Reference voltage at pin P3[0] when configured as ADC reference voltage	3.0	–	5.25	V	The voltage level at P3[0] (when configured as ADC reference voltage) must always be maintained to be less than chip supply voltage level on Vdd pin. $V_{ADCVREF}$ < Vdd.
$I_{ADCVREF}$	Current when P3[0] is configured as ADC V_{REF}	3	–	–	mA	
INL	R-2R Integral Non-linearity[10]	-1.2	–	+1.2	LSB	The maximum LSB is over a sub-range not exceeding 1/16 of the full scale range.
DNL	R-2R Differential Non-linearity[11]	-1	–	+1	LSB	Output is monatonic.

Note

9. A maximum of 36 x 50,000 block endurance cycles is allowed. This may be balanced between operations on 36x1 blocks of 50,000 maximum cycles each, 36x2 blocks of 25,000 maximum cycles each, or 36x4 blocks of 12,500 maximum cycles each (to limit the total number of cycles to 36x50,000 and that no single block ever sees more than 50,000 cycles).

   For the full industrial range, the user must employ a temperature sensor user module (FlashTemp) and feed the result to the temperature argument before writing. Refer to the Flash APIs Application Note AN2015 at http://www.cypress.com under Application Notes for more information.
10. At the 7F and 80 points, the maximum INL is 1.5 LSB.
11. For the 7F to 80 transition, the DNL specification is waived.

AC Electrical Characteristics

AC Chip-Level Specifications

The following table lists guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75V to 5.25V and -40°C ≤ T_A ≤ 85°C, or 3.0V to 3.6V and -40°C ≤ T_A ≤ 85°C, respectively. Typical parameters apply to 5V and 3.3V at 25°C and are for design guidance only.

Table 22. 5V and 3.3V AC Chip-Level Specifications

Symbol	Description	Min	Typ	Max	Units	Notes
F_{IMO24}	Internal Main Oscillator Frequency for 24 MHz	22.8	24	25.2[12],[13],[14]	MHz	Trimmed for 5V or 3.3V operation using factory trim values. See Figure 7 on page 13. SLIMO mode = 0.
F_{IMO6}	Internal Main Oscillator Frequency for 6 MHz	5.75	6	6.35[12],[13],[14]	MHz	Trimmed for 5V or 3.3V operation using factory trim values. See Figure 7 on page 13. SLIMO mode = 1.
F_{CPU1}	CPU Frequency (5V Nominal)	0.093	24	24.6[12],[13]	MHz	
F_{CPU2}	CPU Frequency (3.3V Nominal)	0.093	12	12.3[13],[14]	MHz	
F_{48M}	Digital PSoC Block Frequency	0	48	49.2[12],[13],[15]	MHz	Refer to the AC Digital Block Specifications.
F_{24M}	Digital PSoC Block Frequency	0	24	24.6[13],[15]	MHz	
F_{32K1}	Internal Low Speed Oscillator Frequency	15	32	75	kHz	
F_{32K2}	External Crystal Oscillator	–	32.768	–	kHz	Accuracy is capacitor and crystal dependent. 50% duty cycle.
F_{PLL}	PLL Frequency	–	23.986	–	MHz	Is a multiple (x732) of crystal frequency.
Jitter24M2	24 MHz Period Jitter (PLL)	–	–	600	ps	
$T_{PLLSLEW}$	PLL Lock Time	0.5	–	10	ms	
$T_{PLLSLEWSLOW}$	PLL Lock Time for Low Gain Setting	0.5	–	50	ms	
T_{OS}	External Crystal Oscillator Startup to 1%	–	1700	2620	ms	
T_{OSACC}	External Crystal Oscillator Startup to 100 ppm	–	2800	3800	ms	The crystal oscillator frequency is within 100 ppm of its final value by the end of the T_{osacc} period. Correct operation assumes a properly loaded 1 uW maximum drive level 32.768 kHz crystal. 3.0V≤ Vdd≤5.5V, -40°C ≤T_A≤ 85°C
Jitter32k	32 kHz Period Jitter	–	100		ns	
T_{XRST}	External Reset Pulse Width	10	–	–	µs	
DC24M	24 MHz Duty Cycle	40	50	60	%	
Step24M	24 MHz Trim Step Size	–	50	–	kHz	
Fout48M	48 MHz Output Frequency	46.8	48.0	49.2[12],[14]	MHz	Trimmed. Using factory trim values.
Jitter24M1R	24 MHz Period Jitter (IMO) Root Mean Squared	–	–	600	ps	
F_{MAX}	Maximum frequency of signal on row input or row output.	–	–	12.3	MHz	
T_{RAMP}	Supply Ramp Time	0	–	–	µs	

Notes

12. 4.75V < Vdd < 5.25V.
13. Accuracy derived from Internal Main Oscillator with appropriate trim for Vdd range.
14. 3.0V < Vdd < 3.6V. See Application Note AN2012 “Adjusting PSoC Microcontroller Trims for Dual Voltage-Range Operation” for information on trimming for operation at 3.3V.
15. See the individual user module data sheets for information on maximum frequencies for user modules.

Figure 8. PLL Lock Timing Diagram

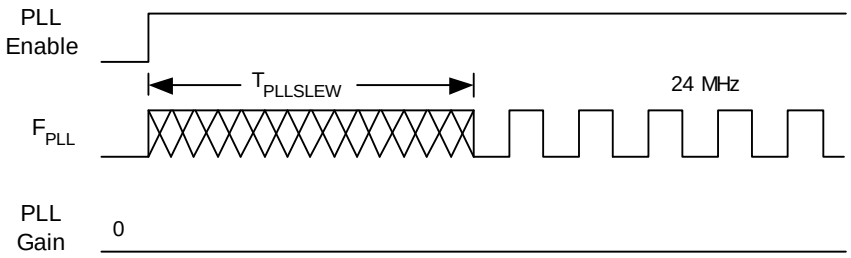


Figure 9. PLL Lock for Low Gain Setting Timing Diagram

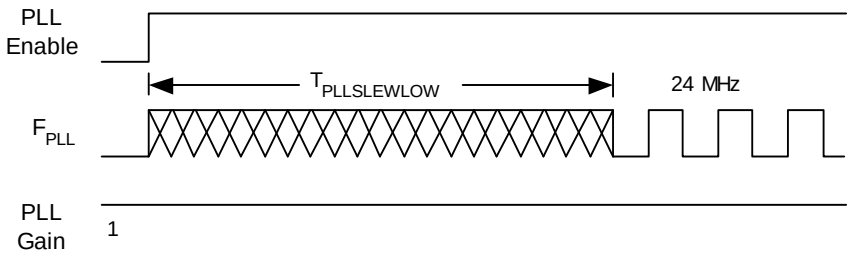


Figure 10. External Crystal Oscillator Startup Timing Diagram

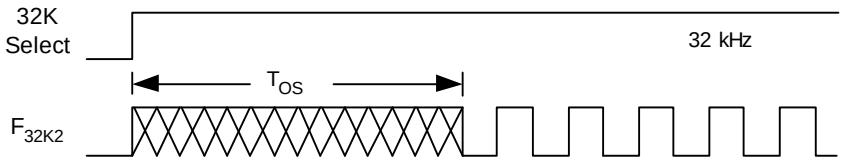


Figure 11. 24 MHz Period Jitter (IMO) Timing Diagram

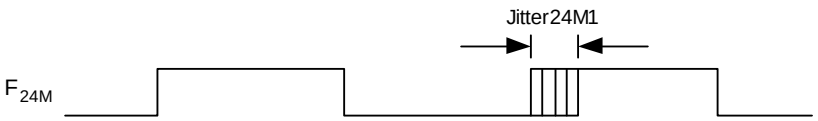
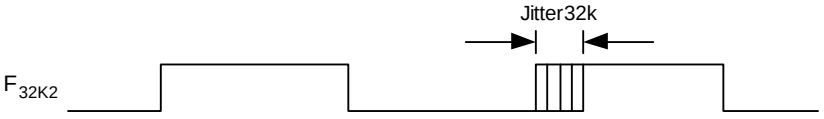


Figure 12. 32 kHz Period Jitter (ECO) Timing Diagram



AC Operational Amplifier Specifications

The following table lists guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75V to 5.25V and -40°C ≤ T_A ≤ 85°C, or 3.0V to 3.6V and -40°C ≤ T_A ≤ 85°C, respectively. Typical parameters apply to 5V and 3.3V at 25°C and are for design guidance only.

Settling times, slew rates, and gain bandwidth are based on the Analog Continuous Time PSoC block.

Power = High and Opamp Bias = High is not supported at 3.3V.

Table 24. 5V AC Operational Amplifier Specifications

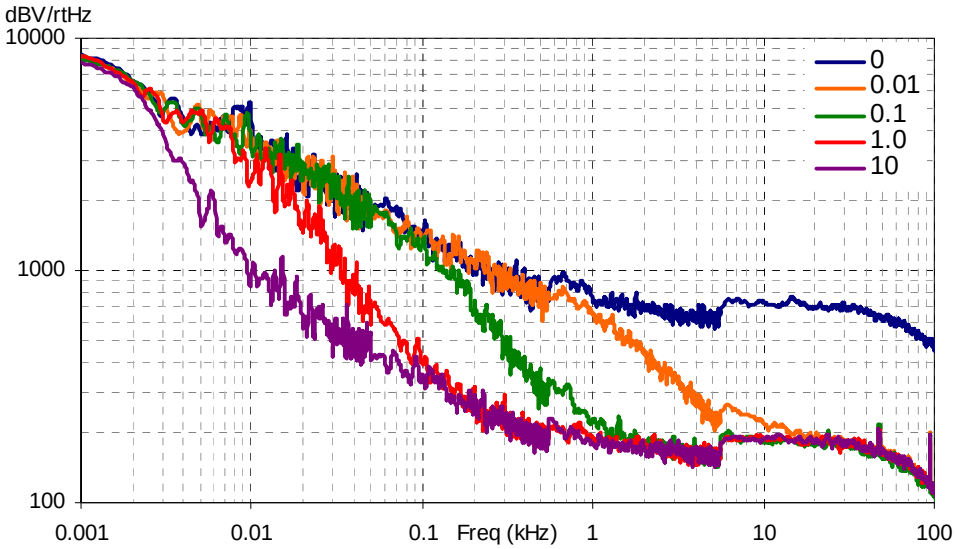
Symbol	Description	Min	Typ	Max	Units
T_{ROA}	Rising Settling Time from 80% of ΔV to 0.1% of ΔV (10 pF load, Unity Gain)				
	Power = Low, Opamp Bias = Low	–	–	3.9	µs
	Power = Medium, Opamp Bias = High	–	–	0.72	µs
	Power = High, Opamp Bias = High	–	–	0.62	µs
T_{SOA}	Falling Settling Time from 20% of ΔV to 0.1% of ΔV (10 pF load, Unity Gain)				
	Power = Low, Opamp Bias = Low	–	–	5.9	µs
	Power = Medium, Opamp Bias = High	–	–	0.92	µs
	Power = High, Opamp Bias = High	–	–	0.72	µs
SR_{ROA}	Rising Slew Rate (20% to 80%)(10 pF load, Unity Gain)				
	Power = Low, Opamp Bias = Low	0.15	–	–	V/µs
	Power = Medium, Opamp Bias = High	1.7	–	–	V/µs
	Power = High, Opamp Bias = High	6.5	–	–	V/µs
SR_{FOA}	Falling Slew Rate (20% to 80%)(10 pF load, Unity Gain)				
	Power = Low, Opamp Bias = Low	0.01	–	–	V/µs
	Power = Medium, Opamp Bias = High	0.5	–	–	V/µs
	Power = High, Opamp Bias = High	4.0	–	–	V/µs
BW_{OA}	Gain Bandwidth Product				
	Power = Low, Opamp Bias = Low	0.75	–	–	MHz
	Power = Medium, Opamp Bias = High	3.1	–	–	MHz
	Power = High, Opamp Bias = High	5.4	–	–	MHz

Table 25. 3.3V AC Operational Amplifier Specifications

Symbol	Description	Min	Typ	Max	Units
T_{ROA}	Rising Settling Time from 80% of ΔV to 0.1% of ΔV (10 pF load, Unity Gain)				
	Power = Low, Opamp Bias = Low	–	–	3.92	µs
	Power = Medium, Opamp Bias = High	–	–	0.72	µs
T_{SOA}	Falling Settling Time from 20% of ΔV to 0.1% of ΔV (10 pF load, Unity Gain)				
	Power = Low, Opamp Bias = Low	–	–	5.41	µs
	Power = Medium, Opamp Bias = High	–	–	0.72	µs
SR_{ROA}	Rising Slew Rate (20% to 80%) (10 pF load, Unity Gain)				
	Power = Low, Opamp Bias = Low	0.31	–	–	V/µs
	Power = Medium, Opamp Bias = High	2.7	–	–	V/µs
SR_{FOA}	Falling Slew Rate (20% to 80%) (10 pF load, Unity Gain)				
	Power = Low, Opamp Bias = Low	0.24	–	–	V/µs
	Power = Medium, Opamp Bias = High	1.8	–	–	V/µs
BW_{OA}	Gain Bandwidth Product				
	Power = Low, Opamp Bias = Low	0.67	–	–	MHz
	Power = Medium, Opamp Bias = High	2.8	–	–	MHz

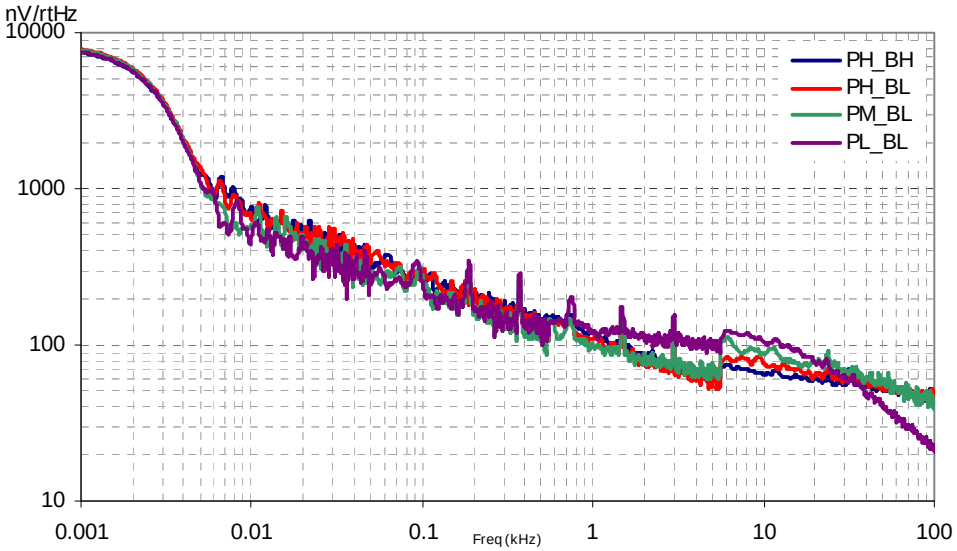
When bypassed by a capacitor on P2[4], the noise of the analog ground signal distributed to each block is reduced by a factor of up to 5 (14 dB). This is at frequencies above the corner frequency defined by the on-chip 8.1k resistance and the external capacitor.

Figure 14. Typical AGND Noise with P2[4] Bypass



At low frequencies, the opamp noise is proportional to 1/f, power independent, and determined by device geometry. At high frequencies, increased power level reduces the noise spectrum level.

Figure 15. Typical Opamp Noise



AC Low Power Comparator Specifications

The following table lists guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75V to 5.25V and -40°C ≤ T_A ≤ 85°C, or 3.0V to 3.6V and -40°C ≤ T_A ≤ 85°C, respectively. Typical parameters apply to 5V and 3.3V at 25°C and are for design guidance only.

Table 26. AC Low Power Comparator Specifications

Symbol	Description	Min	Typ	Max	Units	Notes
T_{RLPC}	LPC response time	–	–	50	µs	≥ 50 mV overdrive comparator reference set within V_{REFLPC}.

AC Digital Block Specifications

The following table lists guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75V to 5.25V and -40°C ≤ T_A ≤ 85°C, or 3.0V to 3.6V and -40°C ≤ T_A ≤ 85°C, respectively. Typical parameters apply to 5V and 3.3V at 25°C and are for design guidance only.

Table 27. 5V and 3.3V AC Digital Block Specifications

Symbol	Description	Min	Typ	Max	Units	Notes
Timer	Capture Pulse Width	50[16]	–	–	ns	
	Maximum Frequency, No Capture	–	–	49.2	MHz	4.75V < Vdd < 5.25V
	Maximum Frequency, With Capture	–	–	24.6	MHz	
Counter	Enable Pulse Width	50[16]	–	–	ns	
	Maximum Frequency, No Enable Input	–	–	49.2	MHz	4.75V < Vdd < 5.25V
	Maximum Frequency, Enable Input	–	–	24.6	MHz	
Dead Band	Kill Pulse Width:					
	Asynchronous Restart Mode	20	–	–	ns	
	Synchronous Restart Mode	50[16]	–	–	ns	
	Disable Mode	50[16]	–	–	ns	
	Maximum Frequency	–	–	49.2	MHz	4.75V < Vdd < 5.25V
CRCPRS (PRS Mode)	Maximum Input Clock Frequency	–	–	49.2	MHz	4.75V < Vdd < 5.25V
CRCPRS (CRC Mode)	Maximum Input Clock Frequency	–	–	24.6	MHz	
SPIM	Maximum Input Clock Frequency	–	–	8.2	MHz	Maximum data rate at 4.1 MHz due to 2 x over clocking.
SPIS	Maximum Input Clock Frequency	–	–	4.1	MHz	
	Width of SS_ Negated Between Transmissions	50[16]	–	–	ns	
Transmitter	Maximum Input Clock Frequency	–	–	24.6	MHz	Maximum data rate at 3.08 MHz due to 8 x over clocking.
	Maximum Input Clock Frequency with Vdd ≥ 4.75V, 2 Stop Bits	–	–	49.2	MHz	Maximum data rate at 6.15 MHz due to 8 x over clocking.
Receiver	Maximum Input Clock Frequency	–	–	24.6	MHz	Maximum data rate at 3.08 MHz due to 8 x over clocking.
	Maximum Input Clock Frequency with Vdd ≥ 4.75V, 2 Stop Bits	–	–	49.2	MHz	Maximum data rate at 6.15 MHz due to 8 x over clocking.

Note
16. 50 ns minimum input pulse width is based on the input synchronizers running at 24 MHz (42 ns nominal period).

AC I²C Specifications

The following table lists guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75V to 5.25V and -40°C ≤ T_A ≤ 85°C, or 3.0V to 3.6V and -40°C ≤ T_A ≤ 85°C, respectively. Typical parameters apply to 5V and 3.3V at 25°C and are for design guidance only.

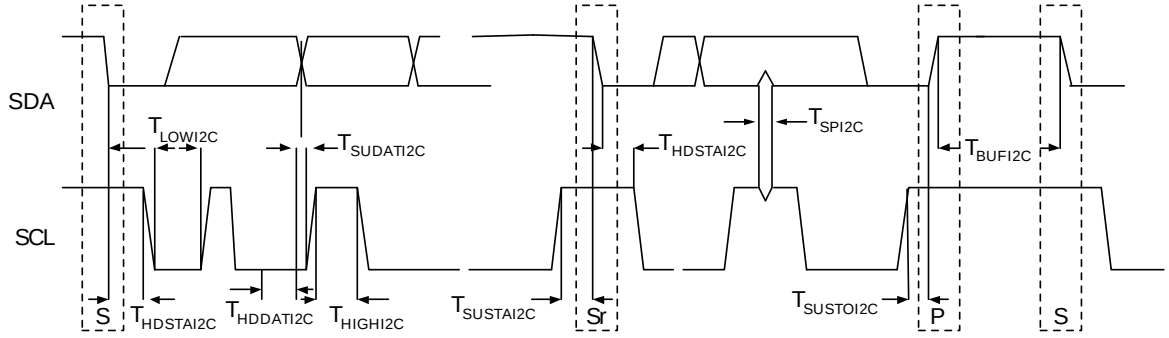
Table 34. AC Characteristics of the I²C SDA and SCL Pins for Vdd > 3.0V

Symbol	Description	Standard Mode		Fast Mode		Units
		Min	Max	Min	Max	
F_{SCLI2C}	SCL Clock Frequency	0	100	0	400	kHz
$T_{HDSTAI2C}$	Hold Time (repeated) START Condition. After this period, the first clock pulse is generated.	4.0	–	0.6	–	µs
T_{LOWI2C}	LOW Period of the SCL Clock	4.7	–	1.3	–	µs
$T_{HIGHI2C}$	HIGH Period of the SCL Clock	4.0	–	0.6	–	µs
$T_{SUSTAI2C}$	Setup Time for a Repeated START Condition	4.7	–	0.6	–	µs
$T_{HDDATI2C}$	Data Hold Time	0	–	0	–	µs
$T_{SUDATI2C}$	Data Setup Time	250	–	100[19]	–	ns
$T_{SUSTOI2C}$	Setup Time for STOP Condition	4.0	–	0.6	–	µs
T_{BUFI2C}	Bus Free Time Between a STOP and START Condition	4.7	–	1.3	–	µs
T_{SPI2C}	Pulse Width of spikes are suppressed by the input filter.	–	–	0	50	ns

Table 35. AC Characteristics of the I²C SDA and SCL Pins for Vdd < 3.0V (Fast Mode Not Supported)

Symbol	Description	Standard Mode		Fast Mode		Units
		Min	Max	Min	Max	
F_{SCLI2C}	SCL Clock Frequency	0	100	–	–	kHz
$T_{HDSTAI2C}$	Hold Time (repeated) START Condition. After this period, the first clock pulse is generated.	4.0	–	–	–	µs
T_{LOWI2C}	LOW Period of the SCL Clock	4.7	–	–	–	µs
$T_{HIGHI2C}$	HIGH Period of the SCL Clock	4.0	–	–	–	µs
$T_{SUSTAI2C}$	Setup Time for a Repeated START Condition	4.7	–	–	–	µs
$T_{HDDATI2C}$	Data Hold Time	0	–	–	–	µs
$T_{SUDATI2C}$	Data Setup Time	250	–	–	–	ns
$T_{SUSTOI2C}$	Setup Time for STOP Condition	4.0	–	–	–	µs
T_{BUFI2C}	Bus Free Time Between a STOP and START Condition	4.7	–	–	–	µs
T_{SPI2C}	Pulse Width of spikes are suppressed by the input filter.	–	–	–	–	ns

Figure 16. Definition for Timing for Fast/Standard Mode on the I²C Bus



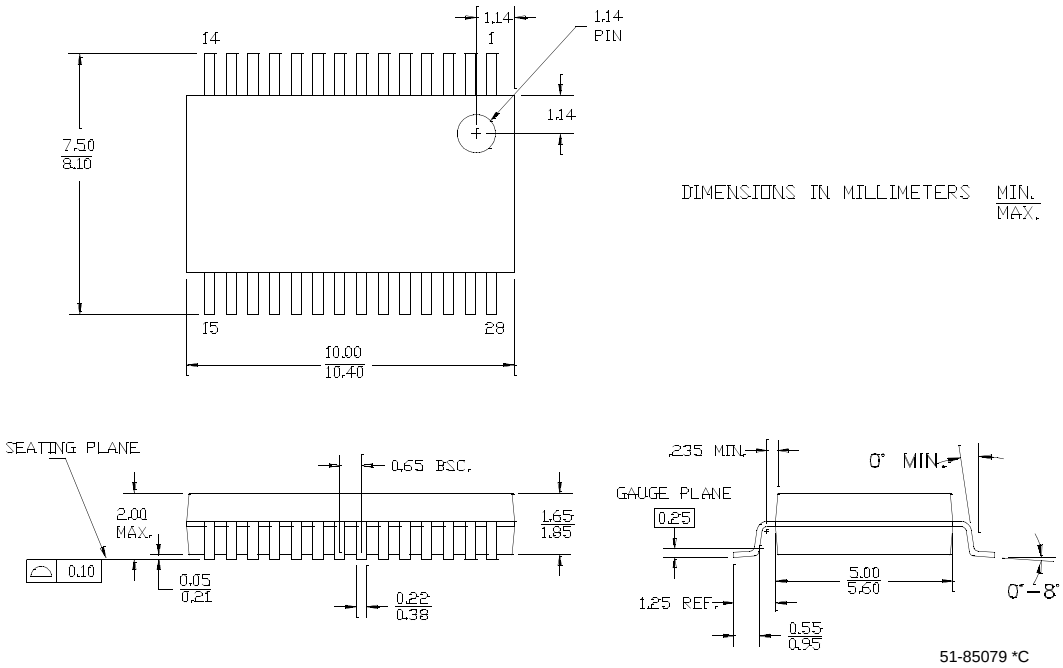
Note

19. A Fast-Mode I2C-bus device can be used in a Standard-Mode I2C-bus system, but the requirement $t_{SU;DAT} \geq 250$ ns must then be met. This is automatically the case if the device does not stretch the LOW period of the SCL signal. If such device does stretch the LOW period of the SCL signal, it must output the next data bit to the SDA line $t_{rmax} + t_{SU;DAT} = 1000 + 250 = 1250$ ns (according to the Standard-Mode I2C-bus specification) before the SCL line is released.

Packaging Information

This section illustrates the packaging specifications for the CY8C24533 PSoC device, along with the thermal impedances for each package, solder reflow peak temperature, and the typical package capacitance on crystal pins.

Figure 17. 28-Pin (210-Mil) SSOP



Thermal Impedances

Table 36. Thermal Impedances by Package

Package	Typical θ_{JA} [20]
28 SSOP	95°C/W

Capacitance on Crystal Pins

Table 37. Typical Package Capacitance on Crystal Pins

Package	Package Capacitance
28 SSOP	2.8 pF

Solder Reflow Peak Temperature

Following is the minimum solder reflow peak temperature to achieve good solderability.

Table 38. Solder Reflow Peak Temperature

Package	Minimum Peak Temperature [21]	Maximum Peak Temperature
28 SSOP	240°C	260°C

Notes
20. $T_J = T_A + POWER \times \theta_{JA}$.
21. Higher temperatures may be required based on the solder melting point. Typical temperatures for solder are 220 ± 5°C with Sn-Pb or 245 ± 5°C with Sn-Ag-Cu paste. Refer to the solder manufacturer specifications.

Ordering Information

The following table lists the CY8C24533 PSoC device family key package features and ordering codes.

Table 39. CY8C24533 PSoC Device Family Key Features and Ordering Information

Package	Ordering Code	Flash (Kbytes)	RAM (Bytes)	Temperature Range	Digital Blocks (Rows of 4)	Analog Blocks (Columns of 3)	Digital IO Pins	Analog Inputs	Analog Outputs	XRES Pin
28 Pin (210 Mil) SSOP	CY8C24533-24PVXI	8	256	-40°C to +85°C	4	4	26	12	2	No
28 Pin (210 Mil) SSOP (Tape and Reel)	CY8C24533-24PVXIT	8	256	-40°C to +85°C	4	4	26	12	2	No